# MULTIVARIATE INTERPOLATION AND CONDITIONALLY POSITIVE DEFINITE FUNCTIONS. II 

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#### Abstract

We continue an earlier study of certain spaces that provide a variational framework for multivariate interpolation. Using the Fourier transform to analyze these spaces, we obtain error estimates of arbitrarily high order for a class of interpolation methods that includes multiquadrics.


## 1. Introduction

This paper continues a study, [11], of certain subspaces $C_{h}$ of $C\left(\mathbf{R}^{n}\right)$, the continuous complex-valued functions on $n$-space $\mathbf{R}^{n}$. The spaces $C_{h}$ provide a variational framework for the following interpolation problem: given numerical values at a scattered set of points in $\mathbf{R}^{n}$, make a good choice of a function $f$ in $C\left(\mathbf{R}^{n}\right)$ that takes on those values.

For the reader's convenience we review some basic features of the development in [11]. The starting point is the selection of an integer $m \geq 0$ and a continuous function $h$ on $\mathbf{R}^{n}$ that is conditionally positive definite of order $m$. For example: $m=1, h(x)=-\sqrt{1+|x|^{2}}$. Using $h$, a space $C_{h}$ with a semi-inner product $(\cdot, \cdot)_{h}$ is constructed. $C_{h}$ is a subspace of $C\left(\mathbf{R}^{h}\right)$, and the null space of $(\cdot, \cdot)_{h}$ is $P_{m-1}$, the polynomials on $\mathbf{R}^{n}$ of degree $m-1$ or less. A key property of $C_{h}$ is this: if $x_{1}, \ldots, x_{N}$ are distinct points in $\mathbf{R}^{n}$ and $v_{1}, \ldots, v_{N}$ are complex numbers, then among all functions $f$ in $C_{h}$ that satisfy the interpolation conditions $f\left(x_{i}\right)=v_{i}$, the quadratic $\|f\|_{h}^{2}=(f, f)_{h}$ is minimized by a function of the form $f=s+p$, where $p$ is in $P_{m-1}$ and

$$
\begin{equation*}
s(x)=\sum_{i=1}^{N} c_{i} h\left(x-x_{i}\right) \tag{1.1}
\end{equation*}
$$

with $\sum_{i=1}^{N} c_{i} x_{i}^{*}=0$ for all $|\alpha|<m$. For the example mentioned, (1.1) is a multiquadric interpolant.

Because the spaces $C_{h}$ are translation-invariant, the Fourier transform is a natural tool for analyzing them; it plays a central role here. To clarify basic ideas and make an orderly division of our results, we avoided Fourier techniques in

[^0][11]. We did, however, rely on them in our earlier investigation [10], which was in fact prompted by the Fourier methods in Duchon [5]. Use of Fourier transforms allows us to give improved descriptions of the spaces $C_{h}$ (see §3) and allows us to single out certain cases where error estimates of order $l \geq m$ are possible (see $\S 4$ ). These estimates apply to the multiquadric case as well as to related examples given in $\S 5$; for each example given there, the integer $l$ can be arbitrarily large.

## 2. Preliminaries

In this section we recall some notation and results involving Fourier transforms and conditionally positive definite functions.

Let $\mathscr{D}\left(\mathbf{R}^{n}\right)$ denote the space of complex-valued functions on $\mathbf{R}^{n}$ that are compactly supported and infinitely differentiable. The Fourier transform of a function $\varphi$ in $\mathscr{D}$ is

$$
\begin{equation*}
\widehat{\varphi}(\xi)=\int e^{-i(x, \breve{\zeta}\rangle} \varphi(x) d x \tag{2.1}
\end{equation*}
$$

In order to make use of theorems from Gelfand and Vilenkin [7], we adopt their definition of $m$ th-order conditional positive definiteness. (Equivalence with the definition used in [11] can be seen from Proposition 2.4 and Theorem 6.1 below.) Thus, for a continuous function $h$ we assume

$$
\begin{equation*}
\int h(x) \varphi * \tilde{\varphi}(x) d x \geq 0 \tag{2.2}
\end{equation*}
$$

holds whenever $\varphi=p(D) \psi$ with $\psi$ in $\mathscr{D}$ and $p(D)$ a linear homogeneous constant coefficient differential operator of order $m$. Here $\tilde{\varphi}(x)=\overline{\varphi(-x)}$ and * denotes the convolution product

$$
\varphi_{1} * \varphi_{2}(t)=\int \varphi_{1}(x) \varphi_{2}(t-x) d x
$$

Note that (2.2) can be rewritten as

$$
\begin{equation*}
\iint h(x-y) \varphi(x) \overline{\varphi(y)} d x d y \geq 0 \tag{2.3}
\end{equation*}
$$

The following result can be found in Chapter II, Section 4.4 of [7]; we incorporate a remark at the end of that section concerning the case where $h$ is continuous.
Theorem 2.1. Let $h$ be continuous and conditionally positive definite of order $m$. Then it is possible to choose a positive Borel measure $\mu$ on $\mathbf{R}^{n} \sim\{0\}$, constants $a_{\gamma},|\gamma| \leq 2 m$ and a function $\chi$ in $\mathscr{D}$ such that: $1-\hat{\chi}(\xi)$ has a zero of order $2 m+1$ at $\xi=0$; both of the integrals $\int_{0<|\xi|<1}|\xi|^{2 m} d \mu(\xi), \int_{|\xi| \geq 1} d \mu(\xi)$ are finite; for all $\psi \in \mathscr{Z}$,

$$
\begin{align*}
\int h(x) \psi(x) d x= & \int\left[\widehat{\psi}(\xi)-\hat{\chi}(\xi) \sum_{|;|<2 m} D^{\prime} \widehat{\psi}(0) \frac{\xi^{\prime \prime}}{\gamma^{\prime}!}\right] d \mu(\xi)  \tag{2.4}\\
& +\sum_{|;| \leq 2 m} D^{\prime} \widehat{\psi}(0) \frac{z^{\prime}}{\gamma!} .
\end{align*}
$$

This uniquely determines the measure $\mu$ and the constants $a_{\gamma}$ for $|\gamma|=2 m$. In addition, for every choice of complex numbers $c_{\alpha},|\alpha|=m$,

$$
\begin{equation*}
\sum_{|\alpha|=m} \sum_{|\beta|=m} a_{\alpha+\beta} c_{\alpha} \bar{c}_{\beta} \geq 0 \tag{2.5}
\end{equation*}
$$

The choice of $\chi$ affects the value of the coefficients $a_{\gamma}$ for $|\gamma|<2 m$. Note that the value of the right side of (2.4) does not change if, for suitable $\varphi, \hat{\chi}$ is replaced by $\hat{\chi}+\varphi$ and the $a_{\gamma}$, for $|\gamma|<2 m$, are replaced by $a_{\gamma}+\int \varphi(\xi) \xi^{\gamma} d \mu(\xi)$.

As can be seen from

$$
\begin{equation*}
(-i)^{|;|} \int x^{\prime \prime} \varphi(x) d x=D^{\gamma} \widehat{\varphi}(0) \tag{2.6}
\end{equation*}
$$

changing a coefficient $a_{i,}$ on the right-hand side of (2.4) corresponds to changing $h(x)$ on the left side by adding a constant multiple of $x^{\gamma}$.

For $m=0,(2.4)$ reduces to $\int h \psi=\int \widehat{\psi} d \lambda$, where $\lambda$ is the Borel measure on $\mathbf{R}^{n}$ given by

$$
\lambda(E)=\mu(E \sim\{0\})+a_{0} \delta(E)
$$

Here $\delta$ is the measure corresponding to a unit mass at the origin; $\delta(E)=1$ if $0 \in E$ and $\delta(E)=0$ otherwise. Recall that Borel measures that are finite on compact sets are called Radon measures. We make the usual identification of a Radon measure on an open set $\Omega \subset \mathbf{R}^{n}$ with the corresponding distribution in $\mathscr{D}^{\prime}(\Omega)$ and write $\langle\lambda, \psi\rangle=\int \psi d \lambda$. Also, if $f \in L_{\mathrm{loc}}^{1}\left(\mathbf{R}^{n}\right)$, we identify it with the distribution in $\mathscr{D}^{\prime}$ given by $\langle f, \psi\rangle=\int \psi(x) f(x) d x$. Thus, for $m=0$, (2.4) says $\langle h, \varphi\rangle=\langle\lambda, \widehat{\varphi}\rangle$.

For an illustration of the theorem when $m \neq 0$, take $n=2, m=1$, $h(x)=-\sqrt{1+|x|^{2}}$. Then $d \mu(\xi)=w(\xi) d \xi$ with

$$
w(\xi)=\frac{(1+|\xi|) e^{-|\xi|}}{(2 \pi)^{2}|\xi|^{3}}
$$

and $a_{i \prime}=0$ for $|\gamma|=2$. If $\chi$ is even, then the coefficients $a_{\gamma}$ for $|\gamma|=1$ are also 0 . The remaining coefficient is $a_{0}=-\left(1+\int[1-\widehat{\chi}(\xi)] w(\xi) d \xi\right)$. Details for this and related examples are given in $\S 5$.

We use $T^{k} \varphi$ to denote the $k$ th-order Taylor polynomial for $\varphi$ about 0 :

$$
\begin{equation*}
T^{k} \varphi(\xi)=\sum_{|\alpha| \leq k} D^{\alpha} \varphi(0) \frac{\xi^{n}}{\alpha!} \tag{2.7}
\end{equation*}
$$

The integral on the right side of (2.4) can then be written as $\int \hat{\psi}-\hat{\chi} T^{2 m-1} \hat{\psi} d \mu$.
The Schwartz space of rapidly decreasing $C^{\infty}$ functions and its dual, the space of tempered distributions, are denoted by the usual letters $\mathscr{S}$ and $\mathscr{S}^{\prime}$.

Proposition 2.2. Let $k$ be a positive integer and let $\sigma$ be a Radon measure on $\mathbf{R}^{n} \sim\{0\}$ such that $\int|\xi|^{k}\left(1+|\xi|^{k}\right)^{-1} d|\sigma|(\xi)<\infty$. Let $s$ be a continuous
function such that $|\xi|^{k} s(\xi)$ is bounded on $\mathbf{R}^{n}$ and $1-s(\xi)=O\left(|\xi|^{k}\right)$ at $\xi=0$. Let

$$
\begin{equation*}
u(x)=\int\left[e^{-i\langle x, \xi\rangle}-s(\xi) \sum_{r=0}^{k-1} \frac{(-i\langle x, \xi\rangle)^{r}}{r!}\right] d \sigma(\xi) \tag{2.8}
\end{equation*}
$$

Then $u \in C\left(\mathbf{R}^{n}\right), u(x)=o\left(|x|^{k}\right)$ as $|x| \rightarrow \infty$ and for all $\varphi$ in $\mathscr{S}$

$$
\begin{equation*}
\int u(x) \varphi(x) d x=\int\left(\widehat{\varphi}-s T^{k-1} \hat{\varphi}\right) d \sigma \tag{2.9}
\end{equation*}
$$

Proof. Let $E(t)=e^{-i t}-\sum_{r=0}^{k-1}(-i t)^{r} / r!$ and note that $u=u_{0}$, where

$$
u_{a}(x)=\int_{|\xi|>a}(1-s(\xi)) e^{-i\langle x, \xi\rangle}+s(\xi) E(\langle x, \xi\rangle) d \sigma(\xi)
$$

From $|E(t)| \leq|t|^{k}$ we have $|s(\xi) E(\langle x, \xi\rangle)| \leq|x|^{k}|\xi|^{k}|s(\xi)|$. Our assumptions on $\sigma$ and $s$ ensure that $1-s(\xi)$ and $|\xi|^{k}|s(\xi)|$ belong to $L^{1}(\sigma)$. Continuity of $u$ can be established using dominated convergence.

To prove $u(x)=o\left(|x|^{k}\right)$, note that $\left|u_{0}(x)-u_{a}(x)\right| \leq\left(c_{1}(a)+c_{2}(a)|x|^{k}\right)$, where $c_{1}(a)$ and $c_{2}(a)$ are the results of integrating $|1-s(\xi)|$ and $|\xi|^{k}|s(\xi)|$ over $0<|\xi| \leq a$ with respect to $|\sigma|$. Given $\varepsilon>0$, choose $a>0$ so that $c_{1}(a)<\varepsilon$ and $c_{2}(a)<\varepsilon$. From $|E(t)| \leq 2|t|^{k-1}$ and $a>0$ we have $u_{a}(x)=O\left(|x|^{k-1}\right)$ as $|x| \rightarrow \infty$. Thus, we may choose $R \geq 1$ such that $\left|u_{a}(x)\right| \leq \varepsilon|x|^{k}$ for all $|x|>R$. Then, for $|x|>R$,

$$
|u(x)| \leq\left|u_{a}(x)\right|+\left|u_{0}(x)-u_{a}(x)\right| \leq \varepsilon|x|^{k}+\varepsilon+\varepsilon|x|^{k}
$$

It follows that $u(x)=o\left(|x|^{k}\right)$.
To establish (2.9), apply Fubini's theorem and use

$$
\int \frac{(-i\langle x, \xi\rangle)^{r}}{r!} \varphi(x) d x=\sum_{|\alpha \gamma|=r} D^{a} \widehat{\varphi}(0) \frac{\xi^{\prime r}}{\alpha!}
$$

This can be verified by using $\left(y_{1}+\cdots+y_{n}\right)^{r} / r!=\sum_{|r|=r} y^{\prime \prime} / \alpha$ ! and (2.6).
If $u$ is defined by (2.8) with $\sigma=\mu, k=2 m$ and $s=\hat{\chi}$, then from (2.4), (2.9) and (2.6) we have $\langle h-u, \psi\rangle=\langle q, \psi\rangle$ for all $\psi$ in $\mathscr{D}$. Here, $q(x)=\sum_{|y| \leq 2 m} a_{i j}(-i x)^{)^{\prime}} / \gamma!$.
Corollary 2.3. Suppose $h$ is continuous and positive definite of order $m$. If $m>0$, then there are unique constants $a_{\gamma},|\gamma|=2 m$, such that

$$
h(x)-\sum_{|; i|=2 m} a_{\gamma}(-i x)^{\gamma} \mid \gamma!=o\left(|x|^{2 m}\right), \quad \text { as }|x| \rightarrow \infty .
$$

These constants are the same as those appearing in (2.4).
For ease in dealing with (2.5), we develop some related notation. Let $V_{m}$ be the space of vectors $v=\left(v_{\alpha}\right)_{|\alpha|=m}$ and let $A$ be the operator on $V_{m}$ defined
by $A v=w$ where $w_{\alpha}=\sum_{|\beta|=m} A_{\alpha, \beta} v_{\beta}$ and $A_{\alpha, \beta}=a_{\alpha+\beta} /(\alpha!\beta!)$. Because of (2.5), $A$ must be real-symmetric. Thus $A v=0$ if and only if $v^{T} \overline{A v}=0$. Equivalently, the null space, $N_{A}$, of $A$ is the null space of the semi-inner product $(v, w)_{A}=v^{T} \overline{A w}$. Let $H_{A}=V_{m} / N_{A}$ be the Hilbert space obtained by identifying $v$ and $w$ whenever $\|v-w\|_{A}=0$. The elements of $H_{A}$ are the cosets $v+N_{A}$, and as $w$ varies over such a coset, $A w$ remains fixed.

By applying Theorem 2.1 we can recover (2.2) for a more convenient set of functions $\varphi$. Let

$$
\begin{equation*}
\mathscr{D}_{m}=\left\{\varphi \in \mathscr{D}: \int x^{\prime \prime} \varphi(x) d x=0 \quad \text { for all }|\alpha|<m\right\} \tag{2.10}
\end{equation*}
$$

Clearly, $\mathscr{D}_{m}=\left\{\varphi \in \mathscr{D}: \widehat{\varphi}(\xi)=O\left(|\xi|^{m}\right)\right.$ at $\left.\xi=0\right\}$. If $\psi=\varphi * \tilde{\varphi}$, then $\widehat{\psi}=|\widehat{\varphi}|^{2}$, so

$$
D^{\gamma} \hat{\psi}=\sum_{\alpha+\beta=\gamma} \frac{\gamma!}{\alpha!\beta!} D^{\alpha} \hat{\varphi} D^{\beta} \overline{\hat{\varphi}}
$$

Hence, for $\psi=\varphi * \grave{\varphi}$ with $\varphi \in \mathscr{D}_{m}$,

$$
\begin{equation*}
\sum_{|\forall| \leq 2 m} D^{\gamma} \widehat{\psi}(0) \frac{a_{\gamma}}{\gamma!}=\sum_{|\alpha|=m} \sum_{|\beta|=m} a_{\alpha+\beta} \frac{D^{\alpha} \widehat{\varphi}(0)}{\alpha!} \frac{D^{\beta} \overline{\hat{\varphi}(0)}}{\beta!}=\left\|\hat{\varphi}^{(m)}(0)\right\|_{A}^{2} \tag{2.11}
\end{equation*}
$$

where $\hat{\varphi}^{(m)}(0)$ is the vector $v$ in $V_{m}$ given by $v_{\alpha}=D^{\alpha} \hat{\varphi}(0)$. From (2.4) we see that if $\varphi \in \mathscr{D}_{m}$, then

$$
\begin{equation*}
\int h(x) \varphi * \tilde{\varphi}(x) d x=\int|\widehat{\varphi}|^{2} d \mu+\left\|\widehat{\varphi}^{(m)}(0)\right\|_{A}^{2} \tag{2.12}
\end{equation*}
$$

and (2.2) holds. Since $\mathscr{D}_{m}$ includes the functions $\varphi$ for which (2.2) was assumed, we conclude that requiring (2.2) for all $\varphi \in \mathscr{D}_{m}$ is an equivalent definition of $h$ being conditionally positive definite of order $m$.

Since $\mathscr{D}_{m+1} \subset \mathscr{D}_{m}$, the latter definition makes it clear that $h$ will be conditionally positive definite of order $m+1$ if it is conditionally positive definite of order $m$. If $m$ is replaced by $m+1$ in Theorem 2.1 , with $h$ held fixed, the measure $\mu$ will remain the same, the coefficients $a_{v,},|\gamma|=2(m+1)$, will be 0 , and the lower-order coefficients will change to reflect changes in $\hat{\chi}$ and additional terms in the Taylor polynomial.

In order to apply results from [11], we verify that $h$ is in the space $Q_{m}\left(\mathbf{R}^{n}\right)$ defined there.

Proposition 2.4. Let $h$ be continuous and assume (2.2) holds for all $\varphi \in \mathscr{D}_{m}$. If $x_{1}, \ldots, x_{N}$ are distinct points in $\mathbf{R}^{n}$ and $c_{1}, \ldots, c_{N}$ are constants that satisfy $\sum_{i=1}^{N} c_{i} x_{i}^{\prime \prime}=0$ for all $|\alpha|<m$, then

$$
\begin{equation*}
\sum_{i, j=1}^{N} c_{i} \bar{c}_{j} h\left(x_{i}-x_{j}\right) \geq 0 \tag{2.13}
\end{equation*}
$$

Proof. Choose $g$ in $\mathscr{X}$ with $\int g(x) d x=1$ and $g(x)=0$ for all $|x| \geq 1$. For $\varepsilon>0$, let $g_{\varepsilon}=\varepsilon^{-n} g(x / \varepsilon)$ and take $\varphi_{\varepsilon}(x)=\sum_{k=1}^{N} c_{k} g_{\varepsilon}\left(x-x_{k}\right)$. Then
$\widehat{\varphi_{\varepsilon}}(\xi)=\tau(\xi) \widehat{g}(\varepsilon \xi)$ with $\tau(\xi)=\sum_{k=1}^{N} c_{k} e^{-i\left\langle x_{k}, \xi\right\rangle}$. From

$$
D^{\alpha} \tau(\xi)=\sum_{k=1}^{N} c_{k}\left(-i x_{k}\right)^{\alpha} e^{-i\left\langle x_{k}, \zeta\right\rangle}
$$

we find $\tau(\xi)=O\left(|\xi|^{m}\right)$ at $\xi=0$. Thus $\varphi_{\varepsilon} \in \mathscr{D}_{m}$ and

$$
0 \leq \int h(x) \varphi_{\varepsilon} * \tilde{\varphi}_{\varepsilon}(x) d x=\iint h(t-y) \varphi_{\varepsilon}(t) \overline{\varphi_{\varepsilon}(y)} d t d y
$$

Letting $\varepsilon \rightarrow 0$, we obtain (2.13).
The following observations will be used in the next section. Let $\widehat{\mathscr{D}}_{m}=$ $\left\{\widehat{\varphi}: \varphi \in \mathscr{D}_{m}\right\}$.
Proposition 2.5. Let $m \geq 0$ and let $\mu$ be a positive Borel measure on $\mathbf{R}^{n} \sim\{0\}$ that satisfies $\int\left(|\xi|^{m} /\left(1+|\xi|^{m}\right)\right)^{2} d \mu(\xi)<\infty$. If $2 k \geq m$, then $\widehat{\mathscr{D}_{2 k}}$ is a dense subset of $L^{2}(\mu)$.
Proof. Let $g \in L^{2}(\mu)$ and $\varepsilon>0$. Choose $g_{1} \in \mathscr{D}\left(\mathbf{R}^{n} \sim\{0\}\right)$ so that $\left\|g-g_{1}\right\|_{L^{2}(\mu)}<\varepsilon$. Then $f(\xi)=|\xi|^{-2 k} g_{1}(\xi)$ is in $\mathscr{D}$. Since $\widehat{\mathscr{D}}$ is dense in $\mathscr{S}$, we can find $\psi \in \mathscr{D}$ so that for all $\xi$ in $\mathbf{R}^{n},|f(\xi)-\widehat{\psi}(\xi)| \leq \varepsilon /\left(1+|\xi|^{2 k}\right)$. Multiplying by $|\xi|^{2 k}$ gives

$$
\left|g_{1}(\xi)-|\xi|^{2 k} \widehat{\psi}\right| \leq \frac{\varepsilon|\xi|^{2 k}}{1+|\xi|^{2 k}}
$$

Let $\varphi=(-\Delta)^{k} \psi$. Then $\varphi \in \mathscr{D}, \widehat{\varphi}(\xi)=|\xi|^{2 k} \widehat{\psi}(\xi)$ and

$$
\int\left|g_{1}-\hat{\varphi}\right|^{2} d \mu \leq \varepsilon^{2} \int\left(\frac{|\xi|^{2 k}}{1+|\xi|^{2 k}}\right)^{2} d \mu(\xi)
$$

Thus $\|g-\hat{\varphi}\|_{L^{2}(\mu)}$ can be made as small as desired with $\varphi \in \mathscr{D}_{2 k}$.
Proposition 2.6. If $T \in \mathscr{D}^{\prime}$ satisfies $T(\varphi)=0$ for all $\varphi$ in $\mathscr{D}_{m}$, then $T$ belongs to $P_{m-1}$.
Proof. Define $T_{\alpha} \in \mathscr{D}^{\prime}$ by $T_{\alpha}(\varphi)=\int x^{\alpha} \varphi(x) d x$ and note that $\cap\left\{T_{\alpha}^{-1}(0)\right.$ : $|\alpha|<m\}=\mathscr{D}_{m}$. By assumption, $\mathscr{D}_{m}$ is contained in $T^{-1}(0)$, the null space of $T$. It follows (see Theorem 1.3 of [9]) that there are constants $c_{\alpha}$ such that $T=\sum_{|a|<m} c_{c k} T_{a}$.

## 3. Fourier description of $C_{h}$

After analyzing the space $\mathscr{C}_{h, m}$ defined below, we will see that it coincides with the space $C_{h}$ studied in [11]. Among the results emerging from this analysis is a Fourier transform description of $\mathscr{C}_{h, m}$.

Definition. Let $h$ be a continuous function on $\mathbf{R}^{n}$ that is conditionally positive definite of order $m$. We write $f \in \mathscr{C}_{h, m}\left(\mathbf{R}^{n}\right)$ if $f \in C\left(\mathbf{R}^{n}\right)$ and there is a constant $c(f)$ such that for all $\varphi$ in $\mathscr{D}_{m}$

$$
\begin{equation*}
\left|\int f(x) \varphi(x) d x\right| \leq c(f)\left\{\iint h(x-y) \varphi(x) \overline{\varphi(y)} d x d y\right\}^{1 / 2} \tag{3.1}
\end{equation*}
$$

If $f \in \mathscr{C}_{h . m}\left(\mathbf{R}^{n}\right)$ we let $c_{*}(f)$ denote the smallest constant for which (3.1) is true.

It is easily checked that if $f_{1}$ and $f_{2}$ are in $\mathscr{C}_{h, m}$, then $f_{1}+f_{2}$ and $a f_{1}, a \in$ $\mathbf{C}$, are also in $\mathscr{C}_{h, m}$ with $c_{*}\left(f_{1}+f_{2}\right) \leq c_{*}\left(f_{1}\right)+c_{*}\left(f_{2}\right)$ and $c_{*}\left(a f_{1}\right)=|a| c_{*}\left(f_{1}\right)$. If $f \in P_{m-1}$ and $\varphi \in \mathscr{D}_{m}$, then $\langle f, \varphi\rangle=0$, so $f \in \mathscr{C}_{h, m}$ and $c_{*}(f)=0$. Conversely, if $c_{*}(f)=0$, then $f \in P_{m-1}$ by Proposition 2.6. Thus $c_{*}(f)$ is a seminorm with null space $P_{m-1}$; for $m=0$, take $P_{-1}=\{0\}$.

Using (2.12), we note that (3.1) is equivalent to

$$
\begin{equation*}
|\langle f, \varphi\rangle| \leq c(f)\left\{\|\widehat{\varphi}\|_{L^{2}(\mu)}^{2}+\left\|\hat{\varphi}^{(m)}(0)\right\|_{A}^{2}\right\}^{1 / 2} \tag{3.2}
\end{equation*}
$$

for all $\varphi$ in $\mathscr{D}_{m}$. If $v \in V_{m}$ and

$$
\begin{equation*}
q(x)=\sum_{|a|=m}(A v)_{\alpha}(-i x)^{\alpha} \tag{3.3}
\end{equation*}
$$

then $\langle q, \varphi\rangle=\sum_{|\alpha|=m}(A v)_{\alpha x} D^{\alpha} \widehat{\varphi}(0)=\left(\widehat{\varphi}^{(m)}(0), \bar{v}\right)_{A}$, so $q \in \mathscr{C}_{h, m}$ with $c_{*}(q)=$ $\|\bar{v}\|_{A}$. If $g \in L^{2}(\mu)$ and $u$ is defined by (2.8) with $\sigma=g \mu, k=m$ and an appropriate choice of $s$ (take $s=0$ for $m=0$ ), then, for $\varphi \in \mathscr{D}_{m}$, (2.9) gives $\langle u, \varphi\rangle=\int \hat{\varphi} g d \mu$. It follows that $u \in \mathscr{C}_{h, m}$ with $c_{*}(u)=\|g\|_{L^{2}(\mu)}$.

Clearly, $\mathscr{C}_{h, m}$ includes all functions of the form $f=u+q+p$ with $u, q$ as above and $p \in P_{m-1}$. The next result, when combined with Proposition 2.6, shows that all functions in $\mathscr{C}_{h, m}$ can be obtained in this way.

From the behavior of $u(x)$ as $|x| \rightarrow \infty$, described by Proposition 2.2, we see that if $m>0$ and $f=u+q+p$, then $f(x)=o\left(|x|^{m}\right)$ is equivalent to $q=0$ (or $A v=0$ ). In any case,

$$
\begin{equation*}
\mathscr{C}_{h, m}\left(\mathbf{R}^{n}\right) \subset\left\{f \in C\left(\mathbf{R}^{n}\right): f(x)=O\left(|x|^{m}\right) \text { as }|x| \rightarrow \infty\right\} \tag{3.4}
\end{equation*}
$$

Proposition 3.1. Let $m, h, \mu$ and $a_{i}$, be as in Theorem 2.1. If $f \in \mathscr{C}_{h, m}$, then there is a function $g \in L^{2}(\mu)$ and a vector $v \in V_{m}$ such that for all $\varphi$ in $\mathscr{D}_{m}$

$$
\begin{equation*}
\langle f, \varphi\rangle=\int \hat{\varphi} g d \mu+\sum_{|\alpha|=m}(A v)_{(x} D^{\ell} \hat{\varphi}(0) \tag{3.5}
\end{equation*}
$$

This uniquely determines $g$ and the coset $v+N_{A}$.
Proof. Define $J: \mathscr{D}_{m} \rightarrow H=L^{2}(\mu) \oplus H_{A}$ by $J \varphi=\widehat{\varphi} \oplus\left(\hat{\varphi}^{(m)}(0)+N_{A}\right)$. From (3.2) we see that $|\langle f, \varphi\rangle| \leq c_{*}(f)\|J \varphi\|_{H}$. From this we deduce that, if $J \varphi_{1}=J \varphi_{2}$, then $\left\langle f, \varphi_{1}\right\rangle=\left\langle f, \varphi_{2}\right\rangle$. It follows that there is a bounded linear functional $L$ on the image $J \mathscr{D}_{m}$ such that $L(J \varphi)=\langle f, \varphi\rangle$ for all $\varphi$
in $\mathscr{D}_{m}$. Since $H$ is a Hilbert space, we can choose $\bar{g} \oplus\left(\bar{v}+N_{A}\right)$ so that for all $\varphi$ in $\mathscr{D}_{m},\langle f, \varphi\rangle=\left(J \varphi, \bar{g} \oplus\left(\bar{v}+N_{A}\right)\right)_{H}$. This gives (3.5).

For uniqueness, we show that $J \mathscr{D}_{m}$ is dense in $H$. Let $g_{1} \in L^{2}(\mu), w \in V_{m}$ and $\eta>0$ be given. Take $2 k>m$ and use Proposition 2.5 to choose $\varphi_{1} \in \mathscr{D}_{2 k}$ with $\left\|g_{1}-\widehat{\varphi}_{1}\right\|_{L^{2}(\mu)}<\eta$. Note that $J \varphi_{1}=\widehat{\varphi}_{1} \oplus 0$ since $2 k>m$. Put $p(\xi) \stackrel{2 k}{=}$ $\sum_{|r|=m} w_{a} \xi^{\prime \prime} / \alpha!$ and take $\chi \in \mathscr{D}$ so that $1-\widehat{\chi}(\xi)=O\left(|\xi|^{m+1}\right)$ at $\xi=0$. Define $\psi_{\varepsilon} \in \mathscr{D}$ by $\widehat{\psi}_{\varepsilon}(\xi)=p(\xi) \widehat{\chi}\left(\varepsilon^{-1} \xi\right)$. Then $J \psi_{\varepsilon}=\widehat{\psi_{\varepsilon}} \oplus\left(w+N_{A}\right)$. Choosing $\varepsilon$ close enough to 0 , we have $\left\|\widehat{\psi}_{\varepsilon}\right\|_{L^{2}(\mu)}<\eta$. Then $\left\|g_{1}+\left(w+N_{A}\right)-J\left(\varphi_{1}+\psi_{\varepsilon}\right)\right\|_{H}<$ $2 \eta$.

If $f \in \mathscr{C}_{h, m}$, let $\Lambda f=g \oplus\left(v+N_{A}\right)$ be the point in $H=L^{2}(\mu) \oplus H_{A}$ determined by (3.5). Clearly, the resulting map $\Lambda: \mathscr{C}_{h, m} \rightarrow H$ is linear. That $\Lambda$ maps onto $H$ is evident from the remarks leading up to Proposition 3.1. From (3.2) and (3.5) we see that $c_{*}(f)=\|\Lambda f\|_{H}$. Note $\|\Lambda f\|_{H}=\left\{(f, f)_{h}\right\}^{1 / 2}=$ $\|f\|_{h}$, where $\left(f_{1}, f_{2}\right)_{h}=\left(\Lambda f_{1}, \Lambda f_{2}\right)_{H}$ is a semi-inner product for $\mathscr{C}_{h, m}$. There is a corresponding inner product on $\mathscr{C}_{h, m} / P_{m-1}$, which is then a Hilbert space isomorphic to $H$ under the quotient map associated with $\Lambda$.

The following provides a converse to Proposition 3.1 and clarifies how the Fourier transform relates $f$ to $g, v$ in (3.5).

Proposition 3.2. Let $m, h, \mu$ and $a_{i}$ be as in Theorem 2.1. Fix $g \in L^{2}(\mu)$, $v \in V_{m}$ and $f \in \mathscr{D}^{\prime}$. The following are equivalent:
(a) (3.5) holds for all $\varphi$ in $\mathscr{Q}_{m}$;
(b) $f \in \mathscr{S}^{\prime}$ and for every $|\alpha|=m, \xi^{\prime \prime} F=\lambda_{t \prime}$, where $F$ is the inverse Fourier transform of $f$ and $\lambda_{\text {cr }}$ is the Radon measure on $\mathbf{R}^{n}$ given by

$$
\begin{equation*}
\lambda_{2}(E)=\int_{E \sim\{0\}} \xi^{\prime \lambda} g(\xi) d \mu(\xi)+\alpha!(A v)_{1_{2}} \delta(E) \tag{3.6}
\end{equation*}
$$

When this is the case, $f \in \mathscr{C}_{h, m}, \Lambda f=g \oplus\left(v+N_{A}\right)$ and $(f, f)_{h}=\int|g|^{2} d \mu+$ $v^{T} \overline{A v}$.
Proof. Let $q$ be as in (3.3) and let $u$ be defined by (2.8) with $\sigma=g \mu, k=m$ and a choice of $s$ that satisfies the hypotheses of Proposition 2.2. If (a) holds, then $\langle f, \varphi\rangle=\langle u+q, \varphi\rangle$ for all $\varphi \in \mathscr{D}_{m}$. By Proposition 2.6, $f-(u+q)=$ $p \in P_{m-1}$. If $\widehat{F}=f$ and $\widehat{\psi}(\xi)=\xi^{\prime k} \varphi(\xi)$, then

$$
\begin{aligned}
\left\langle\xi^{\prime \prime} F, \varphi\right\rangle & =\langle F, \widehat{\psi}\rangle=\langle f, \psi\rangle=\langle u, \psi\rangle+\langle q+p, \psi\rangle \\
& =\int\left(\widehat{\psi}-s T^{m-1} \widehat{\psi}\right) g d \mu+\sum_{|\propto| \leq m} b_{\text {" }} D^{\prime *} \widehat{\psi}(0),
\end{aligned}
$$

where the constants $b_{r r}$ are determined by $q+p(x)=\sum_{|r| \leq m} b_{r r}(i x)^{n}$. Thus,

$$
\begin{equation*}
\left\langle\xi^{\prime \prime} F, \varphi\right\rangle=\int\left(\xi^{\prime \prime} \varphi(\xi)-0\right) g(\xi) d \mu(\xi)+\alpha!(A v)_{n} \varphi(0) \tag{3.7}
\end{equation*}
$$

which establishes (b). To see that (b) implies (a), let $f_{1}=u+q$ with $u$ and $q$ as above. Then (3.7) holds for $F_{1}$, where $\widehat{F}_{1}=f_{1}$. Hence, $\xi^{\wedge} F_{1}=\lambda_{c}$. If (b) holds, then $\xi^{\alpha x} F_{1}=\xi^{\alpha x} F$ for all $|\alpha|=m$. This implies $F_{1}-F=\sum_{|\alpha|<m} b_{n} D^{\alpha} \delta$, which says $f_{1}-f \in P_{m-1}$. Therefore, (a) and the other assertions about $f$ follow from the corresponding facts about $f_{1}$.

For typical choices of $h$ (e.g. those considered in $\S 5$ ) the measure $\mu$ is absolutely continuous with respect to Lebesgue measure, $d \mu(\xi)=w(\xi) d \xi$, and $a_{\gamma}=0$ for all $|\gamma|=2 m$. In such cases the measures $\lambda_{1}$ in (3.6) are given by functions $F_{\alpha}$ in $L_{\mathrm{loc}}^{1}\left(\mathbf{R}^{n}\right) ; d \lambda_{n}(\xi)=F_{\alpha}(\xi) d \xi$, where $F_{\alpha}(\xi)=\xi^{\alpha} g(\xi) w(\xi)$. From $D^{\alpha} f=\left((-i \xi)^{\alpha} F\right)^{\wedge}=(-i)^{n} \widehat{\lambda_{\alpha}}$, we see that $\left(D^{\alpha} f\right)^{\wedge}=(-i)^{m}(2 \pi)^{n} \check{F}_{\alpha} \in$ $L_{\mathrm{loc}}^{1}\left(\mathbf{R}^{n}\right)$, where $\check{F}_{n}(\xi)=F_{a r}(-\xi)$. Let

$$
\begin{equation*}
r(\xi)=\frac{1}{(2 \pi)^{2 n}|\xi|^{2 m} w(-\xi)} \tag{3.8}
\end{equation*}
$$

with $r(\xi)=\infty$ when $w(-\xi)=0$. If $d \rho(\xi)=r(\xi) d \xi$, then $\left(D^{\alpha} f\right)^{\wedge} \in L^{2}(\rho)$ and

$$
\left\|\left(D^{\prime x} f\right)^{\wedge}\right\|_{L^{2}(\rho)}^{2}=\int \frac{\xi^{2 \alpha}|g(\xi)|^{2}}{|\xi|^{2 m}} d \mu(\xi)
$$

Using (4.2) below with $l=m$,

$$
\begin{equation*}
\sum_{|\alpha|=m} \frac{m!}{\alpha!}\left\|\left(D^{(2} f\right)^{\wedge}\right\|_{L^{2}(\rho)}^{2}=\int|g|^{2} d \mu=(f, f)_{h} \tag{3.9}
\end{equation*}
$$

Corollary 3.3. Let $m, h, \mu$, and $a_{i}$, be as in Theorem 2.1. Assume $d \mu(\xi)=$ $w(\xi) d \xi$ and $a_{\gamma}=0$ for all $|\gamma|=2 \mathrm{~m}$. Let $\rho$ be the Borel measure on $\mathbf{R}^{n}$ defined by $d \rho(\xi)=r(\xi) d \xi$, with $r$ as in (3.8). Then $f \in \mathscr{C}_{h, m}$ if and only if $f \in \mathscr{P}^{\prime}$ and $\left(D^{\prime \prime} f\right)^{\wedge} \in L^{2}(\rho)$ for every $|\alpha|=m$. In that case, $(f, f)_{h}$ is given by (3.9).

The translation invariant nature of $\mathscr{C}_{h, m}$ is evident in the following
Proposition 3.4. Let $\tau$ be a compactly supported Radon measure on $\mathbf{R}^{n}$. If $f$ is in $\mathscr{C}_{h, m}$, then so is $\tau * f$. Furthermore, if $\Lambda: \mathscr{C}_{h, m} \rightarrow L^{2}(\mu) \oplus H_{A}$ is as defined above and $\Lambda f=g \oplus\left(v+N_{A}\right)$, then $\Lambda(\tau * f)=t g \oplus\left(t(0) v+N_{A}\right)$, where $t(\xi)=\int e^{i\langle x \cdot \xi\rangle} d \tau(x)$.
Proof. If $\psi(x)=\int \varphi(x+y) d \tau(y)$, then $\langle\tau * f, \varphi\rangle=\langle f, \psi\rangle$ and

$$
\begin{align*}
\widehat{\psi}(\xi) & =\iint e^{-i(x \cdot \bar{\zeta})} \varphi(x+y) d x d \tau(y) \\
& =\iint e^{-i(z-y \cdot \xi\rangle} \varphi(z) d z d \tau(y)=\widehat{\varphi}(\xi) t(\xi) \tag{3.10}
\end{align*}
$$

If $\Lambda f=g \oplus\left(v+N_{A}\right)$, so that (3.5) holds, then for all $\varphi \in \mathscr{D}_{m}$

$$
\begin{aligned}
\langle\tau * f, \varphi\rangle & =\int \widehat{\psi} g d \mu+\sum_{|\alpha|=m} D^{\alpha} \widehat{\psi}(0)(A v)_{\alpha} \\
& =\int \widehat{\varphi} t g d \mu+\sum_{|\alpha|=m} t(0) D^{\alpha} \widehat{\varphi}(0)(A v)_{\alpha}
\end{aligned}
$$

This gives (3.5), with $f, g, v$ replaced by $\tau * f, t g, t(0) v$; the assertions made are now apparent.

In the next result, (3.11) is equivalent to $\Lambda(\nu * h)=n \oplus\left(w+N_{A}\right)$ and (3.12) says $\nu(\tilde{f})=(\nu * h, f)_{h}$. From this it is clear that $\mathscr{C}_{h, m}$ satisfies condition (c) in Theorem 1.1 of [11]. That conditions (a) and (b) are also satisfied can be seen from the discussion above in which the map $\Lambda$ was introduced. Applying Theorem 1.1 of [11], we conclude that $\mathscr{C}_{h, m}=C_{h}$.

Proposition 3.5. Let $m, h, \mu$ and $a_{y}$ be as in Theorem 2.1. Let $\nu$ be a compactly supported Radon measure on $\mathbf{R}^{n}$ and assume that $\int x^{c} d \nu(x)=0$ for all $|\alpha|<m$. Then $\nu * h \in \mathscr{C}_{h, m}$ and for all $\varphi$ in $\mathscr{D}_{m}$

$$
\begin{equation*}
\langle\nu * h, \varphi\rangle=\int \widehat{\varphi} n d \mu+\sum_{|x|=m}(A w)_{a} D^{\alpha} \widehat{\varphi}(0) \tag{3.11}
\end{equation*}
$$

where $n(\xi)=\int e^{i(x, \xi)} d \nu(x)$ and $w_{\beta}=D^{\beta} n(0)=\int(i x)^{\beta} d \nu(x)$. Furthermore, if $f \in \mathscr{C}_{h, m}$ and $\Lambda f=g \oplus\left(v+N_{A}\right)$, then

$$
\begin{equation*}
\int \overline{f(x)} d \nu(x)=\int n \bar{g} d \mu+w^{T} \overline{A v} \tag{3.12}
\end{equation*}
$$

Proof. If $\psi(z)=\int \varphi(z+y) d \nu(y)$, then from (2.4),

$$
\begin{equation*}
\langle\nu * h, \varphi\rangle=\langle h, \psi\rangle=\int \widehat{\psi}-\hat{\chi} T^{2 m-1} \widehat{\psi} d \mu+\sum_{|;| \leq 2 m} D^{\gamma} \widehat{\psi}(0) \frac{a_{\gamma}}{\gamma!} \tag{3.13}
\end{equation*}
$$

and, as in (3.10), $\widehat{\psi}=\widehat{\varphi} n$. Clearly, $D^{*} n(0)=0$ for all $|\alpha|<m$. If $\varphi \in \mathscr{D}_{m}$, then $D^{\gamma} \widehat{\psi}(0)=0$ for $|\gamma|<2 m$, and for $|\gamma|=2 m$

$$
D^{\gamma} \widehat{\psi}(0)=\sum_{\alpha+\beta=\gamma} \frac{\gamma!}{\alpha!\beta!} D^{\alpha} \widehat{\varphi}(0) w_{\beta}
$$

Thus, (3.11) follows from (3.13). To establish (3.12), choose a real-valued function $r$ in $\mathscr{D}$ with $\widehat{r}(0)=1$, and for $\varepsilon>0$ let $\overline{\varphi_{\varepsilon}(x)}=\int \varepsilon^{-n} r\left(\frac{x-y}{\varepsilon}\right) d \nu(y)$. Then $\varphi_{\varepsilon} \in \mathscr{D}_{m}$ and

$$
\left\langle f, \varphi_{\varepsilon}\right\rangle=\int \widehat{\varphi_{\varepsilon}} g d \mu+\sum_{|\alpha|=m}(A v)_{{ }_{\alpha}} D^{\prime \prime} \widehat{\varphi_{\varepsilon}}(0)
$$

This yields (3.12) because

$$
\int \overline{f(x)} d \nu(x)=\lim _{\varepsilon \rightarrow 0} \overline{\left\langle f, \varphi_{\varepsilon}\right\rangle} \quad \text { and } \quad \widehat{\varphi_{\varepsilon}}(\xi)=\widehat{r}(\varepsilon \xi) \overline{n(\xi)}
$$

For $s$ as in (1.1) we have $s=\nu * h$ with $\int \varphi d \nu=\sum_{i=1}^{N} c_{i} \varphi\left(x_{i}\right)$. Thus, such functions $s$ belong to $\mathscr{C}_{h, m}$.

The distribution $D^{\kappa} h,|\kappa| \geq m$, can be obtained as a limit of $\nu * h$ 's by choosing $\nu$ 's that correspond to appropriate difference operators. Such $\nu$ 's satisfy the orthogonality condition $\int x^{\alpha} d \nu(x)=0,|\alpha|<m$. Hence, the following may be regarded as a limiting case of the situation considered above.
Proposition 3.6. Let $m, h, \mu$ and $a_{\gamma}$ be as in Theorem 2.1. Fix $\kappa$ with $|\kappa| \geq m$ and let $p(\xi)=(i \xi)^{\kappa}$. Then, $p \in L^{2}(\mu)$ if and only if the distribution $D^{\kappa} h$ belongs to $\mathscr{C}_{h, n}$. In that case, $\Lambda\left((-D)^{\kappa} h\right)=p \oplus\left(w+N_{A}\right)$ with $w_{\kappa}=D^{\alpha} p(0)$, $|\alpha|=m$.
Proof. Let $\psi=D^{\kappa} \varphi$, so $\widehat{\psi}=p \widehat{\varphi}$. If $\varphi \in \mathscr{D}_{m}$, then, by a calculation like that for (2.11),

$$
\sum_{|;| \leq 2 m} D^{\gamma}(p \widehat{\varphi})(0) \frac{a_{\gamma}}{\gamma!}=\sum_{|\alpha|=m} \sum_{|\beta|=m} a_{\alpha+\beta} \frac{D^{\alpha \gamma} p(0)}{\alpha!} \frac{D^{\beta} \widehat{\varphi}(0)}{\beta!} .
$$

Using (2.4), we have

$$
\begin{equation*}
\left\langle(-D)^{\kappa} h, \varphi\right\rangle=\langle h, \psi\rangle=\int p \hat{\varphi} d \mu+\sum_{|\beta|=m}(A w)_{\beta} D^{\beta} \hat{\varphi}(0) \tag{3.14}
\end{equation*}
$$

for all $\varphi \in \mathscr{D}_{m}$. This is (3.5) with $f=(-D)^{\kappa} h, g=p$ and $v=w$. If $p \in$ $L^{2}(\mu)$ we apply Proposition 3.2 to see that $f \in \mathscr{C}_{h, m}$ and $\Lambda f=p \oplus\left(w+N_{A}\right)$. If $p \notin L^{2}(\mu)$ we apply Proposition 2.5 to obtain a sequence $\varphi_{i} \in \mathscr{D}_{2 k}$ such that $\int\left|\widehat{\varphi}_{i}\right|^{2} d \mu=1$ and $\int p \widehat{\varphi}_{i} d \mu \rightarrow \infty$. We take $2 k>m$ so that $D^{\beta} \widehat{\varphi}_{i}(0)=0$ when $|\beta|=m$. Then (3.14) gives

$$
\left\langle(-D)^{\kappa} h, \varphi_{i}\right\rangle=\int p \widehat{\varphi}_{i} d \mu \rightarrow \infty
$$

Since $\left\|\widehat{\varphi}_{i}\right\|_{L^{2}(\mu)}^{2}+\left\|\widehat{\varphi}_{i}^{(m)}(0)\right\|_{A}^{2}=1$, we see that $f=(-D)^{\kappa} h$ cannot satisfy (3.2) and hence cannot be in $\mathbb{C}_{h, m}$.

## 4. Error estimates

In this section we derive bounds on the difference between a function $g$ in $\mathscr{C}_{h, m}$ and a function $g^{X}$ of minimal $\mathscr{C}_{h, m}$ norm that agrees with $g$ on a set $X \subset \mathbf{R}^{n}$ of 'interpolation points'. These error estimates involve a parameter that measures the spacing of the points in $X$ and are of order $l$ in that parameter; our derivation assumes $l \geq m$ and

$$
\begin{equation*}
\int|\xi|^{2 l} d \mu(\xi)<\infty \tag{4.1}
\end{equation*}
$$

For the examples given in $\S 5$, this assumption is satisfied for arbitrarily large values of $l$; see (5.2) below. In particular, the estimates apply to multiquadric interpolation, since the example there with $a=-1$ gives $h(x)=-2 \sqrt{\pi\left(1+|x|^{2}\right)}$.

Before starting on the error estimates, we look at a related implication of (4.1). Let $p_{i}(\xi)=(i \xi)^{\alpha}$. From

$$
\begin{equation*}
\left(\xi_{1}^{2}+\cdots+\xi_{n}^{2}\right)^{l}=\sum_{|\alpha|=l} \frac{l!}{\alpha!} \xi^{2 \alpha} \tag{4.2}
\end{equation*}
$$

we observe that (4.1) holds if and only if $p_{\alpha} \in L^{2}(\mu)$ for all $|\alpha|=l$. If a distribution has all of its $l$ th order derivatives given by continuous functions, then it will belong to $C^{l}\left(\mathbf{R}^{n}\right)$. Thus, the following result shows that (4.1) holds if and only if $\mathscr{C}_{h, n} \subset C^{\prime}\left(\mathbf{R}^{n}\right)$.

Proposition 4.1. Let $m, h, \mu$ and $a_{\gamma}$ be as in Theorem 2.1. Fix $\alpha$ with $|\alpha| \geq m$. Then the following are equivalent:
(a) $p_{\alpha,} \in L^{2}(\mu)$, where $p_{\alpha}(\xi)=(i \xi)^{\alpha}$;
(b) for every $f$ in $\mathscr{C}_{h, m}$, the distribution $D^{\alpha} f$ belongs to $C\left(\mathbf{R}^{n}\right)$ and there is a constant $c_{a}$ such that for all $f$ in $\mathscr{C}_{h, m},\left\|D^{k} f\right\|_{\infty} \leq c_{\alpha}\|f\|_{h}$;
(c) there is a point $x_{0}$ in $\mathbf{R}^{n}$ and a constant $c_{\alpha}$ such that for all $f$ in $\mathscr{C}_{h, m} \cap C^{\infty},\left|D^{\alpha} f\left(x_{0}\right)\right| \leq c_{\alpha}\|f\|_{h}$.
If these are true, then for all $f \in \mathscr{C}_{h, m}$ and all $y \in \mathbf{R}^{n}$,

$$
D^{\alpha x} f(y)=\left(f, \delta_{y} *(-D)^{\alpha} h\right)_{h}
$$

Proof. Let $f \in \mathscr{C}_{h, m}$ and let $F$ be its inverse Fourier transform, so that $\widehat{F}=f$. If $|\alpha|=m$, then, by Proposition 3.2, $\xi^{\star t} F=\lambda_{\alpha}$ with $\lambda_{\alpha}$ given by (3.6). If $|\alpha|>m$, then $\alpha=\alpha^{\prime}+\beta$ with $\left|\alpha^{\prime}\right|=m$. Hence, $\xi^{\alpha} F=\lambda_{\alpha,}$ with $\lambda_{a}=\xi^{\beta} \lambda_{\alpha}$ where $\lambda_{\alpha^{\prime}}$ is given by (3.6). If (a) holds, then $\lambda_{c k}$ is finite; for $|\alpha|=m$, $\int d\left|\lambda_{r r}\right|={ }^{\prime \prime}\left|\xi^{\alpha} g(\xi)\right| d \mu(\xi)+\left|(A v)_{\alpha \gamma}\right|$ and for $|\alpha|>m, \int d\left|\lambda_{\alpha \gamma}\right|=\int\left|\xi^{\alpha} g(\xi)\right| d \mu(\xi)$. Thus, $\widehat{\lambda_{\alpha}}$ is continuous and bounded by $\int d\left|\lambda_{\alpha}\right|$. Since $(i D)^{\alpha} f=\left(\xi^{\alpha} F\right)^{\wedge}=\widehat{\lambda_{\alpha}}$, we see that (b) holds with $c_{a}=\left\|p_{a} \oplus\left(p_{a}^{(m)}(0)+N_{A}\right)\right\|_{H}$. Thus, (a) implies (b).

That (b) implies (c) is obvious. To see that (c) implies (a), let $\psi$ be an arbitrary function in $\mathscr{D}\left(\mathbf{R}^{n} \sim\{0\}\right)$ and define $u$ by (2.8) with $\sigma=\psi \mu$ and $k=m$. Then, $u \in \mathscr{C}_{h, m}, \Lambda u=\psi \oplus 0$ and $\|u\|_{h}^{2}=\int|\psi|^{2} d \mu$. In addition, $u \in C^{\infty}$ and

$$
D^{\alpha} u\left(x_{0}\right)=\int e^{-i\left\langle x_{0}, \xi\right\rangle}(-i \xi)^{\alpha} \psi(\xi) d \mu(\xi)
$$

Thus, (c) gives $\left|\int e^{-i\left\langle x_{0}, \xi\right\rangle}(-i \xi)^{\kappa} \psi(\xi) d \mu(\xi)\right| \leq c_{\alpha}\|\psi\|_{L^{2}(\mu)}$. Since this holds for all $\psi$ in $\mathscr{D}\left(\mathbf{R}^{n} \sim\{0\}\right)$, a dense subset of $L^{2}(\mu)$, (a) must be true.

To verify the last assertion, suppose $f \in \mathscr{C}_{h, m}$ with $\Lambda f=g \oplus\left(v+N_{A}\right)$. By Proposition 3.6, $\Lambda\left((-D)^{\alpha} h\right)=p_{r r} \oplus\left(p_{a}^{(m)}(0)+N_{A}\right)$. Using Proposition 3.4 with $\tau=\delta_{y}$, we have $t(\xi)=e^{i\langle y, \xi\rangle}$ and

$$
\begin{equation*}
\Lambda\left(\delta_{y} *(-D)^{*} h\right)=t p_{t r} \oplus\left(p_{a}^{(m)}(0)+N_{A}\right) \tag{4.3}
\end{equation*}
$$

Thus, $\left(f, \delta_{y} *(-D)^{\alpha} h\right)_{h}=\int g \overline{t_{\alpha}} d \mu+v^{T} \overline{A p_{\alpha}^{(m)}(0)}=(-i)^{m} \widehat{\lambda_{x}}(y)$. Here, $\lambda_{\alpha x}$ is as above so, as already noted, $\widehat{\lambda_{r}}=(i D)^{\alpha} \widehat{f}$; this gives the desired equality.

Our error estimates will be based on the following
Theorem 4.2. Let $m, h, \mu$ and $a_{,}$be as in Theorem 2.1. Assume that $\mu$ satisfies (4.1) with $l \geq \max \{1, m\}$. For a point $x_{0}$ in $\mathbf{R}^{n}$ suppose that $\sigma$ is a real-valued, compactly supported Radon measure on $\mathbf{R}^{n}$ such that

$$
\begin{equation*}
p\left(x_{0}\right)=\int p(x) d \sigma(x) \tag{4.4}
\end{equation*}
$$

for all $p$ in $P_{l-1}$. Then for all $f$ in $\mathscr{C}_{h, m}$,

$$
\begin{equation*}
\left|f\left(x_{0}\right)-\int f(x) d \sigma(x)\right| \leq c\|f\|_{h} \int\left|x-x_{0}\right|^{\prime} d|\sigma|(x), \tag{4.5}
\end{equation*}
$$

where $c=\left\{s+\int|\xi|^{2 l} /(l!)^{2} d \mu(\xi)\right\}^{1 / 2}$ with $s=\sum_{|\alpha|=m} \sum_{|\beta|=m}\left|A_{\alpha, \beta}\right|$ for $l=m$ and $s=0$ for $l>m$.
Proof. Let $\nu=\delta_{x_{0}}-\sigma$. By (4.4), $\int p(x) d \nu(x)=0$ for all $p \in P_{l-1}$. Since $l \geq m$, Proposition 3.5 applies to $\nu$, and from (3.12),

$$
\begin{equation*}
\left|\int \overline{f(x)} d \nu(x)\right| \leq\left\|n \oplus\left(w+N_{A}\right)\right\|_{H}\|f\|_{h} \tag{4.6}
\end{equation*}
$$

Here, $w_{\beta}=\int(i x)^{\beta} d \nu(x),|\beta|=m$. If $l>m$, then $w=0$; if $l=m$, then

$$
w_{\beta}=i^{m} \int\left(x-x_{0}\right)^{\beta} d \nu(x)=0-i^{m} \int\left(x-x_{0}\right)^{\beta} d \sigma(x)
$$

Defining $R(\theta)$ by $e^{i \theta}=\sum_{k=0}^{l-1}(i \theta)^{k} / k!+R(\theta)$, we have $|R(\theta)| \leq|\theta|^{\prime} / l!$ and

$$
\begin{aligned}
e^{-i\left\langle x_{0}, \xi\right\rangle} n(\xi) & =\int e^{i\left\langle x-x_{0}, \xi\right\rangle} d \nu(x)=\int R\left(\left\langle x-x_{0}, \xi\right\rangle\right) d \nu(x) \\
& =-\int R\left(\left\langle x-x_{0}, \xi\right\rangle\right) d \sigma(x)
\end{aligned}
$$

If $b=\int\left|x-x_{0}\right|^{l} d|\sigma|(x)$, then $|n(\xi)| \leq b|\xi|^{l} / l!$ and, for $l=m,\left|w_{\beta}\right| \leq b$. From this we obtain $\left\|n \oplus\left(w+N_{A}\right)\right\|_{I I} \leq c b$ and (4.5) follows.

To obtain the error estimates mentioned at the beginning of this section, we apply Theorem 4.2 to $f=g-g^{X}$. Because of the minimum norm property of $g^{X},\|f\|_{h} \leq\|g\|_{h}$. Since other fixed bounds on $\|f\|_{h}$ result in acceptable error estimates, the minimum norm requirement on $g^{X}$ could be relaxed to simply a requirement that $\left\|g^{X}\right\|_{h}$ not exceed some set bound. If we choose $\sigma$ so that supp $\sigma \subset X$, then $\int g-g^{X} d \sigma=0$, and (4.5) gives

$$
\begin{equation*}
\left|g\left(x_{0}\right)-g^{x}\left(x_{0}\right)\right| \leq c\|f\|_{h} \int\left|x-x_{0}\right|^{l} d|\sigma|(x) . \tag{4.7}
\end{equation*}
$$

To make such a choice of $\sigma$ possible, it may be necessary to restrict $x_{0}$. From (4.4) we see that if $p \equiv 0$ on $\operatorname{supp} \sigma$ then $p\left(x_{0}\right)=0$. Let

$$
\begin{aligned}
N_{l-1}(X) & =\left\{p \in P_{l-1}: p(x)=0 \quad \text { for all } x \in X\right\} \\
\langle X\rangle_{l-1} & =\left\{x \in \mathbf{R}^{n}: p(x)=0 \quad \text { for all } p \in N_{l-1}(X)\right\} .
\end{aligned}
$$

Proposition 4.3. Let $E_{l-1}\left(x_{0}, X\right)$ be the set of all real-valued, compactly supported Radon measures on $\mathbf{R}^{n}$ that satisfy both (4.4) and $\operatorname{supp} \sigma \subset X$. Then $E_{l-1}\left(x_{0}, X\right)$ is nonempty if and only if $x_{0} \in\langle X\rangle_{l-1}$.
Proof. Necessity of $x_{0} \in\langle X\rangle_{l-1}$ is evident from the preceding discussion. To see that this is also sufficient, consider the linear functionals on $P_{l-1}$ defined by $L_{x}(p)=p(x)$. Choose a (finite) subset $Y$ of $X$ such that $\left\{L_{y}: y \in Y\right\}$ is linearly independent and $L_{x} \in \operatorname{span}\left\{L_{y}: y \in Y\right\}$ for all $x$ in $X$. Then, $N_{l-1}(Y)=N_{l-1}(X)$ and $\langle Y\rangle_{l-1}=\langle X\rangle_{l-1}$. Also, $\left\{L_{y}: y \in Y\right\}$ is a basis for $\left(P_{l-1} / N_{l-1}(Y)\right)^{\prime}$; let $\left\{p_{y}+N_{l-1}(Y): y \in Y\right\}$ be the dual basis. If the polynomials $p_{y}$ are replaced by their real parts, the result is still dual to $\left\{L_{y}: y \in Y\right\}$. We may therefore assume that each $p_{y}$ is real-valued. For $x_{0}$ in $\langle Y\rangle_{l-1}$, $L_{x_{0}}$ gives a linear functional on $P_{l-1} / N_{l-1}(Y)$. Thus, $L_{x_{0}}=\sum_{y \in Y} c_{y} L_{y}$ with $c_{y}=L_{x_{0}}\left(p_{y}\right)$, and it follows that $\sigma=\sum_{y \in Y} c_{y} \delta_{y}$ is in $E_{l-1}\left(x_{0}, X\right)$.

Of course, (4.7) will give a better error estimate if $\sigma$ is chosen from $E_{l-1}\left(x_{0}, X\right)$ so as to minimize $\int\left|x-x_{0}\right|^{l} d|\sigma|(x)$; we made no attempt to do this with our choice of $\sigma$ in the preceding proof.

We turn now to an analysis of the rate at which the error estimate goes to zero as the coverage by $X$ improves. For this we fix a region $\Omega$ and a function $g \in \mathscr{F}_{h, m}$ and, for various $X$, look at bounds on $\left|g-g^{X}\right|_{\Omega}$ given by (4.7). Here we use the notation $|f|_{\Omega}=\sup _{x \in \Omega}|f(x)|$.

The number $d=d(\Omega, X)$ defined by

$$
\begin{equation*}
d(\Omega, X)=\sup _{y \in \Omega} \inf _{x \in X}|y-x| \tag{4.8}
\end{equation*}
$$

is a standard measurement of how closely $X$ covers $\Omega$. Using (4.7) and some mild assumptions about $\Omega$, we will show that

$$
\begin{equation*}
\left|g-g^{X}\right|_{\Omega}=O\left(d^{\prime}\right) \tag{4.9}
\end{equation*}
$$

In order to use (4.7), we assume (4.1). In that case, Proposition 4.1 assures us of a uniform bound for the $l$ th order derivatives of $g-g^{X}$. From this and (4.9), we can deduce that the derivatives $D^{\prime \prime}\left(g-g^{x}\right)$ of intermediate order $0<|\alpha|<l$ satisfy $O\left(d^{l-|r|}\right)$ estimates.

To establish (4.9), we proceed along lines used by Duchon [6]. We start by assuming that there are positive constants $M, \varepsilon_{0}$ such that for every $0<\varepsilon<$ $\varepsilon_{0}$,

$$
\begin{equation*}
\Omega \subset \bigcup\left\{B(t, \varepsilon M): t \in T_{\varepsilon}\right\} \tag{4.10}
\end{equation*}
$$

where $T_{\varepsilon}=\left\{t \in \mathbf{R}^{n}: B(t, \varepsilon) \subset \Omega\right\}, B(t, r)=\left\{x \in \mathbf{R}^{n}:|x-t| \leq r\right\}$. Arguments in $\S 1$ of [6] show that such constants $M, \varepsilon_{0}$ will exist if $\Omega$ satisfies a cone condition.

Next we select a $P_{l-1}$-unisolvent set of points $\mathbf{a}(\alpha) \in \mathbf{R}^{n},|\alpha|<l$. A corresponding set of Lagrange polynominals, $p_{y}^{\mathbf{a}} \in P_{l-1},|\gamma|<l$, is determined by the requirements: $p_{\gamma}^{\mathbf{a}}(\mathbf{a}(\alpha))=1$, for $\alpha=\gamma ; p_{\gamma}^{\mathbf{a}}(\mathbf{a}(\alpha))=0$, for $\alpha \neq \gamma$. The matrix $A_{r, \beta}=(\mathbf{a}(\alpha))^{\beta},|\alpha|<l,|\beta|<l$ is nonsingular. If $p_{\gamma}(x)=\sum_{|\beta|<l}\left(A^{-1}\right)_{\beta, \gamma} x^{\beta}$, then $p_{\gamma^{\prime}}(\mathbf{a}(\alpha))=\left(A A^{-1}\right)_{\alpha, \gamma, \gamma}$, so $p_{y,}=p_{\gamma}^{\mathbf{a}}$. The function $\alpha \rightarrow \mathbf{a}(\alpha)$ can be identified with a point in $\mathbf{B}=\prod_{|\alpha|<l} B(\mathbf{a}(\alpha), \delta)$. Clearly, $\mathbf{b} \in \mathbf{B}$ if and only if $|\mathbf{b}(\alpha)-\mathbf{a}(\alpha)|<\delta$ for all $|\alpha|<l$. Now choose $\delta>0$ so that $B_{\alpha, \beta}=(\mathbf{b}(\alpha))^{\beta}$ is invertible for all $\mathbf{b} \in \mathbf{B}$. As justified by replacing the points $\mathbf{a}(\alpha)$ with the points $\delta^{-1} \mathbf{a}(\alpha)$, we assume $\delta=1$.

Choose $R$ so that $B(0, R)$ contains all the unit balls $B(\mathbf{a}(\alpha), 1),|\alpha|<l$. The Lagrange polynomials $p_{c \gamma}^{\mathbf{b}}$ depend continuously on $\mathbf{b}$. Let

$$
\lambda(r)=\sup \left\{\sum_{|x|<l}\left|p_{t r}^{\mathbf{b}}(x)\right|:|x| \leq r, \mathbf{b} \in \mathbf{B}\right\}
$$

For $d=d(\Omega, X)<\varepsilon_{0} / R$, set $\varepsilon=R d$ and fix a point $t$ in $T_{\varepsilon}$. The balls $B(t+d \mathbf{a}(\alpha), d)$ are contained in $B(t, R d)=B(t, \varepsilon) \subset \Omega$. By (4.8), for every $|\alpha|<l$, there is at least one point $x_{\alpha}$ in $X \cap B(t+d \mathbf{a}(\alpha), d)$. If $\mathbf{b}$ is the point in $\mathbf{B}$ defined by $x_{t}=t+d \mathbf{b}(\alpha)$, and

$$
\sigma=\sum_{|\alpha|<l} p_{a}^{\mathrm{b}}\left(\frac{x_{0}-t}{d}\right) \delta_{x_{a}}
$$

with $x_{0}$ arbitrary, then supp $\sigma \subset X \cap B(t, \varepsilon)$, and (4.4) holds for all $p \in P_{l-1}$; to verify (4.4), take $q$ so that $p(x)=q((x-t) / d)$ and use $\sum_{|\alpha|<1} p_{r t}^{\mathbf{b}}(y) q(\mathbf{b}(\alpha))=$ $q(y)$ with $y=\left(x_{0}-t\right) / d$.

Suppose $x_{0} \in B(t, \varepsilon M+d)$. Then, $\left|x_{0}-t\right| / d \leq(R M+1)$, so $\int d|\sigma| \leq$ $\lambda(R M+1)$. Also, for $x \in \operatorname{supp} \sigma$,

$$
\left|x-x_{0}\right| \leq|x-t|+\left|t-x_{0}\right| \leq(R+R M+1) d .
$$

Thus, $\int\left|x-x_{0}\right|^{l} d|\sigma| \leq C^{0} d^{l}$ with $C^{0}=(R+R M+1)^{\prime} \lambda(R M+1)$. Since $x_{0}$ is any point in $B(t, \varepsilon M+d)$, (4.7) gives $\left|g-g^{X}\right|_{B(t, \varepsilon M+d)} \leq c\|f\|_{h} C^{0} d^{l}$. By (4.10), if $y \in \Omega$, we can choose $t \in T_{\varepsilon}$ so that $y \in B(t, \varepsilon M)$. Then $B(y, d) \subset B(t, \varepsilon M+d)$, so for every $y \in \Omega$,

$$
\begin{equation*}
\left|g-g^{x}\right|_{B(y, d)} \leq c C^{0}\|f\|_{h} d^{l} \tag{4.11}
\end{equation*}
$$

This is more than required for (4.9), but will be useful for derivative estimates.
By Proposition 4.1, $f=g-g^{X}$ is in $C^{\prime}\left(\mathbf{R}^{n}\right)$. For $y \in \Omega, \theta \in \mathbf{R}$ and $u \in \mathbf{R}^{n}$ with $|u|=1$, let $\varphi(\theta)=f(y+\theta u)$. Then

$$
\begin{equation*}
\varphi^{(k)}(\theta)=k!\sum_{|\propto|=k} \frac{u^{\prime \prime}}{\alpha!} D^{\prime \prime} f(y+\theta u) \tag{4.12}
\end{equation*}
$$

By (b) in Proposition (4.1), $\left|\varphi^{(l)}\right|_{\mathbf{R}} \leq C^{\prime}\|f\|_{h}$ with $C^{\prime}=l!\sum_{|\alpha|=l} c_{\alpha} / \alpha$ !. From (4.11) we also have a bound on $|\varphi|_{I}$ where $I$ is the interval $[-d, d]$. For $0<k<l$, the results of Gorny [8] summarized in [12] then give

$$
\begin{equation*}
\left|\varphi^{(k)}(0)\right| \leq C_{k}\|f\|_{h} d^{l-k} \tag{4.13}
\end{equation*}
$$

where $C_{k}=16(2 e)^{k}\left(c C^{0}\right)^{1-k / l}\left[\max \left(C^{\prime}, l!2^{-l} c C^{0}\right)\right]^{k / l}$. Note that $C_{k}$ can be calculated from $n, l, m, h$ and $M$; the choice of $R$ depends only on $l$ and $n$, so $C^{0}$ requires only $l, n, M$, while $c$ and $C^{\prime}$ require only $m, h, l, n$. Combining (4.12) and (4.13) gives

$$
\begin{equation*}
\sup _{|u|=1}\left|\sum_{|\alpha|=k} \frac{u^{\alpha}}{\alpha!} D^{\alpha} f(y)\right| \leq \frac{C_{k}}{k!}\|f\|_{h} d^{l-k} \tag{4.14}
\end{equation*}
$$

for every $y \in \Omega$. Since

$$
|v|_{k}=\sup _{|u|=1}\left|\sum_{|\alpha|=k} \frac{u^{\alpha}}{\alpha!} v_{\alpha}\right|
$$

is a norm for $V_{k}$, we conclude that $\left|D^{\alpha} f\right|_{\Omega}=O\left(d^{l-|\alpha|}\right)$ for every $|\alpha| \leq l$. To summarize, we state

Theorem 4.4. Let $m, h, \mu$ and $a_{\gamma}$ be as in Theorem 2.1. Assume (4.1) holds with $l \geq \max \{1, m\}$, and suppose $\Omega$ is a subset of $\mathbf{R}^{n}$ that satisfies (4.10) for some $M, \varepsilon_{0}>0$. Then there are positive constants $C, d_{0}$ such that if $f \in \mathscr{C}_{h, m}$ vanishes on a set $X$ and the number $d=d(\Omega, X)$ defined by (4.8) is less than $d_{0}$, then for all $|\alpha| \leq l$,

$$
\begin{equation*}
\left|D^{\alpha} f\right|_{\Omega} \leq C\|f\|_{h} d^{l-|\alpha|} \tag{4.15}
\end{equation*}
$$

## 5. Examples

In this section we look at some examples of conditionally positive definite functions $h$. For these examples we determine the measure $\mu$ and coefficients $a_{i \gamma},|\gamma|=2 m$, that appear in (2.4). As can be seen from (5.2) below, these examples all satisfy (4.1) and do so for arbitrarily large choices of $l$. Thus the error estimates in $\S 4$ apply, showing that for interpolation based on any of the $h$ 's given here, approximation of arbitrarily high order can be achieved.

For $a \in \mathbf{R}$, let $w_{a}$ be the function on $\mathbf{R}^{n}$ defined by

$$
\begin{equation*}
w_{a}(\xi)=\frac{2 K_{(n-a) / 2}(|\xi|)}{(2 \pi)^{n / 2} 2^{a / 2}|\xi|^{(n-a) / 2}}, \tag{5.1}
\end{equation*}
$$

where $K_{\nu}$ is a modified Bessel function of the second kind. From the behavior of $K_{l},(r)$ at $r=0$ and $r=\infty$ we note that

$$
\begin{equation*}
\int|\xi|^{2 l} w_{a}(\xi) d \xi<\infty \tag{5.2}
\end{equation*}
$$

if and only if $a+2 l>0$. For $a \in \mathbf{R}, a \neq 0,-2,-4, \ldots$, let

$$
\begin{equation*}
h_{a}(x)=\frac{\Gamma(a / 2)}{\left(1+|x|^{2}\right)^{a / 2}}, \tag{5.3}
\end{equation*}
$$

and for $a=-2 k, k=0,1,2, \ldots$, define $h_{a}$ by

$$
\begin{align*}
h_{-2 k}(x) & =\lim _{a \rightarrow-2 k}\left[h_{a}(x)-\Gamma(a / 2)\left(1+|x|^{2}\right)^{k}\right] \\
& =\frac{(-1)^{k+1}}{k!}\left(1+|x|^{2}\right)^{k} \log \left(1+|x|^{2}\right) \tag{5.4}
\end{align*}
$$

The last equality can be verified by using $\Gamma\left(\frac{a}{2}+k+1\right)=\left(\frac{a}{2}+k\right) \cdots\left(\frac{a}{2}\right) \Gamma\left(\frac{a}{2}\right)$ together with

$$
\left.\frac{d}{d t}\right|_{t=k}\left(1+|x|^{2}\right)^{t}=\lim _{a \rightarrow-2 k} \frac{\left(1+|x|^{2}\right)^{-a / 2}-\left(1+|x|^{2}\right)^{k}}{(-a / 2)-k}
$$

Lemma 5.1. If $\hat{\varphi} \in \mathscr{D}\left(\mathbf{R}^{n} \sim\{0\}\right)$, then for all $a$ in $\mathbf{R}$

$$
\begin{equation*}
\int h_{a}(x) \varphi(x) d x=\int \widehat{\varphi}(\xi) w_{a}(\xi) d \xi \tag{5.5}
\end{equation*}
$$

Proof. A basic fact used in the theory of Bessel potentials is that (5.5) holds for all $\varphi \in \mathscr{S}$ if $a>0$; see [2], [3] or [4]. For $\hat{\varphi} \in \mathscr{D}\left(\mathbf{R}^{n} \sim\{0\}\right)$ an analytic continuation argument gives (5.5) for $a \neq 0,-2,-4, \ldots$. To obtain (5.5) for the remaining values of $a=-2 k$, we take limits. If $f(t)=\left(1+|x|^{2}\right)^{t}$ and $a \neq 0,-2,-4, \ldots$, then

$$
\left[h_{a}(x)-\Gamma\left(\frac{a}{2}\right)\left(1+|x|^{2}\right)^{k}\right]=\left(\frac{a}{2}+k\right) \Gamma\left(\frac{a}{2}\right) \int_{0}^{1} f^{\prime}\left(k-\left(\frac{a}{2}+k\right) s\right) d s
$$

Estimates from this can be used to justify an application of Lebesgue's dominated convergence theorem that shows

$$
\int h_{-2 k}(x) \varphi(x) d x=\lim _{a \rightarrow-2 k} \int\left[h_{a}(x)-\Gamma\left(\frac{a}{2}\right)\left(1+|x|^{2}\right)^{k}\right] \varphi(x) d x
$$

Now $\hat{\varphi} \in \mathscr{D}\left(\mathbf{R}^{n} \sim\{0\}\right)$, so $\int\left(1+|x|^{2}\right)^{k} \varphi(x) d x=0$. We therefore have $\int h_{-2 k}(x) \varphi(x) d x=\lim _{a \rightarrow-2 k} \int \widehat{\varphi}(\xi) w_{a}(\xi) d \xi$, which gives (5.5) for $a=-2 k$.
Theorem 5.2. If $m$ is a nonnegative integer and $a+2 m>0$, then (2.4) holds with $h=h_{a}, d \mu(\xi)=w_{a}(\xi) d \xi$, and $a_{\gamma}=0$ for $|\gamma|=2 m$.
Proof. If $m=0$, then $a>0$. As already mentioned, (5.5) holds for all $\varphi$ in $\mathscr{S}$ if $a>0$; thus, we have (2.4) with $m=0$ and $a>0$. For the rest of the proof we assume $m \geq 1$. Let

$$
u_{a}(x)=\int\left[e^{-i\langle x, \xi\rangle}-\hat{\chi}(\xi) \sum_{k=0}^{2 m-1} \frac{(-i\langle x, \xi\rangle)^{k}}{k!}\right] w_{a}(\xi) d \xi
$$

By Proposition 2.2 we have $u_{a} \in C\left(\mathbf{R}^{n}\right), u_{a}(x)=o\left(|x|^{2 m}\right)$, and for all $\varphi$ in $\mathscr{S}$

$$
\int u_{a}(x) \varphi(x) d x=\left\langle S_{a}, \hat{\varphi}\right\rangle
$$

where $\left\langle S_{a}, \psi\right\rangle=\int\left[\psi-\widehat{\chi} T^{2 m-1} \psi\right](\xi) w_{a}(\xi) d \xi$. Let $T_{a}$ be the tempered distribution defined by $\int h_{a}(x) \varphi(x) d x=\left\langle T_{a}, \widehat{\varphi}\right\rangle$. By (5.5), $\left\langle T_{a}, \psi\right\rangle=\left\langle S_{a}, \psi\right\rangle$ for all $\psi \in \mathscr{D}\left(\mathbf{R}^{n} \sim\{0\}\right)$. Thus, $\left(T_{a}-S_{a}\right)^{\wedge}=h_{a}-u_{a}$ is a polynomial $q$. Both $h_{a}$ and $u_{a}$ are $o\left(|x|^{2 m}\right)$ at $|x|=\infty$, so $\operatorname{deg} q<2 m$. The desired instance of (2.4) now follows from $\left\langle h_{a}-q, \varphi\right\rangle=\left\langle S_{a}, \widehat{\varphi}\right\rangle$.

## 6. EQuivalence of definitions

Theorem 6.1 below, when combined with Proposition 2.4, shows the equivalence of the definition of conditional positive definiteness adopted here with that used in [11]. As in [11], we define $P_{m-1}^{\perp}$ to be the space of all finite measures $\nu$ on $\mathbf{R}^{n}$ that have support consisting of a finite set of points and satisfy $\nu(p)=0$ for all $p \in P_{m-1}$. The space obtained by relaxing the support requirement to allow compact sets, rather than only finite sets, will be denoted by $\left\langle P_{m-1}^{\perp}\right\rangle$. If $\nu=\sum_{i=1}^{N} c_{i} \delta_{x_{i}}$, then

$$
\nu(\overline{\nu * \bar{h}})=\sum_{i=1}^{N} \sum_{j=1}^{N} c_{i} \bar{c}_{j} h\left(x_{i}-x_{j}\right),
$$

and $\nu \in P_{m-1}^{\perp}$ if and only if $\sum_{i=1}^{N} c_{i} x_{i}^{\prime 2}=0$ for all $|\alpha|<m$. If $d \nu(x)=\varphi(x) d x$ then

$$
\nu(\overline{\nu * \bar{h}})=\iint \varphi(x) \overline{\varphi(y)} h(x-y) d x d y
$$

and $\nu$ is in $\left\langle P_{m-1}^{\perp}\right\rangle$ if $\varphi \in \mathscr{D}_{m}$.
Theorem 6.1. Let $h$ be an arbitrary function in $C\left(\mathbf{R}^{n}\right)$. If $\nu(\overline{\nu * \bar{h}}) \geq 0$ holds for all $\nu \in P_{m-1}^{\perp}$, then it holds for all $\nu \in\left\langle P_{m-1}^{\perp}\right\rangle$.
Proof. Fix $\nu$ in $\left\langle P_{m-1}^{\perp}\right\rangle$ and let $K$ be its support. Recall that the finite Borel measures on $K$ form the dual $C(K)^{\prime}$ of $C(K)$, the continuous functions on $K$ with the sup norm topology. The norms involved in this duality will be written as follows: for $f \in C(K),|f|_{K}=\sup _{x \in K}|f(x)|$; for $\sigma \in C(K)^{\prime},\|\sigma\|=\int d|\sigma|$. Let $h_{y}(x)=h(y-x) . K$ is compact, so for every $\varepsilon>0$ there is a finite set $F_{\varepsilon} \subset K$ such that, if $y \in K$, then $\left|h_{y}-h_{y_{0}}\right|_{K}<\varepsilon$ for at least one $y_{0} \in F_{\varepsilon}$. If $\sigma$ is in the weak* neighborhood

$$
U\left(\nu, F_{\varepsilon}, \varepsilon\right)=\left\{\sigma \in C(K)^{\prime}:\left|(\sigma-\nu)\left(\bar{h}_{y_{0}}\right)\right|<\varepsilon \text { for all } y_{0} \in F_{\varepsilon}\right\}
$$

and $y \in K$, then, for a suitable choice of $y_{0} \in F_{\varepsilon}$,

$$
\left|(\sigma-\nu)\left(\bar{h}_{y}\right)\right|=\left|(\sigma-\nu)\left(\bar{h}_{y}-\bar{h}_{y_{0}}\right)+(\sigma-\nu)\left(\bar{h}_{y_{0}}\right)\right| \leq(\|\sigma-\nu\|+1) \varepsilon .
$$

Since $(\sigma-\nu) * \bar{h}(y)=(\sigma-\nu)\left(\bar{h}_{y}\right)$, we get $|(\sigma-\nu) * \bar{h}|_{K} \leq(\|\sigma-\nu\|+1) \varepsilon$ for all $\sigma \in U\left(\nu, F_{\varepsilon}, \varepsilon\right)$. For such $\sigma$ let $w$ be the number defined by

$$
w=\sigma(\overline{\sigma * \bar{h}})-\nu(\overline{\nu * \bar{h}})=\sigma((\overline{\sigma-\nu) * \bar{h}})+(\sigma-\nu)(\overline{\nu * \bar{h}})
$$

and observe $|w| \leq\|\sigma\||(\sigma-\nu) * \bar{h}|_{K}+|(\sigma-\nu)(\overline{\nu * h})|$.

Let $B=\left\{\sigma \in C(K)^{\prime}:\|\sigma\| \leq\|\nu\|\right\}$ and take $C=B \cap\left\langle P_{m-1}^{\perp}\right\rangle, S=B \cap P_{m-1}^{\perp}$. By arguments given below, $S$ is weak* dense in $C$. This allows us to choose

$$
\sigma \in S \cap\left\{\sigma \in U\left(\nu, F_{\varepsilon}, \varepsilon\right):|(\sigma-\nu)(\overline{\nu * \bar{h}})|<\varepsilon\right\}
$$

For that choice we have $\sigma(\overline{\sigma * \bar{h}}) \geq 0$ and

$$
|w| \leq\|\sigma\|(\|\sigma-\nu\|+1) \varepsilon+\varepsilon \leq\|\nu\|(2\|\nu\|+1) \varepsilon+\varepsilon
$$

Since $w$ is arbitrarily small, we see that $\nu(\overline{\nu * \bar{h}})$ must be arbitrarily close to points on the positive real axis and hence must be greater than or equal to zero.
$C$ is convex and weak* compact so, by the Krein-Milman theorem, $C$ is the closed convex hull of its extreme points. Since $S$ is convex, it will be weak* dense if it contains all of the extreme points of $C$. Suppose $\sigma_{0}$ is an extreme point of $C$ that is not in $S$. Then supp $\sigma_{0}$ cannot be a finite set, so we can subdivide it into $J=2\left(1+\operatorname{dim} P_{m-1}\right)$ disjoint subsets $E_{1}, \ldots, E_{J}$ with $\left|\sigma_{0}\right|\left(E_{j}\right) \neq 0$. Let $\sigma_{j}(E)=\sigma_{0}\left(E_{j} \cap E\right)$ and take $c_{\alpha, j}=\int x^{\alpha} d \sigma_{j}(x)$. By a dimension argument, there is a point $a \in \mathbf{R}^{J} \sim\{0\}$ that satisfies the equations

$$
\sum_{j=1}^{J} a_{j}\left\|\sigma_{j}\right\|=0 ; \quad \sum_{j=1}^{J} a_{j} c_{r, j}=0, \quad|\alpha|<m
$$

For $t \in \mathbf{R}$, let $\sigma^{t}=\sum_{j=1}^{J}\left(1+t a_{j}\right) \sigma_{j}$. Then, $\sigma^{t} \in\left\langle P_{m-1}^{\perp}\right\rangle$, and if $\left(1+t a_{j}\right) \geq 0$,

$$
\left\|\sigma^{t}\right\|=\sum_{j=1}^{J}\left(1+t a_{j}\right)\left\|\sigma_{j}\right\|=\sum_{j=1}^{J}\left\|\sigma_{j}\right\|=\left\|\sigma_{0}\right\| \leq\|\nu\| .
$$

Thus, $\sigma^{t} \in C$ for all $t$ in an interval about 0 . This contradicts the assumption that $\sigma_{0}$ was an extreme point of $C$ because $\sigma^{t}=\sigma_{0}$ only if $t=0$, as seen from the fact that $a \neq 0$ and $\left\|\sigma_{j}\right\| \neq 0$ for all $j=1, \ldots, J$.

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