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| Title                        | Muscle fatigue increases beta-band coherence between the firing times of simultaneously active motor units in the first dorsal interosseous muscle |
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| Authors(s)                   | McManus, Lara M.; Hu, Xiaogang; Rymer, William; Suresh, Nina; Lowery, Madeleine M.   |
| Publication date             | 2016-06-01   |
| Publication information      | Journal of Neurophysiology, 115 (6): 2830-2839   |
| Publisher                    | American Psychological Society   |
| Item record/more information | http://hdl.handle.net/10197/8212   |
| Publisher's version (DOI)    | 10.1152/jn.00097.2016  |

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- 1 Muscle fatigue increases beta-band coherence between the firing times of
- 2 simultaneously active motor units in the first dorsal interosseous muscle
- 3 by
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- Number of text pages: 22, figures: 9
- Number of words: abstract: 237, introduction: 810, discussion: 2221
- 17 Total number of words: 7299
- Acknowledgements: The authors declare no competing financial interests.
- 19 Grants: Funding provided by the Irish Research Council.
- 20 Author contributions: L.M. and M.M.L conception and design of research; L.M., X.H. and N.L.S.
- 21 performed experiments; L.M. and M.M.L analyzed data; L.M. and M.M.L interpreted results of
- experiments; L.M. prepared figures; L.M. and M.M.L drafted manuscript; L.M., M.M.L., N.L.S.,

W.Z.R. and X.H. edited and revised manuscript; L.M., M.M.L., X.H., W.Z.R. and N.L.S. approved

24 final version of manuscript.

# **ABSTRACT**

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Synchronization between the firing times of simultaneously active motor units (MUs) is generally assumed to increase during fatiguing contractions. To date, however, estimates of MU synchronization have relied on indirect measures, derived from surface electromyographic (EMG) interference signals. This study used intramuscular coherence to investigate the correlation between MU discharges in the first dorsal interosseous muscle during and immediately following a submaximal fatiguing contraction, and after rest. Coherence between composite MU spike trains, derived from decomposed surface EMG, were examined in the delta (1-4 Hz), alpha (8-12 Hz), beta (15-30 Hz) and gamma (30-60 Hz) band frequency ranges. A significant increase in MU coherence was observed in the delta, alpha and beta frequency bands postfatigue. In addition, wavelet coherence revealed a tendency for delta, alpha and beta-band coherence to increase during the fatiguing contraction, with subjects exhibiting low initial coherence values displaying the greatest relative increase. This was accompanied by an increase in MU shortterm synchronization and a decline in mean firing rate of the majority of MUs detected during the sustained contraction. A model of the motoneuron pool and surface EMG was used to investigate factors influencing the coherence estimate. Simulation results indicated that changes in motoneuron inhibition and firing rates alone could not directly account for increased beta-band coherence postfatigue. The observed increase is, therefore, more likely to arise from an increase in the strength of correlated inputs to MUs as the muscle fatigues. Key words: motor unit coherence, isometric fatigue, intramuscular coherence, beta-band coherence, short-term synchronization

## INTRODUCTION

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As muscle fatigue progresses, a number of adaptations develop within the central and peripheral nervous system, several of which may serve as compensatory or protective mechanisms. These include alterations in motor unit (MU) recruitment and firing rate (McManus et al. 2015a), changes in reflex inputs from metabolically and mechanically sensitive muscle afferents (Macefield et al. 1991), and a progressive reduction in the ability to voluntarily activate the muscle with suboptimal drive from the motor cortex (Gandevia 2001). In addition to these more well-established changes, it is commonly suggested that fatigue also alters the degree of synchronization between the firing times of simultaneously active motor units. Recent studies have added weight to this hypothesis, reporting evidence of a fatigue-induced increase in synchronized motor unit firings using indirect estimates of synchronization derived from surface EMG interference signals (Beretta-Piccoli et al. 2015; Holtermann et al. 2009; Talebinejad et al. 2010; Webber et al. 1995). The observed synchronization of motor unit firing trains can be modulated in specific frequency ranges, including the delta (1-4 Hz), alpha (8-12 Hz), beta (15-30 Hz) and gamma (30-60 Hz) frequency bands. Each type of synchrony is purported to have distinct origins, with beta-band coherence of particular interest, as it is believed to reflect information on oscillatory cortical and sub-cortical processes, and has been shown to be directly correlated with short-term MU synchronization (Lowery et al. 2007). Despite indications of increased MU synchronization postfatigue, direct evidence of an increase in either short-term synchronization or coherent MU firings in the beta frequency range has never been shown. Previous studies using intramuscular EMG have reported no change in MU synchronization with fatigue (Contessa et al. 2009; Nordstrom et al. 1990), with the exception of an early study which reported increased motor unit synchrony following a sustained, fatiguing maximal contraction in the biceps (Buchthal and Madsen 1950). However, in that study MUs were recorded after the recovery of muscle force, which makes it unclear whether the increase in MU synchronization was due to

fatigue, or could be attributed to exercise-induced muscle damage (Dartnall et al. 2008). The conflicting results obtained from intramuscular EMG studies may arise from the relatively low number of motor units detected. This could also explain why methods based on non-linear analysis of the surface EMG signal, which captures a larger representative sample of MU activity, have consistently inferred that MU synchronization increases with fatigue (Beretta-Piccoli et al. 2015; Holtermann et al. 2009; Talebinejad et al. 2010; Webber et al. 1995). Analysis of a greater number of motor units spike trains using surface EMG decomposition techniques has the potential to enhance the detection of correlated MU discharges. Several recent studies have shown a fatigue-induced increase in intermuscular beta coherence between surface EMG of synergistic index finger flexor muscles (Kattla and Lowery 2010), knee extensor muscles (Chang et al. 2012), antagonistic elbow muscles (Wang et al. 2015) and during three-digit grasping (Danna-Dos Santos et al. 2010). Furthermore, increased beta-band coherence was observed between cortical neuron activity and EMG recordings following sustained maximal (Tecchio et al. 2006) and submaximal fatiguing contractions (Ushiyama et al. 2011). Though increases in beta frequency corticomuscular and intermuscular coherence postfatigue have been reported, direct evidence of a similar change in coherent MU discharges within the same muscle has not been shown. The aim of this study was to examine alterations in MU coherence during and after a sustained submaximal fatiguing contraction in the first dorsal interosseous. To do this, a large population of motor unit spike trains, decomposed from the surface EMG signal, were examined. Coherence between groups of simultaneously active motor units was then calculated across a range of frequency bands, before, during, and directly after the fatiguing contraction, and again following a rest period. In addition, the temporal evolution of synchronized motor unit firing was investigated over the course of the fatiguing contraction using wavelet coherence. Finally, model simulations were used to explore whether changes in mean motor unit firing rates, or alterations in the direct inhibition of motoneurons could account for the changes in coherence observed.

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Direct evidence of an increase in short-term MU synchronization and correlated MU firings in the beta-band range during fatigue within a single muscle has been presented for the first time in this study. An increase in delta-band coherence, which is equivalent to the "common drive" modulation of motor unit firing rates (Myers et al. 2004), and alpha-band coherence were also reported both during the sustained contraction and postfatigue. The increase in delta-band coherence was correlated with increases in force variability. A progressive decrease in motor unit mean firing rates was observed during the fatiguing contraction, however, model simulations indicated that changes in firing rates alone were unlikely to account for the increase in coherence postfatigue. Preliminary results from this study were presented at the 7th Annual International IEEE EMBS Conference on Neural Engineering (McManus et al. 2015b).

#### **METHODS**

Experimental Procedure

Written informed consent and ethical approval was obtained for fifteen subjects (8 female,) to examine EMG activity of the FDI muscle during isometric abduction of the right index finger. Details of the experimental procedure have been reported previously in McManus et al. (2015a). Briefly, subjects performed a series of six isometric voluntary contractions prefatigue, the force trajectory contained a 3 s quiescent period for baseline noise calculation, an up-ramp increasing at 10% maximum voluntary contraction (MVC) per second, a constant force of 20% MVC for 10 s, a down-ramp decreasing at 10% MVC/s, and a final 3 s quiescent period. After the six prefatigue trials, a sustained isometric contraction was performed at 30% MVC until task failure, defined as the point at which the subject's force dropped 10% below the required output for 5 or more seconds. Additional verbal encouragement was provided during the contraction. A single MVC was performed directly following task failure, followed by six 10 s contractions at 20% MVC with no rest period between trials to minimize recovery. Subjects were then allowed a 10 minute recovery period before a series of four more 10 s contractions at 20% MVC.

Data Analysis – Motor unit acceptance

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Discriminable MUs were extracted from the surface EMG recorded using the decomposition algorithms described in Nawab et al. (2010) (Delsys, version 4.1.1.0). For each identified MU, the output of the algorithm consisted of MU firing times and 4 motor unit action potential (MUAP) waveforms corresponding to 4 pairs of electrode channels. The identified firing times for each MU were used to spike trigger average (STA) the surface EMG signal on each channel, resulting in 4 representative STA MUAP estimates for each MU. Two separate reliability tests were performed to determine which decomposed MUs would be retained for further analysis, using the procedure outlined in Hu et al. (2013). To quantify the variation of the STA MUAP over time, the coefficient of variation was calculated for the peak-to-peak amplitude of the MUAP templates. The maximum linear correlation coefficient between the STA estimate (calculated over the entire trial duration) and the decomposition-estimated templates was also computed. MUs with an average correlation coefficient (between the STA MUAP estimate and the decomposition MUAP template) > 0.7 and the coefficient of variation of the peak-to-peak amplitude < 0.3 across all four channels were selected for further analysis. In the present study, the MUs identified by the decomposition algorithm during the fatiguing contraction were additionally required to have a correlation coefficient (between the STA MUAP template and the decomposition MU template and between each consecutive STA MUAP template and the average STA MUAP template) > 0.8 and a peak-to-peak MUAP amplitude variation < 0.2 (both between consecutive STA MUAP templates and across all STA MUAP templates), on a

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minimum of two channels to be selected for further analysis. A 400 ms Hanning window filter was

fatiguing contraction. The change in firing rate was examined for each motor unit by fitting a least-

applied to the firing time data to analyze trends in MU mean firing times over the course of the

squares regression line to the mean firing rate data.

Data Analysis – Motor unit coherence, wavelet coherence and short-term synchronization

The number of MU spike trains used for the coherence analysis was chosen to be the maximum number of MU spike trains available across all accepted trials and conditions for each subject. This ensured that an equal sample of MU spike trains were analyzed within each condition. For trials that contained more than the chosen number of motor units for that subject, motor unit spike trains were selected randomly for further analysis. The spike trains from multiple trials were pooled together for each condition, with the same number of trials analyzed per condition. The pooled motor unit trains were then divided into two groups, and the firing instances in each group were summed to obtain two composite spike trains, Figure 1. The composite spike train method has been previously applied to examine corticomuscular coherence and low frequency (<10 Hz) intramuscular coherence during fatigue among a small number of subjects (Castronovo et al. 2015). A pair of composite spike trains was obtained for every available combination of two groups from the pooled MUs. For each subject, the number of paired combinations of composite trains analyzed was constant across prefatigue, postfatigue and recovery conditions.

Figure 1

The magnitude squared coherence,  $C_{xy}(f)$ , was calculated for each pair of composite spike trains, x(t) and y(t), as a function of their power spectral densities,  $P_{xx}(f)$  and  $P_{yy}(f)$ , and cross power spectral density,  $P_{xy}(f)$ .

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$$C_{xy}(f) = \frac{|P_{xy}(f)|^2}{P_{xx}(f)P_{yy}(f)}$$
 (1)

The level at which the magnitude squared coherence was considered significant for overlapping windows with 75% overlap was calculated at the 0.05 significance level (Terry and Griffin 2008). The coherence in each frequency band was estimated as the integral of the magnitude-squared coherence above the significance level, for the delta (1-4 Hz), alpha (8-12 Hz), beta (15-30 Hz) and

gamma (30-60 Hz) frequency bands. The coherence was estimated for three conditions, prefatigue, postfatigue and following the recovery period.

Coherence was estimated for each combination of composite MU trains. The prefatigue coherence estimates were standardized to have zero mean and unit variance, Figure 4. Postfatigue and recovery coherence estimates were then scaled using the prefatigue mean and variance for that subject. Fourier based coherence was used for the short duration contractions pre- and postfatigue, which were assumed to be stationary.

For the longer, non-stationary fatiguing contractions, wavelet coherence analysis was used to examine the temporal evolution of the intramuscular coherence (Lachaux et al. 2002). The wavelet transform,  $W_x(b, s)$ , of a signal x(u) is given by the convolution of the signal with a wavelet function, where b and s are the time shift and scale respectively. For this study, the Morlet waveform  $\Psi_{s,b}(u)$  was chosen as it has both oscillatory features and is complex valued. Similar to Fourier based coherence, the wavelet coherence WCo(t, f) at a time t and frequency f between two signals x(t) and y(t) is defined by

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$$WCo(t,f) = \frac{|SW_{xy}(t,f)|}{[SW_{xx}(t,f).SW_{yy}(t,f)]^{1/2}}$$
 (2)

where  $SW_{xy}(t,f)$  is the wavelet cross-spectrum between x(t) and y(t) and  $SW_{xx}(t,f)$  and  $SW_{yy}(t,f)$  the auto-spectra of the two signals. In the wavelet coherence method, the length of the integration window decreases with increasing frequency, which improves the temporal resolution of the coherence estimate for higher frequencies. The number of cycles of the wavelet ( $n_{co} = 10$ ) and the number of cycles contained within the integration window ( $n_{cy} = 40$ ) were chosen to focus on the change in beta-band wavelet coherence. Delta-band coherence was analyzed separately and the number of cycles of the wavelet was changed to improve the resolution in this frequency band ( $n_{co} = 1$ ). Confidence levels for the detection of significant coherence were calculated for these values of  $n_{co}$  and  $n_{cy}$  using surrogate white noise signals to compute the statistical thresholds (Lachaux et al. 2002). Wavelet coherence was used to examine the coherence between composite MU spike trains

over the fatiguing contraction. Each subject was required to have a minimum number of 8 motor units pass the acceptance criteria to be used in the wavelet coherence analysis. For subjects with a large number of motor units 100 combinations were randomly chosen for the coherence estimate. For each subject, the integral of the coherence in the alpha, beta and gamma frequency bands was calculated at each 1 ms time step over the course of the fatiguing contraction. The change in coherence during the fatiguing contraction was examined for each subject by fitting a least-squares regression line to the integral of the coherence in each frequency band against the percentage of time to task failure, and using the equation of the line to calculate the estimates for the initial and final coherence values. The percentage change in coherence in each frequency band was compared to the percentage change in the coefficient of variation of the force trace, calculated during the first and the last 10 seconds of the fatiguing contraction. In the time-domain, short-term motor unit synchronization was quantified using the synchronization index (SI) (De Luca et al., 1993). Cross-interval histograms were constructed between pulse trains representing the firing times of pairs of motor units, for each possible pair of motor units. The crossinterval histogram was constructed by calculating the first order, forward and backward recurrence times of the alternate motor unit with respect to the reference unit. The peak in the cross-interval histogram was determined by locating bins within 6 ms of the zero time-lag, for which the total number of occurrences lay above the mean number of occurrences at the 95% significance level. SI, the percentage of synchronized firings in excess of what would be expected due to chance, was defined as the ratio between the total number of firings within the peak in excess of the mean, and half the total area under the cross-interval histogram. The synchronization between motor unit pairs

#### **Model Simulation**

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A model of the motoneuron pool, surface EMG signal and force output of first dorsal interosseous muscle was used to examine the degree to which synchronization and coherence between the

was calculated for the first and second half of each fatiguing contraction.

motor unit discharge times is affected by the strength of common pre-synaptic inputs to the motoneuron pool, and possible additional factors, including variations in mean motor unit firing rate and the introduction of a common inhibitory input. The model was designed to produce motor unit activation patterns qualitatively similar to those recorded experimentally. The force generated by the model was continuously compared to a target force, and adjusted based on the difference between the two to emulate the experimental conditions in which a subject tracks a target force trajectory. The model of the motoneuron pool was based on the model described by Lowery and Erim (2005) and was comprised of 100 motoneurons, simulated using a single compartment threshold-crossing model (Powers 1993). Each motoneuron received three inputs: a constant activation current, and a common modulation or oscillatory current, and an independent membrane noise voltage (Lowery and Erim 2005). The motoneuron pool model was coupled to a model of the surface EMG signal based on that described in Lowery et al. (2000) and adapted for the first dorsal interosseous muscle. The muscle was assumed to be trapezoidal in shape with a width of 35 mm, height of 5 mm, and length of 11.5 mm on the medial side extending to 35 mm on the lateral side (Infantolino and Challis 2010). Coordinates within the muscle cross-section for both MUs and fibers within each MU were randomly generated for one hundred motor units using Sobol distributions. The number of fibers assigned to each motor unit was assumed to increase linearly with recruitment threshold from 50 to 360 (Feinstein et al. 1955). Fiber diameters (0.052 - 0.068 mm, Freund (1983)) also increased linearly with motor unit size, and a muscle fiber density of 20 fibers per mm<sup>2</sup> was assumed (Buchthal et al. 1957). All muscle fibers were orientated with a pennation angle of 50° (Infantolino and Challis 2010). The electrode was modelled as 5 point electrodes located at each of the corners and the center of a 5 × 5 mm square, based on the dimensions of the Delsys electrode used experimentally. It was located 15 mm from the proximal end of the muscle and 11 mm from the lateral side of the muscle, 3.5 mm above most superficial muscle fibers, and rotated 20° with respect to the fiber direction to

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replicate experimental placement of the electrode. The muscle fibers were located within homogeneous cylindrically anisotropic muscle tissue, with radial and axial conductivities of 0.063 and 0.33 S/m, respectively. The single fiber action potential detected when each muscle fiber was stimulated was calculated using an infinite volume conductor model for anisotropic muscle (Lowery et al. 2000). The single fiber action potentials generated by all of the fibers in each motor unit summed linearly to yield the MUAP. The common input was simulated by band-pass filtering a random Gaussian signal between 9-25 Hz using a second order Butterworth filter, chosen to generate motor unit coherence spectra qualitatively similar to those recorded experimentally. The amplitude of the signal was varied between 0-0.6 mV to simulate changing levels of shared presynaptic input in the beta-band.

To investigate whether a net inhibition of motoneurons could affect the level of motor unit coherence, inhibition to the motoneuron pool was simulated as follows. Firing of a motoneuron resulted in the generation of an inhibitory post-synaptic potential (IPSP) at the input to that motoneuron, and to its two neighboring motoneurons as defined in terms of the motoneuron recruitment order. To replicate the changes in firing rate and recruitment that were observed experimentally, a weighting function was assigned to the amplitude of the IPSPs such that the earliest recruited motoneurons received the greatest level of inhibition. IPSPs were simulated as an alpha function with a rise time of 5.5 ms and half-width of 18.5 ms, and ranged in amplitude from 5-60  $\mu$ V according to a weighted sigmoidal function, based upon experimental data of Renshaw inhibition (Hamm et al. 1987).

Spike triggered averaging was performed on the simulated EMG data to characterize the MU waveform, using the same acceptance criteria as in the experimental data. To estimate MU coherence from the motoneuron model, 26 MUs were randomly chosen from the pool and coherence was estimated for the composite spike trains for the first 10,000 combinations of two groups, as described previously for the experimental data.

# Statistical Analysis

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A repeated measure analysis of variance was conducted to compare motor unit mean firing rate (MFR) and coherence in each frequency band prefatigue, postfatigue, and following the recovery period. Mauchly's Test of Sphericity was implemented to check the assumption of sphericity, and if violated, a Greenhouse-Geisser correction was applied. Post hoc tests to examine pairwise differences between conditions were conducted using the Fisher's Least Significant Difference test. The relationship between initial motor unit firing rate (the intercept of the regression line) and the change in the motor unit firing rate over the course of the fatiguing contraction (slope of the line) was examined using a Pearson product-moment correlation. The t-statistic was used to test for the significance of the slope. The relationship between the change in motor unit mean firing rate and the change in beta-band coherence was investigated using a Spearman's rank-order non-parametric correlation. A Spearman's correlation was also used to assess the relationship between the initial coherence and the percentage change in coherence over the course of the fatiguing contraction in the delta, alpha, beta and gamma-bands, and the correlation between the percentage change in coherence and the percentage change in the coefficient of variation of the force. Differences in the median SI, between the first and second half of the fatiguing contraction, were tested using a paired Wilcoxon signed rank test.

#### **RESULTS**

Maximum voluntary force was significantly reduced (50.4  $\pm$  11 N to 26  $\pm$  12 N, p < .001) following the sustained isometric fatiguing contraction (248  $\pm$  174 seconds). MVC failed to recover after the period of rest and remained significantly depressed (39.5  $\pm$  15.9 N, p < .001), though still higher than directly postfatigue (p < .005). The average number of motor units detected per trial was 17.6  $\pm$  3 MUs prefatigue, 15.5  $\pm$  3.5 postfatigue, and 17.2  $\pm$  3.8 after recovery, with 80  $\pm$  10% of MUs accepted for further analysis. During the fatiguing contraction, 11 of 15 subjects had the minimum of

8 accepted MUs required to be included in the wavelet coherence analysis. For these subjects, an average of 70  $\pm$  11 MUs were identified by the decomposition algorithm, but due to more stringent criteria applied to the sustained fatiguing contraction, just 27.7  $\pm$  14 % of these MUs were accepted.

Motor unit properties pre and postfatigue

A small, though significant effect of fatigue on the MFR of the decomposed MUAPs was observed (F (2, 22) = 10.04, p < .001), Figure 2 (b). MU mean firing rates decreased significantly (p < .005) from prefatigue to postfatigue conditions ( $10.8 \pm 1.2$  Hz vs.  $10.0 \pm 1.4$  Hz, respectively). After the recovery period MU firing rates increased ( $11.2 \pm 1.2$  Hz, p<.001), and were not statistically different from discharge rates observed before fatigue (p = .15).

# Figure 2

The coherence between composite MU pulse trains is displayed in Figure 3, prefatigue, postfatigue and following a recovery period, for a representative subject. A significant increase in MU coherence was observed in the delta  $(0.64 \pm 0.98 \text{ to } 4.14 \pm 2.4, \text{ p} < .0001)$ , alpha  $(6.2 \pm 3.6 \text{ to } 10.8 \pm 5, \text{ p} < .0001)$  and beta  $(13.9 \pm 7.3 \text{ to } 25.6 \pm 10.2 \text{ , p} < .0001)$  frequency bands postfatigue. The mean and standard deviation of the standardized coherence values across all motor unit combinations are presented in Figure 4 for the (a) delta, (b) alpha, (c) beta and (d) gamma frequency bands.

# Figure 3

Following the recovery period, coherence decreased significantly and was not significantly different from the estimated coherence prefatigue for the delta, alpha and beta frequency bands (p = .3, p = .9 and p = .42, respectively). The changes in gamma frequency coherence did not exhibit a statistically significant effect of condition (F (1.29, 18) = 3.1, p = .087), Figure 4 (d).

#### Figure 4

# Fatiguing Contraction – MU Mean Firing Rate

To investigate the motor unit MFR changes in more detail, MU mean firing rate were analyzed for 11 subjects over the course of the fatiguing contraction, with an average of  $16.9 \pm 6.7$  MUs per subject and initial MFR of  $12.8 \pm 2.8$  Hz. Across all subjects, there was a weak tendency for motor units with higher firing rates to exhibit a decrease in discharge rate during the fatiguing contraction, and those with lower firing rates to increase their MFR (r = -0.27, p < .001). For 6 of the 11 subjects there was a significant, strong negative correlation between initial motor unit firing rate and the change in the motor unit firing rate over the course of the contraction ( $r=-0.7\pm0.09$ ), Figure 5 (a). Over all subjects, a weak correlation between the two variables was still present (r=-0.27, p<0.001), Figure 5 (b). The majority of MUs (74.4 %) exhibited a decline in MFR over the course of the fatiguing contraction, though the average magnitude of the decline was small,  $-10\pm9.4\%$ , and there was a large variation in the magnitude of MU MFR changes per subject. In the remaining motor units, the MFR increased by an average of  $14.7\pm27.5\%$ . Motor units recruited as the contraction progressed exhibited both increases and decreases in their discharge rates.

#### Figure 5

Fatiguing Contraction –MU Coherence and Synchronization

Wavelet coherence and time domain synchronization between motor unit firing times were analyzed for the same 11 subjects during the fatiguing contraction. The majority of subjects exhibited an increase in coherence in the delta, alpha and beta-band over the course of the fatiguing contraction, with median regression slopes of  $0.004 \pm 0.006$ ,  $0.012 \pm 0.01$  and  $0.014 \pm 0.03$  respectively. Motor unit firing rates and the corresponding motor unit wavelet coherence during the fatiguing contraction are shown for a representative subject in Figure 6 (a) & (b). In the gamma frequency band only 5 subjects showed an increase in coherence, with positive regression slopes significantly different to zero. There was a significant negative correlation between the initial value for delta, alpha and beta-band coherence and the percentage change in coherence within that band over the

fatiguing contraction (r = -0.7, p = .019, r = -0.55, p < .01 and r = -0.71, p = .018, respectively), Figure 7 (a). However, this correlation was not significant for the gamma-band (r = -0.59, p = .055). No significant relationship was observed between the magnitude of the change in motor unit mean firing rates and the change in beta-band coherence (r<sub>s</sub> = -0.48, p = .13), nor between the average MU firing rate and the strength of the beta coherence observed (r<sub>s</sub> = 0.4, p = .2).

#### Figure 6

Synchronization was quantified only during the sustained fatiguing contraction, as the pre- and postfatigue trials were not sufficiently long to obtain an accurate estimate. The percentage of MU pairs that displayed significant synchronization was 88.7% and 92.9% in the first and second half of the fatiguing contraction, respectively. In the second half of the contraction the mean synchronization index of the MUs that displayed significant synchronization increased ( $11 \pm 3\%$  to  $15 \pm 4.6\%$ , p < .001), Figure 7 (b). There was a significant correlation between the coefficient of variation of the force and the percentage change in coherence within the delta ( $r_s = 0.76$ , p < .01), Figure 7 (c), but not the alpha-band or beta frequency bands ( $r_s = 0.5$ , p = .11 and  $r_s = 0.44$ , p = .18, respectively).

# Figure 7

# Simulation Results

Using the model, the effect of common or shared neural inputs to the motoneuron pool, changes in motor unit mean firing rate and inhibition of motoneurons were each examined to identify the factors that could contribute to the experimentally observed increase in beta band coherence. The magnitude of the common component of the input signal to the motoneuron pool was first increased to examine the effect on the beta coherence between MU firings, Figure 8 (a) & (b). The integral of the significant coherence in the beta-band in the model increased when a common input

amplitude of 0.4 mV was applied to the motoneuron pool, and increased further at a common input amplitude of 0.6 mV, Figure 9 (b).

To examine the effect of MU mean firing rate on the coherence estimate, the median beta-band coherence was examined at 3 different firing rates, with a shared beta-band input of 0.6 mV, Figure 8 (c) & (d). Increasing the mean firing rate of the motoneuron population from  $11.3\pm3$  Hz to  $12.1\pm3$  Hz resulted in an increase in the median coherence from  $6.4\pm1.4$  to  $8.6\pm1.3$ . A further increase in MFR from  $12.1\pm3$  Hz to  $13.2\pm3$  Hz increased the median coherence to  $8.97\pm1.5$ .

#### Figure 8

Finally, to examine the possible effect of motoneuron inhibition on beta coherence, coherence was estimated after the introduction of inhibition in the presence of a common input of amplitude 0.6 mV (and a resulting reduction in MU MFR from  $12.1\pm3$  Hz to  $10\pm3$  Hz), and were found to decrease from  $8.6\pm1.5$  to  $6.9\pm1.5$ . When an increase in the magnitude of the common input to the motoneuron pool (0.6 mV to 0.8 mV) and an inhibition-induced reduction in motor unit firing rates ( $12.1\pm3$  Hz to  $11\pm3$  Hz) were simultaneously simulated, the median coherence displayed an increase similar to what was observed experimentally ( $8.6\pm1.3$  to  $15\pm1.4$ ), Figure 9.

#### Figure 9

## **DISCUSSION**

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Since the appearance of grouped motor unit activity with muscle fatigue was first reported (Buchthal and Madsen 1950), it has been widely accepted that an increase in the synchronization between the firing times of simultaneously active motor units occurs with the onset of fatigue. However, while estimates of MU synchronization inferred from the surface EMG interference signal support this hypothesis (Beretta-Piccoli et al. 2015; Holtermann et al. 2009; Webber et al. 1995), direct evidence of a fatigue-induced increase in short-term synchronization or beta-range oscillatory coupling between the firing times of simultaneously active motor units within a single muscle has not yet been shown. This study presents direct affirmation of an increase in beta-band MU coherence postfatigue, within motor units of the same muscle, for the first time, Figure 4 (c). The increased coherence postfatigue was preceded by increases in the beta-band MU coherence and short-term MU synchronization over the course of the fatiguing contraction, Figure 6 (b) and Figure 7. Subjects with high initial beta-band MU coherence showed little change in coherence during the fatiguing contraction, possibly indicating a saturation effect, Figure 7 (a), whereby no further increase in neural oscillatory activity is possible beyond a certain point. In addition, increases in delta and alphaband coherence were observed both during the fatiguing contraction and directly postfatigue. After 10 minutes of recovery, there was no significant difference between the coherence estimates and those obtained prefatigue, for any of the frequency bands. This study extends the results of previous studies reporting a significant increase in beta-band intermuscular coherence between surface EMG following isometric fatigue (Chang et al. 2012; Danna-Dos Santos et al. 2010; Kattla and Lowery 2010; Wang et al. 2015). However, other studies have reported no significant increase in beta-band EMG-EMG or motor unit coherence during sustained fatiguing contractions in the elbow flexor muscles (Semmler et al. 2013) and in the tibialis anterior muscle (Castronovo et al. 2015), respectively. Furthermore, although an increase in betaband corticomuscular coherence has been reported postfatigue in the extensor digitorum communis has also been reported during sustained (Yang et al. 2009) elbow flexion and in the flexor digitorum profundus, but not flexor digitorum superficialis, following maximal, intermittent handgrip contractions (Yang et al. 2010). These discrepancies highlight that the presence of correlated MU firings in the beta-band is likely muscle specific and task dependent, and may relate to the weaker contribution of the corticospinal pathway to proximal compared with distal muscles (Palmer and Ashby 1992). Changes in intramuscular beta coherence may be a more accurate reflection of underlying changes in the synchronous common inputs to the motoneuron pool than corresponding alterations in inter-muscular coherence, as the motor unit spike trains used in the coherence analysis were recorded within the same muscle, at the same force level. This may mitigate some of the uncertainty in the synchronization estimate when comparing across muscles with different firing characteristics, active at various force levels (Kline and De Luca 2015). Furthermore, MU coherence estimates derived directly from MU spike trains limit sources of variability present in surface EMG coherence that may arise from inter-subject differences in subcutaneous tissue and muscle composition. It remains unclear whether increased beta-band coherence has a functional role or whether it is epiphenomenal in nature, reflecting underlying changes in cortical or other neural firing patterns. It is possible that the increase in beta-band MU coherence and MU short-term synchronization observed in this study may reflect higher attentional demands and a greater amount of motorrelated neural processing as fatigue progresses (Schmied et al. 2000). A decrease in the magnitude of oscillatory inputs to the motoneuron pool has been shown to cause more variability in motor unit firing trains, and decrease the number of motoneurons recruited to the contraction (Parkis et al.

(Tecchio et al. 2006) and the tibialis anterior (Ushiyama et al. 2011), a weakening of beta coherence

2003).

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2003). Therefore, it is also possible that an increase in synchronized neural inputs may serve to

overcome reduced motoneuron excitability and increase recruitment after fatigue (Andersen et al.

The increase in correlated MU discharges in the delta and alpha frequency band observed in this study has been previously reported following sustained submaximal fatiguing contractions in the tibialis anterior muscle (Castronovo et al. 2015) and in elbow flexor muscles (Semmler et al. 2013). Both synchronization and MU coherence (< 10 Hz) have been found to increase following muscle damage induced by eccentric exercise (Dartnall et al. 2008). The restoration of low-frequency coherence to prefatigue values after the rest period, however, suggests that muscle damage was not a major factor in the coherence increase directly postfatigue. The increase in coherence MU discharges in the delta-band range was observed in the present study was significantly correlated with the coefficient of variation of the force trace, Figure 7 (c). Contessa et al. (2009) observed an increase in the common drive during fatigue, defined in terms of the cross-correlation between MU firing rates and analogous to MU coherence in the 0-4 Hz range (Myers et al. 2004), which was similarly correlated with the force variability. Alpha and beta-band coherence were not significantly correlated with force variability, which may be expected, as simulation studies have shown that mean firing rate fluctuations in the 1-4 Hz range have the greatest relative effect on force variability due to the low-pass filtering effect of the motor unit twitch response (Lowery and Erim 2005). Deltaband coherence may be influenced by recruitment via feedback from muscle spindles, and possibly the Golgi tendon organs (De Luca et al. 2009). Synchrony in the alpha-band is also known to be influenced by the modulation of muscle spindle activity in mechanical and reflex loop resonances (Erimaki and Christakos 2008).

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# Firing Rate

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The mean firing rates of the motor unit population decreased immediately postfatigue, and recovered following the 10 minute rest period, Figure 2. In addition there was a reduction in the firing rates of the majority of motor units (75%) during the sustained fatiguing contraction, Figure 5 and Figure 6 (a). This mirrors the results of previous studies that have shown a reduction in MU firing rate during intermittent and constant force submaximal isometric fatiguing contractions (Duchateau et al. 2002; Garland et al. 1994). Garland et al. (1994) observed changes in the discharge rates of single motor units in the biceps brachii, held just above their threshold of recruitment force. In the present study, changes in discharge rate in a large sample of motor units, concurrently active at the same relative force level, were examined for the first time during a sustained, fatiguing contraction. Though relatively small, the magnitude of the changes in MU MFR during and postfatigue, were comparable to the modest increase in interpulse interval reported in the biceps brachii (Garland et al. 1994). There is evidence that metabolically and mechanically sensitive group III and IV afferents are in part responsible for the decline in motoneuron discharge rate in fatiguing contractions at maximal force levels (Bigland-Ritchie et al. 1986; Garland and McComas 1990), acting at the spinal and/or the supraspinal level (Gandevia 2001). However, a withdrawal of Ia facilitation from muscle spindles (Macefield et al. 1991) or intrinsic motoneuron properties (Spielmann et al. 1993) could also contribute. The alterations in MU coherence postfatigue and during recovery followed a similar time course to the changes observed in the motor unit firing rate and action potential duration presented in McManus et al. (2015a). Sensory ascending pathways can modulate the strength of beta-range corticomuscular coupling (McClelland et al. 2012), though the contribution of various afferent groups are not yet clear (Schmied et al. 2014). It is therefore possible that both the magnitude of MU firing rates and the degree of synchronized MU firings could be affected by increased afferent feedback in response to ionic and metabolic changes within the muscle.

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The increase in MU coherence immediately postfatigue and during the sustained fatiguing contraction is likely to be multifactorial, but the relative contribution of each factor is not clear. Model simulation was used to investigate how alterations in mean MU firing rate and the introduction of inhibitory feedback to the motoneuron pool can affect the coherence estimate obtained. The simulation studies, however, indicated that neither changes in mean motor unit firing rate of the magnitude observed experimentally, nor simulated inhibition of the motoneuron pool could individually account for the change in coherence observed, Figure 8 (c) & (d). In the model, when the mean firing rate increased towards the median frequency of the common input an increase in the estimated coherence was observed without any corresponding increase in the amplitude of the shared input, Figure 8, as previously demonstrated in simulation studies (Lowery et al. 2007). The efficacy of a shared oscillatory inputs in eliciting synchronized motoneuron firings increases when the motoneuron firing rates and the frequency of the oscillatory input are similar (Lowery and Erim 2005). In the experimental data, however, the observed reduction in motor unit mean firing rates is unlikely to have affected the coherence estimate, due to the already low average values ( $10.8 \pm 1.2$  Hz). The introduction of inhibition in the model, in the presence of a common correlated input to the motoneuron pool, decreased the coherence estimate by 20%. An increase in the ratio between the independent components of the synaptic input to the motoneuron pool, in this case direct inhibition, and the common correlated inputs may be expected to reduce motor unit coherence estimates. However, in experimental conditions, the possibility that afferent inputs indirectly enhance the coherence estimate via supraspinal centres cannot be ruled out (Gandevia 2001). In contrast to the moderate differences in the coherence estimate induced by alterations in MU mean firing rates and the introduction of inhibition, a large increase in the coherence estimate was

observed by raising the amplitude of the common input shared across the motoneuron pool. The

magnitude of the change in the coherence spectrum observed experimentally (84%) could be approximated by increasing the amplitude of the shared beta input (74%), while fatigue-induced reductions in MU MFR were replicated with simulated inhibition, Figure 9.

#### **Study Limitations**

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In this study, decomposition of the surface EMG signal was used to obtain the spike trains representing the firing times of individual motor units within a single muscle. The accuracy of the results depends on the accuracy of the decomposition method. To ensure the reliability of the data, the stability of the MUAP waveform was assessed during the pre and postfatigue contractions, and during the sustained fatiguing task, to select the most reliable motor unit firing times for further analysis (Hu et al. 2013). Despite the stringent criteria applied, particularly for the MU trains decomposed from the long fatiguing contraction, there may be inaccuracies in individual firing times present in the spike trains. Frequency domain MU coherence analysis has been shown to be less sensitive to motor unit firing rates than traditional synchronization-based measures of time domain correlation (Lowery et al. 2007), which may make it more robust to the presence of some firing time inaccuracies. In addition, the use of composite spike trains may provide a more aggregate measure of the overall coherence in the motor unit sample and mitigate the influence of minor sources of error. The strict acceptance criteria applied to the stability of the MU waveform may have rejected an undesirably large number of reliable MUs in this study and introduced a possible sampling bias. The large inter-subject variability associated with coherence estimation is a potential limitation of the coherence analysis. The variability in the coherence estimates obtained for each individual may be due to limitations of coherence as an accurate reflection of shared motoneuronal inputs, intrinsic differences in corticomuscular coupling among individuals, or a combination of both. As previously discussed, the interaction between firing rate and coherence may also skew the coherence estimate in some subjects, for example, when the firing rate of the detected MUs is close to the frequency of the observed coherence. Relatively more synchronous firing instances may also be detected if the

MU sample for a subject displays a particularly narrow range of firing rates (Kline and De Luca 2015). Nevertheless, consistent results in terms of the direction of the change in coherence were observed across all frequency bands, with all subjects showing an increase in coherence in the delta range postfatigue, and 14 out of 15 subjects displaying an increase in the alpha and beta-band ranges. Lastly, to investigate the effect of changing motor unit firing rates and increasing inhibitory inputs on the MU coherence estimate, a simplified model of the motoneuron pool was used. As the respective contribution, and distribution, of these inhibitory and excitatory inputs across the motoneuron pool during fatigue are still unclear, the integrated effect of afferent activity was simplified as a net inhibitory input, non-uniformly distributed over the motoneuron pool. Physiologically, no afferent input reaches motoneurons exclusively by a monosynaptic path and combined interplay between the many motoneuron inputs is complex (Gandevia 2001). However, these assumptions were made in order to replicate the simultaneous decrease in motoneuron firing rates and continued motor unit recruitment observed experimentally. It is possible that other forms of simulated inhibitory circuits could enhance the motor unit coherence around the beta-band. Certain intrinsic properties of motoneurons, such as persistent inward currents (Heckman et al. 2005), may have been altered postfatigue but were not included in this model.

#### **CONCLUSION**

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A significant increase was observed in motor unit coherence in the delta, alpha and beta-band ranges following a sustained, fatiguing contraction, which recovered following a period of rest. A progressive increase in delta, alpha and beta-band motor unit coherence was observed over the course of the fatiguing contraction, which was examined using wavelet coherence. The increase in motor unit coherence and short-term synchronization during fatigue were accompanied by a decline in the MFR of the majority of motor units, with larger reductions in MFR associated with higher initial MU firing rates in some subjects. Simulation results suggest that an increase in inhibitory

afferent activity postfatigue, and a resulting or independent reduction in motor unit MFR, cannot account for the magnitude of the increase in beta-band coherence. The increase is, therefore, more likely to arise from a corresponding increase in the correlated common input to the motoneuron pool. Motor unit MFR and coherence recovered following rest, suggesting the possibility that both are modulated by afferent feedback in response to fatigue-induced changes within the muscle. The ability to infer information about oscillatory cortical and sub-cortical processes from the peripheral signal gives a novel insight into the adaptations taking place in the central and peripheral nervous system during fatigue.

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# FIGURE CAPTIONS

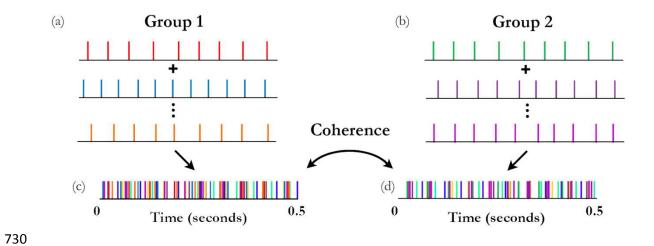
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694 Figure 1. Two sample groups of motor unit spike trains (a) and (b) pooled to form composite MU 695 spike trains (c) and (d). The coherence between the two composite firing trains (c) and (d) was then 696 estimated. 697 Figure 2: Probability density of MU MFR (a) for a single representative subject and (b) across all 698 subjects. 699 Figure 3. The highest coherence between composite MU spike trains observed across motor unit 700 combinations, prefatique, postfatique and following a recovery period for a representative subject 701 (with a 95% confidence interval). 702 Figure 4. The median and standard deviation of the standardized coherence values across all motor 703 unit combinations for the (a) common drive (1-4 Hz), (b) alpha (8-12 Hz), (c) beta (15-30 Hz) and (d) 704 gamma (30-60 Hz) frequency bands, \*p < 0.001. 705 Figure 5. The change in firing rate for each motor unit fatiguing contraction as a function of that 706 unit's initial firing rate for (a) a single subject and (b) over all subjects, \*p < 0.001. 707 Figure 6. (a) The force trace and time-varying mean firing rate of 8 motor units (obtained by low-pass 708 filtering the impulse train with a Hanning window of 5 second duration) and (b) the median wavelet 709 coherence between composite motor unit trains over the fatiguing contraction for the same subject. 710 Figure 7. (a) The relationship between the initial coherence in the alpha and beta-bands and the 711 percentage change in the integral of the wavelet coherence over the course of the fatiguing 712 contraction, (b) the median and standard deviation of the synchronization index across all subjects 713 for the first and second half of the contraction (\* p<0.001), and (c) the relationship between the 714 percentage change in coherence and the percentage change in the coefficient of variation of the 715 force.

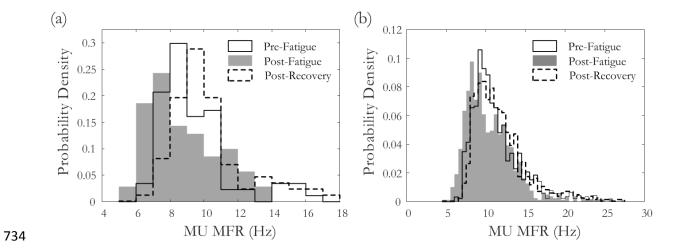
Figure 8: (a) The MU coherence estimate with no common input to the motoneuron pool, a beta-band input of magnitude 0.6 mV and 0.8 mV, with a median MFR of 12.2±3 Hz across the MU pool, and (b) the median and standard deviation of the coherence estimates over all pairs of MU composite trains. (c) The MU coherence estimate for varying motor unit mean firing rate and (d) the median and standard deviation of the coherence estimates over all pairs of MU composite trains, with a beta-band input of magnitude 0.6 mV for the 3 corresponding firing rates.

Figure 9: (a) The coherence spectrum for the pair of MU composite trains with the highest level of coherence with a beta-band input of magnitude 0.6 mV (prefatigue) and 0.8 mV with inhibition (postfatigue) and (b) the median and standard deviation of the coherence estimates over all pairs of MU composite trains.

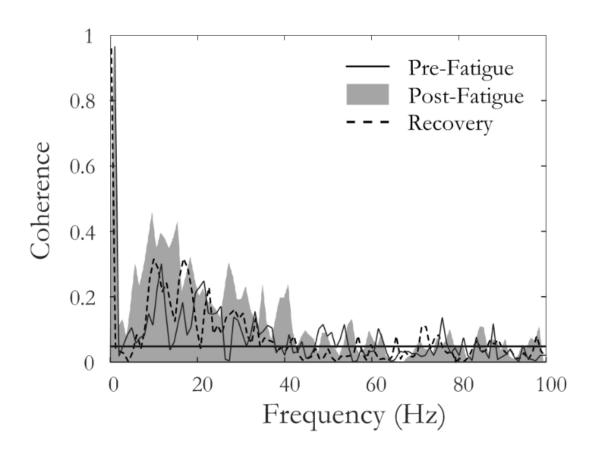
# **FIGURES**



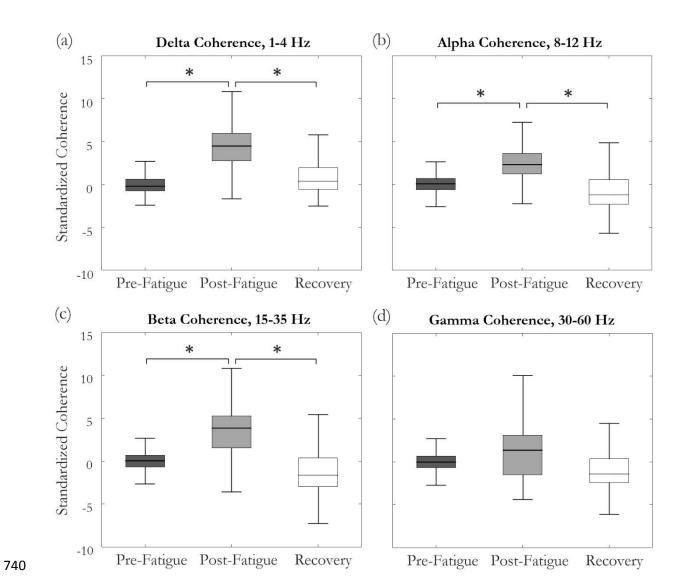
*Figure 1* 



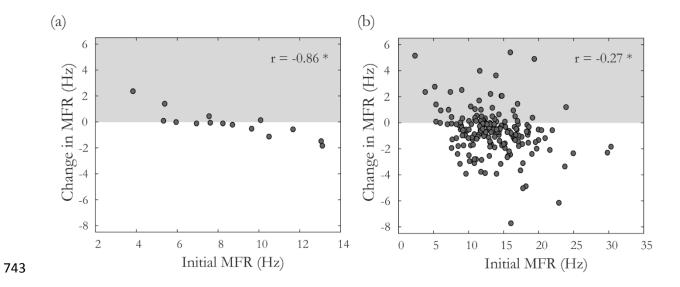
735 Figure 2



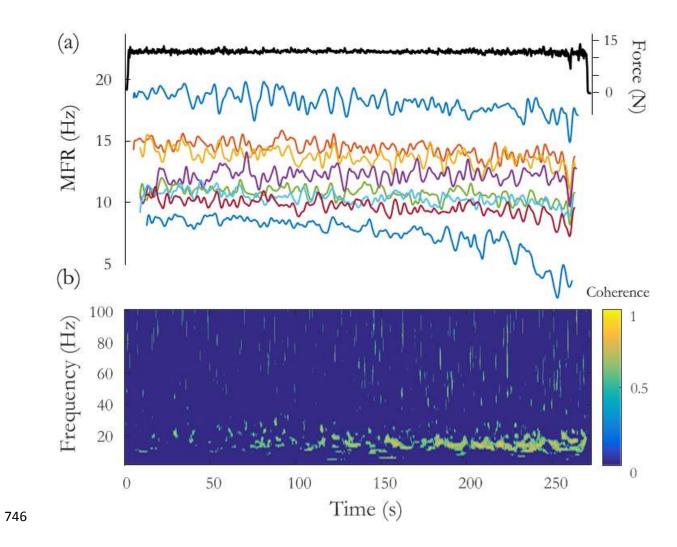
*Figure 3* 



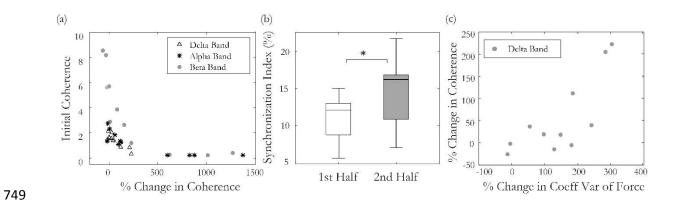
741 Figure 4



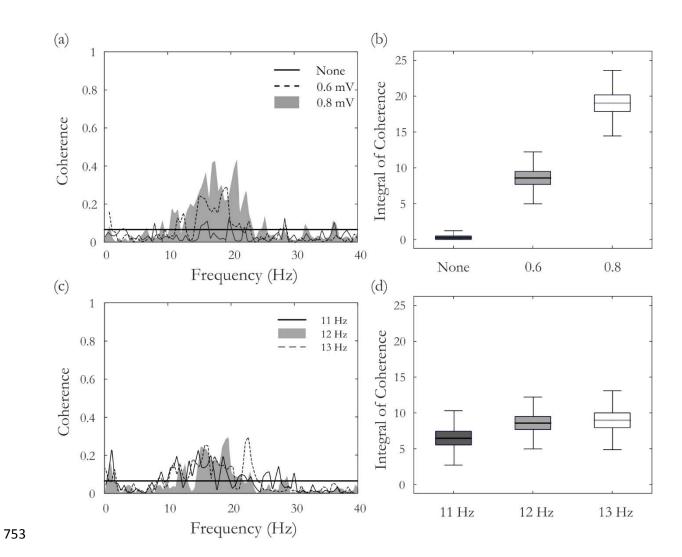
*Figure 5* 



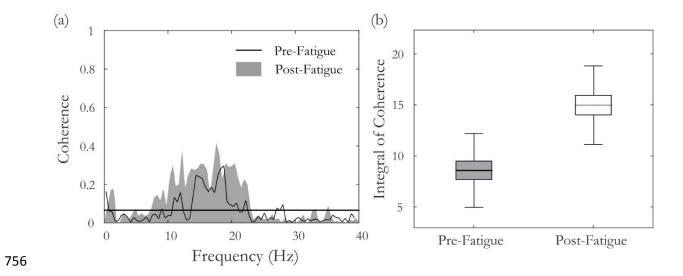
747 Figure 6



*Figure 7* 



*Figure 8* 



*Figure 9*