(n-2)-TIGHTNESS AND CURVATURE OF SUBMANIFOLDS WITH BOUNDARY

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<u>ABSTRACT</u>. The purpose of this note is to establish a connection between the notion of (n-2)-tightness in the sense of N.H. Kuiper and T.F. Banchoff and the total absolute curvature of compact submanifolds-with-boundary of even dimension in Euclidean space. The argument used is a certain geometric inequality similar to that of S.S. Chern and R.K. Lashof where equality characterizes (n-2)-tightness.

KEY WORDS AND PHRASES. tight manifolds, total absolute curvature.

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1. INTRODUCTION.

Let M be a compact n-dimensional smooth manifold with or without boundary - where the boundary is assumed to be smooth - and let

$$f: M \longrightarrow E^{n+k}$$

be a smooth immersion of M into the (n+k)-dimensional euclidean space. This leads to the notion of total absolute curvature

$$TA(f) = \frac{1}{c_{n+k-1}} \int_{N} |K| *1$$

where K denotes the Lipschitz-Killing curvature of f in each normal direction, N the unit normal bundle (with only the 'outer' normals at points of ∂M), and c_m denotes the volume of the unit sphere $S^m \subseteq E^{m+1}$. For detailed definitions, in particular in the case of manifolds with boundary, see[5] or [6]. Let us state the following equation ([6], 2.2)

$$TA(f) = TA(f_{\mid M \setminus \partial M}) + {}^{1}_{2}TA(f_{\mid \partial M})$$
 (1.1)

The famous result of S.S. Chern and R.F. Lashof gives a connection between total absolute curvature and the number of critical points of so-called height functions

$$zf : M \longrightarrow \mathbb{R}$$

defined by $(zf)(p) = \langle z, f(p) \rangle$, $z \in S^{n+k-1}$

Extending this result to the case of manifolds with boundary we can write

$$TA(f) = \frac{1}{c_{n+k-1}} \int_{z \in S} \int_{n+k-1}^{x} (\mu_{i}(zf) + \mu_{i}^{+}(zf)) *1 \qquad (1.2)$$

 for zf_{pM} and $grad_p f$ is a nonvanishing inner vector on M (for details, see [2], [4] or [6]).

The i-th curvature $\tau_{\mathbf{i}}$ introduced by N.H. Kuiper (cf. [7]) can be expressed by

$$\tau_{i}(f) = \frac{1}{c_{n+k-1}} \int_{z \in S^{n+k-1}} (\mu_{i}(zf) + \mu_{i}^{+}(zf)) *1$$

(cf. [6], 1emma 4.2 or [9], 1emma 3.1). So we get

$$TA(f) = \sum_{i} \tau_{i}(f)$$

The Morse-relations give the following connections between the curvatures and some topological invariants of M:

$$\tau_{\mathbf{i}}(f) \ge b_{\mathbf{i}}(M)$$

$$TA(f) \ge b(m) := \sum_{\mathbf{i}} b_{\mathbf{i}}(M)$$

$$\sum_{\mathbf{i}} (-1)^{\mathbf{i}} \tau_{\mathbf{i}}(f) = \chi(M) = \sum_{\mathbf{i}} (-1)^{\mathbf{i}} b_{\mathbf{i}}(M)$$

$$(1.3)$$

where $b_i(M)$ denotes the i-th Betti-number of homology with coefficients in a suitable field. (cf. [7]).

f is called <u>k-tight</u> if for all $k' \leq k$ and for almost all $z \in S^{n+k-1}$ and all real numbers c the inclusion map

$$j: (zf)_c := \{p \in M/ (zf)(p) \le c\} \longrightarrow M$$

induces a monomorphism in the k'-th homology :

$$H_{k'}(j) : H_{k'}((zf)_c) \longrightarrow H_{k'}(M)$$

As usual we write shortly 'tight' instead of 'n-tight'.

Then the results of N.H. Kuiper show

$$TA(f) = b(M)$$
 if and only if f is tight,

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 $\tau_k(f) = b_k(M)$ if and only if $H_k(j)$ and $H_{k-1}(j)$ are monomorphisms for almost all z, all c (cf. [7]).

Results on tightness are collected in the survey article [10] by T.J. Willmore, for results on k-tightness we refer in addition to the notes [1] by T. Banchoff and [9] by L. Rodriguez, who has shown that in some sense (n-2)-tightness is closely related to convexity.

2. RESULTS

As mentioned above there is a relation between tightness on one hand and total absolute curvature and the sum of the Betti-numbers on the other hand. The following results give certain connections between (n-2)-tightness on one hand and usual curvature terms and the sum of the Betti-numbers on the other hand. Note that in case $\partial M = \phi$ by duality arguments tightness is equivalent to k-tightness for $k = \frac{n}{2} - 1$ if n is even and for $k = \frac{n-1}{2}$ if n is odd. But in case $\partial M \neq \phi$ there are examples of (n-2)-tight immersions which are not tight (for example: consider the round hemi-sphere).

THEOREM A. Let M^n be an even-dimensional manifold with non-void boundary and $f: M \to E^{n+k}$ be an immersion. Let N_0 be the unit normal bundle of $f_{M\backslash M}$ and denote by $N_\star \subseteq N_0$ the open set of unit normals where the second fundamental form of f is positive or negative definite.

Then there holds the following inequality

$${}^{1}_{2}TA(f|_{\partial M}) + \frac{1}{c_{n+k-1}} \int_{N_{0} \setminus N_{\star}} |K| *1 \ge b(m)$$
 (2.1)

where equality characterizes (n-2)-tightness of f.

In case of hypersurfaces (k = 1) (2.1) becomes

$${}^{1}_{2}TA(f|_{\partial M}) + TA(f|_{M\backslash M_{*}\backslash \partial M}) \ge b(M)$$
 (2.2)

where M_{\star} denotes the set of points in $M \setminus M$ with positive or negative definite second fundamental form.

In case n = 2 M_{\star} is just the set of points with positive Gaussian curvature, so we get

COROLLARY A 1. Assume n=2 and k=1. Then there holds the following inequality

$$\frac{1}{2\pi} \int_{K < 0} |K| do + \frac{1}{2\pi} \int_{\partial M} |\mathbf{n}| ds \ge b(M) \stackrel{?}{=} 2 - \chi(M)$$
 (2.3)

where equality characterizes 0-tightness of f. Here $|\mathbf{x}|$ denotes the usual curvature of $f_{|M|}$ considered as a space curve. For part of this result see [8], Prop. 9.

COROLLARY A 2. Assume $b(\partial M) = 2 b(M)$. Then (n-2)-tightness of f implies that $f_{\partial M}$ is tight and that the second fundamental form of f has either non-maximal rank of is positive or negative definite.

This is shown in [9], Prop. 5.2 under the assumption that M^n can be embedded in E^n . This condition implies $b(\partial M) = 2 b(M)$ by Alexander duality.

Under the additional assumption that ∂M consists of a certain number of (n-1)-spheres L. Rodriguez has shown that (n-1)-tightness is equivalent to convexity (cf. [9], Theorem 2). This is not true in general, (See Corollary B 2 below).

THEOREM B. Let n be even and $f: M^n \to E^{n+1}$ be (n-2)-tight (if $\partial M \neq \phi$) or tight (if $\partial M = \phi$), and let $\widetilde{M} \subseteq M \setminus \partial M$ be a compact submanifold of dimension n which is contained in some coordinate neighborhood in M. As above M_* denotes the set of points in $M \setminus \partial M$ with positive or negative definite second fundamental form. Then there holds the following inequality

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$$TA(f|_{\partial M}) \ge b(\partial M) + 2 TA(f|_{M \setminus M_{*} \setminus \partial M})$$
 (2.4)

where equality characterizes (n-2)-tightness of $f \mid_{M \setminus (M \setminus \partial M)}$.

REMARK. If M contains only points of vanishing curvature or definite second fundamental form, then $\widetilde{M}\backslash M_* = \emptyset$ and (2.4) reduces to the inequality of S.S Chern and R.K. Lashof for $\widetilde{\partial M}$, otherwise (2.4) is sharper and reflects the additional condition that \widetilde{M} lies inside of some given M. For example in case n=2 and \widetilde{M} being a disk we get

COROLLARY B 1. Let f be as in Theorem B and assume moreover that there is an open region $U \subseteq M$ which is embedded by f in a hyperplane of E^{n+1} which implies $K |_{U} = 0$. Let \tilde{M}^n be an embedded compact submanifold of E^n and assume by changing the scale $\tilde{M} \subseteq f(U)$.

Then $f_{M\backslash f^{-1}(M\backslash \partial M)}$ is (n-2)-tight if and only if ∂M is tightly embedded in E^n .

Note that for $\tilde{M}^n \subseteq E^n$ tightness of \tilde{M} and tightness of $\partial \tilde{M}$ are equivalent: this can be obtained easily using the equations $TA(\tilde{M}) = \frac{1}{2}TA(\partial \tilde{M})$ and $b(\tilde{M}) = \frac{1}{2}b(\partial \tilde{M})$.

Roughly spoken Corollary B 1 says: (n-2)-tight minus tight gives (n-2)-tight. In particular we get the following

COROLLARY B 2. In each even dimension there exist (n-2)-tight hypersurfaces which are not tight and not convex in the sense of [9], in particular where f(3M) is not contained in the boundary of the convex hull of f(M).

3. PROOFS.

In all proofs the immersion f is fixed and so we may write $TA(\partial M)$ instead

of TA(f and so on.

PROOF OF THEOREM A.

From

$$TA(M) = \sum_{i} \tau_{i}(M)$$

and

$$\chi(M) = \sum_{i}^{\Sigma} (-1)^{i} \tau_{i}(M)$$

we get

$$TA(M) + \chi(M) = 2 \sum_{i} \tau_{2i}(M)$$

On the other hand by definition $\tau_n(M)$ is the average of the number of critical points of zf of index n which are precisely the strict local maxima in M\9M. But a point is a strict local extremum of some height function zf if and only if the second fundamental form in the direction of z is positive or negative definite. Hence we get

$$2 \tau_{n}(M) = \frac{1}{c_{n+k-1}} \int_{N_{*}} |K| *1$$

leading to

$$TA(M) - \frac{1}{c_{n+k-1}} \int_{N_{\star}} |K| *1$$

$$= 2 (\tau_0(M) + \tau_2(M) + \dots + \tau_{n-2}(M)) - \chi(M)$$

$$\geq 2 (b_0(M) + b_2(M) + \dots + b_{n-2}(M)) - \chi(M)$$

$$= b(M),$$

where we have used the assumption that n is even and $\partial M \neq \phi$ which implies $b_n(M) = 0$.

The case of equality is equivalent to the following equations:

$$\tau_{o}(M) = b_{o}(M)$$
 , $\tau_{2}(M) = b_{2}(M)$, ... , $\tau_{n-2}(M) = b_{n-2}(M)$ (2.6)

But the equality $\tau_{\mathbf{i}}(M) = b_{\mathbf{i}}(M)$ is equivalent to injectivity of $H_{\mathbf{i}}(\mathbf{j})$ and $H_{\mathbf{i}-1}(\mathbf{j})$ for all inclusions $\mathbf{j}: (\mathbf{zf})_{\mathbf{c}} \to M$, so (2.6) is equivalent to (n-2)-tightness of \mathbf{f} .

The assertion of the theorem then follows from the inequality above using the equation (1.1)

$$TA(M) = TA(M \setminus \partial M) + \frac{1}{2}TA(\partial M)$$

PROOF of Corollary A 2. By theorem A (n-2)-tightness of f implies

$$b(M) = {}^{1}_{2}TA(\partial M) + \frac{1}{c_{n+k-1}} \int_{N_{0} \setminus N_{*}} |K| *1$$

$$\geq {}^{1}2TA(\partial M) \geq {}^{1}2b(\partial M) = b(M)$$

which implies tightness of $f |_{\partial M}$ and moreover the vanishing of the integral of |K| over $N_{\bullet} N_{\star}$, hence K = 0 on $N_{\bullet} N_{\star}$.

PROOF of Theorem B. By assumption and by theorem A we have

$$TA(M\backslash M_{\downarrow}\backslash \partial M) + \frac{1}{2}TA(\partial M) = b(M)$$
, if $\partial M \neq \phi$, (2.7)

TA(M) = b(M), if $\partial M = \phi$

or

which last equality is equivalent to

$$TA(M\backslash M_{\perp}) = b(M) - 2 \tag{2.8}$$

For $f_{M\setminus (M\setminus \partial M)}$ theorem A yields

$$TA(M\backslash M\backslash M_{*}\backslash \partial M\backslash \partial M) + \frac{1}{2}TA(\partial M) + \frac{1}{2}TA(\partial M) \geq b(M\backslash M)$$
 (2.9)

where equality characterizes (n-2)-tightness of $f \mid_{M \setminus (M \setminus \partial M)}$. Subtracting (2.9) from (2.7) or (2.8) respectively we get

$$TA(M \setminus M_{*} \setminus \partial M) - \frac{1}{2}TA(\partial M) \leq b(M) - b(M \setminus M)$$
 (2.10)

$$TA(M\backslash M_{\downarrow}\backslash \partial M) - \frac{1}{2}TA(\partial M) \leq b(M) - b(M\backslash M) - 2$$
 (2.11)

respectively.

Now the assertion follows directly from the following lemma

$$b(M\backslash M) - b(M) = \frac{1}{2}b(\partial M) \quad \text{if} \quad \partial M \neq \emptyset ,$$
 or
$$b(M\backslash M) - b(M) = \frac{1}{2}b(\partial M) - 2 \quad \text{if} \quad \partial M = \emptyset$$

PROOF. Let B be an open coordinate neighborhood in M such that \overline{B} is topologically a closed n-ball . We can assume $\widetilde{M} \subseteq B \subseteq \overline{B} \subseteq M \backslash \partial M$. To compute the Betti-numbers of $M \backslash \widetilde{M}$ in terms of that of M and \widetilde{M} we apply the Mayer-Vietoris sequence to the following three decompostions

I.
$$M = (M \setminus B) \cup \overline{B}$$

$$(M \setminus B) \cap \overline{B} = \partial \overline{B} \cong S^{n-1} ,$$

II.
$$\overline{B} = (\overline{B} \setminus (\widetilde{M} \setminus \partial \widetilde{M})) \cup \widetilde{M}$$
$$(\overline{B} \setminus (\widetilde{M} \setminus \partial \widetilde{M})) \cap \widetilde{M} = \partial \widetilde{M},$$

III.
$$M \setminus (\widetilde{M} \setminus \widetilde{\partial M}) = (M \setminus B) \cup (\overline{B} \setminus (\widetilde{M} \setminus \widetilde{\partial M}))$$

$$(M \setminus B) \cap (\overline{B} \setminus (\widetilde{M} \setminus \widetilde{\partial M})) = \partial \overline{B} \cong S^{n-1} .$$

The first decomposition leads to

$$b(M) = b(M \setminus B) - 1 \quad \text{if } \partial M \neq \emptyset$$
 (2.12)

$$b(M) = b(M \setminus B) + 1 \quad \text{if } \partial M = \phi , \qquad (2.13)$$

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the second one to

$$b(B \setminus M) + b(M) = b(\partial M) + 1$$
 (2.14)

the third one to

$$b(M\backslash M) = b(M\backslash B) + b(\overline{B}\backslash M) - 2$$
 (2.15)

At last we have the equation

$$b(\partial M) = 2 b(M) \tag{2.16}$$

because by assumption \tilde{M} can be embedded in $B \subseteq E^n$ (cf. [9] Prop. 5.1). Now the lemma follows directly from (2.12) - (2.16) .

PROOF of Corollary B 2 . Consider for example an embedding of $S^k \chi S^{n-k}$ in E^{n+1} ($k \ge 1$ arbitrary) as a tight hypersurface of rotation (like the standard-torus in E^3) and change this embedding a little bit such that there is an open region U contained in some hyperplane of E^{n+1} . Now define M by removing a small tight 'solid torus' of type $S^m \chi B^{n-m}$ from U ($m \ge 1$). By Corollary B 1 M is (n-2)-tight but of course it is not tight. By suitable choice of the embedding of $S^k \chi S^{n-k}$ we started from we can assume that U lies not in the boundary of the convex hull $\mathfrak{F}^n M$. So we can obtain an example where $\mathfrak{F}^n M$ lies not in the boundary of $\mathfrak{F}^n M$.

<u>REMARK.</u> In the examples of corollary B 2 the boundary $\Im M$ was always tightly embedded in \mathbb{E}^{n+1} . The natural question whether there exist in higher dimensions (n-2)-tight immersions with non-tight boundary seems to be open. For n=2 an example is due to L. Rodriguez.

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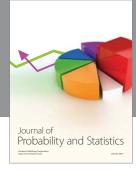
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