# Purna Candra Das Necessary and sufficient conditions for oscillation of neutral equation

Czechoslovak Mathematical Journal, Vol. 44 (1994), No. 2, 281-291

Persistent URL: http://dml.cz/dmlcz/128456

## Terms of use:

© Institute of Mathematics AS CR, 1994

Institute of Mathematics of the Czech Academy of Sciences provides access to digitized documents strictly for personal use. Each copy of any part of this document must contain these *Terms of use*.



This document has been digitized, optimized for electronic delivery and stamped with digital signature within the project *DML-CZ: The Czech Digital Mathematics Library* http://dml.cz

## NECESSARY AND SUFFICIENT CONDITIONS FOR OSCILLATION OF NEUTRAL EQUATION

P. DAS, Berhampur

(Received May 25, 1992)

#### **1. INTRODUCTION**

Consider the neutral delay differential equations

(1.1) 
$$\frac{\mathrm{d}}{\mathrm{d}t}[x(t) + px(t - \tau_0)] + \sum_{i=1}^n p_i(t)x(t - \tau_i) = 0$$

 $\operatorname{and}$ 

(1.2) 
$$\frac{\mathrm{d}}{\mathrm{d}t}[x(t) + px(t-\tau_0)] + Q(t) \Big(\sum_{i=1}^n a_i x(t-\tau_i)\Big) = 0,$$

where

(H<sub>1</sub>)  $p_i \in C([0,\infty), \mathbb{R}^+)$ ,  $p_i(t)$  are periodic functions with common period T and  $\tau_0 < \min\{\tau_i, i = 1, 2, ..., n\};$ 

(H<sub>2</sub>)  $Q \in C([0,\infty), \mathbb{R}^+)$ , Q is T-periodic and  $p, a_i \in \mathbb{R}$ ;

(H<sub>3</sub>)  $\tau_i \in \mathbb{R}^+$  and there exists integers  $n_i$  such that  $\tau_i = n_i T$ .

In this paper we obtain the following necessary and sufficient conditions for oscillation of all solutions of (1.1) and (1.2).

**Theorem 1.** Suppose that

$$P_i = \frac{1}{T} \int_0^T p_i(s) \,\mathrm{d}s, \quad i = 1, 2, \dots, n.$$

If  $(H_1)$ ,  $(H_3)$  hold and  $p \in \mathbb{R}^+$  then the following conditions are equivalent:

(a) Every solution of (1.1) oscillates.

(b) Every solution of the neutral equation with constant coefficients

(1.3) 
$$\frac{\mathrm{d}}{\mathrm{d}t}[x(t) + px(t - \tau_0)] + \sum_{i=1}^n P_i x(t - \tau_i) = 0$$

oscillates.

**Theorem 2.** Suppose that

$$P = \frac{1}{T} \int_0^T Q(s) \,\mathrm{d}s$$

If  $(H_2)$  and  $(H_3)$  hold then the following conditions are equivalent:

- (c) Every solution of (1.2) oscillates.
- (d) Every solution of the neutral equation with constant coefficients

(1.4) 
$$\frac{\mathrm{d}}{\mathrm{d}t}[x(t) + px(t - \tau_0)] + \sum_{i=1}^n Pa_i x(t - \tau_i) = 0$$

oscillates.

**Theorem 3.** Suppose that

$$\sigma_i = \int_0^{\tau_i} Q(s) \,\mathrm{d}s, \quad i = 0, 1, 2, \dots, n.$$

If  $(H_2)$  and  $(H_3)$  hold then the following conditions are equivalent:

(e) Every solution of (1.2) oscillates.

(f) Every solution of the neutral equation with constant coefficients

(1.5) 
$$\frac{\mathrm{d}}{\mathrm{d}t}[x(t) + px(t - \tau_0)] + \sum_{i=1}^n a_i x(t - \sigma_i) = 0$$

oscillates.

By a solution of (1.1) (or (1.2)) on  $[0,\infty)$ , we mean a continuous real valued function x defined on the interval  $[-\rho,\infty)$ , where  $\rho = \max\{\tau_i, i = 0, 1, 2, ..., n\}$  and  $(x(t) + px(t - \tau_0))$  is differentiable in  $[0,\infty)$  and satisfies (1.1) (or (1.2)). As usual, a solution of (1.1) or (1.2) is said to be oscillatory if it has arbitrary large zeros, and nonoscillatory otherwise.

Applications of neutral equations occur in electrical networks containing lossless transmission lines. Such lines arise in high speed computers where the lossless transmission lines are used to interconnect switching circuits (see [1] and [6]).

### 2. Proof of Theorem 1

Without any loss of generality, assume that  $\tau_{i-1} < \tau_i$ , i = 1, 2, ..., n. For the proof of "(a) implies (b)", assume to the contrary that y(t) is a nonoscillatory solution of (1.3). From a result due to Kulenovic, Ladas and Meimaridou [7], it follows that the characteristic equation

(2.1) 
$$F(\lambda) = -\lambda(1+p\mathrm{e}^{\lambda\tau_0}) + \sum_{i=1}^n P_i \mathrm{e}^{\lambda\tau_i} = 0$$

has a real root, say  $\lambda_0$ . For each  $\lambda \in \mathbb{R}$  define

(2.2) 
$$f_{\lambda}(t) = \left(\sum_{i=1}^{n} p_i(t) \mathrm{e}^{\lambda \tau_i}\right) / (1 + p \mathrm{e}^{\lambda \tau_0})$$

For k = 0, 1, 2..., n, we have

(2.3) 
$$\int_{t-\tau_k}^t f_{\lambda}(s) \, \mathrm{d}s = \frac{\tau_k}{1+p\mathrm{e}^{\lambda\tau_0}} \bigg\{ \sum_{i=1}^n \mathrm{e}^{\lambda\tau_i} \bigg( \frac{1}{\tau_k} \int_{t-\tau_k}^t p_i(s) \, \mathrm{d}s \bigg) \bigg\}$$
$$= \frac{\tau_k}{1+p\mathrm{e}^{\lambda\tau_0}} \bigg( \sum_{i=1}^n \mathrm{e}^{\lambda\tau_i} P_i \bigg).$$

Using (2.1) and (2.3) with  $\lambda = \lambda_0$  we obtain

(2.4) 
$$\int_{t-\tau_k}^t f_{\lambda_0}(s) \,\mathrm{d}s = \lambda_0 \tau_k, \quad k = 0, 1, 2, \dots, n.$$

Set

$$x(t) = \exp\left(-\int_0^t f_{\lambda_0}(s) \,\mathrm{d}s\right).$$

By (2.4) we have

(2.5) 
$$\frac{\mathrm{d}}{\mathrm{d}t}[x(t) + px(t - \tau_0)] + \sum_{i=1}^n p_i(t)x(t - \tau_i) \\ = \left(-f_{\lambda_0}(t) - pf_{\lambda_0}(t - \tau_0)\mathrm{e}^{\lambda_0\tau_0} + \sum_{i=1}^n p_i(t)\mathrm{e}^{\lambda_0\tau_i}\right)\exp\left(-\int_0^t f_{\lambda_0}(s)\,\mathrm{d}s\right).$$

Clearly, if  $f_{\lambda_0}(t)$  is a *T*-periodic function then  $f_{\lambda_0}(t) = f_{\lambda_0}(t - \tau_0)$ . Using (2.2) in (2.5) for  $\lambda = \lambda_0$  we see that x(t) is a nonoscillatory solution of (1.1), a contradiction to our assumption. Hence "(a) implies (b)" has been proved.

Now we prove that (b) implies (a). If possible, suppose that y(t) is a nonoscillatory solution of (1.1). Without any loss of generality, assume that y(t) > 0 for  $t \ge t_0$ . To complete the proof of this theorem we have to obtain a contradiction. Whenever we write an inequality, we mean that it holds for large t.

It is known from [7], that all solutions of (1.3) are oscillatory if and only if the characteristic equation  $F(\lambda) = 0$  has no real roots. Since F(0) > 0, we have the following lemmas.

**Lemma 1.** There exists a positive number  $m_0$  such that

$$-\mu(1+p\mathrm{e}^{\mu\tau_0}) + \sum_{i=1}^n P_i \mathrm{e}^{\mu\tau_i} \ge m_0 \quad \text{for } \mu \in \mathbb{R}.$$

**Lemma 2.** If y(t) is a solution of (1.1) then  $x(t) = y(t) + py(t - \tau_0)$  is also a solution of (1.1).

Their proofs are very straightforward and hence are omitted. Now set

$$\begin{aligned} x(t) &= y(t) + py(t - \tau_0), \\ z(t) &= x(t) + px(t - \tau_0), \\ z_1(t) &= z(t) + pz(t - \tau_0) \end{aligned}$$

and

$$z_m(t) = z_{m-1}(t) + p z_{m-1}(t - \tau_0), \quad m = 2, 3, \dots$$

It follows from Lemma 2 that x(t), z(t) and  $z_m(t)$ , m = 1, 2... are solutions of (1.1). Clearly,  $x'(t) = -\sum_{i=1}^{n} p_i(t)y(t-\tau_i)$  implies that x'(t) < 0 eventually. Similarly,  $z'(t) < 0, z'_m(t) < 0, m = 1, 2, ...$  eventually. Let

$$\Lambda_m = \{\lambda > 0 \mid z'_m(t) + f_\lambda(t) z_m(t) \leqslant 0 \text{ for large } t\}$$

Now we prove the following two lemmas for  $\Lambda_m$ .

**Lemma 3.**  $\Lambda_m \neq \emptyset$  for each  $m \in I^+$ ,  $I^+ = \{1, 2, \ldots\}$ .

Proof. First we prove that  $\Lambda_1 \neq \emptyset$ . Since z'(t) < 0 eventually, we have

(2.6) 
$$\frac{z_1(t)}{z(t-\tau_i)} = \frac{z_1(t-\tau_i+\tau_0)}{z(t-\tau_i)} \cdot \frac{z_1(t)}{z_1(t-\tau_i+\tau_0)} \\ = \frac{z(t-\tau_i+\tau_0) + pz(t-\tau_i)}{z(t-\tau_i)} \cdot \frac{z_1(t)}{z_1(t-\tau_i+\tau_0)} \\ \leqslant (1+p) \frac{z_1(t)}{z_1(t-\tau_i+\tau_0)}.$$

Let  $\tau_i - \tau_0 = \alpha_i T$ , where  $\alpha_i \in I^+$ . From (2.6) we have

(2.7) 
$$\frac{z_1(t)}{z(t-\tau_i)} \leq (1+p)\frac{z_1(t)}{z_1(t-\alpha_i T)}.$$

From (2.7) we have

(2.8) 
$$\frac{z_1(t)}{1+p} \leqslant z(t-\tau_i).$$

Using (2.8) and the fact that z(t) is a solution of (1.1) we have

(2.9) 
$$z_1'(t) + \frac{1}{1+p} \Big( \sum_{i=1}^n p_i(t) \Big) z_1(t) \leq z_1'(t) + \sum_{i=1}^n p_i(t) z(t-\tau_i) = 0.$$

Consequently, from (2.9) we obtain

(2.10) 
$$\frac{z_1'(t)}{z_1(t)} \leqslant -\Big(\sum_{i=1}^n p_i(t)\Big)/(1+p).$$

Now using (2.10) we have

$$(2.11) \qquad \frac{z_1(t-\alpha_i T)}{z_1(t)} = \exp\left(-\int_{t-\alpha_i T}^t \frac{z_1'(s)}{z_1(s)} \,\mathrm{d}s\right)$$
$$\geqslant \exp\left\{\frac{1}{1+p} \int_{t-\alpha_i T}^t \left(\sum_{i=1}^n p_i(s)\right) \,\mathrm{d}s\right\}$$
$$= \exp\left\{\frac{\alpha_i T}{1+p} \left(\frac{1}{\alpha_i T} \int_{t-\alpha_i T}^t \left(\sum_{i=1}^n p_i(s)\right) \,\mathrm{d}s\right)\right\}$$
$$= \exp\left\{\frac{\alpha_i T}{1+p} \left(\sum_{i=1}^n P_i\right)\right\}.$$

From (2.7) and (2.11) we have

(2.12) 
$$\frac{z(t-\tau_i)}{z_1(t)} \ge \frac{1}{1+p} \exp\left\{\frac{\alpha_i T}{1+p} \left(\sum_{i=1}^n P_i\right)\right\}.$$

Hence

(2.13) 
$$\sum_{i=1}^{n} p_i(t) \frac{z(t-\tau_i)}{z_1(t)} \ge \sum_{i=1}^{n} p_i(t) K_i,$$

where

$$K_i = \frac{1}{1+p} \exp\left\{\frac{\alpha_i T}{1+p} \left(\sum_{i=1}^n P_i\right)\right\}.$$

Consider the functions

$$g_i(\theta) = rac{\mathrm{e}^{\theta \tau_i}}{1 + p \mathrm{e}^{\theta \tau_0}}, \quad i = 1, 2, \dots, n.$$

Clearly,  $g'_i(\theta) > 0$  and  $g_i(\theta) \to \infty$  monotonically as  $\theta \to \infty$ . Since  $g_i(0) = 1/(1+p)$ and  $K_i > 1/(1+p)$ , there exists a constant  $\mu_i > 0$  such that  $g_i(\mu_i) = K_i$ , i = 1, 2, ..., n. Let  $\mu = \min\{\mu_1, \mu_2, ..., \mu_n\}$ . Then  $\mu > 0$  and  $g_i(\mu_i) \ge g_i(\mu)$ . Consequently, from (2.13) we have

$$\sum_{i=1}^{n} p_i(t) \frac{z(t-\tau_i)}{z_1(t)} \ge \sum_{i=1}^{n} p_i(t) K_i = \sum_{i=1}^{n} p_i(t) g_i(\mu_i) \ge \sum_{i=1}^{n} p_i(t) g_i(\mu),$$

that is,

$$\sum_{i=1}^{n} p_i(t) z(t - \tau_i) \ge \left(\sum_{i=1}^{n} p_i(t) g_i(\mu)\right) z_1(t) = f_{\mu}(t) z_1(t)$$

Hence by the above inequality we have

$$z_1'(t) + f_{\mu}(t)z_1(t) \leq z_1'(t) + \sum_{i=1}^n p_i(t)z(t-\tau_i) = 0.$$

This implies that  $\mu \in \Lambda_1$ . To show that  $\Lambda_n$  is nonempty we adopt exactly the same procedure where  $z_{n-1}(t)$  serves the purpose of z(t). Hence the proof of this lemma is completed.

**Lemma 4.** There exists a positive real number  $\lambda^*$  such that  $\lambda^*$  is the upper bound of  $\Lambda_m$  for all  $m \in I^+$ .

Proof. Clearly, for  $k = 1, 2, \ldots, n$ ,

(2.14) 
$$\frac{z_{m-1}(t-\tau_k)}{z_m(t)} \leqslant \frac{z_{m-1}(t-\tau_k)}{pz_{m-1}(t-\tau_0)}$$

and

$$(2.15) \quad \frac{1}{z_{m-1}(t-\tau_k+\tau_0)} \Big( \sum_{i=1}^n p_i(t) z_{m-2}(t-\tau_i) \Big) \\ \geqslant p_k(t) \frac{z_{m-2}(t-\tau_k)}{z_{m-1}(t-\tau_k+\tau_0)} \\ = p_k(t) \frac{z_{m-2}(t-\tau_k)}{z_{m-2}(t-\tau_k+\tau_0) + p z_{m-2}(t-\tau_k)} \\ \geqslant \frac{p_k(t)}{1+p}.$$

Since  $p_i(t) > 0$ , i = 1, 2, ..., n are periodic functions, there exists a constant  $\beta > 0$ such that  $p_i(t) > \beta$  for all  $t \in [0, \infty)$  and all i = 1, 2, ..., n. Now using (2.15) and the fact that  $z_{m-2}(t)$  is a solution of (1.1) we have

$$(2.16) \quad z'_{m-1}(t) + \frac{\beta}{1+p} z_{m-1} \left( t - (\tau_k - \tau_0) \right) \leqslant z'_{m-1}(t) + \sum_{i=1}^n p_i(t) z_{m-2}(t - \tau_i) = 0.$$

Applying a lemma of Ladas, Sficas and Stavroulakis [10] to (2.16) we have

(2.17) 
$$z_{m-1}(t) \ge \left(\frac{\beta(\tau_k - \tau_0)}{2(1+p)}\right)^2 z_{m-1}(t - (\tau_k - \tau_0)), \quad k = 1, 2, \dots, n.$$

Replacing t by  $t - \tau_0$  in (2.17) and using the resulting inequality along with the fact that  $z_m(t) \ge p z_{m-1}(t - \tau_0)$  we obtain

$$(2.18) \ z'_{m}(t) + \Big\{ \sum_{i=1}^{n} p_{i}(t) \frac{4(1+p)^{2}}{p(\beta(\tau_{i}-\tau_{0}))^{2}} \Big\} z_{m}(t) \ge z'_{m}(t) + \sum_{i=1}^{n} p_{i}(t) z_{m-1}(t-\tau_{i}) = 0.$$

Since  $g_i(\theta) \to 0$  as  $\theta \to -\infty$ , there exists a real number  $\mu_i$  such that

$$g_i(\mu_i) = \frac{4(1+p)^2}{p(\beta(\tau_i - \tau_0))^2}, \quad i = 1, 2, \dots, n.$$

Take  $\lambda^* = \max\{\mu_1, \mu_2, \dots, \mu_n\}$ . Since  $g'_i(t) > 0$ , we have  $g_i(\lambda^*) \ge g_i(\mu_i)$ ,  $i = 1, 2, \dots, n$ . Hence from (2.18) we have

$$(2.19) \quad z'_{m}(t) + f_{\lambda^{\star}}(t)z_{m}(t) = z'_{m}(t) + \Big(\sum_{i=1}^{n} p_{i}(t)g_{i}(\lambda^{\star})\Big)z_{m}(t)$$
$$> z'_{m}(t) + \Big(\sum_{i=1}^{n} p_{i}(t)g_{i}(\mu_{i})\Big)z_{m}(t)$$
$$= z'_{m}(t) + \Big(\sum_{i=1}^{n} p_{i}(t)\frac{4(1+p)^{2}}{p(\beta(\tau_{i}-\tau_{0}))^{2}}\Big)z_{m}(t) \ge 0.$$

Hence  $\lambda^*$  is the upper bound of  $\Lambda_m$ , because if  $\lambda^* < \lambda \in \Lambda_m$  then

$$f_{\lambda^*}(t) = \sum_{i=1}^n p_i(t)g_i(\lambda^*) < \sum_{i=1}^n p_i(t)g_i(\lambda) = f_{\lambda}(t).$$

Consequently,

$$z'_m(t) + f_{\lambda} \cdot (t) z_m(t) \leqslant z'_m(t) + f_{\lambda}(t) z_m(t) = 0,$$

a contradiction to (2.19). This completes the proof of this lemma.

Now we proceed to find our final contradiction. Set  $\Lambda = \bigcup \Lambda_i \subset \mathbb{R}$  and  $\gamma = m/(1 + pe^{\tau_0 \lambda^*})$ . By Lemma 4, the set  $\Lambda$  is bounded. Hence it possesses a finite supremum  $\lambda_*$ . Let  $\lambda \in \Lambda$  be such that  $\lambda_* - \gamma/2 < \lambda < \lambda_*$ . Then there exists an integer m such that  $\lambda \in \Lambda_m$ . Set

(2.20) 
$$\varphi_{\lambda}(t) = z_m(t) \exp\left(\int_0^t f_{\lambda}(s) \,\mathrm{d}s\right).$$

Clearly,  $\varphi'_{\lambda}(t) \leqslant 0$  eventually and

$$(2.21) \quad z'_{m+1}(t) + f_{\lambda+\gamma}(t)z_{m+1}(t) \\ = (z_m(t) + pz_m(t-\tau_0))' + f_{\lambda+\gamma}(t)(z_m(t) + pz_m(t-\tau_0)) \\ = -\left(\sum_{i=1}^n p_i(t)z_m(t-\tau_i)\right) + f_{\lambda+\gamma}(t)(z_m(t) + pz_m(t-\tau_0)) \\ = -\left(\sum_{i=1}^n p_i(t)\varphi_\lambda(t-\tau_i)\right) \exp\left(-\int_0^{t-\tau_i} f_\lambda(s) \,\mathrm{d}s\right) \\ + f_{\lambda+\gamma}(t)\left\{\varphi_\lambda(t)\exp\left(-\int_0^t f_\lambda(s) \,\mathrm{d}s\right) \\ + p\varphi_\lambda(t-\tau_0)\exp\left(-\int_0^t f_\lambda(s) \,\mathrm{d}s\right)\right\} \\ \leqslant \varphi_\lambda(t-\tau_0)\exp\left(-\int_0^t f_\lambda(s) \,\mathrm{d}s\right) \\ \times \left\{-\sum_{i=1}^n p_i(t)\exp\left(\int_{t-\tau_i}^t f_\lambda(s) \,\mathrm{d}s\right) \\ + f_{\lambda+\gamma}(t)\left(1+p\exp\left(\int_{t-\tau_0}^t f_\lambda(s) \,\mathrm{d}s\right)\right)\right\}.$$

Now using (2.3) in (2.21) we obtain

(2.22) 
$$z'_{m+1}(t) + f_{\lambda+\gamma}(t)z_{m+1}(t) \\ \leqslant \frac{\varphi_{\lambda}(t-\tau_{0})\exp(-\int_{0}^{t}f_{\lambda}(s)\,\mathrm{d}s)}{(1+p\mathrm{e}^{N\tau_{0}})^{-1}}\bigg\{-\frac{\sum_{i=1}^{n}p_{i}(t)\mathrm{e}^{N\tau_{i}}}{1+p\mathrm{e}^{N\tau_{0}}}+f_{\lambda+\gamma}\bigg\},$$

where

$$N = \frac{1}{1 + p \mathrm{e}^{\lambda \tau_0}} \Big\{ \sum_{i=1}^n P_i \mathrm{e}^{\lambda \tau_i} \Big\}.$$

Lemma 1 implies

$$N = \frac{1}{1 + p e^{\lambda \tau_0}} \Big\{ \sum_{i=1}^n P_i e^{\lambda \tau_i} \Big\} \ge \lambda + \frac{m_0}{1 + p e^{\lambda \tau_0}} \ge \lambda + \frac{m_0}{1 + p e^{\lambda^* \tau_0}} = \lambda + \gamma.$$

Hence

(2.23) 
$$f_N(t) \ge f_{\lambda+\gamma}(t).$$

By using (2.23) in (2.22) we obtain

$$z'_{m+1}(t) + f_{\lambda+\gamma}(t)z_{m+1}(t) \leq 0.$$

This implies  $\lambda + \gamma \in \Lambda_{m+1}$ . Consequently,  $\lambda + \gamma \in \Lambda$ . But

$$\lambda + \gamma > \lambda_* + \frac{\gamma}{2} > \lambda_*,$$

a contradiction to our assumption. Hence the proof is completed.

## 3. Proof of Theorems 2 and 3

Suppose that every solution of (1.2) oscillates. If possible, suppose that y(t) is a nonoscillatory solution of (1.4). Set

(3.1) 
$$s(t) = \left(\int_0^t Q(\theta) \,\mathrm{d}\theta\right) / \left(\frac{1}{T}\int_0^T Q(\theta) \,\mathrm{d}\theta\right)$$
$$= \frac{1}{P} \left(\int_0^t Q(\theta) \,\mathrm{d}\theta\right) \text{ and } u(t) = y(s(t)).$$

Clearly,  $s(t) \to \infty$  as  $t \to \infty$  and s(t) is increasing on  $[0, \infty)$ . Since Q is T-periodic we have

(3.2)  
$$\int_{t-\tau_i}^t Q(\theta) \,\mathrm{d}\theta = \int_0^{\tau_i} Q(\theta) \,\mathrm{d}\theta = \tau_i \left(\frac{1}{\tau_i} \int_0^{\tau_i} Q(\theta) \,\mathrm{d}\theta\right) = \tau_i P, \quad i = 0, 1, 2, \dots, n.$$

Further, by using (3.2) we have

(3.3) 
$$u(t-\tau_i) = y\left(\frac{1}{P}\int_0^{t-\tau_i} Q(\theta) \,\mathrm{d}\theta\right)$$
$$= y\left(s - \frac{1}{P}\int_{t-\tau_i}^t Q(\theta) \,\mathrm{d}\theta\right) = y(s-\tau_i), \quad i = 0, 1, 2, \dots, n.$$

From (3.2) and the fact that  $\frac{ds}{dt} = Q(t)/P$  we have

$$\begin{aligned} \frac{\mathrm{d}}{\mathrm{d}t} [u(t) + pu(t - \tau_0)] + Q(t) \Big(\sum_{i=1}^n a_i u(t - \tau_i)\Big) \\ &= \frac{\mathrm{d}}{\mathrm{d}s} [y(s) + py(s - \tau_0)] \frac{\mathrm{d}s}{\mathrm{d}t} + Q(t) \Big(\sum_{i=1}^n a_i y(s - \tau_i)\Big) \\ &= \frac{1}{P} \Big\{ \frac{\mathrm{d}}{-} \mathrm{d}sy(s) + py(s - \tau_0) \Big] + P\Big(\sum_{i=1}^n a_i y(s - \tau_i)\Big) \Big\} Q(t) = 0. \end{aligned}$$

Hence u(t) is a nonoscillatory solution of (1.2), a contradiction to our assumption. Thus "(c) implies (d)" has been proved.

The proof of "(d) implies (c)" can be easily done by using this variable transformation in the reverse way.

This completes the proof of Theorem 2.

Now suppose that (e) holds. If possible, suppose that y(t) is a nonoscillatory solution of (1.5). Set

$$s = \int_0^t Q(\theta) \,\mathrm{d} heta \,.$$

Proceeding along the lines of Theorem 2, it can be shown that  $u(t) = y(\int_0^t Q(\theta) d\theta)$  is a nonoscillatory solution of (1.2), a contradiction to our assumption. Hence "(e) implies (f)" holds. The proof of "(f) implies (e)" can be done by using this transformation in the reverse way.

Remark. (i) Theorem 2 and Theorem 3 generalize Theorem 1 due to Philos [11] and Theorem 1 due to Ladas Philos and Sficas [8], respectively.

(ii) We may see that the condition

$$au_0 < \min\{ au_i, \ i = 1, 2, 3, \dots, n\}$$

assumed in Theorem 1 is only useful to show that (b) implies (a).

(iii) When n = 1, it is not necessary to assume the above condition explicitly because the same follows from the assumption that the characteristic equation

$$F(\lambda) = -\lambda(1 + pe^{\lambda\tau_0}) + P_1 e^{\lambda\tau_1} = 0$$

has no real roots and this holds if and only if all solutions of (1.3) are oscillatory. Indeed,  $\tau_0 \ge \tau_1$  implies that  $F(\lambda) < 0$  for large value of  $\lambda$ . Further, F(0) > 0 implies that  $F(\lambda) = 0$  has a real root.

(iv) When p = 0, Theorem 1 reduces to the main result due to Philos [12]. If p < 0 the problem remains open.

A c k n o w l e d g e m e n t. Thanks are extended to the referee for suggesting several modifications.

#### References

- R.K. Brayton and R.A. Willoughby: On the numerical integration of a system of difference-differential equations of neutral type. J. Math. Anal. Appl. 18 (1967), 182-189.
- [2] M.K. Grammmatikopoulos, E.A. Gove and G. Lads: Oscillations of first-order neutral delay differential equations. J. Math. Anal. Appl. 120 (1986), 510-520.
- [3] M.K. Grammmatikopoulos, G. Ladas and Y.G. Sficas: Oscillation and asymptotic behavior of neutral equations with variable coefficients. Radovi Matematicki 2 (1986), 279-303.
- [4] M.K. Grammmatikopoulos, Y.G. Sficas and I.P. Stavroulakis: Necessary and sufficient conditions for oscillation of neutral equations with several coefficients. J. Differential Equations 76 (1988), 294-311.
- [5] E.A. Grove, G. Ladas and A. Meimaridou: A necessary and sufficient condition for the oscillation of neutral equations. J. Math. Anal. Appl. 126 (1987), 341-354.
- [6] J. Hale: Theory of Functional Differential Equations. Springer-Verlag, New York, 1977.
- [7] M.R.S. Kulenovic, G. Ladas and A. Meimaridou: Necessary and sufficient condition for oscillations of neutral differential equations. J. Austral. Math. Soc. (Ser. B) 28 (1987), 362-375.
- [8] G. Ladas, Ch.G. Philos and Y.G. Sficas: Oscillations in neutral equations with periodic coefficients. Proc. Amer. Math. Soc. 113 (1991), 123-134.
- [9] G. Ladas and Y.G. Sficas: Oscillations of neutral delay differential equations. Canad. Math. Bull. 29 (1986), 438-445.
- [10] G. Ladas, Y.G. Sficas and I.P. Stavroulakis: Necessary and sufficient conditions for oscillations. Amer. Math. Monthly 90 (1983), 637-640.
- [11] Ch.G. Philos: Oscillations of some delay differential equations with periodic coefficients. J. Math. Anal. Appl. 162 (1991), 452-475.
- [12] Ch.G. Philos: On the oscillation of differential equations with periodic coefficients. Proc. Amer. Math. Soc. 111 (1991), 433-440.
- [13] Y.G. Sficas and I.P. Stavroulakis: Necessary and sufficient conditions for oscillations of neutral differential equations. J. Math. Anal. Appl. 123 (1987), 494-507.

Author's address: Department of Mathematics, Berhampur University, Berhampur-760007, India;

Present address: Department of Mathematics, University Higher Secondary School, Berhampur University, Berhampur-760007, India.