

Network planning using two-stage programming under uncertainty

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Introduction

Outline of the problem

Examples

Definition of the problem

The underlying deterministic problem is the following:

$$\begin{aligned} \min & (c'u + d'v) \\ & Au \geq b \\ & Tu + Mv \geq \xi, \end{aligned}$$

where ξ is random variable.

First stage problem:

$$\begin{aligned} \min(c'u + E(\mu(u, \xi))) \\ Au \geq b, \\ u \in K, \end{aligned}$$

where $\mu(u, \xi)$ is the optimal value of the **Second stage problem**

$$\begin{aligned} \min(d'v) \\ Tu + Mv \geq \xi, \end{aligned}$$

and $K = \{u; \forall \xi \exists v : Tu + Mv \geq \xi\}$.

How to solve?

- ▶ Solve the first stage problem (function to be minimized depends only on u)
- ▶ Realize ξ
- ▶ Decide on v

Properties

- ▶ K is a convex polyhedron.
- ▶ For every fixed ξ the second stage optimal value $\mu(u, \xi)$ is a convex function of the variable u .
- ▶ If the set of possible values of ξ is convex, then $\mu(u, \xi)$ is convex in ξ .
- ▶ If $E(\xi)$ exists and $\mu(u, \xi)$ is finite for every u and ξ , then $E\mu(u, \xi)$ exists and is a convex function of u .

Up to now we assumed that there exists $\mu(u, \xi)$ for every ξ . Because such assumption is not always valid, we will require the solvability of the second stage problem only by probability:

First stage problem:

$$\begin{aligned} \min(c'u + E(\mu(u, \xi))) \\ Au \geq b, \\ P(u \in K) \geq p, \end{aligned}$$

where p is prescribed and $\mu(u, \xi)$ is the optimal value of the new **Second stage problem**

$$\begin{aligned} \min(d'v + t'z) \\ Tu + Mv + z \geq \xi, \end{aligned}$$

where $t'z$ is the cost of infeasibility. Sometimes non-linear function $\sum t_j(z_j)$ will be used.

Assumptions

- ▶ The power systems form a network.
- ▶ The system must have a reliability level $1 - \text{LOLP} \geq p$, where LOLP is the probability that demand will be higher than supply.
- ▶ We may increase the power generating and the tie line capacities.
- ▶ No distinction will be made between capacity and reserve capacity.
- ▶ Each power system can help others. The tie line between systems a and b is not necessarily the same as that between b and a .
- ▶ Power dispatching and outage cost money.

Notations

N	Number of power systems
x_j	Generating capacity of the j^{th} system, to be determined
$x_j^{(l)}, x_j^{(u)}$	Prescribed lower and upper bound for x_j
y_{hk}	Capacity of the line between system h and system k , to be determined
$y_{hk}^{(l)}, x_{hk}^{(u)}$	Prescribed lower and upper bound for y_{hk}
i_j	Total power dispatched from j^{th} system
i_{hk}	Power dispatched for system h to system k
p	Prescribed lower level for 1 – LOLP
ξ_j	Random demand for electric power at the j^{th} system
$c_j(\cdot)$	Cost function of the generating capacity at the j^{th} system
$c_{hk}(\cdot)$	Cost function of the interconnection capacity between systems h and k
d_{hk}	Cost of dispatching one unit of power from system h to system k
$t_j(\cdot)$	Cost of outage of magnitude z at system j

Let $A(x, y, \xi)$ denote the event that for fixed x and y the total demand in the pool can be met by a suitable power dispatch.

The problem now looks like the following:

$$\min\left(\sum_j c_j(x_j) + \sum_h \sum_k c_{hk}(y_{hk}) + E(\mu)\right)$$

$$P(A(x, y, \mu)) \geq p,$$

$$x_j^{(l)} \leq x_j \leq x_j^{(u)},$$

$$y_{hk}^{(l)} \leq y_{hk} \leq y_{hk}^{(u)}$$

A **flow** i on a network is defined as a function on $N \times N$ satisfying for all $h, k \in N$ the relations

$$\begin{aligned}i(h, k) + i(k, h) &= 0, \\i(h, k) &\leq y_{hk}.\end{aligned}$$

Further define **network demand** $q : N \rightarrow \mathbb{R}$ as $q_j = x_j - \xi_j$ and for $S, T \subset N$:

$$\begin{aligned}q(S) &= \sum_{h \in S} q(h), \\i(S, T) &= \sum_{h \in S} \sum_{k \in T} i(h, k).\end{aligned}$$

Properties of q and i

For all S_1, S_2, T such as $S_1 \cap S_2 = \emptyset$ we have

$$\begin{aligned}q(S_1 \cup S_2) &= q(S_1) + q(S_2), \\i(S_1 \cup S_2, T) &= i(S_1, T) + i(S_2, T), \\i(T, S_1 \cup S_2) &= i(T, S_1) + i(T, S_2), \\i(S, S) &= 0, \\i(S, T) &\leq y_{ST},\end{aligned}$$

where

$$y(S, T) = \sum_{h \in S} \sum_{k \in T} y_{ST}$$

The network demand is called **feasible** if there exists a flow i such that for every $a \in N$ we have

$$i(N, a) \geq q(a)$$

Theorem (Feasibility theorem)

The network demand q is feasible if and only if for every $S \subset N$ we have

$$q(\bar{S}) \leq y(S, \bar{S}).$$

Example 1

Let us consider the pool consisting only of two points. Denote $y = y_{12} = y_{21}$. The feasibility theorem gives

$$\begin{aligned}\xi_1 - x_1 + \xi_2 - x_2 &\leq 0, \\ \xi_1 - x_1 &\leq y, \\ \xi_2 - x_2 &\leq y.\end{aligned}$$

If we denote $i = i(1,2) = -i(2,1)$, we also receive following inequalities

$$\begin{aligned}x_1 - i &\geq \xi_1, \\ x_2 + i &\geq \xi_2, \\ -y &\leq i \leq y.\end{aligned}$$

Example 2

In this example the pool will be formed by three nodes connected together. Denote $y_1 = y_{12}$, $y_2 = y_{23}$ and $y_3 = y_{31}$. Using the feasibility theorem

$$\xi_1 - x_1 + \xi_2 - x_2 + \xi_3 - x_3 \leq 0,$$

$$\xi_1 - x_1 \leq y_1 + y_3,$$

$$\xi_2 - x_2 \leq y_1 + y_2,$$

$$\xi_3 - x_3 \leq y_2 + y_3,$$

$$\xi_1 - x_1 + \xi_2 - x_2 \leq y_2 + y_3,$$

$$\xi_2 - x_2 + \xi_3 - x_3 \leq y_1 + y_3,$$

$$\xi_1 - x_1 + \xi_3 - x_3 \leq y_1 + y_3.$$

The next result will be also similar to that one received in the previous example

$$i_{21} + i_{31} \geq \xi_1 - x_1,$$

$$i_{12} + i_{32} \geq \xi_2 - x_2,$$

$$i_{13} + i_{23} \geq \xi_3 - x_3,$$

$$i_{12} + i_{21} = 0,$$

$$i_{23} + i_{32} = 0,$$

$$i_{13} + i_{31} = 0,$$

$$-y_{12} \leq y_1 \leq y_{12},$$

$$-y_{23} \leq y_2 \leq y_{23},$$

$$-y_{13} \leq y_3 \leq y_{13},$$

Example 3

The power system is the same as in example 1 but this time we will use the model presented in the introduction.

The first stage problem is the following:

$$\min(c_1(x_1) + c_2(x_2) + c(y) + E(\mu(x_1, x_2, y, \xi_1, \xi_2)))$$

$$P \left(\begin{array}{l} \xi_1 + \xi_2 \leq x_1 + x_2 \\ \xi_1 \leq x_1 + y \\ \xi_2 \leq x_2 + y \end{array} \right) \geq p$$

$$x_j^{(l)} \leq x_j \leq x_j^{(u)}$$

$$y^l \leq y \leq y^u$$

and the second stage problem

$$\begin{aligned} \min & (d_{12}i^+ + d_{21}i^- + t_1(z_1) + t_2(z_2)) \\ & x_1 - i^+ + i^- + z_1 \geq \xi_1, \\ & x_2 + i^+ - i^- + z_2 \geq \xi_2, \\ & 0 \leq i^+, i^- \leq y, \\ & i^+, i^-, z_1, z_2 \geq 0. \end{aligned}$$

The main task of this example is to compute $E(\mu)$. But firstly we have to consider four possible cases:

- (i) if $\xi_1 - x_1 \leq 0$ and $\xi_2 - x_2 \leq 0$ then $\mu = 0$.
- (ii) if $\xi_1 - x_1 \leq 0$ and $\xi_2 - x_2 > 0$ then
 $i^+ = \min(x_1 - \xi_1, \xi_2 - x_2, y)$, $i^- = 0$, $z_1 = 0$, $z_2 = \xi_2 - x_2 - i^+$ and
 $\mu = d_{12}i^+ + t_2(z_2)$.
- (iii) if $\xi_1 - x_1 > 0$ and $\xi_2 - x_2 \leq 0$ then
 $i^+ = 0$, $i^- = \min(\xi_1 - x_1, x_2 - \xi_2, y)$, $z_1 = \xi_1 - x_1 - i^-$, $z_2 = 0$
and $\mu = d_{21}i^- + t_1(z_1)$.
- (iv) if $\xi_1 - x_1 > 0$ and $\xi_2 - x_2 > 0$ then
 $i^+ = 0$, $i^- = 0$, $z_1 = \xi_1 - x_1$, $z_2 = \xi_2 - x_2$ and $\mu = t_1(z_1) + t_2(z_2)$.

And finally

$$\begin{aligned} E(\mu) = & \int_{x_2}^{\infty} \int_{-\infty}^{x_1} (d_{12} \min(x_1 - v_1, v_2 - x_2, y) + \\ & + t_2(v_2 - x_2 - \min(x_1 - v_1, v_2 - x_2, y))) f(v_1, v_2) dv_1 dv_2 + \\ & + \int_{-\infty}^{x_2} \int_{x_1}^{\infty} (d_{21} \min(v_1 - x_1, x_2 - v_2, y) + \\ & + t_1(v_1 - x_1 - \min(v_1 - x_1, x_2 - v_2, y))) f(v_1, v_2) dv_1 dv_2 + \\ & + \int_{x_2}^{\infty} \int_{x_1}^{\infty} (t_1(v_1 - x_1) + t_2(v_2 - x_2)) f(v_1, v_2) dv_1 dv_2 \end{aligned}$$

where $f(v_1, v_2)$ is joint probability density function of continuous joint distributions ξ_1 and ξ_2 .

Than you for your patience.