

Institute of Biomedical Engineering
Department of Engineering



Non-local shape descriptor: A new similarity metric for deformable multi-modal registration



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14th International Conference on Medical Image Computing and Computer Assisted Intervention



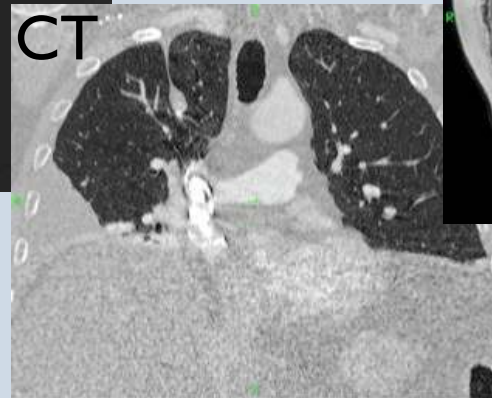
2011, September 19th

Motivation for multimodal image registration

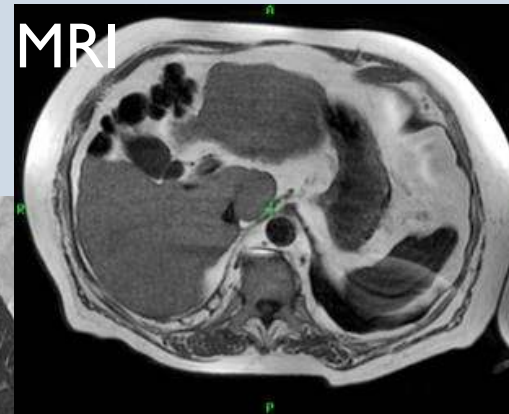
- Combine complementary information from modalities in medical imaging: Ultrasound, CT, MRI, PET, etc...



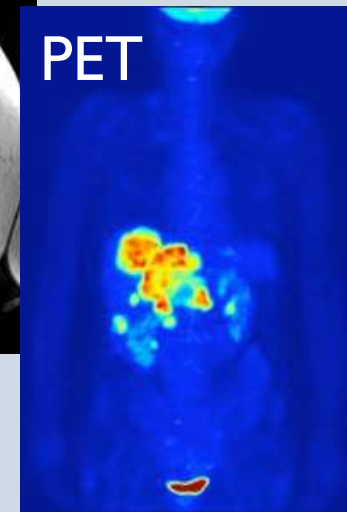
temporal resolution



spatial resolution
dense tissue contrast



soft tissue contrast

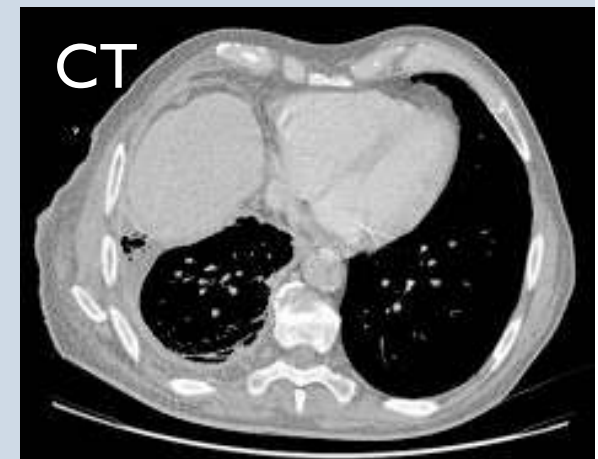
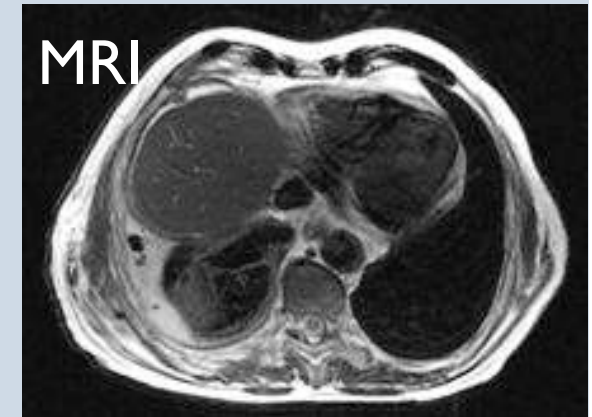


metabolic activity

- Align CT and MRI scans of lung disease patients to improve diagnosis

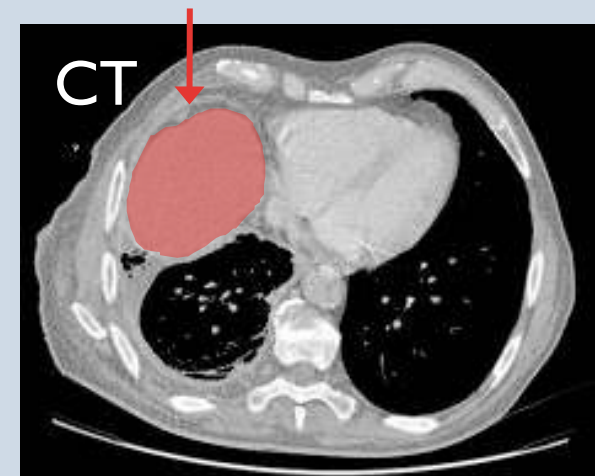
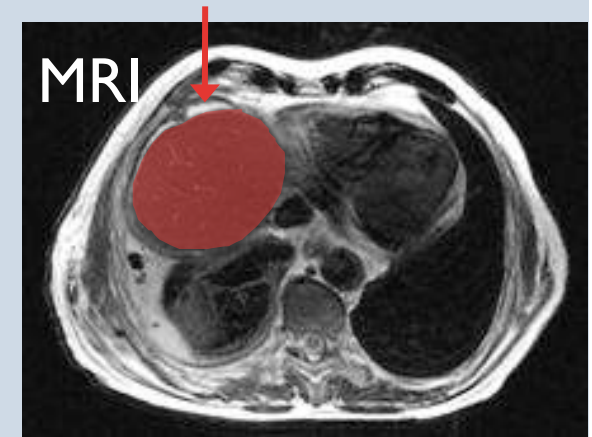
Similarity in multimodal images

- Features used to derive similarity:
(needed for registration cost function)
 - Image intensities (iconic) ■
 - Tissue boundaries / gradients ■
 - Corners / point features (geometric) ■
- Challenging to relate features between modalities
 - different types of features relate to corresponding anatomies in different modalities
 - higher-level models of intensity relations (statistical similarity metrics) need large (up to global) support
 - common similarity metrics use only one feature



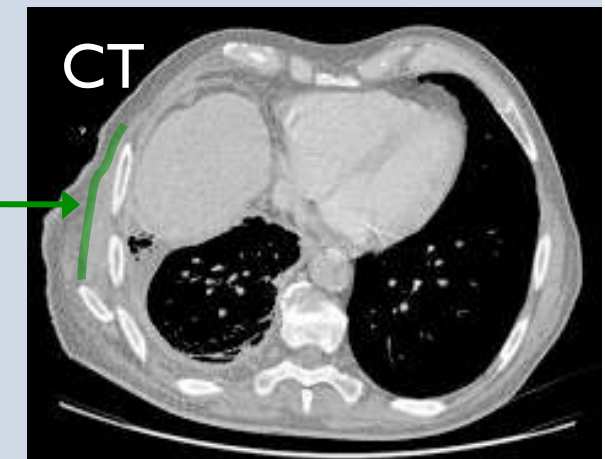
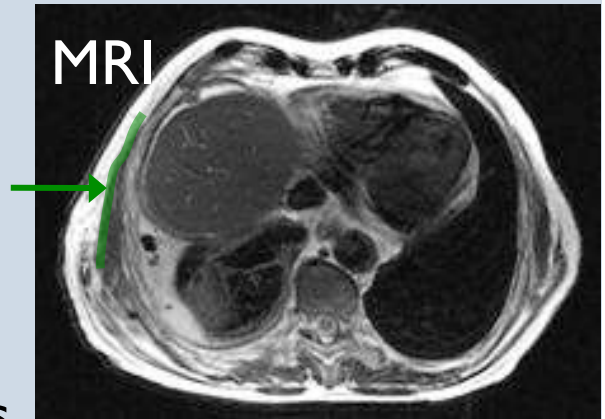
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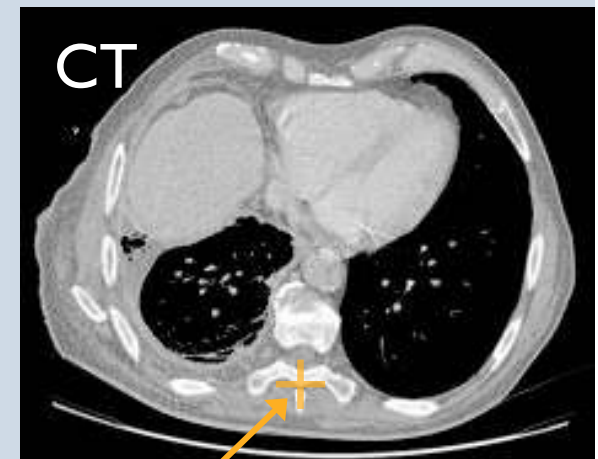
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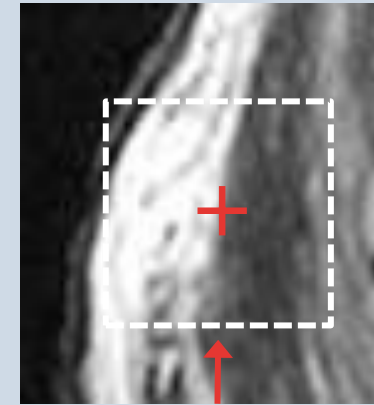


Concept of non-local shape descriptor

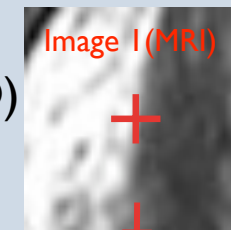
- Single-modal similarity formulations are simple
 - multiple features (intensities, boundaries, textures)
 - more general: image patches
 - similarity metric: sum of squared differences (SSD)

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- Idea of our shape descriptor
 - define a spatial descriptor for a voxel
 - within non-local search region in the same image
 - based on an intensity difference within modality (SSD)



non-local search region N



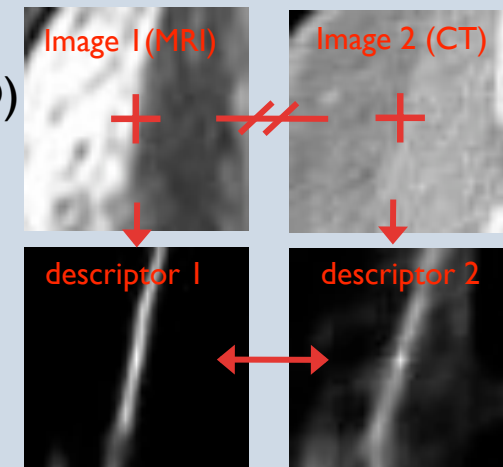
descriptor I

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- Idea of our shape descriptor
 - define a spatial descriptor for a voxel
 - within non-local search region in the same image
 - based on an intensity difference within modality (SSD)
 - compare descriptors of two multimodal images
- Advantages
 - no global relations of intensities is assumed
 - highly discriminative and robust to noise

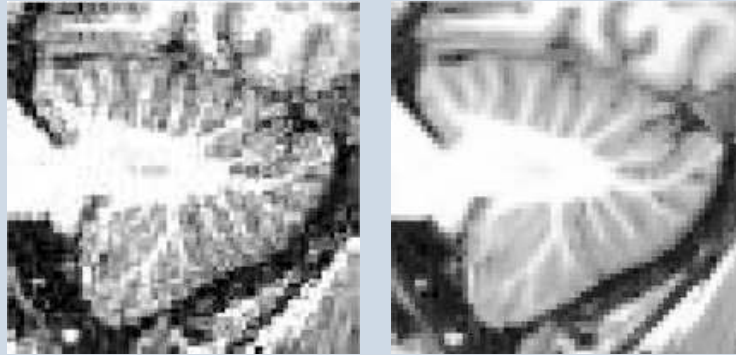


non-local search region N



Related work: application of internal similarity

- Image denoising: non-local means
- Object detection: self-similarities



- P. Coupe, IEEE Trans Med Imag 2008



- E. Shechtman: CVPR 2007

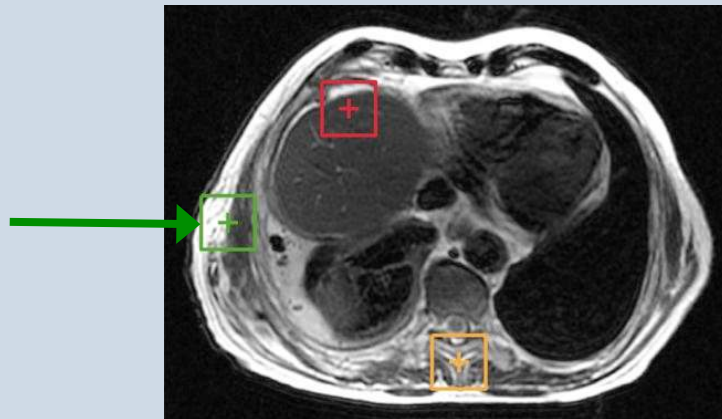
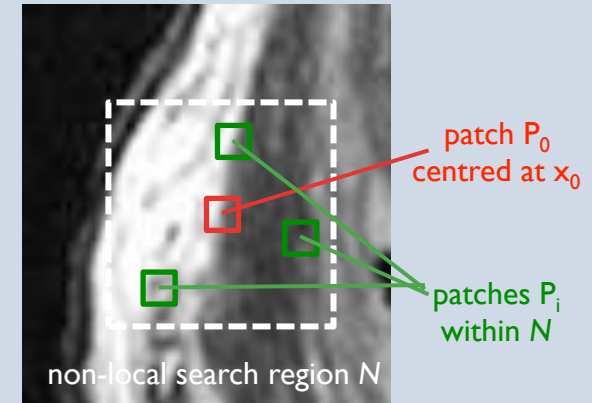
Our contribution: Similarity metric for deformable multi-modal registration

Internal similarity: non-local weights

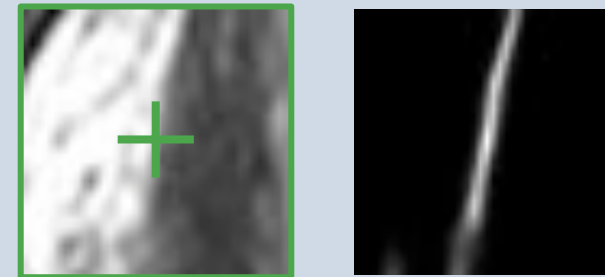
- Uses same principle as non-local means filtering
- (A. Buades, CVPR 2005)
- spatial weight for \mathbf{x}_0 is given by distance function between patches P_0 and P_i (within same image)

$$w(\mathbf{x}_0, \mathbf{x}_i) = \exp(-\text{SSD}(P_0, P_i)/\sigma^2)$$

- non-local weights for 3 voxels in MRI slice
- weights are a good measure of shape



tissue boundary



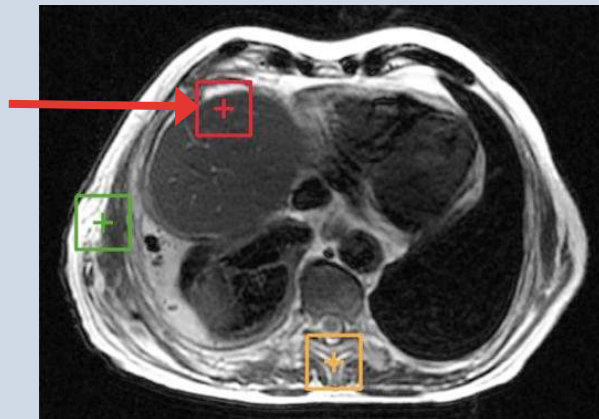
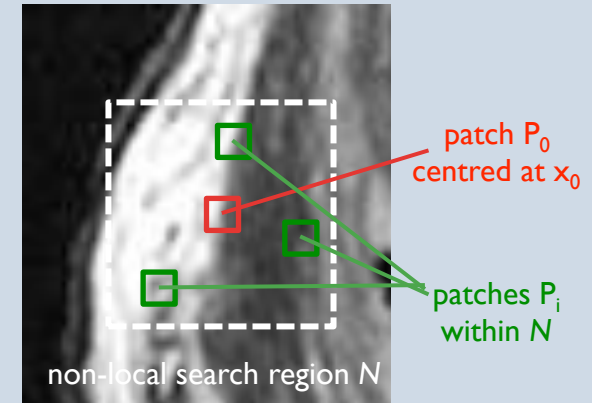
search region N weight $w(\mathbf{x}_0, \mathbf{x}_i)$

Internal similarity: non-local weights

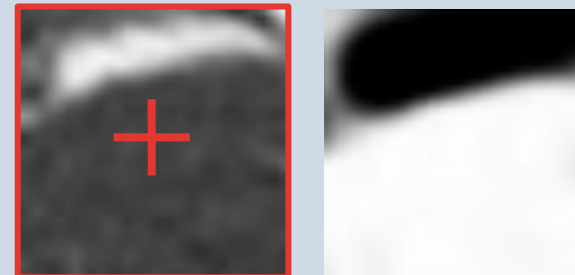
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homogeneous region



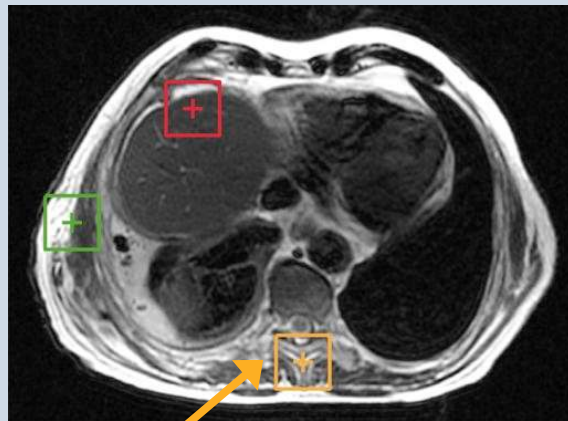
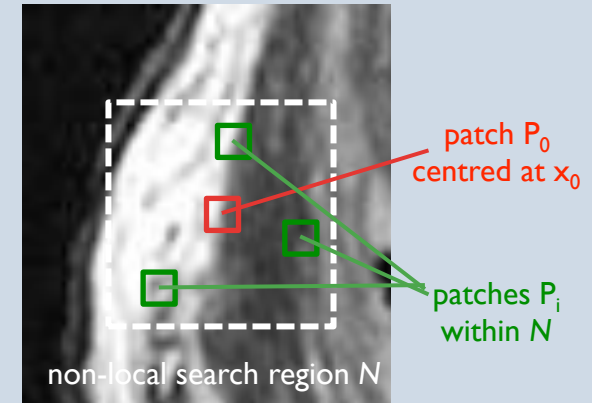
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corner point

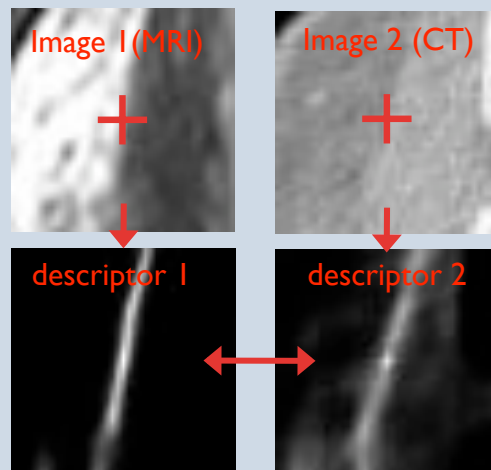


search region N weight $w(\mathbf{x}_0, \mathbf{x}_i)$

Shape descriptor as similarity metric

- Calculate weights in both modalities for each voxel based on patch similarities
- Similarity is defined as cross-correlation between two weights w_1 and w_2 :

$$\text{NLSD}(\mathbf{x}_0) = \text{NCC}(w^1(\mathbf{x}_0, \mathbf{x}_i), w^2(\mathbf{x}_0, \mathbf{x}_i))$$



- weights are almost independent of contrast in different modalities
- using cross-correlation allows to compare regions with different local noise magnitude
 - global noise variance σ is estimate from data
- fast implementation using convolution filter

Comparison to mutual information

- Popular similarity metric *Viola et al., IJCV 1997* and *Maes et al., TMI 1997*
- Measures the mutual dependency of two image intensity distributions
- Difficult local estimation (MI is global measure)
 - Local normalized mutual information (based on global histogram)

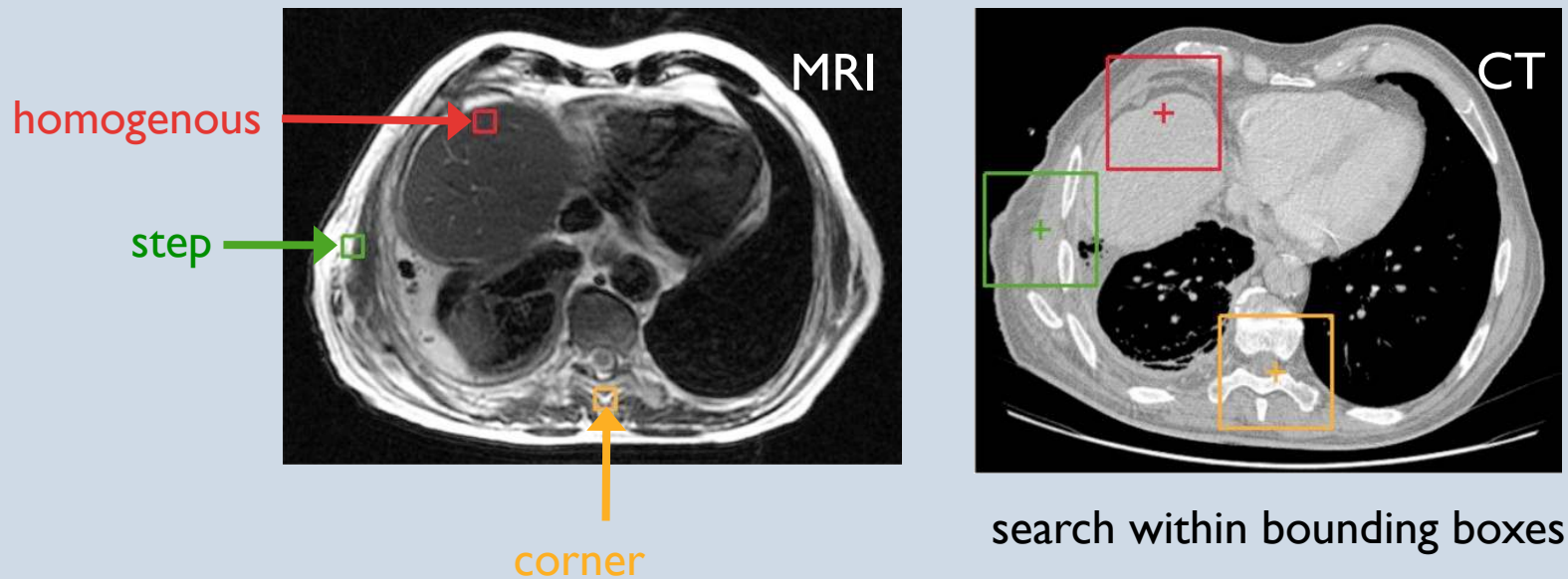
$$\text{LNMI}(\mathbf{x}) = \log \left(\frac{p_{12}(I_1(\mathbf{x}), I_2(\mathbf{x}))}{p_1(I_1(\mathbf{x})) \cdot p_2(I_2(\mathbf{x}))} \right) \frac{1}{\int_{\mathbf{x}} p_1(I_1(\mathbf{x})) \log(p_1(I_1(\mathbf{x}))) d\mathbf{x}}$$

Hermosillo et al., IJCV 2002 and *Rogelj et al., CVIU 2003*

- Converges to local minima if initialisation is far away
- Sensitive to varying contrast (bias field) and noise

Similarity maps of both metrics

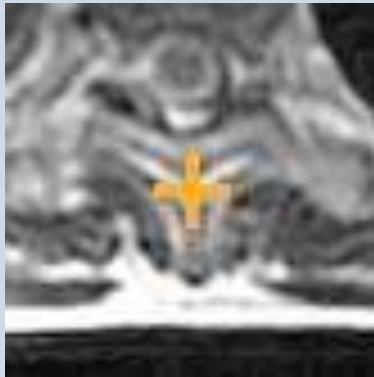
- Comparison of similarity metrics for three different image features in MRI (**step**, **homogenous**, **corner**) over large search region in CT slice



Similarity maps of both metrics

- Feature: Corners / point feature ■

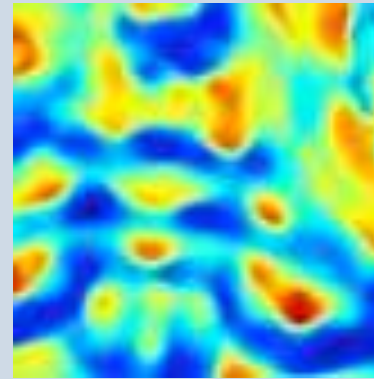
Point feature in
MRI



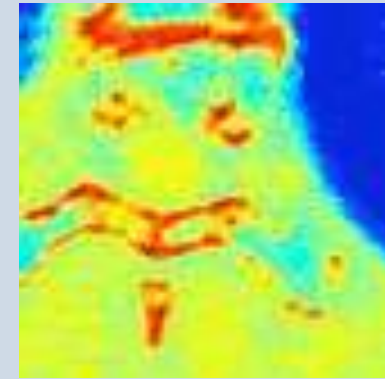
CT search
region



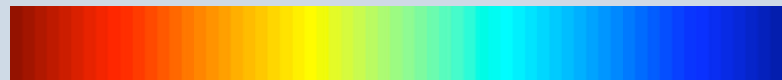
NLSD
(non-local shape
descriptor)



LNMI
(local normalized
mutual information)



- Both metrics show local maxima at correct location

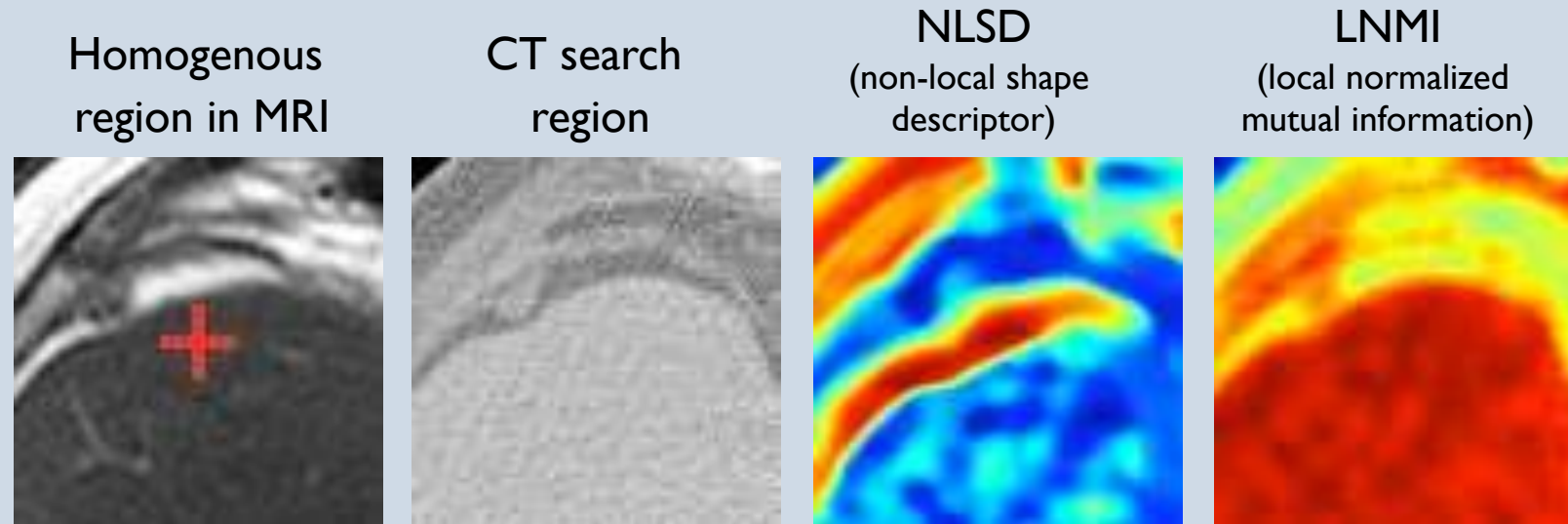


high local similarity

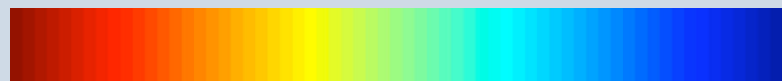
low local similarity

Similarity maps of both metrics

- Feature: Image intensities / homogenous region ■



- The maximum for NLSD in homogenous area is more informative than for mutual information



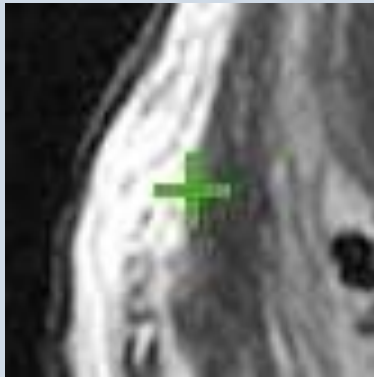
high local similarity

low local similarity

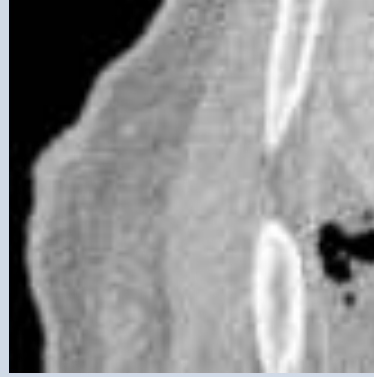
Similarity maps of both metrics

- Feature: Tissue boundaries / step feature ■

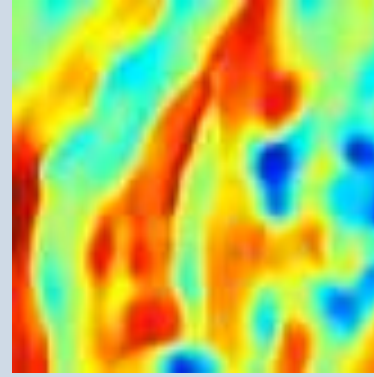
Tissue boundary
in MRI



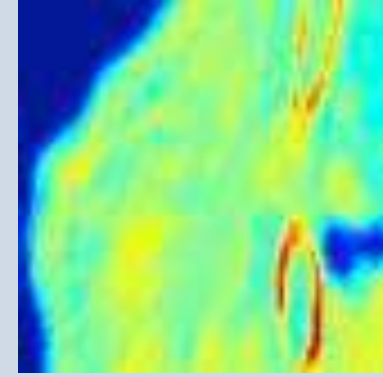
CT search
region



NLSD
(non-local shape
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LNMI
(local normalized
mutual information)



- NLSD distinguishes step features clearly better than LNMI

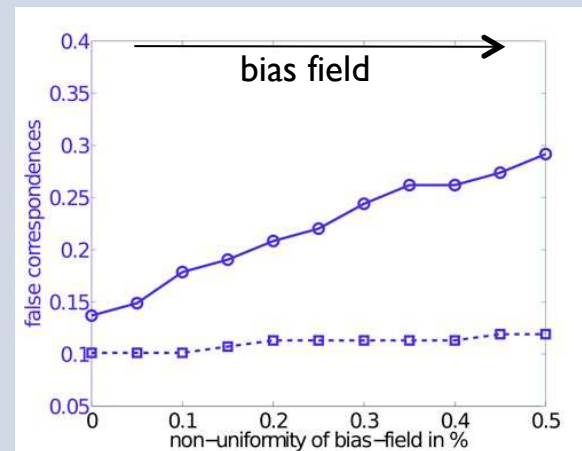
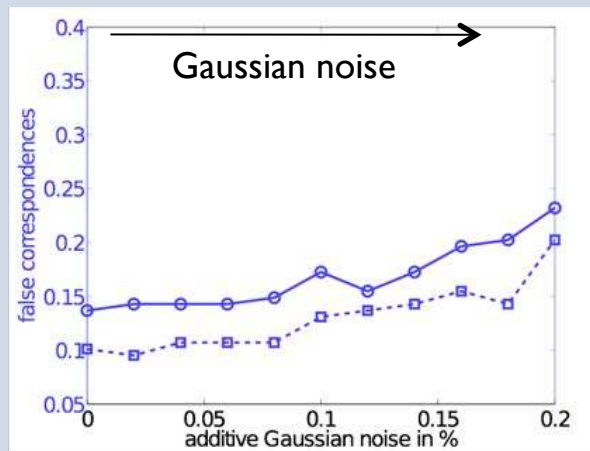


high local similarity

low local similarity

Saliency and robustness of correspondences

- 2D multimodal test images (intrinsically aligned)
 - two colour channels of cryosection (Visible Human)
 - 220 automatic landmarks (Harris corner detector)
- False correspondences (robustness)

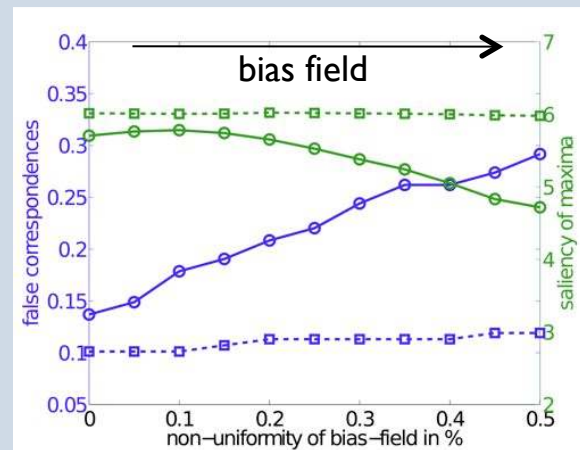
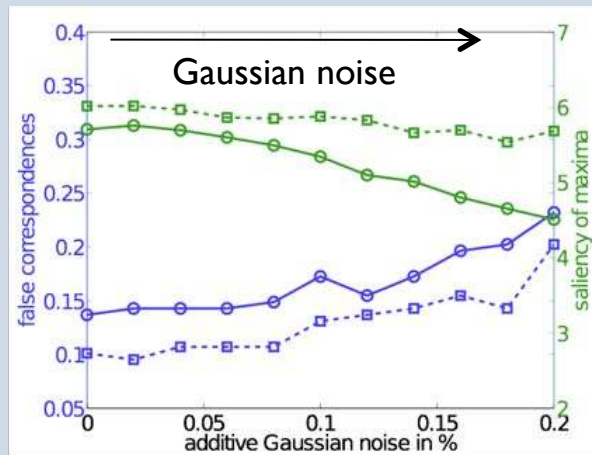


— ○ local normalised mutual information (LNMI)
 - - - □ non-local shape descriptor (NLSD)

- NLSD shows better robustness
 - with increasing noise and bias field

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- Saliency of maxima (discrimination)

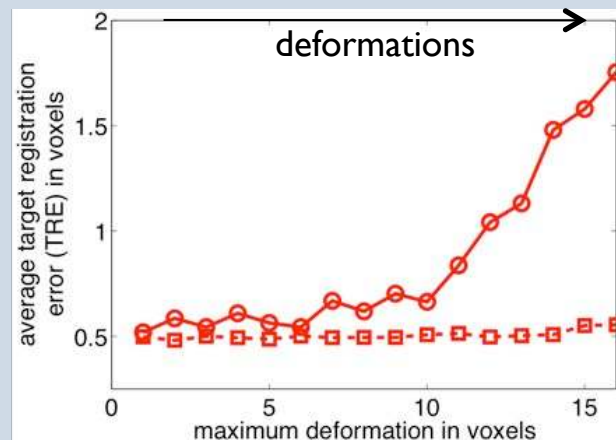
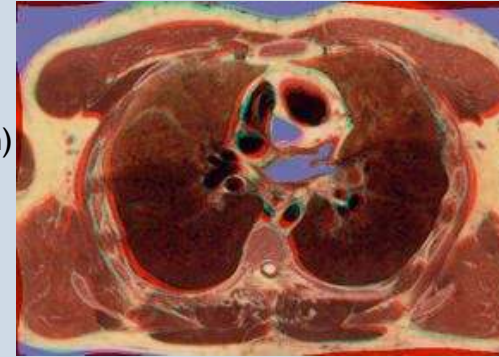


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- NLSD shows better robustness and discrimination
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Saliency and robustness of correspondences

- 2D multimodal test images (intrinsically aligned)
 - two colour channels of cryosection (Visible Human)
 - Synthetic B-Spline deformation of one channel
- **Non-rigid deformations** (average target error)



— ○ local normalised mutual information (LNMI)
- - - □ non-local shape descriptor (NLSD)

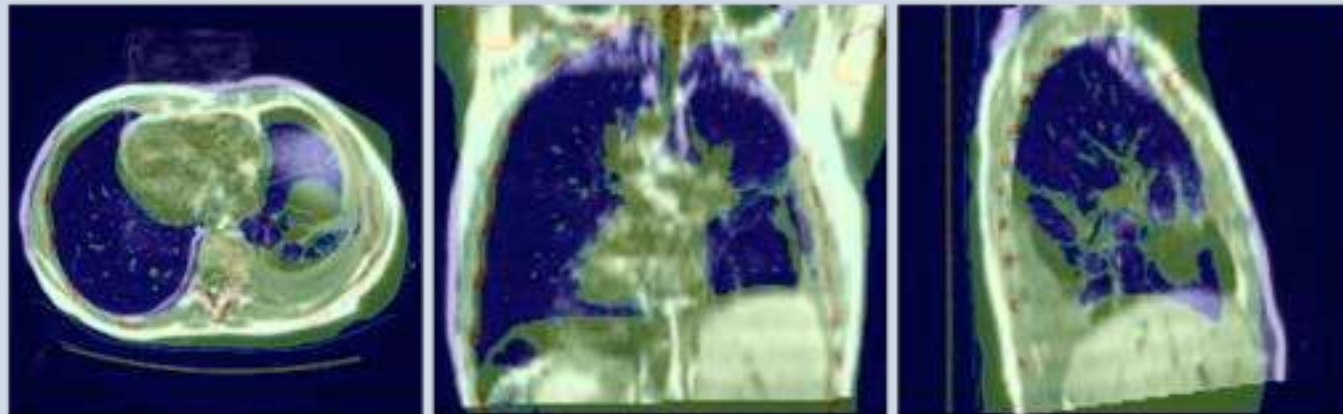
- Registration accuracy is higher for NLSD
 - for larger non-rigid deformations

Application to clinical 3D CT/MRI fusion

- Diagnostic scans (CT and MRI) for patients with lung disease
- Challenges for registration
 - large deformations (collapsed lungs)
 - low z-resolution (up to 8 mm) in MRI
 - bias field in MRI
 - lower soft tissue contrast in CT
- Example of registration outcome
- Deformable registration framework
 - initial rigid alignment
 - diffusion regularized Gauss-Newton optimization
 - multi-resolution scheme (3 levels)
 - more details: please see poster

rigidly aligned

CT colour
MRI gray

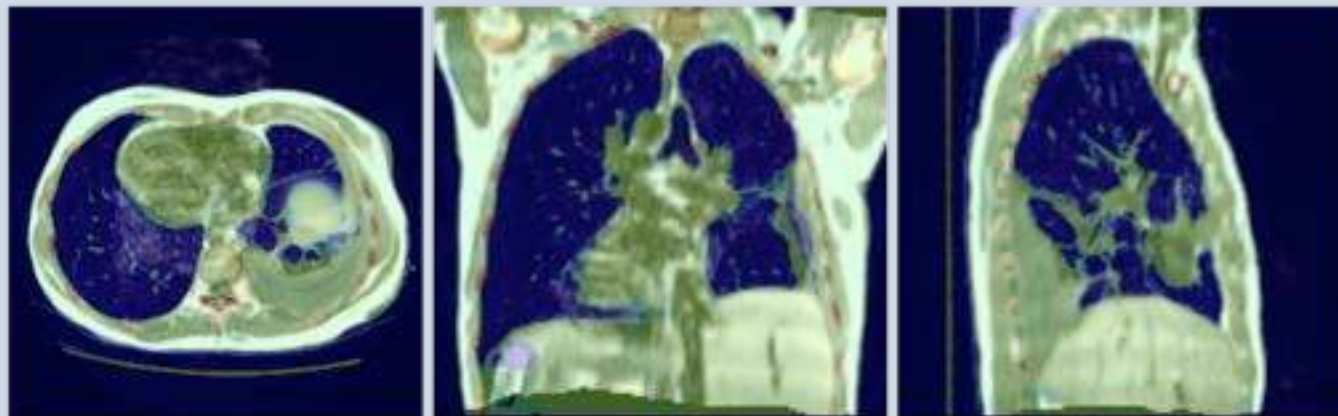


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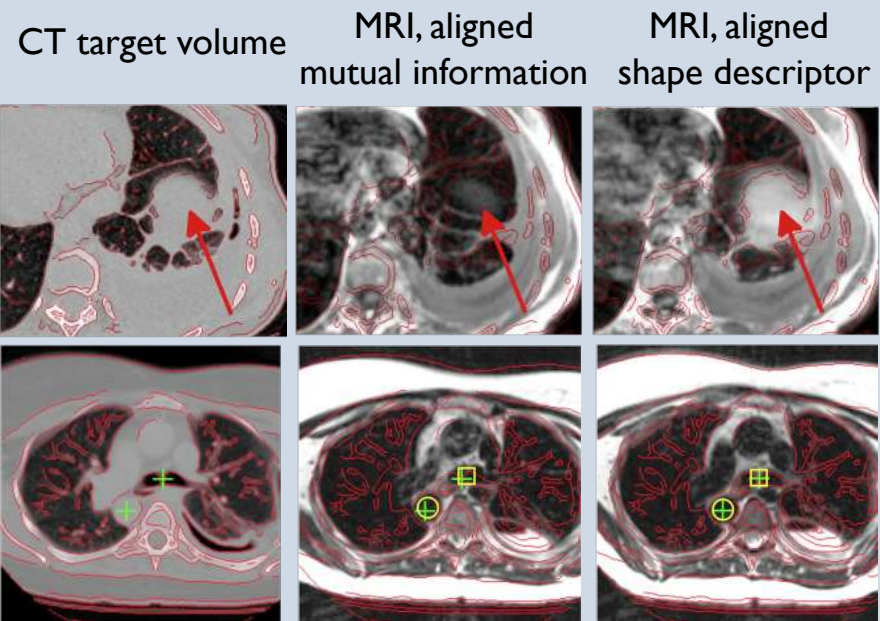
nonrigidly aligned
using NLSD

CT colour
MRI gray



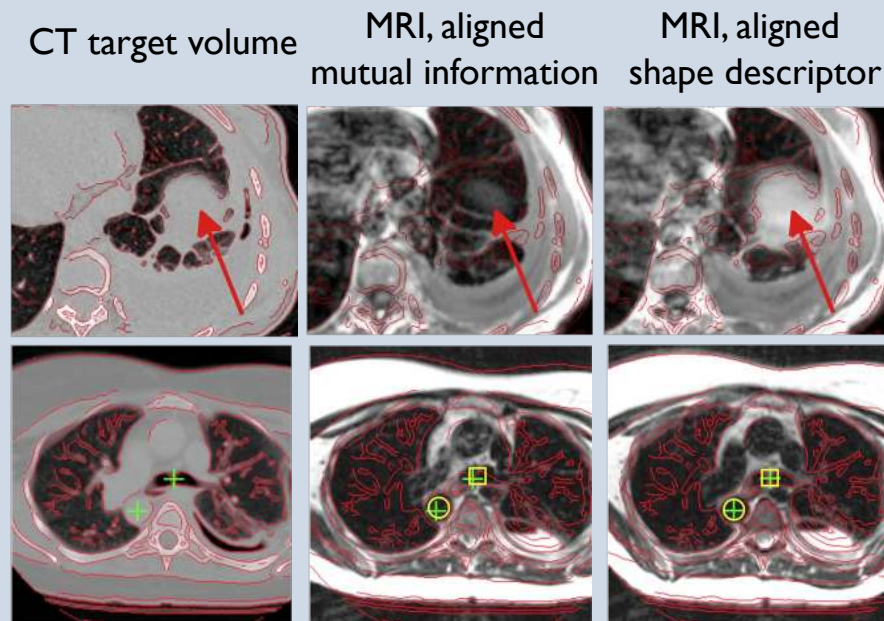
Landmark results for 3D CT/MRI fusion

- Comparison of gold standard with registration outcome (examples)
 - CT contours shown for guidance (red)
 - top row: descending aorta ° carina □
 - bottom row: dome of the diaphragm →

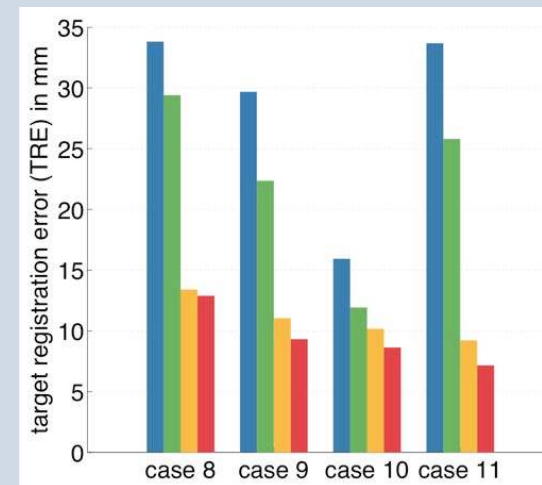


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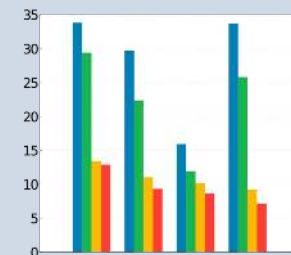
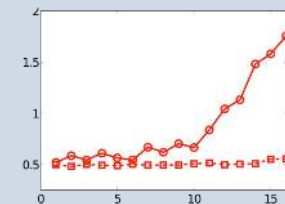
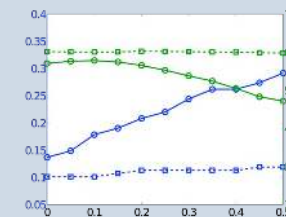
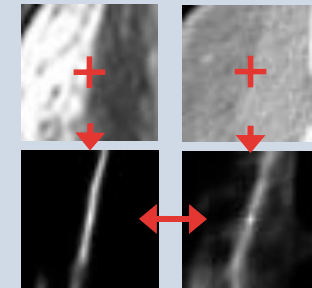
- Manually selected 15 corresponding anatomical landmarks (per case)
 - Evaluation of target registration error
 - Difficult selection of landmarks for expert



- before registration
- mutual information
- rigid registration
- shape descriptor

Conclusion

- Non-local shape descriptor
 - based on intrinsic similarity of image patches
 - sensitive to several image features
 - intensities, gradients, points
- Advantages compared to mutual information
 - robust against: noise, varying contrast, bias fields ..
 - reduces number of (false) local minima
 - can recover larger deformations
 - lower landmark error for 3D CT/MRI fusion



- Thank you for your attention!
- Acknowledgements
 - We would like to thank EPSRC and Cancer Research UK for funding this work within the Oxford Cancer Imaging Centre.
 - JAS also acknowledges funding from EPSRC EP/H050892/1.
 - We thank the MICCAI society for supporting us with a Student Travel Award.
- Poster presentation
 - P8 – 102 – T (Registration I)
 - Tuesday 13:15 – 14:30