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NONNEGATIVE SOLUTIONS TO A SEMILINEAR DIRICHLET
PROBLEM IN A BALL ARE POSITIVE AND RADially SYMMETRIC*

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Abstract

We prove that nonnegative solutions to a semilinear Dirichlet problem in a ball are positive, and hence radially symmetric. In particular this answers a question in [3] where positive solutions were proven to be radially symmetric. In section 4 we provide a sufficient condition on the geometry of the domain which ensures that nonnegative solutions are positive in the interior.

1. INTRODUCTION

Let $f: \mathbb{R} \rightarrow \mathbb{R}$ be a smooth function, Ω a smooth bounded region in \mathbb{R}^n , and $u: \Omega \rightarrow \mathbb{R}$ a classical solution to

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$$-\Delta u = f(u) \quad \text{in } \Omega \quad (1.1)$$

$$u = 0 \quad \text{on } \partial\Omega. \quad (1.2)$$

In Theorem 1 of [G-N-N] it was proven that if Ω is a ball and $u > 0$ in Ω then u is radially symmetric. Moreover (see [3], pp. 220), it was observed that if $f(0) \geq 0$ and $u \geq 0$, $u \not\equiv 0$ in Ω then $u > 0$ in Ω , and hence radially symmetric. Further also in [3] an example of a linear problem where $f(0) < 0$, and a nonnegative solution u with interior zeros is given. In this example $n = 1$. Also see [1] for examples of nonlinear problems with $f(0) < 0$ and nonnegative solutions with interior zeros. Here we prove that these phenomena happen only in dimension $n = 1$. Indeed, here we prove:

Theorem A: If Ω is a ball in \mathbb{R}^n with $n > 1$, u is a nonnegative solution of (1.1) and $u \not\equiv 0$ in Ω then $u > 0$ in Ω and hence radially symmetric.

Our motivation for this study was the observation in [2] that when $f(0) < 0$, if u^- is radially symmetric, nonnegative, and $n > 1$, then $u > 0$ in Ω . Our proofs are based on the maximum principle, and reflexion arguments introduced in [3]. Finally, since Theorem A was established for the case $f(0) \geq 0$ in [3], here we assume throughout that

$$f(0) < 0. \quad (1.3)$$

2. PRELIMINARY LEMMAS AND THEIR PROOFS

First we recall some notations following [3]. Let

$$T_t := \{x \in \mathbb{R}^n ; x \cdot e = t\},$$

$$\Sigma_t := \{x \in \Omega ; x \cdot e > t\}$$

where $e = (1, 0, \dots, 0)$, and \cdot denotes the usual inner product in \mathbb{R}^n and let Σ_t' be the reflexion of Σ_t across T_t . For $x \in \mathbb{R}^n$ we will denote by x^t the reflexion of x across T_t . Also u_i will denote the partial derivative of u with respect to x_i , similarly u_{ij} . Further for $x \in \partial\Omega$ we will denote by $\nu(x) = (\nu_1(x), \dots, \nu_n(x))$ the outward unit normal and by the ϵ -neighbourhood theorem there exists $\gamma > 0$ such that for every $0 < \epsilon < \gamma$, we can define (see [4])

$$\begin{aligned} D_\epsilon &= \{x \in \Omega ; \text{dist.}(x, \partial\Omega) < \epsilon\} \\ &= \{x + t\nu(x) ; x \in \partial\Omega \text{ and } t \in (-\epsilon, 0)\}. \end{aligned}$$

We now state:

Lemma P: Let $u: \bar{\Omega} \rightarrow \mathbb{R}$ be a nonnegative solution to (1.1)-(1.3). If
for some $t \in (0, 1)$ we have

$$u_1(x) \leq 0 \quad \forall x \in \Sigma_t, \quad (2.1)$$

$$u(x) \leq u(x^t) \quad \forall x \in \Sigma_t, \quad (2.2)$$

and

$$\bar{u}(\alpha) < u(\alpha^t), \text{ for some } \alpha \in \Sigma_t, \quad (2.3)$$

then

$$u(x) < u(x^t) \quad \forall x \in \Sigma_t, \quad (2.4)$$

and

$$u_1(x) < 0 \quad \forall x \in T_t \cap \Omega. \quad (2.5)$$

Proof: see proof of Lemma 2.2 in [G-N-N] and observe that one requires that only $u \geq 0$.

Next we state and prove:

Lemma Q: Let $u: \bar{\Omega} \rightarrow \mathbb{R}$ be a solution to (1.1)-(1.3) and $z \in \partial\Omega$. If
 $\nu_1(z) > 0$ and there exists $\epsilon > 0$ such that $u(x) \geq 0$ for $x \in \bar{\Omega}$ with

$\|x - z\| < \epsilon$, then there exists $\epsilon_1 \in (0, \epsilon)$ such that $u_1(x) < 0 \forall x \in \Omega$ with $\|x - z\| < \epsilon_1$.

Proof: Since $v_1(z) > 0$, without loss of generality we can assume that $v_1(x) > 0 \forall x \in \partial\Omega$ with $\|x - z\| < \epsilon$. This and the assumption that $u \geq 0$ on $\|x - z\| < \epsilon$ imply that

$$u_1(x) \leq 0 \quad \forall x \in \partial\Omega \text{ with } \|x - z\| < \epsilon. \quad (2.6)$$

If $u_1(z) < 0$ then the existence of ϵ_1 follows from the continuity of u_1 . On the other hand if $u_1(z) = 0$, then $\nabla u(z) = 0$. Now for $k \in \{2, \dots, n\}$ we let $y = (-v_k(z), 0, \dots, 0, v_1(z), 0, \dots, 0)$. Since y is tangent to $\partial\Omega$ at z we can find $\phi: (-1, 1) \rightarrow \partial\Omega$ such that $\phi(0) = z$ and $\phi'(0) = y$. Since now $\nabla u(z) = 0$ we see that $u_1(\phi(t))_-$ has a local maximum at $t = 0$. In particular,

$$\begin{aligned} 0 &= \frac{d}{dt} (u_1(\phi(t))) \Big|_{t=0} = \nabla u_1(z) \cdot y \\ &= u_{11}(z)(-v_k(z)) + u_{1k}(z)v_1(z). \end{aligned} \quad (2.7)$$

On the other hand, because $u(\phi(t)) \equiv 0$, computing the second derivative of u with respect to t at $t = 0$, we have

$$\begin{aligned} 0 &= \sum_{i,j=1}^n u_{ij}(z)\phi_i'(0)\phi_j'(0) + \nabla u(z) \cdot \phi''(0) \\ &= u_{11}(z)(v_k(z))^2 - 2u_{1k}v_1(z)v_k(z) + u_{kk}(z)(v_1(z))^2, \end{aligned} \quad (2.8)$$

where the ϕ_k 's are the components of ϕ . Now from (2.7) and (2.8) we have for $k = 2, \dots, n$

$$u_{kk}(z)(v_1(z))^2 = u_{11}(z)(v_k(z))^2, \quad (2.9)$$

and since $v_1(z) > 0$ we obtain,

$$\begin{aligned} -f(0) &= \Delta u(z) \\ &= u_{11}(z) \left\{ 1 + \sum_{k=2}^n (v_k(z)/v_1(z))^2 \right\}. \end{aligned} \quad (2.10)$$

But $f(0) < 0$. Thus by (2.10) and the continuity of u_{11} we see that there exists $\varepsilon_1 \in (0, \varepsilon)$ such that $u_{11}(x) > 0$ for $\|x-z\| < \varepsilon_1$ with $x \in \bar{\Omega}$. Now since $v_1(x) > 0 \forall x \in \partial\Omega$ with $\|x-z\| < \varepsilon_1$, we can further assume that if $\|x-z\| < \varepsilon_1$ with $x \in \Omega$, then there exists $b(x) \in \partial\Omega$ of the form $b(x) = x + \delta e$ ($\delta > 0$) with $x + se \in \Omega \forall s \in (0, \delta)$. Hence

$$0 > u_1(b(x)) - \int_0^\delta u_{11}(x + se) ds = u_1(x), \quad (2.11)$$

and Lemma Q is proven.

Remark: Lemma Q extends Lemma 2.1 of [3] in that we do not assume $u > 0$ in Ω .

Corollary R: If u is a solution to (1.1)-(1.3) and $u \geq 0$ on a neighbourhood of $\partial\Omega$, then there exists $\mu > 0$ such that $u > 0$ on D_μ .

Proof: Let $Z \in \partial\Omega$. Since Δ is invariant under rotations and translations, without loss of generality, we can assume that $Z = v(Z) = e$. By Lemma Q there exists $\epsilon_1 > 0$ such that $u(x) > 0$ if $x \in \Omega$ and $\|x-Z\| < \epsilon_1(Z)$. Since $\partial\Omega$ is compact we can find x_1, x_2, \dots, x_m such that $x_i \in \partial\Omega$ and such that

$$W = B(x_1, \epsilon(x_1)) \cup B(x_2, \epsilon(x_2)) \cup \dots \cup B(x_m, \epsilon(x_m)) \supset \partial\Omega.$$

Since W is open in \mathbb{R}^n and $\partial\Omega$ is closed, there exists $\mu > 0$ such that $\{x \in \mathbb{R}^n; d(x, \partial\Omega) < \mu\} \subset W$. In particular, if $x \in \Omega$ and $d(x, \partial\Omega) < \mu$ we have $u(x) > 0$.

3. PROOF OF THEOREM A

Suppose now there exists $y \in B$ such that $u(y) = 0$. By Corollary R we have $\|y\| \leq 1 - \mu$. Without loss of generality, we can assume y to have maximal norm. Further, because Δ is invariant under rotations, we can assume that

$$y = (\delta, 0, \dots, 0) \text{ with } \delta \in [0, 1 - \mu]. \quad (3.1)$$

Now since $u(y) = 0$, by Corollary R there exists $t^* \in ((1/2), 1)$ for which (2.4) does not hold. Let ζ be defined by

$$\zeta = \inf\{s \in [0, 1]; (2.1)-(2.3) \text{ hold on } \Sigma_t \forall t \in (s, 1]\}. \quad (3.2)$$

By Lemma Q there exists $k \geq 2$ such that

$$\zeta \leq 1 - (\epsilon_1/k). \quad (3.3)$$

Also since $\delta \geq 0$ we see that (using Corollary R)

$$\zeta \geq 1/2. \quad (3.4)$$

By the continuity of u and u_1 we see that (2.1) and (2.2) hold on Σ_ζ . If (2.3) does not hold on Σ_ζ , then by Lemma P we have $u(x) = u(x^\zeta)$ $\forall x \in \Sigma_\zeta$. In particular, by the continuity of u we have

$$u(x^\zeta) = 0 \quad \text{if} \quad \|x\| = 1 \quad (3.5)$$

Thus, setting $\sigma = \mu/m$ where μ is as in Corollary R and $m > 2\zeta$ is large enough so that $\zeta + \sigma < 1$, we obtain,

$$\begin{aligned} -0 &= u(\zeta+\sigma, \sqrt{1-(\zeta+\sigma)^2}, 0, \dots, 0) \\ &= u(\zeta-\sigma, \sqrt{1-(\zeta+\sigma)^2}, 0, \dots, 0). \end{aligned} \quad (3.6)$$

But

$$\begin{aligned} \left\| (\zeta-\sigma, \sqrt{1-(\zeta+\sigma)^2}, 0, \dots, 0) \right\|^2 &= (\zeta-\sigma)^2 + 1 - (\zeta+\sigma)^2 \\ &= 1 - 2\zeta\sigma \\ &> 1 - m\sigma \\ &= 1 - \mu, \end{aligned}$$

hence (3.6) contradicts Corollary R. Thus (2.3) hold on Σ_ζ .

Now we claim that:

there exists $\eta > 0$ such that if $\|x\| < 1$ and $x.e > \zeta - \eta$

then $u_1(x) < 0$. (3.7)

If not there exists a sequence $\{x_n\}$ with $\|x_n\| < 1$, $\{x_n.e\}$ converging

to ζ , and $u_1(x_n) \geq 0$. Thus, without loss of generality, we can assume that $\{x_n\}$ converges to $z \in T_\zeta \cap \bar{B}$. If $z \in T_\zeta \cap B$ then by (2.5) we have

$$0 > u_1(z) = \lim u_1(x_n) \geq 0, \quad (3.8)$$

which is a contradiction. On the other hand if $z \in T_\zeta \cap \partial B$, by Lemma Q for n large $u_1(x_n) < 0$ which contradicts the definition of $\{x_n\}$, and (3.7) is proven.

Next we show that:

$$\text{there exists } \gamma \in (0, \eta) \text{ such that if } t \in (\zeta - \gamma, \zeta), x \in \Sigma_t \text{ then} \\ u(x^t) \geq u(x). \quad (3.9)$$

In fact, if not there exists a sequence (t_n, x_n) with $t_n \rightarrow \zeta$, $x_n \in \Sigma_{t_n}$ such that $u(x_n^{t_n}) < u(x_n)$. Without loss of generality we can assume that $\{x_n\}$ converges to z . Since $t_n \rightarrow \zeta$ we see that $z \in \bar{\Sigma}_\zeta$. If $z \in \Sigma_\zeta$ we have

$$u(z^\zeta) = \lim u(x_n^{t_n}) \leq \lim u(x_n) = u(z) \quad (3.10)$$

contradicting that (2.4) holds on Σ_ζ . Thus either $\|z\| = 1$ or $z \in T_\zeta \cap B$. If $z \in T_\zeta \cap B$ then $x_n^{t_n} \rightarrow z$. By the mean value theorem there exists a sequence $\{y_n\}$ with y_n in the segment joining $x_n^{t_n}$ with x_n such that $u_1(y_n) \geq 0$. Since for n large $y_n \cdot e > \zeta - \eta$, by (3.7) we have a contradiction. Thus $\|z\| = 1$ and $z \cdot e > \zeta$. Now for $x \in \bar{\Sigma}_\zeta$ we define $w(x) = u(x^\zeta) - u(x)$. Since (2.4) hold on Σ_ζ we have $w > 0$ on Σ_ζ . Since, also by the continuity of u we have

$$u(z^t) = \lim u(x_n^{t_n}) \leq \lim u(x_n) = u(z) = 0, \quad (3.11)$$

and hence $w(z) = 0$. Thus by Hopf's maximum principle (see Lemma H in [G-N-N]) we have $0 > w_1(z)$. Since $u \geq 0$, by (3.11) we have $u_1(z^\zeta) = 0$. Further since $u \geq 0$, $u_1(z) \leq 0$. Hence

$$0 > w_1(z) = -u_1(z^\zeta) - u_1(z) \geq 0. \quad (3.12)$$

This contradiction proves (3.9), and we have shown that for some $\theta < \zeta$, (2.2) holds for all $t \in [\theta, \zeta)$. By taking $\theta \in (\zeta - \eta, \zeta)$, from (3.7) we see that if $t \in [\theta, \zeta)$ then (2.1) as well as (2.3) hold. Hence this contradicts the definition of ζ . Thus there does not exist $y \in B$ such that $u(y) = 0$. That is, every nonnegative solution to (1.1)-(1.3) is positive in B , and by Theorem 1 of [3] it is also radially symmetric, which proves Theorem A.

4. EXTENSIONS

Doublechecking the proof of Theorem A it is readily seen that nonnegative solutions to (1.1)-(1.2) are actually positive in the interior if Ω satisfies the following geometrical condition.

For each $y \in \Omega$ there exists $x \in \partial\Omega$ such that (4.1)

- (a) $\{z; (z - x) \cdot v(x) > 0\} \cap \Omega = \emptyset$,
- (b) For some $t < 0$, $y \in \Sigma_{t,x} \cup \Sigma'_{t,x}$, where $\Sigma_{t,x}$ is the connected component of $\{z \in \Omega; (z - x) \cdot v(x) > t\}$ containing x in its closure and $\Sigma'_{t,x}$ the reflexion of $\Sigma_{t,x}$ across the plane $\{z; (z - x) \cdot v(x) = t\}$,
- (c) for all $z \in \partial\Omega \cap \partial\Sigma_{t,x}$ $v(z) \cdot v(x) > 0$, and $\Sigma_{t,x} \cup \Sigma'_{t,x} \subset \Omega$.

Examples of regions satisfying (4.1) include balls, the region between two balls, and the union of two balls. The condition that Ω be bounded is necessary. Indeed, if $\Omega = \{(x,y); 0 < x < 1, y \in \mathbb{R}\}$, v is a nonnegative solution to $-v'' = f(v)$, $v(0) = v(1) = 0$ with zeroes in

$(0,1)$ (see [1], [2], [3]) then defining $u(x,y) = v(x)$ we have a solution to (1.1)-(1.2) with interior zeroes.

Finally, as noted in the introduction, examples of non-negative solutions in bounded regions with interior zeroes can be found in [1] and [3].

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