

## NOTES ON ALMOST ISOMETRIES

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### § 0. Introduction.

Chern and Hsiung [1] proved a theorem stating that a volume-preserving almost isometry between two compact submanifolds in euclidean space satisfying certain conditions is an isometry.

The purpose of the present paper is to give a different approach to this subject, which seems to be somewhat related to a paper of Gardner [3].

### § 1. Almost isometries.

Let  $M$  be an  $n$ -dimensional Riemannian manifold covered by a system of coordinate neighborhoods  $\{U; x^h\}$  where here and throughout the paper the indices  $h, i, j, k, \dots$  run over the range  $\{1, 2, 3, \dots, n\}$ . We denote by  $g_{ji}$ ,  $\{^h_{j i}\}$ ,  $\nabla_i$ ,  $K_{kji}{}^h$  and  $K_{ji}$  the components of the metric tensor, the Christoffel symbols formed with  $g_{ji}$ , the operator of covariant differentiation with respect to the Christoffel symbols, the curvature tensor and the Ricci tensor respectively.

A transformation is said to be affine when it does not change the Levi-Civita connection defined by the Christoffel symbols. In order that an infinitesimal transformation  $v^h$  be an affine transformation, it is necessary and sufficient that

$$(1.1) \quad \mathcal{L}_v \left\{ \begin{matrix} h \\ j \ i \end{matrix} \right\} = \nabla_j \nabla_i v^h + K_{kji}{}^h v^k = 0,$$

where  $\mathcal{L}_v$  denotes the Lie derivative with respect to the infinitesimal transformation  $v^h$ , [7].

An infinitesimal transformation  $v^h$  satisfying

$$(1.2) \quad g^{ji} \left( \mathcal{L}_v \left\{ \begin{matrix} h \\ j \ i \end{matrix} \right\} \right) = g^{ji} \nabla_j \nabla_i v^h + K_i{}^h v^i = 0$$

is called an infinitesimal almost isometry, where  $K_i{}^h = K_{ii}{}^h$ . Thus an affine transformation is an almost isometry.

A transformation is said to be isometric when it does not change the Riemannian metric. In order that an infinitesimal transformation  $v^h$  be an isometry, it is necessary and sufficient that

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$$(1.3) \quad \mathcal{L}_v g_{ji} = \nabla_j v_i + \nabla_i v_j = 0,$$

where  $v_i = g_{ih} v^h$ . Since (1.3) implies (1.1) and consequently (1.2), an isometry is an almost isometry.

One of the present authors proved in [6, 8] that a necessary and sufficient condition for an infinitesimal transformation  $v^h$  in a compact Riemannian manifold  $M$  to be an isometry is that

$$(1.4) \quad g^{ji} \nabla_j \nabla_i v^h + K_i^h v^i = 0 \quad \text{and} \quad \nabla_i v^i = 0,$$

or that the infinitesimal transformation  $v^h$  defines an almost isometry and preserves the volume.

Since (1.1) implies (1.4), we see that an infinitesimal affine transformation in a compact Riemannian manifold is an isometry.

Now consider a transformation in the Riemannian manifold  $M$  and denote by  $\bar{g}_{ji}$  the transformed metric and by  $\{\bar{h}_{ji}\}$  the transformed Christoffel symbols. We put

$$(1.5) \quad \left\{ \begin{matrix} \bar{h} \\ j \ i \end{matrix} \right\} = \left\{ \begin{matrix} h \\ j \ i \end{matrix} \right\} + U_{ji}^h,$$

$U_{ji}^h$  being components of a tensor field of type (1, 2).

If

$$(1.6) \quad U_{ji}^h = 0,$$

then the transformation is affine, if

$$(1.7) \quad g^{ji} U_{ji}^h = 0$$

then the transformation is an almost isometry with respect to  $g_{ji}$ , if

$$(1.8) \quad \bar{g}^{ji} U_{ji}^h = 0,$$

then the transformation is an almost isometry with respect to  $\bar{g}_{ji}$  and if

$$(1.9) \quad \det(\bar{g}_{ji}) = \det(g_{ji})$$

$\det(\ )$  denoting the determinant formed with elements between braces, the transformation is volume-preserving. In this case we have

$$(1.10) \quad U_{ji}^t = 0.$$

If

$$(1.11) \quad \bar{g}_{ji} = g_{ji},$$

the transformation is an isometry.

Denoting by  $\bar{V}_i$  the operator of covariant differentiation with respect to  $\{\bar{j}^h_i\}$ , we have

$$\begin{aligned} 0 &= \bar{V}_k \bar{g}_{ji} = \partial_k \bar{g}_{ji} - \left\{ \begin{matrix} t \\ k \ j \end{matrix} \right\} \bar{g}_{ti} - \left\{ \begin{matrix} t \\ k \ i \end{matrix} \right\} \bar{g}_{jt} \\ &= \partial_k \bar{g}_{ji} - \left( \left\{ \begin{matrix} t \\ k \ j \end{matrix} \right\} + U_{kj}{}^t \right) \bar{g}_{ti} - \left( \left\{ \begin{matrix} t \\ k \ i \end{matrix} \right\} + U_{ki}{}^t \right) \bar{g}_{jt}, \end{aligned}$$

from which

$$(1.12) \quad \bar{V}_k \bar{g}_{ji} = U_{kj}{}^t \bar{g}_{ti} + U_{ki}{}^t \bar{g}_{jt}.$$

Thus, for an affine transformation, we have

$$(1.13) \quad \bar{V}_k \bar{g}_{ji} = 0,$$

and consequently for an affine transformation in an irreducible Riemannian manifold, we have, by a theorem of Schur,

$$(1.14) \quad \bar{g}_{ji} = c^2 g_{ji},$$

$c$  being a non-zero constant, that is, the transformation is homothetic. If the affine transformation preserves the volume, then we have

$$(1.15) \quad \bar{g}_{ji} = g_{ji},$$

that is, the transformation is isometry. See [4], [5].

It is not yet known whether an almost isometry preserving the volume is an isometry or not.

## §2. Integral formulas.

Let  $E$  be euclidean space of dimension  $m (> n)$  and consider an immersion  $X: M \rightarrow E$ , that is, a differentiable mapping  $X$  of  $M$  into  $E$  such that the induced linear mapping on the tangent space is univalent everywhere. We regard  $X(p)$ ,  $p \in M$  as a position vector in  $E$ . As the Riemannian manifold  $M$  is covered by a system of coordinate neighborhoods  $\{U; x^h\}$ , we can consider the position vector  $X$  as function of  $x^1, x^2, \dots, x^n$ .

We put

$$(2.1) \quad X_i = \partial_i X, \quad \partial_i = \partial / \partial x^i,$$

then  $X_i$  are  $n$  linearly independent vectors tangent to  $X(M)$ . Assuming that  $M$  is oriented and the immersion  $X: M \rightarrow E$  is orientation-preserving, we choose  $m-n$

mutually orthogonal unit normals  $C_x$  to  $X(M)$  in such a way that  $X_1, \dots, X_n, C_{n+1}, \dots, C_m$  give the positive orientation of  $E$ , where here and throughout the paper the indices  $x, y, z$  run over the range  $\{n+1, \dots, m\}$ .

Now the components of the metric tensor are given by

$$(2.2) \quad g_{ji} = X_j \cdot X_i,$$

the dot denoting the inner product of vectors in  $E$ , and the equations of Gauss are written as

$$(2.3) \quad \nabla_j X_i = \partial_j X_i - \left\{ \begin{matrix} h \\ j \ i \end{matrix} \right\} X_h = h_{jix} C_x,$$

where  $h_{jix}$  are components of the second fundamental tensors with respect to the normals  $C_x$ . The equations of Weingarten are written as

$$(2.4) \quad \nabla_j C_x = \partial_j C_x = -h_j^i{}^x X_i + l_{jxy} C_y,$$

where  $h_j^i{}^x = h_{jix} g^{ii}$  and  $l_{jxy}$  are components of the so-called third fundamental tensor.

We now put

$$(2.5) \quad X = X_i z^i + C_x \alpha_x,$$

where  $z^i$  are components of a vector field of  $M$  and  $\alpha_x$  are  $m-n$  functions of  $M$  and compute the covariant derivative of  $X$ . Then we obtain

$$X_j = h_{jix} z^i C_x + X_i \nabla_j z^i + (-h_j^i{}^x X_i + l_{jxy} C_y) \alpha_x + C_x \nabla_j \alpha_x,$$

from which

$$(2.6) \quad \nabla_j z^i = \delta_j^i + h_j^i{}^x \alpha_x$$

and

$$(2.7) \quad \nabla_j \alpha_x = -h_{jix} z^i - l_{jyx} \alpha_y.$$

From (2.6), we obtain

$$(2.8) \quad \nabla_j z_i = g_{ji} + h_{jix} \alpha_x,$$

where  $z_i = g_{ih} z^h$  and

$$(2.9) \quad \nabla_i z^i = n + g^{ji} h_{jix} \alpha_x.$$

Thus, supposing that  $M$  is compact, we obtain the integral formula

$$(2.10) \quad \int_M (n + g^{ji} h_{jix} \alpha_x) dV = 0,$$

$dV$  denoting the volume element.

We now consider the second immersion  $\bar{X}: M \rightarrow E$  and proceed as above, we then obtain similarly

$$(2.11) \quad \bar{V}_j \bar{z}_i = \bar{g}_{ji} + \bar{h}_{jix} \bar{\alpha}_x$$

and

$$(2.12) \quad \bar{V}_i \bar{z}^i = n + \bar{g}^{ji} \bar{h}_{jix} \bar{\alpha}_x$$

and consequently

$$(2.13) \quad \int_M (n + \bar{g}^{ji} \bar{h}_{jix} \bar{\alpha}_x) d\bar{V} = 0.$$

Now, two immersions  $X: M \rightarrow E$  and  $\bar{X}: M \rightarrow E$  define a diffeomorphism  $f: X(M) \rightarrow \bar{X}(M)$ . We assume that this mapping is volume-preserving, that is,

$$(2.14) \quad \det(\bar{g}_{ji}) = \det(g_{ji}).$$

Now the inequality of Gårding [2] says that

$$(2.15) \quad \bar{g}^{ji} g_{ji} \geq n \{ \det(\bar{g}_{ji}) / \det(g_{ji}) \}^{1/n},$$

equality holding if and only if  $\bar{g}_{ji}$  and  $g_{ji}$  are proportional. Thus we have, from (2.14) and (2.15),

$$(2.16) \quad \bar{g}^{ji} g_{ji} \geq n,$$

equality holding if and only if  $\bar{g}_{ji} = g_{ji}$ .

Similarly we have

$$(2.17) \quad g^{ji} \bar{g}_{ji} \geq n$$

equality holding if and only if  $\bar{g}_{ji} = g_{ji}$ .

Now, since

$$\begin{aligned} \bar{V}_j \bar{z}_i &= \partial_j z_i - \left\{ \begin{matrix} h \\ j \quad i \end{matrix} \right\} z_h \\ &= \partial_j z_i - \left( \left\{ \begin{matrix} h \\ j \quad i \end{matrix} \right\} + U_{ji}^h \right) z_h \\ &= \bar{V}_j z_i - U_{ji}^h z_h, \end{aligned}$$

if the transformation is an almost isometry with respect to  $\bar{g}_{ji}$ , then we have

$$\begin{aligned} \bar{g}^{ji} \bar{V}_j \bar{z}_i &= \bar{g}^{ji} \bar{V}_j z_i \\ &= \bar{g}^{ji} (g_{ji} + h_{jix} \alpha_x) \end{aligned}$$

$$\cong n + \bar{g}^{ji} h_{jix} \alpha_x$$

by virtue of (2. 8) and (2. 16). Thus integrating, we have

$$(2. 18) \quad \int_M (n + \bar{g}^{ji} h_{jix} \alpha_x) dV \leq 0,$$

since  $d\bar{V} = dV$ , equality holding if and only if  $\bar{g}_{ji} = g_{ji}$ .

Combining (2. 10) and (2. 18), we obtain

$$(2. 19) \quad \int_M (\bar{g}^{ji} h_{jix} \alpha_x - g^{ji} h_{jix} \alpha_x) dV \leq 0,$$

equality holding if and only if  $\bar{g}_{ji} = g_{ji}$ .

Similarly if the transformation is an almost isometry with respect to  $g_{ji}$ , then we have

$$(2. 20) \quad \int_M (g^{ji} \bar{h}_{jix} \bar{\alpha}_x - \bar{g}^{ji} \bar{h}_{jix} \bar{\alpha}_x) dV \leq 0,$$

equality holding if and only if  $\bar{g}_{ji} = g_{ji}$ .

### § 3. Theorem of Chern and Hsiung.

Chern and Hsiung [1] proved

**THEOREM.** *Let  $\bar{X}, X: M \rightarrow E$  be two immersed compact submanifolds and let  $f: X(M) \rightarrow \bar{X}(M)$  be a volume-preserving almost isometry with respect to the metric of  $\bar{X}(M)$ . If*

$$(3. 1) \quad \bar{g}^{ji} h_{jix} \alpha_x \cong g^{ji} h_{jix} \alpha_x,$$

*then  $f$  is an isometry.*

Under these assumptions, we have, from (2. 19),

$$\int_M (\bar{g}^{ji} h_{jix} \alpha_x - g^{ji} h_{jix} \alpha_x) dV = 0,$$

and consequently

$$(3. 2) \quad \bar{g}_{ji} = g_{ji}.$$

If  $f$  is volume-preserving almost isometry with respect to the metric of  $X(M)$  and

$$(3. 3) \quad g^{ji} \bar{h}_{jix} \bar{\alpha}_x \cong \bar{g}^{ji} \bar{h}_{jix} \bar{\alpha}_x$$

then we have, from (2. 20),

$$\int_M (g^{j\bar{i}}\bar{h}_{j\bar{i}x}\bar{\alpha}_x - \bar{g}^{j\bar{i}}\bar{h}_{j\bar{i}x}\bar{\alpha}_x)dV=0,$$

and consequently we can conclude (3. 2).

#### §4. A theorem.

We have put

$$(4. 1) \quad X = X_i z^i + C_x \alpha_x,$$

from which

$$(4. 2) \quad X_i \cdot X = z_i$$

and consequently

$$(4. 3) \quad \frac{1}{2} \nabla_i (X \cdot X) = z_i.$$

Thus

$$(4. 4) \quad \frac{1}{2} \nabla_j \nabla_i (X \cdot X) = g_{ji} + h_{j\bar{i}x} \alpha_x$$

by virtue of (2. 8).

We have similarly

$$(4. 5) \quad \frac{1}{2} \bar{\nabla}_j \bar{\nabla}_i (\bar{X} \cdot \bar{X}) = \bar{g}_{j\bar{i}} + \bar{h}_{j\bar{i}x} \bar{\alpha}_x.$$

Since

$$\begin{aligned} \frac{1}{2} \bar{\nabla}_j \bar{\nabla}_i (\bar{X} \cdot \bar{X}) &= \frac{1}{2} \left\{ \partial_j \partial_i (\bar{X} \cdot \bar{X}) - \left\{ \begin{matrix} h \\ j \quad i \end{matrix} \right\} \partial_h (\bar{X} \cdot \bar{X}) \right\} \\ &= \frac{1}{2} \left\{ \partial_j \partial_i (\bar{X} \cdot \bar{X}) - \left( \left\{ \begin{matrix} h \\ j \quad i \end{matrix} \right\} + U_{j\bar{i}}{}^h \right) \partial_h (\bar{X} \cdot \bar{X}) \right\} \\ &= \frac{1}{2} \left\{ \bar{\nabla}_j \bar{\nabla}_i (\bar{X} \cdot \bar{X}) - U_{j\bar{i}}{}^h \bar{\nabla}_h (\bar{X} \cdot \bar{X}) \right\}, \end{aligned}$$

we have, from (4. 4) and (4. 5),

$$\begin{aligned} &\frac{1}{2} \nabla_j \nabla_i (\bar{X} \cdot \bar{X} - X \cdot X) - \frac{1}{2} U_{j\bar{i}}{}^h \bar{\nabla}_h (\bar{X} \cdot \bar{X}) \\ &= \bar{g}_{j\bar{i}} - g_{ji} + \bar{h}_{j\bar{i}x} \bar{\alpha}_x - h_{j\bar{i}x} \alpha_x. \end{aligned}$$

Thus, if the transformation is a volume-preserving almost isometry with respect to  $g_{ji}$ , we have

$$\begin{aligned} & \frac{1}{2} g^{ji} \nabla_j \nabla_i (\bar{X} \cdot \bar{X} - X \cdot X) \\ &= g^{ji} (\bar{g}_{ji} - g_{ji}) + g^{ji} \bar{h}_{jix} \bar{\alpha}_x - g^{ji} h_{jix} \alpha_x. \\ &\geq g^{ji} \bar{h}_{jix} \bar{\alpha}_x - g^{ji} h_{jix} \alpha_x, \end{aligned}$$

equality holding if and only if  $\bar{g}_{ji} = g_{ji}$ .

Thus, if

$$g^{ji} \bar{h}_{jix} \bar{\alpha}_x \geq g^{ji} h_{jix} \alpha_x,$$

we have

$$\frac{1}{2} g^{ji} \nabla_j \nabla_i (\bar{X} \cdot \bar{X} - X \cdot X) \geq 0,$$

from which,  $M$  being assumed to be compact,

$$\frac{1}{2} g^{ji} \nabla_j \nabla_i (\bar{X} \cdot \bar{X} - X \cdot X) = 0,$$

by virtue of Bochner's lemma [5].

Thus

$$g^{ji} (\bar{g}_{ji} - g_{ji}) = 0$$

and consequently

$$\bar{g}_{ji} = g_{ji}.$$

Thus we have

**THEOREM.** *Let  $X, \bar{X}: M \rightarrow E$  be two immersed compact submanifolds and let  $f: X(M) \rightarrow \bar{X}(M)$  be a volume-preserving almost isometry with respect to the metric of  $\bar{X}(M)$ .*

*If*

$$g^{ji} \bar{h}_{jix} \bar{\alpha}_x \geq g^{ji} h_{jix} \alpha_x,$$

*then  $f$  is an isometry.*

### §5. Almost parallel displacement.

We know that

$$(5.1) \quad \nabla_j X_i = h_{jix} C_x$$



and

$$(5.2) \quad \bar{\nabla}_j \bar{X}_i = \bar{h}_{ji} \bar{C}_x.$$

We call an almost parallel displacement with respect to  $g_{ji}$  a transformation for which

$$(5.3) \quad g^{ji}(\bar{\nabla}_j \bar{X}_i - \nabla_j X_i) = 0.$$

Now, putting

$$A = \bar{X} - X, \quad A_i = \bar{X}_i - X_i$$

we have

$$\begin{aligned} \nabla_j A_i &= \partial_j (\bar{X}_i - X_i) - \left\{ \begin{matrix} h \\ j \ i \end{matrix} \right\} (\bar{X}_h - X_h) \\ &= \partial_j \bar{X}_i - \left( \left\{ \begin{matrix} h \\ j \ i \end{matrix} \right\} - U_{ji}{}^h \right) \bar{X}_h - \left( \partial_j X_i - \left\{ \begin{matrix} h \\ j \ i \end{matrix} \right\} X_h \right) \\ &= \bar{\nabla}_j \bar{X}_i - \nabla_j X_i + U_{ji}{}^h \bar{X}_h. \end{aligned}$$

Thus, for an almost isometry with respect to  $g_{ji}$ , we have

$$g^{ji} \nabla_j A_i = g^{ji} (\bar{\nabla}_j \bar{X}_i - \nabla_j X_i).$$

Thus, if an almost isometry is an almost parallel displacement, we have

$$g^{ji} \nabla_j A_i = 0.$$

Thus, if  $M$  is compact, all the components of the vector  $A$  are constant and  $A$  is a constant vector. Thus we have

**THEOREM.** *If  $M$  is compact and  $f: X(M) \rightarrow \bar{X}(M)$  is an almost isometry and at the same time an almost parallel displacement, then  $f$  is a parallel displacement.*

**REMARK.** Gardner [3] has employed profitably a fixed vector in  $E$  to get a general rigidity theorem.

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