

RESEARCH

Open Access

Novel 3D micro- and nanofabrication method using thermally activated selective topography equilibration (TASTE) of polymers

Arne Schleunitz², Vitaliy A Guzenko¹, Martin Messerschmidt², Hakan Atasoy², Robert Kirchner¹ and Helmut Schift^{1*}

Abstract

Micro- and nanostructures with three-dimensional (3D) shapes are needed for a variety of applications in optics and fluidics where structures with both smooth and sharp features enhance the performance and functionality. We present a novel method for the generation of true 3D surfaces based on thermally activated selective topography equilibration (TASTE). This technique allows generating almost arbitrary sloped, convex and concave profiles in the same polymer film with dimensions in micro- and nanometer scale. We describe its principal mechanism exemplified by pre-patterned poly (methyl methacrylate) resist which is exposed to high energy electrons prior to a thermal annealing step enabling the selective transformation of stepped contours into smooth surfaces. From this we conclude, that TASTE not only offers an enormous degree of freedom for future process variations, but also will advance the patterning capabilities of current standard 3D micro- and nanofabrication methods.

Keywords: Thermoplastic polymer; Thermal reflow; Three-dimensional; Surface topography; Electron beam lithography; Nanoimprint lithography; Nanofabrication

1 Background

Current applications in micro- and nanotechnology mainly use binary (i.e. two-level) surface topographies provided by state-of-the-art planar fabrication processes. However, the increasing technical requirements for new or enhanced device functionality with sophisticated 3D topographies have to be met. This includes regular sub-wavelength blazed gratings and microprisms for out-coupling of light into planar waveguides for optical application [1,2], as well as shallow tapered inlets bridging micro- to nanofluidics for life-sciences [3,4]. Currently, 3D topographies are often simply approximated by steps with adapted widths and heights which resemble provisional and quasi-3D contours. In this case, viable pattern fidelity is connected to high process complexity since non-continuous multi-level features need multiple lithographic and etching [5] or electroplating steps [6]. Alternative approaches for continuous contours using anisotropic etching of crystalline silicon in alkaline solutions are restricted to specific

geometries [7,8]. Thus novel process strategies are required in order to overcome the limitations of generic micro- and nanofabrication techniques.

By implementing the TASTE method (i.e. thermally activated selective topography equilibration), we demonstrate the possibility to generate truly 3D shaped topographies with decreased technical effort while the geometrical diversity is enhanced at the same time. TASTE is a further development and generalization of an effect observed during selective thermal reflow of grayscale structures, presented in [9]. In this original process grayscale lithography and thermal reflow were combined, i.e. a positive resist was locally exposed with a modulated dose of high energy (100 keV) electrons, which enabled to create a height profile with distinct steps after development in a suitable solvent. The stepped structures could be transferred into a linear slope by selective reflow by heating to a moderate temperature. This was possible because the exposure led to the simultaneous local modification of both etch rate and glass transition temperature T_g over the entire film thickness. This led to distinct heights of remaining resist during development and selectivity during reflow, both between exposed structures which could be modified and

* Correspondence: helmut.schift@psi.ch

¹Paul Scherrer Institut, Laboratory for Micro- and Nanotechnology, 5232 Villigen, PSI, Switzerland

Full list of author information is available at the end of the article

unexposed structures which remained unaffected. Apart from this pronounced selectivity, the basic principles of the selective reflow are:

- the high thermo-mechanical selectivity between exposed and unexposed resist
- a local reflow and redistribution of polymer of only a few steps
- the definition of the final shape due to volume conservation and pinning on the interface to the unexposed structures and to the cleared substrate.

As can be seen in the compilation of exemplary 3D structures illustrated in Figure 1, the variety of achievable structures comprises the creation of stepped, sloped, concave and convex contours, with a range of slope angles and curvatures, as well as sizes, orientations and density variations in the very same polymer surface. In all cases TASTE was applied to a 1 μm thick poly(methyl methacrylate) resist (PMMA) on a silicon substrate resulting into diverse 3D topographies exhibiting exceptionally smooth contours, enabled by the selective transformation of stepped surfaces into new continuous topographies during a single thermal annealing step. Up to now, slope angles of up to 45° in 2 μm thick resists with optically smooth surfaces with a few nm roughness were achieved [9-11].

1.1 Background: Fundamental working principle

As fundamental aspect of TASTE, we have previously identified the local variations of viscosity in the electron-beam exposed PMMA resist during the heating step, which originates from the dose dependent reduction in molecular

weight M_w (here weight-averaged molecular weight) and glass transition temperature T_g of the polymer. A typical asymmetric 5-level grayscale PMMA structure is depicted in Figure 2 to which locally five different doses (D1 - D5) were applied according to a specific lateral design, prior to development in pure methyl-isobutyl-ketone (MIBK). Here, D0 represents an unexposed area, where the initial resist thickness is preserved, while D5 corresponds to the dose required to completely clear the resist upon development, i.e. dose-to-clear. Since for a stepped structure the highest step (D1) will have M_w nearest to the original M_w (D0 = 0), this results also in a reduced ability to flow. This can be reduced by using a high enough reflow temperature near to the T_g of the unexposed ridge, leading to a softening and thus slight inclination. A simplification can therefore be achieved if an already produced slope structure with a homogeneous M_w is generated, e.g. by using an imprinted thermoplastic resist structure such as PMMA which is flood exposed with a dose $D > D1$ over all steps. Using this, all steps can be exposed to generate low M_w , which enables a complete reflow and an equal smoothing, particularly also the uppermost step of the 5-level pattern with the lowest reduction in M_w . Furthermore it enables to do the reflow at low temperature, at which the non-exposed ridge with a high M_w is less affected by the reflow step. Aiming for a versatile and robust process, our investigations were focused on defining thresholds which enhance the selectivity in reflow behavior for a range of surface topographies, i.e. a selective transformation of structures into defined contours while others remain unaltered. For this we have analyzed the specific correlation between M_w and resulting T_g of the exemplary PMMA resist used in this work.

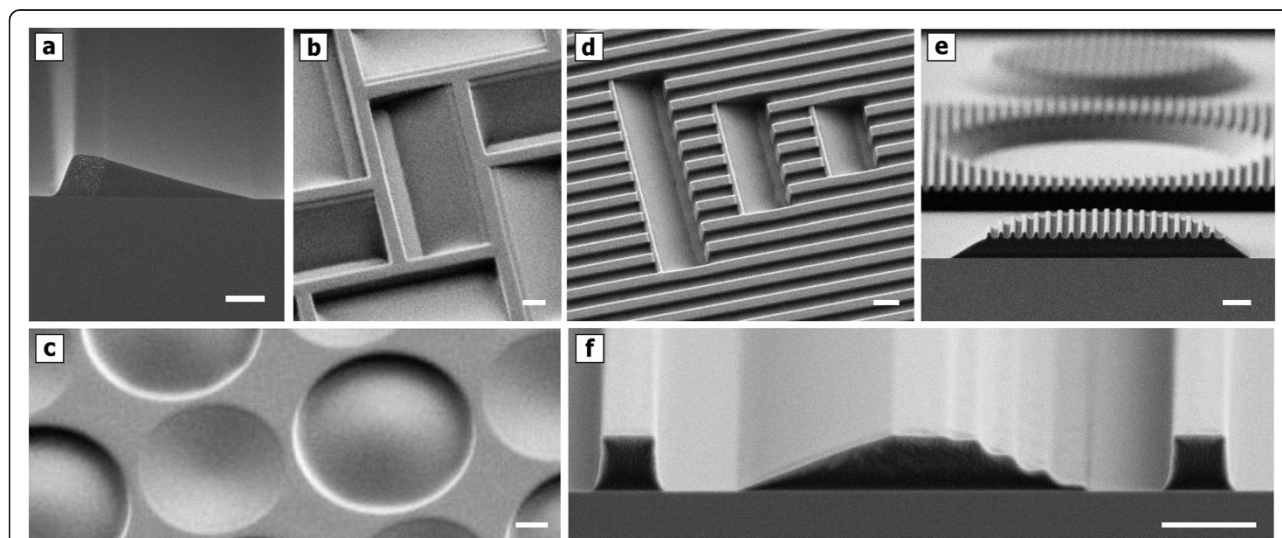
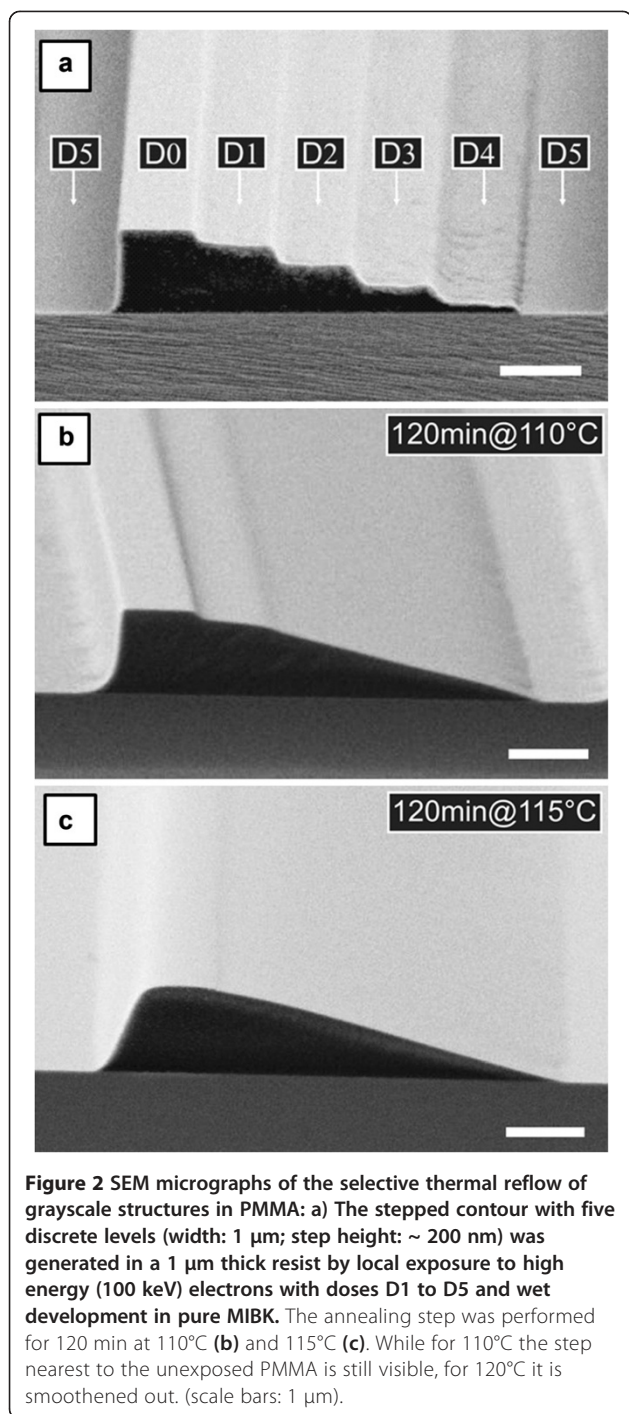


Figure 1 Compilation of exemplary 3D contours in a thin PMMA film enabled by the TASTE method. The SEM micrographs (angled views and cross sections) depict refined PMMA topographies after exposure of pre-patterned PMMA to high energy electrons and subsequent thermal annealing. Achievable contours comprise (a-c) binary, stepped, sloped, convex and concave structures, as well as (d-f) hybrid structures with specific pattern combinations. (scale bars: 1 μm).



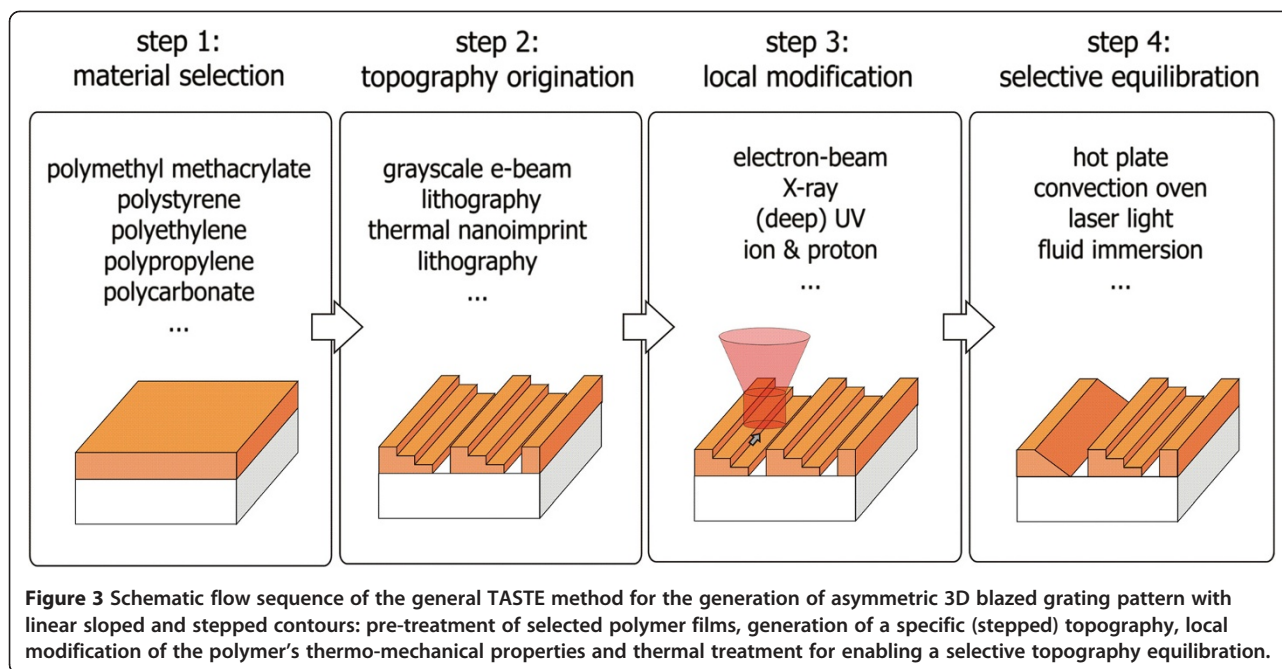
Before a detailed technical discussion is given further below, the basic process sequence of the generalized TASTE method is illustrated in Figure 3 for the generation of asymmetric 3D grating elements with linear sloped and stepped contours. Here, a thermoplastic polymer material is deposited on a solid substrate (*step 1*: material selection) and patterned with a specific stepped topography, e.g. using standard lithographic methods such as grayscale

electron-beam lithography [12-15] (*step 2*: topography origination). Next, the polymer material is precisely modified over selected steps, e.g. upon irradiation to high energy electrons using defined doses (*step 3*: local modification), if not already done by grayscale lithography. This way, the thermo-mechanical properties of the polymer are locally adjusted, allowing an optimized transformation of the exposed stepped contours into smooth slopes, if the polymer is subsequently heated to an appropriate temperature (*step 4*: selective equilibration). Although the annealing step is performed to the entire film-coated substrate, only the locally exposed polymer structures are softened which allows surface tension driven topography equilibration to selectively convert steps into smooth slopes. Since the original shape of unexposed areas stays unaltered upon thermal treatment, the generation of entirely novel topographies is enabled which includes vertical, stepped and slopes contours in close vicinity to each other (see Figure 1f). This makes TASTE a unique method since it is different to traditional thermal reflow at higher temperatures which aims for the collapse into spherical or cylindrical shapes or decay of all structures [16-18].

The combination of material and lithography used in this contribution, i.e. PMMA and electron beam lithography (EBL), is only one specific example of a TASTE method which allows a precise control of resolution, dose and alignment in a well-defined material. The schematic in Figure 3 also specifies possible alternative materials and sub-processes indicating the high degree of freedom for alternative technical implementations of TASTE. This contribution has two aims: To review the achievements and possibilities of TASTE and to present an analysis of the relation exposure dose to M_w and T_g , which is the cornerstone of TASTE. By this we will demonstrate the width of process window possible by exposure with standard EBL. At the end we will give an insight about how shapes of TASTE structures could be predicted by simulation using a soapfilm-based model.

2 Methods

The PMMA for spincoating is an experimental sample provided by micro resist technology GmbH (Germany), with a specified weight averaged molecular weight M_w of 120 k (kg mol^{-1}). As it will be shown below, the actual M_w is much lower than 120 k, and for comparison, it is much more convenient to use M_n (number-averaged molecular weight) instead of M_w . In comparison to high M_w PMMA generally used for EBL, this M_w was chosen to be low enough to enable a pre patterning of resist using nanoimprint lithography (NIL) (see Figure 1e) [19,20]. This is possible since the typical temperature of imprint (160-180°C) and the T_g of the unexposed resist (122°C) are different enough to enable a selective reflow of exposed structures without affecting imprinted structures [21].



Furthermore the M_w was found high enough to enable a selective reflow of exposed structures with M_w below the T_g -critical threshold. The raw (i.e. unexposed) polymer material was predominantly syndiotactic PMMA (7% isotactic, 54% syndiotactic, 39% atactic; determined by $^1\text{H-NMR}$ spectroscopy). It was dissolved in anisole enabling the spin-coating deposition of $1\ \mu\text{m}$ thick layers on silicon substrate. For the PMMA resist being exposed to different doses, the distinct reduction of the molecular weight distributions was determined using gel permeation chromatography (GPC), and the T_g was analyzed using differential scanning calorimetry (DSC), by removing flakes of exposed PMMA films from the substrate. EBL exposure was performed in a Vistec EBPG 5000 Plus ES. The corresponding contrast curve can be found elsewhere [11]. After exposure, a stepped contour with five discrete levels (step width: $1\ \mu\text{m}$) was generated in a $1\ \mu\text{m}$ PMMA resist after wet development in pure methyl-isobutyl-ketone (MIBK) for 30 s at 20°C . Because the aim was to create a linear slope between the top of the ridge and the substrate as two pinning points, in between a stepped slope with four intermediate steps needed to be placed. This was possible by choosing the step heights different from the average step height of $\sim 200\ \text{nm}$, with a larger step in the center of the slope. This was done according to volume conservation over the entire slope as well as within the vicinity of each step. The annealing step was performed for 120 min at different temperatures near the T_g of the unexposed resist, on a hot plate in ambient condition. Analysis was done via scanning electron microscopy (SEM).

3 Results and discussion

3.1 Polymer analysis

In order to assess the optimum reflow conditions such as the temperature, the GPC measured M_n data were correlated to specific T_g by using DSC. The results are graphically summarized in Figure 4a and quantified by the averaged masses derived from the GPC data presented in Table 1: the exposure induced decay of M_n implicates a significant reduction of the T_g , when the dose is $225\ \mu\text{C cm}^{-2}$ or higher. This results in a reduction of the T_g of unexposed PMMA (initially at $T_{g,\infty} = 122^\circ\text{C}$) of more than 20 K to temperatures in the range of $90 - 100^\circ\text{C}$. The grayscale steps can therefore be selectively transformed into continuous slopes, while the non-exposed ridge is less affected by the reflow step. It is particularly interesting that for PMMA exposed to doses $225\ \mu\text{C cm}^{-2}$ or higher, the M_n of initially $40\ \text{kg mol}^{-1}$ is reduced to $7\ \text{kg mol}^{-1}$ and lower. This leads to altered thermo-mechanical properties of the exposed PMMA since the material cohesion and thus viscosity is changed in particular, when the polymer chain length is below a critical [22] M_n of about $10\ \text{kg mol}^{-1}$. Below this threshold, the chain entanglement is substantially reduced and thus thermally induced chain motions are less retarded, i.e. topological restriction by neighboring chains becomes less important. When the polymer is heated, the induced thermal energy is consumed by activating cooperative translation movements of the polymer molecules. For a decreased M_n , a polymer chain motion is enhanced more easily due to the increased free volume in the polymer resulting from the increased presence of chain ends. This results in a

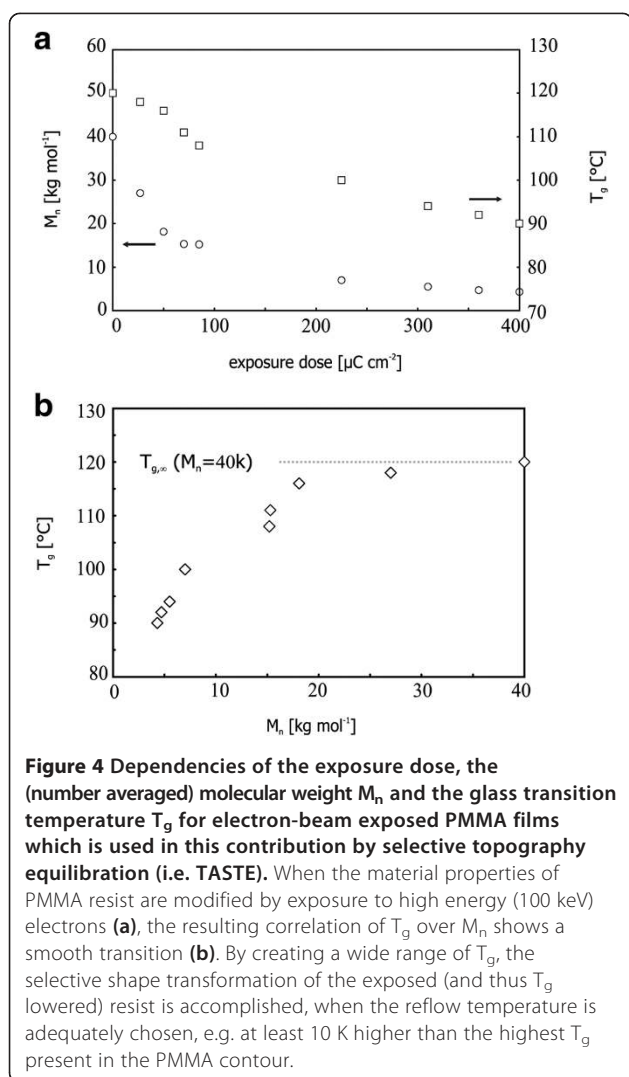


Table 1 Summary of the GPC and DSC measurements quantifying the dose dependencies of the thermo-mechanical properties of PMMA

Exp. dose [$\mu\text{C cm}^{-2}$]	M_n [kg mol^{-1}]	M_w [kg mol^{-1}]	PD [-]	T_g [$^{\circ}\text{C}$]
unexposed	40.0	91.2	2.0	122
27	27.0	58.3	2.2	118
50	18.1	45.2	2.5	116
70	15.3	35.0	2.3	111
85	15.2	34.0	2.2	108
225	7.0	14.6	2.1	100
310	5.5	11.5	2.1	94
360	4.7	10.0	2.1	92
400	4.3	8.9	2.1	90

Upon exposure to high energy electrons, the number averaged molecular weight M_n , weight averaged molecular weight M_w , polydispersity PD (M_w/M_n) and glass transition temperature T_g is modified according to the applied doses.

softening of exposed polymer material already at reduced temperatures which in turn corresponds to a decreased T_g [23]. The variation of a few degrees in T_g results in viscosity changes of orders of magnitude [6] for a given temperature. In the ideal case, flow only occurs between neighboring exposed steps (i.e. in “near field”), which can be accomplished when using proper reflow conditions and thus maintain a sufficient material viscosity. This prevents the formation of cylindrical or spherical pattern as are known from classical reflow processes [16-18]. Consequently, PMMA features exposed to high energy electrons can be selectively reflowed at eligible temperatures while unexposed pattern stay unaltered.

The topography transformation of the exposed areas is enabled by surface tension forces which are oriented parallel to the interface (polymer/ambience) [24] and thus are imbalanced for stepped contours with kinks (protrusions) and edges (depressions). When the PMMA resist is locally softened, the unbalanced surface tension forces initiate localized material movements until the polymer surface is in a favorable energetic state (e.g. which in high temperature reflow is based on pinning and surface minimization where the surfaces are in equilibrium). For stepped 3D resist profiles with a pinning at the unexposed ridge and the cleared substrate, this state is reached for a continuous linear slope. The resulting angle of inclination is predetermined by the pinning and initial geometry. Since the reflow process is based on kinetic effects, which takes place with different progression speeds correlated to the given viscosity variation, more than a mere smoothing into linear slopes is enabled. Convex and concave pattern of distinct shapes (e.g. non-cylindrical and -spherical, which is advantageous over standard reflow) are also possible (see Figure 1c) because the material displacement during smoothing is locally confined. This allows predefining non-linear trajectories based on contour approximation and volume conservation.

3.2 Stepped and sloped sidewalls in close vicinity

Correlating the GPC and DSC data allows drawing T_g directly as a function of M_n , which reveals a rather smooth and gradual decline of T_g (Figure 4b). Thus, an abrupt change in thermal properties for pattern with critical M_n of lower than 10 kg mol^{-1} , as anticipated previously [22], is not confirmed. This leads to an empirically found general definition of TASTE compatible process windows for the PMMA used in this work, which can be described as follows: an optimal reflow temperature is given at least 10 K below the polymers original T_g , and 10 K above the highest T_g present in the polymer pattern, respectively. For a chosen temperature of 110°C , these prerequisites are only achieved for generating PMMA patterns with a maximum M_n of 5 kg mol^{-1} , which according to Figure 4a corresponds to an exposure dose of $400 \mu\text{C cm}^{-2}$ or higher.

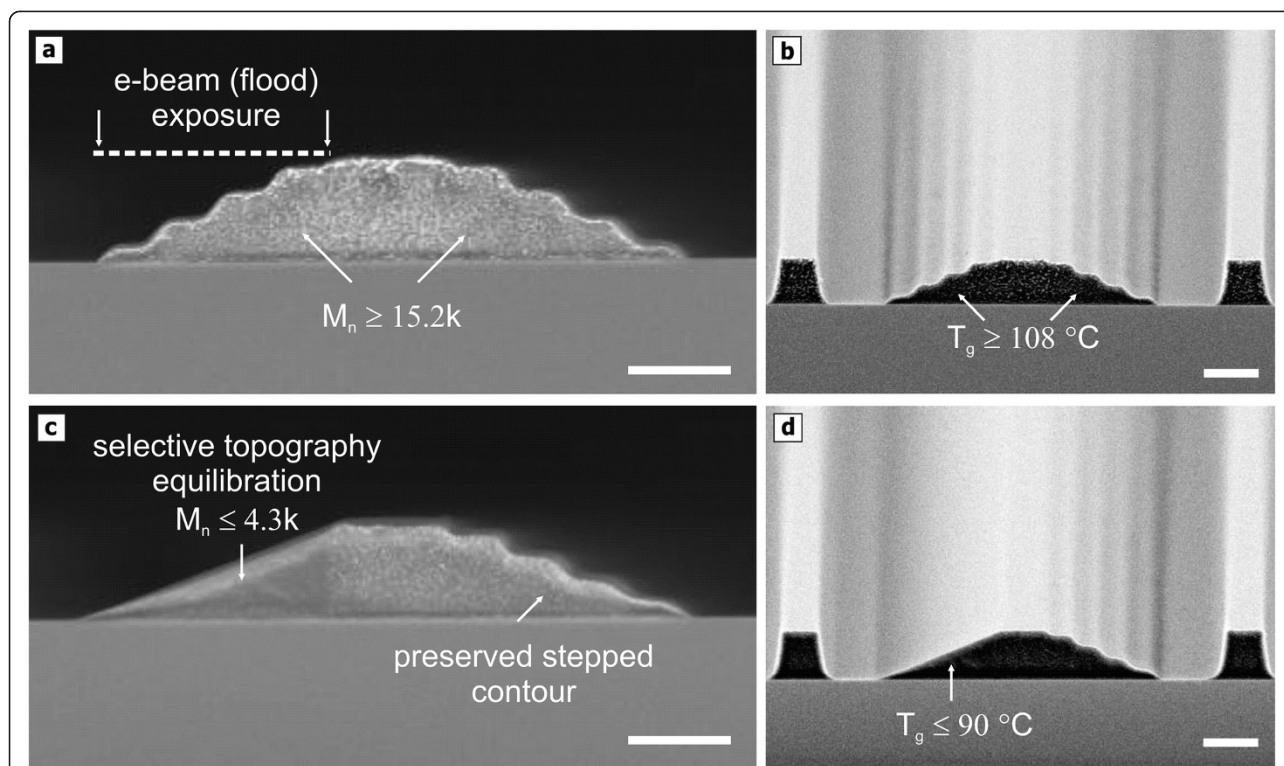


Figure 5 A partially (flood) exposing a multilevel PMMA resist contour within the TASTE process enhances the available pattern variety of 3D structures. The generation of sloped and stepped contours in very close vicinity to each other is enabled by locally exposing a stepped PMMA contours (a-b) with high dosage (i.e. $500 \mu\text{C cm}^{-2}$) and thus reducing the T_g below 92°C . Applying a reflow temperature of 110°C , exposed steps are then selectively transformed into a continuous slope while other topographies are unaltered (c-d). Partial flood exposure also optimizes the overall slope accuracy since the thermal properties of the exposed areas are homogenized (scale bars: $1 \mu\text{m}$).

This way, stepped and sloped topographies can be combined in close vicinity, as demonstrated in Figure 5. Here, the stepped polymer patterns (either fabricated by grayscale EBL or 3D NIL) prior to thermal treatment, i.e. the stepped patterns, are exposed by a well aligned local flood exposure, enables the appropriate reduction of M_n into a favorable regime for reflow with sufficiently reduced T_g . In contrast to previous works by the authors, where grayscale EBL was used for topography origination which led to a rather unspecific modification of the material properties [25], this defines effective M_n values in the resist not correlated to distinct level heights. This way, typical reflow defects at upper most level height reported before are overcome and the overall slope characteristics are optimized (see also Figure 2).

The broad T_g distribution depicted in Figure 4a and 4b achieved by the electron-beam exposure also allows to further advance the available pattern variety, when two identical stepped resist contours are generated in PMMA resist, as shown in Figure 5, using a grayscale EBL with doses between 25 and $85 \mu\text{C cm}^{-2}$ and a respective development time of 15 min. Here, the comparatively low doses result in a moderate reduction of $M_n \gg 10 \text{ kg mol}^{-1}$ for the stepped pattern and thus into marginal decrease of T_g

not less than 108°C . A subsequent and locally confined flood-exposure of $500 \mu\text{C cm}^{-2}$ further reduces (and eventually homogenizes) the M_n range within the exposed steps below 5 kg mol^{-1} , which results in a reduced $T_g < 90^\circ\text{C}$. If a thermal treatment at a fixed temperature of 110°C for 15 min is now applied, only the exposed steps are selectively transformed into a linear slope. The non-flood exposed contours, which have still relatively high T_g , stay unaltered upon reflow since the viscosity remains high. Future advancement can be achieved when an overlap of this flood exposure with the central non-exposed ridge ensures an optimal slope pinning to the upper level without any kink and consequently enhances the overall characteristics of 3D topographies.

3.3 Simulation of reflow using soap film-based model

For many applications not only the final shape, but also the pattern evolution from the initial into the reflow shape (Figure 2) depending on material and process parameters would be of interest. A simulation based on the time-temperature dependent, dynamic evolution of the polymer surface during the reflow process was performed, based on open source software [26]. As an example, the case of a six level (five exposure-level) structure

was simulated (see Figure 6), similar to that in the experiments presented in Figure 5, with an unexposed ridge on the right side and the cleared substrate on the left side. The major influencing parameters during reflow are i) the initial feature geometry after electron beam exposure, ii) the material properties of the reflow thermoplast, and iii) the reflow parameters itself. The influence of all these parameters on the shape evolution is implemented in a soapfilm-based model [26] via a dynamic contact angle between the polymer and the surface wetted by the polymer [27]. The discrete-time model allows determining precisely a point at which the relaxation should be stopped by reducing the sample temperature well below the glass transition to freeze a certain curvature. Using this, in the simulation presented in Figure 6, it is possible that the pinning at the lower end of the slope can be nearly preserved, while the polymer is able to rise up to the top of the unexposed ridge. Apart from pinned slopes, more complex structures can be predicted, including concave and convex shapes. Details can be found in [28].

4 Conclusions

The enormous degrees of freedom offered by the TASTE method brings us to conclude that the process sequence of stepped topography origination, flood exposure and reflow in a thermoplastic polymer layer needs to be specified as a new lithographic method for 3D patterning.

Compared to previous works, the increased reflow selectivity and improved pattern accuracy with less geometrical defects, by introducing a flood exposure to pre-patterned polymer contours, enabled contour transformation to be performed in a pre-determined way almost entirely given by geometry. As already indicated in Figure 3, process variants could employ other polymers (e.g. polystyrene) as *step 1*, which are also known for its nanofabrication capabilities by lithographical means [29,30], or resists suitable for NIL [21]. For topography origination of stepped structures as *step 2*, instead of patterning by grayscale EBL, replication by 3D-NIL could be employed. This allows the replication of diverse preliminary (e.g. stepped, corrugated, defective) structures originating from a range of processes which can be subsequently transformed into structures with desired shape and functionality by localized flood (over entire slopes) or selected area (up to global) exposure. In future, it might also be interesting to explore the possibilities of alternative exposure techniques as *step 3* by exposure to X-rays, ions, proton or (deep) UV-light, also well known to modify the thermo-mechanical properties of resists [31]. As *step 4*, global heating schemes may involve a hotplate and convection oven, but can also include local treatment by laser light irradiation or immersion in heated fluids. Typically, once such complex features are fabricated, it can be used as pattern origination in mass-replication techniques like NIL or other molding processes, where 3D surface reliefs

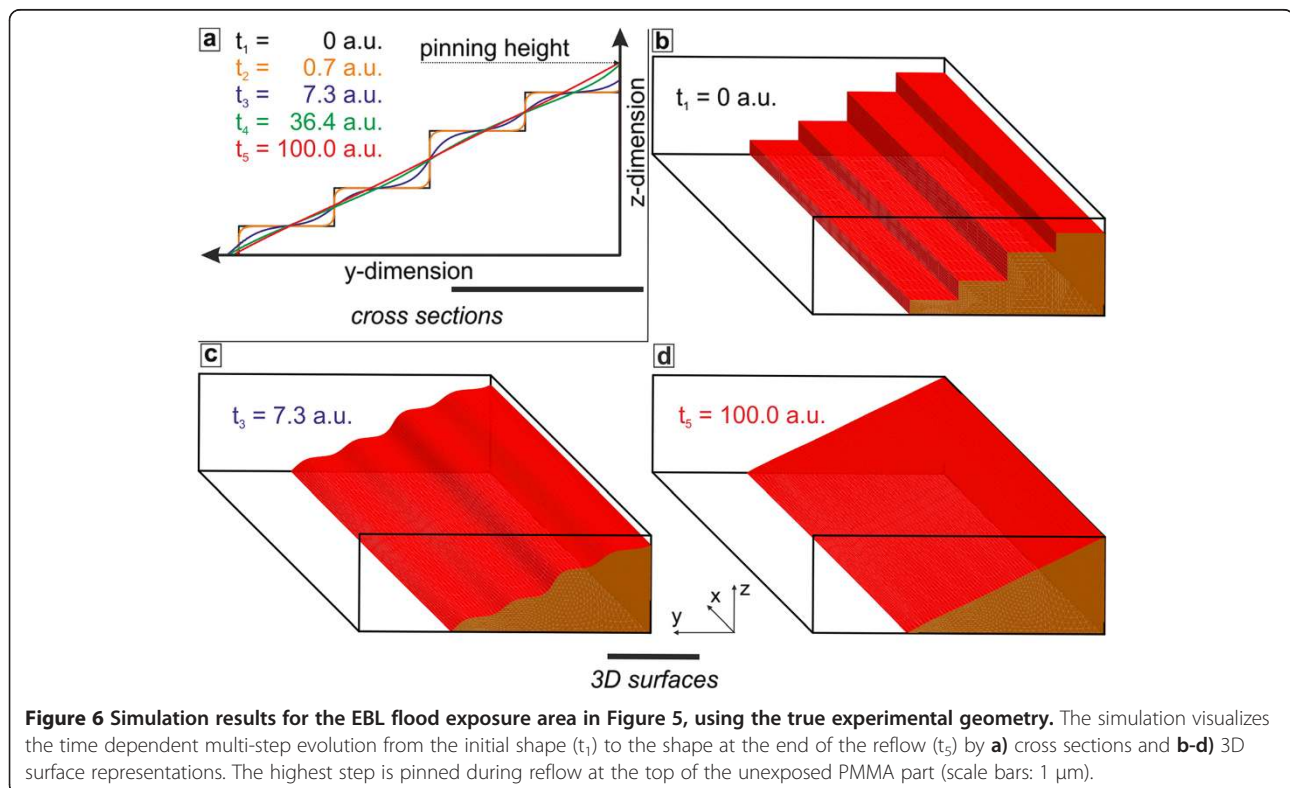


Figure 6 Simulation results for the EBL flood exposure area in Figure 5, using the true experimental geometry. The simulation visualizes the time dependent multi-step evolution from the initial shape (t_1) to the shape at the end of the reflow (t_5) by **a**) cross sections and **b-d**) 3D surface representations. The highest step is pinned during reflow at the top of the unexposed PMMA part (scale bars: 1 μm).

are repeatedly generated by spatial material displacement [19,20]. The potential of the TASTE method towards entirely novel 3D profile variants is high and will direct towards new applications where those varieties are needed.

Abbreviations

TASTE: Thermally activated selective topography equilibration; 3D: Three-dimensional; PMMA: Poly(methyl methacrylate); M_w : Weight-averaged molecular weight; M_n : Number-averaged molecular weight; T_g : glass transition temperature; MIBK: Methyl-isobutyl-ketone; EBL: Electron-beam lithography; NIL: Nanoimprint lithography; SEM: Scanning electron microscopy; GPC: Gel permeation chromatography; DSC: Differential scanning calorimetry.

Competing interests

The authors declare that they have no competing interests.

Authors' contributions

AS is the main author of this paper, who conceived and performed all reflow experiments. VAG has conceived the 3D EBL writing strategies employed in this paper. MM performed the analytics and interpretation of M_w data, HA has provided the polymer samples and contributed in the analytics of the polymer by GPC and DSC. RK has setup and performed simulations with the soapfilm based method based on the experiments. HS conceived the research project and participated in the interpretation of data; he has also written part of this paper and is responsible for the revision of the paper. All authors read and approve the final manuscript.

Authors' information

AS has been previously postdoc in the INKA group at the Paul Scherrer Institut (PSI), where all EBL and NIL experiments were performed. Since 2012 he is employed by micro resist technology GmbH.

Acknowledgements

We thank K. Vogelsang, C. David and J. Gobrecht (PSI Villigen), C. Spreu from Sensirion AG (formerly PSI), as well as J. Voskuhl, A. Kolander, M. Vogler and G. Grützner (*micro resist technology* GmbH) for their help and valuable contributions. We also thank P. Shahgaldian (Fachhochschule Nordwestschweiz) for performing the supplementing NMR measurements. The research presented here was partially funded by Swiss Federal Office for Science and Education in the framework of the EC-funded project NaPANIL (contract no. NMP 214249). The content of this work is the sole responsibility of the authors.

Author details

¹Paul Scherrer Institut, Laboratory for Micro- and Nanotechnology, 5232 Villigen, PSI, Switzerland. ²Micro Resist Technology GmbH, Koepenicker Str. 325, 12555 Berlin, Germany.

Received: 18 October 2013 Accepted: 14 November 2013

Published online: 28 February 2014

References

1. RH Morf, H Kiess, C Heine in: J Turunen, F Wyrowski, *Diffraction Optics* (Akademie Verlag, Berlin, 1997).
2. V Terrazzoni-Daudrix, J Guillet, X Niquille, A Shah, R Morf, A Tishchenko, V Brioude, O Parriaux, D Fischer, *Mat. Res. Soc. Symp. Proc.* **769**, H6.14.1–6 (2003)
3. I Fernandez-Cuesta, AL Palmarelli, X Liang, J Zhang, S Dhuey, D Olynyck, S Cabrini, *J. Vac. Sci. Technol. B* **29**, 06F80 (2011)
4. SM Stavis, EA Strychalski, M Gaitan, *Nanotechnology* **20**, 165302 (2009)
5. YY Zhang, J Zhang, G Luo, X Zhou, GY Xie, T Zhu, ZF Liu, *Nanotechnology* **16**, 422–428 (2005)
6. E Di Fabrizio, F Romanato, M Gentili, S Cabrini, B Kaulich, J Susini, R. Barrett. *Nature* **401**, 895–898 (1999)
7. N Bogdanski, H Schulz, M Wissen, H-C Scheer, J Zajadacz, K Zimmer, *Microelectron. Eng.* **73–74**, 190–195 (2004)
8. H Seidel, L Csepregi, A Heuberger, H Baumgartel, *J. Electrochem. Soc.* **137**, 3612–26 (1990)
9. A Schleunitz, H Schiff, *J. Micromech. Microeng.* **20**, 095002 (2010)
10. A Schleunitz, H Schiff, *Microelectron. Eng.* **88**, 2736–2739 (2011)
11. A Schleunitz, VA Guzenko, A Schander, M Vogler, H Schiff, *J. Vac. Sci. Technol. B* **29**, 06F302 (2011)
12. G Piaszenski, U Barth, A Rudzinski, A Rampe, A Fuchs, M Bender, U Plachetka, *Microelectron. Eng.* **84**, 945–948 (2007)
13. SY Lee, K Anbumony, *J. Vac. Sci. Technol. B* **25**, 2008–2012 (2007)
14. WC Cheong, WM Lee, XC Yuan, LS Zhang, K Dholakia, H Wang, *Appl. Phys. Lett.* **85**, 5784–5786 (2004)
15. DM Koller, A Hohenau, H Ditzbacher, N Galler, AL Baudrion, F Reil, S Schausberger, FR Aussenegg, A Leitner, JR Krenn, *Microelectron. Eng.* **85**, 1639–1641 (2008)
16. SY Chou, Q Xia, *Nature Nanotechnology* **3**, 295–300 (2008)
17. P Ruther, B Gerlach, J Göttert, M Ilie, J Mohr, A Müller, C Oßmann, *Pure Appl. Opt.* **6**, 643–53 (1997)
18. H Schiff, C Spreu, A Schleunitz, JJ Lee, *Microelectron. Eng.* **88**, 87–92 (2011)
19. SY Chou, PR Krauss, PJ Renstrom, *J. Vac. Sci. Technol. B* **14**, 4129–4133 (1996)
20. H Schiff, *J. Vac. Sci. Technol. B* **26**, 458–480 (2008)
21. A Schleunitz, C Spreu, M Vogler, H Atasoy, H Schiff, *J. Vac. Sci. Technol. B* **29**, 06FC01 (2011)
22. K Ute, N Miyatake, K Hatada, *Polymer* **36**, 1415 (1995)
23. JMG Cowie, *Polymers: Chemistry and Physics of Modern Materials* (Blackie Academic, Glasgow, 1991)
24. A Marchand, JH Weijs, JH Snoeijer, B Andreotti, *Am. J. Phys.* **79**, 999 (2011)
25. EA Dobisz, SL Brandow, R Bass, J Mitterender, *J. Vac. Sci. Technol. B* **18**, 107–111 (2000)
26. KA Brakke, *Experimental Mathematics* **1**, 141–165 (1992)
27. S Newman, *J. Colloid Interface Sci.* **26**, 209–213 (1968)
28. R Kirchner, A Schleunitz, H Schiff, *Energy-based thermal reflow simulation for 3D polymer shape prediction using the Surface Evolver, submitted to (J. Micromech. Microeng., 2014)*
29. S Ma, V Con, M Yavuz, B Cui, *Nanoscale Research Letters* **6**, 446 (2011)
30. H-C Scheer, S Möllenbeck, A Mayer, K Dhima, *J. Vac. Sci. Technol.* **28**, C6M1 (2010)
31. JO Choi, JA Moore, JC Corelli, JP Silverman, H Bakhru, *J. Vac. Sci. Technol. B* **6**, 2286–2289 (1988)

doi:10.1186/s40580-014-0007-5

Cite this article as: Schleunitz et al.: Novel 3D micro- and nanofabrication method using thermally activated selective topography equilibration (TASTE) of polymers. *Nano Convergence* 2014 1:7.

Submit your manuscript to a SpringerOpen® journal and benefit from:

- Convenient online submission
- Rigorous peer review
- Immediate publication on acceptance
- Open access: articles freely available online
- High visibility within the field
- Retaining the copyright to your article

Submit your next manuscript at ► springeropen.com