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Numerical analysis of matric suction effects of tree roots

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The use of native vegetation in the coastal regions of Australia has become increasingly popular for stabilising railway corridors built over expansive clays and compressive soft soils. The tree roots provide three stabilising functions: (a) they reinforce the soil; (b) they dissipate excess pore pressures; and (c) they establish sufficient matric suction to increase the shear strength. The matric suction generated within the tree root zone propagates radially into the soil matrix, as a function of the moisture content change. Considering soil conditions, the type of vegetation and atmospheric conditions, a mathematical model for the rate of root water uptake is developed. A conical shape is considered to represent the geometry of the tree root zone. Based on this model for the rate of root water uptake, the pore water pressure distribution and the movement of the ground adjacent to the tree are numerically analysed. Field measurements taken from the previously published literature are compared with the authors' numerical predictions. It is found that, given the approximation of the assumed model parameters, the agreement between the predicted results and field data is still promising. The study indicates that native vegetation improves the shear strength of the soil by increasing the matric suction, and also curtails soil movements.

NOTATION

Energiation 1 an affinition t
Empirical coefficient
Compression index
Swelling index
Change of void ratio in the soil element
mean effective stress change on the soil skeleton
Potential evaporation
Potential evapotranspiration
Root water uptake reduction factor
Function associated with potential transpiration
distribution
Soil heat flux
Function associated with the root density
distribution
Hydraulic conductivity
Empirical coefficient
Empirical coefficient
Experimental coefficient
Experimental coefficient

ks	Saturated coefficient of permeability
п	Empirical coefficient
p_0	Initial mean effective stress
PI	Plasticity index
r_0	Radial coordinate of maximum root density
	point
R_n	Net radiation
S(x, y, z, t)	Root water uptake at point (x, y, z) at time t
S _{max}	Maximum rate of root water uptake
S_r	Degree of saturation
T(t)	Transpiration rate at time t
$T_{\rm P}$	Potential transpiration
<i>u</i> _a	Pore air pressure
<i>u</i> _w	Pore water pressure
V	Total volume
$V_{ m w}$	Volume of water
w	Fraction of soil passing sieve #200
W	Dimensionless weighted function
Ζ	Vertical coordinate
<i>Z</i> ₀	Vertical coordinate of maximum root density
	point
$\beta(x, y, z, t)$	Root density
$\beta_{\max}(t)$	Maximum root density at time t
χ	Effective stress parameter
δ_{ij}	Kronecker's delta
σ_{ij}	Total stress in the porous medium
σ'_{ij}	Effective stress in the porous medium
θ	Volumetric moisture content
ψ	Matric suction
$\psi_{ m an}$	Lowest value of ψ at $S = S_{max}$
$\psi_{ m d}$	Highest value of ψ at $S=S_{\max}$
$\psi_{ m w}$	Soil suction at wilting point
∇	Divergence vector

I. INTRODUCTION

Apart from providing natural soil reinforcement, tree roots dissipate excess pore water pressure and produce sufficient matric suction to increase the shear strength of the surrounding soil. For these reasons, various forms of native vegetation are becoming increasingly popular in Australia for stabilising soft soils. It is well recognised that vegetation has various mechanical and hydrological effects on ground stability. Most attempts to quantify these effects have focused on the mechanical strengthening provided by the roots, but ignore the implications of evapotranspiration for the soil pore water pressure. For instance, the models developed by Chok et al.,¹

Operstein and Frydman,² and Docker and Hubble³ consider the reinforcement effect of roots as a mechanism for increasing soil cohesion. However, the root-based soil suction changes were not considered in detail in their models. In order to quantify pore pressure dissipation and induced matric suction, the complex inter-relationships among the soil, plant and atmosphere should be analysed.

The loss of moisture from the soil may be categorised as: (a) water used for metabolism in plant tissues; and (b) water transpired to the atmosphere. However, as suggested by Radcliffe *et al.*,⁴ the volume of water required for photosynthesis or metabolism in plant tissues compared with the total water uptake by roots is negligible. The total transpiration can then be assumed to be the same as the water uptake through the root zone.

Clearly, soil conditions (soil suction, hydraulic conductivity and penetration resistance), the type of vegetation (root distribution, the relative proportion of active roots and leaf area) and atmospheric conditions (net solar radiation, temperature, humidity, etc.) affect the rate of root water uptake, and hence transpiration. To formulate a comprehensive equation for calculating the rate of root water uptake, the interaction between the above features should be taken into account. However, owing to the complexity of this problem, some of the above features are simplified by the authors, as summarised below.

- (a) As the potential transpiration rate (potential water discharge rate) is used instead of the difference between the water potential of root and soil, the hydraulic conductivity is not directly included in the transpiration rate.
- (b) The penetration resistance of the soil influences root distribution; however, this effect is considered only indirectly through the root distribution effect.
- (c) In the assessment of water uptake rate, the active roots are the most important: thus their relative proportion is considered in the root distribution effect.
- (*d*) As the potential transpiration rate relates to the interaction between the atmosphere and foliage, the leaf area (canopy) is included in the

potential transpiration. The influences of net solar radiation, air density, temperature and humidity changes are ignored in the model proposed by the authors.

In brief, the three

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independent features that are considered in detail in the root water uptake model are soil suction, root distribution and potential transpiration. In order to establish a rigorous formula for estimating the actual transpiration or root water uptake, the abovementioned factors have been quantified through relevant equations in the development of the proposed root water uptake model. In this study, a finite element analysis is employed to predict the soil suction profile and the associated ground surface settlement, based on the proposed governing equations. The FEM results are then compared with three published case studies to verify the numerical predictions.

2. CONCEPTUAL DEVELOPMENT

The key variable for estimating the transpiration rate is the rate of root water uptake, which depends on the geological, hydrological and meteorological conditions. Fig. 1 shows a schematic illustration of the soil-plant-atmosphere interaction. The rate of transpiration depends on the rate of root water uptake:



where T(t) is the transpiration rate at time t; S(x, y, z, t) is the root water uptake at point (x, y, z) at time t; and, if V(t) is the volume of root zone at time t, dV denotes a small volumetric change.

The details of each single root and its interaction with the surrounding soil are required to identify the microscopic interaction between the soil and the root system. A macroscopic approach is adopted in this study, which considers the integrated properties of the entire root system, assuming that both soil and roots are continuous media. Therefore the root water uptake is considered as a volumetric sink term in the flow continuity equation, which can be defined as the volume of water extracted per unit bulk volume of soil per unit time. The soil water flow differential equation, including the sink term, S(x, y, z, t), can then be written as





Fig. I. Schematic sketch of soil-plant-atmosphere system; (a) transpiration; (b) soil-plant-atmosphere interaction; (c) active and main roots

where $\theta = V_w/V$ is the volumetric moisture content ($V_w =$ volume of water, V = total volume); ∇ is the divergence vector; ψ is the soil suction; *k* is the hydraulic conductivity; and *z* is the vertical coordinate (downward is positive).

2.1. Soil suction

Soil suction resists water movement and affects the transpiration rate: the greater the soil suction, the more difficult it becomes for the soil water to be discharged by the roots. Soil suction is a reduction factor for the potential transpiration rate, and as a general algebraic expression, the root water uptake can be written as a function of the maximum possible root water uptake, S_{max} , and matric suction, ψ :

$$S(x, y, z, t) = g(\psi, S_{\max})$$

As suggested by Feddes *et al.*,⁵ the implicit function, $g(\psi, S_{\text{max}})$ can be expressed as two separate functions:

$$S(x, y, z, t) = S_{\max}(x, y, z, t)f(\psi)$$

where $f(\psi)$ is the root water uptake reduction factor as a function of matric suction.

To calculate $f(\psi)$, different approaches have been recommended by researchers. The equation suggested by Feddes *et al.*,⁶ which is a simple and appropriate formula⁷ to determine soil suction effects, is used in this study. Various other equations proposed for $f(\psi)$ are given in Table 1. The relationship between water uptake and soil suction suggested by Feddes et al.⁶ is shown in Fig. 2. Referring to this figure, $f(\psi)$ can be written as

 $f(\psi) = I$





	$f(\psi)=0$	$\psi < \psi_{\mathrm{an}}$
	$f(\psi) = 1$	$\psi_{\mathrm{an}} \leqslant \psi < \psi_{\mathrm{d}}$
5	$f(\psi) = rac{\psi_{ ext{w}} - \psi}{\psi_{ ext{w}} - \psi_{ ext{d}}}$	$\psi_{\rm d} \leq \psi < \psi_{\rm w}$
	$f(\psi)=0$	$\psi_{W} \leqslant \psi$)

where ψ_{w} is the soil suction at wilting point, the suction limit at which a particular vegetation is unable to draw moisture from the soil; $\psi_{\rm d}$ is the highest value of ψ ; and $\psi_{\rm an}$ (soil suction at anaerobiosis point) is the lowest value of ψ at S = S_{max} , where S_{max} is the maximum rate of root water uptake. An experimental study by Kutilek and Nielsen¹¹ also confirms the same trend as given by Feddes *et al.*,⁶ as illustrated in Fig. 2.

2.2. Root distribution

When access to water is not limited, the distribution of transpiration within the root depends on the root density distribution and the potential transpiration distribution within the root zone. Hence:

 $f(\theta) = \frac{0.0001}{0.0001 + 0.9999 \mathrm{e}^{-1.45\theta}}$ Radcliffe et al.4 θ = volumetric soil moisture content, $f(\theta) = f(\psi)$ Molz⁸ $f(\psi)\mathsf{G}(\beta) = \frac{\theta(z, t)L(z, t)\big[\psi(z, t) - \phi_x(t)\big]}{\binom{v(t)}{2}\theta(z, t)L(z, t)\big[\psi(z, t) - \phi_x(t)\big]\mathsf{d}z}$ $\theta(z, t) =$ volumetric soil water content, L(z, t) = length of roots per unit soil volume, $v(t) = \text{depth of root zone}, \phi_x(t)$ = water potential of root xylem, $G(\beta)$ = root density distribution function $f(\psi) = \frac{k(\psi)(\psi_r - \psi)}{k(\psi_0)(\psi_r - \psi_0)} \quad |\psi| > |\psi_0|$ Perrochet⁹ $k(\psi) =$ hydraulic conductivity of soil, $\psi =$ soil suction

 $|\psi| \leq |\psi_0|$

Novak¹⁰

$$f(\psi) = I \qquad \psi_{an} < \psi \le \psi_{d}$$
$$f(\psi) = \frac{\overline{\psi}}{\psi(\overline{z})} \quad \psi_{d} < \psi < \psi_{w}$$

 $f(\psi) = 0$ $\psi_w \leq \psi$

around roots, $\psi_r =$ root suction generated by plant, $\psi_0 =$ soil suction around roots from which transpiration rate starts to diminish

 $\psi_{\rm w}=$ soil suction at wilting point, $\psi_{\rm d}=$ highest value of ψ at which S = S_{max}, $\psi_{\rm an}$ = soil suction at anaerobiosis point, $\overline{\psi}=$ average value of ψ in depth interval where $\psi_{d} < \psi < \psi_{w}$

Table I. Root water uptake reduction factors suggested by various researchers

where $G(\beta)$ is a function associated with the root density distribution; $F(T_P)$ is a function to take the potential transpiration distribution into account; and $\beta(x, y, z, t)$ is the root density. Substituting equation (6) into equation (4) gives

$$S(x, y, z, t) = f(\psi)G(\beta)F(T_{\rm P})$$

A traditional agronomical belief holds that the root area of trees below the ground may be as extensive or less than the average canopy above. Some researchers^{3,12–14} have proposed that the total cross-sectional area of roots, including the depth and distance from the trunk, can be determined as an exponential relationship. It is assumed by symmetry that the maximum root density is on a circle with $r = r_0(t)$ at a depth of $z = z_0(t)$, and that the root density decreases exponentially from this maximum value in both the vertical and radial directions. Therefore:

$$\beta(r, z, t) = \beta_{\max}(t) e^{-k_1|z-z_0(t)|-k_2|r-r_0(t)|}$$

where $\beta_{\max}(t)$ is the maximum root density at time *t*, and k_1 and k_2 are empirical coefficients that depend on the tree root system and type.

For a given transpiration rate, the rate of water uptake from any particular unit volume of wet soil is proportional to β . As suggested by Landsberg, ¹⁴ this relationship is *non-linear*. Based on agronomical research, an *asymptotic* relationship may be assumed for root water uptake, such as the curve shown in Fig. 3. However, there is an uncertainty in this relationship when the roots become widely separated, which can often be the case when the tree roots penetrate deeply into the soil.

As the hyperbolic tangent function represents a non-linear asymptotic curve, the following equation is suggested for the root density correction factor, $G(\beta)$:





where k_3 is an empirical coefficient. The denominator is applied to this factor to normalise the function within the root zone, where

$$\int_{V(t)} G(\beta) \mathrm{d} V = 1$$

To define the overall root zone shape where the active and the main roots unite (Fig. 1(c)), it is assumed that $r_0 = z_0 = 0$: hence equation (8) can be rewritten as

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$$\beta(r, z, t) = \beta_{\max}(t) e^{-k_1 z - k_2 r}$$

The boundary condition to determine the root zone shape is then given by

$$\frac{\beta(r, z, t)_{\text{boundary}}}{\beta_{\text{max}}(t)} = c_1 = \text{constant}$$

where

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$$c_1 = e^{-k_1 z - k_2 r}$$

or

$$\ln c_1 = -k_1 z - k_2 r$$

Assuming $\ln c_1 = c_2$, then

$$c_2 = -k_1 z - k_2 r$$

Equation (14) is linear and implies that, based on the exponential distribution of roots, the root zone shape is an inverted cone, as shown in Fig. 4 in the r-z plane.

2.3. Potential transpiration rate

The potential transpiration is defined as the evaporation of water from the plant tissues to the atmosphere when the soil moisture content is unrestricted. Therefore the maximum possible root water uptake is called the potential transpiration, which relates to meteorological characteristics as well as to the condition and the age of the plant. Direct measurement of potential transpiration is very difficult: hence indirect estimation is usually carried out in practice. Thus:

 $T_{\rm P} = ET_{\rm P} - E_{\rm P}$

where $T_{\rm P}$ is the potential transpiration, $ET_{\rm P}$ is the potential



evapotranspiration (from both plant and soil), and E_P is the potential evaporation (from the soil surface only).

To estimate ET_P and E_P , a combination of energy balance and mass balance methods can be used. Penman, ¹⁵ Monteith ¹⁶ and Rijtema¹⁷ developed appropriate methods for determining the potential transpiration through potential evapotranspiration and evaporation. For example, potential transpiration based on Penman–Brutsaert's model, further described by Lai and Katual, ¹⁸ is given by

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$$T_{\rm P} = W(R_{\rm n} - G) + (1 - W)E_{\rm A}$$

where T_P is the potential latent heat flux; R_n is the net radiation; G is the soil heat flux; W is a dimensionless weighted function that depends on the slope of the saturation vapour pressure–temperature curve and the psychometric constant; and E_A is the atmospheric drying power function.

Referring to the model proposed by Nimah and Hanks,¹⁹ it can be inferred that the potential transpiration is not distributed uniformly within the root zone, and that a linear distribution with depth for potential transpiration is a more appropriate distribution. Accordingly, the following equation is suggested to take the effect of potential transpiration into account:

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$$F(T_{\rm P}) = \frac{T_{\rm P}(1 + k_4 z_{\rm max} - k_4 z)}{\int_{V(t)} G(\beta)(1 + k_4 z_{\rm max} - k_4 z) \mathrm{d}V}$$

where $G(\beta)$ is given by equation (9), and k_4 is an empirical coefficient to take into account the effect of depth on the transpiration rate. The denominator of equation (17) is applied to satisfy the potential transpiration mass balance.

As a result, according to equation (7), the rate of root water uptake, S(x, y, z), can be estimated by multiplying three functions that represent the soil suction effect: $f(\psi)$; the root density effect, $G(\beta)$; and the potential transpiration effect, $F(T_P)$. To calculate $f(\psi)$, equation (5) suggested by Feddes *et al.*⁶ to determine the effects of soil suction is used in this study. In order to determine $G(\beta)$, equation (9) is employed, and to estimate $F(T_P)$, equation (17) in conjunction with equation (16) is adopted. By substituting equation (7) in equation (2) and solving the differential equation, water movement within unsaturated soil caused by transpiration can be quantified.

3. NUMERICAL IMPLEMENTATION

Since Richards²⁰ presented his theory for flow in unsaturated soils, various aspects of transitory water distribution in porous media have been widely investigated. During the past few decades, governing equations describing water flow in partially saturated soil have also been developed comprehensively. These equations are mainly non-linear partial differential equations where some simplifications can lead to meaningful closed-form solutions, given distinct boundary and initial conditions. As a fluid passes through a porous medium, a coupled flow–deformation analysis is required to capture the interaction among the soil, air and water phases. The governing equations for pore fluid diffusion–deformation are a combination of equation (2) and the relevant elasto-plastic deformation equations.

The basic effective stress theory adopted in this study to analyse unsaturated soil behaviour is inspired after Bishop:²¹

$$\sigma_{ij}^{\,\prime}=\sigma_{ij}-u_{\mathrm{a}}\delta_{ij}+\chi(u_{\mathrm{a}}-u_{\mathrm{w}})\delta_{ij}$$

where σ'_{ii} is the effective stress of a point on a solid skeleton; σ_{ij} is the total stress in the porous medium at the point; u_a is the pore air pressure; u_w is the pore water pressure; δ_{ij} is Kronecker's delta (= 1 when i = j and 0 when $i \neq j$); and χ is the effective stress parameter, attaining a value of unity for saturated soils and zero for dry soils. In unsaturated soil mechanics the term $(u_a - u_w)$ is usually called matric suction. The validity of Bishop's effective stress concept for predictions of shear strength and volume change in unsaturated soils has recently been confirmed by Khalili et al.²² and Lu and Griffiths.²³ As mentioned by Bishop,²¹ the value of χ is related to the degree of saturation and soil structure. Khabbaz²⁴ presented a relationship for γ as a function of matric suction and the air entry value. The degree of saturation is associated with matric suction through the soil water characteristic curve (SWCC). The air entry value, related to the soil structure, can be determined using the SWCC.

The non-linear finite element program ABAQUS was employed to investigate soil suction development induced by tree transpiration. ABAQUS is a general-purpose finite element program for analysing engineering problems, with the capability of coupled pore fluid–stress analysis for partially saturated soil.²⁵ In this study, ABAQUS code using the effective stress-based equations has been employed for the numerical analysis. The results of the ABAQUS program were first evaluated against the results for the soil suction profile in the vicinity of a row of trees presented by Fredlund and Hung.²⁶ They applied the theory of stress state variables for unsaturated soils, and analysed the problem with a differential equation solver, PDEeas2D.

In order to verify the proposed mathematical model for root water uptake rate, two case histories have been considered. In the first case, the soil suction development in the vicinity of a spotted gum tree has been simulated. Then the ABAQUS predictions have been compared with the measured field data reported by Jaksa *et al.*²⁷ The second case history is associated with the results of the field moisture content measured in the vicinity of a single lime tree reported by Biddle.²⁸ In both case studies reasonable assumptions have been made for a number of required parameters of the model that were not available in the reported data. The key parameters required to be measured or estimated accurately for predicting the behaviour of expansive clays in the vicinity of vegetation are potential transpiration (T_P), saturated permeability (k_s) and wilting point suction (ψ_w). Moreover, the other parameters including the relevant soil properties and root zone characteristics should be measured accurately either in the laboratory or in the field.

3.1. Initial evaluation of numerical model

The initial evaluation exercise deals with the deformation and soil suction profile near a line of trees using a two-dimensional finite element mesh (Fig. 5), based on ABAQUS code. The mesh consists of 4-noded linear strain quadrilateral elements (CPE4P) with four displacement and four pore pressure nodes positioned at the corners of each element. The entire FE mesh consists of 13 041 nodes and 12 800 elements. As the model parameters should be exactly the same as those used by Fredlund and Hung²⁶ for the purpose of comparison, the coefficient of soil permeability (*k*) is described by equation (19) with a saturated coefficient of permeability (*k*_s) equal to 5·79 × 10⁻⁸ m/s, and the parameters *a* and *n* are taken to be 0·001 and 2 respectively.²⁹

$$k = \frac{k_{\rm s}}{1 + a(\psi/\rho_{\rm w}g)^n}$$

Based on typical field measurements, the initial void ratio of the soil was assumed to be unity. In the same way as Fredlund and Hung,²⁶ the initial matric suction was estimated on the basis of a constant water table at 15 m depth. The discharge of water through the tree roots decreased from 15 mm/day at 1 m depth, to 0 mm/day at 3 m depth following a linear relationship. The soil water characteristic curve employed in this study is shown in Fig. 6.



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The type of soil is normally consolidated clay, and its consolidation behaviour can be defined by

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$$\mathrm{d}e^{\mathrm{el}} = C_{\mathrm{c}} \ln\left(\frac{p_0 + \mathrm{d}p}{\mathrm{d}p}\right)$$

where de^{el} denotes the change of void ratio in the element; C_c is the compression index; p_0 is the initial mean effective stress; and dp is the mean effective stress change on the soil skeleton. For overconsolidated clays C_c is replaced by the swelling index, C_s . In the current analysis, the authors have employed the general theory of effective stress for unsaturated soil (originally conceptualised by Bishop²¹) that is implemented in the ABAQUS source code, rather than the distinctly different stress state variables employed by Fredlund and Hung.²⁶ Based on settlement data, an equivalent compression index of 0.15 and a Poisson's ratio of 0.30 have been assumed for the ABAQUS analysis in lieu of Fredlund and Hung's²⁶ coefficients.

Figures 7 to 9 indicate the contours of the initial matric suction after 1 month, 6 months and 1 year, respectively, based on the FE analysis. Fig. 10 shows a comparison between the results of the equilibrium matric suction obtained from Fredlund and Hung analysis²⁶ and the current model, and Fig. 11 shows a comparison of the vertical settlement results. As Figs 10 and 11 indicate, the numerical results are in acceptable agreement with Fredlund and Hung's analysis.²⁶ The main reason for the notable disparity of the predicted results is the two distinctly different unsaturated soil models utilised in the current study (Bishop's effective stress theory for unsaturated soils in ABAQUS, and that of Fredlund and Hung, i.e. stress state variables for unsaturated soil). As these two theories influence the soil volume change in different ways, the disparities are more evident in the settlement contours than in the suction profiles (Figs 10 and 11). This initial evaluation exercise confirms that if the relevant parameters are known, the current finite element model is appropriate to predict the generated matric suction and the associated deformation caused by tree transpiration.

3.2. Verification of proposed root water uptake model

3.2.1. Case study 1. This case history is associated with the results of field suction, measured in the vicinity of a single





20 m high gum tree (*Eucalyptus maculata*) in Adelaide, South Australia, reported by Jaksa *et al.*²⁷ The tree is located in a relatively flat, open and grassed reserve of clay soil. Table 2 shows the estimated parameters used in the finite element analysis, based on available literature. Seasonal effects have been simplified by considering the average annual potential transpiration rate. As reported by Jaksa *et al.*,²⁷ four boreholes, 40 mm in diameter, were drilled to a depth of 4 m along a line at radial distances of 2·2, 5, 10 and 20 m from the tree trunk. The field study was conducted in November 2000. Total soil suction measurements were taken in the laboratory on cored samples using a transistor psychrometer.

The numerical analysis in this case, similar to the evaluation exercise, is based on the effective stress theory of unsaturated soils incorporated in ABAQUS. The authors' theoretical model representing the rate of root water uptake distribution within the root zone was included in the FE analysis through appropriate Visual Fortran subroutines. The main subroutine includes the rate of root water uptake as moisture flux boundary, applied along the top side of all elements within the root zone. In other words, equation (7) incorporating equations (5), (8), (9) and (17) has been implemented in the numerical model as boundary flux, which can determine the rate of root water uptake within the root zone at each time increment. In this study it is assumed that the tree is well developed, and that the dimensions have not changed during the time interval considered in the analysis. A two-dimensional plane strain finite element mesh with 4-node bilinear displacement and pore pressure elements (CPE4P) was used to model the development of soil suction. The overall mesh consists of 6561 nodes and 6400 elements, and the geometry and boundary conditions of the model are schematically illustrated in Fig. 12. As the geometry of the proposed mesh is considered sufficiently large, there may be marginal implications associated with the elements located at the far sides of the mesh. Because of symmetry, a zero flux boundary was applied along the left boundary of the mesh. It is assumed that rainfall







Fig. 11. Contours of vertical displacement (mm) in vicinity of a row of trees: (a) Fredlund and Hung;²⁶ (b) current finite element analysis

and evaporation can balance each other: thus a 'no water inflow' condition is applied on the top of the soil surface.

The finite element analysis was conducted in two stages:

geostatic loading. This stage is used to ensure that the analysis begins from a state of equilibrium under geostatic loading.(b) Consolidation: for transient response analysis of partially.

conditions for the steady-state equilibrium of ground under

(a) Geostatic: for checking and modifying the defined initial

(b) *Consolidation*: for transient response analysis of partially saturated soil under transpiration. To avoid non-physical

Parameter	Value	Reference	Comments
ψ _{an}	4·9 kPa	Feddes et al. ⁵	Clayey soil with air content of 0.04
ψ _d	40 kPa	Feddes et al. ^{5,6}	40 $<\psi_{\rm d}<$ 80 kPa
k ₁	1·5	Knight ³⁰	Root shape coefficient associated with vertical coordinate
k ₂	2·0	Knight ³⁰	Root shape coefficient associated with radial coordinate
T _P	9 mm/day	Dunin et al. ³¹	Regularly watered condition



oscillations and also convergence problems caused by nonlinearities, this stage included a time-dependent analysis using 1-day intervals for a 1-year period with continuous root water uptake.

The coefficient of unsaturated soil permeability has been calculated based on the following equation with a saturated coefficient of permeability, $k_s = 5 \times 10^{-9}$ m/s:

 $k = k_{\rm s} \times S_{\rm r}^3$

where S_r is the degree of saturation.

The soil water characteristic curve used in this analysis is based on a relationship suggested by Zapata et al.32 A family of curves for different $w \times PI$ is shown in Fig. 13, where w is the fraction of soil passing sieve #200 (75 μ m) as an index between 0 to 1, and PI is the plasticity index.

The soil is assumed to be an overconsolidated clay, given the applied stress range. In addition to the material properties and parameters given earlier in Table 2, the other assumed



Parameter	Value	Comments
ro	7 m	Radial coordinate of maximum root density point
z ₀	3 m	Vertical coordinate of maximum root density point
$\beta_{\max}(t)$	25 m ⁻²	Maximum root length density ³⁰
k ₃	$8.74 imes10^{-2}~{ m m}^{-1}$	Taken from general shape of root suggested by Landsberg ¹⁴
k ₄	0	In this case, it is assumed that potential transpiration is distributed uniformly
r _{max}	15 m	Estimated from field data ²⁷ ($10 < r_{max} < 20$)
Zmax	9 m	Estimated from field data ²⁷
γd	18⋅6 kN/m³	Typical expansive earth soil in Adelaide, Australia
C _s	0.05	Average value for clayey soils in vicinity of building foundations
ν	0.30	Typical value for clayey soils
k _s	5 imes 10 ⁻⁹ m/s	Typical value for clayey soils in vicinity of building foundations
$w \times PI = passing \#200 \times plasticity index$	50	High-plasticity clayey soil
ψ_{w}	3000 kPa	Estimated from field measurements ^{27,33} (1550 kPa $\leq \psi_w \leq$ 3100 kPa)
Initial void ratio, e ₀	I	Typical clay soil

parameters used in the finite element analysis are specified in Table 3. According to the field measurements of soil suction measured by Jaksa *et al.*,²⁷ the initial matric suction is assumed to be hydrostatic. as shown in Fig. 14. Owing to high matric suction within the soil close to the surface, the depth of the tree roots is considerably greater than that considered in the previous analysis.²⁶

The predicted steady-state soil matric suction based on the finite element analysis is presented in Fig. 15, and the measured values reported by Jaksa et al.²⁷ are plotted in Fig. 16 for four different depths. As shown in Fig. 15, in comparison with the suction profile presented by Fredlund and Hung (Fig. 10), the numerical analysis (capturing the root water uptake variation in the soil matrix) indicates that the maximum suction change occurs at a point away from the tree trunk. It can be noted that the maximum suction change takes place at the location of the maximum root density, as computed by the model. Comparison between Figs 15 and 16 indicates that the maximum root density occurs at the point (r_0 , z_0) = (7 m, 3 m). As direct measurements are not available for points at which r = 7 m, the interpolated (estimated) field values are plotted in Fig. 16 with dashed lines. In this case, the interpolated value for the radial distance at which the maximum suction change occurs (i.e. r = 7 m) is in accordance with Jaksa *et al.*,²⁷ who pointed out that the maximum suction change would occur at a radial distance of 5–10 m from the tree trunk. Comparison between the field data (Fig. 16) and numerical predictions (Fig. 15) shows that underneath the tree trunk smaller suction values are observed compared with the predictions. One possible reason for this could be related to irrigation around the tree trunk or the collection of rainwater beside the trunk, resulting in significant reduction of suction. Field measurements also indicate that the soil suction varies considerably with depth, whereas the numerical results indicate less sensitivity to depth. It is of relevance to note that, in the numerical analysis, a homogeneous soil profile has been assumed in Fig. 15. In contrast, a heterogeneous soil profile can influence the root









distribution, thereby affecting the suction distribution significantly. In Fig. 15, as the soil is assumed to be homogeneous, the effect of depth seems to be relatively insignificant, whereas in Fig. 16 the actual field data are probably influenced by the soil heterogeneity, which is reflected by the depth sensitivity of the measured suction.

Figures 17 and 18 depict the ground settlement at various depths for this case study after 1 month and 1 year respectively. In this study only the suction-related settlement is considered. The results show that, after 1 year of continuous transpiration, the rate of change in matric suction $(d\psi/dt)$ is less than 10^{-6} kPa/s, which is considered as the steady-state (equilibrium) condition. It can be seen that the movements near the ground surface would be considerable after 1 year within a radial distance of about 20 m around the tree trunk. As shown in Fig. 17, the maximum ground settlement after 1 month occurs near the point (r_0 , 0) (i.e. on the surface, when $r = r_0 = 7$ m).

Figure 18 indicates that the maximum ground settlement under steady-state conditions takes place below the tree trunk after 1 year. A single tree can influence the ground for a significant distance. For example, if the maximum allowable foundation





settlement is assumed to be 25 mm, then the selected single tree can influence the foundation within a distance of 20 m. The ground settlement would decrease rapidly with radial distance up to 20 m. Comparison between Figs 17 and 18 shows that the radius of the influence zone (in which the ground settlement is greater than 25 mm) increases from about 15 m at the first month to more than 20 m after 1 year. Furthermore, because of the axisymmetric boundary flow under the trunk (left side of the mesh in Fig. 12), the point of the maximum settlement moves toward the tree axis. The predicted displacements, shown in Fig. 18, have the same pattern of settlement as those monitored by Bozozuk and Burn.³⁴ On the ground surface, the 158 mm vertical settlement at the tree trunk location decreases to about 40 mm at 20 m away from the tree trunk (Fig. 18). In addition, comparison between Figs 17 and 18 indicates that the rate of settlement in the first month after starting the transpiration is much faster than the corresponding rate after 1 year, as expected. For instance, on the ground surface at the tree trunk location, the value of settlement of 43 mm in the first month gradually increased to 158 mm after 12 months.

3.2.2. Case study 2. The second case history is related to the results of the field moisture content measured in the vicinity of a single 14 m high lime tree in Milton Keynes, UK, reported by Biddle.²⁸ The tree is located in a mown grass area of Boulder clay. Table 4 shows the estimated parameters used in the finite element analysis, based on the available data in the literature. As reported by Biddle,²⁸ a soil moisture probe incorporating a 70 mCi americium-241/beryllium source was used to measure the moisture content. Also, five access tubes were inserted at varying distances, wherever possible along a single radius. The distances from the tree were $1 \cdot 4 \text{ m}$, $2 \cdot 8 \text{ m}$, $5 \cdot 6 \text{ m}$ and $11 \cdot 2 \text{ m}$. A comparison access tube was located at a distance of twice the tree height (28 m), which is assumed to be unaffected by the tree root suction.

The geometry and boundary conditions of the finite element model are schematically illustrated in Fig. 19. Flow and displacement conditions around the soil mesh are similar to those in case study 1. The overall mesh consists of 1326 nodes and 1250 elements. A finite element analysis similar to case study 1 was conducted in two stages: geostatic and consolidation. The root water uptake model was implemented in the numerical scheme via a Visual Fortran subroutine similar to case study 1. The soil water characteristic curve shown in Fig. 13 was employed in the analysis of this case study also. The osmotic suction effect was assumed to be negligible. The material properties and the main parameters used in this analysis have been given earlier in Table 4; the other required parameters are presented in Table 5.

The predicted steady-state soil matric suction profiles at depths of 0.5, 1 and 1.5 m below the ground surface based on the finite element analysis are shown in Fig. 20. The maximum change in the soil matric suction occurs at 0.5 m depth, which is also the location of the maximum root density (i.e. $z = z_0 = 0.5$ m). The predicted soil suction changes as shown in Fig. 20

Parameter	Value	Reference	Comments
ψ_{an}	4·9 kPa	Feddes et al. ⁵	Clay soil with air content of 0.04
ψ_{w}	1500 kPa	Feddes et al. ⁵	$1500 \leqslant \psi_w \leqslant 2000 \text{ kPa}$
ψ_{d}	40 kPa	Feddes et al. ⁶	$40 < \psi_d < 80 \text{ kPa}$
γ	21 kN/m ³	Powrie et al. ³⁵	Typical value for Boulder clay
k_{s}	10 ^{−10} m/s	Lehane and Simpson ³⁶	Typical value for Boulder clay
PI	23	Biddle ²⁸	Measured
e_{0}	0·60	Powrie et al. ³⁵	Typical value for Boulder clay
C_{c}	0·13	Skempton ³⁷	Typical value for Boulder clay

Table 4. Parameters applied in finite element analysis of case study 2



r_0 6 mRadial coordinate of maximum root density point z_0 0.50 mVertical coordinate of maximum root density point $\beta_{max}(t)$ 25 m ⁻² Taken from general shape or root suggested by Landsberg ¹⁴ k_3 0.0874 m ⁻¹ As above k_4 0.014Coefficient of potential transpiration distribution r_{max} 9 mEstimated from field data ²⁸ (7 m < $r_{max} < 11$ m) z_{max} 1.5 mEstimated from field data ²⁸ k_1 10Coefficient of vertical root distribution v 0.30Coefficient of horizontal root distribution v 0.30Typical value for clayey soils T_P 3 mm/dayRate of potential transpiration	Parameter	Value	Comments
z_0 0.50 mVertical coordinate of maximum root density point $\beta_{max}(t)$ 25 m ⁻² Taken from general shape or root suggested by Landsberg ¹⁴ k_3 0.0874 m ⁻¹ As above k_4 0.014Coefficient of potential transpiration distribution r_{max} 9 mEstimated from field data ²⁸ (7 m < r_{max} < 11 m)	ro	6 m	Radial coordinate of maximum root density point
$ \begin{array}{cccc} \beta_{\max}(t) & 25 \ \mathrm{m}^{-2} & \text{Taken from general shape or root suggested by Landsberg}^{14} \\ k_3 & 0.0874 \ \mathrm{m}^{-1} & \text{As above} \\ k_4 & 0.014 & \text{Coefficient of potential transpiration distribution} \\ r_{\max} & 9 \ \mathrm{m} & \text{Estimated from field data}^{28} (7 \ \mathrm{m} < r_{\max} < 11 \ \mathrm{m}) \\ z_{\max} & 1.5 \ \mathrm{m} & \text{Estimated from field data}^{28} \\ k_1 & 10 & \text{Coefficient of vertical root distribution} \\ k_2 & 0.30 & \text{Coefficient of horizontal root distribution} \\ \nu & 0.30 & \text{Typical value for clayey soils} \\ T_{\mathrm{P}} & 3 \ \mathrm{mm/day} & \text{Rate of potential transpiration} \end{array} $	Zo	0.50 m	Vertical coordinate of maximum root density point
k_3 0.0874 m^{-1} As above k_4 0.014 Coefficient of potential transpiration distribution r_{max} 9 mEstimated from field data ²⁸ (7 m < r_{max} < 11 m)	$\beta_{max}(t)$	25 m ⁻²	Taken from general shape or root suggested by Landsberg ¹⁴
k_4 0.014Coefficient of potential transpiration distribution r_{max} 9 mEstimated from field data ²⁸ (7 m < r_{max} < 11 m) z_{max} 1.5 mEstimated from field data ²⁸ k_1 10Coefficient of vertical root distribution k_2 0.30Coefficient of horizontal root distribution ν 0.30Typical value for clayey soils T_P 3 mm/dayRate of potential transpiration	k ₃	0∙0874 m ^{−1}	As above
r_{max} 9 mEstimated from field data ²⁸ (7 m < r_{max} < 11 m) z_{max} 1.5 mEstimated from field data ²⁸ k_1 10Coefficient of vertical root distribution k_2 0.30Coefficient of horizontal root distribution ν 0.30Typical value for clayey soils T_P 3 mm/dayRate of potential transpiration	k4	0.014	Coefficient of potential transpiration distribution
z_{max} I \cdot 5 mEstimated from field data ²⁸ k_1 10Coefficient of vertical root distribution k_2 0.30Coefficient of horizontal root distribution ν 0.30Typical value for clayey soils T_P 3 mm/dayRate of potential transpiration	r _{max}	9 m	Estimated from field data ²⁸ (7 m $< r_{max} < 11$ m)
k_1 I0Coefficient of vertical root distribution k_2 0.30Coefficient of horizontal root distribution ν 0.30Typical value for clayey soils T_P 3 mm/dayRate of potential transpiration	Z _{max}	l∙5 m	Estimated from field data ²⁸
	k ₁	10	Coefficient of vertical root distribution
ν0.30Typical value for clayey soilsTP3 mm/dayRate of potential transpiration	k ₂	0.30	Coefficient of horizontal root distribution
T _P 3 mm/day Rate of potential transpiration	ν	0.30	Typical value for clayey soils
	TР	3 mm/day	Rate of potential transpiration
Passing #200 55% Typical value for Boulder clay	Passing #200	55%	Typical value for Boulder clay

have the same pattern as those monitored by Jaksa *et al.*²⁷ As presented in Tables 2 and 5, the root length density distribution in the second case study is assumed to be more horizontal (flatter) than the first case study. As a result, the soil suction



reduction will also be flatter, as shown in Fig. 20. Fig. 21 shows a comparison between the field measurements and the predictions of the numerical model for moisture content reduction. The numerical results incorporating the authors' root water uptake model are in acceptable agreement with the field measurements reported by Biddle.²⁸ According to Fig. 21, field measurements of moisture content reduction are noticeably different from the finite element predictions at approximately 6–8 m from the trunk. This is not surprising, given the simplicity of the assumptions with regard to the shape of the root zone. Furthermore, as the foliage alters the uniform distribution of rainfall, moisture content is expected to increase at the canopy edges (say approximately 6–8 m from the tree trunk), thereby probably contributing to the disparity between the field data and finite element predictions.

4. CONCLUSIONS

In this study, a mathematical model has been developed for predicting the rate of tree root water uptake. The main factors affecting the rate of root water uptake, namely (a) soil suction in the vicinity of roots, (b) root density and (c) potential transpiration, were taken into account to establish an appropriate expression for actual transpiration or root water uptake. The authors' numerical analysis was implemented in the ABAQUS finite element code to examine



the soil suction distribution and moisture content profile in the vicinity of a row of trees. The evaluation of the numerical results was successfully examined by comparing the ABAQUS output with a similar analysis performed by Fredlund and Hung.²⁶ The disparity of results between the two methods was attributed to the distinctly different unsaturated soil model used by the authors in ABAQUS in comparison with the Fredlund and Hung approach.²⁶ Then two case histories were considered to verify the authors' root water uptake distribution model.

In the first case study, the results of the predicted soil matric suction pressure around a single eucalyptus tree were compared with the available field data reported by Jaksa et al.²⁷ It was shown that the numerical analysis considering the authors' proposed model could predict the location of the maximum suction change away from the tree trunk as measured by Jaksa et al.27 However, direct comparison of suction values is not possible, because the proposed numerical model can predict only the matric suction changes, whereas the measurements obtained by Jaksa et al. 27 were in total suction. Realistic comparison of suction changes is possible only if the matric suction component of the total suction is accurately known. The contours of ground settlement for this case study indicated that the maximum settlement at initial stages occurred near the point with the highest root water uptake rate. However, in the longer term (after 12 months), the maximum ground settlement takes place below the tree trunk.

In the second case study, the results of the predicted reduction in soil moisture content around a single lime tree were compared with the field measurements reported by Biddle.²⁸ In spite of the uncertainties in the assumptions of some soil parameters, the actual tree root distribution and the atmospheric parameters, acceptable agreement was found between the measured and simulated soil moisture distributions.

Although more comprehensive field data are required to fully verify the root water uptake model presented in this paper, the numerical simulation described here is a promising tool for predicting the matric suction induced by tree roots within a soil matrix. A limitation to be noted is that the role of the root zone as a natural means of providing soil reinforcement has not been implemented in the current model.

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