

Numerical Solution of Nonlinear Integro-Differential Equations with Initial Conditions by Bernstein Operational Matrix of Derivative

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ABSTRACT

In this paper, we present a practical matrix method for solving nonlinear Volterra-Fredholm integro-differential equations under initial conditions in terms of Bernstein polynomials on the interval $[0,1]$. The nonlinear part is approximated in the form of matrices' equations by operational matrices of Bernstein polynomials, and the differential part is approximated in the form of matrices' equations by derivative operational matrix of Bernstein polynomials. Finally, the main equation is transformed into a nonlinear equations system, and the unknown of the main equation is then approximated. We also give some numerical examples to show the applicability of the operational matrices for solving nonlinear Volterra-Fredholm integro-differential equations (NVFIDEs).

Keywords: Bernstein Polynomial; Operational Matrix; Integro-Differential Equations

1. Introduction

Some of the phenomena in physics, electronics, biology, and other applied sciences lead to nonlinear Volterra-Fredholm integro-differential equations. Of course, these equations can also appear when transforming a differential equation into an integral equation [1-7]. In these kinds of equations, the unknown function $u(x)$ appears on both sides; it appears under the integral sign on one side, while it appears as an ordinary derivative on the other side. Investigating the results of nonlinear integro-differential equations, we observe that no obvious algebraic method has been recognized to solve these equations, and thus, approximation methods are used to solve such equations [8-10]. Bernstein polynomials (B-polynomials) have many useful properties [11,12]. In this paper, we use Bernstein polynomials and their resulting operational matrices to solve the following nonlinear Volterra-Fredholm integro-differential equations with the initial conditions indicated as:

$$\begin{aligned} &u''(x) + q(x)u'(x) + r(x)u(x) \\ &= \int_0^x k_1(x,s)[u(s)]^m ds + \int_0^1 k_2(x,s)[u(s)]^\ell ds + f(x), \quad (1) \\ &0 \leq x \leq 1, \quad u(0) = t_0, \quad u'(0) = t_1, \end{aligned}$$

where the functions $q(x), r(x), k_1(x,s), k_2(x,s)$ and $f(x)$ are known, whereas $u(x)$ is unknown. We approximate phrases including derivative of unknown function by operational matrix of derivative D ; and approximate phrases including powers of unknown function by Bernstein polynomial matrix $\phi(x)$. This yields an equation based on the unknown U which is the approximation $u(x)$. To examine the accuracy of the formula, we present some examples. We will show the difference between the accurate and approximation solutions in these examples upon knowing.

2. Bernstein Polynomials and Their Properties

2.1. Definition of Bernstein Polynomials Basis

The Bernstein basis polynomials of degree n are defined by:

$$B_{i,n} = \binom{n}{i} x^i (1-x)^{n-i}, \quad (2)$$

$$0 \leq x \leq 1, \quad i = 0, 1, \dots, n.$$

By using binomial expansion of $(1-x)^{n-i}$, one can show that

$$\binom{n}{i} x^i (1-x)^{n-i} = \sum_{k=0}^{n-i} (-1)^k \binom{n}{i} \binom{n-i}{k} x^{i+k}. \tag{3}$$

With the aid of Equation (3), the Bernstein vector

$$\Phi(x) = [B_{0,n}(x), \dots, B_{n,n}(x)]^T, \tag{4}$$

can be written in the form

$$\Phi(x) = A\Delta_n(x), \tag{5}$$

where

2.2. Function Approximation

A function $f(x)$, square integrable in $(0,1)$, may be expressed in terms of Bernstein basis [13]. In practice, only the first $(n+1)$ terms Bernstein polynomials are considered. Hence, if we write

$$f(x) \cong \sum_{i=0}^n u_i B_{i,n}(x) = U^T \Phi(x), \tag{7}$$

where

$$U^T = [u_0, u_1, \dots, u_n], \tag{8}$$

then

$$U = Q^{-1}(f, \Phi(x)), \tag{9}$$

where Q is said dual matrix of $\Phi(x)$ and is given in [13]. We can also approximate the function $k(x,s) \in L^2([0,1] \times [0,1])$ by double Fourier expansion as follows

$$\begin{aligned} k(x,s) &\cong \sum_{j=0}^n \sum_{i=0}^n k_{ij} B_{i,n}(x) B_{j,n}(s) \\ &= \Phi^T(x) K \Phi(s), \end{aligned} \tag{10}$$

where

$$K = \begin{bmatrix} k_{00} & k_{01} & \dots & k_{0n} \\ k_{10} & k_{11} & \dots & k_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ k_{n0} & k_{n1} & \dots & k_{nn} \end{bmatrix},$$

and k_{ij} elements are given by

$$k_{i,j} = \frac{(B_{i,n}(x), (k(x,s), B_{j,n}(s)))}{(B_{i,n}(x), B_{i,n}(x))(B_{i,n}(s), B_{i,n}(s))}, \tag{11}$$

for $i, j = 0, 1, \dots, n$. Due of (9), we obtain

$$K = Q^{-1}(\Phi(x), (k(x,s), \Phi(s))) Q^{-1} \tag{12}$$

2.3. Operational Matrix of Integration

In performing arithmetic and other operations on Bernstein basis, we frequently encounter the integration of the vector $\Phi(x)$ defined in Equation (4) by

$$\int_0^x \Phi(t) dt \cong P\Phi(x), \tag{13}$$

where P is the $(n+1) \times (n+1)$ operational matrix for integration and is given in [13,14].

2.4. Product Operational Matrix

It is always necessary to evaluate the product of $\Phi(x)$ and $\Phi(x)^T$, which is called the product matrix of Bernstein polynomials basis. Let

$$\Pi(x) = \Phi(x)\Phi(x)^T. \tag{14}$$

Then, multiplying the matrix $\Pi(x)$ with the vector U which is defined in Equation (8), we obtain

$$U^T \Pi(x) = \Phi(x)^T \hat{U}, \tag{15}$$

where \hat{U} is an $(n+1) \times (n+1)$ matrix and is called the coefficient matrix. The details of obtaining this matrix are given in [13].

3. Operational Matrix of Derivative

The differentiation of vector $\Phi(x)$ in Equation (4) can be expressed as:

$$\Phi'(x) = D\Phi(x), \tag{16}$$

where D is the $(n+1) \times (n+1)$ operational matrix of derivatives for Bernstein polynomials. From (5), we have $\Phi(x) = A\Delta_n(x)$ and then

$$A = \begin{bmatrix} (-1)^0 \binom{n}{0} & (-1)^1 \binom{n}{0} \binom{n-0}{1} & \dots & (-1)^{n-0} \binom{n}{0} \binom{n-0}{n-0} \\ \vdots & \vdots & \dots & \vdots \\ 0 & (-1)^0 \binom{n}{i} & \dots & (-1)^{n-i} \binom{n}{i} \binom{n-i}{n-i} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & (-1)^0 \binom{n}{n} \end{bmatrix}, \Delta_n(x) \begin{bmatrix} i \\ x \\ \vdots \\ x^n \end{bmatrix}. \tag{6}$$

$$\Phi'(x) = A \begin{bmatrix} 0 \\ 1 \\ 2x \\ \vdots \\ nx^{n-1} \end{bmatrix}. \tag{17}$$

Defining $(n+1) \times (n)$ matrix V and vector Δ_n^* as

$$V = \begin{bmatrix} 0 & 0 & \dots & 0 \\ 1 & 0 & \dots & 0 \\ 0 & 2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & n \end{bmatrix}, \quad \Delta_n^* = \begin{bmatrix} 1 \\ x \\ x^2 \\ \vdots \\ x^{n-1} \end{bmatrix}, \tag{18}$$

Equation (17) may then be restated as

$$\Phi'(x) = AV\Delta_n^*. \tag{19}$$

We now expand vector Δ_n^* in terms of $\Phi(x)$. We get $\Delta_n^* = B^*\Phi(x)$ where

$$B^* = \begin{bmatrix} A_{[1]}^{-1} \\ A_{[2]}^{-1} \\ A_{[3]}^{-1} \\ \vdots \\ A_{[n]}^{-1} \end{bmatrix}, \tag{20}$$

So

$$\Phi'(x) = AVB^*\Phi(x). \tag{21}$$

Therefore, we have the operational matrix of derivative as

$$D = AVB^*. \tag{22}$$

If we approximate $u(x) \cong U^T\Phi(x)$, then for $n \geq 2$ (n is the order of derivatives), we get

$$u^{(n)}(x) \cong U^T\Phi^{(n)}(x) = U^TD^n\Phi(x). \tag{23}$$

4. Operational Matrices for Numerical Solution of NVFIDE

To obtain the approximate solution of the (1) under the initial conditions, the following matrix method is used. Function $u(x)$ is approximated by using a finite number of terms in (7) as

$$u(x) \cong \sum_{j=0}^n u_j B_{j,n}(x) = U^T\Phi(x). \tag{24}$$

The approximate functions $k_1(x, s)$ and $k_2(x, s)$ by Bernstein polynomials can be framed by:

$$\begin{aligned} k_1(x, s) &\cong \Phi'(x)K_1\Phi(s), \\ k_2(x, s) &\cong \Phi'(x)K_2\Phi(s), \end{aligned} \tag{25}$$

where K_1 and K_2 are defined with (12). For numerical implementation of the method explained in this section, we need to evaluate $[u(s)]^m$ and $[u(s)]^\ell$ where m and ℓ are positive integers, as follows

$$[u(s)]^m \cong U_m\Phi(x), [u(s)]^\ell \cong U_\ell\Phi(x). \tag{26}$$

From (14) and (16), we have

$$\begin{aligned} [u(s)]^2 &\cong (U^T\Phi(X))(U^T\Phi(x)) \\ &= U^T\Phi(x)\Phi(x)^T U \\ &= U^T\hat{U}^T\Phi(x) = U_2\Phi(x), \end{aligned} \tag{27}$$

where the vector $U_2 = U^T\hat{U}^T$ is an $(n+1)$ -vector; then, for $[u(s)]^3$, we get

$$\begin{aligned} [u(s)]^3 &\cong (U^T\Phi(x))(U_2\Phi(x)) \\ &= U^T\Phi(x)\Phi(x)^T U_2^T \\ &= UT\hat{U}_2^T\Phi(x) = U_3\Phi(x). \end{aligned} \tag{28}$$

Therefore, with this method we can approximate $[u(s)]^m$ and $[u(s)]^\ell$ arbitrary m and ℓ .

Suppose that this method holds for $\ell-1$ where $[u(s)]^{\ell-1} = U_{\ell-1}\Phi(x)$. We obtain it for ℓ as follows

$$\begin{aligned} [u(s)]^3 &\cong (U^T\Phi(x))(U_2\Phi(x)) \\ &= U^T\Phi(x)\Phi(x)^T U_2^T \\ &= U^T\hat{U}_2^T\Phi(x) \\ &= U_3\Phi(x). \end{aligned} \tag{29}$$

We have a similar relation for m . So, the components of u_m and u_ℓ can be computed in terms of components of unknown vector U . In this case, for the Volterra and Fredholm part of (1), we have

$$\begin{aligned} &\int_0^x k_1(x, s)[u(s)]^m ds \\ &\cong \int_0^x \Phi^T(x)K_1\Phi(s)U_m\Phi(s) ds \\ &= \Phi^T(x)K_1\int_0^x \Pi(s)U_m^T ds \\ &= \Phi^T(x)K_1\hat{U}_m^T\int_0^x \Phi(s) ds \\ &= \Phi^T(x)K_1\hat{U}_m^T P\Phi(x), \end{aligned} \tag{30}$$

and

$$\begin{aligned} &\int_0^1 k_2(x, s)[u(s)]^\ell ds \\ &\cong \int_0^1 \Phi^T(x)K_2\Phi(s)U_\ell\Phi(s) ds \\ &= \Phi^T(x)K_2\int_0^1 \Phi(s)\Phi(s)^T ds U_\ell^T \\ &= \Phi^T(x)K_2QU_\ell^T. \end{aligned} \tag{31}$$

Also, to approximate the differential part of Equation (1), making use of Equation (23) we have

$$u''(x) + q(x)u'(x) + r(x)u(x) \cong U^T D^2 \Phi(x) + q(x)U^T D\Phi(x) + r(x)U^T \Phi(x). \tag{32}$$

After substituting the approximate Equations (24)-(32) in (1), we get

$$U^T D^2 \Phi(x) + q(x)U^T D\Phi(x) + r(x)U^T \Phi(x) = \Phi^T(x)K_1 \hat{U}_m^T P\Phi(x) + \Phi^T(x)K_2 Q U_l^T + f(x). \tag{33}$$

And also, for the initial conditions, we have

$$U^T \Phi(0) = t_0, U^T D\Phi(0) = t_1. \tag{34}$$

The initial conditions Equation (34) give two linear equations. Since the number of unknowns for a vector U in (33) is $(n+1)$, then we collocate Equation (33) in $n-2+1$ Newton-Cotes points as

$$xp = \frac{2p-1}{2(n+1)}, p = 1, 2, \dots, n-1. \tag{35}$$

For collocating Equation (33), we have used the Newton-Cotes points because of their simplicity and their good utility in our implementation as regards the speed and accuracy of answers. However, we can use other points like the Gauss points, Clenshaw-Curtis points, Lobatto points, etc. Here we present the final system:

$$\begin{aligned} &U^T D^2 \Phi(xp) + q(xp)U^T D\Phi(xp) \\ &+ r(xp)U^T \Phi(xp) - \Phi^T(xp)K_1 \hat{U}_m^T P\Phi(xp) \\ &- \Phi^T(xp)K_2 Q U_l^T = f(xp), \tag{36} \\ &p = 1, 2, \dots, n-1, \\ &U^T \Phi(0) = t_0, U^T D\Phi(0) = t_1. \end{aligned}$$

After solving nonlinear system (36), we get U ; then,

we have the approximate solution of Equation (1).

5. Numerical Examples

To illustrate the effectiveness of the proposed method in the present paper, several examples are presented in this section.

Example 1. Consider the nonlinear Fredholm integro-differential equation [15].

$$\begin{cases} u'(x) = \int_0^1 xy [u(y)]^2 dy + 1 - \frac{1}{4}x, \\ u(0) = 0, \\ u'(0) = 1. \end{cases} \tag{37}$$

The exact solution is $u(x) = x$. The results of proposed method for this example are exhibited in **Table 1** with 4 choices of n . For this complicate NFIDE with a small number of Bernstein basis functions, we get acceptable results.

By applying the method in Section 4, for $n = 4$, we have

$$A = \begin{bmatrix} 1 & -4 & 6 & -4 & 1 \\ 0 & 4 & -12 & -12 & -4 \\ 0 & 0 & 6 & -12 & 6 \\ 0 & 0 & 0 & 4 & -4 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix},$$

$$Q = \begin{bmatrix} 1/9 & 1/18 & 1/42 & 1/126 & 1/630 \\ 1/18 & 4/63 & 1/21 & 8/315 & 1/126 \\ 1/42 & 1/21 & 2/35 & 1/21 & 1/42 \\ 1/126 & 8/315 & 1/21 & 4/63 & 1/18 \\ 1/630 & 1/126 & 1/42 & 1/18 & 1/9 \end{bmatrix},$$

Table 1. Approximate and exact solutions for Example 1.

x	Present method with $n = 2$	Present method with $n = 3$	Present method with $n = 4$	Present method with $n = 5$	Exact solution
0	0	0	0	0	0
0.1	0.1000000000	0.1000000000	0.1000000000	0.1000000001	0.1000000000
0.2	0.2000000000	0.2000000000	0.2000000000	0.2000000004	0.2000000000
0.3	0.3000000000	0.3000000001	0.3000000000	0.3000000009	0.3000000000
0.4	0.4000000000	0.4000000001	0.4000000001	0.4000000016	0.4000000000
0.5	0.5000000000	0.5000000001	0.5000000000	0.5000000022	0.5000000000
0.6	0.6000000000	0.6000000002	0.6000000001	0.6000000030	0.6000000000
0.7	0.7000000000	0.7000000002	0.6999999999	0.7000000052	0.7000000000
0.8	0.7999999999	0.8000000001	0.7999999996	0.8000000146	0.8000000000
0.9	0.8999999999	0.9000000001	0.8999999990	0.9000000428	0.9000000000
1	0.9999999999	1.000000000	0.9999999980	1.000000111	1

$$D = \begin{bmatrix} -4 & -1 & 0 & 0 & 0 \\ 4 & -2 & -2 & 0 & 0 \\ 0 & 3 & 0 & -3 & 0 \\ 0 & 0 & 2 & 2 & -4 \\ 0 & 0 & 0 & 1 & 4 \end{bmatrix},$$

$$P = \begin{bmatrix} \frac{1}{1260} & \frac{617}{2520} & \frac{11}{60} & \frac{517}{2520} & \frac{251}{1260} \\ -\frac{1}{315} & \frac{13}{630} & \frac{4}{15} & \frac{113}{630} & \frac{64}{315} \\ \frac{1}{210} & -\frac{13}{420} & \frac{1}{10} & \frac{97}{420} & \frac{41}{210} \\ -\frac{1}{315} & \frac{13}{630} & -\frac{1}{15} & \frac{113}{630} & \frac{64}{315} \\ \frac{1}{1260} & -\frac{13}{2520} & \frac{1}{60} & -\frac{113}{2520} & \frac{251}{1260} \end{bmatrix},$$

$$K_2 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{16} & \frac{1}{8} & \frac{3}{16} & \frac{1}{4} \\ 0 & \frac{1}{8} & \frac{1}{4} & \frac{3}{8} & \frac{1}{2} \\ 0 & \frac{3}{16} & \frac{3}{8} & \frac{9}{16} & \frac{3}{4} \\ 0 & \frac{1}{4} & \frac{1}{2} & \frac{3}{4} & 1 \end{bmatrix},$$

$$\Phi(x) = \begin{bmatrix} 1-4x+6x^2-4x^3+x^4 \\ 4x-12x^2+12x^3-4x^4 \\ 6x^2-12x^3+6x^4 \\ 4x^3-4x^4 \\ x^4 \end{bmatrix}.$$

We obtain the approximate solutions of the problem for $n = 2, 3, 4$ and $n = 6$ respectively,

$$u_2(x) = x + 0.0000000001x^2,$$

$$u_3(x) = x + 0.000000001x^2 - 0.000000001x^3,$$

$$u_4(x) = x - 0.000000001x^2 - 0.000000006x^3 - 0.000000007x^4,$$

$$u_6(x) = x + 0.00000001x^2 - 0.00000008x^3 + 0.00000032x^4 - 0.00000053x^5 + 0.000000311x^6.$$

Example 2. Consider the nonlinear Fredholm integro-differential equation, as follows [16]:

$$\begin{cases} u'(x) = \int_0^1 (x^2 - y)[u(y)]^2 dy + \frac{5}{4} - \frac{1}{3}x^2, \\ 0 \leq x \leq 1, \\ u(0) = 0, \\ u'(0) = 1. \end{cases} \quad (38)$$

The exact solution is $u(x) = x$. Taking $n = 2$, we compare the obtained solution with exact solution and method [16] in **Table 2**.

By applying the method in Section 4, we have for $n = 2$,

$$A = \begin{bmatrix} 1 & -2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 1 \end{bmatrix}, Q = \begin{bmatrix} 1/5 & 1/10 & 1/30 \\ 1/10 & 2/15 & 1/10 \\ 1/30 & 1/10 & 1/5 \end{bmatrix},$$

$$D = \begin{bmatrix} -2 & -1 & 0 \\ 2 & 0 & -2 \\ 0 & 1 & 2 \end{bmatrix}, P = \begin{bmatrix} \frac{1}{60} & \frac{5}{12} & \frac{19}{60} \\ -\frac{1}{30} & \frac{1}{6} & \frac{11}{30} \\ \frac{1}{60} & -\frac{1}{12} & \frac{19}{60} \end{bmatrix},$$

$$K_2 = \begin{bmatrix} 0 & -1/2 & -1 \\ 0 & -1/2 & -1 \\ 1 & 1/2 & 0 \end{bmatrix}, Q(x) = \begin{bmatrix} 1-2x+x^2 \\ 2x-2x^2 \\ x^2 \end{bmatrix}.$$

We obtain the approximate solutions of the problem $u_2(x) = x$ for $n = 2$.

Example 3. Consider the nonlinear Volterra integro-differential equation, as follows:

$$\begin{cases} u''(x) - xu(x) = \int_0^x x[u(y)]^3 dy - x^2 - \frac{1}{4}x^5, \\ u(0) = 0, \\ u'(0) = 1, \end{cases} \quad (39)$$

where the exact solution is $u(x) = x$. **Table 3** with 4 choices of n illustrates the numerical results for this example.

Table 2. Approximate and exact solutions for Example 2.

x	Present method with $k = 16$	Present method with $k = 32$	Present method with $n = 2$	Exact solution
0	0.001551	0.00001	0	0
0.1	0.10401	0.10002	0.1000000000	0.1000000000
0.2	0.20398	0.20008	0.2000000000	0.2000000000
0.3	0.30147	0.30007	0.3000000000	0.3000000000
0.4	0.40640	0.40008	0.4000000000	0.4000000000
0.5	0.50887	0.50001	0.5000000000	0.5000000000
0.6	0.60382	0.60001	0.6000000000	0.6000000000
0.7	0.70375	0.70002	0.7000000000	0.7000000000
0.8	0.79923	0.80008	0.8000000000	0.8000000000
0.9	0.90214	0.89991	0.9000000000	0.9000000000
1	0.99863	0.99992	1.0000000000	1

By applying the method in Section 4, we have for $n = 3$.

$$A = \begin{bmatrix} 1 & -3 & 3 & 1 \\ 0 & 3 & -6 & 3 \\ 0 & 0 & 3 & -3 \\ 0 & 0 & 0 & 1 \end{bmatrix}, D = \begin{bmatrix} -3 & -1 & 0 & 0 \\ 3 & -1 & -2 & 0 \\ 0 & 2 & 1 & -3 \\ 0 & 0 & 1 & 3 \end{bmatrix},$$

$$K_1 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{2}{3} & \frac{2}{3} & \frac{2}{3} & \frac{2}{3} \\ 1 & 1 & 1 & 1 \end{bmatrix}, Q = \begin{bmatrix} \frac{1}{7} & \frac{1}{14} & \frac{1}{35} & \frac{1}{140} \\ \frac{1}{14} & \frac{3}{35} & \frac{9}{140} & \frac{1}{35} \\ \frac{1}{35} & \frac{9}{140} & \frac{3}{35} & \frac{1}{14} \\ \frac{1}{140} & \frac{1}{35} & \frac{1}{14} & \frac{1}{7} \end{bmatrix},$$

$$P = \begin{bmatrix} \frac{1}{280} & \frac{263}{840} & \frac{193}{840} & \frac{71}{280} \\ \frac{3}{280} & \frac{17}{280} & \frac{87}{280} & \frac{67}{280} \\ \frac{3}{280} & \frac{17}{280} & \frac{53}{280} & \frac{73}{280} \\ \frac{1}{280} & \frac{17}{840} & \frac{53}{840} & \frac{69}{280} \end{bmatrix}.$$

Example 4. Consider the nonlinear Volterra-Fredholm integro-differential equation

$$\begin{cases} u''(x) - u'(x) + u(x) \\ = \int_0^x xy [u(y)]^2 dy + \int_0^1 (x-y) [u(y)]^2 dy + f(x), \\ 0 \leq x \leq 1, \\ u(0) = 0, \\ u'(0) = 0, \end{cases} \tag{40}$$

where $f(x) = \frac{13}{6} - \frac{11}{5}x + x^2 - \frac{1}{6}x^7$.

The exact solution is $u(x) = x^2$. The results of proposed method on this example are exhibited in **Table 4** with 4 choices of n . For this complicated NVFIDE, we get acceptable results with a small number of Bernstein basis functions. We obtain the approximate solutions of the problem for $n = 2, 3, 5$ and $n = 6$ respectively,

$$\begin{aligned} u_2(x) &= 0.9997098280x^2, \\ u_3(x) &= 1.000309299x^2 - 0.0002921170000x^3, \\ u_5(x) &= 1.000029079x^2 - 0.00013307x^3 \\ &\quad + 0.000218757x^4 - 0.000117802x^5, \\ u_6(x) &= 1.000000001x^2 - 0.000000001x^3 \\ &\quad - 0.00000002x^4 + 0.00000003x^5 \\ &\quad - 0.000000014x^6. \end{aligned}$$

Table 3. Approximate and exact solutions for Example 3.

x	Present method with $n = 2$	Present method with $n = 3$	Present method with $n = 4$	Present method with $n = 6$	Exact solution
0	0	0	0	0	0
0.1	0.09999636192	0.1000014485	0.09999999999	0.1000000000	0.1000000000
0.2	0.1999854477	0.2000048251	0.19999999999	0.2000000000	0.2000000000
0.3	0.2999672573	0.3000086757	0.3000000007	0.3000000000	0.3000000000
0.4	0.3999417908	0.4000115470	0.4000000010	0.4000000000	0.4000000000
0.5	0.4999090481	0.5000119848	0.4999999998	0.5000000000	0.5000000000
0.6	0.5998690293	0.6000085357	0.5999999999	0.6000000000	0.6000000000
0.7	0.6998217343	0.699997458	0.7000000020	0.7000000000	0.7000000000
0.8	0.7997671631	0.7999841614	0.8000000026	0.8000000000	0.8000000000
0.9	0.8997053158	0.8999603287	0.9000000009	0.9000000000	0.9000000000
1	0.9996361924	0.9999267940	1.000000002	1.000000000	1

Table 4. Approximate and exact solutions for Example 4.

x	Present method with $n = 2$	Present method with $n = 3$	Present method with $n = 4$	Present method with $n = 6$	Exact solution
0	0	0	0	0	0
0.1	0.009997098280	0.01000280087	0.01000017841	0.01000000005	0.01000000000
0.2	0.03998839312	0.04001003502	0.04000041093	0.04000000011	0.04000000000
0.3	0.08997388452	0.09001994975	0.09000050992	0.09000000017	0.09000000000
0.4	0.1599535725	0.1600307923	0.1600005301	0.1600000003	0.16000000000
0.5	0.2499274570	0.2500408102	0.2500006271	0.2500000006	0.25000000000
0.6	0.3598955381	0.3600482503	0.3600009158	0.3600000009	0.36000000000
0.7	0.4898578157	0.4900513604	0.490001330	0.4900000016	0.49000000000
0.8	0.6398142899	0.6400483875	0.6400014801	0.6400000022	0.64000000000
0.9	0.8097649607	0.8100375789	0.8100005113	0.8100000026	0.81000000000
1	0.9997098280	1.000017182	1.000009640	1.000000003	1

In this regard, we have reported in figures and a table, the values of the exact solution $u(x)$, the approximate solution $u_n(x)$, and the absolute error function $e_n(x) = |u(x) - u_n(x)|$ at the selected points of the given interval.

We have zoomed out **Figures 1** and **2** to a great extent because the exact and approximate solutions are very close.

Example 5. Finally, consider the nonlinear Volterra-Fredholm integro-differential equation [17].

$$\begin{cases} u'''(x) + u(x) \\ = \int_0^x [u(y)]^2 dy + \int_0^1 (x^2 y + xy^2) [u(y)]^2 dy + f(x), \\ 0 \leq x \leq 1, \\ u(0) = -1, \\ u'(0) = 0, \end{cases} \quad (41)$$

where, $f(x) = -1 - \frac{113}{105}x + \frac{5}{6}x^2 + \frac{2}{3}x^3 - \frac{1}{5}x^5$.

The exact solution is $u(x) = x^2 - 1$. The results of the proposed method for this example are exhibited in **Table 5** with 4 choices of n . For this complicated NVFIDE, we get acceptable results with a small number of Bernstein basis functions. We obtain the approximate solutions of the problem for $n = 2, 3, 4$ and $n = 6$ respectively,

$$\begin{aligned} u_2(x) &= -1 + 1.109999968x^2, \\ u_3(x) &= -1 + 0.9864926050x^2 \\ &\quad + 0.0004369190000x^3, \\ u_4(x) &= -1 + 0.99433608x^2 - 0.0001364x^3 \\ &\quad + 0.000266327x^4, \end{aligned}$$

$$\begin{aligned} u_6(x) &= -1 + 1.000014250x^2 + 0.00000003x^3 \\ &\quad - 0.000000138x^4 - 0.00000022x^5 \\ &\quad - 0.000000048x^6. \end{aligned}$$

In this regard, we have reported in figures and a table, the values of the exact solution $u(x)$, the approximate solution $u_n(x)$, and the absolute error function $e_n(x) = |u(x) - u_n(x)|$ at the selected points of the given interval.

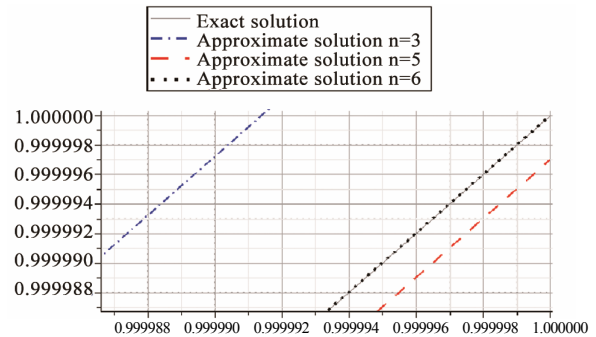


Figure 1. Comparison of the exact solution and the approximate solutions for Example 5.

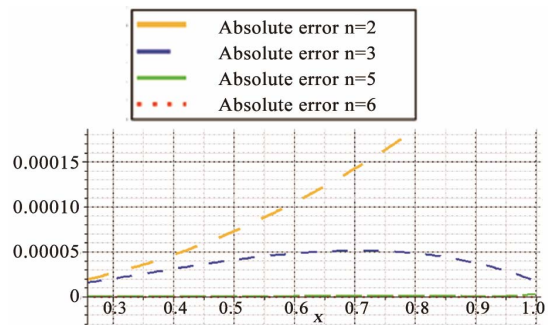


Figure 2. Comparison of the absolute error functions for Example 5.

Table 5. Approximate and exact solutions for Example 5.

x	Present method with n = 2	Present method with n = 3	Present method with n = 4	Present method with n = 6	Exact solution
0	-1	-1	-1	-1	-1
0.1	-0.9889000003	-0.9901346371	-0.9900567490	-0.9899998575	-0.9900000000
0.2	-0.9556000013	-0.9605368004	-0.9602272219	-0.9599994300	-0.9600000000
0.3	-0.9001000029	-0.9112038688	-0.9105112784	-0.9099987185	-0.9100000000
0.4	-0.8224000051	-0.8421332204	-0.8409081388	-0.8399977240	-0.8400000000
0.5	-0.7225000080	-0.7533222339	-0.7514163846	-0.7499964505	-0.7500000000
0.6	-0.6004000115	-0.6447682877	-0.6420339576	-0.6399949000	-0.6400000000
0.7	-0.4898578157	-0.5164687604	-0.5127581609	-0.5099930835	-0.5100000000
0.8	-0.2896000205	-0.3684210303	-0.3635856581	-0.3599910060	-0.3600000000
0.9	-0.1009000259	-0.2006224760	-0.1945124737	-0.1899886825	-0.1900000000
1	0.109999968	-0.1307047600	-0.005533993000	0.000013874	0

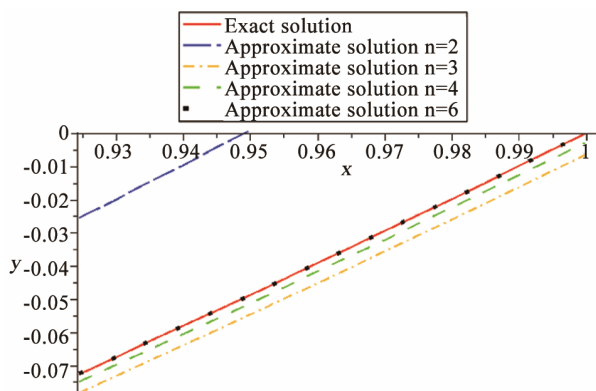


Figure 3. Comparison of the exact solution and the approximate solutions for Example 5.

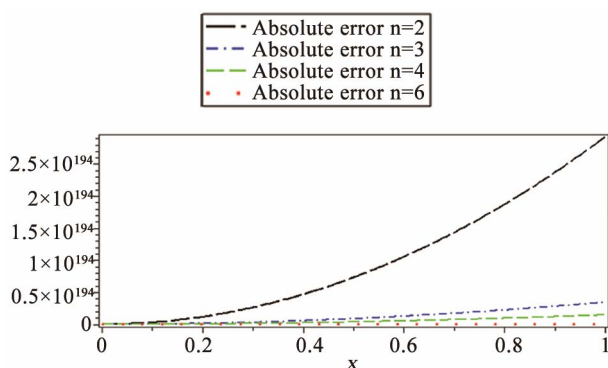


Figure 4. Comparison of the absolute error functions for Example 5.

We have zoomed out Figures 3 and 4 to a great extent because the exact and approximate solutions are very close. While in [17], the adopted method yields no solution for $n = 3$, takes time to give the approximate answer for $n = 5$, and is proper only for $n = 4$, our method is significant not only because it yields solutions for any n , but also because the approximate solutions it gives are very close to exact ones.

6. Conclusion

In this paper, we have proposed a numerical solution to solve nonlinear Volterra-Fredholm integro-differential equations with initial condition by Bernstein polynomials operational matrices and derived operational matrix. We use formula for numerical examples and it is obvious that the numerical solution coincides with the exact solution even with a few Bernstein polynomials used in the approximation. Finally, errors show that the approximation becomes more accurate when n is increased. Therefore, for better results, it is recommended to use a larger n .

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