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On almost paracontact Riemannian manifolds of type (n, n)

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Abstract. In this paper we give a classification with eleven basic classes of almost paracontact Riemannian manifolds of type (n, n) with respect to the covariant derivative of the (1, 1)-tensor of the almost paracontact structure.

Mathematics Subject Classification (2000): 53C15, 53C25. *Key words:* Almost paracontact, Riemannian manifolds.

1. Introduction

In 1976 I. Sato [1] introduced the concepts of almost paracontact manifolds and of almost paracontact Riemannian manifolds as analogues of almost contact manifolds and of almost contact Riemannian manifolds.

After that S. Sasaki [2] defined the notion of an almost paracontact Riemannian manifold of type (p, q) and arbitrary dimension, where p and q are the numbers of the multiplicity of the structural eigenvalues 1 and -1, respectively. In addition, there is a simple eigenvalue 0.

In this paper we consider almost paracontact Riemannian manifolds of type (n, n), i.e. p = q = n. We put this fixation in view of reasons of later investigations relevant to 2*n*-dimensional Riemannian almost product manifolds (M^{2n}, P, g) with structural group $O(n) \times O(n)$, which are classified in [3]. In this reason the manifolds in our consideration could be construct by natural way as a direct product of (M^{2n}, P, g) and a real line or as a hypersurface of (M^{2n}, P, g) .

The method used in the present paper is analogous to the methods of classification in [4] and partly to those in [5] for the almost contact metric manifolds and for the almost contact manifolds with *B*-metric, respectively.

2. Preliminaries

A (2n+1)-dimensional real differentiable manifold *M* is said to have an almost paracontact structure (ϕ, ξ, η) of type (n, n), if it admits a (1, 1)-tensor ϕ , a vector field ξ and a 1-form η satisfying the following conditions:

$$\eta(\xi) = 1, \qquad \phi^2 = I_{2n+1} - \eta \otimes \xi, \qquad tr\phi = 0.$$
 (1)

A positive definite Riemannian metric g is said to be compatible with the almost paracontact structure if it satisfies the following conditions

$$g(x,\xi) = \eta(x), \qquad g(\phi x, \phi y) = g(x, y) - \eta(x)\eta(y)$$
 (2)

for all vectors x, y in the tangent space $T_p M$.

The quadruple (ϕ, ξ, η, g) of an almost paracontact structure of type (n, n) and a compatible metric is called an almost paracontact Riemannian structure of type (n, n).

We introduce the tensor \tilde{g} given by the equation

$$\tilde{g}(\cdot, \cdot) = g(\cdot, \phi \cdot) + \eta(\cdot)\eta(\cdot). \tag{3}$$

It is a compatible metric with the almost paracontact structure, too. The associated metric \tilde{g} to the Riemannian metric g is a pseudo-Riemannian metric of signature (n + 1, n).

Let us denote the tensor of type (0, 3) by the equation

$$F(x, y, z) = g((\nabla_x \phi)y, z) \qquad (x, y, z \in T_p M).$$

$$\tag{4}$$

Because of (1) and (2) the tensor F has the following properties

$$F(x, y, z) = F(x, z, y) = -F(x, \phi y, \phi z) +\eta(y)F(x, \xi, z) + \eta(z)F(x, y, \xi)$$
(5)

for all vectors x, y, z in T_pM .

If $\{e_i, \xi\}$ (i = 1, 2, ..., 2n) is a basis of the tangent space $T_p M$ and g^{ij} are the components of the inverse matrix of g, then the following 1-forms are associated with the tensor F

$$\theta(x) = g^{ij}F(e_i, e_j, x), \quad \theta^*(x) = g^{ij}F(e_i, \phi e_j, x), \quad \omega(x) = F(\xi, \xi, x).$$
(6)

for an arbitrary vector $x \in T_p M$.

3. The space of covariant derivatives of the (1, 1)-tensor of the almost paracontact structure

Let (V, ϕ, ξ, η, g) be (2n + 1)-dimensional vector space with almost paracontact Riemannian structure of type (n, n). We consider the vector space \mathcal{F} of the tensors of type (0, 3) over V having the properties (6). The metric g induces on \mathcal{F} an inner product \langle , \rangle , defined by

$$\langle F', F'' \rangle = g^{ip} g^{jq} g^{kr} F'(e_i, e_j, e_k) F''(e_p, e_q, e_r)$$

for arbitrary elements F', F'' in \mathcal{F} and a V's basis $\{e_i, e_{2n+1} = \xi\}$ (i = 1, 2, ..., 2n).

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The standard representation of the structural group $O(n) \times O(n) \times I$ in *V* induces a natural representation of the structural group in \mathcal{F} :

$$(\lambda(a)F)(x, y, z) = F(a^{-1}x, a^{-1}y, a^{-1}z),$$

where $a \in O(n) \times O(n) \times I$, $F \in \mathcal{F}$, $x, y, z \in V$, so that

$$\langle \lambda(a)F', \lambda(a)F'' \rangle = \langle F', F'' \rangle.$$

We consider operators h, v, w on V with the properties

$$h^{2} = h, \qquad v^{2} = v, \qquad w^{2} = w,$$

$$h \circ v = v \circ h = h \circ w = w \circ h = v \circ w = w \circ v = 0.$$
(7)

The action of these operators on the space \mathcal{F} is represented by the equations

$$\begin{split} hF(x, y, z) &= F(\phi^2 x, \phi^2 y, \phi^2 z), \\ vF(X, Y, Z) &= \eta(x)F(\xi, y, z) + \eta(y)F(x, z, \xi) + \eta(z)F(x, y, \xi) \\ &- 2\eta(x)\left[\eta(y)F(\xi, \xi, z) + \eta(z)F(\xi, \xi, y)\right], \end{split}$$
(8)
$$wF(x, y, z) &= \eta(x)\left[\eta(y)F(\xi, \xi, z) + \eta(z)F(\xi, \xi, y)\right] \end{split}$$

The equality (8) implies

$$F = hF + vF + wF. (9)$$

Now we define basic operators $F_i : \mathcal{F} \to \mathcal{F} (i = 1, 2, ..., 10)$ by the equations:

$$\begin{split} F_{1}(F)(x, y, z) &= \eta(x)F(\xi, y, z), \\ F_{2}(F)(x, y, z) &= \eta(y)F(x, z, \xi) + \eta(z)F(x, y, \xi), \\ F_{3}(F)(x, y, z) &= \eta(x) [\eta(y)F(\xi, \xi, z) + \eta(z)F(\xi, \xi, y)], \\ F_{4}(F)(x, y, z) &= \eta(y)F(z, \xi, x) + \eta(z)F(y, \xi, x) \\ &-2\eta(y)\eta(z)F(\xi, \xi, x), \\ F_{5}(F)(x, y, z) &= \eta(y)F(\phi x, \xi, \phi z) + \eta(z)F(\phi y, \xi, \phi y), \\ F_{6}(F)(x, y, z) &= \eta(y)F(\phi z, \xi, \phi x) + \eta(z)F(\phi y, \xi, \phi x), \\ F_{7}(F)(x, y, z) &= \frac{\theta(F)(\xi)}{2n} \{\eta(y)g(\phi x, \phi z) + \eta(z)g(\phi x, \phi y)\}, \\ F_{8}(F)(x, y, z) &= \frac{\theta^{*}(F)(\xi)}{2n} \{\eta(y)g(x, \phi z) + \eta(z)g(x, \phi y)\}, \\ F_{9}(F)(x, y, z) &= \frac{1}{2n} \{g(\phi x, \phi y)\theta(\phi^{2} z) + g(\phi x, \phi z)\theta(\phi^{2} y) \\ &-g(x, \phi y)\theta(\phi z) - g(x, \phi z)\theta(\phi y)\}, \\ F_{10}(F)(x, y, z) &= \frac{1}{3} \{hF(x, y, z) + hF(y, z, x) + hF(z, x, y)\}. \end{split}$$

It is easy to check that $F_i(F) \in F$ for $F \in \mathcal{F}$ (i = 1, 2, ..., 10).

By necessity we have to compute the compositions of the basic operators and the associated 1-forms of $F_i(F)$.

LEMMA 1. Let $F \in \mathcal{F}$ and $F_{i,j}(F) = F_i(F_j(F))$ (i, j = 1, 2, ..., 10). Then we have:

a) F_{i,i}(F) = F_i(F) for i = 1, 2, 3, 7, ..., 10; F_{i,i}(F) = F₂(F) - F₃(F) for i = 4, 5, 6; F_{1,i}(F) = F_{i,1}(F) = F₃(F) for i = 2, 3; F_{2,i}(F) = F_{i,2}(F) = F_i(F) for i = 3, 4, 5, 6, 7, 8; F_{i,j}(F) = F_k(F) for i, j, k = 4, 5, 6; F_{i,j}(F) = F_{j,i}(F) = F_j(F) for i = 4, 5, 6 and j = 7, 8 and the rest of F_{i,j}(F) are zeros;
b) θ(F_i(F)) = θ(F)(ξ)η for i = 2, 4, 5, 6, 7; θ*(F_i(F)) = θ*(F)(ξ)η for i = 2, 4, 5, 6, 8; ω(F_i(F)) = ω(F) for i = 1, 2, 3 and the rest of the associated 1-forms are zeros.

By virtue of the operators F_i we construct new operators L_i (j = 1, 2, ..., 9). Let

$$L_1: \mathcal{F} \to \mathcal{F}, \qquad L_1(F) = F - 2F_3(F), \qquad F \in \mathcal{F}.$$

In a straightforward way using Lemma 1 we get that the operator L_1 is an involutive isometry on \mathcal{F} and commutes with the action of $O(n) \times O(n) \times I$. Hence L_1 has two eigenvalues +1 and -1, and the corresponding eigenspaces $(L_1\mathcal{F})^+$ and $(L_1\mathcal{F})^-$ are orthogonal and invariant mutually complementary subspaces of \mathcal{F} . Besides that, the components of F in the subspaces $(L_1\mathcal{F})^+$ and $(L_1\mathcal{F})^-$ are $\frac{1}{2}\{F + L_1(F)\}$ and $\frac{1}{2}\{F - L_1(F)\}$, respectively.

It is easy to show

LEMMA 2. If $F \in \mathcal{F}$ then

a) $F_3(F) = 0$ iff $\omega(F) = 0$; b) $F \in (L_1\mathcal{F})^+$, *i.e.* $L_1(F) = F$ iff $F_3(F) = 0$; c) $F \in (L_1\mathcal{F})^-$, *i.e.* $L_1(F) = -F$ iff $F = F_3(F)$.

If we denote $\mathcal{F}_{11} = (L_1 \mathcal{F})^-$ and $\mathcal{F}_{11}^{\perp} = (L_1 \mathcal{F})^+$, then according Lemma 2 we have

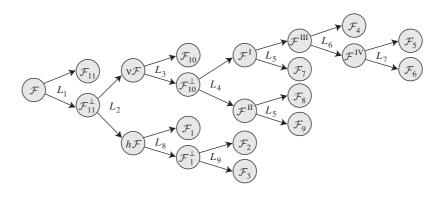
$$\mathcal{F}_{11} = \{ F \in \mathcal{F} \mid F = F_3(F) \}, \qquad \mathcal{F}_{11}^\perp = \{ F \in \mathcal{F} \mid \omega(F) = 0 \}.$$

Thereby we obtain immediately

PROPOSITION 3. The decomposition $\mathcal{F} = \mathcal{F}_{11} \oplus \mathcal{F}_{11}^{\perp}$ is orthogonal and invariant with respect to the action of $O(n) \times O(n) \times I$. The component of an arbitrary element F in \mathcal{F}_{11} (respectively in \mathcal{F}_{11}^{\perp}) is $F_3(F)$ (respectively $F - F_3(F)$).

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Using the same method we continue to decompose \mathcal{F} orthogonally and invariantly with respect to the action of $O(n) \times O(n) \times I$. Thereby we obtain the complete decomposition into irreducible components by the scheme of Figure 1.

The rest of operators L_j (j = 2, 3, ..., 9) we define by:

$$L_{2}(F) = F - 2\{F_{1}(F) + F_{2}(F)\}, \quad L_{6}(F) = F - 2F_{7}(F),$$

$$L_{3}(F) = F_{2}(F) - F_{1}(F), \qquad L_{7}(F) = F - 2F_{8}(F),$$

$$L_{4}(F) = -F_{5}(F), \qquad L_{8}(F) = F - 2F_{9}(F),$$

$$L_{5}(F) = -F_{4}(F), \qquad L_{9}(F) = F - 2F_{10}(F).$$

The operators L_j (j = 2, 3, ..., 9) are involutive isometries on the corresponding subspaces and also commute with the action of $O(n) \times O(n) \times I$. According the applying method the corresponding eigenspaces of the eigenvalues +1 and -1 are orthogonal and mutually complementary subspaces of the reducible subspace of \mathcal{F} .

Since the endomorphism ϕ induces an almost product structure on the orthogonal complement $\{\xi\}^{\perp}$ of the subspace spanned by ξ and the restriction of g on $\{\xi\}^{\perp}$ is a Riemannian metric compatible with the almost product structure, then the decomposition of $h\mathcal{F}$ coincides with the known decomposition of the space of covariant derivatives of the traceless almost product structure [3].

Taking into account the above reasons we obtain

THEOREM 4. The decomposition $\mathcal{F} = \mathcal{F}_1 \oplus \mathcal{F}_2 \oplus \cdots \oplus \mathcal{F}_{11}$ is orthogonal and invariant with respect to the action of $O(n) \times O(n) \times I$. The characterization conditions of the factors \mathcal{F}_i (i = 1, 2, ..., 11) for arbitrary vectors x, y, z in V are:

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$$\begin{array}{ll} \mathcal{F}_{1} : & F(x,y,z) = \frac{1}{2n} \{g(\phi x,\phi y)\theta(\phi^{2}z) + g(\phi x,\phi z)\theta(\phi^{2}y) \\ & -g(x,\phi y)\theta(\phi z) - g(x,\phi z)\theta(\phi y)\}; \\ \mathcal{F}_{2} : & F(x,y,\phi z) + F(y,z,\phi x) + F(z,x,\phi y) = 0, \\ & F(\xi,y,z) = F(x,y,\xi) = 0, \\ \mathcal{F}_{3} : & F(x,y,z) + F(y,z,x) + F(z,x,y) = 0, \\ \mathcal{F}_{4} : & F(x,y,z) = \frac{\theta^{\xi}(\xi)}{2n} \{g(\phi x,\phi y)\eta(z) + g(\phi x,\phi z)\eta(y)\}; \\ \mathcal{F}_{5} : & F(x,y,z) = \frac{\theta^{\xi}(\xi)}{2n} \{g(x,\phi y)\eta(z) + g(x,\phi z)\eta(y)\}; \\ \mathcal{F}_{6} : & F(x,y,z) = \eta(y)F(z,\xi,x) + \eta(z)F(y,\xi,x) - 2\eta(y)\eta(z)F(\xi,\xi,x) \\ & = \eta(y)F(\phi x,\xi,\phi z) + \eta(z)F(\phi x,\xi,\phi y), \\ & \theta(\xi) = \theta^{*}(\xi) = 0; \\ \mathcal{F}_{7} : & F(x,y,z) = -\eta(y)F(z,\xi,x) - \eta(z)F(y,\xi,x) + 2\eta(y)\eta(z)F(\xi,\xi,x) \\ & = \eta(y)F(\phi x,\xi,\phi z) + \eta(z)F(\phi x,\xi,\phi y); \\ \mathcal{F}_{8} : & F(x,y,z) = \eta(y)F(z,\xi,x) - \eta(z)F(y,\xi,x) - 2\eta(y)\eta(z)F(\xi,\xi,x) \\ & = -\eta(y)F(\phi x,\xi,\phi z) - \eta(z)F(\phi x,\xi,\phi y); \\ \mathcal{F}_{9} : & F(x,y,z) = -\eta(y)F(z,\xi,x) - \eta(z)F(y,\xi,x) + 2\eta(y)\eta(z)F(\xi,\xi,x) \\ & = -\eta(y)F(\phi x,\xi,\phi z) - \eta(z)F(\phi x,\xi,\phi y); \\ \mathcal{F}_{10} : & F(x,y,z) = \eta(x)F(\xi,y,z), \\ \mathcal{F}_{11} : & F(x,y,z) = \eta(x)\{\eta(y)\omega(z) + \eta(z)\omega(y)\}. \end{array}$$

The components $p_i(F)$ of an arbitrary element F of \mathcal{F} in \mathcal{F}_i (i = 1, 2, ..., 11) are

 $\begin{array}{ll} p_1(F) = F_9(F), & p_2(F) = F_{10}(F), \\ p_3(F) = hF - F_9(F) - F_{10}(F), & p_4(F) = F_7(F), & p_5(F) = F_8(F), \\ p_6(F) = \frac{1}{4} \{F_2(F) - F_3(F) + F_4(F) + F_5(F) + F_6(F)\} - F_7(F) - F_8(F), \\ p_7(F) = \frac{1}{4} \{F_2(F) - F_3(F) - F_4(F) + F_5(F) - F_6(F)\}, \\ p_8(F) = \frac{1}{4} \{F_2(F) - F_3(F) - F_4(F) - F_5(F) - F_6(F)\}, \\ p_9(F) = \frac{1}{4} \{F_2(F) - F_3(F) - F_4(F) - F_5(F) + F_6(F)\}, \\ p_{10}(F) = F_1(F) - F_3(F), & p_{11}(F) = F_3(F). \end{array}$

4. Basic classes of almost paracontact Riemannian manifolds of type (n, n)

Let (M, ϕ, ξ, η, g) be almost paracontact Riemannian manifolds of type (n, n). The tangent space T_pM at an arbitrary point p in M is the vector space V equipped with an almost paracontact Riemannian structure of type (n, n). Then the corresponding vector space \mathcal{F} considered in the previous section has eleven orthogonal and invariant subspaces \mathcal{F}_i . In such a way the conditions for F at every point $p \in M$ give rise to the corresponding class of manifolds under consideration. Namely, an almost paracontact Riemannian manifold of type (n, n) is said to be in the class \mathcal{F}_i if the tensor F belongs to the subspace \mathcal{F}_i (i = 1, 2, ..., 11) over T_pM at every p in M. Thus the conditions define the eleven basic classes of almost paracontact Riemannian manifolds of type (n, n). Of course, the number of all classes of manifold under conversation is 2^{11} and their defining conditions are

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easily obtainable by the basic ones. The special class \mathcal{F}_0 of almost paracontact Riemannian manifolds of type (n, n) is defined by the condition F = 0. This class belongs to each of the defined classes. It is an analogue to the class of cosymplectic almost contact metric manifolds [4] and to the respective class \mathcal{F}_0 in the classification of almost contact manifolds with *B*-metric [5].

The defined class \mathcal{F}_4 contains paracontact Riemannian manifolds of type (n, n) [1] and in particular para-Sasakian manifolds of type (n, n) [7].

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