# ON CONFORMAL KILLING SYMMETRIC TENSOR FIELDS ON RIEMANNIAN MANIFOLDS 

N. S. DAIRBEKOV AND V. A. SHARAFUTDINOV


#### Abstract

A vector field on a Riemannian manifold is called conformal Killing if it generates one-parameter group of conformal transformation. The class of conformal Killing symmetric tensor fields of an arbitrary rank is a natural generalization of the class of conformal Killing vector fields, and appears in different geometric and physical problems. We prove the statement: A trace-free conformal Killing tensor field is identically zero if it vanishes on some hypersurface. This statement is a basis of the theorem on decomposition of a symmetric tensor field on a compact manifold with boundary to a sum of three fields of special types. We also establish triviality of the space of trace-free conformal Killing tensor fields on some closed manifolds.


## 1. Introduction

Conformal transformation of a Riemannian manifold $(M, g)$ is a diffeomorphism $\varphi$ : $M \rightarrow M$ such that $\varphi^{*} g=\lambda g$ for some positive function $\lambda$ on $M$. A vector field $u$ on $M$ is called conformal Killing if it generates one parameter transformation group of conformal mappings. In local coordinates, a conformal Killing vector field satisfies the equation

$$
\begin{equation*}
\frac{1}{2}\left(\nabla_{i} u_{j}+\nabla_{j} u_{i}\right)=v g_{i j} \tag{1.1}
\end{equation*}
$$

for some scalar function $v$ (depending on $u$ ). Here $\nabla_{i} u_{j}$ denote the covariant derivatives of the field $u$.

The notion of conformal Killing tensor fields is a generalization of the notion of conformal Killing vector fields to the case of higher rank tensors, and the equation that defines the first class of fields generalizes equation (1.1).

Given a Riemannian manifold $(M, g)$, let $C^{\infty}\left(S^{m} \tau_{M}^{\prime}\right)$ be the space of smooth symmetric covariant tensor field of rank $m$ on $M$. The first order differential operator

$$
d=\sigma \nabla: C^{\infty}\left(S^{m-1} \tau_{M}^{\prime}\right) \rightarrow C^{\infty}\left(S^{m} \tau_{M}^{\prime}\right),
$$

is called the inner derivative. Here $\nabla$ denotes the covariant derivative, and $\sigma$ is the symmetrization. The divergence

$$
\delta: C^{\infty}\left(S^{m} \tau_{M}^{\prime}\right) \rightarrow C^{\infty}\left(S^{m-1} \tau_{M}^{\prime}\right)
$$

is defined in local coordinates by $(\delta u)_{i_{1} \ldots i_{m-1}}=g^{j k} \nabla_{j} u_{k i_{1} \ldots i_{m-1}}$. The operators $d$ and $-\delta$ are dual to each other with respect to the natural $L^{2}$-product on the space of symmetric tensor fields (see Section 3). We denote by

$$
i: C^{\infty}\left(S^{m} \tau_{M}^{\prime}\right) \rightarrow C^{\infty}\left(S^{m+2} \tau_{M}^{\prime}\right)
$$

the following algebraic operator of symmetric multiplication by the metric tensor: $i u=$ $\sigma(g \otimes u)$, and the adjoint of $i$ is denoted by $j: C^{\infty}\left(S^{m+2} \tau_{M}^{\prime}\right) \rightarrow C^{\infty}\left(S^{m} \tau_{M}^{\prime}\right)$. In local coordinates, $(j u)_{i_{1} \ldots i_{m}}=g^{j k} u_{j k i_{1} \ldots i_{m}}$. The tensor field $j u$ is called the trace of the field $u$. A symmetric tensor field $u$ is called trace-free if its trace is identically equal to zero:

$$
\begin{equation*}
j u_{1}=0 . \tag{1.2}
\end{equation*}
$$

A Killing tensor field is a symmetric tensor field $u$ satisfying $d u=0$. A conformal Killing tensor field is a symmetric tensor field $u$ satisfying the equation

$$
\begin{equation*}
d u=i v \tag{1.3}
\end{equation*}
$$

for some $v$. Equation (1.3) is a natural generalization of (1.1).
Conformal Killing vector (covector) fields are the classic object of the Riemannian geometry. Conformal Killing symmetric tensor fields of higher rank naturally appear in various problems of physics and geometry (see $[21,7,8,13,20,6,1]$ ). There are also many papers where antisymmetric conformal Killing tensor fields are studied (conformal Killing forms) because of their role in Gravitation Theory and in the Maxwell equations (see $[18,10]$ and the references there).
It should be observed that (in some sense) there are "too many" conformal Killing fields of rank $m \geq 2$. Indeed, if $v$ is any field of rank $m-2$ then the field $u=i v$ satisfies the equation $d u=i(d v)$ because the operators $i$ and $d$ commute. For this reason, it makes sense to study the trace-free conformal Killing fields, i.e., conformal Killing fields $u$ satisfying equation (1.2). In some papers (for example, see $[6,1]$ ), equation (1.2) is included into the definition of a conformal Killing tensor field, but we prefer to speak on the trace-free conformal Killing fields in this case.

Eliminating $v$ from equation (1.3), we get $p d u=0$, where $p$ is an algebraic operator defined in Section 3 below. As is shown in Theorem 5.1 below, the operator $\delta p d$ is elliptic on the bundle of trace-free tensor fields. Therefore, the equation $\delta p d u=0$ implies the following statement: a trace-free conformal Killing field is smooth. Hereafter in the paper, the term "smooth" always means " $C^{\infty}$-smooth".

The definition of a (trace-free) conformal Killing field is invariant with respect to a conformal change of the metric in the following sense. If $u \in C^{\infty}\left(S^{m} \tau_{M}^{\prime}\right)$ is a (trace-free) conformal Killing field with respect to a Riemannian metric $g$ then $\lambda^{m} u$ is a (trace-free) conformal Killing field with respect to the metric $\lambda g$ for any smooth positive function $\lambda$ on $M$.

As well known, the space of conformal Killing vector fields on $M$ has a finite dimension if $n=\operatorname{dim} M \geq 3$. In the two-dimensional case, the space can be of infinite dimension. Nevertheless, in every dimension, a conformal Killing vector field is uniquely determined by its $C^{\infty}$-jet at any point. The following theorem is a generalization of the latter fact.

Theorem 1.1. Let $(M, g)$ be a connected $n$-dimensional Riemannian manifold, with $n \geq$ 3. If a trace-free conformal Killing symmetric field $u$ of rank $m \geq 0$ satisfies the conditions

$$
\begin{equation*}
u\left(x_{0}\right)=0, \quad \nabla u\left(x_{0}\right)=0, \quad \ldots, \quad \nabla^{l} u\left(x_{0}\right)=0 \tag{1.4}
\end{equation*}
$$

at some point $x_{0} \in M$, where $l=l(m) \leq 6 m$ depends only on $m$, then $u \equiv 0$. In particular, the dimension of the space of trace-free conformal Killing fields of rank $m$ is finite. If $n=2$ then the first statement is true if (1.4) is replaced by the following condition: All the derivatives of the field $u$ vanish at the point $x_{0}$.

The theorem was first proved in [14], with $l(m)=6 m$. The results of [6, 1] provide the exact value $l(m)=2 m$ (in the case of $m=2$, see also [21]). Arguments of [6, 1] are based on delicate facts of representation theory and the theory of overdetermined systems. At the same time, the proof given in [14] is quite elementary although it does not allow to obtain the exact value of $l(m)$. For reader's convenience, we reproduce the latter proof in Sections 9 and 11. For $n \geq 3$, the scheme of the proof is as follows. Being written in local coordinates, (1.2) and (1.3) constitute a linear homogeneous system of equations in components of the fields $u$ and $v$, and their first order partial derivatives.

We differentiate these equations $l$ times and show that the resulting system can be solved with respect to all partial derivatives of the highest order $l+1$. This means that the components of the tensors $u(t)=u(x(t))$ and $v(t)=v(x(t))$ satisfy a homogeneous linear system of ordinary differential equations of order $l+1$ along every smooth curve $x=x(t)$. Together with homogeneous initial conditions (1.4), this yields the required result. In the two-dimensional case, the proof consists of reducing system (1.2)-(1.3) to the Cauchy-Riemann equations.
Corollary 1.2. Let $(M, g)$ be a connected Riemannian manifold of dimension $n \geq 3$. If tensor fields $u \in C^{\infty}\left(S^{m} \tau_{M}^{\prime}\right)$ and $v \in C^{\infty}\left(S^{m-1} \tau_{M}^{\prime}\right)(m \geq 0)$ satisfy equation (1.3) and initial conditions (1.4) with the same $l=l(m)$ as in Theorem 1.1 then there exists a field $w \in C^{\infty}\left(S^{m-2} \tau_{M}^{\prime}\right)$ such that $u=i w$ and $v=d w$. For $n=2$, the statement is true if (1.4) is replaced by the following condition: All the derivatives of the field $u$ vanish at the point $x_{0}$.

Theorem 1.1 implies Corollary 1.2 by an algebraic trick presented in Section 3. Theorem 1.1 is also used in the proof of the following proposition.

Theorem 1.3. Let $(M, g)$ be a connected Riemannian manifold of dimension at least 2 , and let $\varnothing \neq \Gamma \subset M$ be a smooth hypersurface. In particular, $\Gamma$ may be a relatively open subset of the boundary $\partial M$. If a trace-free conformal Killing field $u$ vanishes on $\Gamma$ then $u \equiv 0$.

In the case of $m=1$ and $\Gamma=\partial M$, Theorem 1.3 follows from [12, Proposition 3.3].
The authors are indebted to the anonymous referee for verification of the following fact: Theorem 1.3 is not valid if, in the condition $\left.u\right|_{\Gamma}=0$, the hypersurface $\Gamma$ is replaced by a submanifold of dimension less than $\operatorname{dim} M-1$. We quote: "The dimension of the space of trace-free conformal Killing fields of rank 2 on $\mathbb{R}^{3}$ which vanish on a straight line, equals 10, i.e., in some sense, Theorem 1.3 is the best possible result."

Corollary 1.4. Let $(M, g)$ and $\Gamma$ satisfy the hypotheses of Theorem 1.3. If tensor fields $u \in C^{\infty}\left(S^{m} \tau_{M}^{\prime}\right)$ and $v \in C^{\infty}\left(S^{m-1} \tau_{M}^{\prime}\right)$ satisfy the equation $d u=i v$ and the condition $\left.u\right|_{\Gamma}=0$ then there exists a field $w \in C^{\infty}\left(S^{m-2} \tau_{M}^{\prime}\right)$ such that $u=i w, v=d w$, and $\left.w\right|_{\Gamma}=0$.

The following definition was introduced in [16, §3]. A Riemannian manifold with boundary is called conformally rigid if there is no nonzero conformal Killing vector field that vanishes on the boundary. Theorem 1.3 implies conformal rigidity of an arbitrary connected Riemannian manifold with nonempty boundary. For such a compact manifold ( $M, g$ ), Theorem 3.3 of [16] can be formulated as follows: Every rank 2 symmetric tensor field $f$ on $M$ can be uniquely represented in the form

$$
f_{i j}=\frac{1}{2}\left(\nabla_{i} v_{j}+\nabla_{j} v_{i}\right)+\lambda g_{i j}+\tilde{f}_{i j},\left.\quad v\right|_{\partial M}=0, \quad \operatorname{tr} \tilde{f}=0, \quad \delta \tilde{f}=0 .
$$

We generalize this result to higher rank tensor fields. Given a compact $M$, let $H^{k}\left(S^{m} \tau_{M}^{\prime}\right)$ denote the Hilbert space of symmetric tensor fields of rank $m$ whose components are locally square integrable together with their partial derivatives up to order $k$ in an arbitrary coordinate system.

Theorem 1.5. Let $(M, g)$ be a compact connected Riemannian manifold with nonempty boundary. Every symmetric tensor field $f \in H^{k}\left(S^{m} \tau_{M}^{\prime}\right)(m \geq 0, k \geq 1)$ can be uniquely represented in the form

$$
\begin{equation*}
f=d v+i \lambda+\tilde{f} \tag{1.5}
\end{equation*}
$$

where $v \in H^{k+1}\left(S^{m-1} \tau_{M}^{\prime}\right)$ satisfies the conditions

$$
\begin{equation*}
j v=0,\left.\quad v\right|_{\partial M}=0 \tag{1.6}
\end{equation*}
$$

$\lambda \in H^{k}\left(S^{m-2} \tau_{M}^{\prime}\right)$, and $\tilde{f} \in H^{k}\left(S^{m} \tau_{M}^{\prime}\right)$ satisfies the conditions

$$
\begin{equation*}
\delta \tilde{f}=0, \quad j \tilde{f}=0 \tag{1.7}
\end{equation*}
$$

The summands in (1.5) continuously depend on $f$, i.e., the stability estimates

$$
\begin{equation*}
\|v\|_{H^{k+1}} \leq C\|f\|_{H^{k}}, \quad\|\lambda\|_{H^{k}} \leq C\|f\|_{H^{k}}, \quad\|\tilde{f}\|_{H^{k}} \leq C\|f\|_{H^{k}} \tag{1.8}
\end{equation*}
$$

hold with some constant $C$ independent of $f$.
In General Relativity, conformal Killing tensor fields appear as polynomial first integrals of the equation for null geodesics [8]. Our interest in the conformal Killing tensor fields is motivated by the following question from Integral Geometry.

Given a Riemannian manifold ( $M, g$ ), let

$$
\Omega M=\left\{(x, \xi)\left|x \in M, \xi \in T_{x} M,|\xi|^{2}=g_{i j}(x) \xi^{i} \xi^{j}=1\right\}\right.
$$

denote the unit sphere bundle, and let $H: C^{\infty}(\Omega M) \rightarrow C^{\infty}(\Omega M)$ be the differentiation along the geodesic flow. In local coordinates,

$$
\begin{equation*}
H=\xi^{i} \frac{\partial}{\partial x^{i}}-\Gamma_{j k}^{i}(x) \xi^{j} \xi^{k} \frac{\partial}{\partial \xi^{i}}, \tag{1.9}
\end{equation*}
$$

where $\Gamma_{j k}^{i}$ are the Christoffel symbols. As is seen from (1.9), if the function $U(x, \xi)$ polynomially depends on $\xi$ then $H U$ is also a polynomial in $\xi$. More precisely, for $u \in$ $C^{\infty}\left(S^{m-1} \tau_{M}^{\prime}\right)$,

$$
\begin{equation*}
H\left(u_{i_{1} \ldots i_{m-1}}(x) \xi^{i_{1}} \ldots \xi^{i_{m-1}}\right)=(d u)_{i_{1} \ldots i_{m}}(x) \xi^{i_{1}} \ldots \xi^{i_{m}} . \tag{1.10}
\end{equation*}
$$

The question on validity of the converse statement is very important: Is it true that every solution to the boundary value problem

$$
\begin{gather*}
H U=v_{i_{1} \ldots i_{m}}(x) \xi^{i_{1}} \ldots \xi^{i_{m}} \quad \text { on } \quad \Omega M,  \tag{1.11}\\
\left.U\right|_{\partial(\Omega M)}=0 \tag{1.12}
\end{gather*}
$$

is a homogeneous polynomial of degree $m-1$ in $\xi$ ? The question is equivalent to the problem of inversion of the ray transform (see [15, Ch. 1] for a detailed discussion). The question is open in the general case and the positive answer is obtained only under certain curvature conditions.

Consider the following weaker version of the latter question. Assume a solution $U$ to the boundary value problem (1.11)-(1.12) to depend polynomially on $\xi$. Is $U$ a restriction to $\Omega M$ of a homogeneous polynomial of degree $m-1$ ? The question is not trivial since polynomials of different degrees can have the same restriction to $\Omega M$ in view of the identity $\left.g_{i j} \xi^{i} \xi^{j}\right|_{\Omega M}=1$. The positive answer to this question can be easily obtained from Theorem 1.3 even if (1.12) is replaced by the weaker condition

$$
\begin{equation*}
\left.U(x, \xi)\right|_{x \in \Gamma}=0 \tag{1.13}
\end{equation*}
$$

where $\Gamma$ is a relatively open subset of $\partial M$. Indeed, assume a solution $U(x, \xi)$ to the problem (1.11) and (1.13) to be a homogeneous polynomial in $\xi$ of degree $m+2 k-1$ (the case of a nonhomogeneous polynomial can be easily reduced to the considered one). This means the existence of $u \in C^{\infty}\left(S^{m+2 k-1} \tau_{M}^{\prime}\right)$ such that

$$
U(x, \xi)=u_{i_{1} \ldots i_{m+2 k-1}}(x) \xi^{i_{1}} \ldots \xi^{i_{m+2 k-1}} \quad \text { on } \quad \Omega M,\left.\quad u\right|_{\Gamma}=0 .
$$

By (1.10), equation (1.11) takes the form

$$
\begin{equation*}
d u=i^{k} v \tag{1.14}
\end{equation*}
$$

Applying Corollary 1.4, we find $w \in C^{\infty}\left(S^{m+2 k-3} \tau_{M}^{\prime}\right)$ such that $u=i w$ and $\left.w\right|_{\Gamma}=$ 0 . Equation (1.14) can be written in terms of $w$ as $i(d w)=i\left(i^{k-1} v\right)$. Since $i$ is a monomorphism, this implies

$$
d w=i^{k-1} v .
$$

Repeating this argument by induction in $k$, we find the field $\widetilde{w} \in C^{\infty}\left(S^{m-1} \tau_{M}^{\prime}\right)$ such that $u=i^{k} \widetilde{w}$. This means that $\left.U(x, \xi)\right|_{\Omega M}$ coincides with the homogeneous polynomial $\widetilde{w}_{i_{1} \ldots i_{m-1}}(x) \xi^{i_{1}} \cdots \xi^{i_{m-1}}$ of degree $m-1$.

The questions under consideration are also important in the case of closed manifolds (i.e., compact manifolds with no boundary).

Theorem 1.6. If $(M, g)$ is a closed Riemannian manifold of dimension $n \geq 2$ of nonpositive sectional curvature then every trace-free conformal Killing symmetric tensor field $u$ on $M$ is absolutely parallel, i.e., $\nabla u=0$, and every symmetric Killing tensor field is absolutely parallel.

In addition, if $M$ is connected and there is a point $x_{0} \in M$ such that all sectional curvatures at $x_{0}$ are negative then there is no nonzero trace-free conformal Killing symmetric tensor field of any rank and every symmetric Killing tensor field is of the form $c^{k}{ }^{k}$ for some constant $c$.

The classical theorem by Bochner-Yano states: there is no nontrivial conformal Killing vector field on a closed Riemannian manifold of negative Ricci curvature [22, Theorem 2.14]. Theorem 1.6 generalizes the last statement to arbitrary rank tensor fields, however, under the stronger hypothesis: The requirement of negative Ricci curvature is replaced by the requirement of negative sectional curvature.

Theorem 1.7. Let $(M, g)$ be a closed Riemannian manifold of dimension $n \geq 2$ without conjugate points. A vector field on $M$ is conformal Killing if and only if it is a Killing vector field. A trace-free tensor field of rank 2 is conformal Killing if and only if it is the trace-free part of some Killing field. In addition, if the geodesic flow has a dense orbit in $\Omega M$ then there are neither nontrivial conformal Killing vector fields nor nontrivial trace-free conformal Killing fields of rank 2.

The natural assumption is that, under hypotheses of Theorem 1.7, similar statements are valid for higher rank tensor fields. In the case of $\operatorname{dim} M=2$, this easily follows from the uniformization theorem, invariance of the definition of conformal Killing tensor fields with respect to a conformal change of the metric, and from Theorem 1.6.

The following fact is well known: If the geodesic flow has a dense orbit in $\Omega M$ then (regardless of the dimension of $M$ ) every symmetric Killing tensor field is of the form $c g^{k}$ with some constant $c$ (see [3]).

The rest of the paper is organized as follows. Section 2 contains preliminaries from algebra of symmetric tensor fields. In particular, after deriving a commutation formula for the operators $i$ and $j$, we show that the singular decomposition of the operator $j i$ corresponds to the decomposition of polynomials in spherical harmonics.

In Section 3, we introduce the differential operators $d$ and $\delta$ on symmetric tensor fields, prove some commutation formulas for these operators, and obtain some useful propositions. In this section, we derive Corollary 1.2 of Theorem 1.1.

Sections 4 and 5 contain the proofs of Theorems 1.3 and 1.5, respectively. These proofs are essentially based on Theorem 1.1.

In Section 6, we give the proofs of Theorems 1.6 and 1.7. It should be mentioned that this section differs from the others by the nature of the methods. Namely, here we use semi-basic tensor fields and the estimates for a solution to the kinetic equation which are based on Pestov's identity. We cannot present all necessary definitions here because of the volume limitation, so we refer the reader to [15, Chapter 3] for details. This does not concern other sections since they are independent of Section 6.

In Section 7, we discuss higher order differential operators on tensor fields paying a particular attention to the principle parts of operators.

In Section 8, we introduce the Laplace operator on symmetric tensor fields and prove some commutation formulas for powers of the Laplacian which are needed to prove Theorem 1.1.

The proof of Theorem 1.1 in the case of $\operatorname{dim} M \geq 3$ is presented in Section 9.
In Section 10, we derive the equations that relate the Fourier coefficients of a solution to the kinetic equation, to the Fourier coefficients of the right-hand side. We need these equations to prove Theorem 1.1 in the two-dimensional case. These equations are also of some independent interest since they constitute the basis of the so-called method of spherical harmonics for the numerical solution of the kinetic equation and the related linear transport equation. In the literature on the method of spherical harmonics, several versions of the equations are presented for different particular geometries (see [2]). However, the invariant form of the equations, as presented in Theorem 10.2, was probably unknown before.

The final Section 11 contains the proof of Theorem 1.1 in the two-dimensional case.

## 2. Algebra of symmetric tensors

We use the standard terminology of vector bundle theory. For a smooth manifold $N$, we denote the algebra of smooth real functions on $N$ by $C^{\infty}(N)$. If $\xi=(E, \pi, N)$ is a smooth vector bundle and $U \subset N$ is an open set then $C^{\infty}(\xi ; U)$ denotes the $C^{\infty}(U)$-module of smooth sections of $\xi$ over $U$, and $C_{0}^{\infty}(\xi ; U)$ denotes the submodule of compactly supported sections. We often reduce the notation $C^{\infty}(\xi ; N)$ and $C_{0}^{\infty}(\xi ; N)$ to $C^{\infty}(\xi)$ and $C_{0}^{\infty}(\xi)$, respectively. We deal here only with finite dimensional bundles with just one exception: Sometimes, we consider a graded vector bundle $\xi^{*}=\oplus_{m=0}^{\infty} \xi^{m}$, where each summand $\xi^{m}$ has a finite dimension. Such an object can be thought as a sequence of finite-dimensional bundles. If $\eta=\oplus_{m=0}^{\infty} \eta^{m}$ is another graded bundle and $A \in \operatorname{Hom}(\xi, \eta)$ then $A_{m}$ denotes the restriction of $A$ to $\xi^{m}$. We say $A$ has a degree $k$ if $A\left(\xi^{m}\right) \subset \eta^{m+k}$.

Let $(M, g)$ be a smooth Riemannian manifold of dimension $n \geq 2$. By $\tau_{M}=(T M, \pi, M)$ and $\tau_{M}^{\prime}=\left(T^{\prime} M, \pi, M\right)$, we denote the tangent bundle and the cotangent bundle, respectively. We often shorten these notation to $\tau=(T, \pi, M)$ and $\tau^{\prime}=\left(T^{\prime}, \pi, M\right)$. Let $\otimes^{m} \tau^{\prime}=\left(\otimes^{m} T^{\prime}, \pi, M\right)$ be the bundle of real covariant tensors of rank $m$ and let $S^{m} \tau^{\prime}=\left(S^{m} T^{\prime}, \pi, M\right)$ be its subbundle consisting of the symmetric tensors. There is the natural projection $\sigma \in \operatorname{Hom}\left(\otimes^{m} \tau^{\prime}, S^{m} \tau^{\prime}\right)$ acting as follows:

$$
\begin{equation*}
\sigma\left(v_{1} \otimes \cdots \otimes v_{m}\right)=\frac{1}{m!} \sum_{\pi \in \Pi_{m}} v_{\pi(1)} \otimes \cdots \otimes v_{\pi(m)} \tag{2.1}
\end{equation*}
$$

where $\Pi_{m}$ is the group of permutations of the set $\{1, \ldots, m\}$. Note that $S^{1} \tau^{\prime}=\tau^{\prime}$ and $S^{0} \tau^{\prime}=M \times \mathbb{R}$. It is convenient to assume $\otimes^{m} \tau^{\prime}=S^{m} \tau^{\prime}=0$ for $m<0$. For a point $x \in M$, let $T_{x}, T_{x}^{\prime}, \otimes^{m} T_{x}^{\prime}$, and $S^{m} T_{x}^{\prime}$ be the fibers over $x$ of the corresponding bundles.

For $u \in S^{m} T_{x}^{\prime}$ and $v \in S^{l} T_{x}^{\prime}$, the symmetric product is defined by $u v=\sigma(u \otimes v)$. Thus, $S^{*} \tau^{\prime}=\oplus_{m=0}^{\infty} S^{m} \tau^{\prime}$ becomes a bundle of commutative graded algebras.

We will extensively use the coordinate representation of tensors. If $\left(x^{1}, \ldots, x^{n}\right)$ is a local coordinate system in the domain $U \subset M$ then every tensor field $u \in C^{\infty}\left(\otimes^{m} \tau^{\prime} ; U\right)$ is uniquely represented in the form

$$
\begin{equation*}
u=u_{i_{1} \ldots i_{m}} d x^{i_{1}} \otimes \cdots \otimes d x^{i_{m}} \tag{2.2}
\end{equation*}
$$

where the functions $u_{i_{1} \ldots i_{m}} \in C^{\infty}(U)$ are the covariant components of the field $u$ in this coordinate system. In (2.2) and below, we use the Einstein rule: The summation from 1 to $n$ is assumed over an index repeated in the multivariate subscript and superscript of a monomial. Assuming the choice of a coordinate system to be clear from the context, we reduce formula (2.2) to

$$
\begin{equation*}
u=\left(u_{i_{1} \ldots i_{m}}\right) \tag{2.3}
\end{equation*}
$$

For $x \in U$ and $u \in \otimes^{m} T_{x}^{\prime}$, formulas (2.2) and (2.3) also make sense but the components are real numbers in this case. Contravariant components are defined by

$$
u^{i_{1} \ldots i_{m}}=g^{i_{1} j_{1}} \ldots g^{i_{m} j_{m}} u_{j_{1} \ldots j_{m}},
$$

where $\left(g^{i j}\right)$ is the inverse matrix to $\left(g_{i j}\right)$.
A tensor $u=\left(u_{i_{1} \ldots i_{m}}\right) \in \otimes^{m} T_{x}^{\prime}$ belongs to $S^{m} T_{x}^{\prime}$ if and only if its covariant and (or) contravariant components are symmetric with respect to all indices. We will also consider partially symmetric tensors. The partial symmetry of a tensor is denoted by

$$
\begin{equation*}
\operatorname{sym} u_{i_{1} \ldots i_{k} j_{1} \ldots j_{l}}:\left(i_{1} \ldots i_{k-1}\right) i_{k}\left(j_{1} \ldots j_{l-1}\right) j_{l} . \tag{2.4}
\end{equation*}
$$

This means the tensor $\left(u_{i_{1} \ldots i_{k} j_{1} \ldots j_{l}}\right)$ is symmetric in each group of indices in parentheses on the right-hand side of (2.4). Along with the full symmetrization $\sigma$, we will use partial symmetrization operators that are defined in coordinates by

$$
\sigma\left(i_{1} \ldots i_{m}\right) u_{i_{1} \ldots i_{m} j_{1} \ldots j_{l}}=\frac{1}{m!} \sum_{\pi \in \Pi_{m}} u_{i_{\pi(1)} \ldots i_{\pi(m)} j_{1} \ldots j_{l}} .
$$

Lemma 2.1. Let $m \geq 1, p \geq 1$, and $x \in M$. For every tensor $f \in \otimes^{2 m+p} T_{x}^{\prime}$ possessing the symmetry

$$
\begin{equation*}
\operatorname{sym} f_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}}:\left(i_{1} \ldots i_{m} j_{1} \ldots j_{p}\right)\left(k_{1} \ldots k_{m}\right) \tag{2.5}
\end{equation*}
$$

there exists a unique solution to the equation

$$
\begin{equation*}
\sigma\left(i_{1} \ldots i_{m} j_{1} \ldots j_{p}\right) u_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}}=f_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}}, \tag{2.6}
\end{equation*}
$$

possessing the symmetry

$$
\begin{equation*}
\operatorname{sym} u_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}}:\left(i_{1} \ldots i_{m}\right)\left(j_{1} \ldots j_{p} k_{1} \ldots k_{m}\right) \tag{2.7}
\end{equation*}
$$

The solution is expressed by the formula

$$
\begin{align*}
u_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}}= & \sigma\left(i_{1} \ldots i_{m}\right) \sigma\left(j_{1} \ldots j_{p} k_{1} \ldots k_{m}\right) \\
& \times \sum_{l=0}^{m}(-1)^{l}\binom{p+l-1}{l}\binom{m+p}{m-l} f_{i_{1} \ldots i_{m-l} j_{1} \ldots j_{p} k_{1} \ldots k_{m} i_{m-l+1} \ldots i_{m}} \tag{2.8}
\end{align*}
$$

where $\binom{k}{l}=\frac{k!}{l!(k-l)!}$ are the binomial coefficients.
Since this is a purely algebraic statement, it suffices to prove it in the case of $M=\mathbb{R}^{n}$. For $p=1$, the statement is proved in $[15, \S 2.4]$. For an arbitrary $p$, the proof is quite similar. The idea of the proof is as follows. Since the dimension of the space of tensors possessing symmetry (2.5) is equal to the dimension of the space of tensors possessing symmetry (2.7), it suffices to verify the equation obtained by substituting (2.8) into (2.6). This verification can be done by straightforward calculations that are omitted.

There is a natural inner product on $S^{m} T_{x}^{\prime}$ defined in coordinates by

$$
\begin{equation*}
\langle u, v\rangle=u_{i_{m} \ldots i_{m}} v^{i_{m} \ldots i_{m}} . \tag{2.9}
\end{equation*}
$$

We extend the product to $S^{*} T_{x}^{\prime}=\oplus_{m=0}^{\infty} S^{m} T_{x}^{\prime}$ assuming $S^{m} T_{x}^{\prime}$ and $S^{l} T_{x}^{\prime}$ to be orthogonal to each other for $m \neq l$. The product smoothly depends on $x$. Therefore, $S^{*} \tau^{\prime}$ obtains the structure of a Riemannian vector bundle. So we can introduce the $L^{2}$-product on $C_{0}^{\infty}\left(S^{*} \tau^{\prime}\right)$ as follows:

$$
\begin{equation*}
(u, v)_{L^{2}}=\int_{M}\langle u(x), v(x)\rangle d V(x), \tag{2.10}
\end{equation*}
$$

where $d V$ is the Riemannian volume form.
For $u \in S^{*} T_{x}^{\prime}$, let $i_{u}: S^{*} T_{x}^{\prime} \rightarrow S^{*} T_{x}^{\prime}$ be the operator of symmetric multiplication by $u$, i.e., $i_{u} v=u v$, and let $j_{u}$ be the adjoint operator of $i_{u}$. These operators are expressed by the formulas

$$
\begin{gathered}
\left(i_{u} v\right)_{i_{1} \ldots i_{m+l}}=\sigma\left(i_{1} \ldots i_{m+l}\right)\left(u_{i_{1} \ldots i_{m}} v_{i_{m+1} \ldots i_{m+l}}\right), \\
\left(j_{u} v\right)_{i_{1} \ldots i_{m-l}}=v_{i_{1} \ldots i_{l}} u^{i_{l-m+1} \ldots i_{l}}
\end{gathered}
$$

for $u \in S^{m} T_{x}^{\prime}$ and $v \in S^{l} T_{x}^{\prime}$. The second formula makes sense only for $m \leq l$. If $m>l$ then $j_{u} v=0$. For $u \in C^{\infty}\left(S^{*} \tau^{\prime}\right)$, the operators $i_{u}, j_{u} \in \operatorname{Hom}\left(S^{*} \tau^{\prime}, S^{*} \tau^{\prime}\right)$ are defined by $i_{u}(x)=i_{u(x)}$ and $j_{u}(x)=j_{u(x)}$. The operators $i_{g}$ and $j_{g}$ are of a particular importance in the present article, so we distinguish them by introducing the notation $i=i_{g}$ and $j=j_{g}$. These operators were already used in Introduction.

Lemma 2.2. For $m \geq 0$ and $k \geq 1$, the following commutation formula holds on $S^{m} \tau^{\prime}$ :

$$
j i^{k}=\frac{2 k(n+2 m+2 k-2)}{(m+2 k-1)(m+2 k)} i^{k-1}+\frac{m(m-1)}{(m+2 k-1)(m+2 k)} i^{k} j .
$$

In the case of $k=1$, the formula has the form

$$
\begin{equation*}
j i=\frac{2(n+2 m)}{(m+1)(m+2)} E+\frac{m(m-1)}{(m+1)(m+2)} i j, \tag{2.11}
\end{equation*}
$$

where $E$ the identity operator. The latter formula is proved by a straightforward calculation in coordinates which is omitted. The general case easily follows from (2.11) with the help of induction in $k$.

Lemma 2.3. For an arbitrary integer $m \geq 0$, the following decomposition formula holds:

$$
\begin{equation*}
S^{m} \tau^{\prime}=\bigoplus_{k=0}^{[m / 2]} i^{k}\left(\operatorname{Ker} j_{m-2 k}\right) \tag{2.12}
\end{equation*}
$$

where $[m / 2]$ is the integer part of $m / 2$, and $\operatorname{Ker} j_{m-2 k}$ is the kernel of the restriction $j_{m-2 k}$ of the operator $j$ to $S^{m-2 k} \tau^{\prime}$. Each summand of the decomposition is a subbundle in $S^{m} \tau^{\prime}$ and the summands are orthogonal to each other. The operator $i$ is a monomorphism and its range is related to decomposition (2.12) by the formula

$$
\begin{equation*}
\operatorname{Ran} i_{m-2}=\bigoplus_{k=1}^{[m / 2]} i^{k}\left(\operatorname{Ker} j_{m-2 k}\right) \tag{2.13}
\end{equation*}
$$

The product ji is a self-adjoint and positive definite operator. Each summand of (2.12) is a proper subspace of the operator ji associated with the eigenvalue

$$
\lambda_{k}=\frac{2(k+1)(n+2 m-2 k)}{(m+1)(m+2)} .
$$

The dimension of the summand equals $\alpha(m-2 k)-\alpha(m-2 k-2)$, where $\alpha(m)=\alpha(m, n)=$ $\binom{n+m-1}{m}$ is the dimension of $S^{m} \tau^{\prime}$.
Proof. The operator $i j$ is self-adjoint and nonnegative since it is the product of two operators that are dual to each other. Therefore, (2.11) implies that $j i$ is a positive self-adjoint operator. Hence, $i$ is a monomorphism and the orthogonal decomposition

$$
\begin{equation*}
S^{*} \tau^{\prime}=\operatorname{Ker} j \oplus \operatorname{Ran} i \tag{2.14}
\end{equation*}
$$

holds with the summands on the right-hand side being sub-bundles of the left-hand side.
Let $u \in \operatorname{Ker} j_{m-2 k}$. By Lemma 2.2, we get $(j i)\left(i^{k} u\right)=\lambda_{k} i^{k} u$. Therefore, each summand in (2.12) is the eigen-subspace of the operator $j i$ associated with the eigenvalue $\lambda_{k}$. Since all $\lambda_{k}$ are different, all summands are orthogonal to each other. The injectivity of $i$ and equation (2.14) imply

$$
\operatorname{dim}\left[i^{k}\left(\operatorname{Ker} j_{m-2 k}\right]=\operatorname{dim}\left(\operatorname{Ker} j_{m-2 k}\right)=\alpha(m-2 k)-\alpha(m-2 k-2) .\right.
$$

Equality (2.12) is now proved by comparing dimensions of spaces on both sides of the equality.

Let $p \in \operatorname{Hom}\left(S^{*} \tau^{\prime}, \operatorname{Ker} j\right)$ and $q \in \operatorname{Hom}\left(S^{*} \tau^{\prime}, \operatorname{Ran} i\right)$ be the orthogonal projections onto the summands of (2.14). One easily checks the equality

$$
\begin{equation*}
q=i(j i)^{-1} j . \tag{2.15}
\end{equation*}
$$

Decomposition (2.12) is closely related to the expansion of functions on the sphere in Fourier series in spherical harmonics. In order to explain the relationship, we introduce some notation.

If $\left(x^{1}, \ldots, x^{n}\right)$ is a local coordinate system with the domain $U$ then, for $x \in U$, a vector $\xi \in T_{x}$ is uniquely represented as $\xi=\xi^{i} \frac{\partial}{\partial x^{i}}(x)$. The functions $x^{i}, \xi^{i}(i=1, \ldots, n)$ form a local coordinate system on the manifold $T$ with the domain $\pi^{-1}(U)$, where $\pi$ is the projection of the tangent bundle. Strictly speaking, we should write $x^{i} \circ \pi$ instead of $x^{i}$. We use the shorter notation $x^{i}$ and hope it will not cause any ambiguity. Thus, every function $\varphi \in C^{\infty}\left(\pi^{-1}(U)\right)$ can be written in coordinates as follows:

$$
\varphi=\varphi\left(x^{1}, \ldots, x^{n}, \xi^{1}, \ldots, \xi^{n}\right) \quad\left(x \in U, \xi \in T_{x}\right)
$$

Since $T_{x}$ has the structure of an Euclidean space, the Laplace operator $\stackrel{v}{\Delta}_{x}: C^{\infty}\left(T_{x}\right) \rightarrow$ $C^{\infty}\left(T_{x}\right)$ is well defined. It smoothly depends on $x$, and therefore, defines an operator ${ }_{\Delta}^{v}$ $: C^{\infty}(T) \rightarrow C^{\infty}(T)$. (Warning: Do not mix up $C^{\infty}(T)$ and $C^{\infty}(\tau)!$ ) The operator is written in coordinates as

$$
\stackrel{v}{\Delta} \varphi(x, \xi)=g^{i j}(x) \frac{\partial^{2} \varphi(x, \xi)}{\partial \xi^{i} \partial \xi^{j}}
$$

and is called the vertical (or fiberwise) Laplacian.
The embedding $\varkappa_{x}: S^{*} T_{x}^{\prime} \rightarrow C^{\infty}\left(T_{x}\right)$ is defined by

$$
\left(\varkappa_{x} u\right)(\xi)=u_{i_{1} \ldots i_{m}} \xi^{i_{1}} \ldots \xi^{i_{m}}
$$

for $u \in S^{m} T_{x}^{\prime}$. It smoothly depends on $x$, and hence, defines an embedding $\varkappa: C^{\infty}\left(S^{*} \tau^{\prime}\right) \rightarrow$ $C^{\infty}(T)$ by the formula:

$$
(\varkappa u)(x, \xi)=u_{i_{1} \ldots i_{m}}(x) \xi^{i_{1}} \ldots \xi^{i_{m}}
$$

for $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$. Thus, $\varkappa$ identifies rank $m$ symmetric tensor fields with homogeneous polynomials (with respect to $\xi$ ) of degree $m$ on $T$.

Let $\Omega=\Omega M$ be the submanifold of $T$ which consists of the unit vectors, and let $\Omega_{x}=\Omega \cap T_{x}$ be the unit sphere in $T_{x}$. Given $u \in S^{*} T_{x}^{\prime}$, denote the restriction of $\varkappa_{x} u$ to $\Omega_{x}$ by $\lambda_{x} u$. The operator $\lambda_{x}: S^{*} T_{x}^{\prime} \rightarrow C^{\infty}\left(\Omega_{x}\right)$ smoothly depends on $x$ and defines an operator $\lambda: C^{\infty}\left(S^{*} \tau^{\prime}\right) \rightarrow C^{\infty}(\Omega)$.
We introduce an inner product $\langle\cdot, \cdot\rangle_{\omega}$ on the space $C^{\infty}\left(\Omega_{x}\right)$ by the formula

$$
\langle\varphi, \psi\rangle_{\omega}=\int_{\Omega_{x}} \varphi(\xi) \psi(\xi) d \omega(\xi)
$$

where $d \omega$ is the volume form on $\Omega_{x}$ induced by the metric $g$. The index $\omega$ is used in the notation in order to distinguish this product from the product defined by (2.9).
Lemma 2.4. The following equalities hold on $S^{m} T_{x}^{\prime}$ :

$$
\begin{gather*}
\lambda_{x} i=\lambda_{x},  \tag{2.16}\\
m(m-1) \varkappa_{x} j=\Delta_{x}^{v} \varkappa_{x} . \tag{2.17}
\end{gather*}
$$

For $u, v \in S^{m} T_{x}^{\prime}$ such that $j u=j v=0$, the following equality holds:

$$
\begin{equation*}
\left\langle\lambda_{x} u, \lambda_{x} v\right\rangle_{\omega}=\frac{m!\pi^{n / 2}}{2^{m-1} \Gamma(n / 2+m)}\langle u, v\rangle . \tag{2.18}
\end{equation*}
$$

Proof. For $u \in S^{m} T_{x}^{\prime}$ and $\xi \in \Omega_{x}$, we have

$$
\left(\lambda_{x} i u\right)(\xi)=\left(\sigma\left(i_{1} \ldots i_{m+2}\right)\left(u_{i_{1} \ldots i_{m}} g_{i_{m+1} i_{m+2}}\right)\right) \xi^{i_{1}} \ldots \xi^{i_{m+2}}
$$

Since the product $\xi^{i_{1}} \ldots \xi^{i_{m+2}}$ is symmetric with respect to $\left(i_{1}, \ldots, i_{m+2}\right)$, we can omit the symmetrization $\sigma\left(i_{1} \ldots i_{m+2}\right)$ here. So we get

$$
\left(\lambda_{x} i u\right)(\xi)=\left(u_{i_{1} \ldots i_{m}} \xi^{i_{1}} \ldots \xi^{i_{m}}\right)\left(g_{i_{m+1} i_{m+2}} \xi^{i_{m+1}} \xi^{i_{m+2}}\right)=u_{i_{1} \ldots i_{m}} \xi^{i_{1}} \ldots \xi^{i_{m}}
$$

because $g_{i_{m+1} i_{m+2}} \xi^{i_{m+1}} \xi^{i_{m+2}}=1$ on $\Omega_{x}$. By definition, the right-hand side of the last formula equals $\left(\lambda_{x} u\right)(\xi)$. This proves (2.16). Formula (2.17) is also proved by direct calculations:

$$
\begin{aligned}
\left(\stackrel{v}{\Delta}_{x} \varkappa_{x} u\right)(\xi) & =g^{i j} \frac{\partial^{2}}{\partial \xi^{i} \partial \xi^{j}}\left(u_{i_{1} \ldots i_{m}} \xi^{i_{1}} \ldots \xi^{i_{m}}\right) \\
& =m(m-1) g^{i j} u_{i_{1} \ldots i_{m-2} i j} \xi^{i_{1}} \ldots \xi^{i_{m-2}}=m(m-1)\left(\varkappa_{x} j u\right)(\xi)
\end{aligned}
$$

It suffices to prove (2.18) for $u=v$. The polynomial $\varkappa_{x} u$ can be written in the two ways:

$$
\begin{equation*}
\left(\varkappa_{x} u\right)(\xi)=u_{i_{1} \ldots i_{m}} \xi^{i_{1}} \ldots \xi^{i_{m}}=\sum_{|\alpha|=m} u_{\alpha} \xi^{\alpha} \tag{2.19}
\end{equation*}
$$

where $\alpha=\left(\alpha_{1}, \ldots, \alpha_{n}\right)$ is a multiindex. The coefficients of (2.19) are related by the equality $u_{\alpha}=\frac{m!}{\alpha!} u_{i(\alpha)}$, with $i(\alpha)=(1 \ldots 12 \ldots 2 \ldots n \ldots n)$ where 1 is repeated $\alpha_{1}$ times, 2 is repeated $\alpha_{2}$ times, etc.
We choose the coordinates in a neighborhood of $x$ so that $g_{i j}(x)=\delta_{i j}$, where $\left(\delta_{i j}\right)$ is the Kronecker symbol. Then

$$
\begin{equation*}
\langle u, u\rangle=\frac{1}{m!} \sum_{|\alpha|=m} \alpha!\left|u_{\alpha}\right|^{2} . \tag{2.20}
\end{equation*}
$$

Indeed,

$$
\langle u, u\rangle=\sum_{i_{1}, \ldots i_{m}=1}^{n}\left|u_{i_{1} \ldots i_{m}}\right|^{2}=\sum_{|\alpha|=m} \frac{m!}{\alpha!}\left|u_{i(\alpha)}\right|^{2} .
$$

Taking the relations $u_{i(\alpha)}=\alpha!u_{\alpha} / m!$ into account, we obtain (2.20).
For $|\alpha|=m$, formula (2.19) implies

$$
\begin{equation*}
\partial_{\xi}^{\alpha}\left(\varkappa_{x} u\right)=\alpha!u_{\alpha} . \tag{2.21}
\end{equation*}
$$

Therefore equality (2.20) can be written as

$$
\begin{equation*}
\langle u, u\rangle=\frac{1}{m!} \sum_{|\alpha|=m} \frac{1}{\alpha!}\left|\partial_{\xi}^{\alpha}\left(\varkappa_{x} u\right)\right|^{2} . \tag{2.22}
\end{equation*}
$$

In virtue of (2.17), the condition $j u=0$ means $\lambda_{x} u$ is a spherical harmonics of degree $m$. Ass well known, the spherical harmonics satisfy the equality

$$
\begin{equation*}
A_{m, m}=\frac{2^{m} \Gamma(n / 2+m) \Gamma(m+1)}{\Gamma(n / 2)} A_{0, m}, \tag{2.23}
\end{equation*}
$$

(for example, see [17, Lemma XI.1]), where

$$
\begin{gather*}
A_{0, m}=\int_{\Omega_{x}}\left|\lambda_{x} u(\xi)\right|^{2} d \omega(\xi)=\left\langle\lambda_{x} u, \lambda_{x} u\right\rangle_{\omega},  \tag{2.24}\\
A_{m, m}=\sum_{|\alpha|=m} \frac{m!}{\alpha!} \int_{\Omega_{x}}\left|\partial_{\xi}^{\alpha}\left(\varkappa_{x} u\right)\right|^{2} d \omega(\xi)
\end{gather*}
$$

By (2.21), the last integrand is constant and the last formula gives

$$
A_{m, m}=m!\omega_{n} \sum_{|\alpha|=m} \alpha!\left|u_{\alpha}\right|^{2}
$$

where $\omega_{n}$ is the volume of the unit sphere in $\mathbb{R}^{n}$. Together with (2.20), the last formula implies

$$
\begin{equation*}
A_{m, m}=(m!)^{2} \omega_{n}\langle u, u\rangle \tag{2.25}
\end{equation*}
$$

Finally, substituting (2.24), (2.25), and $\omega_{n}=2 \pi^{n / 2} / \Gamma(n / 2)$ into (2.23), we obtain (2.18).

According to Lemma 2.4, the operator $\lambda_{x}$ isomorphically maps the subspace $\operatorname{Ker} j_{m} \subset$ $S^{m} T_{x}^{\prime}$ onto the space of spherical harmonics of degree $m$ on $\Omega_{x}$. Moreover, this isomorphism is an isometry up to a constant factor if $\operatorname{Ker} j_{m}$ is equipped with the inner product $\langle\cdot, \cdot\rangle$ and the space of harmonics is equipped with the product $\langle\cdot, \cdot\rangle_{\omega}$.

As well known (for example, see [17]), spherical harmonics of different degrees are orthogonal to each other and every function $\varphi \in C^{\infty}\left(\Omega_{x}\right)$ can be expanded in the Fourier series in spherical harmonics of different degrees. The series converges absolutely and uniformly. The expansion smoothly depends on the point $x$, and we arrive to the following statement.

Lemma 2.5. Every function $\varphi \in C^{\infty}(\Omega)$ can be uniquely represented by the series

$$
\begin{equation*}
\varphi=\sum_{m=0}^{\infty} \lambda u_{m}, \tag{2.26}
\end{equation*}
$$

where $u_{m} \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$ satisfy the condition $j u_{m}=0$. The series converges absolutely and uniformly on each compact subset of $\Omega$.

By Lemma 2.3, a tensor field $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$ is uniquely represented in the form

$$
\begin{equation*}
u=\sum_{k=0}^{[m / 2]} i^{k} u_{m-2 k}, \tag{2.27}
\end{equation*}
$$

where every $u_{m-2 k} \in C^{\infty}\left(S^{m-2 k} \tau^{\prime}\right)$ satisfies $j u_{m-2 k}=0$. Expansion (2.27) coincides with the Fourier series (2.26) of the function $\lambda u \in C^{\infty}(\Omega)$. More precisely, the Fourier series of the function $\lambda u$ has a finite number of the summands, namely,

$$
\lambda u=\sum_{k=0}^{[m / 2]} \lambda u_{m-2 k}
$$

where the tensor fields $u_{m-2 k}$ are the same as in (2.27).

## 3. The operators $d$ and $\delta$

Given a Riemannian manifold $(M, g)$, let $\nabla: C^{\infty}\left(\otimes^{m} \tau^{\prime}\right) \rightarrow C^{\infty}\left(\otimes^{m+1} \tau^{\prime}\right)$ be the covariant differentiation with respect to the Levi-Civita connection. For a tensor field $u=\left(u_{i_{1} \ldots i_{m}}\right)$, higher order covariant derivatives are denoted by $\nabla^{k} u=\left(\nabla_{j_{1} \ldots j_{k}} u_{i_{1} \ldots i_{m}}\right)$. The inner derivative $d: C^{\infty}\left(S^{*} \tau^{\prime}\right) \rightarrow C^{\infty}\left(S^{*} \tau^{\prime}\right)$ is defined by $d=\sigma \nabla$. The divergence $\delta: C^{\infty}\left(S^{*} \tau^{\prime}\right) \rightarrow C^{\infty}\left(S^{*} \tau^{\prime}\right)$ is defined in local coordinates as $(\delta u)_{i_{1} \ldots i_{m-1}}=g^{j k} \nabla_{j} u_{k i_{1} \ldots i_{m-1}}$. These $d$ and $\delta$ are the first order differential operators of degree 1 and -1 , respectively. They were already mentioned in Introduction.

Theorem 3.1. The operators $d$ and $-\delta$ are dual to each other with respect to the $L^{2}$ product of symmetric tensor fields. Moreover, for a compact manifold $M$ with boundary, Green's formula

$$
\int_{M}(\langle d u, v\rangle+\langle u, \delta v\rangle) d V=\int_{\partial M}\left\langle i_{\nu} u, v\right\rangle d V^{\prime}
$$

holds for $u, v \in C^{\infty}\left(S^{*} \tau^{\prime}\right)$, where $\nu$ is the unit outward normal to the boundary, and $d V$ and $d V^{\prime}$ are the Riemannian volume forms of $M$ and of $\partial M$, respectively.

The proof is given in [15, §3.3].
Lemma 3.2. The following equalities hold on $C^{\infty}\left(S^{*} \tau^{\prime}\right)$ :

$$
\begin{array}{ll}
i d=d i, & j \delta=\delta j \\
p d p=p d, & p \delta p=\delta p \\
q d q=d q, & q \delta q=q \delta \\
p d q=0, & q \delta p=0 \tag{3.4}
\end{array}
$$

Proof. These formulas are written in pairs every of which is formed by two relatively dual relationships. It suffices to prove one formula in each pair. The second formula in (3.1) can be proved by direct calculation in coordinates and we omit it. The first formula in (3.3) is derived from (2.15) and (3.1) as follows:

$$
q d q=i(j i)^{-1} j d i(j i)^{-1} j=i(j i)^{-1} j i d(j i)^{-1} j=i d(j i)^{-1} j=d i(j i)^{-1} j=d q .
$$

Formula (3.2) is obtained from (3.3) by the substitution $q=E-p$. The left multiplication of the first formula of (3.3) by $p$ implies the first formula of (3.4).

Lemma 3.3. The following equalities hold on $C^{\infty}\left(S^{m} \tau^{\prime}\right)$ :

$$
\begin{align*}
\delta i & =\frac{2}{m+2} d+\frac{m}{m+2} i \delta,  \tag{3.5}\\
j d & =\frac{2}{m+1} \delta+\frac{m-1}{m+1} d j . \tag{3.6}
\end{align*}
$$

Proof. It suffices to prove (3.5) since (3.6) is obtained by the duality. For $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$, we have

$$
(\delta i u)_{i_{1} \ldots i_{m j}}=g^{k l}\left[\sigma\left(i_{1} \ldots i_{m} j k\right)\left(g_{j k} \nabla_{l} u_{i_{1} \ldots i_{m}}\right)\right]
$$

by the definition of $i$ and $\delta$, and by the equality $\nabla g=0$. The expression in brackets represents the sum over $\Pi_{m+2}$. We divide all the terms of the sum into four groups as follows: The first group includes the products of the form $g_{r s} \nabla_{l} u_{t_{1} \ldots t_{m}}$ for $\{r, s\}=\{j, k\}$; the second group (the third group) consists of the products such that $k \in\{r, s\}$ and $j \notin\{r, s\} \quad(k \notin\{r, s\}$ and $j \in\{r, s\})$, and the fourth group contains all the remaining terms. We thus obtain

$$
\begin{aligned}
\frac{(m+1)(m+2)}{2}(\delta i u)_{i_{1} \ldots i_{m} j}=g^{k l} & {\left[g_{j k} \nabla_{l} u_{i_{1} \ldots i_{m}}+\sum_{a=1}^{m} g_{k i_{a}} \nabla_{l} u_{j i_{1} \ldots \hat{i_{a} \ldots i_{m}}}\right.} \\
& \left.+\sum_{a=1}^{m} g_{j i_{a}} \nabla_{l} u_{k i_{1} \ldots \hat{i_{a}} \ldots i_{m}}+\sum_{1 \leq a<b \leq m} g_{i_{a} i_{b}} \nabla_{l} u_{j k i_{1} \ldots \hat{i_{a}} \ldots \hat{i_{b}} \ldots i_{m}}\right],
\end{aligned}
$$

where $\wedge$ over an index means the index is omitted. Using the identity $g^{k l} g_{j k}=\delta_{k}^{l}$, where $\left(\delta_{k}^{l}\right)$ is the Kronecker tensor, we rewrite the last formula in the form

$$
\begin{aligned}
\frac{(m+1)(m+2)}{2}(\delta i u)_{i_{1} \ldots i_{m} j} & =\nabla_{j} u_{i_{1} \ldots i_{m}}+\sum_{a=1}^{m} \nabla_{i_{a}} u_{j i_{1} \ldots \hat{i_{a}} \ldots i_{m}} \\
& +\sum_{a=1}^{m} g_{j i_{a}}(\delta u)_{i_{1} \ldots \hat{i_{a}} \ldots i_{m}}+\sum_{1 \leq a<b \leq m} g_{i_{a} i_{b}}(\delta u)_{j i_{1} \ldots \hat{i_{a}} \ldots \hat{i_{b}} \ldots i_{m}} .
\end{aligned}
$$

The sum of the first two summands on the right-hand side of this formula equals $(m+1)(d u)_{j i_{1} \ldots i_{m}}$, and the sum of the last two summands equals $\frac{m(m+1)}{2}(i \delta u)_{j i_{1} \ldots i_{m}}$.

Lemma 3.4. The following equalities hold on $C^{\infty}\left(S^{m} \tau^{\prime}\right)$ :

$$
\begin{array}{ll}
d q=q d-\frac{m}{n+2 m-2} i \delta p, & q \delta=\delta q-\frac{m-1}{n+2 m-4} p d j, \\
d p=p d+\frac{m}{n+2 m-2} i \delta p, & p \delta=\delta p+\frac{m-1}{n+2 m-4} p d j . \tag{3.8}
\end{array}
$$

Proof. As above, the formulas are written in dual pairs and (3.8) is obtained from (3.7) by the substitution $q=E-p$. Hence it suffices to prove the first of formulas (3.7).

By (3.1) and (3.6),

$$
j i d=j d i=\left(\frac{2}{m+3} \delta+\frac{m+1}{m+3} d j\right) i .
$$

The left and right multiplications of this formula by $(j i)^{-1}$ yield

$$
d(j i)^{-1}=\frac{m+1}{m+3}(j i)^{-1} d+\frac{2}{m+3}(j i)^{-1} \delta i(j i)^{-1} .
$$

In virtue of (2.15) and (3.6), this gives

$$
\begin{aligned}
d q=d i(j i)^{-1} j & =i d(j i)^{-1} j=i\left(\frac{m-1}{m+1}(j i)^{-1} d+\frac{2}{m+1}(j i)^{-1} \delta i(j i)^{-1}\right) j \\
& =\frac{m-1}{m+1} i(j i)^{-1}\left(\frac{m+1}{m-1} j d-\frac{2}{m-1} \delta\right)+\frac{2}{m+1} i(j i)^{-1} \delta q \\
& =q d-\frac{2}{m+1} i(j i)^{-1} \delta(E-q)
\end{aligned}
$$

i.e.,

$$
\begin{equation*}
d q=q d-\frac{2}{m+1} i(j i)^{-1} \delta p . \tag{3.9}
\end{equation*}
$$

The equality $j p=0$ follows from the definition of $p$. According to (2.11) and (3.1), this implies

$$
(j i) \delta p=\frac{2(n+2 m-2)}{m(m+1)} \delta p+\frac{(m-1)(m-2)}{m(m+1)} i j \delta p=\frac{2(n+2 m-2)}{m(m+1)} \delta p .
$$

Hence the equality

$$
\begin{equation*}
(j i)^{-1} \delta p=\frac{m(m+1)}{2(n+2 m-2)} \delta p \tag{3.10}
\end{equation*}
$$

holds on $C^{\infty}\left(S^{m} \tau^{\prime}\right)$. Substitution of (3.10) into (3.9) implies the first formula of (3.7).
Let us now demonstrate how does Theorem 1.1 imply Corollary 1.2. Let $u$ and $v$ satisfy the hypotheses of Corollary 1.2, and let $\tilde{u}=p u$. Then

$$
\begin{equation*}
j \tilde{u}=0 . \tag{3.11}
\end{equation*}
$$

Applying the operator $p$ to (1.2), we obtain $p d u=0$. Transformation of the left-hand side of this equality by (3.8) implies

$$
\left(d-\frac{m}{n+2 m-2} i \delta\right) \tilde{u}=0 .
$$

We denote $\tilde{v}=\frac{m}{n+2 m-2} \delta \tilde{u}$ and rewrite the last formula as

$$
\begin{equation*}
d \tilde{u}=i \tilde{v} . \tag{3.12}
\end{equation*}
$$

As is seen from (2.15), the operator $p=E-q$ is represented in coordinates by a matrix whose elements are rational functions of the components $g_{i j}$ of the metric tensor. Therefore conditions (1.4) imply the similar conditions for $\tilde{u}=p u$ :

$$
\begin{equation*}
\tilde{u}\left(x_{0}\right)=0, \quad \nabla \tilde{u}\left(x_{0}\right)=0, \quad \ldots, \quad \nabla^{l} \tilde{u}\left(x_{0}\right)=0 . \tag{3.13}
\end{equation*}
$$

According to (3.11)-(3.13), $\tilde{u}$ satisfies the hypotheses of Theorem 1.1. Assuming the theorem to be valid, we obtain $\tilde{u}=p u=0$. This means the existence of $w$ such that $u=$ $i w$. Theorem 1.3 implies Corollary 1.4 in a similar way.

## 4. Proof of Theorem 1.3

According to Theorem 1.1 whose proof will be given below, Theorem 1.3 follows from a weaker statement formulated in

Lemma 4.1. Let $\Gamma$ be a smooth hypersurface in a Riemannian manifold $M$. If tensor fields $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$ and $v \in C^{\infty}\left(S^{m-1} \tau^{\prime}\right)$ satisfy the conditions

$$
d u=i v, \quad j u=0,\left.\quad u\right|_{\Gamma}=0
$$

then $u$ and $v$ vanish on $\Gamma$ together with all their derivatives.

Proof. The statement is trivial for $m=0$. Let $m \geq 1$. We prove by induction in $k$ the validity of the following statement:

$$
\begin{aligned}
& \left.u\right|_{\Gamma}=0,\left.\nabla u\right|_{\Gamma}=0, \ldots,\left.\nabla^{k} u\right|_{\Gamma}=0, \\
& \left.v\right|_{\Gamma}=0,\left.\nabla v\right|_{\Gamma}=0, \ldots,\left.\nabla^{k-1} v\right|_{\Gamma}=0 .
\end{aligned}
$$

For $k=0$, the statement coincides with the hypothesis $\left.u\right|_{\Gamma}=0$. Assume the required statement to be true for some $k \geq 0$.

We choose a coordinate system $\left(x^{1}, \ldots, x^{n}\right)=\left(x^{11}, \ldots, x^{\prime n-1}, y\right)$ in some neighborhood of $x_{0} \in \Gamma$ so that $\Gamma$ is defined by the equation $y=0$ and $g_{i n}=\delta_{i n}$. Here and below $\left(\delta_{i j}\right)$ is the Kronecker tensor. By the induction hypothesis,

$$
\begin{gather*}
\left.\frac{\partial^{l}}{\partial y^{l}} \partial_{x^{\prime}}^{\beta} u_{i_{1} \ldots i_{m}}\right|_{y=0}=0 \text { for } l \leq k, \\
\left.\frac{\partial^{l}}{\partial y^{l}} \partial_{x^{\prime}}^{\beta} v_{i_{1} \ldots i_{m-1}}\right|_{y=0}=0 \text { for } l \leq k-1 \tag{4.1}
\end{gather*}
$$

for an arbitrary $(n-1)$-variate index $\beta$.
The equality $d u=i v$ has the following form in the chosen coordinates:

$$
\begin{array}{r}
\nabla_{i_{1}} u_{i_{2} \ldots i_{m+1}}+\nabla_{i_{2}} u_{i_{1} i_{3} \ldots i_{m+1}}+\cdots+\nabla_{i_{m+1}} u_{i_{1} \ldots i_{m}} \\
=(m+1) \sigma\left(i_{1} \ldots i_{m+1}\right)\left(g_{i_{1} i_{2}} v_{i_{3} \ldots i_{m+1}}\right) .
\end{array}
$$

Applying the operator $\left.\frac{\partial^{k}}{\partial y^{k}}\right|_{y=0}$ to this equality and taking (4.1) into account, we obtain

$$
\begin{align*}
& \left.\frac{\partial^{k}}{\partial y^{k}}\left(\frac{\partial u_{i_{2} \ldots i_{m+1}}}{\partial x^{i_{1}}}+\cdots+\frac{\partial u_{i_{1} \ldots i_{m}}}{\partial x^{i_{m+1}}}\right)\right|_{y=0} \\
& \quad=(m+1) \sigma\left(i_{1} \ldots i_{m+1}\right)\left(\left.g_{i_{1} i_{2}} \frac{\partial^{k} v_{i_{3} \ldots i_{m+1}}}{\partial y^{k}}\right|_{y=0}\right) \tag{4.2}
\end{align*}
$$

Hereafter we use the following agreement: Greek indices vary from 1 to $n-1$, and the summation from 1 to $n-1$ is assumed over repeated Greek indices. Set $\left(i_{1}, \ldots, i_{m+1}\right)=$ $\left(\alpha_{1}, \ldots, \alpha_{m+1}\right)$ in (4.2). Then the left-hand side of (4.2) equals zero by (4.1) and we obtain

$$
\begin{equation*}
\sigma\left(\alpha_{1} \ldots \alpha_{m+1}\right)\left(\left.g_{\alpha_{1} \alpha_{2}} \frac{\partial^{k} v_{\alpha_{3} \ldots \alpha_{m+1}}}{\partial y^{k}}\right|_{y=0}\right)=0 . \tag{4.3}
\end{equation*}
$$

We rewrite (4.2) in the form

$$
\begin{align*}
& \left.\frac{\partial^{k}}{\partial y^{k}}\left(\frac{\partial u_{i_{2} \ldots i_{m+1}}}{\partial x^{i_{1}}}+\cdots+\frac{\partial u_{i_{1} \ldots i_{m}}}{\partial x^{i_{m+1}}}\right)\right|_{y=0} \\
& \quad=\left.\frac{1}{m!} \sum_{\pi \in \Pi_{m+1}} g_{i_{\pi(1)} i_{\pi(2)}} \frac{\partial^{k} v_{i_{\pi(3)} \cdots i_{\pi(m+1)}}}{\partial y^{k}}\right|_{y=0} \tag{4.4}
\end{align*}
$$

Let $0 \leq s \leq m$. We set $\left(i_{1}, \ldots, i_{m-s}\right)=\left(\alpha_{1}, \ldots, \alpha_{m-s}\right)$ and $i_{m-s+1}=\cdots=i_{m+1}=n$ in (4.4). By (4.1), the first $m-s$ summands on the left-hand side of (4.4) are equal to zero and the last $s+1$ summands coincide, i.e.,

$$
\begin{equation*}
\left.\frac{\partial^{k}}{\partial y^{k}}\left(\frac{\partial u_{i_{2} \ldots i_{m+1}}}{\partial x^{i_{1}}}+\cdots+\frac{\partial u_{i_{1} \ldots i_{m}}}{\partial x^{i_{m+1}}}\right)\right|_{y=0}=\left.(s+1) \frac{\partial^{k+1} u_{\alpha_{1} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k+1}}\right|_{y=0} . \tag{4.5}
\end{equation*}
$$

Let us analyze the right-hand side of (4.4) for the chosen indices. If $\pi(1) \leq m-s$ and $\pi(2)>m-s$ then $g_{i_{\pi(1)} i_{\pi(2)}}=0$. Similarly, $g_{i_{\pi(1)} i_{\pi(2)}}=0$ if $\pi(1)>m-s$ and $\pi(2) \leq m-s$. Therefore

$$
\begin{align*}
& \left.\quad \sum_{\pi \in \Pi_{m+1}} g_{i_{\pi(1)} i_{\pi(2)}} \frac{\partial^{k} v_{i_{\pi(3)} \ldots i_{\pi(m+1)}}}{\partial y^{k}}\right|_{y=0} \\
& \quad=\left.\sum_{\pi \in \Pi_{m+1}(s)} \frac{\partial^{k} v_{i_{\pi(3)} \ldots i_{\pi(m+1)}}}{\partial y^{k}}\right|_{y=0}+\left.\sum_{\pi \in \Pi_{m+1}^{\prime}(s)} g_{i_{\pi(1)} i_{\pi(2)}} \frac{\partial^{k} v_{i_{\pi(3)} \ldots i_{\pi(m+1)}}}{\partial y^{k}}\right|_{y=0}, \tag{4.6}
\end{align*}
$$

where

$$
\begin{aligned}
& \Pi_{m+1}(s)=\left\{\pi \in \Pi_{m+1} \mid \pi(1)>m-s, \pi(2)>m-s\right\}, \\
& \Pi_{m+1}^{\prime}(s)=\left\{\pi \in \Pi_{m+1} \mid \pi(1) \leq m-s, \pi(2) \leq m-s\right\} .
\end{aligned}
$$

All the summands of the first sum on the right-hand side of (4.6) coincide because $v$ is symmetric. And the total amount of the summands is $(m-1)!s(s+1)$, i.e.,

$$
\begin{equation*}
\left.\sum_{\pi \in \Pi_{m+1}(s)} \frac{\partial^{k} v_{i_{\pi(3)} \ldots i_{\pi(m+1)}}}{\partial y^{k}}\right|_{y=0}=\left.(m-1)!s(s+1) \frac{\partial^{k} v_{\alpha_{1} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k}}\right|_{y=0} . \tag{4.7}
\end{equation*}
$$

For $s=0$, the right-hand side of (4.7) is equal to zero due to the factor $s$.
The second sum on the right-hand side of (4.6) is obviously equal to

$$
\begin{equation*}
c(m, s) \sigma\left(\alpha_{1} \ldots \alpha_{m-s}\right)\left(\left.g_{\alpha_{1} \alpha_{2}} \frac{\partial^{k} v_{\alpha_{3} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k}}\right|_{y=0}\right), \tag{4.8}
\end{equation*}
$$

where $c(m, s)=(m-1)!(m-s)(m-s-1)$ is total amount of elements in $\Pi_{m+1}^{\prime}(s)$. Substitute (4.7) and (4.8) into (4.6) to obtain

$$
\begin{align*}
& \left.\frac{1}{(m-1)!} \sum_{\pi \in \Pi_{m+1}} g_{i_{\pi(1)} i_{\pi(2)}} \frac{\partial^{k} v_{i_{\pi(3)} \ldots i_{\pi(m+1)}}}{\partial y^{k}}\right|_{y=0}=\left.s(s+1) \frac{\partial^{k} v_{\alpha_{1} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k}}\right|_{y=0} \\
& \quad+(m-s)(m-s-1) \sigma\left(\alpha_{1} \ldots \alpha_{m-s}\right)\left(\left.g_{\alpha_{1} \alpha_{2}} \frac{\partial^{k} v_{\alpha_{3} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k}}\right|_{y=0}\right) \tag{4.9}
\end{align*}
$$

Next, we substitute (4.5) and (4.9) into (4.4)

$$
\begin{align*}
& \left.\frac{\partial^{k+1} u_{\alpha_{1} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k+1}}\right|_{y=0}=\left.\frac{s}{m} \frac{\partial^{k} v_{\alpha_{1} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k}}\right|_{y=0} \\
& \quad+\frac{(m-s)(m-s-1)}{m(s+1)} \sigma\left(\alpha_{1} \ldots \alpha_{m-s}\right)\left(\left.g_{\alpha_{1} \alpha_{2}} \frac{\partial^{k} v_{\alpha_{3} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k}}\right|_{y=0}\right) . \tag{4.10}
\end{align*}
$$

We define the tensor fields

$$
z^{(s)} \in C^{\infty}\left(S^{m-s} \tau_{\Gamma}^{\prime}\right) \quad(0 \leq s \leq m), \quad w^{(s)} \in C^{\infty}\left(S^{m-s} \tau_{\Gamma}^{\prime}\right) \quad(1 \leq s \leq m)
$$

on $\Gamma$ as follows:

$$
\begin{equation*}
z_{\alpha_{1} \ldots \alpha_{m-s}}^{(s)}=\left.\frac{\partial^{k+1} u_{\alpha_{1} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k+1}}\right|_{y=0}, \quad w_{\alpha_{1} \ldots \alpha_{m-s}}^{(s)}=\left.\frac{\partial^{k} v_{\alpha_{1} \ldots \alpha_{m-s} n \ldots n}}{\partial y^{k}}\right|_{y=0} . \tag{4.11}
\end{equation*}
$$

For convenience, we also define $w^{(0)}=0, w^{(m+1)}=0$, and $w^{(m+2)}=0$. Then (4.10) can be written in the coordinate-free form

$$
\begin{equation*}
z^{(s)}=\frac{s}{m} w^{(s)}+\frac{(m-s)(m-s-1)}{m(s+1)} i w^{(s+2)} \quad(0 \leq s \leq m) \tag{4.12}
\end{equation*}
$$

and (4.3) can be written as $i w^{(1)}=0$. Since $i$ is a monomorphism, this implies

$$
\begin{equation*}
w^{(1)}=0 . \tag{4.13}
\end{equation*}
$$

If $m=1$ then $v$ is a scalar function and (4.13) gives $\left.\frac{\partial^{k} v}{\partial y^{k}}\right|_{y=0}=0$. Equation (4.12) implies

$$
z_{\alpha}^{(0)}=\left.\frac{\partial^{k+1} u_{\alpha}}{\partial y^{k+1}}\right|_{y=0}=0,\left.\quad \frac{\partial^{k+1} u_{n}}{\partial y^{k+1}}\right|_{y=0}=z^{(1)}=w^{(1)}=0 .
$$

This justifies the induction step in the case of $m=1$. Therefore, we assume $m \geq 2$ in the rest of the proof.

In the chosen coordinates, the equation $j u=0$ is written as follows:

$$
u_{i_{1} \ldots i_{m-2} n n}+g^{\beta \gamma} u_{\beta \gamma i_{1} \ldots i_{m-2}}=0 .
$$

Differentiating this identity $k+1$ times with respect to $y$, we obtain

$$
\left.\frac{\partial^{k+1} u_{i_{1} \ldots i_{m-2} n n}}{\partial y^{k+1}}\right|_{y=0}+\left.g^{\beta \gamma} \frac{\partial^{k+1} u_{\beta \gamma i_{1} \ldots i_{m-2}}}{\partial y^{k+1}}\right|_{y=0}=0
$$

We set $\left(i_{1}, \ldots, i_{m-s}\right)=\left(\alpha_{1}, \ldots, \alpha_{m-s}\right)$ and $i_{m-s+1}=\ldots i_{m-2}=n$ in the last formula to obtain

$$
z^{(s)}+j z^{(s-2)}=0 \quad(2 \leq s \leq m) .
$$

This implies

$$
\begin{equation*}
z^{(2 s)}=(-j)^{s} z^{(0)} \quad \text { for } \quad 0 \leq 2 s \leq m, \quad z^{(2 s+1)}=(-j)^{s} z^{(1)} \quad \text { for } \quad 0 \leq 2 s+1 \leq m . \tag{4.14}
\end{equation*}
$$

Setting $s=m$ and then $s=m-1$ in (4.12), we get

$$
w^{(m)}=z^{(m)}, \quad w^{(m-1)}=\frac{m}{m-1} z^{(m-1)} .
$$

Taking (4.14) into account, this implies

$$
\begin{align*}
w^{\left(2 m^{\prime}\right)} & =(-j)^{m^{\prime}} z^{(0)} & \text { for } m=2 m^{\prime}, \\
w^{\left(2 m^{\prime}\right)} & =\frac{2 m^{\prime}+1}{2 m^{\prime}}(-j)^{m^{\prime}} z^{(0)} & \text { for } m=2 m^{\prime}+1,  \tag{4.15}\\
w^{\left(2 m^{\prime}-1\right)} & =\frac{2 m^{\prime}}{2 m^{\prime}-1}(-j)^{m^{\prime}-1} z^{(1)} & \text { for } m=2 m^{\prime},  \tag{4.16}\\
w^{\left(2 m^{\prime}+1\right)} & =(-j)^{m^{\prime}} z^{(1)} & \text { for } m=2 m^{\prime}+1 .
\end{align*}
$$

Now, we are going to prove the representations

$$
\begin{align*}
w^{(2 s)} & =(-1)^{s} \sum_{l=0}^{[m / 2]-s} a(m, s, l) i^{l} j^{s+l} z^{(0)} \quad \text { for } 0<2 s \leq m,  \tag{4.17}\\
w^{(2 s+1)} & =(-1)^{s} \sum_{l=0}^{[m-1 / 2]-s} b(m, s, l) i^{l} j^{s+l} z^{(1)} \quad \text { for } \quad 0<2 s+1 \leq m, \tag{4.18}
\end{align*}
$$

with some positive coefficients $a(m, s, l)$ and $b(m, s, l)$, where $[\cdot]$ denotes, as usual, the integer part of a number. For $0 \leq m-2 s \leq 1$, formula (4.17) coincides with (4.15). We
shall prove (4.17) by induction in $m-2 s$. Let $s>0$ and $m-2 s \geq 2$. If we take $s:=2 s$ in (4.12) then we get

$$
z^{(2 s)}=\frac{2 s}{m} w^{(2 s)}+\frac{(m-2 s)(m-2 s-1)}{m(2 s+1)} i w^{(2 s+2)} .
$$

We express $w^{(2 s)}$ from this equation

$$
w^{(2 s)}=\frac{m}{2 s} z^{(2 s)}-\frac{(m-2 s)(m-2 s-1)}{2 s(2 s+1)} i w^{(2 s+2)} .
$$

We replace the first term on the right-hand side by its value (4.14) and replace the second term by its expression from the inductive hypothesis (4.17)

$$
w^{(2 s)}=(-1)^{s}\left(\frac{m}{2 s} j^{s} z^{(0)}+\frac{(m-2 s)(m-2 s-1)}{2 s(2 s+1)} \sum_{l=0}^{\left[\frac{m}{2}\right]-s-1} a(m, s+1, l) i^{l+1} j^{s+l+1} z^{(0)}\right) .
$$

Changing the summation index, we transform this expression to the form

$$
w^{(2 s)}=(-1)^{s}\left(\frac{m}{2 s} j^{s} z^{(0)}+\frac{(m-2 s)(m-2 s-1)}{2 s(2 s+1)} \sum_{l=1}^{\left[\frac{m}{2}\right]-s} a(m, s+1, l-1) i^{l} j^{s+l} z^{(0)}\right) .
$$

This is equivalent to (4.17) with

$$
a(m, s, l)=\left\{\begin{array}{l}
m / 2 s \quad \text { for } \quad l=0, \\
\frac{(m-2 s)(m-2 s-1)}{2 s(2 s+1)} a(m, s+1, l-1) \quad \text { for } \quad l \geq 1 .
\end{array}\right.
$$

Thus, representation (4.17) is proved. The proof of (4.18) is quite similar.
Set $s=0$ in (4.12)

$$
\begin{equation*}
z^{(0)}=(m-1) i w^{(2)} . \tag{4.19}
\end{equation*}
$$

By (4.17),

$$
w^{(2)}=-\sum_{l=0}^{\left[\frac{m}{2}\right]-1} a(m, 1, l) i^{l} j^{l+1} z^{(0)} .
$$

Substitution of the last expression into (4.19) gives

$$
\begin{equation*}
\left[E+(m-1) \sum_{l=1}^{[m / 2]} a(m, 1, l-1) i^{l} j^{l}\right] z^{(0)}=0 \tag{4.20}
\end{equation*}
$$

where $E$ is the identity operator. The operator in the brackets is nondegenerate since the coefficients of the sum are positive and the operator $i^{l} j^{l}$ is nonnegative. Hence, (4.20) implies $z^{(0)}=0$. So, according to (4.14) and (4.17), $z^{(2 s)}=0$ and $w^{(2 s)}=0$ for all $s$.

By (4.13), $w^{(1)}=0$. On the other hand, setting $s=0$ in (4.18), we see

$$
w^{(1)}=\left[\sum_{l=0}^{\left[\frac{m-1}{2}\right]} b(m, 0, l) i^{l} j^{l}\right] z^{(1)}=0 .
$$

Since the operator in the brackets is nondegenerate, $z^{(1)}=0$. Together with (4.14) and (4.18), this gives $z^{(2 s+1)}=0$ and $w^{(2 s+1)}=0$ for all $s$.

We have proved $z^{(s)}=0$ and $w^{(s)}=0$ for all $s$. Recalling definition (4.11), we see

$$
\left.\frac{\partial^{k+1} u_{i_{1} \ldots i_{m}}}{\partial y^{k+1}}\right|_{y=0}=0,\left.\quad \frac{\partial^{k} v_{i_{1} \ldots i_{m}}}{\partial y^{k}}\right|_{y=0}=0,
$$

and this is the finish of the inductive step.

## 5. Proof of Theorem 1.5

We start with the following observation: the tensor fields $\lambda$ and $\tilde{f}$ can be eliminated from the system (1.5)-(1.7). Indeed, let $f, \tilde{f} \in H^{k}\left(S^{m} \tau^{\prime}\right), v \in H^{k+1}\left(S^{m-1} \tau^{\prime}\right)$, and $\lambda \in$ $H^{k}\left(S^{m-2} \tau^{\prime}\right)$ satisfy (1.5)-(1.7). Applying the operator $j$ to (1.5), we get

$$
j f=j d v+j i \lambda .
$$

Express $\lambda$ from this

$$
\begin{equation*}
\lambda=(j i)^{-1} j(f-d v), \tag{5.1}
\end{equation*}
$$

and substitute the result into (1.5)

$$
f=d v+i(j i)^{-1} j(f-d v)+\tilde{f}
$$

Due to (2.15), this equality can be written in the form

$$
f=d v+q(f-d v)+\tilde{f}
$$

or

$$
(E-q) f=(E-q) d v+\tilde{f},
$$

where $E$ is the identity operator. Since $E-q=p$,

$$
\begin{equation*}
p f=p d v+\tilde{f} \tag{5.2}
\end{equation*}
$$

To eliminate $\tilde{f}$, we apply the operator $\delta$ to equation (5.2). Taking $\delta \tilde{f}=0$ into account, we obtain

$$
\delta p f=\delta p d v
$$

Hence, $v$ is a solution to the boundary value problem

$$
\begin{equation*}
(\delta p d) v=h,\left.\quad v\right|_{\partial M}=0 \tag{5.3}
\end{equation*}
$$

with

$$
\begin{equation*}
h=\delta p f \in H^{k-1}\left(S^{m-1} \tau^{\prime}\right) . \tag{5.4}
\end{equation*}
$$

Recall that the subbundle Ker $j$ of the vector bundle $S^{*} \tau^{\prime}$ was defined in Section 2. The right-hand side $h$ of equation (5.3) belongs to $H^{k-1}(\operatorname{Ker} j)$ by (5.4) and (3.1). The desired solution $v$ to problem (5.3) must be a section of $\operatorname{Ker} j$ since the requirement $j v=0$ is contained in (1.6). Finally, $\delta p d$ can be considered as a differential operator on the vector bundle $\operatorname{Ker} j$, i.e.,

$$
\delta p d: C^{\infty}(\operatorname{Ker} j) \rightarrow C^{\infty}(\operatorname{Ker} j)
$$

since $q(\delta p d)=(q \delta p) d=0$ in view of (3.4). So, (5.3) can be considered as a boundary value problem on the bundle $\operatorname{Ker} j$. We shall prove this is an elliptic problem with zero kernel and co-kernel. Then, applying the theorem on regular solvability of elliptic problems, we shall deduce that, for every $h \in H^{k}(\operatorname{Ker} j)(k \geq 0)$, problem (5.3) has a unique solution $v \in H^{k+2}(\operatorname{Ker} j)$ satisfying the stability estimate

$$
\|v\|_{H^{k+2}} \leq C\|h\|_{H^{k}} .
$$

Setting $h=\delta p f$ and defining $\lambda$ and $\tilde{f}$ by formulas (5.1) and (5.2), we get (1.5)-(1.8). Theorem 1.5 is thus reduced to the following proposition:

Theorem 5.1. Let $M$ be a compact connected Riemannian manifold with nonempty boundary. Being considered on the vector bundle Ker j, the boundary value problem (5.3) is elliptic and has zero kernel and co-kernel.

Proof. We start with checking ellipticity of the operator $\delta p d$ on Ker $j$. The principal symbols $\sigma_{1}(d)$ and $\sigma_{1}(\delta)$ of the operators $d$ and $\delta$ at a point $(x, \xi) \in T^{\prime}$ are

$$
\sigma_{1}(d)=\sqrt{-1} i_{\xi} \quad \sigma_{1}(\delta)=\sqrt{-1} j_{\xi} ;
$$

here $\sqrt{-1}$ is the imaginary unit. Hence,

$$
\sigma_{2}(\delta p d)=-j_{\xi} p i_{\xi} .
$$

For $x \in M$, let $\operatorname{Ker}_{x}^{m} j=\left\{f \in S^{m} T_{x}^{\prime} \mid j f=0\right\}$. We have to prove the operator

$$
\begin{equation*}
j_{\xi} p i_{\xi}: \operatorname{Ker}_{x}^{m} j \rightarrow \operatorname{Ker}_{x}^{m} j \tag{5.5}
\end{equation*}
$$

is an isomorphism for every $m \geq 0$ and every $0 \neq \xi \in T_{x}^{\prime}$.
The operator $j_{\xi} p i_{\xi}$ is easily seen to be nonnegative. Indeed,

$$
\left\langle j_{\xi} p i_{\xi} f, f\right\rangle=\left\langle p i_{\xi} f, i_{\xi} f\right\rangle=\left\langle p i_{\xi} f, p i_{\xi} f\right\rangle=\left|p i_{\xi} f\right|^{2} .
$$

Therefore verification of the ellipticity of $\delta p d$ reduces to the following proposition.
Lemma 5.2. If a tensor $f \in S^{m} T_{x}^{\prime}$ satisfies the conditions

$$
j f=0, \quad p i_{\xi} f=0
$$

for some $0 \neq \xi \in T_{x}^{\prime}$ then $f=0$.
To prove Lemma 5.2, we need the following:
Lemma 5.3. The commutation formula

$$
p i_{\xi}=i_{\xi} p-\frac{2}{m+1} i(j i)^{-1} j_{\xi} p
$$

holds on $S^{m} \tau^{\prime}$.
Proof. The commutation formula

$$
\begin{equation*}
j i_{\xi}=\frac{2}{m+1} j_{\xi}+\frac{m-1}{m+1} i_{\xi} j \quad \text { on } \quad S^{m} \tau^{\prime} \tag{5.6}
\end{equation*}
$$

is checked by direct calculations in coordinates, and we omit them. Using (2.15) and (5.6), we obtain

$$
q i_{\xi}=i(j i)^{-1} j i_{\xi}=i(j i)^{-1}\left(j i_{\xi}\right)=i(j i)^{-1}\left(\frac{2}{m+1} j_{\xi}+\frac{m-1}{m+1} i_{\xi} j\right) .
$$

Hence,

$$
\begin{equation*}
q i_{\xi}=i(j i)^{-1}\left(\frac{2}{m+1} j_{\xi}+\frac{m-1}{m+1} i_{\xi} j\right) \quad \text { on } \quad S^{m} \tau^{\prime} \tag{5.7}
\end{equation*}
$$

Using (5.6) again, we get

$$
j i i_{\xi}=\left(j i_{\xi}\right) i=\left(\frac{2}{m+3} j_{\xi}+\frac{m+1}{m+3} i_{\xi} j\right) i=\frac{2}{m+3} j_{\xi} i+\frac{m+1}{m+3} i_{\xi}(j i) .
$$

Multiplying the extreme parts of this formula by $(j i)^{-1}$ from the left and from the right, we obtain

$$
i_{\xi}(j i)^{-1}=\frac{2}{m+3}(j i)^{-1} j_{\xi} i(j i)^{-1}+\frac{m+1}{m+3}(j i)^{-1} i_{\xi} .
$$

Hence,

$$
\begin{equation*}
(j i)^{-1} i_{\xi}=\frac{m+3}{m+1} i_{\xi}(j i)^{-1}-\frac{2}{m+1}(j i)^{-1} j_{\xi} i(j i)^{-1} \quad \text { on } \quad S^{m} \tau^{\prime} . \tag{5.8}
\end{equation*}
$$

We transform the second summand on the right-hand side of (5.7) with the htlp of (5.8). The summand equals zero in the case of $m=0$ and of $m=1$ due to the factor $j$ on its
right. Therefore we assume $m \geq 2$. Since the operator $j$ acts before $(j i)^{-1} i_{\xi}$, the value $m$ in (5.8) should be changed to $m-2$. Thus, the result of the transformation is as follows:

$$
q i_{\xi}=\frac{2}{m+1} i(j i)^{-1} j_{\xi}+\frac{m-1}{m+1} i\left(\frac{m+1}{m-1} i_{\xi}(j i)^{-1}-\frac{2}{m-1}(j i)^{-1} j_{\xi} i(j i)^{-1}\right) j
$$

We arrange this formula as

$$
q i_{\xi}=i_{\xi} i(j i)^{-1} j+\frac{2}{m+1} i(j i)^{-1} j_{\xi}\left(E-i(j i)^{-1} j\right)
$$

and use (2.15) again to obtain

$$
\begin{equation*}
q i_{\xi}=i_{\xi} q+\frac{2}{m+1} i(j i)^{-1} j_{\xi} p \quad \text { on } \quad S^{m} \tau^{\prime} \tag{5.9}
\end{equation*}
$$

We have thus proved (5.9) in the case of $m \geq 2$. Actually, (5.9) is valid for any $m \geq 0$. Indeed, both sides of this formula are equal to zero in the case of $m=0$. In the case of $m=1$, (5.9) has the form

$$
q i_{\xi}=\frac{1}{n} i j_{\xi} \quad \text { on } \quad \tau^{\prime}
$$

and can be easily checked.
Substituting $q=E-p$ into (5.9), we complete the proof of Lemma 5.3.

Proof of Lemma 5.2. The statement of the lemma is trivial for $m=0$ since $p i_{\xi} f=i_{\xi} f$ in the latter case and $i_{\xi}$ is a monomorphism for $\xi \neq 0$. So we assume $m \geq 1$.

Let $f \in S^{m} T_{x}^{\prime}$ satisfy the equalities $j f=0$ and $p i_{\xi} f=0$. By Lemma 5.3, the second equality implies

$$
0=p i_{\xi} f=i_{\xi} p f-\frac{2}{m+1} i(j i)^{-1} j_{\xi} p f
$$

Since $p f=f$, this equality is simplified to the following one:

$$
i_{\xi} f-\frac{2}{m+1} i(j i)^{-1} j_{\xi} f=0
$$

Taking the scalar product of this with $i_{\xi} f$, we get

$$
\left\langle i_{\xi} f, i_{\xi} f\right\rangle-\frac{2}{m+1}\left\langle i(j i)^{-1} j_{\xi} f, i_{\xi} f\right\rangle=0
$$

or

$$
\begin{equation*}
\left\langle j_{\xi} i_{\xi} f, f\right\rangle-\frac{2}{m+1}\left\langle(j i)^{-1} j_{\xi} f, j i_{\xi} f\right\rangle=0 \tag{5.10}
\end{equation*}
$$

The operators $i_{\xi}$ and $j_{\xi}$ satisfy the commutation formula

$$
\begin{equation*}
j_{\xi} i_{\xi} f=\frac{|\xi|^{2}}{m+1} f+\frac{m}{m+1} i_{\xi} j_{\xi} f \quad \text { for } \quad f \in S^{m} \tau^{\prime} \tag{5.11}
\end{equation*}
$$

(see [15, Lemma 3.3.3]).
Since $j f=0$, formula (5.6) implies

$$
\begin{equation*}
j i_{\xi} f=\frac{2}{m+1} j_{\xi} f \tag{5.12}
\end{equation*}
$$

Using (2.11) and taking $j f=0$ into account, we deduce

$$
(j i)\left(j_{\xi} f\right)=\frac{2(n+2 m-2)}{m(m+1)} j_{\xi} f .
$$

Applying the operator $(j i)^{-1}$ to this equation, we infer

$$
\begin{equation*}
(j i)^{-1}\left(j_{\xi} f\right)=\frac{m(m+1)}{2(n+2 m-2)} j_{\xi} f . \tag{5.13}
\end{equation*}
$$

Substitute (5.11)-(5.13) into (5.10) to obtain

$$
|\xi|^{2}|f|^{2}+m\left(1-\frac{2}{n+2 m-2)}\right)\left|j_{\xi} f\right|^{2}=0 .
$$

Both coefficients of the equality are positive in the case of $n \geq 2, m \geq 1$, and $\xi \neq 0$. Hence, $f=0$.

We have thus proved the ellipticity of the principal symbol $j_{\xi} p i_{\xi}$ of the operator $-\delta p d$ on the bundle $\operatorname{Ker} j$. Actually, we have shown the principal symbol is positive. This implies the ellipticity of the boundary value problem (5.3). Indeed, as is known [19, Chapter 5, Proposition 11.10], the positivity of the principal symbol implies the Lopatinskiĭ condition for the Dirichlet problem.

Next, we are going to prove the triviality of the kernel of the boundary value problem (5.3). Let $v \in H^{k}(\operatorname{Ker} j)(k \geq 2)$ be a solution to the homogeneous problem

$$
\begin{equation*}
(\delta p d) v=0,\left.\quad v\right|_{\partial M}=0 \tag{5.14}
\end{equation*}
$$

Due to the ellipticity, $v$ is smooth: $v \in C^{\infty}(\operatorname{Ker} j)$. Applying Green's formula from Theorem 3.1, we have

$$
(p d v, p d v)_{L^{2}}=(p d v, d v)_{L^{2}}=-(\delta p d v, v)_{L^{2}}=0
$$

i.e., $p d v=0$. Hence, $v$ is a trace-free conformal Killing field. According to Theorem 1.3, if such a field satisfies the homogeneous boundary condition $\left.v\right|_{\partial M}=0$ then it is identically zero.

Let $\left.S^{m} \tau^{\prime}\right|_{\partial M}$ denote the restriction of the bundle $S^{m} \tau^{\prime}$ to the boundary. To prove the triviality of the co-kernel of the boundary value problem (5.3), we need the following proposition.

Lemma 5.4. If a tensor field $u \in C^{\infty}\left(\left.S^{m} \tau^{\prime}\right|_{\partial M}\right)$ satisfies the condition $j u=0$ then there exists $v \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$ satisfying the conditions $\left.v\right|_{\partial M}=0, j v=0$ and such that

$$
\begin{equation*}
\left.j_{\nu} p d v\right|_{\partial M}=u, \tag{5.15}
\end{equation*}
$$

where $\nu$ is the outward normal vector to the boundary.
The proof of Lemma 5.4 will be given below. We now finish the proof of Theorem 5.1 with the help of the lemma.

Assume a field $w \in C^{\infty}(\operatorname{Ker} j)$ to be orthogonal to the range of the operator of the boundary value problem (5.3), i.e.,

$$
\begin{equation*}
(w, \delta p d v)_{L^{2}}=0 \tag{5.16}
\end{equation*}
$$

for every $v \in C^{\infty}(\operatorname{Ker} j)$ satisfying the boundary condition $\left.v\right|_{\partial M}=0$. We have to show $w \equiv 0$. We first choose $v$ such that $\operatorname{supp} v \subset M \backslash \partial M$. Green's formula and (5.16) imply

$$
(\delta p d w, v)_{L^{2}}=(w, \delta p d v)_{L^{2}}=0
$$

Since $v \in C_{0}^{\infty}(\operatorname{Ker} j)$ is arbitrary, this means

$$
\begin{equation*}
\delta p d w=0 \tag{5.17}
\end{equation*}
$$

For an arbitrary $u \in C^{\infty}\left(\left.\operatorname{Ker} j\right|_{\partial M}\right)$, Lemma 5.4 guaranties the existence of some $v \in C^{\infty}(\operatorname{Ker} j)$ which satisfies (5.15) and vanishes on the boundary. With the help of Green's formula, (5.15)-(5.17) yield

$$
0=(w, \delta p d v)_{L^{2}}=(\delta p d w, v)_{L^{2}}+\int_{\partial M}\left\langle w, j_{\nu} p d v\right\rangle d V^{\prime}=\int_{\partial M}\langle w, u\rangle d V^{\prime}
$$

This means $\left.w\right|_{\partial M}=0$ since $u$ is arbitrary. So, $w$ belongs to the kernel of the boundary problem operator. As was already proved, such $w$ must be identically equal to zero. Theorem 5.1 is proved.

Proof of Lemma 5.4. In order to simplify the notation, we give here the proof only in the case of an odd $m$. The case of an even $m$ is considered in a similar way. Both the cases can be considered simultaneously but with much more complicated notation.
In virtue of the condition $\left.v\right|_{\partial M}=0,(5.15)$ can be considered as an algebraic equation in the unknown $\partial v /\left.\partial \nu\right|_{\partial M}$. We are going to prove the existence and uniqueness of a solution to the equation under the condition $j u=0$. Moreover, the solution satisfies $j \partial v /\left.\partial \nu\right|_{\partial M}=0$ as will be shown. Then the proof of the existence is realized by choosing a section $v$ of the vector bundle Ker $j$ with prescribed boundary values $\left.v\right|_{\partial M}=0$ and $\partial v /\left.\partial \nu\right|_{\partial M}$.

We choose normal boundary coordinates $\left(x^{1}, \ldots, x^{n}\right)=\left(x^{1}, \ldots, x^{n-1}, y\right)$ in a neighborhood of a boundary point so that $g_{i n}=\delta_{\text {in }}$ and the boundary is defined by the equation $y=0$. Below the Greek indices change from 1 to $n-1$. We define the tensor fields $u^{(s)}, v^{(s)} \in C^{\infty}\left(S^{s} \tau_{\partial M}^{\prime}\right)$ for $0 \leq s \leq 2 m+1$ by the formulas

$$
\begin{equation*}
v_{\alpha_{1} \ldots \alpha_{s}}^{(s)}=\left.\frac{\partial v_{\alpha_{1} \ldots \alpha_{s} n \ldots n}}{\partial y}\right|_{y=0}, \quad u_{\alpha_{1} \ldots \alpha_{s}}^{(s)}=2(m+1)(n+4 m) u_{\alpha_{1} \ldots \alpha_{s} n \ldots n} . \tag{5.18}
\end{equation*}
$$

The condition $j u=0$ is expressed in terms of $u^{(s)}$ as follows:

$$
u^{(s)}+j u^{(s+2)}=0
$$

From this,

$$
\begin{equation*}
u^{(2 s)}=(-j)^{m-s} u^{(2 m)}, \quad u^{(2 s+1)}=(-j)^{m-s} u^{(2 m+1)} . \tag{5.19}
\end{equation*}
$$

Using (3.8), we transform (5.15) to the form

$$
\left.j_{\nu}\left(d p v-\frac{2 m+1}{n+4 m} i \delta p v\right)\right|_{\partial M}=u
$$

If $j v=0$ then $p v=v$ and the equation simplifies to the following one:

$$
\begin{equation*}
\left.j_{\nu}\left(d v-\frac{2 m+1}{n+4 m} i \delta v\right)\right|_{\partial M}=u \tag{5.20}
\end{equation*}
$$

We are going to derive some recurrent formulas from (5.20) which uniquely determine the tensors $v^{(s)}$.

In the normal boundary coordinates, the vector $\nu$ has the coordinates $(0, \ldots, 0,1)$ and equation (5.20) takes the form

$$
\begin{equation*}
\left.(d v)_{n i_{1} \ldots i_{2 m+1}}\right|_{y=0}-\left.\frac{2 m+1}{n+4 m}(i \delta v)_{n i_{1} \ldots i_{2 m+1}}\right|_{y=0}=u_{i_{1} \ldots i_{2 m+1}} . \tag{5.21}
\end{equation*}
$$

Set $\left(i_{1}, \ldots, i_{s}\right)=\left(\alpha_{1}, \ldots, \alpha_{s}\right)$ and $i_{s+1}=\cdots=i_{2 m+2}=n$ in the equality

$$
(d v)_{i_{1} \ldots i_{2 m+2}}=\frac{1}{2 m+2}\left(\frac{\partial v_{i_{2} \ldots i_{2 m+2}}}{\partial x^{i_{1}}}+\frac{\partial v_{i_{1} i_{3} \ldots i_{2 m+2}}}{\partial x^{i_{2}}}+\cdots+\frac{\partial v_{i_{1} \ldots i_{2 m+2}}}{\partial x^{i_{2 m+1}}}\right) .
$$

The first $s$ summands on the right-hand side vanish on $\partial M$ since $\left.v\right|_{\partial M}=0$. The last $2 m-$ $s+2$ summands are pairwise equal. Hence,

$$
\begin{equation*}
\left.(d v)_{\alpha_{1} \ldots \alpha_{s} n \ldots n}\right|_{y=0}=\frac{2 m-s+2}{2(m+1)} v_{\alpha_{1} \ldots \alpha_{s}}^{(s)} . \tag{5.22}
\end{equation*}
$$

Similarly, we deduce

$$
\begin{equation*}
\left.(\delta v)_{\alpha_{1} \ldots \alpha_{s} n \ldots n}\right|_{y=0}=v_{\alpha_{1} \ldots \alpha_{s}}^{(s)} . \tag{5.23}
\end{equation*}
$$

Setting $\left(i_{1}, \ldots, i_{s}\right)=\left(\alpha_{1}, \ldots, \alpha_{s}\right)$ and $i_{s+1}=\cdots=i_{2 m+2}=n$ in the equality

$$
(i \delta v)_{i_{1} \ldots i_{2 m+2}}=\frac{1}{(2 m+2)!} \sum_{\pi \in \Pi_{2 m+2}} g_{i_{\pi(1)} i_{\pi(2)}}(\delta v)_{i_{\pi(3)} \ldots i_{\pi(2 m+2)}}
$$

and analyzing the right-hand side in the same way as has been used for deriving (4.9), we obtain

$$
\begin{aligned}
\left.(i \delta v)_{\alpha_{1} \ldots \alpha_{s} n \ldots n}\right|_{y=0}= & \left.\frac{(2 m-s+1)(2 m-s+2)}{(2 m+1)(2 m+2)}(\delta v)_{\alpha_{1} \ldots \alpha_{s} n \ldots n}\right|_{y=0} \\
& +\frac{s(s-1)}{(2 m+1)(2 m+2)} \sigma\left(\alpha_{1} \ldots \alpha_{s}\right)\left(\left.g_{\alpha_{1} \alpha_{2}}(\delta v)_{\alpha_{3} \ldots \alpha_{s} \ldots \ldots n}\right|_{y=0}\right) .
\end{aligned}
$$

With the help of (5.23), this gives

$$
\begin{align*}
\left.(i \delta v)_{\alpha_{1} \ldots \alpha_{s} n \ldots n}\right|_{y=0}= & \frac{(2 m-s+1)(2 m-s+2)}{(2 m+1)(2 m+2)} v_{\alpha_{1} \ldots \alpha_{s}}^{(s)} \\
& +\frac{s(s-1)}{(2 m+1)(2 m+2)}\left(i v^{(s-2)}\right)_{\alpha_{1} \ldots \alpha_{s}} . \tag{5.24}
\end{align*}
$$

We set $\left(i_{1}, \ldots, i_{s}\right)=\left(\alpha_{1}, \ldots, \alpha_{s}\right)$ and $i_{s+1}=\cdots=i_{2 m+2}=n$ in (5.21). Then we substitute values (5.22) and (5.24) for the summands on the left-hand side of (5.21) and value (5.18) for the right-hand side of (5.21). In such the way we obtain the recurrent formula

$$
(2 m-s+2)(n+2 m+s-1) v^{(s)}-s(s-1) i v^{(s-2)}=u^{(s)} .
$$

In view of (5.19), this formula can be rewritten as

$$
\begin{align*}
& 2(m-s+1)(n+2 m+2 s-1) v^{(2 s)}-2 s(2 s-1) i v^{(2 s-2)}=(-j)^{m-s} u^{(2 m)}  \tag{5.25}\\
& (2 m-2 s+1)(n+2 m+2 s) v^{(2 s+1)}-2 s(2 s+1) i v^{(2 s-1)}=(-j)^{m-s} u^{(2 m+1)} . \tag{5.26}
\end{align*}
$$

Formulas (5.25) and (5.26) imply the following representations:

$$
\begin{align*}
v^{(2 s)} & =\sum_{k=0}^{s} a(s, k) i^{k} j^{m-s+k} u^{(2 m)},  \tag{5.27}\\
v^{(2 s+1)} & =\sum_{k=0}^{s} b(s, k) i^{k} j^{m-s+k} u^{(2 m+1)}, \tag{5.28}
\end{align*}
$$

with some coefficients $a(s, k)$ and $b(s, k)$ which depend on $n, m, s$, and $k$ only. The dependence on $n$ and $m$ is not indicated explicitly since the values of these two parameters are fixed in the proof.

Substitution of (5.27) and (5.28) into (5.25) and (5.26), respectively, imply the following recurrent relations:

$$
\begin{align*}
a(s, 0) & =\frac{(-1)^{m-s}}{2(m-s+1)(n+2 m+2 s-1)} \\
a(s, k) & =\frac{(2 s-1)}{(m-s+1)(n+2 m+2 s-1)} a(s-1, k-1) \text { for } 1 \leq k \leq s  \tag{5.29}\\
b(s, 0) & =\frac{(-1)^{m-s}}{(2 m-2 s+1)(n+2 m+2 s)} \\
b(s, k) & =\frac{2 s(2 s+1)}{(2 m-2 s+1)(n+2 m+2 s)} b(s-1, k-1) \text { for } 1 \leq k \leq s \tag{5.30}
\end{align*}
$$

The coefficients $a(s, k)$ and $b(s, k)$ are uniquely determined by equations (5.29) and (5.30), and formulas (5.27) and (5.28) show that the tensors $v^{(2 s)}$ and $v^{(2 s+1)}$ are uniquely determined by $u^{(2 m)}$ and $u^{(2 m+1)}$.

Finally, we have to prove the tensors $v^{(2 s)}$ and $v^{(2 s+1)}$ satisfy the equations

$$
\begin{align*}
v^{(2 s)}+j v^{(2 s+2)} & =0 \text { for } 0 \leq s \leq m-1,  \tag{5.31}\\
v^{(2 s+1)}+j v^{(2 s+3)} & =0 \text { for } 0 \leq s \leq m-1 \tag{5.32}
\end{align*}
$$

that are equivalent to the relation $\left.j \frac{\partial v}{\partial \nu}\right|_{\partial M}=0$ in view of the first formula in (5.18).
Applying the operator $j$ to equation (5.27), we obtain

$$
\begin{equation*}
j v^{(2 s+2)}=\sum_{k=0}^{s+1} a(s+1, k) j i^{k} j^{m-s+k-1} u^{(2 m)} . \tag{5.33}
\end{equation*}
$$

We transpose the factors $j$ and $i^{k}$ on the right-hand side of (5.33) with the help of Lemma 2.2. We have to set $n:=n-1$ and $m:=2 s-2 k+2$ in the statement of the ltmma since $j^{m-s+k-1} u^{(2 m)}$ is the tensor of rank $2 s-2 k+2$ on the $(n-1)$-dimensional manifold $\partial M$. So we have

$$
\begin{aligned}
j v^{(2 s+2)}= & \sum_{k=0}^{s+1} a(s+1, k)\left(\frac{k(n+4 s-2 k+1)}{(s+1)(2 s+1)} i^{k-1} j^{m-s+k-1}\right. \\
& \left.\quad+\frac{(s-k+1)(2 s-2 k+1)}{(s+1)(2 s+1)} i^{k} j^{m-s+k}\right) u^{(2 m)}
\end{aligned}
$$

This equality can be transformed as follows:

$$
\begin{align*}
j v^{(2 s+2)}=\sum_{k=0}^{s}( & \frac{(s-k+1)(2 s-2 k+1)}{(s+1)(2 s+1)} a(s+1, k) \\
& \left.+\frac{(k+1)(n+4 s-2 k-1)}{(s+1)(2 s+1)} a(s+1, k+1)\right) i^{k} j^{m-s+k} u^{(2 m)} \tag{5.34}
\end{align*}
$$

Substitution of (5.27) and (5.34) into (5.31) gives

$$
\begin{aligned}
\sum_{k=0}^{s}[a(s, k) & +\frac{(s-k+1)(2 s-2 k+1)}{(s+1)(2 s+1)} a(s+1, k) \\
& \left.+\frac{(k+1)(n+4 s-2 k-1)}{(s+1)(2 s+1)} a(s+1, k+1)\right] i^{k} j^{m-s+k} u^{(2 m)}=0
\end{aligned}
$$

Since $u^{(2 m)}$ is an arbitrary tensor, the expression in the brackets must be equal to zero for all $s$ and $k$, i.e.,

$$
\begin{align*}
a(s, k) & +\frac{(s-k+1)(2 s-2 k+1)}{(s+1)(2 s+1)} a(s+1, k) \\
& +\frac{(k+1)(n+4 s-2 k-1)}{(s+1)(2 s+1)} a(s+1, k+1)=0 \text { for } 0 \leq k \leq s \leq m-1 \tag{5.35}
\end{align*}
$$

Similarly, (5.32) is equivalent to the equation

$$
\begin{align*}
b(s, k) & +\frac{(s-k+1)(2 s-2 k+3)}{(s+1)(2 s+3)} b(s+1, k) \\
& +\frac{(k+1)(n+4 s-2 k+1)}{(s+1)(2 s+1)} b(s+1, k+1)=0 \text { for } 0 \leq k \leq s \leq m-1 . \tag{5.36}
\end{align*}
$$

We have to prove the following statement: Being defined by recurrent formulas (5.29) and (5.30), the coefficients $a(s, k)$ and $b(s, k)$ satisfy equations (5.35) and (5.36), respectively. This can be proved with the help of the following explicit formulas for the coefficients:

$$
\begin{align*}
a(s, k)=\frac{(-1)^{m-s-k}}{2} & \frac{s!(2 s-1)!!(m-s)!}{(n+2 m+2 s-1)!!} \\
& \times \frac{(n+2 m+2 s-2 k-3)!!}{(s-k)!(m-s+k+1)!(2 s-2 k-1)!!},  \tag{5.37}\\
b(s, k)=(-1)^{m-s-k} & \frac{s!(2 s+1)!!(2 m-2 s-1)!!}{(n+2 m+2 s)!!} \\
& \times \frac{2^{k}(n+2 m+2 s-2 k-2)!!}{(s-k)!(2 m-2 s+2 k+1)!!(2 s-2 k+1)!!} . \tag{5.38}
\end{align*}
$$

Here we use the standard notation:

$$
(2 k)!!=2^{k} k!, \quad(2 k+1)!!=(2 k+1)(2 k-1) \ldots 1, \quad(-1)!!=1 .
$$

Formulas (5.37) and (5.38) are proved by substituting them into recurrent formulas (5.29) and (5.30) and checking the validity of the resulting equations. Then the validity of (5.35) and (5.36) is proved by substitution of values (5.37) and (5.38) followed by a direct calculation.

## 6. Proof of Theorems 1.6 and 1.7

In this section, for a Riemannian manifold, we use the notions of a semibasic tensor field and the vertical and horizontal derivatives of such a field. The corresponding definitions are presented in [15, Ch.3] (see also [4, §4] where the case of a Finsler manifold is considered as well). We denote the space of smooth semibasic $(r, s)$-tensor fields on TM by $C^{\infty}\left(\beta_{s}^{r} M\right)$, and $\stackrel{v}{\nabla}, \stackrel{h}{\nabla}: C^{\infty}\left(\beta_{s}^{r} M\right) \rightarrow C^{\infty}\left(\beta_{s+1}^{r} M\right)$ denote the vertical and horizontal derivatives, respectively.

Proof of Theorem 1.6. Let $u \in C^{\infty}\left(S^{m} \tau_{M}^{\prime}\right)$ be a trace-free conformal Killing tensor field, i.e., $j u=0$ and $d u=i v$ for some $v \in C^{\infty}\left(S^{m-1} \tau_{M}^{\prime}\right)$. We assume here $m \geq 1$ since the statement of the theorem is trivial in the case of $m=0$. Define the function $U \in$ $C^{\infty}(T M)=C^{\infty}\left(\beta_{0}^{0} M\right)$ as follows:

$$
\begin{equation*}
U(x, \xi)=u_{i_{1} \ldots i_{m}}(x) \xi^{i_{1}} \cdots \xi^{i_{m}} . \tag{6.1}
\end{equation*}
$$

The function is homogeneous with respect to $\xi$,

$$
\begin{equation*}
U(x, t \xi)=t^{m} U(x, \xi), \tag{6.2}
\end{equation*}
$$

and satisfies the kinetic equation

$$
\begin{equation*}
H U(x, \xi)=|\xi|^{2} v_{i_{1} \ldots i_{m-1}}(x) \xi^{i_{1}} \cdots \xi^{i_{m-1}} \tag{6.3}
\end{equation*}
$$

where $H$ denotes differentiation along the geodesic flow, and $H U(x, \xi)=\xi^{i} \stackrel{h}{\nabla_{i}} U$. Since $j u=0$, the function $U$ satisfies the equation

$$
\begin{equation*}
\stackrel{v}{\Delta} U=0, \tag{6.4}
\end{equation*}
$$

where $\stackrel{v}{\Delta}=\stackrel{v}{\nabla}^{i} \nabla_{i}^{v}$ is the vertical Laplacian (see Lemma 2.4).
Let us derive the commutation formula for $\Delta$ and $H$. Since the vertical and horizontal derivatives commute,

$$
\stackrel{v}{\Delta} H U=\stackrel{v}{\nabla}^{i} \stackrel{v}{\nabla}_{i}\left(\xi^{j} \stackrel{h}{\nabla}_{j} U\right)=\stackrel{v}{\nabla}{ }^{i}\left(\stackrel{h}{\nabla}_{i} U+\xi^{j} \stackrel{h}{\nabla}_{j} \stackrel{v}{\nabla}_{i} U\right)=2 \stackrel{v}{\nabla}^{i} \stackrel{h}{\nabla}_{i} U+H \stackrel{v}{\Delta} U .
$$

By (6.4), this gives

$$
\begin{equation*}
\stackrel{v}{\Delta} H U=2 \stackrel{v}{\nabla}^{i} \stackrel{h}{\nabla_{i}} U . \tag{6.5}
\end{equation*}
$$

We write the Pestov identity for the function $U$ (see [15])

$$
\begin{equation*}
2\langle\stackrel{h}{\nabla} U, \stackrel{v}{\nabla} H U\rangle-\stackrel{v}{\nabla} i\left(\stackrel{h}{\nabla}^{i} U \cdot H U\right)=|\stackrel{h}{\nabla} U|^{2}+\stackrel{h}{\nabla}{ }_{i} w^{i}-R_{\xi}(\stackrel{v}{\nabla} U), \tag{6.6}
\end{equation*}
$$

where

$$
\begin{equation*}
R_{\xi}(\stackrel{v}{\nabla} U)=R_{i j k l} \xi^{i} \xi^{k} \nabla^{j} U \cdot \stackrel{v}{\nabla}^{l} U \tag{6.7}
\end{equation*}
$$

and $w$ is some semibasic vector field on $T M$. It depends on $U$ quadratically but its value is not relevant now. Since the sectional curvature is nonpositive, we have

$$
\begin{equation*}
R_{\xi}(\stackrel{v}{\nabla} U) \leq 0 \tag{6.8}
\end{equation*}
$$

We transform the first summand on the left-hand side of equation (6.6) with the help of (6.5) as follows:

$$
\begin{aligned}
2\langle\stackrel{h}{\nabla} U, \stackrel{v}{\nabla} H U\rangle & =2 \stackrel{h}{\nabla}^{i} U \cdot \stackrel{v}{\nabla}_{i}(H U) \\
& =\stackrel{v}{\nabla}_{i}\left(2 \stackrel{h}{\nabla}^{i} U \cdot H U\right)-2 \stackrel{v}{\nabla}^{i} \stackrel{h}{\nabla}_{i} U \cdot H U \\
& =-\stackrel{v}{\Delta} H U \cdot H U+\stackrel{v}{\nabla}_{i}\left(2 \stackrel{ }{ }^{i} U \cdot H U\right) \\
& =-\stackrel{v}{\nabla}_{i} \stackrel{v}{\nabla}^{i} H U \cdot H U+\stackrel{v}{\nabla}_{i}\left(2 \stackrel{h}{\nabla}^{i} U \cdot H U\right) \\
& =-\stackrel{v}{\nabla}_{i}\left(\nabla^{i} H U \cdot H U\right)+\stackrel{v}{\nabla}^{i} H U \cdot \stackrel{v}{\nabla}_{i} H U+\stackrel{v}{\nabla}_{i}\left(2 \stackrel{\rightharpoonup}{\nabla}^{i} U \cdot H U\right) \\
& =|\stackrel{v}{\nabla} H U|^{2}+\stackrel{v}{\nabla}_{i}\left(2 \stackrel{h}{\nabla}^{i} U \cdot H U-\nabla^{i} H U \cdot H U\right)
\end{aligned}
$$

Substitute this value into (6.6)

$$
|\stackrel{v}{\nabla} H U|^{2}+\stackrel{v}{\nabla}_{i}\left(\stackrel{h}{\nabla}^{i} U \cdot H U-\stackrel{v}{\nabla} i H U \cdot H U\right)=|\stackrel{h}{\nabla} U|^{2}+\stackrel{h}{\nabla}{ }_{i} w^{i}-R_{\xi}(\stackrel{v}{\nabla} U) .
$$

We integrate this equality over $\Omega M$ versus to the Liouville volume form $d \Sigma$ and transform the integrals of divergent terms by the Gauss-Ostrogradsky formulas (see [15, Theorem 3.6.3])

$$
\begin{equation*}
\int_{\Omega M}\left(|\stackrel{v}{\nabla} H U|^{2}+(n+2 m)\langle\xi, \stackrel{h}{\nabla} U-\stackrel{v}{\nabla} H U\rangle H U\right) d \Sigma=\int_{\Omega M}\left(|\stackrel{h}{\nabla} U|^{2}-R_{\xi}\left(\nabla^{v} U\right)\right) d \Sigma \tag{6.9}
\end{equation*}
$$

The coefficient $(n+2 m)$ appears here because the semibasic vector field $(\stackrel{h}{\nabla} U-\stackrel{v}{\nabla} H U) H U$ is homogeneous of degree $2 m+1$ in $\xi$. With the help of the Euler formula for homogeneous functions

$$
\begin{equation*}
\langle\xi, \stackrel{v}{\nabla} H U\rangle=(m+1) H U \tag{6.10}
\end{equation*}
$$

and of $\langle\xi, \stackrel{h}{\nabla} U\rangle=H U$, formula (6.9) takes the form

$$
\begin{equation*}
\int_{\Omega M}\left(|\stackrel{v}{\nabla} H U|^{2}-m(n+2 m)|H U|^{2}\right) d \Sigma=\int_{\Omega M}\left(|\stackrel{h}{\nabla} U|^{2}-R_{\xi}(\stackrel{v}{\nabla} U)\right) d \Sigma \tag{6.11}
\end{equation*}
$$

Now, we estimate the left-hand side of (6.11) as follows. At an arbitrary point $(x, \xi) \in$ $\Omega M$, we represent the vector $\stackrel{v}{\nabla} H U$ in the form

$$
\begin{equation*}
\stackrel{v}{\nabla} H U=\lambda \xi+\stackrel{v}{\nabla}^{\perp} H U, \quad\left\langle\xi, \stackrel{v}{\nabla}^{\perp} H U\right\rangle=0 . \tag{6.12}
\end{equation*}
$$

Here $\lambda=\lambda(x, \xi)$ is some scalar function. The second summand of the representation has a clear geometrical sense: If $\psi_{x}=\left.H U\right|_{\Omega_{x} M}$ is a restriction of $H U$ to the unit sphere $\Omega_{x} M$ then $\nabla^{\nu} H U(x, \xi)=\nabla \psi_{x}(\xi)$ is the gradient of the function $\psi_{x}$ at the point $\xi \in \Omega_{x} M$. Formula (6.3) implies that $\psi_{x}(\xi)=v_{i_{1} . . . i_{i_{m-1}}}(x) \xi^{i_{1}} \cdots \xi^{i_{m-1}}$. Applying the Euler formula (6.10), we see that $\lambda=(m+1) H U$. Thus, (6.12) implies

$$
\begin{equation*}
|\stackrel{v}{\nabla} H U|^{2}=(m+1)^{2}|H U|^{2}+\left|\nabla \psi_{x}\right|^{2} \tag{6.13}
\end{equation*}
$$

By Green's formula,

$$
\int_{\Omega_{x} M}\left|\nabla \psi_{x}\right|^{2} d \omega(\xi)=-\int_{\Omega_{x} M} \psi_{x} \Delta_{\omega} \psi_{x} d \omega(\xi)
$$

where $\Delta_{\omega}$ is the spherical Laplacian on $\Omega_{x} M$. The eigenvalues of $-\Delta_{\omega}$ are $\lambda_{k}=k(n+k-2)$, $k=0,1, \ldots$, and the spherical harmonics of degree $k$ are the eigenfunctions corresponding to $\lambda_{k}$. Since $\psi_{x}$ is a polynomial of degree $m-1$, the last integral can be estimated as follows:

$$
\begin{aligned}
\int_{\Omega_{x} M}\left|\nabla \psi_{x}\right|^{2} d \omega(\xi) & =-\int_{\Omega_{x} M} \psi_{x} \Delta_{\omega} \psi_{x} d \omega(\xi) \\
& \leq \sup _{k \leq m-1} \lambda_{k} \int_{\Omega_{x} M}\left|\psi_{x}\right|^{2} d \omega(\xi) \\
& =(m-1)(n+m-3) \int_{\Omega_{x} M}|H U|^{2} d \omega(\xi) .
\end{aligned}
$$

Together with (6.13), this imply

$$
\int_{\Omega M}\left(|\nabla v H U|^{2}-m(n+2 m)|H U|^{2}\right) d \Sigma \leq-(2 m+n-4) \int_{\Omega M}|H U|^{2} d \Sigma
$$

Taking this inequality into account, we derive from (6.11)

$$
\begin{equation*}
-(2 m+n-4) \int_{\Omega M}|H U|^{2} d \Sigma \geq \int_{\Omega M}\left(|\stackrel{h}{\nabla} U|^{2}-R_{\xi}(\stackrel{v}{\nabla} U)\right) d \Sigma . \tag{6.14}
\end{equation*}
$$

The coefficient $(2 m+n-4)$ is nonnegative since $m \geq 1$ and $n \geq 2$. Hence the lefthand side of (6.14) is nonpositive. At the same time, the right-hand side of (6.14) is nonnegative in virtue of (6.8). Thus, both sides of (6.14) are equal to zero. In particular, $|\stackrel{h}{\nabla} U|^{2}-R_{\xi}(\stackrel{v}{\nabla} U)=0$ on $\Omega M$. Applying (6.8) once more, we obtain

$$
\begin{equation*}
R_{\xi}(\stackrel{v}{\nabla} U)=0 \tag{6.15}
\end{equation*}
$$

and $\stackrel{h}{\nabla} U=0$ on $\Omega M$. Hence, $\stackrel{h}{\nabla} U$ is identically zero on $T M$. Now, (6.1) implies $0=$ ${ }^{h}{ }_{i} U=\nabla_{i} u_{i_{1} \ldots i_{m}} \xi^{i_{1} \ldots i_{m}}$. Thus, $\nabla u$ is identically zero on $M$, i.e., $u$ is absolutely parallel.

Now, we prove the statement: $u\left(x_{0}\right)=0$ if all sectional curvatures at the point $x_{0}$ are negative. This implies $u \equiv 0$ since $u$ is absolutely parallel.
Given $\xi \in \Omega_{x_{0}}$, like in (6.12), we represent the vector $\stackrel{v}{\nabla} U\left(x_{0}, \xi\right)$ in the form

$$
\begin{equation*}
\stackrel{v}{\nabla} U\left(x_{0}, \xi\right)=\mu(\xi) \xi+\stackrel{v}{\nabla}{ }^{\perp} U\left(x_{0}, \xi\right), \quad\left\langle\xi, \stackrel{v}{\nabla}{ }^{\perp} U\left(x_{0}, \xi\right)\right\rangle=0 . \tag{6.16}
\end{equation*}
$$

Here $\mu$ is some scalar function. We claim $\nabla^{v} \perp\left(x_{0}, \xi\right)=0$ for all $\xi \in \Omega_{x_{0}}$. Indeed, assume $\nabla^{\perp} U\left(x_{0}, \xi\right) \neq 0$ for some $\xi$. Then, substituting (6.16) into (6.7) and using symmetries of the curvature tensor, we infer

$$
R_{\xi}\left(\nabla_{\nabla}{ }^{\perp} U\left(x_{0}, \xi\right)\right)=\left.K\left(x_{0}, \xi \wedge \stackrel{v}{\nabla} U\left(x_{0}, \xi\right)\right)| |^{\perp} U\right|^{2}<0 .
$$

Here $K\left(x_{0}, \xi \wedge \stackrel{v}{\nabla} U\left(x_{0}, \xi\right)\right)$ is the value of the sectional curvature at the point $x_{0}$ in the two-dimensional direction $\xi \wedge \stackrel{v}{\nabla} U\left(x_{0}, \xi\right)$. The last inequality contradicts (6.15).

Hence, $\stackrel{v}{ }^{\perp} U\left(x_{0}, \xi\right)=0$ for all $\xi \in \Omega_{x_{0}}$. This means that

$$
\begin{equation*}
\left.U\right|_{\Omega_{x_{0} M} M}=c=\text { const. } \tag{6.17}
\end{equation*}
$$

In the case of an odd $m$, the constant $c$ must be equal to zero since the function $U(x, \xi)$ is odd in $\xi$. In the case of $m=2 l>0,(6.1)$ and (6.17) imply $u\left(x_{0}\right)=c g^{l}$. The condition $j u=0$ implies $c=0$. Thus, $u\left(x_{0}\right)=0$ for all $m$.

We have proved the statements of Theorem 1.6 concerning trace-free conformal Killing tensor fields. We now prove the statements of the theorem concerning a Killing field by induction in the rank $m$ of the field.

The statements are valid in the cases of $m=0$ and of $m=1$ since a Killing vector field is a trace-free conformal Killing field as well. Assume $m \geq 2$ and let $u \in C^{\infty}\left(S^{m} \tau_{M}\right)$ be a Killing tensor field of rank $m$. Represent $u$ in the form

$$
\begin{equation*}
u=\tilde{u}+i v, \tag{6.18}
\end{equation*}
$$

where $\tilde{u}$ satisfies the condition $j \tilde{u}=0$. So, $\tilde{u}$ is a trace-free conformal Killing field, and thus, $\nabla \tilde{u}=0$. Applying the operator $d$ to (6.18), we obtain $i d v=0$. Hence, $d v=0$, i.e., $v$ is a Killing field. We obtain $\nabla v=0$ by the inductive assumption. So, both summands on the right-hand side of (6.18) are absolutely parallel, and $u$ is also an absolutely parallel field.

The remaining statement on Killing fields is proved in a similar way.

Proof of Theorem 1.7. We now need the following corollary of Theorem A from [5] (see also the remark after formulation of the theorem in [5]).

Proposition 6.1. Let $(M, g)$ be a closed Riemannian manifold without conjugate points. Let $h \in C^{\infty}(M)$ and $\theta \in C^{\infty}\left(\tau_{M}^{\prime}\right)$. If the equation

$$
H U(x, \xi)=h(x)+\theta_{i}(x) \xi^{i}, \quad(x, \xi) \in \Omega M
$$

has a solution $U \in C^{\infty}(\Omega M)$ then $h=0$ and $\theta$ is an exact 1-form.
Assume now $u$ to be a conformal Killing covector field, i.e.,

$$
\begin{equation*}
d u=i v \tag{6.19}
\end{equation*}
$$

for some function $v$ on $M$. Define the function $U \in C^{\infty}(\Omega M)$ by

$$
U(x, \xi)=u_{i}(x) \xi^{i}, \quad(x, \xi) \in \Omega M
$$

As follows from (6.19), $U$ satisfies the kinetic equation

$$
H U(x, \xi)=v(x) \text { on } \Omega M
$$

Applying Proposition 6.1, we obtain $v \equiv 0$. Since

$$
(d u(x))_{i j} \xi^{i} \xi^{j}=H U(x, \xi)=v(x)=0,
$$

we see that $d u=0$, i.e., $u$ is a Killing covector field. If the geodesic flow of $(M, g)$ has a dense orbit in $\Omega M$ then $H U=0$ implies $U \equiv$ const. This means that $u \equiv 0$.

Assume now $u$ to be a trace-free conformal Killing symmetric field of rank 2, i.e.,

$$
d u=i v, \quad j u=0
$$

for some covector field $v$. Define the function

$$
U(x, \xi)=u_{i j}(x) \xi^{i} \xi^{j}
$$

on $\Omega M$. It satisfies the equation

$$
\begin{equation*}
H U(x, \xi)=v_{i}(x) \xi^{i}, \quad(x, \xi) \in \Omega M \tag{6.20}
\end{equation*}
$$

By Proposition 6.1, $v$ is an exact 1 -form, i.e.,

$$
\begin{equation*}
v=d \varphi \tag{6.21}
\end{equation*}
$$

for some function $\varphi$ on $M$. Formulas (6.20) and (6.21) imply

$$
\begin{equation*}
d(u-\varphi g)=0 . \tag{6.22}
\end{equation*}
$$

Since $j u=0$, this means $u$ is the trace-free part of the Killing field $u-\varphi g$. On the other hand, the trace-free part of a Killing tensor field is obviousely a trace-free conformal Killing field.

If the geodesic flow $(M, g)$ has a dense in $\Omega M$ orbit then $u-\varphi g=c g$ for some constant $c$, as follows from (6.22). Together with the condition $j u=0$, this means $u=0$. Theorem 1.6 is proved.

## 7. Comparison of differential operators modulo low order terms

In our studying differential operators on tensor fields, we will usually ignore low order terms. In order to simplify the exposition, we introduce the following notation: If $A$ and $B$ are two differential expressions, we write

$$
A u=B u \quad\left(\bmod \nabla^{k} u\right) \text { on } \mathcal{A}
$$

if there exists a differential operator $L^{(k)}$ of order $k$ such that

$$
A u=B u+L^{(k)} u
$$

for all tensor fields $u$ belonging to the subspace $\mathcal{A}$ of the space $C^{\infty}\left(\otimes^{*} \tau^{\prime}\right)$. The choice of the subspace will be mostly clear from the context. Similar notation is used for differential operators depending on several variables.

Lemma 7.1. For $k \geq 1$ and $u \in C^{\infty}\left(\otimes^{m} \tau^{\prime}\right)$,

$$
\nabla_{j_{1} \ldots j_{k}} u_{i_{1} \ldots i_{m}}=\sigma\left(j_{1} \ldots j_{k}\right)\left(\nabla_{j_{1} \ldots j_{k}} u_{i_{1} \ldots i_{m}}\right) \quad\left(\bmod \nabla^{k-2} u\right) .
$$

We omit the proof that can be easily carried out by induction in $k$ starting from the following formula for the second order derivatives:

$$
\begin{equation*}
\left(\nabla_{j k}-\nabla_{k j}\right) u_{i_{1} \ldots i_{m}}=\sum_{a=1}^{m} R_{i_{a} k j}^{p} u_{i_{1} \ldots i_{a-1} p i_{a+1} \ldots i_{m}}, \tag{7.1}
\end{equation*}
$$

where $\left(R_{i j k}^{p}\right)$ is the curvature tensor.
Lemma 7.2. For $v \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$ and $p \geq 0$,

$$
\begin{aligned}
\nabla_{j_{1} \ldots j_{m+p}} v_{i_{1} \ldots i_{m}}= & \sigma\left(i_{1} \ldots i_{m}\right) \sigma\left(j_{1} \ldots j_{m+p}\right) \sum_{l=0}^{m}(-1)^{l}\binom{p+l-1}{l}\binom{m+p}{m-l} \\
& \times \nabla_{i_{m-l+1} \ldots i_{m} j_{l+p+1} \ldots j_{m+p}}\left(d^{p} v\right)_{i_{1} \ldots i_{m-l} j_{1} \ldots j_{l+p}}\left(\bmod \nabla^{m+p-2} v\right) .
\end{aligned}
$$

Proof. Define the tensors $u$ and $f$ as follows:

$$
\begin{align*}
u_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}} & =\sigma\left(j_{1} \ldots j_{p} k_{1} \ldots k_{m}\right) \nabla_{j_{1} \ldots j_{p} k_{1} \ldots k_{m}} v_{i_{1} \ldots i_{m}},  \tag{7.2}\\
f_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}} & =\sigma\left(i_{1} \ldots i_{m} j_{1} \ldots j_{p}\right) \sigma\left(k_{1} \ldots k_{m}\right) \nabla_{j_{1} \ldots j_{p} k_{1} \ldots k_{m}} v_{i_{1} \ldots i_{m}} .
\end{align*}
$$

By Lemma 7.1, we have

$$
\begin{equation*}
\nabla_{j_{1} \ldots j_{p} k_{1} \ldots k_{m}} v_{i_{1} \ldots i_{m}}=u_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}} \quad\left(\bmod \nabla^{m+p-2} v\right) . \tag{7.3}
\end{equation*}
$$

Applying the operator $\sigma\left(i_{1} \ldots i_{m} j_{1} \ldots j_{p}\right) \sigma\left(k_{1} \ldots k_{m}\right)$ to this equation and using (7.2), we obtain

$$
\sigma\left(i_{1} \ldots i_{m} j_{1} \ldots j_{p}\right) u_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}}=f_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}} \quad\left(\bmod \nabla^{m+p-2} v\right) .
$$

Hence, $u$ and $f$ satisfy the hypotheses of Lemma 2.1. Application of the lemma gives

$$
\begin{align*}
u_{i_{1} \ldots i_{m j} \ldots j_{m+p}}= & \sigma\left(i_{1} \ldots i_{m}\right) \sigma\left(j_{1} \ldots j_{m+p}\right) \sum_{l=0}^{m}(-1)^{l}\binom{p+l-1}{m-l}\binom{m+p}{m-l} \\
& \times f_{i_{1} \ldots i_{m-l} j_{1} \ldots j_{m+p} i_{m-l+1} \ldots i_{m}}\left(\bmod \nabla^{m+p-2} v\right) . \tag{7.4}
\end{align*}
$$

From (7.2) and Lemma 7.1, we deduce

$$
f_{i_{1} \ldots i_{m} j_{1} \ldots j_{p} k_{1} \ldots k_{m}}=\sigma\left(k_{1} \ldots k_{m}\right)\left(\nabla_{k_{1} \ldots k_{m}}\left(d^{p} v\right)_{i_{1} \ldots i_{m} j_{1} \ldots j_{p}}\right) \quad\left(\bmod \nabla^{m+p-2} v\right) .
$$

Substituting the last expression into (7.4) and using equality (7.3), we obtain the statement of the lemma.

Lemma 7.3. Let $u_{i} \in C^{\infty}\left(\otimes^{m_{i}} \tau^{\prime}\right)$ for $1 \leq i \leq k$. If, for every $i$, there exists $p_{i} \geq 1$ such that

$$
\nabla^{p_{i}} u_{i}=0 \quad\left(\bmod \nabla^{p_{1}-1} u_{1}, \ldots, \nabla^{p_{k}-1} u_{k}\right)
$$

and $u_{i}\left(x_{0}\right)=0, \nabla u_{i}\left(x_{0}\right)=0, \ldots, \nabla^{p_{i}-1} u_{i}\left(x_{0}\right)=0$ at some point $x_{0}$ of a connected manifold $M$ then all the fields $u_{i}$ are identically equal to zero.

Proof. We present only the scheme of the proof without details. In order to show that $u_{i}$ vanish at some point $x_{1}$, we connect the points $x_{0}$ and $x_{1}$ by a smooth curve $x(t)$. The components of tensors $u_{i}(t)=u_{i}(x(t))$ satisfy a linear homogeneous system of ordinary differential equations with homogeneous initial conditions. The order of the system with respect to $u_{i}(t)$ equals $p_{i}$ and the system is solved with respect to the highest order derivatives. This implies the statement of the lemma.

The last two lemmas imply the following proposition.
Lemma 7.4. Assume $M$ to be connected and $u_{i} \in C^{\infty}\left(S^{m_{i}} \tau^{\prime}\right), 1 \leq i \leq k$. If, for every $i$, there exists $p_{i}$ such that

$$
d^{p_{i}} u_{i}=0 \quad\left(\bmod \nabla^{p_{1}-1} u_{1}, \ldots, \nabla^{p_{k}-1} u_{k}\right)
$$

and

$$
u_{i}\left(x_{0}\right)=0, \quad \nabla u_{i}\left(x_{0}\right)=0, \quad \ldots, \quad \nabla^{m_{i}+p_{i}-1} u_{i}\left(x_{0}\right)=0
$$

at some point $x_{0}$ then all $u_{i}$ are identically equal to zero.

## 8. Commutation formula for $d$ and $\delta$. The operator $\Delta$

Let the operator $\Delta: C^{\infty}\left(S^{m} \tau^{\prime}\right) \rightarrow C^{\infty}\left(S^{m} \tau^{\prime}\right)$ be defined as follows:

$$
\begin{equation*}
(\Delta u)_{i_{1} \ldots i_{m}}=g^{j k} \nabla_{j k} u_{i_{1} \ldots i_{m}} . \tag{8.1}
\end{equation*}
$$

This differential operator has the order 2 and the degree 0 , and acts on sections of the fiber bundle $S^{*} \tau^{\prime}$. Probably, (7.2) is not the best definition of the Laplacian, and some zero order terms should be added to the right-hand side like for the Laplacian on differential forms. However, the most of our statements concerning $\Delta$ are formulated modulo low order terms, and such statements are independent of low order terms on the right-hand side of (8.1).

Lemma 8.1. The operator $\Delta$ is formally self-adjoint and satisfies the relations

$$
\begin{align*}
& \Delta i= i \Delta,  \tag{8.2}\\
& \Delta j=j \Delta,  \tag{8.3}\\
& \Delta^{l} d^{k} u=d^{k} \Delta^{l} u\left(\bmod \nabla^{k+2 l-2} u\right),  \tag{8.4}\\
& \Delta^{l} \delta^{k} u=\delta^{k} \Delta^{l} u \quad\left(\bmod \nabla^{k+2 l-2} u\right) . \tag{8.5}
\end{align*}
$$

Proof. As follows from Green's formula, for $u, v \in C_{0}^{\infty}\left(S^{*} \tau^{\prime}\right)$,

$$
(\Delta u, v)_{L^{2}}=-(\nabla u, \nabla v)_{L^{2}} .
$$

This implies the first statement of the lemma since the right-hand side of the last formula is symmetric in $u$ and $v$. Equality (8.2) is proved by a direct calculation in coordinates which is omitted, and (8.3) follows from (8.2) since these relations are dual to each other.
We now prove (8.4) in the case of $k=l=1$. For $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$, we have

$$
\begin{aligned}
& (\Delta d u)_{i_{1} \ldots i_{m+1}}=\sigma\left(i_{1} \ldots i_{m+1}\right)\left(g^{j k} \nabla_{j k i_{m+1}} u_{i_{1} \ldots i_{m}}\right), \\
& (d \Delta u)_{i_{1} \ldots i_{m+1}}=\sigma\left(i_{1} \ldots i_{m+1}\right)\left(g^{j k} \nabla_{i_{m+1} j k} u_{i_{1} \ldots i_{m}}\right) .
\end{aligned}
$$

By Lemma 7.1, the right-hand sides of these equalities coincide modulo $\nabla u$. This proves (8.4) for $k=l=1$. In the general case, (8.4) is proved by induction in $k$ and $l$. Formula (8.5) follows from (8.4) by conjugation.

We define the operator $R \in \operatorname{Hom}\left(S^{*} \tau^{\prime}, S^{*} \tau^{\prime}\right)$ by setting

$$
(R u)_{i_{1} \ldots i_{m}}=\sum_{a=1}^{m} g^{i j} R_{i i_{a}} u_{j i_{1} \ldots \hat{i}_{a} \ldots i_{m}}+2 \sum_{1 \leq a<b \leq m} g^{i p} g^{j q} R_{i i_{a} j i_{b}} u_{p q i_{1} \ldots \hat{i}_{a} \ldots \hat{i}_{b} \ldots i_{m}}
$$

for $u \in S^{m} \tau^{\prime}$. Here ( $R_{i j k l}$ ) is the curvature tensor, and ( $R_{i j}=g^{k l} R_{k i j l}$ ) is the Ricci tensor. The second sum on the right-hand side is absent in the case of $m=1$, .

Lemma 8.2. The following commutation formula holds on $C^{\infty}\left(S^{m} \tau^{\prime}\right)$ :

$$
\delta d=\frac{1}{m+1}(m d \delta+\Delta-R)
$$

Proof. For $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$, we have

$$
\begin{aligned}
(m+1)(\delta d u)_{i_{1} \ldots i_{m}} & =(m+1) g^{i_{m+1} i_{m+2}} \nabla_{i_{m+2}}(d u)_{i_{1} \ldots i_{m+1}} \\
& =g^{i_{m+1} i_{m+2}}\left(\nabla_{i_{m+2} i_{m+1}} u_{i_{1} \ldots i_{m}}+\sum_{a=1}^{m} \nabla_{i_{m+2} i_{a}} u_{i_{1} \ldots \hat{i_{a} \ldots i_{m+1}}}\right) .
\end{aligned}
$$

This can be written in the form

$$
\begin{aligned}
(m+1)(\delta d u)_{i_{1} \ldots i_{m}}= & (\Delta u)_{i_{1} \ldots i_{m}}+\sum_{a=1}^{m} \nabla_{i_{a}}\left(g^{i_{m+1} i_{m+2}} \nabla_{i_{m+2}} u_{i_{1} \ldots \hat{i_{a}} \ldots i_{m+1}}\right) \\
& -\sum_{a=1}^{m} g^{i_{m+1} i_{m+2}}\left(\nabla_{i_{a} i_{m+2}}-\nabla_{i_{m+2} i_{a}}\right) u_{i_{1} \ldots \hat{i_{a} \ldots i_{m+1}}} .
\end{aligned}
$$

Denote the last sum on the right-hand side of this equality by $A_{i_{1} \ldots i_{m}}$ and rewrite the formula as

$$
\begin{equation*}
(m+1)(\delta d u)_{i_{1} \ldots i_{m}}=(\Delta u)_{i_{1} \ldots i_{m}}+m(d \delta u)_{i_{1} \ldots i_{m}}-A_{i_{1} \ldots i_{m}} . \tag{8.6}
\end{equation*}
$$

According to (7.1), we have

$$
A_{i_{1} \ldots i_{m}}=g^{i_{m+1} i_{m+2}} \sum_{a=1}^{m} \sum_{\substack{b=1 \\ b \neq a}}^{m+1} R_{i_{b} i_{m+2} i_{a}}^{p} u_{i_{1} \ldots \hat{i}_{a} \ldots i_{b-1}} p i_{b+1} \ldots i_{m+1} .
$$

We distinguish the summands corresponding to $b=m+1$. Then

$$
\begin{aligned}
A_{i_{1} \ldots i_{m}}= & \sum_{a=1}^{m} g^{i_{m+1} i_{m+2}} R_{i_{m+1} i_{m+2} i_{a}}^{p} u_{i_{1} \ldots \hat{i}_{a} \ldots i_{m} p} \\
& +2 \sum_{1 \leq a<b \leq m} g^{i_{m+1} i_{m+2}} R_{i_{b} i_{m+2} i_{a}}^{p} u_{i_{1} \ldots \hat{i}_{a} \ldots \hat{i}_{b} \ldots i_{m+1} p}=(R u)_{i_{1} \ldots i_{m}} .
\end{aligned}
$$

The statement of the lemma immediately follows by substituting the last expression into (8.6).

We are going to use only the following corollary of Lemma 8.2:

$$
\begin{equation*}
\delta d u=\frac{m}{m+1} d \delta u+\frac{1}{m+1} \Delta u \quad(\bmod u) \text { for } u \in C^{\infty}\left(S^{m} \tau^{\prime}\right) . \tag{8.7}
\end{equation*}
$$

Lemma 8.3. For arbitrary nonnegative integers $m, k$, and $l$, the equality

$$
\begin{equation*}
\delta^{l} d^{k} u=\frac{l!(m+k-l)!}{(m+k)!} \sum_{p}\binom{k}{p}\binom{m}{l-p} d^{k-p} \Delta^{p} \delta^{l-p} u \quad\left(\bmod \nabla^{k+l-2} u\right) \tag{8.8}
\end{equation*}
$$

holds for all $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$. The summation in (8.8) is taken over all integers $p$ under the agreement:

$$
\begin{equation*}
\binom{i}{j}=0 \text { for } j<0 \text { or } i<j, \text { and } i!=0 \text { for } i<0 . \tag{8.9}
\end{equation*}
$$

Proof. Equality (8.8) is trivial for $k=0$ or $l=0$. For $k=l=1$, it coincides with (8.7). In the case of $l=1$ and and of an arbitrary $k$, (8.8) looks as follows:

$$
\begin{equation*}
\delta d^{k} u=\frac{m}{m+k} d^{k} \delta u+\frac{k}{m+k} d^{k-1} \Delta u \quad\left(\bmod \nabla^{k-1} u\right) . \tag{8.10}
\end{equation*}
$$

The trivial case $m=k=0$ is not considered here. We prove (8.10) by induction in $k$. Assume (8.10) to be valid for some $k \geq 1$. Then

$$
\begin{aligned}
\delta d^{k+1} u & =\delta d^{k}(d u)=\left(\frac{m+1}{m+k+1} d^{k} \delta+\frac{k}{m+k+1} d^{k-1} \Delta \quad\left(\bmod \nabla^{k-1}\right)\right) d u \\
& =\frac{m+1}{m+k+1} d^{k} \delta d u+\frac{k}{m+k+1} d^{k-1} \Delta d u \quad\left(\bmod \nabla^{k} u\right)
\end{aligned}
$$

Taking (8.4) and (8.7) into account, this gives

$$
\begin{aligned}
\delta d^{k+1} u= & \frac{m+1}{m+k+1} d^{k}\left(\frac{m}{m+1} d \delta u+\frac{1}{m+1} \Delta u \quad(\bmod u)\right) \\
& +\frac{k}{m+k+1} d^{k} \Delta u\left(\bmod \nabla^{k} u\right) \\
= & \frac{m}{m+k+1} d^{k+1} \delta u+\frac{k+1}{m+k+1} d^{k} \Delta u \quad\left(\bmod \nabla^{k} u\right) .
\end{aligned}
$$

The last relation coincides with (8.10) for $k:=k+1$. Hence, (8.10) is proved.
Equality (8.8) is trivial for $l>k+m$ since, in this case, both its sides are equal to zero. Hence it suffices to prove (8.8) for $1 \leq l \leq k+m$. We use induction in $l$. For $l=1$, equality (8.8) is already established. Assume now that (8.8) is satisfied for some $1 \leq l<k+m$. Then

$$
\delta^{l+1} d^{k} u=\delta\left(\delta^{l} d^{k} u\right)=\frac{l!(m+k-l)!}{(m+k)!} \sum_{p}\binom{k}{p}\binom{m}{l-p}\left(\delta d^{k-p}\right) \Delta^{p} \delta^{l-p} u \quad\left(\bmod \nabla^{k+l-1} u\right) .
$$

Using (8.10) and (8.5), we transform the last formula to the following one:

$$
\begin{aligned}
\delta^{l+1} d^{k} u & =\frac{l!(m+k-l)!}{(m+k)!} \sum_{p}\binom{k}{p}\binom{m}{l-p} \\
& \times\left[\frac{m-l+p}{m-l+k} d^{k-p} \Delta^{p} \delta^{l-p+1} u+\frac{k-p}{m-l+k} d^{k-p-1} \Delta^{p+1} \delta^{l-p} u\right]\left(\bmod \nabla^{k+l-1} u\right) .
\end{aligned}
$$

Combining the first summand in the brackets of the $p$ th term and the second summand of the $(p-1)$ th term, we arrive to (8.8) for $l:=l+1$.

Lemma 8.4. For arbitrary nonnegative integers $m$ and $k$, the equality

$$
\begin{align*}
\delta^{k} i u=\frac{1}{(m+1)(m+2)}( & 2 k(m-k+2) d \delta^{k-1} u+k(k-1) \Delta \delta^{k-2} u \\
& \left.+(m-k+1)(m-k+2) i \delta^{k} u\right) \quad\left(\bmod \nabla^{k-2} u\right) \tag{8.11}
\end{align*}
$$

is valid for all $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$. If $m+k \geq 2$ then

$$
\begin{align*}
& j d^{k} u=\frac{1}{(m+k-1)(m+k)}\left(2 k m d^{k-1} \delta u+k(k-1) d^{k-2} \Delta u\right. \\
& \left.\quad+m(m-1) d^{k} j u\right) \quad\left(\bmod \nabla^{k-2} u\right) . \tag{8.12}
\end{align*}
$$

Proof. These equalities are dual to each other. Hence it suffices to prove the second one.
We prove (8.12) by induction in $k$. This equality is trivial for $k=0$ and coincides with (3.6) for $k=1$. Assume (8.12) to be valid for some $k \geq 1$. Then

$$
\begin{aligned}
j d^{k+1} u=\left(j d^{k}\right) d u=\frac{1}{(m+k)(m+k+1)} & \left(2 k(m+1) d^{k-1} \delta d u+k(k-1) d^{k-2} \Delta d u\right. \\
& \left.+m(m+1) d^{k} j d u\right) \quad\left(\bmod \nabla^{k-1} u\right) .
\end{aligned}
$$

Transforming each summand on the right-hand side according to Lemmas 8.3, 8.1, and 3.3, respectively, we arrive to (8.12) for $k:=k+1$.

## 9. Proof of theorem 1.1 in the case of $n=\operatorname{dim} M \geq 3$

In the case of $m=0$, equation (1.3) reduces to $d u=0$ for a scalar function $u$, and Theorem 1.1 is obvious in this case. Hence we assume $m \geq 1$ in this section.

Roughly speaking, the next lemma allows us to eliminate $u$ from equations (1.2)-(1.3).
Lemma 9.1. Let $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$ and $v \in C^{\infty}\left(S^{m-1} \tau^{\prime}\right)$ satisfy (1.2)-(1.3). Then

$$
\begin{gather*}
(n+2 m-4) d^{m+1} v=i\left((m-1) d^{m} \delta v-d^{m-1} \Delta v\right) \quad\left(\bmod \nabla^{m} u\right),  \tag{9.1}\\
j v=0,  \tag{9.2}\\
v=0 \quad(\bmod \nabla u) . \tag{9.3}
\end{gather*}
$$

Proof. Applying the operator $j$ to equation (1.3) and using Lemma 3.3, we obtain

$$
(m+1) j i v=(m+1) j d u=2 \delta u+(m-1) d j u .
$$

Since $j u=0$, this gives

$$
\begin{equation*}
v=\frac{2}{m+1}(j i)^{-1} \delta u . \tag{9.4}
\end{equation*}
$$

Observe that $j(\delta u)=\delta j u=0$. Applying Lemma 2.2 to $\delta u$, we obtain

$$
(j i)^{-1} \delta u=\frac{m(m+1)}{2(n+2 m-2)} \delta u .
$$

Substitute this expression into (9.4) to obtain

$$
\begin{equation*}
v=\frac{m}{n+2 m-2} \delta u . \tag{9.5}
\end{equation*}
$$

In particular, this implies (9.2) and (9.3).
In order to prove (9.1), we introduce the temporary notation $f=i v$. Equation (1.3) can be written as $d u=f$. The latter equation can be solved in $\nabla^{m+1} u$. Indeed, applying Lemma 7.2 with $p=1$, we obtain

$$
\begin{align*}
\nabla_{j_{1} \ldots j_{m+1}} u_{i_{1} \ldots i_{m}}= & \sigma\left(i_{1} \ldots i_{m}\right) \sigma\left(j_{1} \ldots j_{m+1}\right) \sum_{l=0}^{m}(-1)^{l}\binom{m+1}{l+1} \\
& \times \nabla_{i_{m-l+1} \ldots i_{m} j_{l+2} \ldots j_{m+1}} f_{i_{1} \ldots i_{m-l} j_{1} \ldots j_{l+1}}\left(\bmod \nabla^{m-1} u\right) . \tag{9.6}
\end{align*}
$$

Our further arguments are different in the cases of $m=1$ and of $m>1$. We first assume $m>1$. We contract equation (9.6) with $g^{i_{m-1} i_{m}}$ (i.e., multiply this equation by $g^{i_{m-1} i_{m}}$ and take the sum over $i_{m-1}$ and $i_{m}$ ). In virtue of the equality

$$
g^{i_{m-1} i_{m}} \nabla_{j_{1} \ldots j_{m+1}} u_{i_{1} \ldots i_{m}}=\nabla_{j_{1} \ldots j_{m+1}}(j u)_{i_{1} \ldots i_{m-2}}=0,
$$

we obtain

$$
\begin{align*}
& \sigma\left(j_{1} \ldots j_{m+1}\right) \sum_{l=1}^{m+1}(-1)^{l}\binom{m+1}{l} g^{i_{m-1} i_{m}} \\
& \quad \times \sigma\left(i_{1} \ldots i_{m}\right) \nabla_{i_{m-l+2} \ldots i_{m} j_{l+1} \ldots j_{m+1}} f_{i_{1} \ldots i_{m-l+1} j_{1} \ldots j_{l}}=0 \quad\left(\bmod \nabla^{m-1} u\right) \tag{9.7}
\end{align*}
$$

Using Lemma 7.1 and the equality $f=i v=0(\bmod \nabla u)$ which follows from (9.3), we can permute the indices in each factor of the product

$$
\nabla_{i_{m-l+2} \ldots i_{m} j_{l+1} \ldots j_{m+1}} f_{i_{1} \ldots i_{m-l+1} j_{1} \ldots j_{l}}
$$

without violating equation (9.7). Using this observation, we divide all summands of the sum in (9.7) to three groups so that the indices $i_{m-1}$ and $i_{m}$ belong to the first (second) factor in all summands of the first (third) group, and belong to different factors in the summands of the second group. Rename these indices as $i_{m-1}=p_{1}$ and $i_{m}=p_{2}$ for clarity. In such the way we obtain

$$
\begin{aligned}
& \sigma\left(i_{1} \ldots i_{m-2}\right) \sigma\left(j_{1} \ldots j_{m+1}\right) \sum_{l=1}^{m+1}(-1)^{l}\binom{m+1}{l} g^{p_{1} p_{2}} \\
& \times\left((l-1)(l-2) \nabla_{i_{m-l+2} \ldots i_{m-2} j_{l+1} \ldots j_{m+1} p_{1} p_{2}} f_{i_{1} \ldots i_{m-l+1} j_{1} \ldots j_{l}}\right. \\
& +2(l-1)(m-l+1) \nabla_{i_{m-l+1} \ldots i_{m-2} j_{l+1} \ldots j_{m+1} p_{2}} f_{i_{1} \ldots i_{m-l} j_{1} \ldots j_{l} p_{1}} \\
& \left.+(m-l)(m-l+1) \nabla_{i_{m-l} \ldots i_{m-2} j_{l+1} \ldots j_{m+1}} f_{i_{1} \ldots i_{m-l-1} j_{1} \ldots j p_{1} p_{2}}\right)=0\left(\bmod \nabla^{m-1} u\right)
\end{aligned}
$$

Now, we symmetrize this equation in all free indices (i.e., apply the operator $\left.\sigma\left(i_{1} \ldots i_{m-2} j_{1} \ldots j_{m+1}\right)\right)$. Changing simultaneously notations as $j_{1}=i_{m-1}, \ldots, j_{m+1}=$ $i_{2 m-1}$, we get

$$
\begin{aligned}
& \sigma\left(i_{1} \ldots i_{2 m-1}\right) \sum_{l=1}^{m+1}(-1)^{l}\binom{m+1}{l} g^{p_{1} p_{2}} \\
& \quad \times\left[\begin{array}{ll}
(l-1)(l-2) \nabla_{i_{m+2} \ldots i_{2 m-1} p_{1} p_{2}} f_{i_{1} \ldots i_{m+1}} \\
& \quad+2(l-1)(m-l+1) \nabla_{i_{m+1} \ldots i_{2 m-1} p_{2}} f_{i_{1} \ldots i_{m} p_{1}} \\
& \quad+(m-l)(m-l+1) \nabla_{i_{m} \ldots i_{2 m-1}} f_{i_{1} \ldots i_{m-1} p_{1} p_{2}}
\end{array}\right]=0 \quad\left(\bmod \nabla^{m-1} u\right) .
\end{aligned}
$$

Observe that, for different values of $l$, the values of the first (second, third) summand in the brackets differ only by some factors. So the equation is transformed to the following form:

$$
\begin{align*}
& \sigma\left(i_{1} \ldots i_{2 m-1}\right)\left(a \nabla_{i_{m+2} \ldots i_{2 m-1} p_{1} p_{2}} f_{i_{1} \ldots i_{m+1}}+b \nabla_{i_{m+1} \ldots i_{2 m-1} p_{2}} f_{i_{1} \ldots i_{m} p_{1}}\right. \\
&\left.+c \nabla_{i_{m} \ldots i_{2 m-1}} f_{i_{1} \ldots i_{m-1} p_{1} p_{2}}\right) g^{p_{1} p_{2}}=0 \quad\left(\bmod \nabla^{m-1} u\right) \tag{9.8}
\end{align*}
$$

where

$$
\begin{aligned}
a & =\sum_{l=1}^{m+1}(-1)^{l}\binom{m+1}{l}(l-1)(l-2)=-2, \\
b & =2 \sum_{l=1}^{m+1}(-1)^{l}\binom{m+1}{l}(l-1)(m-l+1)=2(m+1), \\
c & =\sum_{l=1}^{m+1}(-1)^{l}\binom{m+1}{l}(m-l)(m-l+1)=-m(m+1) .
\end{aligned}
$$

Substituting these values for the coefficients, we write (9.8) in the coordinate-free form

$$
\begin{equation*}
2 d^{m-2} \Delta f-2(m+1) d^{m-1} \delta f+m(m+1) d^{m} j f=0 \quad\left(\bmod \nabla^{m-1} u\right) . \tag{9.9}
\end{equation*}
$$

We recall that $f=i v$ and express all summands of (9.9) in terms of $v$. Lemma 2.2 and (9.2) imply

$$
\begin{equation*}
j f=j i v=\frac{2(n+2 m-2)}{m(m+1)} v . \tag{9.10}
\end{equation*}
$$

With the help of Lemma 3.3, we deduce

$$
\begin{equation*}
\delta f=\delta i v=\frac{2}{m+1} d v+\frac{m-1}{m+1} i \delta v . \tag{9.11}
\end{equation*}
$$

Since the operators $i$ and $\Delta$ commute, we have

$$
\begin{equation*}
\Delta f=\Delta i v=i \Delta v \tag{9.12}
\end{equation*}
$$

Substituting (9.10)-(9.12) into (9.9) and using the commutation formula $d i=i d$, we arrive to the relation

$$
\begin{equation*}
(n+2 m-4) d^{m} v=i\left((m-1) d^{m-1} \delta v-d^{m-2} \Delta v\right) \quad\left(\bmod \nabla^{m-1} u\right) \tag{9.13}
\end{equation*}
$$

Applying the operator $d$ to this equation, we obtain (9.1).
Let us now consider the case of $m=1$. Equation (9.6) takes the form

$$
\nabla_{j_{2} j_{3}} u_{i}=\nabla_{j_{2}} f_{i j_{3}}+\nabla_{j_{3}} f_{i j_{2}}-\nabla_{i} f_{j_{2} j_{3}} \quad(\bmod u) .
$$

After differentiation we obtain

$$
\begin{equation*}
\nabla_{j_{1} j_{2} j_{3}} u_{i}=\nabla_{j_{1} j_{2}} f_{i_{3}}+\nabla_{j_{1} j_{3}} f_{i j_{2}}-\nabla_{j_{1} i} f_{j_{2} j_{3}} \quad(\bmod \nabla u) . \tag{9.14}
\end{equation*}
$$

According to Lemma 9.1, the third order derivatives satisfy the relation

$$
\nabla_{j_{1} j_{2} j_{3}} u_{i}-\nabla_{j_{2} j_{1} j_{3}} u_{i}=0 \quad(\bmod \nabla u) .
$$

Inserting (9.14) into the last equation, we obtain

$$
\nabla_{j_{1} j_{3}} f_{i j_{2}}+\nabla_{i j_{2}} f_{j_{1} j_{3}}-\nabla_{j_{2} j_{3}} f_{i_{j_{1}}}-\nabla_{i j_{2}} f_{j_{2} j_{3}}=0 \quad(\bmod \nabla u) .
$$

Now, substituting $f=i v$, we deduce

$$
g_{i j_{2}} \nabla_{j_{1} j_{3}} v+g_{j_{1} j_{3}} \nabla_{i j_{2}} v-g_{i j_{1}} \nabla_{j_{2} j_{3}} v-g_{j_{2} j_{3}} \nabla_{i j_{1}} v=0 \quad(\bmod \nabla u) .
$$

Contracting this equation with $g^{j_{1} j_{3}}$, we arrive to the formula

$$
(n-2) \nabla_{i j} v=-(\Delta v) g_{i j} \quad(\bmod \nabla u)
$$

that coincides with (9.1) for $m=1$.
Observe that, in the case of $m>1$, we have established relation (9.13) which is stronger than that of Lemma (9.1).

The next statement plays the main role in the proof of Theorem 1.1.

Lemma 9.2. Assume $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$ and $v \in C^{\infty}\left(S^{m-1} \tau^{\prime}\right)$ to satisfy (1.2) and (1.3) for $m \geq 1$. Then, for every integer $l$ such that $0 \leq l \leq 2 m$, the equation

$$
\begin{equation*}
\sum_{p=p_{1}}^{p_{2}} a_{p} d^{m-l+p+1} \Delta^{l-p} \delta^{p} v=i \sum_{p=p_{3}}^{p_{4}} b_{p} d^{m-l+p-1} \Delta^{l-p+1} \delta^{p} v \quad\left(\bmod \nabla^{m+l} u\right) \tag{9.15}
\end{equation*}
$$

is valid with some rational coefficients $a_{p}=a_{p}(n, m, l)$ and $b_{p}=b_{p}(m, l)$. Here the summation limits are defined as follows:

$$
\begin{align*}
& p_{1}=p_{1}(m, l)=\max (0, l-m-1), \\
& p_{2}=p_{2}(m, l)=\min (m-1, l), \\
& p_{3}=p_{3}(m, l)=\max (0, l-m+1),  \tag{9.16}\\
& p_{4}=p_{4}(m, l)=\min (m-1, l+1) .
\end{align*}
$$

The coefficients $a_{p_{1}}$ and $a_{p_{2}}$ are not equal to zero.
Proof. Apply the operator $\delta^{l}$ to equation (9.1)

$$
(n+2 m-4) \delta^{l} d^{m+1} v=\delta^{l} i\left((m-1) d^{m} \delta v-d^{m-1} \Delta v\right) \quad\left(\bmod \nabla^{m+l} u\right)
$$

We transform the right-hand side of this equality with the help of Lemma 8.4 and obtain

$$
\begin{aligned}
& 2 m(2 m-1)(n+2 m-4) \delta^{l} d^{m+1} v-2 l(2 m-l)(m-1) d \delta^{l-1} d^{m} \delta v \\
& \quad-l(l-1)(m-1) \Delta \delta^{l-2} d^{m} \delta v+2 l(2 m-l) d \delta^{l-1} d^{m-1} \Delta v+l(l-1) \Delta \delta^{l-2} d^{m-1} \delta v \\
& \quad=(2 m-l)(2 m-l-1) i\left[(m-1) \delta^{l} d^{m} \delta v-\delta^{l} d^{m-1} \Delta v\right] \quad\left(\bmod \nabla^{m+l} u\right)
\end{aligned}
$$

Taking (9.3) into account, we transform each summand on the left-hand side and the summands in the brackets to the form $d^{r} \Delta^{s} \delta^{t} v$ by using the commutation formulas for powers of $d, \delta$, and $\Delta$ (see Lemmas 8.1 and 8.3). Elementary but cumbersome calculations lead us to equation (9.15) where the summation is taken over all integers $p$ under the agreement $d^{k}=\delta^{k}=\Delta^{k}=0$ for $k<0$, and the coefficients are as follows:

$$
\begin{align*}
a_{p}= & {\left[(n+2 m-4)\binom{m+1}{l-p}+2\binom{m-1}{l-p-1}+\binom{m-1}{l-p-2}\right]\binom{m-1}{p} } \\
& -(m-1)\left[2\binom{m}{l-p}+\binom{m}{l-p-1}\right]\binom{m-2}{p-1},  \tag{9.17}\\
b_{p}= & (m-1)\binom{m}{l-p+1}\binom{m-2}{p-1}-\binom{m-1}{l-p}\binom{m-1}{p} . \tag{9.18}
\end{align*}
$$

Agreement (8.9) is used in (9.17) and (9.18).
Elementary arithmetical analysis of formula (9.17) shows that the coefficients $a_{p}$ can be nonzero for $p_{1} \leq p \leq p_{2}$ only, where $p_{1}$ and $p_{2}$ are defined in (9.16), and $a_{p_{1}}$ and $a_{p_{2}}$ are definitely nonzero. Similarly, (9.18) implies that $b_{p}$ can be nonzero for $p_{3} \leq p \leq p_{4}$ only.

Proof of Theorem 1.1. Recall that we assume $m \geq 1$. First we prove by induction in $k$ the equality

$$
\begin{equation*}
\Delta^{m+k} \delta^{m-k} v=0 \quad\left(\bmod \nabla^{3 m+k-1} u\right) \text { for } 0 \leq k \leq m \tag{9.19}
\end{equation*}
$$

The equality is trivial for $k=0$ since $\delta^{m} v=0$. Assume (9.19) to be valid for $k=$ $0, \ldots, s-1<m$. We write (9.15) for $l=2 m-s+1$ as follows:

$$
\sum_{p=m-s}^{m-1} a_{p} d^{s+p-m} \Delta^{2 m-s+p+1} \delta^{p} v=i \sum_{p=m-s+2}^{m-1} b_{p} d^{s+p-m-2} \Delta^{2 m-s-p+2} \delta^{p} v \quad\left(\bmod \nabla^{3 m-s+1} u\right)
$$

We apply the operator $\Delta^{s-1}$ to this equality and transform all terms of the resulting formula to the form $d^{r} \Delta^{s} \delta^{t} v$ with the help of (8.4). By Lemma 9.2, $a_{m-s} \neq 0$. We distinguish the first summand on the left-hand side and write the result as follows:

$$
\begin{align*}
\Delta^{m+s} \delta^{m-s} v & +\sum_{p=m-s+1}^{m-1} a_{p}^{\prime} d^{s+p-m} \Delta^{2 m-p} \delta^{p} v  \tag{9.20}\\
& =i \sum_{p=m-s+2}^{m-1} b_{p}^{\prime} d^{s+p-m-2} \Delta^{2 m-p+1} \delta^{p} v \quad\left(\bmod \nabla^{3 m+s-1} u\right) .
\end{align*}
$$

By the inductive hypothesis,

$$
\Delta^{m+k} \delta^{m-k} v=0 \quad\left(\bmod \nabla^{3 m+k-1} u\right) \text { for } 0 \leq k \leq s-1 .
$$

Setting $k=m-p$ here, we have

$$
\Delta^{2 m-p} \delta^{p} v=0 \quad\left(\bmod \nabla^{4 m-p-1} u\right) \text { for } m-s+1 \leq p \leq m-1 .
$$

Applying the operators $d^{s+p-m}$ and $d^{s+p-m-2} \Delta$ to this equation, we obtain

$$
\begin{aligned}
& d^{s+p-m} \Delta^{2 m-p} \delta^{p} v=0 \quad\left(\bmod \nabla^{3 m+s-1} u\right) \text { for } m-s+1 \leq p \leq m-1, \\
& d^{s+p-m-2} \Delta^{2 m-p+1} \delta^{p} v=0\left(\bmod \nabla^{3 m+s-1} u\right) \text { for } m-s+2 \leq p \leq m-1 .
\end{aligned}
$$

Both sums on $(9.20)$ are equal to zero $\left(\bmod \nabla^{3 m+s-1} u\right)$, as follows from the last two equations. Hence,

$$
\Delta^{m+s} \delta^{m-s} v=0 \quad\left(\bmod \nabla^{3 m+s-1} u\right)
$$

This coincides with (9.19) in the case of $k=s$. This completes the inductive step. Thus, (9.19) is proved.

Now we prove the equality

$$
\begin{equation*}
d^{m+2 r+k-1} \Delta^{2 m-r-k} \delta^{k} v=0 \quad\left(\bmod \nabla^{5 m-2} u\right) \text { for } 0 \leq r \leq 2 m, 0 \leq k \leq 2 m-r \tag{9.21}
\end{equation*}
$$

by double induction in $r$ and $k$.
Setting $k:=m-k$ in (9.19), we have

$$
\Delta^{2 m-k} \delta^{k} v=0 \quad\left(\bmod \nabla^{4 m-k-1} u\right) \text { for } 0 \leq k \leq m .
$$

Applying the operator $d^{m+k-1}$ to this equality, we obtain (9.21) for $r=0$.
Assume now (9.21) to be valid valid for $0 \leq r \leq s-1<2 m$, i.e.,

$$
\begin{equation*}
d^{m+2 r+k-1} \Delta^{2 m-r-k} \delta^{k} v=0 \quad\left(\bmod \nabla^{5 m-2} u\right) \text { for } 0 \leq r \leq s-1,0 \leq k \leq 2 m-r . \tag{9.22}
\end{equation*}
$$

We are going to prove (9.21) for $r=s$. To this end we write down (9.15) for $l=0$ (this is exactly (9.1)) as follows:

$$
(n+2 m-4) d^{m+1} v=i\left((m-1) d^{m} \delta v-d^{m-1} \Delta v\right) \quad\left(\bmod \nabla^{m} u\right) .
$$

Applying the operator $d^{2 s-2} \Delta^{2 m-s}$ to this equality, we obtain

$$
\begin{aligned}
& (n+2 m-4) d^{m+2 s-1} \Delta^{2 m-s} v \\
& \quad=i\left((m-1) d^{m+2 s-2} \Delta^{2 m-s} \delta v-d^{m-2 s-3} \Delta^{2 m-s+1} v\right) \quad\left(\bmod \nabla^{5 m-2} u\right)
\end{aligned}
$$

Setting $k=0$ and $r=s-1$ in (9.22), and then setting $k=1$ and $r=s-1$ in (9.22), we see that the right-hand side of the last formula equals zero $\left(\bmod \nabla^{5 m-2} u\right)$. We have thus proved (9.21) for $r=s$ and $k=0$.

Assume now (9.21) to be valid for $r=s$ and $0 \leq k \leq t-1<2 m-s$, i.e.,

$$
\begin{equation*}
d^{m+2 s+k-1} \Delta^{2 m-s-k} \delta^{k} v=0 \quad\left(\bmod \nabla^{5 m-2} u\right) \text { for } 0 \leq k \leq t-1 . \tag{9.23}
\end{equation*}
$$

We are going to prove (9.21) for $k=t$.
If $t \geq m$, then (9.21) is obviously true for $k=t$, since $\delta^{t} v=0$ in this case. Therefore we assume

$$
\begin{equation*}
t \leq \min (2 m-s, m-1) \tag{9.24}
\end{equation*}
$$

Recall also that

$$
\begin{equation*}
1 \leq s \leq 2 m . \tag{9.25}
\end{equation*}
$$

Let us write down (9.15) for $l=t$. By (9.24) and (9.25), this equation takes the form

$$
\begin{equation*}
\sum_{p=0}^{t} a_{p} d^{m-t+p+1} \Delta^{t-p} \delta^{p} v=i \sum_{p=0}^{p_{4}} b_{p} d^{m-t+p-1} \Delta^{t-p+1} \delta^{p} v \quad\left(\bmod \nabla^{m+t} u\right) \tag{9.26}
\end{equation*}
$$

where

$$
\begin{equation*}
p_{4}=\min (m-1, t+1) . \tag{9.27}
\end{equation*}
$$

According to Lemma 9.2, the coefficient $a_{t}$ in (9.26) is not zero. We distinguish the last summand on the left-hand side of (9.26) and apply the operator $d^{2 s+t-2} \Delta^{2 m-s-t}$ to this equation

$$
\begin{align*}
& d^{m+2 s+t-1} \Delta^{2 m-s-t} \delta^{t} v+\sum_{p=0}^{t-1} a_{p}^{\prime} d^{m+2 s+p-1} \Delta^{2 m-s-p} \delta^{p} v \\
& \quad=i \sum_{p=0}^{p_{4}} b_{p}^{\prime} d^{m+2 s+p-3} \Delta^{2 m-s-p+1} \delta^{p} v \quad\left(\bmod \nabla^{5 m-2} u\right) . \tag{9.28}
\end{align*}
$$

The sum on the left-hand side of (9.28) equals zero $\left(\bmod \nabla^{5 m-2} u\right)$ by the inductive hypothesis (9.23). We shall prove the same for the right-hand side.

Setting $r=s-1$ and $k=p$ in (9.22), we obtain

$$
\begin{equation*}
d^{m+2 s+p-3} \Delta^{2 m-s-p+1} \delta^{p} v=0 \quad\left(\bmod \nabla^{5 m-2} u\right) \text { for } 0 \leq p \leq 2 m-s+1 . \tag{9.29}
\end{equation*}
$$

Inequalities (9.24) and (9.27) imply $p_{4} \leq 2 m-s+1$. Therefore all the summands on the right-hand side of (9.28) are equal to zero ( $\bmod \nabla^{5 m-2} u$ ) according to (9.29). Hence, (9.28) implies

$$
d^{m+2 s+t-1} \Delta^{2 m-s-t} \delta^{t} v=0 \quad\left(\bmod \nabla^{5 m-2} u\right) .
$$

We have thus proved (9.23) for $k=t$. This completes the inductive step in $k$ and $r$. Thus, (9.21) is proved.

Setting $r=2 m$ and $k=0$ in (9.21), we obtain

$$
\begin{equation*}
d^{5 m-1} v=0 \quad\left(\bmod \nabla^{5 m-2} u\right) \tag{9.30}
\end{equation*}
$$

According to (1.3), we have $d u=0(\bmod v)$. Applying the operator $d^{5 m-2}$ to this equality, we deduce

$$
\begin{equation*}
d^{5 m-1} u=0 \quad\left(\bmod \nabla^{5 m-2} v\right) \tag{9.31}
\end{equation*}
$$

We write the initial conditions (1.4) in the form

$$
\begin{equation*}
u\left(x_{0}\right)=0, \quad \nabla u\left(x_{0}\right)=0, \quad \ldots, \quad \nabla^{6 m-2} u\left(x_{0}\right)=0 . \tag{9.32}
\end{equation*}
$$

From (9.3) and (9.32),

$$
\begin{equation*}
v\left(x_{0}\right)=0, \quad \nabla v\left(x_{0}\right)=0, \quad \ldots, \quad \nabla^{6 m-3} v\left(x_{0}\right)=0 . \tag{9.33}
\end{equation*}
$$

We have thus proved that $u$ and $v$ satisfy equations (9.30) and (9.31) and the initial conditions (9.32) and (9.33). Applying Lemma 7.4, we obtain $u \equiv v \equiv 0$ This finishes the proof of Theorem 1.1 in the case of $n \geq 3$.

Recall that the highest order of derivatives in the initial conditions (1.4) is denoted by $l(m)$. We have shown in the proof that

$$
l(m) \leq 6 m-2 \text { if } m>0 .
$$

As was mentioned after the statement of Theorem 1.1, this estimate is not sharp. The exact value $l(m)=2 m$ was found in [21] for $m=2$, and in $[1,6]$ for an arbitrary $m$. In the same papers, the upper bound

$$
\frac{(n+m-3)!(n+m-2)!(n+2 m-2)(n+2 m-1)(n+2 m)}{m!(m+1)!(n-2)!n!}
$$

was established for the dimension of the space of trace-free conformal Killing symmetric tensor fields of the rank $m$ on a manifold of dimension $n \geq 3$. Both the estimates are sharp and become equalities in the case of a conformal flat manifold.

## 10. Spherical harmonics Fourier series expansion of SOLUTION TO THE KINETIC EQUATION

Let $M$ be a Riemannian manifold. Recall the operator

$$
\lambda: C^{\infty}\left(S^{*} \tau^{\prime}\right) \rightarrow C^{\infty}(\Omega)
$$

was defined in Section 2. Let $H$ be the vector field on $T=T M$ which generates the geodesic flow. The field is expressed by (1.9) in local coordinates. The field is tangent to the submanifold $\Omega \subset T$ at points of the latter submanifold. Hence the field can be considered as a differential operator $H: C^{\infty}(\Omega) \rightarrow C^{\infty}(\Omega)$ on the submanifold.

Lemma 10.1. The following equality holds on $C^{\infty}\left(S^{*} \tau^{\prime}\right)$ :

$$
\begin{equation*}
\lambda d=H \lambda . \tag{10.1}
\end{equation*}
$$

Since $\lambda$ and $H$ are restrictions to $\Omega$ of some operators defined on $T$, it suffices to prove the equality

$$
\begin{equation*}
\varkappa d=H \varkappa, \tag{10.2}
\end{equation*}
$$

where $H$ is considered as an operator on $T$, and the operator $\varkappa: C^{\infty}\left(S^{*} \tau^{\prime}\right) \rightarrow C^{\infty}(T)$ has been defined in $\S 2$. The last equality can be easily checked by calculations in coordinates, and we omit the calculations.

Now, assume functions $U, F \in C^{\infty}(\Omega)$ to be linked by the kinetic equation

$$
\begin{equation*}
H U=F . \tag{10.3}
\end{equation*}
$$

From (10.3), we will deduce some equations that relate the Fourier series of the functions $U$ and $F$.

By Lemma 2.5, the functions $U$ and $F$ can be uniquely represented by the series

$$
\begin{array}{ll}
U=\sum_{m=0}^{\infty} \lambda u_{m}, & u_{m} \in C^{\infty}\left(S^{m} \tau^{\prime}\right), \\
F=\sum_{m=0}^{\infty} \lambda u_{m}=0  \tag{10.5}\\
F & f_{m} \in C^{\infty}\left(S^{m} \tau^{\prime}\right), \\
j f_{m}=0 .
\end{array}
$$

As well known [17], the Fourier series of a sufficiently smooth function on a sphere can be termwise differentiated with respect to the coordinates of a point of the sphere. The same is true for the differentiation with respect to the coordinates of a point $x \in M$ which play the role of parameters in the series. Hence, (10.4) implies

$$
\begin{equation*}
H U=\sum_{m=0}^{\infty} H \lambda u_{m} \tag{10.6}
\end{equation*}
$$

and the series converges absolutely and uniformly on any compact subset of $\Omega$.
According to Lemma 10.1, we have

$$
\begin{equation*}
H \lambda u_{m}=\lambda d u_{m} . \tag{10.7}
\end{equation*}
$$

The condition $j u_{m}=0$ is equivalent to $p u_{m}=u_{m}$. The last equality and Lemma 3.4 imply

$$
d u_{m}=d p u_{m}=p d u_{m}+\frac{m}{n+2 m-2} i \delta p u_{m}=p d u_{m}+\frac{m}{n+2 m-2} i \delta u_{m}
$$

Apply the operator $\lambda$ to this equality and use Lemma 2.4 to obtain

$$
\lambda d u_{m}=\lambda p d u_{m}+\frac{m}{n+2 m-2} \lambda \delta u_{m} .
$$

Comparing this formula with (10.7), we see

$$
H \lambda u_{m}=\lambda p d u_{m}+\frac{m}{n+2 m-2} \lambda \delta u_{m} .
$$

Substitute this expression into (10.6) to obtain

$$
\begin{equation*}
H U=\sum_{m=0}^{\infty} \lambda\left(p d u_{m-1}+\frac{m+1}{n+2 m} \delta u_{m+1}\right) \tag{10.8}
\end{equation*}
$$

For convenience, we assume here $u_{-1}=0$. The expression in parentheses in (10.8) belongs to the kernel of $j$ since $\delta$ and $j$ commute. Hence, (10.8) is the Fourier series of the function $H U=F$ with respect to the spherical harmonics, i.e., (10.8) must coincide with (10.5). We have thus proved the following

Theorem 10.2. Let $U \in C^{\infty}(\Omega)$ be a solution to the kinetic equation $H U=F$, and let (10.4) and (10.5) be the spherical Fourier series of $U$ and $F$, respectively. Then

$$
\begin{aligned}
\delta u_{1} & =n f_{0}, \\
p d u_{m}+\frac{m+2}{n+2 m+2} \delta u_{m+2} & =f_{m+1} \quad \text { for } m=0,1,2, \ldots,
\end{aligned}
$$

where $n=\operatorname{dim} M$.

## 11. Proof of THeorem 1.1 in the two-dimensional case

We assume here $n=\operatorname{dim} M=2$. As well known, an isothermic coordinate system $(x, y)$ exists in some neighborhood of every point of a two-dimensional Riemannian manifold. In such a coordinate system, the Riemannian metric has the form

$$
\begin{equation*}
d s^{2}=e^{2 \mu(x, y)}\left(d x^{2}+d y^{2}\right) \tag{11.1}
\end{equation*}
$$

It suffices to prove Theorem 1.1 under the assumption that such a coordinate system is defined on the whole of $M$.

Define the coordinate system $(x, y, \theta)$ on the three-dimensional manifold $\Omega$ such that $\theta$ is the angle between the unit vector $\xi \in \Omega$ and the coordinate line $y=$ const. The spherical harmonics series expansion of a function $U(x, y, \theta) \in C^{\infty}(\Omega)$ coincides with the Fourier
series with respect to $\theta$. Hence the next statement is a particular case of Lemma 2.5 (cf. the remark after statement of the lemma).

Lemma 11.1. Let $u \in C^{\infty}\left(S^{m} \tau^{\prime}\right)$ and let

$$
(\lambda u)(x, y, \theta)=\frac{1}{2} a_{0}(x, y)+\sum_{k=1}^{m}\left(a_{k}(x, y) \cos k \theta+b_{k}(x, y) \sin k \theta\right)
$$

be the Fourier series of the function $\lambda u \in C^{\infty}(\Omega)$. Then

$$
(\lambda p u)(x, y, \theta)=a_{m}(x, y) \cos m \theta+b_{m}(x, y) \sin m \theta
$$

Assume $u$ and $v$ to satisfy the hypotheses of Theorem 1.1. The assumption $j u=0$ is equivalent to $p u=u$. Then, according to Lemma 11.1, there exist functions $a, b \in C^{\infty}(M)$ such that

$$
\begin{equation*}
(\lambda u)(x, y, \theta)=a(x, y) \cos m \theta+b(x, y) \sin m \theta . \tag{11.2}
\end{equation*}
$$

The condition $d u=i v$ is equivalent to $p d u=0$. According to Lemma 11.1, this means that the Fourier series of the function $\lambda d u$ does not contain the harmonics of order $m+1$. Due to Lemma 10.1, we have $\lambda d u=H \lambda u$. Hence the coefficients at $\cos (m+1) \theta$ and $\sin (m+1) \theta$ in the Fourier series of the function $H \lambda u$ are equal to zero identically in $(x, y)$.

The operator $H$ has the following form in the coordinates $(x, y, \theta)$ :

$$
\begin{equation*}
H=e^{-\mu}\left(\cos \theta \frac{\partial}{\partial x}+\sin \theta \frac{\partial}{\partial y}+\left(-\mu_{x} \sin \theta+\mu_{y} \cos \theta\right) \frac{\partial}{\partial \theta}\right) \tag{11.3}
\end{equation*}
$$

This can be derived from (1.9) and (11.1) by a direct calculation that is omitted.
Now, we express $H \lambda u$ in terms of $a$ and $b$ using (11.2) and (11.3), and then expand $H \lambda u$ in the Fourier series in $\theta$. Equating to zero the coefficients of the series at $\cos (m+1) \theta$ and $\sin (m+1) \theta$, we arrive to the following equations:

$$
\begin{align*}
& a_{x}-b_{y}-m\left(\mu_{x} a-\mu_{y} b\right)=0,  \tag{11.4}\\
& a_{y}+b_{x}-m\left(\mu_{y} a+\mu_{x} b\right)=0 .
\end{align*}
$$

Introducing the notation

$$
z=x+i y, \quad w=a+i b, \quad \frac{\partial}{\partial \bar{z}}=\frac{1}{2}\left(\frac{\partial}{\partial x}+i \frac{\partial}{\partial y}\right)
$$

we write (11.4) in the complex form

$$
\frac{\partial}{\partial \bar{z}}\left(e^{-m \mu} w\right)=0
$$

So, $e^{-m \mu} w$ is a holomorphic function. According to the hypotheses of Theorem 1.1, this function vanishes together with all its derivatives at some point. Hence it is identically zero. Now, (11.2) shows that $\lambda u \equiv 0$. Hence, $u \equiv 0$ and Theorem 1.1. is proved.

## Acknowledgments

The authors are indebted to R. Graham and M. Eastwood for discussions, and to W. Lionheart who has done a series of comments to the manuscript of the paper.

## References

[1] Čap A. Overdetermined systems, conformal differential geometry, and the BCG complex, arXiv:math/0610225v1 [math.DG]
[2] Case K. and Zweifel P. Linear Transport Theory. Addison-Wesely Publ. Co., 1967.
[3] Croke C. B., Sharafutdinov V. A. Spectral rigidity of a negatively curved manifold, Topology 37 (1998) 1265-1273.
[4] N. S. Dairbekov and G. P. Paternain, "Rigidity properties of Anosov optical hypersurfaces," Ergodic Theory Dyn. Syst. 28 (3), 707-737 (2008).
[5] N. S. Dairbekov and G. P. Paternain, "On the cohomological equation of magnetic flows," arXiv:0807.4602v1 [math.DS].
[6] Eastwood M. Higher symmetries of the Laplacian. Annals of Mathematics 161 (2005), no. 3, 16451665.
[7] Edgar S., Rani R., and Barnes A. Irreducible Killing tensors from conformal Killing vectors. Proccedings of Institute of Mathematics of NAS of Ukraine. 50 (2004), part 2, 708-714.
[8] Geroch R. Multipole moments. I. Flat space J. Math. Physics. 11 (1970), no. 6, 1955-1961.
[9] Guillemin V., Kazhdan D. Some inverse spectral results for negatively curved $n$-manifolds. Geometry of the Laplace Operator (Proc. Sympos. Pure Math., Univ. Hawaii, Honolulu, Hawaii, 1979), Proc. Sympos. Pure Math., XXXVI, Amer. Math. Soc., Providence, R.I. (1980), 153-180.
[10] Jezierski J. and Lukasik M. Conformal Yano-Killing tensor for the Kerr metric and conserved quantities, arXiv:gr-qc/0510058v2.
[11] Kobayashi S. Transformation Groups in Differential Geometry. Berlin, New York, Springer-Verlag, 1972.
[12] Lionheart W. Conformal uniqueness results in anisotropic electrical impedance tomography. Inverse Problems 13 (1997), 125-134.
[13] Mikhailov A. Notes on higher spin symmetries, arXiv:hep-th/0201019.
[14] Sharafutdinov V. On symmetric tensor fields on a Riemannian manifold. Preprint 539 (1984) of the Computer Center of the Siberian Division of the USSR Academy of Sciences [in Russian].
[15] Sharafutdinov V. Integral Geometry of Tensor Fields. VSP, Utrecht, the Netherlands, 1994.
[16] Sharafutdinov V. Variations of Dirichlet-to-Neumann map and deformation boundary rigidity of simple 2-manifolds. J. of Geometrical Analysis, 17 (2007), no. 1, 187-227.
[17] Sobolev S.L. Introduction to Theory of Cubature Formulas. Nauka, Moscow (1974) [in Russian].
[18] Stepanov S. The vector space of conformal Killing forms on a Riemannian manifold. Zap. Nauchn. Sem. S.-Petersburg Otdel. Mat. Inst. Steklov (POMI). 261 (1999), Geom. i Topol. 4, 240-265 [in Russian]. Transl. in J. Math. Sci. (New York), 110, no. 4, 2892-2905.
[19] Taylor M. Partial Differential Equations I. Springer, New York, 1997.
[20] Vasiliev M. A. Cubic interactions of Bosonic higher spin gauge fields in $A d S_{5}$, arXiv:hep-th/0106200.
[21] Weir G. Conformal Killing tensors in reducible space. Mathematische Zeitschrift. 245 (2003), 503527.
[22] K. Yano and C. Bochner, Curvature and the Betti Numbers (Princeton Univ. Press, Princeton, 1953).

Kazakh-British Technical University, Almaty, 050000 Kazakhstan
E-mail address: Nurlan.Dairbekov@gmail.com
Sobolev Institute of Mathematics, Novosibirsk, 630090 Russia
E-mail address: sharaf@math.nsc.ru

