## ON CONTACT METRIC MANIFOLDS

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- 1. Introduction. Blair has proven ([1]) that there are no contact metric manifolds of vanishing curvature and of dimension  $\geq 5$ . Generalizing this result we prove in the present paper that any contact metric manifold of constant sectional curvature and of dimension  $\geq 5$  has the sectional curvature equal to 1 and is a Sasakian manifold. Moreover we give some restrictions on the scalar curvature in contact metric manifolds which are conformally flat or of constant  $\phi$ -sectional curvature.
- 2. Preliminaries. Throughout this paper we use the notations and terminology of [1], [2].

Let M be a (2n+1)-dimensional contact metric manifold and  $(\phi, \xi, \eta, g)$  be its contact metric structure. Thus, we have

$$\phi^2=-I+\eta\otimes\xi$$
 ,  $\phi\xi=0$  ,  $\eta\circ\phi=0$  ,  $\eta(\xi)=1$  ,  $g(\phi X,\phi Y)=g(X,Y)-\eta(X)\eta(Y)$  ,  $g(X,\xi)=\eta(X)$  ,  $arPhi(X,Y)=g(X,\phi Y)=d\eta(X,Y)$  .

Define an operator h by  $h=(1/2)\mathscr{L}_{\ell}\phi$ , where  $\mathscr{L}$  denotes Lie differentiation. The vector field  $\xi$  is Killing if and only if h vanishes. Blair has shown ([1], [2]) that h and  $\phi h$  are symmetric operators, h anti-commutes with  $\phi$  (i.e.,  $\phi h + h\phi = 0$ ),  $h\xi = 0$  and  $\eta \circ h = 0$ . Using a  $\phi$ -basis, i.e., an orthonormal frame  $\{E_i, E_{i+n} = \phi E_i, E_{2n+1} = \xi\}$   $(i=1, \cdots, n)$ , one can easily verify that  $\operatorname{tr} h = 0$  and  $\operatorname{tr} \phi h = 0$ . In [1], [2] the following general formulas for a contact metric manifold were obtained

$$(2.1) V_X \xi = -\phi X - \phi h X,$$

$$(2.2)$$
  $(1/2)(R_{\xi X}\xi - \phi R_{\xi \phi X}\xi) = h^2 X + \phi^2 X$  ,

$$(2.3) g(Q\xi,\xi) = 2n - \operatorname{tr} h^2,$$

where  $R_{xy} = [\mathcal{V}_x, \mathcal{V}_y] - \mathcal{V}_{[x,y]}$  is the curvature transformation and Q is the Ricci curvature operator. Finally, we note that  $d\Phi = d^2\eta = 0$  implies

(2.4) 
$$(\nabla_X \Phi)(Y, Z) + (\nabla_Y \Phi)(Z, X) + (\nabla_Z \Phi)(X, Y) = 0$$
.

3. Auxiliary results. First of all, using (2.1) we can easily obtain the following relations

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(3.1) 
$$(\mathcal{V}_{X}\Phi)(\phi Y, Z) - (\mathcal{V}_{X}\Phi)(Y, \phi Z) = -\eta(Y)g(X + hX, \phi Z)$$
$$-\eta(Z)g(X + hX, \phi Y) ,$$

$$\begin{split} (3.2) \qquad & (\mathcal{V}_{\mathbf{X}} \varPhi)(\phi \, Y, \, \phi \mathbf{Z}) \, + \, (\mathcal{V}_{\mathbf{X}} \varPhi)(\, Y, \, \mathbf{Z}) \, = \, \eta(\, Y) g(\mathbf{X} \, + \, h\mathbf{X}, \, \mathbf{Z}) \\ & - \eta(\mathbf{Z}) g(\mathbf{X} \, + \, h\mathbf{X}, \, \mathbf{Y}) \, \, . \end{split}$$

LEMMA 3.1. Any contact metric manifold satisfies the conditions

$$(3.3) \qquad (V_{\phi X}\phi)\phi Y + (V_X\phi)Y = 2g(X, Y)\xi - \eta(Y)(X + hX + \eta(X)\xi),$$

$$(3.4)(a)$$
  $\sum_{i=1}^{2n+1} (V_{E_i} \phi) E_i = 2n \xi$  ,

$$(3.4)(\mathrm{b})$$
  $\sum_{\iota=1}^{2n+1}({\mathcal V}_{E_{\iota}}\phi)\phi E_{\iota}=0$  ,

where  $\{E_1, \dots, E_{2n+1}\}$  is an orthonormal frame.

PROOF. Making use of the identity (2.4) we can write

$$\begin{split} & ( \textit{V}_{\textit{X}} \varPhi)(\textit{Y}, \textit{Z}) + ( \textit{V}_{\textit{Y}} \varPhi)(\textit{Z}, \textit{X}) + ( \textit{V}_{\textit{Z}} \varPhi)(\textit{X}, \textit{Y}) \\ & + ( \textit{V}_{\phi \textit{X}} \varPhi)(\phi \textit{Y}, \textit{Z}) + ( \textit{V}_{\phi \textit{Y}} \varPhi)(\textit{Z}, \phi \textit{X}) + ( \textit{V}_{\textit{Z}} \varPhi)(\phi \textit{X}, \phi \textit{Y}) \\ & + ( \textit{V}_{\phi \textit{X}} \varPhi)(\textit{Y}, \phi \textit{Z}) + ( \textit{V}_{\textit{Y}} \varPhi)(\phi \textit{Z}, \phi \textit{X}) + ( \textit{V}_{\phi \textit{Z}} \varPhi)(\phi \textit{X}, \textit{Y}) \\ & - ( \textit{V}_{\textit{X}} \varPhi)(\phi \textit{Y}, \phi \textit{Z}) - ( \textit{V}_{\phi \textit{Y}} \varPhi)(\phi \textit{Z}, \textit{X}) - ( \textit{V}_{\phi \textit{Z}} \varPhi)(\textit{X}, \phi \textit{Y}) = 0 \; . \end{split}$$

Hence in virtue of (3.1) and (3.2) we obtain

$$egin{aligned} (\emph{V}_{\phi X} \varPhi)(\emph{Z},\, \phi \, \emph{Y}) &+ (\emph{V}_{\it X} \varPhi)(\emph{Z},\, \emph{Y}) &= 2\eta(\emph{Z})g(\emph{X},\, \emph{Y}) \ &- \eta(\emph{Y})g(\emph{X} + \emph{h}\emph{X},\, \emph{Z}) - \eta(\emph{X})\eta(\emph{Y})\eta(\emph{Z}) \;, \end{aligned}$$

which is equivalent to (3.3). Choose a  $\phi$ -basis. As from (3.3) follows  $V_{\varepsilon}\phi = 0$ , we can find (3.4) (a), (b) by using (3.3).

LEMMA 3.2. The curvature tensor of a contact metric manifold satisfies the relations

$$(3.5) \quad g(R_{\rm EX}Y,\,Z) = -({\it V}_{\rm X}\Phi)(Y,\,Z) - g(X,\,({\it V}_{\rm Y}\phi h)Z) \,+\, g(X,\,{\it V}_{\rm Z}\phi h)\,Y) \;\text{,}$$

$$(3.6) g(R_{\varepsilon X}Y, Z) - g(R_{\varepsilon X}\phi Y, \phi Z) + g(R_{\varepsilon\phi X}Y, \phi Z) + g(R_{\varepsilon\phi X}\phi Y, Z)$$

$$= 2(\mathcal{V}_{hX}\Phi)(Y, Z) - 2\eta(Y)g(X + hX, Z) + 2\eta(Z)g(X + hX, Y).$$

PROOF. Let X, Y, Z be tangent vectors at a point  $m \in M$ . By the same letters we denote their extensions to local vector fields. From (2.1) we have

$$R_{vz}\xi = -(\nabla_v\phi)Z + (\nabla_z\phi)Y - (\nabla_v\phi h)Z + (\nabla_z\phi h)Y$$
.

This yields (3.5) in virtue of (2.4). Denote

$$\begin{split} A(X,\ Y,\ Z) &= -(\mathbb{V}_{\scriptscriptstyle X} \varPhi)(Y,\ Z) \,+\, (\mathbb{V}_{\scriptscriptstyle X} \varPhi)(\phi\,Y,\,\phi Z) \,-\, (\mathbb{V}_{\phi \scriptscriptstyle X} \varPhi)(Y,\,\phi Z) \\ &-\, (\mathbb{V}_{\phi \scriptscriptstyle X} \varPhi)(\phi\,Y,\ Z) \,\,, \\ B(X,\ Y,\ Z) &= -g(X,\, (\mathbb{V}_{\scriptscriptstyle Y} \phi h)Z) \,+\, g(X,\, (\mathbb{V}_{\phi \scriptscriptstyle Y} \phi h)\phi Z) \,-\, g(\phi X,\, (\mathbb{V}_{\scriptscriptstyle Y} \phi h)\phi Z) \\ &-\, g(\phi X,\, (\mathbb{V}_{\scriptscriptstyle \delta \scriptscriptstyle Y} \phi h)Z) \,\,. \end{split}$$

In view of (3.5) the left hand side of (3.6) equals A(X, Y, Z) + B(X, Y, Z) - B(X, Z, Y). By (3.2) and (3.3) we obtain

$$A(X, Y, Z) = 2g(X, Y)\eta(Z) - 2g(X, Z)\eta(Y)$$
.

Rewrite B in the following form

$$egin{aligned} B(X,\ Y,\ Z) &= -g(X,\ (
abla_{_Y}\phi)hZ) + g(X,\ h(
abla_{_Y}\phi)Z) + g(X,\ h\phi(
abla_{_{\phi Y}}\phi)Z) \ + g(X,\ \phi(
abla_{_{\phi Y}}\phi)hZ) + \eta(X)\eta((
abla_{_{\phi Y}}h)Z) \ . \end{aligned}$$

We have

$$(3.7) \qquad \phi({\cal V}_{\phi_X}\phi)\,Y=2\eta(\,Y)X-g(X+\,hX,\,\,Y)\xi\,-\,\eta(X)\eta(\,Y)\xi\,+\,({\cal V}_{_X}\phi)\,Y\;.$$
 In fact

$$\begin{split} \phi(\vec{r}_{\phi X}\phi)\,Y &= (\vec{r}_{\phi X}\phi^2)\,Y - (\vec{r}_{\phi X}\phi)\phi\,Y \\ &= (\vec{r}_{\phi X}\eta)(\,Y)\xi \,+\, \eta(\,Y)\vec{r}_{\phi X}\xi \,-\, (\vec{r}_{\phi X}\phi)\phi\,Y\;, \end{split}$$

from which, by (2.1) and (3.3), we find (3.7). Moreover, remembering (2.1), we get

$$\eta((\mathcal{V}_{\phi Y}h)Z) = -(\mathcal{V}_{\phi Y}\eta)(hZ) = g(-Y + hY, hZ)$$
 .

Thus, we obtain in virtue of (3.7)

$$B(X,~Y,~Z)=2g(hX,~({\it V}_{Y}\phi)Z)+2\eta(Z)g(hX,~Y)-2\eta(X)g(~Y,~hZ)$$
 . Therefore

$$egin{aligned} A(X,\ Y,\ Z) &+ B(X,\ Y,\ Z) - B(X,\ Z,\ Y) \ &= -2(arPsi_{_{Y}}arPhi)(Z,\ hX) - 2(arPsi_{_{Z}}arPhi)(hX,\ Y) - 2\eta(\ Y)g(X+\ hX,\ Z) \ &+ 2\eta(Z)g(X+\ hX,\ Y) \ , \end{aligned}$$

which in view of (2.4) equals the right hand side of (3.6). Thus the proof is complete.

Denote by S the scalar curvature of M and define  $S^* = \sum_{i,j=1}^{2n+1} g(R_{E_iE_j}\phi E_j, \phi E_i)$ , where  $\{E_i\}$  is an orthonormal frame.

LEMMA 3.3. For any contact metric manifold M we have

$$(3.8) \hspace{1cm} S^* - S + 4n^2 = \operatorname{tr} h^2 + (1/2)\{|| \digamma \phi ||^2 - 4n\} \geqq 0 \; .$$

Moreover M is Sasakian if and only if  $||\nabla \phi||^2 = 4n$  or equivalently  $S^* - S + 4n^2 = 0$ .

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PROOF. Let  $\{E_1, \dots, E_{2n+1}\}$  be a frame in  $M_m$ . By the same letters we denote local extension vector fields of this frame which are orthonormal and covariant constant at  $m \in M$ . Now (3.4) (a) and (2.1) become

(3.9) 
$$\sum_{i,j=1}^{2n+1} g((V_{E_j}V_{E_i}\phi)E_i, \phi E_j) = -4n^2$$

because  $\operatorname{tr} h = 0$ . On the other hand, by (3.4) (b), we obtain

$$(3.10) -\sum_{i,j=1}^{2n+1} g((V_{E_i}V_{E_j},\phi)E_i,\phi E_j) = \sum_{i,j=1}^{2n+1} g((V_{E_i}\phi)E_j,(V_{E_j}\phi)E_i) .$$

But the right hand side of (3.10) can be transformed as follows

$$egin{aligned} \sum_{i,j,k=1}^{2n+1} g(({m V}_{E_i}\phi)E_j,\ E_k)g(({m V}_{E_j}\phi)E_i,\ E_k) \ &= (1/2)\sum_{i,j,k=1}^{2n+1} \{g(({m V}_{E_i}\phi)E_j,\ E_k)\}^2 = (1/2)\sum_{i,j=1}^{2n+1} ||\ ({m V}_{E_i}\phi)E_j||^2 = (1/2)||{m V}\phi||^2 \end{aligned}$$

in virtue of (2.4). Considering (3.9), (3.10) and the last relation we get

$$\sum_{i,\,j=1}^{2n+1} g((R_{E_jE_i}\phi)E_i,\,\phi E_j) = (1/2)|| extstyle \phi||^2 - 4n^2$$
 .

Hence  $S^* - S + g(Q\xi, \xi) = (1/2)||\nabla \phi||^2 - 4n^2$ , which with the help of (2.3) proves the equality part of (3.8).

Recall that M is Sasakian if and only if  $(\nabla_X \phi) Y = g(X, Y) \xi - \eta(Y) X$ . Consequently, we always have, for a contact metric manifold M,

$$\sum\limits_{i,\,j=1}^{2n+1} \mid\mid ({m arPi}_{E_i}\phi)E_j \,-\, g(E_{\iota},\,E_j)\xi \,+\, \eta(E_j)E_i \mid\mid^2 \,\geqq\, 0$$
 ,

where equality holds if and only if M is Sasakian. By using (3.4) (a) it can be easily shown that the last condition is equivalent to  $||V\phi||^2 - 4n \ge 0$ , where equality holds only in the Sasakian case. Note that from the symmetry of the operator h it follows that  $\operatorname{tr} h^2 \ge 0$  and  $\operatorname{tr} h^2 = 0$  if and only if h = 0. Recall also that on a Sasakian manifold the vector field  $\xi$  is Killing. Therefore, if M is Sasakian, then h vanishes. The above remarks complete the proof of our lemma.

## 4. Main results.

THEOREM 4.1. If a contact metric manifold M is of constant sectional curvature and dim  $M \ge 5$ , then the sectional curvature of M is equal to 1 and M is Sasakian.

PROOF. Let c be the constant sectional curvature of M, i.e.,  $R_{XY}Z = c\{g(Y,Z)X - g(X,Z)Y\}$ . Under this assumption, from (2.2) we obtain  $h^2X = (c-1)\phi^2X$ , hence tr  $h^2 = 2n(1-c)$ . Moreover, (3.6) yields

(4.1) 
$$(\nabla_{hX}\Phi)(Y,Z) = (1-c)\{\eta(Y)g(X,Z) - \eta(Z)g(X,Y)\}$$
$$+ \eta(Y)g(hX,Z) - \eta(Z)g(hX,Y) .$$

Now let us suppose that  $c \neq 1$ . Taking in (4.1) hX instead of X, we have

$$(
abla_{\scriptscriptstyle X}\phi)\,Y=g(X+hX,\;Y)\xi-\eta(Y)(X+hX)$$
 ,

as  $V_{\epsilon}\phi=0$ . From this we find  $||V\phi||^2=4n(2-c)$ . The last relation and equalities S=2n(2n+1)c,  $S^*=2nc$  applied to (3.8) give n=1, a contradiction. Therefore c=1. But in this case, by Lemma 3.3, the manifold M is Sasakian.

THEOREM 4.2. Let M be a conformally flat contact metric manifold with dim  $M \ge 5$ . Then the scalar curvature S of M satisfies  $S \le 2n(2n+1)$ . Moreover, M is Sasakian if and only if S = 2n(2n+1).

PROOF. Conformal flatness yields

$$(4.2) \quad R_{XY}Z = (1/(2n-1)) \Big\{ g \Big( Q\, Y - \frac{S}{2n}\, Y, \, Z \Big) X \, - \, g \Big( QX - \frac{S}{2n}X, \, Z \Big) Y \\ \\ + g(\,Y, \, Z) QX - g(X, \, Z) Q\, Y \Big\} \; .$$

Using the relations (2.3) and (4.2) we compute  $S^* = (1/(2n-1))\{S-2(2n-\operatorname{tr} h^2)\}$ . Then, from (3.8) one can obtain

$$(4.3) \quad (2n-1)\{|| ilde{ au}\phi||^2-4n\}+2(2n-3) \ {
m tr} \ h^2=2(2n-2)\{2n(2n+1)-S\}$$
 , which completes the proof.

REMARK 4.1. Any 3-dimensional contact metric manifold M satisfies the condition (4.2) and therefore (4.3), i.e.,  $||\nabla \phi||^2 - 4n = 2 \operatorname{tr} h^2$ . This shows that M is Sasakian if and only if the vector field  $\xi$  is Killing (cf. [6], [3]).

REMARK 4.2. As is known, any conformally flat contact metric manifold with Killing structure vector field  $\xi$  is of constant curvature (cf. [5], [4]). Then by Theorem 4.2 any conformally flat contact metric manifold M with dim  $M \geq 5$  and the scalar curvature S = 2n(2n+1) is of constant sectional curvature.

In the next theorem we consider a contact metric manifold of constant  $\phi$ -sectional curvature, that is, a manifold M such that at any point  $m \in M$  the sectional curvature  $K(X, \phi X)$  (denote it by  $H_m$ ) is independent of the choice of the tangent vector  $X \in M_m$ ,  $0 \neq X \perp \xi$ . By H we denote the  $\phi$ -sectional curvature of M, i.e.,  $H: M \to R$ ,  $H(m) = H_m$ .

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THEOREM 4.3. Let M be a contact metric manifold of constant  $\phi$ -sectional curvature. Then the scalar curvature S and the  $\phi$ -sectional curvature H satisfy the inequality  $n(n+1)H+3n^2+n \geq S$ . Equality holds if and only if M is Sasakian.

PROOF. By our assumption we have  $g(R_{X \neq X} X, \phi X) + H_m ||X||^4 = 0$  at any point  $m \in M$  and for any  $X \in M_m$ ,  $X \perp \xi$ . It is clear that this condition implies

(4.4) 
$$g(R_{\phi X \phi^2 X} \phi X, \phi^2 X) + H_m ||\phi X||^4 = 0$$

at any point  $m \in M$  and for any  $X \in M_m$ . Set

$$P(X, Y, Z, W) = g(R_{\phi X \phi^2 Y} \phi Z, \phi^2 W) + H_m g(\phi X, \phi Z) g(\phi Y, \phi W)$$
.

The tensor P satisfies P(X, Y, Z, W) = P(Z, W, X, Y). Therefore (4.4) is equivalent to

$$(4.5) \quad P(X, Y, Z, W) + P(X, Y, W, Z) + P(Y, X, Z, W) + P(Y, X, W, Z) \\ + P(X, W, Y, Z) + P(X, W, Z, Y) + P(W, X, Y, Z) + P(W, X, Z, Y) \\ + P(X, Z, Y, W) + P(X, Z, W, Y) + P(Z, X, Y, W) \\ + P(Z, X, W, Y) = 0.$$

Choosing a  $\phi$ -basis, taking  $X=W=E_i$ ,  $Y=Z=E_j$  into (4.5) and summing over i and j we obtain

$$\sum\limits_{i,j=1}^{2n+1}\{P(E_i,\,E_j,\,E_i,\,E_i)\,+\,P(E_i,\,E_j,\,E_i,\,E_j)\,+\,P(E_i,\,E_i,\,E_j,\,E_j)\}=0$$
 ,

which by the definition of P, the first Bianchi identity and (2.3) gives

$$4n(n+1)H - 3S^* - S + 2(2n - \operatorname{tr} h^2) = 0$$
.

Comparing the last identity with (3.8) we obtain

$$n(n+1)H + 3n^2 + n - S = (5/4) \operatorname{tr} h^2 + (3/8)\{||\nabla \phi||^2 - 4n\}$$

which completes the proof.

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