ON EQUIDISTANT CUBIC SPLINE INTERPOLATION

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Let *n* be a natural number and let S[0, n] denote the class of cubic spline functions S(x) defined in the interval [0, n] and having the points $1, \dots, n-1$ as knots. This means that the restriction of S(x) to the inverval $(\nu, \nu+1)$ $(\nu=0, \dots, n-1)$ is a cubic polynomial, and that $S(x) \in C^2[0, n]$. The most general element of S[0, n] is evidently of the form

(1)
$$S(x) = \sum_{0}^{3} a_{\nu}x^{\nu} + \sum_{1}^{n-1} c_{\nu}(x-\nu)^{3}_{+},$$

and is seen to depend linearly on n+3 parameters. Here we have used the function $x_{+} = \max(0, x)$.

The interpolatory properties of the elements of the class S[0, n] have recently attracted considerable attention. The two main kinds of this so-called *cubic spline interpolation* are as follows.

1. Natural cubic spline interpolation. We are required to find $S(x) \in S[0, n]$ such as to satisfy the conditions

(2) $S(\nu) = f(\nu)$ $(\nu = 0, \dots, n),$

(3)
$$S''(0) = S''(n) = 0.$$

2. Complete cubic spline interpolation. Here we are asked to find $\tilde{S}(x) \in S[0, n]$ so as to satisfy the conditions

(4)
$$\tilde{S}(\nu) = f(\nu) \qquad (\nu = 0, \cdots, n),$$

(5)
$$\tilde{S}'(0) = f'(0), \quad \tilde{S}'(n) = f'(n).$$

The existence and unicity of the solutions of these problems is widely known. See [1], [2], or [5, Chapter 4] for illuminating discussions of these problems.

We may describe the solution of the first problem (2), (3) by the interpolation formula

(6)
$$f(x) = \sum_{0}^{n} f(v) L_{\nu}(x) + R,$$

where the fundamental functions $L_{\nu}(x)$ are elements of S[0, n] and

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are characterized by the conditions

(7)
$$L_{\nu}(j) = \delta_{\nu,j}$$
 and $L_{\nu}''(0) = L_{\nu}''(n) = 0$ for all ν .

Likewise the solution of the second problem (4), (5) is described by the formula

(8)
$$f(x) = \sum_{0}^{n} f(\nu) \tilde{L}_{\nu}(x) + f'(0)\Lambda(x) - f'(n)\Lambda(n-x) + R,$$

where the fundamental functions $\tilde{L}_{r}(x)$ and $\Lambda(x)$ are elements of S[0, n] and are characterized by the conditions

(9)
$$\widetilde{L}_{\nu}(j) = \delta_{\nu,j}, \qquad \widetilde{L}'_{\nu}(0) = \widetilde{L}'_{\nu}(n) = 0 \quad \text{for all } \nu,$$

and

(10)
$$\Lambda(j) = 0 \quad \text{for all } j, \quad \Lambda'(0) = 1, \quad \Lambda'(n) = 0.$$

Until now, the solution of these problems, i.e. the construction of the interpolating spline function, has usually required the inversion of a matrix (essentially a tridiagonal matrix) of a size that was roughly $n \times n$. It is the purpose of this note to describe explicit solutions of these problems that do not require any matrix inversion.

Let $M_1(x) = 1$ if $-\frac{1}{2} \le x \le \frac{1}{2}$, and $M_1(x) = 0$ otherwise. The 4-fold convolution $M(x) = M_4(x) = M_1 * M_1 * M_1 * M_1(x)$ is a bell-shaped frequency function with its support in the interval (-2, +2). Explicitly

(11)
$$\begin{array}{l} M(x) = M_4(x) \\ = \frac{1}{6} \{ (x+2)^3_+ - 4(x+1)^3_+ + 6x^3_+ - 4(x-1)^3_+ + (x-2)^3_+ \}, \end{array}$$

an expression which shows that M(x) is a cubic spline function defined for all real x and having knots at the five points -2, -1, 0, 1, 2. See [6, 71], where a graph of M(x) is also given.

A relevant property of the function M(x), called the *cubic B-spline* is expressed by the following:

LEMMA 1. Every $S(x) \in S[0, n]$ admits a unique representation of the form

(12)
$$S(x) = \sum_{j=1}^{n+1} C_j M(x-j) \qquad (0 \le x \le n).$$

Our interpolation problems are solved as soon as we determine the coefficients of the representations

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(13)
$$L_{\nu}(x) = \sum_{-1}^{n+1} c_{j,\nu} M(x-j),$$

(14)
$$\tilde{L}_{p}(x) = \sum_{-1}^{n+1} \tilde{c}_{j,p} M(x-j),$$

(15)
$$\Lambda(x) = \sum_{j=1}^{n+1} \gamma_j M(x-j),$$

and therefore

(16)
$$-\Lambda(n-x) = -\sum_{j=1}^{n+1} \gamma_{n-j} M(x-j)$$

for the last fundamental function in (8).

We need the algebraic integer

(17)
$$\lambda = -2 + \sqrt{3} = -.26794\ 91924,$$

which is the root of least absolute value of the equation $x^2+4x+1=0$. Furthermore, let

(18)
$$\lambda^k = a_k + b_k \sqrt{3}$$
 for all integers k_j

where a_k and b_k are integers. The expressions

(19)
$$a_k = \frac{1}{2}(\lambda^k + \lambda^{-k}), \qquad b_k = \frac{1}{2\sqrt{3}}(\lambda^k - \lambda^{-k})$$

show that both sequences (a_k) and (b_k) satisfy the same recurrence relation

 $x_{k+2} + 4x_{k+1} + x_k = 0$ for all k,

and are defined by it with the initial values

$$a_0 = 1$$
, $a_1 = -2$, and $b_0 = 0$, $b_1 = 1$,

respectively. The sequence (a_k) is even, while the sequence (b_k) is odd. A short table of values is as follows:

k	-1	0	1	2	3	4	5	6
							-362 209	

Incidentally, the numbers $x = |a_k|$, $y = |b_k|$ represent all integer solutions of Pell's equation $x^2 - 3y^2 = 1$.

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Our main results are the following two theorems.

THEOREM 1. The coefficients $c_{j,r}$ of the fundamental functions (13) for natural cubic spline interpolation are described as follows:

(20)

$$c_{j,0} = 2 - (b_{n-1}/b_n) \quad \text{if } j = -1,$$

$$= b_{n-j}/b_n \qquad \text{if } j = 0, 1, \cdots, n+1;$$

$$c_{j,\nu} = -6 \ b_{n-\nu}b_j/b_n \quad \text{if } j \leq \nu, 0 < \nu < n,$$
(21)

$$= -6 \ b_{n-j} b_{\nu} / b_n \quad \text{if } \nu \leq j, \ 0 < \nu < n.$$

Moreover, the symmetry relations

$$(22) c_{j,\nu} = c_{n-j,n-\nu}$$

hold throughout, and in particular for $\nu = n$ we find that

(23)
$$c_{j,n} = c_{n-j,0}$$

are already described by the formulae (20).

THEOREM 2. The coefficients $\tilde{c}_{j,\nu}$ and γ_j of the fundamental functions (14) and (15) for complete cubic spline interpolation are as follows:

(24)
$$\tilde{c}_{j,0} = - a_{n-|j|}/b_n,$$

(25)
$$\tilde{c}_{j,\nu} = -2 a_j a_{n-\nu} / b_n \quad \text{if } j \leq \nu, \ 0 < \nu < n, \\ = -2 a_\nu a_{n-j} / b_n \quad \text{if } \nu \leq j, \ 0 < \nu < n.$$

The symmetry relation

(26)
$$\tilde{c}_{j,\nu} = \tilde{c}_{n-j,n-\nu}$$

holds throughout, and for v = n we find

(27)
$$\tilde{c}_{j,n} = \tilde{c}_{n-j,0}$$

already described by (24). Finally

(28)
$$\gamma_j = -\frac{1}{3} a_{n-j}/b_n.$$

In the application of these formulae there is never any loss of accuracy due to numerical instability, no matter how large n may be. In fact, writing $c_{j,\nu} = c_{j,\nu}^{(n)}$, we have that

(29)
$$\lim c_{j,\nu}^{(n)} = c_{j,\nu}^+, \quad \text{as } n \to \infty,$$

where

(30)
$$L_{\nu}^{+}(x) = \sum_{j=-1}^{\infty} c_{j,\nu}^{+} M(x-j) \quad (\nu = 0, 1, 2, \cdots)$$

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are the fundamental functions of *semicardinal* cubic spline interpolation. Their coefficients are found to be

(31)
$$c_{j,0}^{\dagger} = 2 - \lambda \quad \text{if } j = -1,$$
$$= \lambda^{j} \quad \text{if } i \ge 0;$$

(32)
$$c_{j,\nu}^{+} = -6 b_{j}\lambda^{\nu} \text{ if } j \leq \nu, \nu > 0, \\ = -6 b_{\nu}\lambda^{j} \text{ if } \nu \leq j, \nu > 0.$$

Similar results hold concerning $\tilde{c}_{j,\nu}^{(n)}$ and $\gamma_{j}^{(n)}$.

Our subject has received special attention in $[1, \S2.4]$ and [3]. Greville's approach seems closest to ours. He determines the coefficients a_{ν} and c_{ν} of the solution S(x) of (2) and (3) in its explicit form (1). In order to avoid the loss of accuracy inherent in this formulation by using integer arithmetic (as Greville recommends), one must work with a large number of digits even for moderately large values of n. Indeed, if n = 20, say, products containing close to 20 digits and multiplicands of more than 10 digits appear in the calculations. The advantages of using the representation (12) in terms of *B*-splines become apparent.

Computational advice. Construct the solution S(x) of the problem (2), (3) in the form (12), where the C_j are to be determined from the relations

$$C_j = \sum_{\nu=0}^n c_{j,\nu} f(\nu)$$
 $(j = -1, 0, \cdots, n+1).$

A similar remark concerns the problem (4), (5).

The results here described were obtained by means of the fundamental function and the eigensplines of cardinal spline interpolation as discussed in [7]. In the present cubic case this approach is particularly simple and intuitive. An alternative and shorter way of obtaining Theorems 1 and 2 is to use the results of D. Kershaw as described in [4]. The connection is as follows: If we introduce the representation (12) into the equations (4) and (5), we obtain a system of n+3 equations for the n+3 unknown coefficients C_j . The matrix of this linear system is a special case of one of the matrices that were explicitly inverted by Kershaw in [4]. Similarly, the problem (2) and (3) leads to a matrix that can easily be reduced to a special case of another matrix already inverted by Kershaw. Kershaw does not point out this application of his results, an application that becomes strikingly apparent if we use the representation (12) in terms of *B*splines. However, our approach via cardinal spline interpolation has the advantage of generalizing to higher degree spline interpolation problems. Indeed, in a forthcoming paper [8], written in collaboration with A. Sharma, we present the applications of our approach to quintic spline interpolation problems.

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