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# On Learning Discrete Graphical Models using Group-Sparse Regularization

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<b>Ali Jalali</b> ECE, UT Austin alij@mail.utexas.edu	<b>Pradeep Ravikumar</b> CS, UT Austin pradeepr@cs.utexas.edu	<b>Vishvas Vasuki</b> CS, UT Austin vvasuki@cs.utexas.edu	<b>Sujay Sanghavi</b> ECE, UT Austin sanghavi@mail.utexas.edu
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## Abstract

We study the problem of learning the graph structure associated with a general discrete graphical models (each variable can take any of  $m > 1$  values, the clique factors have maximum size  $c \geq 2$ ) from samples, under high-dimensional scaling where the number of variables  $p$  could be larger than the number of samples  $n$ . We provide a quantitative consistency analysis of a procedure based on node-wise multi-class logistic regression with group-sparse regularization.

We first consider general  $m$ -ary pairwise models – where each factor depends on at most two variables. We show that when the number of samples scale as  $n > K(m-1)^2 d^2 \log((m-1)^2(p-1))$  – where  $d$  is the maximum degree and  $K$  a fixed constant – the procedure succeeds in recovering the graph with high probability. For general models with  $c$ -way factors, the natural multi-way extension of the pairwise method quickly becomes very computationally complex. So we studied the effectiveness of using the pairwise method even while the true model has higher order factors. Surprisingly, we show that under slightly more stringent conditions, the pairwise procedure *still* recovers the graph structure, when the samples scale as  $n > K(m-1)^2 d^{\frac{3}{2}c-1} \log((m-1)^c(p-1)^{c-1})$ .

## 1 Introduction

*Markov Random Fields and Structure Learning.* Undirected graphical models, also known as Markov ran-

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dom fields, are used in a variety of domains, including statistical physics [14], natural language processing [19], image analysis [35, 13, 6], and spatial statistics [27], among others. A Markov random field (MRF) over a  $p$ -dimensional discrete random vector  $X = (X_1, X_2, \dots, X_p)$  is specified by an undirected graph  $G = (V, E)$ , with vertex set  $V = \{1, 2, \dots, p\}$  – one for each variable – and edge set  $E \subset V \times V$ . The structure of this graph encodes certain conditional independence assumptions among subsets of the variables. In this paper, we consider the task of structure learning, i.e. estimating the underlying graph structure associated with a general discrete Markov random field from  $n$  independent and identically distributed samples  $\{x^{(1)}, x^{(2)}, \dots, x^{(n)}\}$ .

*High-dimensional setting and Group sparsity.* We are interested in structure learning in the setting where the dimensionality  $p$  of the data is larger than the number of samples  $n$ . While classical procedures typically break down under such high-dimensional scaling, an active line of recent research has shown it is still possible to obtain practical consistent procedures by leveraging low-dimensional structure. The most popular example is that of leveraging sparsity using  $\ell_1$ -regularization (e.g., [4, 12, 21, 23, 31, 34, 37]). For MRF structure learning, such  $\ell_1$ -regularization has been successfully used for Gaussian [21] and discrete binary pairwise (i.e. Ising) models [26, 17]. In these instances, there is effectively only one parameter per edge, so that a sparse graph corresponds to a sparse set of parameters. In this paper, we are interested in more general discrete graphical models – where each variable can take  $m$  possible values, and factors can be of order higher than two. We now have multiple parameters per edge, and thus the relevant low-dimensional structure is that of *group sparsity*: all parameters of an edge form a group, and a sparse graph now corresponds to certain *groups of parameters* being non-zero. The counterpart of  $\ell_1$  regularization for such group-sparse structure is  $\ell_1/\ell_q$  regularization for  $q > 1$ , where we collate the  $\ell_q$  norms of the groups, and compute their overall  $\ell_1$  norm. Recent work on group and block-sparse linear

regression [32, 8, 22, 18, 24, 25, 2] show that under such group-sparse settings, group-sparse regularization outperforms the use of  $\ell_1$  penalization.

*Our Results: Pairwise  $m$ -ary models.* In this paper, we provide a quantitative consistency analysis of group-sparse regularized structure recovery for general discrete graphical models. We first consider the case of pairwise but otherwise  $m$ -ary discrete graphical models, and analyze a group-sparse variant of the procedures in [26, 21]: for each vertex  $r \in V$ , we estimate its neighborhood set using  $\ell_1/\ell_2$ -regularized maximum conditional likelihood. This reduces to multi-class logistic regression, for which we characterize the number of samples needed for *sparsistency* i.e. consistent recovery of the group-support-set with high probability. This analysis extends recent high-dimensional analyses for linear models to logistic models, and is of independent interest even outside the context of graphical models. We then combine the neighborhood sets across vertices to form the graph estimate. There has been a strong line of work on developing fast algorithms to solve these sparse multiclass logistic regression programs including Meier et al. [20], Krishnapuram et al. [15]. Indeed, [9, 10] show good empirical performance using such  $\ell_1/\ell_q$  regularization even with the joint likelihood over all variables.

*Our Results: General  $m$ -ary models.* One (natural, but expensive) extension to graphical models with higher-order factors is to again use group-sparse regularization but with higher order factors as groups. However, this leads to prohibitive computational complexity – e.g. there are  $\mathcal{O}(p^c)$  possible factors of order  $c$ . Indeed, in their empirical study of such regularizations, Dahinden et al. [9, 10] could scale up to small graph sizes, even while using some intelligent heuristics. This motivates our second main result. Suppose we solve the pairwise graphical model estimation problem, even when the true model has higher order factors. What is the relationship of this estimate with the true underlying graph? We investigate this for *hierarchical* graphical models where the absence of any lower-order factor also implies the absence of factors over supersets of the lower-order factor variables. Higher-order factors could, in principle, cause our pairwise estimator to include spurious edges. Surprisingly, we obtain the result that under slightly more stringent assumptions on the scaling of the sample size (dependent on the size of the higher-order factors) the pairwise estimator excludes the irrelevant edges, and includes all “dominant” pairwise edges whose parameters are larger than a certain threshold that depends on the size of the parameters values of higher-order factors. As a consequence, if all pairwise effects are dominant enough, we recover the graph exactly even

while using a simple pairwise estimator. But even otherwise, the guaranteed false edge exclusion could be used for further greedy procedures, though we defer further discussion in the sequel.

*Existing approaches.* Methods for estimating such graph structure include those based on constraint and hypothesis testing [29], and those that estimate restricted classes of graph structures such as trees [5], polytrees [11], and hypertrees [30]. Another class of approaches estimate the local neighborhood of each node via exhaustive search for the special case of bounded degree graphs. Abbeel et al. [1] propose a method for learning factor graphs based on local conditional entropies and thresholding, but the computational complexity grows at least as quickly as  $\mathcal{O}(p^{d+1})$ , where  $d$  is the maximum neighborhood size in the graphical model. Bresler et al. [3] describe a related local search-based method, and prove under relatively mild assumptions that it can recover the graph structure with  $\Theta(\log p)$  samples. However, in the absence of additional restrictions, the computational complexity of the method is  $\mathcal{O}(p^{d+1})$ . Csiszár and Talata [7] show consistency of a method that uses pseudo-likelihood and a modification of the BIC criterion, but this also involves a prohibitively expensive search.

## 2 Problem Setup and Notation

*MRFs and their Parameterization.* We consider the task of estimating the graph structure associated with a general discrete Markov random field. Let  $X = (X_1, \dots, X_p)$  be a random vector, each variable  $X_i$  taking values in a discrete set  $\mathcal{X} = \{1, 2, \dots, m\}$  of cardinality  $m$ . Let  $G = (V, E)$  denote a graph with  $p$  nodes, corresponding to the  $p$  variables  $\{X_1, \dots, X_p\}$ . Let  $\mathcal{C}$  be a set of cliques (fully-connected subgraphs) of the graph  $G$ , and let  $\{\phi_C : \mathcal{X}^{|\mathcal{C}|} \mapsto \mathbb{R}, C \in \mathcal{C}\}$  be a set of “clique potential” functions. With this notation, the distribution of  $X$  takes the form

$$\mathbb{P}(x) \propto \exp \left\{ \sum_{C \in \mathcal{C}} \phi_C(x_C) \right\}. \quad (1)$$

Since  $\mathcal{X}$  is discrete, each potential function  $\phi_C$  can be parameterized as linear combinations of  $\{0, 1\}$ -valued indicator functions – one for each configuration of  $x_C$ . For each  $s \in V$  and  $j \in \{1, \dots, m-1\}$ , we can define node-wise indicators,

$$\mathcal{I}[x_s = j] = \begin{cases} 1 & \text{if } x_s = j \\ 0 & \text{otherwise.} \end{cases}$$

Note that we omit an indicator for  $x_s = m$  from the list, since it is redundant given the indicators for  $j = 1, \dots, m-1$ . In a similar fashion, we can define the

$|C|$ -way clique-wise indicator functions  $\mathcal{I}[x_C = v]$ , for  $v \in \{1, 2, \dots, m-1\}^{|C|}$ .

With this notation, any set of potential functions can then be written as

$$\phi_C(x_C) = \sum_{v \in \{1, \dots, m-1\}^{|C|}} \theta_{C;v}^* \mathcal{I}[x_C = v] \quad \text{for } C \in \mathcal{C}$$

Thus, (1) can be rewritten as,

$$\mathbb{P}_{\theta^*}(x) \propto \exp \left\{ \sum_{C \in \mathcal{C}; v \in \{1, \dots, m-1\}^{|C|}} \theta_{C;v}^* \mathcal{I}[x_C = v] \right\}. \quad (2)$$

Thus, the Markov random field can be parameterized in terms of the collection of tensors  $\theta^* := \{\theta_{C;v}^* : C \in \mathcal{C}; v \in \{1, \dots, m-1\}^{|C|}\}$ . In the sequel, it will be useful to collate these into vectors  $\theta_C^* \in \mathbb{R}^{(m-1)^{|C|}}$  associated with the cliques  $C \in \mathcal{C}$ .

*Pairwise Markov Random Fields.* Here the set of cliques consists of the set of nodes  $V$  and the set of edges  $E$ . Thus, using nodewise and pairwise indicator functions as before, any pairwise MRF over  $(X_1, \dots, X_p)$  can be expressed as

$$\begin{aligned} \mathbb{P}(x) \propto \exp \left\{ \sum_{s \in V; j \in \{1, \dots, m-1\}} \theta_{s;j}^* \mathcal{I}[x_s = j] \right. \\ \left. + \sum_{(s,t) \in E; j,k \in \{1, \dots, m-1\}} \theta_{st;jk}^* \mathcal{I}[x_s = j, x_t = k] \right\}, \end{aligned} \quad (3)$$

for a set of parameters  $\theta^* := \{\theta_{s;j}^*, \theta_{st;jk}^* : s, t \in V; (s, t) \in E; j, k \in \{1, \dots, m-1\}\}$ . It will be useful to collate these into vectors  $\theta_s^* \in \mathbb{R}^{m-1}$  for each  $s \in V$ , and the vectors  $\theta_{st}^* \in \mathbb{R}^{(m-1)^2}$  associated with each edge.

*Graphical Model Selection.* Suppose that we are given a collection  $D := \{x^{(1)}, \dots, x^{(n)}\}$  of  $n$  samples, where each  $p$ -dimensional vector  $x^{(i)} \in \{1, \dots, m\}^p$  is drawn i.i.d. from a distribution  $\mathbb{P}_{\theta^*}$  of the form (2), for parameters  $\theta^*$  and graph  $G = (V, E^*)$  over the  $p$  variables. The goal of *graphical model selection* is to infer the edge set  $E^*$  of the graphical model defining the probability distribution that generates the samples. Note that the true edge set  $E^*$  can also be expressed as a function of the parameters as

$$E^* = \{(s, t) \in V \times V : \exists C \in \mathcal{C}; \{s, t\} \in C; \theta_C^* \neq 0\}. \quad (4)$$

In this paper, we focus largely on the special case of pairwise Markov random fields.

## 2.1 Pairwise Model Selection

We now describe the graph selection procedure we study for the  $m$ -ary pairwise model. It is the natu-

ral generalization of the procedures for binary graphical models [26] and Gaussian graphical models [21]. Specifically, we first focus on recovering the neighborhood of a fixed vertex  $r \in V$ , and then combine the neighborhood sets across vertices to form the graph estimate.

Let us define the vector  $\Theta_{\setminus r}^* \in \mathbb{R}^{(m-1)^2(p-1)}$ , which is the concatenation of  $(p-1)$  groups – i.e. one (short) vector  $\theta_{rt}^* \in \mathbb{R}^{(m-1)^2}$  for each  $t \in V \setminus \{r\}$ . Note that  $r$  having a small neighborhood is equivalent to many of these vectors  $\theta_{rt}^*$  being zero; in particular, the problem of neighborhood estimation for vertex  $r$  corresponds to the recovery of the set

$$\mathcal{N}(r) = \left\{ u \in V \setminus \{r\} \mid \|\theta_{ru}^*\|_0 \neq 0 \right\}.$$

This is precisely the structure captured by *group-sparsity*. In particular, each  $\theta_{rt}^*$ , with  $t \in V \setminus \{r\}$ , corresponds to a group; if  $r$  has a small neighborhood, only few of these groups will be non-zero.

In order to estimate the neighborhood  $\mathcal{N}(r)$ , we thus perform a regression of  $X_r$  on the rest of the variables  $X_{\setminus r}$ , using the group-sparse regularizer  $\|\Theta_{\setminus r}\|_{1,2} := \sum_{u \in V \setminus \{r\}} \|\theta_{ru}\|_2$ . The conditional distribution of  $X_r$  given the other variables  $X_{\setminus r} = \{X_t \mid t \in V \setminus \{r\}\}$  takes the form

$$\begin{aligned} \mathbb{P}_{\Theta^*}[X_r = j \mid X_{\setminus r} = x_{\setminus r}] = \\ \frac{\exp \left( \theta_{r;j}^* + \sum_{t \in V \setminus \{r\}} \sum_k \theta_{rt;jk}^* \mathcal{I}[x_t = k] \right)}{1 + \sum_{\ell} \exp \left( \theta_{r;\ell}^* + \sum_{t \in V \setminus \{r\}} \sum_k \theta_{rt;\ell k}^* \mathcal{I}[x_t = k] \right)}, \end{aligned} \quad (5)$$

for all  $j \in \{1, \dots, m-1\}$ . Thus,  $X_r$  can be viewed as the response variable in a multiclass logistic regression, in which the indicator functions associated with the other variables

$$\left\{ \mathcal{I}[x_t = k], t \in V \setminus \{r\}, k \in \{1, 2, \dots, m-1\} \right\},$$

play the role of the covariates.

Thus, we study the following convex program as an estimate for  $\Theta_r^*$

$$\hat{\Theta}_{\setminus r} \in \min_{\Theta_{\setminus r} \in \mathbb{R}^{(m-1)^2(p-1)}} \left\{ \ell(\Theta_{\setminus r}; D) + \lambda_n \|\Theta_{\setminus r}\|_{1,2} \right\}, \quad (6)$$

where  $\ell(\Theta_{\setminus r}; D) = \frac{1}{n} \sum_{i=1}^n \ell^{(i)}(\Theta_{\setminus r}; D) := \frac{1}{n} \sum_{i=1}^n \log \mathbb{P}_{\Theta} [X_r = x_r^{(i)} \mid X_{\setminus r} = x_{\setminus r}^{(i)}]$  is the rescaled multiclass logistic likelihood defined by the conditional distribution (5), and  $\lambda_n > 0$  is a regularization parameter. The convex program (6) is an  $\ell_1/\ell_2$ -regularized

multiclass logistic regression problem, and is thus the multiclass logistic analog of the group Lasso [36].

The solution to the program (6) yields an estimate  $\hat{\mathcal{N}}(r)$  of the neighborhood of node  $r$  by

$$\hat{\mathcal{N}}(r) = \{t \in V : t \neq r; \|\hat{\theta}_{rt}\|_2 \neq 0\}.$$

We are interested in the event that all the node neighborhoods are estimated exactly,  $\{\hat{\mathcal{N}}(r) = \mathcal{N}(r); \forall r \in V\}$ , which we also write as  $\{\hat{E} = E^*\}$  since it entails that the full graph is estimated exactly.

*Sparsistency.* Our main result is a high-dimensional analysis of the estimator (6), where allow the problems dimensions such as the number of nodes  $p$ , the maximum node degree  $d$ , the size of the state space  $m$  (and in the case of higher-order MRFs, the maximum clique size  $c$ ) to vary with the number of observations  $n$ . Our goal is to establish sufficient conditions on the scaling of  $(n, p, d, m, c)$  such that our proposed estimator is consistent in the sense that

$$\mathbb{P}[\hat{E}_n = E^*] \rightarrow 1 \quad \text{as } n \rightarrow +\infty.$$

We sometimes call this property sparsistency, as a shorthand for consistency of the sparsity pattern of the parameters.

## 2.2 Higher-order Model Selection

*Natural, high-complexity Extension.* Let us first see what this model selection recipe of node-wise regression with group-sparse regularization, would entail when extended to the general higher-order Markov random fields (2) case. Recall that such a higher-order MRF is parameterized by vectors  $\theta_C^* \in \mathbb{R}^{(m-1)^{|C|}}$  for  $C \in \mathcal{C}$ . Let  $c$  be the maximum clique size. It would be convenient to view the parameters as a collection of  $\sum_{j=1}^c \binom{p}{j}$  vectors indexed by a cliques  $C$  of size less than or equal to  $c$ , but non-zero if and only if the clique  $C \in \mathcal{C}$ .

Again, we fix a node  $r$ , and define the long vector  $\Theta_{\setminus r}^* \in \mathbb{R}^{\sum_{j=1}^{c-1} \binom{p-1}{j} (m-1)^{j+1}}$  as the concatenation of the parameter vectors  $\theta_{rC}^*$  for all  $C \subseteq V \setminus r; |C| < c$ . Note that recovery of the neighborhood of a vertex  $r$  corresponds to the recovery of the set

$$\mathcal{N}(r) = \left\{ u \in V \setminus \{r\} \mid \exists C \subseteq V \setminus \{r, u\}; \|\theta_{r \cup C}^*\|_0 \neq 0 \right\}.$$

Thus, we could again make use of group sparsity where in this case, the groups of parameters are the parameter vectors  $\theta_{rC}^*$  for different  $C \subseteq V \setminus r; |C| < c$ . We can then see that a small neighborhood  $\mathcal{N}(r)$  for node  $r$  entails that  $\Theta_{\setminus r}^*$  will have many of these groups be

zero. The group-structured penalty would then take the form  $\|\Theta_{\setminus r}^*\|_{1,2} := \sum_{\{C \subseteq V \setminus r \mid |C| < c\}} \|\theta_{rC}^*\|_2$ .

Thus we would solve:

$$\min_{\Theta_{\setminus r}^* \in \mathbb{R}^{\sum_{j=1}^{c-1} \binom{p-1}{j} (m-1)^{j+1}}} \left\{ \ell(\Theta_{\setminus r}; D) + \lambda_n \|\Theta_{\setminus r}\|_{1,2} \right\}, \quad (7)$$

where  $\ell(\Theta_{\setminus r}; D)$  is the likelihood of the data as before. Dahinden et al. [9, 10] studied the related program of  $\ell_1/\ell_2$  regularized maximum likelihood over the complete graph (instead of node-wise regressions) but showed good empirical performance of discrete graphical model structure recovery. The caveat with the higher-order group-sparse approach is the prohibitive computational complexity of this procedure. Note that the number of parameters is  $\sum_{j=1}^{c-1} \binom{p-1}{j} (m-1)^{j+1}$  which scales prohibitively even for moderate  $c$ . Indeed, even the computations in the pairwise case are not inexpensive.

*Sparsistency of a Simpler Estimate.* But as we show in Section 4, even when the underlying model is a higher order MRF, surprisingly just solving the pairwise program (6) is *sufficient* to recover the true edges, under certain conditions. Thus, in our second main result, we again analyze the sparsistency of the estimator in (6), but for the case where the underlying graph is a higher-order MRF.

## 2.3 Notation

We use the following notation for group-structured norms. For any vector  $u \in \mathbb{R}^p$  where  $\{1, \dots, p\}$  is partitioned into a set of  $T$  disjoint groups  $\mathcal{G} = \{G_1, \dots, G_T\}$ , we define  $\|u\|_{\mathcal{G}, a, b} = \|(\|u_{G_1}\|_a, \dots, \|u_{G_T}\|_a)\|_b$ . In our case, for the pairwise model, the nodewise regression has the parameter vector  $\Theta_{\setminus r}^* \in \mathbb{R}^{(m-1)^2(p-1)}$ . Its groups are collated on the edges:  $\mathcal{G} = \{\mathcal{G}_{rs}; s \in V \setminus r\}$  where  $\mathcal{G}_{rt}$  is the index set of parameters on the  $(r, t)$  edge,  $\{\theta_{rt, jk}; j, k \in \{1, \dots, m-1\}\}$ .

Similarly, suppose  $\Theta_{\setminus r}^*$  is the nodewise regression parameter for the higher-order model case. Then its groups are collated on the cliques:  $\mathcal{G} = \{\mathcal{G}_{rC}; C \subseteq V \setminus r \mid |C| < c\}$ , where  $\mathcal{G}_{rC}$  is the index set of parameters on the  $r \cup C$  clique,  $\{\theta_{rC, jv}; j \in \{1, \dots, m-1\}; v \in \{1, \dots, m-1\}^{|C|}\}$ . In the sequel, we will suppress the dependence of the group norms on these group partitions  $\mathcal{G}$  when it is clear from context, so that we will simply use  $\|\Theta_{\setminus r}^*\|_{a, b}$  for  $\|\Theta_{\setminus r}^*\|_{\mathcal{G}, a, b}$ .

We will be focusing on the choice  $a = 1, b = 2$  which yields the group-lasso penalty [36]. For a matrix  $M \in \mathbb{R}^{p \times p}$ , and denoting the  $i$ -th row of  $M$  by  $M^i$ , we can define the analogs of the

group-structured norms on matrices:  $\|M\|_{(a,b),(c,d)} := \|(\|M^1\|_{c,d}, \dots, \|M^p\|_{c,d})\|_{a,b}$ . In our analysis, we will always use  $b = d = 2$ , so that we use the minimized notation:  $\|M\|_{a,c}$  to denote  $\|M\|_{(a,2),(c,2)}$ .

### 3 Pairwise Discrete Graphical Models

Let  $S_r = \{u \in V : (r, u) \in E\}$  be the set of all neighbors of the node  $r$  in the graph and  $S_r^c = V \setminus S_r$ . Notice that  $\|\theta_{ru}^*\|_0 = 0$  for all  $u \in S_r^c$ . Fixing  $r \in V$ , and defining  $\Theta_{\setminus r}^*$  as before, let  $S_r^{(ex)}$  be the index set of parameters  $\{\theta_{rt;jk}^* \neq 0\}$  in  $\Theta_{\setminus r}^*$ . When clear from context, we will overload notation and again use  $S_r$  for this index set.

Let  $Q^* = \mathbb{E} \left[ \nabla^2 \log \left( \mathbb{P}_{\Theta_{\setminus r}^*} [X_r | X_{\setminus r}] \right) \right]$  be the population Fisher information matrix. Note that  $Q^* \in \mathbb{R}^{(m-1)^2(p-1) \times (m-1)^2(p-1)}$ . Similarly, let  $Q^n = \frac{1}{n} \sum_{i=1}^n \nabla^2 \ell^{(i)}(\Theta_{\setminus r}; D)$  be the sample Fisher information matrix.

Define  $\mathcal{J}^* = \mathbb{E} \left[ \mathcal{I}[x_{t_2} = k_2] \mathcal{I}[x_{t_1} = k_1]^T \right] \in \mathbb{R}^{(m-1)(p-1) \times (m-1)(p-1)}$ . Accordingly, define  $\mathcal{J}^n$  to be the empirical mean of the same quantity over  $n$  drawn samples. In the proofs (specifically in analyzing the derivative of the Hessian of the log-likelihood function), we will actually need control over  $\mathfrak{S}^* := \mathcal{J}^* \otimes \mathbf{1}_{(m-1) \times (m-1)}$ , the Kronecker product of  $\mathcal{J}^*$  and matrix of all ones (which would be of the size of  $Q^*$ ). But by properties of Kronecker products, we have  $\Lambda_{\max}(\mathfrak{S}^*) = \Lambda_{\max}(\mathcal{J}^*)$ , so that it suffices to impose assumptions on the maximum eigen values of  $\mathcal{J}^*$  and  $\mathcal{J}^n$ .

#### 3.1 Assumptions

We begin by stating the assumptions imposed on the true model. We note that similar sufficient conditions have been imposed in papers analyzing Lasso [33] and block-regularization methods [22, 24].

- (A1) **Invertibility:**  $\Lambda_{\min}(Q_{S_r, S_r}^*) \geq C_{\min} > 0$ .
- (A2) **Incoherence:**  $\left\| Q_{S_r^c, S_r}^* (Q_{S_r, S_r}^*)^{-1} \right\|_{\infty, 2} \leq \frac{1-2\alpha}{\sqrt{d_r}}$   
for some  $\alpha \in (0, \frac{1}{2})$ .
- (A3) **Boundedness:**  $\Lambda_{\max}(\mathcal{J}^*) \leq D_{\max} < \infty$ .

The next lemma states that imposing these assumptions on the population quantities implies analogous conditions on the sample statistics with high probability.

**Lemma 1.** *Assumptions (A1)-(A3) on the population Fisher information matrix yield the following (analogous) properties on the empirical Fisher information matrix:*

- (B1)  $\mathbb{P} \left[ \Lambda_{\min}(Q_{S_r, S_r}^n) < C_{\min} - \epsilon \right] \leq 2 \exp \left( -\frac{1}{8} (\epsilon \sqrt{n} - \sqrt{d_r})^2 + \log((m-1)^2 d_r) \right)$ .
- (B2)  $\mathbb{P} \left[ \left\| Q_{S_r^c, S_r}^n (Q_{S_r, S_r}^n)^{-1} \right\|_{\infty, 2} > \frac{1-\alpha}{\sqrt{d_r}} + \epsilon \right] \leq 6 \exp \left( -\frac{1}{8} (\bar{C}_{\min} \left( \frac{\alpha}{3\sqrt{d_r}} + \epsilon \right) \sqrt{n} - (1 + \frac{\sqrt{d_r}}{C_{\min}^2 \sqrt{n}}) \sqrt{d_r})^2 + \log((m-1)^2(p-1)) \right)$ .
- (B3)  $\mathbb{P} \left[ \Lambda_{\max}(\mathcal{J}^n) > D_{\max} + \epsilon \right] \leq 2 \exp \left( -\frac{1}{8} (\epsilon \sqrt{n} - \sqrt{d_r})^2 + \log((m-1)^2 d_r) \right)$ .

#### 3.2 Main Theorem

We can now state our main result on the sparsistency of the group-sparse regularized estimator.

**Theorem 1.** *Consider a discrete graphical model of the form (3) with parameters  $\Theta^*$  and associated edge set  $E$  such that conditions (A1)-(A3) are satisfied. Suppose the regularization parameter satisfies*

$$\lambda_n \geq \frac{8(2-\alpha)}{\alpha} \left( \sqrt{\frac{\log(p-1)}{n}} + \frac{m-1}{4\sqrt{n}} \right). \quad (8)$$

Then, there exist positive constants  $K$ ,  $c_1$  and  $c_2$  such that if the number of samples  $n$  scales as

$$n \geq K(m-1)^2 d_r^2 \log((m-1)^2(p-1)), \quad (9)$$

then with probability  $1 - c_1 \exp(-c_2 \lambda_n^2 n)$  we are guaranteed

- (a) For each node  $r \in V$ , the  $\ell_1/\ell_2$  regularized logistic regression (6) has a unique solution and hence specifies a neighborhood  $\hat{N}(r)$ .
- (b) For each node  $r \in V$  correctly excludes all edges not in the true neighborhood  $\mathcal{N}(r)$ . Moreover, it includes all edges  $(r, t)$  such that  $\left\| \theta_{rt;jk}^* \right\|_2 \geq \frac{10}{C_{\min}} \lambda_n$ .

Before sketching the proof outline, we first state some lemmas characterizing the solution of (3).

**Lemma 2 (Optimality Conditions).** *Any optimal primal-dual pair  $(\hat{\Theta}_{\setminus r}, \hat{Z}_{\setminus r})$  of (3) satisfies*

1. **(Stationary Condition).**

$$\nabla \ell \left( \hat{\Theta}_{\setminus r} \right) + \lambda_n \hat{Z}_{\setminus r} = 0. \quad (10)$$

2. **(Dual Feasibility).**  $\hat{Z}_{\setminus r}$  is equal to the subgradient  $\partial \|\hat{\Theta}_{\setminus r}\|_{1,2}$  so that for any  $u \in V \setminus r$ ,

(a) if  $(\hat{\Theta}_{\setminus r})_{u;jk} \neq 0$  for some  $j, k$  then

$$(\hat{Z}_{\setminus r})_u = \frac{(\hat{\Theta}_{\setminus r})_u}{\|(\hat{\Theta}_{\setminus r})_u\|_2}.$$

(b) if the entire group  $(\hat{\Theta}_{\setminus r})_u = 0$ , then  $\|(\hat{Z}_{\setminus r})_u\|_2 \leq 1$ .

The next lemma states that structure recovery is guaranteed if the dual is *strictly* feasible.

**Lemma 3 (Strict Dual Feasibility).** *Suppose that there exists an optimal primal-dual pair  $(\hat{\Theta}_{\setminus r}, \hat{Z}_{\setminus r})$  for*

(6) *such that  $\left\| (\hat{Z}_{\setminus r})_{S_r^c} \right\|_{\infty,2} < 1$ . Then, any optimal primal solution  $\tilde{\Theta}_{\setminus r}$  satisfies  $(\tilde{\Theta}_{\setminus r})_{S_r^c} = \mathbf{0}$ . Moreover, if the Hessian sub-matrix  $\left[ \nabla^2 \ell(\hat{\Theta}_{\setminus r}) \right]_{S_r, S_r} \succ 0$  then  $\hat{\Theta}_{\setminus r}$  is the unique optimal solution.*

We are now ready to sketch the proof of Theorem 1.

*Proof. Part (a).* The proof proceeds by a primal-dual witness technique, and consists of the construction of a feasible primal-dual pair in the following two steps:

(i) **Primal Candidate using an oracle subproblem:** Let  $\hat{\Theta}_{\setminus r}$  be the optimal solution of the restricted problem

$$\hat{\Theta}_{\setminus r} = \arg \min_{(\Theta_{\setminus r})_{S_r^c} = \mathbf{0}} \left\{ \ell(\Theta_{\setminus r}; D) + \lambda_n \|\Theta_{\setminus r}\|_{1,2} \right\}. \quad (11)$$

(ii) **Dual Candidate from Stationary Optimality Condition:** For any column  $u \in S_r$  set  $(\hat{Z}_{\setminus r})_u = \frac{1}{\|(\hat{\Theta}_{\setminus r})_u\|_2} (\hat{\Theta}_{\setminus r})_u$ . Set  $(\hat{Z}_{\setminus r})_{S_r^c}$  from the stationary condition (2).

*Showing Strict Dual Feasibility.* By construction, the  $(\hat{\Theta}_{\setminus r}, \hat{Z}_{\setminus r})$  pair satisfies the stationary condition (10). It remains to show that the the dual  $\hat{Z}_{\setminus r}$  is strictly feasible. We show that this holds, and also that the solution is unique, with high probability in Lemma 5.

*Part (b).* By uniqueness of the solution shown in part [(a)], the method excludes all edges that are not in the set of edges. To show that all correct edges are

included, i.e., to show the correct correct sign recovery, it suffices to show that

$$\left\| \hat{\Theta}_{S_r} - \hat{\Theta}_{S_r}^* \right\|_{\infty,2} \leq \frac{\theta_{\min}}{2},$$

where,  $\theta_{\min} = \min_{t \in V \setminus \{r\}} \|\theta_{rt;jk}\|_2$ .

We provide an  $\|\cdot\|_{\infty,2}$  bound on the error in (21), from which

$$\frac{2}{\theta_{\min}} \left\| \hat{\Theta}_{S_r} - \hat{\Theta}_{S_r}^* \right\|_{\infty,2} \leq \frac{2}{\theta_{\min}} \frac{5}{C_{\min}} \lambda_n \leq 1,$$

provided that  $\theta_{\min} > \frac{10}{C_{\min}} \lambda_n$ . □

## 4 Higher-Order Discrete Graphical Models

Consider the general higher-order MRF from (2)

$$\mathbb{P}(x) \propto \exp \left\{ \sum_{C \in \mathcal{C}; v \in \{1, \dots, m-1\}^{|C|}} \theta_{C;v}^* \mathcal{I}[x_C = v] \right\},$$

parameterized by the collection of vectors  $\theta_C^* \in \mathbb{R}^{(m-1)^{|C|}}$  associated with the cliques  $C \in \mathcal{C}$ .

As before, we fix a node  $r$ , and define the long vector  $\Theta_{\setminus r}^* \in \mathbb{R}^{\sum_{j=1}^{c-1} \binom{p-1}{j} (m-1)^{j+1}}$  as the concatenation of the parameter vectors  $\theta_{rC}^*$  for all  $C \subseteq V \setminus r$ ;  $|C| < c$ . Let  $\bar{\Theta}_P^* \in \mathbb{R}^{(m-1)^2 d_r}$  be the vector containing only neighbor-pairwise parameters  $\bar{\theta}_{rt;jk}^*$  for all  $t \in \mathcal{N}(r)$ . Accordingly, let  $\Theta_{P^c}^*$  represent all non-zero non-pairwise entries.

*Hierarchical Models.* A common assumption imposed on such higher-order MRFs is that they be hierarchical models [16]. Specifically, any MRF of the form (2) is hierarchical if for any clique  $C$ ,  $\theta_C^* = 0$  implies that  $\theta_B^* = 0$  for any clique  $B \supseteq A$  containing  $A$ . This has an importance consequence: the set of pairwise effects

$$\mathcal{N}(r) = \left\{ u \in V \setminus \{r\} \mid \|\theta_{ru}^*\|_0 \neq 0 \right\},$$

completely characterizes the set of edges.

Thus, if we are able to estimate just the pairwise parameters of the entire higher-order model, we would still be able to recover the edge-set. Thus, we study the estimator in (6) but now when the observations are actually drawn from  $\bar{\Theta}_{\setminus r}^*$ . The hope is that this solution would still estimate the pairwise parameters of the underlying higher-order model well.

#### 4.1 Assumptions

For fixed positive values  $C_{\min}$ ,  $D_{\max}$  and  $\alpha \in (0, \frac{1}{2})$ , let  $\gamma := \frac{D_{\max}}{C_{\min}} \|\bar{\Theta}_{P^c}^*\|_1$  and  $\tau = \frac{\alpha + \gamma(\sqrt{d_r} + 1)}{1 + \gamma}$ . We impose the following assumptions on the truth:

$$(C0) \text{ Mismatch Factor: } \gamma \leq \left(\frac{\alpha}{2-\alpha}\right)^2 \frac{C_{\min}}{100\sqrt{2}(m-1)d_r}.$$

This condition is required because of the mismatch of the true underlying model and our pairwise model. In other words, we have a non-zero mean noise, caused by model mismatch, that needs to be small. Moreover, since  $C_{\min} \leq (m-1)\sqrt{d_r}$  (see section 7.2), this condition ensures that  $\tau \in (0, \frac{1}{2})$  for suitable choice of  $\alpha$ .

(C1) **Invertibility:**

$$\Lambda_{\min} \left( \mathbb{E} \left[ \nabla^2 \log \left( \mathbb{P}_{\bar{\Theta}_{V_r}^*} [X_r | X_{\setminus r}] \right) \right]_{S_r, S_r} \right) \geq C_{\min}(1+\gamma).$$

(C2) **Incoherence:**

$$\text{Let } \bar{Q}^* := \mathbb{E} \left[ \nabla^2 \log \left( \mathbb{P}_{\bar{\Theta}_{V_r}^*} [X_r | X_{\setminus r}] \right) \right]. \text{ Then}$$

$$\left\| \bar{Q}_{S_r^c, S_r}^* (\bar{Q}_{S_r, S_r}^*)^{-1} \right\|_{\infty, 2} \leq \frac{1-2\tau}{\sqrt{d_r}}.$$

(C3) **Boundedness:**  $\Lambda_{\max}(\mathcal{J}^*) \leq D_{\max} < \infty$ ,

where  $\mathcal{J}^* = \mathbb{E} [\mathcal{I}[X_{S_1} = x_{S_1}] \mathcal{I}[X_{S_2} = x_{S_2}]^T]$  for any subset of nodes  $S_1$  and  $S_2$ , and  $c$  is the size of the maximum clique in the true graphical model. Note that  $\mathcal{J}^* \in \mathbb{R}^{\sum_{i=1}^{c-1} (m-1)^i (p-1)^i \times \sum_{i=1}^{c-1} (m-1)^i (p-1)^i}$ .

As in the pairwise case, in the proofs (to control the derivative of the Hessian of the log-likelihood function), we need to bound the maximum eigen value of matrix  $\mathfrak{S}^* = \mathcal{J}^* \otimes \mathbf{1}_{\sum_{j=1}^{c-1} (m-1)^j \times \sum_{j=1}^{c-1} (m-1)^j}$ . But again by properties of Kronecker products,  $\Lambda_{\max}(\mathfrak{S}^*) = \Lambda_{\max}(\mathcal{J}^*)$ , so that it suffices to impose assumptions on  $\mathcal{J}^*$ .

The next lemma states that imposing these assumptions on the population quantities implies analogous conditions on the sample statistics with high probability. Define  $\mathcal{D} = \sum_{j=1}^{c-1} d_r^j$ .

**Lemma 4.** *Assumptions (C0) - (C3) imply the following bounds on the pairwise parameters*

$$(D1) \mathbb{P} \left[ \Lambda_{\min} \left( \left[ \nabla^2 \ell(\bar{\Theta}_P^*; D) \right]_{S_r, S_r} \right) \leq C_{\min} - \epsilon \right]$$

$$\leq 2 \exp \left( -\frac{1}{8} (\epsilon \sqrt{n} - \sqrt{\mathcal{D}})^2 + \log \left( \sum_{j=2}^c (m-1)^j d_r^{j-1} \right) \right).$$

$$(D2) \mathbb{P} \left[ \left\| \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r^c, S_r} \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r, S_r}^{-1} \right\|_{\infty, 2} > \frac{1-\alpha}{\sqrt{d_r}} + \epsilon \right]$$

$$\leq 6 \exp \left( -\frac{1}{8} \left( \bar{C}_{\min} \left( \frac{\tau}{3\sqrt{\mathcal{D}}} + \epsilon \right) \sqrt{n} - \left( 1 + \frac{\sqrt{\mathcal{D}}}{C_{\min}^2 \sqrt{n}} \right) \sqrt{\mathcal{D}} \right)^2 \right.$$

$$\left. + \log \left( \sum_{j=2}^c (m-1)^j (1-p)^{j-1} \right) \right).$$

$$(D3) \mathbb{P} \left[ \Lambda_{\max} \left( \hat{\mathbb{E}} \left[ \mathcal{I}[X_{t_1} = k_1] \mathcal{I}[X_{t_2} = k_2]^T \right] \right) \geq D_{\max} + \epsilon \right]$$

$$\leq 2 \exp \left( -\frac{1}{8} (\epsilon \sqrt{n} - \sqrt{\mathcal{D}})^2 + \log \left( \sum_{j=2}^c (m-1)^j d_r^{j-1} \right) \right).$$

#### 4.2 Main Theorem

The following theorem shows that if the graphical model satisfies hierarchical assumption, then pairwise estimation exactly recovers the underlying graphical model provided that the higher order dependency parameters are not too large.

**Theorem 2.** *Consider an  $m$ -ary graphical model with parameter  $\bar{\Theta}^*$  and associate edge set  $\bar{E}$  such that conditions (C0)-(C3) and hierarchical assumption are satisfied. Suppose the size of the largest clique in the graph is  $c$  and the regularization parameter satisfies*

$$\lambda_n \geq \frac{8(2-\alpha)}{\alpha} \left( \sqrt{\frac{\log(p-1)}{n}} + \frac{m-1}{4\sqrt{n}} + \frac{1}{4} \|\bar{\Theta}_{P^c}^*\|_1 \right).$$

*Then, there exist positive constants  $K$ ,  $c_1$  and  $c_2$  such that for*

$$n \geq K(m-1)^2 d_r^{\frac{3}{2}c-1} \log \left( (m-1)^c (p-1)^{c-1} \right),$$

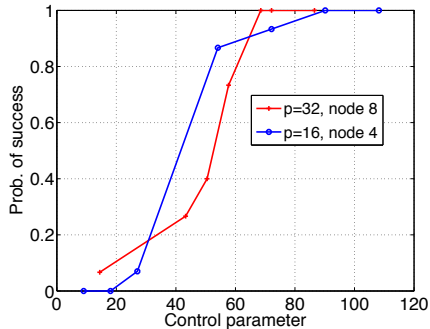
*with probability  $1 - c_1 \exp \left( -c_2 (\lambda_n - 2 \|\bar{\Theta}_{P^c}^*\|_1)^2 n \right)$  we are guaranteed*

(a) *For each node  $r \in V$ , the  $\ell_1/\ell_2$  regularized logistic regression (6) has a unique solution and hence specifies a neighborhood  $\hat{\mathcal{N}}(r)$ .*

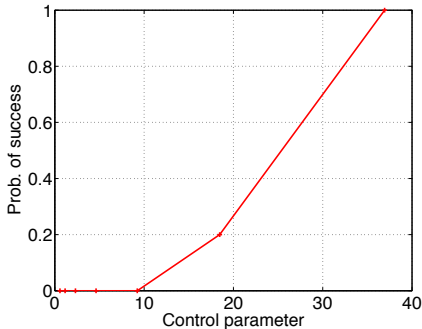
(b) *For each node  $r \in V$  correctly excludes all edges not in the true neighborhood  $\mathcal{N}(r)$ . Moreover, it includes all edges  $(r, t)$  such that  $\left\| \bar{\theta}_{rt, jk}^* \right\|_2 \geq \frac{10}{C_{\min}} \lambda_n$ .*

*Proof. Part [(a)].* The proof proceeds along the same lines as that of Theorem 1. We construct a primal-dual pair precisely as before using an oracle subproblem. However, showing strict-dual feasibility is more delicate when the true model has higher-order factors.

*Showing Strict Dual Feasibility.* By construction, the  $(\hat{\Theta}_{V_r}, \hat{Z}_{V_r})$  pair satisfies the stationary condition (10), as before. We then show that the the dual  $\hat{Z}_{V_r}$  is strictly feasible, and also that the solution is unique, with high probability in Lemma 7.



(a) Line Graph



(b) Grid

Figure 1: Probability of success  $\mathbb{P}[\hat{\mathcal{N}}(r) = \mathcal{N}(r)]$  versus the control parameter  $\beta(n, p, d) = \frac{n}{10d \log(p)}$  for discrete graphical models on a Line Graph and a Grid.

*Part [(b)].* Here again, we can argue as in the proof of Theorem 1 to show that all correct edges are included given an  $\|\cdot\|_{\infty, 2}$  bound on the error provided in (24).  $\square$

## 5 Experiments

In this section, we report a set of synthetic experiments investigating the consequences of the main theorems. These results illustrate the behavior of the structure learning algorithm on various types of graphs. We fix the size of the alphabet  $m = 3$ . For a given graph type, we pick a pairwise parameter set  $\Theta^*$ . We generate  $n$  samples according to the probability distribution corresponding to  $\Theta^*$ . Then, we solve (6) and compare the graph corresponding to the solution with the original graph. If the two graphs are identical, we declare that the algorithm has succeeded.

**Pairwise Model:** We consider two different classes of graphs: line graphs and grids (Fig. 4.2). In particular, we consider line graphs of size  $p = 16, 32$  and a grid of size  $\sqrt{p} \times \sqrt{p} = 16$ . In each of these cases, the parameter vector  $\Theta^*$  is generated by setting each non-zero entry  $\theta_{rt, jk}^* \in [-0.5, 0.5]$  for the line graphs and  $\theta_{rt, jk}^* \in [0, 5]$  for the grid uniformly at random. To

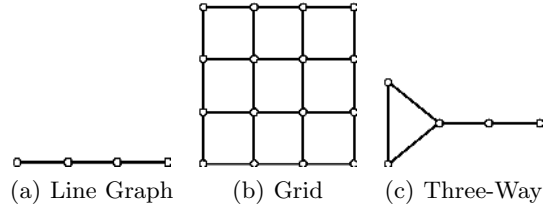


Figure 2: Line graph (a) and Grid (b) are used in studying pairwise graphical model selection. Three-way graph (c) is used for studying higher-order graphical model selection.

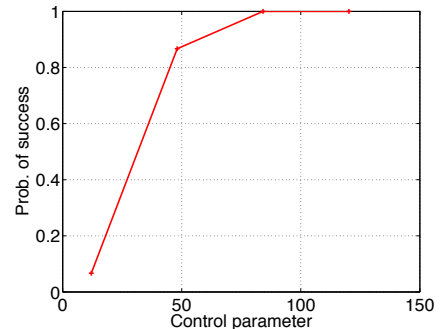


Figure 3: Probability of success  $\mathbb{P}[\hat{\mathcal{N}}(r) = \mathcal{N}(r)]$  versus the control parameter  $\beta(n, p, d) = \frac{n}{10d \log(p)}$  for a higher order discrete graphical model on a Three-way graph.

estimate the probability of success, we use 15 batches of samples drawn from the distribution specified by  $\Theta^*$ . We consider two types of simulations:

**Neighborhood Recovery:** Here, we focus on the recovery of the neighborhood of a particular node in a graph. Fixing a sample batch, for each pair  $(p, n)$ , we set  $\lambda_n = K \left( \sqrt{\frac{p-1}{n}} + \frac{m-1}{4\sqrt{n}} \right)$ , where  $K$  is the constant chosen by cross validation. We compare the graph induced by  $\hat{\Theta}_{K^*}$  with the graph induced by  $\Theta^*$  to get the probability of success. Fig. 4.2 shows the probability of success in neighborhood recovery. Notice that for different values of  $n$  and  $p$ , the phase transition graphs stack on the top of each other; this shows that the scaling of the samples  $n$  is correct.

**Higher-Order Model:** In this case, we consider a graph with higher order dependencies and try to estimate it using the pairwise model. We consider the three-way graph (triangle + line graph of size  $p - 2$ ) shown in Fig 2(c). There is only one three-way factor involving three nodes. The rest of the graph is characterized by pairwise parameters. Solving (7), we investigate the probability of success for neighborhood recovery of the node that connects the line graph and the triangle. Fig. 4.2 illustrates the result.



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## Supplementary Material

### 6 Auxiliary Lemmas: Proof of Lemma 3

*Proof.* We can rewrite (6) as an optimization problem over the  $\ell_1/\ell_2$  ball of radius  $C$  for some  $C(\lambda_n) < \infty$ . Since  $\lambda_n > 0$ , by KKT conditions,  $\|\tilde{\Theta}_{\setminus r}\|_{1,2} = C$  for all optimal primal solution  $\tilde{\Theta}_{\setminus r}$ .

By definition of the  $\ell_1/\ell_2$  subdifferential, we know that for any column  $u \in V \setminus \{r\}$ , we have  $\|(\hat{Z}_{\setminus r})_u\|_2 \leq 1$ . Considering the necessary optimality condition  $\nabla \ell(\hat{\Theta}_{\setminus r}) + \lambda_n \hat{Z}_{\setminus r} = 0$ , by complementary slackness condition, we have  $\langle \tilde{\Theta}_{\setminus r}, \hat{Z}_{\setminus r} \rangle - C = \langle \tilde{\Theta}_{\setminus r}^T, \hat{Z}_{\setminus r} \rangle - \|\tilde{\Theta}_{\setminus r}\|_{1,2} = 0$ . Now if for an arbitrary column  $u \in V \setminus \{r\}$ , we have  $\|(\hat{Z}_{\setminus r})_u\|_2 < 1$  and  $(\tilde{\Theta}_{\setminus r})_u \neq 0$  then this would contradict the condition that  $\langle \tilde{\Theta}_{\setminus r}, \hat{Z}_{\setminus r} \rangle = \|\tilde{\Theta}_{\setminus r}\|_{1,2}$ .

For this restricted problem, if the Hessian sub-matrix is positive definite, then the problem is strictly convex and it has a unique solution.  $\square$

### 7 Derivatives of the Log-Likelihood Function

In this section, we point out the key properties of the gradient, Hessian and derivative of the Hessian for the log-likelihood function. These properties are used to prove the concentration lemmas.

#### 7.1 Gradient

By simple derivation, we have

$$\begin{aligned} & \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell^{(i)}(\Theta_{\setminus r}; D) \\ &= \mathcal{I}[x_t^{(i)} = k] \left( \mathcal{I}[x_r^{(i)} = \ell] - \mathbb{P}_{\Theta_{\setminus r}^*}[X_r = \ell | X_{\setminus r} = x_{\setminus r}^{(i)}] \right). \end{aligned}$$

It is easy to show that  $\mathbb{E}_{\Theta_{\setminus r}^*} \left[ \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell^{(i)}(\Theta_{\setminus r}; D) \right] = 0$  and  $\text{Var} \left( \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell^{(i)}(\Theta_{\setminus r}; D) \right) \leq \frac{1}{4}$ . With i.i.d assumption on drawn samples, we have  $\text{Var} \left( \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell(\Theta_{\setminus r}; D) \right) = \text{Var} \left( \frac{1}{n} \sum_{i=1}^n \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell^{(i)}(\Theta_{\setminus r}; D) \right) \leq \frac{1}{4n}$ . Hence, for a

fixed  $t \in V \setminus \{r\}$  by Jensen's inequality,

$$\begin{aligned} & \mathbb{E}_{\Theta_{\setminus r}^*} \left[ \left\| \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell(\Theta_{\setminus r}; D) \right\|_2 \right] \\ & \leq \sqrt{\mathbb{E}_{\Theta_{\setminus r}^*} \left[ \left\| \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell(\Theta_{\setminus r}; D) \right\|_2^2 \right]} \\ & \leq \frac{m-1}{2\sqrt{n}}. \end{aligned}$$

Considering the terms associated with  $\theta_{rt;\ell k}^*$ 's in the gradient vector of the log-likelihood function, for a fixed  $t \in V \setminus \{r\}$ , only  $m-1$  (out of  $(m-1)^2$ ) values are non-zero. By a simple calculation, we get

$$\max_{t \in V \setminus \{r\}} \left\| \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell^{(i)}(\Theta_{\setminus r}; D) \right\|_2 \leq \sqrt{2} \quad \forall i.$$

By Azuma-Hoeffding inequality, we get

$$\mathbb{P} \left[ \left\| \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell(\Theta_{\setminus r}; D) \right\|_2 > \frac{m-1}{2\sqrt{n}} + \epsilon \right] \leq 2 \exp \left( -\frac{\epsilon^2}{4} n \right),$$

for all  $t \in V \setminus \{r\}$ . Using the union bound, we get

$$\begin{aligned} & \mathbb{P} \left[ \max_{t \in V \setminus \{r\}} \left\| \frac{\partial}{\partial \theta_{rt;\ell k}^*} \ell(\Theta_{\setminus r}; D) \right\|_2 > \frac{m-1}{2\sqrt{n}} + \epsilon \right] \\ & \leq 2 \exp \left( -\frac{\epsilon^2}{4} n + \log(p-1) \right). \end{aligned} \quad (12)$$

#### 7.2 Hessian

For the Hessian of the log-likelihood function, we have

$$\frac{\partial^2 \ell^{(i)}(\Theta_{\setminus r}; D)}{\partial \theta_{rt_2;\ell_2 k_2}^* \partial \theta_{rt_1;\ell_1 k_1}^*} = \mathcal{I}[x_{t_1}^{(i)} = k_1] \mathcal{I}[x_{t_2}^{(i)} = k_2] \eta_{\ell_1 \ell_2}(x^{(i)}),$$

where,

$$\begin{aligned} \eta_{\ell_1 \ell_2}(x^{(i)}) &:= \mathbb{P}_{\Theta_{\setminus r}^*} [X_r = \ell_1 | X_{\setminus r} = x_{\setminus r}^{(i)}] \\ & \left( \mathcal{I}[x_r^{(i)} = \ell_1] \mathcal{I}[x_r^{(i)} = \ell_2] - \mathbb{P}_{\Theta_{\setminus r}^*} [X_r = \ell_2 | X_{\setminus r} = x_{\setminus r}^{(i)}] \right). \end{aligned}$$

Consider the zero-mean random variable

$$\begin{aligned} Z_{t_1 \ell_1 k_1; t_2 \ell_2 k_2}^{(i)} &:= \\ & \frac{\partial^2 \ell^{(i)}(\Theta_{\setminus r}; D)}{\partial \theta_{rt_2;\ell_2 k_2}^* \partial \theta_{rt_1;\ell_1 k_1}^*} - \mathbb{E} \left[ \frac{\partial^2 \ell(\Theta_{\setminus r}; D)}{\partial \theta_{rt_2;\ell_2 k_2}^* \partial \theta_{rt_1;\ell_1 k_1}^*} \right]. \end{aligned}$$

Notice that  $\text{Var} \left( Z_{t_1 \ell_1 k_1; t_2 \ell_2 k_2}^{(i)} \right) \leq 1$  and consequently, by i.i.d assumption,  $\text{Var} \left( \frac{1}{n} \sum_{i=1}^n Z_{t_1 \ell_1 k_1; t_2 \ell_2 k_2}^{(i)} \right) \leq \frac{1}{n}$ .

Hence, for fixed values  $t_1, \ell_1, k_1$  and  $t_2 \in S_2 \subseteq V \setminus \{r\}$ , we have

$$\begin{aligned} \mathbb{E}_{\Theta_{\setminus r}^*} \left[ \left\| \frac{1}{n} \sum_{i=1}^n Z_{t_1 \ell_1 k_1; t_2 \ell_2 k_2}^{(i)} \right\|_2 \right] \\ \leq \sqrt{\mathbb{E}_{\Theta_{\setminus r}^*} \left[ \left\| \frac{1}{n} \sum_{i=1}^n Z_{t_1 \ell_1 k_1; t_2 \ell_2 k_2}^{(i)} \right\|_2^2 \right]} \\ \leq \sqrt{\frac{|S_2|}{n}}. \end{aligned} \quad (13)$$

This random variable, for fixed values  $t_1, \ell_1, k_1$  and a fixed  $t_2$ , is bounded and in particular,  $\left\| \frac{1}{n} \sum_{i=1}^n Z_{t_1 \ell_1 k_1; t_2 \ell_2 k_2}^{(i)} \right\|_2 \leq 2$ . By Azuma-Hoeffding inequality and the union bound,

$$\begin{aligned} \mathbb{P} \left[ \left\| Q_{S_r S_r}^n - Q_{S_r S_r}^* \right\|_{\infty, 2} > \frac{\sqrt{d_r}}{\sqrt{n}} + \epsilon \right] \\ \leq 2 \exp \left( -\frac{\epsilon^2}{8} n + \log((m-1)^2 d_r) \right). \\ \mathbb{P} \left[ \left\| Q_{S_r^c S_r}^n - Q_{S_r^c S_r}^* \right\|_{\infty, 2} > \frac{\sqrt{d_r}}{\sqrt{n}} + \epsilon \right] \\ \leq 2 \exp \left( -\frac{\epsilon^2}{8} n + \log((m-1)^2 (p-d_r-1)) \right). \end{aligned} \quad (14)$$

Similar analysis as (13) combined with the inequality  $\Lambda_{\max}(\cdot) \leq \|\cdot\|_{\infty, 2}$ , shows that

$$\begin{aligned} \mathbb{P} \left[ \Lambda_{\max} \left( Q_{S_r S_r}^n - Q_{S_r S_r}^* \right) > \frac{\sqrt{d_r}}{\sqrt{n}} + \epsilon \right] \\ \leq 2 \exp \left( -\frac{\epsilon^2}{8} n + \log((m-1)^2 d_r) \right). \end{aligned} \quad (15)$$

We also need a control over the deviation of the inverse sample Fisher information matrix from the inverse of its mean. We have

$$\begin{aligned} \Lambda_{\max} \left( \left( Q_{S_r S_r}^n \right)^{-1} - \left( Q_{S_r S_r}^* \right)^{-1} \right) \\ = \Lambda_{\max} \left( \left( Q_{S_r S_r}^* \right)^{-1} \left( Q_{S_r S_r}^* - Q_{S_r S_r}^n \right) \left( Q_{S_r S_r}^n \right)^{-1} \right) \\ \leq \Lambda_{\max} \left( \left( Q_{S_r S_r}^* \right)^{-1} \right) \Lambda_{\max} \left( Q_{S_r S_r}^* - Q_{S_r S_r}^n \right) \\ \Lambda_{\max} \left( \left( Q_{S_r S_r}^n \right)^{-1} \right) \\ \leq \frac{\sqrt{d_r}}{C_{\min} \sqrt{n}} \Lambda_{\max} \left( \left( Q_{S_r S_r}^n \right)^{-1} \right). \end{aligned}$$

By part (B1) in Lemma 1, we have

$$\begin{aligned} \mathbb{P} \left[ \Lambda_{\max} \left( \left( Q_{S_r S_r}^n \right)^{-1} \right) > \frac{1}{C_{\min}} + \epsilon \right] \\ \leq 2 \exp \left( -\frac{\left( \frac{C_{\min} \epsilon \sqrt{n}}{1+C_{\min} \epsilon} - \sqrt{d_r} \right)^2}{8} + \log((m-1)^2 d_r) \right). \end{aligned} \quad (16)$$

Hence, we get,

$$\begin{aligned} \mathbb{P} \left[ \Lambda_{\max} \left( \left( Q_{S_r S_r}^n \right)^{-1} \left( Q_{S_r S_r}^* \right)^{-1} \right) > \frac{\sqrt{d_r}}{C_{\min} \sqrt{n}} + \epsilon \right] \\ \leq 4 \exp \left( -\frac{\left( \frac{C_{\min} \epsilon \sqrt{n}}{1+C_{\min} \epsilon} - \sqrt{d_r} \right)^2}{8} + \log((m-1)^2 d_r) \right). \end{aligned} \quad (17)$$

### 7.3 Derivative of Hessian

We want to bound the rate of the change for the elements of Hessian matrix. Let

$$\begin{aligned} \nabla Q_{t_2 \ell_2 k_2; t_1 \ell_1 k_1}^{(i)} \\ := \frac{\partial}{\partial \Theta_{\setminus r}} \frac{\partial^2 \ell^{(i)}(\Theta_{\setminus r}; D)}{\partial \theta_{rt_2; \ell_2 k_2}^* \partial \theta_{rt_1; \ell_1 k_1}^*} \\ = \mathcal{I} \left[ x_{t_1}^{(i)} = k_1 \right] \mathcal{I} \left[ x_{t_2}^{(i)} = k_2 \right] \frac{\partial}{\partial \Theta_{\setminus r}} \eta_{\ell_1 \ell_2} \left( x^{(i)} \right). \end{aligned}$$

Recall the definition of  $\eta(\cdot)$  from section 7.2. We have

$$\begin{aligned} \frac{\partial \eta_{\ell_1 \ell_2} \left( x^{(i)} \right)}{\partial \theta_{rt_3; \ell_3 k_3}} = \mathcal{I} \left[ x_{t_3}^{(i)} = k_3 \right] \mathbb{P}_{\Theta_{\setminus r}^*} \left[ X_r = \ell_1 \mid X_{\setminus r} = x_{\setminus r}^{(i)} \right] \\ \left( \eta_{\ell_2 \ell_3} \left( x^{(i)} \right) - \frac{\eta_{\ell_1 \ell_2} \left( x^{(i)} \right) \eta_{\ell_1 \ell_3} \left( x^{(i)} \right)}{\mathbb{P}_{\Theta_{\setminus r}^*} \left[ X_r = \ell_1 \mid X_{\setminus r} = x_{\setminus r}^{(i)} \right]^2} \right). \end{aligned}$$

For any  $t_3 \in V \setminus \{r\}$ , each entry is bounded by  $\frac{1}{2}$  and there are only  $m-1$  non-zero entries for each  $k_3$ . Hence, for any  $t_3$ , one can calculate that  $\left\| \frac{\partial}{\partial \theta_{rt_3; \ell_3 k_3}} \eta_{\ell_1 \ell_2} \left( x^{(i)} \right) \right\|_2 \leq \frac{m-1}{\sqrt{2}}$  for all  $i$ . Finally, for all  $\ell_1$  and  $\ell_2$  we have

$$\max_{t_3 \in V \setminus \{r\}} \left\| \frac{\partial}{\partial \theta_{rt_3; \ell_3 k_3}} \eta_{\ell_1 \ell_2} \left( x^{(i)} \right) \right\|_2 \leq \frac{m-1}{\sqrt{2}}. \quad (18)$$

## 8 Proof of Lemma 1

(B1) By variational representation of the smallest eigenvalue, we have

$$\begin{aligned} \Lambda_{\min} \left( Q_{S_r S_r}^* \right) &= \min_{\|x\|_2=1} x^T Q_{S_r S_r}^* x \\ &\leq y^T Q_{S_r S_r}^n y + y^T \left( Q_{S_r S_r}^* - Q_{S_r S_r}^n \right) y, \end{aligned}$$

for all  $y \in \mathbb{R}^{(m-1)^2 d_r}$  with  $\|y\|_2 = 1$  and in particular for the unit-norm minimal eigenvalue of  $Q_{S_r S_r}^n$ . Hence,

$$\Lambda_{\min}(Q_{S_r S_r}^n) \geq \Lambda_{\min}(Q_{S_r S_r}^*) - \Lambda_{\max}(Q_{S_r S_r}^* - Q_{S_r S_r}^n).$$

By (15), we get

$$\begin{aligned} \mathbb{P}[\Lambda_{\min}(Q_{S_r S_r}^n) < C_{\min} - \epsilon] &\leq \mathbb{P}[\Lambda_{\max}(Q_{S_r S_r}^* - Q_{S_r S_r}^n) > \epsilon] \\ &\leq 2 \exp\left(-\frac{(\epsilon\sqrt{n} - \sqrt{d_r})^2}{8} + \log((m-1)^2 d_r)\right). \end{aligned}$$

**(B2)** We can write

$$\begin{aligned} Q_{S_r^c S_r}^n (Q_{S_r S_r}^n)^{-1} &= \underbrace{Q_{S_r^c S_r}^* (Q_{S_r S_r}^*)^{-1}}_{T_0} \\ &\quad + \underbrace{Q_{S_r^c S_r}^* \left( (Q_{S_r S_r}^n)^{-1} - (Q_{S_r S_r}^*)^{-1} \right)}_{T_1} \\ &\quad + \underbrace{\left( Q_{S_r^c S_r}^n - Q_{S_r^c S_r}^* \right) (Q_{S_r S_r}^*)^{-1}}_{T_2} \\ &\quad + \underbrace{\left( Q_{S_r^c S_r}^n - Q_{S_r^c S_r}^* \right) \left( (Q_{S_r S_r}^n)^{-1} - (Q_{S_r S_r}^*)^{-1} \right)}_{T_3}. \end{aligned}$$

Considering assumption (A3),  $\|T_0\|_{\infty,2} < \frac{1-2\alpha}{\sqrt{d_r}}$  and hence, it suffices to show that  $\|T_i\|_{\infty,2} < \frac{\alpha}{3\sqrt{d_r}}$  for  $i = 1, 2, 3$ . For the first term, we have

$$\begin{aligned} &\left\| Q_{S_r^c S_r}^* \left( (Q_{S_r S_r}^n)^{-1} - (Q_{S_r S_r}^*)^{-1} \right) \right\|_{\infty,2} \\ &= \left\| Q_{S_r^c S_r}^* (Q_{S_r S_r}^*)^{-1} (Q_{S_r S_r}^* - Q_{S_r S_r}^n) (Q_{S_r S_r}^n)^{-1} \right\|_{\infty,2} \\ &\leq \left\| Q_{S_r^c S_r}^* (Q_{S_r S_r}^*)^{-1} \right\|_{\infty,2} \Lambda_{\max}(Q_{S_r S_r}^* - Q_{S_r S_r}^n) \\ &\quad \Lambda_{\max}\left( (Q_{S_r S_r}^n)^{-1} \right) \\ &\leq \frac{1-2\alpha}{\sqrt{d_r}} \frac{\sqrt{d_r}}{\sqrt{n}} \frac{1}{C_{\min}}. \end{aligned}$$

The last inequality follows from (14) and (16) with high probability. Setting  $\bar{C}_{\min} = \min(C_{\min}, 1)$ , by applying the union bound,

$$\begin{aligned} \mathbb{P}\left[\left\| Q_{S_r^c S_r}^* \left( (Q_{S_r S_r}^n)^{-1} - (Q_{S_r S_r}^*)^{-1} \right) \right\|_{\infty,2} > \epsilon\right] \\ \leq 4 \exp\left(-\frac{\left(\bar{C}_{\min}\epsilon\sqrt{n} - \sqrt{d_r} - \frac{1-2\alpha}{C_{\min}}\right)^2}{8} + \log((m-1)^2 d_r)\right). \end{aligned}$$

For the second term, we have

$$\begin{aligned} &\left\| \left( Q_{S_r^c S_r}^n - Q_{S_r^c S_r}^* \right) (Q_{S_r S_r}^*)^{-1} \right\|_{\infty,2} \\ &\leq \left\| Q_{S_r^c S_r}^n - Q_{S_r^c S_r}^* \right\|_{\infty,2} \Lambda_{\max}\left( (Q_{S_r S_r}^*)^{-1} \right) \\ &\leq \frac{\sqrt{d_r}}{\sqrt{n}} \frac{1}{C_{\min}}. \end{aligned}$$

The last inequality follows from (14) with high probability. Hence, we have

$$\begin{aligned} \mathbb{P}\left[\left\| \left( Q_{S_r^c S_r}^n - Q_{S_r^c S_r}^* \right) (Q_{S_r S_r}^*)^{-1} \right\|_{\infty,2} > \epsilon\right] \\ \leq 2 \exp\left(-\frac{\left(\epsilon\sqrt{n} - \frac{(1+C_{\min})\sqrt{d_r}}{C_{\min}}\right)^2}{8} + \log((m-1)^2(p-1-d_r))\right). \end{aligned}$$

For the third term, we have

$$\begin{aligned} &\left\| \left( Q_{S_r^c S_r}^n - Q_{S_r^c S_r}^* \right) \left( (Q_{S_r S_r}^n)^{-1} - (Q_{S_r S_r}^*)^{-1} \right) \right\|_{\infty,2} \\ &\leq \left\| Q_{S_r^c S_r}^n - Q_{S_r^c S_r}^* \right\|_{\infty,2} \Lambda_{\max}\left( (Q_{S_r S_r}^n)^{-1} - (Q_{S_r S_r}^*)^{-1} \right) \\ &\leq \frac{\sqrt{d_r}}{\sqrt{n}} \frac{\sqrt{d_r}}{C_{\min}^2 \sqrt{n}} = \frac{d_r}{C_{\min}^2 n} \end{aligned}$$

The last inequality follows from (14) and (17). Hence, we have

$$\begin{aligned} \mathbb{P}\left[\left\| \left( Q_{S_r^c S_r}^n - Q_{S_r^c S_r}^* \right) \left( (Q_{S_r S_r}^n)^{-1} - (Q_{S_r S_r}^*)^{-1} \right) \right\|_{\infty,2} > \epsilon\right] \\ \leq 6 \exp\left(-\frac{\left(\bar{C}_{\min}\epsilon\sqrt{n} - \left(1 + \frac{\sqrt{d_r}}{C_{\min}^2 \sqrt{n}}\right)\sqrt{d_r}\right)^2}{8} \right. \\ \left. + \log((m-1)^2(p-1-d_r))\right). \end{aligned}$$

The result follows by substituting  $\epsilon$  with  $\frac{\alpha}{3\sqrt{d_r}}$ .

**(B3)** We can write

$$\begin{aligned} \mathbb{P}[\Lambda_{\max}(\mathcal{J}^n) > D_{\max} + \epsilon] \\ \leq \mathbb{P}\left[\left\| \frac{1}{n} \sum_{i=1}^n (\mathcal{J}^{(i)} - \mathcal{J}^*) \right\|_F > \epsilon\right]. \end{aligned}$$

Consequently, same analysis as part (B1) gives the result.

This concludes the proof of the Lemma.

## 9 Sufficiency Lemmas for Pairwise Dependencies

**Lemma 5.** *The constructed candidate primal-dual pair  $(\hat{\Theta}_{\setminus r}, \hat{Z}_{\setminus r})$  satisfy the conditions of the Lemma 3*

with probability  $1 - c_1 \exp(-c_2 n)$  for some positive constants  $c_1, c_2 \in \mathbb{R}$ .

*Proof.* Using the mean-value theorem, for some  $\bar{\Theta}_{\setminus r}$  in the convex combination of  $\hat{\Theta}_{\setminus r}$  and  $\Theta_{\setminus r}^*$ , we have

$$\begin{aligned} & \nabla^2 \ell(\Theta_{\setminus r}^*; D) \left[ \hat{\Theta}_{\setminus r} - \Theta_{\setminus r}^* \right] \\ &= \nabla \ell(\hat{\Theta}_{\setminus r}; D) - \nabla \ell(\Theta_{\setminus r}^*; D) \\ & \quad + \left( \nabla^2 \ell(\Theta_{\setminus r}^*; D) - \nabla^2 \ell(\bar{\Theta}_{\setminus r}; D) \right) \left[ \hat{\Theta}_{\setminus r} - \Theta_{\setminus r}^* \right] \\ &= -\lambda_n \hat{Z}_{\setminus r} - \underbrace{\nabla \ell(\Theta_{\setminus r}^*; D)}_{W_{\setminus r}^n} \\ & \quad + \underbrace{\left( \nabla^2 \ell(\Theta_{\setminus r}^*; D) - \nabla^2 \ell(\bar{\Theta}_{\setminus r}; D) \right)}_{R_{\setminus r}^n} \left[ \hat{\Theta}_{\setminus r} - \Theta_{\setminus r}^* \right]. \end{aligned}$$

We can rewrite these set of equations as two sets of equations over  $S_r$  and  $S_r^c$ . By Lemma 1, the Hessian sub-matrix on  $S_r$  is invertible with high probability and thus we get

$$\begin{aligned} & Q_{S_r^c S_r}^n (Q_{S_r S_r}^n)^{-1} \left( -\lambda_n (\hat{Z}_{\setminus r})_{S_r} - (W_{\setminus r}^n)_{S_r} + (R_{\setminus r}^n)_{S_r} \right) \\ &= -\lambda_n (\hat{Z}_{\setminus r})_{S_r^c} - (W_{\setminus r}^n)_{S_r^c} + (R_{\setminus r}^n)_{S_r^c}. \end{aligned}$$

Equivalently, we get

$$\begin{aligned} & (\hat{Z}_{\setminus r})_{S_r^c} = \frac{1}{\lambda_n} \left[ (W_{\setminus r}^n)_{S_r^c} - (R_{\setminus r}^n)_{S_r^c} \right] \\ & \quad - \frac{1}{\lambda_n} Q_{S_r^c S_r}^n (Q_{S_r S_r}^n)^{-1} \left( (W_{\setminus r}^n)_{S_r} - (R_{\setminus r}^n)_{S_r} \right) \\ & \quad + Q_{S_r^c S_r}^n (Q_{S_r S_r}^n)^{-1} (\hat{Z}_{\setminus r})_{S_r}. \end{aligned}$$

Notice that  $\left\| (\hat{Z}_{\setminus r})_{S_r} \right\|_{\infty, 2} = 1$ . Thus, we can establish the following bound

$$\begin{aligned} & \left\| (\hat{Z}_{\setminus r})_{S_r^c} \right\|_{\infty, 2} \\ & \leq \left( 1 + \left\| Q_{S_r^c S_r}^n (Q_{S_r S_r}^n)^{-1} \right\|_{\infty, 2} \sqrt{d_r} \right) \\ & \quad \left[ \frac{\left\| (W_{\setminus r}^n)_{S_r^c} \right\|_{\infty, 2}}{\lambda_n} + \frac{\left\| (R_{\setminus r}^n)_{S_r^c} \right\|_{\infty, 2}}{\lambda_n} + 1 \right] - 1 \\ & \leq (2 - \alpha) \left( \frac{\alpha}{4(2 - \alpha)} + \frac{\alpha}{4(2 - \alpha)} + 1 \right) - 1 \\ & = 1 - \frac{\alpha}{2} < 1. \end{aligned}$$

The second inequality holds with high probability according to Lemma 1 and Lemma 6.  $\square$

**Lemma 6.** For quantities defined in the proof of Lemma 5, the following inequalities hold:

$$\begin{aligned} & \mathbb{P} \left[ \frac{\left\| W_{\setminus r}^n \right\|_{\infty, 2}}{\lambda_n} \geq \frac{\alpha}{4(2 - \alpha)} \right] \\ & \leq 2 \exp \left( - \frac{\left( \frac{\alpha}{4(2 - \alpha)} \lambda_n \sqrt{n} - \frac{m-1}{2} \right)^2}{4} + \log(p-1) \right) \\ & \mathbb{P} \left[ \frac{\left\| R_{\setminus r}^n \right\|_{\infty, 2}}{\lambda_n} > \frac{\alpha}{4(2 - \alpha)} \right] \\ & \leq 2 \exp \left( - \frac{\left( \frac{\alpha}{4(2 - \alpha)} \lambda_n \sqrt{n} - \frac{m-1}{2} \right)^2}{4} + \log(p-1) \right). \end{aligned}$$

*Proof.* The first inequality follows directly from (12), for  $\epsilon = \frac{\alpha}{4(2 - \alpha)} \lambda_n - \frac{m-1}{2\sqrt{n}}$ , provided that  $\lambda_n \geq \frac{2(2 - \alpha)}{\alpha} \frac{m-1}{\sqrt{n}}$ . This probability goes to zero, if  $\lambda_n \geq \frac{8(2 - \alpha)}{\alpha} \left( \sqrt{\frac{\log(p-1)}{n}} + \frac{m-1}{4\sqrt{n}} \right)$ .

Before we proceed, we want to point out a technical fact that we will use it through the rest of the proof. For  $\lambda_n$  achieves the lower bound mentioned above, any positive value  $K$  and  $n \geq \frac{1}{K^2} \frac{64(2 - \alpha)^2}{\alpha^2} \left( \sqrt{\log(p-1)} + \frac{m-1}{4} \right)^2 d_r^2$ , we have  $\lambda_n d_r \leq K$ . Hence, we can assume  $\lambda_n d_r$  is less than any fixed constant  $K$  for sufficiently large  $n$ .

In order to bound  $R_{\setminus r}^n$ , we need to bound  $\left\| (\hat{\Theta}_{\setminus r})_{S_r} - (\Theta_{\setminus r}^*)_{S_r} \right\|_{\infty, 2}$ , using the technique used in Rothman et al. [28]. Let  $G : \mathbb{R}^{(m-1)^2 d_r} \rightarrow \mathbb{R}$  be a function defined as

$$\begin{aligned} & G((U)_{S_r}) := \ell \left( (\Theta_{\setminus r}^*)_{S_r} + (U)_{S_r}; D \right) - \ell \left( (\Theta_{\setminus r}^*)_{S_r}; D \right) \\ & \quad + \lambda_n \left( \left\| (\Theta_{\setminus r}^*)_{S_r} + (U)_{S_r} \right\|_{1, 2} - \left\| (\Theta_{\setminus r}^*)_{S_r} \right\|_{1, 2} \right). \end{aligned}$$

By optimality of  $\hat{\Theta}_{\setminus r}$ , it is clear that  $(\hat{U})_{S_r} = (\hat{\Theta}_{\setminus r})_{S_r} - (\Theta_{\setminus r}^*)_{S_r}$  minimizes  $G$ . Since  $G(\mathbf{0}) = 0$  by construction, we have  $G((\hat{U})_{S_r}) \leq 0$ . Suppose there exist an  $\ell_\infty/\ell_2$  ball with radius  $B_r$  such that for any  $\left\| (U)_{S_r} \right\|_{\infty, 2} = B_r$ , we have that  $G((U)_{S_r}) > 0$ . Then, we can claim that  $\left\| (\hat{U})_{S_r} \right\|_{\infty, 2} \leq B_r$ ; because if, in contrary, we assume that  $(\hat{U})_{S_r}$  is outside the ball,

then for an appropriate choice of  $t \in (0, 1)$ , the point  $t \left( \hat{U} \right)_{S_r} + (1-t)\mathbf{0}$  lies on the boundary of the ball. By convexity of  $G$ , we have

$$G \left( t \left( \hat{U} \right)_{S_r} + (1-t)\mathbf{0} \right) \leq tG \left( \left( \hat{U} \right)_{S_r} \right) + (1-t)G(\mathbf{0}) \leq 0.$$

This is a contradiction to the assumption of the positivity of  $G$  on the boundary of the ball.

Let  $(U)_{S_r} \in \mathbb{R}^{(m-1)d_r}$  be an arbitrary vector with  $\|(U)_{S_r}\|_{\infty,2} = \frac{5}{C_{\min}}\lambda_n$ . Applying mean value theorem to the log likelihood function, for some  $\beta \in [0, 1]$ , we get

$$\begin{aligned} G((U)_{S_r}) &= \left\langle (W_{\setminus r})_{S_r}, (U)_{S_r} \right\rangle \\ &+ \left\langle (U)_{S_r}, \nabla^2 \ell \left( \left( \Theta_{\setminus r}^* \right)_{S_r} + \beta (U)_{S_r}; D \right) (U)_{S_r} \right\rangle \\ &+ \lambda_n \left( \left\| \left( \Theta_{\setminus r}^* \right)_{S_r} + (U)_{S_r} \right\|_{1,2} - \left\| \left( \Theta_{\setminus r}^* \right)_{S_r} \right\|_{1,2} \right). \end{aligned} \quad (19)$$

We bound each of these three terms individually. By Cauchy-Schwartz inequality, we have

$$\begin{aligned} \left| \left\langle (W_{\setminus r})_{S_r}, (U)_{S_r} \right\rangle \right| &\leq \left\| (W_{\setminus r})_{S_r} \right\|_{\infty,2} \left\| (U)_{S_r} \right\|_{1,2} \\ &\leq \frac{\alpha}{4(2-\alpha)} \lambda_n d_r \frac{5}{C_{\min}} \lambda_n \\ &\leq \frac{5}{4C_{\min}} d_r \lambda_n^2. \end{aligned}$$

Moreover, by triangle inequality,

$$\begin{aligned} \lambda_n \left( \left\| \left( \Theta_{\setminus r}^* \right)_{S_r} + (U)_{S_r} \right\|_{1,2} - \left\| \left( \Theta_{\setminus r}^* \right)_{S_r} \right\|_{1,2} \right) \\ \geq -\lambda_n \left\| (U)_{S_r} \right\|_{1,2} \\ \geq -\frac{5}{C_{\min}} d_r \lambda_n^2. \end{aligned}$$

To bound the other term, notice that by Taylor expansion,

we get

$$\begin{aligned} &\Lambda_{\min} \left( \nabla^2 \ell \left( \left( \Theta_{\setminus r}^* \right)_{S_r} + \beta (U)_{S_r}; D \right) \right) \\ &\geq \min_{\beta \in [0,1]} \Lambda_{\min} \left( \nabla^2 \ell \left( \left( \Theta_{\setminus r}^* \right)_{S_r} + \beta (U)_{S_r}; D \right) \right) \\ &\geq \Lambda_{\min} (Q_{S_r, S_r}^*) \\ &\quad - \max_{\beta \in [0,1]} \Lambda_{\max} \left( \left\langle \frac{\partial \nabla^2 \ell (\Theta_{S_r}; D)}{\partial \Theta_{S_r}} \Big|_{\left( \Theta_{\setminus r}^* \right)_{S_r} + \beta (U)_{S_r}}, (U)_{S_r} \right\rangle \right) \\ &\geq C_{\min} - \left( \max_{t_3 \in V \setminus \{r\}} \left\| \frac{\partial}{\partial \theta_{rt_3; \ell_3 k_3}} \eta_{\ell_1 \ell_2} \left( x^{(i)} \right) \right\|_2 \sqrt{d_r} \right) \\ &\quad \Lambda_{\max}(\mathfrak{S}^*) \sqrt{d_r} \|(U)_{S_r}\|_{\infty,2}, \end{aligned} \quad (20)$$

where,  $\eta(\cdot)$  is defined in Section 7.2. We know that  $\Lambda_{\max}(\mathfrak{S}^*) = \Lambda_{\max}(\mathcal{J}^*)$  as a property of Kronecher product. By (18) and assumption on the maximum eigenvalue of  $\mathcal{J}^*$ , we have

$$\begin{aligned} &\Lambda_{\min} \left( \nabla^2 \ell \left( \left( \Theta_{\setminus r}^* \right)_{S_r} + \beta (U)_{S_r}; D \right) \right) \\ &\geq C_{\min} - \frac{m-1}{\sqrt{2}} d_r D_{\max} \|(U)_{S_r}\|_{\infty,2} \\ &\geq C_{\min} - \frac{m-1}{\sqrt{2}} d_r D_{\max} \frac{5}{C_{\min}} \lambda_n \\ &\geq \frac{C_{\min}}{2} \left( \lambda_n d_r \leq \frac{C_{\min}^2}{\sqrt{50}(m-1)D_{\max}} \right). \end{aligned}$$

Hence, from (19), we get

$$G((U)_{S_r}) \geq d_r \frac{5}{C_{\min}} \lambda_n^2 \left( -\frac{1}{4} + \frac{5}{2} - 1 \right) > 0.$$

We can conclude that

$$\left\| \left( \hat{\Theta}_{\setminus r} \right)_{S_r} - \left( \Theta_{\setminus r}^* \right)_{S_r} \right\|_{\infty,2} \leq \frac{5}{C_{\min}} \lambda_n. \quad (21)$$

with high probability. With similar analysis on the maximum eigenvalue of the derivative of Hessian as in (20), it is easy to show that

$$\begin{aligned} &\frac{\left\| R_{\setminus r}^n \right\|_{\infty,2}}{\lambda_n} \\ &\leq \frac{1}{\lambda_n} \frac{m-1}{\sqrt{2}} d_r D_{\max} \left\| \left( \hat{\Theta}_{\setminus r} \right)_{S_r} - \left( \Theta_{\setminus r}^* \right)_{S_r} \right\|_{\infty,2}^2 \\ &\leq \frac{m-1}{\sqrt{2}} d_r D_{\max} \frac{25}{C_{\min}^2} \lambda_n \\ &\leq \frac{\alpha}{4(2-\alpha)}, \end{aligned}$$

provided that  $\lambda_n d_r \leq \frac{C_{\min}^2}{50\sqrt{2}(m-1)D_{\max}} \frac{\alpha}{2-\alpha}$ .  $\square$

## 10 Proof of Lemma 4

(D1) By variational representation of the smallest eigenvalue, we have

$$\begin{aligned}
 & \Lambda_{\min} \left( \left[ \nabla^2 \ell(\bar{\Theta}_P^*; D) \right]_{S_r S_r} \right) \\
 & \geq \Lambda_{\min} \left( \left[ \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D) \right]_{S_r S_r} \right) \\
 & \quad - \Lambda_{\max} \left( \left[ \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D) \right]_{S_r S_r} - \left[ \nabla^2 \ell(\bar{\Theta}_P^*; D) \right]_{S_r S_r} \right) \\
 & \geq C_{\min}(1 + \gamma) \\
 & \quad - \Lambda_{\max} \left( \left[ \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D) \right]_{S_r S_r} - \left[ \nabla^2 \ell(\bar{\Theta}_P^*; D) \right]_{S_r S_r} \right).
 \end{aligned}$$

In the second inequality, we used the result of Lemma 1, i.e., the inequality holds with probability stated in Lemma 4. By Taylor expansion, for some  $\beta \in [0, 1]$ , and by (23), we get

$$\begin{aligned}
 & \Lambda_{\max} \left( \left[ \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D) \right]_{S_r S_r} - \left[ \nabla^2 \ell(\bar{\Theta}_P^*; D) \right]_{S_r S_r} \right) \\
 & \leq \Lambda_{\max} \left( \left\langle \frac{\partial \left[ \nabla^2 \ell(\bar{\Theta}; D) \right]_{S_r S_r}}{\partial \bar{\Theta}} \Big|_{\bar{\Theta}_{\setminus r}^* - \beta \bar{\Theta}_{P^c}^*}, \bar{\Theta}_{P^c}^* \right\rangle \right) \\
 & \leq \left\| \nabla \eta_{\ell_1 \ell_2} \left( x^{(i)} \right) \right\|_{\infty} D_{\max} \left\| \bar{\Theta}_{P^c}^* \right\|_1 \\
 & = \gamma C_{\min}.
 \end{aligned}$$

Note that  $\left\| \nabla \eta_{\ell_1 \ell_2} \left( x^{(i)} \right) \right\|_{\infty} \leq 1$  for  $\eta(\cdot)$  defined in section 7.3. The last inequality holds as a result of Lemma 1 with the probability stated in Lemma 4. Hence, the result follows.

(D2) We can write

$$\nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r^c S_r} \left( \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r S_r} \right)^{-1} = \sum_{i=0}^3 T_i,$$

where,

$$\begin{aligned}
 T_0 &= \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r^c S_r} \left( \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r S_r} \right)^{-1} \\
 T_1 &= \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r^c S_r} \\
 & \quad \left( \left( \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r S_r} \right)^{-1} - \left( \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r S_r} \right)^{-1} \right) \\
 T_2 &= \left( \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r^c S_r} - \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r^c S_r} \right) \\
 & \quad \left( \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r S_r} \right)^{-1} \\
 T_3 &= \left( \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r^c S_r} - \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r^c S_r} \right) \\
 & \quad \left( \left( \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r S_r} \right)^{-1} - \left( \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r S_r} \right)^{-1} \right).
 \end{aligned}$$

By Lemma 1, we have that  $\|T_0\|_{\infty, 1} \leq \frac{1-\tau}{\sqrt{d_r}}$  with the probability stated in Lemma 4. For the second term, we have

$$\begin{aligned}
 & \|T_1\|_{\infty, 2} \\
 & \leq \|T_0\|_{\infty, 2} \Lambda_{\max} \left( \underbrace{\nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r S_r} - \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r S_r}}_{T_{12}} \right) \\
 & \quad \Lambda_{\max} \left( \underbrace{\left( \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r S_r} \right)^{-1}}_{T_{13}} \right) \\
 & \leq \frac{1-\tau}{\sqrt{d_r}} \gamma C_{\min} \frac{1}{C_{\min}} = \frac{1-\tau}{\sqrt{d_r}} \gamma.
 \end{aligned}$$

We used the result of (D1) for  $\Lambda_{\max}(T_{13}) \leq \frac{1}{C_{\min}}$ .

For the third term, we have

$$\begin{aligned}
 \|T_2\|_{\infty, 2} & \leq \left\| \underbrace{\nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r^c S_r} - \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r^c S_r}}_{T_{21}} \right\|_{\infty, 2} \\
 & \quad \Lambda_{\max} \left( \underbrace{\left( \nabla^2 \ell(\bar{\Theta}_{\setminus r}^*; D)_{S_r S_r} \right)^{-1}}_{T_{22}} \right) \\
 & \leq \gamma C_{\min} \frac{1}{C_{\min}(1 + \gamma)} \\
 & = \frac{\gamma}{1 + \gamma}.
 \end{aligned}$$

For the fourth term, we have

$$\begin{aligned}
 \|T_3\|_{\infty, 2} & \leq \|T_{21}\|_{\infty, 2} \Lambda_{\max}(T_{22}) \Lambda_{\max}(T_{12}) \Lambda_{\max}(T_{13}) \\
 & \leq \gamma C_{\min} \frac{1}{C_{\min}(1 + \gamma)} \gamma C_{\min} \frac{1}{C_{\min}} \\
 & \leq \frac{\gamma^2}{1 + \gamma}.
 \end{aligned}$$

Putting all pieces together, we get the result.

(D3) The result follows directly from Lemma 1.

This concludes the proof of Lemma.

## 11 Sufficiency Lemmas for Higher Order Dependencies

**Lemma 7.** *The constructed candidate primal-dual pair  $(\hat{\Theta}_{\setminus r}, \hat{Z}_{\setminus r})$  satisfy the conditions of the Lemma 3*



with probability  $1 - c_1 \exp(-c_2 n)$  for some positive constants  $c_1, c_2 \in \mathbb{R}$ .

*Proof.* Using the mean-value theorem, for some  $\bar{\Theta}_{\setminus r}$  in the convex combination of  $\hat{\Theta}_{\setminus r}$  and  $\bar{\Theta}_P^*$ , we have

$$\begin{aligned} & \nabla^2 \ell(\bar{\Theta}_P^*; D) \left[ \hat{\Theta}_{\setminus r} - \bar{\Theta}_P^* \right] \\ &= \nabla \ell(\hat{\Theta}_{\setminus r}; D) - \nabla \ell(\bar{\Theta}_P^*; D) \\ & \quad + (\nabla^2 \ell(\bar{\Theta}_P^*; D) - \nabla^2 \ell(\bar{\Theta}_{\setminus r}; D)) \left[ \hat{\Theta}_{\setminus r} - \bar{\Theta}_P^* \right] \\ &= -\lambda_n \hat{Z}_{\setminus r} - \underbrace{\nabla \ell(\bar{\Theta}_P^*; D)}_{\bar{W}_{\setminus r}^n} \\ & \quad + \underbrace{(\nabla^2 \ell(\bar{\Theta}_P^*; D) - \nabla^2 \ell(\bar{\Theta}_{\setminus r}; D))}_{\bar{R}_{\setminus r}^n} \left[ \hat{\Theta}_{\setminus r} - \bar{\Theta}_P^* \right]. \end{aligned}$$

We can rewrite these set of equations as two sets of equations over  $S_r$  and  $S_r^c$ . By Lemma 4, the Hessian sub-matrix on  $S_r$  is invertible with high probability and thus we get

$$\begin{aligned} & \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r^c S_r} \left( \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r S_r} \right)^{-1} \\ & \left( -\lambda_n \left( \hat{Z}_{\setminus r} \right)_{S_r} - \left( \bar{W}_{\setminus r}^n \right)_{S_r} + \left( \bar{R}_{\setminus r}^n \right)_{S_r} \right) \\ & \quad = -\lambda_n \left( \hat{Z}_{\setminus r} \right)_{S_r^c} - \left( \bar{W}_{\setminus r}^n \right)_{S_r^c} + \left( \bar{R}_{\setminus r}^n \right)_{S_r^c}. \end{aligned}$$

Notice that  $\left\| \left( \hat{Z}_{\setminus r} \right)_{S_r} \right\|_{\infty, 2} = 1$  and hence, we get

$$\begin{aligned} & \left\| \left( \hat{Z}_{\setminus r} \right)_{S_r^c} \right\|_{\infty, 2} \\ & \leq \left( 1 + \left\| \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r^c S_r} \left( \nabla^2 \ell(\bar{\Theta}_P^*; D)_{S_r S_r} \right)^{-1} \right\|_{\infty, 2} \sqrt{d_r} \right) \\ & \quad \left[ \frac{\left\| \bar{W}_{\setminus r}^n \right\|_{\infty, 2}}{\lambda_n} + \frac{\left\| \bar{R}_{\setminus r}^n \right\|_{\infty, 2}}{\lambda_n} + 1 \right] - 1 \\ & \leq (2 - \alpha) \left( \frac{\alpha}{4(2 - \alpha)} + \frac{\alpha}{4(2 - \alpha)} + 1 \right) - 1 \\ & = 1 - \frac{\alpha}{2} < 1. \end{aligned}$$

The second inequality holds with high probability according to Lemma 4 and Lemma 8.  $\square$

**Lemma 8.** For quantities defined in the proof of

Lemma 7, the following inequalities hold:

$$\begin{aligned} & \mathbb{P} \left[ \frac{\left\| \bar{W}_{\setminus r}^n \right\|_{\infty, 2}}{\lambda_n} > \frac{\alpha}{4(2 - \alpha)} \right] \\ & \leq 2 \exp \left( - \frac{\left( \left( \frac{\alpha}{4(2 - \alpha)} \lambda_n^{-\frac{1}{2}} \left\| \bar{\Theta}_{P^c}^* \right\|_1 \right) \sqrt{n - \frac{m-1}{2}} \right)^2}{4} \right. \\ & \quad \left. + \log(p - 1) \right) \\ & \mathbb{P} \left[ \frac{\left\| \bar{R}_{\setminus r}^n \right\|_{\infty, 2}}{\lambda_n} > \frac{\alpha}{4(2 - \alpha)} \right] \\ & \leq 2 \exp \left( - \frac{\left( \left( \frac{\alpha}{4(2 - \alpha)} \lambda_n^{-\frac{1}{2}} \left\| \bar{\Theta}_{P^c}^* \right\|_1 \right) \sqrt{n - \frac{m-1}{2}} \right)^2}{4} \right. \\ & \quad \left. + \log(p - 1) \right). \end{aligned}$$

*Proof.* By simple derivation, we have

$$\begin{aligned} & \frac{\partial}{\partial \theta_{rt; \ell k}^*} \ell^{(i)}(\bar{\Theta}_P; D) = \mathcal{I} \left[ x_t^{(i)} = k \right] \\ & \quad \left( \mathcal{I} \left[ x_r^{(i)} = \ell \right] - \mathbb{P}_{\bar{\Theta}_P^*} \left[ X_r = \ell \mid X_{\setminus r} = x_{\setminus r}^{(i)} \right] \right). \end{aligned}$$

It is easy to show that

$$\begin{aligned} & \mathbb{E}_{\bar{\Theta}_{\setminus r}^*} \left[ \frac{\partial}{\partial \theta_{rt; \ell k}^*} \ell^{(i)}(\bar{\Theta}_P; D) \right] \\ &= \mathbb{P}_{\bar{\Theta}_{\setminus r}^*} \left[ X_r = \ell \mid X_t = k, X_{\setminus r, t} = x_{\setminus r, t} \right] \\ & \quad - \mathbb{P}_{\bar{\Theta}_P^*} \left[ X_r = \ell \mid X_t = k, X_{\setminus r, t} = x_{\setminus r, t} \right] \\ & \leq \left\| \bar{\Theta}_{P^c}^* \right\|_1 \\ & \quad \max_{\beta \in [0, 1]} \left\| \nabla \mathbb{P}_{\bar{\Theta}_{\setminus r}^* - \beta \bar{\Theta}_{P^c}^*} \left[ X_r = \ell \mid X_t = k, X_{\setminus r, t} = x_{\setminus r, t} \right] \right\|_{\infty} \\ & \leq \frac{1}{4} \left\| \bar{\Theta}_{P^c}^* \right\|_1, \end{aligned}$$

where, with abuse of notation  $\bar{\Theta}_{\setminus r}^* - \beta \bar{\Theta}_{P^c}^*$  represents the matrix  $\bar{\Theta}_{\setminus r}^*$  perturbed only on the entries corresponding to  $\bar{\Theta}_{P^c}^*$ . Also, one can show that  $\text{Var} \left( \frac{\partial}{\partial \theta_{rt; \ell k}^*} \ell^{(i)}(\bar{\Theta}_{\setminus r}; D) \right) \leq \frac{1}{4}$ . Consequently, with i.i.d assumption on drawn samples, we have  $\text{Var} \left( \frac{\partial}{\partial \theta_{rt; \ell k}^*} \ell(\bar{\Theta}_{\setminus r}; D) \right) \leq \frac{1}{4n}$ . For a fixed  $t \in V \setminus \{r\}$

by Jensen's inequality,

$$\begin{aligned} \mathbb{E}_{\Theta_{\setminus r}^*} \left[ \left\| \frac{\partial}{\partial \bar{\theta}_{rt;lk}^*} \ell(\Theta_{\setminus r}; D) \right\|_2 \right] &\leq \sqrt{\mathbb{E}_{\Theta_{\setminus r}^*} \left[ \left\| \frac{\partial}{\partial \bar{\theta}_{rt;lk}^*} \ell(\Theta_{\setminus r}; D) \right\|_2^2 \right]} \\ &\leq \frac{1}{2} \sqrt{\frac{(m-1)^2}{n} + \|\bar{\Theta}_{P^c}^*\|_1^2} \\ &\leq \frac{m-1}{2\sqrt{n}} + \frac{1}{2} \|\bar{\Theta}_{P^c}^*\|_1. \end{aligned}$$

We have  $\max_{t \in V \setminus \{r\}} \left\| \frac{\partial}{\partial \bar{\theta}_{rt;lk}^*} \ell^{(i)}(\Theta_{\setminus r}; D) \right\|_2 \leq \sqrt{2}$  for all  $i$  and hence, by Azuma-Hoeffding inequality and the union bound, we get

$$\mathbb{P} \left[ \left\| \frac{\partial}{\partial \bar{\theta}_{rt;lk}^*} \ell(\Theta_{\setminus r}; D) \right\|_{\infty, 2} > \frac{m-1}{2\sqrt{n}} + \frac{1}{2} \|\bar{\Theta}_{P^c}^*\|_1 + \epsilon \right] \leq 2 \exp \left( -\frac{\epsilon^2}{4} n + \log(p-1) \right).$$

For  $\lambda_n \geq \frac{8(2-\alpha)}{\alpha} \left( \frac{m-1}{4\sqrt{n}} + \frac{1}{4} \|\bar{\Theta}_{P^c}^*\|_1 \right)$ , the result follows.

In order to bound  $\bar{R}_{\setminus r}^n$ , we need to control the estimation error  $(\hat{\Theta}_{\setminus r})_{S_r} - (\bar{\Theta}_{P^c}^*)_{S_r}$ . Let  $H : \mathbb{R}^{(m-1)^2 d_r} \rightarrow \mathbb{R}$  be a function defined as

$$\begin{aligned} H(U_{S_r}) &:= \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r} + U_{S_r}; D \right) - \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r}; D \right) \\ &\quad + \lambda_n \left( \left\| (\bar{\Theta}_{P^c}^*)_{S_r} + U_{S_r} \right\|_{1,2} - \left\| (\bar{\Theta}_{P^c}^*)_{S_r} \right\|_{1,2} \right). \end{aligned}$$

By optimality of  $\hat{\Theta}_{\setminus r}$ , it is clear that  $U^* = (\hat{\Theta}_{\setminus r})_{S_r} - (\bar{\Theta}_{P^c}^*)_{S_r}$  minimizes  $H$ . Since  $H(\mathbf{0}) = 0$  by construction, we have  $H(U^*) \leq 0$ . Suppose there exist an  $\ell_\infty/\ell_2$  ball with radius  $B_r$  such that for any  $\|U\|_{\infty, 2} = B_r$ , we have that  $H(U) > 0$ . Then, we can claim that  $\|U^*\|_{\infty, 2} \leq B_r$ . See proof of Lemma 6 for more discussion on this proof technique. Let  $U_0 \in \mathbb{R}^{(m-1)^2 d_r}$  be an arbitrary vector with  $\|U_0\|_{\infty, 2} = \frac{5}{C_{\min}} \lambda_n$ . We have

$$\begin{aligned} H(U_0) &:= \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r} + U_0; D \right) - \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r}; D \right) \\ &\quad + \lambda_n \left( \left\| (\bar{\Theta}_{P^c}^*)_{S_r} + U_0 \right\|_{1,2} - \left\| (\bar{\Theta}_{P^c}^*)_{S_r} \right\|_{1,2} \right). \end{aligned} \tag{22}$$

We bound each of these three terms individually. Applying mean value theorem to the log likelihood func-

tion, for some  $\beta \in [0, 1]$ , we get

$$\begin{aligned} &\ell \left( (\bar{\Theta}_{P^c}^*)_{S_r} + U_0; D \right) - \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r}; D \right) \\ &= \left\langle (\bar{W}_{\setminus r}^n)_{S_r}, U_0 \right\rangle + \left\langle U_0, \nabla^2 \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r} + \beta U_0; D \right) U_0 \right\rangle. \end{aligned}$$

Note that  $\frac{\alpha}{4(2-\alpha)} \lambda_n \leq \frac{1}{4} \lambda_n$  and hence, by our bound on  $\bar{W}_{\setminus r}^n$  and Cauchy-Schwartz inequality, we have

$$\begin{aligned} \left| \left\langle (\bar{W}_{\setminus r}^n)_{S_r}, U_0 \right\rangle \right| &\leq \left\| (\bar{W}_{\setminus r}^n)_{S_r} \right\|_{\infty, 2} \|U_0\|_{1,2} \\ &\leq \frac{\lambda_n}{4} d_r \|U_0\|_{\infty, 2} \\ &\leq \frac{5}{4C_{\min}} \lambda_n^2 d_r. \end{aligned}$$

To bound the other term, by Taylor expansion, we get

$$\begin{aligned} &\Lambda_{\min} \left( \nabla^2 \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r} + \beta U_0; D \right) \right) \\ &\geq \min_{\beta \in [0, 1]} \Lambda_{\min} \left( \nabla^2 \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r} + \beta U_0; D \right) \right) \\ &\geq \Lambda_{\min} \left( \nabla^2 \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r}; D \right) \right) \\ &\quad - \max_{\beta \in [0, 1]} \Lambda_{\max} \left( \left\langle \frac{\partial \nabla^2 \ell \left( (\bar{\Theta}_{P^c}^*)_{S_r}; D \right)}{\partial (\bar{\Theta}_{P^c}^*)_{S_r}} \Big|_{(\bar{\Theta}_{P^c}^*)_{S_r} + \beta U_0}, U_0 \right\rangle \right) \\ &\geq C_{\min} \\ &\quad - \max_{t_3 \in V \setminus \{r\}} \left\| \frac{\partial \eta_{\ell_1 \ell_2} (x^{(i)})}{\partial \bar{\theta}_{rt_3; \ell_3 k_3}} \right\|_2 d_r \Lambda_{\max}(\mathfrak{S}^*) \|U_0\|_{\infty, 2} \\ &\geq C_{\min} - \frac{m-1}{\sqrt{2}} d_r D_{\max} \|U_0\|_{\infty, 2} \\ &\geq \frac{C_{\min}}{2} \left( \lambda_n d_r \leq \frac{C_{\min}^2}{\sqrt{50}(m-1)D_{\max}} \right). \end{aligned} \tag{23}$$

Here, we used the fact that  $\Lambda_{\max}(\mathfrak{S}^*) = \Lambda_{\max}(\mathcal{J}^*)$  as a property of Kronecher product and also our assumption on the maximum eigenvalue of  $\mathcal{J}^*$ . By triangle inequality,

$$\begin{aligned} \lambda_n \left( \left\| \bar{\Theta}_{P^c}^* + U_0 \right\|_{1,2} - \left\| \bar{\Theta}_{P^c}^* \right\|_{1,2} \right) &\geq -\lambda_n \|U_0\|_{1,2} \\ &\geq -\lambda_n d_r \|U_0\|_{\infty, 2} \\ &\geq -\frac{5\lambda_n^2 d_r}{C_{\min}}. \end{aligned}$$

Hence, from (22), we get  $H(U_0) \geq \frac{5\lambda_n^2 d_r}{4C_{\min}} > 0$  and hence,

$$\left\| (\hat{\Theta}_{\setminus r})_{S_r} - (\bar{\Theta}_{P^c}^*)_{S_r} \right\|_{\infty, 2} \leq \frac{5}{C_{\min}} \lambda_n, \tag{24}$$

with high probability. With similar analysis as in 23,

we have

$$\begin{aligned}
 & \frac{\|\bar{R}_{\setminus r}^n\|_{\infty,2}}{\lambda_n} \\
 & \leq \frac{1}{\lambda_n} \frac{m-1}{\sqrt{2}} d_r D_{\max} \left\| \left( \hat{\Theta}_{\setminus r} \right)_{S_r} - \left( \Theta_{\setminus r}^* \right)_{S_r} \right\|_{\infty,2}^2 \\
 & \leq \frac{m-1}{\sqrt{2}} d_r D_{\max} \frac{25}{C_{\min}^2} \lambda_n \\
 & \leq \frac{\alpha}{4(2-\alpha)},
 \end{aligned}$$

provided that  $\lambda_n d_r \leq \frac{C_{\min}^2}{50\sqrt{2}(m-1)D_{\max}} \frac{\alpha}{2-\alpha}$ .

□