

On M-Projective Curvature Tensor of Lorentzian α -Sasakian Manifolds

D.G. Prakasha and Vasant Chavan

Department of Mathematics, Karnatak University,
Dharwad - 580 003, India

E-mail: prakashadg@gmail.com and kcvasant@gmail.com

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Abstract. In this paper, we study the nature of Lorentzian α -Sasakian manifolds admitting M-projective curvature tensor. We show that M-projectively flat and irrotational M-projective curvature tensor of Lorentzian α -Sasakian manifolds are locally isometric to unit sphere $S^n(c)$, where $c = \alpha^2$. Next we study Lorentzian α -Sasakian manifold with conservative M-projective curvature tensor. Finally, we find certain geometrical results if the Lorentzian α -Sasakian manifold satisfying the relation $M(X, Y) \cdot R = 0$.

1. Introduction

If a differentiable manifold has a Lorentzian metric g , i.e., a symmetric non-degenerate $(0,2)$ tensor field of index 1, then it is called a Lorentzian manifold. The notion of Lorentzian manifold was first introduced by Matsumoto [12] in 1989. The same notion was independently studied by Mihai and Rosca [13]. Since then several geometers studied Lorentzian manifold and obtained various important properties. Our present note deals with a special kind of manifold i.e., Lorentzian α -Sasakian manifold. At first we give some introduction about the development of such manifold. An almost contact metric manifold with structure tensors (ϕ, ξ, η, g) , where ϕ is a tensor field of type $(1, 1)$, ξ a vector field, η a 1-form and g is a Riemannian metric on M is called trans-Sasakian structure [16] if $(M \times \mathbf{R}, J, G)$ belongs to the class W_4 [7] of the Hermitian structure, where J is the almost complex structure on $(M \times \mathbf{R})$ defined by

$$(J, X \frac{d}{dt}) = (\phi X - f, \eta(X) \frac{d}{dt}),$$

for all vector fields X on M and smooth functions f on $(M \times \mathbf{R})$, G is the product metric on $M \times \mathbf{R}$. This may be expressed by the condition

$$(\nabla_X \phi)(Y) = \alpha[g(X, Y)\xi + \eta(Y)X] + \beta[g(\phi X, Y) - \eta(Y)\phi X],$$

for smooth functions α and β on M in [2], and we say that the trans-Sasakian structure is of type (α, β) . A trans-Sasakian structure of type (α, β) is α -Sasakian, if $\beta = 0$ and α a nonzero constant [8], if $\alpha = 1$, then α -Sasakian manifold is a Sasakian manifold. Also in 2005, Yildiz and Murathan [23] introduced and studied Lorentzian α -Sasakian manifolds. In [19], Prakasha and his coauthors investigated Weyl-pseudosymmetric and partially Ricci-pseudosymmetric Lorentzian α -Sasakian manifolds. In [24], some classes of Lorentzian α -Sasakian manifolds were studied. Also, three-dimensional Lorentzian α -Sasakian manifolds have been studied in [25]. Further Lorentzian α -Sasakian manifolds were also studied by Prakasha and Yildiz [20], Bhattacharyya and Patra [1]. Recently Dey and Bhattacharyya have studied some curvature properties of Lorentzian α -Sasakian manifolds [6] and many others (see, [9, 10]).

The M-projective curvature tensor of Riemannian manifold M^n was defined by Pokhariyal and Mishra [17] is of the following form:

$$\begin{aligned} M(X, Y)Z &= R(X, Y)Z - \frac{1}{2(n-1)}[S(Y, Z)X - S(X, Z)Y \\ &+ g(Y, Z)QX - g(X, Z)QY], \end{aligned} \quad (1.1)$$

where Q is the Ricci operator defined on $S(X, Y) = g(QX, Y)$. The authors extensively studied the properties of M-projective curvature tensor on the various manifolds (see, [3, 11, 14, 15, 18, 22, 26, 27]). In this paper, we have studied some special properties of Lorentzian α -Sasakian manifold.

The purpose of this paper is to study the properties of M-projective curvature tensor in Lorentzian α -Sasakian manifolds. The paper is organized as follows. Section 2 is concerned with preliminaries of Lorentzian α -Sasakian manifolds. In section 3, we study the M-projectively flat of Lorentzian α -Sasakian manifold. Section 4 deals with the M-projectively flat Lorentzian α -Sasakian manifold satisfies the condition $R(X, Y) \cdot S = 0$. In section 5, we study conservative M-projective curvature tensor of Lorentzian α -Sasakian manifold. In section 6, irrotational M-projective curvature tensor of Lorentzian α -Sasakian manifold are studied. Section 7 is devoted with study of Lorentzian α -Sasakian manifold satisfies the condition $M(X, Y) \cdot R = 0$.

2. Preliminaries

A differential manifold M^n of dimension n is said to be a *Lorentzian α -Sasakian manifold* if it admits a $(1, 1)$ -tensor field ϕ , a vector field ξ , a 1-form η , and Lorentzian metric g which satisfy the conditions

$$\eta(\xi) = -1, \phi^2 = I + \eta \otimes \xi, \phi(\xi) = 0 \text{ and } g(X, \xi) = \eta(X), \quad (2.1)$$

$$\eta(\phi X) = 0, g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y), \quad (2.2)$$

$$(\nabla_X \phi)(Y) = \alpha \{g(X, Y)\xi + \eta(Y)X\}, \quad (2.3)$$

for all $X, Y \in \chi(M^n)$, where $\chi(M^n)$ is the Lie algebra of smooth vector fields on M^n , and ∇ denotes the covariant differentiation operator of Lorentzian metric g . Also, on a Lorentzian α -Sasakian manifold M^n , we have (see [19, 25])

$$\nabla_X \xi = -\alpha \phi X, (\nabla_X \eta)Y = -\alpha g(\phi X, Y) = (\nabla_Y \eta)(X). \quad (2.4)$$

Further, on a Lorentzian α -Sasakian manifold M^n the following results holds (see, [23, 19])

$$\eta(R(X, Y)Z) = \alpha^2 \{g(Y, Z)\eta(X) - g(X, Z)\eta(Y)\}, \quad (2.5)$$

$$R(\xi, X)Y = \alpha^2 \{g(X, Y)\xi - \eta(Y)X\}, \quad (2.6)$$

$$R(X, Y)\xi = \alpha^2 \{\eta(Y)X - \eta(X)Y\}, \quad (2.7)$$

$$S(X, \xi) = (n-1)\alpha^2 \eta(X), \quad (2.8)$$

$$S(\phi X, \phi Y) = S(X, Y) + (n-1)\alpha^2 \eta(X)\eta(Y). \quad (2.9)$$

Definition 2.1. A Lorentzian α -Sasakian manifold M^n is said to be η -Einstein if its Ricci tensor S is of the form

$$S(X, Y) = ag(X, Y) + b\eta(X)\eta(Y), \quad (2.10)$$

where a, b are functions on M^n . If $b = 0$, then η -Einstein manifold becomes Einstein manifold.

In view of (2.1) and (2.10), we have

$$QX = aX + b\eta(X)\xi, \quad (2.11)$$

Let us consider an η -Einstein Lorentzian α -Sasakian manifold. Then putting $X = Y = e_i$ in (2.10), $i = 1, 2, \dots, n$ and taking summation for $1 \leq i \leq n$, we have

$$r = na - b. \quad (2.12)$$

Now, setting $X = Y = \xi$ in (2.10) and using (2.1) and (2.8), we obtain

$$a - b = (n-1)\alpha^2. \quad (2.13)$$

From the conditions (2.12) and (2.13), gives

$$a = \frac{r}{n-1} - \alpha^2 \quad \text{and} \quad b = \frac{r}{n-1} - n\alpha^2. \quad (2.14)$$

In view of (2.5)-(2.7), it can be easily constructed that in n -dimensional Lorentzian α -Sasakian manifold M^n , the M-projective curvature tensor satisfies the following condition from (1.1):

$$M(X, Y)\xi = \frac{\alpha^2}{2} \{\eta(Y)X - \eta(X)Y\} - \frac{1}{2(n-1)} \{\eta(Y)QX - \eta(X)QY\}, \quad (2.15)$$

$$M(\xi, X)Y = \frac{\alpha^2}{2} \{g(X, Y)\xi - \eta(Y)X\} - \frac{1}{2(n-1)} \{S(X, Y)\xi - \eta(Y)QX\}, \quad (2.16)$$

$$\begin{aligned} \eta(M(X, Y)Z) &= \frac{\alpha^2}{2} \{g(Y, Z)\eta(X) - g(X, Z)\eta(Y)\} \\ &\quad - \frac{1}{2(n-1)} \{S(Y, Z)\eta(X) - S(X, Z)\eta(Y)\}. \end{aligned} \quad (2.17)$$

The above results will be used in the later sections.

3. M-Projectively Flat Lorentzian α -Sasakian Manifold

Definition 3.1. The Lorentzian α -Sasakian manifold M^n is said to be a M-projectively flat, if we have $M(X, Y)Z = 0$.

By taking into account of relation (1.1) and using Definition 3.1, we get

$$R(X, Y)Z = \frac{1}{2(n-1)} [S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX - g(X, Z)QY]. \quad (3.1)$$

Taking $Z = \xi$ in (3.1) and using (2.1), (2.7) and (2.8), we obtain

$$[\eta(Y)X - \eta(X)Y] = \frac{1}{(n-1)\alpha^2} [\eta(Y)QX - \eta(X)QY]. \quad (3.2)$$

Again, putting $Y = \xi$ in (3.2) and using relation (2.1) and (2.8), we obtain

$$QX = (n-1)\alpha^2 X \Leftrightarrow S(X, Y) = (n-1)\alpha^2 g(X, Y). \quad (3.3)$$

Thus, we get the following theorem

Theorem 3.1. *If an n-dimensional Lorentzian α -Sasakian manifold M^n is M-Projectively flat, then it is an Einstein manifold and Ricci tensor of M has the form $S(X, Y) = (n-1)\alpha^2 g(X, Y)$.*

In this case, by using (3.3) in (3.1), we obtain

$$R(X, Y)Z = \alpha^2 \{g(Y, Z)X - g(X, Z)Y\}. \quad (3.4)$$

Theorem 3.2. *If an n-dimensional Lorentzian α -Sasakian manifold M^n is M-Projectively flat, then it is an locally isometric to the unit sphere $S^n(c)$, where $c = \alpha^2$.*

4. M-Projectively Flat Lorentzian α -Sasakian Manifold Satisfying $R(X, Y) \cdot S = 0$.

In the present section, we consider that M^n is an M-projectively flat Lorentzian α -Sasakian manifold (M^n, g) satisfying the condition $R(X, Y) \cdot S = 0$. Thus we have

$$S(R(X, Y)Z, U) + S(Z, R(X, Y)U) = 0. \quad (4.1)$$

In view of (3.1) in (4.1), we obtain

$$\begin{aligned} & \frac{1}{2(n-1)} [S(QX, U)g(Y, Z) - S(QY, U)g(X, Z) \\ & + S(QX, Z)g(Y, U) - S(QY, Z)g(X, U)] = 0. \end{aligned} \quad (4.2)$$

Setting $Y = Z = \xi$ in (4.2) and using (2.1) and (2.8), we obtain

$$[S(QX, U) + \eta(X)S(Q\xi, U) - \eta(U)S(QX, \xi) + g(X, U)S(Q\xi, \xi)] = 0. \quad (4.3)$$

Again, by using (2.8) in (4.3), we find

$$-S(QX, U) - (n-1)^2 \alpha^4 \eta(X)\eta(U) + \eta(U)S(QX, \xi) + (n-1)^2 \alpha^4 g(X, U) = 0. \quad (4.4)$$

Let λ be the eigen value of the endomorphism Q corresponding to an eigen vector X . Then putting $QX = \lambda X$ in (4.4) and using relation $g(QX, Y) = S(X, Y)$, we find

$$\begin{aligned} & -\lambda^2 g(X, U) + (n-1)\alpha^2 \lambda \eta(X)\eta(U) - (n-1)^2 \alpha^4 \eta(X)\eta(U) \\ & + (n-1)^2 \alpha^4 g(X, U) = 0. \end{aligned} \quad (4.5)$$

Now, putting $U = \xi$ in (4.5), we obtain

$$[\lambda^2 + (n-1)\alpha^2 \lambda - 2(n-1)^2 \alpha^4] \eta(X) = 0. \quad (4.6)$$

In this case, since $\eta(X) \neq 0$, the relation (4.6) implies that

$$\lambda^2 + (n-1)\alpha^2 \lambda - 2(n-1)^2 \alpha^4 = 0. \quad (4.7)$$

From (4.7) it follows that the endomorphism Q has two different non-zero eigenvalues, namely, $(n-1)\alpha^2$ and $-2(n-1)\alpha^2$. Thus we can state :

Theorem 4.1. *Let M^n be an n-dimensional M-Projectively flat Lorentzian α -Sasakian manifold satisfies $R(X, Y) \cdot S = 0$, then symmetric endomorphism Q of the tangent space corresponding to S has two different non-zero eigenvalues.*

5. Conservative M-Projective Curvature Tensor on Lorentzian α -Sasakian Manifold

Definition 5.1. The Lorentzian α -Sasakian manifold (M^n, g) is said to be M-projective conservative if,

$$\operatorname{div}M = 0, \quad (5.1)$$

where div denotes the divergence.

Taking the covariant derivative of (1.1), we get

$$\begin{aligned} (\nabla_U M)(X, Y)Z &= (\nabla_U R)(X, Y)Z - \frac{1}{2(n-1)} [(\nabla_U S)(Y, Z)X - (\nabla_U S)(X, Z)Y \\ &+ g(Y, Z)(\nabla_U Q)X - g(X, Z)(\nabla_U Q)Y]. \end{aligned} \quad (5.2)$$

Contracting with respect to U in (5.2), we obtain

$$\begin{aligned} (\operatorname{div}M)(X, Y)Z &= (\operatorname{div}R)(X, Y)Z - \frac{1}{2(n-1)} [(\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z) \\ &+ g(Y, Z)\operatorname{div}QX - g(X, Z)\operatorname{div}QY]. \end{aligned} \quad (5.3)$$

We know that

$$\operatorname{div}Q(X) = \frac{1}{2} \nabla_X r. \quad (5.4)$$

By virtue of (5.4) in (5.3), we obtain

$$\begin{aligned} (\operatorname{div}M)(X, Y)Z &= (\operatorname{div}R)(X, Y)Z - \frac{1}{2(n-1)} [(\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z) \\ &+ \frac{1}{2} g(Y, Z)\nabla_X r - \frac{1}{2} g(X, Z)\nabla_Y r]. \end{aligned} \quad (5.5)$$

But from [4], we have

$$\operatorname{div}R = (\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z). \quad (5.6)$$

Again, by virtue of (5.1) and (5.6) in (5.5), reduces to

$$(\nabla_X S)(Y, Z) - (\nabla_Y S)(X, Z) = \frac{1}{2(2n-3)} \{g(Y, Z)\nabla_X r - g(X, Z)\nabla_Y r\}. \quad (5.7)$$

Setting $X = \xi$ in (5.7), we obtain

$$(\nabla_\xi S)(Y, Z) - (\nabla_Y S)(\xi, Z) = \frac{1}{2(2n-3)} \{g(Y, Z)\nabla_\xi r - g(\xi, Z)\nabla_Y r\}. \quad (5.8)$$

Further, we know that

$$\begin{aligned} (\nabla_\xi S)(X, Y) &= \xi S(X, Y) - S(\nabla_\xi X, Y) - S(X, \nabla_\xi Y) \\ &= \xi S(X, Y) - S([\xi, X] + \nabla_X \xi, Y) - S(X, [\xi, Y] + \nabla_Y \xi) \\ &= \xi S(X, Y) - S([\xi, X], Y) - S(\nabla_X \xi, Y) - S(X, [\xi, Y]) - S(X, \nabla_Y \xi) \\ &= (L_\xi S)(X, Y) - S(\nabla_X \xi, Y) - S(X, \nabla_Y \xi). \end{aligned} \quad (5.9)$$

The Lie derivative of metric g along with vector field X is

$$(L_X g)(Y, Z) = L_X g(Y, Z) - g(L_X Y, Z) - g(Y, L_X Z). \quad (5.10)$$

Setting $X = \xi$ in (5.10) and using (2.4), we obtain

$$(L_{\xi}g)(Y, Z) = -2\alpha g(\phi Y, Z). \quad (5.11)$$

We now recall that $g(QX, Y) = S(X, Y)$ and using relation (5.11), we get

$$(L_{\xi}S)(Y, Z) = -2\alpha S(\phi Y, Z). \quad (5.12)$$

Using (2.4) and (5.12) in (5.9), we obtain

$$(\nabla_{\xi}S)(Y, Z) = 0, \quad (5.13)$$

which implies

$$\nabla_{\xi}r = 0. \quad (5.14)$$

By virtue of (5.8) and using (2.2), (2.4), (5.13) and (5.14), we obtain

$$S(\phi Y, Z) = (n-1)\alpha^2 g(\phi Y, Z) + \frac{1}{2\alpha(2n-3)}\eta(Z)dr(Y). \quad (5.15)$$

Replacing $Z = \phi Z$ in (5.15) and using (2.2) and (2.9), we obtain

$$S(Y, Z) = (n-1)\alpha^2 g(Y, Z). \quad (5.16)$$

Contracting the equation (5.16), we obtain

$$r = n(n-1)\alpha^2. \quad (5.17)$$

Thus, we can state the following:

Theorem 5.1. *Let M^n be an n-dimensional M-Projective curvature tensor of Lorentzian α -Sasakian manifold is conservative. Then M^n is an Einstein manifold with a scalar curvature is constant.*

6. Irrotational M-Projective Curvature Tensor on η -Einstein Lorentzian α -Sasakian Manifold

Definition 6.1. *The rotation (curl) of M-projective curvature tensor on a Lorentzian α -Sasakian manifold M^n is defined as*

$$\begin{aligned} RotM &= (\nabla_U M)(X, Y)Z + (\nabla_X M)(U, Y)Z \\ &+ (\nabla_Y M)(X, U)Z - (\nabla_Z M)(X, Y)U. \end{aligned} \quad (6.1)$$

By taking into account of second Bianchi identity for Riemannian connection ∇ , (6.1) becomes

$$RotM = -(\nabla_Z M)(X, Y)U. \quad (6.2)$$

If the M-projective curvature tensor is irrotational, then $curl M = 0$ and so by (6.2), we get

$$(\nabla_Z M)(X, Y)U = 0,$$

which implies

$$\nabla_Z(M(X, Y)U) = M(\nabla_Z X, Y)U + M(X, \nabla_Z Y)U + M(X, Y)\nabla_Z U. \quad (6.3)$$

Putting $U = \xi$ in (6.3), we obtain

$$\nabla_Z(M(X, Y)\xi) = M(\nabla_Z X, Y)\xi + M(X, \nabla_Z Y)\xi + M(X, Y)\nabla_Z \xi. \quad (6.4)$$

Now, substituting $Z = \xi$ in (1.1) and using (2.1), (2.7), (2.8) and (2.11), we obtain

$$M(X, Y)\xi = \lambda[\eta(X)Y - \eta(Y)X], \quad (6.5)$$

where

$$\lambda = \frac{1}{2(n-1)^2} [n(n-1)\alpha^2 - r]. \quad (6.6)$$

By virtue of (6.5) and (2.4) in (6.4), we obtain

$$M(X, Y)\phi Z = \lambda[g(Y, \phi Z)X - g(X, \phi Z)Y]. \quad (6.7)$$

Replacing Z by ϕZ in (6.7) and simplifying by using (2.1), we get

$$M(X, Y)Z = \lambda[g(Y, Z)X - g(X, Z)Y]. \quad (6.8)$$

In addition from (1.1) and (6.8), we have

$$\begin{aligned} \lambda[g(Y, Z)X - g(X, Z)Y] &= R(X, Y)Z - \frac{1}{2(n-1)} [S(Y, Z)X - S(X, Z)Y \\ &+ g(Y, Z)QX - g(X, Z)QY]. \end{aligned} \quad (6.9)$$

Contracting (6.9) over X and using (6.6), we can find

$$S(Y, Z) = (n-1)\alpha^2 g(Y, Z). \quad (6.10)$$

from (6.10), we obtain

$$r = n(n-1)\alpha^2. \quad (6.11)$$

As a result of (1.1), (6.6), (6.8), (6.10) and (6.11), we obtain

$$R(X, Y)Z = \alpha^2 [g(Y, Z)X - g(X, Z)Y]. \quad (6.12)$$

Thus we can state following:

Theorem 6.1. *The M -projective curvature tensor in a Lorentzian α -Sasakian manifold M^n is irrotational, then it is locally isometric to the unit sphere $S^n(c)$, where $c = \alpha^2$.*

7. Lorentzain α -Sasakian Manifold Satisfying $M \cdot R = 0$.

Consider an Lorentzain α - Sasakian manifold satisfying the condition

$$M(X, Y) \cdot R = 0. \quad (7.1)$$

Then from the relation (7.1), it follows that

$$\begin{aligned} M(\xi, X)R(Y, Z)U - R(M(\xi, X)Y, Z)U \\ - R(Y, M(\xi, X)Z)U - R(Y, Z)M(\xi, X)U = 0. \end{aligned} \quad (7.2)$$

In view of (2.16), it follows from (7.2) that

$$\begin{aligned} \frac{\alpha^2}{2} [g(R(Y, Z)U, X)\xi - \eta(R(Y, Z)U)X - g(X, Y)R(\xi, Z)U - \eta(Y)R(X, Z)U \\ - g(X, Z)R(Y, \xi)U - \eta(Z)R(Y, X)U - g(X, U)R(Y, Z)\xi - \eta(U)R(Y, Z)X] \\ - \frac{1}{2(n-1)} [g(R(Y, Z)U, QX)\xi - \eta(R(Y, Z)U)QX] - S(X, Y)R(\xi, Z)U \\ + \eta(Y)R(QX, Z)U - S(X, Z)R(Y, \xi)U + \eta(Z)R(Y, QX)U \\ - S(X, U)R(Y, Z)\xi + \eta(Z)R(Y, Z)QX] = 0. \end{aligned} \quad (7.3)$$

Taking the inner product of the above equation with ξ , we get

$$\begin{aligned} & -\frac{\alpha^2}{2}R'(Y,Z,U,X) - \frac{\alpha^2}{2}[g(X,Y)\eta(R(\xi,Z)U) - \eta(Y)\eta(R(X,Z)U) \\ & + g(X,Z)\eta(R(Y,\xi)U) - \eta(Z)\eta(R(Y,X)U) + g(X,U)\eta(R(Y,Z)\xi) \\ & - \eta(U)\eta(R(Y,Z)X)] + \frac{1}{2(n-1)}R'(Y,Z,U,QX) + \frac{1}{2(n-1)}[S(X,Y)\eta(R(\xi,Z)U) \\ & - \eta(Y)\eta(R(QX,Z)U) + S(X,Z)\eta(R(Y,\xi)U) - \eta(Z)\eta(R(Y,QX)U) \\ & + S(X,U)\eta(R(Y,Z)\xi) - \eta(U)\eta(R(Y,Z)QX)] = 0. \end{aligned} \quad (7.4)$$

By virtue of (2.5), (2.6) and (2.7) in (7.4), we obtain

$$\begin{aligned} & -\frac{\alpha^2}{2}R'(Y,Z,U,X) + \frac{1}{2(n-1)}R'(Y,Z,U,QX) \\ & + \frac{\alpha^4}{2}\{g(X,Y)g(Z,U) - g(X,Z)g(Y,U)\} \\ & - \frac{\alpha^2}{2(n-1)}\{S(X,Y)g(Z,U) - S(X,Z)g(Y,U)\} = 0. \end{aligned} \quad (7.5)$$

Setting $Z = U = e_i$ in (7.5) and taking summation over i , $1 \leq i \leq n$, we obtain

$$S^2(X,Y) = (n-1)\alpha^2\{2S(X,Y) - (n-1)\alpha^2g(X,Y)\}. \quad (7.6)$$

Therefore the S^2 of the Ricci tensor S is the linear combination of the Ricci tensor and the metric tensor g . Here the $(0,2)$ -tensor S^2 is defined by $S^2(X,Y) = S(QX,Y)$. Hence we have the following:

Theorem 7.1. *Let M be an n -dimensional Lorentzian α -Sasakian manifold is satisfying the condition $M \cdot R = 0$. Then the S^2 of the Ricci tensor S is the linear combination of the Ricci tensor and the metric tensor g has the form $S^2(X,Y) = (n-1)\alpha^2\{2S(X,Y) - (n-1)\alpha^2g(X,Y)\}$.*

It is well known that:

Lemma 7.1. [21] *If $\theta = g \wedge A$ be the Kulkarni-Nomizu product of g and A , where g being Riemannian metric and A be a symmetric tensor of type $(0,2)$ at point x of a semi-Reimannian manifold (M^n, g) . Then relation $\theta \cdot \theta = \beta Q(g, \theta)$, $\beta \in \mathbf{R}$ is true at x if and only if the condition $A^2 = \beta A + \mu g$, $\mu \in \mathbf{R}$ holds at x*

In consequence of Theorem 7.1 and Lemma 7.1, we have the following corollary:

Corollary 7.1. *Let M an n -dimensional Lorentzain α -Sasakian manifold is satisfying the condition $M(X,Y) \cdot R = 0$, then $\theta \cdot \theta = \beta Q(g, \theta)$, where $\theta = g \wedge S$ and $\beta = 2(n-1)\alpha^2$.*

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