



Article On One- and Two-Dimensional α–Stancu–Schurer–Kantorovich Operators and Their Approximation Properties

Md. Heshamuddin ¹, Nadeem Rao ², Bishnu P. Lamichhane ³, Adem Kiliçman ^{4,*} and Mohammad Ayman-Mursaleen ^{3,4,*}

- ¹ Department of Natural & Applied Sciences, Glocal University, Saharanpur-247121, Uttar Pradesh, India
- ² Department of Applied Sciences & Humanities, Panipat Institute of Engineering and Technology, Pattikalyana, Samalkha, Panipat-132102, Haryana, India
- ³ School of Information & Physical Sciences, The University of Newcastle, University Drive, Callaghan, NSW 2308, Australia
- ⁴ Department of Mathematics & Statistics, Faculty of Science, Universiti Putra Malaysia, UPM Serdang 43400, Selangor, Malaysia
- * Correspondence: akilic@upm.edu.my (A.K.); mohdaymanm@gmail.com or mohammad.mursaleen@uon.edu.au or mursaleen.ayman@student.upm.edu.my (M.A.-M.)

Abstract: The goal of this research article is to introduce a sequence of α -Stancu–Schurer–Kantorovich operators. We calculate moments and central moments and find the order of approximation with the aid of modulus of continuity. A Voronovskaja-type approximation result is also proven. Next, error analysis and convergence of the operators for certain functions are presented numerically and graphically. Furthermore, two-dimensional α -Stancu–Schurer–Kantorovich operators are constructed and their rate of convergence, graphical representation of approximation and numerical error estimates are presented.

Keywords: rate of convergence; order of approximation; modulus of continuity; weighted approximation; A-statistical approximation

MSC: 41A10; 41A25; 41A28; 41A35; 41A36

1. Introduction

Operator theory has been a fascinating field of research during the last two decades due to the advent of the computer. It plays an important role in applied and pure mathematics *viz*. fixed point theory [1], numerical analysis [2], image processing [3], neural networks, machine learning [4], finding solutions for ordinary and partial differential equations [5], bio-inspired soft computing [6], and robotics [7]. In the computational aspects of mathematics and the shape of geometric objects, CAGD (computer-aided geometric design) plays an interesting role in the mathematical description. It focuses on mathematics, which is compatible with computers in shape designing. To investigate the behavior of parametric surfaces and curves, control nets and control points have significant roles, respectively. CAGD is widely used as an application in applied mathematics and industries. It has several applications in other branches of sciences, e.g., approximation theory, computer graphics, data structures, numerical analysis, and computer algebra. In 1912, Bernstein [8] was the first who introduced a sequence of polynomials to present the simplest and shortest proof of the celebrated Weierstrass approximation theorem with the aid of binomial distribution as follows:

$$\mathbb{B}_{l}(g;y) = \sum_{\nu=0}^{l} g\left(\frac{\nu}{l}\right) \begin{pmatrix} l \\ \nu \end{pmatrix} y^{\nu} (1-y)^{l-\nu}, \quad y \in [0,1], \tag{1}$$



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Copyright: © 2022 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https:// creativecommons.org/licenses/by/ 4.0/). where g is a bounded function defined on [0, 1]. The basis $\binom{l}{\nu}y^{\nu}(1-y)^{l-\nu}$ of the Bernstein polynomials (1) has significant role in preserving the shape of the surfaces or curves (see [9–11]). Graphic design programs *viz*. Photoshop Inkspaces and Adobe's Illustrator deal with Bernstein polynomials in the form of Bèzier curves. To preserve the shape of the parametric surface or curve, it depends on the basis $\binom{l}{\nu}y^{\nu}(1-y)^{l-\nu}$, which is used to design the curves.

In 1962, Schurer [12] presented the following modification of the Bernstein operators (1) denoted as $\mathbb{B}_{m,l}$: $C[0, 1+l] \rightarrow C[0, 1]$ and given by:

$$\mathbb{B}_{m,l}(h;y) = \sum_{j=0}^{m+l} h\left(\frac{j}{m}\right) \binom{m+l}{j} y^j (1-y)^{m+l-j}, y \in [0,1].$$
(2)

for $l \in \mathbb{N} \cup \{0\}$ and $h \in C[0, 1 + l]$. Note that the operators (2) are an improved version of the operators (1) as the domain of the function is extended from C[0, 1] to C[0, 1 + l].

In the recent past, Chen et al. [13] introduced a family of generalized Bernstein operators that is termed as a α -Bernstein operator based on $\alpha \in [-1, 1]$ as:

$$\mathcal{P}_{m,\alpha}(h;y) = \sum_{j=0}^{m} h\left(\frac{j}{m}\right) \mathcal{Q}_{m,j}^{(\alpha)}(y),$$
(3)

where the α -Bernstein polynomial $\mathcal{Q}_{m,j}^{(\alpha)}(y)$ of degree m is given by $\mathcal{Q}_{1,0}^{(\alpha)}(y) = 1 - y$, $\mathcal{Q}_{1,1}^{(\alpha)}(y) = y$ and:

$$\begin{aligned} \mathcal{Q}_{m,j}^{(\alpha)}(y) &= \left[\binom{m-2}{j} (1-\alpha)y + \binom{m-2}{j-2} (1-\alpha)(1-y) \right. \\ &+ \left. \binom{m}{j} \alpha y(1-y) \right] \times y^{j-1} (1-y)^{m-j-1}, \end{aligned}$$

with $m \ge 2$, $y \in [0, 1]$. Furthermore, Cai et al. [14] found that the α -Bernstein operators are positive linear operators for $0 \le \alpha \le 1$. In [13], the authors investigated various pointwise and uniform approximation results. Furthermore, many researchers, e.g., Kilicman et al. [15], Acar et al. [16], Aral et al. [17], Cai et al. [18,19], Çetin et al. [20,21], Mohiuddine et al. [22], Aslan et al. [23,24], Acu et al. [25], Agrawal [26], Nasiruzzaman et al. [27], and Ayman-Mursaleen et al. [28,29], have intensively studied α -Bernstein operators and their modifications for better approximation results. In [30–32] some interesting studies have been carried out. Recently, Çetin [33] introduced a modification of Bernstein–Schurer operators introduced in (3) as:

$$\mathcal{L}_{m,\alpha,l}(h;y) = \sum_{j=0}^{m+l} h\left(\frac{j}{m}\right) \mathcal{C}_{m,j}^{(\alpha)}(y), \tag{4}$$

where the α -BernsteinSchurer polynomial $C_{m,j}^{(\alpha)}(y)$ of degree m is introduced by $C_{1,0}^{(\alpha)}(y) = 1 - y$, $C_{1,1}^{(\alpha)}(y) = y$ and:

$$\mathcal{C}_{m,j}^{(\alpha)}(y) = \left\{ \binom{m+l-2}{j} (1-\alpha)y + \binom{m+l-2}{j-2} (1-\alpha)(1-y) \right\}$$
(5)

+
$$\binom{m+l}{j} \alpha y(1-y) \bigg\} y^{j-1} (1-y)^{m+l-j-1},$$
 (6)

where $m + l \ge 2, y \in [0, 1]$. Furthermore, Rao et al. [34] constructed α -Stancu–Schurer operators to approximate a class of continuous functions as:

$$\mathcal{D}_{m,\alpha,l}^{\delta,\gamma}(h;y) = \sum_{j=0}^{m+l} \mathcal{C}_{m,j}^{(\alpha)}(y)h\bigg(\frac{j+\delta}{m+\gamma}\bigg),\tag{7}$$

whenever the above sum converges. Here, $C_{m,j}^{(\alpha)}$ is given by (5) and $0 \le \delta \le \gamma$. The operators (7) can approximate only the continuous functions. To approximate the wider class of functions, i.e., the Lebesgue integrable functions, we define a new sequence of linear positive operators as follows:

$$\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(h;y) = (m+\gamma+1) \sum_{j=0}^{m+l} \mathcal{C}_{m,j}^{(\alpha)}(y) \int_{\frac{j+\delta}{m+\gamma+1}}^{\frac{j+\delta+1}{m+\gamma+1}} h(u) du.$$
(8)

In the subsequent sections, we obtain moments and central moments, the order of approximation, local and global approximation results in terms of modulus of continuity, Peetre's K-functional and second-order modulus of smoothness. A Voronovskaja-type approximation result is also proven. Lastly, two-dimensional α -Stancu-Schurer-Kantorovich operators are introduced and their rate of convergence, numerical error estimates and graphical representation are also presented.

2. Preliminary Results

Here, we consider $e_j(t) = t^j$ and $\psi_j(\mu, t) = (\mu - t)^j$, $j \in \{0, 1, 2\}$ as test functions and central moments, respectively.

Lemma 1 ([34]). Let the operators $\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(\cdot;\cdot)$ be introduced by (7). Then, we have:

$$\begin{split} \mathcal{D}_{m,\alpha,l}^{\delta,\gamma}(e_{0};x) &= 1, \\ \mathcal{D}_{m,\alpha,l}^{\delta,\gamma}(e_{1};x) &= \left(\frac{m+l}{m+\gamma}\right)x + \frac{\delta}{m+\gamma}, \\ \mathcal{D}_{m,\sigma,l}^{\delta,\gamma}(e_{2};x) &= \left(\frac{m+l}{m+\gamma}\right)^{2}x^{2} + \left\{\frac{[m+l+2(1-\sigma)]}{(m+\gamma)^{2}}(1-x) + \frac{2\delta(m+l)}{(m+\gamma)^{2}}\right\}x \\ &+ \frac{\delta^{2}}{(m+\gamma)^{2}}, \\ \mathcal{D}_{m,\alpha,l}^{\delta,\gamma}(e_{4};x) &= \left\{\frac{[(m+l)^{4} - 6(m+l)^{3} + (12\sigma - 1)(m+l)^{2} + 6(9 - 10\sigma)(m+l)]}{(m+\gamma)^{4}} \\ &- \frac{72(1-\sigma)}{(m+\gamma)^{4}}\right\}x^{4} + \mathcal{O}\left(\frac{1}{m+\gamma}\right). \end{split}$$

Lemma 2. Let the operators $\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(\cdot;\cdot)$ be introduced by (8). Then, we have:

$$\begin{split} \mathcal{D}^{*\delta,\gamma}_{m,\sigma,l}(e_0;x) &= 1, \\ \mathcal{D}^{*\delta,\gamma}_{m,\sigma,l}(e_1;x) &= \left(\frac{m+l}{m+\gamma+1}\right)x + \frac{\delta}{m+\gamma+1} + \frac{1}{2(m+\gamma+1)}, \\ \mathcal{D}^{*\delta,\gamma}_{m,\sigma,l}(e_2;x) &= \left(\frac{m+l}{m+\gamma+1}\right)^2 x^2 + \left\{\frac{[m+l+2(1-\sigma)]}{(m+\gamma+1)^2}(1-x) + \frac{2\delta(m+l)}{(m+\gamma+1)^2}\right\}x \\ &+ \frac{\delta^2}{(m+\gamma+1)^2} + \left(\frac{m+l}{(m+\gamma+1)^2}\right)x + \frac{\delta}{(m+\gamma+1)^2} \\ &+ \frac{1}{(m+\gamma+1)^2} + \frac{1}{3(m+\gamma+1)^2}. \end{split}$$

Proof. We prove above equations with the aid of Lemma 1 as:

$$\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(e_0;x) = (m+\gamma+1) \sum_{j=0}^{m+l} \mathcal{C}_{m,j}^{(\alpha)}(x) \int_{\frac{j+\delta}{m+\gamma+1}}^{\frac{j+\delta+1}{m+\gamma+1}} du$$
$$= 1.$$

$$\begin{split} \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(e_{1};x) &= (m+\gamma+1) \sum_{j=0}^{m+l} \mathcal{C}_{m,j}^{(\alpha)}(x) \int_{\frac{j+\delta}{m+\gamma+1}}^{\frac{j+\delta+\gamma}{m+\gamma+1}} u du \\ &= \left(\frac{m+\gamma}{m+\gamma+1}\right) \mathcal{D}_{m,\alpha,l}^{\delta,\gamma}(e_{1};x) + \left(\frac{1}{2(m+\gamma+1)}\right) \mathcal{D}_{m,\alpha,l}^{\delta,\gamma}(e_{0};x) \\ &= \left(\frac{m+l}{m+\gamma+1}\right) x + \frac{\delta}{m+\gamma+1} + \frac{1}{2(m+\gamma+1)} \\ \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(e_{2};x) &= (m+\gamma+1) \sum_{j=0}^{m+l} \mathcal{C}_{m,j}^{(\alpha)}(x) \int_{\frac{j+\delta}{m+\gamma+1}}^{\frac{j+\delta+1}{m+\gamma+1}} u^{2} du \\ &= \left(\frac{m+\gamma}{m+\gamma+1}\right)^{2} \mathcal{D}_{m,\alpha,l}^{\delta,\gamma}(e_{2};x) + \left(\frac{m+\gamma}{(m+\gamma+1)^{2}}\right) \mathcal{D}_{m,\alpha,l}^{\delta,\gamma}(e_{1};x) + \frac{1}{(m+\gamma+1)} \mathcal{D}_{m,\alpha,l}^{\delta,\gamma}(e_{0};x) \\ &= \left(\frac{m+l}{m+\gamma+1}\right)^{2} x^{2} + \left\{\frac{[m+l+2(1-\alpha)]}{(m+\gamma+1)^{2}}(1-x) + \frac{2\delta(m+l)}{(m+\gamma+1)^{2}}\right\} x \\ &+ \frac{\delta^{2}}{(m+\gamma+1)^{2}} + \left(\frac{m+l}{(m+\gamma+1)^{2}}\right) x + \frac{\delta}{(m+\gamma+1)^{2}} \\ &+ \left\{\frac{[m+l+6(1-\alpha)]}{(m+\gamma+1)^{3}}\right\} + \frac{3\delta[m+l+2(1-\alpha)]}{(m+\gamma+1)^{3}}(1-x) + \frac{3\delta^{2}(m+l)}{(m+\gamma+1)^{3}}(1-x) \\ &+ \frac{\delta^{3}}{(m+\gamma+1)^{3}} + 2\left(\frac{(m+l)^{2}}{(m+\gamma+1)^{3}}\right) x^{2} + \left\{\frac{[m+l+2(1-\alpha)]}{(m+\gamma+1)^{3}}(1-x) \\ &+ \frac{2\delta(m+l)}{(m+\gamma+1)^{3}}\right\} x + \frac{\delta^{2}}{(m+\gamma+1)^{3}} + \frac{1}{2(m+\gamma+1)^{2}} + \left(\frac{m+l}{(m+\gamma+1)^{3}}\right) x \\ &+ \frac{\delta}{(m+\gamma+1)^{3}} + \frac{1}{2(m+\gamma+1)^{3}} + \frac{1}{4(m+\gamma+1)^{3}}. \end{split}$$

This completes the proof. \Box

Lemma 3. Let $\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(.;.)$ be the sequence of operators introduced in (8). Then,

$$\begin{split} \mathcal{D}^{*\delta,\gamma}_{m,\alpha,l}(\psi^{1}_{x}(t);x) &= \left(\frac{l-\gamma-1}{m+\gamma+1}\right)x + \frac{\delta}{m+\gamma+1} + \frac{1}{2(m+\gamma+1)},\\ \mathcal{D}^{*\delta,\gamma}_{m,\alpha,l}(\psi^{2}_{x}(t);x) &= \left(\frac{m+l}{m+\gamma+1}\right)^{2}x^{2} + \left\{\frac{[m+l+2(1-\alpha)]}{(m+\gamma+1)^{2}}(1-x) + \frac{2\delta(m+l)}{(m+\gamma+1)^{2}}\right\}x\\ &+ \frac{\delta^{2}}{(m+\gamma+1)^{2}} + \left(\frac{m+l}{(m+\gamma+1)^{2}}\right)x + \frac{\delta}{(m+\gamma+1)^{2}}\\ &+ \frac{1}{(m+\gamma+1)^{2}} + \frac{1}{3(m+\gamma+1)^{2}} - 2\left(\frac{m+l}{m+\gamma+1}\right)x^{2}\\ &- \frac{2x\delta}{m+\gamma+1} - \frac{x}{(m+\gamma+1)} - x^{2}. \end{split}$$

Proof. In view of Lemma 2 and using property of linearity, we can easily calculate

$$\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(\psi_x^1(t);x) = \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(t;x) - x\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(1;0)$$

$$= \left(\frac{m+l}{m+\gamma+1}\right)x + \frac{\delta}{m+\gamma+1} + \frac{1}{2(m+\gamma+1)} - x$$

$$= \left(\frac{m+l}{m+\gamma+1} - 1\right)x + \frac{\delta}{m+\gamma+1} + \frac{1}{2(m+\gamma+1)}$$

$$= \left(\frac{l-r-1}{m+\gamma+1}\right)x + \frac{\delta}{m+\gamma+1} + \frac{1}{2(m+\gamma+1)}.$$

Now,

$$\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(\psi_x^2(t);x) = \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(t^2;x) - 2x\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(t;x) + x^2\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(1;0).$$

Similarly, we can obtain the second central moment by using Lemma 2 and the proof follows immediately. \Box

3. Order of Approximation

Theorem 1. Let $h \in C[0, 1+l]$ for $l \in \mathbb{R}^+$ and $\omega(h; \theta_{m,\gamma})$ be the modulus of smoothness. Then,

$$\left|\mathcal{D}_{m,\alpha,l}^{*\delta,\theta_{m,\gamma}}(h;x) - h(x)\right| \leq \left\{1 + \sqrt{\Gamma_m^{\delta,\gamma}(y)}\right\} \omega(h;\theta_{m,\gamma})$$

where $\theta_{m,\gamma} = (m + \gamma + 1)^{-\frac{1}{2}}$ and

$$\Gamma_m^{\delta,\gamma}(x) = \frac{(m-l)^2 x^2 + [m+l+2(1-\alpha)]x(1-x) + 2\delta(l-\gamma+1)x + \delta^2 + (m+l)x + \delta}{(m+\gamma+1)}$$

Proof. For $h \in C[0, 1 + l]$, $y \in [0, 1 + l]$ and in view of monotonicity (let $T : C[a, b] \rightarrow C[a, b]$ be an operator and $f, g \in C[a, b]$; then, $T(f) \leq T(g)$ or $T(f) \geq T(g)$ as $f(x) \leq g(x)$ or $f(x) \geq g(x) \forall x \in [a, b]$, respectively) and the linearity property of the operators given by (8), we can easily find:

$$\begin{split} \left| \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(h;x) - h(x) \right| &\leq \left\{ 1 + \theta_{m,\gamma}^{-1} \sqrt{\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(\psi_x(t)^2;x)} \right\} \omega(h;\theta_{m,\gamma}) \\ &\leq \left\{ 1 + \sqrt{\frac{(m-l)^2 x^2 + [m+l+2(1-\alpha)]x(1-x) + 2\delta(l-\gamma+1)x + \delta^2 + (m+l)x + \delta}{(m+\gamma+1)}} \right\} \omega(h;\theta_{m,\gamma}), \end{split}$$

where $\theta_{m,\gamma} \ge 0$. Thus, we arrive at the required result. \Box

Next, we give the order of approximation for operators defined in (8) using the modulus of smoothness of the first derivative of the function, i.e., $\omega(f'; \theta_{m,\gamma}) = \omega_1(f; \theta_{m,\gamma})$.

Theorem 2. For the operators defined in (8) and $0 \le \theta \le \gamma$, we have:

$$\begin{aligned} \left| \mathcal{D}^{*\delta,\gamma}_{m,\alpha,l}(h;y) - h(y) \right| &\leq \omega_1 \left((m+\gamma+1)^{\frac{-1}{2}} \right) \sqrt{\mathcal{D}^{*\delta,\gamma}_{m,\alpha,l}(\tau_t^2(t);y)} \\ &\left\{ 1 + \sqrt{(m+\gamma+1)} \sqrt{\mathcal{D}^{*\delta,\gamma}_{m,\alpha,l}(\tau_t^2(t);y)} \right\}. \end{aligned}$$

Proof. For any $a \le y_1, y_2 \le b$, we know that:

$$h(y_1) - h(y_2) = (y_1 - y_2)h'(\xi) = (y_1 - y_2)h'(y_1) + (y_1 - y_2)[h'(\xi) - h'(y_1)],$$
(9)

where $\xi \in (y_1, y_2)$. Furthermore, we have:

$$|(y_1 - y_2)[h'(\xi) - h'(y_1)]| \le |y_1 - y_2|(\lambda + 1)\omega_1(\theta_{m,\gamma}), \quad \lambda = \lambda(y_1, y_2; \theta_{m,\gamma}).$$
(10)

Next, we obtain:

$$\left|\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(h;y) - h(y)\right| = \left|\sum_{j=0}^{\infty} C_{m,j}^{(\alpha)}(y) \left\{ h\left(\frac{j+\delta}{m+\gamma+1}\right) - h(y) \right\} \right|.$$
(11)

In view of (9)–(11), we obtain

$$\begin{aligned} \left| \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(h;y) - h(y) \right| &\leq \left| \sum_{j=0}^{\infty} C_{m,j}^{(\alpha)}(y) \left(\frac{j+\delta}{m+\gamma+1} - y \right) h'(y) \right| \\ &+ \omega_1(\theta_{m,\gamma}) \sum_{j=0}^{\infty} \left| \frac{j+\delta}{m+\gamma+1} - y \right| (\lambda+1) C_{m,j}^{(\alpha)}(y) \\ &\leq \omega_1(\theta_{m,\gamma}) \left\{ \sum_{j=0}^{\infty} \left| \frac{j+\delta}{m+\gamma+1} - y \right| C_{m,j}^{(\alpha)}(y) \right\} \\ &+ \sum_{\lambda \ge 1} \left| \frac{j+\delta}{m+\gamma+1} - y \right| \lambda \left(y_1, \frac{j+\delta}{m+\gamma+1}; \theta \right) C_{m,j}^{(\alpha)}(y) \right\} \\ &\leq \omega_1(\theta_{m\gamma}) \left\{ \sum_{j=0}^{\infty} \left| \frac{j+\delta}{m+\gamma+1} - y \right| C_{m,j}^{(\alpha)}(y) \right\} \\ &+ \theta^{-1} \sum_{j=0}^{\infty} \left(\frac{j+\delta}{m+\gamma+1} - y \right)^2 C_{m,l}^{(\alpha)}(y) \right\} \\ &\leq \omega_1(\theta_{m,\gamma}) \sqrt{\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(\tau_t^2(t);y)} \left\{ 1 + \theta_{m,\gamma}^{-1} \sqrt{\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(\tau_t^2(t);y)} \right\}. \end{aligned}$$

Choosing $\theta_{m,\gamma} = (m + \gamma + 1)^{\frac{-1}{2}}$, we obtain:

$$\begin{split} \left| \mathcal{D}^{*\delta,\gamma}_{m,\alpha,l}(h;y) - h(y) \right| &\leq \omega_1 \Big((m+\gamma+1)^{\frac{-1}{2}} \Big) \sqrt{\mathcal{D}^{*\delta,\gamma}_{m,\alpha,l}(\tau_t^2(t);y)} \\ & \left\{ 1 + \sqrt{(m+\gamma+1)} \sqrt{\mathcal{D}^{*\delta,\gamma}_{m,\alpha,l}(\tau_t^2(t);y)} \right\}, \end{split}$$

which completes the proof of Theorem 2. \Box

4. Voronovskaja-Type Results

Theorem 3. Let $0 \le \delta \le \gamma$. Then, for $h \in C^2[0, 1+l]$, we have:

$$\lim_{m\to\infty} m\Big\{\mathcal{D}^{*\delta,\gamma}_{m,\alpha,l}(h;y)-h(y)\Big\}=[(l-\gamma)y+\delta]h'(y)+\frac{y(1-y)}{2}h''(y).$$

Proof. For $y, t \in [0, 1], h \in C^2[0, 1 + l]$ and using Taylor's series expansion, one has:

$$h(t) = h(y) + (t - y)h'(y) + \frac{(t - y)^2}{2}h''(y) + \eta(t, y)(t - y)^2,$$

where $\eta(t, y)$ denotes the continuous function over C[0, 1 + l] and $\lim_{t\to y} \eta(t, y) = 0$. Operating $C_{m,j}^{\alpha}$ for both sides and summing over *j*, we have:

$$\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(h;y) = h(y)\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(1;y) + h'(y)\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(t-y;y) + \frac{h''(y)}{2}\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}\left((t-y)^{2};y\right) \\ + \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(\eta(t,y)(t-y);y).$$

From Lemma (2), we obtain:

$$\lim_{m \to \infty} m \left\{ \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(h;y) - h(y) \right\} = \left[(l-\gamma)y + \delta \right] h(y)' + \frac{y(1-y)}{2} h''(y) + \lim_{m \to \infty} \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma} \left(\eta(t;y)(t-y)^2; y \right).$$
(12)

Now, we calculate the last term in view of Hölder's inequality and Lemma (2) as:

$$m\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}\Big(\eta(t;y)(t-y)^2;y\Big) \le m^2 \mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}\Big((t-y)^4;y\Big)\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}\Big(\eta(t;y)^2;y\Big).$$

Let $\varphi(t; y) = \eta^2(t; y)$. Then, $\lim_{t \to y} \varphi(t; y) = 0$. Therefore,

$$\lim_{m\to\infty} m\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}\Big(\eta(t;y)(t-y)^2;y\Big) = 0.$$

Using this relation in Equation (12), we arrive at the desired result. \Box

5. Error Analysis

In this section, we present the convergence of the operators given in (8) for the function $h(y) = y^3 + 10y^2 - y + 1$. In Table 1, the error has been computed for different values of m = 10, 20, 30 for the operator $\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(.;.)$ by taking $\alpha = 0.9, \delta = 0.2, \gamma = 0.1, l = p = 1$, and using the error formula $E_{m,\alpha,l}^{*\delta,\gamma} = |\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(h,y) - h(y)|$. Graphical representations of the convergence and error of the operator given by (8) are shown in the graphs given in Figures 1 and 2, respectively, by taking the values of m = 10, 20, 30 and $h(y) = y^3 + 10y^2 - y + 1$.

Table 1. Error analysis for the operator $\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(.;.)$.

y	$E^{*\delta,\gamma}_{10,\alpha,l}(h;y)$	$E^{*\delta,\gamma}_{20,\alpha,l}(h;y)$	$E^{*\delta,\gamma}_{30,\alpha,l}(h;y)$
0.1	0.3359466972	0.1634341528	0.1076829667
0.2	0.5446198858	0.2725230647	0.1815299016
0.3	0.7365273448	0.3730292257	0.2496102364
0.4	0.9097637900	0.4639282561	0.3112238357
0.5	1.06236899	0.5441657615	0.3656499644
0.6	1.192318799	0.6126519842	0.4121435043
0.7	1.2975149875	0.66825566	0.4499305863
0.8	1.3757737241	0.7097969736	0.4782035582
0.9	1.4248125475	0.7360394949	0.4961151963



Figure 1. Graphical approximation representation of $\mathcal{D}_{m,\alpha,l}^{*\delta,\gamma}(\cdot,\cdot)$ with h(y).



Figure 2. Graphical representation of error.

6. Construction of Two-Dimensional α–Stancu–Schurer–Kantorovich Operators

Let $J = \{(y_1, y_2) : 0 \le y_1 \le 1 + l_1, 0 \le y_2 \le 1 + l_2\}$ and C(J) be the class of all continuous functions on J equipped with the norm $||g||_{C(J)} = sup_{(y_1, y_2) \in J} |g(y_1, y_2)|$.

Then, for all $h \in C(J)$ and $m_1, m_2 \in \mathbb{N}$, we construct a new sequence of bivariate α -Stancu–Schurer–Kantorovich operators as follows:

$$\mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(h;y_{1},y_{2}) = (m_{1}+\gamma_{1}+1)(m_{2}+\gamma_{2}+1)\sum_{j_{1}=0}^{m_{1}+l_{1}}\sum_{j_{2}=0}^{m_{2}+l_{2}}\mathcal{C}_{m_{1},j_{1}}^{(\alpha)}(y_{1})\mathcal{C}_{m_{2},j_{2}}^{(\alpha)}(y_{2})$$

$$\times \int_{\frac{j_{1}+\delta_{1}+1}{m_{1}+\gamma_{1}+1}}^{\frac{j_{1}+\delta_{1}+1}{m_{1}+\gamma_{1}+1}}h(t_{1},t_{2})dt_{1}dt_{2}\int_{\frac{j_{2}+\delta_{2}+1}{m_{2}+\gamma_{2}+1}}^{\frac{j_{2}+\delta_{2}}{m_{2}+\gamma_{2}+1}}h(t_{1},t_{2})dt_{1}dt_{2}, \quad (13)$$

where:

$$\begin{split} \mathcal{C}_{m_{i},j_{i}}^{(\alpha)}(y_{i}) &= \left\{ \binom{m_{i}+l_{i}-2}{j_{i}}(1-\alpha)y_{i} + \binom{m_{i}+l_{i}-2}{j_{i}-2}(1-\alpha)(1-y_{i}) \right. \\ &+ \left. \binom{m_{i}+l_{i}}{j_{i}}\alpha y_{i}(1-y_{i}) \right\} \times y_{i}^{j_{i}-1}(1-y_{i})^{m_{i}+l_{i}-j_{i}-1}, \ for \ i \in \{1,2\}. \end{split}$$

Lemma 4. Let $e_{i,j}(y_1, y_2) = y_1^i y_2^j \ 0 \le i, j \le 2$ such that $0 \le i + j \le 2$. Then, for the operator given by (13), we have:

$$\begin{split} \mathcal{H}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}_{m_{1}m_{2},\alpha,l_{1},l_{2}}(e_{0,0};y_{1},y_{2}) = 1, \\ \mathcal{H}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}_{m_{1}m_{2},\alpha,l_{1},l_{2}}(e_{1,0};y_{1},y_{2}) = \left(\frac{m_{1}+l}{m_{1}+\gamma_{1}+1}\right)y_{1} + \frac{\delta_{1}}{m_{1}+\gamma_{1}+1} + \frac{1}{2(m_{1}+\gamma_{1}+1)}, \\ \mathcal{H}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}_{m_{1}m_{2},\alpha,l_{1},l_{2}}(e_{0,1};y_{1},y_{2}) = \left(\frac{m_{2}+l}{m_{2}+\gamma_{2}+1}\right)y_{2} + \frac{\delta_{2}}{m_{2}+\gamma_{2}+1} + \frac{1}{2(m_{1}+\gamma_{1}+1)}, \\ \mathcal{H}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}_{m_{1}m_{2},\alpha,l_{1},l_{2}}(e_{1,1};y_{1},y_{2}) = \left(\left(\frac{m_{1}+l}{m_{1}+\gamma_{1}+1}\right)y_{1} + \frac{\delta_{1}}{m_{1}+\gamma_{1}+1} + \frac{1}{2(m_{1}+\gamma_{1}+1)}\right) \\ \times \left(\left(\frac{m_{2}+l}{m_{2}+\gamma_{2}+1}\right)y_{2} + \frac{\delta_{2}}{m_{2}+\gamma_{2}+1} + \frac{1}{2(m_{2}+\gamma_{2}+1)}\right), \\ \mathcal{H}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}_{m_{1}m_{2},\alpha,l_{1},l_{2}}(e_{0,2};y_{1},y_{2}) = \left(\frac{m_{2}+l_{2}}{m_{2}+\gamma_{2}+1}\right)^{2}y_{2}^{2} + \left\{\frac{[m_{2}+l_{2}+2(1-\alpha)]}{(m_{2}+\gamma_{2}+1)^{2}}(1-y_{2}) \right. \\ + \frac{(2\delta_{2}+1)(m_{2}+l_{2})}{(m_{2}+\gamma_{2}+1)^{2}}\right\}y_{2} + \frac{\delta_{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \frac{1}{(m_{2}+\gamma_{2}+1)^{2}} \\ \mathcal{H}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}_{m_{1}m_{2},\alpha,l_{1},l_{2}}(e_{2,0};y_{1},y_{2}) = \left(\frac{m_{1}+l_{1}}{m_{1}+\gamma_{1}+1}\right)^{2}y_{1}^{2} + \left\{\frac{[m_{1}+l_{1}+2(1-\alpha)]}{(m_{1}+\gamma_{1}+1)^{2}}(1-y_{1})\right. \\ + \frac{2\delta_{1}(m_{1}+l_{1})}{(m_{1}+\gamma_{1}+1)^{2}}\right\}y_{1} + \frac{\delta_{1}^{2}}{(m_{1}+\gamma_{1}+1)^{2}} + \left(\frac{m_{1}+l_{1}}{(m_{1}+\gamma_{1}+1)^{2}}\right)y_{1} \\ + \frac{\delta_{1}}{(m_{1}+\gamma_{1}+1)^{2}} + \frac{1}{(m_{1}+\gamma_{1}+1)^{2}} + \frac{1}{(m_{1}+\gamma_{1}+1)^{2}}. \end{split}$$

Proof. Using Equations (13), (8), Lemma 2 and the linearity property, we have:

$$\begin{aligned} \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(e_{0,0};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{0};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{0};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(e_{1,0};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{1};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{0};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(e_{0,1};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{0};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{1};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(e_{1,1};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{1};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{1};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(e_{2,0};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{2};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{0};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(e_{0,2};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{0};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{0};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(e_{0,2};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{0};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{2};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(e_{0,2};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{0};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{2};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}(e_{0,2};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{0};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{2};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{2},\gamma_{1},\gamma_{2}}(e_{0,2};y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{0};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{2};y_{2}), \\ \mathcal{H}_{m_{1},m_{2},\alpha,l_{1},l_{2}}^{*\delta_{2},\gamma_{2}}(e_{0};y_{2},y_{1},y_{2}) &= \mathcal{D}_{m_{1},\alpha,l_{1}}^{*\delta_{1},\gamma_{1}}(e_{0};y_{1})\mathcal{D}_{m_{2},\alpha,l_{2}}^{*\delta_{2},\gamma_{2}}(e_{2};y_{2},y_{1},y_{2}), \\ \mathcal{H}_{m_{1},m_{2},m_$$

Lemma 5. Let $\Psi_{i,j}^{y_1,y_2}(t,s) = \eta_{i,j}(t,s) = (t-y_1)^i(s-y_2)^j$ for $i,j \in \{0,1,2\}$ such that $0 \le i+j \le 2$ is the central moments. Then, the operator given by Equation (13) satisfies the following identities:

$$\begin{aligned} \mathcal{H}_{m_{1}m_{2},\alpha,l_{1},l_{2}}^{s_{1},\rho_{2},\gamma_{1},\gamma_{2}}(\eta_{0,0};y_{1},y_{2}) &= 1, \\ \mathcal{H}_{m_{1}m_{2},\alpha,l_{1},l_{2}}^{s_{1},\delta_{2},\gamma_{1},\gamma_{2}}(\eta_{1,0};y_{1},y_{2}) &= \left(\frac{l_{1}-\gamma_{1}-1}{m_{1}+\gamma_{1}+1}\right)y_{1} + \frac{\delta_{1}}{m_{1}+\gamma_{1}+1} + \frac{1}{2(m_{1}+\gamma_{1}+1)}, \\ \mathcal{H}_{m_{1}m_{2},\alpha,l_{1},l_{2}}^{s_{1},\delta_{2},\gamma_{1},\gamma_{2}}(\eta_{0,1};y_{1},y_{2}) &= \left(\frac{l_{2}-\gamma_{2}-1}{m_{2}+\gamma_{2}+1}\right)y_{2} + \frac{\delta_{2}}{m_{2}+\gamma_{2}+1} + \frac{1}{2(m_{2}+\gamma_{2}+1)}, \\ \mathcal{H}_{m_{1}m_{2},\alpha,l_{1},l_{2}}^{s_{1},\delta_{2},\gamma_{1},\gamma_{2}}(\eta_{1,1};y_{1},y_{2}) &= \left(\left(\frac{l_{1}-\gamma_{1}-1}{m_{1}+\gamma_{1}+1}\right)y_{1} + \frac{\delta_{1}}{m_{1}+\gamma_{1}+1} + \frac{1}{2(m_{1}+\gamma_{1}+1)}\right) \\ \times \left(\left(\frac{l_{2}-\gamma_{2}-1}{m_{2}+\gamma_{2}+1}\right)y_{2} + \frac{\delta_{2}}{m_{2}+\gamma_{2}+1} + \frac{1}{2(m_{2}+\gamma_{2}+1)}\right), \\ \mathcal{H}_{m_{1}m_{2},\alpha,l_{1},l_{2}}^{s_{1},\delta_{2},\gamma_{1},\gamma_{2}}(\eta_{2,0};y_{1},y_{2}) &= \left(\frac{m_{1}+l_{1}}{m_{1}+\gamma_{1}+1}\right)^{2}y_{1}^{2} + \left\{\frac{[m_{1}+l_{1}+2(1-\alpha)]}{(m_{1}+\gamma_{2}+1)^{2}}(1-y_{1}) \right. \\ &+ \frac{2\delta_{1}(m_{1}+l_{1})}{(m_{1}+\gamma_{1}+1)^{2}}\right\} + \frac{\delta_{1}^{2}}{(m_{1}+\gamma_{1}+1)^{2}} + \left(\frac{m_{1}+l_{1}}{(m_{1}+\gamma_{1}+1)^{2}}\right)y_{1} \\ &+ \frac{\delta_{1}}{(m_{1}+\gamma_{1}+1)^{2}} + \frac{\delta_{1}}{(m_{1}+\gamma_{1}+1)^{2}} + \frac{\delta_{1}}{(m_{1}+\gamma_{1}+1)^{2}}(1-y_{1}) \\ &+ \frac{2\delta_{2}(m_{2}+l_{2})}{(m_{2}+\gamma_{2}+1)^{2}}\right)y_{1}^{2} + \frac{\delta_{2}^{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \left(\frac{m_{2}+l_{2}}{(m_{2}+\gamma_{2}+1)^{2}}\right)(1-y_{2}) \\ &+ \frac{2\delta_{2}(m_{2}+l_{2})}{(m_{2}+\gamma_{2}+1)^{2}}\right\} + \frac{\delta_{2}^{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \left(\frac{m_{2}+l_{2}}{(m_{2}+\gamma_{2}+1)^{2}}\right)(1-y_{2}) \\ &+ \frac{\delta_{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \frac{\delta_{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \left(\frac{m_{2}+l_{2}}{(m_{2}+\gamma_{2}+1)^{2}}\right)y_{2} \\ &+ \frac{\delta_{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \frac{\delta_{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \frac{\delta_{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \frac{\delta_{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \frac{\delta_{2}}{(m_{2}+\gamma_{2}+1)^{2}} \\ &+ \frac{\delta_{2}}{(m_{2}+\gamma_{2}+1)^{2}} + \frac$$

Proof. The proof follows from Equation (8), (13), Lemma 3 and the linearity property of $\mathcal{H}_{m_1,m_2,\alpha,l_1,l_2}^{*\delta_1,\delta_2,\gamma_1,\gamma_2}(.;.)$.

7. Convergence of the Operators (13)

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To establish the convergence of $\mathcal{H}^{*\delta_{1},\delta_{2},\gamma_{1},\gamma_{2}}_{m_{1},m_{2},\alpha,l_{1},l_{2}}(.;.)$ (13), we recall the following result due to Volkov [35]:

Theorem 4. Let I_1 and I_2 be compact intervals of the real line. Let T_{m_1,m_2} : $C(I_1 \times I_2) \rightarrow C(I_1 \times I_2), (m_1, m_2) \in \mathbb{N} \times \mathbb{N}$ be positive linear operators. If

 $\lim_{\substack{m_1,m_2\to\infty}} T_{m_1,m_2}(e_{i,j}) = e_{i,j}, (i,j) \in \{(0,0), (1,0), (0,1)\}, \text{ and}$ $\lim_{\substack{m_1,m_2\to\infty}} T_{m_1,m_2}(e_{2,0}+e_{0,2}) = e_{2,0}+e_{0,2},$

uniformly on $I_1 \times I_2$, then the sequence $(T_{m_1,m_2}g)$ converges to g uniformly on $I_1 \times I_2$ for any $g \in I_1 \times I_2$.

Theorem 5. For the sequence of operators presented in (13), we have:

$$\lim_{m_1,m_2\to\infty}\mathcal{H}^*_{m_1,m_2,\alpha,l_1,l_2}^{\delta_1,\delta_2,\gamma_1,\gamma_2}(h;y_1,y_2) = h \text{ uniformly for every } h \in C(I^2).$$

Proof. The proof follows easily from Lemma 4 and Theorem 4. \Box

8. Numerical and Graphical Representation for Approximating the Operator (13)

To verify the convergence of the operator defined in (13), we take the polynomial $f(y_1, y_2) = y_1^3 y_2^2 + y_1^2 y_2^3$ and the following values of the parameters: $\delta_1 = \delta_2 = 0.2$, $\gamma_1 = \gamma_2 = 0.1$, $l_1 = l_2 = 1$, $\alpha = 0.9$. In Table 2, the error has been computed for Operator (13) for different values of m_1, m_2 by using the formula $E^*_{m_1,m_2}(.;.) = |\mathcal{H}^{*\delta_1,\delta_2,\gamma_1,\gamma_2}_{m_1,m_2,\alpha,l_1,l_2}(.;.) - f(y_1,y_2)|$.

Table 2. Error analysis of the operator $\mathcal{H}_{m_1,m_2,\alpha,l_1,h_2}^{*\delta_1,\delta_2,\gamma_1,\gamma_2}(.;.)$.

y_1 and y_2	$E_{10,10}^{*}(f;y_1,y_2)$	$E_{30,30}^{*}(f;y_1,y_2)$
$y_1 = 0, y_2 = 0$	$3.52494263 imes 10^{-6}$	$2.04157341 imes 10^{-8}$
$y_1 = 0.1, y_2 = 0.1$	0.0006257139	0.0000873557
$y_1 = 0.2, y_2 = 0.2$	0.0044650040	0.00094126079
$y_1 = 0.3, y_2 = 0.3$	0.0157503994	0.00394907782
$y_1 = 0.4, y_2 = 0.4$	0.0394690253	0.01089453119
$y_1 = 0.5, y_2 = 0.5$	0.0800191042	0.02362500785
$y_1 = 0.6, y_2 = 0.6$	0.1364247324	0.04371864830
$y_1 = 0.7, y_2 = 0.7$	0.1802440791	0.07212098313
$y_1 = 0.8, y_2 = 0.8$	0.0748802638	0.07015913210
$y_1 = 0.9, y_2 = 0.9$	0.5863803996	0.02385931554

Graphical analysis was also carried out for the convergence and error of Operator (13) in Figures 3 and 4, respectively. The blue color represents the graph of the function f, and the green and red colors show errors for $m_1 = m_2 = 10$ and $m_1 = m_2 = 30$, respectively.



Figure 3. Graphical representation of approximation.



Figure 4. Graphical representation of error.

9. Conclusions

In this research work, we have constructed α -Stancu-Schurer-Kantorovich operators in single and two variables. Furthermore, the order of approximation was obtained for these operators. Moreover, we analyzed the error estimation and rate of approximation numerically and graphically for both the sequences of operators presented in Equations (8) and (13), respectively.

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