

## ON PLANE VISCOUS MAGNETOHYDRODYNAMIC FLOWS\*

By

V. I. NATH AND O. P. CHANDNA

*(University of Windsor, Windsor, Ontario)*

**1. Introduction.** Martin [1] derived a new form for the basic equations governing the plane flow of viscous, incompressible, non-conducting fluids. He used this new form of equations to prove the following:

(i) If the streamlines are straight lines, the straight lines must be concurrent or parallel.

(ii) The streamlines can be involutes of a curve only if the curve reduces to a point and the streamlines are circles concentric at this point.

Following Martin's approach, we show that when streamlines  $\Psi = \text{constant}$  and magnetic lines  $\phi = \text{constant}$  of plane, non-aligned flow of a viscous incompressible fluid of infinite electrical conductivity are taken as the curvilinear coordinate system  $\phi, \Psi$  in the physical plane the fundamental equations governing the flow can be replaced by a new system of equations. In these equations  $\phi, \Psi$  are the independent variables.

In case of orthogonal flows we prove the following:

(i) If the streamlines are straight lines but not parallel, then they must be concurrent.

(ii) If the streamlines are involutes of a curve, then the streamlines are concentric circles.

Finally, we find solutions to vortex and source flow problems.

**2. Flow equations.** The steady flow of an incompressible fluid of infinite electrical conductivity, in the absence of heat conduction, is governed by the system of five non-linear partial differential equations

$$(\partial v_1 / \partial x) + (\partial v_2 / \partial y) = 0, \tag{2.1}$$

$$\rho \left( v_1 \frac{\partial v_1}{\partial x} + v_2 \frac{\partial v_1}{\partial y} \right) + \frac{\partial p}{\partial x} = \eta \left( \frac{\partial^2 v_1}{\partial x^2} + \frac{\partial^2 v_1}{\partial y^2} \right) - \mu H_2 \left( \frac{\partial H_2}{\partial x} - \frac{\partial H_1}{\partial y} \right), \tag{2.2}$$

$$\rho \left( v_1 \frac{\partial v_2}{\partial x} + v_2 \frac{\partial v_2}{\partial y} \right) + \frac{\partial p}{\partial y} = \eta \left( \frac{\partial^2 v_2}{\partial x^2} + \frac{\partial^2 v_2}{\partial y^2} \right) + \mu H_1 \left( \frac{\partial H_2}{\partial x} - \frac{\partial H_1}{\partial y} \right), \tag{2.3}$$

$$v_1 H_2 - v_2 H_1 = k, \tag{2.4}$$

$$(\partial H_1 / \partial x) + (\partial H_2 / \partial y) = 0, \tag{2.5}$$

where  $v_1, v_2$  are the velocity components,  $H_1$  and  $H_2$  the components of the magnetic field vector  $\mathbf{H}$ ,  $p$  the pressure,  $\rho$  the constant density,  $\eta$  the constant coefficient of viscosity,  $\mu$  the constant magnetic permeability and  $k$  an arbitrary constant.

---

\* Received October 16, 1972.

Throughout this paper, we assume that the streamlines are nowhere parallel to the magnetic lines i.e.  $k \neq 0$ .

On introducing the functions

$$\begin{aligned}\omega &= (\partial v_2/\partial x) - (\partial v_1/\partial y), \\ \Omega &= (\partial H_2/\partial x) - (\partial H_1/\partial y), \\ h &= (\rho/2)V^2 + p,\end{aligned}\tag{2.6}$$

where

$$V^2 = v_1^2 + v_2^2,\tag{2.7}$$

Eq. (2.2) can be written as

$$\rho\left(v_1 \frac{\partial v_1}{\partial x} + v_2 \frac{\partial v_1}{\partial y}\right) + \frac{\partial h}{\partial x} - \rho\left(v_1 \frac{\partial v_1}{\partial x} + v_2 \frac{\partial v_2}{\partial x}\right) = \eta\left\{\frac{\partial^2 v_1}{\partial x^2} + \left(\frac{\partial^2 v_2}{\partial x \partial y} - \frac{\partial \omega}{\partial y}\right)\right\} - \mu\Omega H_2,$$

or

$$-\rho v_2\left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y}\right) + \frac{\partial h}{\partial x} = -\eta \frac{\partial \omega}{\partial y} + \eta \frac{\partial}{\partial x}\left(\frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y}\right) - \mu\Omega H_2.$$

Using (2.1) and the first equation of (2.6), we get

$$\eta(\partial\omega/\partial y) - \rho\omega v_2 + \mu\Omega H_2 = -(\partial h/\partial x).$$

Similarly, (2.3) gives us

$$\eta(\partial\omega/\partial x) - \rho\omega v_1 + \mu\Omega H_1 = \partial h/\partial y.$$

The system of five partial differential equations (2.1)–(2.5) may be replaced by the following seven partial differential equations:

$$(\partial v_1/\partial x) + (\partial v_2/\partial y) = 0,\tag{2.8}$$

$$\eta(\partial\omega/\partial y) - \rho\omega v_2 + \mu\Omega H_2 = -(\partial h/\partial x),\tag{2.9}$$

$$\eta(\partial\omega/\partial x) - \rho\omega v_1 + \mu\Omega H_1 = \partial h/\partial y,\tag{2.10}$$

$$v_1 H_2 - v_2 H_1 = k \neq 0,\tag{2.11}$$

$$(\partial H_1/\partial x) + (\partial H_2/\partial y) = 0,\tag{2.12}$$

$$(\partial v_2/\partial x) - (\partial v_1/\partial y) = \omega,\tag{2.13}$$

$$(\partial H_2/\partial x) - (\partial H_1/\partial y) = \Omega.\tag{2.14}$$

The set of equations (2.8)–(2.14) is a system of non-linear partial differential equations in seven dependent variables  $v_1$ ,  $v_2$ ,  $H_1$ ,  $H_2$ ,  $\omega$ ,  $\Omega$  and  $h$ . Although the number of equations and dependent variables has increased by two, the order has decreased from two to one.

**3. Some results from differential geometry.** Let

$$x = x(\phi, \Psi), \quad y = y(\phi, \Psi)\tag{3.1}$$

define a system of curvilinear coordinates in the  $(x, y)$ -plane. In the curvilinear coordinate system  $(\phi, \Psi)$  the squared element of arc length is given by

$$ds^2 = E d\phi^2 + 2F d\phi d\Psi + G d\Psi^2\tag{3.2}$$

where

$$\begin{aligned} E &= (\partial x/\partial\phi)^2 + (\partial y/\partial\phi)^2, \\ F &= (\partial x/\partial\phi)(\partial x/\partial\Psi) + (\partial y/\partial\phi)(\partial y/\partial\Psi), \\ G &= (\partial x/\partial\Psi)^2 + (\partial y/\partial\Psi)^2. \end{aligned} \tag{3.3}$$

Eq. (3.1) can be used to obtain  $\phi = \phi(x, y)$ ,  $\Psi = \Psi(x, y)$  such that

$$\frac{\partial x}{\partial\phi} = J \frac{\partial\Psi}{\partial y}, \quad \frac{\partial y}{\partial\phi} = -J \frac{\partial\Psi}{\partial x}, \quad \frac{\partial x}{\partial\Psi} = -J \frac{\partial\phi}{\partial y}, \quad \frac{\partial y}{\partial\Psi} = J \frac{\partial\phi}{\partial x} \tag{3.4}$$

provided that  $0 < |J| < \infty$ , where  $J$  denotes the Jacobian

$$J = (\partial x/\partial\phi)(\partial y/\partial\Psi) - (\partial x/\partial\Psi)(\partial y/\partial\phi). \tag{3.5}$$

From (3.3) and (3.5), we have

$$J = \pm W \tag{3.6}$$

where  $W = (EG - F^2)^{1/2}$ . Let  $\beta$  be the angle made by the tangent to the coordinate line  $\phi = \text{constant}$ , directed in the sense of increasing  $\Psi$ , with the  $x$ -axis. From the third equation of (3.3), we write

$$(\partial x/\partial\Psi) = \sqrt{G} \cos \beta, \quad (\partial y/\partial\Psi) = \sqrt{G} \sin \beta. \tag{3.7}$$

Substitution of  $\partial x/\partial\Psi$  and  $\partial y/\partial\Psi$  from (3.7) in the second equation of (3.3) yields

$$F = \sqrt{G} \left[ \frac{\partial x}{\partial\phi} \cos \beta + \frac{\partial y}{\partial\phi} \sin \beta \right]. \tag{3.8}$$

Eliminating  $\partial y/\partial\phi$  between (3.8) and the first equation of (3.3) and solving for  $\partial x/\partial\phi$ , we obtain

$$\partial x/\partial\phi = (F/\sqrt{G}) \cos \beta + (J/\sqrt{G}) \sin \beta. \tag{3.9}$$

The first equation of (3.3) and (3.9) require

$$\partial y/\partial\phi = (F/\sqrt{G}) \sin \beta - (J/\sqrt{G}) \cos \beta. \tag{3.10}$$

From (3.7), (3.9), (3.10) and the conditions that the second-order mixed derivatives of  $x$  and  $y$  with respect to  $\phi$  and  $\Psi$  are independent of the order of differentiation, we find that

$$\partial\beta/\partial\phi = (J/G)\gamma_{12}^2, \quad \partial\beta/\partial\Psi = (J/G)\gamma_{11}^2, \tag{3.11}$$

where

$$\begin{aligned} \gamma_{11}^2 &= \frac{1}{2W^2} \left[ F \frac{\partial G}{\partial\Psi} - 2G \frac{\partial F}{\partial\Psi} + G \frac{\partial G}{\partial\phi} \right], \\ \gamma_{12}^2 &= \frac{1}{2W^2} \left[ F \frac{\partial G}{\partial\phi} - G \frac{\partial E}{\partial\Psi} \right]. \end{aligned} \tag{3.12}$$

Proceeding exactly as Martin [1], it is found that if  $E, F, G$  are given functions of  $\phi$  and  $\Psi$ , then (3.1) will serve as planar curvilinear co-ordinate system if and only if

$$\partial/\partial\Psi((J/G)\gamma_{12}^2) - \partial/\partial\phi((J/G)\gamma_{11}^2) = 0 \tag{3.13}$$

where  $\gamma_{11}^2$  and  $\gamma_{12}^2$  are given by (3.12).

When the condition (3.13) is satisfied, the functions  $x(\phi, \Psi)$ ,  $y(\phi, \Psi)$  can be obtained from the relation

$$z = x + iy = \int \frac{\exp(i\beta)}{\sqrt{G}} \{(F - iJ) d\phi + G d\Psi\} \quad (3.14)$$

where  $\beta$  as a function of  $\phi$  and  $\Psi$  is given by

$$\beta = \int \frac{J}{G} \{\gamma_{12}^2 d\phi + \gamma_{11}^2 d\Psi\}. \quad (3.15)$$

**4. New form for the fundamental equations.** Eqs. (2.8) and (2.12), respectively, imply the existence of a stream function  $\Psi(x, y)$  and the magnetic function  $\phi(x, y)$  such that

$$v_2 = -(\partial\Psi/\partial x), \quad v_1 = \partial\Psi/\partial y \quad (4.1)$$

and

$$H_2 = \partial\phi/\partial x, \quad H_1 = -(\partial\phi/\partial y). \quad (4.2)$$

We assume that the curves  $\Psi = \text{constant}$  and the curves  $\phi = \text{constant}$  form the curvilinear coordinate system discussed in Sec. 3 of this paper.

Using (4.1) and (4.2) in (2.11), we find

$$\frac{\partial\Psi}{\partial y} \frac{\partial\phi}{\partial x} - \frac{\partial\Psi}{\partial x} \frac{\partial\phi}{\partial y} = \frac{\partial(\phi, \Psi)}{\partial(x, y)} = \frac{1}{J} = k \neq 0 \quad (4.3)$$

where  $J$  is defined by (3.5). Eq. (4.3) implies that if we know  $x$  and  $y$  as functions of  $\phi$  and  $\Psi$ , then we can obtain  $\phi$  and  $\Psi$  as functions of  $x$  and  $y$ .

In what follows we transform the flow equations to such a form that their solution gives us  $v_1, v_2, H_1, H_2, \omega, \Omega$  and  $h$  as functions of  $\phi$  and  $\Psi$ .

*Solenoidal condition on  $\mathbf{H}$ .* Using (3.4) in (4.2), we get

$$\partial x/\partial\Psi = JH_1, \quad \partial y/\partial\Psi = JH_2. \quad (4.4)$$

Let  $\theta$  be the angle made by the magnetic field  $\mathbf{H}$  with  $x$ -axis. The components  $H_1$  and  $H_2$  of  $\mathbf{H}$  can be written as

$$H_1 = H \cos \theta, \quad H_2 = H \sin \theta \quad (4.5)$$

where  $H = |\mathbf{H}|$ . From (4.4) and (4.5) we have

$$\partial x/\partial\Psi = JH \cos \theta, \quad \partial y/\partial\Psi = JH \sin \theta. \quad (4.6)$$

Now two cases arise:

1:  $\theta = \beta$ , where  $\beta$  is defined in Sec. 3. In this case (4.6) becomes

$$\partial x/\partial\Psi = JH \cos \beta, \quad \partial y/\partial\Psi = JH \sin \beta. \quad (4.7)$$

From (3.7) and (4.7), we get

$$JH = \sqrt{G}, \quad (4.8)$$

i.e.  $J > 0$ .

2:  $\theta = \beta + \pi$ . From (4.6), we obtain

$$\partial x/\partial \Psi = -JH \cos \beta, \quad \partial y/\partial \Psi = -JH \sin \beta. \tag{4.9}$$

Eqs. (4.9) together with (3.7) give

$$-JH = \sqrt{G}, \tag{4.10}$$

i.e.  $J < 0$ .

From the above two cases, we conclude that the magnetic field acts along the magnetic lines towards higher or lower parameter values  $\Psi$  accordingly as  $J$  is positive or negative. In either case (3.6) requires that

$$WH = \sqrt{G}. \tag{4.11}$$

Eqs. (3.7) and (4.4) imply that

$$H_1 + iH_2 = (\sqrt{G}/J) \exp(i\beta). \tag{4.12}$$

*Equation of continuity.* Martin [1] has shown that the equation of continuity implies that the fluid flows along the streamlines towards higher or low parameter values  $\phi$  accordingly as  $J$  is positive or negative. He has also proven that

$$WV = \sqrt{E} \tag{4.13}$$

and

$$v_1 + iv_2 = (\sqrt{E}/J) \exp(i\alpha) \tag{4.14}$$

where  $\alpha$  is the angle between the tangent to the coordinate line  $\Psi = \text{constant}$ , directed in the sense of increasing  $\phi$ , with the  $x$ -axis.

*The function  $\Omega$ .* By the definition of  $\Omega$  and (3.4) we find that

$$J\Omega = \left( \frac{\partial H_2}{\partial \phi} \frac{\partial y}{\partial \Psi} - \frac{\partial H_2}{\partial \Psi} \frac{\partial y}{\partial \phi} \right) + \left( \frac{\partial H_1}{\partial \phi} \frac{\partial x}{\partial \Psi} - \frac{\partial H_1}{\partial \Psi} \frac{\partial x}{\partial \phi} \right)$$

On substituting  $H_1 = \pm H \cos \beta$ ,  $H_2 = \pm H \sin \beta$ , we find

$$\begin{aligned} \pm J\Omega = & \left[ \left( \frac{\partial H}{\partial \phi} \sin \beta + H \cos \beta \frac{\partial \beta}{\partial \phi} \right) \frac{\partial y}{\partial \Psi} - \left( \frac{\partial H}{\partial \Psi} \sin \beta + H \cos \beta \frac{\partial \beta}{\partial \Psi} \right) \frac{\partial y}{\partial \phi} \right] \\ & + \left[ \left( \frac{\partial H}{\partial \phi} \cos \beta - H \sin \beta \frac{\partial \beta}{\partial \phi} \right) \frac{\partial x}{\partial \Psi} - \left( \frac{\partial H}{\partial \Psi} \cos \beta - H \sin \beta \frac{\partial \beta}{\partial \Psi} \right) \frac{\partial x}{\partial \phi} \right]. \end{aligned}$$

Using (3.7), (3.9) and (3.10), we get

$$\sqrt{G} W\Omega = G \frac{\partial H}{\partial \phi} - F \frac{\partial H}{\partial \Psi} + HJ \frac{\partial \beta}{\partial \Psi}. \tag{4.15}$$

Eliminating  $H$  and  $\beta$  between (3.11), (4.11) and (4.15), and using the identities

$$(\partial/\partial \phi)(G/2W^2) = (1/W^2)(G\gamma_{22}^2 - F\gamma_{12}^2)$$

and

$$(\partial/\partial \Psi)(G/2W^2) = (1/W^2)(G\gamma_{12}^2 - F\gamma_{12}^2),$$

where

$$\gamma_{22}^2 = \frac{1}{2W^2} \left[ -G \frac{\partial E}{\partial \phi} + 2F \frac{\partial F}{\partial \phi} - F \frac{\partial E}{\partial \Psi} \right],$$

we find that

$$W\Omega = \frac{1}{W} \{G\gamma_{22}^2 - 2F\gamma_{12}^2 + E\gamma_{11}^2\}. \quad (4.16)$$

On differentiating  $(G/W)$  with respect to  $\phi$  and  $(F/W)$  with respect to  $\Psi$ , we see that

$$\frac{\partial}{\partial \phi} \left( \frac{G}{W} \right) - \frac{\partial}{\partial \Psi} \left( \frac{F}{W} \right) = \frac{1}{W} (G\gamma_{22}^2 - 2F\gamma_{12}^2 + E\gamma_{11}^2). \quad (4.17)$$

From (4.16) and (4.17), we get

$$\Omega = \frac{1}{W} \left\{ \frac{\partial}{\partial \phi} \left( \frac{G}{W} \right) - \frac{\partial}{\partial \Psi} \left( \frac{F}{W} \right) \right\} \quad (4.18)$$

*The vorticity  $\omega$ .* Martin [1] has proven that

$$\omega = \frac{1}{W} \left\{ \frac{\partial}{\partial \phi} \left( \frac{F}{W} \right) - \frac{\partial}{\partial \Psi} \left( \frac{E}{W} \right) \right\}.$$

*Equations of momentum.* Eq. (2.9) can be written as

$$\eta \left( \frac{\partial \omega}{\partial \phi} \frac{\partial \phi}{\partial y} + \frac{\partial \omega}{\partial \Psi} \frac{\partial \Psi}{\partial y} \right) + \rho \omega \frac{\partial \Psi}{\partial x} + \mu \Omega \frac{\partial \phi}{\partial x} = - \left( \frac{\partial h}{\partial \phi} \frac{\partial \phi}{\partial x} + \frac{\partial h}{\partial \Psi} \frac{\partial \Psi}{\partial x} \right) \quad (4.19)$$

where (4.1) and (4.2) have been used to eliminate  $v_2$  and  $H_2$ . Eq. (4.19), on using (3.4), becomes

$$\eta \left( - \frac{\partial \omega}{\partial \phi} \frac{\partial x}{\partial \Psi} + \frac{\partial \omega}{\partial \Psi} \frac{\partial x}{\partial \phi} \right) - \rho \omega \frac{\partial y}{\partial \phi} + \mu \Omega \frac{\partial y}{\partial \Psi} = \left( - \frac{\partial h}{\partial \phi} \frac{\partial x}{\partial \Psi} + \frac{\partial h}{\partial \Psi} \frac{\partial x}{\partial \phi} \right). \quad (4.20)$$

Similarly, (2.10) gives us

$$\eta \frac{\partial \omega}{\partial \phi} \frac{\partial y}{\partial \Psi} - \frac{\partial \omega}{\partial \Psi} \frac{\partial y}{\partial \phi} - \rho \omega \frac{\partial x}{\partial \phi} + \mu \Omega \frac{\partial x}{\partial \Psi} = - \frac{\partial h}{\partial \phi} \frac{\partial x}{\partial \Psi} + \frac{\partial h}{\partial \Psi} \frac{\partial x}{\partial \phi}. \quad (4.21)$$

Multiplying (4.20) by  $\partial y/\partial \phi$ , (4.21) by  $\partial x/\partial \phi$  and adding, we get

$$-F \left( \frac{\partial h}{\partial \phi} + \mu \Omega \right) + E \left( \frac{\partial h}{\partial \Psi} + \rho \omega \right) = \eta J \frac{\partial \omega}{\partial \phi} \quad (4.22)$$

where  $E$ ,  $F$  and  $J$  are given by (3.3) and (3.5). Again, multiplying (4.20) by  $\partial y/\partial \Psi$ , (4.21) by  $\partial x/\partial \Psi$  and adding, we obtain

$$G \left( \frac{\partial h}{\partial \phi} + \mu \Omega \right) - F \left( \frac{\partial h}{\partial \Psi} + \rho \omega \right) = -\eta J \frac{\partial \omega}{\partial \Psi}. \quad (4.23)$$

Eqs. (4.22) and (4.23) are the new forms for the momentum equations.

Eqs. (4.22) and (4.23) can be written in another form by eliminating  $\partial h/\partial \Psi$  and

$\partial h/\partial\phi$  respectively between them; the resulting equations are

$$\begin{aligned} \frac{\partial h}{\partial\phi} + \mu\Omega &= \frac{\eta}{J} \left( F \frac{\partial\omega}{\partial\phi} - E \frac{\partial\omega}{\partial\Psi} \right), \\ \frac{\partial h}{\partial\Psi} + \rho\omega &= \frac{\eta}{J} \left( G \frac{\partial\omega}{\partial\phi} - F \frac{\partial\omega}{\partial\Psi} \right). \end{aligned} \tag{4.24}$$

Summing up the results obtained thus far, we have

**THEOREM 1.** When the streamlines  $\Psi = \text{constant}$  and the magnetic lines  $\phi = \text{constant}$  of steady, plane flow of a viscous, infinitely conducting (electrically), incompressible fluid are taken as the curvilinear coordinate system  $\phi, \Psi$  in the physical plane, the set of seven partial differential equations (2.8)–(2.14) for  $v_1, v_2, H_1, H_2, \omega, \Omega$  and  $h$  as functions of  $x, y$  may be replaced by the system

$$\begin{aligned} -F((\partial h/\partial\phi) + \mu\Omega) + E((\partial h/\partial\Psi) + \rho\omega) &= \eta J(\partial\omega/\partial\phi), \\ G((\partial h/\partial\phi) + \mu\Omega) - F((\partial h/\partial\Psi) + \rho\omega) &= -\eta J(\partial\omega/\partial\Psi), \\ (\partial/\partial\Psi)((J/G)\gamma_{12}^2) - (\partial/\partial\phi)((J/G)\gamma_{11}^2) &= 0, \\ \Omega &= \frac{1}{W} \left[ \frac{\partial}{\partial\phi} \left( \frac{G}{W} \right) - \frac{\partial}{\partial\Psi} \left( \frac{F}{W} \right) \right], \\ \omega &= \frac{1}{W} \left[ \frac{\partial}{\partial\phi} \left( \frac{F}{W} \right) - \frac{\partial}{\partial\Psi} \left( \frac{E}{W} \right) \right], \\ W^2 &= J^2 = EG - F^2 = 1/k^2 \end{aligned} \tag{4.25}$$

of six partial differential equations for  $E, F, G, \omega, \Omega$  and  $h$  as functions of  $\phi, \Psi$ . Here  $E, F, G$  are given by  $ds^2 = E d\phi^2 + 2F d\phi d\Psi + G d\Psi^2$ , where  $ds$  is the element of arc length in the physical plane. The Jacobian  $J$  is positive or negative as the parameter  $\Psi$  increases or decreases in the direction of the magnetic field vector  $\mathbf{H}$ .

Given a solution

$$\begin{aligned} E &= E(\phi, \Psi) & F &= F(\phi, \Omega); & G &= G(\phi, \Psi) \\ \omega &= \omega(\phi, \Psi); & \Omega &= \Omega(\phi, \Psi); & h &= h(\phi, \Psi) \end{aligned}$$

of the system (4.25), we can find  $x, y$  as functions of  $\phi, \Psi$  from

$$z = x + iy = \int \frac{\exp(i\beta)}{\sqrt{G}} \{ (F - iJ) d\phi + G d\Psi \}$$

where  $\beta = \int J/G(\gamma_{12}^2 d\phi + \gamma_{11}^2 d\Psi)$ , and thus obtain  $E, F, G, \omega, \Omega$  and  $h$  as functions of  $x, y$ , since  $0 < |J| < \infty$ . Once we obtain  $E, F, G$  and  $h$  as functions of  $x, y$  then  $H_1, H_2, v_1, v_2$  and  $p$  as functions of  $x, y$  are given by

$$\begin{aligned} H_1 + iH_2 &= (\sqrt{G/J}) \exp(i\beta), \\ v_1 + iv_2 &= (\sqrt{E/J}) \exp(i\alpha), \\ p &= h - (\rho/2)(E/W^2). \end{aligned}$$

5. Application of the fundamental equations in the new form. Eqs. (4.24) can be rewritten as

$$\frac{\partial h}{\partial \phi} = -\mu\Omega + \frac{\eta}{J} \left( F \frac{\partial \omega}{\partial \phi} - E \frac{\partial \omega}{\partial \Psi} \right), \quad (5.1)$$

$$\frac{\partial h}{\partial \Psi} = -\rho\omega + \frac{\eta}{J} \left( G \frac{\partial \omega}{\partial \phi} - F \frac{\partial \omega}{\partial \Psi} \right). \quad (5.2)$$

Differentiating (5.1) with respect to  $\Psi$ , (5.2) with respect to  $\phi$  and using the condition that the second-order mixed derivative of  $h$  with respect to  $\phi$  and  $\Psi$  is independent of the order of differentiation, we find

$$\eta J \Delta_2 \omega + \mu(\partial \Omega / \partial \Psi) - \rho(\partial \omega / \partial \phi) = 0$$

where

$$\Delta_2 \omega \equiv \frac{1}{J} \left[ \frac{\partial}{\partial \phi} \left\{ \frac{1}{J} \left( G \frac{\partial \omega}{\partial \phi} - F \frac{\partial \omega}{\partial \Psi} \right) \right\} + \frac{\partial}{\partial \Psi} \left\{ \frac{1}{J} \left( E \frac{\partial \omega}{\partial \Psi} - F \frac{\partial \omega}{\partial \phi} \right) \right\} \right]. \quad (5.3)$$

Therefore, the system of equations (4.25) is reduced to five equations

$$\eta J \Delta_2 \omega + \mu(\partial \Omega / \partial \Psi) - \rho(\partial \omega / \partial \phi) = 0, \quad (5.4)$$

$$\Omega = \frac{1}{J} \left[ \frac{\partial}{\partial \phi} \left( \frac{G}{J} \right) - \frac{\partial}{\partial \Psi} \left( \frac{F}{J} \right) \right], \quad (5.5)$$

$$\omega = \frac{1}{J} \left[ \frac{\partial}{\partial \phi} \left( \frac{F}{J} \right) - \frac{\partial}{\partial \Psi} \left( \frac{E}{J} \right) \right], \quad (5.6)$$

$$EG - F^2 = 1/k^2, \quad (5.7)$$

$$\frac{\partial}{\partial \Psi} \left( \frac{J}{G} \gamma_{12}^2 \right) - \frac{\partial}{\partial \phi} \left( \frac{J}{G} \gamma_{11}^2 \right) = 0 \quad (5.8)$$

in five dependent variables  $E$ ,  $F$ ,  $G$ ,  $\omega$  and  $\Omega$ . If the solutions to these equations are given, we can find  $h = h(\phi, \Psi)$  from the equations of momentum.

We shall now study two examples in which the curves  $\Psi = \text{constant}$  and the curves  $\phi = \text{constant}$  form an orthogonal curvilinear coordinate system.

*Example 1.* In this example we prescribe the streamlines to be straight lines. We assume that they are not parallel but envelop a curve  $\Gamma$ . We now take the tangent lines to the curve  $\Gamma$ , and their orthogonal trajectories, the involutes of  $\Gamma$  as the system of orthogonal curvilinear coordinates. The square of the element of arc length  $ds$  in this orthogonal curvilinear coordinate system is given by  $ds^2 = ds_1^2 + ds_2^2$ , where  $ds_1$  and  $ds_2$  are the elements of arc length of the involute and the tangent respectively.

The element of arc length of the involute is [2]

$$ds_1 = (\xi - \sigma)\kappa d\sigma$$

where  $\sigma$  denotes the arc length,  $\kappa$  the curvature of the curve  $\Gamma$  and  $\xi$  is a parameter constant along each involute. Therefore, we have

$$ds^2 = d\xi^2 + (\xi - \sigma)^2 \kappa^2 d\sigma^2. \quad (5.9)$$

But

$$\kappa = d\eta/d\sigma \quad (5.10)$$



where  $\eta$  is the angle subtended by the tangent line with  $x$ -axis. Eqs. (5.9) and (5.10) give us

$$ds^2 = d\xi^2 + (\xi - \sigma)^2 d\eta^2 \tag{5.11}$$

where  $\sigma = \sigma(\eta)$ . In this coordinate system, the coordinate curves  $\xi = \text{constant}$  are the involutes of the curve  $\Gamma$  and the curves  $\eta = \text{constant}$  its tangent lines.

We now investigate the flows for which

$$\phi = \phi(\xi), \quad \Psi = \Psi(\eta). \tag{5.12}$$

Using (5.12) in (3.2), we get

$$ds^2 = (\phi')^2 E d\xi^2 + 2F\phi'\Psi' d\xi d\eta + G(\Psi')^2 d\eta^2. \tag{5.13}$$

Comparing (5.11) and (5.13), we find

$$\begin{aligned} E &= (1/\phi')^2, & F &= 0, & G &= (\xi - \sigma(\eta))/\Psi'^2, \\ J &= (\xi - \sigma(\eta))/\phi'\Psi'. \end{aligned} \tag{5.14}$$

Since  $F = 0$ , (3.12) gives us

$$\gamma_{11}^2 = \frac{1}{2J^2} G \frac{\partial G}{\partial \phi}, \quad \gamma_{12}^2 = -\frac{1}{2J^2} G \frac{\partial E}{\partial \Psi}.$$

Using (5.14), we get

$$\gamma_{11}^2 = \frac{\xi - \sigma(\eta)}{\Psi'} \phi', \quad \gamma_{12}^2 = 0. \tag{5.15}$$

Substituting for  $G, J, \gamma_{11}^2, \gamma_{12}^2$  from (5.14) and (5.15) in (5.8), we find that it is automatically satisfied. Using (5.14) in (5.5) and (5.6), we find

$$\Omega = \frac{1}{\xi - \sigma(\eta)} \frac{\partial}{\partial \xi} \{ \phi'(\xi - \sigma(\eta)) \} \tag{5.16}$$

and

$$\omega = -\frac{1}{\xi - \sigma(\eta)} \frac{\partial}{\partial \eta} \left( \frac{\Psi'}{\xi - \sigma(\eta)} \right). \tag{5.17}$$

From (5.4) and (5.14), we obtain

$$\eta \left[ \frac{\partial}{\partial \xi} \left\{ (\xi - \sigma(\eta)) \frac{\partial \omega}{\partial \xi} \right\} + \frac{\partial}{\partial \eta} \left\{ \frac{1}{\xi - \sigma(\eta)} \frac{\partial \omega}{\partial \eta} \right\} \right] + \mu \phi' \frac{\partial \Omega}{\partial \eta} - \rho \Psi' \frac{\partial \omega}{\partial \xi} = 0 \tag{5.18}$$

or

$$\begin{aligned} 15\eta\Psi'(\sigma')^3 + (\xi - \sigma)[10\eta\Psi'\sigma'\sigma'' + 15\eta\Psi''(\sigma')^2] \\ + (\xi - \sigma)^2[9\eta\Psi'\sigma' + 4\eta\Psi''\sigma'' + \eta\Psi'\sigma''' + 6\eta\Psi'''\sigma' + 3\rho(\Psi')^2\sigma'] \\ + (\xi - \sigma)^3[4\eta\Psi'' + \eta\Psi^{(iv)} + 2\rho\Psi'\Psi''] - (\xi - \sigma)^4[\mu(\phi')^2\sigma'] \equiv 0. \end{aligned} \tag{5.19}$$

The curve  $\Gamma$  appears as the curve  $\xi = \sigma(\eta)$  in the plane of variables  $\xi, \eta$ . For the relation (5.19) to hold identically, it must hold on the curve  $\xi = \sigma(\eta)$ , and therefore we have [1]  $\sigma' = 0$ , i.e.  $\kappa \rightarrow \infty$ .

**THEOREM 2.** If the streamlines in two dimensional flow of a viscous fluid are straight but not parallel, then they must be concurrent.

*Example 2.* In this example, we consider the involutes of the curve  $\Gamma$  as the streamlines and the tangents to the curve  $\Gamma$  as the magnetic lines.

As in the previous example, the square of the element of arc length in this orthogonal curvilinear coordinate system is

$$ds^2 = d\xi^2 + (\xi - \sigma)^2 d\eta^2. \quad (5.20)$$

For the flows under investigations, we have

$$\phi = \phi(\eta), \quad \Psi = \Psi(\xi). \quad (5.21)$$

Using (5.21) in (3.2), we get

$$ds^2 = (\phi')^2 E d\eta^2 + 2F\phi'\Psi' d\xi d\eta + G(\Psi')^2 d\xi^2. \quad (5.22)$$

Comparing (5.20) with (5.22), we obtain

$$E = \left(\frac{\xi - \sigma}{\phi'}\right)^2, \quad F = 0, \quad G = \left(\frac{1}{\Psi'}\right)^2, \quad J = \frac{\xi - \sigma}{\phi'\Psi'}. \quad (5.23)$$

Condition (5.8) is again automatically satisfied. Using (5.23) in (5.4), (5.5) and (5.6), we get

$$\eta \frac{\partial}{\partial \xi} \left[ (\xi - \sigma) \frac{\partial \omega}{\partial \xi} \right] + \eta \frac{\partial}{\partial \eta} \left[ \frac{1}{\xi - \sigma} \frac{\partial \omega}{\partial \eta} \right] + \mu \phi' \frac{\partial \Omega}{\partial \xi} - \rho \Psi' \frac{\partial \omega}{\partial \eta} = 0, \quad (5.24)$$

$$\Omega = \frac{1}{\xi - \sigma} \frac{\partial}{\partial \eta} \left( \frac{\phi'}{\xi - \sigma} \right), \quad (5.25)$$

and

$$\omega = -\frac{1}{\xi - \sigma} \frac{\partial}{\partial \xi} [\Psi'(\xi - \sigma)] \quad (5.26)$$

Elimination of  $\Omega$  and  $\omega$  between (5.24), (5.25) and (5.26) gives

$$3\sigma'[\eta\Psi'\sigma' + \mu(\phi')^2] + (\xi - \sigma)[\eta\Psi'\sigma'' + 2\mu\phi'\phi''] \\ + (\xi - \sigma)^2[\eta\Psi' - (\Psi')^2\sigma'] - \Psi''(\xi - \sigma)^3 + 2\Psi'''(\xi - \sigma)^4 + \Psi^{(iv)}(\xi - \sigma)^5 \equiv 0$$

By the same argument as used in example 1, we have either  $\sigma' = 0$ , i.e.  $\kappa \rightarrow \infty$ , or

$$\Psi' = -\mu \frac{(\phi')^2}{\eta\sigma} = A,$$

a constant. If  $\Psi' = \text{constant}$ , Eqs. (5.23) imply that  $G = \text{constant}$ . This is not possible. Therefore, we have

**THEOREM 3.** If the streamlines in plane flow of a viscous fluid are involutes of a curve  $\Gamma$ , then the streamlines are concentric circles.

**6. Radial and vortex flows.** In this section we study the radial and vortex flows when the magnetic field vector  $\mathbf{H}$  is orthogonal to the velocity vector  $\mathbf{V}$ .

A. *Radial flows.* The square of the element of arc length in polar coordinate system is given by

$$ds^2 = dr^2 + r^2 d\theta^2. \quad (6.1)$$

Since the flows are radial, we have

$$\phi = \phi(r), \quad \Psi = \Psi(\theta). \quad (6.2)$$

Using (6.2) in (3.2), we get

$$ds^2 = E(\phi')^2 dr^2 + 2F\phi'\Psi' d\theta dr + G(\Psi')^2 d\theta^2. \quad (6.3)$$

Comparing (6.1) with (6.3), we find

$$E = 1/(\phi')^2, \quad F = 0, \quad G = r^2/(\Psi')^2. \quad (6.4)$$

From (5.7) and (6.4), we have

$$\Psi' = kr/\phi' = A, \quad (6.5)$$

where  $A$  is an arbitrary constant. Using (6.4) and (6.5) in (5.5) and (5.6), we obtain

$$\Omega = 2k/A, \quad \omega = 0. \quad (6.6)$$

Eqs. (4.11) and (4.13) give

$$H = (k/A)r, \quad V = A/r \quad (6.7)$$

where  $A$ , an arbitrary constant, can be determined from the boundary conditions. From Eqs. (5.1), (5.2) and (6.6), we get

$$h = -\mu(k^2r^2/A^2) + D$$

or

$$p = -\mu \frac{k^2r^2}{A^2} - \frac{\rho}{2} \frac{A^2}{r^2} + D,$$

where  $D$  is an arbitrary constant.

B. *Vortex flows.* We investigate the flows for which

$$\Psi = \Psi(r), \quad \phi = \phi(\theta) \quad (6.8)$$

where  $(r, \theta)$  are the polar coordinates of a point in the plane of flow. For this case, we have

$$E = r^2/(\phi')^2, \quad F = 0, \quad G = 1/(\Psi')^2. \quad (6.9)$$

Eq. (5.7), on using (6.9), gives

$$\phi' = rk/\Psi' = A, \quad (6.10)$$

where  $A$  is an arbitrary constant. Using (6.9) and (6.10) in (5.5) and (5.6), we obtain

$$\Omega = 0, \quad \omega = -(2k/A). \quad (6.11)$$

Substituting (6.9) and (6.10) in (4.11) and (4.13), we find

$$H = (A/r) \quad \text{and} \quad V = (k/A)r \quad (6.12)$$

From Eqs. (5.1), (5.2) and (6.12), we get

$$h = \rho \frac{k^2 r^2}{A^2} + D$$

or

$$= \frac{\rho}{2} \frac{k^2 r^2}{A^2} + D,$$

where  $D$  is an arbitrary constant.

#### REFERENCES

- [1] M. H. Martin, *The flow of a viscous fluid*, Arch. Rat. Mech. Anal. **41** (1971) 266–286
- [2] C. E. Weatherburn, *Differential geometry of three dimensions*, Cambridge (1939), 30–31