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# On Pseudo Cyclic Ricci Symmetric Manifolds 

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#### Abstract

The object of the present paper is to study concircularly symmetric $(P C R S)_{n}$, concircularly recurrent $(P C R S)_{n}$, decomposable $(P C R S)_{n}$. Among others it is shown that in a decomposable $(P C R S)_{n}$ one of the decompositions is Ricci flat and the other decomposition is cyclic parallel. The totally umbilical hypersurfaces of $(P C R S)_{n}$ are also studied.


Key words: Concircularly symmetric manifold, Concircularly recurrent manifold, Decomposable manifold, Pseudo cyclic Ricci symmetric manifold, Totally umbilical hypersurfaces.

Mathematics Subject Classification 2000: 53B30, 53B50, 53C15, 53C25

## Yarı Devirli Ricci Simetrik Manifoldlar Üzerine


#### Abstract

Bu makalenin amacı, konsirkular simetrik $(P C R S)_{n}$, konsirkular tekrarlı $(P C R S)_{n}$, ayrışabilir (PCRS) ${ }_{n}$ manifoldları incelemektir. (PCRS) ${ }_{n}$ ayrışabilir manifoldunda ayrışımlardan birisinin Ricci düzlemsellik (flat), diğerinin de devirli paralellik olduğu gösterilmiştir. Aynı zamanda (PCRS) ${ }_{n}$ nin tümüyle umbilik hiperyüzeyleri çalışılmıştr.

Anahtar kelimeler: Konsirkular simetrik manifold, Konsirkular tekrarlı manifold, Ayrişabilir manifold, Yarı devirli Ricci simetrik manifold, Tümüyle umbilik hiperyüzeyler.


## 1. Introduction

A Riemannian manifold is Ricci symmetric if its Ricci tensor $S$ of type $(0,2)$ satisfies $\nabla S=0$, where $\nabla$ denotes the Riemannian connection. During the last five decades, the notion of Ricci symmetry has been weakened by many authors in several ways such as Ricci-recurrent manifolds [1], Ricci semi-symmetric manifolds [2], pseudo Ricci symmetric manifolds by M. C. Chaki [3]. A non-flat Riemannian manifold ( $M^{n}, g$ ) is said to be pseudo Ricci symmetric [3] if its Ricci tensor $S$ of type $(0,2)$ is not identically zero and satisfies the condition

$$
\begin{equation*}
\left(\nabla_{X} S\right)(Y, Z)=2 A(X) S(Y, Z)+A(Y) S(Z, X)+A(Z) S(X, Y), \tag{1}
\end{equation*}
$$

where $A$ is a nowhere vanishing 1 -form. Such an $n$-dimensional manifold is denoted by $(P R S)_{n}$.

Extending the notion of pseudo Ricci symmetric manifold, recently A. A. Shaikh and the present author [4] introduced the notion of pseudo cyclic Ricci symmetric manifolds. A Riemannian manifold $\left(M^{n}, g\right)(n>2)$ is said to be pseudo cyclic Ricci symmetric

## S.K. Hиi

manifold if its Ricci tensor $S$ of type $(0,2)$ is not identically zero and satisfies the following:

$$
\begin{align*}
& \left(\nabla_{X} S\right)(Y, Z)+\left(\nabla_{Y} S\right)(Z, X)+\left(\nabla_{Z} S\right)(X, Y) \\
& \quad=2 A(X) S(Y, Z)+A(Y) S(X, Z)+A(Z) S(Y, X) \\
& \text { or } \\
& \left(\nabla_{X} S\right)(Y, Z)+\left(\nabla_{Y} S\right)(Z, X)+\left(\nabla_{Z} S\right)(X, Y)  \tag{2}\\
& \quad=2 A(Y) S(Z, X)+A(Z) S(X, Y)+A(X) S(Y, Z) \\
& \text { or } \\
& \left(\nabla_{X} S\right)(Y, Z)+\left(\nabla_{Y} S\right)(Z, X)+\left(\nabla_{Z} S\right)(X, Y) \\
& \quad=2 A(Z) S(X, Y)+A(X) S(Y, Z)+A(Y) S(Z, X),
\end{align*}
$$

where $A$ is a nowhere vanishing 1 -form associated to the vector field $\rho$ such that $A(X)=g(X, \rho)$ for all $X$. Such an $n$-dimensional manifold is denoted by $(P C R S)_{n}$. The $(P C R S)_{n}$ admitting semi-symmetric metric connection is also studied in [5]. The pseudo cyclic Ricci symmetric manifolds are also studied in [6, 7].

The object of the present paper is to study $(P C R S)_{n}$. The paper is organized as follows. Section 2 is devoted to the study of concircularly symmetric $(P C R S)_{n}$. It is shown that in a concircularly symmetric $(P C R S)_{n}$ with constant scalar curvature, $-r$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $\rho$. Section 3 deals with a study of concircularly recurrent $(P C R S)_{n}$. It is proved that in a concircularly recurrent $(P C R S)_{n}$ with constant scalar curvature, $-n$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $\rho$. In section 4, we study decomposable $(P C R S)_{n}$ and it is shown that in a decomposable $(P C R S)_{n}$, one of the decompositions is Ricci flat and the Ricci tensor of the other decomposition is cyclic parallel.

Recently Özen and Altay [8] studied the totally umbilical hypersurfaces of weakly and pseudosymmetric spaces. Again Özen and Altay [9] also studied the totally umbilical hypersurfaces of weakly concircular and pseudo concircular symmetric spaces. In this connection it may be mentioned that Shaikh, Roy and Hui [10] studied the totally umbilical hypersurfaces of weakly conharmonically symmetric spaces. Section 5 deals with the study of totally umbilical hypersurfaces of $(P C R S)_{n}$. It is proved that the totally geodesic hypersurface of a $(P C R S)_{n}$ is also a $(P C R S)_{n}$.

## 2. Concircularly Symmetric (PCRS) ${ }_{n}$

A $(P C R S)_{n}$ is said to be concircularly symmetric if its concircular curvature tensor $\tilde{C}$, given by,

$$
\begin{equation*}
\tilde{C}(Y, Z, U, V)=R(Y, Z, U, V)-\frac{r}{n(n-1)} G(Y, Z, U, V), \tag{3}
\end{equation*}
$$

where $r$ is the scalar curvature of the manifold and the tensor $G$ is defined by

$$
\begin{equation*}
G(Y, Z, U, V)=g(Z, U) g(Y, V)-g(Y, U) g(Z, V), \tag{4}
\end{equation*}
$$

satisfies the relation

$$
\begin{equation*}
\left(\nabla_{X} \tilde{C}\right)(Y, Z, U, V)=0 . \tag{5}
\end{equation*}
$$

Let us consider a concircularly symmetric (PCRS) ${ }_{n}$. Then by virtue of (3), it follows from (5) that

$$
\begin{equation*}
\left(\nabla_{X} R\right)(Y, Z, U, V)-\frac{d r(X)}{n(n-1)} G(Y, Z, U, V)=0 . \tag{6}
\end{equation*}
$$

Let $\left\{e_{i}: i=1,2, \ldots, n\right\}$ be an orthonormal basis of the tangent space at any point of the manifold. Then putting $Y=V=e_{i}$ in (6) and taking summation over $i, l \leq i \leq n$, we get

$$
\begin{equation*}
\left(\nabla_{X} S\right)(Z, U)=\frac{d r(X)}{n} g(Z, U) . \tag{7}
\end{equation*}
$$

Using (7) in (2), we obtain

$$
\begin{align*}
& 2 A(X) S(Y, Z)+A(Y) S(X, Z)+A(Z) S(Y, X) \\
& \quad=\frac{1}{\mathrm{n}}[d r(X) g(Y, Z)+d r(Y) g(Z, X)+d r(Z) g(X, Y)] . \tag{8}
\end{align*}
$$

Taking contraction of (8) over $Y$ and $Z$, we get

$$
\begin{equation*}
A(Q X)+r A(X)=\frac{n+2}{2 n} d r(X), \tag{9}
\end{equation*}
$$

where $Q$ is the Ricci-operator i.e., $g(Q X, Y)=S(X, Y)$ for all $X, Y$.
We now suppose that the scalar curvature $r$ is constant, then

$$
\begin{equation*}
d r(X)=0 \text { for all } X . \tag{10}
\end{equation*}
$$

In view of (10), (9) yields

$$
\begin{equation*}
A(Q X)=-r A(X), \tag{11}
\end{equation*}
$$

i.e.,

$$
\begin{equation*}
S(X, \rho)=-r g(X, \rho) . \tag{12}
\end{equation*}
$$

This leads to the following:
Theorem 2.1. In a concircularly symmetric $(P C R S)_{n}$ with constant scalar curvature, $-r$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $\rho$.

Since every concircularly flat manifold is concircularly symmetric. So by virtue of Theorem 2.1, we can state the following:

Corollary 2.1. In a concircularly flat $(P C R S)_{n}$ with constant scalar curvature, $-r$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $\rho$.

## 3. Concircularly Recurrent (PCRS) ${ }_{n}$

Definition 3.1. A $(P C R S)_{n}$ is said to be concircularly recurrent ([11, 12]) if its concircular curvature tensor $\tilde{C}$ satisfies the relation

$$
\begin{equation*}
\left(\nabla_{X} \tilde{C}\right)(Y, Z, U, V)=A(X) \tilde{C}(Y, Z, U, V), \tag{13}
\end{equation*}
$$

where $A$ is a non-vanishing 1-form.
We now consider a concircularly recurrent $(P C R S)_{n}$. Then by virtue of (3), it follows from (13) that

$$
\begin{align*}
& \left(\nabla_{X} R\right)(Y, Z, U, V)-\frac{d r(X)}{n(n-1)} G(Y, Z, U, V)  \tag{14}\\
& \quad=A(X)\left[R(Y, Z, U, V)-\frac{r}{n(n-1)} G(Y, Z, U, V)\right] .
\end{align*}
$$

Contracting (14) over $Y$ and $V$, we get

$$
\begin{equation*}
\left(\nabla_{X} S\right)(Z, U)-\frac{d r(X)}{n} g(Z, U)=A(X)\left[S(Z, U)-\frac{r}{n} g(Z, U)\right] . \tag{15}
\end{equation*}
$$

By virtue of (10), (15) yields

$$
\begin{equation*}
\left(\nabla_{x} S\right)(Z, U)=A(X)\left[S(Z, U)-\frac{r}{n} g(Z, U)\right] . \tag{16}
\end{equation*}
$$

Using (16) in (2), we obtain

$$
\begin{equation*}
A(X) S(Y, Z)=-\frac{r}{n}[A(X) g(Y, Z)+A(Y) g(Z, X)+A(Z) g(X, Y)] . \tag{17}
\end{equation*}
$$

Again taking contraction of (17) over $Y$ and $Z$, we get

$$
\begin{equation*}
r[A(Q X)+n A(X)]=0 \quad \text { for all } X . \tag{18}
\end{equation*}
$$

Since the scalar curvature $r$ of $(P C R S)_{n}$ is always non-zero [4]. Therefore (3.6) yields

$$
\begin{equation*}
A(Q X)=-n A(X), \tag{19}
\end{equation*}
$$

i.e.,

$$
\begin{equation*}
S(X, \rho)=-n g(X, \rho) . \tag{20}
\end{equation*}
$$

Thus we can state the following:
Theorem 3.1. In a concircularly recurrent $(P C R S)_{n}$ with constant scalar curvature, $-n$ is an eigenvalue of the Ricci tensor $S$ corresponding to the eigenvector $\rho$.

## 4. Decomposable (PCRS) ${ }_{n}$

A Riemannian manifold $\left(M^{n}, g\right)$ is said to be decomposable manifold [13] if it can be expressed as $M_{1}^{p} \times M_{2}^{n-p}$ for $2 \leq p \leq n-2$, that is, in some coordinate neighbourhood of the Riemannian manifold ( $M^{n}, g$ ), the metric can be expressed as
$\qquad$

$$
\begin{equation*}
d s^{2}=g_{i j} d x^{i} d x^{j}=\bar{g}_{a b} d x^{a} d x^{b}+\stackrel{*}{g}_{\alpha \beta} d x^{\alpha} d x^{\beta}, \tag{21}
\end{equation*}
$$

where $\bar{g}_{a b}$ are functions of $x^{l}, x^{2}, \ldots, x^{p}(p<n)$ denoted by $\bar{x}$ and $\stackrel{*}{g}_{\alpha \beta}$ are functions of $x^{p+1}, x^{p+2}, \ldots, x^{n}$ denoted by ${ }^{*} ; a, b, c, \ldots$ run from 1 to $p$ and $\alpha, \beta, \gamma, \ldots$ run from $p+1$ to $n$. The two parts of (21) are the metrics of $M_{1}^{p}(p \geq 2)$ and $M_{2}^{n-p}(n-p \geq 2)$ which are called the decompositions of the decomposable manifold

Let $\left(M^{n}, g\right)$ be a decomposable Riemannian manifold such that for $2 \leq p \leq n-2$. Here throughout this section each object denoted by a 'bar' is assumed to be from $M_{l}$ and each object denoted by a 'star' is assumed to be from $M_{2}$.
Let $\bar{X}, \bar{Y}, \bar{Z}, \bar{U}, \bar{V} \in \chi\left(M_{l}\right)$ and $\stackrel{*}{X}, \stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}, V^{*} \in \chi\left(M_{2}\right), \chi\left(M_{i}\right)$ being the Lie algebra of smooth vector fields on $M_{i}, i=1,2$. Then we have the following relations [13]:

$$
\begin{aligned}
R(\stackrel{*}{X}, \bar{Y}, \bar{Z}, \bar{U}) & =R(\bar{X}, \stackrel{*}{Y}, \bar{Z}, \stackrel{*}{U})=R(\bar{X}, \stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U})=0, \\
\left(\nabla_{\dot{X}} R\right)(\bar{Y}, \bar{Z}, \bar{U}, \bar{V}) & =\left(\nabla_{\bar{X}} R\right)(\bar{Y}, \stackrel{*}{Z}, \bar{U}, \stackrel{*}{V})=\left(\nabla_{\dot{*}} R\right)(\bar{Y}, \stackrel{*}{Z}, \bar{U}, \stackrel{*}{V})=0, \\
R(\bar{X}, \bar{Y}, \bar{Z}, \bar{U}) & =\bar{R}(\bar{X}, \bar{Y}, \bar{Z}, \bar{U}), \\
R(\stackrel{*}{X}, \stackrel{*}{Y}, \stackrel{*}{Z}, \stackrel{*}{U}) & =\stackrel{*}{R}(\stackrel{*}{X}, \stackrel{*}{Y}, \stackrel{*}{U}), \\
S(\bar{X}, \bar{Y}) & =\bar{S}(\bar{X}, \bar{Y}), \\
S(\stackrel{*}{X}, \stackrel{*}{Y}) & =\stackrel{*}{S}\left(\stackrel{*}{X}^{*}, \stackrel{*}{Y}\right), \\
\left(\nabla_{\bar{X}} S\right)(\bar{Y}, \bar{Z}) & =\left(\bar{\nabla}_{\bar{X}} S\right)(\bar{Y}, \bar{Z}), \\
\left(\nabla_{\dot{X}} S\right)(\stackrel{*}{Y}, \stackrel{*}{Z}) & =\left(\stackrel{*}{\nabla}_{\dot{X}}^{*} S\right)(\stackrel{*}{Y}, \stackrel{*}{Z}), \\
r & =\bar{r}+\stackrel{*}{r},
\end{aligned}
$$

where $r, \bar{r}$ and $r$ are the scalar curvature of $M, M_{1}, M_{2}$ respectively.
Let us consider a Riemannian manifold ( $M^{n}, g$ ) which is decomposable $(P C R S)_{n}$. Then $M^{n}=M_{1}^{p} \times M_{2}^{n-p},(2 \leq p \leq n-2)$.

Now from (2), we have

$$
\begin{align*}
& \left.\begin{array}{r}
\left(\nabla_{\bar{X}} S\right.
\end{array}\right)(\bar{Y}, \bar{Z})+\left(\nabla_{\bar{Y}} S\right)(\bar{Z}, \bar{X})+\left(\nabla_{\bar{Z}} S\right)(\bar{X}, \bar{Y}) \\
& \quad=2 A(\bar{X}) S(\bar{Y}, \bar{Z})+A(\bar{Y}) S(\bar{X}, \bar{Z})+A(\bar{Z}) S(\bar{Y}, \bar{X}) \\
& \text { or, } \\
& \begin{aligned}
\left(\nabla_{\bar{X}} S\right. & )(\bar{Y}, \bar{Z})+\left(\nabla_{\bar{Y}} S\right)(\bar{Z}, \bar{X})+\left(\nabla_{\bar{Z}} S\right)(\bar{X}, \bar{Y}) \\
\quad & 2 A(\bar{Y}) S(\bar{Z}, \bar{X})+A(\bar{Z}) S(\bar{X}, \bar{Y})+A(\bar{X}) S(\bar{Y}, \bar{Z})
\end{aligned} \tag{22}
\end{align*}
$$

or,
$\left(\nabla_{\bar{X}} S\right)(\bar{Y}, \bar{Z})+\left(\nabla_{\bar{Y}} S\right)(\bar{Z}, \bar{X})+\left(\nabla_{\bar{Z}} S\right)(\bar{X}, \bar{Y})$ $=2 A(\bar{Z}) S(\bar{X}, \bar{Y})+A(\bar{X}) S(\bar{Y}, \bar{Z})+A(\bar{Y}) S(\bar{Z}, \bar{X})$,
and

$$
\begin{aligned}
& \left(\nabla_{\dot{X}} S\right)(\stackrel{*}{Y}, \stackrel{*}{Z})+\left(\nabla_{\dot{Y}} S\right)(\stackrel{*}{Z}, \stackrel{*}{X})+\left(\nabla_{\dot{Z}} S\right)(\stackrel{*}{X}, \stackrel{*}{Y}) \\
& \quad=2 A(\stackrel{*}{X}) S(\stackrel{*}{Y}, \stackrel{*}{Z})+A(\stackrel{*}{Y}) S(\stackrel{*}{X}, \stackrel{*}{Z})+A(\stackrel{*}{Z}) S(\stackrel{*}{Y})
\end{aligned}
$$

or,

$$
\begin{align*}
& \left(\nabla_{\dot{X}} S\right)(\stackrel{*}{Y}, \stackrel{*}{Z})+\left(\nabla_{\dot{Y}} S\right)(\stackrel{*}{Z}, \stackrel{*}{X})+\left(\nabla_{\dot{Z}} S\right)\left(\stackrel{*}{X}_{X}, \stackrel{*}{Y}\right)  \tag{23}\\
& \quad=2 A(\stackrel{*}{Y}) S(\stackrel{*}{Z}, \stackrel{*}{X})+A(\stackrel{*}{Z}) S(\stackrel{*}{X}, \stackrel{*}{Y})+A(\stackrel{*}{X}) S(\stackrel{*}{Y}, \stackrel{*}{Z})
\end{align*}
$$

or,

$$
\begin{aligned}
\left(\nabla_{\dot{X}} S\right. & )(\stackrel{*}{Y}, \stackrel{*}{Z})+\left(\nabla_{\dot{Y}} S\right)(\stackrel{*}{Z}, \stackrel{*}{X})+\left(\nabla_{\dot{Z}} S\right)(\stackrel{*}{X}, \stackrel{*}{Y}) \\
& =2 A\left(\stackrel{*}{Z}_{Z}^{X}\right) S(\stackrel{*}{X})+A(\stackrel{*}{X}) S(\stackrel{*}{Y})+A(\stackrel{*}{Y}) S\left(\stackrel{*}{Z}_{Z}^{X}\right)
\end{aligned}
$$

From (22), we find

$$
\begin{align*}
& A(\stackrel{*}{X}) S(\bar{Y}, \bar{Z})=0  \tag{24}\\
& A(\bar{X}) S(\stackrel{*}{Y}, \stackrel{*}{Z})=0 \tag{25}
\end{align*}
$$

Now from (24) it follows that either $A(X)=0$ for any vector field $\stackrel{*}{X} \in \chi\left(M_{2}\right)$ or $S(\bar{Y}, \bar{Z})=0$ for all vector fields $\bar{Y}, \bar{Z} \in \chi\left(M_{l}\right)$, i.e., the decomposition $M_{l}$ is Ricci flat.
Again if $A\left({ }_{X}^{*}\right)=0$ then from (23), we get

$$
\left(\nabla_{\dot{X}} S\right)(\stackrel{*}{Y}, \underset{Z}{*})+\left(\nabla_{\dot{Y}} S\right)(\stackrel{*}{Z}, \stackrel{*}{X})+\left(\nabla_{\dot{Z}} S\right)(\stackrel{*}{X}, \stackrel{*}{Y})=0,
$$

that is, the Ricci tensor of the decomposition $M_{2}$ is cyclic parallel.
Similarly from (25), we obtain either the Ricci tensor of the decomposition $M_{1}$ is cyclic parallel or the decomposition $M_{2}$ is Ricci flat. Thus, we can state the following:

Theorem 4.1. In a decomposable $(P C R S)_{n}$, one of the decompositions is Ricci flat and the Ricci tensor of the other decomposition is cyclic parallel.

## 5. Totally Umbilical Hypersurfaces of (PCRS) ${ }_{n}$

Let $(\bar{V}, \bar{g})$ be an ( $n+1$ )-dimensional Riemannian manifold covered by a system of coordinate neighbourhoods $\left\{U, y^{\alpha}\right\}$. Let $(V, g)$ be a hypersurface of $(\bar{V}, \bar{g})$ defined in a locally coordinate system by means of a system of parametric equation $y^{\alpha}=y^{\alpha}\left(x^{i}\right)$, where Greek indices take values $1,2, \ldots, n$ and Latin indices take values $1,2, \ldots,(n+1)$. Let $N^{\alpha}$ be the components of a local unit normal to $(V, g)$. Then we have

$$
\begin{align*}
g_{i j} & =\bar{g}_{\alpha \beta} y_{i}^{\alpha} y_{j}^{\beta}  \tag{26}\\
\bar{g}_{\alpha \beta} N^{\alpha} y_{j}^{\beta} & =0, \bar{g}_{\alpha \beta} N^{\alpha} N^{\beta}=e=1,  \tag{27}\\
y_{i}^{\alpha} y_{j}^{\beta} g^{i j} & =\bar{g}^{\alpha \beta}-N^{\alpha} N^{\beta}, y_{i}^{\alpha}=\frac{\partial y^{\alpha}}{\partial x^{i}} . \tag{28}
\end{align*}
$$

The hypersurface $(V, g)$ is called a totally umbilical hypersurface $([14,15])$ of $(\bar{V}, \bar{g})$ if its second fundamental form $\Omega_{i j}$ satisfies

$$
\begin{equation*}
\Omega_{i j}=H g_{i j}, y_{i, j}^{\alpha}=g_{i j} H N^{\alpha}, \tag{29}
\end{equation*}
$$

where the scalar function $H$ is called the mean curvature of $(V, g)$ given by $H=\frac{1}{n} \Sigma g^{i j} \Omega_{i j}$. If, in particular, $H=0$, i.e.,

$$
\begin{equation*}
\Omega_{i j}=0, \tag{30}
\end{equation*}
$$

then the totally umbilical hypersurface is called a totally geodesic hypersurface of $(\bar{V}, \bar{g})$.
The equation of Weingarten for $(V, g)$ can be written as $N_{, j}^{\alpha}=-\frac{H}{n} y_{j}^{\alpha}$. The structure equations of Gauss and Codazzi $([14,15])$ for $(V, g)$ and $(\bar{V}, \bar{g})$ are respectively given by

$$
\begin{align*}
& R_{i j k l}=\bar{R}_{\alpha \beta \gamma \delta} B_{i j k l}^{\alpha \beta \gamma \delta}+H^{2} G_{i j k l},  \tag{31}\\
& \bar{R}_{\alpha \beta \gamma \delta} B_{i j k}^{\alpha \beta \gamma} N^{\delta}=H_{, i} g_{j k}-H_{, j} g_{i k}, \tag{32}
\end{align*}
$$

where $R_{i j k l}$ and $\bar{R}_{\alpha \beta \gamma \delta}$ are curvature tensors of $(V, g)$ and $(\bar{V}, \bar{g})$ respectively, and

$$
B_{i j k l}^{\alpha \beta \gamma \delta}=B_{i}^{\alpha} B_{j}^{\beta} B_{k}^{\gamma} B_{l}^{\delta}, B_{i}^{\alpha}=y_{i}^{\alpha}, G_{i j k l}=g_{i l} g_{j k}-g_{i k} g_{j l} .
$$

Also we have $([14,15])$

$$
\begin{gather*}
\bar{S}_{\alpha \delta} B_{i}^{\alpha} B_{j}^{\delta}=S_{i j}-(n-1) H^{2} g_{i j},  \tag{33}\\
\bar{S}_{\alpha \delta} N^{\alpha} B_{i}^{\delta}=(n-1) H_{, i},  \tag{34}\\
\bar{r}=r-n(n-1) H^{2}, \tag{35}
\end{gather*}
$$

where $S_{i j}$ and $\bar{S}_{\alpha \delta}$ are the Ricci tensors of $(V, g)$ and $(\bar{V}, \bar{g})$ respectively and $r$ and $\bar{r}$ are the scalar curvatures of $(V, g)$ and $(\bar{V}, \bar{g})$ respectively.

In terms of local coordinates the relation (2) can be written as

$$
\begin{align*}
& S_{i j, k}+S_{j k, i}+S_{k i, j}=2 A_{k} S_{i j}+A_{i} S_{j k}+A_{j} S_{k i} \\
& \text { or, } \\
& S_{i j, k}+S_{j k, i}+S_{k i, j}=2 A_{i} S_{j k}+A_{j} S_{k i}+A_{k} S_{i j}  \tag{36}\\
& \text { or, } \\
& S_{i j, k}+S_{j k, i}+S_{k i, j}=2 A_{j} S_{k i}+A_{k} S_{i j}+A_{i} S_{j k} .
\end{align*}
$$

## S.K. Hиi

Let $(\bar{V}, \bar{g})$ be a $(P C R S)_{n}$. Then we get

$$
\begin{align*}
& \bar{S}_{\alpha \beta, \gamma}+\bar{S}_{\beta \gamma, \alpha}+\bar{S}_{\gamma \alpha, \beta}=2 A_{\gamma} \bar{S}_{\alpha \beta}+A_{\alpha} \bar{S}_{\beta \gamma}+A_{\beta} \bar{S}_{\gamma \alpha} \\
& \text { or, } \\
& \bar{S}_{\alpha \beta, \gamma}+\bar{S}_{\beta \gamma, \alpha}+\bar{S}_{\gamma \alpha, \beta}=2 A_{\alpha} \bar{S}_{\beta \gamma}+A_{\beta} \bar{S}_{\gamma \alpha}+A_{\gamma} \bar{S}_{\alpha \beta}  \tag{37}\\
& \text { or, } \\
& \bar{S}_{\alpha \beta, \gamma}+\bar{S}_{\beta \gamma, \alpha}+\bar{S}_{\gamma \alpha, \beta}=2 A_{\beta} \bar{S}_{\gamma \alpha}+A_{\gamma} \bar{S}_{\alpha \beta}+A_{\alpha} \bar{S}_{\beta \gamma}
\end{align*}
$$

where $A, B$ are nowhere vanishing 1-forms.
Multiplying both sides of (37) by $B_{i j k}^{\alpha \beta \gamma}$ and then using (33) and (36), we obtain either

$$
H=0
$$

or

$$
\begin{equation*}
2\left[H_{, k} g_{i j}+H_{, i} g_{k j}+H_{, j} g_{i k}\right]=H\left[2 A_{k} g_{i j}+A_{i} g_{k j}+A_{j} g_{i k}\right] . \tag{38}
\end{equation*}
$$

Transvecting (38) by $g^{i j}$, we obtain

$$
\begin{equation*}
H_{, k}=\frac{n+1}{n+2} A_{k} \tag{39}
\end{equation*}
$$

for all $k$. This leads to the following:
Theorem 5.1. If the totally umbilical hypersurface of a $(P C R S)_{n}$ is a $(P C R S)_{n}$ then either the manifold is a totally geodesic hypersurface or the associated 1-form $A$ satisfies the relation (39).

We now consider that the space $(V, g)$ is totally geodesic hypersurface, i.e.,

$$
\begin{equation*}
H=0 . \tag{40}
\end{equation*}
$$

In view of (40), (33) yields

$$
\begin{equation*}
\overline{S_{\alpha \delta}} B_{i}^{\alpha} B_{j}^{\delta}=S_{i j} \tag{41}
\end{equation*}
$$

Using (41) in (37), we have the relation (36). Thus we can state the following:
Theorem 5.2. The totally geodesic hypersurface of a $(P C R S)_{n}$ is also $(P C R S)_{n}$.

## References

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