

On Regular Fréchet-Lie Groups IV

Definition and Fundamental Theorems

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Introduction

In the previous papers [10], [11], [12], we have seen that Fourier integral operators on a compact manifold have some group theoretical characters. Indeed, one of the purposes of this series is to show that the group of all invertible Fourier integral operators of order 0 on a C^∞ compact riemannian manifold is an *infinite dimensional Lie group*. It should, however, be remarked that we have not given in the previous papers the definition of infinite dimensional Lie groups. It will be given in this paper, hence *one may read this paper without knowing anything about the previous papers*.

Now, it continues to be a basic question when one may call a group G an infinite dimensional Lie group. However, taking the basic properties of finite dimensional Lie groups in mind, we suggest the following (L1)~(L3) are necessary at least, where

(L1) G is a C^∞ infinite dimensional manifold and the tangent space \mathfrak{g} at the identity has a Lie algebra structure, called the Lie algebra of G .

(L2) There exists the exponential mapping \exp of \mathfrak{g} into G such that $\{\exp tu; t \in \mathbf{R}\}$ is a smooth one parameter subgroup of G for every $u \in \mathfrak{g}$.

(L3) Local group structures of G (i.e., a neighborhood of the identity) can be determined by its Lie algebra \mathfrak{g} .

Hilbert or Banach-Lie groups [1], [5] satisfy these conditions and so do strong *ILB*- (or strong *ILH*-) Lie groups defined by Omori [8], [9].

Note that strong *ILB*-Lie groups include Banach-Lie groups, hence finite dimensional Lie groups. In this paper, we shall define a wider concept of infinite dimensional Lie groups, which will be called regular Fréchet-Lie groups throughout this series. Roughly speaking, a regular Fréchet-Lie group is a C^∞ manifold modeled on a locally convex Fréchet space, having a C^∞ group structure on which product integrals can be well-defined and have some smoothness properties.

§ 1. Several remarks on differentiability.

In this paper, we shall use the notion of differentiability defined in [3]. Let U be an open subset of a Fréchet space E , and F another Fréchet space, where all Fréchet spaces in this series are assumed to be locally convex. A mapping $f: U \rightarrow F$ is a C^0 mapping, if it is continuous. f is called to be *r-times differentiable at $x \in U$* , if f is C^{r-1} on a neighborhood of x and there exists a continuous symmetric r -linear mapping

$$(D^r f)(x): \underbrace{E \times \cdots \times E}_r \longrightarrow F$$

such that

$$F(v) = f(x+v) - f(x) - (Df)(x)(v) - \cdots - \frac{1}{r!} (D^r f)(x)(v, \dots, v)$$

satisfies the property that

$$R(t, v) = \begin{cases} F(tv)/t^r, & t \neq 0 \\ 0, & t = 0 \end{cases}$$

is continuous on a neighborhood of $(0, 0)$. f is called a *C^r mapping*, if f is r -times differentiable at each $x \in U$ and the mapping

$$D^r f: U \times E \times \cdots \times E \rightarrow F$$

is continuous. (Cf. See [2], [13] for the various definitions of the differentiability.)

Let U, V be open subsets of E, F respectively, and G another Fréchet space. $f: U \times V \rightarrow G$ will be called a *C^r mapping with respect to the first variable* if for each fixed $v \in V$, $f: U \rightarrow G$ is C^r and every $D_1^s f$ for $0 \leq s \leq r$ is a continuous mapping of $U \times V \times E \times \cdots \times E$ into G , where the suffix 1 of D means the derivative with respect to the first variable. The partial differentiability for the second variable is defined by the similar manner and the derivative is denoted by D_2 , etc..

The following properties of C^r mappings are used very often in this series. (For the proof, see [3] and [4]):

(A) A composition $f \circ g$ of C^r mappings f, g is a C^r mapping, and $D(f \circ g) = Df \cdot Dg$, more precisely

$$D(f \circ g)(x)(v) = (Df)(g(x))((Dg)(x)(v)) .$$

(B) If $f: U \rightarrow F$ is C^r , then $D^s f: U \times E \times \dots \times E \rightarrow F$ is C^{r-s} for $s \leq r$, and $D_t^t D^s f = D^{t+s} f$, $t+s \leq r$.

(C) $f: U \times V \rightarrow G$ is C^r if and only if f is C^r with respect to both first and second variables.

As Fréchet spaces are assumed to be locally convex, there are a lot of continuous linear functionals. Let $\lambda: F \rightarrow \mathbf{R}$ be one of them. For a C^1 mapping $f: U \rightarrow F$, $h(t) = \lambda f(x + tv)$ is an \mathbf{R} -valued C^1 -function on $[0, 1]$. Using the mean value theorem for h , we obtain

$$(1) \quad f(x+v) = f(x) + \int_0^1 (Df)(x+tv)(v) dt .$$

Thus, using (B) successively, one can get the following Taylor's expansion theorem: For a C^r function f ,

$$(2) \quad \begin{aligned} f(x+v) &= f(x) + (Df)(x)(v) + \dots + \frac{1}{(r-1)!} (D^{r-1}f)(x)(v, \dots, v) \\ &\quad + \int_0^1 \frac{(1-t)^{r-1}}{(r-1)!} (D^r f)(x+tv)(v, \dots, v) dt \\ &= f(x) + (Df)(x)(v) + \dots + \frac{1}{r!} (D^r f)(x)(v, \dots, v) \\ &\quad + \int_0^1 \frac{(1-t)^{r-1}}{(r-1)!} \{ (D^r f)(x+tv) - (D^r f)(x) \}(v, \dots, v) dt . \end{aligned}$$

By this formula, one can get the converse of (B), namely,

(B') $f: U \rightarrow F$ is C^r if and only if f is C^s for some $s (\leq r)$ and $D^s f: U \times E \times \dots \times E \rightarrow F$ is C^{r-s} .

REMARK. The above notion of differentiability coincides with the usual one if E, F, G are finite dimensional vector spaces. However, if E, F, G are infinite dimensional Banach spaces, the above notion is weaker than the usual definition of differentiability. For instance, the above definition requests only the continuity of $D^r f: U \times E \times \dots \times E \rightarrow F$, while in Banach spaces the continuity $D^r f: U \rightarrow L_{sym}^r(E, F)$ is usually requested, where the last one is the Banach space of symmetric r -linear mappings of $E \times \dots \times E$ into F with the uniform topology. The continuity of

$D^r f: U \times E \times \cdots \times E \rightarrow F$ ensures only that $D^r f: U \rightarrow L_{\text{sym}}^r(E, F)$ is locally bounded, namely for any $x \in U$ there is a neighborhood W of x , and a positive constant C such that

$$\|(D^r f)(y)(v_1, \cdots, v_r)\| \leq C \|v_1\| \|v_2\| \cdots \|v_r\|$$

for every $y \in W, v_1, \cdots, v_r \in E$. Thus, by $D_1 D^{r-1} f = D^r f$ and the mean value theorem (1), we have

$$\|(D^{r-1} f)(x+w) - (D^{r-1} f)(x)\| \leq C \|w\|.$$

Therefore, if $f: U \rightarrow F$ is C^r in the above sense, then f is C^{r-1} in the usual sense in Banach spaces. Thus, if we concern only C^∞ mappings, the above two notions of differentiability make no difference.

It should be remarked, however, that above two notions make a difference for the partial differentiability. In our definition, we request only the continuity of $D_i^s f: U \times V \times E \times \cdots \times E \rightarrow G$ for $s \leq r$. For a fixed $v \in V, D_1^{s-1} f: U \rightarrow L_{\text{sym}}^{s-1}(E, G)$ is continuous by the above remark, but this does not mean the continuity of $D_1^{s-1} f: U \times V \rightarrow L_{\text{sym}}^{s-1}(E, G)$.

Suppose E, F are Fréchet spaces and U, V are open subsets of E, F respectively. Let $f: U \rightarrow V$ be a C^r mapping ($r \geq 1$). We define the differential map $df: U \times E \rightarrow V \times F$ by

$$(df)(x, v) = (f(x), (Df)(x)(v)).$$

$Df(x)(v)$ is denoted sometimes by $(df)_x v, (Tf)_x v$ or $f_{*x} v$. Obviously, $df: U \times E \rightarrow V \times F$ is a C^{r-1} mapping by (B'). If f is a C^r -diffeomorphism (i.e., f^{-1} exists and C^r), then df is a C^{r-1} diffeomorphism.

LEMMA 1.1. *If $f: U \rightarrow V$ is invertible and C^r mapping ($r \geq 1$) and if f^{-1} is C^1 mapping, then f^{-1} is C^r mapping.*

PROOF. By using the composition rule (A), the derivative of f^{-1} at y is given by

$$(Df^{-1})(y) = (Df(x))^{-1}, \quad y = f(x) \in V.$$

Therefore, if $y, y+w \in V$

$$\begin{aligned} & (Df^{-1})(y+w) - (Df^{-1})(y) \\ &= -(Df^{-1})(y)((Df)(f^{-1}(y+w)) - (Df)(f^{-1}(y)))(Df^{-1}(y+w)). \end{aligned}$$

Hence by the continuity of $(Df^{-1})(y)w$ and the smoothness of f , we see that $(Df^{-1})(y)w$ is C^1 , and hence f^{-1} is C^2 . The desired regularity follows inductively by this manner. \square

Now, we define the notion of C^∞ Fréchet manifold M modeled on E as usual, i.e., M admits an admissible atlas which is a collection of pairs (U, ϕ) of local charts with C^∞ coordinate transformations. A tangent vector X_x , at $x \in M$, is an equivalence class of triples (U_i, ϕ_i, X_i) where (U_i, ϕ_i) is an arbitrary chart of M at x and X_i is a vector of E ; two triples are equivalent if

$$X_j = D(\phi_j \circ \phi_i^{-1})(\phi_i(x))X_i.$$

The representative $X_i \in E$ of X_x in the triple (U_i, ϕ_i, X_i) plays the same role as the components in a local coordinate system. The space of vectors tangent at the point x , together with its natural vector space structure is the tangent vector space $T_x M$. It can be easily verified that the set of vectors tangent to M , $TM = \bigcup_{x \in M} T_x M$ has a structure of a C^∞ differentiable manifold modeled on $E \times E$ by the family of charts $\{(\bigcup_{x \in M} T_x M, T\phi)\}$ where $\{(U, \phi)\}$ is an atlas of M modeled on E and $T\phi$ the homeomorphism of $\bigcup_{x \in U} T_x M$ on $U \times E$ defined by

$$T\phi(x, X_x) = (\phi(x), X)$$

X being the representative of X_x in the map (U, ϕ) . Moreover, the space T_M is given a fibre bundle structure with the natural projection $\pi: T_M \rightarrow M$ of C^∞ mapping and is called the Tangent bundle. Thus, the $C^k (k \leq \infty)$ vector fields are defined as usual as C^k sections of $\pi: T_M \rightarrow M$. However, we do not define the structure of vector bundle on T_M , for it is not easy to define a reasonable topology for $GL(E)$ as a topological group.

A subset N of M will be called a C^∞ Fréchet submanifold, if there is a closed subspace F of E and for every $x \in N$ there is a C^∞ local coordinate system $\phi: U \rightarrow M$ of M at x such that ϕ maps $U \cap F$ homeomorphically onto the arcwise connected component of x of a neighborhood of x in N under the relative topology.

A subset \mathcal{V} of T_M will be called a subbundle of T_M if the following conditions are satisfied:

(SB1) $\pi: \mathcal{V} \rightarrow M$ is surjective, and $\pi^{-1}(x) \cap \mathcal{V}$ is a closed linear subspace of $T_x M$ for every $x \in M$. We denote $\pi^{-1}(x) \cap \mathcal{V}$ by F_x and call it the fiber of \mathcal{V} at x .

(SB2) There exists an open neighborhood V_x of each $x \in M$, and a C^∞ diffeomorphism ψ_x of $V_x \times F_x$ onto $\pi^{-1}(V_x) \cap \mathcal{V} \subset T_M$ such that $\pi\psi_x(y, v) \equiv y$, $y \in V_x$, and ψ_x is linear with respect to the second variable.

(SB3) If $V_x \cap V_y \neq \emptyset$, then $\psi_x^{-1}\psi_y: (V_x \cap V_y) \times F_y \rightarrow (V_x \cap V_y) \times F_x$ is C^∞ . Given a Fréchet space E and a unit interval $I = [0, 1]$, let $C^k(I, E)$

be the set of all C^k mappings from I into \mathbf{E} ($k=0, 1, 2, \dots$). The set $C^k(I, \mathbf{E})$ has the structure of vector space in the obvious way. Consider the evaluation map

$$\text{ev}^k: I \times C^k(I, \mathbf{E}) \longrightarrow \underbrace{\mathbf{E} \times \dots \times \mathbf{E}}_{k+1}$$

given by

$$\text{ev}^k(t, c) = (c(t), (Dc)(t), \dots, (D^k c)(t)).$$

Putting a Fréchet structure into $\mathbf{E} \times \dots \times \mathbf{E}$, we obtain the uniform topology of $C^k(I, \mathbf{E})$.

Let M be a C^∞ Fréchet manifold modeled on \mathbf{E} and let $C^k(I, M)$ $k=0, 1, 2, \dots$, be a space of all C^k mappings from I into M . Then, we have the following.

LEMMA 1.2. $C^k(I, M)$ is a C^∞ Fréchet manifold modeled on $C^k(I, \mathbf{E})$ for each $k=0, 1, 2, \dots$. For a fixed point $p \in M$,

$$C_p^k(I, M) = \{c \in C^k(I, M); c(0) = p\}$$

is a C^∞ Fréchet submanifold of $C^k(I, M)$.

PROOF. Let U, V be open subsets of \mathbf{E} and let $\phi: U \rightarrow V$ a C^∞ diffeomorphism. Define a mapping $f: C^0(I, U) \rightarrow C^0(I, V)$ by $f(\lambda)(t) = \phi(\lambda(t))$. Obviously, the crucial part of the proof is to show that f is of C^∞ . For that purpose, set

$$\begin{aligned} F(\mu)(t) &= \phi((\lambda + \mu)(t)) - \phi(\lambda(t)) - (D\phi)(\lambda(t))(\mu(t)) - \dots \\ &\quad - \frac{1}{r!} (D^r \phi)(\lambda(t))(\mu(t), \dots, \mu(t)). \end{aligned}$$

By Taylor's theorem, we have

$$F(\mu)(t) = \int_0^1 \frac{(1-\theta)^{r-1}}{(r-1)!} \{D^r \phi(\lambda(t) + \theta \mu(t)) - D^r \phi(\lambda(t))\}(\mu(t), \dots, \mu(t)) d\theta.$$

Thus, using the uniform continuity of $D^r \phi(\lambda(t) + \theta \mu(t))$ we see that

$$R(s, \mu) = \begin{cases} F(s\mu)/s^r & s \neq 0 \\ 0 & s = 0 \end{cases}$$

is continuous on a neighborhood of $(0, 0)$. Since $D^r \phi(\lambda(t))(\mu_1(t), \dots, \mu_r(t))$ is continuous with respect to $\lambda \in C^0(I, U)$, $\mu_1, \dots, \mu_r \in C^0(I, \mathbf{E})$, for all

$r \geq 0$, we have that $f: C^0(I, U) \rightarrow C^0(I, V)$ is C^r and $D^r f(\lambda)(\mu_1, \dots, \mu_r)(t) = D^r \phi(\lambda(t))(\mu_1(t), \dots, \mu_r(t))$.

To prove the differentiability for $k > 0$, we have only to use $d^k \phi: U \times E \times \dots \times E \rightarrow V \times E \times \dots \times E$ instead of ϕ . □

§ 2. Several remarks on *FL*-groups.

An *FL*-group is the combined concept of a topological group and a C^∞ Fréchet manifold such that the group operations are C^∞ . Therefore, one may call an *FL*-group a Fréchet-Lie group. However, we hesitate to use the name "Lie", for a general *FL*-group may not have the properties (L1)~(L3) mentioned in the introduction.

Now, let G be an *FL*-group. The tangent space \mathfrak{g} of G at the identity e is naturally identified with its model space, and hence \mathfrak{g} is a Fréchet space. By definition, there is a C^∞ diffeomorphism ξ of an open neighborhood U of 0 in \mathfrak{g} onto an open neighborhood \tilde{U} of e in G such that $\xi(0) = e, (d\xi)_0 = \text{Id}$. $\xi: U \rightarrow \tilde{U}$ will be called a *local coordinate system* at e . (Usually, $\xi^{-1}: \tilde{U} \rightarrow U$ is called a "local coordinate system". We use the above definition in accordance with the exponential map of the group.) As \mathfrak{g} satisfies the first countability axiom, so also does G , and hence G has a right-invariant metric (cf [6] p. 34), where a metric ρ on G is called a *right-invariant metric* if $\rho(xa, ya) = \rho(x, y)$ for every $x, y, a \in G$.

As G is a topological group, there is an open neighborhood V of 0 in \mathfrak{g} such $\xi(V)^2 \subset \tilde{U}, \xi(V)^{-1} = \xi(V)$. Therefore, by the local coordinate system ξ at e , the group operations of G are represented by

$$\eta(u, v) = \xi^{-1}(\xi(u)\xi(v)), \quad \iota(u) = \xi^{-1}(\xi(u)^{-1}).$$

For every $g \in G$, there is an open neighborhood W of 0 in \mathfrak{g} such that $g\xi(W)g^{-1} \subset \tilde{U}$. We set

$$\tilde{A}_g(u) = \xi^{-1}(g\xi(u)g^{-1}).$$

As G is *FL*-group, η, ι and \tilde{A}_g are C^∞ on the domain on which they are defined.

Since $\eta(u, 0) \equiv u, \eta(0, v) \equiv v$, we see $(D_1\eta)_{(0,0)} = (D_2\eta)_{(0,0)} = \text{Id}$ (the identity). Let $a(t), b(t)$ be C^1 curves in G such that $a(0) = b(0) = e$. Then, $\dot{a}(0), \dot{b}(0) \in \mathfrak{g}$, where $\dot{a}(0) = (d/dt)|_{t=0} a(t)$. The product $c(t) = a(t)hb(t)$ is a C^1 curve in G with $c(0) = h \in G$. The following is easy to prove.

LEMMA 2.1.

$$\begin{aligned} \frac{d}{dt} \Big|_{t=0} a(t)hb(t) &= dR_h \dot{a}(0) + dL_h \dot{b}(0) \\ \frac{d}{dt} \Big|_{t=0} a(t)^{-1} &= -\dot{a}(0). \end{aligned}$$

where R_h (resp. L_g) denotes the right- (resp. left-) translation.

Let G be an FL -group. For every $g \in G$, define the map A_g on G by $A_g h = ghg^{-1}$. Then the map $A: G \times G \rightarrow G$,

$$(3) \quad A(g, h) = A_g h$$

is C^∞ . We often use the notation $A(g)h$ instead of $A_g h$. Given $u \in \mathfrak{g}$, there is a C^∞ curve $c(t)$ in G such that $c(0) = e$, and $\dot{c}(0) = u$ (for instance, $c(t) = \xi(tu)$ satisfies this). Define the adjoint map $\text{Ad}(g)$, $g \in G$ on \mathfrak{g} by

$$(4) \quad \text{Ad}(g)u = \frac{d}{dt} \Big|_{t=0} gc(t)g^{-1} \left(= \frac{d}{dt} \Big|_{t=0} A_g c(t) \right).$$

The adjoint map $\text{Ad}(g)$ can be expressed in terms of the left and right auxiliary functions. If we denote the left- (resp. right-) translation by

$$L_g: h \longrightarrow gh \quad (\text{resp. } R_g: h \longrightarrow hg), \quad g, h \in G,$$

then we get $\text{Ad}(g)u = (dR_g)^{-1}(dL_g)u$. Therefore, the definition (4) does not depend on the choice of the curve $c(t)$. Also, we put the following map of $G \times \mathfrak{g}$ to \mathfrak{g} by

$$\text{Ad}(g, u) = \text{Ad}(g)u, \quad g \in G, u \in \mathfrak{g}.$$

Let T_g be the tangent bundle of FL -group G . Since $T_g G = g \cdot g (= (dR_g)_g)$, $g \in G$, we see that T_g is C^∞ diffeomorphic to $\mathfrak{g} \times G$. The differential map of the product operation on G gives the group structure on T_g . Namely, under the identification between T_g and $\mathfrak{g} \times G$, we obtain the product $*$ on $\mathfrak{g} \times G$ by

$$(5) \quad (u, g) * (v, h) = (dR_{gh})(u + \text{Ad}(g)v) (= (u + \text{Ad}(g)v) \cdot gh).$$

LEMMA 2.2. *By the product $*$ of (5), $\mathfrak{g} \times G$ turns out to be an FL -group with $(0, e)$ as the identity and can be identified with T_g as FL -group. Moreover, $\mathfrak{g} \times \{e\}$ is a normal abelian subgroup of $\mathfrak{g} \times G$.*

The above FL -group will be denoted by $\mathfrak{g} * G$

Let $g(t)$ be a C^∞ curve in G such that $g(0) = e$, $\dot{g}(0) = u$. We define the bracket $[u, v]$ on \mathfrak{g} by

$$(6) \quad [u, v] = \left. \frac{d}{dt} \right|_{t=0} \text{Ad}(g(t))v, \quad v \in \mathfrak{g}.$$

To obtain that (6) satisfies the properties of the Lie bracket, we give the other description of (6). Denote for every $u \in \mathfrak{g}$ by u^* the right-invariant C^∞ vector field on G such that $u^*(e) = u$, i.e.,

$$(7) \quad u^*(g) = u \cdot g = (dR_g)_e u.$$

Then, we have the following by taking a C^∞ curve such that $c(0) = e$, $\dot{c}(0) = v$:

$$\begin{aligned} \left. \frac{d}{dt} \right|_{t=0} \text{Ad}(g(t))v &= \left. \frac{\partial^2}{\partial t \partial s} \right|_{\substack{t=0 \\ s=0}} g(t)c(s)g(t)^{-1} \\ &= \left. \frac{d}{ds} \right|_{s=0} \{dR_{c(s)}u - dL_{c(s)}u\} \quad (\text{Lemma 2.1}) \\ &= \partial_v u^* - \left. \frac{\partial^2}{\partial s \partial t} \right|_{\substack{t=0 \\ s=0}} c(s)g(t) \\ &= \partial_v u^* - \left. \frac{d}{dt} \right|_{t=0} dR_{g(t)}v \\ &= \partial_v u^* - \partial_u v^*, \end{aligned}$$

where in the above computations, differentials are computed by taking a local coordinate expression. Though $\partial_v u^*, \partial_u v^*$ depend on the choice of a local coordinate system, $\partial_v u^* - \partial_u v^*$ does not depend on it. Moreover, we see that $(d/dt)|_{t=0} \text{Ad}(g(t))v$ does not depend on the choice of $g(t)$. Hence, we get

$$(8) \quad [u, v] = \partial_v u^* - \partial_u v^*.$$

Since $(d^2 u^*)_e(v, w) = (d^2 u^*)_e(w, v)$, $u, v, w \in \mathfrak{g}$, the above bracket product satisfies the Jacobi identity, and hence \mathfrak{g} is a Lie algebra such that $[\cdot, \cdot]: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ is a continuous bi-linear mapping, i.e., \mathfrak{g} is a Fréchet-Lie algebra. \mathfrak{g} will be called the *Lie algebra* of G .

LEMMA 2.3. *Let $g(t)$ be a C^1 curve in G . Then,*

$$\begin{aligned} \frac{d}{dt} \text{Ad}(g(t))v &= [u(t), \text{Ad}(g(t))v], \\ \frac{d}{dt} \text{Ad}(g(t)^{-1})v &= -\text{Ad}(g(t)^{-1})[u(t), v], \end{aligned}$$

where $u(t) = (dg(t)/dt) \cdot g(t)^{-1} \in \mathfrak{g}$.

PROOF. Remark at first that $\text{Ad}(g(t))v$ is C^1 with respect to t . Note that $\text{Ad}(g)\text{Ad}(h)=\text{Ad}(gh)$ and $(dg/dt) \cdot g(t)^{-1}=d\xi(su(t))/ds|_{s=0}$. We compute as follows:

$$\begin{aligned} \frac{d}{dt}\text{Ad}(g(t))v &= \frac{d}{ds} \Big|_{s=0} \text{Ad}(g(t+s))v \\ &= \frac{d}{ds} \Big|_{s=0} \text{Ad}(\xi(su(t)) \cdot g(t))v \\ &= \frac{d}{ds} \Big|_{s=0} \text{Ad}(\xi(su(t)))\text{Ad}(g(t))v \\ &= [u(t), \text{Ad}(g(t))v]. \end{aligned}$$

(Remark that $\xi(su(t))$ is C^∞ w.r.t. s and use (6)). Similarly, by Lemma 2.1 and (6),

$$\begin{aligned} \frac{d}{dt}\text{Ad}(g(t)^{-1})v &= \frac{d}{ds} \Big|_{s=0} \text{Ad}(g(t)^{-1})\text{Ad}(\xi(su(t))^{-1})v \\ &= \text{Ad}(g(t)^{-1}) \frac{d}{ds} \Big|_{s=0} \text{Ad}(\xi(su(t))^{-1})v \\ &= -\text{Ad}(g(t)^{-1})[u(t), v]. \quad \square \end{aligned}$$

LEMMA 2.4. $\text{Ad}(g): \mathfrak{g} \rightarrow \mathfrak{g}$ is an automorphism of the Lie algebra and $\text{Ad}: G \times \mathfrak{g} \rightarrow \mathfrak{g}$, $\text{Ad}(g, u) = \text{Ad}(g)u$, $g \in G$, $u \in \mathfrak{g}$, is a C^∞ mapping.

PROOF. As $G \times G \rightarrow G$, $(g, h) \mapsto ghg^{-1}$ is C^∞ , the second assertion is obvious by definition. For every $g \in G$, $\text{Ad}(g): \mathfrak{g} \rightarrow \mathfrak{g}$ is obviously a linear isomorphism. Thus, we have only to show $\text{Ad}(g)[u, v] = [\text{Ad}(g)u, \text{Ad}(g)v]$. This is given as follows:

$$\begin{aligned} \text{Ad}(g)[u, v] &= \text{Ad}(g) \frac{d}{dt} \Big|_{t=0} \text{Ad}(c(t))v \\ &= \frac{d}{dt} \Big|_{t=0} \text{Ad}(gc(t))v \\ &= \frac{d}{dt} \Big|_{t=0} \text{Ad}(gc(t)g^{-1})\text{Ad}(g)v \\ &= [\text{Ad}(g)u, \text{Ad}(g)v], \end{aligned}$$

where $c(t)$ is a C^∞ curve in G such that $c(0)=e$ and $\dot{c}(0)=u$. The last equality follows from (6), for $(d/dt)gc(t)g^{-1}|_{t=0} = \text{Ad}(g)u$.

Remark that it is not known whether there is the exponential mapping $\exp: \mathfrak{g} \rightarrow G$ on every FL -group. Namely one might not be able

to solve the equation $(d/dt)g(t) = u(t) \cdot g(t)$. However, one can get the following uniqueness theorem:

LEMMA 2.5. *Let $u(t)$ be a \mathfrak{g} -valued continuous function on $[0, 1]$. Then, the uniqueness holds for the equation*

$$\frac{d}{dt}g(t) = u(t) \cdot g(t), \quad g(0) = e.$$

PROOF. Let $h(t)$ be another solution such that $h(0) = e$. Then, by

$$\frac{d}{dt}h(t)^{-1}g(t) = -dL_{h(t)^{-1}}dR_{g(t)}u(t) + dL_{h(t)^{-1}}dR_{g(t)}u(t) \equiv 0.$$

Hence by the mean value theorem (1), we have $h(t)^{-1}g(t) \equiv e$. □

Let $g(t)$ be a C^1 curve in G defined on $[0, 1]$. We set $u(t) = (dg(t)/dt) \cdot g(t)^{-1} \in \mathfrak{g}$.

LEMMA 2.6. *Let $w(t)$ be a \mathfrak{g} -valued C^0 function on $[0, 1]$. For the above $u(t)$, the differential equation*

$$\frac{d}{dt}v(t) - [u(t), v(t)] = w(t), \quad v(0) = 0$$

has a unique solution $\text{Ad}(g(t)) \int_0^t \text{Ad}(g(s)^{-1})w(s)ds$.

PROOF. By using Lemma 2.3, we see easily that

$$\text{Ad}(g(t)) \int_0^t \text{Ad}(g(s)^{-1})w(s)ds$$

is a solution. Suppose there is another solution $\bar{v}(t)$. Then $v(t) - \bar{v}(t)$ satisfies $(d/dt)(v(t) - \bar{v}(t)) = [u(t), v(t) - \bar{v}(t)]$ and $v(0) - \bar{v}(0) = 0$. Compute $(d/dt) \text{Ad}(g(t)^{-1})(v(t) - \bar{v}(t))$, by using Lemma 2.3, and we see easily that it is identically 0. Hence by the mean value theorem (1), we have $v(t) = \bar{v}(t)$. □

§ 3. Product integrals and the definition of regular Fréchet-Lie groups.

Now, we start with considering a division $\Delta: a = t_0 < t_1 < \dots < t_m = b$, of a closed interval $J = [a, b]$. By Δ we indicate also the set of dividing points $\{t_0, \dots, t_m\}$. For a division Δ of $[a, b]$, we denote by $|\Delta|$ the maximum of $|t_{j+1} - t_j|$.

Let G be an FL -group and \mathfrak{g} its Lie algebra.

DEFINITION 3.1. A *step function* defined on $[0, \varepsilon] \times [a, b]$ is a pair (h, Δ) of a division Δ of $[a, b]$ such that $|\Delta| < \varepsilon$ and a mapping $h: [0, \varepsilon] \times [a, b] \rightarrow G$ satisfying the following:

- (i) $h(0, t) = e$ for all $t \in [a, b]$, and $h(s, t)$ is C^1 in s for each fixed t .
- (ii) $h(s, t) = h(s, t_j)$ for $(s, t) \in [0, \varepsilon] \times [t_j, t_{j+1})$.

EXAMPLE. Let $\xi: U \rightarrow \tilde{U}$ be a local coordinate system at e such that U is a convex neighborhood of 0 in \mathfrak{g} . Let $u: [a, b] \rightarrow \mathfrak{g}$ be a mapping which is piecewise constant. Then $h(s, t) = \xi(su(t))$ is a step function defined on $[0, \varepsilon] \times [a, b]$ for an appropriately small ε .

Denote $[a, b]$ by J . By $\mathcal{S}_{\varepsilon, J}(G)$ we denote the space of all step functions on $[0, \varepsilon] \times J$, and by $S_{\varepsilon, J}(G)$ the space of all mappings $h: [0, \varepsilon] \times J \rightarrow G$ such that (h, Δ) is a step function for some Δ .

DEFINITION 3.2. A mapping $h: [0, \varepsilon] \times J \rightarrow G$ will be called a C^1 -hair at e if

- (i) $h(0, t) = e$ for all $t \in J$, and $h(s, t)$ is C^1 in s for each fixed t .
- (ii) $h(s, t)$ and $(\partial h / \partial s)(s, t)$ is C^0 with respect to $(s, t) \in [0, \varepsilon] \times J$.

If $u: J \rightarrow \mathfrak{g}$ is a continuous mapping, then $\xi(su(t))$ is a C^1 -hair at e defined on $[0, \varepsilon] \times J$ for a small ε . By $H_{\varepsilon, J}^1(G)$ we denote the space of all C^1 -hairs at e defined on $[0, \varepsilon] \times J$.

Let ρ be a right-invariant metric on G mentioned in the previous section, and d a metric on \mathfrak{g} by which \mathfrak{g} is a Fréchet space. Define a metric $\tilde{\rho}$ on the space of the union of $S_{\varepsilon, J}(G)$ and $H_{\varepsilon, J}^1(G)$ as follows:

$$(9) \quad \tilde{\rho}(h, h') = \max_{[0, \varepsilon] \times J} \rho(h(s, t), h'(s, t)) \\ + \max_{[0, \varepsilon] \times J} d\left(\frac{\partial h(s, t)}{\partial s} h(s, t)^{-1}, \frac{\partial h'(s, t)}{\partial s} h'(s, t)^{-1}\right).$$

Given $h \in H_{\varepsilon, J}^1(G)$ and a division $\Delta: a = t_0 < t_1 < \dots < t_m = b$ of J , we define a step function $(\sigma_{\Delta}(h), \Delta) \in \mathcal{S}_{\varepsilon, J}(G)$ by

$$(10) \quad \sigma_{\Delta}(h)(s, t) = h(s, t_j) \quad \text{for } t \in [t_j, t_{j+1}).$$

LEMMA 3.3. Let $\{\Delta_n\}$ be a sequence of a division of J such that $\lim_{n \rightarrow \infty} |\Delta_n| = 0$. Then, for any $h \in H_{\varepsilon, J}^1(G)$, $\lim_{n \rightarrow \infty} \sigma_{\Delta_n}(h) = h$ with respect to $\tilde{\rho}$ defined by (9).

PROOF. Since $h(s, t)$ and $(\partial h(s, t) / \partial s) h(s, t)^{-1}$ are uniformly continuous in (s, t) , we get easily $\lim_{n \rightarrow \infty} \tilde{\rho}(\sigma_{\Delta_n}(h), h) = 0$. \square

Let K be a compact subset of $H_{\varepsilon, J}^1(G)$. Then it is easy to see that h and $(\partial h(s, t) / \partial s) h(s, t)^{-1}$ are equi-continuous whenever $h \in K$. Hence we

have

COROLLARY 3.4. *For a fixed sequence of a division Δ_n of J such that $\lim_{n \rightarrow \infty} |\Delta_n| = 0$, $\lim_{n \rightarrow \infty} \sigma_{\Delta_n}$ converges uniformly to the identity on every compact subset K of $H_{\varepsilon, J}^1(G)$.*

For a step function $(h, \Delta) \in \mathcal{S}_{\varepsilon, J}(G)$, we define a product integral $\prod_s^t (h, \Delta)(t \geq s)$ by

$$(11) \quad \prod_s^t (h, \Delta) = h(t - t_k, t_k) h(\Delta t_k, t_{k-1}) \cdots h(\Delta t_{l+1}, t_l) h(t_l - s, s)$$

where k, l are the numbers such that $t \in [t_k, t_{k+1})$, $s \in [t_{l-1}, t_l)$ respectively, and set $\Delta t_j = t_j - t_{j-1}$.

DEFINITION 3.5. An FL-group G will be called a *regular Fréchet-Lie group*, if the following condition is satisfied: Let $\{(h_n, \Delta_n)\}$ be any sequence in $\mathcal{S}_{\varepsilon, J}(G)$ for some $\varepsilon > 0$ and $J = [a, b]$ such that $\lim_{n \rightarrow \infty} |\Delta_n| = 0$ and $\lim_{n \rightarrow \infty} h_n = h \in H_{\varepsilon, J}^1(G)$ with respect to $\tilde{\rho}$. Then, the product integral $\prod_a^t (h_n, \Delta_n)$ converges uniformly in $t \in [a, b]$.

Once such a condition is satisfied, the limit $\lim_{n \rightarrow \infty} \prod_a^t (h_n, \Delta_n)$ depends only on $h \in H_{\varepsilon, J}^1(G)$. Hence we denote the limit by $\prod_a^t (h, d\tau)$ and call it *the product integral of h* . Since $g_n(t) = \prod_a^t (h_n, \Delta_n)$ are continuous curves in G such that $g_n(a) = e$, so is the limit $g(t) = \prod_a^t (h, d\tau) = \lim_{n \rightarrow \infty} g_n(t)$, for the uniformity of the convergence is assumed. (For the aspects of the product integral, see [7]. p. 15.)

If $d < c$, we define

$$\prod_d^c (h, d\tau) = \left\{ \prod_d^c (h, d\tau) \right\}^{-1}.$$

With this convention, we always have

LEMMA 3.6. *Let G be a regular Fréchet-Lie group and let h be a C^1 -hair at e defined on $[0, \varepsilon] \times J$. Then,*

$$\prod_\alpha^\gamma (h, d\tau) = \prod_\beta^\gamma (h, d\tau) \prod_\alpha^\beta (h, d\tau)$$

for every $\alpha, \beta, \gamma \in J$.

PROOF. We may prove only for case $\alpha \leq \beta \leq \gamma$. Notice that if we take a division Δ of J such that β is a dividing point of Δ , then for each step function (h, Δ) we get

$$\prod_{\alpha}^{\gamma} (h, \Delta) = \prod_{\beta}^{\gamma} (h, \Delta) \prod_{\alpha}^{\beta} (h, \Delta).$$

Using the above equality, we get the desired equality. \square

LEMMA 3.7. *Let $\Phi: J \times H_{i,j}^1(G) \rightarrow G$ be a mapping defined by $\Phi(t, h) = \prod_{\alpha}^t(h, d\tau)$. Then Φ is continuous, where the topology on $H_{i,j}^1(G)$ is given by $\tilde{\rho}$ defined by (9).*

PROOF. Suppose that Φ is discontinuous at (t, h) . Then there is a sequence (t_k, h_k) such that $|t - t_k| \rightarrow 0$, $\tilde{\rho}(h_k, h) \rightarrow 0$ but there is $\delta > 0$ such that $\rho(\prod_{\alpha}^{t_k}(h_k, d\tau), \prod_{\alpha}^t(h, d\tau)) \geq \delta$. Use Corollary 3.4 for the compact subset $K = \{h, h_k, k = 1, 2, 3, \dots\}$. Note that if $m \rightarrow \infty$ as $k \rightarrow \infty$ then $(\sigma_m(h_k), \Delta_m)$'s are step functions such that $\lim_{k \rightarrow \infty} \tilde{\rho}(\sigma_m(h_k), h) = 0$, where σ_m is the abbreviation of σ_{Δ_m} . Hence by the hypothesis of regular Fréchet-Lie groups, $\prod_{\alpha}^t(\sigma_m(h_k), \Delta_m)$ must converge to $\prod_{\alpha}^t(h, d\tau)$ uniformly as $k \rightarrow \infty$. This contradicts the assumption if we choose $n(k)$ for each k so that it may satisfy $\rho(\prod_{\alpha}^{t_k}(\sigma_{n(k)}(h_k), \Delta_{n(k)}), \prod_{\alpha}^{t_k}(h_k, d\tau)) < \delta/3$. \square

REMARK. In what follows, we often use the notation σ_m instead of σ_{Δ_m} for a typographical reason.

Note that the Lie algebra \mathfrak{g} of G is an abelian FL-group. For sufficiently small $\varepsilon > 0$, consider a C^1 -hair $\lambda \in H_{i,j}^1(\mathfrak{g})$. Then, $\xi \circ \lambda$ is a C^1 -hair at e defined on $[0, \varepsilon] \times J$. Set

$$\xi \circ \lambda_r(s, t) = \xi \circ \lambda(rs, t) \quad (0 \leq r \leq 1).$$

Then, obviously $\lim_{r \rightarrow 0} \xi \circ \lambda_r = e$ with respect to $\tilde{\rho}$.

COROLLARY 3.8. *Let G be a regular Fréchet-Lie group. Notations being as above, $\lim_{r \rightarrow 0} \prod_{\alpha}^t(\xi \circ \lambda_r, d\tau)$ converges to e uniformly on J .*

PROOF. If it does not, there must exist a sequence (t_k, r_k) such that $t_k \in J$, $\lim_{k \rightarrow \infty} r_k = 0$ but $\rho(\prod_{\alpha}^{t_k}(\xi \circ \lambda_{r_k}, d\tau), e) \geq \delta (> 0)$ for some δ . Since J is compact, one may suppose that $\{t_k\}$ converges to $t \in J$. Hence, this contradicts the continuity of Φ in the above lemma. \square

Finally, we shall remark the following:

LEMMA 3.9. *Every Fréchet space E is a regular Fréchet-Lie group.*

PROOF. Let $\{(h_n, \Delta_n)\}$ be a sequence in $\mathcal{S}_{i,j}(E)$ such that $\lim_{n \rightarrow \infty} |\Delta_n| = 0$ and $\{h_n\}$ converges to $h \in H_{i,j}^1(E)$ with respect to $\tilde{\rho}$. We set

$$v_n(s, t) = \frac{\partial h_n}{\partial s}(s, t), \quad v(s, t) = \frac{\partial h}{\partial s}(s, t).$$

Then, by (11)

$$\begin{aligned} \prod_a^t (h_n, \Delta_n) &= \int_0^{t-t_k} v_n(\theta, t_k) d\theta + \sum_{i=0}^{k-1} \int_0^{\Delta^{t_i+1}} v_n(\theta, t_i) d\theta \\ &= \int_a^t v_n(0, t) dt + \int_0^{t-t_k} (v_n(\theta, t_k) - v_n(0, t_k)) d\theta \\ &\quad + \sum_{i=0}^{k-1} \int_0^{\Delta^{t_i+1}} (v_n(\theta, t_i) - v_n(0, t_i)) d\theta, \end{aligned}$$

where $\Delta_n: a=t_0 < t_1 < \dots < t_{m_n} = b, t \in [t_k, t_{k+1})$. Note that

$$\lim_{n \rightarrow \infty} \int_a^t v_n(0, t) dt = \int_a^t v(0, t) dt.$$

Now, remark that the topology of E can be given by countably many semi-norms. Let $|\cdot|_\alpha$ be any one of them. Then, we have

$$\begin{aligned} \left| \prod_a^t (h_n, \Delta_n) - \int_a^t v(0, t) dt \right|_\alpha &\leq \int_a^t |v_n(0, t) - v(0, t)|_\alpha dt \\ &\quad + (b-a) \max_{\substack{t \in J \\ 0 \leq \theta \leq |\Delta_n|}} |v_n(\theta, t) - v_n(0, t)|_\alpha. \end{aligned}$$

Hence, we see $\lim_{n \rightarrow \infty} \prod_a^t (h_n, \Delta_n) = \int_a^t v(0, t) dt$ uniformly in $t \in J$. □

§ 4. The first fundamental theorem.

The goal of this section is as follows:

THEOREM 4.1 (First fundamental theorem). *Suppose G is a regular Fréchet-Lie group. For a C^1 -hair h at e on $[0, \epsilon] \times J$, the product integral $g(t) = \prod_a^t (h, d\tau)$ is C^1 in t and satisfies the equation*

$$\frac{dg(t)}{dt} = u(t) \cdot g(t), \quad g(a) = e,$$

where $u(t) = (\partial h / \partial s)(0, t)$.

REMARK. By Lemma 2.5, $\prod_a^t (h, d\tau)$ depends only on $u(t) = (\partial h / \partial s)(0, t)$, hence $\prod_a^t (h, d\tau)$ is denoted often by $\prod_a^t (1 + u(\tau)) d\tau$.

Now, let $\Delta_n: a < a + (1/n)(b-a) < a + (2/n)(b-a) < \dots < a + (n/n)(b-a) = b$, be a division of $J = [a, b]$. By $(\sigma_n(h), \Delta_n)$ we denote the step function defined by (10) (see also Remark after Lemma 3.7) for an arbitrarily fixed $h \in H_{\epsilon, J}^1(G)$.

Recall that $\prod_a^t (h, d\tau)$ is continuous in t by Lemma 3.7 and that

$\prod_a^t(\sigma_n(h), \Delta_n)$ converges uniformly to $\prod_a^t(h, d\tau)$, $t \in J$. Then, we easily obtain the following:

LEMMA 4.2. *For any open neighborhood \tilde{U} of e in G , there are $\delta > 0$ and n_0 such that if $n \geq n_0$ then $\prod_a^t(\sigma_n(h), \Delta_n)$ and $\prod_a^t(h, d\tau)$ are both contained in \tilde{U} for every $t \in J_s$, where $J_s = [a, a + \delta]$.*

Now suppose $\xi: U \rightarrow \tilde{U}$ is a local coordinate system at e in G . By the above lemma one may assume that $\prod_a^t(\sigma_n(h), \Delta_n) \in \tilde{U}$, $\prod_a^t(h, d\tau) \in \tilde{U}$, for large n and $t \in J_0 = [a, b']$, if we choose b' such that $b' - a$ is small.

Let $\eta(u, v) = \xi^{-1}(\xi(u)\xi(v))$. This map η is defined for all pairs u, v in U such that $\xi(u)\xi(v) \in \tilde{U}$. For a small $\varepsilon > 0$ and a C^1 -hair $h \in H_{i,j}^1(G)$, set

$$\lambda(s, t) = \xi^{-1} \circ h(s, t).$$

We see easily that $\lambda(0, t) \equiv 0$, $(\partial\lambda/\partial s)(0, t) = u(t)$, where $u(t) = (\partial h/\partial s)(0, t)$.

LEMMA 4.3. *Given $u(a) \in \mathfrak{g}$ and any convex neighborhood V of 0 in \mathfrak{g} , there is a convex neighborhood V_1 of 0 which is contained in a coordinate neighborhood U such that*

$$((d\eta_w)_v - \text{Id})u' \in V, \text{ for } w, v \in V_1, u' \in u(a) + V_1,$$

where we set $\eta_w(v) = \eta(v, w)$, $u(a) + V_1 = \{u(a) + v_1; v_1 \in V_1\}$.

Proof is easy, because $(d\eta_0)_0 = \text{Id}$ and $(d\eta_w)_v u'$ is continuous in (w, v, u') . □

By Lemma 4.2, there are $\delta > 0$ and n_0 such that $\xi^{-1} \circ \prod_a^t(h, d\tau) \in V_1$ for $t \in J_s$, $J_s = [a, a + \delta]$ and that $\xi^{-1} \circ \prod_a^t(\sigma_n(h), \Delta_n) \in V_1$ for $n \geq n_0$, $t \in J_s$. Moreover, since $\lambda(s, t)$ is continuous and $\lambda(0, t) \equiv 0$, one may assume that $\lambda(s, t) \in V_1$ for $t \in J_s$, $s \in [0, |\Delta_{n_0}|]$, $|\Delta_{n_0}| = (b - a)/n_0$.

Now, set $w_n(t) = \xi^{-1} \circ \prod_a^t(\sigma_n(h), \Delta_n)$, $w(t) = \xi^{-1} \circ \prod_a^t(h, d\tau)$. For simplicity we set also $t_i = (i(b - a)/n) + a$. Then we have

$$(12) \quad \begin{cases} w_n(t) = \eta(\lambda(t - t_k, t_k), w_n(t_k)), & t \in [t_k, t_{k+1}), \\ w_n(t_{i+1}) = \eta(\lambda(|\Delta_n|, t_i), w_n(t_i)), & 0 \leq i \leq k - 1, \end{cases}$$

where $|\Delta_n| = (b - a)/n$. Hence we get

$$\begin{cases} w_n(t) = \int_0^1 (d\eta_{w_n(t_k)})_{s\lambda(t-t_k, t_k)} \lambda(t - t_k, t_k) ds + w_n(t_k), & t \in [t_k, t_{k+1}), \\ w_n(t_{i+1}) = \int_0^1 (d\eta_{w_n(t_i)})_{s\lambda(|\Delta_n|, t_i)} \lambda(|\Delta_n|, t_i) ds + w_n(t_i), & 0 \leq i \leq k - 1. \end{cases}$$

Therefore, for $t \in [t_k, t_{k+1}]$,

$$\begin{aligned}
 (13) \quad w_n(t) &= \int_0^1 (d\eta_{w_n(t_k)})_{s\lambda(t-t_k, t_k)} \lambda(t-t_k, t_k) ds \\
 &\quad + \sum_{i=0}^{k-1} \int_0^1 (d\eta_{w_n(t_i)})_{s\lambda(|\Delta_n|, t_i)} \lambda(|\Delta_n|, t_i) ds \\
 &= \lambda(t-t_k, t_k) + \sum_{i=0}^{k-1} \lambda(|\Delta_n|, t_i) \\
 &\quad + \int_0^1 [(d\eta_{w_n(t_k)})_{s\lambda(t-t_k, t_k)} - \text{Id}] \lambda(t-t_k, t_k) ds \\
 &\quad + \sum_{i=0}^{k-1} \int_0^1 [(d\eta_{w_n(t_i)})_{s\lambda(|\Delta_n|, t_i)} - \text{Id}] \lambda(|\Delta_n|, t_i) ds .
 \end{aligned}$$

LEMMA 4.4. For a sufficiently large n and for a sufficiently small $\delta_0 > 0$, if $t \in J_{\delta_0}$, then

$$\begin{aligned}
 \frac{1}{t-t_k} \lambda(t-t_k, t_k) &\in u(a) + V_1, \quad t \in [t_k, t_{k+1}), \\
 \frac{1}{|\Delta_n|} \lambda(|\Delta_n|, t_i) &\in u(a) + V_1, \quad 0 \leq i \leq k-1,
 \end{aligned}$$

where V_1 is the convex neighborhood given in Lemma 4.3.

PROOF. Note that $\lim_{s \rightarrow 0} (1/s)\lambda(s, t) = u(t)$. Using the mean value theorem (1), we see easily that the above convergence is uniform in $t \in J_\delta$. Hence, there is $\delta' > 0$ such that $(1/s)\lambda(s, t) \in u(t) + (1/2)V_1$ for $s \leq \delta'$, where $aV_1 = \{au'; u' \in V_1\}$. As $u(t)$ is continuous, we get the desired result. \square

Recall that $w_n(t) = \xi^{-1} \circ \prod_a^t(\sigma_n(h), \Delta_n)$ for $t \in J_\delta, n \geq n_0$, and $\lambda(s, t) \in V_1$ for $(s, t) \in [0, |\Delta_{n_0}] \times J_\delta$. It follows from Lemma 4.3 and Lemma 4.4 that

$$\begin{aligned}
 [(d\eta_{w_n(t_k)})_{s\lambda(t-t_k, t_k)} - \text{Id}] \lambda(t-t_k, t_k) &\in (t-t_k)V \subset |\Delta_n|V, \\
 [(d\eta_{w_n(t_i)})_{s\lambda(|\Delta_n|, t_i)} - \text{Id}] \lambda(|\Delta_n|, t_i) &\in |\Delta_n|V.
 \end{aligned}$$

Since V is convex, we get from (13) that for any $t \in J_{\delta_0}$,

$$(14) \quad w_n(t) - \left\{ \lambda(t-t_k, t_k) + \sum_{i=0}^{k-1} \lambda(|\Delta_n|, t_i) \right\} \in (k+1)|\Delta_n|V,$$

where $t \in [t_k, t_{k+1})$.

Keep in mind that V is an arbitrary convex neighborhood of 0 in \mathfrak{g} .

LEMMA 4.5. $\lambda(t-t_k, t_k) + \sum_{i=0}^{k-1} \lambda(|\Delta_n|, t_i) \in (t-a)u(a) + (k+1)|\Delta_n|V_1, t \in [t_k, t_{k+1})$.

PROOF. By Lemma 4.4, we see for $t \in [t_k, t_{k+1})$,

$$\begin{aligned} \lambda(t-t_k, t_k) &\in (t-t_k)(u(a) + V_1) \subset (t-t_k)u(a) + |\Delta_n|V_1, \\ \lambda(|\Delta_n|, t_i) &\in |\Delta_n|(u(a) + V_1) \end{aligned}$$

Thus we get the desired one by using the convexity of V_1 . □

Using Lemma 4.5 and (14), we obtain that

$$w_n(t) \in (t-a)u(a) + (k+1)|\Delta_n|V_1 + (k+1)|\Delta_n|V, \quad t \in J_{t_0}.$$

Note that $t \in [t_k, t_{k+1})$, hence $k|\Delta_n| \leq t-a < (k+1)|\Delta_n|$. Thus,

$$w_n(t) \in (t-a)(u(a) + V_1 + V) + |\Delta_n|(V_1 + V).$$

Hence recalling $w(t) = \lim_{n \rightarrow \infty} w_n(t)$, we get

$$\lim_{t \rightarrow a^+} \frac{1}{t-a} w(t) \in u(a) + (V_1 + V)^-,$$

where $(V_1 + V)^-$ is the closure of $V_1 + V$. Remark that V and V_1 can be chosen arbitrarily small. Therefore, the above result shows that

$$\lim_{t \rightarrow a^+} \frac{1}{t-a} w(t) = u(a).$$

Namely,

$$\lim_{t \rightarrow a^+} \frac{1}{t-a} \xi^{-1} \circ \prod_a^t(h, d\tau) = \frac{\partial(\xi^{-1} \circ h)}{\partial s}(0, a) = \frac{\partial h}{\partial s}(0, a).$$

This means that $w(t)$ is differentiable at a from the right hand side. Since $\prod_a^t(h, d\tau) \cdot \prod_a^t(h, d\tau) = \prod_a^t(h, d\tau)$, the above result shows also that $w(t) = \xi^{-1} \circ \prod_a^t(h, d\tau)$ is differentiable from the right hand side at every $t \in [a, a + \delta_0]$ and the derivative $D^+w(t)$ is given by

$$D^+w(t) = (d\eta_{w(t)})_0 u(t).$$

As $w(t)$ and $u(t)$ are continuous in $t \in [a, a + \delta_0]$, so is $(d\eta_{w(t)})_0 u(t)$. Set $\bar{w}(t) = \int_0^t (d\eta_{w(s)})_0 u(s) ds$. Then $\bar{w}(t)$ is C^1 and $D^+(w(t) - \bar{w}(t)) \equiv 0$, $w(a) - \bar{w}(a) = 0$.

LEMMA 4.6. *Let $v(t)$ be a continuous mapping from $[a, a + \delta_0]$ into g such that $v(t)$ is differentiable from the right hand side and $D^+v \equiv 0$ on $[a, a + \delta_0]$. Suppose $v(a) = 0$. Then $v \equiv 0$.*

PROOF. This fact is well-known for \mathbb{R} -valued functions. Let $\kappa: g \rightarrow \mathbb{R}$ be an arbitrary continuous linear mapping. Then we have $\kappa v(a) = 0$ and $D^+ \kappa v(t) = \kappa \circ D^+ v(t) \equiv 0$. Thus, $\kappa v \equiv 0$ for every κ . It follows $v \equiv 0$ because g is assumed to be locally convex. □

PROOF OF THEOREM 4.1. The above lemma shows that $w(t) = \xi^{-1} \circ \prod_a^t(h, d\tau)$ is C^1 for $t \in [a, a + \delta]$, where δ is sufficiently small, and $(d/dt)w(t) = (d\eta_{w(t)})_0 u(t)$. This implies that

$$\frac{d}{dt} \prod_a^t(h, d\tau) = u(t) \cdot \prod_a^t(h, d\tau), \quad t \in [a, a + \delta].$$

Recall again that $\prod_a^t(h, d\tau) \cdot \prod_a^s(h, d\tau) = \prod_a^{t+s}(h, d\tau)$. This relation gives us that $\prod_a^t(h, d\tau)$ is C^1 for all $t \in [a, b]$ and satisfies the above equation. Theorem 4.1 is thereby proved. \square

§ 5. The second fundamental theorem.

Suppose G is a regular Fréchet-Lie group with the Lie algebra \mathfrak{g} . As G is a C^∞ Fréchet manifold, there is a C^∞ local coordinate system $\xi: U \rightarrow \tilde{U}$ at e such that $\xi(0) = e$. Let u be a continuous mapping of the closed interval $I = [0, 1]$ into \mathfrak{g} . If we set $h(s, t) = \xi(su(t))$ for a sufficiently small s , then it is clear that $h \in H_{\varepsilon, I}^1(G)$ for some $\varepsilon > 0$. By Theorem 4.1 $g(t) = \prod_0^t(h, d\tau)$ satisfies the equation

$$\frac{d}{dt}g(t) = u(t) \cdot g(t), \quad g(0) = e.$$

Hence by the uniqueness theorem (cf. Lemma 2.5) we denote this product integral by $\prod_0^t(1 + u(\tau))d\tau$, for it depends only on $u(t)$.

Let $C^0(I, \mathfrak{g})$ be the linear space of all C^0 mappings of I into \mathfrak{g} . $C^0(I, \mathfrak{g})$ is a Fréchet-Lie group (Lemma 3.9). We denote by $C_0^1(I, G)$ the totality of C^1 mappings $c: I \rightarrow G$ such that $c(0) = e$. $C_0^1(I, G)$ is a group under the pointwise group-operations, and a topological group under the C^1 uniform topology. Moreover, by Lemma 1.2 $C_0^1(I, G)$ is a C^∞ Fréchet manifold. The goal of this section is as follows:

THEOREM 5.1 (Second fundamental theorem). *Notations and assumptions being as above $C_0^1(I, G)$ is an FL-group, and the mapping $\mathcal{S}: C^0(I, \mathfrak{g}) \rightarrow C_0^1(I, G)$ defined by $\mathcal{S}(u)(t) = \prod_0^t(1 + u(\tau))d\tau$ is a C^∞ -diffeomorphism.*

First of all, we shall remark the following:

LEMMA 5.2. *Suppose G is an FL-group. Then $C_0^1(I, G)$ is an FL-group with the Lie algebra $C_0^1(I, \mathfrak{g})$ which is the totality of C^1 mappings $u: I \rightarrow \mathfrak{g}$ such that $u(0) = 0$.*

PROOF. It is easy to see that $C_0^1(I, \mathfrak{g})$ is a Fréchet space under the C^1 uniform topology (cf. Lemma 1.2). Let $\xi: U \rightarrow \tilde{U}$ be a local coordinate system at e of G . We set

$$\begin{aligned}\Sigma &= \{u \in C_0^1(I, \mathfrak{g}); u(t) \in U \text{ for all } t \in I\} \\ \tilde{\Sigma} &= \{c \in C_0^1(I, G); c(t) \in \tilde{U} \text{ for all } t \in I\}.\end{aligned}$$

Define $\hat{\xi}: \Sigma \rightarrow \tilde{\Sigma}$ by $\hat{\xi}(u)(t) = \xi(u(t))$. We set $\hat{\eta}(u, v) = \hat{\xi}^{-1}(\hat{\xi}(u)\hat{\xi}(v))$, $\hat{\iota}(u) = \hat{\xi}^{-1}(\hat{\xi}(u)^{-1})$. These are well-defined if u, v are contained in a small neighborhood of 0, and these are C^∞ because $\hat{\eta}(u, v)(t) = \eta(u(t), v(t))$, $\hat{\iota}(u)(t) = \iota(u(t))$ and η, ι are C^∞ (cf. the proof of Lemma 1.2.). For every $g \in C_0^1(I, G)$, we set

$$\hat{A}_g(u) = \hat{\xi}^{-1}(g\hat{\xi}(u)g^{-1}).$$

Then, $\hat{A}_g(u)(t) = \xi^{-1}(g(t)\xi(u(t))g(t)^{-1})$, and hence it is C^∞ on a neighborhood of 0 in $C_0^1(I, \mathfrak{g})$. Thus, $C_0^1(I, \mathfrak{g})$ is an *FL*-group. \square

REMARK. It will be proved in the next paper that if G is a regular Fréchet-Lie group, then $C_0^1(I, G)$ is a regular Fréchet-Lie group.

First we remark that the mapping $\mathcal{S}: C^0(I, \mathfrak{g}) \rightarrow C_0^1(I, G)$ is bijective. In fact, \mathcal{S} is injective by the uniqueness theorem (Lemma 2.5). Also, \mathcal{S} is invertible since the inverse mapping \mathcal{S}^{-1} can be written as

$$(15) \quad \mathcal{S}^{-1}(g)(t) = \frac{dg}{dt} \cdot g(t)^{-1}, \quad g \in C_0^1(I, G).$$

LEMMA 5.3. *Let G be a regular Fréchet-Lie group. Then the mapping $\mathcal{S}: C^0(I, \mathfrak{g}) \rightarrow C_0^1(I, G)$ is continuous.*

PROOF. For every $u \in C^0(I, \mathfrak{g})$, define $\sigma(u)(s, t) = \xi(su(t))$ for small s . Then, $\sigma(u) \in H_{\varepsilon, I}^1(G)$ for a sufficiently small $\varepsilon > 0$. Note that there is a neighborhood W of u such that $\sigma(u') \in H_{\varepsilon, I}^1(G)$ for any $u' \in W$. It is obvious that $\sigma: W \rightarrow H_{\varepsilon, I}^1(G)$ is continuous, and hence by Lemma 3.7, $\mathcal{S}: C^0(I, \mathfrak{g}) \rightarrow C_0^1(I, G)$ is continuous.

Remark that $\mathcal{S}(u)(t)$ is C^1 in t and $(d/dt)\mathcal{S}(u)(t) = u(t) \cdot \mathcal{S}(u(t))$, hence $(d/dt)\mathcal{S}(u)$ depends continuously on u . Thus, $\mathcal{S}: C^0(I, \mathfrak{g}) \rightarrow C_0^1(I, G)$ is continuous. \square

Now, let G be an *FL*-group. Then the tangent bundle T_G is a C^∞ Fréchet manifold modeled on $\mathfrak{g} \oplus \mathfrak{g}$. By Lemma 2.2, T_G can be regarded as an *FL*-group $\mathfrak{g} * G$. Let $C^0(I, T_G)$ be the space of all continuous mappings of I into T_G . By Lemma 1.2, $C^0(I, T_G)$ is a C^∞ Fréchet manifold. Let $\hat{d}: C_0^1(I, G) \rightarrow C^0(I, T_G)$ be a mapping defined by $\hat{d}(g)(t) = (dg/dt)(t) \in T_G$, for $g \in C_0^1(I, G)$. It is not hard to see that \hat{d} is a C^∞ -mapping.

LEMMA 5.4. *Suppose G is a regular Fréchet-Lie group. Then, the mapping $\mathcal{J}^{-1}: C^1_c(I, G) \rightarrow C^0(I, \mathfrak{g})$ is C^∞ .*

PROOF. Let $\pi: T_g \rightarrow G$ be the projection. For every $w \in C^0(I, T_g)$, there is a C^0 mapping $v: I \rightarrow \mathfrak{G}$ such that $w(t) = v(t) \cdot \pi w(t)$. By this manner $C^0(I, T_g)$ is C^∞ -diffeomorphic to $C^0(I, \mathfrak{g} * G)$. We denote this diffeomorphism by ψ . Note that $\mathfrak{g} * G = \mathfrak{g} \times G$ as Fréchet manifolds. Hence $C^0(I, \mathfrak{g} * G) = C^0(I, \mathfrak{g}) \times C^0(I, G)$. Let ν be the projection of $C^0(I, \mathfrak{g}) \times C^0(I, G)$ to the first component. Remark that $\mathcal{J}^{-1}(g)(t) = (dg/dt)(t) \cdot g(t)^{-1}$ and hence $\mathcal{J}^{-1} = \nu \circ \psi \circ \hat{d}$. Since ν, ψ, \hat{d} are C^∞ we get the desired result. \square

Combining Lemma 5.3 and Lemma 5.4, we get

COROLLARY 5.5. *Let G be a regular Fréchet-Lie group. Then the mapping $\mathcal{J}: C^0(I, \mathfrak{g}) \rightarrow C^1_c(I, G)$ is a homeomorphism.*

To prove Theorem 5.1 we must study about the differentiability of \mathcal{J} . Let $g \in C^1_c(I, G)$ and ω an element of the tangent space $T_g C^1_c(I, G)$ of $C^1_c(I, G)$ at g . ω is a C^1 mapping of I into T_g such that $\pi \omega(t) = g(t)$ and $\omega(0) = 0$. Put $v(t) = \omega(t) \cdot g(t)^{-1}$. Then, v is a C^1 mapping of I into \mathfrak{g} such that $v(0) = 0$.

Lemma 5.6. *Notations and assumptions being as above. The derivative $(d\mathcal{J}^{-1})_g \omega, \omega \in T_g C^1_c(I, G)$, is given by*

$$((d\mathcal{J}^{-1})_g \omega)(t) = \frac{d}{dt} v(t) - [u(t), v(t)],$$

where $v(t) = \omega(t) \cdot g(t)^{-1}$ and $u(t)$ is defined by $(dg/dt)(t) = u(t)g(t)$.

PROOF. Let $\xi: U \rightarrow \tilde{U}$ be a local coordinate system of G at e . Then, we see that

$$\begin{aligned} ((d\mathcal{J}^{-1})_g \omega)(t) &= \frac{\partial}{\partial s} \Big|_{s=0} \left(\frac{\partial}{\partial t} \xi(sv(t))g(t) \right) g(t)^{-1} \xi(sv(t))^{-1} \\ &= \frac{\partial}{\partial s} \Big|_{s=0} \left(\frac{\partial}{\partial t} \xi(sv(t))g(t) \right) g(t)^{-1} + \frac{\partial}{\partial s} \Big|_{s=0} u(t) \cdot \xi(sv(t))^{-1} \\ &= \frac{\partial}{\partial s} \Big|_{s=0} (d\xi)_{sv(t)} s \dot{v}(t) + \frac{\partial^2}{\partial s \partial \delta} \Big|_{s=0} \xi(sv(t)) \cdot \xi(\delta u(t)) - \partial_{v(t)} u^*(t) \\ &= \dot{v}(t) + \partial_{u(t)} v^*(t) - \partial_{v(t)} u^*(t) \end{aligned}$$

where $u^*(t), v^*(t)$ are right-invariant vector field on G such that $u^*(t)(g) =$

$u(t) \cdot g, v^*(t)(g) = v(t) \cdot g$ respectively. Remark that $(\partial_{u(t) \cdot g(t)} v^*(t)) \cdot g(t)^{-1} = \partial_{u(t)} v^*(t)$. Hence by (8) in §2 we have the desired equality. \square

Now, we consider the differential equation

$$(16) \quad \frac{d}{dt}v(t) - [u(t), v(t)] = w(t), \quad v(0) = 0,$$

for an arbitrarily given $w \in C^0(I, \mathfrak{g})$. By Lemma 2.6, we see that (16) has the unique solution

$$v(t) = \text{Ad}(g(t)) \int_0^t \text{Ad}(g(s)^{-1})w(s)ds.$$

LEMMA 5.7. *Notations and assumptions being as above, the derivative $(d\mathcal{F}^{-1})_g: T_g C^1(I, G) \rightarrow C^0(I, \mathfrak{g})$ is a continuous linear isomorphism and $(d\mathcal{F}^{-1})^{-1}: C^1(I, G) \times C^0(I, \mathfrak{g}) \rightarrow T_{C^1(I, G)}$ (the tangent bundle) defined by $(d\mathcal{F}^{-1})^{-1}(g, w) = (d\mathcal{F}^{-1})_g^{-1}w$ is continuous with respect to (g, w) .*

PROOF. Using Lemma 5.6 and the uniqueness of the solution (16), we have easily the first statement. Remark that $\text{Ad}(g(t)) \int_0^t \text{Ad}(g(s)^{-1})w(s)ds$ and its derivative in t is continuous with respect to (g, w) . This implies the desired continuity. \square

We globalize Lemma 1.1 and easily obtain the following from Lemma 5.4 and Corollary 5.5.

LEMMA 5.8. *Suppose for a while that $\mathcal{F}: C^0(I, \mathfrak{g}) \rightarrow C^1(I, G)$ is differentiable at every point. Then, \mathcal{F} is C^∞ diffeomorphism.*

By the above lemma, we have only to show the differentiability of \mathcal{F} for the proof of Theorem 5.1.

For a sufficiently small $\varepsilon > 0$, let $\lambda \in H_{\varepsilon, I}^1(\mathfrak{g})$. Then, $h(s, t) = \xi \circ \lambda(s, t) \in H_{\varepsilon, I}^1(G)$. What we shall prove at first is the following:

PROPOSITION 5.9. *Notations being as above, set $h_r(s, t) = h(rs, t)$ ($0 < r < 1$). Then the function $G(r, \lambda)$ defined by*

$$G(r, \lambda)(t) = \begin{cases} \frac{1}{r} \xi^{-1} \circ \prod_0^t (h_r, d\tau) - \int_0^t \frac{\partial \lambda}{\partial s}(0, \tau) d\tau, & r \neq 0 \\ 0, & r = 0, \end{cases}$$

is continuous on a neighborhood of $(0, \lambda) \in \mathbf{R}^+ \times H_{\varepsilon, I}^1(\mathfrak{g})$.

PROOF. Remark at first that $\xi^{-1} \circ \prod_0^t (h_0, d\tau) = 0$. Hence for every fixed λ , there is a neighborhood \hat{W} of λ in $H_{\varepsilon, I}^1(\mathfrak{g})$ such that $\xi \circ \mu \in H_{\varepsilon, I}^1(G)$ for

all $\mu \in \widehat{W}$, and there is $\delta > 0$ such that $\xi^{-1} \circ \prod_0^t (\xi \circ \mu_r, d\tau)$, $\mu_r(s, t) = \mu(rs, t)$ (cf. Corollary 3.8), is well-defined for all $\mu \in \widehat{W}$, $r \in [0, \delta]$ and $t \in I$.

Let $\{\Delta_n\}$ be a sequence of division I such that $\lim_{n \rightarrow \infty} |\Delta_n| = 0$ and $|\Delta_n| < \varepsilon$ for all n . Recall that $\prod_0^t (\xi \circ \mu_r, d\tau) = \lim_{n \rightarrow \infty} \prod_0^t (\sigma_n(\xi \circ \mu_r), \Delta_n)$. By the same computation as in (12) and (13), we have the following, by setting $w_{n,r}(t) = \xi^{-1} \circ \prod_0^t (\sigma_n(\xi \circ \mu_r), \Delta_n)$:

$$\begin{aligned} w_{n,r}(t) &= \mu((t-t_k)r, t_k) + \sum_{i=0}^{k-1} \mu((\Delta t_{i+1})r, t_i) \\ &\quad + \int_0^1 [(d\eta_{w_{n,r}(t_k)})_{s\mu((t-t_k)r, t_k)} - \text{Id}] \mu((t-t_k)r, t_k) ds \\ &\quad + \sum_{i=0}^{k-1} \int_0^1 [(d\eta_{w_{n,r}(t_i)})_{s\mu((\Delta t_{i+1})r, t_i)} - \text{Id}] \mu((\Delta t_{i+1})r, t_i) ds, \end{aligned}$$

where $t \in [t_k, t_{k+1})$, $\Delta t_{i+1} = t_{i+1} - t_i$. Remark that

$$((d\eta_w)_v - \text{Id})u = (d\eta_w)_v u - (d\eta_0)_v u = \int_0^1 (d_2 d_1 \eta)_{(v, \tau w)}(u, w) d\tau.$$

We have the following by setting

$$\begin{aligned} \mu_{r,k} &= \mu((t-t_k)r, t_k), \quad \mu_{r,i} = \mu((\Delta t_{i+1})r, t_i), \\ w_{n,r}(t) &= \int_0^1 \frac{\partial \mu}{\partial s}(sr(t-t_k), t_k) ds \cdot (t-t_k)r \\ &\quad + \sum_{i=0}^{k-1} \int_0^1 \frac{\partial \mu}{\partial s}(sr(\Delta t_{i+1}), t_i) ds \cdot (\Delta t_{i+1})r \\ &\quad + \int_0^1 \int_0^1 (d_2 d_1 \eta)_{(s\mu_{r,k}, \nu w_{n,r}(t_k))}(\mu_{r,k}, w_{n,r}(t_k)) d\nu ds \\ &\quad + \sum_{i=0}^{k-1} \int_0^1 \int_0^1 (d_2 d_1 \eta)_{(s\mu_{r,i}, \nu w_{n,r}(t_i))}(\mu_{r,i}, w_{n,r}(t_i)) d\nu ds. \end{aligned}$$

Thus, putting $w_r(t) = \lim_{n \rightarrow \infty} w_{n,r}(t)$, we have that

$$\frac{1}{r} w_r(t) = \int_0^t \frac{\partial \mu}{\partial s}(0, \tau) d\tau + \int_0^t \int_0^1 (d_2 d_1 \eta)_{(0, \nu w_r(t))} \left(\frac{\partial \mu}{\partial s}(0, \tau), w_r(\tau) \right) d\nu d\tau.$$

Therefore, if $r \neq 0$, then

$$G(r, \mu)(t) = \int_0^t \int_0^1 (d_2 d_1 \eta)_{(0, \nu w_r(\tau))} \left(\frac{\partial \mu}{\partial s}(0, \tau), w_r(\tau) \right) d\nu d\tau.$$

Recall that $w_r(t) = \xi^{-1} \circ \prod_0^t (h_r, d\tau)$, and that $\lim_{r \rightarrow 0} w_r(t) = 0$ by Corollary 3.8. Thus, we get that $G(r, \mu)$ is continuous on a neighborhood of $(0, \lambda)$. □

COROLLARY 5.10. $\mathcal{S}: C^0(I, \mathfrak{g}) \rightarrow C^1(I, G)$ is differentiable at 0.

PROOF. Apply the above result to $\mu(s, t) = su(t)$. Then, we see that

$$G(r, \mu)(t) = \begin{cases} \frac{1}{r} \xi^{-1} \circ \prod_0^t (1 + ru(\tau)) d\tau - \int_0^t u(\tau) d\tau, & r \neq 0, \\ 0, & r = 0, \end{cases}$$

is continuous on a neighborhood of $(0, 0)$ in $\mathbf{R}^+ \times C^0(I, \mathfrak{g})$, where $\mathbf{R}^+ = \{r \geq 0\}$. This implies that \mathcal{S} is differentiable at $u=0$ and $((d\mathcal{S})_0 u)(t) = \int_0^t u(\tau) d\tau$. \square

To prove the differentiability at $u \in C^0(I, \mathfrak{g})$, we set

$$\xi(s(u(t) + v(t))) = \xi(\hat{v}(s, t)) \xi(su(t)),$$

for a sufficiently small s , say $0 \leq s \leq \varepsilon$. Denote

$$\hat{h}(s, t) = \xi \circ \hat{v}(s, t), \quad h(s, t) = \xi(su(t)), \quad \hat{h}h(s, t) = \xi(\hat{v}(s, t)) \xi(su(t)).$$

Let $\{\Delta_n\}$ be a sequence of division of I such that $|\Delta_n| < \varepsilon$ for all n . Then putting $A(g, h) = ghg^{-1}$, we have for $t \in [t_k, t_{k+1})$,

$$\begin{aligned} (17) \quad & \prod_0^t (\sigma_n(\hat{h}h), \Delta_n) \\ &= \hat{h}(t - t_k, t_k) h(t - t_k, t_k) \hat{h}(\Delta t_k, t_{k-1}) h(\Delta t_k, t_{k-1}) \cdots \hat{h}(\Delta t_1, t_0) h(\Delta t_1, t_0) \\ &= \hat{h}(t - t_k, t_k) A \left(\prod_{t_k}^t (\sigma_n(h), \Delta_n), \hat{h}(\Delta t_k, t_{k-1}) \right) \times \cdots \\ & \quad \cdots \times A \left(\prod_{t_i}^t (\sigma_n(h), \Delta_n), \hat{h}(\Delta t_i, t_{i-1}) \right) \times \cdots \\ & \quad \cdots \times A \left(\prod_{t_1}^t (\sigma_n(h), \Delta_n), \hat{h}(\Delta t_1, t_0) \right) \times \prod_0^t (\sigma_n(h), \Delta_n). \end{aligned}$$

Consider a step function \tilde{h}_n by

$$\tilde{h}_n(s, t') = \begin{cases} \hat{h}(s, t_k), & t' \in [t_k, t_{k+1}) \\ A \left(\prod_{t_i}^t (\sigma_n(h), \Delta_n), \hat{h}(s, t_{i-1}) \right), & t' \in [t_{i-1}, t_i), 1 \leq i \leq k \end{cases}$$

defined on $[0, \varepsilon] \times [0, t]$. Then, obviously,

$$\prod_0^t (\sigma_n(\hat{h}h), \Delta_n) = \prod_0^t (\tilde{h}_n, \Delta_n) \prod_0^t (\sigma_n(h), \Delta_n).$$

The following lemma is easy to prove.

LEMMA 5.11. $\{\tilde{h}_n\}$ converges to a C^1 -hair $\tilde{h} \in H_{c,[0,t]}^1(G)$ with respect to $\tilde{\rho}$, where

$$\tilde{h}(s, t) = A\left(\prod_0^t(h, d\tau), \hat{h}(s, t)\right) = A\left(\prod_0^t(h, d\tau), A\left(\prod_0^{t'}(h, d\tau)^{-1}, \hat{h}(s, t')\right)\right)$$

PROOF OF THEOREM 5.1. Suppose s is sufficiently small. Then $\tilde{\mu}(s, t) = \xi^{-1} \circ \tilde{h}(s, t)$ is well-defined, and

$$(18) \quad \begin{aligned} \frac{\partial \tilde{\mu}}{\partial s}(0, t') &= \text{Ad}\left(\prod_0^t(h, d\tau)\right) \text{Ad}\left(\prod_0^{t'}(h, d\tau)^{-1}\right) \frac{\partial \hat{v}}{\partial s}(0, t') \\ &= \text{Ad}(g(t)) \text{Ad}(g(t')^{-1})v(t'), \end{aligned}$$

where $g(t) = \prod_0^t(h, d\tau) = \prod_0^t(1 + u(\tau))d\tau$. Remark that

$$(19) \quad \prod_0^t(1 + u(\tau) + v(\tau))d\tau \left\{ \prod_0^t(1 + u(\tau))d\tau \right\}^{-1} = \prod_0^t(\tilde{h}, d\tau).$$

So, set

$$\tilde{h}_r(s, \tau) = A_{g(t)} A_{g(\tau)^{-1}} \hat{h}(rs, \tau) (= A_{g(t)} A_{g(\tau)^{-1}} \xi(\hat{v}(rs, t))),$$

and define $G(r, v)$ by

$$G(r, v)(t) = \begin{cases} \frac{1}{r} \xi^{-1} \circ \prod_0^t(\tilde{h}_r, d\tau) - \text{Ad}(g(t)) \int_0^t \text{Ad}(g(\tau)^{-1})v(\tau)d\tau, & r \neq 0, \\ 0, & r = 0. \end{cases}$$

By (18) and Proposition 5.9, we see that $G(r, v)$ is continuous on a neighborhood of $(0, 0)$. Using (19) we see that $\mathcal{S}: C^0(I, \mathfrak{g}) \rightarrow C^1(I, G)$ is differentiable at $u \in C^0(I, \mathfrak{g})$ and $((d\mathcal{S})_u v)(t) = \text{Ad}(g(t)) \int_0^t \text{Ad}(g(\tau)^{-1})v(\tau)d\tau$. By Lemma 5.8, we obtain that \mathcal{S} is a C^∞ diffeomorphism. \square

Now, let G be a regular Fréchet-Lie group with the Lie algebra \mathfrak{g} . The following is an immediate conclusion from Theorem 5.1:

COROLLARY 5.12. There is a C^∞ mapping $\exp: \mathfrak{g} \rightarrow G$ such that for each $u \in \mathfrak{g}$ $\{\exp tu\}_{t \in \mathbb{R}}$ is a C^∞ one parameter subgroup of G .

PROOF. For $u \in \mathfrak{g}$, we define $\exp tu$ by $\prod_0^t(1 + u)d\tau$. Then, $g(t) = \exp tu$ satisfies the equation $(dg/dt)(t) = u \cdot g(t)$, $g(0) = e$. Since $\exp tu \cdot \exp su$, $\exp(t+s)u$ satisfy the same differential equation, we see that $\exp tu \cdot \exp su = \exp(t+s)u$ by using Lemma 2.5. Hence $\exp tu$ is a one parameter subgroup of G . As $((d/dt)\exp tu)(\exp -tu) \equiv u$, we see that $\exp tu$ is C^∞ with

respect to t . By the second fundamental theorem, $\exp u$ depends smoothly on u . \square

REMARK. In the next paper, we shall prove that regular Fréchet-Lie group have the properties (L1)~(L3) mentioned in the introduction.

§6. Strong *ILB*-Lie groups are regular Fréchet-Lie groups.

In this section, we shall show that strong *ILB*-Lie groups defined in [8] or [9] are regular Fréchet-Lie groups. By this result, we have a lot of concrete examples of regular Fréchet-Lie groups. Roughly speaking, a strong *ILB*-Lie group is a *Lie* group, which is modeled on a system $\{\mathbf{E}, E^k, k \in N(d)\}$ called an *ILB*-chain instead of a single vector space.

DEFINITION 6.1. A system $\{\mathbf{E}, E^k, k \in N(d)\}$ is called an *ILB*-chain if the following are satisfied:

- (i) $N(d)$ is the set of integers such that $k \geq d$.
- (ii) E^k is a Banach space such that $E^{k+1} \subset E^k$. The inclusion is continuous and has a dense image.
- (iii) $\mathbf{E} = \bigcap E^k$ with the inverse limit topology.

If all E^k 's are Hilbert spaces, then we call $\{\mathbf{E}, E^k, k \in N(d)\}$ an *ILH*-chain.

DEFINITION 6.2. A group G will be called a *strong ILB-Lie group* modeled on an *ILB*-chain $\{\mathbf{E}, E^k, k \in N(d)\}$, if the following conditions (N, 1)~(N, 7) are satisfied:

(N, 1) There are an open convex neighborhood U of 0 in E^d and a bijective mapping ξ of $U \cap \mathbf{E}$ onto a subset \tilde{U} of G such that $\xi(0) = e$.

(N, 2) There is an open convex neighborhood V of 0 in E^d such that

$$\xi(V \cap \mathbf{E})^2 \subset \xi(U \cap \mathbf{E}), \quad \xi(V \cap \mathbf{E})^{-1} \subset \xi(U \cap \mathbf{E}).$$

(N, 3) Set $\eta(u, v) = \xi^{-1}(\xi(u)\xi(v))$ for $u, v \in V \cap \mathbf{E}$. Then $\eta: V \cap \mathbf{E} \times V \cap \mathbf{E} \rightarrow U \cap \mathbf{E}$ can be extended to a continuous mapping of $V \cap E^k \times V \cap E^k$ into $U \cap E^k$ for every $k \in N(d)$. (The extended mapping will be denoted by the same notation.)

(N, 4) Set $\eta_v(u) = \eta(u, v)$ for $v \in V \cap E^k$. Then $\eta_v: V \cap E^k \rightarrow U \cap E^k$ is a C^∞ mapping.

(N, 5) Set $\theta(w, u, v) = (d\eta_v)_* w$. For every integer $l \geq 0$, $k \in N(d)$, θ can be extended to a C^l -mapping of $E^{k+l} \times (V \cap E^{k+l}) \times (V \cap E^k)$ into E^k .

(N, 6) Define $\iota: V \cap \mathbf{E} \rightarrow U \cap \mathbf{E}$ by $\iota(u) = \xi^{-1}(\xi(u)^{-1})$. Then ι can be extended to a continuous mapping of $V \cap E^k$ into $U \cap E^k$ for every $k \in N(d)$.

(N, 7) For every $g \in G$, there is a neighborhood W of 0 in E^d such

that $g^{-1}\xi(W \cap E)g \subset \xi(U \cap E)$, and the mapping $u \rightarrow \xi^{-1}(g^{-1}\xi(u)g)$ can be extended to a C^∞ mapping of $W \cap E^k$ into $U \cap E^k$ for every $k \in N(d)$.

REMARK 1. The above conditions are little weaker than those in [8] in the statement. However, it is not hard to see that those are in fact the same conditions. (See [9], pp. 52-59.)

REMARK 2. If the model space $\{E, E^k, k \in N(d)\}$ is an *ILH-chain*, we call G a *strong ILH-Lie group*. If $E = \dots = E^k = \dots = E^d$, and E^d is a Banach (resp. Hilbert) space, then G will be called a Banach (resp. Hilbert) Lie group. Of course, if $\dim E^d < \infty$, then G is a usual Lie group.

Now, we summarize several properties of strong *ILB-Lie groups* which will be used later.

LEMMA 6.3. Let \mathfrak{N}^k be a basis of neighborhoods of 0 in E^k such that $W \subset V \cap E^k$ for every $W \in \mathfrak{N}^k$. Then $\{\xi(W \cap E); W \in \mathfrak{N}^k\}$ satisfies the axioms of neighborhoods of the identity e of a topological group. Hence G turns out to be a topological group under this topology, which will be denoted by (G, \mathfrak{N}^k) . (See [9] 1.2 Proposition, or [8] 1.2.4 Lemma.)

Let G^k be the completion of (G, \mathfrak{N}^k) by the right-uniform structure. In general, G^k is only a topological semi-group. However, in our case the property (N, 6) ensures that G^k is a topological group.

THEOREM 6.4. Notations being as above, $\{G^k, k \in N(d)\}$ has the following properties:

- (G, 1) Each G^k is a C^∞ Banach manifold modeled on E^k .
- (G, 2) $G^{k+1} \subset G^k$. The inclusion map is a C^∞ homomorphism having a dense image.
- (G, 3) $G = \bigcap G^k$. (Thus, G is a topological group under the inverse limit topology.)
- (G, 4) The product $G \times G \rightarrow G, (g, h) \rightarrow g \cdot h$, can be extended to a C^l -mapping of $G^{k+l} \times G^k$ into G^k for any $l \geq 0, k \in N(d)$.
- (G, 5) The inversion $G \rightarrow G, g \rightarrow g^{-1}$, can be extended to a C^l -mapping of G^{k+l} into G^k for any $l \geq 0, k \in N(d)$.
- (G, 6) For any $g \in G^k$, the right-translation $R_g: G^k \rightarrow G^k$ is C^∞ .
- (G, 7) Define $dR(u, g) = dR_g u$. Then $dR: T_{G^{k+l}} \times G^k \rightarrow T_{G^k}$ is a C^l -mapping for every $l \geq 0, k \in N(d)$.
- (G, 8) $\xi: V \cap E \rightarrow G$ can be extended to a C^∞ diffeomorphism of $V \cap E^k$ onto a neighborhood $\tilde{V} \cap G^k$ of e in G^k , where $\tilde{V} = \xi(V \cap E^d)$.

REMARK. We call a system $\{G, G^k, k \in N(d)\}$ of topological groups an *ILB-Lie group*, if it satisfies above (G, 1)~(G, 7). It is not hard to see

that if an *ILB*-Lie group $\{G, G^k, k \in N(d)\}$ satisfies (G, 8), then G is a strong *ILB*-group.

By the above definition and the above theorem, we see that every strong *ILB*-Lie group is an *FL*-group.

Suppose we have a strong *ILB*-Lie group G modeled on an *ILB*-chain $\{E, E^k, k \in N(d)\}$. Notations being as in Theorem 6.4, let \mathfrak{g}^k be the tangent space of G^k at the identity e , and let $\mathfrak{g} = \bigcap \mathfrak{g}^k \cdot \mathfrak{g}$ can be naturally identified with the model space E . Note that

$$\eta: V \cap E^k \times V \cap E^{k-1} \longrightarrow U \cap E^{k-1}$$

is a C^1 mapping by virtue of (G, 4) in Theorem 6.4. Set $\eta'_u(v) = \eta(u, v)$. Then $(d\eta'_u)_v: E^{k-1} \rightarrow E^{k-1}$ is a bounded linear mapping, which is continuous with respect to u, v such that $u \in V \cap E^k, v \in V \cap E^{k-1}$.

LEMMA 6.5. For an arbitrarily fixed $k \in N(d)$, there are a δ -neighborhood W^k of 0 in \mathfrak{g}^k ($0 < \delta < 1$), and a constant C_k satisfying the following:

- (a) $\bar{W}^k \subset V \cap E^k$.
- (b) $\|(d\eta'_u)_v w\|_{k-1} \leq C_k \|w\|_{k-1}$ for every $u, v \in W^k$.
- (c) $\|\theta(w, u, v)\|_{k-j} \leq C_k \|w\|_{k-j}$ ($j=0, 1$) for every $u, v \in W^k, w \in \mathfrak{g}^{k-1}$.
- (d) $\|(d_3\theta)_{(w,u,v)}(v')\|_{k-1} \leq C_k \|v'\|_{k-1} \|w\|_k$ for every $u, v \in W^k, v' \in \mathfrak{g}^{k-1}$ and $w \in \mathfrak{g}^k$, where $d_3\theta$ is the partial derivative with respect to the third variable.

PROOF. Note that $(d\eta'_0)_0 = 0, \theta(0, 0, 0) = 0$, (a)~(c) follow immediately by the continuity of $d\eta'_u$ and θ . Remark that

$$\theta: \mathfrak{g}^k \times V \cap \mathfrak{g}^k \times V \cap \mathfrak{g}^{k-1} \longrightarrow \mathfrak{g}^{k-1}$$

is C^1 (cf. (N, 5) in Definition 6.2). Hence $d_3\theta$ makes sense, and $(d_3\theta)_{(w,u,v)}(v')$ defines a continuous bilinear mapping of $\mathfrak{g}^k \times \mathfrak{g}^{k-1}$ into \mathfrak{g}^{k-1} for every fixed u, v . Note that $(d_3\theta)_{(0,0,0)}(0) = 0$. Then (d) follows from the continuity of $d_3\theta$. \square

Let $\{(h_n, \Delta_n)\}$ be a sequence of step functions in G defined on $[0, \varepsilon] \times J, J = [a, b]$, such that $\lim_{n \rightarrow \infty} |\Delta_n| = 0$, and $\{h_n\}$ converges to a C^1 -hair $h \in H_{\varepsilon, J}^1(G)$ with respect to $\tilde{\rho}$ (cf. (6)). For an arbitrarily fixed $k \in N(d)$, we choose W^k as in Lemma 6.5. Since $h(0, t) \equiv e$, we see that if s is sufficiently close to 0, say $s \leq \varepsilon'$, then $h(s, t) \in \xi(W^k \cap \mathfrak{g})$ for every $t \in J$. Thus, one may assume without loss of generality that $\varepsilon' = \varepsilon$. Moreover, as $\{h_n\}$ converges uniformly to h , one may assume that $h_n(s, t) \in \xi(W^k \cap \mathfrak{g})$ for all n and $(s, t) \in [0, \varepsilon] \times J$.

Now, we set $\lambda_n(s, t) = \xi^{-1} \circ h_n(s, t), \lambda(s, t) = \xi^{-1} \circ h(s, t)$. Obviously, $\{\lambda_n\}$ converges uniformly to λ with their partial derivatives $\{\partial \lambda_n / \partial s\}$.

LEMMA 6.6. *Notations and assumptions being as above there is a constant K_k such that $\|\lambda_n(s, t)\|_k \leq K_k s$ for all n and $(s, t) \in [0, \varepsilon] \times J$.*

PROOF. Note that $\lambda_n(s, t) = \int_0^s (\partial\lambda_n/\partial s)(\sigma, t) d\sigma$. Since $\{\partial\lambda_n/\partial s\}$ converges uniformly to $\partial\lambda/\partial s$, there is K_k such that $\|(\partial\lambda_n/\partial s)(s, t)\|_k \leq K_k$ for all n , and $(s, t) \in [0, \varepsilon] \times J$. Thus, using $0 < \varepsilon < 1$, we get the desired one. □

LEMMA 6.7. *Notations and assumptions being as above, if $t - a < \delta/C_k K_k$, then $\prod_a^t(h_n, \Delta_n) \in \xi(W^k \cap g)$ for a sufficiently large n . More precisely,*

$$\left\| \xi^{-1} \circ \prod_a^t(h_n, \Delta_n) \right\|_k \leq C_k K_k (t - a).$$

PROOF. Let $\Delta_n = \{t_0, t_1, \dots, t_{m_n}\}$, and let l be the integer such that $t \in [t_l, t_{l+1}]$. Note that one may assume $C_k \geq 1$ without loss of generality. If $t \in (t_0, t_1]$, then $\xi^{-1} \circ \prod_a^t(h_n, \Delta_n) = \lambda_n(t - t_0, t_0)$, and hence $\|\xi^{-1} \circ \prod_a^t(h_n, \Delta_n)\|_k \leq C_k K_k (t - a)$ by the above lemma. Suppose that desired inequality holds for $t \in (t_0, t_l]$ and suppose $t \in (t_l, t_{l+1}]$. Then

$$\xi^{-1} \circ \left(\prod_a^t(h_n, \Delta_n) \right) = \eta \left(\lambda_n(t - t_l, t_l), \xi^{-1} \circ \prod_a^{t_l}(h_n, \Delta_n) \right).$$

We get therefore

$$\begin{aligned} \left\| \xi^{-1} \circ \prod_a^t(h_n, \Delta_n) \right\|_k &\leq \int_0^1 \left\| \theta \left(\lambda_n(t - t_l, t_l), \sigma \lambda_n(t - t_l, t_l), \xi^{-1} \circ \prod_a^{t_l}(h_n, \Delta_n) \right) \right\|_k d\sigma \\ &\quad + C_k K_k (t_l - a). \end{aligned}$$

Apply inequality (c) in Lemma 6.5, and use Lemma 6.6. Then,

$$\begin{aligned} \left\| \xi^{-1} \circ \prod_a^t(h_n, \Delta_n) \right\|_k &\leq C_k \|\lambda_n(t - t_l, t_l)\|_k + C_k K_k (t_l - a) \\ &\leq C_k K_k (t - a) < \delta. \end{aligned} \quad \square$$

LEMMA 6.8. *Notations being as above, let Δ'_n be a subdivision of Δ_n . Then $(h_n, \Delta'_n) \in \mathcal{S}_{i,j}(G)$ and*

$$\lim_{n \rightarrow \infty} \left\| \xi^{-1} \circ \prod_a^t(h_n, \Delta_n) - \xi^{-1} \circ \prod_a^t(h_n, \Delta'_n) \right\|_{k-1} = 0$$

uniformly on the interval $a \leq t \leq a + \delta/(C_k K_k)$.

PROOF. Let $\Delta_n = \{t_0, t_1, \dots, t_{m_n}\}$, and let l be the integer such that $t \in [t_l, t_{l+1}]$. By the same proof as in Lemma 6.7, we see that $\omega_n(i) =$

$\xi^{-1} \circ \prod_a^{t_{i+1}}(h_n, A'_n)$, $\omega_n(l) = \xi^{-1} \circ \prod_a^{t_l}(h_n, A'_n)$ are well-defined, and $\prod_a^t(h_n, A'_n) = \xi(\omega_n(l))\xi(\omega_n(l-1)) \cdots \xi(\omega_n(0))$ is contained in $\xi(W^k \cap g)$ for every t such that $t-a \leq \delta/C_k K_k$. We set

$$\alpha_n(i) = \xi^{-1} \circ \prod_a^{t_i}(h_n, A'_n), \quad \beta_n(i) = \xi^{-1} \circ \prod_a^{t_i}(h_n, A'_n).$$

Then using the telescope equality

$$a_1 a_2 \cdots a_m - b_1 b_2 \cdots b_m = \sum_{j=1}^m b_1 \cdots b_{j-1} (a_j - b_j) a_{j+1} \cdots a_m,$$

we obtain that

$$\begin{aligned} & \xi^{-1} \circ \prod_a^t(h_n, A'_n) - \xi^{-1} \circ \prod_a^{t'}(h_n, A'_n) \\ &= \sum_{j=0}^t [\eta(\beta_n(j+1), \eta(\lambda_n(t_{j+1}-t_j, t_j), \alpha_n(j))) - \eta(\beta_n(j+1), \eta(\omega_n(j), \alpha_n(j)))] \end{aligned}$$

where we use the convention $t = t_{i+1}$. Since $\beta_n(j), \alpha_n(j) \in W^k$ by Lemma 6.7, we can apply the following inequality

$$\begin{aligned} & \|\eta(\beta, \eta(v_1, \alpha)) - \eta(\beta, \eta(v_2, \alpha))\|_{k-1} = \|\eta'_\beta(\eta(v_1, \alpha)) - \eta'_\beta(\eta(v_2, \alpha))\|_{k-1} \\ & \leq C_k \|\eta(v_1, \alpha) - \eta(v_2, \alpha)\|_{k-1} \leq C_k^2 \|v_1 - v_2\|_{k-1}. \end{aligned}$$

Therefore, we have

$$\left\| \xi^{-1} \circ \prod_a^t(h_n, A'_n) - \xi^{-1} \circ \prod_a^{t'}(h_n, A'_n) \right\|_{k-1} \leq C_k^2 \sum_{j=0}^t \|\lambda_n(t_{j+1}-t_j, t_j) - \omega_n(j)\|_{k-1}.$$

Set $\lambda_{n,j}(s) = \lambda_n(s, t_j)$, and let $t_j = \tau_0 < \tau_1 < \cdots < \tau_p = t_{j+1}$ be the points in A'_n contained in $[t_j, t_{j+1}]$. Then,

$$\begin{aligned} \omega_n(j) &= \eta(\lambda_{n,j}(\tau_p - \tau_{p-1}), \xi^{-1} \circ \prod_{\tau_0}^{\tau_{p-1}}(h_n, A'_n)) \\ &= \int_0^1 \theta(\lambda_{n,j}(\tau_p - \tau_{p-1}), \sigma \lambda_{n,j}(\tau_p - \tau_{p-1}), \xi^{-1} \circ \prod_{\tau_0}^{\tau_{p-1}}(h_n, A'_n)) d\sigma + \xi^{-1} \circ \prod_{\tau_0}^{\tau_{p-1}}(h_n, A'_n) \\ &= \sum_{i=0}^{p-1} \int_0^1 \theta(\lambda_{n,j}(\tau_{i+1} - \tau_i), \sigma \lambda_{n,j}(\tau_{i+1} - \tau_i), \xi^{-1} \circ \prod_{\tau_0}^{\tau_i}(h_n, A'_n)) d\sigma \\ &= \sum_{i=0}^{p-1} \int_0^1 \int_0^1 \theta(v_n(s, t_j), \sigma \lambda_{n,j}(\tau_{i+1} - \tau_i), \xi^{-1} \circ \prod_{\tau_0}^{\tau_i}(h_n, A'_n)) ds d\sigma, \end{aligned}$$

where $v_n(s, t_j) = (\partial \lambda_n / \partial s)(s, t_j)$. Thus, we get

$$\begin{aligned} &\lambda_n(t_{j+1}-t_j, t_j) - \omega_n(j) \\ &= \sum_{i=0}^{p-1} \int_0^1 \int_0^{\tau_{i+1}-\tau_i} \left[v_n(s+\tau'_i, t_j) - \theta(v_n(s, t_j), \sigma u_{n,j}(\tau_{i+1}-\tau_i), \xi^{-1} \circ \prod_{\tau_0}^{\tau_i}(h_n, A'_n)) \right] ds d\sigma, \end{aligned}$$

where $\tau'_i = \tau_i - t_j$. Note that

$$\theta(v, u, \alpha) = v + \int_0^1 (d_s \theta)_{(v, u, \lambda \alpha)} \alpha d\lambda.$$

Using this, we have

$$\begin{aligned} &\lambda_n(t_{j+1}-t_j, t_j) - \omega_n(j) \\ &= \sum_{i=1}^{p-1} \int_0^{\tau_{i+1}-\tau_i} [v_n(s+\tau'_i, t_j) - v_n(s, t_j)] ds \\ &\quad + \sum_{i=0}^{p-1} \int_0^1 \int_0^{\tau_{i+1}-\tau_i} \int_0^1 (d_s \theta)_{(*)} \xi^{-1} \circ \prod_{\tau_0}^{\tau_i}(h_n, A'_n) d\lambda ds d\sigma, \end{aligned}$$

where $(*) = (v_n(s, t_j), \sigma u_{n,j}(\tau_{i+1}-\tau_i), \lambda \xi^{-1} \circ \prod_{\tau_0}^{\tau_i}(h_n, A'_n))$. Remark that $\lambda \xi^{-1} \circ \prod_{\tau_0}^{\tau_i}(h_n, A'_n) \in W^k \cap \mathfrak{g}$ for every $\lambda \in [0, 1]$. Thus, applying inequality (d) in Lemma 6.5, we obtain

$$\begin{aligned} &\left\| \xi^{-1} \circ \prod_a^t(h_n, A_n) - \xi^{-1} \circ \prod_a^t(h_n, A'_n) \right\|_{k-1} \\ &\leq C_k^2 \sum_{j=0}^l \left[\sum_{i=0}^{p-1} \int_0^{\tau_{i+1}-\tau_i} \|v_n(s+\tau'_i, t_j) - v_n(s, t_j)\|_{k-1} ds \right. \\ &\quad \left. + \sum_{i=0}^{p-1} \int_0^1 \int_0^{\tau_{i+1}-\tau_i} \int_0^1 C_k \left\| \xi^{-1} \circ \prod_{\tau_0}^{\tau_i}(h_n, A'_n) \right\|_{k-1} \|v_n(s, t_j)\|_k d\lambda ds d\sigma \right]. \end{aligned}$$

Note that $\|v_n(s, t_j)\|_k \leq K_k$, and note that there is a constant C'_k such that $\|z\|_{k-1} \leq C'_k \|z\|_k$ for every $z \in \mathfrak{g}^k$. Hence, using Lemma 6.7, we get that the above quantity is not larger than

$$\begin{aligned} &C_k^2 \sum_{j=0}^l \sum_{i=0}^{p-1} \int_0^{\tau_{i+1}-\tau_i} \|v_n(s+\tau'_i, t_j) - v_n(s, t_j)\|_{k-1} ds \\ &\quad + C_k^2 \sum_{j=0}^l \sum_{i=0}^{p-1} (K_k C_k)^2 C'_k (\tau_{i+1} - \tau_i) |A_n|. \end{aligned}$$

Remark $\{v_n\}$ is equi-continuous on $[0, \varepsilon] \times J$, that is, for every $\delta_1 > 0$, there is $\delta_2 > 0$ such that if $|s-s'| + |t-t'| < \delta_2$, then $\|v_n(s, t) - v_n(s', t')\|_{k-1} < \delta_1$. For sufficiently large n , we have $|A_n| < \delta_2$ and hence $\tau'_i < \delta_2$. Therefore

$$\|v_n(s+\tau'_i, t_j) - v_n(s, t_j)\|_{k-1} < \delta_1$$

and hence for a sufficiently large n

$$\begin{aligned} & \left\| \xi^{-1} \circ \prod_a^t(h_n, \Delta_n) - \xi^{-1} \circ \prod_a^t(h_n, \Delta'_n) \right\|_{k-1} \\ & \leq C_k^2(t-a)\delta_1 + K_k^2 C_k^4 C'_k(t-a) |\Delta_n|. \end{aligned}$$

Thus, we get the desired result. □

THEOREM 6.9. *Every strong ILB-Lie group is a regular Fréchet-Lie group.*

PROOF. Notations and assumptions being as above, we shall show at first that $\{\prod_a^t(h_n, \Delta_n)\}$ converges in G^{k-1} uniformly on $[a, a + (\delta/C_k K_k)]$. To prove this, we have only to show that $\{\xi^{-1} \circ \prod_a^t(h_n, \Delta_n)\}$ is a uniform Cauchy sequence in W^k for $t, a \leq t \leq a + (\delta/C_k K_k)$. Thus, we consider $\|\xi^{-1} \circ \prod_a^t(h_n, \Delta_n) - \xi^{-1} \circ \prod_a^t(h_m, \Delta_m)\|_{k-1}$. Assume $n \geq m$ and let Δ'_m be a common subdivision of Δ_n, Δ_m . By the above lemma we have only to show that

$$\lim_{m \rightarrow \infty} \left\| \xi^{-1} \circ \prod_a^t(h_n, \Delta'_m) - \xi^{-1} \circ \prod_a^t(h_m, \Delta'_m) \right\|_{k-1} = 0$$

uniformly in t . Let $\Delta'_m = \{t_0, t_1, t_2, \dots, t_{n_m}\}$, and set

$$\alpha_n(i) = \xi^{-1} \circ \prod_a^{t_i}(h_n, \Delta'_m), \quad \beta_m(i) = \prod_{t_i}^t(h_m, \Delta'_m) \quad (\in W^k \cap \mathfrak{g}).$$

Using telescope equality

$$\begin{aligned} & \left\| \xi^{-1} \circ \prod_a^t(h_n, \Delta'_m) - \xi^{-1} \circ \prod_a^t(h_m, \Delta'_m) \right\|_{k-1} \\ & \leq \sum_{j=0}^l \left\| \eta(\beta_m(j+1), \eta(\lambda_n(t_{j+1}-t_j, t_j), \alpha_n(j))) \right. \\ & \quad \left. - \eta(\beta_m(j+1), \eta(\lambda_m(t_{j+1}-t_j, t_j), \alpha_n(j))) \right\|_{k-1} \\ & \leq C_k^2 \sum_{j=0}^l \left\| \lambda_n(t_{j+1}-t_j, t_j) - \lambda_m(t_{j+1}-t_j, t_j) \right\|_{k-1} \\ & \leq C_k^2 \sum_{j=0}^l \int_0^{t_{j+1}-t_j} \|v_n(s, t_j) - v_m(s, t_j)\|_{k-1} ds, \end{aligned}$$

where $v_n = \partial \lambda_n / \partial s, v_m = \partial \lambda_m / \partial s$. Since $\{v_n\}$ converges uniformly, for every $\delta_1 > 0$, there is n_0 such that if $n \geq m \geq n_0$ then $\|v_n(s, t) - v_m(s, t)\|_{k-1} < \delta_1$. Therefore, if $n \geq m \geq n_0$ then the above quantity is less than

$$C_k^2 \sum_{j=0}^l (t_{j+1} - t_j) \delta_1 = C_k^2 (t - a) \delta_1.$$

Thus, we have that $\{\xi^{-1} \circ \prod_a^t(h_n, \Delta_n)\}$ converges in \mathfrak{g}^{k-1} uniformly on $[a, a + \delta/C_k K_k]$. It follows immediately that $\{\prod_a^t(h_n, \Delta_n)\}$ converges uni-

formly in G^{k-1} on the same interval.

Remark that C_k, K_k depends only on W^k and $h \in H_{\varepsilon, J}^1(G)$. Hence the above argument shows also that if $a' \in J$, then $\{\prod_a^t(h_n, \Delta_n)\}$ converges uniformly in G^{k-1} on the interval $[a', a' + \delta/C_k K_k]$. Hence by using $\prod_a^t(h_n, \Delta_n) = \prod_b^t(h_n, \Delta_n) \cdot \prod_a^b(h_n, \Delta_n)$, we see that $\{\prod_a^t(h_n, \Delta_n)\}$ converges in G^{k-1} uniformly on the interval $J = [a, b]$. As k is arbitrary, the above result shows that $\{\prod_a^t(h_n, \Delta_n)\}$ converges in G uniformly on J . This completes the proof of Theorem 6.9. \square

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