# On Repeated Games with General Information Function ${ }^{1}$ ) 

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#### Abstract

For a class of repeated two-person zero-sum games with incomplete information it was proved by Aumann and Mascheer that $\lim v_{n}$ exists, $v_{n}$ being the value of the game with $n$ repetitions. If the players know at each stage the moves done by both players at all previous stages, Aumann and Maschler could prove that the error term $\delta_{n}=\left|v_{n}-\lim v_{n}\right|$ satisfies $\delta_{n} \leq c / \sqrt{n}$ for some $c>0$. It was then shown by Zamir that this bound is the lowest possible. In this paper it is shown that if previous moves are not always announced, $\delta_{n}$ may be of higher order of magnitude e.g. $\delta_{n} \geq c / n^{1 / 3}$ for some $c>0$. New upper bounds for $\delta_{n}$ are given for two classes of games.


## 1. Introduction

The class of games considered in this paper are those discussed by Aumann and Maschler [1968]. They can be described as follows:

Let $A^{1}, \ldots, A^{k} ;(k \geq 2)$ be $l \times m$ matrices of real numbers viewed as two-person zero-sum games. Let $H^{1}, \ldots, H^{k}$, be $l \times m$ matrices whose elements are symbols (e.g. letters, digits, pairs of digits, etc.). The matrices $\left\{A^{v} \mid v=1, \ldots, k\right\}$ will be called the payoff matrices and their elements will be denoted by $a_{i j}^{v} ; i=1, \ldots, l$; $j=1, \ldots, m ; v=1, \ldots, k$. The matrices $\left\{H^{v} \mid v=1, \ldots, k\right\}$ will be called the information matrices and their elements will be denoted by $h_{i j}^{v}$. For each $p$ in the simplex $P=\left\{p=\left(p^{1}, \ldots, p^{k}\right) \mid p^{v} \geq 0, v=1, \ldots, k, \sum_{1}^{k} p^{v}=1\right\}$ and for each positive integer $n$, consider the game $\Gamma_{n}(p)$ played as follows: Chance chooses one of the $k$ games $\left\{A^{v}\right\}$ assigning to $A^{v}$ the probability $p^{v}$. Player I is then informed of chance's choice but player II is not. The game chosen by chance is then played $n$ times. If at a certain stage the player played pure strategies $i$ and $j$ respectively, then player I is credited and player II is debited by $a_{i j}^{v}$ and in addition $h_{i j}^{v}$ is announced by the referee, where $v$ is the index of the game chosen by chance. Neither the payoffs nor the moves are told explicitly. The only way for the players to learn something about the moves or the payoffs is through the information $h_{i j}^{v}$ announced after each play (Player I however has the big advantage of knowing $v$ ). The payoff in $\Gamma_{n}(p)$ is defined to be the sum of the payoffs of the $n$ individual plays of the game chosen by chance, divided by $n$. Both players of course know the rules of $\Gamma_{n}(p)$ described above. We shall describe the specifications of such a game schematically by:

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The main feature of the game $\Gamma_{n}(p)$ is the following: Player II would like to learn as much as possible concerning which game was chosen by chance since the more he knows about it the higher his profits will usually be (certainly not less). However, the procedure of learning may be costly for him, therefore he will balance learning against profits at each stage of the game.

For the purpose of computing the value of our games we will make use of the minimax theorem which we will read roughly as: "The value of the game is the best that player II (or I) can guarantee if his opponent has to announce his mixed strategy in advance". In other words we will assume that player II knows player I's strategy and suggests a 'best reply' for it. Then we will maximize over all player I's strategies and obtain the value. Now since player I knows the choice of chance $v$, his move at each stage may depend on $v$. The strategy of player I together with player II's move, $j$, induce a probability distribution on the elements $h_{i j}^{v} ; v=1, \ldots, k$; $i=1, \ldots, l$. Hence given the announced information player II will compute a new conditional distribution on the choice of chance $v$. Realizing this mechanism of player II to gain knowledge about the choice of chance, the essential notion for classifying strategies of player I becomes that of a non-separating strategy defined as follows:

## Definition 1:

A mixed strategy $\sigma$ of player I in $\Gamma_{1}(p)$ will be called non-separating if for any $j(1 \leq j \leq m)$ the probability distribution induced by $\sigma, j$ and $v$ on the elements of $H^{v}$ is the same for all $v$ with $p^{v}>0$ (considered as distributions on $H=$ $\left\{h_{i j}^{v} \mid 1 \leq i \leq l, 1 \leq j \leq m, 1 \leq v \leq k\right\}$.
In other words if at a certain stage player I uses a non-separating strategy then whatever player II does, his conditional probability about the choice of chance after that stage is the same as it was before. This means that player II can gain no knowledge about the choice of chance in a stage in which player I uses a non-separating strategy.

Denote by $N S(p)$ the set of non-separating strategies in $\Gamma_{1}(p)$ and by $\Delta(p)$ the one stage game $\Gamma_{1}(p)$ in which the strategy space of player $I$ is restricted to $N S(p)$. Note that it is possible that for some $p \in P, N S(p)$ is the empty set $\emptyset$ in which case $\Delta(p)$ is not defined. However at least when $p$ is an extreme point of $P$ we have $N S(p) \neq \emptyset$. In fact if $p$ is the $v$ th unit vector $(0, \ldots, 1, \ldots, 0)$ then $\Delta(p)$ is the ordinary two-person zero-sum game $A^{v}$.

Let $v_{n}(p)$ denote the $(\operatorname{minimax})$ value of $\Gamma_{n}(p)$ and let $u(p)$ denote the value of $\Delta(p)(u(p)$ is defined whenever $N S(p) \neq \emptyset)$. Denote by $u^{*}(p)$ the concavification of $u(p)$ i.e. the smallest concave function on $P$ satisfying $u^{*}(p) \geq u(p)$ whenever $u(p)$ is defined.

Theorem 1 (Aumann-Maschler [1968]):

$$
\lim _{n \rightarrow \infty} v_{n}(p)=u^{*}(p) \text { for all } p \in P
$$

The special case in which $h_{i j}^{v}=(i, j)$ will be referred to as the case of standard information. In such games the information announced after each stage is just the moves ( $i, j$ ) done by the players at that stage. For standard information Aumann and Maschler [1966] proved a stronger version of Theorem 1, namely:

## Theorem $1_{s}$ :

In the case of standard information

$$
v_{n}(p)=u^{*}(p)+\delta_{n}(p) \text { for } p \in P ; n=1,2, \ldots
$$

where $\delta_{n}(p) \leq c / \sqrt{n}$ for some $c>0$.
The error term $\delta_{n}(p)$ which measures the speed of convergence of $v_{n}(p)$ is the subject of our paper. In an earlier paper on this subject [Zamir, 1971/72] we proved among other things that in the standard information case $c / \sqrt{n}$ is the best bound possible. There are games for which $\delta_{n} \geq c^{\prime} / \sqrt{n}$ for $c^{\prime}>0$. As for the general case, nothing is said about the error term in Theorem 1. The main question is of course: Does $\delta_{n} \leq c / \sqrt{n}$ still hold for the non-standard information case? The answer is no: In Section 1 we describe a game in which $c^{\prime} / n^{1 / 3} \leq \delta_{n} \leq c / n^{1 / 3} ;\left(c>0, c^{\prime}>0\right)$. The next natural question is: What is an upper bound for $\delta_{n}$ in the non-standard information case? This question is answered only for the case $k=2$ (only two possible choices of chance). In Section 3 we shall prove at this case $\delta_{n} \leq c / n^{1 / 6}$. If, in addition, we have $N S(p)=\emptyset$ for $0<p<1$, a stronger bound is valid, namely $\delta_{n} \leq c / n^{1 / 4}$.

It will be convenient to use in this paper the following terminology:

## Definition 2 :

Two sequences of non-negative numbers $\left\{a_{n}\right\}$ and $\left\{b_{n}\right\}$ is said to be of the same order of magnitude if there are constants $c_{1}>0$ and $c_{2}>0$ s.t. $c_{2} b_{n} \leq a_{n} \leq c_{1} b_{n}$; $n=1,2, \ldots$. This will be denoted by $a_{n}=0^{*}\left(b_{n}\right)\left(\right.$ or $b_{n}=0^{*}\left(a_{n}\right)$ ).

## 2. A Game with $\delta_{\boldsymbol{n}}=0^{*}\left(1 / n^{1 / 3}\right)$

Consider the game:

where: $\begin{array}{rll}A^{1}=\left(\begin{array}{rrr}\alpha & \beta & \gamma \\ 8 & 3 & -1 \\ 8 & -3 & 1\end{array}\right) & H^{1}=\left(\begin{array}{lll}a & c & d \\ b & c & d\end{array}\right) \\ A^{2}=\left(\begin{array}{rrr}8 & 2 & -2 \\ 8 & -2 & 2\end{array}\right) & H^{2}=\left(\begin{array}{lll}a & c & d \\ b & c & d\end{array}\right)\end{array}$
(We use the notation $x^{\prime}$ for $1-x$ for any $0 \leq x \leq 1$.) Denoting the pure strategies of player II by $\alpha, \beta, \gamma$, we observe that deleting the strategy $\alpha$ and changing $H^{v}$ to standard information matrices we obtain the game with $\delta_{n}=0^{*}(1 / \sqrt{n})$ analyzed in our previous paper. The main feature of our present game is that player II does not collect any information about the choice of chance as long as he restricts himself to the strategies $\beta$ and $\gamma$. The only way for him to gain some information is to use his dominated strategy $\alpha$. In other words player II "has to buy the information", whenever he wants to know player I's move he has to pay 8 units. This will cause the enlargement of the order of magnitude of $\delta_{n}$ from $1 / n^{1 / 2}$ to $1 / n^{1 / 3}$.

A general strategy of player I in $\Gamma_{1}(p)$ is $\sigma=\left[\left(s, s^{\prime}\right),\left(t, t^{\prime}\right)\right] ; 0 \leq s \leq 1,0 \leq t \leq 1$; which is to say: Play the mixed strategy $\left(s, s^{\prime}\right)$ in $A^{1}$ and the mixed strategy $\left(t, t^{\prime}\right)$ in $A^{2}$. We will write $\sigma$ in short as $\sigma=(s, t)$. It is easily verified that:

$$
\begin{aligned}
& N S(0)=N S(1)=\{(s, t) \mid 0 \leq s \leq 1,0 \leq t \leq 1\} \\
& N S(p)=\{(s, t) \mid s=t ; 0 \leq s \leq 1\} \text { for } p p^{\prime} \neq 0
\end{aligned}
$$

(I.e. except for $p=0$ or $p=1$, the only non-separating strategies for player I are those in which he plays in the same way in $A^{1}$ and $A^{2}$.)
$\Delta(p)$ is therefore the game:

$$
\left(\begin{array}{rrr}
8 & 3 p+2 p^{\prime} & -p-2 p^{\prime} \\
8 & -3 p-2 p^{\prime} & p+2 p^{\prime}
\end{array}\right)
$$

and its value is $u(p)=0$ for $0<p<1$; since also $u(1)=\operatorname{val}\left(A^{1}\right)=0=\operatorname{val} .\left(A^{2}\right)=$ $u(0)$ we conclude that $u^{*}(p)=0$ for $0 \leq p \leq 1$..

## Lemma 1:

$$
\begin{align*}
v_{n+1}(p)= & \min _{0 \leq \varepsilon \leq 1} \max _{0 \leq s, t \leq 1} \frac{1}{n+1}\left\{8 \varepsilon+(1-\varepsilon) \min \left[3 p\left(s-s^{\prime}\right)\right.\right. \\
& \left.+2 p^{\prime}\left(t-t^{\prime}\right) ; p\left(s^{\prime}-s\right)+2 p^{\prime}\left(t^{\prime}-t\right)\right] \\
& \left.+n(1-\varepsilon) v_{n}(p)+n \varepsilon\left[R^{a} v_{n}\left(p^{a}\right)+R^{b} v_{n}\left(p^{b}\right)\right]\right\} \tag{1}
\end{align*}
$$

for $0 \leq p \leq 1 ; n=1,2, \ldots$ where

$$
\begin{align*}
& R^{a}=p s+p^{\prime} t ; \quad p^{a}=p s / R^{a} \\
& R^{b}=p s^{\prime}+p^{\prime} t^{\prime} ; \quad p^{b}=p s^{\prime} / R^{b} \tag{2}
\end{align*}
$$

Proof:
Let $\sigma=(\mathrm{s}, t)$ be the part concerning the first play in any strategy of player I in $\Gamma_{n+1}(p)$. Let $\tau=(\varepsilon, x, y)$ where $\varepsilon \geq 0, x \geq 0, y \geq 0, \varepsilon+x+y=1$ be the
corresponding part for player II. With strategies starting this way the expected payoff in the first play will be:

$$
\begin{aligned}
E\left(H_{1}\right) & =8 \varepsilon+x\left[3 p\left(s-s^{\prime}\right)+2 p^{\prime}\left(t-t^{\prime}\right)\right]+y\left[p\left(s^{\prime}-s\right)+2 p^{\prime}\left(t^{\prime}-t\right)\right] \\
& \geq 8 \varepsilon+(1-\varepsilon) \min \left[3 p\left(s-s^{\prime}\right)+2 p^{\prime}\left(t-t^{\prime}\right) ; p\left(s^{\prime}-s\right)+2 p^{\prime}\left(t^{\prime}-t\right)\right]
\end{aligned}
$$

After the first play the information announced will be:
$a$ - with probability $\varepsilon R^{a}$
$b$ - with probability $\varepsilon R^{b}$
$c$ or $d$ - with probability $1-\varepsilon$,
where $R^{a}$ and $R^{b}$ given by (2). Given the information $a, b, c$, or $d$, the conditional probability (for player II) of the event "Chance has chosen $A^{1 "}$ is $p^{a}, p^{b}, p^{c}$ or $p^{d}$ respectively where $p^{c}=p^{d}=p$ and $p^{a}$ and $p^{b}$ are given by (2). After the first play therefore the players will face a situation equivalent to either

$$
\begin{aligned}
& \quad \Gamma_{n}(p)(\text { with probability } 1-\varepsilon) \\
& \text { or } \Gamma_{n}\left(p^{a}\right)\left(\text { with probability } \varepsilon R^{a}\right) \\
& \text { or } \Gamma_{n}\left(p^{b}\right)\left(\text { with probability } \varepsilon R^{b}\right) .
\end{aligned}
$$

By playing optimally in $\Gamma_{n}(p), \Gamma_{n}\left(p^{a}\right)$ or $\Gamma_{n}\left(p^{b}\right)$ player I can guarantee a total expected payoff of $n v_{n}(p), n v_{n}\left(p^{a}\right)$ or $n v_{n}\left(p^{b}\right)$ respectively, for the last $n$ plays, thus:

$$
\begin{align*}
v_{n+1}(p) \geq & \min _{0 \leq \varepsilon \leq 1} \max _{0 \leq s, t \leq 1} \frac{1}{n+1}\left\{8 \varepsilon+(1-\varepsilon) \min \left[3 p\left(s-s^{\prime}\right)\right.\right. \\
& \left.+2 p^{\prime}\left(t-t^{\prime}\right) ; p\left(s^{\prime}-s\right)+2 p^{\prime}\left(t^{\prime}-t\right)\right]+n(1-\varepsilon) v_{n}(p) \\
& \left.+n \varepsilon\left[R^{a} v_{n}\left(p^{a}\right)+R^{b} v_{n}\left(p^{b}\right)\right]\right\} . \tag{3}
\end{align*}
$$

On the other hand, for each $\varepsilon, 0 \leq \varepsilon \leq 1$, player II, by playing optimally, can guarantee to pay not more than $\max _{0 \leq s, t \leq 1}\{\ldots\} /(n+1)$ and hence:

$$
v_{n+1}(p) \leq \min _{0 \leq \varepsilon \leq 1} \max _{0 \leq s, t \leq 1}\{\ldots\} /(n+1)
$$

which together with (3) proves (1).
Lemma 2:

$$
\begin{equation*}
v_{n}(p) \geq p p^{\prime} / n^{1 / 3} \tag{4}
\end{equation*}
$$

for $0 \leq p \leq 1, n=1,2, \ldots$.
Proof:
Since (4) is clearly true for $p=0$ or $p=1$ we may assume $p p^{\prime} \neq 0$. It is easily verified that $v_{1}(p)=\min \left(p, p^{\prime}\right) \geq p p^{\prime}$ in accordance with (4). We proceed by induction: Assume (4) is true for $n$ then apply (1) and restrict $s$ and $t$ by the relation:

$$
\begin{equation*}
p\left(s-s^{\prime}\right)=p^{\prime}\left(t^{\prime}-t\right) \quad \text { i.e. } \quad t=\frac{1}{2}-\frac{p\left(s-s^{\prime}\right)}{2 p^{\prime}} \tag{5}
\end{equation*}
$$

which implies:

$$
\min \left[3 p\left(s-s^{\prime}\right)+2 p^{\prime}\left(t-t^{\prime}\right) ; p\left(s^{\prime}-s\right)+2 p^{\prime}\left(t^{\prime}-t\right)\right]=p\left(s-s^{\prime}\right)
$$

and also: $p^{a}=2 p s, p^{b}=2 p s^{\prime}, R^{a}=R^{b}=\frac{1}{2}$. So by (1) we have

$$
\begin{aligned}
v_{n+1}(p) \geq & \min _{0 \leq \varepsilon \leq 1} \max _{\substack{0 \leq s \leq 1 \\
0 \leq \frac{1}{2}-\frac{p\left(s-s^{\prime}\right)}{2 p^{\prime}} \leq 1}} \frac{1}{n+1}\left\{8 \varepsilon+(1-\varepsilon) p\left(s-s^{\prime}\right)+n\left[(1-\varepsilon) v_{n}(p)\right.\right. \\
& \left.\left.+\frac{\varepsilon}{2}\left(v_{n}(2 p s)+v_{n}\left(2 p s^{\prime}\right)\right)\right]\right\}
\end{aligned}
$$

and by induction hypothesis

$$
\begin{equation*}
v_{n+1}(p) \geq \min _{0 \leq \varepsilon \leq 1} \max _{\substack{0 \leq s \leq 1 \\ 0 \leq \frac{1}{2}-\frac{p\left(s-s^{\prime}\right.}{2 p^{\prime}} \leq 1}} \frac{1}{n+1}\left\{8 \varepsilon+(1-\varepsilon) p p^{\prime} n^{2 / 3}+\varphi(s)\right\} \tag{6}
\end{equation*}
$$

where

$$
\begin{aligned}
\varphi(s) & =(1-\varepsilon) p\left(s-s^{\prime}\right)+\frac{\varepsilon n^{2 / 3}}{2}\left(2 p s(2 p s)^{\prime}+2 p s^{\prime}\left(2 p s^{\prime}\right)^{\prime}\right) \\
& =(1-\varepsilon) p\left(s-s^{\prime}\right)+\varepsilon p n^{2 / 3}\left(1-4 p s s^{\prime}-2 p\left(s-s^{\prime}\right)^{2}\right)
\end{aligned}
$$

and since $s s^{\prime} \leq 1 / 4$ we have

$$
\begin{align*}
\varphi(s) \geq \psi(s) & =(1-\varepsilon) p\left(s-s^{\prime}\right)+\varepsilon p n^{2 / 3}\left(p^{\prime}-2 p\left(s-s^{\prime}\right)^{2}\right) \\
& =\varepsilon p p^{\prime} n^{2 / 3}+(1-\varepsilon) p\left(s-s^{\prime}\right)-2 \varepsilon p^{2} n^{2 / 3}\left(s-s^{\prime}\right)^{2} \tag{7}
\end{align*}
$$

$\psi(s)$ attains its maximum at $s_{0}$ such that

$$
\begin{equation*}
\left(s_{0}-s_{0}^{\prime}\right)=\frac{1-\varepsilon}{4 p \varepsilon n^{2 / 3}} \quad \text { and } \quad \psi\left(s_{0}\right)=\varepsilon p p^{\prime} n^{2 / 3}+\frac{(1-\varepsilon)^{2}}{8 \varepsilon n^{2 / 3}} \tag{8}
\end{equation*}
$$

Consider the two cases:
Case $a: s_{0}$ is in the domain of maximization of (6) then by (6) and (8):

$$
v_{n+1}(p) \geq \min _{0 \leq \varepsilon \leq 1} \frac{1}{n+1}\left\{8 \varepsilon+p p^{\prime} n^{2 / 3}+\frac{(1-\varepsilon)^{2}}{8 \varepsilon n^{2 / 3}}\right\}
$$

This minimum is attained at $\varepsilon_{0}=1 / \sqrt{64 n^{2 / 3}+1}$, so

$$
\begin{aligned}
v_{n+1}(p) \geq & \frac{1}{n+1}\left\{p p^{\prime} n^{2 / 3}+\frac{8}{\sqrt{64 n^{2 / 3}+1}}+\frac{\sqrt{64 n^{2 / 3}+1}}{8 n^{2 / 3}}-\frac{1}{4 n^{2 / 3}}\right. \\
& \left.+\frac{1}{8 n^{2 / 3} \sqrt{64 n^{2 / 3}+1}}\right\} \geq \frac{p p^{\prime}}{n+1}\left(n^{2 / 3}+1 / n^{1 / 3}\right) \geq p p^{\prime} /(n+1)^{1 / 3}
\end{aligned}
$$

which is the desired inequality.
Case $b: s_{0}$ is out of the domain of maximization of (6). Let us split this case into three subcases:

Case $b_{1}: s_{0}-s_{0}^{\prime}>1$ (i.e. $\left.p<(1-\varepsilon) /\left(4 \varepsilon n^{2 / 3}\right)\right)$ and $p \leq p^{\prime}$.
In this case choose $s-s^{\prime}=1$ and $p\left(s-s^{\prime}\right)=p^{\prime}\left(t^{\prime}-t\right) . \mathrm{By}(6)$ and (7) we then get:
$v_{n+1}(p) \geq \min _{\left\{\varepsilon \left\lvert\, p \leq \frac{1-\varepsilon}{4 \varepsilon n^{2 / 3}}\right.\right\}} \frac{1}{n+1}\left\{p p^{\prime} n^{2 / 3}+p+\varepsilon\left(8-p-2 p^{2} n^{2 / 3}\right)\right\} \geq p p^{\prime} /(n+1)^{1 / 3}$.
The last inequality is a result of a careful and straightforward examination.
Case $b_{2}: s_{0}-s_{0}^{\prime}>1$ and $p>p^{\prime}$. In this case we choose $t^{\prime}-t=1$ and $p\left(s-s^{\prime}\right)=$ $p^{\prime}\left(t^{\prime}-t\right)$. Again by (6) and (7) we get very similarly:

$$
\begin{aligned}
v_{n+1}(p) & \geq \min _{\left\{\varepsilon \left\lvert\, p \leq \frac{1-\varepsilon}{4 \varepsilon n^{2 / 3}}\right.\right\}} \frac{1}{n+1}\left\{p p^{\prime} n^{2 / 3}+p^{\prime}+\varepsilon\left(8-p^{\prime}-2 p^{\prime 2} n^{2 / 3}\right)\right\} \\
& \geq \min _{\left\{\varepsilon \left\lvert\, p^{\prime} \leq \frac{1-\varepsilon}{4 \varepsilon n^{2 / 3}}\right.\right\}^{2}} \frac{1}{n+1}\{\cdots\} \geq p p^{\prime} /(n+1)^{1 / 3}
\end{aligned}
$$

Case $_{3}: s_{0}-s_{0}^{\prime} \leq 1$ and $t_{0}=1 / 2-p\left(s-s^{\prime}\right) / 2 p^{\prime}<0$, i.e. $p^{\prime}<(1-\varepsilon) /\left(4 \varepsilon n^{2 / 3}\right) \leq p$. In this case we again choose $t^{\prime}-t=1$ and $p\left(s-s^{\prime}\right)=p^{\prime}\left(t^{\prime}-t\right)$ and get the same expression as in the last step of case $b_{2}$. Hence the proof of Lemma 2 is complete.

Lemma 2 asserts that $1 / \sqrt{n}$ which is the upper bound for (the order of magnitude of) $\delta_{n}$ in the standard information case is not an upper bound in the general case. The upper bound is at least $1 / n^{1 / 3}$, and this is the only thing that can be said from our example since in this example $\delta_{n}$ is actually of the order of $1 / n^{1 / 3}$ as it is shown by the next theorem.

## Theorem 2:

In the game under consideration,

$$
v_{n}(p)=0^{*}\left(1 / n^{1 / 3}\right)
$$

## Proof:

First notice that since $\lim v_{n}(p)=0$ we have actually $v_{n}(p)=\delta_{n}(p)$. Now in view of Lemma 2 the proof of the theorem will be concluded by proving

$$
\begin{equation*}
v_{n}(p) \leq \alpha \sqrt{p p^{\prime}} / n^{1 / 3}, \quad \text { where } \quad \alpha=\sqrt[3]{192} \tag{9}
\end{equation*}
$$

We shall prove (9) by induction on $n$. For $n=1$ we have $v_{1}(p)=\min \left(p, p^{\prime}\right) \leq \sqrt{p p^{\prime}}$ in accordance with (9). Assume (9) holds for $n$ and let us prove it for $n+1$. First we notice that by $\min (A, B) \leq(1-p / 4) A+(1+p / 4) B$ we get:

$$
\begin{equation*}
\min \left[3 p\left(s-s^{\prime}\right)+2 p^{\prime}\left(t-t^{\prime}\right) ; p\left(s^{\prime}-s\right)+2 p^{\prime}\left(t^{\prime}-t\right)\right] \leq 2 p p^{\prime}(s-t) \tag{10}
\end{equation*}
$$

Combining (10) and (1) we have:

$$
\begin{aligned}
v_{n+1}(p) \leq & \min _{0 \leq \varepsilon \leq 1} \max _{0 \leq s, t \leq 1} \frac{1}{n+1}\left\{8 \varepsilon+2(1-\varepsilon) p p^{\prime}(s-t)+n(1-\varepsilon) v_{n}(p)\right. \\
& \left.+n \varepsilon\left[R^{a} v_{n}\left(p^{a}\right)+R^{b} v_{n}\left(p^{b}\right)\right]\right\}
\end{aligned}
$$

Using the induction hypothesis and noticing that by (2)

$$
R^{a} \sqrt{p^{a} p^{a^{\prime}}}+R^{b} \sqrt{p^{b} p^{b^{\prime}}} \leq \sqrt{p p^{\prime}}\left(1-\frac{(s-t)^{2}}{4}\right)
$$

we get

$$
v_{n+1}(p) \leq \frac{\alpha \sqrt{p p^{\prime}} n^{2 / 3}}{n+1}+\min _{0 \leq \varepsilon \leq 1} \max _{0 \leq t, s \leq 1} \frac{1}{n+1} \varphi((s-t))
$$

where

$$
\varphi((s-t))=8 \varepsilon+2 p p^{\prime}(s-t)-\alpha \varepsilon \sqrt{p p^{\prime}} n^{2 / 3} \frac{(s-t)^{2}}{4}
$$

$\varphi((s-t))$ attains its maximum at $(s-t)_{0}=4 \sqrt{p p^{\prime}} /\left(\alpha \varepsilon n^{2 / 3}\right)$ and $\varphi\left((s-t)_{0}\right)=$ $8 \varepsilon+4 p p^{\prime} \sqrt{p p^{\prime}} /\left(\alpha \varepsilon n^{2 / 3}\right)$, therefore,

$$
\begin{equation*}
v_{n+1}(p) \leq \frac{\alpha \sqrt{p p^{\prime}} n^{2 / 3}}{n+1}+\frac{1}{n+1} \min _{0 \leq \varepsilon \leq 1}\left\{8 \varepsilon+\frac{4 p p^{\prime} \sqrt{p p^{\prime}}}{\alpha \varepsilon n^{2 / 3}}\right\} \tag{12}
\end{equation*}
$$

The expression $\{\ldots\}$ as a function of $\varepsilon$ attains its minimum at $\varepsilon_{0}=\left(p p^{\prime}\right)^{3 / 4} /$ $(2 \alpha)^{1 / 2} n^{1 / 3}<1$, so by (12)

$$
\begin{aligned}
v_{n+1}(p) & \leq \frac{\alpha \sqrt{p p^{\prime}} n^{2 / 3}}{n+1}+\frac{1}{n+1} \frac{16\left(p p^{\prime}\right)^{3 / 4}}{(2 \alpha)^{1 / 2} n^{1 / 3}} \\
& \leq \frac{\alpha \sqrt{p p^{\prime}}}{n+1}\left(n^{2 / 3}+\frac{1}{\sqrt{3} n^{1 / 3}}\right)<\alpha \sqrt{p p^{\prime}} /(n+1)^{1 / 3}
\end{aligned}
$$

which completes the proof of Theorem 2.

## 3. An Upper Bound for $\boldsymbol{\delta}_{\boldsymbol{n}}$

In this section we discuss the order of magnitude of the error term $\delta_{n}$ when $k=2$, i.e. chance chooses one of two games $A^{1}$ and $A^{2}$ with the corresponding information matrix $H^{1}$ or $H^{2}$ respectively.

Let $H=\left\{h_{i j}^{v} \mid 1 \leq i \leq l, 1 \leq j \leq m, v=1,2\right\} . H$ may be called the information set and it is the set of all possible pieces of information that can be announced by the referee throughout the game. $A k$-stage history is a $k$-tuple of elements of $H$ denoted by $A_{k}=\left(h_{1}, \ldots, h_{k}\right)$. It is to be interpreted as the list of announcements of the referee for the first $k$ stages of the game. A strategy ${ }^{3}$ ) of player I in $\Gamma_{n}(p)$ is an $n$-tuple $\sigma_{n}=\left(f_{1}, \ldots, f_{n}\right)$ where $f_{k}(1 \leq k \leq n)$ is a function from the set of all $k-1$ stage histories to the set of mixed strategies (of player I) in $\Gamma_{1}(p)$. A strategy for player II in $\Gamma_{n}(p)$ is $\tau_{n}=\left(g_{1}, \ldots, g_{n}\right)$ defined similarly. Denote by $\tau_{k}^{*}=\left(j_{1}, \ldots, j_{k}\right)$ the $k$-tuple of pure strategies actually played by player II in the first $k$ stages. The probability distribution on all possible $\tau_{k}^{*}$ is determined by $\tau$. Now, $\sigma_{n}, \tau_{k}^{*}$ and $p$ induce a probability distribution on the set of all $k-1$ stage histories. Therefore, given $\sigma_{n}$ and $\Lambda_{k-1}$, player II can compute the conditional probability of the event "Chance has chosen $A^{1 "}$. Denote this probability by $p_{k}$, i.e.,

$$
p_{k}=\operatorname{prob}\left\{\text { chance has chosen } A^{1} \mid \sigma_{n}, \tau_{k-1}^{*}, \Lambda_{k-1}\right\}
$$

Notice that $E\left(p_{k}\right)=p$ for $k=1,2, \ldots$ ( $E$ denotes expectation).

[^1]The probability $p_{k}$ is a state variable in the sense that the situation in $\Gamma_{n}(p)$ before the $k^{\text {th }}$ stage is equivalent to that of a new game $\Gamma_{n-k+1}\left(p_{k}\right)$ with $n-k+1$ stages and a probability $p_{k}$ for chance to choose $A^{1}$.

In what follows we shall use the expression "given $p_{k}$ ", in symbols ( $\ldots \mid p_{k}$ ), as a short form of saying: "Given a strategy $\sigma_{n}$ of player I and given that before the $k^{\text {th }}$ stage, the history was $\Lambda_{k-1}$, and the sequence of pure strategies played by player II up to that stage was $\tau_{k-1}^{*}$, such that the conditional probability of the event 'Chance has chosen $A^{1}{ }^{\prime}$ is $p_{k}$ ".

We denote as usual the one-stage strategy of player I by $\sigma=\left(s^{1}, s^{2}\right)=$ $\left[\left(s_{1}^{1}, \ldots, s_{l_{1}}^{1}\right),\left(s_{1}^{2}, \ldots, s_{l_{2}}^{2}\right)\right] \in \Sigma^{1} \times \Sigma^{2}$ where $\Sigma^{1}$ and $\Sigma^{2}$ are the spaces of mixed strategies for player I in $A^{1}$ and $A^{2}$ respectively. (For the general model as well as for what we are going to prove, player I need not have the same number of pure strategies in all $A^{v}$.) The non-separating strategies of player I are then given by:

$$
\begin{gathered}
N S(0)=N S(1)=\Sigma^{1} \times \Sigma^{2}, \quad \text { and } \\
N S(p)=\left\{\sigma \mid \sum_{i=1}^{l_{1}} s_{i}^{1} \varepsilon_{i j h}^{1}-\sum_{i=1}^{l_{2}} s_{i}^{2} \varepsilon_{i j h}^{2}=0 ; j=1, \ldots, m ; h \in H\right\}
\end{gathered}
$$

for $0<p<1$, where:

$$
\varepsilon_{i j h}^{v}=\left\{\begin{array}{ll}
1 & h_{i j}^{\nu}=h \\
0 & h_{i j}^{\nu} \neq h
\end{array} \quad v=1,2 .\right.
$$

Notice that $N S(p)$ is the same for any $p$ with $0<p<1$.
We are now in the position to state our next result:

## Theorem 3:

If $N S(p)=\emptyset$ for $0<p<1$ then there exists a positive constant $c$ such that $v_{n}(p) \leq u^{*}(p)+c / n^{1 / 4}$ for $n=1,2, \ldots, 0 \leq p \leq 1$.

## Proof:

Note first that since $u^{*}(p)$ is concave, it is always true that $u^{*}(p) \geq p u(1)+p^{\prime} u(0)$. However when $N S(p)=\emptyset, u(p)$ is not defined for $0<p<1$ and hence $u^{*}(p)=$ $p u(1)+p^{\prime} u(0)$ for $0 \leq p \leq 1$.

## Proposition 1:

There is a constant $\alpha>0$ such that given $p_{k}$, player II can guarantee $E\left(H_{k} \mid p_{k}\right) \leq$ $u^{*}\left(p_{k}\right)+\alpha p_{k} p_{k}^{\prime}$. ( $H_{k}$ is the payoff at the $k^{\text {th }}$ stage.)

To see this, let $\tau_{1}$ and $\tau_{0}$ be two optimal strategies (for player II) in $A^{1}$ and $A^{2}$ respectively. Using $\tau_{1}$ player II guarantees: $E\left(H_{k} \mid p_{k}\right) \leq u(1)+B p_{k}^{\prime}$ where $B=\max _{i, j, v}\left|a_{i j}^{v}\right|$. Similarly $\tau_{0}$ guarantees $E\left(H_{k} \mid p_{k}\right) \leq u(0)+B p_{k}$. Thus mixing $\tau_{1}$ and $\tau_{0}$ with probabilities $p_{k}$ and $p_{k}^{\prime}$ guarantees:

$$
E\left(H_{k} \mid p_{k}\right) \leq p_{k} u(1)+p_{k}^{\prime} u(0)+2 B p_{k} p_{k}^{\prime} \leq u^{*}\left(p_{k}\right)+\alpha p_{k} p_{k}^{\prime}
$$

where $\alpha=2 B$.

We notice that Proposition 1 is valid (and in fact it was proved) in the general case, without the assumption $N S(p)=\emptyset$.

## Proposition 2:

There is a constant $\eta>0$ such that for any $\sigma \in \Sigma^{1} \times \Sigma^{2}$

$$
\begin{equation*}
\max _{h \in H}\left|\sum_{i} s_{i}^{1} \varepsilon_{i j h}^{1}-\sum_{i} s_{i}^{2} \varepsilon_{i j h}^{2}\right| \geq \eta \tag{13}
\end{equation*}
$$

This follows since the left hand side of the inequality is a non-negative continuous function on the compact set $\Sigma^{1} \times \Sigma^{2}$ and therefore it attains its minimum. This minimum, $\eta$, cannot be 0 since this would imply $N S(p)=\emptyset$ for $0<p<1$.

For any $\sigma \in \Sigma^{1} \times \Sigma^{2}$ let $h_{\sigma}$ be the element in $H$ for which the maximum in (13) is attained. Let $j_{\sigma}$ be such that $\varepsilon_{i j_{\sigma} h_{\sigma}}^{v}=1$ for some $i$ and $v$. For $0 \leq \varepsilon \leq 1$ define a strategy $\tau(\varepsilon)$ for player II as follows: Choose $j_{\sigma}$ with probability $\varepsilon$, and with probability $(1-\varepsilon)$ play the strategy that guarantees $E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+$ $\alpha p_{k} p_{k^{*}}^{\prime}$. By using $\tau(\varepsilon)$ in the $k^{\text {th }}$ stage, player II guarantees:

$$
\begin{equation*}
E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+\varepsilon B+\alpha p_{k} p_{k}^{\prime} \tag{14}
\end{equation*}
$$

where $B=\max _{i, j, v}\left|a_{i j}^{v}\right|$.
When $\sigma$ and $\tau(\varepsilon)$ are played, the information $h_{\sigma}$ will be announced with a probability $p\left\{h_{\sigma}\right\}$ satisfying:

$$
p\left\{h_{\sigma}\right\} \geq \varepsilon\left(p_{k} \sum_{i} s_{i}^{1} \varepsilon_{i j_{\sigma} h_{\sigma}}^{1}+p_{k}^{\prime} \sum_{i} s_{i}^{2} \varepsilon_{i j_{\sigma} h_{\sigma}}^{2}\right)
$$

In this event the new conditional probability will be:

$$
p_{k+1}\left(h_{\sigma}\right)=\frac{p_{k} \sum_{i} s_{i}^{1} \varepsilon_{i j_{\sigma} h_{\sigma}}^{1}}{p_{k} \sum_{i} s_{i}^{1} \varepsilon_{i j_{\sigma} h_{\sigma}}^{1}+p_{k}^{\prime} \sum_{i} s_{i}^{2} \varepsilon_{i j_{\sigma} h_{\sigma}}^{2}} .
$$

Therefore, by (13):

$$
\begin{equation*}
E\left(\mid p_{k+1}-p_{k} \| p_{k}\right) \geq\left|p_{k+1}\left(h_{\sigma}\right)-p_{k}\right| \cdot p\left\{h_{\sigma}\right\} \geq p_{k} p_{k}^{\prime} \eta \varepsilon \tag{15}
\end{equation*}
$$

Combining (14) and (15) we have

$$
E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+\varepsilon B+\frac{\alpha E\left(\left|p_{k+1}-p_{k}\right| \mid p_{k}\right)}{\eta \varepsilon}
$$

Taking $\varepsilon_{0}=\sqrt{\alpha /(B \eta)} \sqrt{E\left(\left|p_{k+1}-p_{k}\right| \mid p_{k}\right)}$, and choosing $N$ such that $k \geq N \Rightarrow$ $\varepsilon_{0} \leq 1$. (This is possible since $E\left(\left|p_{k+1}-p_{k}\right| \mid p_{k}\right) \rightarrow 0$ ) we get:

$$
k \geq N \Rightarrow E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+2 \sqrt{\frac{\alpha B}{\eta}} \sqrt{E\left(\left|p_{k+1}-p_{k}\right| \mid p_{k}\right)} .
$$

Let $L=\sum_{k=1}^{N-1} E\left(H_{k}\right)$. Using $E\left(p_{k}\right)=p$, the linearity of $u^{*}(p)$ and the concavity of the function $\sqrt{x}$ we get:

$$
\begin{aligned}
v_{n}(p) \leq \frac{E\left(\sum_{i}^{n} H_{k}\right)}{n} & \leq u^{*}(p)+\frac{L}{n}+2 \sqrt{\frac{\alpha B}{\eta}} \frac{\left.\sum_{i}^{n} \sqrt{E\left(\left|p_{k+1}-p_{k}\right|\right.}\right)}{n} \\
& \leq u^{*}(p)+\frac{L}{n}+2 \sqrt{\frac{\alpha B}{\eta}} \frac{\sqrt{n \sum_{i}^{n} E\left(\left|p_{k+1}-p_{k}\right|\right)}}{n}
\end{aligned}
$$

Since $E\left(\sum_{i}^{k}\left|p_{k+1}-p_{k}\right|\right) \leq \sqrt{n}$, (see, AUMANN \& MASChLER, or ZAMIR), we obtain
finally:

$$
v_{n}(p) \leq u^{*}(p)+c / n^{1 / 4}
$$

where $c=2 \sqrt{\alpha B / \eta}+L$, which concludes the proof of Theorem 3 .

## Lemma 3:

Let $S$ be a non-empty polyhedron in $E^{m}$ and let $L_{i} x=0, i=1, \ldots, d ; x=\left(x_{1}, \ldots, x_{m}\right)$ be hyperplanes in $E^{m}$. Define $N S=\left\{x \mid x \in S ; L_{i} x=0, i=1, \ldots, d\right\}$. If $N S \neq \emptyset$ then there exists a constant $D>0$ depending only on $L_{i}, i=1, \ldots, d$ and $S$ such that

$$
\begin{equation*}
\max _{i}\left|L_{i} x\right| \geq D\|x-N S\| \text { for all } x \in S \tag{16}
\end{equation*}
$$

$\left(\|x-N S\|=\min _{y \in N S}\|x-y\|,\|x\|\right.$ being the Euclidean norm in $\left.E^{m}.\right)$

## Proof:

## Proposition 1:

If $\{x \mid L x=0\}$ is a hyperplane, $L x_{0}=0$ and $a \neq x_{0}$, then for each $x$ in the half line $\left\{x \mid x=x_{0}+\theta(a-x) ; \theta>0\right\}$ we have

$$
\frac{|L x|}{\left\|x-x_{0}\right\|}=\frac{|L a|}{\left\|a-x_{0}\right\|}
$$

This is demonstrated by:

$$
\frac{|L x|}{\left\|x-x_{0}\right\|}=\frac{\left|L\left(x_{0}+\theta\left(a-x_{0}\right)\right)\right|}{\left\|\theta\left(a-x_{0}\right)\right\|}=\frac{L \theta a}{\left\|\theta\left(a-x_{0}\right)\right\|}=\frac{|L a|}{\left\|a-x_{0}\right\|}
$$

Proposition 2:
If $N S$ is a convex set in $E^{m}, x_{0} \in N S, a \notin N S$ such that $\|a-N S\|=\left\|a-x_{0}\right\|$, then for any $x$ in the half line $\left\{x \mid x=x_{0}+\theta\left(a-x_{0}\right) ; \theta>0\right\},\|x-N S\|=\left\|x-x_{0}\right\|$ holds.

To prove this we will show that the hyperplane through $x_{0}$ and perpendicular to the half line, separates a from NS. In other words we show that

$$
\begin{equation*}
\left(a-x_{0}\right)\left(y-x_{0}\right) \leq 0 \quad \forall y \in N S . \tag{17}
\end{equation*}
$$

Assume that there is $z \in N S$ such that

$$
\begin{equation*}
\left(a-x_{0}\right)\left(z-x_{0}\right)>0 \tag{18}
\end{equation*}
$$

then by the definition of $x_{0}$ :

$$
\begin{aligned}
& \left\|a-x_{0}\right\|^{2}<\|a-z\|^{2} \\
& =\left[\left(a-x_{0}\right)+\left(x_{0}-z\right)\right](a-z) \\
& \\
& \\
& \\
& \\
& \text { hence }
\end{aligned}
$$

$$
\begin{equation*}
(a-z)\left(z-x_{0}\right)<0 . \tag{19}
\end{equation*}
$$

From (18) and (19) it follows that there is $z^{*}, z^{*}=\theta x_{0}+(1-\theta) z, 0<\theta<1$ such that

$$
\begin{equation*}
\left(a-z^{*}\right)\left(z-x_{0}\right)=0 . \tag{20}
\end{equation*}
$$

Since $N S$ is convex it follows that $z^{*} \in N S$ and

$$
\begin{aligned}
\left\|a-z^{*}\right\|^{2} & =\left(a-z^{*}\right)\left[\left(a-z^{*}\right)+(1-\theta)\left(z-x_{0}\right)\right] \\
& =\left(a-z^{*}\right)\left(a-x_{0}\right)=\left[\left(a-x_{0}\right)-(1-\theta)\left(z-x_{0}\right)\right]\left(a-x_{0}\right) \\
& =\left\|a-x_{0}\right\|^{2}-(1-\theta)\left(a-x_{0}\right)\left(z-x_{0}\right)<\left\|a-x_{0}\right\|^{2},
\end{aligned}
$$

which contradicts the definition of $x_{0}$ and hence proves Proposition 2.
Let us prove now Lemma 3 by induction on the dimension of $S$ : If $\operatorname{dim} S=0$ ( $S$ is one point) there is nothing to prove. If $\operatorname{dim} S=1$, i.e., $S=\{x \mid x=\theta a+(1-\theta) b$; $0 \leq \theta \leq 1\}$ then (16) follows easily from Proposition 1. Assume that the lemma is true for $\operatorname{dim} S \leq k<m$ and it is wrong for $\operatorname{dim} S=k+1$. Then there is a sequence $\left\{x_{n}\right\}$ of points in $S$ such that:

$$
\begin{equation*}
\left|L_{i} x_{n}\right|<\frac{1}{n}\left\|x_{n}-N S\right\|, \quad i=1, \ldots, d ; n=1,2, \ldots \tag{21}
\end{equation*}
$$

Let $y_{n}$ be the point in NS nearest to $x_{n}$, i.e.:

$$
\left\|x_{n}-N S\right\|=\left\|x_{n}-y_{n}\right\|, \quad n=1,2, \ldots
$$

Define:

$$
\begin{aligned}
& \theta_{n}=\max \left\{\theta \mid y_{n}+\theta\left(x_{n}-y_{n}\right) \in S\right\} \\
& x_{n}^{\prime}=y_{n}+\theta_{n}\left(x_{n}-y_{n}\right)
\end{aligned}
$$

Clearly each $x_{n}^{\prime}$ is on a face of $S$ and since $S$ has a finite number of faces we can assume (by taking a subsequence) that $x_{n}^{\prime}$ are on one face, say $\pi$, of $S$ for $n=1,2, \ldots$.

Now by Proposition $1\left|L_{i} x_{n}^{\prime}\right| /\left\|x_{n}^{\prime}-y_{n}| |=\left|L_{i} x_{n}\right| /\right\| x_{n}-y_{n} \|$, and by Proposition 2: $\left\|x_{n}^{\prime}-N S\right\|=\left\|x_{n}^{\prime}-y_{n}\right\|$. Hence by (21):

$$
\begin{equation*}
\left|L_{i} x_{n}^{\prime}\right|<\frac{1}{n}\left\|x_{n}^{\prime}-N S\right\|, \quad i=1, \ldots, d ; n=1,2, \ldots \tag{22}
\end{equation*}
$$

Let $x_{0}$ be a limit point for a subsequence of $\left\{x_{n}^{\prime}\right\}$, then since $\left\|x_{n}^{\prime}-N S\right\|$ is bounded we have: $L_{i} x_{0}=0$ for $i=1, \ldots, d$; which implies $x_{0} \in N S$. On the other hand since the face $\pi$ is closed we have also $x_{0} \in \pi$. So if we define $N S^{\prime}=N S \cap \pi$ we have $N S^{\prime} \neq \emptyset$. Now clearly $\left\|x_{n}^{\prime}-N S\right\| \leq\left\|x_{n}^{\prime}-N S^{\prime}\right\|$, hence:

$$
\begin{equation*}
\left|L_{i} x_{n}^{\prime}\right|<\frac{1}{n}\left\|x_{n}^{\prime}-N S^{\prime}\right\|, \quad i=1, \ldots, d ; n=1,2, \ldots \tag{23}
\end{equation*}
$$

which contradicts the induction hypothesis since $\pi$ is a polyhedron of dimension $k$. This completes the proof of Lemma 3.

## Theorem 4:

For any game $\Gamma_{n}(p)$ with $k=2$, there exists a constant $c$ such that

$$
\begin{align*}
v_{n}(p) & \leq u^{*}(p)+c / n^{1 / 6}  \tag{24}\\
\text { for } \quad 0 & \leq p \leq 1 \quad \text { and } n=1,2, \ldots
\end{align*}
$$

Proof:
If $N S(p)=\emptyset, 0<p<1$, then (24) follows from Theorem 3. Assume therefore that $N S(p)=N S \neq \emptyset$ for $0<p<1$, then by Lemma 3 there is a constant $D>0$ such that for any $\sigma \in \Sigma^{1} \times \Sigma^{2}$ we have:

$$
\begin{equation*}
\max _{h}\left|\sum_{i} s_{i}^{1} \varepsilon_{i j h}^{1}-\sum_{i} s_{i}^{2} \varepsilon_{i j h}^{2}\right| \geq D\|\sigma-N S\| \tag{25}
\end{equation*}
$$

for $0<p<1$.

## Proposition 1:

Given $p_{k}$, player II has a pure strategy $j_{0}$ such that when used with probability $\varepsilon$ it guarantees $E\left(\left|p_{k+1}-p_{k}\right| \mid p_{k}\right) \geq \varepsilon p_{k} p_{k}^{\prime}\|\sigma-N S\|$ for any $\sigma \in \Sigma^{1} \times \Sigma^{2}$ played by player I.

This can be shown by very much the same argument used to prove (15) in the proof of Theorem 3 (namely $j_{0}$ is the column in which is found $h_{\sigma}$ that maximizes the left hand side of (25).)

## Proposition 2:

Player II can guarantee:

$$
\begin{equation*}
E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+B\|\sigma-N S\| \tag{26}
\end{equation*}
$$

where $B=\max _{i, j, v}\left|a_{i j}^{v}\right|$.
In fact he can do this by playing an optimal strategy in $\Delta\left(p_{k}\right)$.
A combination of Proposition 2 and Proposition 1 in the proof of Theorem 3 gives:

## Proposition 3:

Given $p_{k}$, player II has a strategy $\tau_{*}$ that guarantees $E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+$ $\min \left(B\|\sigma-N S\|, \alpha p_{k} p_{k}^{\prime}\right)$, and hence:

$$
\begin{equation*}
E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+(B \alpha)^{1 / 2}\left(p_{k} p_{k}^{\prime}\right)^{1 / 2}\|\sigma-N S\|^{1 / 2} \tag{27}
\end{equation*}
$$

For $0 \leq \varepsilon \leq 1$ define $\tau_{*}(\varepsilon)=\varepsilon j_{0} \stackrel{*}{+}(1-\varepsilon) \tau_{*}\left(j_{0}\right.$ is defined by Proposition 1 and $\stackrel{*}{+}$ is a formal probabilistic mixture). Playing $\tau_{*}(\varepsilon)$ at stage $k$ player II guarantees:

$$
E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+\varepsilon B+(B \alpha)^{1 / 2}\left(p_{k} p_{k}^{\prime}\right)^{1 / 2}\|\sigma-N S\|^{1 / 2}
$$

and by Proposition 1 :

$$
\begin{equation*}
E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+\varepsilon B+\frac{\bar{c}\left[E\left(\left|p_{k+1}-p_{k}\right| \mid p_{k}\right)\right]^{1 / 2}}{\varepsilon^{1 / 2}} \tag{28}
\end{equation*}
$$

where $\bar{c}=(\alpha B / D)^{1 / 2}$. Now minimize the right hand side of (28) by choosing $\varepsilon_{0}=(\bar{c} /(2 B))^{2 / 3}\left[E\left(\left|p_{k+1}-p_{k}\right| \mid p_{k}\right)\right]^{1 / 3}$, for $k \geq N($ where $N$ is such that $k \geq N \Rightarrow$ $\varepsilon_{0} \leq 1$ ), we get:

$$
\begin{equation*}
k \geq N \Rightarrow E\left(H_{k} \mid p_{k}\right) \leq u^{*}\left(p_{k}\right)+\bar{D}\left[E\left(\left|p_{k+1}-p_{k}\right| \mid p_{k}\right)\right]^{1 / 3} \tag{29}
\end{equation*}
$$

where $\bar{D}=2 B \bar{c}$. Letting $L=\sum_{1}^{N-1} E\left(H_{k}\right)$ we get by using the concavity of $u^{*}(p)$
and of $x^{1 / 3}$ :

$$
\begin{equation*}
v_{n}(p) \leq \frac{1}{n} \sum_{1}^{n} E\left(H_{k}\right) \leq u^{*}(p)+\frac{L}{n}+\frac{\bar{D}}{n} \sum_{1}^{n}\left[E\left(\left|p_{k+1}-p_{k}\right|\right)\right]^{1 / 3} . \tag{30}
\end{equation*}
$$

By Hölder inequality and since $E\left(\sum_{1}^{n}\left|p_{k+1}-p_{k}\right|\right) \leq n^{1 / 2}$ :

$$
\begin{aligned}
\sum_{i}^{n}\left[E\left(\left|p_{k+1}-p_{k}\right|\right)\right]^{1 / 3} & \leq\left[\sum_{i}^{n} E\left(\left|p_{k+1}-p_{k}\right|\right)\right]^{1 / 3} n^{2 / 3} \\
& \leq\left[n^{1 / 2}\right]^{1 / 3} n^{2 / 3}=n^{5 / 6}
\end{aligned}
$$

Inserting this in (30) and setting $c=\bar{D}+L$ we obtain finally $v_{n}(p) \leq u^{*}(p)+c / n^{1 / 6}$ which completes the proof of Theorem 4.

## 4. Some Open Questions

There are several questions still to be answered:

1) What is the upper bound for $\delta_{n}$ when $k>2$ ? Quite surprisingly, the generalization of our results for $k=2$ is not straightforward.
2) What is the least upper bound for the order of magnitude of $\delta_{n}$ ? This is interesting even when $k=2$ since there is a gap between our bound $1 / n^{1 / 6}$ and the order of magnitude of $\delta_{n}$ in our example which is $1 / n^{1 / 3}$. In fact we conjecture that the least upper bound is lower than $1 / n^{1 / 6}$.
3) Even for $k=2$ and $N S(p)=\emptyset$ it is not known whether the bound $1 / n^{1 / 4}$ is the least upper bound.
4) In what way does the error term depends on the information matrices of both players? In this work we assumed that the information announced by the referee was the same for both players. More generally this information may be different for each player. Aumann and Maschler [1968] showed that the information to player I (the one who knows the choice of chance) is irrelevant as far as the value of the game is concerned. We feel that it may play an important role in the speed of convergence, namely in $\delta_{n}$.

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[^0]:    ${ }^{1}$ ) This research was done in part under NSF Grant No. GP-33431 X.
    ${ }^{2}$ ) Prof. Shmuel Zamir, Department of Mathematics, University of California, Los Angeles, California.

[^1]:    ${ }^{3}$ ) Essentially a behavioural strategy.

