

## **General Disclaimer**

### **One or more of the Following Statements may affect this Document**

- This document has been reproduced from the best copy furnished by the organizational source. It is being released in the interest of making available as much information as possible.
- This document may contain data, which exceeds the sheet parameters. It was furnished in this condition by the organizational source and is the best copy available.
- This document may contain tone-on-tone or color graphs, charts and/or pictures, which have been reproduced in black and white.
- This document is paginated as submitted by the original source.
- Portions of this document are not fully legible due to the historical nature of some of the material. However, it is the best reproduction available from the original submission.

ON THE UNIFORM ASYMPTOTIC STABILITY OF FUNCTIONAL  
DIFFERENTIAL EQUATIONS OF THE NEUTRAL TYPE

by

J. K. Hale<sup>+</sup>

Center for Dynamical Systems  
Division of Applied Mathematics  
Brown University  
Providence, Rhode Island

and

A. F. Ize<sup>++</sup>

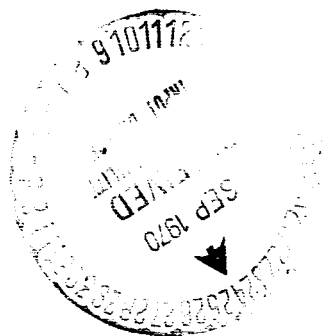
Center for Dynamical Systems  
Division of Applied Mathematics  
Brown University  
Providence, Rhode Island

and

Escola de Engenharia de São Carlos  
Universidade de São Paulo  
São Carlos, São Paulo, Brasil

<sup>+</sup>This research was supported in part by the National Aeronautics and Space Administration under Grant No. NGL 40-002-015 and in part by the Air Force Office of Scientific Research under Grant No. AF-AFOSR 693-67.

<sup>++</sup>This research was supported in part by the Conselho Nacional de Pesquisas, in part by Fundação de Amparo à Pesquisa do Estado de São Paulo, and in part by the Air Force Office of Scientific Research under Grant No. AF-AFOSR 693-67B.



N70:41243  
(ACCESSION NUMBER)  
14  
(PAGES)  
CB-13889  
(NASA CR OR TMX OR AD NUMBER)

(HRL)  
19  
(CODE)  
(CATEGORY)

FACILITY FORM 602

### Abstract

Consider the functional equations of neutral type

$$(1) \frac{d}{dt} D(t, x_t) = f(t, x_t) \quad \text{and} \quad (2) \frac{d}{dt} [D(t, x_t) - G(t, x_t)] =$$

$= f(t, x_t) + F(t, x_t)$  where  $D, f$  are bounded linear operators from  $C[a, b]$  into  $R^n$  or  $C^n$  for each fixed  $t$  in  $[0, \infty)$ ,

$$F = F_1 + F_2, \quad G = G_1 + G_2, \quad |F_1(t, \phi)| \leq v(t)|\phi|, \quad |G_1(t, \phi)| \leq r(t)|\phi|,$$

$r(t)$ , bounded and for any  $\varepsilon > 0$ , there exists  $\delta(\varepsilon) > 0$  such that

$$|F_2(t, \phi)| \leq \varepsilon|\phi|, \quad |G_2(t, \phi)| \leq \varepsilon|\phi|, \quad t \geq 0, \quad |\phi| < \delta(\varepsilon). \quad \text{The authors}$$

prove that if (1) is uniformly asymptotically stable, then there

is a  $\xi_0, 0 < \xi_0 < 1$  such that for any  $p > 0, 0 < \xi < \xi_0$  there

are constants  $v_0 > 0, M_0 > 0, s_0 > 0$  such that if  $\pi(t) < M_0,$

$t \geq s_0, \frac{1}{p} \int_t^{t+p} v(s) ds < \xi v_0, t > 0$  then the solution  $x = 0$  of (2)

is uniformly asymptotically stable. The result generalizes previous

results which consider only terms of the form  $F_1, G_1$  or  $F_2, G_2$

but not both simultaneously, and the stronger hypothesis

$$\lim_{t \rightarrow \infty} \pi(t) = 0.$$

List of Symbols

$\infty$	$\phi$	$\sigma$	$\nu$	$\pi$
$\delta$	$\Omega$	$\epsilon$	$\alpha$	$\epsilon$
[ ]	$\rightarrow$	$\int$	$\beta$	$\eta$
$\theta$	$\times$	$\mu$	$\gamma$	$\zeta$
$\beta$	/	$\Sigma$	$>$	

ON THE UNIFORM ASYMPTOTIC STABILITY OF FUNCTIONAL  
DIFFERENTIAL EQUATIONS OF THE NEUTRAL TYPE

J. K. Hale and A. F. Ize

Suppose  $r \geq 0$  is a given real number,  $R = (-\infty, \infty)$ ,  $E$  is a real or complex  $n$ -dimensional linear vector space with norm  $|\cdot|$ ,  $C([a, b], E)$  is the Banach space of continuous functions mapping the interval  $[a, b]$  into  $E$  with the topology of uniform convergence. If  $[a, b] = [-r, 0]$ , we let  $C = ([-r, 0], E)$  and designate the norm of an element  $\phi$  in  $C$  by  $|\phi| = \sup_{-r \leq \theta \leq 0} |\phi(\theta)|$ . If  $\Omega$  is an open subset of  $R \times C$  and  $f, D: \Omega \rightarrow E$  are given continuous functions, we say that the relation

$$\frac{d}{dt} D(t, x_t) = f(t, x_t) \quad (1)$$

is a functional differential equation. A function  $x$  is said to be a solution of (1) if there are  $\sigma \in R$ ,  $A > 0$  such that  $x \in C([\sigma-r, \sigma+A], E)$ ,  $(t, x_t) \in \Omega$ ,  $t \in (\sigma, \sigma+A)$  and  $x$  satisfies (1) on  $(\sigma, \sigma+A)$ . Notice this definition implies that  $D(t, x_t)$  and not  $x(t)$  is continuously differentiable on  $(\sigma, \sigma+A)$ . For a given  $\sigma \in R$ ,  $\phi \in C$ ,  $(\sigma, \phi) \in \Omega$ , we say  $x(\sigma, \phi)$  is a solution of (1) with initial value  $(\sigma, \phi)$  if there is an  $A > 0$  such that  $x(\sigma, \phi)$  is a solution of (1) on  $[\sigma-r, \sigma+A)$  and  $x_\sigma(\sigma, \phi) = \phi$ .

Our objective is to study the relationship between the

uniform asymptotic stability of the linear neutral differential equation

$$\frac{d}{dt} D(t, x_t) = f(t, x_t) \quad (2)$$

and the perturbed equation

$$\frac{d}{dt} [D(t, x_t) - G(t, x_t)] = f(t, x_t) + F(t, x_t), \quad (3)$$

where  $D(t, x_t) = \phi(0) - g(t, \phi)$ ,  $g(t, \cdot)$ ,  $f(t, \cdot)$  are bounded linear operators from  $C$  into  $E$  for each fixed  $t$  in  $[0, \infty)$ ,  $g(t, \phi)$  is continuous for  $(t, \phi) \in [0, \infty) \times C$

$$g(t, \phi) = \int_{-r}^0 [d_{\theta} \mu(t, \theta)] \phi(\theta), \quad f(t, \phi) = \int_{-r}^0 [d_{\theta} \eta(t, \theta)] \phi(\theta)$$

$$|g(t, \phi)| \leq K |\phi| \quad |f(t, \phi)| \leq l(t) |\phi|, \quad (t, \phi) \in [0, \infty) \times C$$

for some non-negative constant  $K$ , continuous non-negative function  $l$  and  $\mu(t, \cdot)$ ,  $\eta(t, \cdot)$  are  $n \times n$  matrix functions of bounded variation on  $[-r, 0]$ . We also assume that  $g$  is uniformly non-atomic at zero, that is, there exists a continuous, non-negative, non-decreasing function  $\gamma(s)$  for  $s$  in  $[0, r]$  such that

$$\gamma(0) = 0 \quad \left| \int_{-s}^0 [d_{\theta} \mu(t, \theta)] \phi(\theta) \right| \leq \gamma(s) |\phi|.$$

Throughout the paper, we assume that  $D - G, F$  satisfy

enough smoothness conditions to ensure that a solution of (3) exist through each point  $(\sigma, \phi) \in [0, \infty) \times C$ , is unique, depends continuously upon  $(\sigma, \phi)$  and can be continued to the right as long as the trajectory remains in a bounded set in  $[0, \infty) \times C$ . Sufficient conditions for these properties to be true are contained in [2].

Basic to this investigation is the variation of constants formula given in [1]. If the solution  $x_t(\sigma, \phi)$  of the linear system is designated by  $T(t, \sigma)\phi$ , then there is an  $n \times n$  matrix function  $B(t, s)$  defined for  $0 \leq s \leq t + r$ ,  $t \in [0, \infty)$ , continuous in  $s$  from the right, of bounded variation in  $s$ ,  $B(t, s) = 0$ ,  $t \leq s \leq t + r$ , such that the solution  $x(\sigma, \phi)$  of (3) is given by

$$x_t(\sigma, \phi) = T(t, \sigma)\phi + \int_{\sigma}^t [-[d_s B_t(\cdot, s)]G(s, x_s) + B_t(\cdot, s)F(s, x_s)]ds, \quad t \geq \sigma. \quad (4)$$

Furthermore, by [1], if the solution  $x = 0$  of (6) is uniformly asymptotically stable, there are constants  $M \geq 1$ ,  $\alpha > 0$ , such that

$$\begin{aligned} |T(t, \sigma)\phi| &\leq Me^{-\alpha(t-\sigma)}|\phi|, \quad t \geq \sigma \geq 0, \phi \in C, \\ |B_t(\cdot, s)| &\leq Me^{-\alpha(t-s)}, \quad t \geq s \geq 0 \\ \int_{\sigma}^s |d_u B_t(\cdot, u)| &\leq Me^{-\alpha(t-s)}, \quad t \geq s \geq \sigma \geq 0. \end{aligned} \quad (5)$$

In the following we will also assume that

$$G = G_1 + G_2, \quad F = F_1 + F_2 \quad (6)$$

where

$$\begin{aligned} |F_1(t, \phi)| &\leq v(t)|\phi| \\ |G_1(t, \phi)| &\leq \pi(t)|\phi|, \quad t \geq 0, \quad \phi \in C \end{aligned} \quad (7)$$

where  $\pi(t), v(t)$  are continuous,  $\pi(t), \int_t^{t+1} v(s)ds$  are bounded for  $t \geq 0$  and for any  $\varepsilon > 0$  there is a  $\delta(\varepsilon) > 0$  such that

$$|F_2(t, \phi)| \leq \varepsilon|\phi|, \quad |G_2(t, \phi)| \leq \varepsilon|\phi|, \quad t \geq 0, \quad |\phi| < \delta(\varepsilon). \quad (8)$$

We can now prove the following

Theorem. Suppose  $F_1, G_1$  satisfy (7) and  $F_2, G_2$  satisfy (8). If system (2) is uniformly asymptotically stable, then there is a  $\zeta_0, 0 < \zeta_0 < 1$  such that for any  $p > 0, 0 < \zeta < \zeta_0$  there are constants  $v_0 > 0, M_0 > 0, s_0 > 0$ , such that if

$$\pi(t) < M_0, \quad t \geq s_0 \quad (9)$$

$$\frac{1}{p} \int_t^{t+p} v(s)ds \leq \zeta v_0, \quad t \geq 0, \quad (10)$$



then the solution  $x = 0$  of (3) is uniformly asymptotically stable.

Proof. Let  $R^+ = [0, \infty)$ . The boundedness hypotheses on  $\pi(t)$ ,  $\int_t^{t+1} v(s)ds$  and using an argument very similar to the one in lemma 1, of [3] imply for any  $\beta > 0$ , there are  $\delta_1(\beta) > 0$ ,  $M_1(\beta) > 0$  such that for any  $\sigma \in R^+$  the solution  $x = x(\sigma, \phi)$  of (1.1) through  $(\sigma, \phi)$  satisfies  $|x_t(\sigma, \phi)| \leq M_1(\beta)|\phi|$  for  $\sigma \leq t \leq \sigma + 2\beta$ , provided that  $|\phi| \leq \delta_1(\beta)$ . From the hypothesis of uniform asymptotic stability there are constants  $M \geq 1$ ,  $\alpha > 0$ , such that  $B$  and  $T$  in (4) satisfy (5).  $\eta$   $e$   
 $0 < \zeta < 1/(2M-1)$ . Then  $\zeta < 1$  and  $\zeta < (1+\zeta)/2M$ . Let  $M_2(\beta, \zeta) = \max [M(1+\pi^*(0) + \epsilon), M_1(\beta)]/2/(1-\zeta)$ . Choose  $M_0 > 0$ ,  $\beta > 0$ ,  $\epsilon > 0$  such that

$$\eta \stackrel{\text{def}}{=} M\pi^*(0)e^{-\alpha\beta} + M_2(\beta, \zeta)M_0 + M_2(\beta, \zeta)\epsilon(1+\alpha^{-1}) + \zeta < (1+\zeta)/2M, \quad (11)$$

where  $\pi^*(s) = \sup_{s \leq t} \pi(t)$ . The choice of  $M_0, \beta, \epsilon$  satisfying (11) can be made in the following way. First choose  $\beta$  so that

$$M\pi^*(0)e^{-\alpha\beta} < (1+\zeta)/6M - \zeta/3,$$

then choose  $M_0$  so that

$$M_2(\beta, \zeta)M_0 < (1+\zeta)/6M - \zeta/3$$

and finally choose  $\varepsilon$  so that

$$M_2(\beta, \xi)\varepsilon(1+\alpha^{-1}) < (1+\xi)/6M - \xi/3.$$

Let  $s_0 = \sigma + \beta$  and suppose (9) is satisfied.

From the hypotheses on  $F_2, G_2$ , for the above  $\varepsilon > 0$ , there is a  $\delta_2(\varepsilon) > 0$  such that

$$|F_2(t, \phi)| \leq \varepsilon|\phi|, \quad |G_2(t, \phi)| \leq \varepsilon|\phi|$$

for  $|\phi| < \delta_2(\varepsilon)$ . Choose  $\delta > 0$  such that

$$M_2(\beta, \xi)\delta < \min(\delta_1(\beta), \delta_2(\varepsilon)).$$

For any  $p > 0$ , choose  $v_0$  so that

$$pM_2(\beta, \xi)v_0 = (e^{\alpha p} - 1)/(2e^{\alpha p} - 1)$$

and suppose (10) is satisfied for this  $v_0$ .

If  $k = k(t-\sigma)$  is the integer such that  $kp \leq t - \sigma < (k+1)p$  then

$$\begin{aligned}
\int_{\sigma}^t e^{-\alpha(t-u)} v(u) du &= \int_{\sigma+kp}^t e^{-\alpha(t-u)} v(u) du + \sum_{j=0}^{k-1} \int_{\sigma+jp}^{\sigma+(j+1)p} e^{-\alpha(t-u)} v(u) du \\
&\leq p \zeta v_0 + \sum_{j=0}^{k-1} e^{-\alpha(t-\sigma-jp-p)} p \zeta v_0 \\
&= \left[ 1 + e^{-\alpha(t-\sigma-p)} \frac{1-e^{\alpha kp}}{1-e^{\alpha p}} \right] p \zeta v_0 \\
&= \left[ 1 + \frac{e^{\alpha p}}{e^{\alpha p}-1} \left\{ e^{-\alpha(t-\sigma-kp)} - e^{-\alpha(t-\sigma)} \right\} \right] p \zeta v_0 \\
&\leq \frac{2e^{\alpha p}-1}{e^{\alpha p}-1} p \zeta v_0 \\
&= \frac{\zeta}{M_2(\beta, \zeta)}
\end{aligned}$$

or

$$M_2(\beta, \zeta) \int_{\sigma}^t e^{-\alpha(t-u)} v(u) du \leq \zeta. \quad (12)$$

Furthermore, since  $M \leq (1-\zeta)M_2(\beta, \zeta)/2$ , we have

$$M \int_{\sigma}^t e^{-\alpha(t-u)} v(u) du \leq \frac{M \zeta}{M_2(\beta, \zeta)} \leq \frac{(1-\zeta)\zeta}{2(1+\pi^*(0)+e)} \leq \frac{(1-\zeta)\zeta}{2} < \zeta. \quad (13)$$

Let us write the variation of constants formula for the solution  $x = x(\sigma, \phi)$  of (3) in the form

$$\begin{aligned}
x_t = & T(t, \sigma)\phi + \left( \int_{\sigma}^s + \int_s^t \right) [d_u B_t(\cdot, u)] [G_1(\sigma, \phi) - G_1(u, x_u)] \\
& + \int_{\sigma}^t B_t(\cdot, u) F_1(u, x_u) du \\
& + \int_{\sigma}^t [d_u B_t(\cdot, u)] [G_2(\sigma, \phi) - G_1(u, x_u)] \\
& + \int_{\sigma}^t B_t(\cdot, u) F_2(u, x_u) du
\end{aligned} \tag{14}$$

for  $\sigma \leq s \leq t$ .

Therefore, as long as  $|x_t| \leq \delta_2(\epsilon)$ , it follows from (5) and the hypotheses on  $F, G$ , that

$$\begin{aligned}
|x_t| \leq & M(1+\pi^*(0) + \epsilon)|\phi| e^{-\alpha(t-\sigma)} \\
& + M[\pi^*(\sigma) e^{-\alpha(t-\sigma)} + \pi^*(s) + \epsilon(1+\alpha^{-1}) + \int_{\sigma}^t e^{-\alpha(t-u)} v(u) du] \sup_{\sigma \leq u \leq t} |x_u|
\end{aligned}$$

for  $\sigma \leq s \leq t$ . Take  $s = s_0 = \sigma + \beta$  and use our estimates on  $\beta, \epsilon, M_0$  and (9), (10), (11), then

$$\begin{aligned}
|x_t| & \leq M(1+\pi^*(0) + \epsilon)|\phi| + \eta \sup_{\sigma \leq u \leq t} |x_u| \\
& \leq \frac{1-\zeta}{2} M_2 |\phi| + \eta \sup_{\sigma \leq u \leq t} |x_u|
\end{aligned}$$

for  $t \geq \sigma + 2\beta$  as long as  $|x_t| \leq \delta_2(\epsilon)$ . If  $\delta$  is chosen as above and  $|\phi| < \delta$ , then we know that

$$|x_t| \leq M_1(\beta) |\phi| \leq (1-\zeta) M_2(\beta, \epsilon) |\phi| / 2 \leq M_2(\beta, \epsilon) |\phi| \leq \delta_2(\epsilon)$$

for  $\sigma \leq t \leq \sigma + 2\beta$ . Therefore,

$$|x_t| \leq \frac{1-\zeta}{2} M_2(\beta, \varepsilon) |\phi| + \eta \sup_{\sigma \leq u \leq t} |x_u|$$

for all  $t \geq \sigma$  for which  $|x_t| \leq \delta_2(\varepsilon)$ . Consequently, for  $|x_t| \leq \delta_2(\varepsilon)$ ,

$$\begin{aligned} \sup_{\sigma \leq u \leq t} |x_u| &\leq \frac{1-\zeta}{2(1-\eta)} M_2(\beta, \varepsilon) |\phi| \\ &\leq \frac{M(1-\zeta)}{2M-1-\zeta} M_2(\beta, \varepsilon) |\phi| \\ &\leq M_2(\beta, \varepsilon) |\phi| \leq \delta_2(\varepsilon) \end{aligned} \quad (15)$$

for  $|\phi| < \delta$  since  $M \geq 1$ . The continuation theorem implies that  $x(t)$  is defined for  $t \geq \sigma - r$ , (15) is satisfied for  $t \geq \sigma$  and the solution  $x = 0$  of (3) is uniformly stable.

For  $s = s_0 = \sigma + \beta$  in (14) and  $t \geq \sigma + 2\beta$ , it follows from (14) and the estimates (15) and (13) that

$$\begin{aligned} |x_t| &\leq M \left\{ (1 + \pi^*(0) + \varepsilon) e^{-\alpha(t-\sigma)} + \pi^*(\sigma) M e^{-\alpha(t-s_0)} + \pi^*(s_0) M_2(\beta, \zeta) \right. \\ &\quad \left. + M_2(\beta, \zeta) \varepsilon (1 + \alpha^{-1}) + \zeta \right\} |\phi| \\ &\leq M \left\{ (1 + \pi^*(0) + \varepsilon) e^{-\alpha(t-\sigma)} + \eta \right\} |\phi| \\ &\leq M \left\{ (1 + \pi^*(0) + \varepsilon) e^{-\alpha(t-\sigma)} + \frac{1+\zeta}{2M} \right\} |\phi|. \end{aligned}$$

For any  $\delta_0$ ,  $(1+\xi)/2 < \delta_0 < 1$ , choose  $T \geq 2\beta$  so large that

$$Me^{-\alpha T}(1+\pi^*(0) + \epsilon) + \frac{1+\xi}{2} < \delta_0.$$

For  $t \geq \sigma + T$ , it follows that

$$|x_t| \leq \delta_0 |\phi|.$$

Since  $T$  is independent of  $\sigma$  and  $\phi$ , this clearly implies exponential asymptotic stability and proves the theorem.

In [1], asymptotic stability theorems of the above type were proved for systems which contained either terms of the form  $F_1, G_1$  or  $F_2, G_2$  but not both simultaneously. In addition to combining these results into one, the more significant part of the above theorem is the fact that uniform asymptotic stability is proved under the weak hypothesis (9). In [1], it was assumed that  $\pi(t) \rightarrow 0$  as  $t \rightarrow \infty$ .

## References

1. J. K. Hale and M. A. Cruz, Asymptotic behavior of neutral functional differential equations, Archives for Rational Mechanics and Analysis, V. 34, No. 5, 1969, p. 331-353.
2. J. K. Hale and M. A. Cruz, Existence, uniqueness and continuous dependence for hereditary systems, Annali di Mat. Pura Appl., Serie IV - Tomo LXXXV - 1970.
3. J. K. Hale and K. R. Meyer, A class of functional equations of neutral type, Memoirs of the American Math. Society, No. 76, 1967.

## Footnotes

A.M.S. subject classification number: Primary 3475, secondary 3451.

Key phrases: Functional differential equations of neutral type, Banach space, topology of uniform convergence, uniform asymptotic stability, bounded operator, bounded variation, uniformly nonatomic, trajectory, variation of constants formula, uniform stability, exponential asymptotic stability.