# ON TYPE NUMBER OF REAL HYPERSURFACES IN $\boldsymbol{P}_{n}(\boldsymbol{C})$ 

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## Introduction.

Let $P_{n}(\boldsymbol{C})$ denote an $n$-dimensional complex projective space with the FubiniStudy metric of constant holomorphic sectional curvature $4 c$. Real hypersurfaces in $P_{n}(\boldsymbol{C})$ have been studied by many differential geometers (See [2], [3], [4], [5] and [6]).

In particular, as for a problem with respect to the typec number $t$, i. e., the rank of the second fundamental form of real hypersurfaces $M$ in $P_{n}(\boldsymbol{C})$, R. Takagi showed in [6] that there is a point $p$ on $M$ such that $t(p) \geqq 2$, and M. Kimura and S. Maeda [4] gave an example of real hypersurfaces in $P_{n}(\boldsymbol{C})$ satisfying $t=2$, which is non-complete. In this paper we shall prove

Theorem 1. Let $M$ be a complete real hypersurface in $P_{n}(\boldsymbol{C})(n \geqq 3)$. Then there exists a point $p$ on $M$ such that $t(p) \geqq 3$.

REMAPK. It is known that a certain geodesic hypersphere in $P_{2}(\boldsymbol{C})$ has a property $t=2$ (cf. [2], [7]). Thus the assumption $n \geqq 3$ in Theorem 1 can not be removed.

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## 1. Preliminaries.

Let $M$ be a real hypersurface in $P_{n}(\boldsymbol{C})(n \geqq 2)$. Let $\left\{e_{1}, \cdots, e_{2 n}\right\}$ be a local field of orthonormal frame in $P_{n}(\boldsymbol{C})$ such that, restricted to $M, e_{1}, \cdots, e_{2 n-1}$ are tangent to $M$. Denote its dual frame field by $\theta_{1}, \cdots, \theta_{2 n}$. We use the following convention on the range of indices unless otherwise stated; $A, B, \cdots,=1, \cdots$, $2 n$ and $i, j, \cdots,=1, \cdots, 2 n-1$.

The connection forms $\theta_{A B}$ are defined as the 1 -forms satisfying

[^0]\[

$$
\begin{equation*}
d \theta_{A}=-\Sigma \theta_{A B} \wedge \theta_{B}, \quad \theta_{A B}+\theta_{B A}=0 \tag{1.1}
\end{equation*}
$$

\]

Restrict the forms under consideration to $M$. Then, we set $\theta_{2 n}=0$ and the forms $\theta_{2 n, i}$ can be written as

$$
\begin{equation*}
\phi_{i} \equiv \theta_{2 n, i}=\Sigma h_{i j} \theta_{j}, \quad h_{i j}=h_{j i} . \tag{1.2}
\end{equation*}
$$

The quadratic form $\Sigma h_{i j} \theta_{i} \otimes \theta_{j}$ is called the second fundamental form of $M$ with direction of $e_{2 n}$. The curvature forms $\Theta_{i j}$ of $M$ are defined by

$$
\begin{equation*}
\Theta_{i j}=d \theta_{i j}+\Sigma \theta_{i k} \wedge \theta_{k j} \tag{1.3}
\end{equation*}
$$

We denote by $J$ the complex structure of $P_{n}(\boldsymbol{C})$, and put

$$
J e_{i}=\Sigma J_{j i} e_{j}+f_{i} e_{2 n}
$$

Then the almost contact structure ( $J_{i j}, f_{k}$ ) satisfies

$$
\begin{gather*}
\left\{\begin{array}{l}
\Sigma J_{i k} J_{k j}=f_{i} f_{j}-\delta_{i j}, \quad \sum f_{j} J_{j i}=0 \\
\Sigma f_{i}^{2}=1, \quad J_{i j}+J_{j i}=0 .
\end{array}\right.  \tag{1.4}\\
\left\{\begin{array}{l}
d J_{i j}=\Sigma\left(J_{i k} \theta_{k j}-J_{j k} \theta_{k i}\right)-f_{i} \phi_{j}+f_{j} \phi_{i}, \\
d f_{i}=\Sigma\left(f_{j} \theta_{j i}-J_{j i} \phi_{j}\right) .
\end{array}\right. \tag{1.5}
\end{gather*}
$$

The equations of Gauss and Codazzi are given by

$$
\begin{gather*}
\Theta_{i j}=\phi_{i} \wedge \phi_{j}+c \theta_{i} \wedge \theta_{j}+c \Sigma\left(J_{i k} J_{j l}+J_{i j} J_{k l}\right) \theta_{k} \wedge \theta_{l},  \tag{1.6}\\
d \phi_{i}=-\Sigma \phi_{j} \wedge \theta_{j i}+c \Sigma\left(f_{i} J_{j k}+f_{j} J_{i k}\right) \theta_{j} \wedge \theta_{k}, \tag{1.7}
\end{gather*}
$$

respectively.

## 2. Lemmas.

Let $M$ be a real hypersurface in $P_{n}(\boldsymbol{C})$. We choose an arbitary point $p$ in $M$, and use the following convention on the range of indices; $a, b, \cdots,=1, \cdots$, $t(p)$ and $r, s, \cdots,=t(p)+1, \cdots, 2 n-1$. Then we can take a field $\left\{e_{1}, \cdots, e_{2 n}\right\}$ of orthonormal frame on a neighborhood of $p$ in such a way that the 1 -forms $\phi_{i}$ can be written as

$$
\left\{\begin{array}{l}
\phi_{a}=\sum h_{b a} \theta_{b}, \quad h_{a b}=h_{b a},  \tag{2.1}\\
\phi_{r}=0,
\end{array}\right.
$$

at $p$. We call such a field $\left\{e_{1}, \cdots, e_{2 n}\right\}$ to be associated with a point $p$.
Under this notation we have
Lemma 2.1. Assume that $J_{r s}(p)=0$ at a point $p$ on $M$. Then $t(p) \geqq n-1$. Furthermore, the equality holds if and only if $f_{a}=0$ and $J_{a b}=0$ at $p$.

Proof. By (1.4) we have

$$
\begin{align*}
& \Sigma_{b} J_{a b}^{2}+\Sigma_{r} J_{a r}^{2}+f_{a}^{2}=1,  \tag{2.2}\\
& \Sigma_{a} J_{r a}^{2}+f_{r}^{2}=1 \tag{2.3}
\end{align*}
$$

Summing up (2.2) on $a$, and (2.3) on $r$, we have

$$
\begin{align*}
& \Sigma_{a, b} J_{a b}^{2}+\Sigma_{a, r} J_{a r}^{2}+\Sigma_{a} f_{a}^{2}=t(p),  \tag{2.4}\\
& \Sigma_{a, r} J_{a r}^{2}+\Sigma_{r} f_{r}^{2}=2 n-1-t(p) . \tag{2.5}
\end{align*}
$$

Substituting (2.5) into (2.4) and making use of $\Sigma_{a} f_{a}^{2}+\Sigma_{r} f_{r}^{2}=1$, we have

$$
\sum_{a, b} J_{a b}^{2}+2 \sum_{a} f_{a}^{2}=2(t(p)-(n-1)) \geqq 0,
$$

and so our assertion follows.
This concludes the proof.
Now we consider a point $p$ where the type number $t$ attains the maximal value, say $T$. Then there is a neighborhood $U$ of $p$, on which the function $t$ is constant and the equation (2.1) holds.

Put $\theta_{a r}=\sum A_{a r b} \theta_{b}+\sum B_{a r s} \theta_{s}$. Then, taking the exterior derivative of $\phi_{r}=0$ and using (1.7), we have

$$
\sum h_{a b} \theta_{b} \wedge \theta_{a r}-c \Sigma\left(f_{r} J_{i j}+f_{i} J_{r j}\right) \theta_{i} \wedge \theta_{j}=0,
$$

from which we have

$$
\begin{align*}
& \Sigma\left(h_{a c} A_{c r b}-h_{b c} A_{c r a}\right)-c f_{a} J_{r b}+c f_{b} J_{r a}-2 c f_{r} J_{a b}=0,  \tag{2.6}\\
& \Sigma h_{a b} B_{b r s}-c f_{a} J_{r s}+c f_{s} J_{r a}-2 c f_{r} J_{a s}=0,  \tag{2.7}\\
& f_{s} J_{r t}-f_{t} J_{r s}+2 f_{r} J_{s t}=0 . \tag{2.8}
\end{align*}
$$

It is easy to see that (2.8) is reduced to

$$
\begin{equation*}
f_{r} J_{s t}=0 . \tag{2.9}
\end{equation*}
$$

Similarly, taking the exterior derivative of $\phi_{a}=\sum h_{b a} \theta_{b}$ and using the equation (1.7) of Codazzi, we have

$$
\begin{aligned}
& \Sigma_{b}\left\{d h_{a b}-\sum_{c}\left(h_{a c} \theta_{c b}+h_{c b} \theta_{c a}-\sum_{r} h_{a c} A_{c r b} \theta_{r}-c f_{b} J_{a c} \theta_{c}\right.\right. \\
& \left.\left.\quad+c f_{c} J_{a b} \theta_{c}-2 c f_{a} J_{b c} \theta_{c}\right)+c \sum_{r}\left(f_{b} J_{a r} \theta_{r}-f_{r} J_{a b} \theta_{r}+2 f_{a} J_{b r} \theta_{r}\right)\right\} \wedge \theta_{b}=0 .
\end{aligned}
$$

Therefore, we can put

$$
\begin{align*}
& d h_{a b}-\Sigma_{c}\left(h_{a c} \theta_{c b}+h_{c b} \theta_{c a}-\Sigma_{r} h_{a c} A_{c r b} \theta_{r}-c f_{b} J_{a c} \theta_{c}+c f_{c} J_{a b} \theta_{c}\right.  \tag{2.10}\\
& \left.\quad-2 c f_{a} J_{b c} \theta_{c}\right)+c \Sigma_{r}\left(f_{b} J_{a r} \theta_{r}-f_{r} J_{a b} \theta_{r}+2 f_{a} J_{b r} \theta_{r}\right)=\sum C_{a b c} \theta_{c},
\end{align*}
$$

where $C_{a b c}=C_{a c b}=C_{b a c}$.

Under such a situation we have
Lemma 2.2. If $J_{r s}=0$ on $U$, then $T \geqq n$ on $U$.
Proof. If $T<n$, then by Lemma 2.1 we have $T=n-1$, and $f_{a}=0$ on $U$. For a suitable choice of a field $\left\{e_{r}\right\}$ of orthonormal frames, if necessary, we may set $f_{2 n-1}=1$ and $f_{r}=0$ for $r=n, \cdots, 2 n-2$. Then from (1.5) we have

$$
0=d f_{r}=-\Sigma J_{a r} \phi_{a} .
$$

But, since rank $J=2 n-2$, we have $\operatorname{det}\left(J_{a r}\right) \neq 0(a=1, \cdots, n-1, r=n, \cdots, 2 n-2)$. Thus the above equation implies $\phi_{a}=0$, which contradicts the fact that $\operatorname{det}\left(h_{a b}\right)$ $\neq 0$.

This concludes the proof.
In the remainder of this section we restrict the forms under consideration to the following open set $V_{T}$ defined by

$$
V_{T}=\left\{p \in M \mid J_{r s}(p) \neq 0, t(p)=T\right\},
$$

where $J_{r s}(p) \neq 0$ means " $J_{r s}(p) \neq 0$ for some $r, s=T+1, \cdots, 2 n-1$ ". First from (2.9) we have $f_{r}=0$. Thus we may set $f_{1}=1$, and $f_{a}=0$ for $a \geqq 2$. Hence we have

$$
\begin{equation*}
J_{1 a}=0, \quad J_{1 r}=0 . \tag{2.11}
\end{equation*}
$$

Furthermore, $d f_{a}=0$ and $d f_{r}=0$ give

$$
\begin{align*}
& \theta_{1 a}=\sum J_{b a} \phi_{b},  \tag{2.12}\\
& A_{1 r a}=\sum h_{a b} J_{b r},  \tag{2.13}\\
& B_{1 r s}=0 . \tag{2.14}
\end{align*}
$$

The equation (2.7) amounts to

$$
\begin{equation*}
\sum h_{a b} B_{b r s}=c f_{a} J_{r s} \tag{2.15}
\end{equation*}
$$

Lemma 2.3. $\operatorname{det}\left(h_{a b}\right)=0(a, b=2, \cdots, T)$ on $V_{T}$.
Proof. Here indices $a, b$ run from 2 to $T$. If $\operatorname{det}\left(h_{a b}\right) \neq 0$, then by (2.15) we have $B_{\text {ars }}=0$, which together with (2.14) gives $J_{r s}=0$. A contradiction to the fact $J_{r s}(p) \neq 0$ on $V_{T}$.

This concludes the proof.

## 3. Proof of Theorem 1.

We keep the notation in section 2. If $J_{r s}=0$ on a nonempty open set, then

Lemma 2. 2 proves Theorem 1. Therefore, we have only to consider the case where the open set $V_{T}$ defined in section 2 is not empty.

Assume $T=2$. Then we shall derive a contradiction. First by Lemma 2.3 we have $h_{22}=0$.

Now we put $F=h_{12}$. Then from (2.13) we have

$$
\begin{equation*}
A_{1 r 1}=F J_{2 r}, \quad A_{1 r 2}=0 . \tag{3.1}
\end{equation*}
$$

Put $a=1$ and $b=2$ in (2.6) to get

$$
\begin{equation*}
F A_{2 r 2}-F A_{1 r 1}-c J_{r 2}=0 . \tag{3.2}
\end{equation*}
$$

Then (3.1) and (3.2) give

$$
\begin{equation*}
F A_{2 r 2}=\left(F^{2}-c\right) J_{2 r} . \tag{3.3}
\end{equation*}
$$

According to (2.12), we have

$$
\theta_{12}=0 .
$$

Put $a=1$ and $b=2$ in (2.10). Then, together with (3.3) we find

$$
\begin{equation*}
d F+\left(F^{2}+c\right) \sum J_{2 r} \theta_{r}=\sum D_{12 a} \theta_{a}, \tag{3.4}
\end{equation*}
$$

where we have put $D_{12 a}=C_{12 a}-2 c J_{2 a}$.
Let $p$ be any point of $V_{2}$ and let $\alpha: I \rightarrow V_{2}$ be the maximal integral curve of the unit dual vector field $\Sigma J_{2 r} \theta_{r}$ on $V_{2}$ such that $\alpha(0)=p, \Sigma_{r} J_{2 r} \theta_{r}\left(\alpha^{\prime}(t)\right)=1$ and $D_{12 a} \theta_{a}\left(\alpha^{\prime}(t)\right)=0$, where $(0 \in) I$ denotes an open interval of $R$.

Assume that there exists $\sup I$, say $t_{0}$. Since $M$ is complete, we have a point $p_{0}=\lim _{t \rightarrow t_{0}} \alpha(t)$ on $M$. We assert $F\left(p_{0}\right)=\lim _{t \rightarrow t_{0}} F(\alpha(t))=0$. In order to prove this assertion, it suffices to show that $t\left(p_{0}\right) \leqq 1$, because $\operatorname{det}\left(h_{i j}\right)=-F^{2}$ by $h_{22}=0$ at $p_{0}$. For this we assume $t\left(p_{0}\right)=2$. Thus we can consider that our frame field $\left\{e_{i}\right\}$ is defined also on the neighborhood of $p_{0}$. Since $p_{0} \in \bar{V}_{2}, J_{r s}\left(p_{0}\right)=0$ for any $r, s \geqq 3$. Then by Lemma 2. 1 we have $t\left(p_{0}\right) \geqq n-1 \geqq 3$ for $n \geqq 4$, which is a contradiction. For a case where $n=3$ also by using Lemma 2.1 we get $J_{a b}=0$ and $f_{a}=0$ at $p_{0}$ for all $a, b=1,2$. This also contradicts to the fact that $f_{1}=1$ at $p_{0}$, which proves our assertion.

Now we shall show that $\inf I=-\infty$. Indeed, if there exists $t_{1}=\inf I$, then we find $\lim _{t \rightarrow t_{1}} F(\alpha(t))=0$ by an argument similar to the above. Thus there is a real number $t^{\prime}$ such that $t_{1}<t^{\prime}<t_{0}, d F=0$ at $\alpha\left(t^{\prime}\right)$. Then (3.4) gives $J_{2 r}=0$. From this together with $J_{1 r}=0$ in (2.11) it follows that rank $J \leqq 2 n-3$, which makes a contradiction to the fact that rank $J=2 n-2$.

Now the function $|F|$ defined on the interval $\left(-\infty, t_{0}\right)$ satisfies by (3.4)

$$
\frac{d|F|}{d t}=F^{2}+c \quad \text { or } \quad \frac{1}{F^{2}+c} \frac{d|F|}{d t}=1 .
$$

Solving the above differential equation, we have

$$
F(\alpha(t))=\sqrt{c} \tan \sqrt{c}\left(t-t_{0}\right),
$$

which is a contradiction, because $F(\alpha(t))$ is defined on ( $-\infty, t_{0}$ ) but the right hand side can not be defined at the points such that $\sqrt{c}\left(t-t_{0}\right)=(2 k+1) \pi / 2$, where $k$ is an integer.

For a case where $\sup I=\infty$, we can take a point $\alpha\left(t_{0}\right) \in V_{2}$ such that $F\left(\alpha\left(t_{0}\right)\right)$ $=F_{0} \neq 0$ for $t_{0}<\infty$. This case also contains the situation such that $F(\alpha(t))$ is defined on $(-\infty, \infty)$ and $\alpha(t)$ is contained in $V_{2}$. Using the similar method to the above, we also get

$$
F(\alpha(t))=\sqrt{c} \tan \sqrt{c}\left(t-t_{0}+s_{0}\right) \quad \text { on } \quad\left(-\infty, t_{0}\right]
$$

where we have put $\sqrt{c} s_{0}=\tan ^{-1}\left(F_{0} / \sqrt{c}\right)$. This also makes a contradiction as in the above case.

It completes the proof of Theorem 1.

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