# On Weak symmetries of Generalized Sasakian-Space-Forms 

## Research Article

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#### Abstract

The purpose of the paper is to study weakly symmetric and weakly Ricci-symmetric generalized Sasakian-space-forms. We consider the locally symmetric and recurrent type of weakly symmetric generalized Sasakian-space-forms. Also, locally Ricci-symmetric and Ricci-recurrent weakly Ricci-symmetric generalized Sasakian-space-forms are discussed.


Keywords. Generalized Sasakian-space-forms; Weakly symmetric; Weakly Ricci-symmetric; Specially weakly Ricci-symmetric

MSC. 53C15; 53C25
Received: November 27, 2014
Accepted: December 29, 2014
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## 1. Introduction

The notion of generalized Sasakian space forms was introduced and studied by P. Alegre et al. [1] with several examples. A generalized Sasakian-space-form is an almost contact metric manifold $M(\phi, \xi, \eta, g)$ whose curvature tensor is given by

$$
\begin{aligned}
R(X, Y) Z= & f_{1}\{g(Y, Z) X-g(X, Z) Y\}+f_{2}\{g(X, \phi Z) \phi Y-g(Y, \phi Z) \phi X+2 g(X, \phi Y) \phi Z\} \\
& +f_{3}\{\eta(X) \eta(Z) Y-\eta(Y) \eta(Z) X+g(X, Z) \eta(Y) \xi-g(Y, Z) \eta(X) \xi\},
\end{aligned}
$$

where $f_{1}, f_{2}, f_{3}$ are differentiable functions and $X, Y, Z$ are vector fields on $M$. In such case we will write the manifold as $M\left(f_{1}, f_{2}, f_{3}\right)$. This kind of manifolds appears as a natural generalization of the Sasakian-space-forms: $f_{1}=\frac{c+3}{4}$ and $f_{1}=f_{3}=\frac{c-1}{4}$, where $c$ denotes constant $\phi$-sectional curvature. The $\phi$-sectional curvature of generalized Sasakian-space-forms $M\left(f_{1}, f_{2}, f_{3}\right)$ is $f_{1}+3 f_{2}$. Moreover, cosymplectic space-forms and Kenmotsu space-forms also
consider as particular types of generalized Sasakian-space-forms. Generalized Sasakian-spaceforms have been studied by many authors. For example see $[2-4,6,9,9,10,12,14]$.

The notion of weakly symmetric and weakly Ricci-symmetric manifolds were introduced by L. Tamassy and T.Q. Binh ( [18] and [19]). These types of manifold were studied with different structures by several authors (see [7, 8, 11, 13, 15, 16]). In this connection, we would mention the works of Yadav and Suthar [20] on generalized Sasakian-space-forms.

The paper is organized as follows: Section 2 is devoted to preliminaries on generalized Sasakian-space-forms. In Section 3, we consider weakly symmetric generalized Sasakian-space-forms and study the characteristic properties of locally symmetric and recurrent spaces. Section 4 deals with the study on weakly Ricci-symmetric generalized Sasakian-space-forms. We study the characteristic properties of locally Ricci-symmetric and locally Ricci-recurrent spaces. Also, we show that special weakly Ricci-symmetric generalized Sasakian-space-forms cannot be locally Ricci-symmetric.

## 2. Preliminaries

In almost contact metric manifold we have [5]

$$
\begin{align*}
& \phi^{2}(X)=-X+\eta(X) \xi, \quad \phi \xi=0, \quad \eta(\xi)=1, \quad \eta(\phi X)=0,  \tag{2.1}\\
& g(X, \xi)=\eta(X), \quad g(\phi X, \phi Y)=g(X, Y)-\eta(X) \eta(Y),  \tag{2.2}\\
& g(\phi X, Y)=-g(X, \phi Y), \quad g(\phi X, X)=0 . \tag{2.3}
\end{align*}
$$

Again, for a $(2 n+1)$-dimensional generalized Sasakian-space-form we have [1]

$$
\begin{align*}
& S(X, Y)=\left(2 n f_{1}+3 f_{2}-f_{3}\right) g(X, Y)-\left(3 f_{2}+(2 n-1) f_{3}\right) \eta(X) \eta(Y),  \tag{2.4}\\
& R(X, Y) \xi=\left(f_{1}-f_{3}\right)[\eta(Y) X-\eta(X) Y],  \tag{2.5}\\
& R(\xi, X) Y=\left(f_{1}-f_{3}\right)[g(X, Y) \xi-\eta(Y) X],  \tag{2.6}\\
& S(X, \xi)=2 n\left(f_{1}-f_{3}\right) \eta(X), \tag{2.7}
\end{align*}
$$

where $R$ and $S$ are the curvature tensor and the Ricci tensor of the space-form, respectively.

## 3. Weakly Symmetric Generalized Sasakian-Space-Forms

In this section, we study the characterizations of locally symmetric and recurrent spaces.
Definition 3.1. Generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ is called weakly symmetric if there exists 1 -forms $A, B, C, D$ and their curvature tensor $R$ satisfies the condition

$$
\begin{align*}
\left(\nabla_{X} R\right)(Y, Z, V)= & A(X) R(Y, Z, V)+B(Y) R(X, Z, V)+C(Z) R(Y, X, V) \\
& +D(V) R(Y, Z, X)+g(R(Y, Z, V), X) P \tag{3.1}
\end{align*}
$$

Definition 3.2. A weakly symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ is said to be locally symmetric, if

$$
\nabla R=0
$$

Suppose a weakly symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ is locally symmetric with $f_{1}-f_{3} \neq 0$. Then from (3.1) and Definition 3.2, we have

$$
\begin{equation*}
A(X) S(Z, V)+B(R(X, Z) V)+C(Z) S(X, V)+D(V) S(X, Z)+E(R(X, V) Z)=0 \tag{3.2}
\end{equation*}
$$

Replacing $V$ by $\xi$ in (3.2) and then using (2.5) and (2.7) we obtain

$$
\begin{align*}
& \left(f_{1}-f_{3}\right)[(n-1)\{A(X) \eta(Z)+C(Z) \eta(X)\}+\{B(X) \eta(Z)-B(Z) \eta(X)+E(X) \eta(Z)\} \\
& \quad+E(\xi) g(X, Z)]+D(\xi) S(X, Z)=0 \tag{3.3}
\end{align*}
$$

Putting $X=Z=\xi$ in (3.3), we can easily get

$$
(n-1)\left(f_{1}-f_{3}\right)[A(\xi)+C(\xi)+D(\xi)]=0
$$

which implies that

$$
\begin{equation*}
A(\xi)+C(\xi)+D(\xi)=0 . \tag{3.4}
\end{equation*}
$$

Next, plugging $Z$ in (3.2) and then using (2.5) and (2.7) we have

$$
\begin{align*}
& \left(f_{1}-f_{3}\right)[(n-1)\{A(X) \eta(V)+D(V) \eta(X)\}+\{B(X) \eta(V)+E(X) \eta(V)-E(V) \eta(X) \\
& \quad-B(\xi) g(X, V)\}]+C(\xi) S(X, V)=0 \tag{3.5}
\end{align*}
$$

Setting $V=\xi$ in (3.5), we get

$$
\begin{align*}
& \left(f_{1}-f_{3}\right)[(n-1)\{A(X)+D(\xi) \eta(X)\}+\{B(X)+E(X)-E(\xi) \eta(X) \\
& \quad-B(\xi) \eta(X)\}+(n-1) C(\xi) \eta(X)]=0 \tag{3.6}
\end{align*}
$$

Similarly, if we set $X=\xi$ in (3.5) we obtain

$$
\begin{equation*}
\left(f_{1}-f_{3}\right)[(n-1)\{A(\xi) \eta(V)+D(V)\}+\{E(\xi) \eta(V)-E(V)\}+(n-1)\{C(\xi) \eta(V)\}]=0 . \tag{3.7}
\end{equation*}
$$

Replacing $V$ by $X$ in (3.7), we have

$$
\begin{equation*}
\left(f_{1}-f_{3}\right)[(n-1)\{A(\xi) \eta(V)+D(V)\}+\{E(\xi) \eta(V)-E(V)\}+(n-1)\{C(\xi) \eta(V)\}]=0 . \tag{3.8}
\end{equation*}
$$

Adding (3.6) and (3.8) and using (3.4), we have

$$
\begin{equation*}
\left(f_{1}-f_{3}\right)[(n-1)\{A(X)-A(\xi) \eta(X)\}+\{B(X)-B(\xi) \eta(X)\}+\{D(X)-D(\xi) \eta(X)\}]=0 . \tag{3.9}
\end{equation*}
$$

Next, putting $X=\xi$ in (3.3), we have

$$
\begin{equation*}
\left(f_{1}-f_{3}\right)[(n-1)\{C(Z)-C(\xi) \eta(Z)\}+\{B(\xi) \eta(Z)-B(Z)\}]=0 . \tag{3.10}
\end{equation*}
$$

Replacing $Z$ by $X$ in above equation and then adding with equation (3.9), we get

$$
A(X)+C(X)+D(X)=0
$$

Hence we are able to state the following;

Theorem 3.1. If a weakly symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ with $f_{1}-f_{3} \neq 0$ is locally symmetric, then the sum of the associated 1 -forms $A, C$ and $D$ is zero everywhere.

Definition 3.3. A weakly symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ is said to recurrent if

$$
\nabla R=A \otimes R
$$

On the other hand, let us consider a weakly symmetric generalized Sasakian space forms $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ with $f_{1}-f_{3} \neq 0$ is recurrent, then from (3.1) and Definition 3.3 we find,

$$
\begin{equation*}
B(Y) R(X, Z, V)+C(Z) R(Y, X, V)+D(V) R(Y, Z, X)+g(R(Y, Z, V), X) \rho=0 \tag{3.11}
\end{equation*}
$$

Next, putting $X=Y=Z=V=\xi$ in (3.11) and then using (2.5), we obtain

$$
C(\xi)+D(\xi)=0 .
$$

Further proceeding as in the proof of the previous theorem and using the fact that $C(\xi)+D(\xi)=0$, obviously, one can get $C(X)+D(X)=0$ for any vector field $X$ on $M\left(f_{1}, f_{2}, f_{3}\right)$, so that $C+D=0$ everywhere on $M$. Hence we state the following result:

Theorem 3.2. If a weakly symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ with $f_{1}-f_{3} \neq 0$ is recurrent, then the 1 -forms $C$ and $D$ are in the opposite direction.

## 4. Weakly Ricci-Symmetric Generalized Sasakian Space Forms

In this section, we investigate characterizations of locally Ricci-symmetric and Ricci-recurrent spaces.

Definition 4.1. A generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ called weakly Riccisymmetric if there exist 1 -forms $\alpha, \beta$ and $\gamma$ and their Ricci tensor $S$ of type $(0,2)$ satisfies the conditions

$$
\begin{equation*}
\left(\nabla_{X} S\right)(Y, Z)=\alpha(X) S(Y, Z)+\beta(Y) S(X, Z)+\gamma(Z) S(Y, X) \tag{4.1}
\end{equation*}
$$

for all vector fields $X, Y$ and $Z$ on $M\left(f_{1}, f_{2}, f_{3}\right)$.
Definition 4.2. A weakly Ricci-symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ is said to be locally Ricci-symmetric if

$$
\nabla S=0
$$

Let us consider a weakly Ricci-symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)$ $(n>2)$ with $f_{1}-f_{3} \neq 0$ which is locally Ricci-symmetric. Then by virtue of (4.1) and Definition4.2, we have

$$
\begin{equation*}
\alpha(X) S(Y, Z)+\beta(Y) S(X, Z)+\gamma(Z) S(Y, X)=0 . \tag{4.2}
\end{equation*}
$$

Setting $X=Y=Z=\xi$ in (4.2), we find

$$
\begin{equation*}
\alpha(\xi)+\beta(\xi)+\gamma(\xi)=0 . \tag{4.3}
\end{equation*}
$$

Now taking $Y=Z=\xi$ in (4.2) and then using (2.7), we get

$$
\begin{equation*}
\alpha(X)-\alpha(\xi) \eta(X)=0 . \tag{4.4}
\end{equation*}
$$

In a similar manner, we can obtain

$$
\begin{equation*}
\beta(X)-\beta(\xi) \eta(X)=0 \tag{4.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\gamma(X)-\gamma(\xi) \eta(X)=0 . \tag{4.6}
\end{equation*}
$$

Adding (4.4), (4.5) and (4.6) and using (4.3) we obtain

$$
\begin{equation*}
\alpha(X)+\beta(X)+\gamma(X)=0, \tag{4.7}
\end{equation*}
$$

for all $X$ on $M\left(f_{1}, f_{2}, f_{3}\right)$. Thus we state following:
Theorem 4.1. In weakly Ricci-symmetric generalized Sasakian-space-form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ with $f_{1}-f_{3} \neq 0$ is locally Ricci-symmetric, then the sum of associated 1 -forms $\alpha, \beta$ and $\gamma$ is zero everywhere.

If in (4.1) the 1 -form $\alpha$ is replaced by $2 \alpha$ and $\beta$ and $\gamma$ are equal to $\alpha$ then we have

$$
\begin{equation*}
\left(\nabla_{X} S\right)(Y, Z)=2 \alpha(X) S(Y, Z)+\alpha(Y) S(X, Z)+\alpha(Z) S(Y, X) \tag{4.8}
\end{equation*}
$$

where $\alpha$ is a non-zero 1 -form defined by $\alpha(X)=g(X, \rho)$. A manifold which satisfies (4.8) is called a specially weakly Ricci-symmetric manifold (see [17]).

Suppose that $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ is a specially weakly Ricci-symmetric generalized Sasakian-space-forms. If $M\left(f_{1}, f_{2}, f_{3}\right)$ is locally Ricci-symmetric, then from (4.7), we have

$$
2 \alpha(X)+\alpha(X)+\alpha(X)=0
$$

for any $X$ on $M\left(f_{1}, f_{2}, f_{3}\right)$, that is $\alpha(X)=0$. Which is contradicts the definition. Hence $M\left(f_{1}, f_{2}, f_{3}\right)$ can not be locally Ricci-symmetric. This gives us to state:

Theorem 4.2. Let $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ be a specially weakly Ricci-symmetric generalized Sasakian-space-form with $f_{1}-f_{3} \neq 0$. Then $M\left(f_{1}, f_{2}, f_{3}\right)$ cannot be locally Ricci-symmetric.

Definition 4.3. A weakly Ricci-symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ is said to be Ricci-recurrent if it satisfies the condition

$$
\nabla S=\alpha \otimes S
$$

Suppose, weakly Ricci-symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ with $f_{1}-f_{3} \neq 0$ is Ricci-recurrent, then from (4.1) and Definition 4.3, we have

$$
\begin{equation*}
\beta(Y) S(X, Z)+\gamma(Z) S(Y, X)=0 . \tag{4.9}
\end{equation*}
$$

Putting $X=Y=Z=\xi$ in (4.9) and then using (2.7), we obtain

$$
\begin{equation*}
\beta(\xi)+\gamma(\xi)=0 . \tag{4.10}
\end{equation*}
$$

Setting $X=Y=\xi$ in (4.9), we get

$$
\begin{equation*}
\gamma(Z)=-\beta(\xi) \eta(Z) . \tag{4.11}
\end{equation*}
$$

Similarly, we have

$$
\begin{equation*}
\beta(Z)=-\gamma(\xi) \eta(Z) . \tag{4.12}
\end{equation*}
$$

Adding the above equation with (4.11) and using (4.10), we get

$$
\beta(Z)+\gamma(Z)=0,
$$

for any vector field $Z$ on $M$. So that $\beta$ and $\gamma$ are in opposite direction. Hence we state
Theorem 4.3. If a weakly Ricci-symmetric generalized Sasakian space form $M\left(f_{1}, f_{2}, f_{3}\right)(n>2)$ with $f_{1}-f_{3} \neq 0$ is locally Ricci-recurrent, then the 1 -forms $\beta$ and $\gamma$ are in opposite direction.

## Acknowledgement

The second author is thankful to UGC for financial support in the form of Rajiv Gandhi National fellowship (F1-17.1/2013-14/RGNF-2013-14-SC-KAR-46330).

## Competing Interests

The authors declare that they have no competing interests.

## Authors' Contributions

Both authors contributed equally and significantly in writing this article. Both authors read and approved the final manuscript.

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