# Optimal Compound Orthogonal Arrays and Single Arrays for Robust Parameter Design Experiments

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#### Abstract

Compound orthogonal arrays (COAs) and single arrays are alternatives to the innerouter arrays advocated by Taguchi for robust parameter design experiments. A criterion based on the wordtype patterns and strengths of COAs is proposed to select optimal COAs. Single arrays are classified into prodigal single arrays (PSAs) and economical single arrays (ESAs) according to their relative estimation capacities, and various optimality criteria again based on the wordtype patterns are proposed for selecting optimal single arrays. Useful optimal COAs, PSAs and ESAs are constructed and tabulated as convenient references for experimenters in practice.

KEY WORDS: Robust parameter design, compound orthogonal array, single array

# **1 INTRODUCTION**

Robust parameter design (or briefly parameter design) is an engineering strategy, originally proposed by Taguchi (1986), for quality improvement in industrial systems. Factors that affect a system can be classified into two types, *control factors* and *noise factors*. Control factors refer to the variables whose levels are adjustable, while noise factors refer to the variables whose levels are hard or impossible to control in a system's normal operation state. In a parameter design experiment, both control and noise factors are varied systematically. The key idea of parameter design is to explore the effects of control factors, noise factors and their interactions, and choose control factor settings to simultaneously bring the system's mean response on target and reduce its performance variation caused by noise factors. For comprehensive reviews on parameter design, see Nair (1992) and Steinberg (1996).

Taguchi originally proposed to use inner-outer array, or *cross array*, as the experimental plan for parameter design. A cross array is the cross product of an orthogonal array for control factors (or briefly control array) and an orthogonal array for noise factors (or briefly noise array).

After data are generated from an experiment using cross array, response mean and variance at each setting of control factors are calculated, and the *location-dispersion modeling* approach is usually used to identify location and dispersion effects for parameter design optimization (Vining and Myers, 1990). Due to the concerns over the run size and flexibility of cross array, Lucas (1989), Welch et al. (1990) and Shoemake et al. (1991) proposed to use combined array, or *single array*, as an alternative to cross array. A single array is an ordinary orthogonal array that accommodate both control and noise factors and does not necessarily possess the "crossing" structure as cross array. In analyzing the data generated from an experiment using single array, the *response modeling* approach is usually used to directly model response as a function of control factors, noise factors and their interactions, then control-by-noise plots and the transmitted variance model are employed to identify location and dispersion effects. The idea of response modeling was first hinted in Easterling (1985).

The advantages and disadvantages of cross array and single array were discussed in Nair (1992) and Steinberg (1996). Recently there is a fair amount of effort devoted to the selection of optimal experimental plans for parameter design. In a series of papers, Rosenbaum (1994, 1996, 1998) extended cross array to compound orthogonal array (COA) and provided justifications for using COAs in parameter design experiments. COA relaxes the rigid crossing structure required by cross array so that different arrays can be employed for noise factors at different settings of control factors. A detailed description of COA will be given in Section 3.1. Hedayat and Stufken (1999) studied the basic properties of COAs and constructed the tables of COAs with both the numbers of control and noise factors less than six. However, the optimal selection of COAs have not been addressed in the literature.

Although combinatorially single arrays are just ordinary orthogonal arrays, their optimal selection is not straightforward due to the presence of two different types of factors. Bingham and Sitter (2003) proposed a minimum-aberration type of criterion based on modified wordlengths, and constructed the tables of small arrays applicable in split-plot parameter design experiments. The tables show that the criterion is not sensitive in discriminating single arrays when their sizes are relatively large. Wu and Zhu (2003) developed a general framework for selecting optimal single arrays, again using a minimum-aberration type of criterion. The framework becomes too complicated when high order effects are taken into consideration. Hence, a simple and direct approach is still needed for the selection of optimal single arrays

The current paper is intended to address the optimal selection of COAs and single arrays and is organized as follows. Section 2 is a brief review of fractional factorial design with two groups of factors. Section 3 introduces COAs and proposes a minimum aberration criterion for selecting optimal COAs. In Section 4, single arrays are classified into economical single arrays and prodigal single arrays, several criteria for selecting optimal single arrays are proposed, and optimal economical single arrays and prodigal single arrays are tabulated and discussed. Concluding remarks are given in Section 5. In this paper, we focus on COAs and single arrays that are regular two-level fractional factorial designs.

# 2 $2^{(l_1+l_2)-m}$ DESIGNS WITH TWO GROUPS OF FACTORS

Regular two-level fractional factorial designs, i.e.,  $2^{l-m}$  designs, are generated by defining relations (or defining words) among experimental factors. The collection of all the possible defining words of a design d is referred to as its defining contrast subgroup denoted by  $\mathcal{G}$ . Let  $W_i$  be the number of defining words of length i in  $\mathcal{G}$  for  $1 \leq i \leq l$  and  $W = (W_0, W_1, W_2, \ldots, W_l)$ . Then W is called the wordlength pattern of d. The resolution of d is the smallest positive integer i such that  $W_i > 0$ . If d has resolution R, it is well-known that the strength of d is R - 1; see Rao (1947) for the definition of strength for general orthogonal arrays. Suppose  $d_1$  and  $d_2$  are two designs,  $d_1$  is said to have less aberration than  $d_2$  if  $W_{i_0}(d_1) < W_{i_0}(d_2)$  where  $i_0$  is the smallest integer i such that  $W_i(d_1) \neq W_i(d_2)$ . If there does not exist a design with less aberration than  $d_1$ , then  $d_1$  is said to have minimum aberration (MA) (Fries and Hunter, 1980). A main effect or a two-factor interaction (2fi) is said to be clear or clearly estimable if it is not aliased with any other main effects or 2fi's, and is eligible if it is not clear but only aliased with some other 2fi's (Wu and Chen, 1992).

In  $2^{l-m}$  design, experimental factors are treated symmetrically. This, however, is not proper when multiple groups, or types, of factors are involved, for example, in parameter design where factors are divided into control factors and noise factors. In this paper, we only consider the case of two groups of factors , which are denoted by Group I and Group II. Let  $l_1$  and  $l_2$  be the number of factors in Group I and Group II respectively. A  $2_{\tau}^{(l_1+l_2)-p}$  design d is a two-level fractional factorial design with  $l_1$  columns assigned to Group I factors and the remaining  $l_2$ columns to Group II factors, where  $\tau$  represents the assignment of the columns and is usually suppressed. d is also determined by its defining contrast subgroup  $\mathcal{G}$ . However, the wordlength pattern W is not a proper aliasing characterization for  $\mathcal{G}$ , because defining words with the same length can consist of different numbers of group I and group II factors. Zhu (2003) proposed using the *wordtype pattern* matrix,  $(A_{i,j})_{0 \le i \le l_1, 0 \le j \le l_2}$ , to characterize the aliasing pattern of  $\mathcal{G}$ , where  $A_{i,j}$  is the number of defining words in  $\mathcal{G}$  involving *i* Group I factors and *j* Group II factors. In a parameter design experiment involving  $l_c$  control factors and  $l_n$  noise factors, we assume Group I consists of the control factors and Group II the noise factors. If we only consider two-level regular fractional factorial designs as possible experiment plans, then cross arrays, COAs and single arrays are in fact  $2^{(l_c+l_n)-m}$  designs with or without additional constraints. As a convention in the paper, we use capital letters such as A, B, etc. to represent control factors, and little letters such as a, b, etc. to represent noise factors.

## **3 OPTIMAL COMPOUND ORTHOGONAL ARRAYS**

#### 3.1 COAs and Maximum Strengths

Let OA(N, l, 2, t) denote a two-level orthogonal array with N rows, l columns and strength t (Rao, 1947). A COA with parameters  $N_c$ ,  $N_n$ ,  $l_c$ ,  $l_n$ ,  $t_c$ ,  $t_n$  and  $t_a$  is an  $N_cN_n \times (l_c + l_n)$  orthogonal array with the following properties: (P1) The first  $l_c$  columns are assigned to control factors and consists of  $N_n$  replications of an  $OA(N_c, l_c, 2, t_c)$ ; (P2) The remaining  $l_n$  columns are assigned to noise factors, and for each fixed setting of the  $l_c$  control factors, denoted by  $c_i$  for  $1 \leq i \leq N_c$ , the corresponding settings of the  $l_n$  noise factors form an  $OA_{c_i}(N_n, l_n, 2, t_n)$ , where the subscript  $c_i$  indicates that the array may vary from one setting to another; (P3) The entire array has strength  $t_a$ . Let  $T = (t_c, t_n, t_a)$ . We call T the strength vector of a COA. It can be verified that  $\min(t_c, t_n) \leq t_a \leq (t_c + t_n)$  (Hedayat and Stufken, 1999). When all the  $OA_{c_i}(N_n, l_n, 2, t_n)$ 's are identical for  $1 \leq i \leq N_c$ , the COA is a cross array. A COA is said to be regular if it is a regular  $2^{(l_c+l_n)-m}$  design that satisfies (P1)-(P3). As mentioned earlier, we only consider regular COAs in the current paper.

**Example 1.** Suppose a 32-run experiment involves four control factors (A, B, C, D) and three noise factors (a, b, c). Consider the following two  $2^{(4+3)-2}$  designs:  $d_1 : I = ABCD =$ ABabc = CDabc and  $d_2 : I = ABCD = abc = ABCDabc$ . Both  $d_1$  and  $d_2$  have 32 rows and seven columns with the first four assigned to the control factors and the remaining three to the noise factors. In  $d_1$ , the control factor columns consist of four copies of a 16-run  $2^{4-1}$  resolution IV design defined by I = ABCD. At each fixed setting of A, B, C and D, the corresponding settings of the noise factors form a 4-run resolution III design defined by AB = CD = abc. For example, at the setting (1, -1, 1, -1) of the control factors, the corresponding settings of a, band c are generated by -I = abc, which are (-1, -1, -1), (-1, 1, 1), (1, -1, 1), (1, 1, -1). So,  $d_1$  is a COA with  $N_c = 8$ ,  $N_n = 4$ ,  $l_c = 4$ ,  $l_n = 3$ ,  $t_c = 3$ ,  $t_n = 2$  and  $t_a = 3$ , and  $T(d_1) = (3, 2, 3)$ . Similarly, it can be verified that  $d_2$  is a COA with  $T(d_2) = (3, 2, 2)$ . Notice that, in  $d_2$ , at different settings of the control factors, the noise arrays are identical, which is generated by I = abc. Hence,  $d_2$  is a cross array. It is clear that  $d_1$  is not a cross array and it has higher overall strength than  $d_2$ . The wordtype patterns of  $d_1$  are  $A_{0.0} = 1$ ,  $A_{2.3} = 2$ ,  $A_{4.0} = 1$ , and  $A_{i,j} = 0$  otherwise; the wordtype patterns of  $d_2$  are  $A_{0.0} = 1$ ,  $A_{0.3} = A_{4.0} = A_{4.3} = 1$ , and  $A_{i,j} = 0$  otherwise.

Let d be a  $2^{(l_c+l_n)-m}$  COA with wordtype pattern matrix  $(A_{i,j})$ . Considering the relationship between strength and resolution, we can verify that

$$t_c = \min(l_c, \min\{i-1 : A_{i,0} \neq 0 \text{ and } i \ge 1\}),$$
  
 $t_n = \min(l_n, \min\{j-1 : A_{i,j} \neq 0 \text{ and } j \ge 1\}),$ 

and

$$t_a = \min\{i + j - 1 : A_{i,j} \neq 0 \text{ and } i + j \ge 1\}.$$

Hence  $(A_{i,j})$  determines T(d). In the definition of COA above, there is no specific requirement for  $t_n$ , so  $t_n$  can take on any nonnegative integer values. Rosenbaum (1994, 1996) proposed COAs as an extension of cross arrays and pointed out that COAs with  $t_n < 2$  are not able to identify dispersion effects and are unlikely to be useful; see Theorem 1 and Section 3.1 of Rosenbaum (1996). In other words, COAs with  $t_n \leq 1$  are not a reasonable extension of cross arrays. When investigating the maximum strengths of COAs from a theoretical perspective, Hedayat and Stufken (1999) included COAs with  $t_n \leq 1$ . In this paper, we are more interested in COAs that are useful in parameter design, therefore, in addition to the three properties given above, we further require COAs to satisfy the following condition,

(P4) 
$$t_c \ge \min(l_c, 2)$$
 and  $t_n \ge \min(l_n, 2)$ .

For regular  $2^{(l_c+l_n)-m}$  COAs with resolution III or higher, that is,  $t_a \ge 2$ , the condition  $t_c \ge \min(l_c, 2)$  is automatically satisfied. When  $l_n \ge 2$ , the condition  $t_n \ge \min(l_n, 2)$  requires that the noise arrays of a COA have strength at least 2. In terms of wordtype patterns,  $t_n \ge \min(l_n, 2)$  is equivalent to  $A_{i,1} = A_{i,2} = 0$  for  $1 \le i \le l_c$ . Clearly, cross arrays are COAs. Both  $d_1$  and  $d_2$  in Example 1 satisfy (P4), so they are still COAs.

For given  $l_c$ ,  $l_n$  and run size  $2^k$ , COAs do not always exist. Define

$$\mathcal{S}(2^k) = \{(i,j) : \lceil \log_2(i+1) \rceil + \lceil \log_2(j+1) \rceil \le k\},\tag{1}$$

where  $\lceil x \rceil$  represents the smallest integer greater than or equal to x.

**Proposition 1.** The necessary and sufficient condition for the existence of a COA with  $l_c$  control factors,  $l_n$  noise factors and  $2^k$  runs is  $(l_c, l_n) \in \mathcal{S}(2^k)$ 

The proof of Proposition 1 is given in the Appendix. When k = 4,  $\mathcal{S}(2^4) = \{(1, j)\}_{1 \le j \le 7} \cup \{(i, 1)\}_{1 \le i \le 7} \cup \{(2, 2), (2, 3), (3, 2), (3, 3)\}$ . Because  $(3, 4) \notin \mathcal{S}(2^4)$ , there does not exist a 16-run COA with three control factors and four noise factors. Note that the necessary and sufficient condition for the existence of cross arrays is exactly the same as that for COAs.

Suppose d is a COA with  $T(d) = (t_c(d), t_n(d), t_a(d))$ . d is said to have maximum strengths if there does not exist another COA  $\tilde{d}$  with the same run size,  $l_c$  and  $l_n$  as d such that  $T(\tilde{d}) \ge T(d)$ componentwisely and at least one of the inequalities is strict. The preference of COAs with maximum strengths is justified by Theorem 1 in Rosenbaum (1996) and an observation of Hedayat and Stufken (1999) that has further improved part c of Theorem 1 in Rosenbaum (1996); see the beginning of Section 2 in Hedayat and Stufken (1999). When the response modeling approach is used in analysis, COAs with maximum strengths should also be preferred according to Section 4 in Rosenbaum (1996). In Example 1,  $T(d_1) = (3, 2, 3)$  and  $T(d_2) = (3, 2, 2)$ . Clearly,  $T(d_1) \ge T(d_2)$  and  $t_a(d_1) > t_a(d_2)$ . Hence,  $d_2$ , a cross array, does not achieve maximum strengths. In fact, we can show that  $d_1$  attains maximum strengths as a COA with 32-run, four control factors and three noise factors.

#### **3.2** $W_c$ -Aberration and Optimal COAs

The strength vector T of a COA can be considered as an extension of the resolution R of a fractional factorial design. Different COAs may share the same strength vector and need to be further discriminated.

**Example 2**. Let us consider a 64-run parameter design experiment that involves four control factors (A, B, C, D) and six noise factors (a, b, c, d, e, f). Four possible  $2^{(4+6)-4}$  COAs are given below. Due to limited space, only a set of independent defining words is listed for each array.

$$egin{aligned} &d_3:ABCD,Dabd,Dace,Dbcf;\ &d_4:ABCD,abde,ABacd,ACabf;\ &d_5:ABCD,abce,abdf,ACacd;\ &d_6:ABCD,abd,ace,bcf. \end{aligned}$$

 $d_3$  was the design given in Table 1 in Rosenbaum (1996);  $d_4$  is a MA  $2^{10-4}$  design with the distinction between control factors and noise factors neglected; and  $d_6$  is a cross array. The strength vectors of the four COAs are  $T(d_3) = T(d_4) = T(d_5) = (3, 2, 3)$  and  $T(d_6) = (3, 2, 2)$ . It can be shown that  $d_3$ ,  $d_4$  and  $d_5$  all have achieved the maximum strengths for COAs with 64 rows, four control factors and six noise factors. However, they are still quite different from each other as will be shown below, so further discrimination between them is necessary in order to select the best plan for the experiment.

The defining contrast subgroups and wordtype pattern matrices of the above arrays can be derived from independent defining words. It can be verified that the wordtype pattern matrices are different from each other. In the following, we further compare  $d_3$ ,  $d_4$  and  $d_5$ in terms of their detailed aliasing patterns. For simplicity, we assume effects of order 3 or higher are negligible. So we only need to consider the defining words with length less than five, which are  $\{ABCD, Dabd, Dace, Dbcf, Ddef, bcde, acdf, abef\}$  for  $d_3$ ,  $\{ABCD, abde\}$  for  $d_4$ , and  $\{ABCD, abce, abdf, cdef\}$  for  $d_5$ . Because all the three arrays have resolution IV, their control and noise main effects are clear. Because ABCD appears in  $d_3$ ,  $d_4$  and  $d_5$ , the controlby-control 2fi's in all the three arrays are eligible. Consider the 24 possible control-by-noise 2fi's. In  $d_3$ , the 18 control-by-noise 2fi's between  $\{A, B, C\}$  and  $\{a, b, c, d, e, f\}$  are clear, and the six control-by-noise 2fi's between  $\{D\}$  and  $\{a, b, c, d, e, f\}$  are aliased with some noise-by-noise 2fi's and thus are only eligible; in  $d_4$ , all the 24 control-by-noise 2fi's are clear, in addition, the noise-by-noise 2fi's ac, bc, cd, ce, cf, af, bf, df and ef are also clear, and the other six noise-by-noise 2fi's are eligible; in  $d_5$ , all the 24 control-by-noise 2fi's are clear, but all the noiseby-noise 2fi's are only eligible. Heuristically,  $d_4$  is the best among the three arrays according to their aliasing patterns, followed by  $d_5$  and  $d_3$ . Hence,  $d_4$  should be selected for the experiment.

Example 2 shows that COAs with maximum strengths may not be unique and they can be further discriminated by their wordtype patterns. Let  $\overbrace{C \cdots C n \cdots n}^{i}$  represent a defining word consisting of *i* control factors and *j* noise factors, which is said to be of type (i, j). Note that  $A_{i,j}$  is the number of defining words of type (i, j) in the defining contrast subgroup of a COA. Defining words of length *k* have (k+1) different types, which are  $(k, 0), (k-1, 1), \ldots, (1, k-1),$ and (0, k). In the following, we re-arrange  $A_{i,j}$  into a sequence that can be used to rank-order different COAs. First, we consider the defining words of length 3: CCC, CCn, Cnn and nnn. In COAs, CCn and Cnn are not present. Because the purposes of robust parameter design are mean response optimization and variance reduction, in terms of aliasing severity, CCC is considered more severe than *nnn*, which we write as  $CCC \triangleleft nnn$ , or,  $A_{3.0} \triangleleft A_{0.3}$ . Next, we consider the defining words of length 4: CCCC, CCCn, CCnn, Cnnn and *nnnn*. Similarly, CCCn and CCnn are not present in COAs, and we regard CCCC as being more severe than *nnnn*, that is,  $CCCC \triangleleft nnnn$ . It is reasonable that Cnnn should be considered more severe than *nnnn*, however, the comparison between CCCC and Cnnn is not conclusive at first glance. CCCC causes aliasing between control-by-control 2fi's, which may hinder the identification of *second order* location effects for response mean optimization, while Cnnn causes aliasing between control-by-noise 2fi's, which may hinder the identification of *first order* dispersion effects for variation reduction. Therefore, we regard Cnnn to be more sever than CCCC, and  $Cnnn \triangleleft CCCC \triangleleft nnnn$ , or,  $A_{1.3} \triangleleft A_{4.0}, \triangleleft A_{0.4}$ . For the defining words of order 5, we have  $CCnnn \triangleleft Cnnnn \triangleleft CCCCC \triangleleft nnnnn$ , or,  $A_{2.3} \triangleleft A_{1.4} \triangleleft A_{5.0} \triangleleft A_{0.5}$ . In general,  $A_{i_1,j_1} \triangleleft A_{i_2,j_2}$  if

(i) 
$$i_1 + j_1 < i_2 + j_2$$
; or  
(ii)  $|i_1 - j_1| < |i_2 - j_2|$  and  $i_1 + j_1 = i_2 + j_2$ ; or  
(iii)  $i_1 > i_2$  and  $|i_1 - j_1| = |i_2 - j_2|$  and  $i_1 + j_1 = i_2 + j_2$ .  
(2)

Thus, following  $\triangleleft$ , all the wordtype patterns  $A_{i,j}$  can be arranged into a sequence, denoted by  $W_c$ , from the most severe to the least severe, as follows:

 $W_c = (A_{3.0}, A_{0.3}, A_{1.3}, A_{4.0}, A_{0.4}, A_{2.3}, A_{1.4}, A_{5.0}, A_{0.5}, A_{3.3}, A_{2.4}, A_{1.5}, A_{6.0}, A_{0.6}, \cdots).$ (3)

And we refer to  $W_c$  as the wordtype pattern sequence for COAs. Note that  $A_{i,j}$  with  $0 \le i+j \le 2$  are constants for designs with resolution at least III, so they are not included in  $W_c$ .

Suppose  $d_1$  and  $d_2$  are two COAs whose wordtype pattern sequences are  $W_c(d_1)$  and  $W_c(d_2)$ respectively. Let  $A_{i_0,j_0}$  be the first component of  $W_c$  such that  $A_{i_0,j_0}(d_1) \neq A_{i_0,j_0}(d_2)$ . If  $A_{i_0,j_0}(d_1) < A_{i_0,j_0}(d_2)$ , then  $d_1$  is said to have less  $W_c$ -aberration than  $d_2$ . If there does not exist a COA with less  $W_c$ -aberration than  $d_1$ ,  $d_1$  is said to have minimum  $W_c$ -aberration. Furthermore, if  $d_1$  has minimum  $W_c$ -aberration and maximum strengths, then  $d_1$  is said to be an optimal COA. The reason to include the requirement of maximum strengths in the optimality criterion for COAs is that it is not necessarily true that  $T(d_1) \geq T(d_2)$  componentwisely when  $d_1$  has less  $W_c$ -aberration than  $d_2$ . Though all the known minimum  $W_c$ -aberration COAs achieve maximum strengths, we are not able to prove that it is always true. So we conjecture that minimum  $W_c$ -aberration COAs also achieve maximum strengths.

**Example 2** (Continued). For  $d_3$ ,  $d_4$ ,  $d_5$  and  $d_6$ ,  $W_c(d_3) = (0, 0, 4, 1, 3, 0, 0, 0, 0, 4, 0, ...)$ ,  $W_c(d_4) = (0, 0, 0, 1, 1, 8, 0, 0, 0, 0, 4, ...)$ ,  $W_c(d_5) = (0, 0, 0, 1, 3, 8, 0, 0, 0, 0, 0, ...)$  and  $W_c(d_6) = (0, 0, 0, 1, 1, 8, 0, 0, 0, 0, 0, 4, ...)$ 

 $(0, 4, 0, 1, 3, 0, 0, 0, 0, 0, 0, \dots)$ . In the order of increasing  $W_c$ -aberration, we have  $d_4$ ,  $d_5$ ,  $d_3$  and  $d_6$ . Complete computer search concludes that  $d_4$  has minimum  $W_c$ -aberration and maximum strengths among all the 64-run COAs with four control factors and six noise factors. Hence,  $d_4$  is the optimal COA and should be recommended for the experiment, and the second best is  $d_5$ .

#### **3.3** Tables of Optimal COAs with $l_n \geq 3$

Because optimal COAs of 16-, 32- and 64-run are useful for parameter design experiments, it is valuable to tabulate them as a convenient reference for experimenters in practice. The optimal COAs with  $2^k$  runs and one or two noise factors can be easily constructed as follows. Because  $l_n \leq 2$ ,  $W_c$  is reduced to be  $(A_{i,0})_{3\leq i\leq l_c}$  after the zero components are removed. For  $(l_c, 1)$  or  $(l_c, 2)$  that belongs to  $\mathcal{S}(2^k)$ , the optimal COA is a cross array, where the control array is a  $2^{l_c}$  full factorial design for  $1 \leq l_c \leq k - 1$ , or a  $2^{l_c - (l_c + l_n - k)}$  MA design for  $l_c \geq k$ , and the noise array is a  $2^{l_n}$  full factorial design.

When  $l_n \geq 3$ , in general, how to construct optimal COAs with  $(l_c, l_n) \in \mathcal{S}(2^k)$  is unknown, so we have conducted extensive computer search with complete isomorphism checking to select optimal COAs. Two  $2^{(l_1+l_2)-p}$  designs d and d' are said to be isomorphic, if there exists a relabeling of the factors of d that transforms  $\mathcal{G}(d)$  to  $\mathcal{G}(d')$ , where  $\mathcal{G}(d)$  and  $\mathcal{G}(d')$  are the defining contrast subgroups of d and d', respectively. Our search procedure consists of three steps. The first step is to construct the list of all nonisomorphic  $2^{(l_1+l_2)-p}$  designs, the second step is to sort all the nonisomorphic designs according to the optimality criterion for COAs for any given  $l_c$ ,  $l_n$  and k (k = 4, 5, 6), and the third step is to output the optimal COAs. For 16and 32-run designs, we have utilized the lists of nonisomorphic  $2^{l-p}$  designs generated by Sun et al. (1993), where factors are not separated into two groups. For 64-run designs, we have constructed the list of nonisomorphic  $2^{(l_1+l_2)-p}$  designs from scratch for  $l_1 + l_2$  up to 16.

The final output of our computer search is reported in Table 1 and Table 2. Table 1 contains all the 16-run and 32-run optimal COAs with  $l_n \geq 3$ , and Table 2 contains all the 64-run optimal COAs with  $l_c + l_n \leq 16$  and  $l_n \geq 3$ . In both the tables, every row gives an optimal COA, and the columns, from the left to the right, give  $(l_c, l_n)$ , independent defining words (or generators), strength vector  $T = (t_c, t_n, t_a)$  and the number of clear control main effect, noise main effects, control-by-control 2fi's, control-by-noise 2fi's and noise-by-noise 2fi's, respectively. For example, from Table 1, the optimal 32-run COA with  $l_c = 2$  and  $l_n = 7$ , denoted by  $d_1$ , is

 $(2,7)^{\star}$  abce abdf acdg ABbcd (2,2,3) (2,7,1,14,0);

the optimal 32-run COA with  $l_c = 3$  and  $l_n = 6$ , denoted by  $d_2$ , is

#### $(3,6)^{\circ}$ ABC Aabd Aace Bbcf (2,2,2) (0, 6, 0, 8, 1).

 $d_1$  is a resolution IV design with its control array and noise arrays of strength 2. In  $d_1$ , all the control main effects, the noise main effects, the control-by-control 2fi's and the control-by-noise 2fi's are clear. The 32-run cross array with  $l_c = 2$  and  $l_n = 7$ , denoted by  $d'_1$ , is given by crossing a 2<sup>2</sup> control array and a 2<sup>7-4</sup> noise array. Note that the noise array in  $d'_1$  is a saturated 8-run fractional factorial design. The resolution of  $d'_1$  is III, which is less than that of  $d_1$ . In  $d'_1$ , the control main effects and the control-by-noise 2fi's are also clear, but the noise main effects are only eligible. Therefore, in terms of both strengths and the number of clear effects,  $d_1$  is better than  $d'_1$ , which is indicated by the  $\star$  in  $(2, 7)^{\star}$ . The same interpretation applies to other arrays marked with  $\star$  in Tables 1 and 2.

The optimal COA  $d_2$  above is a resolution III design with its control array and noise arrays of strength 2. In  $d_2$ , six noise main effects, eight control-by-noise 2fi's and one noise-by-noise 2fi are clear, and control main effects are aliased with control-by-control 2fi's and the other control-by-noise 2fi's and noise-by-noise 2fi's are only eligible. The corresponding 32-run cross array, denoted by  $d'_2$ , is given by crossing a 4-run  $2^{3-1}$  control array and a 8-run  $2^{6-3}$  design.  $d_2$  and  $d'_2$  have the same strength vector. In  $d'_2$ , all the control-by-noise 2fi's are clear, control main effects are aliased with some control-by-control 2fi's, noise main effects are aliased with some noise-by-noise 2fi's, and the rest 2fi's are eligible. There clearly exists a trade-off between  $d_2$  and  $d'_2$ , that is,  $d_2$  guarantees the clear estimation of the noise main effects while  $d'_2$  ensures the clear estimation of all the control-by-noise 2fi's. Due to the trade-off, the advantage of  $d'_2$ over  $d_2$  is not as clear as that of  $d_1$  over  $d'_1$  discussed in the proceeding paragraph. We indicate this trade-off by the  $\circ$  in  $(3, 6)^{\circ}$ . The same interpretation applies to other arrays marked with  $\circ$  in Tables 1 and 2. The trade-off can also be regarded as an indication that the array for the given  $l_c$  and  $l_n$  is already too tight to simultaneously possess a crossing structure and a good estimation capability for important effects. It may suggest that single array be considered instead; see the good single arrays with  $l_c = 3$  and  $l_n = 6$  reported in Table 3 later. Some of the designs reported in Tables 1 and 2 were also obtained by Hedayat and Stufken (1999) and Bingham and Sitter (2003). Nonetheless, they are included in the tables for completeness.

#### **4 OPTIMAL SINGLE ARRAYS**

From the discussion in Section 3.1, we know that the smallest COA or cross array with  $l_c$  control factors and  $l_n$  noise factors requires  $2^{\lceil \log_2(l_c+1) \rceil + \lceil \log_2(l_n+1) \rceil}$  runs. When both  $l_c$  and  $l_n$  increase, COAs become too large to be feasible in practice. For example, there does not exist

16-run: $(1, 4)^*$ Aabcd $(2, 3)^*$ ABabc $(1, 5)^\circ$ Act Acce $(1, 2)^\circ$ Act Acce	$ \begin{array}{c} 4,  6) \\ 6,  3) \end{array} $
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{pmatrix} 4, \ 6 \\ 6, \ 3 \end{pmatrix}$
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{pmatrix} 0, \ 0 \end{pmatrix} \\ 6, \ 0 \end{pmatrix} \\ 0, \ 0 \end{pmatrix} \\ 0, \ 0 \end{pmatrix}$
32-run:	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{c} 5, 10) \\ 8, 6) \\ 9, 3) \\ 6, 9) \\ 10, 4) \\ 12, 6) \\ 12, 3) \\ 7, 6) \\ 12, 0) \\ 9, 4) \\ 7, 6) \\ 12, 0) \\ 9, 4) \\ 12, 3) \\ 7, 6) \\ 12, 0) \\ 9, 4) \\ 12, 3) \\ 12, 3) \\ 12, 3) \\ 13, 3) \\ 0, 0) \\ 18, 0) \\ 18, 0) \\ 18, 0) \\ 18, 0) \\ 0, 0) \\ 18, 0) \\ 18, 0) \\ 0, 0) \\ 18, 0) \\ 10, 0) \\$
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	(, 0, 0) (, 0, 0) (, 0, 0) (, 0, 0)

Table 1: 16- and 32-Run Optimal Strong Compound Orthogonal Arrays

Table 2: 64-Run Optimal Strong Compound Orthogonal Arrays

Design	generators	strength	clear effects
$(1,6)^{\star}$	Aabcdef	(1, 5, 6)	(1, 6, 0, 6, 15)
$(2,5)^{*}$	ABabcde	(2, 4, 6)	(2, 5, 1, 10, 10)
$(\bar{3}, \bar{4})^*$	ABCabed	(3, 3, 6)	(3, 4, 3, 12, 6)
$(4, 3)^{\star}$	ABCDabc	(4, 2, 6)	(4, 3, 6, 12, 3)
$\begin{pmatrix} 4, 0 \\ 1 & 7 \end{pmatrix} \star$	Ashaf abdag	(4, 2, 0)	(1, 3, 0, 12, 3)
(1, 1)	Adocj dodey Ashao Dahaf	(1, 3, 4)	(1, 7, 0, 7, 21)
$(2,0)^{\circ}$	Adoce Dabaj	(2, 3, 4)	(2, 0, 1, 12, 10)
$(3, 5)^{\uparrow}$	ABaba Cabce	(3, 2, 4)	(3, 5, 3, 15, 10)
$(4,4)^{}$	ABCD ABabcd	(3, 3, 3)	(4, 4, 0, 16, 6)
$(5,3)^*$	ABabc ABCDE	(4, 2, 4)	(5, 3, 10, 15, 3)
$(1,8)^{\star}$	abcf Aabdg acdeh	(1, 3, 3)	(1, 8, 0, 8, 22)
$(2,7)^{\star}$	abce Aabdf Bacdg	(2, 3, 3)	(2, 7, 1, 14, 15)
$(3, 6)^{\star}$	abce ACabd Bacdf	(3, 2, 3)	(3, 6, 3, 18, 9)
$(4,5)^{\star}$	ABCD ABabd ACace	(3, 2, 3)	(4, 5, 0, 20, 10)
$(5, 4)^*$	ABD ACE BCabcd	(2, 3, 2)	(0, 4, 0, 20, 6)
$(6,3)^*$	ABCE ABDF ACDabc	(3, 2, 3)	(6, 3, 0, 18, 3)
$(1, 9)^*$	abef Aabda Aabeb acdei	(1, 3, 3)	(1, 9, 0, 9, 24)
$(2,8)^{*}$	abef Aabda Aabeh Bacde	(2, 3, 3)	(2, 8, 1, 16, 16)
(3,7)*	abef abda Bacde ACabe	(3, 2, 3)	(3, 7, 3, 21, 6)
(4, 6)*	ABCD ABabd ABace ACbcf	(3, 2, 3)	(1, 1, 0, 21, 0)
(4,0)	ADD	(3, 2, 3)	(4, 0, 0, 24, 3)
(3, 3)	ADD ACE DOUGA ADOUCE	(2, 2, 2)	(0, 5, 0, 25, 10)
$(0, 4)^{\circ}$	ABD ACE BUF ABCalca	(2, 3, 2)	(0, 4, 0, 24, 6)
$(7,3)^{2}$	ABCE ABDF ACDG BCDabc	(3, 2, 3)	(7, 3, 0, 21, 3)
$(1, 10)^{*}$	abcg abdh acdei acdfj Aabef	(1, 3, 3)	(1, 10, 0, 10, 24)
$(2,9)^{\star}$	abcf abdg abeh acdei ABbcde	(2, 2, 3)	(2, 9, 1, 18, 8)
$(3,8)^{\star}$	ABC abce Aabdf Bacdg ABbcdh	(2, 3, 2)	(0, 8, 0, 24, 16)
$(4,7)^{\star}$	abce abdf ACacd BDacd ABabg	(3, 2, 3)	(4, 7, 0, 28, 6)
$(5, 6)^{\star}$	ABD ACE BCabd BCace ABCbcf	(2, 2, 2)	(0, 6, 0, 30, 9)
$(6,5)^{\star}$	ABD ACE BCF ABCabd ABCace	(2, 2, 2)	(0, 5, 0, 30, 4)
$(7, 4)^{*}$	ABD ACE BCF ABCG Aabcd	(2, 3, 2)	(0, 4, 0, 28, 6)
$(8,3)^*$	ABCE ABDE ACDG BCDH ABabc	(3, 2, 3)	(8, 3, 0, 24, 3)
(1, 11)*	abca abdh acei adf i ae fk Aabcde f	(1, 3, 3)	(1, 11, 0, 11, 10)
(2, 10)*	abef abda aceb adei abedei ABaed	(2, 2, 3)	(2, 10, 1, 20, 0)
$(3, 9)^{\circ}$	ABC Aabe Aacf Bada Abcdb ABabcdi	(2, 2, 3)	(0, 9, 0, 17, 16)
(5, 5)	ABD ACE BCabd BCace BChef Aabea	(2, 2, 2, 2)	(0, 3, 0, 11, 10) (0, 7, 0, 35, 6)
(5, 7)	ADD ACE DCubi DCuce DCocj Aubly	(2, 2, 2)	(0, 7, 0, 35, 0)
(0,0)	ADD ACE DOF ADOute ADOute ADOut	(2, 2, 2)	(0, 0, 0, 0, 30, 0)
(7, 5)	ADD ACE DUF ADUG Adud Dace	(2, 2, 2)	(0, 5, 0, 29, 4)
$(9,3)^{^{^{^{^{^{^{^{^{^{^{^{^{^{^{^{^{^{}}}}}}$	ABE ACF ADG BCDH ABCDI BCabc	(2, 2, 2)	(0, 3, 0, 27, 3)
$(1, 12)^{^{}}$	abcg abah abei Abcae acfj defk acdefl	(1, 3, 3)	(1, 12, 0, 12, 0)
$(2, 11)^{\star}$	abcf abdg acdh abei acej adek ABbcd	(2, 2, 3)	(2, 11, 1, 22, 0)
$(3, 10)^{\circ}$	ABC Aabe Aacf Bbcg Badh Abcdi ABabcdj	(2, 2, 2)	(0, 10, 0, 10, 17)
$(6,7)^{\star}$	ABD ACE BCF ABCabd ABCace ABCbcf abcg	(2, 2, 2)	(0, 7, 0, 42, 0)
$(7,6)^{\circ}_{}$	ABD ACE BCF ABCG Aabd Bace Cbcf	(2, 2, 2)	(0, 6, 0, 30, 3)
$(10, 3)^{\star}$	ABE ACF BCG ADH BCDI ABCDJ BDabc	(2, 2, 2)	(0, 3, 0, 30, 3)
$(1, 13)^*$	abcg abdh acei adej abfk Abcdf cefl defm	(1, 3, 3)	(1, 13, 0, 13, 0)
$(2, 12)^*$	abcf abdq acdh bcdi abej acek adel ABbce	(2, 2, 3)	(2, 12, 1, 24, 0)
$(3, 11)^{\circ}$	ABC Aabe Aacf Bbcg Aadh Bbdi Bacdj Abcdk	(2, 2, 2)	(0, 11, 0, 8, 6)
$(7,7)^{\circ}$	ABD ACE BCF ABCG Aabd Bace Cbcf ABCabca	(2, 2, 2)	(0, 7, 0, 28, 0)
$(11,3)^*$	ABE ACF BCG ADH BDI ACDJ BCDK ABCDabc	(2, 2, 2)	(0, 3, 0, 33, 3)
$(1, 14)^*$	abca abdh acei adei abcdek abfl Aacdf aefm abcefn	(1, 3, 3)	(1, 14, 0, 14, 0)
(2, 13)*	abcf abda acdb bcdi abei acek bcel adem ABbde	(2, 2, 3)	(2, 13, 1, 26, 0)
3 1210	ABC Aabe Aacf Bhca Aadh Bhdi ABacdi Abcdk abcdl	2 2 2	(0, 12, 0, 7, 3)
(12 3)	ARE ACE RCC ADH RDI ACDI RCDK ARCDI ARCaba	(2, 2, 2)	(0, 12, 0, 1, 0)
$\begin{pmatrix} 12, 3 \\ 1 & 15 \\ \end{pmatrix}$	abea abdb acei adei abedek abfl Acedf acfm abecfn abdefa	$\begin{pmatrix} 2 \\ 1 \\ 2 \\ 2 \end{pmatrix}$	(0, 3, 0, 30, 3)
$(1, 10) \times$	abef abda aadh hadi abai aadh hadi adam hdam ABada	$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$	(1, 10, 0, 10, 0)
$\binom{2}{2}$	APC Ashe Asef Abes Pakeh Asdi Abdi Dahla Dada asdar	$\begin{pmatrix} 2, 2, 3 \\ 2, 2 \end{pmatrix}$	$\begin{pmatrix} 2, 14, 1, 20, 0 \end{pmatrix}$
$(3, 13)^{\circ}$	ADC Auve Aucj Aocg Baoch Adai Adaj Baoak Beal acam	(2, 2, 2)	(0, 13, 0, 6, 2)
$(13,3)^{\circ}$	ABE AUF BUG ABUH ADI BDJ ABDK UDL AUDM BUDabe	(2, 2, 2)	(0, 3, 0, 39, 3)

a 32-run COA with  $l_c = 4$  and  $l_n = 6$ . If one can only afford to conduct a 32-run experiment, he/she should consider single arrays. For given  $l_c$ ,  $l_n$  and run size  $2^k$ , formally, a single array is a  $2^{(l_c+l_n)-m}$  design with  $l_c$  columns assigned to the control factors and the remaining  $l_n$  columns assigned to the noise factors, where  $m = l_c + l_n - k$  (Wu and Zhu, 2003). The necessary and sufficient condition for the existence of a single array is  $l_c + l_n \leq 2^k - 1$ . For the experiment with four control factors (A, B, C, D) and six noise factors (a, b, c, d, e, f), for example, the single array generated by the independent defining words *abd*, *ace*, *bcf*, *ACabc* and *ABDa*, can be considered.

COAs are single arrays that possess crossing structures, so they are special cases of single arrays. Based on the number of control factors  $(l_c)$ , the number of noise factors  $(l_n)$ , and the run size  $(2^k)$ , we propose to classify single arrays into two categories, which are prodigal single arrays and economical single arrays, as follows. A single array with  $l_c$ ,  $l_n$  and run size  $2^k$  is a prodigal single array (PSA) if  $(l_c, l_n) \in \mathcal{S}(2^k)$ , and it is an economical single array (ESA) if  $(l_c, l_n) \notin \mathcal{S}(2^k)$ .

We know that  $2^k$ -run single arrays exist for  $l_c$  control factors and  $l_n$  noise factors if  $l_c + l_n \leq 1$  $2^k - 1$ . For  $2^k$ -run single arrays, the total degrees of freedom are fixed to be  $2^k$ , but  $l_c$  and  $l_n$  can vary. Heuristically, when  $l_c + l_n$  is small, the number of lower-order effects such as the control main effects and the control-by-noise 2fi's is small, so it may be possible to construct the single array in a way such that all the lower-order effects can be clearly estimable, and we claim that the single array has large relative estimation capacity with respect to  $l_c$  and  $l_n$ . When  $l_c + l_n$  is large, the number of lower-order effects is large, so it may not be possible to have a single array in which all the lower-order effects are clearly estimable, and we claim that the single array has small relative estimation capacity with respect to  $l_c$  and  $l_n$ . One purpose of classifying single arrays into PSAs and ESAs is to distinguish single arrays with large relative estimation capacities, i.e., PSAs, from those with small relative estimation capacities, i.e., ESAs. As will be clear later, different criteria need to be used for selecting optimal PSAs and ESAs. Another purpose of the above classification is to facilitate the fair comparison between cross arrays and single arrays. In the literature, there is much discussion regarding the advantages and disadvantages of single arrays versus cross arrays, however, no general conclusions have been reached. We suggest that cross arrays or COAs are only comparable with PSAs, but not directly with ESAs. This greatly clarifies the discussion, and leads to various useful criteria for choosing COAs, PSAs and ESAs. In the rest of the section, we focus on proposing optimality criteria for single arrays in general in Section 4.1, then discuss the selection of optimal ESAs in Section 4.2, and

the selection of optimal PSAs in Section 4.3.

#### 4.1 Optimality Criteria for Single Arrays

#### 4.1.1 $W_s$ -Aberration

The wordtype patterns  $A_{i,j}$  of single arrays are not subject to the restrictions  $A_{i,1} = A_{i,2} = 0$ . The arguments used to arrange  $A_{i,j}$  with  $j \ge 3$  into  $W_c$  in Section 3.2 are still valid for single arrays. To obtain a complete sequence of wordtype patterns for single arrays, we need a proper way to insert  $A_{i,j}$  with j = 1, 2 into  $W_c$ . Let us first consider  $A_{2,1}$  and  $A_{1,2}$ , or equivalently, CCnand Cnn. The worst aliasing relations induced by CCn and Cnn are C = Cn and Cn = nrespectively. Because C and Cn are of primary importance for parameter design, C = Cn is more severe than Cn = n. So  $CCn \triangleleft Cnn$ . Clearly, both CCn and Cnn are more severe in terms of aliasing severity than CCC and nnn. Hence, we have  $CCn \triangleleft Cnn \triangleleft CCC \triangleleft nnn$ , or,  $A_{2.1} \triangleleft A_{1.2} \triangleleft A_{3.0} \triangleleft A_{0.3}$ . Next, we consider  $A_{4.1}$  and  $A_{4.2}$ , or CCCn and CCnn. The worst aliasing relation induced by CCCn is CC = Cn and the worst by CCnn is Cn = Cn. Both CCand Cn are effects of order 2, but Cn plays a more crucial role in parameter design than CC. So Cn = Cn is considered to be more severe than CC = Cn, which implies  $CCnn \triangleleft CCCn$ . In a similar way, we have  $CCCn \triangleleft Cnnn$ . Hence,  $CCnn \triangleleft CCCn \triangleleft Cnnn \triangleleft CCCC \triangleleft nnnn$ , or  $A_{2.2} \triangleleft A_{3.1} \triangleleft A_{1.3} \triangleleft A_{4.0} \triangleleft A_{0.4}$ . We can further compare defining words with length larger than four. This leads to the same scheme as stated in (3) for ranking two different wordtype patterns  $A_{i_1.j_1}$  and  $A_{i_2.j_2}$  in terms of aliasing severity. We denote the resulted sequence by  $W_s$ , which is

$$W_s = (A_{2.1}, A_{1.2}, A_{3.0}, A_{0.3}, A_{2.2}, A_{3.1}, A_{1.3}, A_{4.0}, A_{0.4}, A_{3.2}, A_{2.3}, A_{4.1}, A_{1.4}, A_{5.0}, A_{0.5}, \ldots).$$
(4)

Note that  $W_c$  is a subsequence of  $W_s$ .

The hierarchical ordering principle states that (i) effects of lower order are more important than those of higher order; (ii) effects of the same order are equally important. In  $W_s$ , (i) is preserved, but (ii) does not hold. In fact, effects with the same order are further distinguished according to their relative importance for parameter design. Based on  $W_s$ ,  $W_s$ -aberration and the minimum  $W_s$ -aberration criterion can be defined and proposed for selecting optimal single arrays. In the derivation of  $W_s$ , we have only considered the aliasing relations implied by the wordtype patterns and have not taken into account the run size of a single array, or to be more precise, the relative estimation capacity of a single array. When the relative estimation capacity of a single array is much limited, for example, in an economical single array, it is impossible to guarantee that all the lower-order effects can be clearly estimated. Hence, in selecting practically useful single arrays, one needs to prioritize the estimation of important effects versus less important effects. In extreme cases, the estimation of the less important effects may need to be compromised entirely.

# 4.1.2 Split Wordtype Patterns and $(W_{sm}, W_{sn})$ -Aberration

The major advantage of using ESAs is run size economy. As mentioned in the end of the previous subsection, the relative estimation capacities of ESAs are already small. In other words, ESAs usually do not have enough capacities to accommodate all the low-order effects in a balanced way. Nonetheless, the use of ESAs in practice can be justified by the effects sparsity principle and the effects asymmetry existing in parameter design (Shoemaker, et al., 1991). The effects sparsity principle states that the number of effects that are significant in a factorial experiment is relatively small (Box and Meyer, 1986), and the effects asymmetry refers to the fact that control-by-noise 2fi's as well as control main effects are more important than noise main effects and other 2fi's. If an ESA ensures the clear estimation of the important effects, e.g., noise effects, it is still a practically useful experimental plan. To reflect the emphasis on the important effects and the discrimination against the less important effects, we first split  $W_s$  into two separate sequences:

$$W_{sm} = (A_{2.1}, A_{1.2}, A_{3.0}, A_{2.2}, A_{3.1}, A_{1.3}, A_{4.0}, A_{3.2}, A_{2.3}, A_{4.1}, A_{1.4}, A_{5.0}, A_{3.3}, \ldots),$$
(5)

and

$$W_{sn} = (A_{0.3}, A_{0.4}, A_{0.5}, A_{0.6}, \dots).$$
(6)

Notice that  $W_{sm}$  consists of  $A_{i,j}$  with i > 1 that involve at least one control factor;  $W_{sn}$  consists of  $A_{i,j}$  with i = 0 that involve only noise factors. We call  $W_{sm}$  the mixed wordtype pattern sequence and  $W_{sn}$  the noise wordtype pattern sequence. Next we append  $W_{sn}$  in the end of  $W_{sm}$  to form a longer sequence  $(W_{sm}, W_{sn})$ , which is called the split wordtype pattern sequence.

Based on  $(W_{sm}, W_{sn})$ ,  $(W_{sm}, W_{sn})$ -aberration and the minimum  $(W_{sm}, W_{sn})$ -aberration criterion can be defined. Note that, in  $(W_{sm}, W_{sn})$ , noise effects are treated as secondary, and are sacrificed to ensure more estimation capacity for control effects and control-by-noise interactions. Thus both statements (i) and (ii) in the hierarchical ordering principle are violated. It is known that defining words that contain only noise factors can also induce aliasing between important effects. For instance, nnn induces Cn = Cnn. As will be discussed in the following subsection, the split wordtype pattern sequence is one of the possible compromising schemes aimed at allocating most estimation capacity to important effects. It usually does not guarantee the clear estimation of all important effects, neither do other schemes. We propose  $(W_{sm}, W_{sn})$ first because it is a systematic scheme that possesses clear combinatorial structure and often leads to overall good single arrays, especially good ESAs.

#### 4.1.3 Shifted Wordtype Patterns and $W_{ss}$ -Aberration

In contrast to  $(W_{sm}, W_{sn})$ , milder compromising schemes can be introduced by shifting  $A_{0,j}$ with  $j \geq 3$  rightward to new positions in  $W_s$ , instead of appending all of them at the end of  $W_{sm}$ . We propose one possible shifting scheme next. Because the estimation of noise effects is to be compromised, we ignore the aliasing between them in the following discussion. We follow the worst-case argument used by Bingham and Sitter (2003). Consider  $A_{0,3}$  or nnn. The worst alias relation induced by nnn is Cn = Cnn, similar to  $C_1n = C_2nn$ , which is the worst aliasing relation induced by CCnnn. This implies that nnn and CCnnn are comparable in terms of aliasing severity. So we can have either nnn  $\triangleleft CCnnn$  or  $CCnnn \triangleleft nnn$ . We decide to select nnn  $\triangleleft CCnnn$  and move  $A_{0,3}$  to the position between  $A_{3,2}$  and  $A_{2,3}$ . Next, consider  $A_{0,4}$  or nnnn. The worst case induced by nnn is Cnn = Cnn, similar to  $C_1nn = C_2nn$ , which is induced by CCnnnn. Hence, we shift  $A_{0,4}$  to the position between  $A_{4,2}$  and  $A_{2,4}$ . In general, following the same argument, we have  $A_{i,2} \triangleleft A_{0,i} \triangleleft A_{2,i}$  for  $i \geq 3$ . Shifting all  $A_{0,i}$  rightward as described above,  $W_s$  becomes

$$W_{ss} = (A_{2.1}, A_{1.2}, A_{3.0}, A_{2.2}, A_{3.1}, A_{1.3}, A_{4.0}, A_{3.2}, \mathbf{A_{0.3}}, A_{2.3}, A_{4.1}, A_{1.4}, A_{5.0}, A_{3.3}, A_{4.2}, \mathbf{A_{0.4}}, A_{2.4}, A_{5.1}, A_{1.5}, A_{6.0}, A_{4.3}, \ldots).$$

$$(7)$$

 $A_{0.3}$  and  $A_{0.4}$  are highlighted in  $W_{ss}$  to indicate their new positions.  $W_{ss}$  is called the shifted wordtype pattern sequence.

The difference between  $W_{ss}$  and a list of rank-ordered effects given in Bingham and Sitter (2003) is that  $W_{ss}$  further distinguishes wordtype patterns with the same modified wordlength. For example, CCn and Cnn have the same modified wordlength 2.5, but  $CCn \triangleleft Cnn$  in  $W_{ss}$ ; CCC and CCnn have the same modified wordlength 3, but  $CCC \triangleleft CCnn$  in  $W_{ss}$ . Bingham and Sitter (2003) treated nnn as equally important as CCCC, CCCnn and CCnnn, while in  $W_{ss}$ ,  $CCCC \triangleleft CCCnn \triangleleft nnn \triangleleft CCCnn$ . If the wordtypes with the same modified wordlength wordlength wordlength wordlength  $W_{ss}$  is reduced to be

$$W_{DR} = (A_{2.1} + A_{1.2}, A_{3.0} + A_{2.2}, A_{3.1} + A_{1.3}, A_{4.0} + A_{3.2} + \mathbf{A_{0.3}} + A_{2.3}, A_{4.1} + A_{1.4}, A_{5.0} + A_{3.3} + A_{4.2})$$

$$+\mathbf{A_{0.4}} + A_{2.4}, A_{5.1} + A_{1.5}, A_{6.0} + A_{4.3}, \ldots),$$
(8)

which was exactly the sequence proposed in Bingham and Sitter (2003). The  $W_{ss}$ -aberration and the  $W_{DR}$ -aberration can be defined in a standard fashion, so are the minimum  $W_{ss}$ -aberration criterion and the  $W_{DR}$ -aberration criterion. Bingham and Sitter (2003) reported minimum  $W_{DR}$ -aberration designs. Because  $W_{DR}$  is relatively a coarse sequence, it may not be able to discriminate designs that may have different aliasing and structural properties.

In summary, on one hand,  $W_{ss}$  is more elaborate than  $W_{DR}$ , therefore it is more sensitive in discriminating different designs. On the other hand,  $W_{DR}$  is more conservative, because the minimum  $W_{DR}$ -aberration criterion usually leads to a group of designs so that good designs would not be missed.

#### 4.2 Optimal Economical Single Arrays

Because PSAs and ESAs are fairly different from each other in terms of their relative estimation capacities, different optimality criteria should be employed to select optimal PSAs and ESAs. In this section, we will focus on the selection of optimal ESAs. For ESAs, because their relative estimation capacities are already limited, the minimum  $W_{ss}$ -aberration and  $(W_{sm}, W_{sn})$ -aberration criteria are more appropriate than the minimum  $W_s$ -aberration criterion. We have also found that  $W_{ss}$ -aberration and  $(W_{sm}, W_{sn})$ -aberration often lead to the same optimal ESAs. Hence, the minimum  $(W_{sm}, W_{sn})$ -aberration criterion more genuinely reflects the structures of optimal ESAs. In this paper, we only report the ESAs with minimum  $(W_{sm}, W_{sn})$ -aberrations.

Similar to the selection of optimal COAs, we have carried out exhaustive computer search with isomorphism checking to select ESAs with minimum  $(W_{sm}, W_{sn})$ -aberration, and have obtained all the optimal 16-, 32- and 64-run (up to 16 factors) ESAs. Due to limited space, only some of the optimal ESAs are chosen and presented in Table 3. There are two general rules to guide the choice of optimal ESAs. First, Table 3 only includes optimal ESAs with  $l_c + l_n \leq 2^{k-1}$ for k = 4, 5;  $l_c + l_n \leq 16$  for k = 6. Second, if an optimal ESA with  $l_c$  and  $l_n$  is also an ordinary MA  $2^{(l_c+l_n)-m}$  design ( $m = l_c + l_n - k$ ), it is not listed in Table 3. The complete tables of 16-, 32- and 64-run optimal ESAs can be requested from the authors.

# 4.3 Optimal Prodigal Single Arrays

For fixed  $l_c$  and  $l_n$ , compared with ESAs, PSAs have larger relative estimation capacities. Hence, discrimination against less important effects in the selection of optimal PSAs may not be as necessary as in the selection of optimal ESAs. Among the three optimality criteria proposed in Sections 4.1.2-3, it appears that the minimum  $W_s$ -aberration criterion is the most suitable for PSAs. Although, for most  $l_c$  and  $l_n$ , the optimal PSAs according to the minimum  $W_s$ -aberration criterion are much better than the optimal PSAs according to the other two criteria in terms of strengths and the number of clearly estimable effects, there exist cases where the latter two criteria select better arrays. These cases occur usually when  $(l_c, l_n)$  are on the boundary of  $S(2^k)$  in the sense that there does not exist  $(l'_c, l'_n) \in S(2^k)$  such that  $l'_c \ge l_c$ ,  $l'_n \ge l_n$  and  $l'_c + l'_n > l_c + l_n$ . Hence, when constructing the tables of optimal PSAs of 16-, 32- and 64-run, we have considered all the three criteria. In the cases where the criteria lead to different optimal PSAs, if one optimal PSA is apparently better than the others, it will be selected only; if they are comparable with each other, we keep all of them in the tables. The obtained optimal PSAs are reported in Table 4 including 16- and 32-run arrays and in Table 5 including 64-run arrays with up to 16 factors.

In both Tables 4 and 5, from the left to the right, the first two columns give  $(l_c, l_n)$  and the independent defining words (or Generators), the next three columns indicate whether an array is optimal according to  $W_{s^-}$ ,  $(W_{sm}, W_{sn})$ - and  $W_{ss}$ -aberration, and the last two columns indicate whether the array is also a COA and whether it is a MA design with the distinction between control and noise factors neglected. For example, in Table 4, there are two optimal 32-run PSAs for  $l_c = 4$  and  $l_n = 3$ , which are

Table 3:	16-	32-	and	64-Run	Optimal	ESAs

Dociern	reperator	aloon 96
16-run.	generator	Utai 211
(2,4) (2,5) (2,6)	abc ABad abd ace ABbc abd ace bcf ABabc	(2, 1, 0, 4, 2) (2, 0, 0, 2, 0) (2, 0, 0, 0, 0)
32-run:		
$\begin{array}{c} (4,5)\\ (5,4)\\ (2,8)\\ (4,6)\\ (5,5)\\ (6,4)\\ (2,9)\\ (3,8)\\ (4,7)\\ (5,5)\\ (7,4)\\ (8,310)\\ (3,9)\\ (4,8)\\ (5,7)\\ (6,6)\\ (2,11)\\ (3,10)\\ (4,9)\\ (2,11)\\ (2,13)\\ (3,12)\\ (2,14)\\ (3,13) \end{array}$	ABac ABbd Aabe BCDab abd ACac BDac ABEb abd ace bcf abcg ABah abd ace bcf ACabc ABDa abd ace bcf ACabc ABDa abd ace bCb BDbc ABEa abc ABDa ACEa BCFa ABCbd abe acf bcg abch adi ABbd abd ace bcf Acabc Babch ABCa abd ace bcf ACabc BDabc ABEa abd ace bcf ACabc BDbc ABEa abd ace ACbc BDbc ABEa ABFabc ABac ACDa BCEa ABCF Aabd BGab ABDa ACEa BCFa ABCG Aabc BHab abe acf bcg abch adi bdj ABcd abf acg adh Abcd aei Bbce Cbde abd ace bcf ACabc BDabc ABEa ABFbc ACab CBabc BDabc ABEa ABFbc abd ace bcf ACabc BDabc ABEa abf acg adh Abcd aei Bbce Cbde abd ace bcf ACabc BDabc ABEa ABFbc ACab Dabc Aacd AEbc BFab ABGa ABbch abe acf bcg abch adi bdj abdk ABcd abe acf bcg abch adi bdj abdk ABcd abe acf bcg abch adi bdj abdk call ACad abf acg adh Abcd aei Bbce Cbde aba ace bcf ACabc BDabc ABEa ABFbc ACab Dabc Aacd AEbc BFab ABGa ABHb abe acf bcg abch adi bdj abdk call ABacd abf acg adh Abi acij ABabc ACabd Acdk abe acf bcg abch adi bdj abdk call ABacd abe acf bcg abch adi bdj abdk call ABacd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam ABbcd abe acf bcg abch adi bdj abdk call acam Abbcd abe acf bcg abch adi bdj abdk call acam ACabb Acadl abe acf bcg abch adi bdj abdk call acam ACabb Acadl abe acf bcg abch adi bdj abdk call acam ACabb Acadl abe acf bcg abch adi bdj abdk call acam ACabbcd	$ \begin{array}{l} (4,5,5,10,0) \\ (5,1,0,7,2) \\ (2,1,0,12,6) \\ (4,0,0,8,0) \\ (5,0,0,4,0) \\ (5,0,0,4,0) \\ (6,1,0,6,2) \\ (2,0,0,10,0) \\ (3,2,0,4,0) \\ (4,1,0,4,0) \\ (5,0,0,4,0) \\ (6,0,0,0,0) \\ (7,4,0,0,0) \\ (7,4,0,0,0) \\ (8,3,0,0,0) \\ (2,0,0,8,0) \\ (3,0,0,3,0) \\ (4,2,0,0,0) \\ (5,1,0,0,0) \\ (5,1,0,0,0) \\ (5,1,0,0,0) \\ (5,1,0,0,0) \\ (5,1,0,0,0) \\ (5,1,0,0,0) \\ (5,1,0,0,0) \\ (5,1,0,0,0) \\ (2,0,0,6,0) \\ (3,1,0,0,0) \\ (2,0,0,2,0) \\ (3,1,0,0,0) \\ (2,0,0,0,0) \\ (2,0,0,0,0) \\ (3,1,0,0,0) \\ (2,0,0,0,0) \\ (3,1,0,0,0) \\ (2,0,0,0,0) \\ (3,1,0,0,0) \\ (3,1,0,0,0) \end{array} $
64-run:		
	abe acf bcg Aabch ACad BDabcd Cabc Dabd AEacd BFacd ABGab ABHbcd abe acf bcg adh Aabci ACbd ABDacd abd ace bcf abcg ABDa ACEb BCch Aabd Aace ADbc BEabc CFabc ABCG ABCHabc ABCE ABDF ACDG ABHa BCDbc Aabd ABCDIab abf acg bch adi bdj Babce Cabde ADcde abe acf bcg abch adi ACbd BDabd ABEc abd ace bcf Abac ABDa ACEb BCFc ABCabch abd ace bcf ADabc ABEa ACFa BCGabc ABCHbc ABCE ABDF ACDG ABHa ACEb BCFc ABCabch abd ace bcf ADabc ABEa ACFa BCGabc ABCHbc ABEa ACFa BDGa CDHa ABCDIa Aabc BCabd ABCJb abe acf bcg adh bdi acdj ACabc BAbcd BBCd abe acf bcg adh bdi acdj ACab BAbcd ABEb abe acf bcg abch adi bdj ACcd BDacd ABEb abe acf bcg abch adi bdj ACcd BDacd ABEb abe acf bcg abch adi Abb BDbd ABEc ABFabcd abe acf bcg abch adi bdj ACcd BDacd ABEb abe acf bcg abch adi Abb BDbd ABEc ABFabcd abe acf bcg abch adi Abb BDbd ABEc ABFabcd abe acf bcg abch Adi Abc BCbd BFabcd ABGb ABHacd abe acf bcg abch Abbc Abbh BEabcd ABGb ABHacd abd ace bcf ADabc BEbc ABFa CGbc ACHa BCIabc ABCJ abd ADac BEac ABFb CGac ACHb BCIabc ABCJ abd ADac BEac ABFb CGac ACHb BCIabc ABCJ abe acf bcg adh bdi acdj bcdk ACabc Aabdl ABDcd abe acf bcg adh bdi acdj bcdk ACabc Abdl ABDcd abe acf bcg adh bdi acdj bcdk ACabc Abdbl ABLC abd ace bcf ADabc BEbc ABFa CGbc ACHa BCIabc ABCJ abd ADac BEac ABFb CGac ACHb BCIabc ABCJ abd ADac BEac ABFb CGac ACHb BCIabc ABCJ abe acf bcg abch adi bdj ACcd BDacd ABEb abe acf bcg abch adi bdj ACcd BDacd ABEa ABFbcd abf acg adh Bbcd aei Cbce Dbde AEbc AFabde AGGacde abe acf bcg Cabcd ADabc AEad BFabc CGabc ACHb BCIc ABCJ abd ace bcf ADabc BEabc ABFa CGabc ACHb BCIc ABCJ abd ace bcf ADabc BEabc ABFa CGabc ACHb BCIc ABCJ abd ace ADbc BEbc ABFa CGabc ACHb BCIa CABCJ ABCK	$ \begin{array}{c} (4, 2, 5, 20, 4) \\ (8, 4, 12, 24, 0) \\ (4, 1, 5, 20, 2) \\ (5, 1, 2, 26, 5) \\ (8, 5, 6, 30, 0) \\ (9, 4, 6, 16, 0) \\ (4, 1, 5, 20, 0) \\ (5, 0, 2, 23, 0) \\ (6, 1, 0, 24, 4) \\ (8, 0, 0, 24, 0) \\ (9, 0, 0, 20, 0) \\ (10, 4, 4, 12, 0) \\ (4, 1, 5, 22, 0) \\ (5, 0, 2, 20, 0) \\ (6, 0, 0, 20, 0) \\ (10, 4, 4, 12, 0) \\ (4, 1, 5, 22, 0) \\ (5, 0, 2, 20, 0) \\ (6, 0, 0, 20, 0) \\ (7, 1, 0, 14, 1) \\ (8, 0, 0, 15, 0) \\ (9, 0, 4, 12, 0) \\ (11, 1, 0, 8, 2) \\ (4, 1, 5, 24, 0) \\ (5, 0, 2, 17, 0) \\ (6, 0, 0, 14, 0) \\ (7, 0, 0, 16, 0) \\ (11, 1, 0, 8, 2) \\ (4, 1, 5, 24, 0) \\ (5, 0, 2, 17, 0) \\ (6, 0, 0, 14, 0) \\ (7, 0, 0, 10, 0) \\ (8, 1, 0, 14, 1) \\ (9, 1, 0, 8, 0) \\ (10, 0, 3, 12, 0) \\ (11, 0, 0,$

Design Generators 
$$W_s$$
  $(W_{sm}, W_{sn})$   $W_{ss}$  COA MA  
 $\begin{pmatrix} (4,3) \\ (4,3) \\ abc \ ABCDa \end{pmatrix}$   $\checkmark$   $\checkmark$   $\checkmark$   $\checkmark$   $\checkmark$   $\checkmark$ 

We refer to the first array above as  $d_1$  and the second as  $d_2$ .  $d_1$  is optimal according to the minimum  $W_s$ -aberration criterion and it is in fact an optimal COA, while  $d_2$  is optimal according to the minimum  $(W_{sm}, W_{sn})$ -aberration and  $W_{ss}$ -aberration criteria. Note that for a 32-run parameter design experiment involving four control factors and three noise factors, the optimal COA coincides with the optimal PSA according to  $W_s$ -aberration. However, this is not generally true in other cases as shown in Tables 4 and 5. It is not difficult to see that  $d_2$  is not a COA.  $d_2$  guarantees the clear estimation of all the control main effects , the control-by-control 2fi's and the control-by-noise 2fi's, but the noise main effects and noise-by-noise 2fi's are aliased with each other. In  $d_1$ , the noise main effects and noise-by-noise 2fi's are clearly estimable, but the control-by-control 2fi's are aliased with each other. As a single array,  $d_2$  is better than  $d_1$ if the noise 2fi's are assumed to be negligible.

When  $l_c = 3$  and  $l_n = 5$ , there are also two optimal 32-run PSAs reported in Table 4, which are

Design Generators 
$$W_s$$
  $(W_{sm}, W_{sn})$   $W_{ss}$  COA MA  
(3,5) Aabd Aace ABCbc  $\checkmark$   $\checkmark$   $\checkmark$   
(3,5) abd ace ABCbc  $\checkmark$   $\checkmark$   $\checkmark$ 

We denote the first array above as  $d_3$  and the second array as  $d_4$ .  $d_3$  is optimal according to the minimum  $W_s$ -aberration criterion while  $d_4$  is optimal according to the minimum  $(W_{sm}, W_{sn})$ aberration and  $W_{ss}$ -aberration criteria. Neither of  $d_3$  and  $d_4$  is COA. The optimal 32-run COA
for three control factors and four noise factors given in Table 1 is generated by ABC, Aabd and Bace and we denote it as  $d_5$ . In terms of the number of clearly estimable effects,  $d_3$  and  $d_4$  are
better than  $d_5$ .

#### **5 CONCLUDING REMARKS**

In this paper, we suggest that structural constraints and relative estimation capacities should be taken into consideration when selecting optimal plans for parameter design experiments. We have proposed various optimality criteria for selecting useful COAs, ESAs and PSAs. Using the tables provided in this paper, experimenters can consider and compare possible good experimental plans, which are optimal in one way or another, and choose the one that best fits their experimental constraints, capacity and goals. For example, suppose there are four control

Design	Generators	$W_s$	$(W_{sm}, W_{sn})$	$W_{ss}$	COA	MA
16-Run:						
(1, 4)	Aabcd			,		
(2, 3)	ABabc ABCab		/		$\checkmark$	
(3, 2) (4, 1)	ABCDa		$\sqrt[n]{\sqrt{1}}$			
(1, 5)	abd ace	•	$\sqrt[n]{}$	$\sqrt[v]{}$	$\checkmark$	•
(3, 3)	ABCa ABbc	$\checkmark$	/	/		$\checkmark$
(3, 3) (5, 1)	ABDa ACEa	./	$\sim$	$\overline{\mathbf{v}}$		./
(1, 6)	abd ace bcf	v	$\sqrt[n]{}$	$\sqrt[]{}$	$\checkmark$	v
(6, 1)	ABDa ACEa BCFa	$\checkmark$		V,		$\checkmark$
$\begin{pmatrix} 1, 7 \\ 7 & 1 \end{pmatrix}$	abd ace bcf abcg ABDa ACEa BCEa ABCC	. /		$\checkmark$	$\checkmark$	. /
(1, 1)		v	V	$\mathbf{v}$		V
32-Run: (1 5)	Aabede	./			./	./
(2, 4)	ABabcd	$\sqrt[n]{}$			$\sqrt[n]{}$	$\sqrt[n]{}$
(3, 3)	ABCabc	V,	,	V,		V,
(4, 2)	ABCDab					
(1, 6)	abce Aabdf	V	$\mathbf{v}$	$\mathbf{v}$	1	
(2, 5)	abcd ABabe			$\checkmark$	$\checkmark$	V.
(3, 4)	abcd ABCab				,	
(4, 3) (4, 3)	ABCD ABabc abc ABCDa	$\checkmark$	./	./	$\checkmark$	$\checkmark$
(5,2)	ABCD ABEab	$\checkmark$	$\sqrt[n]{}$	$\sqrt[n]{}$		
(6, 1)	ABCE ABDFa	V,			,	$\overline{}$
(1,7)	abce abdf Aacdg			/		
(2, 0) (3, 5)	Aabd Aace ABCbc	V		$\mathbf{v}$	$\mathbf{v}$	V
(3,5)	abd ace ABCbc	v	$\checkmark$	$\checkmark$		v
(5, 3)	ABDa ACEa BCabc					
(6, 2)	ABCE ABDF ACDCa	$\checkmark$		$\checkmark$		$\sim$
(1, 8)	abcf abdg abeh Aacde	$\sqrt[n]{}$	V	V		$\sqrt[n]{}$
(2,7)	abce abdf acdg ABbcd	V.		$\checkmark$		v
(3, 6)	Aabd Aace Abcf BCabc	$\checkmark$	/	/		
(3, 0) (6, 3)	ABDa ACEa BCFa ABCbc	1	$\checkmark$	$\checkmark$		
(7,2)	ABCE ABDF ACDG BCDab	$\sqrt[v]{}$	$\checkmark$	$\checkmark$		$\checkmark$
(8, 1)	ABCF ABDG ABEH ACDEa			V,	,	
(1,9)	abe acf adg bedh abedi abd ace hef abea ABCa			$\checkmark$	$\checkmark$	
(3, 7) (7, 3)	aba ace bej abeg ADea abc ABDa ACEa BCFa ABCGb		$\sqrt[n]{}$	$\sqrt[n]{}$		
(9,1)	ABEa ACFa ADGa BCDHa ABCDI	$\checkmark$		V.		$\checkmark$
(1, 10)	abe acf bcg adh bcdi abcdj	/			$\checkmark$	/
(10, 1) (1, 11)	abe acf bea adh bdi acdi bedk	$\checkmark$	$\mathbf{v}$	$\sim$	./	$\checkmark$
(11, 1)	ABCE ABDF ACDG BCDH ABIa ACJa ADKa	$\checkmark$	$\sqrt[n]{}$	$\sqrt[n]{}$	v	$\checkmark$
(1, 12)	abe acf bcg adh bdi acdj bcdk abcdl	,		V,	$\checkmark$	
(12, 1) (1, 13)	ABUT ABDG AUDH BUDI ABEJ AUEK BUEL ADEa abe act bea abeb adi bdi abdk edl aedm	$\checkmark$		$\checkmark$	./	$\checkmark$
(13, 1)	ABEa ACFa BCGa ABCH ADIa BDJa ABDK CDLa ACDM		$\sqrt[n]{}$	$\sqrt[n]{}$	V	
(1 1 4)	ACDM	v	•	•	,	*
(1, 14)	abe act beg aben adı bdj abdk edl aedm bedn ABEa ACEa BCCa ABCH ADIa BDIa ABDK CDIa	./			$\checkmark$	./
(14,1)	ACDM BCDN	V	$\mathbf{v}$	$\mathbf{v}$		$\mathbf{v}$
(1, 15)	abe acf bcg abch adi bdj abdk cdl acdm bcdn abcdo	,			$\checkmark$	,
(15, 1)	ABEA AUFA BUGA ABUH ADIA BDJA ABDK CDLA ACDM BCDN ABCDOa	$\checkmark$	$\checkmark$	$\checkmark$		$\checkmark$

Table 4: 16- and 32-Run Optimal PSAs with  $(l_c, l_n) \in \mathcal{S}(2^k)$ 

Design	Generators	Ws	$(W_{sm}, W_{sn})$	Wss	COA	MA
(1, 6)	Abcdef		( 311) 311)	/		
(2, 5) (3, 4)	ABaocae ABCabcd	$\checkmark$		$\sqrt[]{}$	$\sqrt[]{}$	$\sqrt[]{}$
(4, 3)	ABCDabc		/	V,	$\checkmark$	V,
(6, 1)	ABCDEFa	$\checkmark$	$\overset{\vee}{\checkmark}$	$\checkmark$		$\sqrt[n]{}$
(1,7)	Aabcf abdeg Aabce Babdf					
(2, 0) (3, 5)	ABabd Cabce	$\checkmark$			$\sqrt[n]{}$	$\sqrt[n]{\sqrt{2}}$
(4, 4)	Aabcd ABCDa ABaba ABCDE	V,		/		V,
(6, 2)	ABCEa ABDFb	$\checkmark$	$\checkmark$	$\sqrt[n]{}$	$\mathbf{v}$	$\sqrt[n]{}$
(7, 1)	ABCFa ABDEG	V,		$\checkmark$	/	V,
(2,7)	abce Aabdf Bacdg	$\checkmark$			$\checkmark$	$\sqrt[n]{}$
(3, 6)	abce ACabd Bacdf			/	$\checkmark$	
(4, 5) (5, 4)	abcd ABDab ACEac	V.		v		V.
(6,3)	ABCE ABabc ACDFa abc ABCEa ABDEb	$\checkmark$	./	./		$\checkmark$
(7, 2)	ABCE ABDFa ACDGb		V.	V.		
(8, 1) (1, 9)	ABCF ABDGa ACDEH abcf Aabda Aabeb acdei	$\sim$	$\checkmark$	$\checkmark$	./	
(2, 8)	abcf Aabdg Aabeh Bacde	V.			V.	$\sqrt[V]{}$
(3,7) (4,6)	abcf abdg Bacde ACabe abce abdf ACacd BDbcd	$\sim$		./	$\checkmark$	
(5, 5)	abce ACabd BDabd ABEac	$\checkmark$		v .		$\checkmark$
(5,5) (6,4)	abd ace ABDbc ACEabc abcd ABDab ACEab BCFac	~/	$\checkmark$	$\checkmark$		1
(7, 3)	ABCE ABDF ACDGa ABabc	v	,	,		v
(7, 3) (8, 2)	abc ABCE ABDFa ACDGb ABCF ABDGa ABEHa ACDEb	~				1
(9, 1)	ABCF ABDGa ABEHa ACDEI	Ň,	v	v	,	V,
(1, 10) (2, 9)	abcg abdh acdei acdfj Aabef abcf abdg abeh acdei ABbcde					$\checkmark$
(3, 8)	abcf abdg abeh Bacde ACbcde	Ň,		v	•	,
(4, 7) (4, 7)	abce abdf ACacd BDacd ABabg abe acf adg ACbcd BDabcd	$\checkmark$			$\checkmark$	$\checkmark$
(5, 6)	abce abdf ÅCacd BDacd ABEab			$\checkmark$		,
(6, 5) (6, 5)	abd ace ABDbc ACEbc BCFabc	$\checkmark$				$\checkmark$
(7, 4)	ABCE ABDF ACDac ACDbd ABGab		·	•		$\checkmark$
(8,3)	abc ABCE ABDFa ACDGb BCDHab	$\checkmark$	$\checkmark$	$\checkmark$		
(9, 2)	ABCF ABDG ABEH ACDEI BCDEab		V,	V,		,
(10, 1) (1, 11)	abcg abdh acei adfj aefk Aabcdef	$\checkmark$	$\checkmark$	$\checkmark$		$\checkmark$
(2, 10)	abcf abdg aceh adei abcdej ABacd	$\checkmark$		/	Ň,	
(2, 10) (3, 9)	abe acf beg adh bedi ABCabed			$\sqrt[n]{}$	$\checkmark$	
(3, 9)	abe acf bcg abch adi ABCabd ABCE ABDe ACDed ACDes ABabf BCDebs	/	$\checkmark$			/
(5,7)	abe acf adg ACbcd BDabcd ABEb	v		$\checkmark$		v
(5,7)	abd ace bcf abcg ABDa ACEb abce abdf ACacd BDacd ABEab ABEbcd	./	$\checkmark$	./		./
(7, 5)	abd ace ABDbc ACEbc BCFbc ABCGa	v .	$\checkmark$	$\checkmark$		v
(9, 3)	ABCG ABDH ABEI BCDEa ACFb DEFc abc ABEa ACFa ADGb BCDHa ABCDIab	$\checkmark$	./	./		
(10, 2)	ABCF ABDG ACEH ADEI ABCDEJ ACDab		V.	V.		
(11, 1) (1, 12)	ABCG ABDH ACEI ADFJ AEFK ABCDEFa abca abdh abei Abcde acfi defk acdefl	$\sim$	$\checkmark$	$\checkmark$	./	
(2, 11)	abcf abdg acdh abei acej adek ABbcd	$\checkmark$		,	$\sqrt[2]{}$	
(3, 10) (3, 10)	abe acf bcg adh bdi acdj ABCbcd abe acf bcg abch adi bdi ABCcd		~	$\checkmark$		
(6,7)	ABDa ACEa BCFa ABCbd ABCce abcf ABCabcg	$\checkmark$	v	,		
(7, 6) (10, 3)	abd ace bcf ABDabc ACEabc BCFabc ABCG ABCG ABDH ACEI ADEa ABFJ BCDFb CEFc	~		$\checkmark$		
(10, 3)	abc ABEa ACFa BCGb ADHb BCDIa ABCDJab	•,				
(11, 2) (12, 1)	ABCF ABDG ACDH ABEI ACEJ ADEK BCDao ABCG ABDH ABEI BCDEa ACFJ DEFK ACDEFL	$\checkmark$	$\bigvee$	$\checkmark$		
(1, 13)	abcg abdh acei adej abfk Abcdf cefl defm	V,	•	•		
(2, 12) (3, 11)	abe acf beg adh bdi aedj bedk ABCabed	$\checkmark$		$\checkmark$	$\checkmark$	
(11, 3)	ABCF ABDG ACEH ADEI ABCDEb ABJa ACDac AEKa	$\checkmark$	/			
(11, 3) (12, 2)	ABCF ABDG ACDH BCDI ABEJ ACEK ADEL BCEab	$\checkmark$	$\bigvee$	$\sqrt[n]{}$		
(13, 1)	ABCG ABDH ACEI ADEJ ABFK BCDFa CEFL DEFM	V,		$\checkmark$	./	
(2, 13)	abcf abdg acdh bcdi abej acek bcel adem ABbde	$\sqrt[]{}$		$\checkmark$	$\sqrt[]{}$	
(3, 12)	abe acf bcg abch adi bdj abdk cdl ABCacd ABCG ABDH ACDI BCDI ABEK ACEg ABEL ADEL ABCDEEc	./	$\checkmark$	$\checkmark$		
(12, 3)	abc ABEa ACFa BCGb ADHa BDIb ACDJab BCDKa ABCDL	V .				
(13, 2) (14, 1)	ABCF ABDG ACDH BCDI ABEJ ACEK BCEL ADEM BDEab ABCG ABDH ACEI ADEI ABCDEK ABEL ACDEA AEEM ABCEEN			$\checkmark$		
(1, 15)	abcg abdh acei adej abcdek abfl Aacdf aefm abcefn abdefo	V.	v	v .		
(2, 14) (3, 13)	abct abdg acdh bcdi abej acek bcel adem bden ABcde abe acf bcg abch adi bdi abdk cdl acdm ABCbcd	$\checkmark$	2/		$\checkmark$	
(13, 3)	ABCF ABDG ACDH BCDI ABEJ ACEK ADEb ABLa ACMa ABCDEac	$\checkmark$	×	× ,		
(13, 3) (14, 2)	aoc abla acfa buga abuho adia bdja Abdko udlo audm ABCF ABDG ACDH BCDI ABEJ ACEK BCEL ADEM BDEN CDEab	1				
(15, 1)	ABCG ABDH ACEI ADEJ ABCDEK ABFL ACDFa AEFM ABCEFN ABDEFO	Ň	Ň	Ň		

Table 5: 64-Run Optimal PSAs with  $(l_c, l_n) \in \mathcal{S}(2^k)$ 

factors (A, B, C, D) and five noise factors (a, b, c, d, e) in a parameter design experiment. Because  $(4, 5) \notin S(2^5)$ , there does not exist a 32-run COA with  $l_c = 4$  and  $l_n = 5$ . The optimal 64-run COA d' can be found in Table 2, which is generated by ABCD, ABabd and ACace. The experimenter may also consider if the optimal 64-run PSA can be better. Table 5 lists the optimal 64-run PSA d'' with  $l_c = 4$  and  $l_n = 5$ , which is generated by abce, ACabd and ABCDbc. If the crossing structure is not crucial in experiment and analysis, it appears that d'' is a better choice than d' because d'' guarantees the clear estimation of the control-by-control 2f.i.'s. If the experimenter cannot afford to run a 64-run design, he/she may consider using 32-run ESAs. The optimal 32-run ESA d''' with  $l_c = 4$  and  $l_n = 5$  can be found in Table 3, which is generated by ABac, ABbd, Aabe, BCDab. Due to limited capacity, d''' does not guarantee the clear estimation of all the important effects.

## 6 APPENDIX

Proof of Proposition 1: Sufficiency. Because  $(l_c, l_n) \in \mathcal{S}(2^k)$ ,  $\lceil \log_2(l_c+1) \rceil + \lceil \log_2(l_n+1) \rceil \leq k$ . Let  $k_c = \lceil \log_2(l_c+1) \rceil$  and  $k_n = \lceil \log_2(l_n+1) \rceil$ . It is clear that  $l_c \leq 2^{k_c} - 1$  and  $l_n \leq 2^{k_n} - 1$ . Hence two fractional factorial designs, denoted by  $d_1$  and  $d_2$ , can be constructed for the control factors and the noise factors, respectively. Crossing  $d_1$  and  $d_2$  gives an COA with run size  $2^{k_c} \times 2^{k_n} \leq 2^k$ . Necessity. Suppose d is a COA with  $l_c$  control factors,  $l_n$  noise factors and  $2^k$  runs. Let  $N_c$  and  $N_c$  be the run sizes of the control array and the noise arrays.  $N_c N_n = 2^k$ . Because both  $N_c$  and  $N_n$  are powers of 2, there exist  $k_c$  and  $k_n$  such that  $k_c + k_n = k$ ,  $N_c = 2^{k_c}$  and  $N_n = 2^{k_n}$ . According to the definition,  $t_c \geq \min(l_c, 2)$  and  $t_n \geq \min(l_n, 2)$ . Hence the control array and the noise arrays are either full factorial designs or have resolutions higher than three. Hence, one has  $l_c \leq 2^{k_c} - 1$  and  $l_n \leq 2^{k_n} - 1$ , which implies that  $(l_c, l_n) \in \mathcal{S}(2^k)$ .

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