

# **Optimal relaxation parameter for the Uzawa Method**

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**Summary.** We consider the Uzawa method to solve the stationary Stokes equations discretized with stable finite elements. An iteration step consists of a velocity update  $\mathbf{u}^{n+1}$  involving the (augmented Lagrangian) operator  $-\nu\Delta - \rho\nabla \text{div}$  with  $\rho \ge 0$ , followed by the pressure update  $p^{n+1} = p^n - \alpha\nu \text{div} \mathbf{u}^{n+1}$ , the so-called Richardson update. We prove that the inf-sup constant  $\beta$  satisfies  $\beta \le 1$  and that, if  $\sigma = 1 + \rho\nu^{-1}$ , the iteration converges linearly with a contraction factor  $\beta^2 \alpha \sigma^{-1} (2\sigma - \alpha)$  provided  $0 < \alpha < 2\sigma$ . This yields the optimal value  $\alpha = \sigma$  regardless of  $\beta$ .

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### **1** Introduction

Given an open bounded polygon  $\Omega$  in  $\mathbb{R}^d$ , with  $d \ge 2$ , we consider the stationary Stokes equations, namely the simplest model for incompressible viscous flows:

(1.1) 
$$-\nu \Delta \mathbf{u} + \nabla p = \mathbf{f}, \quad \text{in } \Omega,$$

(1.2) 
$$\operatorname{div} \mathbf{u} = 0, \quad \operatorname{in} \Omega,$$

with vanishing Dirichlet boundary condition  $\mathbf{u} = \mathbf{0}$  on  $\partial \Omega$  and pressure mean-value  $\int_{\Omega} p = 0$ . Here the unknowns are the (vector) velocity field  $\mathbf{u} \in \mathbf{H}_0^1(\Omega)$  and the (scalar) pressure  $p \in L_0^2(\Omega)$ ; the forcing function satisfies  $\mathbf{f} \in \mathbf{L}^2(\Omega)$  and  $\nu = Re^{-1}$  is the reciprocal of the Reynolds number.

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In view of the incompressibility constraint (1.2), the momentum equation (1.1) is equivalent to the *augmented Lagrangian* formulation with  $\rho \ge 0$ 

$$-\nu \Delta \mathbf{u} - \rho \nabla \operatorname{div} \mathbf{u} + \nabla p = \mathbf{f}, \quad \text{in } \Omega.$$

This equivalence is no longer true at the discrete level, where the additional operator  $-\rho \nabla div$  may improve the convergence of iterative methods [3]. We provide a quantitative measure of such improvement in this paper.

The following (infinite-dimensional) Uzawa algorithm to solve the Stokes system is known to converge for appropriate values of the *relaxation parameter*  $\alpha$  [2–6].

**Algorithm 1** (Uzawa Method) Given a suitable relaxation parameter  $\alpha > 0$  and initial guess  $p^0$ :

*Step 1: Find*  $\mathbf{u}^{n+1} \in \mathbf{H}_0^1(\Omega)$  *as the solution of* 

$$-\nu \Delta \mathbf{u}^{n+1} - \rho \nabla \operatorname{div} \mathbf{u}^{n+1} + \nabla p^n = \mathbf{f}, \quad in \ \Omega;$$

*Step 2:* Find  $p^{n+1} \in L^2_0(\Omega)$  from the Richardson update

$$p^{n+1} = p^n - \alpha \nu \operatorname{div} \mathbf{u}^{n+1}.$$

Convergence of Algorithm 1 for  $\rho = 0$  is proved via boundedness and coercivity of the Schur complement operator  $S = -\text{div} (-\Delta^{-1})\nabla$  with sufficiently small  $\alpha < 1$  in [2,4]. In [6] Temam shows the convergence range  $0 < \alpha < 2$  also for  $\rho = 0$ , but does not quite prove that Algorithm 1 is a contraction and thus cannot find the optimal value of  $\alpha$ . For the case  $\rho > 0$ , Fortin and Glowinski prove convergence for  $0 < \alpha \le 2\rho/\nu$  using a spectral analysis [3].

The choice of relaxation parameter  $\alpha > 0$  is crucial for the convergence of Uzawa method because a small value of  $\alpha$  yields a large contraction factor whereas a large value may lead to divergence. It is the purpose of this note to show convergence for all  $0 < \alpha < 2(1 + \rho/\nu)$  and that  $\alpha = 1 + \rho/\nu$ is an optimal choice. This has been already instrumental in [1] for  $\rho = 0$ . Our analysis is in the spirit of that in [6] for  $\rho = 0$ , but it gives rise to more precise bounds.

We consider now a finite element discretization. Let  $\mathfrak{T} = \{K\}$  be a shaperegular partition of  $\Omega$  of local meshsize *h* into closed elements *K*;  $\mathfrak{T}$  can be highly graded though. The finite element spaces to be used for approximating the velocity space  $\mathbf{H}_0^1(\Omega)$  and pressure space  $L_0^2(\Omega)$  are:

$$\mathbb{V}_h := \{ \mathbf{v}_h \in \mathbf{H}_0^1(\Omega) : \mathbf{v}_h |_K \in \mathcal{P}(K), \text{ for all } K \in \mathfrak{T} \}, \\ \mathbb{P}_h := \{ \mathbf{v}_h \in L^2(\Omega) : p_h |_K \in \mathcal{Q}(K), \text{ for all } K \in \mathfrak{T} \}, \end{cases}$$

where  $\mathcal{P}(K)$  and  $\mathcal{Q}(K)$  are spaces of polynomials with degree bounded uniformly with respect to  $K \in \mathfrak{T}$  [2,4]. These spaces are compatible, namely

they satisfy the following discrete *inf-sup condition: There exists a constant*  $\beta > 0$  such that [2,4]

(1.3) 
$$\inf_{p_h \in \mathbb{P}_h} \sup_{\mathbf{v}_h \in \mathbb{V}_h} \frac{\langle \operatorname{div} \mathbf{v}_h , p_h \rangle}{\|\nabla \mathbf{v}_h\| \|p_h\|} \ge \beta;$$

hereafter  $\|\cdot\|$  indicates the  $L^2$ -norm in  $\Omega$ . Hence, there is a unique solution  $(\mathbf{u}_h, p_h) \in \mathbb{V}_h \times \mathbb{P}_h$  to the following discrete Stokes problem [2,4]:

(1.4) 
$$\begin{array}{c} \nu \left\langle \nabla \mathbf{u}_h , \nabla \mathbf{w}_h \right\rangle - \left\langle p_h , \operatorname{div} \mathbf{w}_h \right\rangle = \left\langle \mathbf{f} , \mathbf{w}_h \right\rangle, & \forall \mathbf{w}_h \in \mathbb{V}_h, \\ \left\langle \operatorname{div} \mathbf{u}_h , q_h \right\rangle = 0, & \forall q_h \in \mathbb{P}_h. \end{array}$$

**Proposition 1** (Inf-Sup Constant) Let  $\beta$  be the inf-sup constant of (1.3). *Then we have* 

$$(1.5) \qquad \qquad \beta \le 1$$

The discrete Uzawa method, a discrete version of Algorithm 1, is known to be an effective iteration to compute  $(\mathbf{u}_h, p_h)$ , and reads as follows [2,4].

Algorithm 2 (Discrete Uzawa Method) For a suitable  $\alpha > 0$  and initial guess  $p_h^0 \in \mathbb{P}_h$ :

*Step 1:* Find  $\mathbf{u}_h^{n+1} \in \mathbb{V}_h$  as the solution of

(1.6) 
$$\nu \left\langle \nabla \mathbf{u}_{h}^{n+1}, \nabla \mathbf{w}_{h} \right\rangle + \rho \left\langle \operatorname{div} \mathbf{u}_{h}^{n+1}, \operatorname{div} \mathbf{w}_{h} \right\rangle - \left\langle p_{h}^{n}, \operatorname{div} \mathbf{w}_{h} \right\rangle$$
$$= \left\langle \mathbf{f}, \mathbf{w}_{h} \right\rangle, \quad \forall \mathbf{w}_{h} \in \mathbb{V}_{h};$$

*Step 2:* Find  $p_h^{n+1} \in \mathbb{P}_h$  from the Richardson update

(1.7) 
$$\langle p_h^{n+1}, q_h \rangle = \langle p_h^n, q_h \rangle - \alpha \nu \langle \operatorname{div} \mathbf{u}_h^{n+1}, q_h \rangle.$$

In §§3 and 4, we prove the following sharp decay estimates.

**Theorem 1** (Convergence Rate for Pressure) If  $0 < \alpha < 2\sigma$ , then Algorithm 2 satisfies

(1.8) 
$$||p_h - p_h^{n+1}|| \le (1 - \alpha \beta^2 \sigma^{-2} (2\sigma - \alpha))^{1/2} ||p_h - p_h^n||,$$

where  $\sigma := 1 + \frac{\rho}{v}$ . The same estimate is valid for Algorithm 1.

**Corollary 1** (Convergence Rate for Velocity) Both Algorithms 1 and 2 satisfy

(1.9) 
$$\|\nabla(\mathbf{u}_h - \mathbf{u}_h^{n+1})\| \le \nu^{-1} (1 - \alpha \beta^2 \sigma^{-2} (2\sigma - \alpha))^{n/2} \|p_h - p_h^0\|.$$

*Remark 1.1 (Optimal relaxation Parameter)* Consider now the function  $f(\alpha) = (1 - \frac{\alpha\beta^2}{\sigma^2}(2\sigma - \alpha))$ . We see that Algorithm 2 converges *linearly* with contraction factor  $0 < f(\alpha) < 1$  provided  $0 < \alpha < 2\sigma$ . Since the minimum of  $f(\alpha)$  is  $1 - \beta^2$  at  $\alpha = \sigma$ , we conclude that the *optimal* value of  $\alpha$  is

$$\alpha = 1 + \frac{\rho}{\nu}.$$

We observe that this result is independent of the domain  $\Omega$ , and valid for both Algorithms 1 and 2, whereas the eigenvalues of the Schur complement operator, the discrete version of  $S := \operatorname{div} (\Delta + \rho \nu^{-1} \nabla \operatorname{div})^{-1} \nabla$ , depend on  $\Omega$ . It is plausible that for a given  $\Omega$  and finite element pair  $(\mathbb{V}_h, \mathbb{P}_h)$ , a special analysis would yield a better value for  $\alpha$  since Uzawa is simply a Richardson iteration for the Schur complement. It is also plausible that for a rectangular domain with high aspect ratio,  $\alpha = \sigma$  is the only choice valid for all aspect ratios. This deserves further investigation.

We also point out that (1.9) improves upon [6], where  $\mathbf{u}^n$  is shown to converge weakly in  $\mathbf{H}_0^1(\Omega)$ .

#### 2 Proof of Proposition 1

In this section, we prove a couple of crucial properties of the divergence operator, in particular an upper bound for the inf-sup constant  $\beta$  of (1.3). Since the following known result plays a pivotal role in our subsequent discussion, we present its elementary proof; we refer to [6, p.140].

## **Lemma 2.1** (Div-Grad Relation) For all $\mathbf{v} \in \mathbf{H}_0^1(\Omega)$ , we have

$$\|\operatorname{div} \mathbf{v}\| \le \|\nabla \mathbf{v}\|.$$

*Proof* Given  $\mathbf{v} = (v_i)_{i=1}^d \in \mathbf{H}_0^1(\Omega)$ , there exists a sequence  $\{\mathbf{v}^n\} \in \mathbf{C}_0^\infty(\Omega)$  such that

(2.2) 
$$\|\nabla(\mathbf{v}^n - \mathbf{v})\| \to 0$$
 as  $n \to \infty$ .

Since  $\mathbf{v}^n \in \mathbf{C}_0^{\infty}(\Omega)$ , integration by parts implies

$$\|\operatorname{div} \mathbf{v}^{n}\|^{2} = \int_{\Omega} \left( \sum_{i=1}^{d} \partial_{x_{i}} v_{i}^{n} \right)^{2} d\mathbf{x}$$
$$= \int_{\Omega} \sum_{i=1}^{d} \sum_{j=1}^{d} \partial_{x_{i}} v_{i}^{n} \partial_{x_{j}} v_{j}^{n} d\mathbf{x}$$

$$= \int_{\Omega} \sum_{i=1}^{d} \sum_{j=1}^{d} \partial_{x_i} v_j^n \partial_{x_j} v_i^n d\mathbf{x}$$
$$\leq \int_{\Omega} \sum_{i=1}^{d} \sum_{j=1}^{d} (\partial_{x_i} v_j^n)^2 d\mathbf{x} = \|\nabla \mathbf{v}^n\|^2.$$

The assertion (2.1) follows from (2.2) upon passing to the limit  $n \to \infty$ .  $\Box$ 

Applying Lemma 2.1, we can find an upper bound of the inf-sup constant  $\beta$  of (1.3).

*Proof of Proposition 1* Let  $q_h \in \mathbb{P}_h$  be an arbitrary function. Then, the discrete inf-sup condition (1.3) is equivalent to the existence of a function  $\mathbf{v}_h \in \mathbb{V}_h$  such that [2,4]

(2.3) 
$$\langle \operatorname{div} \mathbf{v}_h, q_h \rangle = \|q_h\|^2$$
 and  $\|\nabla \mathbf{v}_h\| \le \frac{1}{\beta} \|q_h\|.$ 

Then, by virtue of (2.3) and Lemma 2.1, we obtain

$$\|q_h\|^2 = \langle \operatorname{div} \mathbf{v}_h, q_h \rangle \le \|\operatorname{div} \mathbf{v}_h\| \|q_h\| \le \|\nabla \mathbf{v}_h\| \|q_h\| \le \frac{1}{\beta} \|q_h\|^2,$$

which implies the asserted estimate (1.5).

#### **3** Proof of Theorem 1: Case $\rho = 0$

In this section we prove Theorem 1 for  $\rho = 0$ . To this end, we use the following error functions:

$$\mathbf{E}_{h}^{n+1} = \mathbf{u}_{h} - \mathbf{u}_{h}^{n+1}, \qquad e_{h}^{n+1} = p_{h} - p_{h}^{n+1}.$$

We proceed in several steps. Upon subtracting (1.6) (with  $\rho = 0$ ) from (1.4), we have

(3.1) 
$$\nu \langle \nabla \mathbf{E}_h^{n+1}, \nabla \mathbf{w}_h \rangle - \langle e_h^n, \operatorname{div} \mathbf{w}_h \rangle = 0, \quad \forall \mathbf{w}_h \in \mathbb{V}_h.$$

Since  $\mathbf{u}_h$  is a discrete divergence free function, (1.7) can be written by

(3.2) 
$$\langle e_h^{n+1}, q_h \rangle = \langle e_h^n, q_h \rangle - \alpha \nu \langle \operatorname{div} \mathbf{E}_h^{n+1}, q_h \rangle, \quad \forall q_h \in \mathbb{P}_h.$$

If we choose  $\mathbf{w}_h = \mathbf{E}_h^{n+1}$ , then (3.1) becomes

(3.3) 
$$\nu \left\| \nabla \mathbf{E}_{h}^{n+1} \right\|^{2} - \left\langle e_{h}^{n}, \operatorname{div} \mathbf{E}_{h}^{n+1} \right\rangle = 0.$$

In light of (3.2) and (3.3), we obtain

(3.4)  
$$\nu \|\nabla \mathbf{E}_{h}^{n+1}\|^{2} = -\frac{1}{\alpha\nu} \langle e_{h}^{n}, e_{h}^{n+1} - e_{h}^{n} \rangle$$
$$= -\frac{1}{2\alpha\nu} \left( \|e_{h}^{n+1}\|^{2} - \|e_{h}^{n}\|^{2} - \|e_{h}^{n+1} - e_{h}^{n}\|^{2} \right).$$

Consequently, we arrive at

(3.5) 
$$2\alpha\nu^{2} \|\nabla \mathbf{E}_{h}^{n+1}\|^{2} + \|e_{h}^{n+1}\|^{2} = \|e_{h}^{n}\|^{2} + \|e_{h}^{n+1} - e_{h}^{n}\|^{2}.$$

The next step is to estimate  $||e_h^{n+1} - e_h^n||^2$ . Choosing  $q_h = e_h^{n+1} - e_h^n$  in (3.2) gives

$$\|e_{h}^{n+1} - e_{h}^{n}\|^{2} = -\alpha\nu \left\langle \text{div } \mathbf{E}_{h}^{n+1}, e_{h}^{n+1} - e_{h}^{n} \right\rangle \le \alpha\nu \|\text{div } \mathbf{E}_{h}^{n+1}\| \|e_{h}^{n+1} - e_{h}^{n}\|,$$

whence

(3.6) 
$$\left\|e_{h}^{n+1}-e_{h}^{n}\right\|\leq\alpha\nu\left\|\operatorname{div}\mathbf{E}_{h}^{n+1}\right\|\leq\alpha\nu\left\|\nabla\mathbf{E}_{h}^{n+1}\right\|$$

Replacing (3.6) into (3.5) immediately leads to

(3.7) 
$$v^{2}\alpha(2-\alpha) \left\| \nabla \mathbf{E}_{h}^{n+1} \right\|^{2} + \left\| e_{h}^{n+1} \right\|^{2} \leq \left\| e_{h}^{n} \right\|^{2}.$$

We finally prove (1.8) for  $\rho = 0$ . Since  $e_h^n \in \mathbb{P}_h$ , there exists a function  $\mathbf{v}_h \in \mathbb{V}_h$  such that

(3.8) 
$$\langle \operatorname{div} \mathbf{v}_h, e_h^n \rangle = \|e_h^n\|^2$$
 and  $\|\nabla \mathbf{v}_h\| \leq \frac{1}{\beta} \|e_h^n\|,$ 

which is equivalent to (1.3) [2,4]. In view of (3.1) and (3.8), we get

$$\begin{split} \|\boldsymbol{e}_{h}^{n}\|^{2} &= \left\langle \operatorname{div} \mathbf{v}_{h} , \, \boldsymbol{e}_{h}^{n} \right\rangle \\ &= \nu \left\langle \nabla \mathbf{E}_{h}^{n+1} , \, \nabla \mathbf{v}_{h} \right\rangle \\ &\leq \nu \|\nabla \mathbf{E}_{h}^{n+1}\| \|\nabla \mathbf{v}_{h}\| \\ &\leq \frac{\nu}{\beta} \|\nabla \mathbf{E}_{h}^{n+1}\| \|\boldsymbol{e}_{h}^{n}\|. \end{split}$$

Consequently,

(3.9) 
$$\beta \left\| e_h^n \right\| \le \nu \left\| \nabla \mathbf{E}_h^{n+1} \right\|$$

In light of (3.7) and (3.9), we easily obtain

$$\beta^{2}\alpha(2-\alpha) \|e_{h}^{n}\|^{2} + \|e_{h}^{n+1}\|^{2} \le \|e_{h}^{n}\|^{2},$$

which implies (1.8) for  $\rho = 0$ , and thus completes the proof of Theorem 1.

On the other hand, Corollary 1 follows from (3.3) together with Proposition 1 and Theorem 1.

## 4 Proof of Theorem 1: Case $\rho > 0$

In this section, we prove Theorem 1 for  $\rho > 0$ . We note that both (3.2) and (3.6) are still valid for  $\rho > 0$ , because they are solely based on the Richardson update (1.7). Upon subtracting (1.6) (with  $\rho > 0$ ) from (1.4), we have

(4.1)  

$$\nu \langle \nabla \mathbf{E}_{h}^{n+1}, \nabla \mathbf{w}_{h} \rangle + \rho \langle \operatorname{div} \mathbf{E}_{h}^{n+1}, \operatorname{div} \mathbf{w}_{h} \rangle - \langle e_{h}^{n}, \operatorname{div} \mathbf{w}_{h} \rangle = 0, \quad \forall \mathbf{w}_{h} \in \mathbb{V}_{h}.$$

Choosing  $\mathbf{w}_h = \mathbf{E}_h^{n+1}$  and applying (3.2), (4.1) becomes

$$\begin{split} \nu \| \nabla \mathbf{E}_{h}^{n+1} \|^{2} + \rho \| \operatorname{div} \mathbf{E}_{h}^{n+1} \|^{2} &= \langle e_{h}^{n}, \operatorname{div} \mathbf{E}_{h} \rangle \\ &= -\frac{1}{\alpha \nu} \langle e_{h}^{n}, e_{h}^{n+1} - e_{h}^{n} \rangle \\ &= -\frac{1}{2\alpha \nu} \left( \| e_{h}^{n+1} \|^{2} - \| e_{h}^{n} \|^{2} - \| e_{h}^{n+1} - e_{h}^{n} \|^{2} \right), \end{split}$$

instead of (3.4). In light of (3.6), we thus obtain

(4.2)  

$$2\alpha\nu^{2}\left(\left\|\nabla\mathbf{E}_{h}^{n+1}\right\|^{2}+\frac{\rho}{\nu}\left\|\operatorname{div}\,\mathbf{E}_{h}^{n+1}\right\|^{2}-\frac{\alpha}{2}\left\|\operatorname{div}\,\mathbf{E}_{h}^{n+1}\right\|^{2}\right)+\left\|e_{h}^{n+1}\right\|^{2}\leq\left\|e_{h}^{n}\right\|^{2}.$$

Replacing now

$$-\frac{\alpha}{2} \|\operatorname{div} \mathbf{E}_{h}^{n+1}\|^{2} = -\frac{\alpha\nu}{2\rho} \left( \|\nabla \mathbf{E}_{h}^{n+1}\|^{2} + \frac{\rho}{\nu} \|\operatorname{div} \mathbf{E}_{h}^{n+1}\|^{2} \right) + \frac{\alpha\nu}{2\rho} \|\nabla \mathbf{E}_{h}^{n+1}\|^{2},$$

into (4.2), we end up with

$$2\alpha\nu^{2}\left(1-\frac{\alpha\nu}{2\rho}\right)\left(\left\|\nabla\mathbf{E}_{h}^{n+1}\right\|^{2}+\frac{\rho}{\nu}\left\|\operatorname{div}\mathbf{E}_{h}^{n+1}\right\|^{2}\right)+\frac{\alpha^{2}\nu^{3}}{\rho}\left\|\nabla\mathbf{E}_{h}^{n+1}\right\|^{2} +\left\|e_{h}^{n+1}\right\|^{2} \leq \left\|e_{h}^{n}\right\|^{2}.$$
(4.3)

Using inf-sup property (3.8), we deduce

$$\begin{split} \|\boldsymbol{e}_{h}^{n}\|^{2} &= \langle \operatorname{div} \mathbf{v}_{h}, \, \boldsymbol{e}_{h}^{n} \rangle \\ &= \nu \left\langle \nabla \mathbf{E}_{h}^{n+1}, \, \nabla \mathbf{v}_{h} \right\rangle + \rho \left\langle \operatorname{div} \mathbf{E}_{h}^{n+1}, \, \operatorname{div} \mathbf{v}_{h} \right\rangle \\ &\leq \nu \|\nabla \mathbf{E}_{h}^{n+1}\| \|\nabla \mathbf{v}_{h}\| + \rho \|\operatorname{div} \mathbf{E}_{h}^{n+1}\| \|\operatorname{div} \mathbf{v}_{h}\| \\ &\leq \left(\nu \|\nabla \mathbf{v}_{h}\|^{2} + \rho \|\operatorname{div} \mathbf{v}_{h}\|^{2}\right)^{\frac{1}{2}} \left(\nu \|\nabla \mathbf{E}_{h}^{n+1}\|^{2} + \rho \|\operatorname{div} \mathbf{E}_{h}^{n+1}\|^{2}\right)^{\frac{1}{2}} \\ &\leq \frac{\nu \sqrt{\sigma}}{\beta} \|\nabla \boldsymbol{e}_{h}^{n}\| \left( \|\nabla \mathbf{E}_{h}^{n+1}\|^{2} + \frac{\rho}{\nu} \|\operatorname{div} \mathbf{E}_{h}^{n+1}\|^{2} \right)^{\frac{1}{2}}, \end{split}$$

where we have used (2.1) for  $\mathbf{v} = \mathbf{v}_h$  and  $\sigma = 1 + \frac{\rho}{\nu}$ . Consequently, we infer that

$$\|\boldsymbol{e}_{h}^{n}\|^{2} \leq \frac{\nu^{2}\sigma}{\beta^{2}} \left( \left\| \nabla \mathbf{E}_{h}^{n+1} \right\|^{2} + \frac{\rho}{\nu} \left\| \operatorname{div} \mathbf{E}_{h}^{n+1} \right\|^{2} \right)$$

and, making use of (2.1) again for  $\mathbf{v} = \mathbf{E}_h^{n+1}$ , that

$$\|\boldsymbol{e}_h^n\|^2 \leq \frac{\nu^2 \sigma^2}{\beta^2} \|\nabla \mathbf{E}_h^{n+1}\|^2.$$

Replacing these two inequalities into (4.3), we obtain

$$\left(\frac{2\alpha\beta^2}{\sigma}\left(1-\frac{\alpha\nu}{2\rho}\right)+\frac{\alpha^2\beta^2\nu}{\rho\sigma^2}\right)\|e_h^n\|^2+\|e_h^{n+1}\|^2\leq \|e_h^n\|^2,$$

or equivalently,

$$\begin{split} \left\| e_h^{n+1} \right\|^2 &\leq \left( 1 - \frac{\alpha \beta^2}{\sigma^2} \left( 2\sigma - \frac{\alpha \nu}{\rho} (\sigma - 1) \right) \right) \| e_h^n \|^2 \\ &= \left( 1 - \frac{\alpha \beta^2}{\sigma^2} (2\sigma - \alpha) \right) \| e_h^n \|^2. \end{split}$$

This is the asserted estimate (1.8). The proof of Theorem 1 for  $\rho > 0$  is thus complete. Finally, the proof of Corollary 1 for  $\rho > 0$  is identical to the case  $\rho = 0$ .

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