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Optimization of selective laser-induced etching (SLE) for fabrication of 3D glass microfluidic device with multi-layer micro channels



Sungil Kim^{1,2}, Jeongtae Kim¹, Yeun-Ho Joung¹, Sanghoon Ahn², Jiyeon Choi^{2*}, and Chiwan Koo^{1*}

Abstract

We present the selective laser-induced etching (SLE) process and design guidelines for the fabrication of threedimensional (3D) microfluidic channels in a glass. The SLE process consisting of laser direct patterning and wet chemical etching uses different etch rates between the laser modified area and the unmodified area. The etch selectivity is an important factor for the processing speed and the fabrication resolution of the 3D structures. In order to obtain the maximum etching selectivity, we investigated the process window of the SLE process: the laser pulse energy, pulse repetition rate, and scan speed. When using potassium hydroxide (KOH) as a wet etchant, the maximum etch rate of the laser-modified glass was obtained to be 166 µm/h, exhibiting the highest selectivity about 333 respect to the pristine glass. Based on the optimized process window, a 3D microfluidic channel branching to three multilayered channels was successfully fabricated in a 4 mm-thick glass. In addition, appropriate design guidelines for preventing cracks in a glass and calibrating the position of the dimension of the hollow channels were studied.

Keywords: Glass micromachining, 3D laser micromachining, Selective laser-induced etching, Subtractive manufacturing, 3D microchannel, Glass microfluidic device

Introduction

Over the past 30 years, researches on microfluidic devices using soft lithography have been conducted in a variety of industries including biology, chemistry, medicine, food, energy, and the environment [1–4]. The development of robust devices that can respond to various samples is essential for the expansion of the microfluidic devices' capabilities. Typically, most microfluidic devices use polymer materials such as polydimethylsiloxane (PDMS) and polymethymethacrylate (PMMA). Nevertheless, glass can provide many advantages to the microfluidic device research because of its excellent optical properties, mechanical durability, chemical resistance, and easy electrode patterning [5-7]. However, in the fabrication of glass microfluidic devices, various microelectromechanical systems (MEMS) process steps such as masking, etching, drilling, and bonding are required and thus it takes more time and cost than soft lithography [8]. To overcome these disadvantages, we have studied a rapid fabrication process that can make an all-glass microfluidic device within an hour using ultrafast laser 3D direct writing [9, 10]. Ultrafast laser technology has been widely used in the microfabrication of various materials by taking the benefit of ultrashort laser pulses to minimize heat-affected zone (HAZ) which is critical for high precision, high speed, and high-quality manufacturing. Furthermore, the nonlinear absorption, which occurs in transparent media at very high laser intensity exceeding the order of $\sim 10^{12}$ W/cm², is the principle of 3D micro



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^{*}Correspondence: jchoi@kimm.re.kr; cwankoo@hanbat.ac.kr

¹ Department of Electronics and Control Engineering, Hanbat National University, 125 Dongseodaero, Yuseong-gu, Daejeon 34158, Republic of Korea

² Department of Laser and Electron Beam Application, Korea Institute of Machinery and Materials, 156 Gajeongbuk-ro, Yuseong-gu, Daejeon 34103, Republic of Korea

processing in glass [11]. Ultrashort laser pulses cause the absorption of photon only in the vicinity of a laser focus thus enable direct writing of 3D freeform patterns in a transparent material without a mask [12]. Therefore, ultrafast laser process has brought the opportunity of rapid and efficient glass microfabrication to microfluidics research [13–15].

Two-dimensional (2D) microfluidic channels of labon-a-chip and micro total analysis systems (µ-TAS) provide simple and normal fluidic flow but have limited applications [16]. In the notion of three-dimensional (3D) channel structures enabling diverse applications upon intentionally designed complex flow characteristics, numerous 3D fabrication techniques such as multilayer bonding and stereo lithography have been explored [17–19]. Recently, ultrafast laser based 2-photon polymerization (TPP) has been demonstrated [20-22]. However, TPP can only fabricate 3D microstructures in liquid phase polymer or glassy materials, thus the strength of final structures is not as stiff as made from solid phase materials. A 3D glass fabrication process called selective laser-induced etching (SLE), which was developed by Marcinkeviciu et al. in 2001, is a two-step hybrid process consisting of ultrafast laser beam irradiation and wet etch [23]. In the first step, a highly focused laser beam locally irradiates a glass and modifies its material properties to increase the chemical etch-ability. The laser-exposed area has different chemical and physical properties from pristine glass due to the nano-grating formation, volume expansion, and internal stress [24-27]. In the second step, the modified area is selectively removed by wet etch. Therefore, the SLE process is basically a subtractive technique such as computer numerical control (CNC) or milling, not additive manufacturing such as a conventional 3D printer. It is similar to the stereo lithography for 3D structure fabrication using positive photoresist.

In the 3D structure fabrication, subtractive manufacturing like SLE process has several advantages over additive manufacturing. First, the tunneling process to etch a path inside material is very effective in fabricating microfluidic channels and drilling holes with a high aspect ratio. Second, it is possible to fabricate rigid 3D structures maintaining intrinsic material properties because the subtractive manufacturing only removes unnecessary regions without adding other materials to the 3D structure. Besides, subtractive manufacturing does not require additional work-pieces such as supports and bridges, unlike additive manufacturing. Third, it is a faster process than conventional glass microfabrication using photolithography, wet etching, and laser ablation. In particular, its' direct writing nature offers any freeform patterns programmed in computer-aided design (CAD) without a mask, and the structure formed inside glass has high durability because of no bonding process [28]. It also provides the good surface quality below 1 μ m surface roughness after wet etching [10, 15, 29].

However, sufficient investigations have not been conducted extensively yet to understand sophisticated variation of process parameters of the SLE process to obtain high precision and dimension control for 3D microstructures inside glass. Therefore, in this paper, we fabricated 3D glass microfluidic channels with SLE process optimization based on the ultrafast laser. As a result, the microfluidic channel height resolution and channel expansion (dimension error) due to etching of the non-modified area were investigated.

Experiment setup

For the SLE experiments, an ultra-short pulsed laser (Satsuma HP2, Amplitude Systèmes, Pessac, France) with a central wavelength of 1030 nm and the maximum output power of 20 W was used. The maximum laser pulse energy was 40 μ J at the pulse repetition rate of 500 kHz and the pulse width variation was from 370 fs to 10 ps. The pulse repetition rate was variable up to 2000 kHz. For 3D fabrication machine, the laser amplifier was integrated with a 2-axis (XY) galvano scanner (DynAXIS, ScanLab, Puchheim, Germany) and an air bearing 3-axis(XYZ) servo motion stage with a controller (A3200, Aerotech, pittsburgh, USA). A focusing objective lens (NA=0.4, model No. 378-867-5, Mitutoyo, Kawasaki, JAPAN) was assembled with the galvano scanner for high scan speed. The focused laser beam size is estimated about 2 µm. The combined scan speed of the scanner and 3D stage is up to 200 mm/s and the field size is 100 mm \times 100 mm. After laser modification process, the exposed glass substrate was etched using 8 mol potassium hydroxide (KOH) at 85 °C in an ultrasonic bath for uniform concentration control.

Optimization of the SLE process window for high selectivity

The SLE process window for high selectivity has been studied by various groups as the selectivity is the most important parameter that affects the fabrication resolution and processing speed of 3D fabrication [24, 25, 30–34]. As shown in the Eq. 1, the etch selectivity (S) can be obtained by dividing the laser-modified glass etch rate per hour (r_m) and the pristine glass (unmodified) etch rate per hour (r_n).

$$S = (r_m + r_n)/r_n. \tag{1}$$

Processing parameters such as focusing geometry, polarization direction, laser pulse width, pulse repetition rate, pulse energy, and scan speed can affect the etch selectivity thus correct combination of process parameters need to be considered during the fabrication process. According to a prior study by Gottman et al., the pulse width of the picosecond regime provides a faster etch rate than femtosecond regime and the polarization direction of the laser leads a faster etch rate of the linearly polarized light of the vector perpendicular to the direction of the laser beam. It has been reported by Hermans et al. and Hnatovsky et al. [25-27, 29]. However, it is a challenging task to maintain vertical linear polarization in a laser scanning path for 3D structures [33]. Therefore, pulse energy, pulse repetition rate, and beam scan speed while using a fixed laser pulse width and x-axis polarization were dominant processing parameters to obtain an optimized process window. 5 mm lines were patterned five times with 50 µm intervals in a 25 mm \times 25 mm \times 1 mm fused silica substrate (JMC glass, Ansan, Korea) as shown in Fig. 1a, b. The depth position was 0.5 mm, and two scan speeds at 50 mm/s and 200 mm/s were tested.

The modification threshold of the laser pulse energy was 300 nJ so that the pulse energy range was set up from 300 to 1000 nJ. The pulse repetition rate was 500 kHz and 1000 kHz. After wet etching in KOH, the substrate was rinsed with deionized (DI) water and dried using nitrogen gas. Then the modified glass was observed through a transmitted illumination optical microscope. Figure 1a, b shows the formation of hollow channels in the glass after KOH etch. The one side of the channels was the starting point for the etch process and larger than the other side. The etch rate of the modified glass and the pristine glass in KOH was measured and the calculated selectivity is summarized in Fig. 1c. The average etch rate of the unmodified glass is 0.5 µm/h. When using 300 nJ and 500 kHz, the average etch rate of the modified glass is about 166 µm/h and the selectivity is up to 333. In addition, it seems that there is no significant difference in the selectivity in terms of the scan speed. However, a higher repetition rate decreases the selectivity since it generated high heat accumulation at the modified area and affected its etch rate.

How to design 3D structures using slice and hatch lines for laser direct writing

We optimized the structuring using slice and hatch lines and fabricated a 3D text structure as a demonstration. Figure 2a shows a schematic of the whole process. A computer software for the laser 3D path creation in a bulk glass was developed to convert from a 3D CAD file consisting of hundreds to millions of vectors (STL format with polygon contour data) to horizontal slicing data (in the z-axis). After the conversion, the area to be removed is automatically filled with hatch lines having a set spacing (The first diagram in Fig. 2a). A fabrication controller

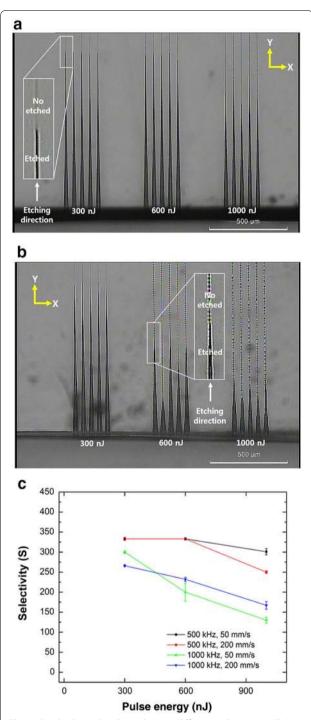
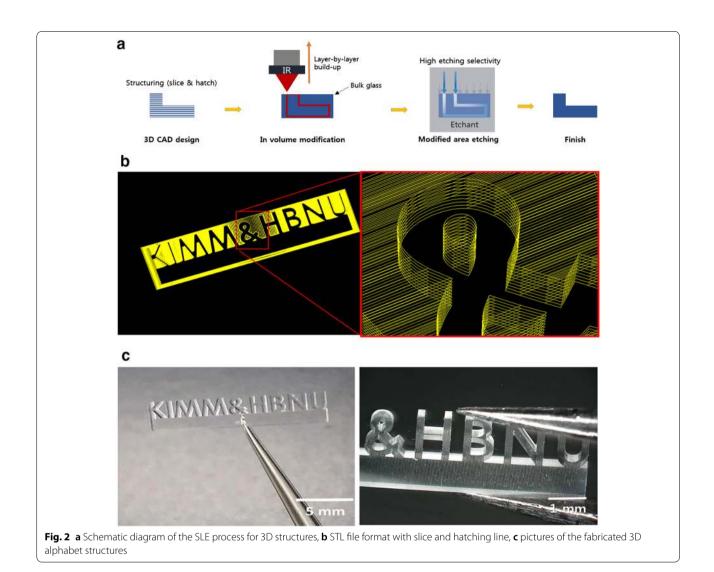


Fig. 1 Single channel etch result using different pulse energy (Ep), pulse repetition rate (Rr), and scan speed (Ss). Etching time in KOH was 6 h. Optical images of fabricated channels with Ep: 300 nJ, 600 nJ, 1000 nJ, Ss: 50 mm/s at different repetition rates **a** Rr: 500 kHz, and **b** Rr: 1000 kHz, **c** a graph of the selectivity according to various combinations of pulse energy, pulse repetition rate, and scan speed



in the laser direct writing system computed the optimized laser beam path and conducted laser direct writing in a glass sample (The second diagram in Fig. 2a). Then, the glass was immersed in KOH to etch the exterior of the 3D structure and to release the structure from the bulk glass (The third and fourth diagram in Fig. 2a). The test structure was designed in normal STL format and converted to slice and hatch data. The slice lines for the structuring are shown in Fig. 2b. Based on the data, the 3D structure was fabricated successfully (Fig. 2c). A 25 mm × 25 mm × 1 mm fused silica was used as a bulk substrate and the dimension of the 3D structure was 17 mm × 2.5 mm × 0.5 mm. The time for laser writing was about 2 h and the wet etch time in KOH was about 12 h.

The smaller slice and hatch line spacing induced a faster wet etch. However proper slice and hatch spacing should be selected, otherwise internal cracking was

occurred during laser direct writing or wet etching process where the glass exposed excessively. To investigate the effect of the small slice and hatch line spacing, several 3D hollow cubes with the width of 500 µm were fabricated using the combinations of the slice and hatch size of 10 or 20 µm. The pulse energy was 300 nJ for overall writing process. As shown in Fig. 3, the dense slice structuring using 10 µm spacing created microcracks at the corners of the cubes where the laser dose was slightly higher than interior of the cube due to the acceleration and deceleration of the scanner. On the other hand, if larger spacing of slice over 40 µm was used, some part of the glass was not etched as designed. Therefore, the slice and hatch sizes should be adjusted appropriately. Figure 4 shows the world smallest glass beer mug with the volume of 3 μ L fabricated with the optimized slice and hatch line spacing of 20 µm, as far as our knowledge goes. It was fabricated with the pulse energy and the scan speed was

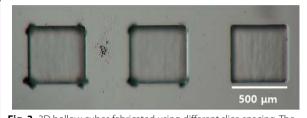
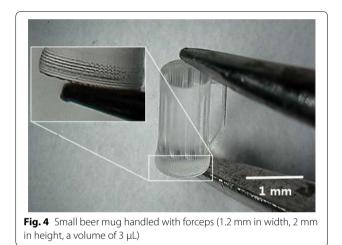


Fig. 3 3D hollow cubes fabricated using different slice spacing. The left one used 10 μ m slice and 10 μ m hatch spacing. The middle one used 10 μ m slice and 20 μ m hatch spacing. The right one used 20 μ m slice and 20 μ m hatch spacing



600 nJ and 200 mm/s respectively, and followed by 12 h etching. In addition, we could fabricate a few micrometer patterns on the bottom and side of the beer mug.

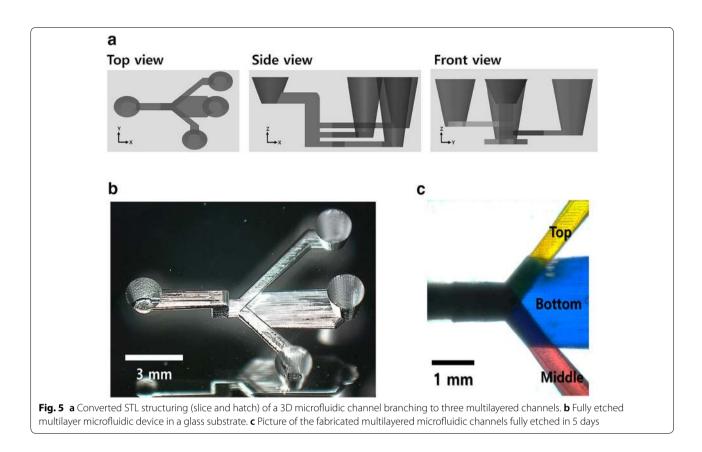
Design and fabrication of 3D glass multilayer microfluidic device

3D glass device having multilayer microfluidic structures was designed and fabricated in a 4 mm thick fused silica substrate, as shown in Fig. 5a. In the design, the maximum length of the 3D microfluidic channel was 11 mm and the branching section to three microfluidic channels was at the center of the 3D channel. The branched microfluidic channels were located at different depths. In the initial experiment, to investigate the minimum resolution for the height of the channel coming from the z-axis slice space, the height of each channel was designed to be 10 μ m that is less than the slice spacing of 20 μ m. Thus, only one slice was used for writing the channels. In a result, the fabricated channel height was about $35-38 \,\mu m$ and it was due to the length of the volume pixel (voxel) of the in-volume focused laser beam that was 35 μ m in depth. Therefore, the length of a voxel determined the minimum resolution of the height of the channel. The horizontal resolution is decided by the laser beam spot size (about 2 μ m). The resolution can be improved by using an objective lens with higher magnification or using shorter laser wavelength by shrinking a voxel. In the next experiment, the height of the microfluidic channels was designed to be 20 μ m. The slice and hatch sizes for structuring in the laser software were all set to be 20 μ m. The laser scan speed was set to 200 mm/s and the total scan time took 20 min for the designed 3D branching microfluidic channel. Figure 5b shows the results of the fabricated 3D glass device having multilayer microfluidic structures after 5 days wet etch.

To check a blocked area or leakage inside multilayered microfluidic channels, three different color dyes were injected using a syringe pump, as shown in Fig. 5c. The device showed the independent flow of the dyes without any blocked area. However, the fabricated channel showed a tapered channel shape with a larger width at the starting point than the width in the middle of the channel. The etchant penetration into the microfluidic channel starts from both ends of the channel that are the inlet and the outlet. The etching at the starting point of the channel was accumulated for 5 days and the width and height of the channel region were increased compared to the design dimension. Therefore, the tapered microfluidic channel shape is inevitable [24] and the offset should be considered when designing the channel dimension. In our result, the taper angle of the 11 mm long microfluidic channel was about 1.5°.

Conclusions and discussions

We introduced the selective laser-induced etching process using ultrafast laser direct writing and demonstrated the glass 3D micromachining that was highly challenged when using conventional fabrication methods. We investigated that the etch rate is not proportionally increasing to laser dose, rather it is only maximized within narrow process windows in terms of scan speed, pulse energy, and proper hatch and slicing distance. First, the etch rates of the modified glass and the non-modified glass by ultrafast laser exposure were investigated and the etch selectivity of about 333 was obtained by optimizing the laser process conditions. Second, we optimized the structuring using slice and hatch lines. Overall, we found that the proper distribution of voxels which leads to uniform modification of glass is the key to successful SLE process. Lastly, a 3D glass microfluidic device with multilayered microfluidic channels was demonstrated successfully. The etching time for the 11 mm microfluidic channel structure was too long as about 5 days in KOH so that an optimized etch condition or a new etchant should be researched in future. We hope that the presented process helps to



design and fabricate not only glass parts including optical components but also 3D microfluidic structures that develops a new dynamics fluid that conventional 2D microfluidic channels cannot provide.

Authors' contributions

SK optimization of SLE process and writing this paper. JK design of 3D microfluidic channel and analyzing structure. Y-HJ analysis of wet etching results. SA analysis of laser modified structures. JC improved 3D laser micromachining and reviewed this paper. CK supervised and reviewed this paper. All authors read and approved the final manuscript.

Funding

This work was supported by the Ministry of Trade Industry and Energy (MOTIE) under the Global Excellent Technology Innovation (Project No. 10053877) and National Research Foundation of Korea (NRF) funded by the Ministry of Science ICT and Future Planning (Project No. 2018R1C1B5044079).

Availability of data and materials

Not applicable.

Competing interests

The authors declare that they have no competing interests.

Received: 27 July 2019 Accepted: 30 September 2019 Published online: 08 October 2019

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