# Partial Regularity of Minimizers of Quasiconvex Integrals with Subquadratic Growth (*). 

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Abstract. - We prove partial regularity for minimizers of quasiconvex integrals of the form $\int_{\Omega} F(D u(x)) d x$ where the integrand $F(\xi)$ has subquadratic growth, i.e. $|F(\xi)| \leqslant L\left(1+|\xi|^{p}\right)$,
with $1<p<2$.

## 1. - Introduction.

In this paper we study the partial regularity of minimizers of the functional

$$
I(u)=\int_{\Omega} F(D u(x)) d x
$$

where $\Omega$ is a bounded open subset of $\mathbb{R}^{n}, u$ is a $W^{1, p}\left(\Omega ; \mathbb{R}^{N}\right)$ function, with $p>1$, and $F(\xi): \mathbb{R}^{n N} \rightarrow \mathbb{R}$ is a $C^{2}$ uniformly strict quasiconvex function i.e.

$$
\begin{equation*}
\int_{\Omega} F(\xi+D \phi(x)) d x \geqslant \int_{\Omega}\left[F(\xi)+v\left(1+|\xi|^{2}+|D \phi(x)|^{2}\right)^{(p-2) / 2}|D \phi(x)|^{2}\right] d x \tag{1.1}
\end{equation*}
$$

for any $\xi \in \mathbb{R}^{n N}$ and $\phi \in C_{0}^{1}\left(\Omega ; \mathbb{R}^{N}\right)$.
This condition was introduced in case $p \geqslant 2$ in a paper by Evans (see [7]). He proved that if $F$ satisfies (1.1) and

$$
\begin{equation*}
\left|D^{2} F(\xi)\right| \leqslant L\left(1+|\xi|^{2}\right)^{(p-2) / 2} \tag{1.2}
\end{equation*}
$$

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then a minimizer of $I(u)$ is $C^{1, \alpha}$ on an open subset $\Omega_{0} \subset \Omega$ such that meas $\left(\Omega-\Omega_{0}\right)=0$.
This result was later generalized in [3] where condition (1.2) is dropped (see also [12]). At the time these papers were written no examples of genuine quasiconvex functions with subquadratic growth at infinity were known. However recently V. Sverak (see [16]) gave an example of a quasiconvex ( and not convex neither polyconvex) function depending on $2 \times 2$ matrices and having polynomial growth with exponent $1<p<2$.

In this paper we extend Evans' result to the case where $F$ satisfies (1.1) and $p$ is any exponent between 1 and 2 .

We notice that a first regularity result in this direction was obtained in [5] under the more restrictive assumption $2 n /(n+2)<p<2$.

The proof of the regularity of $u$ is based, as usual, on a blow-up argument aimed to establish a decay estimate for the excess function

$$
E\left(x_{0}, R\right)=-\oint_{B_{R}\left(x_{0}\right)}\left|V(D u(x))-V\left((D u)_{x_{0}, R}\right)\right|^{2} d x
$$

where

$$
V(\xi)=\left(1+|\xi|^{2}\right)^{(p-2) / 4} \xi .
$$

Comparing to the case $p \geqslant 2$ and the case studied in [5], we have to face a few technical difficulties.

A point where one needs the assumption $p>2 n /(n+2)$ is in proving the following Sobolev-Poincaré type inequality

$$
\begin{equation*}
\left(f_{B_{R}}\left|V\left(\frac{u-u_{R}}{R}\right)\right|^{2 n /(n-2)}\right)^{(n-2) / 2 n} \leqslant c\left(f_{B_{R}}|V(D u)|^{2} d x\right)^{1 / 2} \tag{1.3}
\end{equation*}
$$

provided $u \in W^{1, p}\left(\Omega ; R^{N}\right)$.
It is not clear to us if (1.3) holds when $p \in(1,2)$. Indeed we can prove that an inequality of this kind is still true if one adds a constant $c=c(n, p)$ on the right hand side of (1.3), but unfortunately this extra term would give serious troubles when one blows up the solution.

However, we have been able ( see Theorem 2.4) to prove that if $p \in(1,2)$ an inequality of the type (1.3) holds if one increases the radius of the ball on the right hand side.

Another technical point to overcome is to prove that if $u \in W^{1,1}\left(\Omega ; \mathbb{R}^{N}\right)$ is a weak solution of a linear elliptic system with constant coefficients, satisfying the strong Leg-endre-Hadamard condition, then $u$ is locally $W^{1,2}$ hence $C^{\infty}$ : a fact that does not seem to be known in the literature.

## 2. - Preliminary results.

In the following $\Omega$ will denote a bounded open set of $\mathbb{R}^{n}, B_{R}\left(x_{0}\right)$ the ball $\{x \in$ $\left.\in \mathrm{R}^{n}:\left|x-x_{0}\right|<R\right\}$, and if $h$ is an integrable function we define

$$
h_{x_{0}, R}:=f_{B_{R}\left(x_{0}\right)} h(x) d x=\frac{1}{\omega_{n} R^{n}} \int_{B_{R}\left(x_{0}\right)} h(x) d x,
$$

where $\omega_{n}$ is the Lebesgue measure of the $n$-dimensional unit ball. When no confusion may arise we write simply $h_{R}$ in place of $h_{x_{0}, R}$ or $B_{R}$ in place of $B_{R}\left(x_{0}\right)$. Throughout the paper $p$ will be a number between 1 and 2 and for $\xi \in \mathbb{R}^{k}$ we shall denote

$$
\begin{equation*}
V(\xi)=\left(1+|\xi|^{2}\right)^{(p-2) / 4} \xi . \tag{2.1}
\end{equation*}
$$

The following statement contains some useful properties of the function $V$.
Lemma 2.1. - Let $1<p<2$, and $V: \mathbb{R}^{k} \rightarrow \mathbb{R}^{k}$ the function defined by (2.1), then for any $\xi, \eta \in \mathbb{R}^{k}, t>0$
(i) $2^{(p-2) / 4} \min \left\{|\xi|,|\xi|^{p / 2}\right\} \leqslant|V(\xi)| \leqslant \min \left\{|\xi|,|\xi|^{p / 2}\right\}$,
(ii) $|V(t \xi)| \leqslant \max \left\{t, t^{p / 2}\right\}|V(\xi)|$,
(iii) $|V(\xi+\eta)| \leqslant c(p)[|V(\xi)|+|V(\eta)|]$,
(iv) $\frac{p}{2}|\xi-\eta| \leqslant \frac{|V(\xi)-V(\eta)|}{\left(1+|\xi|^{2}+|\eta|^{2}\right)^{(p-2) / 4}} \leqslant c(k, p)|\xi-\eta|$,
(v) $|V(\xi)-V(\eta)| \leqslant c(k, p)|V(\xi-\eta)|$,
(vi) $|V(\xi-\eta)| \leqslant c(p, M)|V(\xi)-V(\eta)|$ if $|\eta| \leqslant M$ and $\xi \in \mathbb{R}^{k}$.

Proof. - Properties (i)-(ii) are easy to check.
To prove (iii) let us assume $|\eta| \leqslant|\xi|$. If $|\xi| \leqslant 1$ by (i) we get

$$
|V(\xi+\eta)| \leqslant|\xi+\eta| \leqslant 2|\xi| \leqslant c(p)|V(\xi)|,
$$

and if $|\xi| \geqslant 1$ by (i) again we get

$$
|V(\xi+\eta)| \leqslant|\xi+\eta|^{p / 2} \leqslant c(p)|\xi|^{p / 2} \leqslant c(p)|V(\xi)| .
$$

Inequality (iv) is proved in Lemma 2.2 in [4], while (v) can be immediately derived from (iv).

To prove (vi) notice that if $|\eta| \leqslant M$

$$
|\xi-\eta|^{2} \geqslant|\xi|^{2}+|\eta|^{2}-2|\xi||\eta| \geqslant \frac{3}{4}|\xi|^{2}-3|\eta|^{2} \geqslant \frac{3}{4}|\xi|^{2}-3 M^{2} .
$$

From this inequality and from the inequality on the left in (iv) we then get

$$
\begin{aligned}
|V(\xi-\eta)|= & \left(1+|\xi-\eta|^{2}\right)^{(p-2) / 4}|\xi-\eta| \leqslant \\
& \leqslant\left(1+4 M^{2}\right)^{(2-p) / 4}\left(1+4 M^{2}+|\xi-\eta|^{2}\right)^{(p-2) / 4}|\xi-\eta| \leqslant \\
& \leqslant\left(1+4 M^{2}\right)^{(2-p) / 4}\left(1+M^{2}+\frac{3}{4}|\xi|^{2}\right)^{(p-2) / 4}|\xi-\eta| \leqslant \\
& \leqslant c(p, M)\left(1+|\xi|^{2}+|\eta|^{2}\right)^{(p-2) / 4}|\xi-\eta| \leqslant c(p, M)|V(\xi)-V(\eta)| .
\end{aligned}
$$

Let $h: \mathbb{R}^{n} \rightarrow \mathbb{R}^{k}$ be a locally integrable function. The Hardy-Littlewood maximal function $M(h)$ is defined for any $x \in \mathbb{R}^{n}$ as

$$
M(h)(x)=\sup _{r>0} f_{B_{R}(x)}|h(y)| d y
$$

It is well known that $M$ is a continuous operator from $L^{q}$ to $L^{q}$, if $q>1$. The following result, which is a slightly modified version of Proposition 1.2 in [10], shows that the continuity properties of the maximal operator $M$ hold in more general situations.

Proposition 2.2. - Let $A:[0,+\infty[\rightarrow[0,+\infty[$ be a continuous function such that
(i) $A(2 t) \leqslant K A(t)$ for any $t>0$,
(ii) there exists $r>1$ such that $t \rightarrow A(t) / t^{r}$ is increasing.

Then there exists a constant $c \equiv c(n, K, r)$ such that iff is a nonnegative, measurable function in $\mathbb{R}^{n}$, then

$$
\int_{\mathbb{R}^{n}} A(M(f)) d x \leqslant c \int_{\mathbb{R}^{n}} A(f) d x .
$$

We now apply this proposition to a particular case, which will be useful in the sequel.

Proposition 2.3. - Let $1<p<2$ and $\alpha>2 / p$, then there exists $c \equiv c(\alpha, p, n)$ such that if $h: \mathbb{R}^{n} \rightarrow \mathbb{R}^{h}$ is measurable, then

$$
\int_{\mathbb{R}^{n}}|V(M(h))|^{a} d x \leqslant \int_{\mathbb{R}^{a}}|V(h)|^{a} d x .
$$

Proof. - Set for $t>0$

$$
A(t)=\left[\left(1+t^{2}\right)^{(p-2) / 4} t\right]^{\alpha}
$$

and notice that, by (ii) of Lemma 2.1, we have for any $t>0$

$$
A(2 t) \leqslant 2^{\alpha} A(t)
$$

and that, if $r=\alpha p / 2>1$, the function

$$
\frac{A(t)}{t^{r}}=\left[\frac{t}{\left(1+t^{2}\right)^{1 / 2}}\right]^{(\alpha(2-p)) / 2}
$$

is increasing in $[0,+\infty[$. The result then follows from Proposition 2.2.
We are now in position to prove the following Sobolev-Poincaré type inequality.
Theorem 2.4. - If $1<p<2$, there exist $2 / p<\alpha<2$ and $\sigma>0$ such that if $u \in$ $\in W^{1, p}\left(B_{3 R}\left(x_{0}\right), \mathbb{R}^{N}\right)$, then

$$
\begin{equation*}
\left(f_{B_{R}\left(x_{0}\right)}\left|V\left(\frac{u-u_{x_{0}, R}}{R}\right)\right|^{2(1+\sigma)} d x\right)^{1 /(2(1+\sigma))} \leqslant c\left(f_{B_{3 R}\left(x_{0}\right)}|V(D u)|^{a} d x\right)^{1 / \alpha} \tag{2.2}
\end{equation*}
$$

where $c \equiv c(n, p, N)$ is independent on $R$ and $u$.
Proof. - Setting $\tilde{u}(y)=(1 / R)\left[u\left(x_{0}+R y\right)-u_{x_{0}, R}\right]$, we may always assume $x_{0}=0$, $R=1$ and $u_{0,1}=0$. Then for any $x \in B_{1}$ we have

$$
\begin{aligned}
& |u(x)| \leqslant c(n, N) \int_{B_{1}} \frac{|D u(y)|}{|x-y|^{n-1}} d y= \\
& \qquad=c(n, N)\left[\int_{B_{1} \cap B_{\varepsilon}(x)} \frac{|D u(y)|}{|x-y|^{n-1}} d y+\int_{B_{1} \backslash B_{\varepsilon}(x)} \frac{|D u(y)|}{|x-y|^{n-1}} d y\right],
\end{aligned}
$$

with $0<\varepsilon \leqslant 1$ to be chosen. Denoting by $\overline{D u}$ the zero extension of $D u$ outside $B_{3}$, we have

$$
\begin{aligned}
&|u(x)| \leqslant c\left[\sum_{i=0}^{\infty}\left(\frac{2^{i}}{\varepsilon}\right)^{n-1} \int_{\left\{\varepsilon 2^{-i-1} \leqslant|x-y|<\varepsilon 2^{-i}\right\}}|D u(y)| d y+\frac{1}{\varepsilon^{n-1}} \int_{B_{2}(x)}|D u(y)| d y\right] \leqslant \\
& \leqslant c\left[\sum_{i=0}^{\infty} \frac{\varepsilon}{2^{i}} \int_{B_{\varepsilon / 2}(x)}|D u(y)| d y+\frac{1}{\varepsilon^{n-1}} \int_{B_{2}(x)}|D u(y)| d y\right] \leqslant \\
& \leqslant c\left[\varepsilon(M(\overline{D u}))(x)+\frac{1}{\varepsilon^{n-1}} \int_{B_{2}(x)}|D u(y)| d y\right] .
\end{aligned}
$$

Noticing that the function $t \rightarrow\left(1+t^{2}\right)^{(p-2) / 2} t^{2}$ is increasing in [ $0,+\infty$ [ and using
(ii) and (iii) of Lemma 2.1, from the inequality above we deduce, since $0<\varepsilon \leqslant 1$,

$$
\begin{align*}
|V(u(x))|^{2} & \leqslant c(n, p, N)\left[|V(\varepsilon M(\overline{D u})(x))|^{2}+\left|V\left(\frac{1}{\varepsilon^{n-1}} f_{B_{2}(x)}|D u(y)| d y\right)\right|^{2}\right] \leqslant  \tag{2.3}\\
& \leqslant c\left[\frac{\varepsilon^{p}}{p}|V(M(\overline{D u})(x))|^{2}+\frac{1}{2(n-1) \varepsilon^{2(n-1)}}\left|V\left(f_{B_{2}(x)}|D u(y)| d y\right)\right|^{2}\right] .
\end{align*}
$$

The quantity in square brackets attains its minimum when

$$
\varepsilon=\left[\frac{\left|V\left({\underset{B}{2}(x)}_{f}^{f}|D u(y)| d y\right)\right|}{|V(M(\overline{D u})(x))|}\right]^{2 /(2(n-1)+p)} .
$$

Since

$$
f_{B_{2}(x)}|D u(y)| d y \leqslant(M(\overline{D u}))(x)
$$

the value of $\varepsilon$ given above is less than or equal to 1 . Inserting this value in (2.3) we obtain easily

$$
\begin{equation*}
|V(u(x))|^{2} \leqslant c|V(M(\overline{D u})(x))|^{(4(n-1)) /(2(n-1)+p)}\left|V\left(f_{B_{2}(x)}|D u(y)|\right)\right|^{2 p /(2(n-1)+p)} \tag{2.4}
\end{equation*}
$$

Let us choose now $\alpha$ such that

$$
\max \left\{\frac{2}{p}, \frac{4(n-1)}{2(n-1)+p}\right\}<\alpha<2
$$

Raising both sides of (2.4) to $\alpha((2(n-1)+p) / 4(n-1))$, integrating on $B_{1}$, and using (ii) of Lemma 2.1 and Proposition 2.3 we have
$\int_{B_{1}}|V(u(x))|^{\alpha[2(n-1)+p] / 2(n-1)} d x \leqslant$

$$
\begin{aligned}
\leqslant & c\left|V\left(f_{B_{3}}|D u(y)| d y\right)\right|^{\alpha p / 2(n-1)} \int_{B_{1}}|V(M(\overline{D u})(x))|^{\alpha} d x \leqslant \\
& \leqslant c\left[\left|V\left(f_{B_{3}}|D u(y)| d y\right)\right|^{\alpha}\right]^{p / 2(n-1)} \int_{B_{3}}|V(D u(x))|^{\alpha} d x .
\end{aligned}
$$

Finally, notice that from (i) of Lemma 2.1 it is clear that there exists $c_{a}$ such that

$$
c_{a}^{-1} g_{\alpha}(|\xi|) \leqslant|V(\xi)|^{\alpha} \leqslant c_{a} g_{\alpha}(|\xi|), \quad \text { for any } \xi,
$$

where

$$
g_{a}(t):= \begin{cases}t^{a}, & \text { if } 0 \leqslant t \leqslant 1, \\ \frac{2}{p} t^{\alpha p / 2}+1-\frac{2}{p}, & \text { if } t \geqslant 1 .\end{cases}
$$

Since $\alpha>2 / p, g_{a}$ is convex, hence we have, using Jensen's inequality

$$
\begin{aligned}
& \int_{B_{1}}|V(u(x))|^{\alpha[2(n-1)+p] / 2(n-1)} d x \leqslant \\
& \quad \leqslant c\left[g_{\alpha}\left(f_{B_{3}}|D u(x)| d x\right)\right]^{p / 2(n-1)} \int_{B_{3}}|V(D u(x))|^{\alpha} d x \leqslant \\
& \quad \leqslant c\left(f_{B_{3}} g_{\alpha}(|D u(x)|) d x\right)^{p / 2(n-1)} \int_{B_{3}}|V(D u(x))|^{\alpha} d x \leqslant c\left(\int_{B_{3}}|V(D u(x))|^{\alpha} d x\right)^{1+(p / 2(n-1))}
\end{aligned}
$$

Setting $1+\sigma=\alpha[2(n-1)+p] / 4(n-1)$ and noticing that from the definition of $\alpha$ it is clear that $\sigma>0$, from the inequality above we then get

$$
\int_{B_{1}}|V(u(x))|^{2(1+\sigma)} d x \leqslant c\left(\int_{B_{3}}|V(D u(y))|^{\alpha} d y\right)^{2(1+\sigma) / \alpha}
$$

which proves the result.
Remark 2.5. - The Sobolev-Poincaré inequality we have just proved uses some ideas from [14]. This inequality is an essential tool in order to get the regularity result Theorem 3.2. It is also one point where our case most differs from the case $p \geqslant 2$, when $|V(\xi)|$ is equivalent to $|\xi|^{2}+|\xi|^{p}$. Under the extra assumption $p>2 n /(n+2)$ one can show that the inequality proved in Theorem 2.4 holds with the same ball (see [5]). It is not clear to us if one can still get in our situation the same sort of estimate without having to pass from the ball $B_{R}$ to $B_{3 R}$.

The following simple lemma is proved in [11] (see Lemma 3.1, Chap. 5).
Lemma 2.6. - Let $f:[r / 2, r] \rightarrow[0,+\infty[$ be a bounded function such that for all $r / 2<t<s<r$

$$
f(t) \leqslant \theta f(s)+\frac{A}{(s-t)^{\alpha}},
$$

where $A, \alpha, \theta$ are nonnegative constants such that $\theta<1$. Then there exists $c \equiv c(\theta)$
such that

$$
f\left(\frac{r}{2}\right) \leqslant c(\theta) \frac{A}{r^{a}} .
$$

This result can be easily extended, using condition (ii) in place of homogenity.
Lemma 2.7. - Let $f:[r / 2, r] \rightarrow[0,+\infty[$ be a bounded function such that for all $r / 2<t<s<r$

$$
f(t) \leqslant \theta f(s)+A \int_{B_{r}}\left|V\left(\frac{h(x)}{s-t}\right)\right|^{2} d x
$$

where $h \in L^{p}\left(B_{r}\right), A>0$, and $0<\theta<1$. Then there exists $c \equiv c(\theta)$ such that

$$
f\left(\frac{r}{2}\right) \leqslant c(\theta) A \int_{B_{r}}\left|V\left(\frac{h(x)}{r}\right)\right|^{2} d x .
$$

We are now in position to prove the following higher integrability result (see [3], for the case $p \geqslant 2$ ).

Lemma 2.8. - Let $g: \mathbb{R}^{n N} \rightarrow \mathbb{R}$ be a continuous function such that

$$
\begin{gathered}
|g(\xi)| \leqslant L|V(\lambda \xi)|^{2} \\
\int_{\Omega} g(D \phi(x)) d x \geqslant v \int_{\Omega}|V(\lambda D \phi(x))|^{2} d x
\end{gathered}
$$

for any $\phi \in C_{0}^{1}\left(\Omega, \mathbb{R}^{N}\right)$ and suitable constants $L, \nu, \lambda>0$. Let $u \in W^{1, p}\left(\Omega, \mathbb{R}^{N}\right)$ satisfy

$$
\int_{\Omega} g(D u(x)) d x \leqslant \int_{\Omega} g(D u(x)+D \phi(x)) d x
$$

for all $\phi \in C_{0}^{1}\left(\Omega, \mathbb{R}^{N}\right)$, where $1<p<2$. Then there exist $c, \delta$, depending only on $p, n$, $N, L, v$ but not on $\lambda$ and $u$ such that for any $B_{R}\left(x_{0}\right) \subset \Omega$

$$
\begin{equation*}
f_{B_{R / 2}}|V(\lambda D u)|^{2(1+\delta)} d x \leqslant c\left(f_{B_{R}}|V(\lambda D u)|^{2} d x\right)^{1+\delta} \tag{2.5}
\end{equation*}
$$

Proof. - Fix $B_{r}$ such that $B_{3 r} \subset \Omega, r / 2<t<s<r$, and take a cut-off function $\zeta \in C_{0}^{1}\left(B_{s}\right)$ such that $0 \leqslant \zeta \leqslant 1, \zeta \equiv 1$ on $B_{t}$ and $|D \zeta| \leqslant 2 /(s-t)$. If we set

$$
\phi_{1}=\left[u-u_{r}\right] \zeta, \quad \phi_{2}=\left[u-u_{r}\right](1-\zeta),
$$

then $D \phi_{1}+D \phi_{2}=D u$, and we have, by the minimality of $u$

$$
\begin{aligned}
& v \int_{B_{s}}\left|V\left(\lambda D \phi_{1}\right)\right|^{2} d x \leqslant \int_{B_{s}} g\left(D \phi_{1}\right) d x=\int_{B_{s}} g\left(D u-D \phi_{2}\right) d x= \\
&=\int_{B_{s}} g(D u) d x+\int_{B_{s}}\left[g\left(D u-D \phi_{2}\right)-g(D u)\right] d x \leqslant \\
& \leqslant \int_{B_{s} \backslash B_{t}} g\left(D \phi_{2}\right) d x+\int_{B_{s} \backslash B_{t}}\left[g\left(D u-D \phi_{2}\right)-g(D u)\right] d x \leqslant \\
& \leqslant L \int_{B_{s} \backslash B_{t}}\left[\left|V\left(\lambda D \phi_{2}\right)\right|^{2}+\left|V\left(\lambda\left(D u-D \phi_{2}\right)\right)\right|^{2}+|V(\lambda D u)|^{2}\right] d x .
\end{aligned}
$$

From this inequality, using (iii) of Lemma 2.1 we then get

$$
\int_{B_{t}}|V(\lambda D u)|^{2} d x \leqslant \int_{B_{s}}\left|V\left(\lambda D \phi_{1}\right)\right|^{2} d x \leqslant \tilde{c} \int_{B_{s} \backslash B_{t}}|V(\lambda D u)|^{2} d x+\tilde{\boldsymbol{c}} \int_{B_{s} \backslash B_{t}}\left|V\left(\lambda \frac{u-u_{r}}{s-t}\right)\right|^{2} d x .
$$

Adding to both sides of the previous inequality the quantity
we obtain that for any $r / 2<t<s<r$ :

$$
\int_{B_{l}}|V(\lambda D u)|^{2} d x \leqslant \frac{\tilde{c}}{1+\tilde{c}_{B_{s}}} \int_{\mid}|V(\lambda D u)|^{2} d x+\frac{\tilde{c}}{1+\tilde{c}_{B_{r}}} \int_{\mid}\left|V\left(\lambda \frac{u-u_{r}}{s-t}\right)\right|^{2} d x .
$$

Now, Lemma 2.7 implies that

$$
\int_{B_{r / 2}}|V(\lambda D u)|^{2} d x \leqslant c \int_{B_{r}}\left|V\left(\lambda \frac{u-u_{r}}{r}\right)\right|^{2} d x
$$

and so, by (2.2) we get

$$
\underset{B_{r / 2}}{f}|V(\lambda D u)|^{2} \leqslant c\left(f_{B_{r}}\left|V\left(\lambda \frac{u-u_{r}}{r}\right)\right|^{2(1+\sigma)}\right)^{1 /(1+\sigma)} \leqslant c\left(f_{B_{3 r}}|V(\lambda D u)|^{\alpha}\right)^{2 / \alpha},
$$

with $2 / p<\alpha<2$. From this inequality the result follows immediately just applying the Gehring's Lemma version due to Giaquinta and Modica (see [11] Theorem 1.1, Chap. 5).

The following lemma is a slightly modified version of the approximation result proved in [2].

Lemma 2.9. - Let $u \in W^{1, q}\left(\mathbb{R}^{n}, \mathbb{R}^{N}\right)$, with $q \geqslant 1$. For every $K>0$, if we set

$$
H_{K}=\left\{x \in \mathbb{R}^{n}: M(D u) \leqslant K\right\}
$$

then there exists a lipschitz function $w: \mathbb{R}^{n} \rightarrow \mathbb{R}^{N}$ such that

$$
\begin{gathered}
\|D w\|_{\infty} \leqslant c K, \quad w=v \quad \text { on } H_{K}, \\
\operatorname{meas}\left(\mathbb{R}^{n} \backslash H_{K}\right) \leqslant \frac{c\|D u\|_{q}^{q}}{K^{q}},
\end{gathered}
$$

where $c$ depends only on $n, N, q$.
Next result is a simple consequence of the a priori estimates for solutions of linear elliptic systems with constant coefficients.

Proposition 2.10. - Let $u \in W^{1,1}\left(\Omega, \mathbb{R}^{N}\right)$ such that

$$
\begin{equation*}
\int_{\Omega} A_{\alpha \beta}^{i j} D_{\alpha} u^{i} D_{\beta} \phi^{j} d x=0 \tag{2.6}
\end{equation*}
$$

for any $\phi \in C_{0}^{1}\left(\Omega, \mathbb{R}^{N}\right)$, where $\left(A_{\alpha \beta}^{i j}\right)$ is a constant matrix satisfying the strong Legen-dre-Hadamard condition:

$$
A_{\alpha \beta}^{i j} \lambda^{i} \lambda^{j} \mu_{\alpha} \mu_{\beta}>v|\lambda|^{2}|\mu|^{2}, \quad \text { for any } \lambda \in \mathbb{R}^{N}, \quad \mu \in \mathbb{R}^{n}
$$

Then $u$ is $C^{\infty}$ and for any $B_{R}\left(x_{0}\right) \subset \Omega$ and $0<\varrho<R$

$$
\begin{equation*}
\sup _{B_{R / 2}}|D u| \leqslant \frac{c}{R_{B_{R}}^{n}} \int|D u| d x \tag{2.7}
\end{equation*}
$$

where $c$ depends only on $n, N, p, v$ and $\max \left|A_{\alpha \beta}^{i j}\right|$.
Proof. - Step 1. Let $v \in W_{\text {loc }}^{1,2}\left(\Omega, \mathbb{R}^{N}\right)$ be a weak solution of (2.6). It is well known that $v$ is $C^{\infty}$ in $\Omega$. We want to show that if $B_{R}\left(x_{0}\right) \subset \subset \Omega$ then

$$
\begin{equation*}
\sup _{B_{R / 2}}|D v| \leqslant \frac{c}{R^{n}} \int_{B_{R}}|D v| d x \tag{2.8}
\end{equation*}
$$

By a rescaling argument it is clear that to prove this inequality we may assume $x_{0}=0$ and $R=1$. From Caccioppoli inequality for solutions of linear elliptic systems we get that for any $1 / 2<t<s<1$

$$
\int_{B_{t}}|D v|^{2} d x \leqslant \frac{c}{(s-t)^{2}} \int_{B_{s}}|v|^{2} d x
$$

Since also higher order derivatives of $v$ are solutions of (2.6), iterating the inequality
above on suitably nested balls we get that for any $h=1,2, \ldots$

$$
\int_{B_{t}}\left|D^{h} v\right|^{2} d x \leqslant \frac{c(h)}{(s-t)^{2 h}} \int_{B_{s}}|v|^{2} d x
$$

Therefore, since $1 / 2<t<1$, we may estimate

$$
\sup _{B_{t}}|v| d x \leqslant c(n)\|v\|_{W^{n, 2}\left(B_{t}\right)} \leqslant \frac{c}{(s-t)^{n}}\left(\int_{B_{s}}|v|^{2} d x\right)^{1 / 2} \leqslant \frac{c}{(s-t)^{n}}\left(\int_{B_{s}}|v| d x\right)^{1 / 2}\left(\sup _{B_{s}}|v|\right)^{1 / 2}
$$

Using Young inequality we obtain

$$
\sup _{B_{t}}|v| \leqslant \frac{1}{2} \sup _{B_{s}}|v|+\frac{c}{(s-t)^{2 n}} \int_{B_{1}}|v| d x .
$$

Finally, from Lemma 2.6 we conclude that

$$
\sup _{B_{1 / 2}}|v| \leqslant c \int_{B_{1}}|v| d x
$$

Applying this estimate to the derivatives $D_{i} v$ of $v$ we then get (2.8).
Step 2. Let $u \in W^{1,1}\left(\Omega, \mathbb{R}^{N}\right)$ be a solution of (2.6). If $\varrho(x)$ is a simmetric mollifier we set for any $x \in \Omega_{\varepsilon}=\{x \in \Omega: d(x, \partial \Omega)<\varepsilon\}$

$$
u_{\varepsilon}(x)=\int_{|z|<1} \varrho(z) u(x+\varepsilon z) d z
$$

Then $u_{\varepsilon}$ is smooth and one readily checks that for any $\phi \in C_{0}^{1}\left(\Omega_{\varepsilon}, \mathbb{R}^{N}\right)$

$$
\int_{\Omega_{\varepsilon}} A_{\alpha \beta}^{i j} D_{\alpha} u_{\varepsilon}^{i} D_{\beta} \phi^{j} d x=0 .
$$

From (2.8) it follows that if $B_{R} \subset \Omega_{\varepsilon}$

$$
\sup _{B_{R / 2}}\left|D u_{\varepsilon}\right| \leqslant \frac{c}{R^{n}} \int_{B_{R}}\left|D u_{\varepsilon}\right| d x
$$

Since $D u_{\varepsilon} \rightarrow D u$ locally in $L^{1}$ it follows that $u$ satisfies (2.7), and so it is smooth.

We conclude this section recalling a selection lemma due to Eisen (see [6]).
Lemma 2.11. - Let $G$ be a measurable subset of $\mathbb{R}^{c}$, with meas $(G)<+\infty$. Assume $\left(M_{h}\right)$ is a sequence of measurable subets of $G$ such that, for some $\varepsilon>0$, the following
estimate holds:

$$
\operatorname{meas}\left(M_{h}\right) \geqslant \varepsilon \quad \text { for all } h \in \mathbb{N} .
$$

Then a subsequence $\left(M_{h_{k}}\right)$ can be selected such that $\cap_{k} M_{h_{k}} \neq \emptyset$.

## 3. - Proof of the main result.

In this section we will prove the partial regularity of minimizers of the functional

$$
I(v):=\int_{\Omega} F(D v(x)) d x
$$

where $v \in W^{1, p}\left(\Omega, \mathbb{R}^{N}\right), 1<p<2$, and $F: \mathbb{R}^{n N} \rightarrow \mathbb{R}$ is a $C^{2}$ function satisfying the following assumptions

$$
\begin{equation*}
|F(\xi)| \leqslant L\left(1+|\xi|^{p}\right), \tag{1}
\end{equation*}
$$

$$
\begin{equation*}
\int_{\Omega} F(\xi+D \phi(x)) d x \geqslant \int_{\Omega}\left[F(\xi)+v\left(1+|\xi|^{2}+|D \phi(x)|^{2}\right)^{(p-2) / 2}|D \phi(x)|^{2}\right] d x \tag{2}
\end{equation*}
$$

for any $\xi \in \mathbb{R}^{n N}$ and any $\phi \in C_{0}^{1}\left(\Omega, \mathbb{R}^{N}\right)$, with $\nu>0$.
Remark 3.1. - Condition $\left(\mathrm{H}_{2}\right)$, introduced in [7] in the case $p \geqslant 2$, is called uniform strict quasiconvexity and implies that for any $\xi \in \mathbb{R}^{n N}, \lambda \in \mathbb{R}^{N}, \mu \in \mathbb{R}^{n}$

$$
\frac{\partial^{2} F}{\partial \xi_{\alpha}^{i} \partial \xi_{\beta}^{j}}(\xi) \lambda^{i} \lambda^{j} \mu_{a} \mu_{\beta} \geqslant c v\left(1+|\xi|^{2}\right)^{(p-2) / 2}|\lambda|^{2}|\mu|^{2}
$$

with $c$ independent on $\xi, \lambda, \mu$.
Notice that we do not assume any control on second derivatives. However, if a function $F$ is quasiconvex, i.e. verifies $\left(\mathrm{H}_{2}\right)$ with $v=0$, and has the growth control $\left(\mathrm{H}_{1}\right)$, then it is well known (see [15]) that

$$
\begin{equation*}
|D F(\xi)| \leqslant c(n, N, p) L\left(1+|\xi|^{p-1}\right) . \tag{3.1}
\end{equation*}
$$

We also recall that a function $u \in W^{1, p}\left(\Omega, \mathbb{R}^{N}\right)$ is a minimizer of $I(v)$ if for any function $\phi \in W_{0}^{1, p}\left(\Omega, \mathbb{R}^{N}\right)$

$$
I(u) \leqslant I(u+\phi)
$$

We can now state the main result of this section.
Theorem 3.2. - Let $F$ be a $C^{2}$ function satisfying $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{2}\right)$ and $u \in$ $\in W^{1, p}\left(\Omega, \mathbb{R}^{N}\right)$ be a minimizer of functional $I(v)$. Then there exists an open subset $\Omega_{0}$ of $\Omega$ such that meas $\left(\Omega \backslash \Omega_{0}\right)=0$ and $u$ is $C^{1, \gamma}\left(\Omega_{0}, \mathbb{R}^{N}\right)$ for any $\gamma<1$.

A standard technique in order to prove such kind of results is to look at the decay in small balls around a point $x_{0}$ of the so called excess of the gradient of the solution $u$. Roughly speaking the excess $E\left(x_{0}, R\right)$ measures how far is the gradient from being
constant in the ball $B_{R}\left(x_{0}\right)$. In our case it is convenient to define

$$
E\left(x_{0}, R\right)=\underset{B_{R}\left(x_{0}\right)}{ }\left|V(D u(x))-V\left((D u)_{x_{0}, R}\right)\right|^{2} d x,
$$

where $V$ is the function given by (2.1). Notice that if $p \geqslant 2$ this quantity is equivalent to

$$
f_{B_{R}\left(x_{0}\right)}\left|D u(x)-(D u)_{x_{0}, R}\right|^{2}+f_{B_{R}\left(x_{0}\right)}\left|D u(x)-(D u)_{x_{0}, R}\right|^{p} d x
$$

but it is not so in our case.
We shall prove our decay estimate, Proposition 3.4 below, by a more or less standard argument consisting in blowing up the solution in small balls and reducing the problem to the study of convergence in the unit ball of solutions of suitably rescaled functionals. To this aim we need the following simple technical result which is a modified version of Lemma 2.4 in [4] and is proved exactly in the same way.

Lemma 3.3. - Let $f: \mathbb{R}^{k} \rightarrow \mathbb{R}$ be a function of class $C^{2}$ satisfying for any $\xi \in \mathbb{R}^{k}$

$$
|D f(\xi)| \leqslant L\left(1+|\xi|^{2}\right)^{(p-1) / 2},
$$

with $1<p<2$. Then for any $M>0$ there exists a constant $c$ depending only on $M, p$, $L$, such that if we set for any $\lambda>0$ and $A \in \mathbb{R}^{k}$ with $|A| \leqslant M$

$$
f_{A, \lambda}(\xi)=\lambda^{-2}[f(A+\lambda \xi)-f(A)-\lambda D f(A) \xi],
$$

then

$$
\left|f_{A, \lambda}(\xi)\right| \leqslant c(p, L, M)\left(1+|\lambda \xi|^{2}\right)^{(p-2) / 2}|\xi|^{2} .
$$

We can now establish the decay estimate of $E\left(x_{0}, R\right)$. The proof we give is based on an idea contained in [8], later modified in [4] in order to deal with functionals with no control on the second derivatives (see also [5]). We will follow closely the various steps of the proof as presented in [4].

Proposition 3.4 [Decay estimate]. - Fix $M>0$; there exists a constant $C_{M}$ such that for every $0<\tau<1 / 4$ there is an $\varepsilon \equiv \varepsilon(\tau, M)$ such that if

$$
\left|(D u)_{x_{0}, R}\right| \leqslant M \quad \text { and } E\left(x_{0}, R\right)<\varepsilon
$$

then

$$
E\left(x_{0}, \tau R\right) \leqslant C_{M} \tau^{2} E\left(x_{0}, R\right) .
$$

Proof. - Fix $M$ and $\tau$. We shall determine $C_{M}$ at the end of the proof.
Step 1: blow-up. We argue by contradiction, assuming that there is a sequence $B_{R_{h}}\left(x_{h}\right)$ of balls contained in $\Omega$ such that

$$
\left|(D u)_{x_{k}, R_{h}}\right| \leqslant M, \quad \lim _{h} E\left(x_{h}, R_{h}\right)=0
$$

and

$$
\begin{equation*}
E\left(x_{h}, \tau R_{h}\right)>C_{M} \tau^{2} E\left(x_{h}, R_{h}\right) . \tag{3.2}
\end{equation*}
$$

We introduce the following notations:

$$
a_{h}=u_{x_{h}, R_{h}}, \quad A_{h}=(D u)_{x_{h}, R_{h}}, \quad \lambda_{h}^{2}=E\left(x_{h}, R_{h}\right) ;
$$

and rescale the function $u$ in each ball $B_{R_{h}}\left(x_{h}\right)$ to obtain a sequence of functions on $B_{1}(0)$ :

$$
v_{h}(y)=\frac{1}{\lambda_{h} R_{h}}\left[u\left(x_{h}+R_{h} y\right)-a_{h}-R_{h} A_{h} y\right]
$$

Clearly, we have

$$
D v_{h}(y)=\frac{1}{\lambda_{h}}\left[D u\left(x_{h}+R_{h} y\right)-A_{h}\right], \quad\left(v_{h}\right)_{0,1}=0, \quad\left(D v_{h}\right)_{0,1}=0
$$

Moreover from (ii) and (vi) of Lemma 2.1 we have

$$
\begin{aligned}
& f_{B_{1}(0)}\left|V\left(D v_{h}(y)\right)\right|^{2} d y=f_{B_{R_{h}}\left(x_{h}\right)}\left|V\left(\frac{D u(x)-(D u)_{x_{h}, R_{h}}}{\lambda_{h}}\right)\right|^{2} d x \leqslant \\
& \leqslant \frac{\tilde{c}(M)}{\lambda_{h}^{2}} \underset{B_{R_{h}}\left(x_{h}\right)}{f}\left|V(D u(x))-V\left((D u)_{x_{h}, R_{h}}\right)\right|^{2} d x=\tilde{c} .
\end{aligned}
$$

Hence from (i) of Lemma 2.1 we may conclude that the sequence ( $D v_{h}$ ) is bounded in $L^{p}\left(B_{1}, \mathbb{R}^{n N}\right)$ :

$$
\begin{equation*}
\left\|D v_{h}\right\|_{p} \leqslant c, \quad \text { for any } h, \tag{3.3}
\end{equation*}
$$

and assume, without loss of generality, that

$$
v_{h} \rightharpoonup v, \quad \text { weakly in } W^{1, p}\left(B_{1}, \mathbb{R}^{N}\right)
$$

and, since $\left|A_{h}\right| \leqslant M$,

$$
A_{h} \rightarrow A .
$$

Step 2: $v$ solves a linear system. From the Euler system for $u$, rescaled in each $B_{R_{h}}\left(x_{h}\right)$, we deduce for every $\phi \in C_{0}^{1}\left(B_{1}, \mathbb{R}^{N}\right)$

$$
\int_{B_{1}} \frac{\partial F}{\partial \xi_{a}^{i}}\left(A_{h}+\lambda_{h} D v_{h}\right) D_{\alpha} \phi^{i} d y=0
$$

and also

$$
\int_{B_{1}}\left[\frac{\partial F}{\partial \xi_{\alpha}^{i}}\left(A_{h}+\lambda_{h} D v_{h}\right)-\frac{\partial F}{\partial \xi_{\alpha}^{i}}\left(A_{h}\right)\right] D_{\alpha} \phi^{i} d y=0 .
$$

If we split $B_{1}$ as

$$
E_{h}^{+} \cup E_{h}^{-}=\left\{y \in B_{1}: \lambda_{h}\left|D v_{h}(y)\right| \geqslant 1\right\} \cup\left\{y \in B_{1}: \lambda_{h}\left|D v_{h}(y)\right|<1\right\},
$$

we get by (3.3)

$$
\begin{equation*}
\operatorname{meas}\left(E_{h}^{+}\right) \leqslant \int_{B_{1}} \lambda_{h}^{p}\left|D v_{h}\right|^{p} d y \leqslant c \lambda_{h}^{p} . \tag{3.4}
\end{equation*}
$$

Therefore, using (3.1) and (3.3), we deduce that

$$
\begin{aligned}
\left.\frac{1}{\lambda_{h}} \int_{E_{h}^{+}} \right\rvert\,\left[D F\left(A_{h}+\lambda_{h} D v_{h}\right)-\right. & \left.D F\left(A_{h}\right)\right] D \phi \mid d y \leqslant \\
& \leqslant \frac{c}{\lambda_{h}} \int_{E_{h}^{+}}\left(1+\lambda_{h}^{p-1}\left|D v_{h}\right|^{p-1}\right) d y \leqslant \\
& \leqslant c \frac{\left|E_{h}^{+}\right|}{\lambda_{h}}+c \lambda_{h}^{p-2}\left(\int_{E_{h}^{+}}\left|D v_{h}\right|^{p} d y\right)^{(p-1) / p}\left|E_{h}^{+}\right|^{1 / p} \leqslant c \lambda_{h}^{p-1}
\end{aligned}
$$

which implies

$$
\begin{equation*}
\lim _{h} \frac{1}{\lambda_{h}} \int_{E_{h}^{+}}\left|\left[D F\left(A_{h}+\lambda_{h} D v_{h}\right)-D F\left(A_{h}\right)\right] D \phi\right| d y=0 . \tag{3.5}
\end{equation*}
$$

Now we observe that (3.4) implies that $\chi_{E_{h}^{-}} \rightarrow 1$ in $L^{q}\left(B_{1}\right)$ for all $q<\infty$ and that by (3.3) we have $\lambda_{h} D v_{h}(y) \rightarrow 0$ a.e. in $B_{1}$. Then on $E_{h}^{-}$we may write

$$
\begin{aligned}
\int_{E_{h}^{-}} & {\left[D F\left(A_{h}+\lambda_{h} D v_{h}\right)-D F\left(A_{h}\right)\right] D \phi d y=\int_{E_{h}^{-}} d y \int_{0}^{1} D^{2} F\left(A_{h}+s \lambda_{h} D v_{h}\right) D v_{h} D \phi d s=} \\
& =\int_{E_{h}^{-}} d y \int_{0}^{1}\left[D^{2} F\left(A_{h}+s \lambda_{h} D v_{h}\right)-D^{2} F\left(A_{h}\right)\right] D v_{h} D \phi d s+\int_{E_{k}^{-}} D^{2} F\left(A_{h}\right) D v_{h} D \phi d y .
\end{aligned}
$$

letting $h \rightarrow \infty$ and using the uniform continuity of $D^{2} F$ on bounded sets we obtain

$$
\lim _{h} \frac{1}{\lambda_{h_{E_{h}}}} \int_{E_{h}}\left[D F\left(A_{h}+\lambda_{h} D v_{h}\right)-D F\left(A_{h}\right)\right] D \phi d y=\int_{B_{1}} D^{2} F(A) D v D \phi d y,
$$

which together with (3.5) implies

$$
\int_{B_{1}} \frac{\partial^{2} F}{\partial \xi_{a}^{i} \partial \xi_{\beta}^{j}}(A) D_{\alpha} v^{i} D_{\beta} \phi^{j} d y=0
$$

By Remark 3.1 the coefficients of this linear system satisfy the inequality

$$
c(\nu, M)|\lambda|^{2}|\mu|^{2} \leqslant \frac{\partial^{2} F}{\partial \xi_{\alpha}^{i} \partial \xi_{\beta}^{j}}(A) \lambda^{i} \lambda^{j} \mu_{\alpha} \mu_{\beta} \leqslant c(M)|\lambda|^{2}|\mu|^{2},
$$

hence from Lemma 2.10 we deduce that $v$ is $C^{\infty}$ in $B_{1}$. Moreover from the theory of linear systems (see [11], Theorem 2.1, Chap. 3) and by (2.7) and (3.3) we get that if $0<\tau<1 / 2$

$$
\begin{align*}
& f_{B_{\tau}}\left|D v-(D v)_{\tau}\right|^{2} d y \leqslant c(M) \tau^{2} f_{B_{1 / 2}}\left|D v-(D v)_{1 / 2}\right|^{2} d y \leqslant  \tag{3.6}\\
& \qquad \leqslant c(M) \tau^{2} \sup _{B_{1 / 2}}|D v|^{2} \leqslant c(M) \tau^{2}\left(f_{B_{1}}|D v|^{p}\right)^{2 / p} \leqslant C^{*}(M) \tau^{2} .
\end{align*}
$$

Step 3: higher integrability of $v_{h}$. If we set

$$
F_{h}(\xi):=\lambda_{h}^{-2}\left[F\left(A_{h}+\lambda_{h} \xi\right)-F\left(A_{h}\right)-\lambda_{h} D F\left(A_{h}\right) \xi\right],
$$

by (3.1) we may apply Lemma 3.3 and deduce

$$
\begin{equation*}
\left|F_{h}(\xi)\right| \leqslant \frac{c(M)}{\lambda_{h}^{2}}\left|V\left(\lambda_{h} \xi\right)\right|^{2} \tag{3.7}
\end{equation*}
$$

On the other hand $\left(\mathrm{H}_{2}\right)$ implies that

$$
\begin{equation*}
\int_{B_{1}} F_{h}(D \phi(y)) d y \geqslant \frac{v}{\lambda_{h_{B_{1}}}^{2}} \int_{B_{1}}\left|V\left(\lambda_{h} D \phi(y)\right)\right|^{2} d y \tag{3.8}
\end{equation*}
$$

for any $\phi \in C_{0}^{1}\left(B_{1}, \mathbb{R}^{N}\right)$. Set for any $0<r \leqslant 1$

$$
I_{r}^{h}(w):=\int_{B_{r}} F_{h}(D w(y)) d y
$$

it is then easily verified that $v_{h}$ is a minimizer of $I_{r}^{h}$. Therefore, applying Lemma 2.8 to the functions $g_{h}(\xi)=\lambda_{h}^{2} F_{h}(\xi)$, we get by (2.5) and (vi) of Lemma 2.1

$$
\begin{align*}
f_{B_{1 / 2}}\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2(1+\delta)} d y & \leqslant c\left(f_{B_{1}}\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2} d y\right)^{1+\delta}=  \tag{3.9}\\
& =c\left(f_{B_{R_{h}}\left(x_{h}\right)}\left|V\left(D u(x)-A_{h}\right)\right|^{2} d x\right)^{1+\delta} \leqslant \\
& \leqslant c(M)\left(f_{B_{R_{h}}\left(x_{h}\right)}\left|V(D u(x))-V\left(A_{h}\right)\right|^{2} d x\right)^{1+\delta} \leqslant c \lambda_{h}^{2(1+\delta)},
\end{align*}
$$

and this gives immediately by (i) of Lemma 2.1 that the sequence ( $D v_{h}$ ) is bounded in $L^{p(1+\delta)}\left(B_{1 / 2}, \mathbb{R}^{n N}\right)$.

Step 4: upper bound. Fix $r<1 / 3$. Passing to a (not relabelled) subsequence, we may always assume that

$$
\lim _{h}\left[I_{r}^{h}\left(v_{h}\right)-I_{r}^{h}(v)\right]
$$

exists. We claim that

$$
\lim _{h}\left[I_{r}^{h}\left(v_{h}\right)-I_{r}^{h}(v)\right] \leqslant 0
$$

Choose $s<r$ and take $\zeta \in C_{0}^{\infty}\left(B_{r}\right)$ such that $0 \leqslant \xi \leqslant 1, \zeta=1$ on $B_{s}$ and $|D \zeta| \leqslant$ $\leqslant 2 /(r-s)$. If we set $\phi_{h}=\left(v-v_{h}\right) \zeta$ by (iii) and (ii) of Lemma 2.1, (3.7) and the minimality of $v_{h}$ it follows

$$
\begin{aligned}
I_{r}^{h}\left(v_{h}\right)-I_{r}^{h}(v) & \leqslant I_{r}^{h}\left(v_{h}+\phi_{h}\right)-I_{r}^{h}(v)=\int_{B_{r} \backslash B_{s}}\left[F_{h}\left(D v_{h}+D \phi_{h}\right)-F_{h}(D v)\right] d y \leqslant \\
& \leqslant \frac{c}{\lambda_{h}^{2}} \int_{B_{r} \backslash B_{s}}\left[\left|V\left(\lambda_{h} D v\right)\right|^{2}+\left|V\left(\lambda_{h}\left(v-v_{h}\right) D \xi+\lambda_{h} \xi D v+\lambda_{h}(1-\xi) D v_{h}\right)\right|^{2}\right] d y \leqslant \\
& \leqslant \frac{c}{\lambda_{h}^{2}} \int_{B_{r} \backslash B_{s}}\left[\left|V\left(\lambda_{h} D v\right)\right|^{2}+\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2}+\frac{1}{(r-s)^{2}}\left|V\left(\lambda_{h}\left(v-v_{h}\right)\right)\right|^{2}\right] d y
\end{aligned}
$$

Now from (3.9) we have

$$
\begin{aligned}
& \int_{B_{r} \backslash B_{s}}\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2} d y \leqslant \\
& \leqslant\left(\int_{B_{r} \backslash B_{s}}\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2(1+\delta)} d y\right)^{1 /(1+\delta)}\left|B_{r} \backslash B_{s}\right|^{\delta /(1+\delta)} \leqslant c \lambda_{h}^{2}(r-s)^{\delta /(1+\delta)}
\end{aligned}
$$

and by (2.2), taking $\theta$ such that $1 / 2=\theta+(1-\theta) /(2(1+\sigma))$, we obtain, using (iii) and (ii) of Lemma 2.1,

$$
\begin{aligned}
& \int_{B_{r} \backslash B_{s}}\left|V\left(\lambda_{h}\left(v-v_{h}\right)\right)\right|^{2} d y \leqslant\left(\int_{B_{r} \backslash B_{s}}\left|V\left(\lambda_{h}\left(v-v_{h}\right)\right)\right| d y\right)^{2 \theta} . \\
& \cdot\left(\int_{B_{r} \backslash B_{s}}\left|V\left(\lambda_{h}\left(v-v_{h}\right)\right)\right|^{2(1+\sigma)} d y\right)^{(1-\theta) /(1+\sigma)} \leqslant c \lambda_{h}^{2 \theta}\left(\int_{B_{1}}\left|v-v_{h}\right| d y\right)^{2 \theta} \cdot \\
& \cdot\left(\int_{B_{1 / 3}}\left|V\left(\lambda_{h}\left(v-v_{h}\right)-\lambda_{h}\left(v-v_{h}\right)_{0,1 / 3}\right)\right|^{2(1+\sigma)} d y+\left|V\left(\lambda_{h}\left(v-v_{h}\right)_{0,1 / 3}\right)\right|^{2(1+\sigma)}\right)^{(1-\theta) /(1+\sigma)} \leqslant \\
& \quad \leqslant c \lambda_{h}^{2 \theta}\left(\int_{B_{1}}\left|v-v_{h}\right| d y\right)^{2 \theta}\left[\left(\int_{B_{1}}\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2} d y\right)^{1-\theta}+\lambda_{h}^{2(1-\theta)}\right] \leqslant c \lambda_{h}^{2}\left(\int_{B_{1}}\left|v-v_{h}\right| d y\right)^{2 \theta},
\end{aligned}
$$

where we used the estimate (see (3.9))

$$
\begin{equation*}
f_{B_{1}}\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2} d y \leqslant c \lambda_{h}^{2} \tag{3.10}
\end{equation*}
$$

Finally from the estimates above we conclude that

$$
I_{r}^{h}\left(v_{h}\right)-I_{r}^{h}(v) \leqslant c\left[\left(\sup _{B_{r}}|D v|^{2}\right)(r-s)+(r-s)^{\delta /(1+\delta)}+\frac{1}{(r-s)^{2}}\left(\int_{B_{1}}\left|v-v_{h}\right| d y\right)^{2 \theta}\right]
$$

Since $v_{h} \rightarrow v$ in $L^{p}\left(B_{1}, \mathbb{R}^{N}\right)$, letting first $h \rightarrow \infty$ and then $s \rightarrow r$ we prove the claim.

Step 5: lower bound. We claim that if $t<r<1 / 4$

$$
\limsup _{h} \frac{1}{\lambda_{h}^{2}} \int_{B_{t}}\left|V\left(\lambda_{h}\left(D v-D v_{h}\right)\right)\right|^{2} d y \leqslant c \lim _{h}\left[I_{r}^{h}\left(v_{h}\right)-I_{r}^{h}(v)\right] .
$$

Let $\phi \in C_{0}^{1}\left(B_{1 / 3}\right)$ such that $0 \leqslant \phi \leqslant 1, \phi=1$ on $B_{1 / 4}$ and $|D \phi| \leqslant c$. Set

$$
\tilde{v}_{h}=v_{h} \phi, \quad \tilde{v}=v \phi .
$$

We may always assume that the exponent $\delta$ given by the higher integrability estimate (3.9) is less than or equal to the exponent $\sigma$ provided by the Sobolev-Poincaré inequality (2.2). Therefore we get by (3.9) and (3.10)

$$
\begin{aligned}
& \int_{\mathbb{R}^{n}}\left|V\left(\lambda_{h} D \tilde{v}_{h}\right)\right|^{2(1+\delta)} d y \leqslant c \int_{B_{1 / 3}}\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2(1+\delta)} d y+c \int_{B_{1 / 3}}\left|V\left(\lambda_{h} v_{h}\right)\right|^{2(1+\delta)} d y \leqslant \\
& \quad \leqslant c \int_{B_{1 / 3}}\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2(1+\delta)} d y+c \int_{B_{1 / 3}}\left|V\left(\lambda_{h} v_{h}-\lambda_{h}\left(v_{h}\right)_{0,1 / 3}\right)\right|^{2(1+\delta)} d y . \\
& \quad \cdot c\left|V\left(\lambda_{h}\left(v_{h}\right)_{0,1 / 3}\right)\right|^{2(1+\delta)} \leqslant c \lambda_{h}^{2(1+\delta)}+c\left(\int_{B_{1}}\left|V\left(\lambda_{h} D v_{h}\right)\right|^{2} d y\right)^{1+\delta} \leqslant c \lambda_{h}^{2(1+\delta)} .
\end{aligned}
$$

From this estimate and Proposition 2.3 it then follows that

$$
\begin{equation*}
\lambda_{h}^{-1}\left[\left\|V\left(\lambda_{h} D \tilde{v}_{h}\right)\right\|_{L^{2(1+\delta)}\left(\mathbb{R}^{n}\right)}+\| V\left(\lambda_{h} M\left(D \tilde{v}_{h}\right) \|_{L^{2(1+\delta)\left(\mathbb{R}^{n}\right)}}\right] \leqslant c\right. \tag{3.11}
\end{equation*}
$$

for all $h$. Fix $\varepsilon>0$, from the estimate above it is clear that there exists $\eta>0$ such that if $G \subset \mathbb{R}^{n}$ is a measurable set, with meas $(G)<\eta$

$$
\begin{equation*}
\frac{1}{\lambda_{h}^{2}}\left[\int_{G}\left|V\left(\lambda_{h} D \tilde{v}_{h}\right)\right|^{2} d y+\int_{G}\left|V\left(\lambda_{h} M\left(D \tilde{v}_{h}\right)\right)\right|^{2} d y\right]<\varepsilon . \tag{3.12}
\end{equation*}
$$

Notice that (3.11) implies also that $\left(\tilde{v}_{h}\right)$ is bounded in $W^{1, p(1+\delta)}\left(\mathbb{R}^{n}, \mathbb{R}^{N}\right)$, therefore by the continuity of the maximal function in $L^{q}$ spaces we deduce that there exists
$K>1$ such that, setting $S_{h}=\left\{y \in \mathbb{R}^{n}: M\left(D \tilde{v}_{h}\right)(y)>K\right\}$,

$$
\begin{equation*}
\text { meas }\left(S_{h}\right)<\eta \quad \text { for all } h . \tag{3.1}
\end{equation*}
$$

Having chosen $K$, we now apply Lemma 2.9 to find a sequence of functions $w_{h} \in$ $\in W^{1, \infty}\left(\mathbb{R}^{n}, \mathbb{R}^{N}\right)$ such that

$$
\begin{equation*}
w_{h}=\tilde{v}_{h} \text { on } \mathbb{R}^{n} \backslash S_{h}, \quad\left\|D w_{h}\right\|_{\infty} \leqslant c K . \tag{3.14}
\end{equation*}
$$

Therefore, passing to a (not relabelled) subsequence we may also suppose that

$$
w_{h} \rightarrow w \quad \text { weakly* in } W^{1, \infty}\left(\mathbb{R}^{n}, \mathbb{R}^{N}\right) .
$$

Notice that by (3.12), (3.13) and the definition of $S_{h}$ we have the estimate
which gives

$$
\begin{equation*}
\operatorname{meas}\left(S_{h}\right) \leqslant \varepsilon \frac{\left(1+\lambda_{h}^{2} K^{2}\right)^{(2-p) / 2}}{K^{2}}<\frac{2 \varepsilon}{K^{2}} \tag{3.15}
\end{equation*}
$$

for $h$ large enough. We turn now to estimate the difference

$$
\begin{align*}
& I_{r}^{h}\left(v_{h}\right)-I_{r}^{h}(v)=  \tag{3.16}\\
& \quad=\left[I_{r}^{h}\left(\tilde{v}_{h}\right)-I_{r}^{h}\left(w_{h}\right)\right]+\left[I_{r}^{h}\left(w_{h}\right)-I_{r}^{h}(w)\right]+\left[I_{r}^{h}(w)-I_{r}^{h}(v)\right]=R_{1}^{h}+R_{2}^{h}+R_{3}^{h} .
\end{align*}
$$

By (3.7), (3.12), (3.13) and (3.14) we get

$$
\begin{align*}
\left|R_{1}^{h}\right| \leqslant \int_{S_{h} \cap B_{r}}\left|F_{h}\left(D \tilde{v}_{h}\right)-F_{h}\left(D w_{h}\right)\right| d y & \leqslant  \tag{3.17}\\
& \leqslant \frac{c}{\lambda_{h}^{2}} \int_{S_{h}}\left[\left.V\left(\lambda_{h} D \tilde{v}_{h}\right)\right|^{2}+\left.V\left(\lambda_{h} M\left(D \tilde{v}_{h}\right)\right)\right|^{2}\right] d y<c \varepsilon .
\end{align*}
$$

Now choose $t<s<r$ and take a cut-off function $\zeta$ as in Step 4. Setting $\psi_{h}=$ ( $w_{h}-w$ ) ) we split $R_{2}^{h}$ as follows:

$$
\begin{align*}
& R_{2}^{h}=\left[I_{r}^{h}\left(w_{h}\right)-I_{r}^{h}\left(w+\psi_{h}\right)\right]+  \tag{3.18}\\
&+\left[I_{r}^{h}\left(w+\psi_{h}\right)-I_{r}^{h}(w)-I_{r}^{h}\left(\psi_{h}\right)\right]+I_{r}^{h}\left(\psi_{h}\right)=R_{4}^{h}+R_{5}^{h}+R_{6}^{h} .
\end{align*}
$$

Again by (3.7), (3.14) and (iii), (ii) of Lemma 2.1 we have

$$
\begin{aligned}
& \left|R_{4}^{h}\right| \leqslant \int_{B_{r} \backslash B_{s}}\left|F_{h}\left(D w_{h}\right)-F_{h}\left(D w+D \psi_{h}\right)\right| d y \leqslant \\
& \leqslant \frac{c}{\lambda_{h}^{2}} \int_{B_{r} \backslash B_{s}}\left[\left|V\left(\lambda_{h} D w_{h}\right)\right|^{2}+\left|V\left(\lambda_{h} D w\right)\right|^{2}+\frac{1}{(r-s)^{2}}\left|V\left(\lambda_{h}\left(w_{h}-w\right)\right)\right|^{2}\right] d y \leqslant \\
&
\end{aligned}
$$

Since $w_{h} \rightarrow w$ uniformly we conclude that

$$
\begin{equation*}
\limsup _{h}\left|R_{4}^{h}\right| \leqslant c(K)(r-s) \tag{3.19}
\end{equation*}
$$

To bound $R_{5}^{h}$ we observe that for any $A, B \in \mathbb{R}^{n N}$

$$
F_{h}(A+B)-F_{h}(A)-F_{h}(B)=\int_{0}^{1} \int_{0}^{1} D^{2} F_{h}(s A+t B) d s d t
$$

and therefore

$$
R_{5}^{h}=\int_{B_{r}} d x \int_{0}^{1} \int_{0}^{1} D^{2} F\left(A_{h}+s \lambda_{h} D w_{h}+t \lambda_{h} D \psi_{h}\right) D w D \psi_{h} d s d t
$$

Since $D^{2} F\left(A_{h}+s \lambda_{h} D w_{h}+t \lambda_{h} D \psi_{h}\right)$ converges to $D^{2} F(A)$ uniformly, and $w_{h} \rightharpoonup w$ weakly* in $W^{1, \infty}$ we easily get

$$
\begin{equation*}
\lim _{h} R_{5}^{h}=0 \tag{3.20}
\end{equation*}
$$

Moreover (3.8) implies that

$$
R_{6}^{h}=\int_{B_{r}} F_{h}\left(D \psi_{h}\right) d y \geqslant \frac{v}{\lambda_{h_{B_{r}}^{2}}^{2}} \int_{B_{h}}\left|V\left(\lambda_{h} D \psi_{h}\right)\right|^{2} d y \geqslant \frac{v}{\lambda_{h_{B_{s}}^{2}}^{2}} \int\left|V\left(\lambda_{h}\left(D w_{h}-D w\right)\right)\right|^{2} d y .
$$

Passing possibly to a subsequence we may suppose that

$$
\lim _{h} R_{2}^{h}
$$

exists too. Therefore by (3.18), (3.19), (3.20) we deduce

$$
\begin{equation*}
\lim _{h} R_{2}^{h} \geqslant \lim _{h} \sup \frac{v}{\lambda_{h_{B_{s}}^{2}}} \int\left|V\left(\lambda_{h}\left(D w_{h}-D w\right)\right)\right|^{2} d y-c(K)(r-s) \tag{3.21}
\end{equation*}
$$

To deal with $R_{3}^{h}$ we use a technique introduced in [1]. First we prove that

$$
\begin{equation*}
\operatorname{meas}\left\{y \in B_{r}: v(y) \neq w(y)\right\} \leqslant \frac{3 \varepsilon}{K^{2}} \tag{3.22}
\end{equation*}
$$

Set $S=\left\{y \in B_{r}: v(y) \neq w(y)\right\}$ and

$$
\tilde{S}=S \cap\left\{y \in B_{r}: v(y)=\lim _{h} v_{h}(y)\right\}
$$

Then meas $(S)=\operatorname{meas}(\tilde{S})$. We argue by contradiction. If

$$
\operatorname{meas}(S)>\frac{3 \varepsilon}{K^{2}}
$$

then by (3.15)

$$
\operatorname{meas}\left(\tilde{S} \backslash S_{h}\right)>\frac{\varepsilon}{K^{2}}
$$

for $h$ large enough and by Lemma 2.11 there exists $\bar{y} \in B_{r}$ such that

$$
\bar{y} \in \tilde{S} \backslash S_{h} \quad \text { for infinitely many } h
$$

Passing to this subsequence, we have

$$
v(\bar{y})=\lim _{h} v_{h}(\bar{y})=\lim _{h} w_{h}(\bar{y})=w(\bar{y}) ;
$$

hence $\bar{y} \notin S$, which is a contradiction. This proves (3.22). Now, since $D v=D w$ a.e. in $B_{r} \backslash S$, by (3.7) and (3.22) we get

$$
\begin{align*}
& \text { 23) } \begin{array}{l}
\left|R_{3}^{h}\right| \leqslant \int_{B_{r} \cap S}\left|F_{h}(D w)-F_{h}(D v)\right| d y \leqslant \\
\leqslant \frac{c}{\lambda_{h}^{2}} \int_{B_{r} \cap S}\left[\left|V\left(\lambda_{h} D v\right)\right|^{2}+\left|V\left(\lambda_{h} D w\right)\right|^{2}\right] d y \leqslant c\left(1+K^{2}\right) \operatorname{meas}(S) \leqslant \frac{c\left(1+K^{2}\right) \varepsilon}{K^{2}} \leqslant c \varepsilon
\end{array},=\text {, } \tag{3.23}
\end{align*}
$$

since $K>1$. By this inequality, (3.16),(3.17) and (3.21) we conclude that
(3.24) $\lim _{h}\left[I_{r}^{h}\left(v_{h}\right)-I_{r}^{h}(v)\right] \geqslant$

$$
\geqslant \limsup _{h} \frac{v}{\lambda_{h}^{2}} \int_{B_{s}}\left|V\left(\lambda_{h}\left(D w_{h}-D w\right)\right)\right|^{2} d y-c(K)(r-s)-c \varepsilon
$$

By (iii) of Lemma 2.1 we then have
(3.25)

$$
\begin{aligned}
& \frac{1}{\lambda_{h_{B_{t}}^{2}}^{2}} \int_{\left|V\left(\lambda_{h}\left(D v-D v_{h}\right)\right)\right|^{2} d y \leqslant \frac{c}{\lambda_{h_{B_{s}}^{2}}^{2}} \int_{B_{s}}\left|V\left(\lambda_{h}\left(D w-D w_{h}\right)\right)\right|^{2} d y+}^{\quad+\frac{c}{\lambda_{h_{B_{s}}^{2} \cap S_{h}}} \int_{h_{h_{s}} \cap S_{h}}\left|V\left(\lambda_{h}\left(D w_{h}-D v_{h}\right)\right)\right|^{2} d y+\frac{c}{\lambda^{2}} \int\left|V\left(\lambda_{h}(D v-D w)\right)\right|^{2} d y} .
\end{aligned}
$$

With the same argument used to prove (3.23) we get also

$$
\begin{equation*}
\frac{c}{\lambda_{h_{B_{s}}^{2} \cap S}} \int_{S} \left\lvert\, V\left(\left.\lambda_{h}(D v-D w)\right|^{2} d y \leqslant \frac{c}{\lambda_{h_{B_{r}}^{2} \cap S}} \int_{{ }^{2}}\left[\left|V\left(\lambda_{h} D v\right)\right|^{2}+\left|V\left(\lambda_{h} D w\right)\right|^{2}\right] d y \leqslant c \varepsilon\right.\right. \tag{3.26}
\end{equation*}
$$

and as in (3.17) we get

$$
\frac{c}{\lambda_{h}^{2}} \int_{B_{s} \cap S_{k}}\left|V\left(\lambda_{h}\left(D v_{h}-D w_{h}\right)\right)\right|^{2} d y \leqslant \frac{c}{\lambda_{h_{S_{h}}^{2}}} \int_{S_{k}}\left[\left|V\left(\lambda_{h} D \tilde{v}_{h}\right)\right|^{2}+\left|V\left(\lambda_{h} M\left(D \tilde{v}_{h}\right)\right)\right|^{2}\right] d y \leqslant c \varepsilon .
$$

Therefore, from this estimate, (3.24), (3.25), (3.26) we finally conclude that

$$
\limsup _{h} \frac{1}{\lambda_{h}^{2}} \int_{B_{t}}\left|V\left(\lambda_{h}\left(D v-D v_{h}\right)\right)\right|^{2} d y \leqslant c \lim _{h}\left[I_{r}^{h}\left(v_{h}\right)-I_{r}^{h}(v)\right]+c \varepsilon+c(K)(r-s) .
$$

The proof of the claim then follows by letting first $s \rightarrow r$ and then $\varepsilon \rightarrow 0^{+}$.
Step 6: conclusion of the proof. From the two previous steps we have that for any $0<\tau<1 / 4$

$$
\left.\lim _{h} \frac{1}{\lambda_{h}^{2}} \int_{B_{\tau}}| | V\left(\lambda_{h}\left(D v-D v_{h}\right)\right)\right|^{2} d y=0 .
$$

Now from this inequality, (v), (iii) of Lemma 2.1 and (3.6) we get

$$
\begin{aligned}
& \lim _{h} \sup \frac{E\left(x_{h}, \tau R_{h}\right)}{\lambda_{h}^{2}}=\lim _{h} \sup \frac{1}{\lambda_{h}^{2}} f_{B_{z R_{h}}\left(x_{h}\right)}\left|V(D u)-V\left((D u)_{x_{k}, \tau R_{h}}\right)\right|^{2} d x \leqslant \\
& \leqslant \limsup _{h} \frac{c}{\lambda_{h}^{2}} f_{B_{z_{h} h}\left(x_{h}\right)}\left|V\left(D u-(D u)_{x_{h}, \tau R_{h}}\right)\right|^{2} d x= \\
&=\lim _{h} \sup \frac{c}{\lambda_{h}^{2}} f_{B_{\tau}}\left|V\left(\lambda_{h}\left(D v_{h}-\left(D v_{h}\right)_{\tau}\right)\right)\right|^{2} d y \leqslant \\
& \leqslant \lim _{h} \sup \frac{c}{\lambda_{h}^{2}} \underset{B_{\tau}}{f}\left[\left|V\left(\lambda_{h}\left(D v_{h}-D v\right)\right)\right|^{2}+\right. \\
&\left.+\left|V\left(\lambda_{h}\left(D v-(D v)_{\tau}\right)\right)\right|^{2}+\left|V\left(\lambda_{h}\left((D v)_{\tau}-\left(D v_{h}\right)_{\tau}\right)\right)\right|^{2}\right] d y \leqslant \\
& \leqslant\left[C^{*}(M) \tau^{2}+\lim _{h}\left|(D v)_{\tau}-\left(D v_{h}\right)_{\tau}\right|^{2}\right],
\end{aligned}
$$

and since $D v_{h} \longrightarrow D v$ weakly in $L^{p}\left(B_{1}, \mathbb{R}^{n N}\right)$ we deduce that

$$
\lim _{h} \frac{E\left(x_{h}, \tau R_{h}\right)}{\lambda_{h}^{2}} \leqslant C^{*}(M) \tau^{2},
$$

which contradicts (3.2) if we choose $C_{M}=2 C^{*}(M)$.
Proof of the Theorem 3.2. - Following the argument used in section 6 of [9], from the Decay estimate just proved, one can easily obtain that for any $M>0$ there exist $0<$ $<\tau<1 / 4$ and $\eta>0$ such that if

$$
\begin{equation*}
\left|(D u)_{x_{0}, R}\right| \leqslant M \quad \text { and } \quad E\left(x_{0}, R\right)<\eta \tag{3.27}
\end{equation*}
$$

then for any $k=1,2, \ldots$

$$
E\left(x_{0}, \tau^{k} R\right) \leqslant c(M) \tau^{2 k} E\left(x_{0}, R\right), \quad\left|(D u)_{x_{0}, \tau^{k} R}\right| \leqslant 2 M .
$$

From this estimate one then gets that if (3.27) holds for any $0<\varrho<R$ we have

$$
\left|(D u)_{x_{0}, \varrho}\right| \leqslant c(M) \quad \text { and } \quad E\left(x_{0}, \varrho\right) \leqslant c(M)\left(\frac{\varrho}{R}\right)^{2} E\left(x_{0}, R\right)
$$

Therefore from Lemma 2.1 we get that

$$
\begin{align*}
& f_{B_{e}\left(x_{0}\right)}\left|D u-(D u)_{x_{0}, e}\right| d y \leqslant f_{B_{\ell}\left(x_{0}\right) \cap\left\{x:\left|D u-(D u)_{x_{0}, e}\right| \leqslant 1\right\}}\left|D u-(D u)_{x_{0}, e}\right| d y+  \tag{3.28}\\
& +f_{B_{e}\left(x_{0}\right) \cap\left\{x:\left|D u-(D u)_{x_{0}, e}\right|>1\right\}}\left|D u-(D u)_{x_{0}, \varrho}\right| d y \leqslant \\
& \leqslant c f_{B_{e}\left(x_{0}\right)}\left|V\left(D u-(D u)_{x_{0}, \varrho}\right)\right| d y+c\left(f_{B_{e}\left(x_{0}\right)}\left|V\left(D u-(D u)_{x_{0}, \varrho}\right)\right|^{2} d y\right)^{1 / p} \leqslant
\end{align*}
$$

$$
\begin{aligned}
& \leqslant c(M)\left[E^{1 / 2}\left(x_{0}, \varrho\right)+E^{1 / p}\left(x_{0}, \varrho\right)\right] \leqslant c(M, R) \varrho .
\end{aligned}
$$

From this estimate it is then clear that if we set

$$
\Omega_{0}=\left\{x \in \Omega: \sup _{r>0}\left|(D u)_{x_{0}, r}\right|<\infty \text { and } \lim _{r \rightarrow 0} E\left(x_{0}, r\right)=0\right\}
$$

$\Omega_{0}$ is an open set such that meas ( $\Omega-\Omega_{0}$ )=0 and by (3.28) $u \in C^{1, a}\left(\Omega_{0}\right)$ for any $0<\alpha<1$.

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