

# Performance Evaluation and Design Trade-Offs for Wireless Network-on-Chip Architectures

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Massive levels of integration are making modern multicore chips all pervasive in several domains. High performance, robustness, and energy-efficiency are crucial for the widespread adoption of such platforms. Networks-on-Chip (NoCs) have emerged as communication backbones to enable a high degree of integration in multicore Systems-on-Chip (SoCs). Despite their advantages, an important performance limitation in traditional NoCs arises from planar metal interconnect-based multihop links with high latency and power consumption. This limitation can be addressed by drawing inspiration from the evolution of natural complex networks, which offer great performance-cost trade-offs. Analogous with many natural complex systems, future multicore chips are expected to be hierarchical and heterogeneous in nature as well. In this article we undertake a detailed performance evaluation for hierarchical small-world NoC architectures where the long-range communications links are established through the millimeter-wave wireless communication channels. Through architecture-space exploration in conjunction with novel power-efficient on-chip wireless link design, we demonstrate that it is possible to improve performance of conventional NoC architectures significantly without incurring high area overhead.

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## 1. INTRODUCTION

Power density limitations will continue to drive an increase in the number of cores in modern electronic chips. While traditional cluster computers are more constrained by power and cooling costs for solving extreme-scale (or exascale) problems, the continuing progress and integration levels in silicon technologies make possible complete end-user systems on a single chip. This massive level of integration makes modern multicore

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chips all pervasive in domains ranging from climate forecasting and astronomical data analysis, to consumer electronics, and biological applications [Pande et al. 2011]. According to the U.S. Environmental Protection Agency (EPA), one of the promising ways to reduce energy dissipation of data centers is to design energy-efficient multicore chips [EPA 2007]. With increasing number of cores, high performance, robustness, and low power are crucial for the widespread adoption of such platforms. Achieving all of these goals cannot simply be attained by traditional paradigms and we are forced to rethink the basis of designing such systems, in particular the overall interconnect architecture. Network-on-Chip (NoC) is accepted as the preferable communication backbone for multicore Systems-on-Chip (SoCs). The achievable performance gain of a traditional NoC is limited by planar metal interconnect-based multihop links, where the data transfer between two far apart blocks causes high latency and power consumption. With a further increase in the number of cores on a chip, this problem will be significantly aggravated. On the other hand, natural complex networks are known to provide excellent trade-offs between latency and power with limited resources [Petermann et al. 2006]. Thus, drawing inspiration from such networks could enable radically new designs. The human brain, colonies of microbes, and many other natural complex networks have the so-called small-world property, which means that the average hop count between any two nodes is very short due to the addition of a few long-range links. Such an approach can be incorporated in NoCs, as has been done with metal wires in the past [Ogras et al. 2006]. However, the performance gain was limited due to the multihop wired links that are necessary for longer distances. In this article we evaluate the performance of hierarchical small-world NoC architectures with millimeter (mm)-wave wireless communication channels used as long-range shortcuts. These on-chip wireless shortcuts are CMOS-compatible and do not need any new technology. But they have associated antenna and wireless transceiver area and power overheads. Thus, to achieve the best performance, the wireless resources need to be placed and used optimally. To accomplish that goal, hybrid, hierarchical networks where nearby cores communicate through traditional metal wires, but long distance communications are predominantly achieved through high-performance single-hop wireless links, have been proposed [Ganguly et al. 2010]. In this article we perform a detailed performance analysis and establish trade-offs for various architectural choices for hierarchical wireless NoCs. The novel contributions of this work are as follows.

- The hybrid and hierarchical nature of the mm-wave wireless NoC (mWNoC) introduces various possibilities for the overall system architecture. We benchmark the performance of several mWNoC architectures and establish suitable design trade-offs. The analysis undertaken in this article helps us to choose the topological configuration of a particular mWNoC architecture that offers the best trade-off in terms of achievable peak bandwidth, energy dissipation, and area overhead.
- As a part of the performance evaluation, we also evaluate the performance of the mWNoC architecture with respect to two other types of hierarchical small-world NoC architectures where the long-range links are implemented with the RF-Interconnect (RF-I) [Chang et al. 2008] and G-lines [Mensink et al. 2007].
- On-chip wireless transceiver circuits are crucial components of the mWNoCs. The energy efficiencies of mWNoC architectures are shown to improve by incorporating novel body biased mm-wave transceiver circuit design methodologies.

## 2. RELATED WORK

The NoC paradigm has emerged as a communication backbone to enable a high degree of integration in multicore System-on-Chips (SoCs) [Pande et al. 2005]. To alleviate the problem of multihop communication links, the concept of express virtual channels

is introduced in Kumar et al. [2008b]. It is shown that by using express virtual lanes to connect distant cores in the network, it is possible to avoid the router overhead at intermediate nodes, and thereby greatly improve NoC performance. Performance is further improved by incorporating ultra low-latency multidrop on-chip global lines (G-lines) for flow control signals [Krishna et al. 2008]. NoCs have been shown to perform better by inserting long-range wired links following principles of small-world graphs [Ogras et al. 2006]. Despite significant performance gains, the preceding schemes still require laying out long wires across the chip and hence performance improvements beyond a certain limit may not be achievable.

The design principles of photonic NoCs are elaborated in various recent publications [Shacham et al. 2008; Joshi et al. 2009; Kurian et al. 2010]. The components of a complete photonic NoC, including dense waveguides, switches, optical modulators, and detectors, are now viable for integration on a single silicon chip. It is estimated that a photonic NoC will dissipate significantly less power than its electrical counterpart. Another alternative is NoCs with multiband RF interconnects [Chang et al. 2008]. In these NoCs, Electromagnetic (EM) waves are guided along on-chip transmission lines created by multiple layers of metal and dielectric stack. As the EM waves travel at the effective speed of light, low-latency and high-bandwidth communication can be achieved.

Recently, the design of a wireless NoC based on *CMOS Ultra Wideband* (UWB) technology was proposed [Zhao et al. 2008]. The antennas used in Zhao et al. [2008] achieve a transmission range of 1 mm with a length of 2.98 mm. Consequently, for a NoC spreading typically over a die area of 20 mm  $\times$  20 mm, this architecture essentially requires multihop communication through the on-chip wireless channels. The performance of silicon integrated on-chip antennas for intra- and inter-chip communication with longer range have already been demonstrated by the authors of Lin et al. [2007]. They have primarily used metal zig-zag antennas operating in the range of tens of GHz. The propagation mechanisms of radio waves over intra-chip channels with integrated antennas were also investigated [Zhang et al. 2007]. At mm-wave frequencies, the effect of metal interference structures such as power grids, local clock trees, and data lines on on-chip antenna characteristics like gain and phase are investigated in Seok et al. [2005]. The demonstration of intra-chip wireless interconnection in a 407-pin flip-chip package with a Ball Grid Array (BGA) mounted on a PC board [Branch et al. 2005] has addressed the concerns related to the influence of packaging on antenna characteristics. Design rules for increasing the predictability of on-chip antenna characteristics have been proposed in Seok et al. [2005]. Using antennas with a differential or balanced feed structure can significantly reduce coupling of switching noise, which is mostly common-mode in nature [Mehta et al. 2002]. In Lee et al. [2009], the feasibility of designing on-chip wireless communication networks with miniature antennas and simple transceivers that operate at the sub-THz range of 100–500 GHz has been demonstrated. If the transmission frequencies can be increased to THz/optical range then the corresponding antenna sizes decrease, occupying much less chip real estate. One possibility is to use nanoscale antennas based on Carbon NanoTubes (CNTs) operating in the THz/optical frequency range [Kempa et al. 2007]. Consequently, building an on-chip wireless interconnection network using THz frequencies for inter-core communications becomes feasible. The design of a small-world wireless NoC operating in the THz frequency range using CNT antennas is elaborated in Ganguly et al. [2010]. Though this particular NoC is shown to improve the performance of traditional wireline NoC by orders of magnitude, the integration and reliability of CNT devices need more investigation. The basic ideas regarding the design of a small-world NoC with mm-wave wireless links were proposed in Deb et al. [2010]. Following the basic design principles proposed in Deb et al. [2010], the current article undertakes a detailed

performance evaluation and aims to establish the design trade-offs associated with hierarchical small-world mm-wave wireless NoC architectures and highlight the key design considerations necessary for high-bandwidth and low-power on-chip wireless transceivers.

### 3. MM-WAVE WIRELESS NOC ARCHITECTURES

#### 3.1. Proposed Architecture

In a traditional wired NoC, the communications among embedded cores are generally via multiple switches/routers and wired links. This multihop communication becomes a major bottleneck in system performance, which gives rise to high latency and energy dissipation. To overcome this performance limitation we propose to adopt novel architectures inspired by complex network theory in conjunction with strategically placed on-chip mm-wave wireless links to design high-performance and low-power NoCs.

Modern complex network theory [Albert et al. 2002] provides a powerful method to analyze network topologies. Between a regular, locally interconnected mesh network and a completely random Erdős-Rényi topology, there are other classes of graphs, such as small-world and scale-free graphs. Networks with the small-world property have a very short average path length, defined as the number of hops between any pair of nodes. The average shortest path length of small-world graphs is bounded by a polynomial in  $\log(N)$ , where  $N$  is the number of nodes, making them particularly interesting for efficient communication with minimal resources [Buchanan 2003; Teuscher 2007].

A small-world topology can be constructed from a locally connected network by rewiring connections randomly, thus creating shortcuts in the network [Watts et al. 1998]. These random long-range links can be established following probability distributions depending on the inter-node distances [Petermann et al. 2006] and frequency of interaction between nodes. NoCs incorporating these shortcuts can perform significantly better than locally interconnected mesh-like networks [Ogras et al. 2006; Teuscher 2007], yet they require far fewer resources compared to a fully connected system.

Our goal here is to use the small-world approach to build a highly efficient NoC based on both wired and wireless links. The small-world topology can be incorporated in NoCs by introducing long-range, high-bandwidth, and low-power wireless links between far apart cores. We first divide the whole system into multiple small clusters of neighboring cores and call these smaller networks subnets. Subnets consist of relatively fewer cores, enhancing flexibility in designing their architectures. These subnets have NoC switches and links as in a standard NoC. As subnets are smaller networks, intra-subnet communication will have a shorter average path length than a single NoC spanning the whole system. The cores are connected to a centrally located hub through direct links and the hubs from all subnets are connected in a 2<sup>nd</sup>-level network forming a hierarchical structure. This upper hierarchical level is designed to have small-world graph characteristics constructed with both wired and wireless links. The hubs connected through wireless links require Wireless Interfaces (WIs). To reduce wireless link overheads and increase network connectivity, neighboring hubs are connected by traditional wired links and a few wireless links are distributed between hubs separated by relatively long physical distances. As will be described in a later section, we use a Simulated Annealing (SA) [Kirkpatrick et. al. 1983]-based algorithm to optimally place the WIs. The key to our approach is establishing an optimal overall network topology under given resource constraint, that is, number of WIs.

The proposed hybrid (wireless/wired) and hierarchical NoC architecture is shown in Figure 1 with the augmenting heterogeneous subnets. The hubs are interconnected via both wireless and wired links while the subnets are wired only. The hubs with

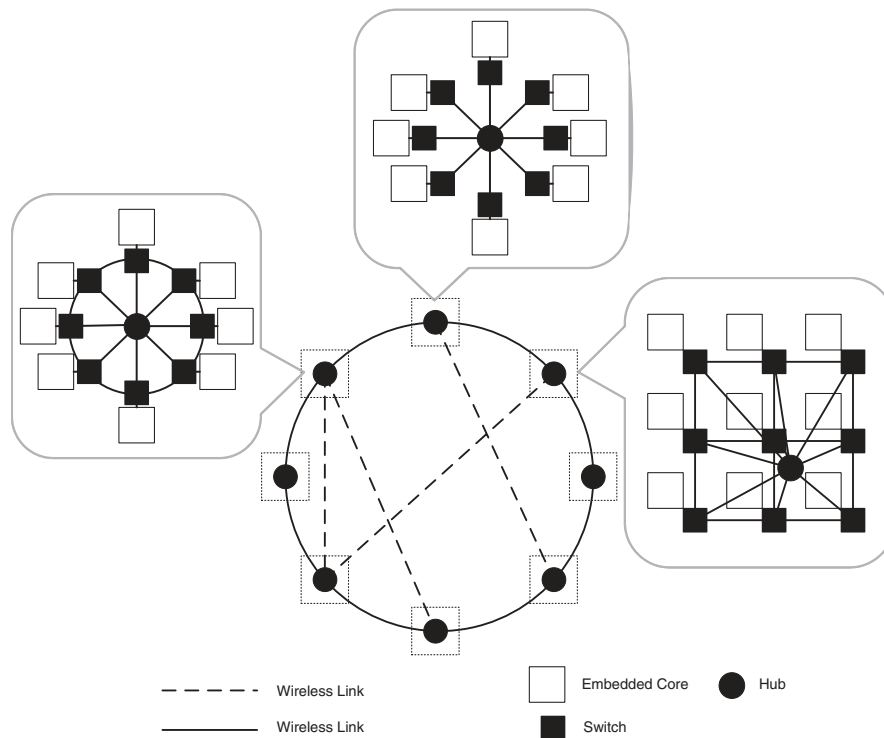


Fig. 1. A hybrid (wireless/wired) hierarchical NoC architecture with heterogeneous subnets and small-world-based upper-level configuration.

wireless links are equipped with WIs that transmit and receive data packets over the wireless channels. For inter-subnet data exchange, a packet first travels to its respective hub and reaches the hub of the destination subnet via the small-world network, where it is then routed to the final destination core.

There can be various subnet architectures, like mesh, star, ring, etc. Similarly, the basic architecture of the 2<sup>nd</sup> level of the hierarchy may vary. As an example the hubs may be connected in a mesh architecture with a few long-range wireless links spread across them creating a small-world network in the 2<sup>nd</sup> level of the hierarchy. As case studies, in this work we consider two types of subnet architectures, namely mesh and star-ring (a ring architecture with a central hub connecting to every core). Corresponding to each subnet architecture, we consider two upper-level small-world configurations, mesh and ring, with long-range wireless shortcuts distributed among the hubs. Thus, the following four hierarchical mm-wave NoC architectures are considered: Ring-StarRing, Ring-Mesh, Mesh-StarRing, and Mesh-Mesh. As an example, in the Ring-StarRing architecture, the first term (Ring) denotes the upper-level architecture and the second term (StarRing) indicates that the subnet is a star-ring topology. The same nomenclature applies to the rest of the hierarchical architectures in this article.

### 3.2. Placement of WIs

The WI placement is crucial for optimum performance gain as it establishes high-speed, low-energy interconnects on the network. Finding an optimal network topology with a limited number of WIs is a nontrivial problem with a large search space. It is shown in Ganguly et al. [2010] that for placement of wireless links in a NoC, the Simulated

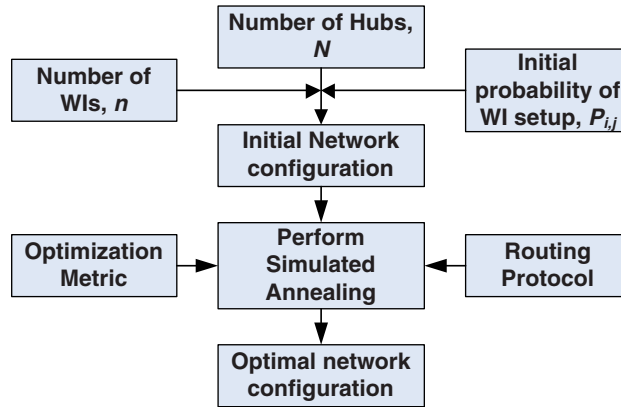


Fig. 2. Flow diagram for the simulated annealing-based optimization of mWNoC architectures.

Annealing (SA) algorithm converges to the optimal configuration much faster than the exhaustive search technique. Hence, we adopt an SA [Kirkpatrick et al. 1983]-based optimization technique for placement of the WIs to get maximum benefits of using the wireless shortcuts. SA offers a simple, well-established, and scalable approach for the optimized placement of WIs as opposed to an exhaustive search. Initially, the WIs are placed randomly with each hub having equal probability of getting a WI. The only constraint observed while deploying the WIs to the hubs is that a single hub could have a maximum of one WI.

Once the network is initialized randomly, an optimization step is performed using SA. Since the deployment of WIs is only on the hubs, the optimization is performed solely on the 2<sup>nd</sup>-level network of hubs. If there are  $N$  hubs in the network and  $n$  WIs to distribute, the size of the search space  $S$  is given by

$$|S| = \binom{N}{n}. \quad (1)$$

Thus, with increasing  $N$ , it becomes increasingly difficult to find the best solution by exhaustive search. To perform SA, a metric  $\mu$  is established, which is closely related to the connectivity of the network. To compute  $\mu$ , the shortest distances between all pairs of hubs are computed following the routing strategy outlined in the next section. The distances are then weighted with a normalized frequency of communication between the particular pair of hubs. The optimization metric  $\mu$  can be computed as

$$\mu = \sum_{ij} h_{ij} f_{ij}, \quad (2)$$

where  $h_{ij}$  is the distance (in hops) between the  $i^{\text{th}}$  source and  $j^{\text{th}}$  destination. The normalized frequency  $f_{ij}$  of communication between the  $i^{\text{th}}$  source and  $j^{\text{th}}$  destination is the a priori probability of traffic interactions between the subnets determined by particular traffic patterns depending upon the application mapped onto the NoC. In this case, equal weightage is attached to both inter-hub distance and frequency of communication. The steps used to optimize the network are shown in Figure 2.

An important point to note here is that similar results can also be obtained using other optimization techniques, like Evolutionary Algorithms (EAs) [Eiben et al. 2003] and coevolutionary algorithms [Sipper 1997]. Although EAs are generally believed to give better results, SA reaches comparably good solutions much faster [Jansen et al. 2007]. We have used SA in this work as an example.

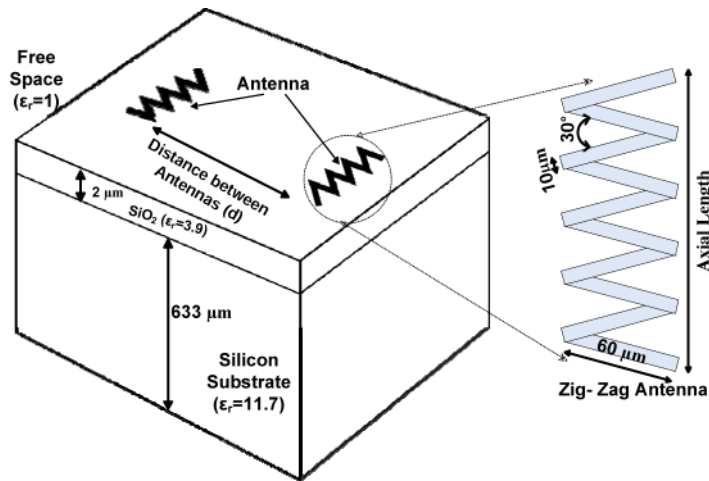


Fig. 3. Zig-zag antenna simulation setup.

#### 4. COMMUNICATION SCHEME

The hubs with WIs are responsible for supporting efficient data transfer between the distant nodes within the mWNoC by using the wireless communication channel. In this section we describe the various components of the WIs and the adopted data routing strategy. The two principal components of the WIs are the antenna and the transceiver. Characteristics of these two components are discussed in Sections 4.1 and 4.2, respectively.

##### 4.1. On-Chip Antennas

To be effective for the mWNoC application the on-chip antenna must be wideband, highly efficient, and sufficiently small. It has to provide the best power gain for the smallest area overhead. A metal zig-zag antenna [Floyd et al. 2002] has been demonstrated to possess these characteristics. This antenna also has negligible effect of rotation (relative angle between transmitting and receiving antennas) on received signal strength, making it most suitable for mWNoC application [Zhang et al. 2007]. The zig-zag antenna is designed with  $10 \mu\text{m}$  trace width,  $60 \mu\text{m}$  arm length, and  $30^\circ$  bend angle. The axial length depends on the operating frequency of the antenna which is determined in Section 5.1. The details of the antenna simulation setup and antenna structure are shown in Figure 3.

##### 4.2. Wireless Transceiver Circuit

The design of a low-power wideband wireless transceiver is the key to guarantee the desired performance of the mWNoC. Therefore, at both architecture and circuit levels of the transceiver, low-power design considerations were taken into account. As illustrated in the transceiver architecture diagram in Figure 4, the transmitter (TX) circuitry consists of an up-conversion mixer and a Power Amplifier (PA). At the receiver (RX) side, direct-conversion topology is adopted, which consists of a Low Noise Amplifier (LNA), a down-conversion mixer, and a baseband amplifier. An injection-lock Voltage-Controlled Oscillator (VCO) is reused for TX and RX. With both direct-conversion and injection-lock technologies, a power-hungry Phase-Lock Loop (PLL) is eliminated in the transceiver [Kawasaki et al. 2010]. Moreover, at circuit level, body-enabled design techniques [Deen et al. 2002], including both Forward Body-Bias (FBB) with DC voltages, as well as body-driven by AC signals [Kathiresan et al. 2006], are implemented in most of the circuit subblocks to further decrease their power consumptions.

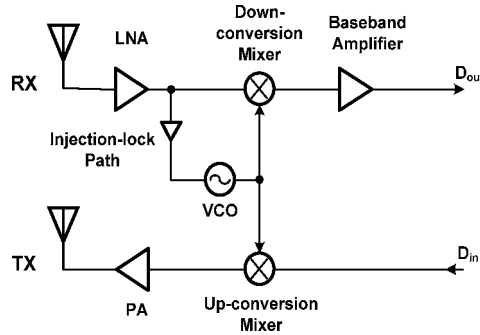


Fig. 4. Block diagram of the mm-wave direct-conversion transceiver with injection-lock VCO.

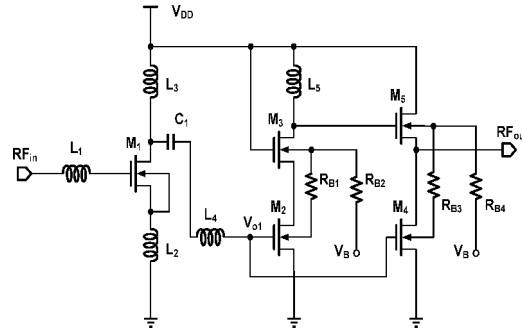


Fig. 5. Schematic of the body-biased LNA with a feed-forward path for bandwidth extension.

The LNA is a crucial component in the RX chain as it determines the sensitivity of the entire receiver. To achieve a wide bandwidth, a novel feed-forward path is implemented. Moreover, using body-enabled design, low power consumption is maintained. Figure 5 demonstrates the circuit topology of the proposed low-power wideband LNA, consisting of three stages. A Common-Source (CS) amplifier with inductive source degeneration is chosen for the first stage since it has better noise performance than the cascode topology. At the drain of the transistor  $M_1$ , inductors  $L_3$  and  $L_4$  form a bridged-shunt-series peaking structure that serves to extend the bandwidth [Shekhar et al. 2006]. The second stage employs a cascode topology to enhance the overall gain and reverse isolation of the LNA. Inductor  $L_5$  is adjusted to peak the gain at a slightly different frequency from the first stage, realizing a wideband overall frequency response. Moreover, a feed-forward path, which can boost up the gain of the first stage, is introduced in the third stage, directly coupling the gate of  $M_2$  to  $M_4$  [Yu et al. 2010]. With the peak gain of the second stage set at a higher frequency than that of the first stage, this feed-forward path extends the bandwidth of the entire LNA at the lower end. Moreover, the feed-forward path only causes trivial degradation to the overall Noise Figure (NF) of the LNA, since the noise introduced by  $M_4$  is suppressed by the gain of the first stage. In addition,  $M_4$  reuses the bias current with  $M_5$ , hence no extra power consumption is introduced.

As can be seen in Figure 5, FBB is implemented in the last two stages of the LNA. The threshold voltage of an NMOS transistor can be expressed as [Sedra et al. 2004]

$$V_t = V_{t0} + \gamma \left( \sqrt{2\phi_F + V_{SB}} - \sqrt{2\phi_F} \right),$$



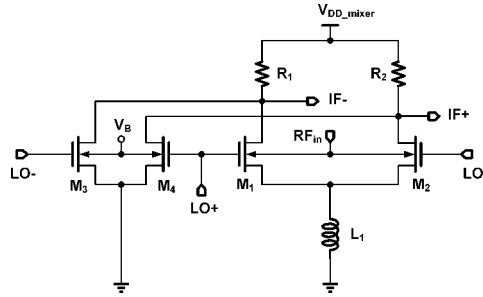


Fig. 6. Schematic of the body-driven down-conversion mixer with body-biased dummy switching pair for LO-feedthrough cancellation.

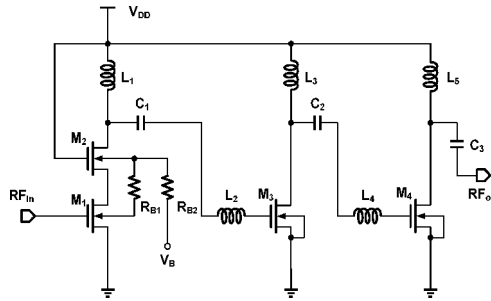


Fig. 7. Circuit topology of the low-power wideband body-biased PA.

where  $V_{SB}$  is the voltage between body and source terminals,  $V_{t0}$  is the threshold voltage when  $V_{SB} = 0$ ,  $\gamma$  is a process-dependent parameter, and  $\phi_F$  is the bulk Fermi potential. This indicates that by applying a positive bias voltage at the body terminal, the threshold voltage of the NMOS can be effectively decreased without degradations in device characteristics in terms of gain, linearity, and noise figure [Deen et al. 2002]. Accordingly, in the second stage of the LNA, since the source voltages of  $M_2$  and  $M_3$  are different, two different DC voltage levels are generated by the bias voltage  $V_B$  and the voltage divider  $R_{B1}$  and  $R_{B2}$ , and applied to the body terminals of  $M_2$  and  $M_3$ , respectively. The FBB in the third stage is implemented in a similar way. This decreases the threshold voltages of these transistors, and hence the supply voltage is reduced from 1 V to 0.8 V.

The down-conversion mixer shown in Figure 6 uses a bulk-driven topology to save power without sacrificing the performance. Since the body terminal acts as a “back-gate”, the RF signal is directly fed into the body terminals of the switching pair. In this way, not only the switching pair can be biased at very low DC current, the removal of the stacked transconductance stage also leads to a lower supply voltage. In addition, in order to eliminate Local Oscillator (LO) feed through at the Intermediate Frequency (IF) port, a novel body-biased dummy switching pair consisting of  $M_3$  and  $M_4$  is introduced. By adjusting the body-bias voltage of the dummy pair, the level of LO cancellation can be optimized.

At the TX side, due to the short communication range of the mWNoC, the required PA output power is much lower than in conventional mm-wave power amplifiers. Nevertheless it still needs to maintain a wide bandwidth for the required high data rate. The circuit topology of the proposed three-stage PA is shown in Figure 7. The cascode structure is used in the first stage for its high gain and better reverse isolation. Similar to the LNA design, FBB is implemented in the cascode stack to lower the power

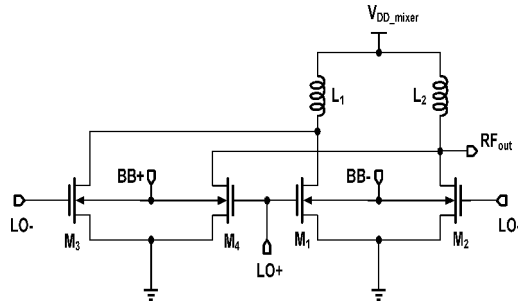


Fig. 8. The body-driven up-conversion mixer circuit.

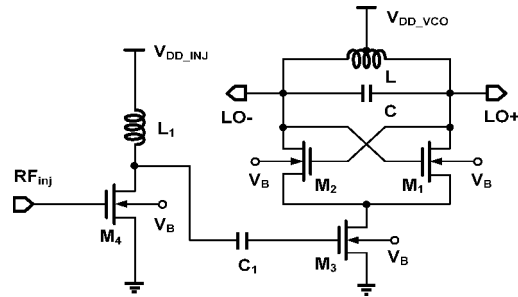


Fig. 9. The body-biased injection-lock VCO circuit.

consumption of the PA. The other two are both CS stages, which can provide larger voltage headroom and thus better linearity. Moreover, for bandwidth extension, inductive peaking is created by  $L_2$  and  $L_4$  at the output of the first and the second stages, respectively. Note that the bias current densities of the last two stages are set to around  $0.3 \text{ mA}/\mu\text{m}$  for maximum linearity [Yao et al. 2007]. A body-driven double-balanced mixer serves as the up-conversion mixer. As depicted in Figure 8, the baseband signal is fed into the body terminals of the switching pair, modulating the 55-GHz carrier signal.

The proposed schematic of the injection-lock VCO is shown in Figure 9. The injection locking technique [Razavi 2004] not only lowers the phase noise, but also reduces the frequency and phase variation in the VCO without the use of a PLL. Moreover, FBB is applied at the body terminals of all the transistors to lower their threshold voltages, so that a lower bias voltage can be used to decrease the power consumption. As shown in the schematic, transistors  $M_1$  and  $M_2$  form a NMOS cross-coupled pair. Transistor  $M_3$  acts as a tail current source as well as signal injection point for the VCO. Furthermore, in order to achieve a desirable locking range for the VCO, an injection amplifier  $M_4$  is also implemented to boost the signal before being fed into  $M_3$ .

### 4.3. Adopted Routing Strategy

In this proposed hierarchical NoC, intra-subnet data routing is done depending on the topology of the subnet. In this work, we consider two subnet topologies (i.e., mesh and star-ring). In a mesh subnet, the data routing follows a deadlock-free dimension order (e-cube) routing. In a star-ring subnet, if the destination core is within two hops on the ring from the source, then the flit is routed along the ring. If the destination is more than two hops away, then the flit goes through the central hub to its destination. Thus, within the star-ring subnet, each core is at a distance of at most two hops from any other cores. To avoid deadlock, we adopt the virtual channel management scheme from

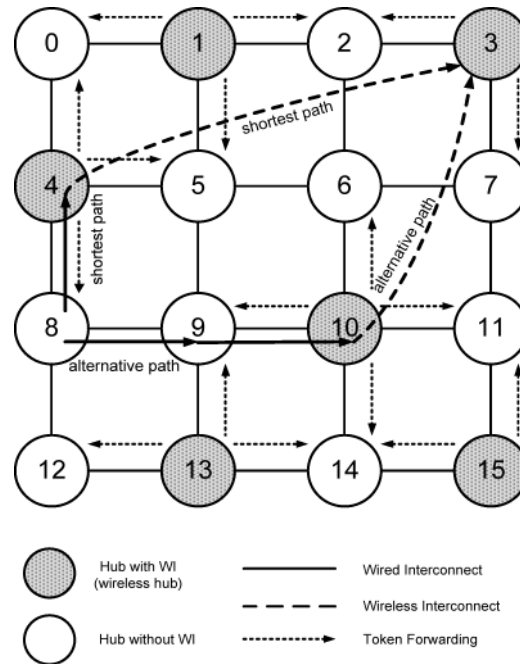


Fig. 10. An example of token-flow-control-based distributed routing.

Red Rover algorithm [Draper et al. 1997], in which the ring is divided into two equal sets of contiguous nodes. Messages originating from each group of nodes use dedicated virtual channels. This scheme breaks cyclic dependencies and prevents deadlock.

Inter-subnet data routing, however, requires the flits to use the upper-level network consisting of wired and wireless links. By using the wireless shortcuts between the hubs with WIs, flits can be transferred in a single hop between them. If the source hub does not have a WI, the flits are routed to the nearest hub with a WI via the wired links and are then transmitted through the wireless channel. Likewise, if the destination hub does not have a WI, then the hub nearest to it with a WI receives the data and routes it to the destination through wired links. Between a pair of source and destination hubs without WIs, the routing path involving the wireless medium is chosen if it reduces the total path length compared to the wired path. This can potentially give rise to a hotspot situation in all the WIs because many messages try to access wireless shortcuts simultaneously, thus overloading the WIs and resulting in higher latency. A token flow control [Kumar et al. 2008a] along with a distributed routing strategy is adopted to alleviate this problem. Tokens are used to communicate the status of the input buffers of a particular WI to the other nearby hubs, which need to use that WI for accessing wireless shortcuts. Every input port of a WI has a token and the token is turned on if the availability of the buffer at that particular port is greater than a fixed threshold and turned off otherwise. The routing adopted here is a combination of dimension order routing for the hubs without WIs and South-East routing algorithm for the hubs with WIs. This routing algorithm is proved to be deadlock free in Ogras et al. [2006]. Figure 10 shows a particular communication snapshot of a mesh-based upper-level network where hub 8 wants to communicate with hub 3. First at source 8, the nearest WI (4 in this case) is identified. Then the routing algorithm checks whether taking this WI reduces the total hop count. If so, the token for the south input port of

hub 4 is checked and this path is taken only if the token is available. If this is not the case, the message at hub 8 follows dimension order routing towards the destination and arrives at hub 9. At hub 9, again the shortest path using WIs is searched and if the token from hub 10 allows the usage of wireless shortcuts, then the message is routed through hub 10. Otherwise, the message follows dimension order routing and keeps looking for the shortest path using WIs at every hub until the destination hub is reached. Consequently, the distributed routing along with token flow control prevents deadlocks and effectively improves performance by distributing traffic through alternative paths. It is also livelock free since it generates a minimal path towards the destination, as the adopted routing here ensures that the wireless shortcuts are only followed if that reduces the hop count between source and destination. As a result, this routing always tries to find the shortest path and never allows routing away from the destination.

In a ring-based upper-level network, the same principle of distributed routing and token flow control is used. The message follows ring routing and keeps looking for the shortest path with available WI at every hub until the destination hub is reached. As mentioned before, the ring routing adopted here is based on the Red Rover algorithm [Draper et al. 1997], which provides deadlock-free routing by dividing the ring into two equal sectors and using virtual channels. In this case also routing will never allow any packet to be routed away from the destination and hence the routing is livelock free.

As all the wireless hubs are tuned to the same channel and can send or receive data from any other wireless hub on the chip, an arbitration mechanism needs to be designed in order to grant access to the wireless medium to a particular hub at a given instant to avoid interference and contention. To avoid the need for a centralized control and synchronization mechanism, the arbitration policy adopted is a wireless token passing protocol. It should be noted that the use of the word token in this case differs from the usage in the aforementioned token flow control. According to this scheme, the particular WI possessing the wireless token can broadcast flits into the wireless medium. All other hubs will receive the flit as their antennas are tuned to the same frequency band. However, only if the destination address matches the address of the receiving hub is the flit accepted for further routing, either to a core in the subnet of that hub or to an adjacent hub. The wireless token is forwarded to the next hub with a WI after all flits belonging to a packet at the current wireless token-holding hub are transmitted.

## 5. PERFORMANCE EVALUATION

In this section we characterize the performance of the proposed mWNoC through rigorous simulation and analysis in presence of various traffic patterns. First, we present the characteristics of the on-chip wireless communication channel by elaborating the performances of the antenna and the transceiver circuits. Then we describe the detailed network-level simulations considering various system sizes and traffic patterns.

Figure 11 shows an overview of the performance evaluation setup for a mWNoC. To obtain the gain and bandwidth of the antennas we use ADS momentum tool [Agilent 2012]. Bandwidth and gain of the antennas are necessary for establishing the required design specifications for the transceivers. The mm-wave wideband wireless transceiver is designed and simulated using Cadence tools with TSMC 65-nm standard CMOS process to obtain its power and delay characteristics. The subnet switches and the digital components of the hubs are synthesized using Synopsys tools with 65-nm standard cell library from TSMC at a clock frequency of 2.5 GHz. Energy dissipation of all the wired links are obtained from actual layout in Cadence assuming a  $20\text{ mm} \times 20\text{ mm}$  die area.

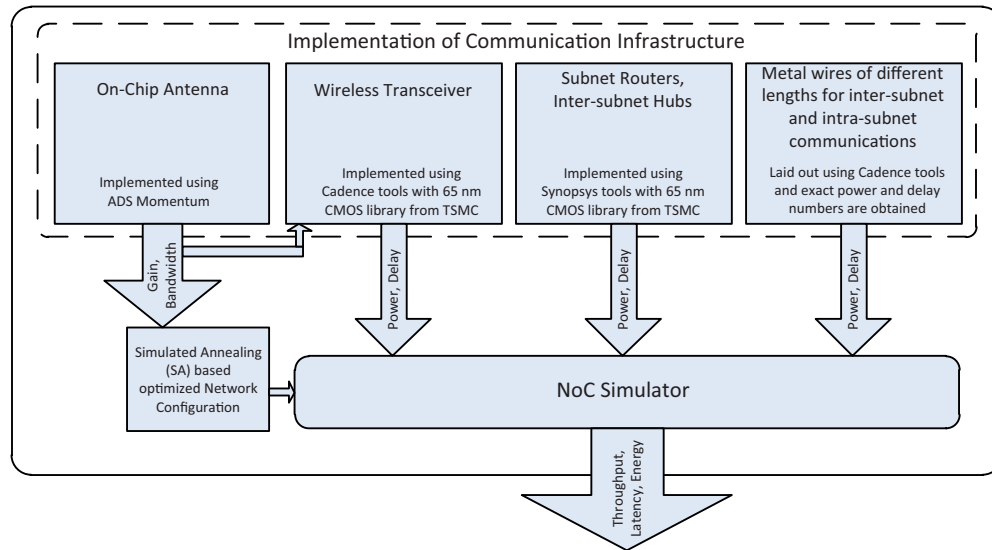


Fig. 11. Overview of performance evaluation setup for mWNoC.

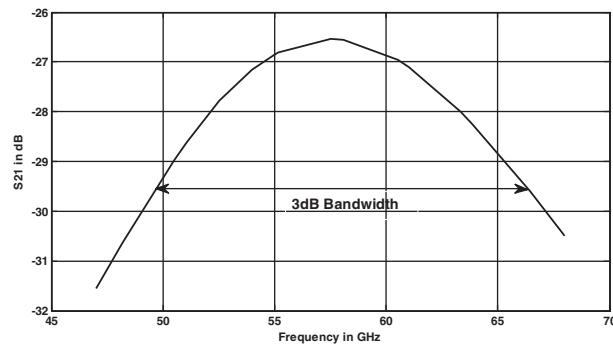


Fig. 12. Antenna S21 response.

All the power and delay numbers of various components are then fed into the network simulator to obtain overall mWNoC performance.

### 5.1. Wireless Channel Characteristics

The metal zig-zag antennas described earlier are used to establish the on-chip wireless communication channels. Figure 3 shows the simulation setup for on-chip wireless antennas. High resistivity silicon substrate ( $\rho = 5 \text{ k}\Omega\text{-cm}$ ) is used for the simulation. In our experimental setup, depending on the architecture of the 2<sup>nd</sup> level of the hierarchy, the maximum distance between a transmitter and receiver pair is 18 mm and for the antenna simulations this communication range is used. The forward transmission gain (S21) of the antenna is shown in Figure 12. For optimum power efficiency, the quarter wave antenna needs an axial length of 0.38 mm in the silicon substrate.

As shown in Figure 11 earlier, the mm-wave wideband wireless transceiver is designed and simulated using TSMC 65-nm standard CMOS process. The overall conversion gain and Noise Figure (NF) of the receiver, including the proposed LNA and mixer, are shown in Figure 13. The VCO generated  $-5 \text{ dBm}$  of output power, and the

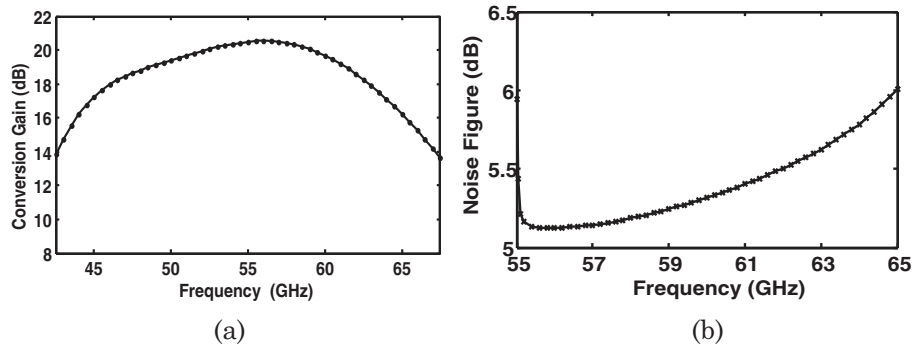


Fig. 13. Simulated (a) gain, and (b) double-sideband NF of the receiver.

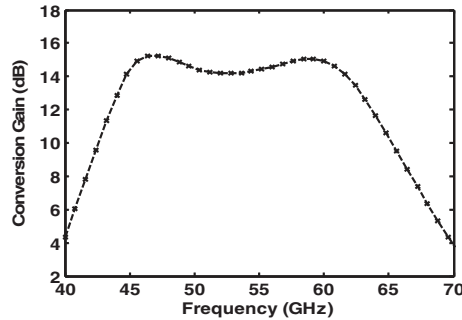


Fig. 14. Simulated TX conversion gain.

LO frequency was set to 55 GHz, in accordance with the center frequency of the LNA's pass-band. The conversion gain is 20 dB at the center frequency, and rises up to 20.5 dB at the peak. This indicates that the mixer contributes around 7 dB of conversion gain. Figure 13(a) also shows that the overall 3-dB bandwidth of the receiver front-end is 18 GHz. From Figure 13(b), it can be seen that the overall NF stays below 6 dB. Note that double sideband (DSB) NF is used since the proposed receiver has a direct-conversion structure. The LNA and the mixer drain 10.8 mA and 0.75 mA of current, respectively, from the 0.8 V DC bias. Accordingly, the aggregate power consumption of the receiver front-end is 9.24 mW.

The conversion gain of the transmitter is illustrated in Figure 14. The transmitter has a peak gain of 15 dB, and a 3-dB bandwidth of 18.1 GHz. Furthermore, circuit simulation also shows that the output 1-dB gain compression point ( $P_{1dB}$ ) of the transmitter is 0 dBm. With the implementation of body-enabled design in both the PA and up-conversion mixer, the TX front-end consumes only 14 mW from a 0.8-V supply voltage.

The achieved aggregate power consumption of the entire transceiver is 36.7 mW, 16% lower than the previous design without using body-enabled techniques [Yu et al. 2010; Deb et al. 2010]. It is able to support a data rate of at least 16 Gbps, and a BER  $< 10^{-15}$  using an OOK modulation scheme.

Using the preceding characteristics of the antennas and mm-wave transceivers, we carried out a comparative performance analysis between the wireless and wired communication channels. The wired channels are considered to be 32 bits wide, which is equal to the flit width considered in this article. Each link of the wired channel is designed with the optimum number of uniformly placed and sized repeaters. Figure 15

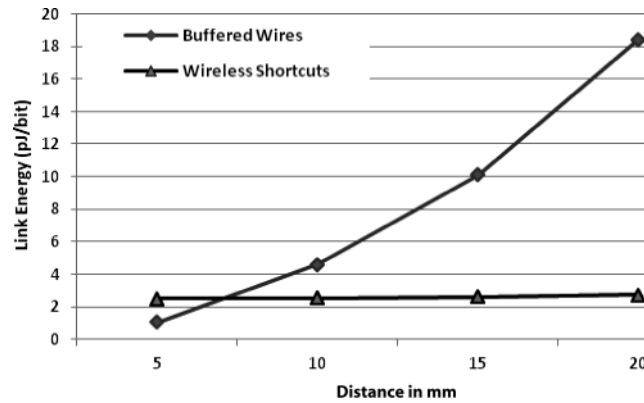


Fig. 15. The variation of energy dissipation per bit with distance for a wired and a wireless link.

presents how energy dissipated per bit changes as a function of length for both wireless and wired links. From this plot it can be observed that wireless shortcuts are always energy efficient whenever the link length is 7 mm or more. Moreover, wireless links eliminate the need to lay out long buffered wire links with many via cuts from the upper-layer wires all the way down to the substrate. Hence, implementation of long-range links beyond 7 mm using wireless makes the design energy efficient and simpler in terms of layout. In our implementation, the minimum and maximum distances between the WIs communicating using the wireless channel are 7.07 mm and 18 mm, respectively. Therefore, in this case, using the wireless channel is always more energy efficient.

## 5.2. Network-Level Performance Evaluation

In this section, we analyze the characteristics of the proposed mWNoC and study the trends in performance as the number of WIs is increased for a particular system. Our aim is to establish a design trade-off point that helps us in selecting the optimum number of WIs for certain performance requirements. For our experiments, we consider three different system sizes, namely 128, 256, and 512 cores, and the die area is kept fixed at 20 mm × 20 mm in all the cases. The subnet switch architecture is adopted from Pande et al. [2005]. It has three functional stages, namely, input arbitration, routing/switch traversal, and output arbitration. Each packet consists of 64 flits. The input and output ports including the ones on the wireless links have 4 virtual channels per port, each having a buffer depth of 2 flits. The subnet switches and the hubs handle the inputs and outputs separately as explained in Dally [1992]. The average message latency decreases when buffer size increases [Duato et al. 2002]. According to Duato et al. [2002], the effect of buffer size on performance is small. Moreover, increasing buffer capacity does not increase performance significantly if messages are longer than the diameter of the network times the total buffer capacity of a virtual channel (which is the case for all the system sizes considered in this study) [Duato et al. 2002]. This is also verified using our own simulations, and the trade-off point for buffer depth that provides optimum performance without consuming excessive silicon area is obtained as two flits.

Similar to the intra-subnet communication, we adopt wormhole routing in the wireless channel too. Consequently, the hubs have similar architectures to the NoC switches in the subnets. Hence, each port of the hub has the same input and output arbiters, and an equal number of virtual channels with same buffer depths as the subnet switches. The number of ports in a hub depends on the number of links connected to it. The hubs

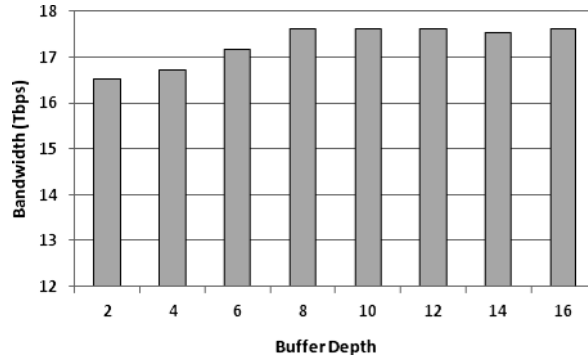


Fig. 16. Performance variation with change in buffer depth for the ports associated with WIs for a 256-core Mesh-StarRing system.

also have three functional stages, but as the number of cores increases in a subnet, the delays in arbitration and switching for some cases are more than a clock cycle. Depending on the subnet sizes, traversal through these stages needs multiple cycles and this has been taken into consideration when evaluating overall performance of the mWNoC. The ports associated with the WIs have an increased buffer depth of 8 flits to avoid excessive latency penalty while waiting for the token. Increasing the buffer depth beyond this limit does not produce any further performance improvement for this particular packet size, but will give rise to additional area overhead. This is shown in Figure 16 for a 256-core Mesh-StarRing system divided into 16 subnets. The wireless ports of the WIs are assumed to be equipped with antennas and wireless transceivers. A self-similar traffic injection process is assumed.

The network architectures developed earlier are simulated using a cycle-accurate simulator. The delays in flit traversals along all the wired interconnects that enable the proposed hybrid NoC architecture are considered when quantifying the performance. These include the intra-subnet core-to-hub wired links and the inter-hub links in the upper level of the network. The delays through the switches and inter-switch wires of the subnets and the hubs are taken into account as well.

To quantify the energy dissipation characteristics of the proposed mWNoC architecture, we determine the packet energy dissipation,  $E_{pkt}$ . The packet energy is the energy dissipated on average by a packet from its injection at the source to delivery at the destination. This is calculated as

$$E_{pkt} = \frac{N_{intrasubnet} E_{subnet,hop} h_{subnet} + N_{intersubnet} E_{s-w} h_{s-w}}{N_{intrasubnet} + N_{intersubnet}},$$

where  $N_{intrasubnet}$  and  $N_{intersubnet}$  are the total number of packets routed within the subnet and between the subnets, respectively,  $E_{subnet,hop}$  is the energy dissipated by a packet traversing a single hop on the wired subnet including a wired link and a switch, and  $E_{s-w}$  is the energy dissipated by a packet traversing a single hop on the 2<sup>nd</sup> level of the mWNoC network, which has the small-world property. The average number of hops per packet in the subnet and the upper-level small-world network are denoted by  $h_{subnet}$  and  $h_{s-w}$  respectively.

To determine the optimum division of the proposed hierarchical architecture in terms of achievable bandwidth, we evaluate the performance by dividing the whole system in various alternative ways. Figure 17 shows the achievable bandwidth for a 256-core Mesh-StarRing mWNoC divided into different numbers of subnets. As can be seen from the plot, the division of the whole system into 16 subnets with 16 cores in each performs the best. Similarly, the suitable hierarchical division that achieves best performance is



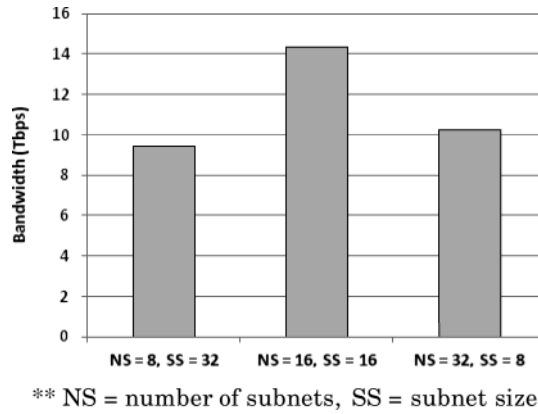


Fig. 17. Bandwidth of a 256-core Mesh-StarRing mWNoC for various hierarchical configurations.

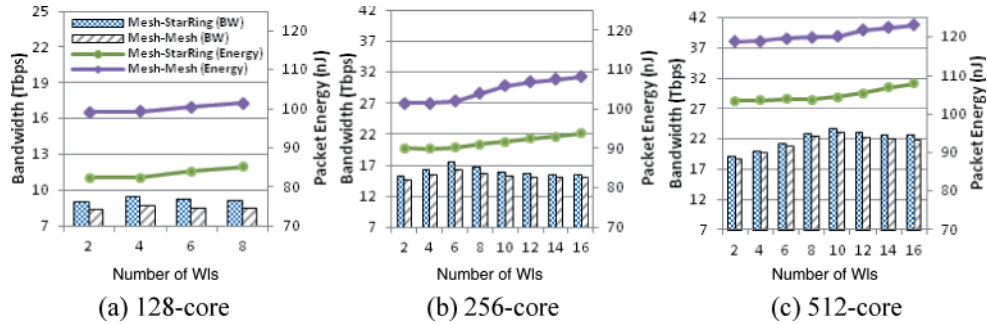


Fig. 18. Achievable bandwidth and energy trade-offs for Mesh-Mesh and Mesh-StarRing architectures with varying number of WIs.

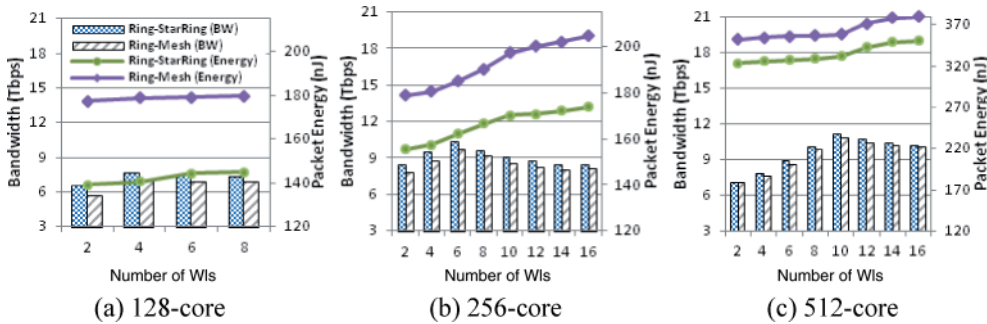


Fig. 19. Achievable bandwidth and energy trade-offs for Ring-Mesh and Ring-StarRing architectures with varying number of WIs.

determined for all the other system sizes. For system sizes of 128 and 512, the optimum number of subnets turns out to be 8 and 32, respectively.

Figures 18 and 19 show the achievable bandwidth and packet energy trade-offs of the proposed mWNoC with varying number of WIs under uniform random spatial traffic distribution for the three system sizes of 128, 256, and 512 cores divided into 8, 16, and 32 subnets, respectively. Figure 18 considers two specific architectures (i.e., Mesh-Mesh and Mesh-StarRing), where the upper levels are mesh-based topologies, and the

subnets are Mesh and StarRing, respectively. Figure 19 represents the characteristics of Ring-Mesh and Ring-StarRing architectures. It can be observed that, for all system sizes and architectures, the bandwidth increases as we start placing more WIs in the system initially, then it reaches a saturation point and starts decreasing. Placing more WIs in the system beyond a certain threshold has negative impact on system performance. This happens because the wireless communication channel is a shared medium. As explained in Section 4.3 before, each WI needs to obtain a token to access the wireless channel. Since there is only one wireless token circulating among all the WIs, as the number of WIs goes up, the delay in acquiring the wireless medium for a particular WI increases. Consequently, it degrades the overall system performance. Moreover, as the number of WIs increases, the overall energy dissipation from the WIs becomes higher, and it causes the packet energy to increase as well. Considering all these factors, we can find the optimum number of WIs corresponding to each system size.

From our experiments we find that the overall bandwidth reaches a maximum with 4, 6, and 10 WIs for 128, 256, and 512 core systems, respectively. Beyond this limit, the bandwidth degrades, but the energy dissipation continues to increase. This study helps us to determine the optimum number of WIs for each system size. It is also evident that the Mesh-StarRing architecture always outperforms Mesh-Mesh architecture as it has better connectivity in the subnets. It results in lower packet energy for the Mesh-StarRing architecture compared with Mesh-Mesh architecture. The same trend is also observed in the architectures with ring-based upper levels, where systems with StarRing subnets always achieve higher bandwidth than those with Mesh subnets. In terms of upper-level topologies, systems with a mesh-based upper level always perform better and have lower packet energy than those with ring-based upper-level due to a more efficient upper-level network. These advantages of the mesh-based upper-level network come at the cost of extra wiring overhead. For a 256-core system, a mesh-based upper-level network has 24 wired links whereas a ring-based counterpart only has 16 wired links, or 33% less links. The new Mesh-StarRing architecture along with the routing mechanism elaborated in Section 4.3 results in 14.6% bandwidth improvement and 48% saving in packet energy for a 256-core system with 6 WIs in comparison with our previous work [Deb et al. 2010].

### 5.3. Comparative Performance Evaluation with Other Interconnect Technologies

In this section, we consider two other possible interconnect technologies, namely, RF-I and G-line, that can be used as long-range links in the proposed hierarchical small-world architecture. Here, we consider a 256-core Mesh-StarRing architecture, and undertake a comparative study to establish the relative performance benefits achieved by using these alternatives as long-range shortcuts in the upper-level small-world network. We first design a small-world NoC (RFNoC) using RF-I links as the shortcuts, maintaining the same hierarchical topology. As mentioned in Chang et al. [2008], in 65-nm technology it is possible to have 8 different frequency channels each operating with a data rate of 6 Gbps. Like the wireless channel, these RF links can be used as the long-range shortcuts in the hierarchical NoC architecture. These shortcuts are optimally placed using the same SA-based optimization as used for placing the WIs in the mWNoC. The optimum locations of the hubs with RF-I interfaces are not the same as those of mWNoC due to the difference in their characteristics. Next, we construct a small-world NoC (GLNoC) by replacing the shortcuts of RFNoC by G-lines [Mensink et al. 2007], and still maintain the same hierarchical topology. Each G-line uses a capacitive preemphasis transmitter that increases the bandwidth and decreases the voltage swing without the need of an additional power supply. To avoid cross-talk, differential interconnects are implemented with a pair of twisted wires. A decision feedback equalizer is employed at the receiver to further increase the achievable data

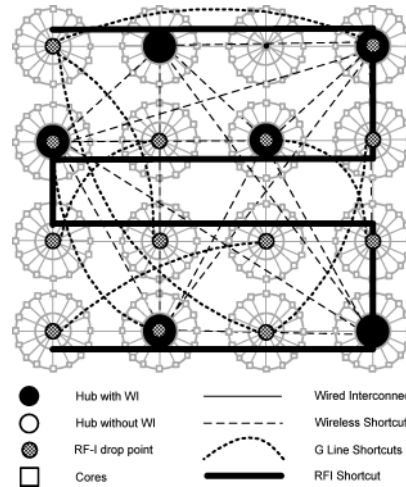


Fig. 20. Implementation details of different NoC shortcuts.

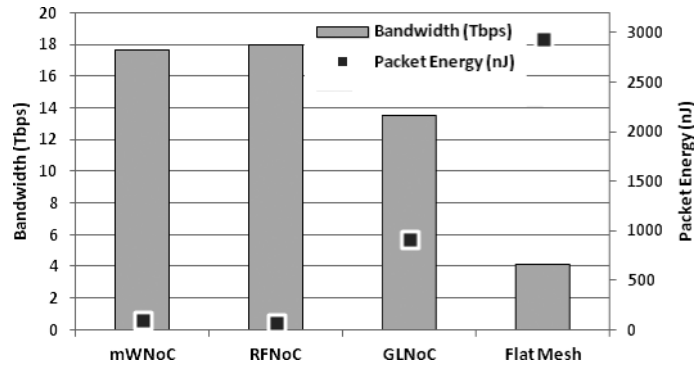


Fig. 21. Comparative analysis of hierarchical small-world NoCs with three types of long-range shortcuts with uniform random traffic.

rate. Each G-line can sustain a bandwidth of around 2.5 Gbps for a wire length of 11 mm. The exact implementation details for the NoC architectures with different shortcuts are shown in Figure 20.

Figure 21 shows the overall system bandwidth and packet energy dissipation for mWNoC, RFNoC, and GLNoC in a 256-core Mesh-StarRing system under uniform random traffic. A 256-core flat mesh is also included for comparison. Compared to the flat mesh architecture, the three hierarchical NoCs achieve much higher bandwidth and consume significantly less energy. This is because a hierarchical network reduces the average hop count, and hence improves the performance. Moreover, packets get routed faster and hence occupy resources for less time and dissipate less energy in the process. The energy dissipation for G-line and RFI is obtained from Chang et al. [2008] and Mensink et al. [2007] respectively. It can be observed that, among the three types of small-world NoCs, GLNoC has the lowest bandwidth and highest packet energy. The length of the shortcuts is more than 11 mm and hence the G-line communication essentially becomes multihop. Consequently, this reduces the overall achievable bandwidth for GLNoC. In addition, the high capacitance of G-line links causes more energy

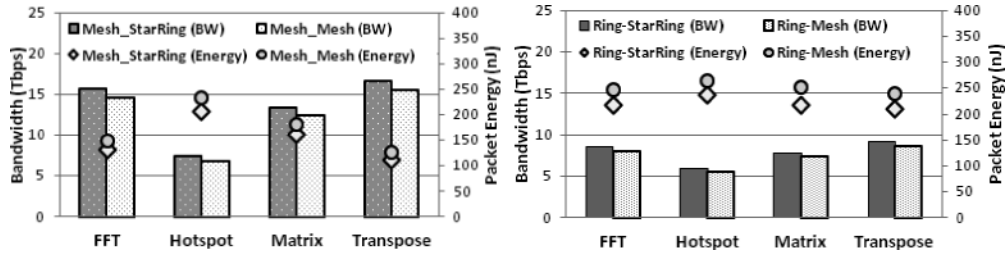


Fig. 22. (a) 256-core system with mesh-based upper-level architecture. (b) 256-core system with ring-based upper-level architecture.

dissipation. Though mWNoC and RFNoC have the same hierarchical architecture, the latter performs better because in RFNoC multiple shortcuts can work simultaneously whereas in mWNoC only one pair can communicate at a particular instant of time since the wireless channel is a shared medium. But the long-range link area overhead and layout challenges of the RFNoC will be more than that of the mWNoC. For example, in case of a  $20 \times 20 \text{ mm}^2$  die, an RF interconnect of approximately 100 mm length has to be laid for RFNoC. This is significantly higher than the combined length of all the antennas used in mWNoC, which is 3.8 mm for the highest system size (512-core system with 10 WIs) considered in this article. A detailed link area overhead analysis for all the different NoC architectures is presented in Section 5.5.

#### 5.4. Performance Evaluation with Nonuniform Traffic

In order to evaluate the performance of the proposed mWNoC architecture with nonuniform traffic patterns, we consider both synthetic, and application-based traffic distributions. In the following analysis, the system size considered is 256 (with 16 subnets and 16 cores per subnet), and the number of WIs is chosen to be 6 as obtained from Section 4.2. The WIs are placed optimally depending on the particular traffic scenario following the algorithm discussed in Section 3.2.

We consider two types of synthetic traffic to evaluate the performance of the proposed mWNoC architecture. First, a transpose traffic pattern [Ogras et al. 2006] is considered where a certain number of hubs communicate more frequently with each other. We have considered 3 such pairs of subnets and 50% of packets generated from one of these subnets are targeted towards the other in the pair. The other synthetic traffic pattern considered was the hotspot [Ogras et al. 2006], where each hub communicates with a certain number of hubs more frequently than with the others. We have considered three such hotspot locations to which all other hubs send 50% of the packets that originate from them. To represent a real application, a 256-point Fast Fourier Transform (FFT) is considered on the same 256-core mWNoC subdivided into 16 subnets. Each core is considered to perform a 2-point radix 2 FFT computation. The traffic pattern generated in performing multiplication of two  $128 \times 128$  matrices is also used to evaluate the performance of the mWNoC.

Figure 22 presents the bandwidth and packet energy for different traffic patterns. The same performance-energy trade-off trend as with the uniform random traffic is observed in this case also. The architectures with mesh-based upper levels always outperform the architectures with ring-based upper levels. Systems with StarRing subnets also perform better than those with Mesh subnets.

We also evaluate the performance of a 256-core Mesh-StarRing mWNoC with respect to a corresponding RFNoC and GLNoC of the same size in the presence of the aforementioned application-specific traffic patterns. As shown in Figure 23, the same

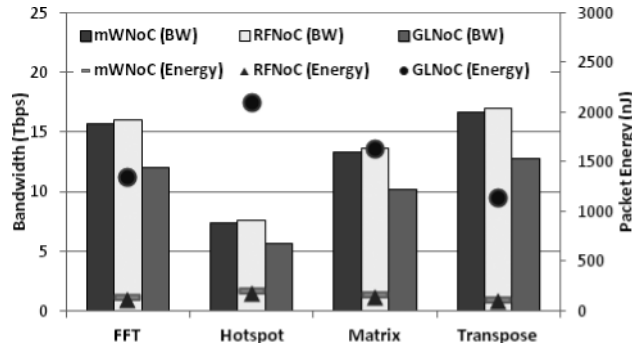


Fig. 23. Comparison of the three types of hierarchical small-world NoC architectures with nonuniform traffic patterns.

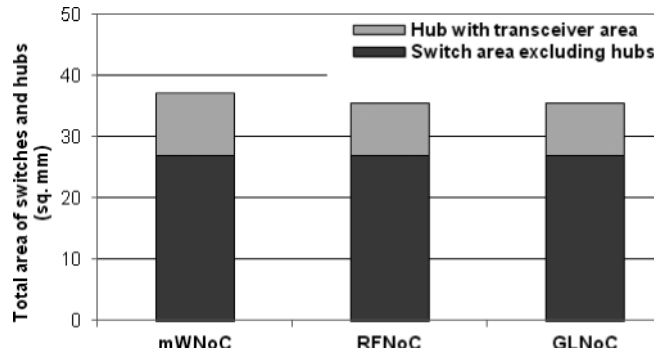


Fig. 24. Total silicon area for 256-core mWNoC, RFNoC, and GLNoC.

bandwidth and energy dissipation trend is observed as in the uniform random traffic case.

### 5.5. Area Overheads

In this subsection, we quantify the area overhead for the hierarchical mWNoC as well as for the RFNoC and the GLNoC studied in the previous section. In mWNoC, the antenna used is a 0.38 mm long zig-zag antenna. The area of the transceiver circuits required per WI is the total area required for the OOK modulator/demodulator, LNA, PA, and VCO. The total area overhead per wireless transceiver turns out to be 0.3 mm<sup>2</sup> for the selected frequency range. The digital part for each WI, which is very similar to a traditional wireline NoC switch, has an area overhead of 0.40 mm<sup>2</sup>. Therefore, total circuit area overhead per hub with a WI is 0.7 mm<sup>2</sup>. The transceiver area overhead for RF-I and G-line are taken from Chang et al. [2008] and Mensink et al. [2007] respectively. Total silicon area overheads for mWNoC, RFNoC, and GLNoC in a 256-core Mesh-StarRing system are shown in Figure 24. The required silicon area is largely dominated by the intra-subnet switches associated with the NoC architectures. The area overheads arising due to the hubs along with the required transceivers for different shortcuts are shown separately. The hub area is dominated by the non-transceiver digital components. Though the transceiver areas of the mm-wave wireless links, RF-I, and G-line vary, the digital components of the hubs are the same irrespective of the particular interconnect technology used. Consequently, the overall hub area overhead does not vary much depending on the interconnect technology. This is

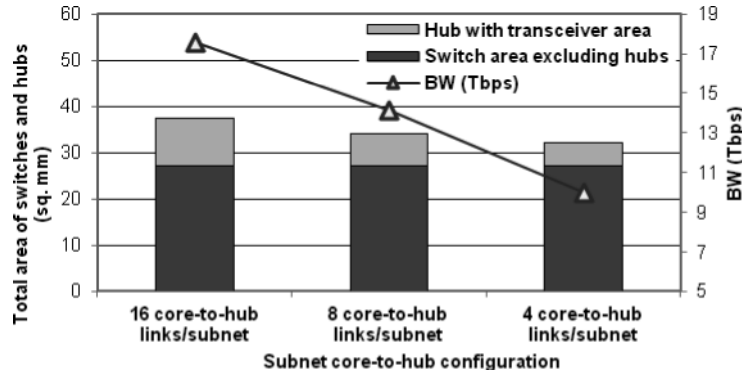


Fig. 25. Area overhead and performance degradation trade-off with decreasing the number of connections of each hub for a 256-core mWNoC.

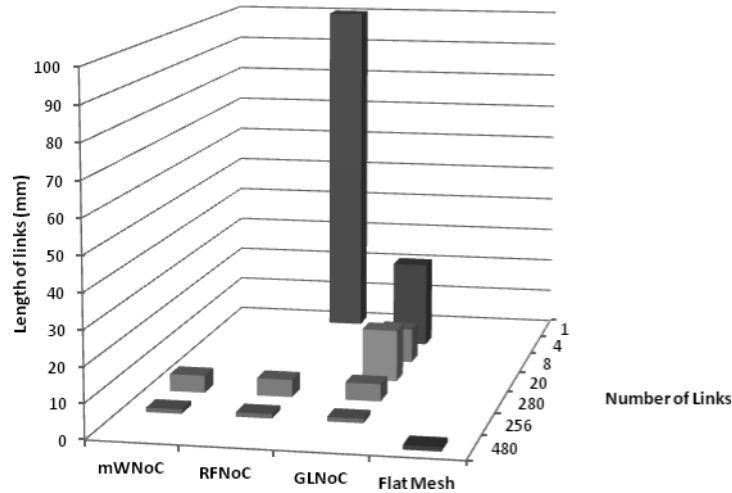


Fig. 26. Total wiring requirements for 256-core mWNoC, RFNoC, and GLNoC.

also clearly evident from the plots of Figure 24. By decreasing the number of core-to-hub direct connections in each subnet the hub area overhead can be reduced. But that will result in performance degradation. In Figure 25, we show the area overhead-performance degradation due to decreasing the number of connections of each hub. It is clear that by reducing the number of core-to-hub direct connections the hub area overhead reduces but it also significantly affects the overall achievable bandwidth of the system.

All the three hierarchical NoC architectures have varying link area requirements. Figure 26 shows the wiring overhead of the three NoCs (i.e., mWNoC, RFNoC, GLNoC) built upon a 256-core Mesh-StarRing architecture in a 20 mm × 20 mm die. The wiring requirements for a flat mesh architecture are shown for comparison. In Figure 26, it is obvious that RFNoC requires an additional 100 mm wire to establish long-range shortcuts in the upper level compared to mWNoC. Similarly, GLNoC also requires several additional long wires as the long-range shortcuts. In mWNoC, long-range communication is predominantly done by wireless links and as a result there is no requirement of long wires as can be seen from Figure 26. It may be noted that in the hierarchical NoC

architectures, there are no inter-subnet direct core to core links. Hence, all the three hierarchical NoC architectures eliminate a number of wireline links along the subnet boundaries which are present in the flat mesh topology.

## 6. CONCLUSIONS

The Network-on-Chip (NoC) is an enabling methodology to integrate large numbers of embedded cores on a single die. The existing method of implementing a NoC with planar metal interconnects is deficient due to high latency and significant power consumption arising out of multihop links used in data exchanges. One of the promising ways to address this is to replace multihop wired interconnects with high-bandwidth single-hop long-range millimeter (mm)-wave wireless links. Through a detailed performance evaluation, we establish the relevant design trade-offs for various mm-wave wireless NoC (mWNoC) architectures. A detailed comparison of hierarchical NoCs based on wireless, RF-I, and G-line links shows their respective merits and limitations. It is shown that in mWNoC, by adopting a hierarchical and small-world architecture incorporating body-biased on-chip wireless links, the performance improves significantly without unduly large area overhead compared to more conventional wire line counterparts.

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