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PERFORMANCE TESTS OF THE 600-kW cw, 80-MHz, RADIO-FREQUENCY SYSTEMS FOR THE FMIT ACCELERATOR*

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<u>Summary</u>

The high-power rf system for the Fusion Materials Irradiation Test (FMIT) accelerator consists of 14 sets of equipment,** each of which can deliver up to 600 kW (cw) at 80 MHz into a load having a VSWR of 1.4 or less (any phase). The equipment was designed and constructed to FMIT specifications by Continental Electronics Mfg. Co. (CEMC) of Dallas, Texas.

four sets have been shipped to Los Alamos for use with the accelerator [two with the radio-frequency guilrupole (RFO) and two with the drift-tube linac (DTL)]. The first set was fully tested at CFMC; results are summarized in Table I. Further tests conducted at Los Alamos, both into a resistive (electro-lytic) load and into a resonant cavity ($0 \sim 21000$), have confirmed that this system weets, and in most cases far exceeds, the specified performance limits.

Cases far exceeds, the specified performance limits. The first of the 13 production sets (No. 5) also was tested at CLMC before shipping any of the rf equipment to the Hantord Engineering and Development laboratory at Pichland, Washington. Because of the differences in behavior observed when No. 1 was operated at Los Alamos with a different tube installed in the final power amplifier (FPA) cavity, CLMC agreed to test No. 5 with two tubes having widely differing characteristics (notably primary screen emission). As expected, behavior differed markedly, and some design modification was necessary to meet all specifications with either tube. Results of final performance tests on No. 5 are summarized in Table Labo.

As noted in the table, detailed test results are presented in the FEM. Acceptance test Reports (ATRS) dated April ', 1911' and January V, 1923. Discussion of the most significant aspects of CEMC's tests and of those performed at the Alamos follows a brief description of the equipment.

Equipment Description

Functionally, each set of equipment is simply a three-stage amplifier. The first stage uses a triode (3CW5000A7), the second (Driver) and third FPA, tetrodes (4CW50000E and 8973/X2170). All three stages operate in the grounded-grid configuration. Both the input and output cavities of each stage are turable during operation. Provision is made for adjusting both resonant frequency (tuning) and impedance (load-ing) in all cavities except the input of the iPA, making a total of 11 motor-driven mechanisms.

The first two stages are well within the power and frequency range of conventional cavity-amplifier design with which CFMC has had extensive experience. Even so, during the test program's early stages, rf arcing developed in the Driver and FPA, destroying two tubes in each stage. It is now believed that the arcing in the Driver resulted from problems were fully understood, air circulation in the Driver was improved in an attempt to reduce this arcing tendency. More extensive and difficult changes were made to the FPA,

The FPA design is not novel, although it incorporates several features that are proprietary to CEMC. This application involves operation at a higher frequeacy than previous designs for this power level, and therein lie the problems. CEMC believes the rf arring mentioned above was due to 1-band parasities originating in the tube under certain load conditions, when the instantaneous anode voltage is relatively low. Because the arring primarily was in the region between the grids, CEMC felt that ferrite loading in that region would suppress the parasities, but direct byparating of the screen and grid to ground did not allow sufficient volume to add the ferrite. Ferrite loading in other areas was ineffective. Furthermore, it added

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*Work supported by the P. Department of Energy.

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**Loree additional sets have been manufactures; these

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to the dissipation without the cavities, compounding the cooling problems that already had appeared.

Also, because of space limitations, the corona (contact) rings supplied with the tube could not be used. This left the vacuum seals exposed to highvoltage fields and resulted in poor contact between the anode and the output cavity's center conductor. This condition caused a third FPA tube failure.

Modifications

The modified design is shown in Fig. 1. A $\lambda/2$

cavity, filled with dissipative material (Eccosorh^R*), was added in the grid/screen region to produce a low impedance between the screen and the control grid in the active region. Parasitics were suppressed by add-ing ferrite "necklaces" around the grid contact ring. Air circulation was improved by adding a large blower at the top of the output cavity and allowing some of

this air to escape between the Eccosorb^R blocks in the screen region. Also, holes were added in the input cavity to allow air to impinge on the metal portion of the tube envelope at screen potential, which still reaches temperatures somewhat above the maximum recommended in the tube data sheet $(200^{\circ}C)$.^T To protect the tube from rf arcing, should it occur in spite of these precautions, special contact rings were added at both ends of the main ceramic. Also, optical arc detectors were added.



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lig. 1. Linal LPA cavity design.

*Registered trademark of Emerson and Cuming.

The type manufacturer (Elmac Div, of Varian Asso clates, San Carlos, California) was contacted, and formal acceptance of the higher operating temperature was obtained under full warranty. The tube design is being modified for better heat transfer in the screen region, but modified tubes are not yet available.

2

Some of these changes (the ferrite "neck]aces" and improved air circulation in the screen cavity) were not incorporated in the prototype unit. It met all performance specifications when tested at CEMC, as shown in Table I. However, when these tests were repeated at Los Alamos with a different tube, the problems experienced earlier reappeared. Another tube was installed, but before tests with the electrolytic load could be completed, the load and some of the 14-in. transmission-line components were damaged. The FPA appeared to be operating satisfactorily; therefore, we decided to begin tests with the resonant load rather than wait for repair of the test stand.

Meanwhile, tests on No. 5 began at CEMC. tially, it appeared that no further modifications would be necessary. However, because of the difficulty experienced with the prototype, Los Alamos pro-posed, and CEMC agreed, that a second tube be installed in the FPA. This tube had significantly higher primary screen emission, when tested by Eimac before shipment. In other respects, its behavior was similar to the others. When operation was attempted, parasitic oscillations appeared from 800 to 1000 MHz with the high VSWR load at some phase settings.

In the course of investigating this problem, the Eccosorb^R material in the screen cavity overheated. CEMC decided to rearrange this material to improve air circulation by channeling inward the air entering from the output cavity before allowing it to exit the screen cavity. Ultimately, adding the ferrite neckinces suppressed the parasitics, which were probably responsible for the overheating; thus, reconfiguring the material may have been unnecessary. However, all production units are being modified in this manner, and the four units at Los Alamos will be modified at assembly or, in the case of the prototype, if a problem develops or the tube must be changed.

Tuning

The specification requires that the ampliflers pass all tests without retuning the cavities. Because it was not possible to change load conditions over the range required without interrupting operation, it was most expedient to conduct all tests at one VSWR before changing to another. Initially, the amplifiers were tuned with a matched load, following the usual proce-dure of maximizing output power and minimizing the reflected (RO-MHz) power at each stage's input. Although this procedure worked guile well, we found that some retuning was necessary for several reasons:

The simple procedure described above does not necessarily result in optimum performance with a mismatched load.

(2) Some of the cavities required at least half an hour to reach thermal equilibrium. Therefore, once the optimum settings were established, only tests conducted after the first how, of operation under each load condition were considered valid.

(3) When the EPA tube was changed, retuning was necessary to suppress parasitic oscillations unler certain load conditions. With the ferrites in place, the amplifier is stable with either tube under all specified load conditions unless the FPA is grossly mistunea.

Changes in de blas voltages can affect (4) behavior to the degree that retuning is required to restore optimum performance. Only the IPA screen voltage is regulated; thus, line voltage variations produce many different effects.

Despite these difficulties, only a few tests had to be repeated, and then it was found that performance was affected very little by the retuning that had been done.

Performance Tests with Resistive Load

Performance tests were conducted using procedures adopted during development (see ATRs), using an electrolytic load or designed and built by CEMC) to establish the and a motor-driven 14-in. coaxial phase-shifter (d) used and built by Dielectric Communications) As an in Table I, performance was specified at full wer for a VSWR of 1.4 under two extremes of phase a signated V_{MAX} (maximum rf anode voltage) and V_{MIN} (maximum rf anode current). Performance

ance also was specifie at 200 kW with a VSWR or 3 and at 250 kW (pulsed) intr an infinite VSWR of any phase. Additional tests were made at unity VSWR to explore further the amplifiers' frequency response, but no requirements were imposed beyond the basic 3-dB bandwidth specification. Finally, a 200-h heat run was conducted on No. 1 to establish reliability and longterm stability. At the end of the run, the amplifiers were examined for signs of damage and overheating.

Results of the tests at CEMC are summarized in Table 1; details are available in the ATRs. A few additional comments are given below.

The amplifier gain was at least 40% (1.5 dB) greater than specified for all load conditions tested. Linearity was within the $\pm 10\%$ limit from 30 to 90% of full-power output. There was an ~ 3 -dB difference in gain between V_{MAX} and V_{MIN} on No. 5, although the variation with power level at fixed phase was about the same in all cases. The variation with poace is plotted for No. 5 if the 50% power level (Fig. 2). This variation is responsible for some of the difficulty in controlling amplitude and phase with a resonant load under transient conditions.

Amplitude and phase drift over a 1-min period were well within limits. During the 200-h heat run, amplitude remained constant for several hours without adjusting either the amplifiers or the load.

The beat run was performed at a load VSWR of 1.4, 100 b at V_{MAV} and 100 b at V_{MIN} . During the first few hours the output power began to drop, and the HVPS had to be channed to a higher voltage tap to restore it to its initial level. The remainder of the test went smoothly. No equipment reached excessive temperatures; the hottest measured on the HVP's off tak's surface was 110°, and that represented an s20°C rise over the outside ambient. However, when the amplifiers were disassembled for inspection, some damage to finger stock was noted, and temperature-sensitive paint in the screen region of the LPA tube



Fig. 2. Gain versus relative phase.

envelope indicated a temperature between 200 and 250°C had been reached. The equipment was repaired and modified after inspection, then operated again long enough to reach thermal equilibrium. Some tests were repeated to ensure performance was unaffected by the modifications or by the change to higher anode voltage during the heat run. The equipment then was disassembled and re-inspected before shipment to Los Alamos.

At Los Alamos, the equipment (Set No. 1) was installed in a duplicate test stand, and many of the tests were repeated. However, before this program could be completed, the failures in the load and in the 14-in. coaxial transmission line forced us to abandon these tests and to move the equipment into position for tests with the resonant load.

Resunant Load Testing

The high-power rf system has been successfully operated, open loop, into a resonant cavity at 600-kW peak, 24-kW average power.

This resonant cavity consists, in part, of the B-ft-diam FMIT DTL tank. Because the actual drift tubes are not yet available, a single, stainless steel, dummy drift tube (DDT) has been installed in the tank to make it resonant at 80 MHz in a TFM mode. Stainless steel was chosen as the DDT material to lower the resonator's 0, thereby reducing the voltage gradients across the drift-tube to end-wall gaps. This was necessary to permit running two rf systems, each at 600-kW peak power, without causing sparking in the cavity. The cavity 0 with the DDT is 21 000. Because the DDI cooling can dissipate only 25 kW of average power, we are limited to about a 2% duty factor when testing two amplifier systems at full power.

Conditioning the cavity to 24 kW of average power took ~10 h, operating one amplifier at a 4% duty factor. The amplifier behaved in a very stable manner at all power levels in open-loop operation.

Recently we have closed the cavity-amplitude and phase-control loops around a single of system. The main problem encountered involved turning on the of system with the cavity-amplifier control in the closed-loop configuration and the cavity empty. During the cavity fill time, the load impedance presonted to the tube changes from an infinite VSWR to unity. This causes a slo-dB change in amplifier gain. This fact, coupled with the overshoot in the control system, causes output power to rise to sROO kW at the pulse's leading edge. To prevent this, we decided to turn on in an open-loop condition, to a preset power level, and to close the cavity-amplitude loop approximately one-cavity fill-time constant (s120 µs) later.

With the amplifier operating at the 400-kW level, a step disturbance simulating beam leading was introduced into the cavity amplitude controller. During the transient at the leading edge of the step disturbance, the cavity field amplitude was held constant to within US. The transfert damped out in 540 ps, resulting in a steady-state error of well under US.

A phase-control loop was employed to maintain zero phase shift between the rf chain input and out put. A 445" step phase error was introduced into the control loop. The transfent error resulted in a phase shift that reached a steady state value in 40 ps of well under 1".

We are currently in the process of adding a second of system to the cavity to test the concept of multiple of orive sources powering a single structure.

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