

Periodic Review Inventory Policy for Non-Instantaneous Deteriorating Items with Time Dependent Deterioration Rate

Anwasha Samanta

Department of Statistics University of Calcutta, Kolkata, India
Anisam87@gmail.com

Manisha Pal

Department of Statistics University of Calcutta, Kolkata, India
manishapal2@gmail.com

Abstract

The paper studies a periodic review inventory model with no shortages and different demand rates during pre- and post- deterioration periods. Deterioration of units start after a fixed time interval, and the deterioration rate is time dependent. The model determines the optimal reorder interval and the optimal order quantity so as to minimize the total cost per unit length of an inventory cycle. An extension of the model to include price discount has been further considered. Numerical examples are presented to illustrate the model and a sensitivity analysis is also reported.

Keywords: Periodic review inventory model; Non-instantaneous deterioration, Time dependent deterioration.

1. Introduction

Traditional inventory models assume that depletion from stock is caused only by the arrival of demands. However, in reality, many physical products like volatile liquids, agricultural items, films, blood, drugs, fashion goods, electrical components etc. undergo deterioration through evaporation, spoilage, dryness etc. during their normal storage period. As a result, while developing inventory policies for such products, the loss due to deterioration cannot be ignored. The earliest work along this line is due to Ghare and Schrader (1963), who developed the EOQ model for an exponentially decaying inventory. Thereafter, many authors discussed different inventory models for deteriorating items, like Covert and Philip (1973) extended the model for variable rate of deterioration assuming two parameter Weibull distribution, Philip (1974) generalized EOQ model for items with Weibull distribution.

Generally, it is assumed that the deterioration occurs as soon as the items arrive in inventory. However, in real life, most items retain their quality or original condition for a certain span of time before deteriorating. This phenomenon has been termed as ‘non-instantaneous deterioration’ by Wu et al. (2006), and can be commonly observed in products like fruits, vegetables and fashion items. For such items the assumption that the deterioration starts from the instant of arrival in stock may cause retailers to make inappropriate replenishment policies. Lin and Shi (1999) classified inventory models into two categories, viz. decay models and finite lifetime models. Castro and Alfa (2004) proposed a lifetime replacement policy in discrete time for a single unit system. Ouyang et al. (2006) developed an inventory model for non-instantaneous deteriorating items with permissible delay in payments. Chang et al. (2010) developed optimal replenishment

policies for non-instantaneous deteriorating items with stock-dependent demand. In most of these studies deterioration rate has been assumed to be independent of time.

In this paper we consider an inventory model for non-instantaneous deteriorating items when the deterioration rate is a general function of time. Demand is assumed to be uniform, but the demand rate decreases when the items start to deteriorate. The paper is organized as follows. Section 2 defines the assumptions made and the notations used. Section 3 analyses the model. In Section 4 we introduce price discount in the model. Some numerical examples are given and a study of the sensitivity of the model to change in model parameters is carried out in Section 5. Finally, in Section 6, we make some concluding remarks on our study.

2. Assumptions and Notations

We make the following assumptions in our model:

- 1) There is no lead time.
- 2) Shortages are not allowed.
- 3) Deterioration rate is a general function of time.
- 4) The item considered in inventory is of the Non-instantaneous deteriorating type, i.e. it maintains its freshness for a fixed time interval before deteriorating.
- 5) Demand occurs at a uniform rate. The demand rate during pre-deterioration period is greater than that in the post-deterioration period.

The following notations have been used in the study:

D_1 : Pre-deterioration demand rate.

D_2 : Post-deterioration demand rate, $D_1 \geq D_2$.

$\theta(t)$: Deterioration rate..

T : Length of a reorder interval.

Q : Optimal order quantity.

μ : Length of pre- deterioration period, $0 < \mu \leq T$.

C_S : Ordering cost per order, independent of the order quantity.

C_1 : Purchase cost per unit.

C_2 : Deterioration cost per unit deteriorating.

p : a fraction such that pC_1 denotes the carrying cost per item per unit time

$I(t)$: Inventory level at time t .

3. The Model and its Analysis

The inventory policy is to place an order for Q units at the beginning of each reorder interval of length T .

Consider the reorder interval $(0, T)$. Since demand rate is D_1 in the interval $(0, \mu)$ and D_2 in the interval (μ, T) , and depletion from stock occurs due to both demand and deterioration in the latter interval, the inventory level $I(t)$ satisfies the following differential equations:

$$\begin{aligned} \frac{dI(t)}{dt} &= -D_1, & 0 \leq t \leq \mu \\ \frac{dI(t)}{dt} + \theta(t)I(t) &= -D_2 & \mu \leq t \leq T, D_1 \geq D_2. \end{aligned}$$

The boundary conditions are $I(0) = Q$ and $I(T) = 0$, which give

$$I(t) = Q - D_1 t, \quad 0 \leq t \leq \mu \quad (1)$$

$$= D_2 \int_t^T \exp\left(\int_t^y \theta(x) dx\right) dy, \quad \mu \leq t \leq T \quad (2)$$

From (1) and (2), we have

$$Q = D_1 \mu + D_2 \int_\mu^T \exp\left(\int_\mu^y \theta(x) dx\right) dy \quad (3)$$

Equation (3) gives a relationship between the order quantity Q and T . Hence, we have only one independent decision variable. Let us take it to be T .

Cost Function:

The different components of the cost function over the interval $(0, T)$ are as follows:

$$1) \quad \text{Ordering cost} = C_s \quad (4)$$

$$2) \quad \text{Purchase cost} = P = C_1 Q = C_1 D_1 \mu + C_1 D_2 \int_\mu^T \exp\left(\int_\mu^y \theta(x) dx\right) dy \quad (5)$$

$$\begin{aligned} 3) \quad \text{Deterioration cost} &= D^* = C_2 \int_\mu^T \theta(t) I(t) dt \\ &= C_2 D_2 \int_\mu^T \int_t^T \theta(t) \exp\left(\int_t^y \theta(x) dx\right) dy dt \end{aligned} \quad (6)$$

$$\begin{aligned} 4) \quad \text{Holding cost} &= H = C_1 p \int_0^T I(t) dt \\ &= C_1 p \left[\frac{D_1 \mu^2}{2} + D_2 \int_0^\mu \int_\mu^T \exp\left(\int_\mu^y \theta(x) dx\right) dy dt + \right. \\ &\quad \left. D_2 \int_\mu^T \int_t^T \exp\left(\int_t^y \theta(x) dx\right) dy dt \right] \end{aligned} \quad (7)$$

Since the length of the cycle is a decision variable, we consider the cost per unit length of a cycle. Let it be denoted by $C(T)$.

Then,

$$\begin{aligned} C(T) &= \frac{1}{T} [C_s + P + D^* + H] \\ &= \frac{1}{T} [C_s + C_1 D_1 \mu + C_1 D_2 \int_\mu^T \exp\left(\int_\mu^y \theta(x) dx\right) dy + \\ &\quad C_2 D_2 \int_\mu^T \int_t^T \theta(t) \exp\left(\int_t^y \theta(x) dx\right) dy dt + C_1 p \frac{D_1 \mu^2}{2}] \end{aligned}$$

$$\begin{aligned}
& +C_1 p D_2 \int_0^\mu \int_\mu^T \exp\left(\int_\mu^y \theta(x) dx\right) dy dt \\
& +C_1 p D_2 \int_\mu^T \int_t^T \exp\left(\int_t^y \theta(x) dx\right) dy dt] \\
& = \frac{N(T)}{T}, \text{ say,}
\end{aligned} \tag{8}$$

Solution Procedure:

The optimal value of T that minimises $C(T)$ is a solution of the equation

$$\frac{\partial C(T)}{\partial T} = 0, \tag{9}$$

which gives

$$\begin{aligned}
C(T) = & C_1 D_2 \exp\left(\int_\mu^T \theta(t) dt\right) + C_2 D_2 \int_\mu^T \theta(t) \exp\left(\int_t^T \theta(x) dx\right) dt + \\
& C_1 p D_2 \int_0^\mu \exp\left(\int_\mu^T \theta(x) dx\right) dt + C_1 p D_2 \int_\mu^T \exp\left(\int_t^T \theta(x) dx\right) dt
\end{aligned} \tag{10}$$

Special Cases:

Case 1 : $\theta(t) = \theta$, for all $t \geq \mu$.

In this case, the order quantity Q is related to T according to the following equation:

$$Q = D_1 \mu + \frac{D_2}{\theta} (e^{\theta(T-\mu)} - 1) \tag{11}$$

The expression for $C(T)$ is obtained as:

$$C(T) = \frac{1}{T} [C_0 + H_1 e^{\theta(T-\mu)} - H_2 (T-\mu)], \tag{12}$$

where

$$C_0 = C_S + C_1 D_1 \mu + C_1 p \frac{D_1 \mu^2}{2} - \frac{D_2}{\theta} (C_1 + C_2) - C_1 p \frac{D_2}{\theta^2} (\mu\theta + 1) \tag{13}$$

$$H_1 = \frac{D_2}{\theta} (C_1 + C_2) + C_1 p \frac{D_2}{\theta^2} (\mu\theta + 1) \tag{14}$$

$$H_2 = C_2 D_2 + C_1 p \frac{D_2}{\theta}, \tag{15}$$

and (10) gives

$$e^{\theta(T-\mu)} (\theta T - 1) = \frac{C_0 + H_2 \mu}{H_1}, \quad T \geq \mu \tag{16}$$

Theorem 1: The optimal value of T is

$$\begin{aligned}
T = & \mu, \text{ if } \theta\mu - 1 \geq \frac{C_0 + H_2 \mu}{H_1} \\
& = T^*, \text{ if } \theta\mu - 1 < \frac{C_0 + H_2 \mu}{H_1},
\end{aligned}$$

where T^* is the value of T satisfying (10).

Proof: We have

$$\frac{\partial C(T)}{\partial T} = e^{\theta(T-\mu)} (\theta T - 1) - \frac{C_0 + H_2\mu}{H_1}.$$

Let, $f(T) = e^{\theta(T-\mu)} (\theta T - 1)$.

$f(T)$ is an increasing function of T , with $f(\mu) = \theta\mu - 1$. Hence, when $\theta\mu - 1 \geq \frac{C_0 + H_2\mu}{H_1}$, that is $f(\mu) \geq \frac{C_0 + H_2\mu}{H_1}$, we have $\frac{\partial C(T)}{\partial T} \geq 0$ for $T \geq \mu$. Thus, in the range $T \geq \mu$, optimum value of T is μ .

When $\theta\mu - 1 < \frac{C_0 + H_2\mu}{H_1}$, $f(\mu) < \frac{C_0 + H_2\mu}{H_1}$ and $f(\infty) > \frac{C_0 + H_2\mu}{H_1}$. Hence, the curve $y = f(T)$ cuts the line $y = \frac{C_0 + H_2\mu}{H_1}$ at a point $T = T^* \in (0, \infty)$. Therefore,

$$\frac{\partial C(T)}{\partial T} \leq 0 \text{ for } T \leq T^* \text{ and } \frac{\partial C(T)}{\partial T} \geq 0 \text{ for } T \geq T^*.$$

Case 2 : $\theta(t) = \theta(t-\mu)$ for all $t \geq \mu$.

In this case, the order quantity Q is related to T according to the following equation:

$$Q = D_1\mu + D_2 \int_0^{T-\mu} \exp\left(\frac{\theta}{2} z^2\right) dz \quad (17)$$

The expression for $C(T)$ is given by

$$C(T) = \frac{1}{T} [Cs + P + D^* + H],$$

where

$$P = C_1 D_1 \mu + C_1 D_2 \int_0^{T-\mu} \exp\left(\frac{\theta}{2} z^2\right) dz$$

$$D^* = C_2 D_2 \int_0^{T-\mu} \exp\left(\frac{\theta}{2} z^2\right) dz - C_2 D_2 (T - \mu)$$

$$H = C_1 p \left[\frac{D_1 \mu^2}{2} + D_2 \left(\mu - \sqrt{\frac{\pi}{2\theta}} \right) \int_0^{T-\mu} \exp\left(\frac{\theta}{2} z^2\right) dz + D_2 \sqrt{\frac{2\pi}{\theta}} \int_0^{T-\mu} \exp\left(\frac{\theta}{2} z^2\right) \Phi(z\sqrt{\theta}) dz \right].$$

Thus, we can write

$$C(T) = \frac{1}{T} [A_1 - A_2(T - \mu) + A_3 \int_0^{T-\mu} \exp\left(\frac{\theta}{2} z^2\right) dz + A_4 \int_0^{T-\mu} \exp\left(\frac{\theta}{2} z^2\right) \Phi(z\sqrt{\theta}) dz],$$

where $A_1 = C_1 D_1 \mu + C_1 p \frac{D_1 \mu^2}{2} + Cs$, $A_2 = C_2 D_2$, $A_3 = (C_1 + C_2) D_2 + C_1 p D_2 \left(\mu - \sqrt{\frac{\pi}{2\theta}} \right)$,

$$A_4 = C_1 p D_2 \sqrt{\frac{2\pi}{\theta}}.$$

The optimal value of T that minimises $C(T)$ must satisfy

$$\frac{\partial C(T)}{\partial T} = 0, \quad (18)$$

which gives

$$C(T) = -A_2 + A_3 \exp\left(\frac{\theta}{2}(T-\mu)^2\right) + A_4 \exp\left(\frac{\theta}{2}(T-\mu)^2\right) \Phi((T-\mu)\sqrt{\theta}).$$

Now,

$$\begin{aligned} \frac{\partial^2}{\partial T^2} C(T) &= \exp\left(\frac{\theta}{2}(T-\mu)^2\right) [\{A_3 \theta(T-\mu) + A_4 \Phi\{(T-\mu)\sqrt{\theta}\}\theta(T-\mu) + A_4\sqrt{\theta} \Phi\{(T-\mu)\sqrt{\theta}\}\}] \\ &\geq 0, \text{ for } T \geq \mu. \end{aligned}$$

Hence the cost function $C(T)$ is convex of T . This means that any solution of (18) will give the optimal value of T .

4. Model with Price Discount

It is a common experience that when the inventory manager orders a large quantity of goods he is given a discount on his purchase. Different inventory models with price discount have been studied by many authors. See, for example, Ardalan (1994), Wee and Yu (1997), Pal and Dutta (2007), Panda et al. (2009), Cardanas-Barron et al. (2010).

Let,

$$\begin{aligned} C_1 &= C_{1U}, \text{ if } Q < b \\ &= C_{1D}, \text{ if } Q \geq b, \end{aligned}$$

where $C_{1U} > C_{1D}$.

We assume that $b \geq D_1\mu$. This is because, from (3), $Q < b$ is equivalent to

$$\int_{\mu}^T \exp\left(\int_{\mu}^y \theta(x) dx\right) dy < \frac{b - D_1\mu}{D_2}. \quad (19)$$

LHS of (19) ≥ 0 for $T \geq \mu$, but RHS < 0 unless $b \geq D_1\mu$.

Let the cost function be denoted by

$$\begin{aligned} C(Q) &= C_U(Q), \text{ if } Q < b \\ &= C_D(Q), \text{ if } Q \geq b, \end{aligned}$$

Since $C(Q)$ is a linear function of C_1 , and $C_{1U} > C_{1D}$, it follows that $C_U(Q) > C_D(Q)$ for all $Q > 0$.

From (3) it is obvious that Q is a one-to-one increasing function of T . Hence, we can write $T = g(Q)$, for some increasing function $g(\cdot)$. We, therefore, have that if $T_0 = g(b)$, then $Q < b$ is equivalent to $T < T_0$.

Thus,

(i) for $\theta(t) = \theta$, independent of t , $T_0 = \mu + \frac{1}{\theta} \ln \left[1 + \frac{\theta}{D_2} (b - D_1\mu) \right]$;

(ii) for $\theta(t) = \theta(t-\mu)$, T_0 is obtained by solving the equation

$$\int_0^{T_0-\mu} \exp\left(\frac{\theta}{2}z^2\right) dz = \frac{b - D_1\mu}{D_2}. \quad (20)$$

We can, therefore, write

$$\begin{aligned} C(T) &= C_U(T), \text{ for } \mu \leq T < T_0 \\ &= C_D(T), \text{ for } T \geq T_0. \end{aligned}$$

Further, $C_U(T) > C_D(T)$ for all $T \geq \mu$.

To find the optimal value of T , and hence of Q , that minimizes $C(T)$, we compare the minimum values of $C_U(T)$ and $C_D(T)$. If $C_U(T)$ and $C_D(T)$ be strictly convex in T , for $\mu \leq T < \infty$, with minimum at T_U and T_D respectively, then we can use the following algorithm to find the optimal value of T that minimizes $C(T)$.

Algorithm 1:

Step 1: Find T_D minimising $C_D(T)$.

- (i) If $T_D \geq T_0$, T_D is the optimal value of T that minimizes $C(T)$.
- (ii) If $T_D < T_0$, go to Step 2.

Step 2: Find T_U minimising $C_U(T)$, and compute $C_U(T_U)$ and $C_D(T_0)$.

- (i) If $C_D(T_0) \geq C_U(T_U)$, $T = T_U$ minimizes $C(T)$.
- (ii) If $C_D(T_0) \leq C_U(T_U)$, $T = T_0$ minimizes $C(T)$.

The algorithm follows from the following arguments:

- (a) When $T_D \geq T_0$,

$$\begin{aligned} C(T) &= C_D(T) \geq C_D(T_D) = C(T_D), \text{ for } T \geq T_0 \\ C(T) &= C_U(T) \geq C_D(T) \geq C_D(T_D) = C(T_D), \text{ for } \mu \leq T < T_0. \end{aligned}$$

Thus, $C(T) \geq C(T_D)$, for all $T \geq \mu$.

- (b) When $T_D < T_0$, $C_D(T)$ is an increasing function of T for $T \geq T_0$. Hence,

$$\min_{T \geq T_0} C_D(T) = C_D(T_0).$$

Then,

- (i) for $C_D(T_0) \geq C_U(T_U)$,

$$\begin{aligned} C(T) &= C_D(T) \geq C_D(T_0) \geq C_U(T_U) = C(T_U), \text{ for } T \geq T_0 \\ C(T) &= C_U(T) \geq C_U(T_U) = C(T_U), \text{ for } \mu \leq T < T_0. \end{aligned}$$

Hence, $C(T) \geq C(T_U)$, for all $T \geq \mu$;

- (ii) for $C_D(T_0) \leq C_U(T_U)$,

$$\begin{aligned} C(T) &= C_D(T) \geq C_D(T_0) = C(T_0), \text{ for } T \geq T_0 \\ C(T) &= C_U(T) \geq C_D(T_0) = C(T_0), \text{ for } \mu \leq T < T_0. \end{aligned}$$

Hence, $C(T) \geq C(T_0)$, for all $T \geq \mu$.

4. Numerical Examples and Sensitivity Analysis

Example 1: Consider an item that can maintain its freshness for 6 months and then starts deteriorating with a deteriorating rate 0.2 per unit time. The demand rate for the item is 300 units per unit time before deterioration but decreases to 200 units per unit time when the item starts to deteriorate. The costs are: $C_3 = \text{Rs. } 100$, $C_1 = \text{Rs. } 12$ per unit, $p = 1/3$, $C_2 = \text{Rs. } 5$ per unit deteriorating. We have to determine the optimal order quantity and the optimal reorder interval.

Here, $\theta\mu - 1 = 0.2$ and $\frac{C_0 + H_2\mu}{H_1} = 0.908 > \theta\mu - 1$.

Hence optimal T is obtained by solving the equation (16), which gives $T = 8.0275$ months. The optimal order quantity Q is, therefore, 2050.026 units and the minimum cost per unit length of an inventory cycle is Rs. 6649.996.

Example 2: Let us consider an item that can maintain its freshness for 2 months and then starts to deteriorate with a deteriorating rate 0.02 ($t - \mu$) per unit time. The demand for the item is 80 units per unit time in its fresh state, but reduces to 50 units per unit time when deterioration starts. The ordering cost is Rs. 100 per unit, purchase cost is Re. 1 per unit, deterioration cost is Rs. 0.75 per unit and the carrying cost is a proportion 0.6 of the cost per unit.

Solving equation (18) we get optimal $T = 3.500713$ months, optimal order quantity = 235.5977 units and minimum cost per unit length of a cycle is Rs. 159.0462.

Example 3: Suppose in example 2 the purchase cost is Rs. 3 per unit if $Q < 200$ units, and is Rs. 2 per unit for $Q \geq 200$ units.

Here $T_0 = 2.8$ months. Since the cost function is convex in T , algorithm 1 can be applied.

We get $T_D = 3.069$ months, which is greater than T_0 . Hence the inventory manager should accept the discount offer. The optimum order quantity is then $Q = 213.66$ units, and the total cost per month is Rs. 282.9942.

We next examine the sensitivity of the model to a change in the model parameters. For the study, we consider example 2.

Tables 1-5 show the change in the optimal values of T and Q and the percent change in the minimal cost when the value of a parameter changes.

Table 1: Change in the optimal values of T and Q , and the percent change in $C(T)$ with change in C_1

C_1	T	Q	$C(T)$	% change in $C(T)$
1	3.500477	235.5977	159.0462	0
1.5	3.232944	221.9581	224.1392	40.93
2	3.06907	213.6559	287.5992	80.83
2.5	2.970891	208.6961	351.1999	120.82
3	2.902255	205.2434	414.6293	160.70

Table 2: Change in the optimal values of T and Q , and the percent change in $C(T)$ with change in p

p	T	Q	$C(T)$	% change in $C(T)$
0.5	3.730301	247.3803	148.3024	-6.76
0.6	3.500477	235.5977	159.0462	0
0.7	3.31651	226.2044	169.3587	6.48
0.75	3.178974	219.2204	171.8892	8.08
0.8	3.165855	218.5555	179.3300	12.75

Table 3: Change in the optimal values of T and Q , and the percent change in $C(T)$ with change in C_2

C_2	T	Q	$C(T)$	% change in $C(T)$
0.5	3.51975	236.5718	159.314	0.17
0.75	3.500477	235.5977	159.0462	0
1	3.493685	235.2389	159.0845	0.02
2	3.467634	233.9076	159.2308	0.12
3	3.443883	232.7320	159.3928	0.21

Table 4: Change in the optimal values of T and Q , and the percent change in $C(T)$ with change in θ

θ	T	Q	$C(T)$	% change in $C(T)$
0.01	3.553233	237.9813	158.7628	0.18
0.02	3.500477	235.5977	159.0462	0
0.03	3.46152	233.8640	159.3166	0.17
0.04	3.413477	231.6313	159.5637	0.32
0.05	3.376839	229.9407	159.7927	0.47

Table 5: Change in the optimal values of T and Q , and the percent change in $C(T)$ with change in μ

μ	T	Q	$C(T)$	% change in $C(T)$
1	2.896916	255.9844	142.5872	-10.35
2	3.500477	235.5977	159.0462	0
3	4.16786	218.6569	177.7867	11.78
4	4.713061	195.7130	198.7911	24.99
5	5.598705	189.9720	218.8527	37.60

The above tables indicate that the model is highly sensitive to change in C_1 , the purchase cost per unit, moderately sensitive to changes in p and μ , but is quite insensitive to changes in the deterioration cost C_2 and θ .

6. Conclusion

The paper studies a periodic review inventory model for a non-instantaneous deteriorating item that has a general deteriorating time distribution. Withdrawal from stock occurs at a uniform rate, but the rate decreases when items in stock start to deteriorate. The situation where discount is offered to the inventory manager on a purchase of a large quantity of the item is also discussed.

The model has scope for extension by considering demand to be dependent on time and stock, as well as on the deterioration rate.

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