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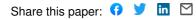
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### PERSISTENTLY &-OPTIMAL STRATEGIES

#### by

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## Abstract

There are strategies available for nonnegative gambling problems which are not only  $\epsilon$ -optimal but persist in being conditionally  $\epsilon$ -optimal along every history.

<u>Key words</u>: gambling, optimal strategies, probability, finite additivity, dynamic programming, stochastic control, decision theory.

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#### 1. Introduction.

Let  $(F, \Gamma, u)$  be a gambling problem where, as in [3], F is the set of fortunes or states,  $\Gamma$  is the gambling house, and u the utility function. The gambling problem is <u>nonnegative</u> if u is a nonnegative, possibly unbounded function.

Let  $0 \le \epsilon \le 1$ , f  $\epsilon$  F, and V(f) be the most a gambler with fortune f can achieve ([3], section 3.3). A strategy  $\sigma$  available at f in  $\Gamma$  is (<u>multiplicatively</u>)  $\underline{\epsilon}$ -optimal at f if  $u(\sigma) \ge (1-\epsilon)V(f)$ . Let  $p = (f_1, \dots, f_n)$ . Then  $\sigma$  is <u>conditionally</u> (<u>multiplicatively</u>)  $\underline{\epsilon}$ -optimal given p if the conditional strategy  $\sigma[p]$  is multiplicatively  $\epsilon$ -optimal at  $f_n$ . If  $\sigma$  is (multiplicatively)  $\epsilon$ -optimal at f and is conditionally (multiplicatively)  $\epsilon$ -optimal given p for every partial history p, then  $\sigma$  is said to be <u>persistently</u> (<u>multiplicatively</u>)  $\underline{\epsilon}$ -optimal at f. If u is bounded or, more generally, if u is nonnegative and V is everywhere finite, then persistently  $\epsilon$ -optimal strategies are always available (Theorem 1 below). If, in addition, the gambling problem is sufficiently measurable, there exist measurable strategies which are persistently  $\epsilon$ -optimal (Theorem 2).

The notion of persistently (or thoroughly) optimal strategies was introduced in [3, section 3.5]. It is related to the concept of stationarity. For suppose  $\bar{\sigma}$  is a stationary family of  $\varepsilon$ -optimal strategies. Then, for every f,  $\bar{\sigma}(f)$  is persistently  $\varepsilon$ -optimal since  $\bar{\sigma}(f)[f_1, \dots, f_n] = \bar{\sigma}(f_n)$ .

Gambles in [3] were taken to be finitely additive probability measures defined on all subsets of F. Here a gamble  $\gamma$  can be regarded as a nonnegative functional with domain the collection h of nonnegative,

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real-valued functions defined on F and satisfying

$$\gamma(u + v) = \gamma u + \gamma v$$
,  
 $\gamma(a u) = a \gamma u$ 

for u, v  $\in$  h and a  $\ge 0$ . A gamble in the present sense is, when restricted to the collection of indicator functions, a gamble in the sense of [3]. Thus the gambling problems considered here are slightly more general than those of [3]. However, much of the theory remains unchanged and appropriate definitions and results from [3] will be used without further comment.

#### 2. Preliminaries.

Let  $H = F \times F \times ...$  be the set of histories. A mapping t from H to  $\{1,2,...\} \cup \{\infty\}$  is called a <u>stopping time</u> if, whenever h and h' are in H,  $t(h) = n < \infty$ , and h' agrees with h in the first n coordinates, then t(h') = n. A stopping time which assumes only finite values is a <u>stop rule</u>. Let n be a positive integer and  $h = (f_1,...,f_n,...)$ be a history. Recall that  $p_n(h) = (f_1,...,f_n)$ . (See [3] for a detailed explanation of the notation and terminology.) If r is a stopping time, the conditional stopping time given  $p_n(h)$  is defined by  $t[p_n(h)](h') = t(p_n(h)h') - n$  for h'  $\varepsilon$  H. Notice that  $t[p_n(h)]$  is a stopping time or identically zero according as  $r(p_n(h)h')$  is greater than or equal to n.

Let  $(\sigma, t)$  be a policy and s be a stop rule. Make the convention that  $u(\sigma[p_s(h)], t[p_s(h)])$  is  $u(f_t(h))$  when  $s(h) \ge t(h)$ . Then the formula

(1) 
$$u(\sigma, t) = \int u(\sigma[p_{\sigma}], t[p_{\sigma}]) d\sigma$$

is a special case of formula 3.7.1, [3]. The similar formula

(2) 
$$u(\sigma) = \int u(\sigma[p_s]) d\sigma$$

follows from Theorem 3.2.1, [3] and an argument by induction on the structure of  $p_s$ . The first lemma below generalizes (2) and gives a formula which, in a sense, separates the utility of a strategy into that earned before a given time r and that earned afterwards.

For simplicity, assume henceforth that u is nonnegative and all strategies have finite utility.

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Lemma 1. Let  $\sigma$  be a strategy and r be a stopping time. Then

(3) 
$$u(\sigma) = \lim_{t \to \infty} \sup_{\sigma, t} u_r(\sigma, t)$$

where

$$u_{r}(\sigma,t) = \int u(f_{t})d\sigma + \int u(\sigma[p_{r}])d\sigma$$
$$[t \le r] \qquad [t \ge r]$$

and the lim sup is taken over the directed set of stop rules. <u>Proof:</u> By definition ([3], section 3.2)

(4) 
$$u(\sigma) = \limsup_{t \to \infty} u(\sigma, t)$$
.

For t a stop rule, apply (1) with  $s = t \wedge r$  to get

(5) 
$$u(\sigma,t) = \int u(\sigma[p_{tAr}], t[p_{tAr}]) d\sigma$$
  
$$= \int u(f_t) d\sigma + \int u(\sigma[p_r], t[p_r]) d\sigma \cdot \int [t \le r] d\sigma \cdot \int [t \le r] d\sigma \cdot \int [t \ge r] d\sigma \cdot \int [t \ge r] d\sigma$$

Let  $\varepsilon > 0$ .

<u>Claim</u>: There is a stop rule  $t_0$  such that, for every stop rule t,

$$\int_{[t>r,t_0\leq r]} u(\sigma[p_r], t[p_r])d\sigma < \varepsilon .$$

Suppose the claim is false. Then, for every stop rule t, there is a stop rule s such that

$$\int_{\substack{u(\sigma[p_r], s[p_r])d\sigma \geq \varepsilon \\ [s>r, t\leq r]}} u(\sigma[p_r], s[p_r])d\sigma \geq \varepsilon .$$

Define  $t_1 = t$  if t > r or  $s \le t$ ,

= s if  $t \leq r$  and s > t.

Then  $t_1$  is a stop rule,  $t_1 \ge t$  and

$$\int u(\sigma[p_r], t_1[p_r]) d\sigma = \int u(\sigma[p_r], t[p_r]) d\sigma + \int u(\sigma[p_r], s[p_r]) d\sigma$$

$$[t>r] \qquad [t>r] \qquad [t\leq r, s>r]^r$$

$$\geq \int u(\sigma[p_r], t[p_r]) d\sigma + \varepsilon .$$

$$[t>r]$$

Similarly, there exist stop rules  $t_2, t_3, \dots$  such that  $t_n \le t_{n+1}$  and

$$\int u(\sigma[p_r], t_{n+1}[p_r]) d\sigma \geq \int u(\sigma[p_r], t_n[p_r]) d\sigma + \epsilon .$$

$$[t_{n+1} > r] \qquad [t_n > r]$$

Thus, for  $n = 1, 2, \ldots, t_n \ge t$  and

$$u(\sigma,t_n) \ge \int u(\sigma[p_r], t_n[p_r]) d\sigma \ge n \epsilon$$
.  
 $[t_n > r]$ 

Hence,  $u(\sigma) = \infty$ , a contradiction which establishes the claim.

Next, define a stop rule t' thus: If  $t_0(h) \le r(h)$ , set t'(h) =  $t_0(h)$ . If  $t_0(h) \ge r(h)$ , choose a stop rule  $t_h$  such that  $t_h \ge t_0[p_r(h)]$  and, for every stop rule  $s \ge t_h$ ,

(6) 
$$u(\sigma[p_r(h)],s) \le u(\sigma[p_r(h)] + \epsilon$$
.

Then set  $t'(h) = r(h) + t_h(f_{r(h)+1}, f_{r(h)+2}, ...)$  so that  $t'[p_r(h)] = t_h$ . Notice that  $t' \ge t_0$ .

Suppose t is a stop rule and  $t \ge t^{1}$ . Then

$$u(\sigma,t) = \int u(f_t) d\sigma + \int u(\sigma[p_r], t[p_r]) d\sigma + \int u(\sigma[p_r], t[p_r]) d\sigma$$

$$(by (5))$$

$$\leq \int u(f_t) d\sigma + \int u(\sigma[p_r]) d\sigma + 2 \varepsilon$$

$$(by (6) \text{ and the Claim})$$

$$\leq \int u(f_t) d\sigma + \int u(\sigma[p_r]) d\sigma + 2 \varepsilon$$
$$[t \leq r] \qquad [t > r]$$
$$= u_r(\sigma, t) + 2 \varepsilon$$

Hence,  $u(\sigma) \leq \limsup_{t \to \infty} u_r(\sigma, t)$ .

To prove the opposite inequality, again let  $\varepsilon > 0$  and s be a stop rule. Define a stop rule t as follows: If  $s(h) \le r(h)$ , let t(h) = s(h). If s(h) > r(h), choose  $t_h$  to be a stop rule at least as large as  $s[p_r(h)]$  and such that

(7) 
$$u(\sigma[p_r(h)], t_h) \ge u(\sigma[p_r(h)] - \epsilon$$

Set  $t(h) = r(h) + t_h(f_{r(h)+1}, f_{r(h)+2}, \dots)$  so that  $t[p_r(h)] = t_h$ . Then  $t \ge s$  and

$$u(\sigma,t) \ge u_r(\sigma,t) - \epsilon$$
 (by (5) and (7))  
=  $u_r(\sigma,s) - \epsilon$ .

Hence,  $u(\sigma) \ge \limsup_{t \to \infty} u_r(\sigma, t) . \square$ 

Let r be a stopping time. The strategies  $\sigma$  and  $\sigma'$  <u>agree up</u> <u>to time r-</u> if  $\sigma_0 = \sigma'_0$  and, for every h  $\varepsilon$  H and 0 < n < r(h),  $\sigma_n(p_n(h)) = \sigma'_n(p_n(h))$ . Here is a formulation of the nearly obvious fact that if  $\sigma$  and  $\sigma'$  agree up to some time and if, given the past up to that time,  $\sigma'$  does conditionally nearly as well as  $\sigma$ , then unconditionally  $\sigma'$  does nearly as well as  $\sigma$ .

<u>Lemma 2.</u> If r is a stopping time,  $\sigma$  and  $\sigma'$  are strategies which agree up to time r- and  $\epsilon > 0$ , then each of the following conditions

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implies its successor:

- (i)  $\sigma'$  is available in  $\Gamma$  and  $u(\sigma[p_r(h)]) \ge (1-\varepsilon)V(f_r(h))$  whenever r(h) <  $\infty$ ;
- (ii)  $u(\sigma[p_r(h)] \ge (1-\varepsilon)u(\sigma'[p_r(h)])$  whenever  $r(h) \le \infty$ ; (iii)  $u(\sigma) \ge (1-\varepsilon)u(\sigma')$ .
- <u>Proof:</u> To see that (i) implies (ii), observe that  $u(\sigma'[p_r(h)]) \leq V(f_r(h))$  when  $r(h) < \infty$ . Use Lemma 1 for an easy proof that (ii) implies (iii).  $\Box$

The next lemma states that a good strategy earns relatively little income after it becomes conditionally bad. Moreover, any strategy which agrees with a good strategy until it becomes conditionally bad is itself a fairly good strategy. A related fact (Lemma 3.1 in [6]) is that a sufficiently good strategy is unlikely to ever become conditionally bad. First some notation: If  $\sigma$  is a strategy and  $0 < \alpha < 1$ , let  $r(\sigma, \alpha)$ be the first time (if any) when  $\sigma$  is not conditionally  $\alpha$ -optimal. That is,

(8) 
$$r(\sigma,\alpha)(h) = \inf\{n:u(\sigma[p_n(h)]) < (1-\alpha)V(f_n)\}$$
.

The infimum of the empty set is taken to be infinite.

Lemma 3. Let  $\alpha$  and  $\beta$  be numbers in (0,1). Suppose  $\sigma$  is available at f in  $\Gamma$  and  $u(\sigma) \ge (1-\beta)V(f)$ . If  $r = r(\sigma, \alpha)$ , then, for every stop rule t,

(9) 
$$\int_{[t>r]} V(f_r) d\sigma \leq \beta \alpha^{-1} V(f) .$$

Furthermore, if  $\sigma'$  is available at f in  $\Gamma$  and if  $\sigma'$  and  $\sigma$  agree up to time r-, then

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(10) 
$$u(\sigma') \ge (1-\varepsilon)V(f)$$

where  $\epsilon = \beta(1 + \alpha^{-1})$ .

<u>Proof:</u> Let t be a stop rule and set  $v_t = \int_{[t>r]} V(f_r) d\sigma$ . Then

$$(1-\beta)V(f) \le u(\sigma)$$

$$= \int u(\sigma[p_{tAr}])d\sigma \quad (by (2))$$

$$= \int u(\sigma[p_t])d\sigma + \int u(\sigma[p_r])d\sigma$$

$$\le \int V(f_t)d\sigma + (1-\alpha)\int V(f_r)d\sigma$$

$$= \int V(f_t)d\sigma + (1-\alpha)\int V(f_r)d\sigma$$

$$= \int V(f_{tAr})d\sigma - \alpha v_t$$

$$\le V(f) - \alpha v_t \quad (Corollary 3.3.4, [3])$$

Inequality (9) is now clear.

Now let s be a stop rule and  $\epsilon' > 0$ . By Lemma 1 there is a stop rule t such that  $t \ge s$  and

Hence,

$$\int_{[t\leq r]}^{u(f_t)d\sigma'} + \int_{[t>r]}^{u(\sigma'[p_r])d\sigma'} \ge \int_{[t\leq r]}^{u(f_t)d\sigma'} \\ = \int_{[t\leq r]}^{u(f_t)d\sigma}$$

(since  $\sigma$  and  $\sigma'$  agree up to r-)

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 $\geq (1-\beta)V(f) - v_{t} - \epsilon'$ (by (11))  $\geq (1-\epsilon)V(f) - \epsilon' .$ (by (9))

Inequality (10) now follows from another application of Lemma 1.

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### 3. The existence proof.

Let  $(F, \Gamma, u)$  be a nonnegative gambling problem. A <u>family of</u> <u>strategies</u> is a mapping from F to the set of strategies. Let  $\bar{\rho}$  be a family of strategies and  $0 < \alpha < 1$ . Define another family of strategies  $\bar{\sigma} = \psi(\bar{\rho}, \alpha)$  as follows: For every f'  $\epsilon$  F, let

(12) 
$$r(f') = r(\rho(f'), \alpha)$$
 (see formula (8)).

Fix  $f \in F$ . Set s(1) = r(f) and, for n = 1, 2, ..., let <math>s(n+1) be the composition of s(n) with the family  $r(\cdot)$  (p. 22, [3]); that is, for  $h = (f_1, f_2, ...) \in H$ , let

(13) 
$$s(n+1)(h) = s(n)(h) + r(f_{s(n)}(h))(f_{s(n)}(h)+1, f_{s(n)}(h)+2, \cdots)$$
  
if  $s(n)(h) < \infty$ ,  
 $= \infty$  if  $s(n)(h) = \infty$ .

Define  $\bar{\sigma}(f)$  to be that strategy which agrees with  $\bar{\rho}(f)$  up to time r(f)- and is such that, for  $n \ge 1$  and  $h \in H$ ,  $\sigma[p_{s(n)}(h)]$  agrees with  $\bar{\rho}(f_{s(n)}(h))$  up to time  $r(f_{s(n)}(h))$ -. The family  $\bar{\sigma} = \psi(\bar{\rho}, \alpha)$  is now defined.

Let  $0 < \beta < 1$ . Let  $S(\beta)$  be the collection of families of strategies  $\bar{\rho}$  such that, for every f,  $\bar{\rho}(f)$  is available at f in  $\Gamma$  and  $u(\bar{\rho}(f)) \ge (1-\beta)V(f)$ . Define  $P(\alpha, \beta)$  to be the set of families of strategies  $\bar{\sigma}$  such that  $\bar{\sigma} = \psi(\bar{\rho}, \alpha)$  for some  $\bar{\rho}$  in  $S(\beta)$ . Intuitively, to construct an element of  $P(\alpha, \beta)$ , start with a family  $\bar{\rho}$  of  $\beta$ -optimal strategies; use the strategy which  $\bar{\rho}$  specifies at the initial fortune until it becomes conditionally less than  $\alpha$ -optimal; then switch

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to the strategy specified by  $\rho$  at the current fortune and use it until it becomes conditionally less than  $\alpha$ -optimal and so forth.

Notice that if V is everywhere finite then  $S(\beta)$  and  $P(\alpha, \beta)$  are not empty.

<u>Theorem 1.</u> Let  $(F, \Gamma, u)$  be a nonnegative gambling problem with V everywhere finite. For every  $f \in F$  and  $0 \le 1$ , there is available at f in  $\Gamma$  a strategy  $\sigma$  which is persistently (multiplicatively)  $\varepsilon$ -optimal. Indeed if

(14) 
$$0 < \alpha < 1, 0 < \beta < 1, (1-\beta(1 + \alpha^{-1}))(1-\alpha) \ge 1 - \epsilon$$
,

and  $\bar{\sigma} \in P(\alpha, \beta)$ , then  $\bar{\sigma}(f)$  is persistently (multiplicatively)  $\epsilon$ -optimal at f. <u>Proof:</u> Choose  $\alpha, \beta$  to satisfy (14). Let  $\bar{\rho} \in S(\beta)$  and  $\bar{\sigma} = \psi(\bar{\rho}, \alpha) \in P(\alpha, \beta)$ . Set  $\sigma = \bar{\sigma}(f)$ . Let r(f) and s(n) be as in the definition of  $\bar{\sigma}$ . Set  $\epsilon' = \beta(1 + \alpha^{-1})$ . Since  $u(\bar{\rho}(f)) \ge (1-\beta)V(f)$ and  $\sigma$  agrees with  $\bar{\rho}(f)$  up to time r(f)-, Lemma 3 applies to show  $u(\sigma) \ge (1 - \epsilon')V(f) \ge (1-\epsilon)V(f)$ . Similarly, for each positive integer m and h  $\epsilon$  H, it follows from Lemma 3 that, whenever  $s(m)(h) < \infty$ ,

(15) 
$$u(\sigma[p_{s(m)}(h)]) \ge (1 - e')V(f_{s(m)}(h))$$
$$\ge (1 - e)V(f_{s(m)}(h)).$$

Consider next a partial history  $p = (f_1, \dots, f_n)$  which, for every  $k = 1, 2, \dots$ , is not of the form  $p_{s(k)}(h)$ . Let m be the least positive integer such that n < s(m)(ph') for some h' (and, hence, every h'). If  $m \ge 2$ , let  $k = s(m-1)(f_1, \dots, f_n, \dots)$  so that  $f_k = f_{s(m-1)}(f_1, \dots, f_n, \dots)$ . If m = 1, let k = 0 and  $f_k = f$ . Set  $\sigma' = \overline{\rho}(f_k)[(f_{k+1}, \dots, f_n)]$  and  $r_0 = r(f_k)[(f_{k+1},...,f_n)]$ . Use the definitions of  $r(f_k)$  and s(m) (formulas (12) and (13)) to see that

(16) 
$$u(\sigma') \ge (1 - \alpha)V(f_n)$$
.

Check that  $\sigma[p]$  and  $\sigma'$  agree up to time  $r_0^-$ . Also, for h'  $\epsilon$  H,

$$\begin{aligned} u(\sigma[p][p_{r_{O}}(h')]) &= u(\sigma[p_{s(m)}(ph')]) \\ &\geq (1 - \varepsilon')V(f_{s(m)}(ph')) \qquad (by (15)) \\ &= (1 - \varepsilon')V(f_{r_{O}}(h')) , \end{aligned}$$

whenever  $r_0(h') < \infty$ . Apply Lemma 2 to the strategies  $\sigma[p]$  and  $\sigma'$  to conclude

(17) 
$$u(\sigma[p]) \ge (1 - \varepsilon')u(\sigma')$$
.

By (16) and (17),

$$u(\sigma[p]) \ge (1 - \epsilon')(1 - \alpha)V(f_n)$$
$$\ge (1 - \epsilon)V(f_n) .$$

The proof of the theorem is now complete.  $\Box$ 

Even if optimal strategies are available at every fortune, persistently O-optimal strategies need not be as can be seen from the following example.

Example. Let 
$$F = \{0, 1, ...\}; u(1) = 1, u(n) = 0$$
 if  $n \neq 1;$   
 $\Gamma(n) = \{\delta(n)\}$  for  $n \le 1$ ,  $\Gamma(n) = \{\delta(n), (1-n^{-1})\delta(1) + n^{-1}\delta(0), \gamma\}$   
for  $n \ge 2$  where  $\gamma$  is a diffuse gamble on  $F$ .

<u>Corollary 1.</u> Let  $(F, \Gamma, u)$  be a gambling problem with u bounded. For each  $f \in F$  and  $\varepsilon > 0$ , there is a strategy  $\sigma$  available at fin  $\Gamma$  such that  $u(\sigma) \ge V(f) - \varepsilon$  and  $u(\sigma[p]) \ge V(f_n) - \varepsilon$  for every  $p = (f_1, \dots, f_n)$ . <u>Proof:</u> There is no real loss of generality in assuming u is nonnegative. Since V is bounded, the conclusion follows easily from the theorem.

An example of Blackwell in [1] can easily be modified to show that for unbounded, even nonnegative u, there need not exist strategies which are persistently (additively)  $\epsilon$ -optimal, that is, strategies which satisfy the conclusion of Corollary 1.

#### 4. Measurable gambling problems.

Let X be a separable metric space. Call X <u>analytic</u> if there is a continuous function from the set of irrationals in the unit interval onto X. (See Kuratowski [4] or Blackwell, Freedman, and Orkin [2] for a discussion of analytic sets.) Let  $\mathfrak{G}(X)$  denote the sigma-field of Borel subsets of X. A nonnegative, real-valued function g defined on X is <u>semi-analytic</u> if  $\{x:g(x) > a\}$  is analytic for all nonnegative a. (See [2] and [4].) Denote by  $\mathfrak{P}(X)$  the set of countably additive probability measures defined on  $\mathfrak{G}(X)$ . Equip  $\mathfrak{P}(X)$  with the weak-star topology. Then  $\mathfrak{P}(X)$  is an analytic set if X is. (Lemma (25) in [2]). A function g from an analytic set X into an analytic set Y is <u>universally measurable</u> or <u>measurable</u> for short if, for every S  $\in \mathfrak{G}(Y)$ and  $p \in \mathfrak{P}(X)$ ,  $g^{-1}(S)$  is in the completion of  $\mathfrak{G}(X)$  under p.

A gambling problem  $(F, \Gamma, u)$  is <u>nonnegative analytic</u> if F is an analytic set, u is semi-analytic, and the set  $\{(f,\gamma):\gamma \in \Gamma(f)\}$  is an analytic subset of  $F \propto P(F)$ . (Here each gamble  $\gamma$  is identified with its restriction to B(F) and is assumed to be countably additive on B(F).) This definition of analytic gambling problems was inspired by Blackwell, Freedman, and Orkin [2]. Analytic gambling problems include the Borel measurable gambling problems defined by Strauch [5].

A strategy  $\sigma$  is <u>measurable</u> if, for  $n = 1, 2, ..., the mappings <math>(f_1, \ldots, f_n) \rightarrow \sigma_n(f_1, \ldots, f_n)$  are measurable from  $F^n$  to  $\mathcal{P}(F)$ . A measurable strategy  $\sigma$  determines a probability measure  $p(\sigma)$  on the Borel subsets of the product space  $H = F \times F \times \ldots$  as follows: the  $p(\sigma)$ -marginal distribution of  $f_1$  is  $\sigma_0$  and, for every  $(f_1, \ldots, f_n)$ 

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the  $p(\sigma)$ -distribution of  $f_{n+1}$  given  $(f_1, \ldots, f_n)$  is  $\sigma_n(f_1, \ldots, f_n)$ . For simplicity, denote  $p(\sigma)$  by  $\sigma$  below. A <u>measurable family of</u> <u>strategies</u> is a mapping  $\bar{\sigma}$  which assigns to each  $f \in F$  a measurable strategy  $\bar{\sigma}(f)$  in such a way that, for every  $n = 0, 1, \ldots$ , the function  $(f, f_1, \ldots, f_n) \rightarrow \bar{\sigma}(f)_n(f_1, \ldots, f_n)$  is measurable from  $F^{n+1}$ to P(F). The family is <u>available</u> if  $\bar{\sigma}(f)$  is available at f for every f.

Lemma 4. If  $\overline{\sigma}$  is a measurable family of strategies and u is a bounded Borel function from F to the reals, then the mapping  $\varphi: f \rightarrow u(\overline{\sigma}(f))$  is measurable from F to the reals and the mappings  $\varphi_n: (f, h) \rightarrow u(\overline{\sigma}(f)[p_n(h)])$ are measurable from F x H to the reals for n = 1, 2, ...

<u>Proof:</u> If g is a nonnegative Borel function from H to the real line and if g depends only on a finite number of coordinates, then, by Corollary (41a) of [2], the mapping

 $\varphi_{g}: f \rightarrow \int g d \bar{\sigma}(f)$ 

is measurable. The collection G of functions g such that  $\varphi_g$  is measurable includes, in particular, the indicator functions of Borel cylinder sets. Since G is closed under linear combinations and increasing limits of nonnegative functions, conclude that G contains all nonnegative Borel functions on H. By Theorem 3.2 of [8],  $u(\bar{\sigma}(f)) = \int u^* d\bar{\sigma}(f)$  where  $u^*(f_1, f_2, \ldots) = \lim_{n \to \infty} \sup u(f_n)$ . Thus  $\varphi = \varphi_{u^*}$  is measurable. The proof that the  $\varphi_n$  are measurable is similar.  $\Box$ <u>Theorem 2.</u> Let  $(F, \Gamma, u)$  be a nonnegative analytic gambling problem and assume u is a bounded, Borel measurable function. Suppose that, for every  $\beta \in (0, 1)$ , there is a measurable family of (multiplicatively)

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 $\beta$ -optimal strategies available. Then, for every  $\in \epsilon$  (0,1), there is available a measurable family of strategies which are persistently (multiplicatively)  $\epsilon$ -optimal.

<u>Proof:</u> First notice that V is measurable. To see this, let  $\overline{\sigma}_n$  be a measurable family of  $n^{-1}$ -optimal strategies for n = 1, 2, .... Then  $V(f) = \sup u(\overline{\sigma}_n(f))$  and, by Lemma 4, V is measurable.

To prove the assertion of the theorem, it suffices, by Theorem 1, to show that, given  $\alpha$ ,  $\beta \in (0, 1)$ , there is a measurable family  $\overline{\sigma}$ in  $P(\alpha, \beta)$ . By assumption, there is a measurable family  $\overline{\rho} \in S(\beta)$ . Let  $\overline{\sigma} = \psi(\overline{\rho}, \alpha)$ . By definition,  $\overline{\sigma} \in P(\alpha, \beta)$ . In checking that  $\overline{\sigma}$  is measurable, the only real difficulty lies in showing that the map  $(f,h) \rightarrow r(f)(h)$  is measurable from  $F \times H$  to the real line. (See formulas (12) and (8).) This in turn follows easily from the measurability of V together with Lemma 4.  $\Box$ 

Perhaps, the conclusion of Theorem 2 holds for every nonnegative analytic gambling problem which has V everywhere finite. However, up to the present only two special cases have been treated. It was shown in [4] that good measurable strategies are available for leavable, Borel measurable problems with a bounded utility function. In fact, good measurable families of strategies are always available for leavable, nonnegative analytic problems and so Theorem 2 applies. The same is true for nonleavable problems in which u is the indicator of a single fortune (see [7] for the Borel case). Of course, if F is countable, every strategy is measurable and Theorem 1 yields the existence of persistently good measurable strategies.

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