PINCHING AND NONEXISTENCE OF STABLE HARMONIC MAPS

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1. Introduction. Let $f: N^m \to M^n$ be a harmonic map from a compact Riemannian manifold N to a Riemannian manifold M. f is said to be stable if its second variation of the energy is non-negative.

Leung [6] proved that if M^n is a unit sphere S^n $(n \ge 3)$, then constant maps are the only stable harmonic maps for an arbitrary N^m . Considering the above result and some of its generalization (cf. [4], [7] and [8]), we can ask the following:

QUESTION. Let M^n be a complete simply-connected strictly (1/4)-pinched Riemannian manifold of dimension $n(n \ge 3)$ (i.e., the sectional curvature K_M satisfies $1/4 < K_M \le 1$). Let N^m be an arbitrary compact Riemannian manifold. Is every stable harmonic map $f: N^m \to M^n$ a constant map?

This is a "harmonic-version" of the famous conjecture of Lawson and Simons (cf. [5]) on stable minimal submanifolds (or more generally stable currents). To this question, Howard [3] obtained a partial affirmative answer. He showed that for each $n \geq 3$ there exists a constant $\delta(n)$ satisfying $1/4 < \delta(n) < 1$ such that if M^n is a simply-connected compact strictly $\delta(n)$ -pinched Riemannian manifold of dimension n, then there are no nonconstant stable harmonic maps from any compact Riemannian manifold to M. But unfortunately $\lim_{n\to\infty} \delta(n) = 1$.

The purpose of this paper is to give a dimension-independent pinching constant. We prove:

MAIN THEOREM. Let M^n be a compact simply-connected 0.83-pinched Riemannian manifold ($n \ge 3$) (i.e. $0.83 \le K_{\scriptscriptstyle M} \le 1$). Then for any compact Riemannian manifold N^m , any stable harmonic map $f: N^m \to M^n$ is a constant map.

In Section 2 we present some necessary formulas and in Section 3 we prove the main theorem. In Section 4 we use the same technique used in the proof of the main theorem to prove Theorem 3 which is an extension of a theorem of Ohnita [8], and as a corollary we get topological information on minimal submanifolds of sufficiently pinched spheres.

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2. Preliminaries. In this section we always assume that M^n is a compact simply-connected δ -pinched Riemannian manifold.

When M^n is a convex hypersurface in the Euclidean space \mathbb{R}^{n+1} , using the flat connection of \mathbb{R}^{n+1} and taking the average of the second variations, Leung [7] proved that for a certain convex hypersurface M^n in \mathbb{R}^{n+1} any stable harmonic map $f: N^m \to M^n$ is a constant map. The idea now is to follow the pattern of his calculation. To carry this idea out, we construct a vector bundle E on M and a flat connection ∇' on E instead of $M \times \mathbb{R}^{n+1}$ and the flat connection on $M \times \mathbb{R}^{n+1}$, respectively. For the construction we follow [1] and [2].

As in [2] we normalize the δ -pinched metric of M by multiplication with $(1+\delta)/2$. Put $E=TM \oplus \varepsilon(M)$, where TM is the tangent bundle of M and $\varepsilon(M)$ is a trivial line bundle on M with a metric. Thus E naturally becomes a Euclidean vector bundle on M. Let e be a cross-section of length one in $\varepsilon(M)$. We define a metric connection ∇'' on E as follows:

(1)
$$\nabla_x'' Y = \nabla_x Y - \langle X, Y \rangle \cdot e$$

$$\nabla_X^{\prime\prime} e = X,$$

where X and Y are vector fields on M, \langle , \rangle and ∇ are the Riemannian metric andt he Riemannian connection of M, respectively. Under the pinching assumption, the curvature R'' of ∇'' is small. We obtain a flat metric connection ∇' close to ∇'' exactly as in [2]. To measure the closeness we define

$$\|\nabla' - \nabla''\| := \text{Max} \{ \|\nabla'_X Y - \nabla''_X Y\|; X \in TM, \|X\| = 1, Y \in E, \|Y\| = 1 \}.$$

Note that our $\|\nabla' - \nabla''\|$ is half of $\|\nabla' - \nabla''\|$ in [1]. We define $k_1(\delta)$, $k_2(\delta)$ and $k_3(\delta)$ as follows:

$$(\ 3\) \hspace{1cm} k_{_{1}}\!(\delta) = rac{4}{3}(1-\delta)\delta^{_{-1}}\!\!\left[1+\left(\delta^{_{1/2}}\!\cdot\!\sinrac{1}{2}\pi\delta^{_{-1/2}}
ight)^{_{-1}}
ight].$$

$$(\ 4\) \hspace{1cm} k_{\scriptscriptstyle 2}(\delta) = \left[rac{1}{2}(1\ +\ \delta)
ight]^{\scriptscriptstyle -1} \cdot k_{\scriptscriptstyle 1}(\delta) \; .$$

$$(\, 5\,) \hspace{1cm} k_{\scriptscriptstyle 3}(\delta) = k_{\scriptscriptstyle 2}(\delta) \Big\{ \! 1 + \Big[1 - rac{1}{24} \pi^{\scriptscriptstyle 2} (k_{\scriptscriptstyle 1}(\delta))^{\scriptscriptstyle 2} \Big]^{\scriptscriptstyle -2} \! \Big\}^{\scriptscriptstyle 1/2} \, .$$

By [1, 4.13], we get

$$\|\nabla' - \nabla''\| \leq \frac{1}{2}k_{\mathfrak{z}}(\delta).$$

3. Proof of the main theorem. Consider a harmonic map $f: N^m \to M^n$. Let e_a $(a = 1, \dots, m)$ be a local orthonormal frame on N. The energy of f is defined as

$$E(f) = rac{1}{2} \int_{N} \sum_{a} \|f_{*}e_{a}\|^{2}$$
.

For any vector field V on M, we denote by ϕ_t the flow generated by V. Then we get the following second variational formula (cf. [6]) for the variational vector field V.

$$\begin{split} I(\textit{V}, \; \textit{V}) := \frac{d^2}{dt^2} \Big|_{t=0} E(\phi_t \circ f) \\ = \int_{N} \sum_{a} \left\{ ||\nabla_{f_* e_a} \textit{V}||^2 - \langle \textit{R}(\textit{V}, f_* e_a) f_* e_a, \; \textit{V} \rangle \right\} \,, \end{split}$$

where ∇ and R denote the Riemannian connection and curvature tensor of M, respectively.

Theorem 1. Let M^n be a compact simply-connected δ -pinched n-dimensional Riemannian manifold. Suppose that n and δ satisfy

$$(8) \qquad rac{n+1}{4} (k_{\scriptscriptstyle 3}(\delta))^2 + 1 - rac{2\delta}{1+\delta} (n-1) + (n+1)^{\scriptscriptstyle 1/2} k_{\scriptscriptstyle 3}(\delta) < 0 \; .$$

Then the only stable harmonic map $f: N^m \to M^n$ for an arbitrary compact Riemannian manifold N^m is a constant map.

PROOF. First we normalize the metric of M by multiplication with $(1 + \delta)/2$. Let E be the vector bundle on M constructed in Section 2. For $W \in E$ we denote by W^T and W^s the TM-component and the $\varepsilon(M)$ -component of W, respectively. Let V be a parallel cross-section of E with respect to ∇' . From (7), the second variation corresponding to V^T is given by

$$(9) I(V^{T}, V^{T}) = \int_{N} \sum_{a} \{ ||\nabla_{f_{*}e_{a}}V^{T}||^{2} - \langle R(V^{T}, f_{*}e_{a})f_{*}e_{a}, V^{T} \rangle \}.$$

Observe that

$$\begin{split} \nabla_{f_{*}e_{a}}V^{\scriptscriptstyle T} &= \{\nabla_{f_{*}e_{a}}^{\prime\prime}(V-V^{\scriptscriptstyle \varepsilon})\}^{\scriptscriptstyle T} = (\nabla_{f_{*}e_{a}}^{\prime\prime}V)^{\scriptscriptstyle T} - \{\nabla_{f_{*}e_{a}}^{\prime\prime}(\langle V,e\rangle e)\}^{\scriptscriptstyle T} \\ &= (\nabla_{f_{*}e_{a}}^{\prime\prime}V)^{\scriptscriptstyle T} - \langle V,e\rangle f_{*}e_{a} \; . \end{split}$$

Using (6)

$$\begin{split} (10) \qquad & \|\nabla_{f_{*}e_{a}}V^{T}\|^{2} \leqq (1+k)\|\nabla_{f_{*}e_{a}}^{\prime\prime}V\|^{2} + \left(1+\frac{1}{k}\right)\!\langle\,V,\,e\rangle^{2}\|f_{*}e_{a}\|^{2} \\ & \leqq \frac{1+k}{4}(k_{3}(\delta))^{2}\!\cdot\!\|\,V\|^{2}\!\cdot\!\|f_{*}e_{a}\|^{2} + \left(1+\frac{1}{k}\right)\!\langle\,V,\,e\rangle^{2}\|f_{*}e_{a}\|^{2} \;, \end{split}$$

where k is a positive constant fixed later. On the other hand, since we normalized the δ -pinched metric of M by multiplication with $(1 + \delta)/2$,

$$(11) \qquad \langle R(V^{\scriptscriptstyle T}, f_* e_a) f_* e_a, \ V^{\scriptscriptstyle T} \rangle \geq \frac{2\delta}{1+\delta} \{ \|V^{\scriptscriptstyle T}\|^2 \cdot \|f_* e_a\|^2 - \langle V^{\scriptscriptstyle T}, f_* e_a \rangle^2 \} \ .$$

Combining (9), (10) and (11), we get

$$\begin{split} I(V^{\scriptscriptstyle T},\ V^{\scriptscriptstyle T}) & \leq \int_{\scriptscriptstyle N} \sum_{a} \left\{ \frac{1+k}{4} (k_{\scriptscriptstyle 3}(\delta))^2 \|\,V\|^2 \!\cdot\! \|f_{\scriptscriptstyle *} e_a\|^2 \right. \\ & \left. + \left(1+\frac{1}{k}\right) \!\langle\,V,\,e\rangle^2 \|f_{\scriptscriptstyle *} e_a\|^2 - \frac{2\delta}{1+\delta} [\|\,V^{\scriptscriptstyle T}\|^2 \!\cdot\! \|f_{\scriptscriptstyle *} e_a\|^2 - \langle\,V^{\scriptscriptstyle T},\,f_{\scriptscriptstyle *} e_a\rangle^2] \right\} \,. \end{split}$$

We now define $\mathscr{W} = \{V \in \Gamma(E); \nabla' V = 0\}$, where $\Gamma(E)$ denotes the vector space consisting of all smooth cross-sections of E. Then \mathscr{W} is isomorphic to \mathbb{R}^{n+1} and has a natural inner product. We define a quadratic form Q on \mathscr{W} by

(13)
$$Q(V) = \text{the right hand side of } (12) := \int_{N} \sum_{a} q_{a}.$$

Take an orthonormal basis $\{W_1, \dots, W_{n+1}\}$ of \mathcal{W} . Then we obtain

Since the trace of q_a is independent of the choice of an orthonormal basis for each fiber of E, at each point $x \in M$ we choose an orthonormal basis $\{V_1, \dots, V_n, e\}$ such that the V_i are tangent to M. Then we get

(15)
$$\operatorname{tr} Q = \int_{N} \sum_{a} \left\{ \frac{(n+1)(1+k)}{4} (k_{3}(\delta))^{2} + 1 + \frac{1}{k} - \frac{2(n-1)\delta}{1+\delta} \right\} \cdot ||f_{*}e_{a}||^{2}.$$

Now we take $k = ((n + 1)/4)^{-1/2}k_3(\delta)^{-1}$. Then

(16)
$$\operatorname{tr} Q = \int_{N} \sum_{a} \left\{ \frac{n+1}{4} (k_{\mathfrak{z}}(\delta))^{2} + 1 - \frac{2\delta}{1+\delta} (n-1) + (n+1)^{1/2} k_{\mathfrak{z}}(\delta) \right\} ||f_{*}e_{a}||^{2}.$$

To get the conclusion, we suppose that f is a nonconstant harmonic map and that n and δ satisfy (8). Then we get $\operatorname{tr} Q < 0$. By (14) we obtain $I(W_j^T, W_j^T) < 0$ for some j. Thus f is unstable. q.e.d.

PROOF OF THE MAIN THEOREM. Since we have $k_3(0.83) = 0.964$, (8) is equivalent to $n \ge 8$ for $\delta = 0.83$. On the other hand, the constant $\delta(n)$ of Howard [3] satisfies $\delta(n) < 0.83$ for $3 \le n \le 7$. Thus we get the conclusion.

REMARK. The value δ satisfying $k_{\mathfrak{d}}(\delta)^2 = 8\delta/(1+\delta)$ is $0.76 \cdots$. So our estimate for δ can be improved up to $0.76 \cdots$ if n is large.

4. An extension of a theorem of Ohnita and its application to minimal submanifolds. Ohnita [8] proved the following theorem.

THEOREM 2. Let M^n be an n-dimensional compact minimal submanifold immersed in a unit sphere $S^{N-1}(1)$. If the Ricci curvature Ric_M of M satisfies $\mathrm{Ric}_M > n/2$, then M is harmonically unstable. That is, there exists no nonconstant stable harmonic map from M to any Riemannian manifold nor from any compact Riemannian manifold to M.

Now we prove the following theorem which is a partial extension of Theorem 2.

Theorem 3. Let (\overline{M}^{N-1},h) be a complete simply-connected δ -pinched (N-1)-dimensional Riemannian manifold with $(k_3(\delta))^2 \leq 4(2n+\delta-1)/N(1+\delta)$. Suppose that $f:(M^n,g) \to (\overline{M}^{N-1},h)$ is an isometric minimal immersion of a complete n-dimensional Riemannian manifold (M^n,g) with $\rho > c(N,n,\delta) := (2n+\delta-1)/4 + \{[(2n+\delta-1)/4]^2 - [(2n+\delta-1)/4-N(1+\delta)k_3(\delta)^2/16]^2\}^{1/2}$, where ρ is the infimum of the Ricci curvature of M. Then for any compact Riemannian manifold M', any stable harmonic map $\phi: M' \to M$ is a constant map.

PROOF. We normalize the metrics g and h by multiplication with $(1+\delta)/2$. We use the same letters g, h for the normalized metrics. Let ∇ , \overline{R} be the Riemannian connection and the curvature tensor of (\overline{M}^{N-1}, h) . We construct a Euclidean vector bundle E on (\overline{M}^{N-1}, h) and also construct metric connections ∇' , ∇'' on E as in Section 2. Let $\langle \ , \ \rangle$ be the metric on E. Thus we have

$$abla_x''Y = \bar{\nabla}_x Y - h(X, Y) \cdot e$$
 $abla_x''e = X,$

where X and Y are vector fields on (\overline{M}^{N-1}, h) . Let σ be the second fundamental form of M^n in (\overline{M}^{N-1}, h) and let ∇ be the Riemannian connection of M. Set $N(M) := \{X \in f^*E; X \perp TM\}$. Then we obtain

$$ar{
abla}_{\scriptscriptstyle X}Y =
abla_{\scriptscriptstyle X}Y + \sigma(X, Y) \ ar{
abla}_{\scriptscriptstyle X}\xi = -A^{\epsilon}X +
abla_{\scriptscriptstyle X}^{\perp}\xi \; ,$$

where $X, Y \in TM$, $\xi \in N(M) \cap T\overline{M}^{N-1}$ and A^{ξ} , ∇^{\perp} are the Weingarten map in the direction of ξ and the normal connection of M in (\overline{M}^{N-1}, h) respectively. Let V be a parallel cross-section of E with respect to ∇' . Let V^T and V^N be the TM-component and the N(M)-component of V, respectively. Thus

$$V^{\scriptscriptstyle N} = \langle \mathit{V}, \, e
angle e + \sum\limits_{i} \langle \mathit{V}, \, \xi_{i}
angle \xi_{i}$$
 ,

where $\{\xi_1, \dots, \xi_{N-1-n}\}$ is an orthonormal basis of $N(M) \cap T\bar{M}^{N-1}$. The second variation of $E(\phi)$ corresponding to V^T is given by

(17)
$$I(V^{T}, V^{T}) = \int_{M'} \sum_{a} \{ \|\nabla_{\phi_{*}e_{a}} V^{T}\|^{2} - \langle R(\phi_{*}e_{a}, V^{T}) V^{T}, \phi_{*}e_{a} \rangle \},$$

where $\{e_a\}$ is a local orthonormal frame of M' and R is the curvature tensor of M. For $W \in E$ we denote by W^{TM} and $W^{T\overline{M}^{N-1}}$ the TM-component and the $T\overline{M}^{N-1}$ -component of W, respectively. Observe that

(18)
$$\nabla_{\phi * e_{a}} V^{T} = (\bar{\nabla}_{\phi * e_{a}} V^{T})^{TM} = \{ (\nabla_{\phi * e_{a}}^{"} V^{T})^{T\overline{M}^{N-1}} \}^{TM}$$

$$= \{ (\nabla_{\phi * e_{a}}^{"} V)^{T\overline{M}^{N-1}} - (\nabla_{\phi * e_{a}}^{"} V^{N})^{T\overline{M}^{N-1}} \}^{TM}$$

$$= (\nabla_{\phi * e_{a}}^{"} V)^{TM} - (\nabla_{\phi * e_{a}}^{"} V^{N})^{TM}$$

and

$$(19) \qquad (\nabla''_{\phi*e_a}V^N)^{TM} = \{\nabla''_{\phi*e_a}(\langle V, e \rangle e)\}^{TM} + \sum_{j} \{\nabla''_{\phi*e_a}(\langle V, \xi_j \rangle \xi_j)\}^{TM}$$

$$= \langle V, e \rangle \phi_* e_a + \sum_{j} \langle V, \xi_j \rangle \{\nabla''_{\phi*e_a} \xi_j\}^{TM}$$

$$= \langle V, e \rangle \phi_* e_a + \sum_{j} \langle V, \xi_j \rangle \{\bar{\nabla}_{\phi*e_a} \xi_j\}^{TM}$$

$$= \langle V, e \rangle \phi_* e_a - \sum_{j} \langle V, \xi_j \rangle A^j (\phi_* e_a) ,$$

where we abbreviate $A^{j} = A^{i}$. Hence we obtain from (18), (19) and (6) that

$$\begin{split} \|\nabla_{\phi_{\bullet e_a}} V^T\|^2 & \leq (1+k) \|\nabla_{\phi_{\bullet e_a}}^{\prime\prime} V\|^2 + \left(1+\frac{1}{k}\right) \left\|\left\langle V,\, e\right\rangle \phi_{\ast} e_a - \sum_j \left\langle V,\, \xi_j\right\rangle A^j (\phi_{\ast} e_a) \right\|^2 \\ & \leq \frac{(1+k)}{4} (k_3(\delta))^2 \cdot \|V\|^2 \cdot \|\phi_{\ast} e_a\|^2 \\ & + \left(1+\frac{1}{k}\right) \left\|\left\langle V,\, e\right\rangle \phi_{\ast} e_a - \sum_j \left\langle V,\, \xi_j\right\rangle A^j (\phi_{\ast} e_a) \right\|^2 \,, \end{split}$$

where k is a positive constant fixed later. Therefore from (17)

$$\begin{split} I(V^{T},\ V^{T}) & \leq \int_{\mathbb{M}^{'}} \sum_{a} \left\{ \frac{(1+k)}{4} (k_{3}(\delta))^{2} \cdot \|V\|^{2} \cdot \|\phi_{*}e_{a}\|^{2} \right. \\ & \left. + \left(1 + \frac{1}{k}\right) \left\| \langle V, e \rangle \phi_{*}e_{a} - \sum_{j} \langle V, \xi_{j} \rangle A^{j}(\phi_{*}e_{a}) \right\|^{2} \\ & \left. - \langle R(\phi_{*}e_{a},\ V^{T})V^{T},\ \phi_{*}e_{a} \rangle \right\} \; . \end{split}$$

Denote by Q(V) the right hand side of (20). Then Q is a quadratic form on $\mathscr{W} = \{V \in \Gamma(E); \nabla' V = 0\}$. We take the trace of Q on \mathscr{W} . Then we obtain

$$\begin{split} \text{(21)} \quad & \text{tr } Q = \int_{{}_{M^{'}}} \sum_{a} \, \left\{ \frac{(1\,+\,k)N}{4} (k_{3}(\delta))^{2} \cdot \|\phi_{*}e_{a}\|^{2} \right. \\ & \left. + \left(1\,+\,\frac{1}{k}\right) \|\phi_{*}e_{a}\|^{2} + \left(1\,+\,\frac{1}{k}\right) \sum_{j} \, \|A^{j}(\phi_{*}e_{a})\|^{2} - \text{Ric}_{M}(\phi_{*}e_{a},\,\phi_{*}e_{a}) \right\} \,. \end{split}$$

Let $\{V_1, \dots, V_n\}$ be a local orthonormal basis of TM. Then we get

(22)
$$\sum_{j} \|A^{j}(\phi_{*}e_{a})\|^{2} = \sum_{j,i} \langle A^{j}(\phi_{*}e_{a}), V_{i} \rangle^{2}$$

$$= \sum_{j,i} \langle \xi_{j}, \sigma(\phi_{*}e_{a}, V_{i}) \rangle^{2} = \sum_{i} \|\sigma(\phi_{*}e_{a}, V_{i})\|^{2} .$$

On the other hand, since

$$egin{aligned} \langle R(\phi_*e_a,\ V_i)V_i,\ \phi_*e_a
angle &= \langle ar{R}(\phi_*e_a,\ V_i)V_i,\ \phi_*e_a
angle + \langle \sigma(\phi_*e_a,\ \phi_*e_a),\ \sigma(V_i,\ V_i)
angle \ &- \langle \sigma(\phi_*e_a,\ V_i),\ \sigma(\phi_*e_a,\ V_i)
angle \ &\leq rac{2}{1+\delta}\{\|V_i\|^2\!\cdot\!\|\phi_*e_a\|^2 - \langle V_i,\ \phi_*e_a
angle^2\} \ &+ \langle \sigma(\phi_*e_a,\ \phi_*e_a),\ \sigma(V_i,\ V_i)
angle - \|\sigma(\phi_*e_a,\ V_i)\|^2 \ , \end{aligned}$$

from the assumption that M is a minimal submanifold of (\bar{M}^{N-1}, h) , we obtain

(23)
$$\operatorname{Ric}_{M}(\phi_{*}e_{a}, \phi_{*}e_{a}) \leq \frac{2(n-1)}{1+\delta} \|\phi_{*}e_{a}\|^{2} - \sum_{i} \|\sigma(\phi_{*}e_{a}, V_{i})\|^{2}.$$

From (22) and (23) we get

(24)
$$\sum_{j} \|A^{j}(\phi_{*}e_{a})\|^{2} \leq \frac{2(n-1)}{1+\delta} \|\phi_{*}e_{a}\|^{2} - \operatorname{Ric}_{M}(\phi_{*}e_{a}, \phi_{*}e_{a})$$

$$\leq \frac{2(n-1)}{1+\delta} \|\phi_{*}e_{a}\|^{2} - \frac{2\rho}{1+\delta} \|\phi_{*}e_{a}\|^{2} .$$

Thus from (21) and (24)

$$\begin{split} \text{(25)} \qquad & \text{tr } Q \leqq \int_{\mathtt{M}'} \sum_{a} \Big\{ \frac{(1+k)N}{4} (k_{\scriptscriptstyle 3}(\delta))^2 + 1 + \frac{1}{k} \\ & + \Big(1 + \frac{1}{k} \Big) \! \Big[\frac{2(n-1)}{1+\delta} - \frac{2\rho}{1+\delta} \Big] - \frac{2\rho}{1+\delta} \Big\} \| \phi_* e_a \|^2 \; . \end{split}$$

Now we set $k=(N/4)^{-1/2}k_3(\delta)^{-1}\{1+2(n-1)/(1+\delta)-2\rho/(1+\delta)\}^{1/2}$. Then $\operatorname{tr} Q \leqq \int_{M'} \sum_a \Big\{\frac{N}{4}(k_3(\delta))^2 + \frac{2n+\delta-1}{1+\delta} - \frac{4}{1+\delta}\rho \\ + \Big\lceil \frac{N}{1+\delta}(2n-2\rho+\delta-1) \Big\rceil^{1/2}k_3(\delta)\Big\} \|\phi_*e_a\|^2 \ .$

When $(k_3(\delta))^2 \le 4(2n+\delta-1)/N(1+\delta)$, $c(N, n, \delta)$ is a unique solution of the following equation for t.

$$rac{N}{4}(k_{\scriptscriptstyle 3}(\delta))^{\scriptscriptstyle 2} + rac{2n \, + \, \delta - 1}{1 \, + \, \delta} - rac{4}{1 \, + \, \delta} \, t \, + \left[rac{N}{1 \, + \, \delta}(2n \, - \, 2t \, + \, \delta \, - \, 1)
ight]^{\scriptscriptstyle 1/2}\!\! k_{\scriptscriptstyle 3}(\delta) = 0 \; .$$

Thus tr Q < 0, from which the theorem follows.

We obtain the following corollary as in [8].

COROLLARY. Let (\overline{M}^{N-1}, h) be a complete simply-connected δ -pinched Riemannian manifold with $(k_3(\delta))^2 \leq 4(2n + \delta - 1)/N(1 + \delta)$.

Suppose that $f: M^n \to (\overline{M}^{N-1}, h)$ is a minimal immersion of a complete Riemannian manifold. If the Ricci curvature of M satisfies $\mathrm{Ric}_M > c(N, n, \delta)$, then $\pi_1 M = \{1\}$ and $\pi_2 M = \{1\}$.

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