# Posterior contraction of the population polytope in finite admixture models 

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#### Abstract

We study the posterior contraction behavior of the latent population structure that arises in admixture models as the amount of data increases. We adopt the geometric view of admixture models - alternatively known as topic models - as a data generating mechanism for points randomly sampled from the interior of a (convex) population polytope, whose extreme points correspond to the population structure variables of interest. Rates of posterior contraction are established with respect to Hausdorff metric and a minimum matching Euclidean metric defined on polytopes. Tools developed include posterior asymptotics of hierarchical models and arguments from convex geometry.


Keywords: Bayesian asymptotics; convex geometry; convex polytope; Hausdorff metric; latent mixing measures; population structure; rates of convergence; topic simplex

## 1. Introduction

We study a class of hierarchical mixture models for categorical data known as the admixtures, which were independently developed in the landmark papers by Pritchard, Stephens and Donnelly [13] and Blei, Ng and Jordan [4]. The former set of authors applied their modeling to population genetics, while the latter considered applications in text processing and computer vision, where their models are more widely known as the latent Dirichlet allocation model, or a topic model. Admixture modeling has been applied to and extended in a vast number of fields of engineering and sciences - in fact, the Google scholar pages for these two original papers alone combine for more than a dozen thousands of citations. In spite of their wide uses, asymptotic behavior of hierarchical models such as the admixtures remains largely unexplored, to the best of our knowledge.

A finite admixture model posits that there are $k$ populations, each of which is characterized by a $\Delta^{d}$-valued vector $\boldsymbol{\theta}_{j}$ of frequencies for generating a set of discrete values $\{0,1, \ldots, d\}$, for $j=1, \ldots, k$. Here, $\Delta^{d}$ is the $d$-dimensional probability simplex. A sampled individual may have mixed ancestry and as a result inherits some fraction of its values from each of its ancestral populations. Thus, an individual is associated with a proportion vector $\boldsymbol{\beta}=\left(\beta_{1}, \ldots, \beta_{k}\right) \in \Delta^{k-1}$, where $\beta_{j}$ denotes the proportion of the individual's data that are generated according to population $j$ 's frequency vector $\boldsymbol{\theta}_{j}$. This yields a vector of frequencies $\boldsymbol{\eta}=\sum_{j=1}^{k} \beta_{j} \boldsymbol{\theta}_{j} \in \Delta^{d}$ associated with that individual. In most applications, one does not observe $\eta$ directly, but rather an i.i.d. sample generated from a multinomial distribution parameterized by $\boldsymbol{\eta}$. The collection of $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$ is referred to as the population structure in the admixture. In population genetics modeling, $\boldsymbol{\theta}_{j}$ represents the allele frequencies at each locus in an individual's genome from the $j$ th population. In
text document modeling, $\boldsymbol{\theta}_{j}$ represents the frequencies of words generated by the $j$ th topic, while an individual is a document, that is, a collection of words. In computer vision, $\boldsymbol{\theta}_{j}$ represents the frequencies of objects generated by the $j$ th scenary topic, while an individual is a natural image, that is, a collection of scenary objects. The primary interest is the inference of the population structure on the basis of sampled data. In a Bayesian estimation setting, the population structure is assumed random and endowed with a prior distribution - accordingly one is interested in the behavior of the posterior distribution of the population structure given the available data.

The goal of this paper is to obtain contraction rates of the posterior distribution of the latent population structure that arises in admixture models, as the amount of data increases. Admixture models present a canonical mixture model for categorical data in which the population structure provides the support for the mixing measure. Existing works on convergence behavior of mixing measures in a mixture model are quite rare, in either frequentist or Bayesian estimation literature. Chen provided the optimal convergence rate of mixing measures in several finite mixtures for univariate data [5] (see also [10]). Recent progress on multivariate mixture models include papers by Rousseau and Mengersen [14] and Nguyen [12]. In [12], posterior contraction rates of mixing measures in several finite and infinite mixture models for multivariate and continuous data were obtained. Toussile and Gassiat established consistency of a penalized MLE procedure for a finite admixture model [17]. This issue has also attracted increased attention in machine learning. Recent papers by Arora et al. [2] and Anandkumar et al. [1] study convergence properties of certain computationally efficient learning algorithms based on matrix factorization techniques.

There are a number of questions that arise in the convergence analysis of admixture models for categorical data. The first question is to find a suitable metric in order to establish rates of convergence. It would be ideal to establish convergence for each individual element $\boldsymbol{\theta}_{\boldsymbol{i}}$, for $i=1, \ldots, k$. This is a challenging task due to the problems of identifiability. A (relatively) minor issue is known as "label-switching" problem. That is, one can identify the collection of $\boldsymbol{\theta}_{i}$ 's only up to a permutation. A deeper problem is that any $\boldsymbol{\theta}_{j}$ that can be expressed as a convex combination of the others $\boldsymbol{\theta}_{j^{\prime}}$ for $j^{\prime} \neq j$ may be difficult to identify, estimate, and analyze. To get around this difficulty, we propose to study the convergence of population structure variables through its convex hull $G=\operatorname{conv}\left(\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}\right)$, which shall be referred to as the population polytope. Convergence of convex polytopes can be evaluated in terms of Hausdorff metric $d_{\mathcal{H}}$, a metric commonly utilized in convex geometry [15]. Moreover, under some geometric identifiability conditions, it can be shown that convergence in Hausdorff metric entails convergence of all extreme points of the polytope via a minimum-matching distance metric (defined in Section 2). This is the theory we aim for in this paper. Note however that in a typical setting of topic modeling where $d \geq k$, all population structure variables $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$ in general positions in $\Delta^{d}$ are extreme points of the population polytope. Thus, in this setting, convergence in Hausdorff metric entails convergence of the population structure variables up to a permutation of labels. Convergence behavior of (the posterior of) non-extreme points among $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$, when $k>d$, remains elusive as of this writing.

The second question in an asymptotic study of a hierarchical model is how to address multiple quantities that define the amount of empirical data. The admixture model we consider has two asymptotic quantities that play asymmetric roles $-m$ is the number of individuals, and $n$ is the number of data points associated with each individual. Both $m$ and $n$ are allowed to increase to infinity. A simple way to think about this asymptotic setting is to let $m$ go to infinity, while
$n:=n(m)$ tends to infinity at a certain rate which may be constrained with respect to $m$. Let $\Pi$ be a prior distribution on variables $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$. The goal is to derive a vanishing sequence of $\delta_{m, n}$, depending on both $m$ and $n$, such that the posterior distribution of the $\boldsymbol{\theta}_{i}$ 's satisfies, for some sufficiently large constant $C$,

$$
\Pi\left(d_{\mathcal{H}}\left(G, G_{0}\right) \geq C \delta_{m, n} \mid \mathcal{S}_{[n]}^{[m]}\right) \rightarrow 0
$$

in $P_{\mathcal{S}_{[n]} \mid G_{0}}^{m}$-probability as $m \rightarrow \infty$ and $n=n(m) \rightarrow \infty$ suitably. Here, $P_{\mathcal{S}_{[n]} \mid G_{0}}^{m}$ denotes the true distribution associated with population polytope $G_{0}$ that generates a given $m \times n$ data set $\mathcal{S}_{[n]}^{[m]}$. As mentioned, $\delta_{m, n}$ is also the posterior contraction rate for the extreme points among population structure variables $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$.

## Overview of results

Suppose that $n \rightarrow \infty$ at a rate constrained by $\log m<n$ and $\log n=o(m)$. In an overfitted setting, that is, when the true population polytope may have less than $k$ extreme points, we show that under some mild identifiability conditions the posterior contraction rate in either Hausdorff or minimum-matching distance metric is $\delta_{m, n} \asymp\left[\frac{\log m}{m}+\frac{\log n}{n}+\frac{\log n}{m}\right]^{1 /(2(p+\alpha))}$, where $p=(k-1) \wedge$ $d$ is the intrinsic dimension of the population polytope while $\alpha$ denotes the regularity level near boundary of the support of the density function for $\boldsymbol{\eta}$ (to be defined in sequel). On the other hand, if either the true population polytope is known to have exactly $k$ extreme points, or if the pairwise distances among the extreme points are bounded from below by a known positive constant, then the contraction rate is improved to a parametric rate $\delta_{m, n} \asymp\left[\frac{\log m}{m}+\frac{\log n}{n}+\frac{\log n}{m}\right]^{1 /(2(1+\alpha))}$.

The constraints on $n=n(m)$, and the appearance of quantity $\log n / m$ in the convergence rate are quite interesting. Both the constraints and the derived rate are rooted in a condition on the required thickness of the prior support of the marginal densities of the data and an upper bound on the entropy of the space of such densities. This suggests an interesting interaction between layers in the latent hierarchy of the admixture model worthy of further investigation. For instance, it is not clear whether posterior consistency continues to hold if $n$ falls outside of the specified range, and what effects this has on convergence rates, with or without additional assumptions on the data. This appears quite difficult with our present set of techniques.

We also establish minimax lower bounds for both settings. In the overfitted setting, the obtained lower bound is $(m n)^{-1 /\left(q+\alpha^{\prime}\right)}$, where $q=\lfloor k / 2\rfloor \wedge d$, and $\alpha^{\prime}$ is a non-negative constant to be defined in the sequel that satisfies $\alpha^{\prime} \leq \alpha$. This lower bound can be strengthened with additional conditions on the model. Although this lower bound does not match exactly with the posterior contraction rate, both are notably nonparametrics-like for depending on dimensionality $d$ and on $k$. In particular, if $n \asymp m$, and $k \geq 2 d$, the posterior contraction rate becomes $(\log m / m)^{-1 /(2(d+\alpha))}$. Compare this to the lower bound $m^{-2 /\left(d+\alpha^{\prime}\right)}$, whose exponent differs approximately by only a factor of 4 for large $d$.

## Method of proofs and tools

The general framework of posterior asymptotics for density estimation has been well-established [7,16] (see also [3,8,9,19,20]). This framework continues to be very useful, but the analysis of
mixing measure estimation in multi-level models presents distinct new challenges. In Section 4, we shall formulate an abstract theorem (Theorem 4) on posterior contraction of latent variables of interest in an admixture model, given $m \times n$ data, by reposing on the framework of [7] (see also [12]). The main novelty here is that we work on the space of latent variables (e.g., space of latent population structures endowed with Hausdorff or a comparable metric) as opposed to the space of data densities endowed with Hellinger metric. A basic quantity is the Hellinger information of the Hausdorff metric for a given subset of polytopes. Indeed, the Hellinger information is a fundamental quantity running through the analysis, which ties together the amount of data $m$ and $n$ - key quantities that are associated with different levels in the model hierarchy.

The bulk of the paper is devoted to establishing properties of the Hellinger information, which are fed into Theorem 4 so as to obtain concrete convergence rates. This is achieved through a number of inequalities which illuminate the relationship between Hausdorff distance of a given pair of population polytopes $G, G^{\prime}$, and divergence functionals (e.g., Kullback-Leibler divergence or variational distance) of the induced marginal data densities. The technical challenges lie in the fact that in order to relate $G$ to the marginal density of the data, one has to integrate out multiple layers of latent variables, $\boldsymbol{\eta}$ and $\boldsymbol{\beta}$. Techniques in convex geometry come in very handily in the derivation of both lower and upper bounds [15].

The remainder of the paper is organized as follows. The model and main results are described in Section 2. Section 3 describes the basic geometric assumptions and their consequences. An abstract theorem for posterior contraction for $m \times n$ data setting is formulated in Section 4, whose conditions are verified in the subsequent sections. Section 5 presents inequalities for Hausdorff distances which result in lower bounds on the Hellinger information, while Section 6 provides a lower bound on Kullback-Leibler neighborhoods of the prior support (that is, a bound the prior thickness). Proofs of main theorems and other technical lemmas are presented in Section 7 and the Appendices.

## Notations

$B_{p}(\boldsymbol{\theta}, r)$ denotes a closed $p$-dimensional Euclidean ball centered at $\boldsymbol{\theta}$ and has radius $r . G_{\varepsilon}$ denotes the Minkowsky sum $G_{\varepsilon}:=G+B_{d+1}(\mathbf{0}, \varepsilon)$. bd $G$, extr $G$, $\operatorname{Diam} G$, aff $G, \operatorname{vol}_{p} G$ denote the boundary, the set of extreme points, the diameter, the affine span, and the $p$-dimensional volume of set $G$, respectively. "Extreme points" and "vertices" are interchangeable throughout this paper. We define the dimension of a convex polytope to be the dimension of its affine hull. It is a well-known fact that if a polytope has $k$ extreme points in general positions in $\Delta^{d}$, then its dimension is $(k-1) \wedge d$. Set-theoretic difference between two sets is defined as $G \Delta G^{\prime}=\left(G \backslash G^{\prime}\right) \cup\left(G^{\prime} \backslash G\right) . N\left(\varepsilon, \mathcal{G}, d_{\mathcal{H}}\right)$ denotes the covering number of $\mathcal{G}$ in Hausdorff metric $d_{\mathcal{H}} . D\left(\varepsilon, \mathcal{G}, d_{\mathcal{H}}\right)$ is the packing number of $\mathcal{G}$ in Hausdorff metric. Several divergence measures for probability distributions are employed: $K(p, q), h(p, q), V(p, q)$ denote Kullback-Leibler divergence, Hellinger and total variation distance between two densities $p$ and $q$ defined with respect to a measure on a common space: $K(p, q)=\int p \log (p / q), h^{2}(p, q)=\frac{1}{2} \int(\sqrt{p}-\sqrt{q})^{2}$ and $V(P, Q)=\frac{1}{2} \int|p-q|$. In addition, we define $K_{2}=\int p[\log (p / q)]^{2}$. Throughout the paper, $f(m, n, \varepsilon) \lesssim g(m, n, \varepsilon)$, equivalently, $f=\mathrm{O}(g)$, means $f(m, n, \varepsilon) \leq C g(m, n, \varepsilon)$ for some constant $C$ independent of asymptotic quantities $m, n$ and $\varepsilon$ - details about the dependence of $C$ are
made explicit unless obvious from the context. Similarly, $f(m, n, \varepsilon) \gtrsim g(m, n, \varepsilon)$ or $f=\Omega(g)$ means $f(m, n, \varepsilon) \geq C g(m, n, \varepsilon)$.

## 2. Main results

## Model description

As mentioned in the Introduction, the central objects of the admixture model are population structure variables $\left(\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}\right)$, whose convex hull is called the population polytope: $G=\operatorname{conv}\left(\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}\right) . \boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$ reside in $d$-dimensional probability simplex $\Delta^{d} . k<\infty$ is assumed known. Note that $G$ has at most $k$ vertices (i.e., extreme points) among $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$.

A random vector $\boldsymbol{\eta} \in G$ is parameterized by $\boldsymbol{\eta}=\beta_{1} \boldsymbol{\theta}_{1}+\cdots+\beta_{k} \boldsymbol{\theta}_{k}$, where $\boldsymbol{\beta}=\left(\beta_{1}, \ldots, \beta_{k}\right) \in$ $\Delta^{k-1}$ is a random vector distributed according to a distribution $P_{\boldsymbol{\beta} \mid \gamma}$ for some parameter $\gamma$ (both [13] and [4] used the Dirichlet distribution). Given $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$, this induces a probability distribution $P_{\eta \mid G}$ whose support is the convex set $G$. Details of this distribution, suppressed for the time being, are given explicitly by Equations (14) and (15). [To be precise, $P_{\eta \mid G}$ should be written as $P_{\eta \mid \boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k} ; G}$. That is, $G$ is always attached with a specific set of $\boldsymbol{\theta}_{j}$ 's. Throughout the paper, this specification of $G$ is always understood but notationally suppressed to avoid cluttering.]

For each individual $i=1, \ldots, m$, let $\boldsymbol{\eta}_{i} \in \Delta^{d}$ be an independent random vector distributed by $P_{\eta \mid G}$. The observed data associated with $i, \mathcal{S}_{[n]}^{i}=\left(X_{i j}\right)_{j=1}^{n}$ are assumed to be i.i.d. draws from the multinomial distribution $\operatorname{Mult}\left(\boldsymbol{\eta}_{i}\right)$ specified by $\boldsymbol{\eta}_{i}:=\left(\eta_{i 0}, \ldots, \eta_{i d}\right)$. That is, $X_{i j} \in\{0, \ldots, d\}$ such that $P\left(X_{i j}=l \mid \boldsymbol{\eta}_{i}\right)=\eta_{i l}$ for $l=0, \ldots, d$.

Admixture models are simple when specified in a hierarchical manner as given above. The relevant distributions are written down below. The joint distribution of the generic random variable $\eta$ and $n$-vector $\mathcal{S}_{[n]}$ (dropping superscript $i$ used for indexing a specific individual) is denoted by $P_{\eta \times \mathcal{S}_{[n]} \mid G}$ and its density $p_{\eta \times \mathcal{S}_{[n]} \mid G}$. We have

$$
\begin{equation*}
p_{\eta \times \mathcal{S}_{[n]} \mid G}\left(\boldsymbol{\eta}_{i}, \mathcal{S}_{[n]}^{i}\right)=p_{\eta \mid G}\left(\boldsymbol{\eta}_{i}\right) \times \prod_{j=1}^{n} \prod_{l=0}^{d} \eta_{i l}^{\mathbb{I}\left(X_{i j}=l\right)} \tag{1}
\end{equation*}
$$

The distribution of $\mathcal{S}_{[n]}$, denoted by $P_{\mathcal{S}_{[n]} \mid G}$, is obtained by integrating out $\eta$, which yields the following density with respect to counting measure:

$$
\begin{equation*}
p_{\mathcal{S}_{[n]} \mid G}\left(\mathcal{S}_{[n]}^{i}\right)=\int_{G} \prod_{j=1}^{n} \prod_{l=0}^{d} \eta_{i l}^{\mathbb{I}\left(X_{i j}=l\right)} \mathrm{d} P_{\eta \mid G}\left(\boldsymbol{\eta}_{i}\right) \tag{2}
\end{equation*}
$$

The joint distribution of the full data set $\mathcal{S}_{[n]}^{[m]}:=\left(\mathcal{S}_{[n]}^{i}\right)_{i=1}^{m}$, denoted by $P_{\mathcal{S}_{[n]} \mid G}^{m}$, is a product distribution:

$$
\begin{equation*}
P_{\mathcal{S}_{[n]} \mid G}^{m}\left(\mathcal{S}_{[n]}^{[m]}\right):=\prod_{i=1}^{m} P_{\mathcal{S}_{[n]} \mid G}\left(\mathcal{S}_{[n]}^{i}\right) . \tag{3}
\end{equation*}
$$

Admixture models are customarily introduced in an equivalent way as follows [4,13]: For each $i=1, \ldots, m$, draw an independent random variable $\boldsymbol{\beta} \in \Delta^{k-1}$ as $\boldsymbol{\beta} \sim P_{\boldsymbol{\beta} \mid \gamma}$. Given $i$ and $\boldsymbol{\beta}$, for $j=1, \ldots, n$, draw $Z_{i j} \mid \beta \stackrel{\text { i.i.d. }}{\sim} \operatorname{Mult}(\boldsymbol{\beta}) . Z_{i j}$ takes values in $\{1, \ldots, k\}$. Now, data point $X_{i j}$ is randomly generated by $X_{i j} \mid Z_{i j}=l, \boldsymbol{\theta} \sim \operatorname{Mult}\left(\boldsymbol{\theta}_{l}\right)$. This yields the same joint distribution of $\mathcal{S}_{[n]}^{i}=\left(X_{i j}\right)_{j=1}^{n}$ as the one described earlier. The use of latent variables $Z_{i j}$ is amenable to the development of computational algorithms for inference. However, this representation bears no significance within the scope of this work.

## Asymptotic setting and metrics on population polytopes

Assume the data set $\mathcal{S}_{[n]}^{[m]}=\left(\mathcal{S}_{[n]}^{i}\right)_{i=1}^{m}$ of size $m \times n$ is generated according an admixture model given by "true" parameters $\boldsymbol{\theta}_{1}^{*}, \ldots, \boldsymbol{\theta}_{k}^{*}$. $G_{0}=\operatorname{conv}\left(\boldsymbol{\theta}_{1}^{*}, \ldots, \boldsymbol{\theta}_{k}^{*}\right)$ is the true population polytope. Under the Bayesian estimation framework, the population structure variables $\left(\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}\right)$ are random and endowed with a prior distribution $\Pi$. The main question to be addressed in this paper is the contraction behavior of the posterior distribution $\Pi\left(G \mid \mathcal{S}_{[n]}^{[m]}\right)$, as the number of data points $m \times n$ goes to infinity.

It is noted that we do not always assume that the number of extreme points of the population polytope $G_{0}$ is $k$. We work in a general overfitted setting where $k$ only serves as the upper bound of the true number of extreme points for the purpose of model parameterization. The special case in which the number of extreme points of $G_{0}$ is known a priori is also interesting and will be considered.

Let extr $G$ denote the set of extreme points of a given polytope $G . \mathcal{G}^{k}$ is the set of population polytopes in $\Delta^{d}$ such that $|\operatorname{extr} G| \leq k$. Let $\mathcal{G}^{*}=\bigcup_{2 \leq k<\infty} \mathcal{G}^{k}$ be the set of population polytopes that have finite number of extreme points in $\Delta^{d}$. A natural metric on $\mathcal{G}^{*}$ is the following "minimum-matching" Euclidean distance:

$$
d_{\mathcal{M}}\left(G, G^{\prime}\right)=\max _{\boldsymbol{\theta} \in \operatorname{extr} G} \min _{\boldsymbol{\theta}^{\prime} \in \operatorname{extr} G^{\prime}}\left\|\boldsymbol{\theta}-\boldsymbol{\theta}^{\prime}\right\| \vee \max _{\boldsymbol{\theta}^{\prime} \in \mathrm{extr} G^{\prime}} \min _{\boldsymbol{\theta} \in \mathrm{extr} G}\left\|\boldsymbol{\theta}^{\prime}-\boldsymbol{\theta}\right\|
$$

A more common metric is the Hausdorff metric:

$$
d_{\mathcal{H}}\left(G, G^{\prime}\right)=\min \left\{\varepsilon \geq 0 \mid G \subset G_{\varepsilon}^{\prime} ; G^{\prime} \subset G_{\varepsilon}\right\}=\max _{\boldsymbol{\theta} \in G} d\left(\boldsymbol{\theta}, G^{\prime}\right) \vee \max _{\boldsymbol{\theta}^{\prime} \in G^{\prime}} d\left(\boldsymbol{\theta}^{\prime}, G\right)
$$

Here, $G_{\varepsilon}=G+B_{d+1}(\mathbf{0}, \varepsilon):=\left\{\boldsymbol{\theta}+e \mid \boldsymbol{\theta} \in G, e \in \mathbb{R}^{d+1},\|e\| \leq 1\right\}$, and $d\left(\boldsymbol{\theta}, G^{\prime}\right):=\inf \{\| \boldsymbol{\theta}-$ $\left.\boldsymbol{\theta}^{\prime} \|, \boldsymbol{\theta}^{\prime} \in G^{\prime}\right\}$. Observe that $d_{\mathcal{H}}$ depends on the boundary structure of sets, while $d_{\mathcal{M}}$ depends on only extreme points. In general, $d_{\mathcal{M}}$ dominates $d_{\mathcal{H}}$, but under additional mild assumptions the two metrics are equivalent (see Lemma 1).

We introduce a notion of regularity for a family probability distributions defined on convex polytopes $G \in \mathcal{G}^{*}$. This notion is concerned with the behavior near the boundary of the support of distributions $P_{\eta \mid G}$. We say a family of distributions $\left\{P_{\eta \mid G} \mid G \in \mathcal{G}^{k}\right\}$ is $\alpha$-regular if for any $G \in \mathcal{G}^{k}$ and any $\boldsymbol{\eta}_{0} \in \operatorname{bd} G$,

$$
\begin{equation*}
P_{\eta \mid G}\left(\left\|\boldsymbol{\eta}-\boldsymbol{\eta}_{0}\right\| \leq \varepsilon\right) \geq c \varepsilon^{\alpha} \operatorname{vol}_{p}\left(G \cap B_{d+1}\left(\boldsymbol{\eta}_{0}, \varepsilon\right)\right) \tag{4}
\end{equation*}
$$

where $p$ is the number of dimensions of the affine space aff $G$ that spans $G$, constant $c>0$ is independent of $G, \eta_{0}$ and $\varepsilon$.

According to Lemma 4 (in Section 6) $\alpha$-regularity holds for a range of $\alpha$, when $P_{\boldsymbol{\beta} \mid \gamma}$ is a Dirichlet distribution, but there may be other choices. We will see that $\alpha$ plays an important role in characterize the rates of contraction for the posterior of the population polytope.

Assumptions. $\Pi$ is a prior distribution on $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$ such that the following hold for the relevant parameters that reside in the support of $\Pi$ :
(S0) Geometric properties (A1) and (A2) listed in Section 3 are satisfied uniformly for all $G$.
(S1) Each of $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$ is bounded away from the boundary of $\Delta^{d}$. That is, if $\boldsymbol{\theta}_{j}=$ $\left(\theta_{j, 0}, \ldots, \theta_{j, d}\right)$ then $\min _{l=0, \ldots, d} \theta_{j, l}>c_{0}$ for all $j=1, \ldots, k$.
(S2) For any small $\varepsilon, \Pi\left(\left\|\boldsymbol{\theta}_{j}-\boldsymbol{\theta}_{j}^{*}\right\| \leq \varepsilon \forall j=1, \ldots, k\right) \geq c_{0}^{\prime} \varepsilon^{k d}$, for some $c_{0}^{\prime}>0$.
(S3a) $P_{\beta}$ induces a family of distributions $\left\{P_{\eta \mid G} \mid G \in \mathcal{G}^{k}\right\}$ that is $\alpha$-regular.
(S3b) $\boldsymbol{\beta}=\left(\beta_{1}, \ldots, \beta_{k}\right)$ is distributed (a priori) according to a symmetric probability distribution $P_{\beta}$ on $\Delta^{k-1}$. That is, the random variables $\beta_{1}, \ldots, \beta_{k}$ are a priori exchangeable.

Theorem 1. Let $G_{0} \in \mathcal{G}^{k}$ and $G_{0}$ is in the support of prior $\Pi$. Let $p=(k-1) \wedge d$. Under assumptions (S0)-(S3) of the admixture model, as $m \rightarrow \infty$ and $n \rightarrow \infty$ such as $\log \log m \leq$ $\log n=\mathrm{o}(m)$, for some sufficiently large constant $C$ independent of $m$ and $n$,

$$
\begin{equation*}
\Pi\left(d_{\mathcal{M}}\left(G_{0}, G\right) \geq C \delta_{m, n} \mid \mathcal{S}_{[n]}^{[m]}\right) \longrightarrow 0 \tag{5}
\end{equation*}
$$

in $P_{\mathcal{S}_{[n]} \mid G_{0}}^{m}$-probability. Here,

$$
\delta_{m, n}=\left[\frac{\log m}{m}+\frac{\log n}{n}+\frac{\log n}{m}\right]^{1 /(2(p+\alpha))} .
$$

The same statement holds for the Hausdorff metric $d_{\mathcal{H}}$.

## Remarks.

1. Geometric assumption (S0) and its consequences are presented in the next section. (S0), (S1) and (S2) are mild assumptions observed in practice (cf. [4,13]).
2. The assumption in (S3b) that $P_{\boldsymbol{\beta}}$ is symmetric is relatively strong, but it has been widely adopted in practice (e.g., symmetric Dirichlet distributions, including the uniform distribution). This technical condition is not intrinsic to the theory, and is required only to establish an upper bound of the Kullback-Leibler distance in terms of Hausdorff distance. In fact, it may be replaced if such an upper bound can be established by some other means. See also the remark following the statement of Lemma 7.
3. In practice, $P_{\boldsymbol{\beta}}$ may be further parameterized as $P_{\boldsymbol{\beta} \mid \gamma}$, where $\gamma$ is endowed with a prior distribution. Then, it would be of interest to also study the posterior contraction behavior for $\gamma$. In this paper, we have opted to focus only on convergence behavior of the population structure to simplify the exposition and the results.
4. The appearance of both $m^{-1}$ and $n^{-1}$ in the contraction rate suggests that if either $m$ or $n$ is small, the rate would suffer even if the total amount of data $m \times n$ increases. What is quite interesting is the appearance of $\log n / m$. This is rooted in an entropy condition (cf. Theorem 4 in Section 4), which requires an upper bound of the KL divergence in terms of Hausdorff distance. It is possible that the appearance of $\log n / m$ is due to our general proof technique of posterior contraction presented in Section 4. From a hierarchical modeling viewpoint, this result highlights an interesting interaction of sample sizes provided to different levels in the model hierarchy. This issue has not been widely discussed in the hierarchical modeling literature in a theoretical manner, to the best of our knowledge.
5. Note the constraints that $n>\log m$ and $\log n=\mathrm{o}(m)$ are required in order to obtain rates of posterior contraction. These constraints are related to the term $\log n / m$ mentioned above they stem from the upper bound on Kullback-Leibler in Lemma 6. The remark following the statement of this lemma explains why the upper bound almost always grows with $n$. A very special situation is presented in Lemma 5 where an upper bound on KullbackLeibler distance can be obtained that is independent of $n$. However, such a situation cannot be verified in any reasonable estimation setting. This suggests that with our proof technique, we almost always require $n$ to grow at a constrained rate relatively to $m$ in order to obtain posterior contraction rates.
6. Constant $\alpha$ plays an important role in the rate exponent. Intuitively, the larger $\alpha$ is, the weaker the guaranteed probability mass accrued near the boundary of the population polytope, which implies less data observed for points located near the boundary. This entails a weaker guarantee on the rate of convergence. Indeed, a key step in the proof of the theorem is that Equation (4) enables us to transfer an upper bound on the diminishing variational distance between, say distributions $P_{\eta \mid G}$ and $P_{\eta \mid G^{\prime}}$, to an upper bound on the Hausdorff distance between $G$ and $G^{\prime}$, while incurring an extra term $\alpha$ in the exponent.
7. The exponent $\frac{1}{2(p+\alpha)}$ suggests a slow, nonparametric-like convergence rate. Moreover, later in Theorem 3 we show that this is qualitatively quite close to a minimax lower bound. On the other hand, the following theorem shows that it is possible to achieve a parametric rate if additional constraints are imposed on the true $G_{0}$ and/or the prior $\Pi$ :

Theorem 2. Let $G_{0} \in \mathcal{G}^{k}$ and $G_{0}$ is in the support of prior $П$. Assume $(\mathrm{S} 0)-(\mathrm{S} 3 \mathrm{a})$, ( S 3 b ), and either one of the following two conditions hold:
(a) $\mid$ extr $G_{0} \mid=k$, or
(b) There is a known constant $r_{0}>0$ such that the pairwise distances of the extreme points of all $G$ in the support of the prior are bounded from below by $r_{0}$.

Then, as $m \rightarrow \infty$ and $n \rightarrow \infty$ such that $\log m<n$ and $\log n=\mathrm{o}(m)$, Equation (5) holds with

$$
\delta_{m, n}=\left[\frac{\log m}{m}+\frac{\log n}{n}+\frac{\log n}{m}\right]^{1 /(2(1+\alpha))}
$$

The same statement holds for the Hausdorff metric $d_{\mathcal{H}}$.
The next theorem produces minimax lower bounds that are qualitatively quite similar to the nonparametric-like rates obtained in Theorem 1. In the following theorem, $\boldsymbol{\eta}$ is not parameterized
by $\boldsymbol{\beta}$ and $\boldsymbol{\theta}_{j}$ 's as in the admixture model. Instead, we shall simply replace assumptions (S3a) and (S3b) on $P_{\beta \mid \gamma}$ by either one of the following assumptions on $P_{\eta \mid G}$ :
(S4) There is a non-negative constant $\alpha^{\prime}$ such that for any pair of $p$-dimensional polytopes $G^{\prime} \subset G$ that satisfy Property A1,

$$
V\left(P_{\eta \mid G}, P_{\eta \mid G^{\prime}}\right) \lesssim d_{\mathcal{H}}\left(G, G^{\prime}\right)^{\alpha^{\prime}} \operatorname{vol}_{p} G \backslash G^{\prime} .
$$

( $\mathrm{S} 4^{\prime}$ ) For any $p$-dimensional polytope $G, P_{\eta \mid G}$ is the uniform distribution on $G$.
Note that the condition of $\alpha$-regularity (cf. Equation (4)) implies that $\alpha \geq \alpha^{\prime}$. In particular, if $\left(\mathrm{S} 4^{\prime}\right)$ is satisfied, then both (S3a)/(S3b) and (S4) hold with $\alpha=\alpha^{\prime}=0$.

Since a parameterization for $\eta$ is not needed, the overall model can be simplified as follows: Given population polytope $G \in \Delta^{d}$, for each $i=1, \ldots, m$, draw $\eta_{i} \stackrel{\text { i.i.d. }}{\sim} P_{\eta \mid G}$. For each $j=$ $1, \ldots, n$, draw $\mathcal{S}_{[n]}^{i}=\left(X_{i j}\right)_{j=1}^{n} \stackrel{\text { i.i.d. }}{\sim} \operatorname{Mult}\left(\boldsymbol{\eta}_{\boldsymbol{i}}\right)$.

Theorem 3. Suppose that $G_{0} \in \mathcal{G}^{k}$ satisfies assumptions (S0), (S1) and (S2). Point estimates $\hat{G}=\hat{G}\left(\mathcal{S}_{[n]}^{[m]}\right)$ take value in the set $\mathcal{G}^{*}$. In the following, the multiplying constants in $\gtrsim$ depend only on constants specified by these assumptions.
(a) Let $q=\lfloor k / 2\rfloor \wedge d$. Under assumption (S4), we have

$$
\inf _{\hat{G} \in \mathcal{G}^{*}} \sup _{G_{0} \in \mathcal{G}^{k}} P_{\mathcal{S}_{[n]} \mid G_{0}}^{m} d_{\mathcal{H}}\left(G_{0}, \hat{G}\right) \gtrsim\left(\frac{1}{m n}\right)^{1 /\left(q+\alpha^{\prime}\right)}
$$

(b) Let $q=\lfloor k / 2\rfloor \wedge d$. Under assumption ( $\mathbf{S}^{\prime}$ ), we have

$$
\inf _{\hat{G} \in \mathcal{G}^{*}} \sup _{G_{0} \in \mathcal{G}^{k}} P_{\mathcal{S}_{[n]} \mid G_{0}}^{m} d_{\mathcal{H}}\left(G_{0}, \hat{G}\right) \gtrsim\left(\frac{1}{m}\right)^{1 / q}
$$

(c) Assume (S4), and that either condition (a) or (b) of Theorem 2 holds, then

$$
\inf _{\hat{G} \in \mathcal{G}^{*}} \sup _{G_{0} \in \mathcal{G}^{k}} P_{\mathcal{S}_{[n]} \mid G_{0}}^{m} d_{\mathcal{H}}\left(G_{0}, \hat{G}\right) \gtrsim\left(\frac{1}{m n}\right)^{1 /\left(1+\alpha^{\prime}\right)}
$$

Furthermore, if (S4) is replaced by (S4'), the lower bound becomes $1 / m$.

## Remarks.

1. There is a gap between the posterior contraction rate in Theorem 1 and the minimax lower bound in Theorem 3(a). This is expected because the infimum over point estimates $\hat{G}$ is taken over $\mathcal{G}^{*}$, as opposed to $\mathcal{G}^{k}$. Nonetheless, the lower bounds are notably dependent on $d$ and $k$, thereby provide a partial justification for the nonparametics-like posterior contraction rates. It is interesting to note that if $k \geq 2 d \gg \alpha$, and allowing $m \asymp n$, the rate exponents differ approximately by only a factor of 4 . That is, $m^{-1 / 2(d+\alpha)}$ vis-à-vis $m^{-2 /\left(d+\alpha^{\prime}\right)}$.
2. The nonparametrics-like lower bounds in part (a) and (b) in the overfitted setting are somewhat surprising even if $P_{\boldsymbol{\beta}}$ is known exactly (e.g., $P_{\boldsymbol{\beta}}$ is uniform distribution). Since we are more likely to be in the overfitted setting than knowing the exact number of extreme points, an implication of this is that it is important in practice to impose a lower bound on the pairwise distances between the extreme points of the population polytope.
3. The results in part (b) and (c) under assumption ( $\mathrm{S} 4^{\prime}$ ) present an interesting scenario in which the obtained lower bounds do not depend on $n$, which determines the amount of data at the bottom level in the model hierarchy.

## 3. Geometric assumptions and basic lemmas

In this section, we discuss the geometric assumptions postulated in the main theorems, and describe their consequences using elementary arguments in convex geometry of Euclidean spaces. These results relate Hausdorff metric, the minimum-matching metric, and the volume of the settheoretic difference of polytopes. These relationships prove crucial in obtaining explicit posterior contraction rates. Here, we state the properties and prove the results for $p$-dimensional polytopes and convex bodies of points in $\Delta^{d}$, for a given $p \leq d$. (Convex bodies are bounded convex sets that may have an unbounded number of extreme points. Within this section, the detail of the ambient space is irrelevant. For instance, $\Delta^{d}$ may be replaced by $\mathbb{R}^{d+1}$ or a higher dimensional Euclidean space.)

Property A1 (Property of thick body). For some $r, R>0, \boldsymbol{\theta}_{c} \in \Delta^{d}$, $G$ contains the spherical ball $B_{p}\left(\boldsymbol{\theta}_{c}, r\right)$ and is contained in $B_{p}\left(\boldsymbol{\theta}_{c}, R\right)$.

Property A2 (Property of non-obtute corners). For some small $\delta>0$, at each vertex of $G$ there is a supporting hyperplane whose angle formed with any edges adjacent to that vertex is bounded from below by $\delta$.

We state key geometric lemmas that will be used throughout the paper. Bounds such as those given by Lemma 2 are probably well-known in the folklore of convex geometry (for instance, part (b) of that lemma is similar to (but not precisely the same as) Lemma 2.3.6. from [15]). Due to the absence of direct references, we include the proof of this and other lemmas in the Appendix.

## Lemma 1.

(a) $d_{\mathcal{H}}\left(G, G^{\prime}\right) \leq d_{\mathcal{M}}\left(G, G^{\prime}\right)$.
(b) If the two polytopes $G, G^{\prime}$ satisfy Property A2, then $d_{\mathcal{M}}\left(G, G^{\prime}\right) \leq C_{0} d_{\mathcal{H}}\left(G, G^{\prime}\right)$, for some positive constant $C_{0}>0$ depending only on $\delta$.

According to part (b) of this lemma, convergence of a sequence of convex polytope $G \in \mathcal{G}^{k}$ to $G_{0} \in \mathcal{G}^{k}$ in Hausdorff metric entails the convergence of the extreme points of $G$ to those of $G_{0}$. Moreover, they share the same rate as the Hausdorff convergence.

Lemma 2. There are positive constants $C_{1}$ and $c_{1}$ depending only on $r, R, p$ such that for any two p-dimensional convex bodies $G, G^{\prime}$ satisfying Property A1:
(a) $\operatorname{vol}_{p} G \triangle G^{\prime} \geq c_{1} d_{\mathcal{H}}\left(G, G^{\prime}\right)^{p}$.
(b) $\operatorname{vol}_{p} G \triangle G^{\prime} \leq C_{1} d_{\mathcal{H}}\left(G, G^{\prime}\right)$.

Remark. The exponents in both bounds in Lemma 2 are attainable. Indeed, for the lower bound in part (a), consider a fixed convex polytope $G$. For each vertex $\boldsymbol{\theta}_{i} \in G$, consider point $x$ that lie on edges incident to $\boldsymbol{\theta}_{i}$ such that $\left\|x-\boldsymbol{\theta}_{i}\right\|=\varepsilon$. Let $G^{\prime}$ be the convex hull of all such $x$ 's and the remaining vertices of $G$. Clearly, $d_{\mathcal{H}}\left(G, G^{\prime}\right)=\mathrm{O}(\varepsilon)$, and $\operatorname{vol}_{p} G \backslash G^{\prime} \leq \mathrm{O}\left(\varepsilon^{p}\right)$. Thus, for the collection of convex polytopes $G^{\prime}$ constructed in this way, $\operatorname{vol}_{p}\left(G \triangle G^{\prime}\right) \asymp d_{\mathcal{H}}\left(G, G^{\prime}\right)^{p}$. The upper bound in part (b) is also tight for a broad class of convex polytopes, as exemplified by the following lemma.

Lemma 3. Let $G$ be a fixed polytope and $|\operatorname{extr} G|=k<\infty . G^{\prime}$ an arbitrary polytope in $\mathcal{G}^{*}$. Moreover, either one of the following conditions holds:
(a) $\left|\operatorname{extr} G^{\prime}\right|=k$, or
(b) The pairwise distances between the extreme points of $G^{\prime}$ is bounded away from a constant $r_{0}>0$.
Then, there is a positive constant $\varepsilon_{0}=\varepsilon_{0}(G)$ depending only on $G$, a positive constant $c_{2}=$ $c_{2}(G)$ in case (a) and $c_{2}=c_{2}\left(G, r_{0}\right)$ in case (b), such that

$$
\operatorname{vol}_{p} G \triangle G^{\prime} \geq c_{2} d_{\mathcal{H}}\left(G, G^{\prime}\right)
$$

as soon as $d_{\mathcal{H}}\left(G, G^{\prime}\right) \leq \varepsilon_{0}(G)$.
Remark. We note that the bound obtained in this lemma is substantially stronger than the one obtained by Lemma 2 part (a). This is due to the asymmetric roles of $G$, which is held fixed, and $G^{\prime}$, which can vary. As a result, constant $c_{2}$ as stated in the present lemma is independent of $G^{\prime}$ but allowed to be dependent on $G$. By contrast, constant $c_{1}$ in Lemma 2 part (a) is independent of both $G$ and $G^{\prime}$.

## 4. An abstract posterior contraction theorem

In this section, we state an abstract posterior contraction theorem for hierarchical models, whose proof is given in the Appendix. The setting of this theorem is a general hierarchical model defined as follows

$$
\begin{aligned}
G & \sim \Pi, & \eta_{1}, \ldots, \boldsymbol{\eta}_{m} \mid G \sim P_{\eta \mid G} \\
\mathcal{S}_{[n]}^{i} \mid \boldsymbol{\eta}_{i} & \sim P_{\mathcal{S}_{[n]} \mid \eta_{i}} & \text { for } i=1, \ldots, m .
\end{aligned}
$$

The detail of conditional distributions in above specifications is actually irrelevant. Thus, results in this section may be of general interest for hierarchical models with $m \times n$ data.

As before $p_{\mathcal{S}_{[n]} \mid G}$ is marginal density of the generic $\mathcal{S}_{[n]}$ which is obtained by integrating out the generic random vector $\boldsymbol{\eta}$ (e.g., see Equation (2)). We need several key notions. Define the Hausdorff ball as:

$$
B_{d_{\mathcal{H}}}\left(G_{1}, \delta\right):=\left\{G \in \Delta^{d}: d_{\mathcal{H}}\left(G_{1}, G\right) \leq \delta\right\} .
$$

A useful quantity for proving posterior concentration theorems is the Hellinger information of Hausdorff metric for a given set:

Definition 1. Fix $G_{0} \in \mathcal{G}^{*}$. For a fixed $n$, the sample size of $\mathcal{S}_{[n]}$, define the Hellinger information of $d_{\mathcal{H}}$ metric for set $\mathcal{G} \subset \mathcal{G}^{*}$ as a real-valued function on the positive reals $\Psi_{\mathcal{G}, n}: \mathbb{R}_{+} \rightarrow \mathbb{R}$ :

$$
\begin{equation*}
\Psi_{\mathcal{G}, n}(\delta):=\inf _{G \in \mathcal{G} ; d_{\mathcal{H}}\left(G_{0}, G\right) \geq \delta / 2} h^{2}\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G}\right) \tag{6}
\end{equation*}
$$

We also define $\Phi_{\mathcal{G}, n}: \mathbb{R}_{+} \rightarrow \mathbb{R}$ to be an arbitrary non-negative valued function on the positive reals such that for any $\delta>0$,

$$
\sup _{G, G^{\prime} \in \mathcal{G} ; d_{\mathcal{H}}\left(G, G^{\prime}\right) \leq \Phi_{\mathcal{G}, n}(\delta)} h^{2}\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) \leq \Psi_{\mathcal{G}, n}(\delta) / 4
$$

In both definitions of $\Phi$ and $\Psi$, we suppress the dependence on (the fixed) $G_{0}$ to simplify notations. Note that if $G_{0} \in \mathcal{G}$, it follows from the definition that $\Phi_{\mathcal{G}, n}(\delta)<\delta / 2$.

Remark. Suppose that conditions of Lemma 7(b) hold, so that

$$
h^{2}\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) \leq K\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) \leq \frac{n}{c_{0}} C_{0} d_{\mathcal{H}}\left(G, G^{\prime}\right)
$$

Then it suffices to choose $\Phi_{\mathcal{G}, n}(\delta)=\frac{c_{0}}{4 n C_{0}} \Psi_{\mathcal{G}, n}(\delta)$.
Define the neighborhood of the prior support around $G_{0}$ in terms of Kullback-Leibler distance of the marginal densities $p_{\mathcal{S}_{[n]} \mid G}$ :

$$
\begin{equation*}
B_{K}\left(G_{0}, \delta\right)=\left\{G \in \mathcal{G}^{*} \mid K\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G}\right) \leq \delta^{2} ; K_{2}\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G}\right) \leq \delta^{2}\right\} . \tag{7}
\end{equation*}
$$

Theorem 4. Let $\mathcal{G}$ denote the support of the prior $\Pi$. Fix $G_{0} \in \mathcal{G}$ and suppose that
(a) $m \rightarrow \infty$ and $n \rightarrow \infty$ at a certain rate relative to $m$.
(b) There is a large constant $C$, a sequence of scalars $\varepsilon_{m, n} \rightarrow 0$ defined in terms of $m$ and $n$ such that $m \varepsilon_{m, n}^{2}$ tends to infinity, such that

$$
\begin{align*}
& \sup _{G_{1} \in \mathcal{G}} \log D\left(\Phi_{\mathcal{G}, n}(\varepsilon), \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \varepsilon / 2\right), d_{\mathcal{H}}\right) \\
& \quad \quad+\log D\left(\varepsilon / 2, \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{0}, 2 \varepsilon\right) \backslash B_{d_{\mathcal{H}}}\left(G_{0}, \varepsilon\right), d_{\mathcal{H}}\right) \leq m \varepsilon_{m, n}^{2}  \tag{8}\\
& \quad \forall \varepsilon \geq \varepsilon_{m, n} \\
& \Pi\left(B_{K}\left(G_{0}, \varepsilon_{m, n}\right)\right) \geq \exp \left[-m \varepsilon_{m, n}^{2} C\right] \tag{9}
\end{align*}
$$

(c) There is a sequence of positive scalars $M_{m}$ such that

$$
\begin{gather*}
\Psi_{\mathcal{G}, n}\left(M_{m} \varepsilon_{m, n}\right) \geq 8 \varepsilon_{m, n}^{2}(C+4)  \tag{10}\\
\exp \left(2 m \varepsilon_{m, n}^{2}\right) \sum_{j \geq M_{m}} \exp \left[-m \Psi_{\mathcal{G}, n}\left(j \varepsilon_{m, n}\right) / 8\right] \rightarrow 0 \tag{11}
\end{gather*}
$$

Then, $\Pi\left(G: d_{\mathcal{H}}\left(G_{0}, G\right) \geq M_{m} \varepsilon_{m, n} \mid \mathcal{S}_{[n]}^{[m]}\right) \rightarrow 0$ in $P_{\mathcal{S}_{[n]} \mid G_{0}}^{m}$-probability as $m$ and $n \rightarrow \infty$.
Condition (8) is referred to as entropy condition for certain sets in the support of the prior. Condition (9) is concerned with the "thickness" of the prior as measured by the Kullback-Leibler distance (see also [7]). Conditions (10) and (11) are related to the Hellinger information function (see also [12]). The proof of this theorem is deferred to the Appendix. As noted above, this result is applicable to any hierarchical models for $m \times n$ data. The choice of Hausdorff metric $d_{\mathcal{H}}$ is arbitrary here, and can be replaced by any other valid metric (e.g., $d_{\mathcal{M}}$ ). The remainder of the paper is devoted to verifying the conditions of this theorem so it can be applied. These conditions hinge on our having established a lower bound for the Hellinger information function $\Psi_{\mathcal{G}, n}(\cdot)$ (via Theorem 5), and a lower bound for the prior probability defined on Kullback-Leibler balls $B_{K}\left(G_{0}, \cdot\right)$ (via Theorem 6). Both types of results are obtained by utilizing the convex geometry lemmas described in the previous section.

## 5. Inequalities for the Hausdorff distance

The following results guarantee that as marginal densities of $\mathcal{S}_{[n]}$ get closer in total variation distance metric (or Hellinger metric), so do the corresponding population polytopes in Hausdorff metric (or minimum matching metric). This gives a lower bound for the Hellinger information defined by Equation (6), because $h$ is related to $V$ via inequality $h \geq V$.

## Theorem 5.

(a) Let $G, G^{\prime}$ be two convex bodies in $\Delta^{d}$. $G$ is a p-dimensional body containing spherical ball $B_{p}\left(\boldsymbol{\theta}_{c}, r\right)$, while $G^{\prime}$ is $p^{\prime}$-dimensional body containing $B_{p^{\prime}}\left(\boldsymbol{\theta}_{c}, r\right)$ for some $p, p^{\prime} \leq$ $d, r>0, \boldsymbol{\theta}_{c} \in \Delta^{d}$. In addition, assume that both $p_{\eta \mid G}$ and $p_{\eta \mid G^{\prime}}$ are $\alpha$-regular densities on $G$ and $G^{\prime}$, respectively. Then, there is $c_{1}>0$ independent of $G, G^{\prime}$ such that

$$
c_{1} d_{\mathcal{H}}\left(G, G^{\prime}\right)^{\left(p \vee p^{\prime}\right)+\alpha} \leq V\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right)+6(d+1) \exp \left[-\frac{n}{8(d+1)} d_{\mathcal{H}}\left(G, G^{\prime}\right)^{2}\right]
$$

(b) Assume further that $G$ is fixed convex polytope, $G^{\prime}$ an arbitrary polytope, $p^{\prime}=p$, and that either $\left|\operatorname{extr} G^{\prime}\right|=|\operatorname{extr} G|$ or the pairwise distances of extreme points of $G^{\prime}$ is bounded from below by a constant $r_{0}>0$. Then, there are constants $c_{2}, C_{3}>0$ depending only on $G$ and $r_{0}$ (and independent of $G^{\prime}$ ) such that

$$
c_{2} d_{\mathcal{H}}\left(G, G^{\prime}\right)^{1+\alpha} \leq V\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right)+6(d+1) \exp \left[-\frac{n}{C_{3}(d+1)} d_{\mathcal{H}}\left(G, G^{\prime}\right)^{2}\right]
$$

Remark. Part (a) holds for varying pairs of $G, G^{\prime}$ satisfying certain conditions. It is consequence of Lemma 2(a). Part (b) produces a tighter bound, but it holds only for a fixed $G$, while $G^{\prime}$ is allowed to vary while satisfying certain conditions. This is a consequence of Lemma 3. Constants $c_{1}, c_{2}$ are the same as those from Lemmas 2(a) and 3, respectively.

Proof of Theorem 5. (a) The main idea of the proof is the construction of a suitable test set in order to distinguish $p_{\mathcal{S}_{[n]} \mid G^{\prime}}$ from $p_{\mathcal{S}_{[n]} \mid G}$. The proof is organized as a sequence of steps.
Step 1. Given a data vector $\mathcal{S}_{[n]}=\left(X_{1}, \ldots, X_{n}\right)$, define $\hat{\boldsymbol{\eta}}(\mathcal{S}) \in \Delta^{d}$ such that the $i$-element of $\hat{\boldsymbol{\eta}}(\mathcal{S})$ is $\frac{1}{n} \sum_{j=1}^{n} \mathbb{I}\left(X_{j}=i\right)$ for each $i=0, \ldots, d$. In the following, we simply use $\hat{\boldsymbol{\eta}}$ to ease the notations. By the definition of the variational distance,

$$
\begin{equation*}
V\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right)=\sup _{A}\left|P_{\mathcal{S}_{[n]} \mid G}(\hat{\boldsymbol{\eta}} \in A)-P_{\mathcal{S}_{[n]} \mid G^{\prime}}(\hat{\boldsymbol{\eta}} \in A)\right|, \tag{12}
\end{equation*}
$$

where the supremum is taken over all measurable subsets of $\Delta^{d}$.
Step 2. Fix a constant $\varepsilon>0$. By Hoeffding's inequality and the union bound, under the conditional distribution $P_{\mathcal{S}_{[\eta]} \mid \eta}$,

$$
P_{\mathcal{S}_{[n]} \mid \eta}\left(\max _{i=0, \ldots, d}\left|\hat{\eta}_{i}-\eta_{i}\right| \geq \varepsilon\right) \leq 2(d+1) \exp \left(-2 n \varepsilon^{2}\right)
$$

with probability one (as $\eta$ is random). It follows that

$$
\begin{aligned}
P_{\eta \times \mathcal{S}_{[n]} \mid G}(\|\hat{\boldsymbol{\eta}}-\eta\| \geq \varepsilon) & \leq P_{\eta \times \mathcal{S}_{[n]} \mid G}\left(\max _{i=0, \ldots, d}\left|\hat{\eta}_{i}-\eta_{i}\right| \geq \varepsilon(d+1)^{-1 / 2}\right) \\
& \leq 2(d+1) \exp \left[-2 n \varepsilon^{2} /(d+1)\right]
\end{aligned}
$$

The same bound holds under $P_{\eta \times \mathcal{S}_{[n]} \mid G^{\prime}}$.
Step 3. Define event $B=\{\|\hat{\boldsymbol{\eta}}-\boldsymbol{\eta}\|<\varepsilon\}$. Take any (measurable) set $A \subset \Delta^{d}$,

$$
\begin{align*}
& \left|P_{\mathcal{S}_{[n]} \mid G}(\hat{\boldsymbol{\eta}} \in A)-P_{\mathcal{S}_{[n]} \mid G^{\prime}}(\hat{\boldsymbol{\eta}} \in A)\right| \\
& =\mid \\
& \quad \mid P_{\eta \times \mathcal{S}_{[n]} \mid G}(\hat{\boldsymbol{\eta}} \in A ; B)+P_{\eta \times \mathcal{S}_{[n]} \mid G}\left(\hat{\boldsymbol{\eta}} \in A ; B^{C}\right)  \tag{13}\\
& \quad-P_{\eta \times \mathcal{S}_{[n] \mid} G^{\prime}}(\hat{\boldsymbol{\eta}} \in A ; B)-P_{\eta \times \mathcal{S}_{[n]} \mid G^{\prime}}\left(\hat{\boldsymbol{\eta}} \in A ; B^{C}\right) \mid \\
& \geq \\
& \geq \\
& \quad\left|P_{\eta \times \mathcal{S}_{[n]} \mid G}(\hat{\boldsymbol{\eta}} \in A ; B)-P_{\eta \times \mathcal{S}_{[n]} \mid G^{\prime}}(\hat{\boldsymbol{\eta}} \in A ; B)\right| \\
& \quad-4(d+1) \exp \left[-2 n \varepsilon^{2} /(d+1)\right] .
\end{align*}
$$

Step 4. Let $\varepsilon_{1}=d_{\mathcal{H}}\left(G, G^{\prime}\right) / 4$. For any $\varepsilon \leq \varepsilon_{1}$, recall the outer $\varepsilon$-parallel set $G_{\varepsilon}=(G+$ $B_{d+1}(\mathbf{0}, \varepsilon)$ ), which is full-dimensional $(d+1)$ even though $G$ may not be. By triangular inequality, $d_{\mathcal{H}}\left(G_{\varepsilon}, G_{\varepsilon}^{\prime}\right) \geq d_{\mathcal{H}}\left(G, G^{\prime}\right) / 2$. We shall argue that for any $\varepsilon \leq \varepsilon_{1}$, there is a constant $c_{1}>0$ independent of $G, G^{\prime}, \varepsilon$ and $\varepsilon_{1}$ such that either one of the two scenarios holds:
(i) There is a set $A^{*} \subset G \backslash G^{\prime}$ such that $A_{\varepsilon}^{*} \cap G_{\varepsilon}^{\prime}=\varnothing$ and $\operatorname{vol}_{p}\left(A^{*}\right) \geq c_{1} \varepsilon_{1}^{p}$, or
(ii) There is a set $A^{*} \subset G^{\prime} \backslash G$ such that $A_{\varepsilon}^{*} \cap G_{\varepsilon}=\varnothing$ and $\operatorname{vol}_{p^{\prime}}\left(A^{*}\right) \geq c_{1} \varepsilon_{1}^{p^{\prime}}$.

Indeed, since $\varepsilon \leq d_{\mathcal{H}}\left(G, G^{\prime}\right) / 4$, either one of the following two inequalities holds: $d_{\mathcal{H}}(G \backslash$ $\left.G_{3 \varepsilon}^{\prime}, G^{\prime}\right) \geq d_{\mathcal{H}}\left(G, G^{\prime}\right) / 4$ or $d_{\mathcal{H}}\left(G^{\prime} \backslash G_{3 \varepsilon}, G\right) \geq d_{\mathcal{H}}\left(G, G^{\prime}\right) / 4$. If the former inequality holds, let $A^{*}=G \backslash G_{3 \varepsilon}^{\prime}$. Then, $A^{*} \subset G \backslash G^{\prime}$ and $A_{\varepsilon}^{*} \cap G_{\varepsilon}^{\prime}=\varnothing$. Moreover, by Lemma 2(a), $\operatorname{vol}_{p}\left(A^{*}\right) \geq$ $c_{1} \varepsilon_{1}^{p}$, for some constant $c_{1}>0$ independent of $\varepsilon, \varepsilon_{1}, G, G^{\prime}$, so $A^{*}$ satisfies (i). In fact, using the same argument as in the proof of Lemma 2(a) there is a point $x \in \operatorname{bd} G$ such that $G^{\prime} \cap B_{p}\left(x, \varepsilon_{1}\right)=$ $\varnothing$. Combined with the $\alpha$-regularity of $P_{\eta \mid G}$, we have $P_{\eta \mid G}\left(A^{*}\right) \geq \varepsilon^{\alpha} \operatorname{vol}_{p}\left(G \cap B_{p}\left(x, \varepsilon_{1}\right)\right) \geq$ $c_{1} \varepsilon^{p+\alpha}$ for some constant $c_{1}>0$. If the latter inequality holds, the same argument applies by defining $A^{*}=G^{\prime} \backslash G_{3 \varepsilon}$ so that (ii) holds.
Step 5. Suppose that (i) holds for the chosen $A^{*}$. This means that $P_{\eta \times \mathcal{S}_{[n]} \mid G^{\prime}}\left(\hat{\boldsymbol{\eta}} \in A_{\varepsilon}^{*} ; B\right) \leq$ $P_{\eta \mid G^{\prime}}\left(\boldsymbol{\eta} \in A_{2 \varepsilon}^{*}\right)=0$, since $A_{2 \varepsilon}^{*} \cap G^{\prime}=\varnothing$, which is a consequence of $A_{\varepsilon}^{*} \cap G_{\varepsilon}^{\prime}=\varnothing$. In addition,

$$
\begin{aligned}
P_{\eta \times \mathcal{S}_{[n]} \mid G}\left(\hat{\boldsymbol{\eta}} \in A_{\varepsilon}^{*} ; B\right) & \geq P_{\eta \times \mathcal{S}_{[n]} \mid G}\left(\eta \in A^{*} ; B\right) \\
& \geq P_{\eta \mid G}\left(A^{*}\right)-P_{\eta \times \mathcal{S}_{[n]} \mid G}\left(B^{C}\right) \\
& \geq P_{\eta \mid G}\left(A^{*}\right)-2(d+1) \exp \left(-2 n \varepsilon^{2} /(d+1)\right) \\
& \geq c_{1} \varepsilon_{1}^{p+\alpha}-2(d+1) \exp \left(-2 n \varepsilon^{2} /(d+1)\right) .
\end{aligned}
$$

Hence, by Equation (13) $\left|P_{\mathcal{S}_{[n]} \mid G}\left(\hat{\boldsymbol{\eta}} \in A_{\varepsilon}^{*}\right)-P_{\mathcal{S}_{[n]} \mid G^{\prime}}\left(\hat{\boldsymbol{\eta}} \in A_{\varepsilon}^{*}\right)\right| \geq c_{1} \varepsilon_{1}^{p+\alpha}-6(d+1) \exp \left(-2 n \varepsilon^{2}\right)$. Set $\varepsilon=\varepsilon_{1}$, the conclusion then follows by invoking Equation (12). The scenario of (ii) proceeds in the same way.
(b) Under the condition that the pairwise distances of extreme points of $G^{\prime}$ are bounded from below by $r_{0}>0$, the proof is very similar to part (a), by invoking Lemma 3. Under the condition that $\mid$ extr $G^{\prime} \mid=k$, the proof is also similar, but it requires a suitable modification for the existence of set $A^{*}$. For any small $\varepsilon$, let $\tilde{G}_{\varepsilon}$ be the minimum-volume homethetic transformation of $G$, with respect to center $\boldsymbol{\theta}_{c}$, such that $\tilde{G}_{\varepsilon}$ contains $G_{\varepsilon}$. Since $B_{p}\left(\boldsymbol{\theta}_{c}, r\right) \subset G \subset B_{p}\left(\boldsymbol{\theta}_{c}, R\right)$ for $R=1$, it is simple to see that $d_{\mathcal{H}}\left(G, \tilde{G}_{\varepsilon}\right) \leq \varepsilon R / r=\varepsilon / r$.

Set $\varepsilon_{1}=d_{\mathcal{H}}\left(G, G^{\prime}\right) r / 4$. We shall argue that for any $\varepsilon \leq \varepsilon_{1}$, there is a constant $c_{0}>0$ independent of $G^{\prime}, \varepsilon$ and $\varepsilon_{1}$ such that either one of the following two scenarios hold:
(iii) There is a set $A^{*} \subset G \backslash G^{\prime}$ such that $A_{\varepsilon}^{*} \cap G_{\varepsilon}^{\prime}=\varnothing$ and $\operatorname{vol}_{p}\left(A^{*}\right) \geq c_{2} \varepsilon_{1}$, or
(iv) There is a set $A^{*} \subset G^{\prime} \backslash G$ such that $A_{\varepsilon}^{*} \cap G_{\varepsilon}=\varnothing$ and $\operatorname{vol}_{p}\left(A^{*}\right) \geq c_{2} \varepsilon_{1}$.

Indeed, note that either one of the following two inequalities holds: $d_{\mathcal{H}}\left(G \backslash \tilde{G}_{3 \varepsilon}^{\prime}, G^{\prime}\right) \geq$ $d_{\mathcal{H}}\left(G, G^{\prime}\right) / 4$ or $d_{\mathcal{H}}\left(G^{\prime} \backslash \tilde{G}_{3 \varepsilon}, G\right) \geq d_{\mathcal{H}}\left(G, G^{\prime}\right) / 4$. If the former inequality holds, let $A^{*}=$ $G \backslash \tilde{G}_{3 \varepsilon}^{\prime}$. Then, $A^{*} \subset G \backslash G^{\prime}$ and $A_{\varepsilon}^{*} \cap \tilde{G}_{\varepsilon}^{\prime}=\varnothing$. Observe that both $G$ and $\tilde{G}_{3 \varepsilon}^{\prime}$ have the same number of extreme points by the construction. Moreover, $G$ is fixed so that all geometric Properties A2, A1 are satisfied for both $G$ and $\tilde{G}_{3 \varepsilon}^{\prime}$ for sufficiently small $d_{\mathcal{H}}\left(G, G^{\prime}\right)$. By Lemma 3, $\operatorname{vol}_{p}\left(A^{*}\right) \geq c_{2} \varepsilon_{1}$. Hence, (iii) holds. If the latter inequality holds, the same argument applies by defining $A^{*}=G^{\prime} \backslash \tilde{G}_{3 \varepsilon}$ so that (iv) holds.

Now the proof of the theorem proceeds in the same manner as in part (a).

## 6. Concentration properties of the prior support

In this section, we study properties of the support of the prior probabilities as specified by the admixture model, including bounds for the support of the prior as defined by Kullback-Leibler neighborhoods.

## $\alpha$-regularity

Let $\boldsymbol{\beta}$ be a random variable taking values in $\Delta^{k-1}$ that has a density $p_{\beta}$ (with respect to the $k-1$-dimensional Hausdorff measure $\mathcal{H}^{k-1}$ on $\mathbb{R}^{k}$ ). For a definition of the Hausdorff measure, see [6], which in our case reduces to the Lebesgue measure defined on simplex $\Delta^{k-1}$. Define random variable $\boldsymbol{\eta}=\beta_{1} \boldsymbol{\theta}_{1}+\cdots+\beta_{k} \boldsymbol{\theta}_{k}$, which takes values in $G=\operatorname{conv}\left(\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}\right)$. Write $\boldsymbol{\eta}=L \boldsymbol{\beta}$, where $L=\left[\begin{array}{lll}\boldsymbol{\theta}_{1} & \cdots & \boldsymbol{\theta}_{k}\end{array}\right]$ is a $(d+1) \times k$ matrix. If $k \leq d+1, \boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$ are generally linearly independent, in which case matrix $L$ has rank $k-1$. By the change of variable formula [6] (Chapter 3), $P_{\beta}$ induces a distribution $P_{\eta \mid G}$ on $G \subset \Delta^{d}$, which admits the following density with respect to the $k-1$ dimensional Hausdorff measure $\mathcal{H}^{k-1}$ on $\Delta^{d}$ :

$$
\begin{equation*}
p_{\eta}(\eta \mid G)=p_{\beta}\left(L^{-1}(\eta)\right) J(L)^{-1} . \tag{14}
\end{equation*}
$$

Here, $J(L)$ denotes the Jacobian of the linear map. On the other hand, if $k \geq d+1$, then $L$ is generally $d$-ranked. The induced distribution for $\eta$ admits the following density with respect to the $k-(d+1)$-dimensional Hausdorff measure on $\mathbb{R}^{d+1}$ :

$$
\begin{equation*}
p_{\eta}(\eta \mid G)=\int_{L^{-1}\{\eta\}} p_{\boldsymbol{\beta}}(\boldsymbol{\beta}) J(L)^{-1} \mathcal{H}^{k-(d+1)}(\mathrm{d} \boldsymbol{\beta}) \tag{15}
\end{equation*}
$$

A common choice for $P_{\boldsymbol{\beta}}$ is the Dirichlet distribution, as adopted by [4,13]: given parameter $\gamma \in \mathbb{R}_{+}^{k}$, for any $A \subset \Delta^{k-1}$,

$$
P_{\boldsymbol{\beta}}(\boldsymbol{\beta} \in A \mid \gamma)=\int_{A} \frac{\Gamma\left(\sum \gamma_{j}\right)}{\prod_{j=1}^{k} \Gamma\left(\gamma_{j}\right)} \prod_{j=1}^{k} \beta_{j}^{\gamma_{j}-1} \mathcal{H}^{k-1}(\mathrm{~d} \boldsymbol{\beta})
$$

Lemma 4. Let $\boldsymbol{\eta}=\sum_{j=1}^{k} \beta_{j} \boldsymbol{\theta}_{j}$, where $\boldsymbol{\beta}$ is distributed according to a $k-1$-dimensional Dirichlet distribution with parameters $\gamma_{j} \in(0,1]$ for $j=1, \ldots, k$.
(a) If $k \leq d+1$, there is constant $\varepsilon_{0}=\varepsilon_{0}(k)>0$, and constant $c_{6}=c_{6}(\gamma, k, d)>0$ dependent on $\gamma, k$ and $d$ such that for any $\varepsilon<\varepsilon_{0}$,

$$
\inf _{G \subset \Delta^{d}} \inf _{\eta^{*} \in G} P_{\eta \mid G}\left(\left\|\boldsymbol{\eta}-\eta^{*}\right\| \leq \varepsilon\right) \geq c_{6} \varepsilon^{k-1}
$$

(b) If $k>d+1$, the statement holds with a lower bound $c_{6} \varepsilon^{d+\sum_{i=1}^{k} \gamma_{i}}$.

A consequence of this lemma is that if $\gamma_{j} \leq 1$ for all $j=1, \ldots, k, k \leq d+1$ and $G$ is $k-1$ dimensional, then the induced $P_{\eta \mid G}$ has a Hausdorff density that is bounded away from 0 on the entire its support $\Delta^{k-1}$, which implies 0-regularity. On the other hand, if $\gamma_{j} \leq 1$ for all $j$, $k>d+1$, and $G$ is $d$-dimensional, the $P_{\eta \mid G}$ is at least $\sum_{j=1}^{k} \gamma_{j}$-regularity. Note that the $\alpha$ regularity condition is concerned with the density behavior near the boundary of its support, and thus is weaker than what is guaranteed here.

## Bounds on KL divergences

Suppose that the population polytope $G$ is endowed with a prior distribution on $\mathcal{G}^{k}$ (via prior on the population structures $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}$ ). Given $G$, the marginal density $p_{\mathcal{S}_{[n]} \mid G}$ of $n$-vector $\mathcal{S}_{[n]}$ is obtained via Equation (2). To establish the concentration properties of Kullback-Leibler neighborhood $B_{K}$ as induced by the prior, we need to obtain an upper bound on the KL divergences for the marginal densities in terms of Hausdorff metric on population polytopes. First, consider a very special case.

Lemma 5. Let $G, G^{\prime} \subset \Delta^{d}$ be closed convex sets satisfying Property A1. Moreover, assume that
(a) $G \subset G^{\prime}$, aff $G=\operatorname{aff} G^{\prime}$ is $p$-dimensional, for $p \leq d$.
(b) $P_{\eta \mid G}$ (resp. $P_{\eta \mid G^{\prime}}$ ) are uniform distributions on $G$ (resp. $G^{\prime}$ ).

Then, there is a constant $C_{1}=C_{1}(r, p)>0$ such that $K\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) \leq C_{1} d_{\mathcal{H}}\left(G, G^{\prime}\right)$.
Proof. First, we note a well-known fact of KL divergences: the divergence between marginal distributions (e.g., on $\mathcal{S}_{[n]}$ ) is bounded from above by the divergence between joint distributions (e.g., on $\eta$ and $\mathcal{S}_{[n]}$ via Equation (1)):

$$
K\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) \leq K\left(P_{\eta \times \mathcal{S}_{[n]} \mid G}, P_{\eta \times \mathcal{S}_{[n]} \mid G^{\prime}}\right) .
$$

Due to the hierarchical specification, $p_{\eta \times \mathcal{S}_{[n]} \mid G}=p_{\eta \mid G} \times p_{\mathcal{S}_{[n]} \mid \eta}$ and $p_{\eta \times \mathcal{S}_{[\eta]} \mid G^{\prime}}=p_{\eta \mid G^{\prime}} \times p_{\mathcal{S}_{[\eta]} \mid \eta}$, so $K\left(P_{\eta \times \mathcal{S}_{[n]} \mid G}, P_{\eta \times \mathcal{S}_{[n]} \mid G^{\prime}}\right)=K\left(p_{\eta \mid G}, p_{\eta \mid G^{\prime}}\right)$. The assumption aff $G=\operatorname{aff} G^{\prime}$ and moreover $G \subset G^{\prime}$ implies that $K\left(p_{\eta \mid G}, p_{\eta \mid G^{\prime}}\right)<\infty$. In addition, $P_{\eta \mid G}$ and $P_{\eta \mid G^{\prime}}$ are assumed to be uniform distributions on $G$ and $G^{\prime}$, respectively, so

$$
K\left(p_{\eta \mid G}, p_{\eta \mid G^{\prime}}\right)=\int \log \frac{1 / \operatorname{vol}_{p} G}{1 / \operatorname{vol}_{p} G^{\prime}} \mathrm{d} P_{\eta \mid G}
$$

By Lemma 2(b), $\log \left[\operatorname{vol}_{p} G^{\prime} / \operatorname{vol}_{p} G\right] \leq \log \left(1+C_{1} d_{\mathcal{H}}\left(G, G^{\prime}\right)\right) \leq C_{1} d_{\mathcal{H}}\left(G, G^{\prime}\right)$ for some constant $C_{1}=C_{1}(r, p)>0$. This completes the proof.

Remark. The previous lemma requires a particularly stringent condition, aff $G=\operatorname{aff} G^{\prime}$, and moreover $G \subset G^{\prime}$, which is usually violated when $k<d+1$. However, the conclusion is worth noting in that the upper bound does not depend on the sample size $n$ (for $\mathcal{S}_{[n]}$ ). The next lemma removes this condition and the condition that both $p_{\eta \mid G}$ and $p_{\eta \mid G^{\prime}}$ be uniform. As a result the
upper bound obtained is weaker, in the sense that the bound is not in terms of a Hausdorff distance, but in terms of a Wasserstein distance.

Let $Q\left(\boldsymbol{\eta}_{1}, \boldsymbol{\eta}_{2}\right)$ denote a coupling of $P(\boldsymbol{\eta} \mid \boldsymbol{G})$ and $P\left(\boldsymbol{\eta} \mid G^{\prime}\right)$, that is, a joint distribution on $G \times G^{\prime}$ whose induced marginal distributions of $\eta_{1}$ and $\eta_{2}$ are equal to $P(\boldsymbol{\eta} \mid G)$ and $P\left(\eta \mid G^{\prime}\right)$, respectively. Let $\mathcal{Q}$ be the set of all such couplings. The Wasserstein distance between $p_{\eta \mid G}$ and $p_{\eta \mid G^{\prime}}$ is defined as

$$
W_{1}\left(p_{\eta \mid G}, p_{\eta \mid G^{\prime}}\right)=\inf _{Q \in \mathcal{Q}} \int\left\|\boldsymbol{\eta}_{1}-\boldsymbol{\eta}_{2}\right\| \mathrm{d} Q\left(\boldsymbol{\eta}_{1}, \boldsymbol{\eta}_{2}\right)
$$

Lemma 6. Let $G, G^{\prime} \subset \Delta^{d}$ be closed convex subsets such that any $\eta=\left(\eta_{0}, \ldots, \eta_{d}\right) \in G \cup G^{\prime}$ satisfies $\min _{l=0, \ldots, d} \eta_{l}>c_{0}$ for some constant $c_{0}>0$. Then

$$
K\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) \leq \frac{n}{c_{0}} W_{1}\left(p_{\eta \mid G}, p_{\eta \mid G^{\prime}}\right) .
$$

Remark. As $n \rightarrow \infty$, the upper bound tends to infinity. This is expected, because the marginal distribution $P_{\mathcal{S}_{[n]} \mid G}$ should degenerate. Since typically aff $G \neq$ aff $G^{\prime}$, Kullback-Leibler distances between $P_{\mathcal{S}_{[n]} \mid G}$ and $P_{\mathcal{S}_{[n]} \mid G^{\prime}}$ should typically tend to infinity.

Proof of Lemma 6. Associating each sample $\mathcal{S}_{[n]}=\left(X_{1}, \ldots, X_{n}\right)$ with a $d+1$-dimensional vector $\boldsymbol{\eta}(\mathcal{S}) \in \Delta^{d}$, where $\boldsymbol{\eta}(\mathcal{S})_{i}=\frac{1}{n} \sum_{j=1}^{n} \mathbb{I}\left(X_{j}=i\right)$ for each $i=0, \ldots, d$. The density of $\mathcal{S}_{[n]}$ given $G$ (with respect to the counting measure) takes the form:

$$
p_{\mathcal{S}_{[n]} \mid G}\left(\mathcal{S}_{[n]}\right)=\int_{G} p\left(\mathcal{S}_{[n]} \mid \boldsymbol{\eta}\right) \mathrm{d} P(\boldsymbol{\eta} \mid G)=\int_{G} \exp \left(n \sum_{i=0}^{d} \boldsymbol{\eta}(\mathcal{S})_{i} \log \boldsymbol{\eta}_{i}\right) \mathrm{d} P(\boldsymbol{\eta} \mid G)
$$

Due to the convexity of Kullback-Leibler divergence, by Jensen inequality, for any coupling $Q \in \mathcal{Q}$ :

$$
\begin{aligned}
K\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) & =K\left(\int p\left(\mathcal{S}_{[n]} \mid \boldsymbol{\eta}_{1}\right) \mathrm{d} Q\left(\boldsymbol{\eta}_{1}, \boldsymbol{\eta}_{2}\right), \int p\left(\mathcal{S}_{[n]} \mid \boldsymbol{\eta}_{2}\right) \mathrm{d} Q\left(\boldsymbol{\eta}_{1}, \boldsymbol{\eta}_{2}\right)\right) \\
& \leq \int K\left(p\left(\mathcal{S}_{[n]} \mid \boldsymbol{\eta}_{1}\right), p\left(\mathcal{S}_{[n]} \mid \boldsymbol{\eta}_{2}\right)\right) \mathrm{d} Q\left(\boldsymbol{\eta}_{1}, \boldsymbol{\eta}_{2}\right)
\end{aligned}
$$

It follows that $K\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) \leq \inf _{Q} \int K\left(p_{\mathcal{S}_{[n]} \mid \eta_{1}}, p_{\mathcal{S}_{[n]} \mid \eta_{2}}\right) \mathrm{d} Q\left(\boldsymbol{\eta}_{1}, \boldsymbol{\eta}_{2}\right)$.
Note that $K\left(P_{\mathcal{S}_{[n]} \mid \eta_{1}}, P_{\mathcal{S}_{[n]} \mid \boldsymbol{\eta}_{2}}\right)=\sum_{\mathcal{S}_{[n]}} n\left(K\left(\boldsymbol{\eta}(\mathcal{S}), \boldsymbol{\eta}_{2}\right)-K\left(\boldsymbol{\eta}(\mathcal{S}), \boldsymbol{\eta}_{1}\right)\right) p_{\mathcal{S}_{[n]} \mid \boldsymbol{\eta}_{1}}$, where the summation is taken over all realizations of $\mathcal{S}_{[n]} \in\{0, \ldots, d\}^{n}$. For any $\eta(\mathcal{S}) \in \Delta^{d}, \eta_{1} \in G$ and $\eta_{2} \in G^{\prime}$,

$$
\begin{aligned}
\left|K\left(\boldsymbol{\eta}(\mathcal{S}), \boldsymbol{\eta}_{1}\right)-K\left(\boldsymbol{\eta}(\mathcal{S}), \boldsymbol{\eta}_{2}\right)\right| & =\left|\sum_{i=0}^{d} \boldsymbol{\eta}(\mathcal{S})_{i} \log \left(\eta_{1, i} / \eta_{2, i}\right)\right| \\
& \leq \sum_{i} \boldsymbol{\eta}(\mathcal{S})_{i}\left|\eta_{1, i}-\eta_{2, i}\right| / c_{0}
\end{aligned}
$$

$$
\begin{aligned}
& \leq\left(\sum_{i} \eta(\mathcal{S})_{i}^{2}\right)^{1 / 2}\left\|\boldsymbol{\eta}_{1}-\boldsymbol{\eta}_{2}\right\| / c_{0} \\
& \leq\left\|\boldsymbol{\eta}_{1}-\boldsymbol{\eta}_{2}\right\| / c_{0}
\end{aligned}
$$

Here, the first inequality is due the assumption, the second due to Cauchy-Schwarz. It follows that $K\left(P_{\mathcal{S}_{[n]} \mid \eta_{1}}, P_{\mathcal{S}_{[n]} \mid \eta_{2}}\right) \leq n\left\|\boldsymbol{\eta}_{1}-\boldsymbol{\eta}_{2}\right\| / c_{0}$, so $K\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) \leq \frac{n}{c_{0}} W_{1}\left(p_{\eta \mid G}, p_{\eta \mid G^{\prime}}\right)$.

Lemma 7. Let $G=\operatorname{conv}\left(\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}\right)$ and $G^{\prime}=\operatorname{conv}\left(\boldsymbol{\theta}_{1}^{\prime}, \ldots, \boldsymbol{\theta}_{k}^{\prime}\right)$ (same $k$ ). A random variable $\boldsymbol{\eta} \sim P_{\eta \mid G}$ is parameterized by $\boldsymbol{\eta}=\sum_{j} \beta_{j} \boldsymbol{\eta}_{j}$, while a random variable $\boldsymbol{\eta} \sim P_{\eta \mid G^{\prime}}$ is parameterized by $\eta=\sum_{j} \beta_{j}^{\prime} \eta_{j}^{\prime}$, where $\boldsymbol{\beta}$ and $\boldsymbol{\beta}^{\prime}$ are both distributed according to a symmetric probability density $p_{\beta}$.
(a) Assume that both $G, G^{\prime}$ satisfy Property A2. Then, for small $d_{\mathcal{H}}\left(G, G^{\prime}\right), W_{1}\left(p_{\eta \mid G}\right.$, $\left.p_{\eta \mid G^{\prime}}\right) \leq C_{0} d_{\mathcal{H}}\left(G, G^{\prime}\right)$ for some constant $C_{0}$ specified by Lemma 1 .
(b) Assume further that assumptions in Lemma 6 hold, then $K\left(p_{[n] \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right) \leq \frac{n}{c_{0}} C_{0} \times$ $d_{\mathcal{H}}\left(G, G^{\prime}\right)$.

Remark. In order to obtain an upper bound for $K\left(p_{\mathcal{S}_{[n] \mid}, G}, p_{\mathcal{S}_{[n] \mid} G^{\prime}}\right)$ in terms of $d_{\mathcal{H}}\left(G, G^{\prime}\right)$, the assumption that $p_{\beta}$ is symmetric appears essential. That is, random variables $\beta_{1}, \ldots, \beta_{k}$ are exchangeable under $p_{\beta}$. Without this assumption, it is possible to have $d_{\mathcal{H}}\left(G, G^{\prime}\right)=0$, but $K\left(p_{\mathcal{S}_{[n]} \mid G}, p_{\mathcal{S}_{[n]} \mid G^{\prime}}\right)>0$.

Proof of Lemma 7. By Lemma 1 under Property A2, $d_{\mathcal{M}}\left(G, G^{\prime}\right) \leq C_{0} d_{\mathcal{H}}\left(G, G^{\prime}\right)$ for some constant $C_{0}$. Let $d_{\mathcal{H}}\left(G, G^{\prime}\right) \leq \varepsilon$ for some small $\varepsilon>0$. Assume without loss of generality that $\left|\boldsymbol{\theta}_{j}-\boldsymbol{\theta}_{j}^{\prime}\right| \leq C_{0} \varepsilon$ for all $j=1, \ldots, k$ (otherwise, simply relabel the subscripts for $\boldsymbol{\theta}_{j}^{\prime}$ 's).

Let $Q\left(\boldsymbol{\eta}, \boldsymbol{\eta}^{\prime}\right)$ be a coupling of $P_{\eta \mid G}$ and $P_{\eta \mid G^{\prime}}$ such that under $Q, \boldsymbol{\eta}=\sum_{j=1}^{k} \beta_{j} \boldsymbol{\theta}_{j}$ and $\boldsymbol{\eta}^{\prime}=$ $\sum_{j=1}^{k} \beta_{j} \boldsymbol{\theta}_{j}^{\prime}$, that is, $\boldsymbol{\eta}$ and $\boldsymbol{\eta}^{\prime}$ share the same $\boldsymbol{\beta}$, where $\boldsymbol{\beta}$ is a random variable with density $p_{\boldsymbol{\beta}}$. This is a valid coupling, since $p_{\boldsymbol{\beta}}$ is assumed to be symmetric.

Under distribution $Q, \mathbb{E}\left\|\boldsymbol{\eta}-\boldsymbol{\eta}^{\prime}\right\| \leq \mathbb{E} \sum_{j=1}^{k} \beta_{j}\left\|\boldsymbol{\theta}_{j}-\boldsymbol{\theta}_{j}^{\prime}\right\| \leq C_{0} \varepsilon \mathbb{E} \sum_{j=1}^{k} \beta_{j}=C_{0} \varepsilon$. Hence, $W_{1}\left(P_{\eta \mid G}, P_{\eta \mid G^{\prime}}\right) \leq C_{0} \varepsilon$. Part (b) is an immediate consequence.

Recall the definition of Kullback-Leibler neighborhood given by Equation (7). We are now ready to prove the main result of this section.

Theorem 6. Under assumptions (S1) and (S2), for any $G_{0}$ in the support of prior $\Pi$, for any $\delta>0$ and $n>\log (1 / \delta)$

$$
\Pi\left(G \in B_{K}\left(G_{0}, \delta\right)\right) \geq c\left(\delta^{2} / n^{3}\right)^{k d}
$$

where constant $c=c\left(c_{0}, c_{0}^{\prime}\right)$ depends only on $c_{0}, c_{0}^{\prime}$.
Proof. We shall invoke a bound of [21] (Theorem 5) on the KL divergence. This bound says that if $p$ and $q$ are two densities on a common space such that $\int p^{2} / q<M$, then for some
universal constant $\varepsilon_{0}>0$, as long as $h(p, q) \leq \varepsilon<\varepsilon_{0}$, there holds: $K(p, q)=\mathrm{O}\left(\varepsilon^{2} \log (M / \varepsilon)\right)$, and $K_{2}(p, q):=\int p(\log (p / q))^{2}=\mathrm{O}\left(\varepsilon^{2}[\log (M / \varepsilon)]^{2}\right)$, where the big O constants are universal.

Let $G_{0}=\operatorname{conv}\left(\boldsymbol{\theta}_{1}^{*}, \ldots, \boldsymbol{\theta}_{k}^{*}\right)$. Consider a random set $G \in \mathcal{G}^{k}$ represented by $G=\operatorname{conv}\left(\boldsymbol{\theta}_{1}, \ldots\right.$, $\boldsymbol{\theta}_{k}$ ), and the event $\mathcal{E}$ that $\left\|\boldsymbol{\theta}_{j}-\boldsymbol{\theta}_{j}^{*}\right\| \leq \varepsilon$ for all $j=1, \ldots, k$. For the pair of $G_{0}$ and $G$, consider a coupling $Q$ for $P_{\eta \mid G}$ and $P_{\eta \mid G_{0}}$ such that any $\left(\boldsymbol{\eta}_{1}, \boldsymbol{\eta}_{2}\right)$ distributed by $Q$ is parameterized by $\boldsymbol{\eta}_{1}=\beta_{1} \boldsymbol{\theta}_{1}+\cdots+\beta_{k} \boldsymbol{\theta}_{k}$ and $\boldsymbol{\eta}_{2}=\beta_{1} \boldsymbol{\theta}_{1}^{*}+\cdots+\beta_{k} \boldsymbol{\theta}_{k}^{*}$ (that is, under the coupling $\boldsymbol{\eta}_{1}$ and $\boldsymbol{\eta}_{2}$ share the same vector $\boldsymbol{\beta}$ ). Then, under $Q, \mathbb{E}\left\|\boldsymbol{\eta}_{1}-\boldsymbol{\eta}_{2}\right\| \leq \varepsilon$. This entails that $W_{1}\left(P_{\eta \mid G}, P_{\eta \mid G_{0}}\right) \leq \varepsilon$. (We note here that the argument appears similar to the one from Lemma 7, but we do not need to assume that $p_{\boldsymbol{\beta}}$ be symmetric in this theorem.) If $G$ is randomly distributed according to prior $\Pi$, under assumption (S2), the probability of event $\mathcal{E}$ is lower bounded by $c_{0}^{\prime} \varepsilon^{k d}$. By Lemma 6 , $h^{2}\left(p_{G_{0}}, p_{G}\right) \leq K\left(p_{G_{0}}, p_{G}\right) / 2 \leq\left(n / c_{0}\right) W_{1}\left(P_{\eta \mid G}, P_{\eta \mid G_{0}}\right) \leq n \varepsilon /\left(2 c_{0}\right)$. Note that the density ratio $p_{\mathcal{S}_{[n]} \mid G} / p_{\mathcal{S}_{[n]} \mid G_{0}} \leq\left(1 / c_{0}\right)^{n}$, which implies that $\sum_{\mathcal{S}_{[n]}} p_{\mathcal{S}_{[n]} \mid G_{0}}{ }^{2} / p_{\mathcal{S}_{[n]} \mid G} \leq\left(1 / c_{0}\right)^{n}$. We can apply the upper bound described in the previous paragraph to obtain:

$$
K_{2}\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G}\right)=\mathrm{O}\left(\frac{n \varepsilon}{2 c_{0}}\left[\frac{1}{2} \log \frac{2 c_{0}}{n \varepsilon}+n \log \frac{1}{c_{0}}\right]^{2}\right)
$$

Here, the big O constant is universal. If we set $\varepsilon=\delta^{2} / n^{3}$, then the quantity in the right hand side of the previous display is bounded by $\mathrm{O}\left(\delta^{2}\right)$ as long as $n>\log (1 / \delta)$. Combining with the probability bound $c_{0}^{\prime} \varepsilon^{k d}$ derived above, we obtain the desired result.

## 7. Proofs of main theorems and auxiliary lemmas

Proof of Theorem 1 (Overfitted setting). The proof proceeds by verifying conditions of Theorem 4. Let $\varepsilon_{m, n}=(\log m / m)^{1 / 2}+(\log n / m)^{1 / 2}+(\log n / n)^{1 / 2}$. Let $\mathcal{G}:=\operatorname{supp} \Pi \subset \mathcal{G}^{k}$. Starting with the entropy condition (8), we note that

$$
\log D\left(\varepsilon / 2, \mathcal{G} \cap B_{\mathcal{H}}\left(G_{0}, 2 \varepsilon\right), d_{\mathcal{H}}\right) \leq \log N\left(\varepsilon / 4, \mathcal{G} \cap B_{\mathcal{H}}\left(G_{0}, 2 \varepsilon\right), d_{\mathcal{H}}\right)=\mathrm{O}(1)
$$

By Theorem 5(a), assumption (S3a) and the general inequality that $h \geq V$, we have:

$$
\Psi_{\mathcal{G}, n}(\varepsilon) \geq\left[c_{1}(\varepsilon / 2)^{p+\alpha}-6(d+1) \mathrm{e}^{-n \varepsilon^{2} / 32(d+1)}\right]^{2}
$$

where $p=\min (k-1, d)$. So $\Psi_{\mathcal{G}, n}(\varepsilon) \geq c \varepsilon^{2(p+\alpha)}$ as long as $c_{1}(\varepsilon / 2)^{p+\alpha} \geq 12(d+1) \exp \left[-n \varepsilon^{2} /\right.$ $32(d+1)]$. Here, $c$ is a constant depending on $c_{1}, p, d$. This is satisfied if $\varepsilon$ is bounded from below by a large multiple of $\varepsilon_{m, n}>(\log n / n)^{1 / 2}$. Using $\Phi_{\mathcal{G}, n}(\delta):=\frac{c_{0}}{4 n C_{0}} \Psi_{\mathcal{G}, n}(\delta)$ (cf. Remark following Definition 1) it follows that

$$
\begin{aligned}
& \log D\left(c_{0} \Psi_{\mathcal{G}, n}(\varepsilon) /\left(4 n C_{0}\right), \mathcal{G} \cap B_{\mathcal{H}}\left(G_{1}, \varepsilon / 2\right), d_{\mathcal{H}}\right) \\
& \quad \leq \log N\left(c_{0} c \varepsilon^{2(p+\alpha)} /\left(4 n C_{0}\right), \mathcal{G} \cap B_{\mathcal{H}}\left(G_{1}, \varepsilon / 2\right), d_{\mathcal{H}}\right) \\
& \quad \lesssim \log \left(n^{k d} \varepsilon^{-(2 p+2 \alpha-1) k d}\right) \leq m \varepsilon^{2}
\end{aligned}
$$

where the last inequality holds since $\varepsilon$ is bounded from below by a large multiple of $\varepsilon_{m, n}>$ $(\log n / m)^{1 / 2}+(\log m / m)^{1 / 2}$. Thus, the entropy condition (8) is established.

To verify condition Equation (11), we note that for some constant $c>0$,

$$
\begin{aligned}
& \exp \left(2 m \varepsilon_{m, n}^{2}\right) \sum_{j \geq M_{m}} \exp \left[-m \Psi_{\mathcal{G}, n}\left(j \varepsilon_{m, n}\right) / 8\right] \\
& \quad \leq \exp \left(2 m \varepsilon_{m, n}^{2}\right) \sum_{j \geq M_{m}} \exp \left[-c m\left(j \varepsilon_{m, n}\right)^{2(p+\alpha)} / 8\right] \\
& \quad \lesssim \exp \left(2 m \varepsilon_{m, n}^{2}\right) \exp \left[-c m\left(M_{m} \varepsilon_{m, n}\right)^{2(p+\alpha)} / 8\right]
\end{aligned}
$$

where the right side of the above display vanishes if $\left(M_{m} \varepsilon_{m, n}\right)^{p+\alpha}$ is a sufficiently large multiple of $\varepsilon_{m, n}$. This holds if we choose $M_{m}=M \varepsilon_{m, n}^{-(p+\alpha-1) /(p+\alpha)}$ for a large constant $M$. Equation (10) also holds.

It remains to verify Equation (9). By Theorem 6, as long as $n \gtrsim \log \left(1 / \varepsilon_{m, n}\right)$,

$$
\begin{aligned}
\log \Pi\left(G \in B_{K}\left(G_{0}, \varepsilon_{m, n}\right)\right) & \geq c\left(c_{0}\right) \log \left(\varepsilon_{m, n}^{2} / n^{3}\right)^{k d} \\
& =c\left(c_{0}\right) k d\left(2 \log \varepsilon_{m, n}-3 \log n\right)
\end{aligned}
$$

Equation (9) holds for a sufficiently large constant $C$ because $\varepsilon_{m, n}>(\log n / m)^{1 / 2}+(\log m /$ $m)^{1 / 2}$, and the constraint that $n>\log m$.

Now, we can apply Theorem 4 to obtain a posterior contraction rate $M_{m} \varepsilon_{m, n} \asymp \varepsilon_{m, n}^{1 /(p+\alpha)}$.
Proof of Theorem 2. The proof proceeds in exactly the same way as Theorem 1, except that part (b) of Theorem 5 is applied instead of part (a). Accordingly, $p$ is replaced by 1 in the rate exponent.

Proof of Theorem 3 (Minimax lower bounds). (a) The proof involves the construction of a pair of polytopes in $\mathcal{G}^{k}$ whose set difference has small volume for a given Hausdorff distance. We consider two separate cases: (i) $k / 2 \leq d$ and (ii) $k>2 d$.

If $k / 2 \leq d$, consider a $q=\lfloor k / 2\rfloor$-simplex $G_{0}$ that is spanned by $q+1$ vertices in general positions. Take a vertex of $G_{0}$, say $\boldsymbol{\theta}_{0}$. Construct $G_{0}^{\prime}$ by chopping $G_{0}$ off by an $\varepsilon$-cap that is obtained by the convex hull of $\boldsymbol{\theta}_{0}$ and $q$ other points which lie on the edges adjacent to $\boldsymbol{\theta}_{0}$, and of distance $\varepsilon$ from $\boldsymbol{\theta}_{0}$. Clearly, $G_{0}^{\prime}$ has $2 q \leq k$ vertices, so both $G_{0}$ and $G_{0}^{\prime}$ are in $\mathcal{G}^{k}$. We have $d_{\mathcal{H}}\left(G_{0}, G_{0}^{\prime}\right) \asymp \varepsilon$, and $\operatorname{vol}_{q}\left(G_{0} \backslash G_{0}^{\prime}\right) \asymp \varepsilon^{q}$. Due to assumption (S4), $V\left(p_{\eta \mid G_{0}}, p_{\eta \mid G_{0}^{\prime}}\right) \lesssim \varepsilon^{q+\alpha^{\prime}}$. We note here and for the rest of the proof, the multiplying constants in asymptotic inequalities depend only on $r, R, \delta$ of Properties A1 and A2.

If $k>2 d$, consider a $d$-dimensional polytope $G_{0}$ which has $k-d+1$ vertices in general positions. Construct $G_{0}^{\prime}$ in the same way as above (by chopping $G_{0}$ off by an $\varepsilon$-cap that contains a vertex $\boldsymbol{\theta}_{0}$ which has $d$ adjacent vertices). Then, $G_{0}^{\prime}$ has $(k-d+1)-1+d=k$ vertices. Thus, both $G_{0}^{\prime}$ and $G_{0}$ are in $\mathcal{G}^{k}$. We have $d_{\mathcal{H}}\left(G_{0}, G_{0}^{\prime}\right) \asymp \varepsilon$, and vol ${ }_{d}\left(G_{0} \backslash G_{0}^{\prime}\right) \asymp \varepsilon^{d}$. Due to assumption (S4), V( $\left.p_{\eta \mid G_{0}}, p_{\eta \mid G_{0}^{\prime}}\right) \lesssim \varepsilon^{d+\alpha^{\prime}}$.

To combine the two cases, let $q=\min (\lfloor k / 2\rfloor, d)$. We have constructed a pair of $G_{0}, G_{0}^{\prime} \in \mathcal{G}^{k}$ such that $d_{\mathcal{H}}\left(G_{0}, G_{0}^{\prime}\right) \asymp \varepsilon$, and $V\left(p_{\eta \mid G_{0}}, p_{\eta \mid G_{0}^{\prime}}\right) \lesssim \varepsilon^{q+\alpha^{\prime}}$. By Lemma 6, $K\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}\right) \lesssim$ $n W_{1}\left(p_{\eta \mid G_{0}}, p_{\eta \mid G_{0}^{\prime}}\right) \lesssim n V\left(p_{\eta \mid G_{0}}, p_{\eta \mid G_{0}^{\prime}}\right) \leq C n \varepsilon^{q+\alpha^{\prime}}$ for some constant $C>0$ independent of $\varepsilon$ and $n$. Note that the second inequality in the above display is due to Theorem 6.15 of [18].

Applying the method due to Le Cam (cf. [22], Lemma 1), for any estimator $\hat{G} \in \mathcal{G}^{*}$,

$$
\max _{G \in\left\{G_{0}, G_{0}^{\prime}\right\}} P_{\mathcal{S}_{[n]} \mid G_{0}} d_{\mathcal{H}}(G, \hat{G}) \gtrsim \varepsilon\left(1-\frac{1}{2} V\left(P_{\mathcal{S}_{[n]} \mid G_{0}}^{m}, P_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}^{m}\right)\right)
$$

Here, $P_{\mathcal{S}_{[n]} \mid G_{0}}^{m}$ denotes the (product) distribution of the $m$-sample $\mathcal{S}_{[n]}^{1}, \ldots, \mathcal{S}_{[n]}^{m}$. Thus,

$$
\begin{aligned}
V^{2}\left(P_{\mathcal{S}_{[n]} \mid G_{0}}^{m}, P_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}^{m}\right) & \leq h^{2}\left(P_{\mathcal{S}_{[n]} \mid G_{0}}^{m}, P_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}^{m}\right) \\
& =1-\int\left[P_{\mathcal{S}_{[n]} \mid G_{0}}^{m} P_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}^{m}\right]^{1 / 2} \\
& =1-\left[1-h^{2}\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}\right]^{m}\right. \\
& \leq 1-\left(1-C n \varepsilon^{q+\alpha^{\prime}}\right)^{m} .
\end{aligned}
$$

The last inequality is due to $h^{2}\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}\right) \leq K\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}\right) \leq C n \varepsilon^{q+\alpha^{\prime}}$. Thus,

$$
\max _{G \in\left\{G_{0}, G_{0}^{\prime}\right\}} P_{\mathcal{S}_{[n]} \mid G_{0}} d_{\mathcal{H}}(G, \hat{G}) \gtrsim \varepsilon\left(1-\frac{1}{2}\left[1-\left(1-C n \varepsilon^{q+\alpha^{\prime}}\right)^{m}\right]^{1 / 2}\right) .
$$

Letting $\varepsilon^{q+\alpha^{\prime}}=\frac{1}{\text { Cmn }}$, the right side of the previous display is bounded from below by $\varepsilon(1-$ $\frac{1}{2}(1-1 / 2)^{1 / 2}$ ).
(b) We employ the same construction of $G_{0}$ and $G_{0}^{\prime}$ as in part (a). Using the argument used in the proof of Lemma 5, $K\left(p_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}, p_{\mathcal{S}_{[n]} \mid G_{0}}\right)=\int \log \left[\operatorname{vol}_{q} G_{0} / \operatorname{vol}_{q} G_{0}^{\prime}\right] \mathrm{d} P_{\eta \mid G_{0}} \leq \int \log (1+$ $\left.C \varepsilon^{q}\right) P_{\eta \mid G_{0}} \lesssim \varepsilon^{q}$. So, $h^{2}\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}\right) \leq K\left(p_{\mathcal{S}_{[n]} \mid G_{0}^{\prime}}, p_{\mathcal{S}_{[n]} \mid G_{0}}\right) \lesssim \varepsilon^{q}$. Then, the proof proceeds as in part (a).
(c) Let $G_{0}^{\prime}$ be a polytope such that $\left|\operatorname{extr} G_{0}^{\prime}\right|=\left|\operatorname{extr} G_{0}\right|=k$ and $d_{\mathcal{H}}\left(G_{0}^{\prime}, G_{0}\right)=\varepsilon$. By Lemma 2, $\operatorname{vol}_{p}\left(G_{0} \Delta G_{0}^{\prime}\right)=\mathrm{O}(\varepsilon)$, where $p=(k-1) \wedge d$. The proof proceeds as in part (a) to obtain $(1 / m n)^{1 /\left(1+\alpha^{\prime}\right)}$ rate for the lower bound under assumption (S4). Under assumption (S4'), as in part (b), the dependence on $n$ can be removed to obtain $1 / m$ rate.

Proof of $\alpha$-regularity of the Dirichlet-induced densities in Lemma 4. First, consider the case $k \leq d+1$. For $\boldsymbol{\eta}^{*} \in G$, write $\eta^{*}=\beta_{1}^{*} \boldsymbol{\theta}_{1}+\cdots+\beta_{k}^{*} \boldsymbol{\theta}_{k}$. For $\boldsymbol{\beta} \in \Delta^{k-1}$ such that $\left|\beta_{i}-\beta_{i}^{*}\right| \leq \varepsilon / k$ for all $i=1, \ldots, k-1$, we have $\left\|\boldsymbol{\eta}-\boldsymbol{\eta}^{*}\right\|=\left\|\sum_{i=1}^{k}\left(\beta_{i}-\beta_{i}^{*}\right) \boldsymbol{\theta}_{i}\right\| \leq \sum_{i=1}^{k}\left|\beta_{i}-\beta_{i}^{*}\right| \leq 2 \sum_{i=1}^{k-1} \mid \beta_{i}-$ $\beta_{i}^{*} \mid \leq 2 \varepsilon$. Here, we used the fact that $\left\|\boldsymbol{\theta}_{i}\right\| \leq 1$ for any $\boldsymbol{\theta}_{i} \in \Delta^{d}$. Without loss of generality, assume that $\beta_{k}^{*} \geq 1 / k$. Then, for any $\varepsilon<1 / k$

$$
\begin{aligned}
& P_{\eta \mid G}\left(\left\|\boldsymbol{\eta}-\eta^{*}\right\| \leq 2 \varepsilon\right) \\
& \quad \geq P_{\boldsymbol{\beta}}\left(\left|\beta_{i}-\beta_{i}^{*}\right| \leq \varepsilon / k ; i=1, \ldots, k-1\right)
\end{aligned}
$$

$$
\begin{aligned}
& =\frac{\Gamma\left(\sum \gamma_{i}\right)}{\prod_{i} \Gamma\left(\gamma_{i}\right)} \int_{\beta_{i} \in[0,1] ;\left|\beta_{i}-\beta_{i}^{*}\right| \leq \varepsilon / k ; i=1, \ldots, k-1} \prod_{i=1}^{k-1} \beta_{i}^{\gamma_{i}-1}\left(1-\sum_{i=1}^{k-1} \beta_{i}\right)^{\gamma_{k}-1} \mathrm{~d} \beta_{1} \cdots \mathrm{~d} \beta_{k-1} \\
& \geq \frac{\Gamma\left(\sum \gamma_{i}\right)}{\prod_{i} \Gamma\left(\gamma_{i}\right)} \prod_{i=1}^{k-1} \int_{\max \left(\gamma_{i}^{*}-\varepsilon / k, 0\right)}^{\min \left(\gamma_{i}^{*}+\varepsilon / k, 1\right)} \beta_{i}^{\gamma_{i}-1} \mathrm{~d} \beta_{i} \geq \frac{\Gamma\left(\sum \gamma_{i}\right)}{\prod_{i} \Gamma\left(\gamma_{i}\right)}(\varepsilon / k)^{k-1} .
\end{aligned}
$$

Both the second and the third inequality in the previous display exploits the fact that since $\gamma_{i} \leq 1$, $x^{\gamma_{i}-1} \geq 1$ for any $x \leq 1$.

Now, consider the case $k>d+1$. The proof in the previous case applies, but we can achieve a better lower bound because the intrinsic dimensionality of $G$ is $d$, not $k-1$. Since $\boldsymbol{\eta}^{*} \in \operatorname{conv}\left(\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}\right) \subset \Delta^{d}$, by Carathéodory's theorem, $\boldsymbol{\eta}^{*}$ is the convex combination of $d+1$ or fewer extreme points among $\boldsymbol{\theta}_{i}$ 's. Without loss of generality, let $\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{d+1}$ be such points, and write $\boldsymbol{\eta}^{*}=\beta_{1}^{*} \boldsymbol{\theta}_{1}+\cdots+\beta_{d+1}^{*} \boldsymbol{\theta}_{d+1}$. Consider $\boldsymbol{\eta}=\beta_{1} \boldsymbol{\theta}_{1}+\cdots+\beta_{k} \boldsymbol{\theta}_{k}$, where $\| \beta_{i}-\beta_{i}^{*} \mid \leq \varepsilon / k$, for $i=1, \ldots, d$, while $0 \leq \beta_{i} \leq \varepsilon / k$ for $i=d+2, \ldots, k$. Then, $\left\|\boldsymbol{\eta}-\eta^{*}\right\| \leq 2 \varepsilon$. This implies that

$$
\begin{aligned}
& P_{\eta \mid G}\left(\left\|\boldsymbol{\eta}-\eta^{*}\right\| \leq 2 \varepsilon\right) \\
& \quad \geq P_{\boldsymbol{\beta}}\left(\left|\beta_{i}-\beta_{i}^{*}\right| \leq \varepsilon / k, i=1, \ldots, d+1 ;\left|\beta_{j}\right| \leq \varepsilon / k, j>d+1\right) \\
& \quad \geq \frac{\Gamma\left(\sum_{i} \gamma_{i}\right)}{\prod_{i} \Gamma\left(\gamma_{i}\right)} \prod_{i=1}^{d} \int_{\max \left(\gamma_{i}^{*}-\varepsilon / k, 0\right)}^{\min \left(\gamma_{i}^{*}+\varepsilon / k, 1\right)} \beta_{i}^{\gamma_{i}-1} \mathrm{~d} \beta_{i} \prod_{i=d+2}^{k} \int_{0}^{\varepsilon / k} \beta_{i}^{\gamma_{i}-1} \mathrm{~d} \beta_{i} \\
& \quad \geq \frac{\Gamma\left(\sum \gamma_{i}\right)}{\prod_{i} \Gamma\left(\gamma_{i}\right)}(\varepsilon / k)^{d+\sum_{i=d+2}^{k} \gamma_{i}} / \prod_{i=d+2}^{n} \gamma_{i} \gtrsim \varepsilon^{d+\sum_{i=1}^{k} \gamma_{i}} .
\end{aligned}
$$

This concludes the proof.

## Appendix A: Proofs of geometric lemmas

Proof of Lemma 1. (a) Let $G=\operatorname{conv}\left(\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}\right)$ and $G^{\prime}=\operatorname{conv}\left(\boldsymbol{\theta}_{1}^{\prime}, \ldots, \boldsymbol{\theta}_{k^{\prime}}^{\prime}\right)$. This part of the lemma is immediate from the definition by noting that for any $x \in G, d\left(x, G^{\prime}\right) \leq \min _{j}\left\|x-\boldsymbol{\theta}_{j}^{\prime}\right\|$, while the maximum of $d\left(x, G^{\prime}\right)$ is attained at some extreme point of $G$.
(b) Let $d_{\mathcal{H}}\left(G, G^{\prime}\right)=\varepsilon$ for some small $\varepsilon>0$. Take an extreme point of $G$, say $\boldsymbol{\theta}_{1}$. Due to A2, there is a ray emanating from $\boldsymbol{\theta}_{1}$ that intersects with the interior of $G$ and the angles formed by the ray and all (exposed) edges incident to $\boldsymbol{\theta}_{1}$ are bounded from above by $\pi / 2-\delta$. Let $x$ be the intersection between the ray and the boundary of $B_{p}\left(\boldsymbol{\theta}_{1}, \varepsilon\right)$.

Let $H$ be a $p$-1-dimensional hyperplane in $\mathbb{R}^{p}$ that touches (intersects with) $B_{p}\left(\boldsymbol{\theta}_{1}, \varepsilon\right)$ at only $x$. Define $C(x)$, resp. $C_{\varepsilon}(x)$, to be the $p$-dimensional caps obtained by the intersection between $G$, resp. $G_{\varepsilon}$, with the half-space which contains $\boldsymbol{\theta}_{1}$ and which is supported by $H$. For any $x^{\prime}$ that lies in the intersection of $H$ and a line segment $\left[\boldsymbol{\theta}_{1}, \boldsymbol{\theta}_{i}\right]$, where $\boldsymbol{\theta}_{i}$ is another vertex of $G$, the line segment $\left[x, x^{\prime}\right] \in H$ and $\left\|x-x^{\prime}\right\| \leq \varepsilon \cot \delta$. Suppose that the ray emanating from $x$ through $x^{\prime}$ intersects with $\operatorname{bd} G_{\varepsilon}$ at $x^{\prime \prime}$. Then, $\left\|x^{\prime}-x^{\prime \prime}\right\| \leq \varepsilon / \sin \delta$, which implies that $\| x-$
$x^{\prime \prime} \| \leq \varepsilon(\cot \delta+1 / \sin \delta)$ by triangle inequality. This entails that $\operatorname{Diam} C_{\varepsilon}(x) \leq C \varepsilon$, where $C=$ $\left(1+(\cot \delta+1 / \sin \delta)^{2}\right)^{1 / 2}$.

Now, $d_{\mathcal{H}}\left(G, G^{\prime}\right)=\varepsilon$ implies that $G^{\prime} \cap B_{p}\left(\boldsymbol{\theta}_{1}, \varepsilon\right) \neq \varnothing$. There is an extreme point of $G^{\prime}$ in the half-space which contains $B\left(\boldsymbol{\theta}_{1}, \varepsilon\right)$ and is supported by $H$. But $G^{\prime} \subset G_{\varepsilon}$, so there is an extreme point of $G^{\prime}$ in $C_{\varepsilon}(x)$. Hence, there is $\boldsymbol{\theta}_{j}^{\prime} \in G^{\prime}$ such that $\left\|\boldsymbol{\theta}_{j}^{\prime}-\boldsymbol{\theta}_{1}\right\| \leq \operatorname{Diam}\left(C_{\varepsilon}(x)\right) \leq C \varepsilon$. Repeat this argument for all other extreme points of $G$ to conclude that $d_{\mathcal{M}}\left(G, G^{\prime}\right) \leq C \varepsilon$.

Proof of Lemma 2. (a) Let $d_{\mathcal{H}}\left(G, G^{\prime}\right)=\varepsilon$. There exists either a point $x \in \operatorname{bd} G$ such that $G^{\prime} \cap B_{p}(x, \varepsilon / 2)=\varnothing$, or a point $x^{\prime} \in \operatorname{bd} G^{\prime}$ such that $G \cap B_{p}(x, \varepsilon / 2)=\varnothing$. Without loss of generality, assume the former. Thus, $\operatorname{vol}_{p} G \Delta G^{\prime} \geq \operatorname{vol}_{p} B_{p}(x, \varepsilon / 2) \cap G$. Consider the convex cone emanating from $x$ that circumscribes the $p$-dimensional spherical ball $B_{p}\left(\boldsymbol{\theta}_{c}, r\right)$ (whose existence is given by Property A1). Since $\left\|x-\boldsymbol{\theta}_{c}\right\| \leq R$, the angle between the line segment $\left[x, \boldsymbol{\theta}_{c}\right]$ and the cone's rays is bounded from below by $\sin \varphi \geq r / R$. So, $\operatorname{vol}_{p} B_{d}(x, \varepsilon / 2) \cap G \geq c_{1} \varepsilon^{p}$, where $c_{1}$ depends only on $r, R, p$.
(b) Let $d_{\mathcal{H}}\left(G, G^{\prime}\right)=\varepsilon$. Then $G^{\prime} \subset G_{\varepsilon}$ and $G \subset G_{\varepsilon}^{\prime}$. Take any point $x \in \operatorname{bd} G$, let $x^{\prime}$ be the intersection between $\operatorname{bd} G_{\varepsilon}$ and the ray emanating from $\boldsymbol{\theta}_{c}$ and passing through $x$. Let $H_{1}$ be a $p-1$ dimensional supporting hyperplane for $G$ at $x$. There is also a supporting hyperplane $H_{2}$ of $G^{\prime}$ that is parallel to $H_{1}$ and of at most $\varepsilon$ distance away from $H_{1}$. Since $\left\|\boldsymbol{\theta}_{c}-x\right\| \leq R$, while the distance from $\boldsymbol{\theta}_{c}$ to $H_{1}$ is lower bounded by $r$, the angle $\varphi$ between vector $\boldsymbol{\theta}_{c}-x$ and the vector normal to $H_{1}$ satisfies $\cos \varphi \geq r / R$. This implies that $\left\|x^{\prime}-x\right\| \leq \varepsilon / \cos \varphi \leq \varepsilon R / r$, so $\left\|x^{\prime}-\boldsymbol{\theta}_{c}\right\| /\left\|x-\boldsymbol{\theta}_{c}\right\| \leq 1+\varepsilon R / r^{2}$. In other words, $G_{\varepsilon}-\boldsymbol{\theta}_{c} \subset\left(1+\varepsilon R / r^{2}\right)\left(G-\boldsymbol{\theta}_{c}\right)$. So, $\operatorname{vol}_{p} G^{\prime} \backslash G \leq \operatorname{vol}_{p} G_{\varepsilon} \backslash G \leq\left[\left(1+\varepsilon R / r^{2}\right)^{p}-1\right] \operatorname{vol}_{p} G \leq C_{1} \varepsilon$, where $C_{1}$ depends only on $r, R, p$. We obtain a similar bound for $\operatorname{vol}_{p} G \backslash G^{\prime}$, which concludes the proof.

Proof of Lemma 3. We provide a proof for case (a). Let $G=\operatorname{conv}\left(\boldsymbol{\theta}_{1}, \ldots, \boldsymbol{\theta}_{k}\right)$ and $G^{\prime}=$ $\operatorname{conv}\left(\boldsymbol{\theta}_{1}^{\prime}, \ldots, \boldsymbol{\theta}_{k}^{\prime}\right)$, where $G$ is fixed but $G^{\prime}$ is allowed to vary. Since $G$ is fixed, it satisfies A1 and A2 for some constants $r, R$ and $\delta$ (depending on $G$ ). Moreover, there is some $\varepsilon_{0}=\varepsilon_{0}(G)$ depending only $G$ such that as soon as $d_{\mathcal{H}}\left(G, G^{\prime}\right) \leq \varepsilon_{0}, G^{\prime}$ also satisfies A1 and A2 for constants $\delta^{\prime}=\delta / 2, r^{\prime}=r / 2, R^{\prime}=2 R$.

Suppose that $d_{\mathcal{H}}\left(G, G^{\prime}\right)=\varepsilon$ such that $\varepsilon<\varepsilon_{0}$. By Lemma 1(b) for each vertex of $G$, say $\boldsymbol{\theta}_{i}$, there is a vertice of $G^{\prime}$, say $\boldsymbol{\theta}_{i}^{\prime}$, such that $\boldsymbol{\theta}_{i}^{\prime} \in B_{p}\left(\boldsymbol{\theta}_{i}, C_{0} \varepsilon\right)$ with $C_{0}=C_{0}(G)$ depending only on $\delta$. Moreover, there is at least one vertice of $G$, say $\boldsymbol{\theta}_{1}$, for which $\left\|\boldsymbol{\theta}_{1}^{\prime}-\boldsymbol{\theta}_{1}\right\| \geq \varepsilon$.

There are only three possible general positions for $\boldsymbol{\theta}_{1}^{\prime}$ relatively to $G$. Either
(i) $\boldsymbol{\theta}_{1}^{\prime} \in G$, or
(ii) $\boldsymbol{\theta}_{1}^{\prime} \in 2 \boldsymbol{\theta}_{1}-G$, or
(iii) $\boldsymbol{\theta}_{1}^{\prime}$ lies in a cone formed by all half-spaces supported by the $p-1$ dimensional faces adjacent to $\boldsymbol{\theta}_{1}$. Among these there is one half-space that contains $G$, and one that does not contain $G$.

If (i) is true, by Property A1, $G$ has at least one face $S \supset \boldsymbol{\theta}_{1}$ such that the distance from $\boldsymbol{\theta}_{1}^{\prime}$ to the hyperplane that provides support for $S$ is bounded from below by $\varepsilon r / R$. Let $B \subset S$ be a homothetic transformation of $S$ with respect to center $\boldsymbol{\theta}_{1}$ that maps $x \in S$ to $\tilde{x} \in B$ such that the ratio $\eta:=\left\|\boldsymbol{\theta}_{1}-\tilde{x}\right\| /\left\|\boldsymbol{\theta}_{1}-x\right\|$ satisfies $1-\eta=2 C_{0} \varepsilon / \min _{i \neq j}\left\|\boldsymbol{\theta}_{i}-\boldsymbol{\theta}_{j}\right\| \in(0,1 / 2)$. This is possible as soon as $\varepsilon<\min _{i \neq j}\left\|\boldsymbol{\theta}_{i}-\boldsymbol{\theta}_{j}\right\| / 4 C_{0}$. Then, for any $\boldsymbol{\theta}_{j} \in S, j \neq 1$, under
this transformation $\boldsymbol{\theta}_{j} \mapsto \tilde{\boldsymbol{\theta}}_{j} \in S$ for which $\left\|\tilde{\boldsymbol{\theta}}_{j}-\boldsymbol{\theta}_{j}\right\|=(1-\eta)\left\|\boldsymbol{\theta}_{1}-\boldsymbol{\theta}_{j}\right\| \geq 2 C_{0} \varepsilon$. Since $\left\|\boldsymbol{\theta}_{j}^{\prime}-\boldsymbol{\theta}_{j}\right\| \leq C_{0} \varepsilon$, the construction of $B$ implies that $\boldsymbol{\theta}_{j}^{\prime} \notin B$. As a result, $B \cap G^{\prime}=\varnothing$. Moreover, $\operatorname{vol}_{p-1} B=\eta^{p-1} \operatorname{vol}_{p-1} S \geq(1 / 2)^{p-1} \operatorname{vol}_{p-1} S \geq c_{0}(G)$, a constant depending only on $G$. Let $Q$ be a $p$-pyramid which has apex $\boldsymbol{\theta}_{1}^{\prime}$ and base $B$. It follows that relint $Q \cap$ relint $G^{\prime}=\varnothing$, which implies that relint $Q \subset G \backslash G^{\prime}$ (relint stands for the relative interior of a set). Hence, $\operatorname{vol}_{p} G \backslash G^{\prime} \geq \operatorname{vol}_{p} Q \geq \frac{1}{p} \varepsilon r / R \operatorname{vol}_{p-1} B \geq \frac{1}{p} \varepsilon c_{0}(G) r / R$.

If (ii) is true, the same argument can be applied to show that $\operatorname{vol}_{p}\left(G^{\prime} \backslash G\right)=\Omega(\varepsilon)$. If (iii) is true, a similar argument continues to apply: we obtain a lower bound for either $\operatorname{vol}_{p} G^{\prime} \backslash G$ or $\operatorname{vol}_{p} G \backslash G^{\prime} . G$ has a face (supported by a hyperplane, say, $H$ ) such that the distance from $\boldsymbol{\theta}_{1}^{\prime}$ to $H$ is $\Omega(\varepsilon)$. If the half-space supported by $H$ that contains $\boldsymbol{\theta}_{1}^{\prime}$ but does not contain $G$, then $\operatorname{vol}_{p} G^{\prime} \backslash G=\Omega(\varepsilon)$. If, on the other hand, the associated half-space does contain $G$, then $\operatorname{vol}_{p} G \backslash G^{\prime}=\Omega(\varepsilon)$. The proof for case (b) is similar and is omitted.

## Appendix B: Proof of abstract posterior contraction theorem

A key ingredient in the general analysis of convergence of posterior distributions is through establishing the existence of tests for subsets of parameters of interest. A test $\varphi_{m, n}$ is a measurable indicator function of the $m \times n$-sample $\mathcal{S}_{[n]}^{[m]}=\left(\mathcal{S}_{[n]}^{1}, \ldots, \mathcal{S}_{[n]}^{m}\right)$ from an admixture model. For a fixed pair of convex polytopes $G_{0}, G_{1} \in \mathcal{G}$, where $\mathcal{G}$ is a given subset of $\Delta^{d}$, consider tests for discriminating $G_{0}$ against a closed Hausdorff ball centered at $G_{1}$. The following two lemmas on the existence of tests highlight the fundamental role of the Hellinger information:

Lemma 8. Fix a pair of $\left(G_{0}, G_{1}\right) \in\left(\mathcal{G}^{*} \times \mathcal{G}\right)$ and let $\delta=d_{\mathcal{H}}\left(G_{0}, G_{1}\right)$. Then, there exist tests $\left\{\varphi_{m, n}\right\}$ that have the following properties:

$$
\begin{align*}
P_{\mathcal{S}_{[n]} \mid G_{0}}^{m} \varphi_{m, n} & \leq D \exp \left[-m \Psi_{\mathcal{G}, n}(\delta) / 8\right],  \tag{16}\\
\sup _{G \in \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \delta / 2\right)} P_{\mathcal{S}_{[n]} \mid G}^{m}\left(1-\varphi_{m, n}\right) & \leq \exp \left[-m \Psi_{\mathcal{G}, n}(\delta) / 8\right] . \tag{17}
\end{align*}
$$

Here, $D:=D\left(\Phi_{\mathcal{G}, n}(\delta), \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \delta / 2\right), d_{\mathcal{H}}\right)$, i.e., the maximal number of elements in $\mathcal{G} \cap$ $B_{d_{\mathcal{H}}}\left(G_{1}, \delta / 2\right)$ that are mutually separated by at least $\Phi_{\mathcal{G}, n}(\delta)$ in Hausdorff metric $d_{\mathcal{H}}$.

Proof. We begin the proof by noting that a direct application of standard results on existence of tests (cf. [11], Chapter 4) is not possible, due to the lack of convexity of the space of densities of $\mathcal{S}_{[n]}$ as $G$ varies in some subset $\mathcal{G} \subset \mathcal{G}^{*}$, even if $\mathcal{G}$ is convex. This difficulty is overcome by appealing to a packing argument.

Consider a maximal $\Phi_{\mathcal{G}, n}(\delta)$-packing in $d_{\mathcal{H}}$ metric for the set $\mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \delta / 2\right)$. This yields a set of $D=D\left(\Phi_{\mathcal{G}, n}(\delta), \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \delta / 2\right), d_{\mathcal{H}}\right)$ elements $\tilde{G}_{1}, \ldots, \tilde{G}_{D} \in \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \delta / 2\right)$.

Next, we note the following fact: for any $t=1, \ldots, D$, if $G \in \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \delta / 2\right)$ and $d_{\mathcal{H}}\left(G, \tilde{G}_{t}\right) \leq \Phi_{\mathcal{G}, n}(\delta)$, then by the definition of $\Phi, h^{2}\left(p_{\mathcal{S}_{[n]} \mid G}, p_{S_{[n] \mid} \tilde{G}_{t}}\right) \leq \frac{1}{4} \Psi_{\mathcal{G}, n}(\delta)$. By the definition of Hellinger information, $h^{2}\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{S_{[n]} \mid \tilde{G}_{t}}\right) \geq \Psi_{\mathcal{G}, n}(\delta)$. Thus, by triangle inequality, $h\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{\mathcal{S}_{[n]} \mid G}\right) \geq \frac{1}{2} \Psi_{\mathcal{G}, n}(\delta)^{1 / 2}$.

For each pair of $G_{0}, \tilde{G}_{t}$ there exist tests $\omega_{n}^{(t)}$ of $p_{\mathcal{S}_{[n]} \mid G_{0}}$ versus the Hellinger ball $\mathcal{P}_{2}(t):=$ $\left\{p_{\mathcal{S}_{[n]} \mid G} \mid G \in \mathcal{G}^{*} ; h\left(p_{\mathcal{S}_{[n]} \mid G}, p_{S_{[n]} \mid \tilde{G}_{t}}\right) \leq \frac{1}{2} h\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{S_{[n]} \mid \tilde{G}_{t}}\right)\right\}$ such that,

$$
\begin{aligned}
P_{\mathcal{S}_{[n]} \mid G_{0}}^{m} \omega_{m, n}^{(t)} & \leq \exp \left[-m h^{2}\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{S_{[n]} \tilde{G}_{t}}\right) / 8\right], \\
\sup _{P_{2} \in \mathcal{P}_{2}(t)} P_{2}^{m}\left(1-\omega_{m, n}^{(t)}\right) & \leq \exp \left[-m h^{2}\left(p_{\mathcal{S}_{[n]} \mid G_{0}}, p_{S_{[n]} \mid \tilde{G}_{t}}\right) / 8\right] .
\end{aligned}
$$

Consider the test $\varphi_{m, n}=\max _{1 \leq t \leq D} \omega_{m, n}^{(t)}$, then

$$
\begin{aligned}
P_{\mathcal{S}_{[n]} \mid G_{0}}^{m} \varphi_{m, n} & \leq D \times \exp \left[-m \Psi_{\mathcal{G}, n}(\delta) / 8\right], \\
\sup _{G \in \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \delta / 2\right)} P_{\mathcal{S}_{[n]} \mid G}^{m}\left(1-\varphi_{m, n}\right) & \leq \exp \left[-m \Psi_{\mathcal{G}, n}(\delta) / 8\right] .
\end{aligned}
$$

The first inequality is due to $\varphi_{m, n} \leq \sum_{t=1}^{D} \omega_{m, n}^{(t)}$, and the second is due to the fact that for any $G \in \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \delta / 2\right)$ there is some $d=1, \ldots, D$ such that $d_{\mathcal{H}}\left(G, \tilde{G}_{t}\right) \leq \Phi_{\mathcal{G}, n}(\delta)$, so that $p_{\mathcal{S}_{[n]} \mid G} \in \mathcal{P}_{2}(t)$.

Next, the existence of tests can be shown for discriminating $G_{0}$ against the complement of a closed Hausdorff ball:

Lemma 9. Let $G_{0} \in \mathcal{G}^{*}$ and $\mathcal{G} \subset \mathcal{G}^{*}$. Suppose that for some non-increasing function $D(\varepsilon)$, some $\varepsilon_{m, n} \geq 0$ and every $\varepsilon>\varepsilon_{m, n}$,

$$
\begin{array}{rl}
\sup _{G_{1} \in \mathcal{G}} & D\left(\Phi_{\mathcal{G}, n}(\varepsilon), \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, \varepsilon / 2\right), d_{\mathcal{H}}\right) \\
& \times D\left(\varepsilon / 2, \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{0}, 2 \varepsilon\right) \backslash B_{W}\left(G_{0}, \varepsilon\right), d_{\mathcal{H}}\right) \leq D(\varepsilon) \tag{18}
\end{array}
$$

Then, for every $\varepsilon>\varepsilon_{m, n}$, and any $t_{0} \in \mathbb{N}$, there exist tests $\varphi_{m, n}$ (depending on $\varepsilon>0$ ) such that

$$
\begin{align*}
P_{G_{0}} \varphi_{m, n} & \leq D(\varepsilon) \sum_{t=t_{0}}^{\lceil\operatorname{Diam}(\mathcal{G}) / \varepsilon\rceil} \exp \left[-m \Psi_{\mathcal{G}, n}(t \varepsilon) / 8\right],  \tag{19}\\
\sup _{G \in \mathcal{G}: d_{\mathcal{H}}\left(G_{0}, G\right)>t_{0} \varepsilon} P_{G}\left(1-\varphi_{m, n}\right) & \leq \exp \left[-m \Psi_{\mathcal{G}, n}\left(t_{0} \varepsilon\right) / 8\right] . \tag{20}
\end{align*}
$$

Proof. The proof consists of a standard peeling device (e.g., [7]) and a packing argument as in the previous proof. For a given $t \in \mathbb{N}$ choose a maximal $t \varepsilon / 2$-packing for set $S_{t}=\{G$ : $t \varepsilon<$ $\left.d_{\mathcal{H}}\left(G_{0}, G\right) \leq(t+1) \varepsilon\right\}$. This yields a set $S_{t}^{\prime}$ of at most $D\left(t \varepsilon / 2, S_{t}, d_{\mathcal{H}}\right)$ points. Moreover, every $G \in S_{t}$ is within distance $t \varepsilon / 2$ of at least one of the points in $S_{t}^{\prime}$. For every such point $G_{1} \in S_{t}^{\prime}$, there exists a test $\omega_{m, n}$ satisfying Equations (16) and (17), where $\delta$ is taken to be $\delta=t \varepsilon$. Take $\varphi_{m, n}$ to be the maximum of all tests attached this way to some point $G_{1} \in S_{t}^{\prime}$ for some $t \geq t_{0}$.

Note that $G \in \mathcal{G} \subset \Delta^{d}$, so $t \leq\lceil\operatorname{Diam}(\mathcal{G}) / \varepsilon\rceil$. Then, by union bound, and the condition that $D(\varepsilon)$ is non-increasing,

$$
\begin{aligned}
& P_{\mathcal{S}_{[n]} \mid G_{0}}^{m} \varphi_{m, n} \leq \sum_{t=t_{0}}^{\lceil\operatorname{Diam}(\mathcal{G}) / \varepsilon\rceil} \sum_{G_{1} \in S_{t}^{\prime}} D\left(\Phi_{\mathcal{G}, n}(t \varepsilon), \mathcal{G} \cap B_{d_{\mathcal{H}}}\left(G_{1}, t \varepsilon / 2\right), d_{\mathcal{H}}\right) \\
& \times \exp \left[-m \Psi_{\mathcal{G}, n}(t \varepsilon) / 8\right] \\
& \leq D(\varepsilon) \sum_{t \geq t_{0}} \exp \left[-m \Psi_{\mathcal{G}, n}(t \varepsilon) / 8\right]
\end{aligned}
$$

and

$$
\begin{aligned}
\sup _{G \in \bigcup_{u \geq t_{0}} S_{u}} P_{\mathcal{S}_{[n]} \mid G}^{m}\left(1-\varphi_{n}\right) & \leq \sup _{u \geq t_{0}} \exp \left[-m \Psi_{\mathcal{G}, n}(u \varepsilon) / 8\right] \\
& \leq \exp \left[-m \Psi_{\mathcal{G}, n}\left(t_{0} \varepsilon\right) / 8\right]
\end{aligned}
$$

where the last inequality is due the monotonicity of $\Psi_{\mathcal{G}, n}(\cdot)$.
Proof of the abstract posterior contraction theorem (Theorem 4). In this proof, to simplify notations denote $P_{G}:=P_{\mathcal{S}_{[n]} \mid G}$. By a result of Ghosal et al. [7] (Lemma 8.1, page 524), for every $\varepsilon>0, C>0$ and every probability measure $\Pi_{0}$ supported on the set $B_{K}\left(G_{0}, \varepsilon\right)$ defined by Equation (7), we have,

$$
P_{G_{0}}\left(\int \prod_{i=1}^{m} \frac{p_{G}\left(\mathcal{S}_{[n]}^{i}\right)}{p_{G_{0}}\left(\mathcal{S}_{[n]}^{i}\right)} \mathrm{d} \Pi_{0}(G) \leq \exp \left(-(1+C) m \varepsilon^{2}\right)\right) \leq \frac{1}{C^{2} m \varepsilon^{2}}
$$

This entails that, by fixing $C=1$, there is an event $A_{m}$ with $P_{G_{0}}^{m}$-probability at least $1-$ $\left(m \varepsilon_{m, n}^{2}\right)^{-1}$, for which there holds:

$$
\begin{equation*}
\int \prod_{i=1}^{n} p_{G}\left(\mathcal{S}_{[n]}^{i}\right) / p_{G_{0}}\left(\mathcal{S}_{[n]}^{i}\right) \mathrm{d} \Pi(G) \geq \exp \left(-2 m \varepsilon_{m, n}^{2}\right) \Pi\left(B_{K}\left(G_{0}, \varepsilon_{m, n}\right)\right) \tag{21}
\end{equation*}
$$

Let $\mathcal{O}_{m}=\left\{G \in \mathcal{G}^{*}: d_{\mathcal{H}}\left(G_{0}, G\right) \geq M_{m} \varepsilon_{m, n}\right\}$. Due to Equation (8), the condition specified by Lemma 9 is satisfied by setting $D(\varepsilon)=\exp \left(m \varepsilon_{m, n}^{2}\right)$ (constant in $\varepsilon$ ). Thus, there exist tests $\varphi_{m, n}$ for which Equations (19) and (20) hold with respect to $\mathcal{G}=\operatorname{supp} \Pi$ and the given $G_{0}$. Then,

$$
\begin{aligned}
P_{G_{0}} \Pi\left(G \in \mathcal{O}_{m} \mid \mathcal{S}_{[n]}^{[m]}\right)= & P_{G_{0}}\left[\varphi_{m, n} \Pi\left(G \in \mathcal{O}_{m} \mid \mathcal{S}_{[n]}^{[m]}\right)\right]+P_{G_{0}}\left[\left(1-\varphi_{m, n}\right) \Pi\left(G \in \mathcal{O}_{m} \mid \mathcal{S}_{[n]}^{[m]}\right)\right] \\
\leq & P_{G_{0}}\left[\varphi_{m, n} \Pi\left(G \in \mathcal{O}_{m} \mid \mathcal{S}_{[n]}^{[m]}\right)\right]+P_{G_{0}} \mathbb{I}\left(A_{m}^{c}\right) \\
& +P_{G_{0}}\left[\left(1-\varphi_{m, n}\right) \Pi\left(G \in \mathcal{O}_{m} \mid \mathcal{S}_{[n]}^{[m]}\right) \mathbb{I}\left(A_{m}\right)\right]
\end{aligned}
$$

Applying Lemma 9, the first term in the preceding display is bounded above by

$$
P_{G_{0}} \varphi_{m, n} \leq D\left(\varepsilon_{m, n}\right) \sum_{j \geq M_{m}} \exp \left[-m \Psi_{\mathcal{G}, n}\left(j \varepsilon_{m, n}\right) / 8\right] \rightarrow 0
$$

thanks to Equation (11). The second term in the above display is bounded by $\left(m \varepsilon_{m, n}^{2}\right)^{-1}$ by the definition of $A_{m}$, so this term vanishes. It remains to show that third term in the display also vanishes as $m \rightarrow \infty$. By Bayes' rule,

$$
\Pi\left(G \in \mathcal{O}_{m} \mid \mathcal{S}_{[n]}^{[m]}\right)=\frac{\int_{\mathcal{O}_{m}} \prod_{i=1}^{m} p_{G}\left(\mathcal{S}_{[n]}^{i}\right) / p_{G_{0}}\left(\mathcal{S}_{[n]}^{i}\right) \mathrm{d} \Pi(G)}{\int \prod_{i=1}^{m} p_{G}\left(\mathcal{S}_{[n]}^{i}\right) / p_{G_{0}}\left(\mathcal{S}_{[n]}^{i}\right) \mathrm{d} \Pi(G)},
$$

and then obtain a lower bound for the denominator by Equation (21). For the nominator, by Fubini's theorem:

$$
\begin{align*}
& P_{G_{0}} \int_{\mathcal{O}_{m} \cap \mathcal{G}}\left(1-\varphi_{m, n}\right) \prod_{i=1}^{m} p_{G}\left(\mathcal{S}_{[n]}^{i}\right) / p_{G_{0}}\left(\mathcal{S}_{[n]}^{i}\right) \mathrm{d} \Pi(G) \\
& \quad=\int_{\mathcal{O}_{m} \cap \mathcal{G}} P_{G}\left(1-\varphi_{m, n}\right) \mathrm{d} \Pi(G) \leq \exp \left[-m \Psi_{\mathcal{G}, n}\left(M_{m} \varepsilon_{m, n}\right) / 8\right] \tag{22}
\end{align*}
$$

where the last inequality is due to Equation (20).
Now, combining bounds (22) and (21) with condition (10), we obtain:

$$
\begin{aligned}
& P_{G_{0}}\left(1-\varphi_{m, n}\right) \Pi\left(G \in \mathcal{O}_{m} \mid \mathcal{S}_{[n]}^{[m]}\right) \mathbb{I}\left(A_{m}\right) \\
& \quad \leq \frac{\exp \left[-m \Psi_{G_{0}, n}\left(\mathcal{G}_{m}, M_{m} \varepsilon_{m, n}\right) / 8\right]}{\exp \left(-2 m \varepsilon_{m, n}^{2}\right) \Pi\left(B_{K}\left(G_{0}, \varepsilon_{m, n}\right)\right)} .
\end{aligned}
$$

The upper bound in the preceeding display converges to 0 by Equation (10), thereby concluding the proof.

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