

PRECISE TIME DELAYS FROM STRONGLY GRAVITATIONALLY LENSED TYPE IA SUPERNOVAE WITH CHROMATICALLY MICROLENSSED IMAGES

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ABSTRACT

Time delays between the multiple images of strongly lensed Type Ia supernovae (gIa) have the potential to deliver precise cosmological constraints, but the effects of microlensing on the measurement have not been studied in detail. Here we quantify the effect of microlensing on the gIa yield of the Large Synoptic Survey Telescope (LSST) and the effect of microlensing on the precision and accuracy of time delays that can be extracted from LSST gIa. Microlensing has a negligible effect on the LSST gIa yield, but it can be increased by a factor of ~ 2 to 930 systems using a novel photometric identification technique based on spectral template fitting. Crucially, the microlensing of gIa is achromatic until 3 rest-frame weeks after the explosion, making the early-time color curves microlensing-insensitive time delay indicators. By fitting simulated flux and color observations of microlensed gIa with their underlying, unlensed spectral templates, we forecast the distribution of absolute time delay error due to microlensing for LSST, which is unbiased at the sub-percent level and peaked at 1% for color curve observations in the achromatic phase, while for light curve observations it is comparable to state-of-the-art mass modeling uncertainties (4%). About 70% of LSST gIa images should be discovered during the achromatic phase, indicating that microlensing time delay uncertainties can be minimized if prompt multicolor follow-up observations are obtained. Accounting for microlensing, the 1–2 day time delay on the recently discovered gIa iPTF16geu can be measured to 40% precision, limiting its cosmological utility.

Keywords: Supernovae: general — gravitational lensing: strong — gravitational lensing: micro

1. INTRODUCTION

Since the discovery of cosmic acceleration (Riess et al. 1998; Perlmutter et al. 1999), Λ CDM has become the observationally favored cosmology, implying that the universe is spatially flat, that it contains cold dark matter and baryons, and that its accelerated expansion is driven by a cosmological constant. Recently, a deviation from Λ CDM was reported by Riess et al. (2016), whose measurement of the Hubble constant H_0 using the cosmic distance ladder is in 3.4σ tension with the value inferred from the cosmic microwave background (CMB; Planck Collaboration et al. 2016), assuming a Λ CDM cosmology and the standard model of particle physics. Independent measurements of H_0 with percent-level accuracy are necessary to determine whether the discrepancy is due to new physics (e.g., a new neutrino species; Riess et al. 2016; Bonvin et al. 2017) or to systematics.

Strong gravitational lensing is an independent probe of the cosmological parameters (Oguri et al. 2012; Suyu et al. 2013; Collett & Auger 2014). Time delays between multiple images of strongly gravitationally lensed variable sources are particularly sensitive to H_0 , making

them ideal tools to test this discrepancy. They also are sensitive to other parameters of the cosmological model, such as the dark energy equation of state and its evolution with redshift (Linder 2004, 2011; Treu & Marshall 2016).

Measuring cosmological parameters to percent level accuracy with strong lens time delays requires three main ingredients (Suyu et al. 2017). First, one must measure the time delays (e.g. Tewes et al. 2013; Bonvin et al. 2017). Second, the lensing potential must be inferred to convert the observed time delays into measurements of the time delay distance (e.g., Wong et al. 2017). This relies on reconstruction of the extended features of a lensed host. Finally, the effect of weak lensing by mass close to the lens and along the line of sight must be included (e.g., Suyu et al. 2010; Collett et al. 2013; Rusu et al. 2017; McCully et al. 2017), since lenses are typically found in overdense regions of the universe (Fassnacht et al. 2011).

To date, time delay cosmography has only been attempted with strongly lensed active galactic nuclei (AGNs; e.g., Vuissoz et al. 2008; Suyu et al. 2013; Tewes et al. 2013; Bonvin et al. 2016). Lensed AGNs complicate these ingredients, making percent-level constraints on H_0 difficult. Because the light curves of AGNs are stochastic and heterogeneous, they typically require years of cadenced monitoring to yield precise time delays (Liao et al. 2015). Inferring the lensing potential by reconstructing the lensed host light is challenging since AGNs typically outshine their host galaxies by several magnitudes. Detecting lensed AGNs requires observations of multiple images introducing a selection function for larger Einstein radii and hence an overdense line of sight (Collett & Cunningham 2016), leading to systematic overestimates

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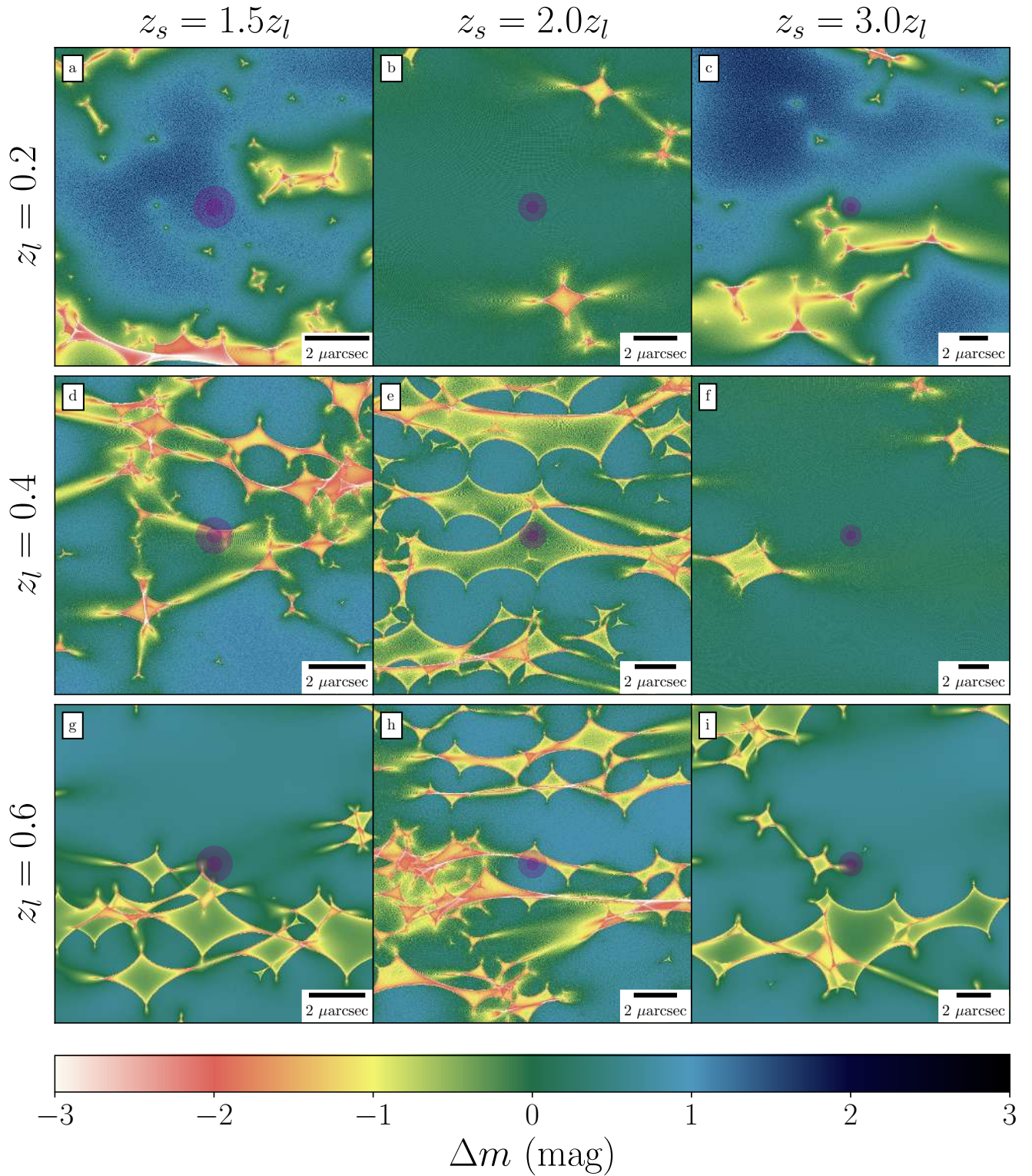


Figure 1. Source-plane magnification patterns of nine of 78,184 the lens galaxy star fields considered in this analysis. Each panel consists of $1,000^2$ pixels and has a side length of 10 times the Einstein radius of a $1M_\odot$ deflector projected onto the source plane. The detailed parameters of each map are given in Table 1. The size of the exterior shell ($4 \times 10^4 \text{ km s}^{-1}$) of the SN Ia model W7 at 20 (50) days after explosion is plotted as the interior (exterior) purple circle at the center of each map. Negative (positive) Δm indicates magnification (demagnification) over the value from a smooth mass model without microlensing.

of H_0 .

In contrast, the light curves of Type Ia supernovae (SNe Ia) are remarkably homogeneous, and strongly lensed SN Ia (glSN Ia) light curves evolve over weeks, not years, allowing their time delays to be measured with far less observational overhead than those of AGNs. In addition, glSNe Ia fade away, allowing a simpler reconstruction of the lensed hosts. glSNe Ia can be detected without resolving multiple images (Goobar et al. 2017), simplifying the selection function. Because glSNe Ia are standardizable candles, they also have the potential to directly determine the lensing magnification factor μ , which breaks the degeneracy between the lens potential and the Hubble constant (Oguri & Kawano 2003), if the microlensing and macrolensing magnifications can be separated. The well known spectral energy distributions (SEDs) of SNe Ia also allow one to correct for extinction along the paths of each SN Ia image—another major advantage over AGNs.

So far, only one glSN Ia, iPTF16geu, has been discovered with resolved images (Goobar et al. 2017). However, future surveys, especially the Large Synoptic Survey Telescope (LSST; LSST Science Collaboration et al. 2009), are expected to discover hundreds (Goldstein & Nugent 2017). Thus the prospects for discovering a sufficient number of glSNe Ia to perform time-delay cosmography in the near future are good.

However, there is a foreground that threatens this outlook: microlensing. It has long been known that lens galaxy field stars can significantly magnify and demagnify cosmologically distant background AGNs (Chang & Refsdal 1979) and supernovae (Dobler & Keeton 2006; Bagherpour et al. 2006). In the microlensing scenario, different macroimages of the same source propagate through different regions of the lens galaxy, passing through distinct lens galaxy star fields. The star fields possess rich networks of caustics that introduce magnification patterns into the source plane. These patterns vary over characteristic angular scales of microarcseconds (hence “microlensing,” see Figure 1), which are typically comparable to the physical sizes of supernovae and AGNs. Thus, as a strongly lensed supernova expands over the source plane, it can experience time- and wavelength-dependent magnifications unique to each lensed image, distorting their light curves and spectra in different ways. These distortions can make it harder to “match up” the light curves of multiple images and extract an accurate time delay.⁷

Microlensing of lensed variable sources is more than a theoretical exercise: it has been reported in many strongly lensed quasars (e.g., Kayser et al. 1986), and there is also evidence that it affects the images of iPTF16geu (More et al. 2017). Dobler & Keeton (2006) estimated that microlensing can introduce uncertainties of several days into the features of supernova light curves that can yield time delays. Typical time delays for glSNe Ia are a couple of weeks (Goldstein & Nugent 2017), translating to a typical fractional time delay uncertainty of (a few days) / (two weeks) $\sim 20\%$. At this

⁷ N.B. The general relativistic time delays introduced by microlensing into macroimages are of order microseconds (Moore & Hewitt 1996)—too small to detect. The uncertainty microlensing introduces into time delays is solely due to time- and wavelength-dependent distortions of macroimage light curves and spectra.

Table 1
Properties of the magnification patterns in Figure 1.

	κ	f_*	γ	q	$\langle\mu\rangle$
a	1.30	0.84	1.30	0.20	0.63
b	0.24	0.35	0.25	0.10	1.93
c	1.25	0.83	1.26	0.20	0.65
d	0.87	0.72	0.93	1.00	1.19
e	0.75	0.80	0.76	1.00	1.96
f	0.30	0.38	0.27	1.00	2.39
g	0.36	0.49	0.33	1.00	3.30
h	0.84	0.72	0.79	0.10	1.66
i	0.37	0.50	0.31	1.00	3.29

Note. — κ : local convergence. f_* : fraction of surface density in stars. γ : local shear. q : mass ratio m_{min}/m_{max} of the stellar mass function. $\langle\mu\rangle$: magnification of the field from a smooth mass model without microlensing.

precision, ~ 400 glSN Ia time delays would be required to reach a 1% uncertainty on H_0 , assuming no other sources of error, whereas a single glSN Ia time delay with 1% precision could accomplish the same goal. Thus, controlling microlensing is of critical importance to the success of time delay cosmography with glSNe Ia.

If, as proposed by Goldstein & Nugent (2017), the microlensing magnification affects all wavelengths equally (i.e., if it is “achromatic”)—then one could use the color curves of glSNe Ia instead of the broadband light curves to extract time delays even if the images are affected by microlensing. For example, for a given image, if the B -band is macro- and microlensed as much as the U -band, then in the $U - B$ color curve, the micro- and macrolensing magnifications will both cancel out, leaving features common to the color curves of all images that can pin down the time delays to high precision. This would enable color curves of different images to be compared meaningfully, yielding time delays with less uncertainty.

In this article, we use detailed radiation transport simulations of a well-understood SN Ia model to assess the viability of extracting time delays from the color curves of glSNe Ia to circumvent the effects of microlensing. We also perform the first glSN Ia yield calculation that takes microlensing into account. The structure of the paper is as follows. In Section 2, we describe the radiation transport, glSN Ia population, and microlensing models used to synthesize representative microlensed glSN Ia SEDs. In Section 3, we present the results of our simulations and use them to show that the microlensing of glSNe Ia exhibits an achromatic phase at early times. In Section 4, we present a novel spectral template-based glSN Ia photometric detection technique and use it to forecast the glSN Ia yield of LSST. In Section 5, we forecast the time delay uncertainty due to microlensing and show that it can be controlled to 1% for typical LSST systems. We conclude in Section 6. Throughout this paper we assume a Planck Collaboration et al. (2016) cosmology with $\Omega_\Lambda = 0.6925$, $\Omega_m = 0.3075$, and $h = 0.6774$.

2. POPULATION, RADIATION TRANSPORT, AND MICROLENSING SIMULATIONS

In this section, we describe the simulation framework we use to generate a realistic population of gISNe Ia. First, the framework realizes a population of unlensed SNe Ia and elliptical galaxy lenses using measured redshift distributions. It solves the lens equation for supernovae and lenses close together on the sky, and when a multiply imaged system is produced, it yields image multiplicities, time delays, magnifications, and image positions. For each lensed supernova image, the framework generates a microlensing magnification pattern based on the image properties. A theoretical SN Ia spectral time series is convolved with the magnification pattern, giving the lensing amplification of the supernova SED as a function of time and wavelength. This in turn is applied to an empirical SN Ia SED template. Realistic LSST light curves are generated from these microlensed spectral templates and fed to a novel detection algorithm.

2.1. The Strongly Lensed Type Ia Supernova Population

In the present analysis we use the same gISN Ia population model as Goldstein & Nugent (2017). We consider only elliptical galaxy lenses and model their mass distribution as a Singular Isothermal Ellipsoid (SIE; Kormann et al. 1994), which has shown excellent agreement with observations (e.g., Koopmans et al. 2009). The SIE convergence κ is given by:

$$\kappa(x, y) = \frac{\theta_E}{2} \frac{\lambda(e)}{\sqrt{(1-e)^{-1}x^2 + (1-e)y^2}}, \quad (1)$$

where

$$\theta_E = 4\pi \left(\frac{\sigma}{c}\right)^2 \frac{D_{ls}}{D_s}. \quad (2)$$

In the above equations, σ is the velocity dispersion of the lens galaxy, e is its ellipticity, and $\lambda(e)$ is its so-called ‘‘dynamical normalization,’’ a parameter related to three-dimensional shape. Here we make the simplifying assumption that there are an equal number of oblate and prolate galaxies, which Chae (2003) showed implies $\lambda(e) \simeq 1$. As in Oguri et al. (2008), we assume e follows a truncated normal distribution on the interval $[0.0, 0.9]$, with $\mu_e = 0.3$, $\sigma_e = 0.16$.

We also include external shear to account for the effect of the lens environment (e.g., Kochanek 1991; Keeton et al. 1997; Witt & Mao 1997). We assume $\log_{10} \gamma_{\text{ext}}$ follows a normal distribution with mean -1.30 and scale 0.2 , consistent with the level of external shear expected from ray tracing in N -body simulations (Holder & Schechter 2003). The orientation of the external shear is assumed to be random.

We model the velocity distribution of elliptical galaxies as a modified Schechter function (Sheth et al. 2003):

$$dn = \phi(\sigma)d\sigma = \phi_* \left(\frac{\sigma}{\sigma_*}\right)^\alpha \exp\left[-\left(\frac{\sigma}{\sigma_*}\right)^\beta\right] \frac{\beta}{\Gamma(\alpha/\beta)} \frac{d\sigma}{\sigma}, \quad (3)$$

where Γ is the gamma function, and dn is the differential number of galaxies per unit velocity dispersion per unit comoving volume. We use the parameter values of Choi et al. (2007) from the Sloan Digital Sky Survey (SDSS; York et al. 2000): $(\phi_*, \sigma_*, \alpha, \beta) = (8 \times 10^{-3} h^3 \text{ Mpc}, 161 \text{ km s}^{-1}, 2.32, 2.67)$. We assume

the mass distribution and velocity function do not evolve with redshift, consistent with the results of Chae (2007), Oguri et al. (2008), and Bezanson et al. (2011).

To convert Equation 3 into a redshift distribution, we use the definition of the comoving volume element:

$$dV_C = D_H \frac{(1+z)^2 D_A^2}{E(z)} dz d\Omega, \quad (4)$$

where $D_H = c/H_0$ is the Hubble distance, $E(z) = \sqrt{\Omega_M(1+z)^3 + \Omega_\Lambda}$ in our assumed cosmology, and D_A is the angular diameter distance. Since $dn = dN/dV_C$, for the unnormalized all-sky ($d\Omega = 4\pi$) galaxy distribution we have

$$\frac{dN}{d\sigma dz} = 4\pi D_H \frac{(1+z)^2 D_A^2}{E(z)} \phi(\sigma). \quad (5)$$

Integrating Equation 3 over $0 \leq z \leq 1$ and $10^{1.7} \text{ km s}^{-1} \leq \sigma \leq 10^{2.6} \text{ km s}^{-1}$, we find that there are $N_{\text{gal}} \simeq 3.8 \times 10^8$ elliptical galaxies, all sky, that can act as strong lenses. This gives the joint probability density function for σ and z :

$$p(\sigma, z) = \frac{1}{N_{\text{gal}}} \frac{dN}{d\sigma dz}. \quad (6)$$

SNe Ia exhibit a redshift-dependent volumetric rate and an intrinsic dispersion in rest-frame M_B . In our model of the SN Ia population, we take the redshift-dependent SN Ia rate from Sullivan et al. (2000). We assume that the peak rest-frame M_B is normally distributed with $\mu_M = -19.3$ and $\sigma_M = 0.2$. For simplicity, we neglect extinction.

The lens and source populations are realized in a Monte Carlo simulation. We generate 10^5 lens galaxies with parameters drawn at random from their underlying distributions. For each lens galaxy, an effective lensing area of influence is estimated as a $[8\theta_{E, z_s=\infty}]^2$ box centered on the galaxy.⁸ We simulate 5×10^4 years of SNe Ia, randomly distributed across the box, rejecting systems where $z_s < z_l$. For each remaining source, we solve the lens equation using glafic (Oguri 2010) to determine the macrolensing magnification, image multiplicity, and time delays. In total we generated 37,100 multiply imaged systems containing a total of 78,184 images. Since our simulation only covers $10^5/N_{\text{gal}} \approx 0.026\%$ of the sky, this corresponds to a rate of 2,675 systems, all sky, per year to $z_s = 2$.

2.2. Microlensing Magnification Patterns

For each image we calculate a source-plane magnification pattern with microlens (Wambsganss 1990, 1999), an inverse ray-tracing code. In this scheme, stars modeled as point-mass deflectors are realized from a mass function at random locations in a two-dimensional field of the lens galaxy. The size of the pattern is characterized by the Einstein radius \bar{R}_E of a deflector of mass \bar{m} projected onto the source plane,

$$\bar{R}_E = \sqrt{\frac{4G\bar{m}}{c^2} \frac{D_{ls}D_s}{D_l}}, \quad (7)$$

⁸ This box size was chosen to be large enough to accommodate the effects of ellipticity and external shear.

where D_l is the angular diameter distance to the lens, D_s is the angular diameter distance to the source, and D_{ls} is the angular diameter distance between the lens and the source. Our magnification patterns are $10\bar{R}_E$ on a side, which for typical source and lens redshifts ($z_s = 1.2, z_l = 0.6$) corresponds to an angular scale of $10\bar{R}_E/D_s \approx 1.5 \times 10^{-5}$ arcsec. At the same redshifts, $\bar{R}_E \approx 2.7 \times 10^3$ AU, which is roughly 5 times larger than the extent of the supernova model near peak brightness.

The magnification patterns are specified by four parameters: (1) the local convergence, κ , (2) the local shear, γ , including the contributions of both the SIE and external potentials, (3) the fraction of the local convergence in stars, f_* ,⁹ and (4) the dynamic range of the stellar mass function, $q = m_{min}/m_{max}$. Supplying these parameters allows `microlens` to solve the general microlensing equation, $\beta = \theta - \alpha$, which resolves to

$$\beta = \begin{pmatrix} 1 - \gamma - \kappa_c & 0 \\ 0 & 1 + \gamma - \kappa_c \end{pmatrix} \theta - \sum_{i=1}^{N_*} \frac{M_i(\theta - \theta_i)}{(\theta - \theta_i)^2}, \quad (8)$$

where $\kappa_c = (1 - f_*)\kappa$ is the local convergence in continuously distributed matter, the two-dimensional vector β is the angular position of the source in the absence of lensing, θ is the angular position of the observed macroimage, θ_i is the angular position of the i 'th star, and N_* is the number of stars in the field, determined from the local convergence in stars $\kappa_* = f_*\kappa$ using the procedure of [Schneider & Weiss \(1987\)](#).

We use a [Salpeter \(1955\)](#) mass function, $dn/dm \propto m^{-2.35}$, to model the population of stars in our microlensing calculations. As we will show in [Section 3](#), this choice has no effect on our results as the achromaticity of gISN Ia microlensing is driven entirely by the color evolution of SNe Ia and not by the properties of the microlensing magnification patterns. Following [Dobler & Keeton \(2006\)](#), we take the mean mass $\bar{m} = 1M_\odot$. The microlensing parameters κ and γ are determined by evaluating the SIE and external shear lensing potentials at the location of each image. f_* is estimated following the method of [Dobler & Keeton \(2006\)](#), assuming a de Vaucouleurs stellar profile normalized so that the maximum $f_* = 1$. For each image, the dynamic range parameter q is sampled uniformly at random from (0.1, 0.2, 0.5, 1.0), appropriate for the old stellar populations in elliptical galaxies. [Figure 1](#) shows a random selection of nine of the maps, highlighting their morphological diversity. [Figure 2](#) shows two dimensional projections of the joint distributions of the macrolensing parameters σ , e , and γ_{ext} , the microlensing parameters κ , γ , and f_* , and the time- and wavelength-averaged microlensing magnification μ_{ML} .

2.3. Supernova Modeling

We use the well-understood, spherically symmetric¹⁰ SN Ia atmosphere model W7 ([Nomoto et al. 1984](#)) to estimate the time- and wavelength-dependent magnification of gISNe Ia due to microlensing. This radiation transport model is the result of a one-dimensional explosion simulation in which a Chandrasekhar-mass carbon-oxygen

white dwarf undergoes a deflagration. The explosion of the white dwarf completely unbinds the star and deposits the energy liberated by nuclear burning into the ejected mass. The deposited energy controls the velocity distribution of the ejecta and its density profile, which is assumed to reach homology seconds after the explosion. We use the time-dependent, Monte Carlo radiation transport code `SEDONA` ([Kasen et al. 2006](#)) to calculate the spectral time series of the model. Details of our `SEDONA` simulations appear in [Appendix A](#).

The observed spectrum F_λ of the model at wavelength λ and time t is obtained by convolving its time-evolving specific intensity with the lensing amplification pattern over a plane normal to the observer's line of sight. Since the model is spherical, this integral takes the form:

$$F_\lambda(\lambda, t) = D_L^{-2} \int_0^{2\pi} \int_0^{P_m} I_\lambda(P, \phi, \lambda, t) \mu(P, \phi) P dP d\phi, \quad (9)$$

where ϕ and P are azimuthal and impact parameter coordinates on the plane, I_λ is the specific intensity of the model, μ is the lensing amplification,¹¹ D_L is the luminosity distance to the supernova, and P_m is the maximum impact parameter of the model. For a derivation of [Equation 9](#), see [Appendix B](#). The time- and wavelength-dependent magnification of a given magnification pattern is obtained by dividing F_λ by the unlensed spectrum of the model ([Equation 9](#) with $\mu = 1$).

We interpolate each magnification pattern bilinearly and convolve it with the redshifted¹² specific intensities of the supernova model. The redshift configurations control the projected size of the supernova on the magnification pattern and thus the magnification experienced by each differential element of the projected supernova atmosphere. They also control θ_E and thus κ , γ , and f_* at the location of the image. We always place the supernova model at the center of the magnification pattern. We model the homologous expansion of the supernova behind the magnification pattern (i.e., the projected size of the supernova on the magnification pattern changes with time), but not relative motion between the supernova and the lens galaxy star field. In general, supernova atmospheres both expand and move with respect to the lens galaxy, but the characteristic expansion velocity of the atmosphere ($\sim 10^4$ km s⁻¹) is much larger than the characteristic relative velocity between the lens galaxy and the supernova ($\sim 10^2$ km s⁻¹), so here we model only the effects of expansion.

3. TWO PHASES OF TYPE IA SUPERNOVA MICROLENSING

Example spectra and difference light curves of our microlensed SN Ia atmosphere appear in [Figures 3](#) and [4](#), respectively; confidence regions of all $U - B$, $B - V$, $V - R$, and $R - I$ color curves produced by our simulation appear in [Figure 5](#). The difference light curves give

⁹ The remainder of the convergence is assumed to take the form of continuously distributed matter (i.e., dark matter).

¹⁰ Spectropolarimetry indicates that SNe Ia are globally spherically symmetric to \sim a few percent. See [Wang & Wheeler \(2008\)](#).

¹¹ In this paper, μ refers exclusively to lensing amplification. Nowhere should μ be interpreted as $\mu = \cos\theta$, the viewing angle parameter that frequently appears in supernova modeling papers.

¹² We refer here to cosmological redshift only; Doppler shifts due to supernova expansion velocity are accounted for implicitly in the radiation transport simulation.

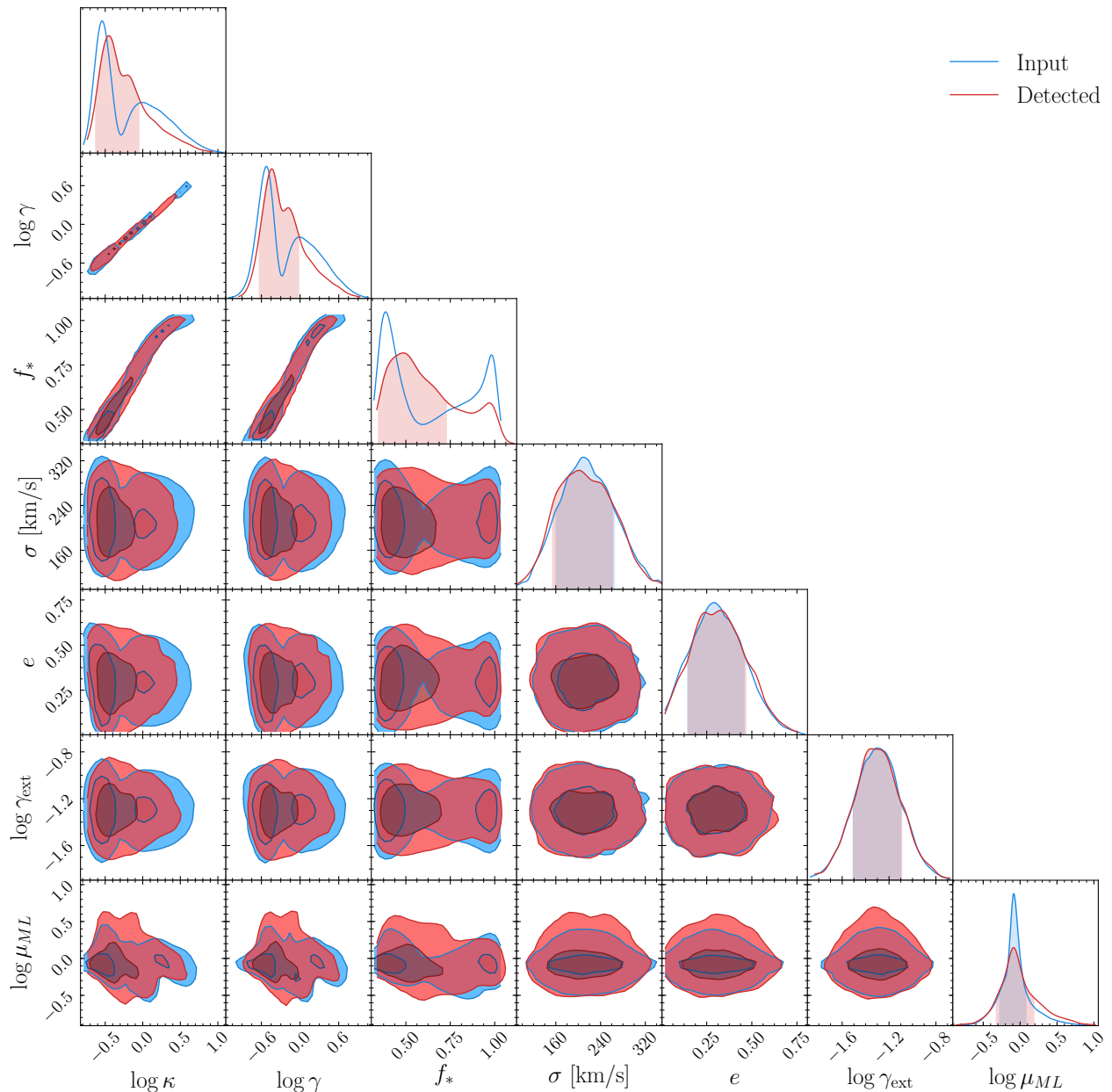


Figure 2. Two-dimensional projections of the joint distributions of lensed image macrolensing and microlensing parameters. The input distributions (blue) represent all 78,184 simulated lensed images from Section 2.1, and the detected distributions (red) represent only the images of the gISNe Ia detected in Section 4.2. The bimodal input distributions of f_* , γ , and κ represent the amplified ($f_* \approx 0.4$) and overfocussed ($f_* \approx 1$) images produced by SIE lenses. Joint contours show 1 and 2 σ . Marginal shaded regions show 1 σ .

the microlensing amplification in magnitudes,

$$\Delta M(t) = -2.5 \log_{10} \left(\frac{L(t)}{\mu_0 U(t)} \right), \quad (10)$$

where $U(t)$ and $L(t)$ are the unlensed and observed fluxes of the supernova, respectively, and μ_0 is the magnification in the absence of microlensing (i.e., if there were only macrolensing due to the lens galaxy). In the absence of microlensing, $\Delta M = 0$.

Each of these figures demonstrates that gISN Ia mi-

cro-lensing has two phases, an “achromatic” phase, in which the microlensing magnification is the same at all wavelengths to a few millimag, followed by a “chromatic” phase, in which the microlensing magnification varies strongly (and unpredictably) with wavelength. The difference light curves show that the achromatic phase lasts roughly 3 rest-frame weeks after the explosion, transitioning to a chromatic phase between the time of peak brightness and the onset of the infrared secondary maximum. During the achromatic phase, the light curves of

glSNe Ia can be deformed enough to bias time delay extraction; although ΔM is the same in all bands, it is not necessarily constant in time.

3.1. Physics of Achromatic and Chromatic SN Ia Microlensing

What is the physics responsible for the “achromatic” and “chromatic” phases of microlensing evident in Figures 4 and 5? Figure 6 shows the specific intensity profile $I_\lambda(v)$ of our unlensed model at 20 and 40 days after explosion, where v is the velocity of the shell, equivalent to a radial variable (i.e., P).¹³ The left panel of the figure shows that near peak (20 days after explosion), the ratio $I_{X_1}(v)/I_{X_2}(v)$, where X_1 and X_2 are any two bands, is roughly constant over all v . Thus the supernova near peak has a specific intensity profile that is independent of v up to an overall normalization factor. As a result, any magnification pattern $\mu(P, \phi)$ will not change its color.

However, after peak, the supernova expands and cools enough for some part of the atmosphere to reach a temperature of 7000K. Kasen (2006) and Kasen & Woosley (2007) note that this is the temperature at which Fe III recombines to Fe II, which presents a significantly higher opacity to blue and ultraviolet radiation than Fe III. This line blanketing has the effect of enabling one to see redder emission from deeper in the supernova, while emission in the blue and the UV is pushed to larger radii. Additionally, a “fluorescent shell” of iron recombination, which causes a peak in the redder bands in the specific intensity profile of the supernova, develops near the onset of the secondary maximum. This shell is clearly visible in the righthand panel of Figure 6. These two effects, line blanketing and a fluorescent shell, make the supernova’s specific intensity ratio no longer spatially constant. As a result, the supernova atmosphere becomes susceptible to chromatic fluctuations.

4. THE EFFECT OF MICROLENSING ON LSST LENSED TYPE IA SUPERNOVA YIELDS

Previous estimates of glSN Ia yields, including those of Oguri & Marshall (2010), Quimby et al. (2014), and Goldstein & Nugent (2017), modeled only the effects of macrolensing. In this section, we present a novel method of identifying glSNe Ia photometrically based on spectral template fitting. We apply this technique to our simulated micro- and macrolensed glSN Ia light curves to present a new estimate of glSN Ia yields for LSST.

4.1. Efficient Identification of Lensed Type Ia Supernovae with Spectral Template Fitting

Our detection strategy rests on three observational facts. First, normal SNe Ia are the brightest type of supernovae that have ever been observed to occur in elliptical galaxies (Maoz et al. 2014). Second, the absolute magnitudes of normal SNe Ia in elliptical galaxies are remarkably homogenous, even without correcting for their colors or lightcurve shapes ($\sigma_M \sim 0.4$ mag), with a component of the population being underluminous (Li et al. 2011). Finally, due to the sharp 4000Å break in their spectra, elliptical galaxies tend to provide accurate

photometric redshifts from large-scale multi-color galaxy surveys such as SDSS.

A high-cadence, wide-field imaging survey can leverage these facts to systematically search for strongly lensed SNe Ia in the following way. First, by spatially cross-matching its list of supernova candidates with a catalog of elliptical galaxies for which secure photometric redshifts have been obtained, supernovae that appear to be hosted by elliptical galaxies can be identified. The hypothesis that one of these supernovae actually resides in its apparent host can be tested by fitting its broadband light curves with an SN Ia spectral template (as SNe Ia are the only types of supernovae that occur in ellipticals) fixed to the photometric redshift of the galaxy and constrained to obey $-18.5 > M_B > -20$, a liberal absolute magnitude range for SNe Ia, assuming a fiducial cosmology. If the transient is a lensed supernova at higher redshift, then the spectral template fit will fail catastrophically, as the supernova light curves will be strongly inconsistent with the redshift and brightness implied by the lens galaxy.

4.2. Monte Carlo Simulation

We use SALT2 (Guy et al. 2007), a parametrized SN Ia spectral template that is the *de facto* standard tool to place SNe Ia on the Hubble diagram, to test this method. The template possesses four parameters: t_0 , x_0 , x_1 , and c , encoding a reference time, an overall SED normalization, a supernova “stretch,” and a color-law coefficient, respectively. The flux of the template is given by

$$F_\lambda(\lambda, t) = x_0[M_0(\lambda, t) + x_1M_1(\lambda, t)] \exp[cCL(\lambda)], \quad (11)$$

where M_0 and M_1 are eigenspectra derived from a training sample of measured SN Ia spectra and $CL(\lambda)$ is the average color-correction law of the sample (see Guy et al. 2007, for details). The template aims to model the mean evolution of the SED sequence of SNe Ia and its variation with a few dominant components, including a time independent variation with color, whether it is intrinsic or due to extinction by dust in the host galaxy (or both).

We consider an LSST lensed supernova search in which the photometry is performed with a PSF that is artificially enlarged to blend the multiple images together into a single source. We randomly assign each of the 37,100 simulated glSNe Ia from Section 2.1 an LSST field from the nominal observing strategy (`minion_1016`; LSST Science Collaborations in preparation).¹⁴ We compute the phase- and wavelength- dependent magnification $\mu(\lambda, t)$ of each lensed image by placing its corresponding microlensed W7 SED into the rest frame, then dividing each by the unlensed spectral sequence of the model. We then generate the rest-frame spectral model for the image $F(\lambda, t)$ according to

$$F(\lambda, t) = \mu(\lambda, t)H(\lambda, t), \quad (12)$$

where $H(\lambda, t)$ is the Hsiao et al. (2007) SN Ia spectral template. We employ a warped Hsiao template rather than the microlensed W7 SEDs to mitigate uncertainties in the radiation transport.¹⁵ We then place the templates of each image at their correct redshifts, and we rescale

¹³ As our model is spherically symmetric, I_λ possesses no ϕ dependence.

¹⁴ <https://github.com/LSSTScienceCollaborations/ObservingStrategy>

¹⁵ The Hsiao template is an empirical, time-dependent SED

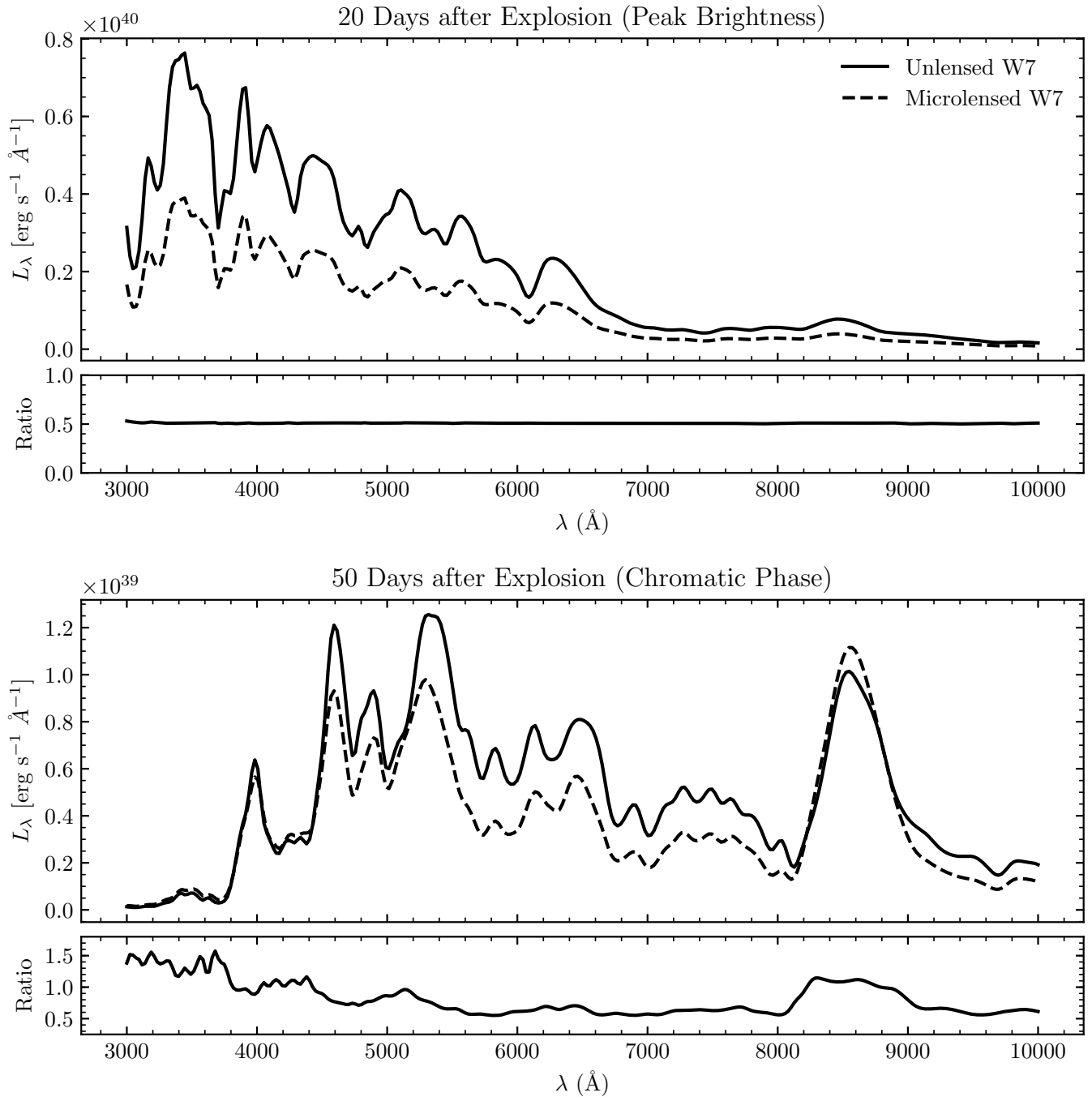


Figure 3. Rest-frame spectra of model W7 (Nomoto et al. 1984) computed with SEDONA near peak brightness and well into the onset of the infrared secondary maximum. The solid curve is unlensed and the dashed curve is lensed by star field (h) from Figure 1. Near peak brightness, microlensing does not have a large effect on the shape of the spectrum or the relative strengths of its features. During the chromatic phase, lensing-induced continuum shifts and spectral line distortions are visible in the ratios of the spectra. Such chromatic distortions can affect the colors of the supernova.

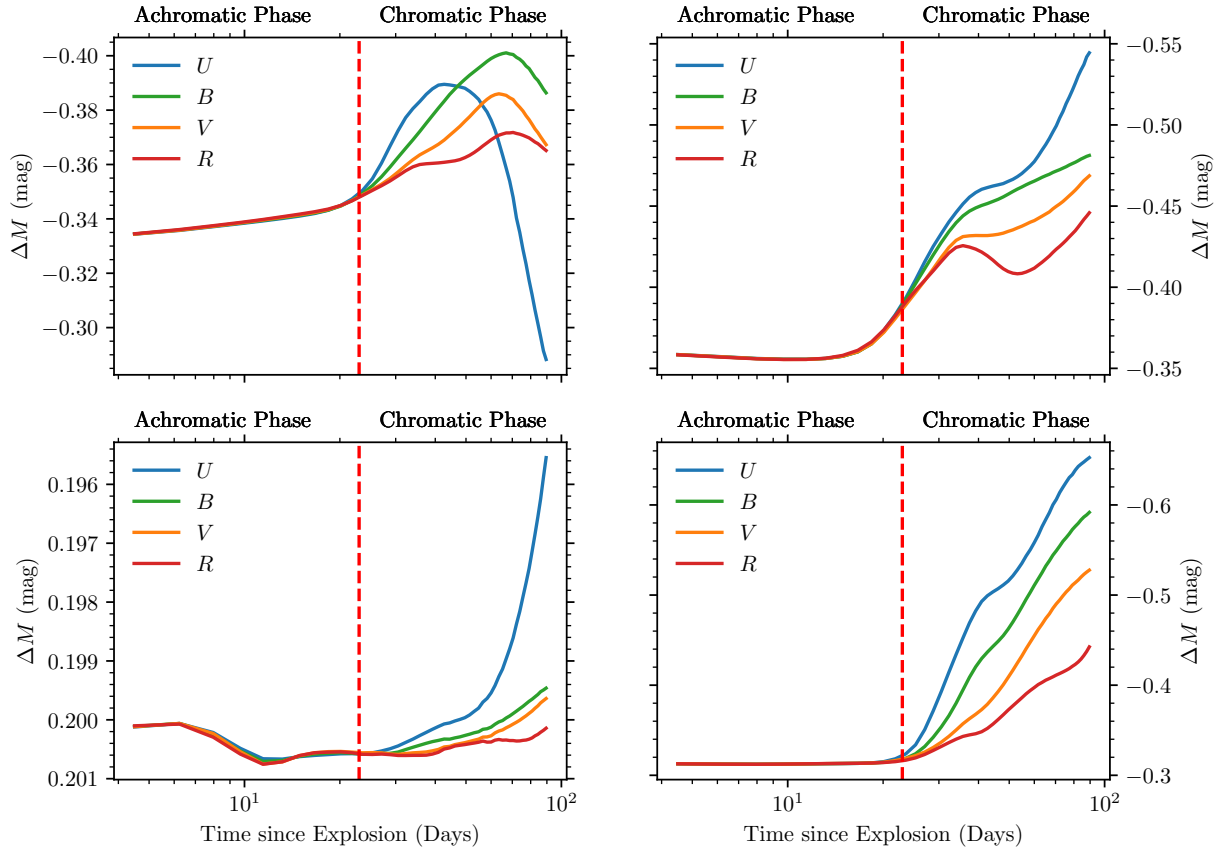


Figure 4. Four randomly chosen examples of broadband rest-frame difference light curves of model W7 computed by SEDONA. Each set of difference light curves has two distinct phases: an “achromatic” phase in which ΔM is the same in all bands to within a few millimag, and a “chromatic” phase in which ΔM can vary significantly from band to band.

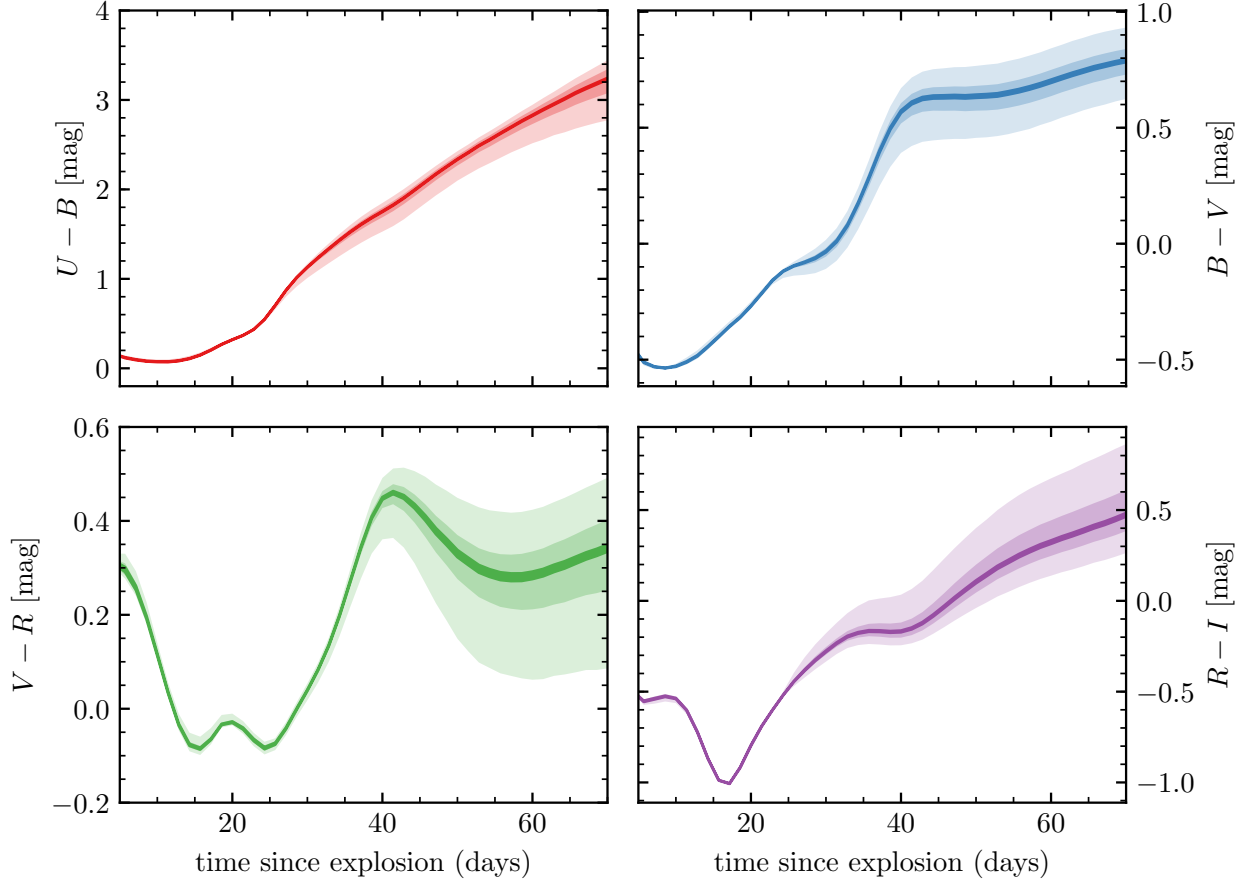


Figure 5. Rest-frame microlensed color curves of model W7. The intervals containing 68%, 95%, and 99% of the 78,184 microlensed color curves described in Section 3 are plotted as progressively less opaque shaded regions. The color curves of the unlensed model are indistinguishable from the 68% confidence regions of the microlensed models.

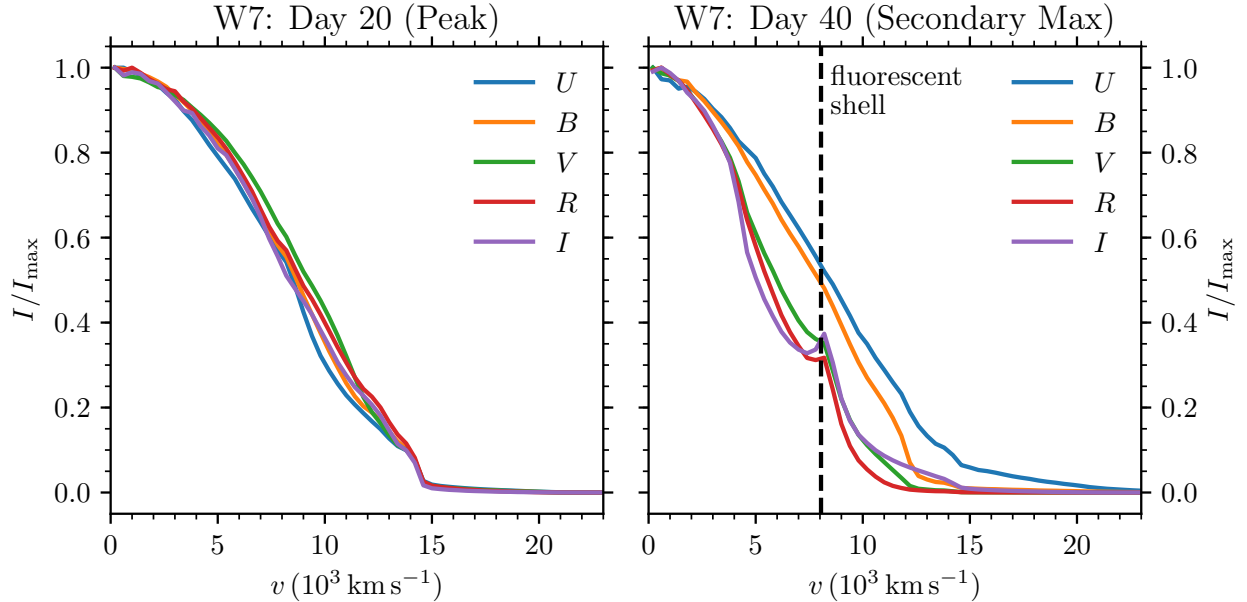


Figure 6. Normalized projected specific intensity profiles of model W7. Near peak, the specific intensity profiles in $UBVRI$ are similar, so microlensing is achromatic. At day 40, UV line blanketing and the “fluorescent shell” (in which $\text{Fe III} \rightarrow \text{Fe II}$ recombination occurs) causes different bands have different specific intensity profiles. As a result, microlensing is chromatic at this stage.

and time-shift them to account for the macrolensing and time delays. Finally, we draw a random time for the system (arbitrarily chosen to be the observer-frame time of rest-frame B -band maximum of the first image) from the 11 year period spanning 6 months before the beginning of the survey until 6 months following the end of the survey.

We realize broadband photometry of each blended gLSN Ia (summing the flux of each microlensed image) using the sky brightnesses, FWHMs, exposure times, observation times, and limiting magnitudes of the assigned field provided by `minion_1016`, assuming the total area covered by the survey is $25,000 \text{ deg}^2$. Starting from the first observation of the SN Ia, we fit the light curve with SALT2, fixed to the redshift of the lens galaxy (assumed to be known either as a photometric or spectroscopic redshift) and fixed to obey $-18.5 > M_B > -20$ at that redshift (effectively a constraint on x_0). Additionally, we enforce bounds of $[-0.2, 0.2]$ on c and $[-1, 1]$ on x_1 , values characteristic of normal SNe Ia (Scalzo et al. 2014). We use the CERN minimization routine MIGRAD (James & Roos 1975) to fit the data. If the light curve has at least one data point that is at least 5σ discrepant from the best fit and at least 4 data points with $S/N \geq 5$, then the object is marked “detected.” If not, then the next observation is added and the process is repeated until the object is detected or all observations are added, resulting in a non-detection.

Figure 7 shows an example of this procedure being used to detect one of our simulated gLSNe Ia at $z_s = 1.91$. The red data points show the “current” light curve, and the red line shows the best fit model, fixed to $z_l = 0.96$. Although the model fits the data well in the bluer bands, the high redshift of the source makes the data much brighter in the infrared than the model expects given the redshift of the lens. Thus the object is detected shortly after peak due to 10σ discrepant points in y -band.

4.3. Yields

Our spectral template fitting approach to gLSN Ia identification delivers almost twice as many LSST gLSNe Ia than the method of Goldstein & Nugent (2017). In total, LSST should find ~ 925 microlensed gLSNe Ia with the new method over the duration of its 10-year survey. This is almost identical to the case with no microlensing, which would yield 935 gLSNe Ia over the same period, with a nearly identical redshift distribution (see Figure 9). This represents a major increase in the expected gLSN Ia yield for LSST, comparable to the number of expected lensed quasars (Oguri & Marshall 2010).

Figure 8 shows the rest-frame phase distribution of discovered microlensed gLSN Ia images (a phase of 0 corresponds to peak brightness in B). The 68% confidence interval of the image phase distribution is $-1.01^{+10.24}_{-10.77}$, so about half of the images should be discovered before peak brightness. 73% of the images and 64% of the image pairs should be discovered during the achromatic phase.

5. THE EFFECT OF MICROLENSING ON LENSED TYPE IA SUPERNOVA TIME DELAYS

In Section 3, we showed that microlensing introduces time- and wavelength-dependent fluctuations into the light curves of SNe Ia. In this section, we quantify the

effect of these fluctuations on the time delays that can be extracted from simulated photometric observations of typical LSST gLSNe Ia, using as input the results of Section 4.3. We demonstrate that microlensing can introduce time delay uncertainties of $\sim 4\%$ into the light curves of typical LSST gLSNe Ia, but that this number decreases to $\sim 1\%$ when achromatic-phase color curves of the same supernovae are used instead.

5.1. Monte Carlo Simulations of Microlensing Time Delay Uncertainty

Since many of the gLSNe Ia that will be discovered by LSST will require higher-spatial resolution follow-up observations to extract time delays, either with ground-based adaptive optics or space-based imaging, we simulate “time-delay observations” with the Wide Field Camera 3 (WFC3) on the *Hubble Space Telescope* (*HST*). The redshift distribution in Figure 9 implies that most LSST gLSNe Ia will be brightest in the IR, so we use the F814W, F125W, and F160W filters (roughly I , J , and H bands, respectively) on WFC3 for this simulation.

For each of the “detected” microlensed gLSN Ia systems from Section 4.3, we realize 45 photometric observations of each image in F814W, F125W, and F160W with infinite signal to noise, with a uniform temporal spacing, spanning the light curve. The spectral template for each image is the same as the one used in Section 4 (see Equation 12). Using MIGRAD, we fit the realized light curves of each pair of images using the redshifted, unlensed spectral template $H(\lambda, t)$. For each fit, we estimate the fitted time delay as

$$\Delta t = t_{0,2} - t_{0,1}, \quad (13)$$

where $t_{0,2}$ and $t_{0,1}$ are the fitted reference times of the second and first images, respectively. We then measure the error on the fitted time delay as

$$\epsilon = \left| \frac{\Delta t - \Delta t'}{\Delta t'} \right|, \quad (14)$$

where $\Delta t'$ is the true time delay of the pair of images.¹⁶

Next, we prune the photometric observations to the achromatic phase, masking all observations more than 5 rest-frame days from the date of B -band maximum. We then synthesize F814W – F125W, F125W – F160W, and F814W – F160W color curves from the photometry.

We apply the same fitting procedure to the color curves and estimate the fitted time delays and uncertainties using Equations 13 and 14. Figure 10 shows an example of the procedure being applied to the light curves and achromatic-phase color curves of two images of a supernova. While the light curve data show microlensing-induced offsets near peak brightness and the secondary maximum that produce a large time delay error of $\sim 10\%$, the residuals show that these offsets are nearly the same in all bands during the achromatic phase, and thus the fits to the color curve have errors $< 1\%$.

Figure 11 shows the joint distribution of time delays and microlensing-induced time delay uncertainties for all detected pairs of images in our simulation. We find that the median time delay of detected pairs of images is ~ 10

¹⁶ N.B. If Δt is distributed as a Gaussian with width σ , then the ensemble average of ϵ is only 0.79σ .

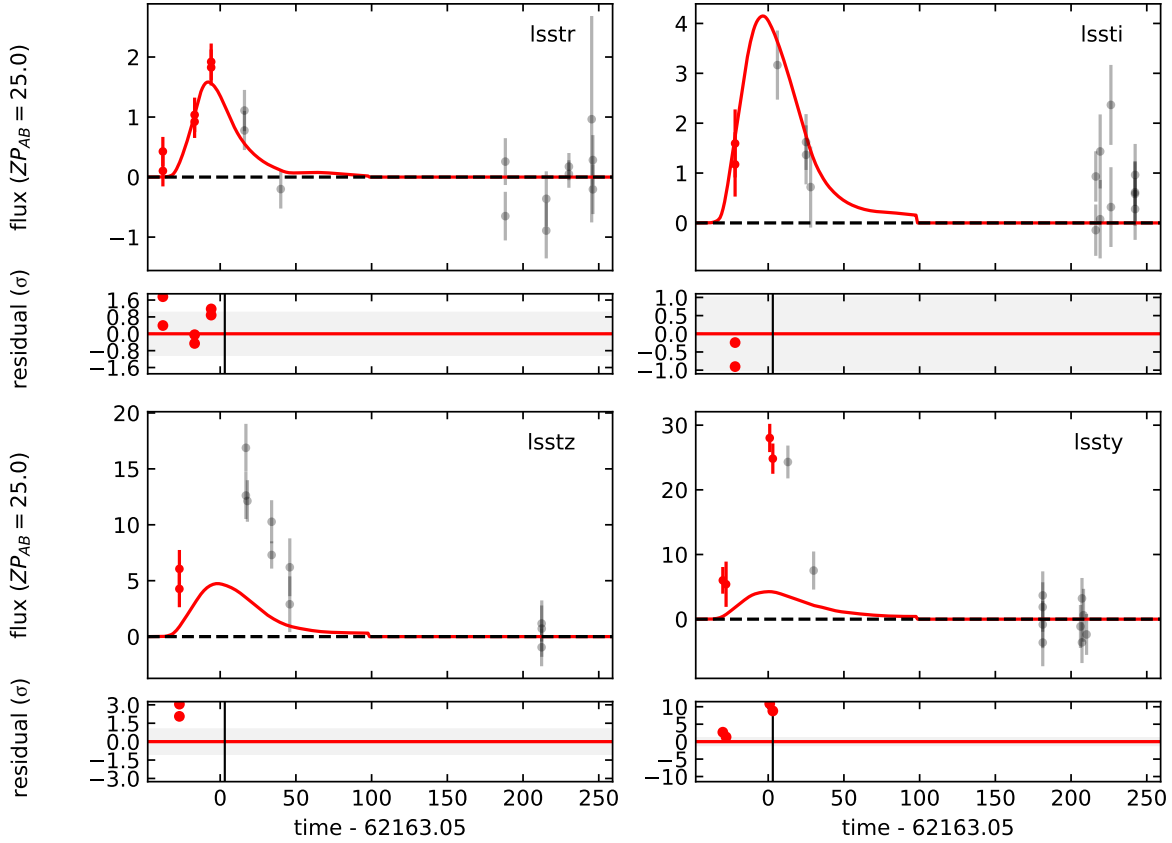


Figure 7. Detecting a $z_s = 1.91, z_l = 0.96$ LSST gISN Ia with SALT2. The red data points show the “current” light curve, and the red line shows the best fit SALT2 model fixed to the photometric redshift of the lens galaxy. The gray points show future observations that are not included in this iteration of the fit. The black vertical line in the residual plots shows the date when the supernova is detected. Although the model fits the data well in the bluer bands, the high redshift of the source makes the data much brighter in the infrared than the model expects given the redshift of the lens. Thus the object is detected shortly after peak due to 10σ discrepant points in y -band.

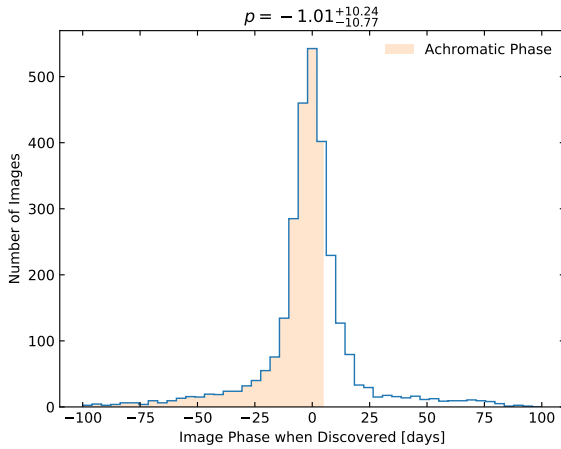


Figure 8. Phases of detected LSN images when they are discovered. Phases are given relative to each image, not to the peak of the total flux of the multiple blended images of SN. 73% of the images and 64% of the image pairs are discovered during the achromatic phase.

days, and that the median microlensing-induced time delay uncertainty using light curve fits is 4%, comparable to the current uncertainties on mass modeling. However, this number drops down to 1% (~ 2.5 hours on a 10 day

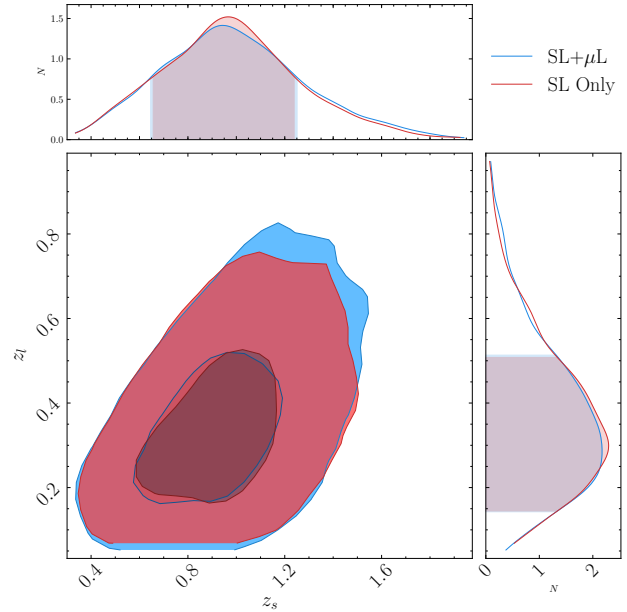


Figure 9. Source and lens redshift distributions of the gISNe Ia with at least 4 data points with $S/N > 5$ detected with (blue) and without microlensing (red). The joint contours show 1 and 2σ . The marginal shaded regions show 1σ .

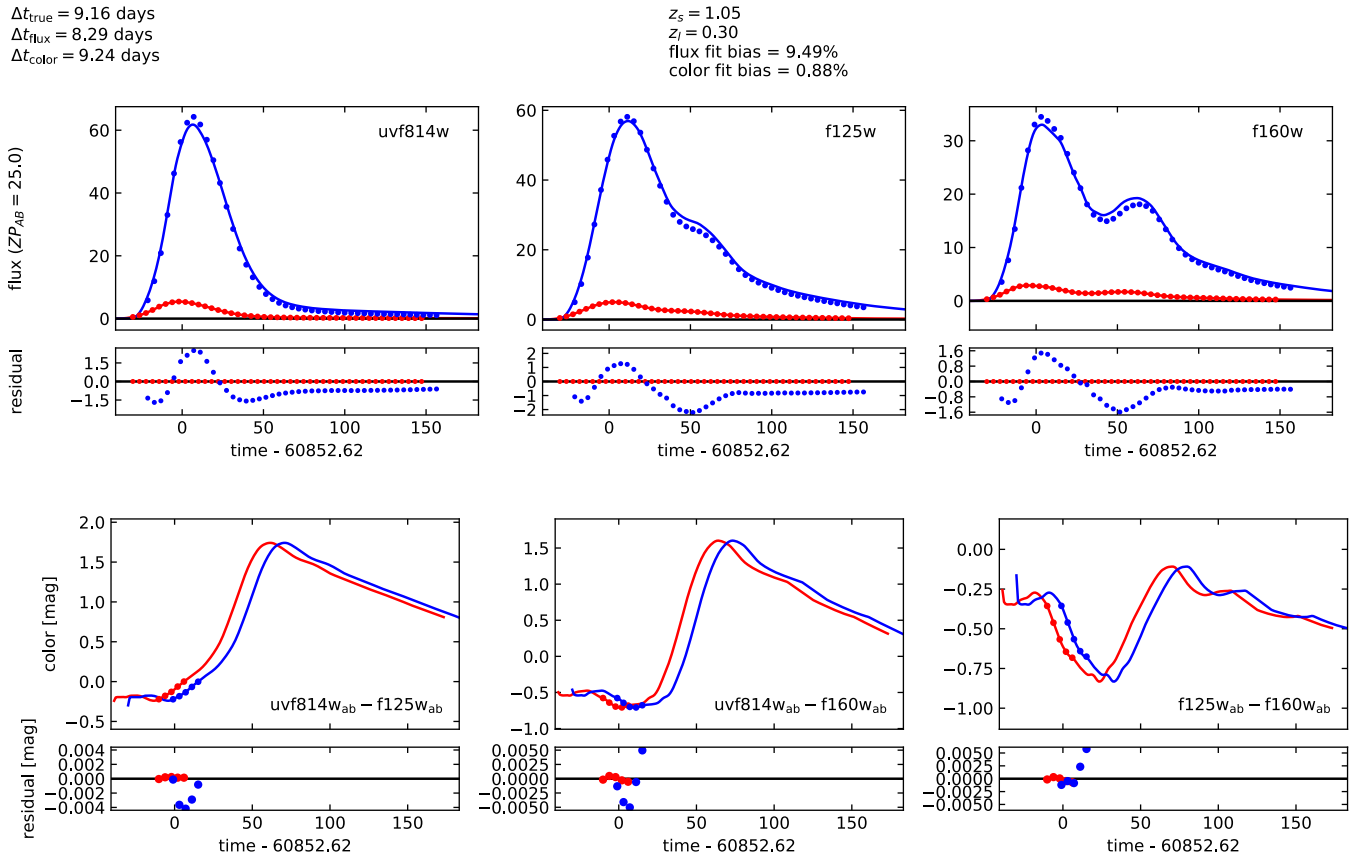


Figure 10. Fitting infinite S/N light curves and color curves (in the achromatic phase) of two images of a microlensed supernova with the unlensed Hsiao template to estimate time delay error. Microlensing produces visible offsets in the features of the light curves, but the residuals show that during the achromatic phase (until a few weeks after peak brightness) the offsets are achromatic. Thus when the color curves are fit in the achromatic phase, the uncertainty on the time delay is more than an order of magnitude smaller.

time delay) when achromatic-phase color curves are used instead of light curves.

Figure 12 shows the systematic microlensing bias on time delays from fitting light curves and color curves in the achromatic phase. The achromatic phase color curve fits are consistent with zero bias down to $\Delta t = 1$ day, while the light curve fits are consistent with zero bias down to $\Delta t \approx$ a few days. This result indicates that time delay bias from microlensing will not be a major systematic for cosmography with gISNe Ia.

5.2. *iPTF16geu*

iPTF16geu is the only gISNe Ia with resolved images that has been discovered to date. Here we consider its potential time delay precision and cosmological impact. Before it faded, multiwavelength follow-up observations of the event were obtained with a variable cadence using the Washington *C*, *g*, *r*, wide *I*, *Z*, *J*, and *H* bands of WFC3 on *HST* (DD 14862, PI: Goobar). The bluer bands were only observed sporadically, but the redder bands were observed with a roughly 4-day cadence.¹⁷ Unfortunately, the observations were obtained well into the chromatic phase, and thus the light curves and color curves exhibit significant microlensing uncertainties. Final photometry of the event has not yet been produced,

as not enough time has passed to take final reference images. The current best estimate of the time delay on this system is 35 hours (Goobar et al. 2017). Based on Figure 11, we estimate the time delay uncertainty due to microlensing from this event to be $\sim 40\%$. If the event were discovered earlier so that color curves during the achromatic phase could be constructed, then the microlensing time delay uncertainty would drop to $\sim 10\%$.

6. CONCLUSION

In this article, we assessed the impact of microlensing on the yields and time delay precisions of LSST gISNe Ia. We presented microlensed broadband difference light curves and color curves of the well-understood SN Ia ejecta model W7 for 78,184 microlensing magnification patterns drawn from a realistic population model of gISNe Ia images. We found that until shortly after peak brightness, the microlensing of SNe Ia is achromatic, and thus time delays from early-time color curves are less sensitive to microlensing than time delays from light curves. We interpreted the achromaticity of microlensing before the onset of the secondary maximum as being due to UV line blanketing and the emergence of a fluorescent shell of Fe III \rightarrow II recombination that alters the specific intensity profile of the ejecta as suggested by Kasen (2006) and Kasen & Woosley (2007). We found that microlensing does not have a significant impact on gISNe Ia yields,

¹⁷ A full description of the observations is available [here](#).

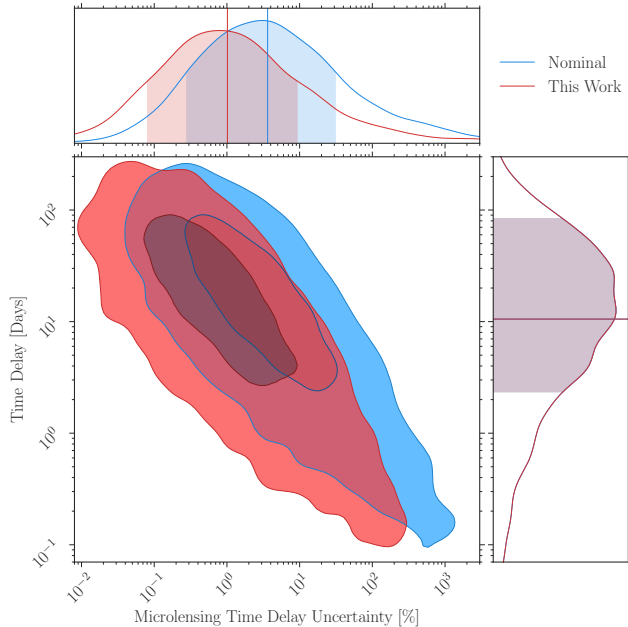


Figure 11. Joint distribution of the true time delay and the microlensing time delay uncertainty as a percentage of the true time delay for all discovered pairs of gISN Ia images. The median time delay uncertainty is 4% for light curves, but just 1% for color curve measurements in the achromatic phase. The median time delay that LSST will detect is 10 days. Marginal shaded regions show 1σ . Contours show 1 and 2σ .

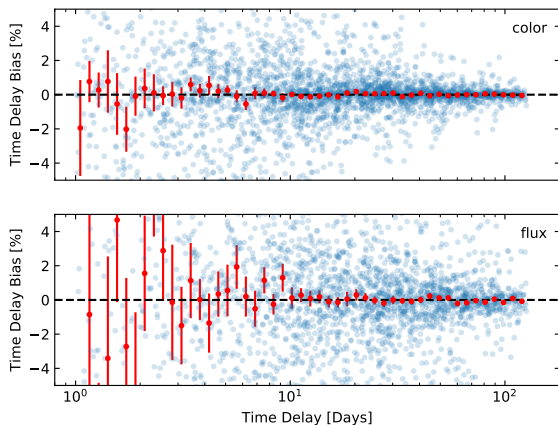


Figure 12. Bias as a function of true time delay for all discovered microlensed image pairs, fitting color curves in the achromatic phase (top panel) and entire light curves (bottom panel). Blue points show individual fits; red points show bin averages.

but that they can be increased by a factor of ~ 2 over the predictions of Goldstein & Nugent (2017) using a novel photometric detection technique.

Our SEDONA calculation of W7 represents the most detailed SN Ia spectrum synthesis calculation that has been used to investigate SN Ia microlensing to date, but it is inherently one-dimensional and makes a number of physical approximations for computational expediency. It does not perfectly reproduce the observed colors of SNe Ia, especially at UV wavelengths, where line blanketing is strong and small differences in the underlying

model can have pronounced effects. Additionally, W7 is just one SN Ia model, and there is diversity in the SN Ia population. However, we expect that this model captures the key physical behavior that leads to chromatic effects, and so we do not expect the results to change significantly with different one-dimensional models. Although there is evidence from spectropolarimetry that global asymmetry in SNe Ia is very small (Wang & Wheeler 2008), asymmetric explosion scenarios have not been ruled out by observations. In the future, it will be useful to assess whether asymmetric, multi-dimensional supernova models confirm the two phases of gISN Ia microlensing identified in this work, or whether viewing angle effects become important.

Despite the complication of microlensing, time-delays can be robustly measured to sub-percent precision for many gISNe Ia. By photometrically detecting the first image of a strongly lensed core-collapse supernova before light from the other images arrives, one can use the sharp shock-breakout light curve as a time delay indicator with precision $\sim (30 \text{ min})(1+z_s)/\Delta t$. Such precision is difficult to achieve with lensed AGNs (Tewes et al. 2013; Bonvin et al. 2017; Tie & Kochanek 2017), which also require a significantly longer observing campaign (Liao et al. 2015). This result provides a straightforward first step to inferring cosmological parameters with gISNe Ia. The latter steps of inferring the lens potential, and the effect of line-of-sight structures have already been implemented for lensed AGNs (e.g. Suyu et al. 2017; Rusu et al. 2017; Wong et al. 2017; Bonvin et al. 2017), and the solutions from lensed AGNs should be directly portable to gISNe Ia. Inferring the lens potential may even be easier than for AGNs as a more detailed reconstruction of the lensed SN Ia host should be possible once the supernova has faded. Those lensed SNe Ia with time-delays greater than a month are therefore golden lenses with which to measure H_0 . With a method for extracting precise time delays from these objects in hand, a renewed focus should be placed on the discovery and follow up of gISNe Ia.

APPENDIX

A. RADIATION TRANSPORT SIMULATION

In this Appendix, we provide the details of the radiation transport simulations that we use to calculate the time-evolving SN Ia SED in Section 2.3. The SEDONA code (Kasen et al. 2006) is a time-dependent, multi-dimensional Monte Carlo radiative transfer code, designed to calculate the light curves, spectra and polarization of supernova explosion models. Given a homologously expanding SN ejecta structure, SEDONA calculates the full time series of emergent spectra at high wavelength resolution. In the present calculations, we employ a modified version of SEDONA that tags photons with their P and ϕ values, thus we calculate $I_\lambda(P, \phi, t, \lambda)$. In addition to being fully time-dependent, the SEDONA calculation accounts for the extendedness of continuum emitting regions in SN Ia atmospheres and the wavelength dependence of their location and extent. It also explicitly accounts for light travel time across the atmosphere. Broadband light curves are constructed by convolving the synthetic spectrum at each time with the appropriate instrumental throughputs. SEDONA includes a detailed

treatment of gamma-ray transfer to determine the instantaneous energy deposition rate from radioactive ^{56}Ni and ^{56}Co decay. Other decay chains that can change the composition of the ejecta, such as $^{48}\text{Cr} \rightarrow ^{48}\text{V} \rightarrow ^{48}\text{Ti}$, are not treated. Radiative heating and cooling rates are evaluated from Monte Carlo estimators, and the temperature structure of the ejecta is determined by iterating the model to thermal equilibrium.

Several significant approximations are made in our SEDONA simulation, notably the assumption of local thermodynamic equilibrium (LTE) in computing the atomic level populations. In addition, bound-bound line transitions are treated using the expansion opacity formalism (implying the Sobolev approximation; Jeffery 1995). In this formalism, the opacities of spectral lines within a wavelength bin are represented in aggregate by a single effective opacity. Although the SEDONA code is capable of a direct Monte Carlo treatment of NLTE line processes, due to computational constraints this functionality is not exploited here. Instead, the line source functions are treated using an approximate two-level atom approach. In the present calculations, we assume for simplicity that all lines are “purely absorptive,” i.e., in the two-level atom formalism the ratio of the probability of redistribution to pure scattering is taken to be $\epsilon_{\text{th}} = 1$ for all lines. In this case, the line source functions are given by the Planck function, consistent with our adoption of LTE level populations.

The numerical gridding in the present calculations was as follows: *spatial*: 100 equally spaced radial zones with a maximum velocity of $4 \times 10^4 \text{ km s}^{-1}$; *temporal*: 459 time points beginning at day 1 and extending to day 100 with logarithmic spacing $\Delta \log t = 0.175$; *wavelength*: covering the range 100–30,000 Å with resolution of 10 Å. Extensive testing confirms the adequacy of this gridding for the problem at hand. Atomic line list data were taken from the Kurucz CD 23 line list (Kurucz & Bell 1995), which contains nearly 500,000 lines. 10^{10} photon packets were used for the calculation, which allowed for acceptable signal-to-noise in the synthetic broadband light curves, spectra, and velocity-dependent specific intensity profiles.

B. DERIVATION OF EQUATION 9

The observed monochromatic flux density F_λ of a source is obtained by setting up a small element of area dA perpendicular to the line of sight at the location of the observer, and integrating the specific intensity of the field I_λ in the direction normal to dA over the solid angle subtended by the source (Rybicki & Lightman 1979),

$$F_\lambda = \int I_\lambda \cos \theta d\Omega. \quad (\text{B1})$$

In Equation B1, θ is defined by $\tan \theta = P/D_L$, where D_L is the luminosity distance from the observer to the closest point on the plane.¹⁸ From this definition we can construct the radial differential dP ,

$$dP = D_L \sec^2 \theta d\theta. \quad (\text{B2})$$

¹⁸ The luminosity distance (not the angular diameter distance) is used here because the intrinsic luminosity of the source is known.

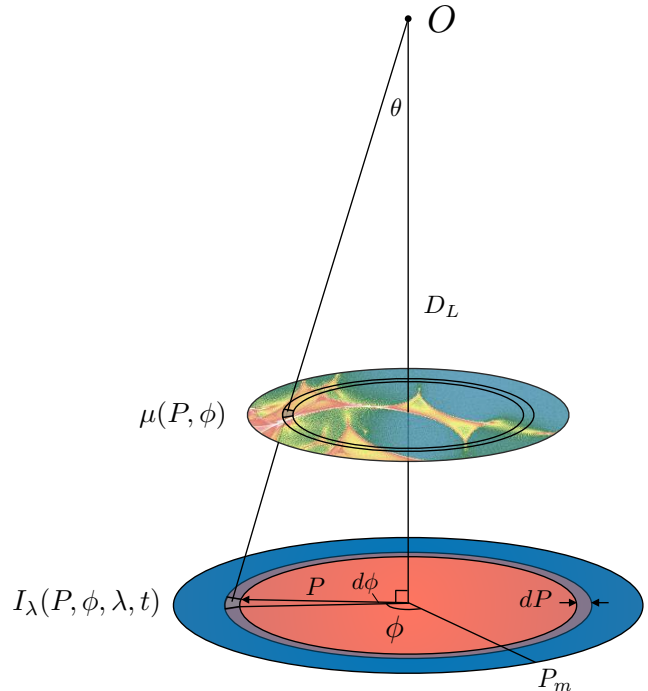


Figure 13. Integration geometry for Appendix B.

Using $d\Omega \equiv \sin \theta d\theta d\phi$, Equation B1 becomes

$$F_\lambda = \int_0^{2\pi} \int_0^{\theta_m} I_\lambda \cos \theta \sin \theta d\theta d\phi, \quad (\text{B3})$$

where θ_m is the maximum angular extent of the atmosphere. Making the change of variables shown in Equation B2, and using $\cos \theta = D_L / \sqrt{P^2 + D_L^2}$ and $\sin \theta = P / \sqrt{P^2 + D_L^2}$, Equation B3 becomes

$$F_\lambda = \int_0^{2\pi} \int_0^{P_m} \frac{P D_L^2 I_\lambda}{(P^2 + D_L^2)^2} dP d\phi. \quad (\text{B4})$$

As we are in the $P \ll D_L$ limit, by Taylor expanding the denominator of the integrand of Equation B4 in powers of (P/D_L) and keeping only first order terms, Equation B4 reduces to

$$F_\lambda = D_L^{-2} \int_0^{2\pi} \int_0^{P_m} I_\lambda P dP d\phi. \quad (\text{B5})$$

Since lensing conserves surface brightness, the application of a spatially varying microlensing magnification pattern transforms $I_\lambda \rightarrow \mu(P, \phi) I_\lambda(P, \phi)$. Making this substitution in equation B5, we are left with Equation 9. A schematic of the integration geometry is presented in Figure 13.

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