Probabilistic analysis of the Grassmann condition number

Dennis Amelunxen^{*}

Peter Bürgisser[†]

July 4, 2013

Abstract

We analyze the probability that a random *m*-dimensional linear subspace of \mathbb{R}^n both intersects a regular closed convex cone $C \subseteq \mathbb{R}^n$ and lies within distance α of an *m*dimensional subspace not intersecting C (except at the origin). The result is expressed in terms of the spherical intrinsic volumes of the cone C. This allows us to perform an average analysis of the Grassmann condition number $\mathscr{C}(A)$ for the homogeneous convex feasibility problem $\exists x \in C \setminus 0 : Ax = 0$. The Grassmann condition number is a geometric version of Renegar's condition number, that we have introduced recently in [SIOPT 22(3):1029–1041, 2012]. We thus give the first average analysis of convex programming that is not restricted to linear programming. In particular, we prove that if the entries of $A \in \mathbb{R}^{m \times n}$ are chosen i.i.d. standard normal, then for any regular cone C, we have $\mathbb{E}[\ln \mathscr{C}(A)] < 1.5 \ln(n) + 1.5$. The proofs rely on various techniques from Riemannian geometry applied to Grassmann manifolds.

AMS subject classifications: 90C25, 90C22, 90C31, 52A22, 52A55, 60D05

Key words: convex programming, perturbation, condition number, average analysis, spherically convex sets, Grassmann manifold, tube formula

1 Introduction

Convex programming is an efficient tool in modern applied mathematics. In fact, a commonly accepted technique in current scientific computing is to "convexify" supposedly hard problems, solve the relaxed convex problem, and then hope that the result is close to a solution of the original problem. To quote from [7, §1.3.2]: "With only a bit of exaggeration, we can say that, if you formulate a practical problem as a convex optimization problem, then you have solved the original problem."

But what is the complexity of convex programming? To specify this question further, we ask for the number of arithmetic operations, or the number of iterations of an interior-point method. Steve Smale suggested in [42] to use the concepts of condition numbers and probabilistic analysis in a two-part scheme for the analysis of numerical algorithms: 1. Establish a bound for the running time, which is polynomial in the size of the input and (the logarithm

^{*}E-mail: damelunx@gmail.com. Partially supported by DFG Research Training Group on Scientific Computation GRK 693 (PaSCo GK) and DFG grants BU 1371/2-2, AM 386/1-1, AM 386/1-2.

[†]E-mail: pbuerg@upb.de. Partially supported by DFG grant BU 1371/2-2.

of) a certain condition number of the input. 2. Analyze the condition number of a random input in form of tail estimates.

The first step of this scheme, i.e., the analysis of the role of condition numbers in convex programming, was initialized by Jim Renegar in [37, 38, 39], and is an active area of research, cf. [48, 49, 19, 21, 22, 34, 36, 13, 14, 17, 35, 20, 47, 4]. In these references, the role of condition numbers is analyzed for linear and nonlinear convex programming, for exact arithmetic and for finite-precision arithmetic, for ellipsoid and for interior-point methods, etc.

Yet, the second step of Smale's scheme, i.e., the probabilistic analysis of the condition number, was until now severly restricted to the linear programming case. See the survey article [8] and the references given therein for more details on probabilistic analyses of condition numbers for linear programming.

We will give in this paper the first average analysis of a condition number for the general homogeneous convex feasibility problem. This includes the special cases of linear programming, second-order programming, and notably also the semidefinite programming case. More precisely, we consider the following problem:

Let $C \subseteq \mathbb{R}^n$ be a regular cone, i.e., C is a closed convex cone with nonempty interior that does not contain a nontrivial linear subspace. The *polar cone* of C is defined as $\check{C} := \{z \in \mathbb{R}^n \mid \forall x \in C : z^T x \leq 0\}$. We call C self-dual if $\check{C} = -C$. The homogeneous convex feasibility problem is to decide for a given matrix $A \in \mathbb{R}^{m \times n}$, $1 \leq m < n$, the alternative¹

$$\exists x \in \mathbb{R}^n \setminus 0 \quad \text{s.t.} \quad Ax = 0, \ x \in \check{C},\tag{P}$$

$$\exists y \in \mathbb{R}^m \setminus 0 \quad \text{s.t.} \qquad A^T y \in C. \tag{D}$$

This problem reduces to the linear feasibility problem if $C = \mathbb{R}^n_+$; it reduces to the second-order feasibility problem if $C = \mathcal{L}^{n_1} \times \ldots \times \mathcal{L}^{n_r}$, where $\mathcal{L}^n := \{x \in \mathbb{R}^n \mid x_n \ge (x_1^2 + \cdots + \ldots, x_{n-1}^2)^{1/2}\}$ denotes the *n*-dimensional *Lorentz cone*; and it reduces to the semidefinite feasibility problem if $C = \operatorname{Sym}^k_+ = \{M \in \operatorname{Sym}^k \mid M \succeq 0\}$ is the *cone of positive semidefinite matrices*, where $\operatorname{Sym}^k = \{M \in \mathbb{R}^{k \times k} \mid M^T = M\}$.

1.1 Grassmann condition number

The condition number, for which we will provide an average analysis, is the *Grassmann con*dition number, that we have introduced in [1, 3], cf. also [4]. Let us recall the necessary definitions from [3]. We fix $1 \leq m < n$ and consider the *Grassmann manifold* $\operatorname{Gr}_{n,m}$, that is defined as the set of *m*-dimensional linear subspaces W of \mathbb{R}^n .

We also fix a regular cone $C \subseteq \mathbb{R}^n$. The sets of *dual feasible* and *primal feasible* subspaces with respect to C, respectively, are defined as follows:

$$\mathcal{D}_m(C) := \{ W \in \operatorname{Gr}_{n,m} \mid W \cap C \neq \{0\} \}, \qquad \mathcal{P}_m(C) := \{ W \in \operatorname{Gr}_{n,m} \mid W^{\perp} \cap \check{C} \neq \{0\} \}.$$

Moreover, we we define the set of *ill-posed subspaces with respect to* C by

$$\Sigma_m(C) := \mathcal{D}_m(C) \cap \mathcal{P}_m(C).$$

¹In fact, (P) and (D) are only weak alternatives, as it may happen that both (P) and (D) are satisfiable. But the Lebesgue measure of the set of these ill-posed inputs in $\mathbb{R}^{m \times n}$ is zero.

It is known (cf. [3]) that $\mathcal{D}_m(C)$ and $\mathcal{P}_m(C)$ are compact subsets of $\operatorname{Gr}_{n,m}$ and $\operatorname{Gr}_{n,m} = \mathcal{D}_m(C) \cup \mathcal{P}_m(C)$. Moreover, the boundaries of $\mathcal{D}_m(C)$ and $\mathcal{P}_m(C)$ coincide with $\Sigma_m(C)$. Furthermore,

$$\Sigma_m(C) = \{ W \in \operatorname{Gr}_{n,m} \mid W \cap C \neq \{0\} \text{ and } W \cap \operatorname{int}(C) = \emptyset \}.$$

In other words, the set of ill-posed subspaces consists of those subspaces, which touch the cone C at the boundary. One can show that $\mathcal{P}_m(C) \setminus \Sigma_m(C)$ and $\mathcal{D}_m(C) \setminus \Sigma_m(C)$ are the connected components of $\operatorname{Gr}_{n,m} \setminus \Sigma_m(C)$.

The projection distance $d_p(W_1, W_2)$ of two subspaces $W_1, W_2 \in \operatorname{Gr}_{n,m}$ is defined as the spectral norm $d_p(W_1, W_2) := \|\Pi_{W_1} - \Pi_{W_2}\|$, where Π_{W_i} denotes the orthogonal projection onto W_i , cf. [26, §2.6]. Clearly, this defines a metric and a corresponding topology on $\operatorname{Gr}_{n,m}$.

In [3, Def. 1.2] we made the following definition.

Definition 1.1. The *Grassmann condition* with respect to the regular cone $C \subseteq \mathbb{R}^n$ is defined as the function

$$\mathscr{C}_C \colon \operatorname{Gr}_{n,m} \to [1,\infty], \quad \mathscr{C}_C(W) := \frac{1}{d_p(W, \Sigma_m(C))},$$

where $d_p(W, \Sigma_m(C)) := \min\{d_p(W, W') \mid W' \in \Sigma_m(C)\}.$

Suppose that $W \in \operatorname{Gr}_{n,m}$ is represented by $W = \operatorname{im}(A^T)$ with a matrix $A \in \mathbb{R}^{m \times n}$ of full rank. Let $\kappa(A)$ denote the matrix condition number, i.e., the ratio between the largest and the smallest singular value of A. In [3, Thm. 1.4] (see also [4]), we proved the following basic relation between the Grassmann condition number $\mathscr{C}(W)$ of W and Renegar's condition number $\mathcal{R}(A)$ of the matrix A:

$$\mathscr{C}(W) \leq \mathcal{R}(A) \leq \kappa(A) \mathscr{C}(W). \tag{1.1}$$

This shows that the Grassmann condition number can be interpreted as a coordinate-free version of Renegar's condition number. The condition of the matrix A representing W enters Renegar's condition number $\mathcal{R}(A)$, but $\mathscr{C}(W)$ is independent of this representation.

Our probabilistic analysis of the Grassmann condition crucially relies on a geometric interpretation of this quantity that we explain next. There is a natural Riemannian metric on the compact Grassmann manifold $\operatorname{Gr}_{n,m}$ that is invariant under the action of O(n), and which is uniquely determined up to a scaling factor [27]. This induces an O(n)-invariant volume form on $\operatorname{Gr}_{n,m}$, which allows to define the volume rvol B of Borel measurable subsets $B \subseteq \operatorname{Gr}_{n,m}$. We assume that rvol $\operatorname{Gr}_{n,m} = 1$.

The geodesic distance $d_g(W_1, W_2)$ between $W_1, W_2 \in \operatorname{Gr}_{n,m}$ is defined as the minimum length of a piecewise smooth curve in $\operatorname{Gr}_{n,m}$ connecting W_1 with W_2 . We remark that one can nicely express $d_g(W_1, W_2)$ in terms of the principle angles between these subspaces, cf. [3, equation (8)]; in particular, the diameter of $\operatorname{Gr}_{n,m}$ equals $\pi/2$.

In [3, Thm. 1.8] we proved that $d_p(W, \Sigma_m) = \sin d_g(W, \Sigma_m)$ for $W \in \operatorname{Gr}_{n,m}$, where we write $\Sigma_m := \Sigma_m(C)$ to simplify notation. This implies that the tube $\mathcal{T}(\Sigma_m, \alpha)$ of radius α around Σ_m , defined as follows,

$$\mathcal{T}(\Sigma_m, \alpha) := \left\{ W \in \operatorname{Gr}_{n,m} \mid d_g(W, \Sigma_m) \le \alpha \right\}$$
(1.2)

equals the set of $W \in \operatorname{Gr}_{n,m}$ having Grassmann condition at least $t := (\sin \alpha)^{-1}$.

Suppose now that $A \in \mathbb{R}^{m \times n}$ is a standard Gaussian random matrix. Then A almost surely has full rank and $W = \operatorname{im} A^T$ is uniformly random in $\operatorname{Gr}_{n,m}$ with respect to the normalized volume measure rvol. The goal of this work is to prove upper bounds on $\operatorname{Prob}[\mathscr{C}(A) \geq t]$ that hold for any regular cone C, thus showing that it is unlikely that $\mathscr{C}(W)$ is large. By (1.2), this means to bound the volume of the tubes around $\Sigma_m(C)$.

This task is very much in the spirit of the seminal paper [15] by Jim Demmel and its refinement in [10]. These papers provide upper bounds on the volume of tubes around algebraic hypersurfaces in spheres. The main tool is a general formula, due to Hermann Weyl [50], on the volume of tubes around smooth hypersurfaces of spheres. In Theorem 1.5 we will derive a similar, though considerably more complicated formula for the volume of the tubes around $\Sigma_m(C)$ in the Grassmann manifold. We think that this new tube formula is of independent mathematical interest. The proof is reduced to the case where the cone C has a smooth boundary, in which $\Sigma_m(C)$ turns out to be a smooth hypersurface in $\operatorname{Gr}_{n,m}$.

An exact tube formula had been previously derived by Glasauer [24, 25] by measure theoretic techniques. However, Glasauer's result has the serious drawback that it only holds for radii below a certain critical value depending on the cone C, and this value is zero for all cones of interest in convex programming; cf. Remark 3.1. By contrast, Theorem 1.5 states an upper bound on the volume of tubes that holds for any radius.

1.2 Main results I: probabilistic analysis

Here is the main result of this paper.

Theorem 1.2. Let $C \subseteq \mathbb{R}^n$ be a regular cone with $n \geq 3$. If $A \in \mathbb{R}^{m \times n}$ is a standard Gaussian random matrix, then we have

$$\begin{aligned} \operatorname{Prob}[\mathscr{C}(A) > t] &< 6\sqrt{m(n-m)} \, \frac{1}{t}, \quad \text{if } t > n^{\frac{3}{2}}, \\ \mathbb{E}\left[\ln \mathscr{C}(A)\right] &< 1.5 \ln(n) + 1.5 \;. \end{aligned}$$

In fact, these bounds hold for any probability distribution on $\mathbb{R}^{m \times n}$, that induces the uniform distribution on the Grassmann manifold $\operatorname{Gr}_{n,m}$ via the map $A \mapsto \operatorname{im} A^T$.

Theorem 1.2 is of relevance for the probabilistic analysis of algorithms in convex programming.

Corollary 1.3. Let C be a self-scaled cone with a self-scaled barrier function. Then there exists an interior point algorithm, that solves the general homogeneous convex feasibility problem for Gaussian random inputs in expected $O(\sqrt{\nu_C}(\ln \nu_C + \ln n))$ number of interior-point iterations. Here, ν_C denotes the complexity parameter of the barrier function for the reference cone C. For linear programming, second-order programming, and semidefinite programming, the expected number of interior-point iterations is $O(\sqrt{n} \ln n)$.

Proof. In [47] the authors describe an interior-point algorithm that solves the general homogeneous convex feasibility problem, for a self-scaled cone C with a self-scaled barrier function, in $O(\sqrt{\nu_C} \ln(\nu_C \mathcal{R}(A)))$ interior-point iterations.

The typical barrier functions for (LP), (SOCP), and (SDP), respectively, have the following complexity parameter ν_C :

$$C = \mathbb{R}^n_+ : \nu_C = n, \qquad C = \mathcal{L}^{n_1} \times \ldots \times \mathcal{L}^{n_r} : \nu_C = 2r, \qquad C = \operatorname{Sym}^k_+ : \nu_C = k.$$

In particular, $\nu_C \leq n$ in all these cases.

By (1.1), we have $\mathbb{E}[\ln \mathcal{R}(A)] \leq \mathbb{E}[\ln \kappa(A)] + \mathbb{E}[\ln \mathscr{C}(A)]$, hence a probabilistic analysis of \mathcal{R} reduces to that of \mathscr{C} and κ . Theorem 1.2 states that $\mathbb{E}[\ln \mathscr{C}(A)] = O(\ln(n))$. In [12] it was shown that $\mathbb{E}[\ln \kappa(A)] = O(\ln n)$ for Gaussian matrices $A \in \mathbb{R}^{m \times n}$. Combining these estimates, we obtain $\mathbb{E}[\ln(\mathcal{R}(A))] = O(\ln n)$. We conclude that the expected number of interior point iterations of the algorithm in [47] is bounded by $O(\sqrt{\nu_C} \ln(\nu_C + \ln n))$.

Remark 1.4. In [47] it is also shown that the condition number of the system of equations, that is solved in each interior-point iteration, is bounded by a factor of $\mathcal{R}(A)^2$. Therefore, our results also imply bounds on the expected cost of each iteration in the above-mentioned algorithm.

1.3 Intrinsic volumes and Weyl's tube formula

The analysis of the homogeneous convex feasibility problem naturally finds its place in the domain of spherical convex geometry. Indeed, a linear subspace intersects a convex cone nontrivially if and only if the corresponding subsphere of the unit sphere intersects the corresponding spherically convex set. While Euclidean convex geometry is a classical and extensively studied subject, the situation for spherical convex geometry is much less established. For more information, we refer to the theses [24, 25], [1], the article [23], and Section 6.5 in [41].

We call a subset $K \subseteq S^{n-1}$ (spherically) convex if for all $p, q \in K$ with $q \neq \pm p$, the great circle segment between p and q is contained in K. This is equivalent to the requirement that $C := \operatorname{cone}(K) := \{\lambda p \mid \lambda \geq 0, p \in K\}$ is a convex cone. Note that $K = C \cap S^{n-1}$. Let $d(p,q) := \operatorname{arccos}(\langle p,q \rangle)$ denote the (spherical) distance between points $p,q \in S^{n-1}$. We are interested in the volume of the tube $\mathcal{T}(K,\alpha) := \{p \in S^{n-1} \mid d(p,K) \leq \alpha\}$ of radius α around K. In general, unlike in Euclidean space, the tubes $\mathcal{T}(K,\alpha)$ are not convex, which causes technical difficulties; see Remark 3.1.

The volumes of the unit sphere $S^{n-1} := \{x \in \mathbb{R}^n \mid ||x|| = 1\}$ and the unit ball $B_n := \{x \in \mathbb{R}^n \mid ||x|| \le 1\}$, respectively, are given by $(n \ge 1)$

$$\mathcal{O}_{n-1} := \operatorname{vol}_{n-1}(S^{n-1}) = \frac{2\pi^{n/2}}{\Gamma(n/2)}, \qquad \omega_n := \operatorname{vol}_n B_n = \frac{\mathcal{O}_{n-1}}{n} = \frac{\pi^{\frac{n}{2}}}{\Gamma(\frac{n+2}{2})}$$
(1.3)

(we also set $\omega_0 := 1$). We define for $0 \le k \le n-1$ and $0 \le \alpha \le \frac{\pi}{2}$ the functions

$$I_{n,k}(\alpha) := \int_0^\alpha \cos(\rho)^k \cdot \sin(\rho)^{n-2-k} \, d\rho \;. \tag{1.4}$$

If S^k denotes a k-dimensional unit subsphere of S^{n-1} , then it is known that (cf. [9, Lem. 20.5])

$$\mathcal{O}_{n-1,k}(\alpha) := \operatorname{vol}_{n-1} \mathcal{T}(S^k, \alpha) = \mathcal{O}_k \cdot \mathcal{O}_{n-2-k} \cdot I_{n,k}(\alpha) .$$
(1.5)

More generally, the volume of $\mathcal{T}(K, \alpha)$ can be expressed in terms of certain quantities assigned to K that we describe next.

Let $C \subseteq \mathbb{R}^n$ be a polyhedral cone. For j = 0, 1, ..., n, we denote by \mathcal{F}_j the set of the relative interiors of the *j*-dimensional faces of *C*. Moreover, we consider the canonical projection $\Pi_C : \mathbb{R}^d \to C, x \mapsto \operatorname{argmin}\{||x - y|| \mid y \in C\}$. Then the *j*-intrinsic volume $V_j(C)$ of *C* is defined by

$$V_j(C) := \sum_{F \in \mathcal{F}_j} \operatorname{Prob}_{x \in N(0, I_d)} \{ \Pi_C(x) \in F \},$$
(1.6)

where $N(0, I_n)$ stands for the standard Gaussian distribution on \mathbb{R}^n . In particular, we have $V_n(C) = \operatorname{rvol}(C \cap S^{n-1})$ and $V_0(C) = \operatorname{rvol}(\check{C} \cap S^{n-1})$. It is easy to check that $V_j(\mathbb{R}^n_+) = \binom{n}{i}2^{-n}$.

By continuous extension, one can assign intrinsic volumes $V_0(C), \ldots, V_n(C)$ to any closed convex cone $C \subseteq \mathbb{R}^n$, see Section 3.3 and [2]. If $K \subseteq S^{n-1}$ is a closed spherically convex subset, we define $V_{i-1}(K) := V_i(C)$, where $C := \operatorname{cone}(K)$ (the index change has certain advantages).

The following result is essentially due to Weyl [50] (compare [23] and [41] for more information): for $0 \le \alpha \le \frac{\pi}{2}$ we have

$$\operatorname{vol}_{n-1} \mathcal{T}(K, \alpha) = \operatorname{vol}_{n-1}(K) + \sum_{j=0}^{n-2} V_j(K) \cdot \mathcal{O}_{n-1,j}(\alpha) .$$
 (1.7)

From (1.6) one can derive that for closed convex cones C_1 and C_2 we have

$$V_j(C_1 \times C_2) = \sum_{i=0}^{j} V_i(C_1) V_{j-i}(C_2), \qquad (1.8)$$

 \leftarrow

a fact that apparently was first observed in [1].

1.4 Main results II: Grassmannian tube formula

Let us return to the situation of Section 1.1. In order to bound the volume of the tube $\mathcal{T}(\Sigma_m(C), \alpha)$, we need to introduce some notation.

Using the analytic extension of the binomial coefficients $\binom{x}{y} := \frac{\Gamma(x+1)}{\Gamma(y+1)\cdot\Gamma(x-y+1)}$, for x > -1 and -1 < y < x + 1, we have

$$\binom{n/2}{m/2} = \frac{\Gamma(\frac{n+2}{2})}{\Gamma(\frac{m+2}{2}) \cdot \Gamma(\frac{n-m+2}{2})} = \frac{\omega_m \cdot \omega_{n-m}}{\omega_n} .$$
(1.9)

We also define the *flag coefficients* (cf. [30])

$$\begin{bmatrix} n\\m \end{bmatrix} := \binom{n}{m} \binom{n/2}{m/2}^{-1} = \frac{\sqrt{\pi} \cdot \Gamma(\frac{n+1}{2})}{\Gamma(\frac{m+1}{2}) \cdot \Gamma(\frac{n-m+1}{2})} .$$
(1.10)

We fix a regular cone $C \subseteq \mathbb{R}^n$ and put $\Sigma_m := \Sigma_m(C)$. Recall the definition of the tube $\mathcal{T}(\Sigma_m, \alpha)$ from (1.2). We define the *primal* and the *dual tube around* Σ_m , respectively, by

$$\mathcal{T}^{\mathcal{P}}(\Sigma_m, \alpha) := \mathcal{T}(\Sigma_m, \alpha) \cap \mathcal{P}_m(C) , \qquad \mathcal{T}^{\mathcal{D}}(\Sigma_m, \alpha) := \mathcal{T}(\Sigma_m, \alpha) \cap \mathcal{D}_m(C) .$$
(1.11)

The following tube formula is the technical heart of our work. In fact, Theorem 1.2 will follow by bounding the right-hand side in this formula, taking into account that $V_j(C) \leq \frac{1}{2}$.

Theorem 1.5. Let $C \subseteq \mathbb{R}^n$ be a regular cone. Then, for $1 \leq m < n$ and $0 \leq \alpha \leq \frac{\pi}{2}$, we have

$$\operatorname{rvol} \mathcal{T}^{\mathbb{P}}(\Sigma_m(C), \alpha) \leq \frac{2m(n-m)}{n} \binom{n/2}{m/2} \sum_{j=0}^{n-2} V_{j+1}(C) \binom{n-2}{j} \sum_{i=0}^{n-2} d_{ij}^{nm} I_{n,i}(\alpha), \quad (1.12)$$

where the constants d_{ij}^{nm} are defined for $i + j + m \equiv 1 \pmod{2}$, $0 \le \frac{i-j}{2} + \frac{m-1}{2} \le m-1$, and $0 \le \frac{i+j}{2} - \frac{m-1}{2} \le n - m - 1$, by

$$d_{ij}^{nm} := \frac{\binom{m-1}{2} \cdot \binom{n-m-1}{2} \cdot \binom{n-m-1}{2}}{\binom{n-2}{j}}; \qquad (1.13)$$

and defined by $d_{ij}^{nm} := 0$ otherwise. (See Table 1.) The same upper bound holds for the volume of $\mathcal{T}^{\mathbb{D}}(\Sigma_m, \alpha)$.

- **Remark 1.6.** 1. It can be shown (see [1] for details) that (1.12) in fact holds with equality if $\mathcal{T}(C \cap S^{n-1}, \alpha)$ is convex and if d_{ij}^{nm} is replaced by $(-1)^{\frac{i-j}{2} \frac{m-1}{2}} \cdot d_{ij}^{mm}$. This reveals that the estimate in Theorem 1.5 is close to being sharp.
 - 2. In the case m = 1 we have $\operatorname{Gr}_{n,1} = \mathbb{P}^{n-1}$ and $\mathcal{T}^{\mathsf{P}}(\Sigma_1, \alpha)$ is the image of $\mathcal{T}(K, \alpha) \setminus K$ under the canonical map $S^{n-1} \to \mathbb{P}^{n-1} = \operatorname{Gr}_{n,1}$. Hence $\operatorname{rvol} \mathcal{T}^{\mathsf{P}}(\Sigma_1, \alpha) = (\operatorname{vol}_{n-1} \mathcal{T}(K, \alpha) - \operatorname{vol}_{n-1} K)/(\mathcal{O}_{n-1}/2)$. Taking into account that $d_{ij}^{n1} = \delta_{ij}$, one can check that (1.12) actually gives the expression in Weyl's tube formula (1.7).
 - 3. The symmetry relations $d_{i,n-2-j}^{n,n-m} = d_{ij}^{nm}$ and $d_{n-2-i,n-2-j}^{nm} = d_{ij}^{nm}$ hold.
 - 4. The bound (1.12) has a remarkable symmetry. The involution ι : $\operatorname{Gr}_{n,m} \to \operatorname{Gr}_{n,n-m}$, $\mathcal{W} \mapsto \mathcal{W}^{\perp}$ maps $\mathcal{P}_m(C)$ to $\mathcal{D}_{n-m}(\check{C})$, and therefore $\iota(\Sigma_m(C)) = \Sigma_{n-m}(\check{C})$, cf. [3]. In particular, ι maps the dual tube $\mathcal{T}^{\mathcal{D}}(\Sigma_m(C), \alpha)$ of C to the primal tube $\mathcal{T}^{\mathcal{P}}(\Sigma_{n-m}(\check{C}), \alpha)$ of \check{C} , and so they must have the same volume. This symmetry is reflected in (1.12). Indeed, if we simplify the upper bound for $\operatorname{rvol} \mathcal{T}^{\mathcal{P}}(\Sigma_{n-m}(\check{C}), \alpha)$ in (1.12) by using the duality property $V_{j+1}(\check{C}) = V_{n-2-j+1}(C)$ (cf. Proposition 3.3), by changing the summation via $j \leftarrow n-2-j$, and by using the symmetry relations $d_{i,n-2-j}^{n,n-m} = d_{ij}^{nm}$, $\binom{n/2}{(n-m)/2} = \binom{n/2}{m/2}$, and $\binom{n-2}{n-2-j} = \binom{n-2}{j}$, then we end up with the upper bound for $\operatorname{rvol} \mathcal{T}^{\mathcal{P}}(\Sigma_m(C), \alpha)$ from (1.12).

$$D_{7,1} = \begin{pmatrix} 1 & & \\ 1 & & \\ & 1 & \\ & & 1 & \\ & & & 1 \end{pmatrix} , \quad D_{7,2} = \begin{pmatrix} \frac{1}{5} & & & \\ 1 & 0 & \frac{2}{5} & & \\ \frac{4}{5} & 0 & \frac{3}{5} & & \\ & \frac{3}{5} & 0 & \frac{4}{5} & \\ & & & \frac{2}{5} & 0 & 1 \\ & & & \frac{3}{5} & 0 & \frac{3}{5} & \\ & \frac{3}{5} & 0 & \frac{3}{5} & 0 & 1 \\ & & & \frac{1}{5} \end{pmatrix} , \quad D_{7,3} = \begin{pmatrix} \frac{1}{10} & & \\ \frac{2}{5} & 0 & \frac{3}{10} & & \\ \frac{2}{5} & 0 & \frac{3}{5} & & \\ 1 & 0 & \frac{3}{5} & 0 & \frac{3}{5} & \\ & \frac{3}{10} & 0 & \frac{2}{5} & \\ & & \frac{1}{10} & & \end{pmatrix} ,$$

$$D_{7,6} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \quad D_{7,5} = \begin{pmatrix} \frac{1}{5} \\ \frac{2}{5} & 0 & 1 \\ \frac{3}{5} & 0 & \frac{4}{5} \\ \frac{4}{5} & 0 & \frac{3}{5} & 5 \\ \frac{4}{5} & 0 & \frac{3}{5} & 5 \\ 1 & 0 & \frac{2}{5} & - \\ \frac{1}{5} & - & - \end{pmatrix}, \quad D_{7,4} = \begin{pmatrix} \frac{1}{10} \\ \frac{3}{10} & 0 & \frac{2}{5} \\ \frac{3}{5} & 0 & \frac{3}{5} & 0 & 1 \\ 1 & 0 & \frac{3}{5} & 0 & \frac{3}{5} \\ \frac{2}{5} & 0 & \frac{3}{10} & - \\ \frac{1}{10} & - & - \end{pmatrix}$$

Table 1: The coefficient matrices $D_{n,m} = (d_{ij}^{nm})_{i,j=0,\dots,n-2}$ for $n = 7, m = 1,\dots,6$.

1.5 Basic outline for proof of tube formula

The basic idea of the proof relies on some Riemannian geometry. (We refer to [16], [6], or [11, Ch. 1] for some general background on Riemannian geometry.)

Let \mathcal{R} be a compact connected Riemannian manifold with distance metric d. The distance $d(p, \mathcal{M})$ of a point $p \in \mathcal{R}$ to a nonempty closed subset \mathcal{M} of \mathcal{R} is defined as the minimum of d(p,q) over all $q \in \mathcal{M}$. For $\alpha \geq 0$ consider the α -neighborhood

$$\mathcal{T}(\mathcal{M}, \alpha) := \left\{ p \in \mathcal{R} \mid d(p, \mathcal{M}) \le \alpha \right\}$$

of \mathcal{M} in \mathcal{R} . We also call $\mathcal{T}(\mathcal{M}, \alpha)$ the *tube of radius* α *around* \mathcal{M} . It is essential that the tube can be described in terms of the exponential map of \mathcal{R} if \mathcal{M} is a smooth submanifold of \mathcal{R} . For stating this, let $T\mathcal{R}$ denote the *tangent bundle* of \mathcal{R} , i.e., the disjoint union of all of its tangent spaces. The *exponential map* of \mathcal{R} is characterized as the map exp: $T\mathcal{R} \to \mathcal{R}$ such that for $p \in \mathcal{R}$ and $v \in T_p\mathcal{R}$, the curve $\gamma \colon \mathbb{R} \to \mathcal{R}, t \mapsto \exp_p(tv)$ is the *geodesic* through p in direction v, that is, $\gamma(0) = p$ and $\dot{\gamma}(0) = v$.

We will only consider a special kind of geodesics in the Grassmann manifold $\operatorname{Gr}_{n,m}$, that have a simple geometric meaning: Let $W \in \operatorname{Gr}_{n,m}$, and consider a two-dimensional linear subspace $E \subseteq \mathbb{R}^n$ such that $\dim(E \cap W) = \dim(E \cap W^{\perp}) = 1$. Letting $R_t \in O(n)$ denote the rotation in E by the angle t that keeps the vectors in E^{\perp} fixed, the map $t \mapsto R_t(W)$ is a geodesic through W.

Suppose now that $\mathcal{M} \subseteq \mathcal{R}$ is a compact hypersurface in \mathcal{R} with unit normal vector field ν . Consider the following smooth map induced by exp:

$$\psi \colon \mathcal{M} \times \mathbb{R} \to \mathcal{R}, \ (p, \theta) \mapsto \exp_p(\theta \nu(p)).$$
 (1.14)

It is a well-known fact that

$$\mathcal{T}(\mathcal{M}, \alpha) = \psi \left(\mathcal{M} \times \left[-\alpha, \alpha \right] \right) \,. \tag{1.15}$$

(For a proof, see [44, Addendum to Chap. 9, proof of Thm. 20].) Combining (1.15) with the coarea formula (compare (2.2)), we obtain

$$\operatorname{vol} \mathcal{T}(\mathcal{M}, \alpha) \leq \int_{(p,\theta) \in \mathcal{M} \times [-\alpha, \alpha]} |\det D_{(p,\theta)} \psi| \, d(\mathcal{M} \times \mathbb{R}).$$
(1.16)

This inequality is the basis of the proof of Theorem 1.5. The main difficulty is to make effective use of the right-hand side in the specific situation at hand.

In the case where the cone $C \subseteq \mathbb{R}^n$ is such that $K := C \cap S^{n-1}$ has a smooth boundary $M := \partial K$ with positive curvature, we will prove that $\mathcal{M} = \Sigma_m(C)$ is a smooth hypersurface in $\mathcal{R} = \operatorname{Gr}_{n,m}$ and that \mathcal{M} has a unit normal vector field (Proposition 4.2). Since any $W \in \Sigma_m(C)$ intersects K in a unique point $p \in M$ (cf. Lemma 4.1), this defines a map $\Pi_M \colon \Sigma_m(C) \to M, W \mapsto p$. We will prove that Π_M allows us to interpret $\Sigma_m(C)$ as the Grassmann bundle $\operatorname{Gr}(M, m-1)$ over M. The most difficult part of the proof of Theorem 1.5 is to understand the normal Jacobian $|\det D\psi|$ of the parameterization map ψ in our specific situation; see Theorem 4.5. It turns out that the normal Jacobian is a certain subspace-dependent version of the characteristic polynomial of the Weingarten map of M, for which we coined the name twisted characteristic polynomal (cf. Section 4.2).

1.6 Main results III: improved probability estimates

Assuming certain conjectures on the growth of the intrinsic volumes of special cones C, we can considerably improve the bounds in Theorem 1.2.

In Section 3.3 we compute the intrinsic volumes

$$f_j(n) := V_j(\mathcal{L}^n) = 2^{-n} \binom{\frac{n-2}{2}}{\frac{j-1}{2}} \quad \text{for } 1 \le j \le n-1$$
 (1.17)

of the *n*-dimensional Lorentz cone

$$\mathcal{L}^{n} := \{ x \in \mathbb{R}^{n} \mid x_{n} \ge (x_{1}^{2} + \dots + \dots, x_{n-1}^{2})^{1/2} \}$$

(See (3.2) for a formula for $f_n(n) = f_0(n)$.) Note that the sequence $f(n) := (f_0(n), \ldots, f_n(n))$ is symmetric, i.e., $f_{n-j}(n) = f_j(n)$, since \mathcal{L}^n is self-dual.

It will be convenient to compare the intrinsic volumes of a self-dual cone $C \subseteq \mathbb{R}^n$ with the intrinsic volumes of the Lorentz cone \mathcal{L}^n . We thus define the excess e(C) of C over the Lorentz cone as

$$e(C) := \min_{0 \le j \le n} \frac{V_j(C)}{f_j(n)} .$$
(1.18)

 \leftarrow

In other words, e(C) is the smallest constant such that the inequality $V_j(C) \leq e(C)f_j(n)$ is satisfied for all j. Clearly, $e(\mathcal{L}^n) = 1$ by definition. One can check that $e(\mathbb{R}^n_+) < \sqrt{2}$ and $\lim_{n\to\infty} e(\mathbb{R}^n_+) = 1$.

Based on experiments, we set up the following conjecture.

Conjecture 1.7. The convolution of $f(n_1)$ with $f(n_2)$ satisfies $f(n_1) * f(n_2) \le 2f(n_1 + n_2)$ for $n_1, n_2 \ge 2$.

From this conjecture and (1.8) it easily follows that $e(C_1 \times C_2) \leq 2 e(C_1) e(C_2)$ for closed convex cones C_1, C_2 . Therefore, $e(\mathcal{L}^{n_1} \times \ldots \times \mathcal{L}^{n_r}) \leq 2^{r-1}$. For the cone of positive semidefinite \leftarrow matrices, we make the following conjecture; see [2] for motivation and experiments.

Conjecture 1.8. We have $e(\text{Sym}^k_+) < 2$ for the cone Sym^k_+ of positive semidefinite matrices.

The following theorem refines Theorem 1.2 in terms of the excess of the Lorentz cone. We remark that, conditional on the above conjectures, the obtained bounds on the condition number are *independent of the dimension* n *of the ambient space*, for second-order cone programming ($C = \mathcal{L}^{n_1} \times \ldots \times \mathcal{L}^{n_r}$ with r fixed), and for semidefinite programming, respectively.

Theorem 1.9. Let $C \subseteq \mathbb{R}^n$ be a self-dual cone. If $A \in \mathbb{R}^{m \times n}$, with $m \ge 8$, is a standard Gaussian random matrix, then we have

$$\begin{aligned} \operatorname{Prob}[\mathscr{C}(A) > t] &< 20 \, e(C) \, \sqrt{m} \, \frac{1}{t}, \quad \text{if } t > m, \\ \mathbb{E}\left[\ln \mathscr{C}(A)\right] &< \ln m + \max\{\ln e(C), 0\} + 3. \end{aligned}$$

To conclude, let us point out that the shape of the distribution of the intrinsic volumes of a convex cone is currently a subject with a wealth of open questions. We make the following conjecture, that can be considered a spherical analog of the *Alexandrov-Fenchel inequality*; cf. [45, 40]. **Conjecture 1.10.** For every closed convex cone $C \subseteq \mathbb{R}^n$, the sequence V(C) of its intrinsic volumes is *log-concave*, i.e., $V_j(C)^2 \ge V_{j-1}(C) V_{j+1}(C)$ for $1 \le j < n$.

We have verified this conjecture for products of circular cones (in particular for the positive orthant and for products of Lorentz cones); see [1, 2] for more information.

1.7 Outline of paper

We recall some basic facts from Riemannian geometry in Section 2. Section 3 is a short review of spherical convex geometry, with particular emphasis on spherical intrinsic volumes. In Section 4 we derive the tube formula in Theorem 1.5 from a main technical lemma about the normal Jacobian of the exponential map that parametrizes the tube around $\Sigma_m(C)$, the proof of which we defer to Section 7. Along the way, we introduce in Section 4 an algebraic object of possible independent interest: to an endomorphism φ of a Euclidean vector space V together with a linear subspace $Y \subseteq V$, we assign its *twisted characteristic polynomial* $ch_Y(\varphi, t)$. For the proof of the tube formula we will use the fact that the expectation of $ch_Y(\varphi, t)$, with respect to a randomly chosed subspace Y, is an explicit function of the characteristic polynomial of φ . In the interest of clarity, we defer the proof of this last fact to the appendix.

In Section 5, based on the tube formula, we provide the proofs of the main results (Theorem 1.2 and Theorem 1.9), which provide the desired average-case analyses of the Grassmann condition number.

The goal of the last part of the paper is to provide the proofs that have been left open in Section 4. For this, a good understanding of the metric properties of Grassmann manifolds, is required: Section 6 presents the necessary background. Finally, the remaining proofs are provided, the most delicate being the one of Theorem 4.5 that expresses the normal Jacobian of the parameterization map of the tube around $\Sigma_m(C)$ in terms of twisted characteristic polynomials of the Weingarten maps of the boundary of the cone C.

Acknowledgments. We are grateful to one of the anonymous referees for criticism that has led to a substantial improvement of the paper's presentation.

2 Differential geometric preliminaries

2.1 Coarea formula

We define the *normal determinant* of a surjective linear map $A: V \to W$ between Euclidean vector spaces V and W by

$$\operatorname{ndet}(A) := |\det(A|_{\ker(A)^{\perp}})|,$$

where $A|_{\ker(A)^{\perp}}$: $\ker(A)^{\perp} \to W$ denotes the restriction of A to the orthogonal complement of the kernel of A. Obviously, if A is bijective, then $\operatorname{ndet}(A) = |\det(A)|$. Thus the normal determinant provides a natural generalization of the absolute value of the determinant.

The smooth coarea formula, stated below, is our main tool for volume computations.

Theorem 2.1. Let $\varphi \colon \mathcal{R}_1 \to \mathcal{R}_2$ be a smooth surjective map between Riemannian manifolds $\mathcal{R}_1, \mathcal{R}_2$. Then for any $f \colon \mathcal{R}_1 \to \mathbb{R}$ that is integrable with respect to $d\mathcal{R}_1$, we have

$$\int_{\mathcal{R}_1} f \, d\mathcal{R}_1 = \int_{q \in \mathcal{R}_2} \int_{p \in \varphi^{-1}(q)} \frac{f}{\operatorname{ndet}(D_p \varphi)} \, d\varphi^{-1}(q) \, d\mathcal{R}_2 \,. \tag{2.1}$$

If additionally $\dim \mathcal{R}_1 = \dim \mathcal{R}_2$, then

$$\operatorname{vol} \mathcal{R}_2 := \int_{\mathcal{R}_2} d\mathcal{R}_2 \le \int_{q \in \mathcal{R}_2} \# \varphi^{-1}(q) \, d\mathcal{R}_2 = \int_{p \in \mathcal{R}_1} \operatorname{ndet}(D_p \varphi) \, d\mathcal{R}_1 \,, \qquad (2.2)$$

where $\#\varphi^{-1}(q)$ denotes the number of elements in the fiber $\varphi^{-1}(q)$.

See [32, 3.8] or [18, 3.2.11] for proofs of the coarea formula where $\mathcal{R}_1, \mathcal{R}_2$ are submanifolds of Euclidean space. For a proof of the coarea formula in the above stated form, see [29, Appendix]. One calls $\operatorname{ndet}(D_p\varphi)$ the normal Jacobian of φ at p.

Remark 2.2. The inner integral in (2.1) over the fiber $\varphi^{-1}(q)$ is well-defined for almost all $q \in \mathcal{R}_2$, which can be seen as follows: Sard's lemma (cf. [43, Thm. 3-14]) implies that almost all $q \in \mathcal{R}_2$ are regular values, i.e., the derivative $D_p \varphi$ has full rank for all $p \in \varphi^{-1}(q)$. The fibers $\varphi^{-1}(q)$ of regular values q are smooth submanifolds of \mathcal{R}_1 and therefore the integral over $\varphi^{-1}(q)$ is well-defined.

2.2 Exponential maps and tubes

Suppose we are in the situation of Section 1.5. Thus let \mathcal{R} be a compact connected Riemannian manifold and $\mathcal{M} \subseteq \mathcal{R}$ be a compact hypersurface with unit normal vector field ν . Recall the map $\psi \colon \mathcal{M} \times \mathbb{R} \to \mathcal{R}$ from (1.14), which satisfies $\mathcal{T}(\mathcal{M}, \alpha) = \psi(\mathcal{R} \times [-\alpha, \alpha])$ according to (1.15).

We additionally assume that there are closed subsets $\mathcal{P}, \mathcal{D} \subseteq \mathcal{R}$ such that $\mathcal{R} = \mathcal{P} \cup \mathcal{D}$ and $\mathcal{M} = \mathcal{P} \cap \mathcal{D}$. Moreover, we assume that there exists $\epsilon > 0$ such that $\psi(\mathcal{M} \times [0, \epsilon]) \subseteq \mathcal{P}$ and $\psi(\mathcal{M} \times [-\epsilon, 0]) \subseteq \mathcal{D}$. (We express this property by saying that ν points into \mathcal{P} and $-\nu$ points into \mathcal{D} .) In Proposition 4.2 we will show that $\mathcal{P}_m(C)$ and $\mathcal{D}_m(C)$ satisfy these assumptions.

Lemma 2.3. We have

$$\mathcal{T}(\mathcal{M},\alpha) \cap \mathcal{P} \subseteq \psi(\mathcal{M} \times [0,\alpha]) \quad and \quad \mathcal{T}(\mathcal{M},\alpha) \cap \mathcal{D} \subseteq \psi(\mathcal{M} \times [-\alpha,0])$$

for all $\alpha \geq 0$.

Proof. By symmetry, it suffices to prove the first inclusion. Let $q \in \mathcal{P}$ with $\alpha := d(q, \mathcal{M}) > 0$. From (1.15) we get that a minimum length geodesic between some $p \in \mathcal{M}$ and q has the form

$$\gamma \colon [0, \alpha] \to \mathcal{R}, \, \rho \mapsto \exp_p(\rho \,\delta \,\nu(p)) \,,$$

where $\delta \in \{1, -1\}$. It is sufficient to prove that $\delta = 1$. By way of contradiction, assume that $\delta = -1$. Then $q = \gamma(\alpha) = \exp_p(-\alpha\nu(p)) \in \mathcal{P}$. Since by our assumption, we have $\gamma(\rho) \in \mathcal{D}$ for sufficiently small $0 < \rho < \alpha$, there exists $0 \le \alpha_0 < \alpha$ such that $\gamma(\alpha_0) \in \mathcal{P} \cap \mathcal{D} = \mathcal{M}$. Therefore, $d(q, \mathcal{M}) \le d(\gamma(\alpha), \gamma(\alpha_0)) \le \alpha - \alpha_0 < \alpha$, which is a contradiction.

2.3 Weingarten maps

We recall a further basic notion from differential geometry (cf. [46, Ch. 9]). Let M be a (smooth) hypersurface of S^{n-1} with a unit normal vector field ν . The Weingarten map \mathcal{W}_p at $p \in M$ is defined as

$$\mathcal{W}_p \colon T_p M \to T_p M, \quad \mathcal{W}_p(\zeta) = -D_p \nu(\zeta) ,$$
 (2.3)

where $D_p\nu$ denotes the derivative of $\nu: M \to S^{n-1}$ at p. It can be shown that the Weingarten map is self-adjoint; we denote its eigenvalues by $\kappa_1(p), \ldots, \kappa_{n-2}(p)$. These are called the *principal curvatures of* M at p. Furthermore, we denote by $\sigma_k(p)$ the kth elementary symmetric function in the eigenvalues of \mathcal{W}_p . We call the product $\sigma_{n-2}(p) := \kappa_1(p) \cdots \kappa_{n-2}(p)$ the *Gaussian curvature* of M at p.

2.4 Volume of Grassmann manifold

Let $O(n) := \{Q \in \mathbb{R}^{n \times n} \mid QQ^T = I_n\}$ denote the orthogonal group. Recall that \mathcal{O}_i denotes the volume of S^{i-1} , cf. (1.3). The following result is well-known.

Lemma 2.4. We have

$$\operatorname{vol} O(n) = \prod_{i=0}^{n-1} \mathcal{O}_i$$
 and $\operatorname{vol} \operatorname{Gr}_{n,m} = \frac{\operatorname{vol} O(n)}{\operatorname{vol} O(m) \cdot \operatorname{vol} O(n-m)}$

Proof. The map $\varphi : O(n) \to S^{n-1}$, $Q \mapsto Qe_1$, where $e_1 \in \mathbb{R}^n$ denotes the first canonical basis vector, is a Riemannian submersion. In particular, we have $\operatorname{ndet}(D_Q\varphi) = 1$ for all $Q \in O(n)$. Moreover, each fiber of φ is isometric to O(n-1). So an application of the coarea formula (2.1) shows that $\operatorname{vol} O(n) = \mathcal{O}_{n-1} \cdot \operatorname{vol} O(n-1)$ and the formula for $\operatorname{vol} O(n)$ follows by induction.

For $\operatorname{Gr}_{n,m}$, it suffices to note that we have a Riemannian submersion $\Pi: O(n) \to \operatorname{Gr}_{n,m}$, whose fibers are isometric to the direct product $O(m) \times O(n-m)$.

For later use, we record the following

$$\frac{\operatorname{vol}\operatorname{Gr}_{n-2,m-1}}{\operatorname{vol}\operatorname{Gr}_{n,m}} = \frac{\prod_{i=n-m-1}^{n-3}\mathcal{O}_i}{\prod_{i=0}^{m-2}\mathcal{O}_i} \cdot \frac{\prod_{i=n-m}^{m-1}\mathcal{O}_i}{\prod_{i=n-m}^{n-1}\mathcal{O}_i} = \frac{\mathcal{O}_{m-1}\cdot\mathcal{O}_{n-m-1}}{\mathcal{O}_{n-2}\cdot\mathcal{O}_{n-1}} \stackrel{(1.3)}{=} \frac{m(n-m)}{n} \cdot \frac{\omega_m\cdot\omega_{n-m}}{\mathcal{O}_{n-2}\cdot\omega_n}$$

$$\stackrel{(1.9)}{=} \frac{m(n-m)}{n} \cdot \binom{n/2}{m/2} \cdot \frac{1}{\mathcal{O}_{n-2}} \cdot (2.4)$$

3 Background from spherical convex geometry

This section extends the background from spherical convex geometry given in Section 1.3 with special emphasis on spherically convex sets with smooth boundary.

3.1 The metric space of spherically convex sets

Recall that a subset $K \subseteq S^{n-1}$ is called (spherically) convex iff $C := \operatorname{cone}(K)$ is a convex cone. We have $K = C \cap S^{n-1}$. We denote the family of closed spherically convex sets by $\mathcal{K}(S^{n-1})$. The duality map, which sends a closed convex cone C to its polar cone \check{C} , naturally defines an involution on $\mathcal{K}(S^{n-1})$: it maps $K \in \mathcal{K}(S^{n-1})$ to $\check{K} := \check{C} \cap S^{n-1}$. It is easy to check that $\check{K} = \{p \in S^{n-1} \mid d(p, K) \geq \frac{\pi}{2}\}$, where d(p, q) denotes the (spherical) distance between $p, q \in S^{n-1}$.

It is easily seen that a closed convex cone is regular if and only if both C and \check{C} have nonempty interior. We say that $K \in \mathcal{K}(S^{n-1})$ is regular if $\operatorname{cone}(K)$ is regular and denote by $\mathcal{K}^r(S^{n-1})$ the set of regular $K \in \mathcal{K}(S^{n-1})$. The set $\mathcal{K}(S^{n-1})$ is a compact metric space with respect to the Hausdorff metric d_{H} , which for $K_1, K_2 \in \mathcal{K}(S^{n-1})$ is defined by

 $d_{\rm H}(K_1, K_2) := \max \left\{ \min\{\alpha \ge 0 \mid K_2 \subseteq \mathcal{T}(K_1, \alpha)\}, \, \min\{\beta \ge 0 \mid K_1 \subseteq \mathcal{T}(K_2, \beta)\} \right\};$

cf. [33, §1.2]. A spherically convex set $K \in \mathcal{K}(S^{n-1})$ is called *polyhedral* if cone(K) is the intersection of finitely many closed half-spaces (containing the origin). One can show that the set $\mathcal{K}^p(S^{n-1})$ of polyhedral convex sets in S^{n-1} is dense in $\mathcal{K}(S^{n-1})$ with respect to the Hausdorff metric. This is seen by an easy adaption (cf. [24, Hilfssatz 2.5] or [1, Prop. 3.3.4]) of the proof for the corresponding Euclidean statement in [40, §2.4].

Remark 3.1. One important difference between Euclidean and spherical convex geometry are the convexity properties of tubes. In the Euclidean case, the tubes around a convex set are again convex. In the spherical case this is rarely true. Suppose that for $K \in \mathcal{K}(S^{n-1})$ the cone C has a supporting hyperplane $H \subseteq \mathbb{R}^n$, $H \cap \operatorname{int}(C) = \emptyset$, such that the face $H \cap C$ has dimension at least two. Then one can show that the tube $\mathcal{T}(K, \alpha)$ is not convex, unless $\alpha = 0$ or $\mathcal{T}(K, \alpha) = S^{n-1}$. This implies that for $n \geq 3$ and $k \geq 3$, the cones \mathbb{R}^n_+ and Sym^k_+ do not have convex tubes, respectively.

3.2 Smooth convex sets

We call $K \in \mathcal{K}(S^{n-1})$ smooth if K is regular and its boundary $M = \partial K$ is a smooth hypersurface of S^{n-1} with nowhere vanishing Gaussian curvature. Let $\mathcal{K}^{sm}(S^{n-1})$ denote the family of smooth $K \in \mathcal{K}(S^{n-1})$. If we chose for $\nu(p)$ the unit vector in T_pS^{n-1} normal to T_pM and pointing inwards K, then all principal curvatures of M at p are positive, i.e., \mathcal{W}_p is positive definite.

Lemma 3.2. $\mathcal{K}^{sm}(S^{n-1})$ is dense in $\mathcal{K}^r(S^{n-1})$.

An Euclidean analogue of this result was first shown by Minkowski (cf. $[5, \S 6]$). Using this result, it is not hard to derive the above lemma; we refer to [1, Prop. 4.1.10] for a proof.

3.3 Intrinsic volumes

In Section 1.3, we defined the intrinsic volumes $V_0(C), \ldots, V_n(C)$ of a polyhedral convex cone $C \subseteq \mathbb{R}^n$. This allows to define the intrinsic volumes $V_j(K) := V_{j+1}(\operatorname{cone}(K))$ for $K \in \mathcal{K}^p(S^{n-1}), -1 \leq j \leq n-1$. Recall from Section 3.1 that $\mathcal{K}^p(S^{n-1})$ is dense in $\mathcal{K}(S^{n-1})$. It is a well-known fact that the functions $V_j \colon \mathcal{K}^p(S^{n-1}) \to \mathbb{R}$ have a unique continuous extension to $\mathcal{K}(S^{n-1})$ with respect to the Hausdorff metric d_H , cf. [41, Sec. 6.5].

The following well-known facts [41, Sec. 6.5] about the intrinsic volumes are easily verified for polyhedral cones and therefore, by continuity, hold for any closed convex cone.

Proposition 3.3. Let $C \subseteq \mathbb{R}^n$ be a closed convex cone.

- 1. The intrinsic volumes $V_0(C), \ldots, V_n(C)$ form a probability distribution: $V_j(C) \ge 0$ and $\sum_{i=0}^{n} V_j(C) = 1$.
- 2. $V_i(QC) = V_i(C)$ for $Q \in O(n)$ (orthogonal invariance).
- 3. We have $V_i(C) = V_{n-i}(\breve{C})$.

For a regular cone C one can slightly improve the bound $V_i(C) \leq 1$.

Lemma 3.4. For any regular cone $C \subseteq \mathbb{R}^n$ we have $V_j(C) \leq \frac{1}{2}$ for all $0 \leq j \leq n$.

Proof. It is known that

$$V_1(C) + V_3(C) + V_5(C) + \ldots = V_0(C) + V_2(C) + V_4(C) + \ldots = \frac{1}{2}\chi(C \cap S^{d-1}),$$

where χ denotes the *Euler characteristic*, cf. [24, Sec. 4.3] or [41, Thm. 6.5.5]. Moreover, C is contained in an open halfspace since C is regular. This implies $\chi(C \cap S^{d-1}) = 1$.

We next state a well-known formula for the spherical intrinsic volumes of smooth spherically convex sets, which directly follows from Weyl's tube formula [50]. (See [1, Ch. 4] for the proof of a more general statement.)

Proposition 3.5. Let $K \in \mathcal{K}^{sm}(S^{n-1})$ and $0 \leq j \leq n-2$. Then the intrinsic volumes of K are given by

$$V_j(K) = \frac{1}{\mathcal{O}_j \cdot \mathcal{O}_{n-2-j}} \int_{p \in M} \sigma_{n-2-j}(p) \, dM \,,$$

where $M := \partial K$ denotes the boundary of K, and $\sigma_k(p)$ denotes the kth elementary symmetric function in the principal curvatures of M.

For an important special case consider a circular cap $K := B(z,\beta) = \{p \in S^{n-1} \mid d(z,p) \leq \beta\}$ of radius $\beta \in (0,\pi)$. The boundary $M = \partial K$ is a sphere of dimension n-2 and radius $\sin \beta$. Hence $\operatorname{vol}_{n-2}(M) = \sin(\beta)^{n-2} \cdot \mathcal{O}_{n-2}$. The principal curvatures of M at any of its points p are given by $\kappa_1(p) = \ldots = \kappa_{n-2}(p) = \operatorname{cot}(\beta)$. In particular, we have $\sigma_i(p) = \binom{n-2}{i} \operatorname{cot}(\beta)^i$. Proposition 3.5 implies that for $1 \leq j < n$,

$$V_{j}(K) = \frac{\mathcal{O}_{n-2}}{\mathcal{O}_{j-1} \cdot \mathcal{O}_{n-j-1}} \cdot {\binom{n-2}{j-1}} \cdot \sin(\beta)^{j-1} \cdot \cos(\beta)^{n-j-1}$$

$$\stackrel{(5.2)}{=} {\binom{(n-2)/2}{(j-1)/2}} \cdot \frac{\sin(\beta)^{j-1} \cdot \cos(\beta)^{n-j-1}}{2} .$$

Furthermore,

$$V_n(K) = \frac{\mathcal{O}_{n-2}}{\mathcal{O}_{n-1}} \cdot \int_0^\beta \sin(\rho)^{n-2} \, d\rho \stackrel{(1.9)}{=} \binom{(n-2)/2}{(n-1)/2} \cdot \frac{n-1}{2} \cdot \int_0^\beta \sin(\rho)^{n-2} \, d\rho \,. \tag{3.1}$$

Recalling $V_0(K) = V_n(\check{K})$, we get from this

$$V_0(K) = \frac{\mathcal{O}_{n-2}}{\mathcal{O}_{n-1}} \cdot \int_0^\beta \cos(\rho)^{n-2} \, d\rho = \binom{(n-2)/2}{-1/2} \cdot \frac{n-1}{2} \cdot \int_0^{\frac{\pi}{2}-\beta} \sin(\rho)^{n-2} \, d\rho \,. \tag{3.2}$$

The intersection of a Lorentz cone \mathcal{L}^n with S^{n-1} is a circular cap of radius $\beta = \frac{\pi}{4}$. From the above, we obtain the formula for $f_j(n) = V_j(\mathcal{L}^n)$ that was already stated in (1.17).

4 Deriving the Grassmannian tube formula

Let $C \subseteq \mathbb{R}^n$ be a regular cone and put $K := C \cap S^{n-1}$. In a first step, we reduce the proof of Theorem 1.5 to the case where K is smooth. Consider both sides of the inequality (1.12): the intrinsic volumes $V_{j+1}(C) = V_j(K)$ are continuous in K with respect to the Hausdorff metric. Furthermore, it is straightforward to check that, for fixed α , rvol $\mathcal{T}^{\mathbb{P}}(\Sigma_m(K), \alpha)$ depends continuously on K, cf. [1, Lemma 6.1.7]. Moreover, by Lemma 3.2, $\mathcal{K}^{\mathrm{sm}}(S^{n-1})$ is dense in $\mathcal{K}^r(S^{n-1})$. Therefore, for proving Theorem 1.5, we can assume without loss of generality that $K \in \mathcal{K}^{\mathrm{sm}}(S^{n-1})$.

4.1 Parameterizing the tube around Σ_m

In this subsection, we assume that $C = \operatorname{cone}(K)$ for some $K \in \mathcal{K}^{\operatorname{sm}}(S^{n-1})$. Fix $1 \leq m < n$. In Section 1.1, we assigned to C the compact subsets $\mathcal{P}_m(C)$ and $\mathcal{D}_m(C)$ of the Grassmann manifold $\operatorname{Gr}_{n,m}$. The set $\Sigma_m(C) = \mathcal{P}_m(C) \cap \mathcal{D}_m(C)$ consists of the subspaces W touching C. It is known that $\Sigma_m := \Sigma_m(C)$ is the common boundary of $\mathcal{P}_m(C)$ and $\mathcal{D}_m(C)$, cf. [2]. We analyze now the geometry of $\Sigma_m(C)$.

We begin with the basic observation that any $W \in \Sigma_m(C)$ intersects K in a unique point p, which moreover lies in the boundary of K. This allows us to define the map $\Pi_M \colon \Sigma_m \to \partial K, W \mapsto p$.

Lemma 4.1. If $W \in \Sigma_m$, then $W \cap K = \{p\}$ for some $p \in \partial K$.

Proof. As $W \in \Sigma_m$, we have $\Sigma_m \cap C = \Sigma_m \cap \partial C \neq \{0\}$. It follows that there exists $p \in W \cap K$. To prove that p is the only element in $W \cap K$, we assume that there exists $q \in W \cap K$, $p \neq q$. As K is regular, we have $p \neq -q$, so that there exists a unique great circle segment between pand q. By convexity of W and K, this arc lies in $W \cap K$, and thus in the boundary of K. But this implies that along this arc, M has zero Gaussian curvature, which contradicts the assumption $K \in \mathcal{K}^{\mathrm{sm}}(S^{n-1})$.

Write $M := \partial K$. Later on, we will see that $\Pi_M \colon \Sigma_m \to M, W \mapsto p$ can be interpreted as the Grassmann bundle $\operatorname{Gr}(M, m-1)$ over M. This will lead us to the following basic result, whose proof is postponed to Section 7.

Proposition 4.2. Let $K \in \mathcal{K}^{sm}(S^{n-1})$ and $C := \operatorname{cone}(K)$. Then $\Sigma_m(C)$ is a connected hypersurface of $\operatorname{Gr}_{n,m}$. Moreover, $\Sigma_m(C)$ has a unit normal vector field ν_{Σ} such that ν_{Σ} points into $\mathcal{P}_m(C)$ and $-\nu_{\Sigma}$ points into $\mathcal{D}_m(C)$ (compare Section 2.2 for this notion).

Proposition 4.2 says that we are in the situation of Section 1.5, where $\mathcal{R} = \operatorname{Gr}_{n,m}$ and $\mathcal{M} = \Sigma_m(C)$. We reparameterize the map $\psi \colon \Sigma_m \times \mathbb{R}, (W, \theta) \mapsto \exp_W(\theta \nu_{\Sigma}(W))$ by setting $t = \tan \theta$ and thus obtain the smooth map

$$\Psi \colon \Sigma_m \times \mathbb{R} \to \operatorname{Gr}_{n,m}, \ W \mapsto \exp_W(\arctan t \,\nu_{\Sigma}(W)) \ . \tag{4.1}$$

The main technical difficulty is to understand the normal Jacobian of Ψ . It turns out that the normal Jacobian is a certain subspace-dependent version of the characteristic polynomial of the Weingarten map of $M = \partial K$. In the next section we define this purely algebraic notion, for which we coined the name twisted characteristic polynomal.

4.2 Twisted characteristic polynomials

Let φ be an endomorphism of a k-dimensional Euclidean vector space V. We denote by $\sigma_j(\varphi)$, $0 \leq j \leq k$, the coefficients of the characteristic polynomial of φ (up to sign). More precisely,

$$\det(\varphi - t \cdot \mathrm{id}_V) = \sum_{i=0}^k (-1)^{k-i} \cdot \sigma_i(\varphi) \cdot t^{k-i} .$$

Note that we have $\sigma_k(\varphi) = \det(\varphi)$, $\sigma_0(\varphi) = 1$, and $\sigma_1(\varphi) = \operatorname{trace}(\varphi)$. In the following we denote by $\operatorname{Gr}(V, \ell)$ the set of all ℓ -dimensional linear subspaces of V.

Definition 4.3. Let $Y \in Gr(V, \ell)$, and denote by Π_Y and $\Pi_{Y^{\perp}}$ the orthogonal projections onto Y and Y^{\perp} , respectively. The *twisted characteristic polynomial* ch_Y with respect to Y is defined as

$$\operatorname{ch}_{Y}(\varphi, t) := t^{k-\ell} \cdot \det \left(\varphi - \left(t \cdot \Pi_{Y} - \frac{1}{t} \cdot \Pi_{Y^{\perp}} \right) \right)$$

We denote by $\varphi_Y \colon Y \to Y$ the *restriction* of φ , i.e., $\varphi_Y(y) \coloneqq \Pi_Y(\varphi(y))$, and we use the notation $\det_Y(\varphi) \coloneqq \det(\varphi_Y)$.

Note that for $\ell = k$ we get $ch_V(\varphi, t) = det(\varphi - t \cdot id_V)$, the usual characteristic polynomial, whereas for $\ell = 0$ we get $ch_0(\varphi, t) = det(t \cdot \varphi + id_V)$.

We claim that

$$ch_Y(\varphi, 0) = det_Y(\varphi) . \tag{4.2}$$

In order to see this, let us express the twisted characteristic polynomial in coordinates. For $A \in \mathbb{R}^{k \times k}$ and $0 \leq \ell \leq k$ we use the notation $\operatorname{ch}_{\ell}(A, t) := \operatorname{ch}_{\mathbb{R}^{\ell} \times 0}(\varphi, t)$, where $\varphi \colon \mathbb{R}^{k} \to \mathbb{R}^{k}$, $x \mapsto Ax$. Note that if A has the block decomposition $A = \begin{pmatrix} A_{1} & A_{2} \\ A_{3} & A_{4} \end{pmatrix}$, where $A_{1} \in \mathbb{R}^{\ell \times \ell}$, and the other blocks accordingly, then

$$ch_{\ell}(A,t) = det \begin{pmatrix} A_1 - tI_{\ell} & A_2 \\ tA_3 & tA_4 + I_{k-\ell} \end{pmatrix}.$$
(4.3)

From this description we get for $Y = \mathbb{R}^{\ell} \times 0$ the identity $\operatorname{ch}_{Y}(\varphi, 0) = \operatorname{det}(A_{1}) = \operatorname{det}_{Y}(\varphi)$, which proves (4.2).

The next result expresses the expectation of the twisted characteristic polynomial $ch_Y(\varphi, t)$, taken over a random subspace $Y \in Gr(V, \ell)$, concisely in terms of the (coefficients of) the characteristic polynomial of φ . We postpone the proof of this result to Appendix A.

Theorem 4.4. Let V be a k-dimensional Euclidean vector space and let φ be an endomorphism of V. If $Y \in Gr(V, \ell)$ is chosen uniformly at random, then

$$\mathbb{E}_{Y}\left[\det_{Y}(\varphi)\right] = \frac{1}{\binom{k}{\ell}} \cdot \sigma_{\ell}(\varphi) .$$
(4.4)

Moreover, the expectation of the twisted characteristic polynomial is given by

$$\mathbb{E}_{Y}[\operatorname{ch}_{Y}(\varphi,t)] = \sum_{i,j=0}^{k} d_{ij} \cdot \sigma_{k-j}(\varphi) \cdot t^{k-i} , \qquad (4.5)$$

where the coefficients d_{ij} are given by

$$d_{ij} := (-1)^{\frac{i-j}{2} - \frac{\ell}{2}} \cdot \frac{\binom{\ell}{i-j} + \binom{k-\ell}{2} \cdot \binom{k-\ell}{\frac{j}{2} - \frac{\ell}{2}}}{\binom{k}{j}},$$

for $i + j + \ell \equiv 0 \mod 2$, $0 \leq \frac{i-j}{2} + \frac{\ell}{2} \leq \ell$, and $0 \leq \frac{i+j}{2} - \frac{\ell}{2} \leq k - \ell$; and given by $d_{ij} := 0$ otherwise. (Note that $|d_{ij}| = d_{ij}^{k+2,\ell+1}$ in the notation of (1.13).)

If φ is positive semidefinite, then we have for $t \in \mathbb{R}$ that

$$\mathbb{E}_{Y}\left[\left|\operatorname{ch}_{Y}(\varphi,t)\right|\right] \leq \sum_{i,j=0}^{k} |d_{ij}| \cdot \sigma_{k-j}(\varphi) \cdot |t|^{k-i} .$$
(4.6)

We are now in a position to state the announced formula that expresses the Jacobian of the parameter map Ψ in terms of the twisted characteristic polynomial of the Weingarten map of ∂K . We postpone the rather difficult proof to Section 7.

Theorem 4.5. Let $K \in \mathcal{K}^{sm}(S^{n-1})$ and write $M := \partial K$, $C := \operatorname{cone}(K)$, and $\Sigma_m := \Sigma_m(C)$. For $W \in \Sigma_m$ let $\nu_{\Sigma}(W) \in T_W \operatorname{Gr}_{n,m}$ denote the unit normal vector pointing inside $\mathcal{P}_m(K)$. We define the maps Π_M and Ψ via

$$\Pi_{M} \colon \Sigma_{m} \to M \qquad \Psi \colon \Sigma_{m} \times \mathbb{R} \to \operatorname{Gr}_{n,m}$$

$$W \mapsto p , \text{ where } W \cap K = \{p\} , \qquad (W,t) \mapsto \exp_{W}(\arctan t \cdot \nu_{\Sigma}(W)) .$$

$$(4.7)$$

Then the normal Jacobians of Π_M and Ψ are given by

$$\operatorname{ndet}(D_W \Pi_M) = \operatorname{det}_Y(\mathcal{W}_p)^{-1}, \qquad |\operatorname{det}(D_{(W,t)}\Psi)| = (1+t^2)^{-n/2} \cdot \frac{|\operatorname{ch}_Y(\mathcal{W}_p, -t)|}{\operatorname{det}_Y(\mathcal{W}_p)}, \qquad (4.8)$$

where $W \cap K = \{p\}, Y := p^{\perp} \cap W$, and \mathcal{W}_p denotes the Weingarten map of M at p.

After these preparations, we are now ready to present the proof of the tube formula stated in Theorem 1.5.

4.3 The Grassmannian tube formula

Proof of Theorem 1.5. By Proposition 4.2, $\mathcal{P}_m(C)$ and $\mathcal{D}_m(C)$ satisfy the assumptions of Lemma 2.3, hence $\mathcal{T}^{\mathsf{P}}(\Sigma_m, \alpha) \subseteq \Psi(\Sigma_m \times [0, \alpha])$. Let $0 \leq \alpha \leq \pi/2$ and put $\tau := \tan \alpha$. Applying the coarea formula to the map Ψ and using the formula in (4.8) for the Jacobian of Ψ , we obtain

$$\operatorname{vol} \mathcal{T}^{\mathsf{P}}(\Sigma_{m}, \alpha) \stackrel{(2.2)}{\leq} \int_{(W,t)\in\Sigma_{m}\times[0,\tau]} |\det(D_{(W,t)}\Psi)| \, d(\Sigma_{m}\times\mathbb{R})$$

$$\stackrel{(4.8)}{=} \int_{W\in\Sigma_{m}} \int_{0}^{\tau} (1+t^{2})^{-n/2} \cdot \frac{|\operatorname{ch}_{Y}(\mathcal{W}_{p}, -t)|}{\det_{Y}(\mathcal{W}_{p})} \, dt \, dW$$

Changing the integration via the coarea formula applied to the map $\Pi_M \colon \Sigma_m \to M$, and using the formula in (4.8) for the normal Jacobian of Π_M , we get

$$\operatorname{vol} \mathcal{T}^{\mathsf{P}}(\Sigma_m, \alpha) \leq \int_{p \in M} \int_{Y \in \operatorname{Gr}(T_pM, m-1)} \int_0^\tau (1+t^2)^{-n/2} \cdot |\operatorname{ch}_Y(\mathcal{W}_p, -t)| \, dt \, dY \, dp$$
$$= \int_{p \in M} \int_0^\tau \frac{\operatorname{vol} \operatorname{Gr}_{n-2, m-1}}{(1+t^2)^{n/2}} \cdot \mathop{\mathbb{E}}_Y \Big[|\operatorname{ch}_Y(\mathcal{W}_p, -t)| \Big] \, dt \, dp \,,$$

where the expectation is with respect to Y chosen uniformly at random in $Gr(T_pM, m-1)$. Using the bound (4.6) in Theorem 4.4 with k = n - 2 and $\ell = m - 1$, we obtain

$$\operatorname{vol} \mathcal{T}^{\mathsf{P}}(\Sigma_{m}, \alpha) \leq \int_{p \in M} \int_{0}^{\tau} \frac{\operatorname{vol} \operatorname{Gr}_{n-2,m-1}}{(1+t^{2})^{n/2}} \cdot \sum_{i,j=0}^{n-2} \left| d_{ij}^{mm} \right| \cdot \sigma_{n-2-j}(\mathcal{W}_{p}) \cdot t^{n-2-i} \, dt \, dp$$

$$= \operatorname{vol} \operatorname{Gr}_{n-2,m-1} \cdot \sum_{i,j=0}^{n-2} \left| d_{ij}^{mm} \right| \cdot \int_{0}^{\tau} \frac{t^{n-2-i}}{(1+t^{2})^{n/2}} \, dt \cdot \int_{p \in M} \sigma_{n-2-j}(\mathcal{W}_{p}) \, dp$$

$$= \operatorname{vol} \operatorname{Gr}_{n-2,m-1} \cdot \sum_{i,j=0}^{n-2} \left| d_{ij}^{nm} \right| \cdot I_{n,i}(\alpha) \cdot \mathcal{O}_{j} \cdot \mathcal{O}_{n-2-j} \cdot V_{j+1}(K) \, ,$$

where for the last equality, we have used Proposition 3.5 and the definition (1.4) of the functions $I_{n,i}(\alpha)$. Finally, we get for rvol $\mathcal{T}^{\mathrm{P}}(\Sigma_m, \alpha) = \frac{\mathrm{vol}\,\mathcal{T}^{\mathrm{P}}(\Sigma_m, \alpha)}{\mathrm{vol}\,\mathrm{Gr}_{n,m}}$, using the formulas (1.9) and (2.4)

$$\operatorname{rvol} \mathcal{T}^{\mathbf{P}}(\Sigma_{m}, \alpha) \leq \frac{\operatorname{vol} \operatorname{Gr}_{n-2,m-1}}{\operatorname{vol} \operatorname{Gr}_{n,m}} \cdot \sum_{i,j=0}^{n-2} \left| d_{ij}^{nm} \right| \cdot I_{n,i}(\alpha) \cdot \mathcal{O}_{j} \cdot \mathcal{O}_{n-2-j} \cdot V_{j+1}(K)$$

$$\stackrel{(2.4)}{=} \frac{2m(n-m)}{n} \cdot \binom{n/2}{m/2} \cdot \sum_{j=0}^{n-2} V_{j+1}(K) \cdot \frac{\mathcal{O}_{j} \cdot \mathcal{O}_{n-2-j}}{2 \cdot \mathcal{O}_{n-2}} \cdot \sum_{i=0}^{n-2} \left| d_{ij}^{nm} \right| \cdot I_{n,i}(\alpha)$$

$$\stackrel{(1.9)}{=} \frac{2m(n-m)}{n} \cdot \binom{n/2}{m/2} \cdot \sum_{j=0}^{n-2} V_{j+1}(K) \cdot \begin{bmatrix} n-2\\ j \end{bmatrix} \cdot \sum_{i=0}^{n-2} \left| d_{ij}^{nm} \right| \cdot I_{n,i}(\alpha) .$$

The upper bound on the volume of $\mathcal{T}^{D}(\Sigma_{m}, \alpha)$ is proved analogously.

5 Condition number estimates

We derive here Theorem 1.2 and Theorem 1.9 from the tube formula in Theorem 1.5.

5.1 Some technical estimations

In the following proposition we collect some useful identities involving the binomial coefficients and the flag coefficients introduced in (1.10).

Proposition 5.1. *1.* For $n, m \in \mathbb{N}$, $n \ge m$,

$$\binom{n}{m} = \binom{n}{m} \binom{n/2}{m/2} = \frac{\sqrt{\pi} \cdot \Gamma(\frac{n+1}{2}) \cdot \Gamma(\frac{n+2}{2})}{\Gamma(\frac{m+1}{2}) \cdot \Gamma(\frac{m+2}{2}) \cdot \Gamma(\frac{n-m+1}{2}) \cdot \Gamma(\frac{n-m+2}{2})}$$

2. For $n, m \in \mathbb{N}$, $n \ge m$,

$$\binom{n/2}{m/2} = \frac{\omega_m \cdot \omega_{n-m}}{\omega_n} \quad , \qquad \begin{bmatrix} n\\m \end{bmatrix} = \frac{\mathcal{O}_m \cdot \mathcal{O}_{n-m}}{2 \mathcal{O}_n} \,. \tag{5.1}$$

In particular,

$$\binom{n}{m} \cdot \frac{\omega_n}{\omega_m \cdot \omega_{n-m}} = \begin{bmatrix} n\\ m \end{bmatrix} \quad , \qquad \binom{n}{m} \cdot \frac{2\mathcal{O}_n}{\mathcal{O}_m \cdot \mathcal{O}_{n-m}} = \binom{n/2}{m/2} \quad . \tag{5.2}$$

3. For $n, m \to \infty$ such that $(n-m) \to \infty$,

$$\begin{bmatrix} n \\ m \end{bmatrix} \sim \sqrt{\frac{\pi}{2}} \cdot \sqrt{\frac{m(n-m)}{n}} \cdot \binom{n/2}{m/2} , \qquad (5.3)$$

where the symbol \sim means that the quotient of the two sides tends to one.

Proof. The first equation in (1) follows from applying the duplication formula of the Γ -function $\Gamma(2x) = \frac{1}{\sqrt{\pi}} \cdot 2^{2x-1} \cdot \Gamma(x) \cdot \Gamma(x+\frac{1}{2})$ to the term $\binom{n}{m} = \frac{\Gamma(n+1)}{\Gamma(m+1) \cdot \Gamma(n-m+1)}$. The remaining equations follow by plugging in the definitions of the corresponding quantities. As for the asymptotics stated in (5.3), we compute

$$\begin{split} \sqrt{\frac{\pi}{2}} \cdot \sqrt{\frac{m(n-m)}{n}} \cdot \binom{n/2}{m/2} &= \sqrt{\frac{\pi}{2}} \cdot \sqrt{\frac{m(n-m)}{n}} \cdot \frac{\Gamma(\frac{n}{2}+1)}{\Gamma(\frac{m}{2}+1) \cdot \Gamma(\frac{n-m}{2}+1)} \\ &= \frac{\sqrt{\pi} \cdot \sqrt{\frac{n}{2}} \cdot \Gamma(\frac{n}{2})}{\sqrt{\frac{m}{2}} \cdot \Gamma(\frac{m}{2}) \cdot \sqrt{\frac{n-m}{2}} \cdot \Gamma(\frac{n-m}{2})} \sim \frac{\sqrt{\pi} \cdot \Gamma(\frac{n+1}{2})}{\Gamma(\frac{m+1}{2}) \cdot \Gamma(\frac{n-m+1}{2})} = \begin{bmatrix} n\\m \end{bmatrix}, \end{split}$$

where we have used the asymptotics $\sqrt{x} \cdot \Gamma(x) \sim \Gamma(x + \frac{1}{2})$ for $x \to \infty$.

We now rewrite the upper bound in Theorem 1.5.

Lemma 5.2. Let $C \subseteq \mathbb{R}^n$ be a regular cone, $1 \leq m < n$, and $0 \leq \alpha \leq \frac{\pi}{2}$. Using the convention $\binom{k}{\ell} := 0$ if $\ell < 0$ or $\ell > k$, we have

$$\operatorname{rvol} \mathcal{T}(\Sigma_m(C), \alpha) \leq 8 \sum_{i,k=0}^{n-2} V_{n-m-i+2k}(C) \cdot \frac{\Gamma(\frac{m+i-2k+1}{2})}{\Gamma(\frac{m}{2})} \cdot \frac{\Gamma(\frac{n-m-i+2k+1}{2})}{\Gamma(\frac{n-m}{2})} \cdot \binom{m-1}{k} \binom{n-m-1}{i-k} \cdot I_{n,n-2-i}(\alpha).$$

Proof. Theorem 1.5 implies that

$$\operatorname{rvol} \mathcal{T}(\Sigma_m(C), \alpha) \leq \frac{4m(n-m)}{n} \binom{n/2}{m/2} \cdot \sum_{j=0}^{n-2} V_{j+1}(C) \cdot {n-2 \brack j} \cdot \sum_{i=0}^{n-2} d_{ij}^{mm} \cdot I_{n,i}(\alpha) . \quad (5.4)$$

Using Proposition 5.1, we derive the following identity:

$$\frac{4m(n-m)}{n} \cdot \frac{\binom{n/2}{m/2} \cdot \binom{n-2}{j}}{\binom{n-2}{j}} \stackrel{(1)}{=} \frac{4m(n-m)}{n} \cdot \frac{\binom{n/2}{m/2}}{\binom{(n-2)/2}{j/2}}$$
$$\stackrel{(1.9)}{=} \frac{4m(n-m)}{n} \cdot \frac{\Gamma(\frac{n+2}{2})}{\Gamma(\frac{m+2}{2}) \cdot \Gamma(\frac{n-m+2}{2})} \cdot \frac{\Gamma(\frac{j+2}{2}) \cdot \Gamma(\frac{n-j}{2})}{\Gamma(\frac{n}{2})} = 8 \cdot \frac{\Gamma(\frac{j+2}{2})}{\Gamma(\frac{m}{2})} \cdot \frac{\Gamma(\frac{n-j}{2})}{\Gamma(\frac{n-m}{2})} .$$

Using this in (5.4), changing the summation via $i \leftarrow n-2-i$ and $j \leftarrow n-2-j$, and taking into account the symmetry relations for d_{ij}^{nm} stated in Remark 1.6, we get

$$\operatorname{rvol} \mathcal{T}(\Sigma_{m}(C), \alpha) \leq 8 \sum_{i,j=0}^{n-2} \frac{\Gamma(\frac{j+2}{2})}{\Gamma(\frac{m}{2})} \cdot \frac{\Gamma(\frac{n-j}{2})}{\Gamma(\frac{n-m}{2})} \cdot V_{j+1}(C) \cdot \binom{n-2}{j} \cdot d_{ij}^{nm} \cdot I_{n,i}(\alpha)$$

$$= 8 \sum_{i,j=0}^{n-2} \frac{\Gamma(\frac{j+2}{2})}{\Gamma(\frac{m}{2})} \cdot \frac{\Gamma(\frac{n-j}{2})}{\Gamma(\frac{n-m}{2})} \cdot V_{n-1-j}(C) \cdot \binom{n-2}{j} \cdot d_{ij}^{nm} \cdot I_{n,n-2-i}(\alpha) \qquad (5.5)$$

$$= 8 \sum_{\substack{i,j=0\\i+j+m\equiv 1\\(\text{mod } 2)}}^{n-2} V_{n-1-j}(C) \cdot \frac{\Gamma(\frac{j+2}{2})}{\Gamma(\frac{m}{2})} \cdot \frac{\Gamma(\frac{n-j}{2})}{\Gamma(\frac{n-m}{2})} \cdot \binom{m-1}{\frac{i-j}{2} + \frac{m-1}{2}} \binom{n-m-1}{\frac{i+j}{2} - \frac{m-1}{2}} \cdot I_{n,n-2-i}(\alpha) .$$

Here we interpret $\binom{k}{\ell} = 0$ if $\ell < 0$ or $\ell > k$, i.e., the above summation over i, j in fact only runs over the rectangle determined by the inequalities $0 \leq \frac{i-j}{2} + \frac{m-1}{2} \leq m-1$ and $0 \leq \frac{i+j}{2} - \frac{m-1}{2} \leq n-m-1$ (cf. Figure 1). As the summation runs only over those i, j, for which $i+j+m \equiv 1 \mod 2$, we may replace the summation over j by a summation over $k = \frac{i-j}{2} + \frac{m-1}{2}$. The above inequalities then transform into $0 \leq k \leq m-1$ and $0 \leq i-k \leq n-m-1$. So we get from (5.5)

$$\operatorname{rvol} \mathcal{T}(\Sigma_m(C), \alpha) = 8 \sum_{i,k=0}^{n-2} V_{n-m-i+2k}(C) \cdot \frac{\Gamma(\frac{m+i-2k+1}{2})}{\Gamma(\frac{m}{2})} \cdot \frac{\Gamma(\frac{n-m-i+2k+1}{2})}{\Gamma(\frac{n-m}{2})} \cdot \binom{m-1}{k} \binom{n-m-1}{i-k} \cdot I_{n,n-2-i}(\alpha) . \qquad \Box$$

In the next lemma we provide a number of technical estimates. For the ease of presentation we defer the proof of this lemma to Appendix B.

Lemma 5.3. Let $i, k, \ell, m, n \in \mathbb{N}$ with $n \ge 2$ and $1 \le m \le n-1$.

1. We have

$$\frac{\Gamma(\frac{m+\ell+1}{2})}{\Gamma(\frac{m}{2})} \le \sqrt{\frac{m}{2}} \cdot \left(\frac{m+\ell}{2}\right)^{\frac{\ell}{2}} .$$
(5.6)

2. For $0 \le k \le m-1$ and $0 \le i-k \le n-m-1$ we have

$$\left(\frac{m+i-2k}{n-m-i+2k}\right)^{\frac{i-2k}{2}} < n^{\frac{i}{2}} .$$
 (5.7)

3. For $0 \le \alpha \le \frac{\pi}{2}$, $t := \sin(\alpha)^{-1}$, and $n \ge 3$, we have

$$\sum_{i=0}^{n-2} \binom{n-2}{i} \cdot n^{\frac{i}{2}} \cdot I_{n,n-2-i}(\alpha) < \frac{3}{t}, \quad if \, t > n^{\frac{3}{2}}, \tag{5.8}$$

$$\sum_{i=0}^{n-2} \binom{n-2}{i} \cdot I_{n,n-2-i}(\alpha) < \exp\left(\frac{n}{m}\right) \cdot \frac{1}{t}, \quad if \ t > m \ . \tag{5.9}$$

5.2 Proof of the general bound

In the following proof, in the remainder of this section as well as in Appendix B, we will mark estimates that are easily checked with a computer algebra system with the symbol $\overline{\blacksquare}$.

Proof of Theorem 1.2. We have $V_j(C) \leq \frac{1}{2}$ by Lemma 3.4. Using this bound in Lemma 5.2 and applying Lemma 5.3, we get

$$\operatorname{rvol} \mathcal{T}(\Sigma_{m}, \alpha) \leq 8 \sum_{i,k=0}^{n-2} V_{n-m-i+2k}(C) \cdot \frac{\Gamma(\frac{m+i-2k+1}{2})}{\Gamma(\frac{m}{2})} \cdot \frac{\Gamma(\frac{n-m-i+2k+1}{2})}{\Gamma(\frac{n-m}{2})} \\ \cdot \binom{m-1}{k} \binom{n-m-1}{i-k} \cdot I_{n,n-2-i}(\alpha) \\ \stackrel{(5.6)}{\leq} 2\sqrt{m(n-m)} \sum_{i,k=0}^{n-2} \left(\frac{m+i-2k}{2}\right)^{\frac{i-2k}{2}} \left(\frac{n-m-i+2k}{2}\right)^{-\frac{i-2k}{2}} \\ \cdot \binom{m-1}{k} \binom{n-m-1}{i-k} \cdot I_{n,n-2-i}(\alpha) \\ \stackrel{(5.7)}{\leq} 2\sqrt{m(n-m)} \sum_{i=0}^{n-2} n^{\frac{i}{2}} \cdot I_{n,n-2-i}(\alpha) \cdot \sum_{k=0}^{n-2} \binom{m-1}{k} \binom{n-m-1}{i-k}.$$

By Vandermonde's identity we have $\sum_{k=0}^{n-2} {m-1 \choose k} {n-m-1 \choose i-k} = {n-2 \choose i}$. So we get

$$\text{rvol } \mathcal{T}(\Sigma_m, \alpha) \leq 2\sqrt{m(n-m)} \sum_{i=0}^{n-2} \binom{n-2}{i} \cdot n^{\frac{i}{2}} \cdot I_{n,n-2-i}(\alpha)$$

$$\stackrel{(5.8)}{<} 6\sqrt{m(n-m)} \frac{1}{t} , \quad \text{if } t > n^{\frac{3}{2}} \text{ and } n \geq 3 .$$

This is the tail bounded stated in Theorem 1.2.

As for the expectation of the logarithm of the Grassmann condition, we compute

$$\begin{split} \mathbb{E}\left[\ln \mathscr{C}_{\rm G}(A)\right] &= \int_{0}^{\infty} \operatorname{Prob}[\ln \mathscr{C}_{\rm G}(A) > s] \, ds \\ &< 1.5 \, \ln(n) + r + \int_{\ln(n^{3/2}) + r}^{\infty} 6 \sqrt{m(n-m)} \cdot \exp(-s) \, ds \\ &= 1.5 \, \ln(n) + r + 6 \underbrace{\frac{\sqrt{m(n-m)}}{n^{3/2}}}_{\leq \frac{2}{3}\sqrt{6} \, , \, \text{if} \, n \geq 3} \cdot \exp(-r) \\ &\underbrace{\underbrace{\leq \frac{2}{3}\sqrt{6}}_{\leq 1.5 \, \ln(n)} + 1.5 \, , \end{split}$$

if we choose $r := \frac{1}{2} \ln \left(\frac{8}{3} \right)$. This finishes the proof of Theorem 1.2.

5.3 A certain log-concave sequence

Before we finish this section with the proof of Theorem 1.9, we need yet another technical lemma. A sequence (a_n) of nonnegative real numbers is called *log-concave* iff $a_n^2 \ge a_{n-1} a_{n+1}$ for all n. See [45] for a survey on log-concave sequences and their appearances in diverse areas of mathematics.

Lemma 5.4. For $n \ge 2$ and $1 \le m \le n-1$ let $g_m(n) := \frac{\Gamma(\frac{n}{2}) \cdot \exp(\frac{n}{m})}{\Gamma(\frac{m}{2}) \cdot \Gamma(\frac{n-m}{2}) \cdot 2^{n/2}}$.

- 1. The sequence $(g_m(n))_n$ is log-concave, i.e., $g_m(n)^2 \ge g_m(n-1) g_m(n+1)$ for $n \ge m+2$.
- 2. For fixed $m \ge 8$ we have $\max\{g_m(n) \mid n > m\} = \max\{g_m(2m+k) \mid k \in \{5, 6, 7\}\}.$
- 3. For $m \ge 8$ we have

$$g_m(n) < 2.5\sqrt{m}$$
 . (5.10)

Proof. (1) We have

$$\frac{g_m(n)^2}{g_m(n-1)\,g_m(n+1)} = \frac{\Gamma(\frac{n}{2})^2}{\Gamma(\frac{n-m}{2})^2} \cdot \frac{\Gamma(\frac{n-1-m}{2})}{\Gamma(\frac{n-1}{2})} \cdot \frac{\Gamma(\frac{n+1-m}{2})}{\Gamma(\frac{n+1}{2})}$$

In order to show that this expression is greater or equal than 1, we use induction on m. For m = 0 this is trivially true, and for m = 1 this is easily checked with a computer algebra system. For $m \ge 2$ we have, using $\Gamma(x+1) = x \cdot \Gamma(x)$,

$$\begin{split} & \frac{\Gamma(\frac{n}{2})^2}{\Gamma(\frac{n-m}{2})^2} \cdot \frac{\Gamma(\frac{n-1-m}{2})}{\Gamma(\frac{n-1}{2})} \cdot \frac{\Gamma(\frac{n+1-m}{2})}{\Gamma(\frac{n+1}{2})} \\ &= \underbrace{\frac{(n-m)^2}{(n-1-m) \cdot (n+1-m)}}_{>1} \cdot \underbrace{\frac{\Gamma(\frac{n}{2})^2}{\Gamma(\frac{n-(m-2)}{2})^2} \cdot \frac{\Gamma(\frac{n-1-(m-2)}{2})}{\Gamma(\frac{n-1}{2})} \cdot \frac{\Gamma(\frac{n+1-(m-2)}{2})}{\Gamma(\frac{n+1}{2})} > 1 \\ &\xrightarrow{\geq 1} \text{ by ind. hyp.} \end{split}$$

(2) As the sequence $(g_m(n))_n$ is log-concave and positive, it follows that it is unimodal. This means that there exists an index N such that $g_m(n-1) \leq g_m(n)$ for all $n \leq N$, and $g_m(n) \geq g_m(n+1)$ for all $n \geq N$ (cf. [45]). Moreover, for $m \geq 8$ we have $N \in \{2m+k \mid k \in \{5,6,7\}\}$, as

$$\frac{g_m(2m+4)}{g_m(2m+5)} = \frac{\Gamma(\frac{2m+4}{2})}{\Gamma(\frac{2m+5}{2})} \cdot \frac{\Gamma(\frac{m+5}{2})}{\Gamma(\frac{m+4}{2})} \cdot \frac{\sqrt{2}}{\exp\left(\frac{1}{m}\right)} \stackrel{(\ensuremath{\blacksquare})}{<} 1 ,$$
$$\frac{g_m(2m+7)}{g_m(2m+8)} = \frac{\Gamma(\frac{2m+7}{2})}{\Gamma(\frac{2m+8}{2})} \cdot \frac{\Gamma(\frac{m+8}{2})}{\Gamma(\frac{m+7}{2})} \cdot \frac{\sqrt{2}}{\exp\left(\frac{1}{m}\right)} \stackrel{(\ensuremath{\blacksquare})}{>} 1 , \qquad \text{for } m \ge 8$$

(3) For fixed k, the following asymptotics is easily verified:

$$\frac{g_m(2m+k)}{\sqrt{m}} \quad \stackrel{m \to \infty}{\longrightarrow} \quad \frac{4 \exp(2)}{\sqrt{2\pi}} < 12 \; .$$

In particular, it follows by (2) that for $m \ge 8$ we have an asymptotic estimate of $g_m(n) = O(\sqrt{m})$. More precisely, it is straightforward to check that for $k \in \{5, 6, 7\}$ and $m \ge 8$ we have $g_m(2m+k) < 2.5\sqrt{m}$. It follows by (2) that for $m \ge 8$ we have $g_m(n) < 2.5\sqrt{m}$. \Box

5.4 Proof of the refined bounds

Proof of Theorem 1.9. We will estimate the intrinsic volumes of C via $V_j(C) \leq e(C) f_j(n)$, where $f_j(n) = V_j(\mathcal{L}^n)$ and e(C) denotes the excess over the Lorentz cone introduced in (1.18). Note that for j = m + i - 2k with $1 \leq j \leq n - 1$, we get from (1.17) using (1.9)

$$f_{n-(m+i-2k)}(n) = \frac{\binom{(n-2)/2}{(n-m-i+2k-1)/2}}{2^{n/2}} = \frac{\Gamma(\frac{n}{2})}{\Gamma(\frac{n-m-i+2k+1}{2}) \cdot \Gamma(\frac{m+i-2k+1}{2}) \cdot 2^{n/2}} .$$
 (5.11)

We thus obtain from Lemma 5.2, using Lemma 5.3 for the last equality:

$$\operatorname{rvol} \mathcal{T}(\Sigma_{m}, \alpha) \leq 8 \sum_{i,k=0}^{n-2} V_{n-m-i+2k}(C) \cdot \frac{\Gamma(\frac{m+i-2k+1}{2})}{\Gamma(\frac{m}{2})} \cdot \frac{\Gamma(\frac{n-m-i+2k+1}{2})}{\Gamma(\frac{n-m}{2})} \\ \cdot \binom{m-1}{k} \binom{n-m-1}{i-k} \cdot I_{n,n-2-i}(\alpha) \\ \overset{(5.11)}{\leq} 8 e(C) \cdot \frac{\Gamma(\frac{n}{2})}{\Gamma(\frac{m}{2}) \cdot \Gamma(\frac{n-m}{2}) \cdot 2^{n/2}} \cdot \sum_{i=0}^{n-2} I_{n,n-2-i}(\alpha) \cdot \sum_{k=0}^{n-2} \binom{m-1}{k} \binom{n-m-1}{i-k} \\ = 8 e(C) \cdot \frac{\Gamma(\frac{n}{2})}{\Gamma(\frac{m}{2}) \cdot \Gamma(\frac{n-m}{2}) \cdot 2^{n/2}} \cdot \sum_{i=0}^{n-2} I_{n,n-2-i}(\alpha) \cdot \binom{n-2}{i} \\ \overset{(5.9)}{\leq} 8 e(C) \cdot \frac{\Gamma(\frac{n}{2}) \cdot \exp(\frac{n}{m})}{\Gamma(\frac{m}{2}) \cdot \Gamma(\frac{n-m}{2}) \cdot 2^{n/2}} \cdot \frac{1}{t}, \quad \text{if } t > m \text{ and } n \geq 3.$$

Using the notation from Lemma 5.4, this implies the desired tail estimate

rvol
$$\mathcal{T}(\Sigma_m, \alpha) < 8 \, e(C) \, g_m(n) \, \frac{1}{t} \stackrel{(5.10)}{<} 20 \, e(C) \, \sqrt{m} \, \frac{1}{t}, \quad \text{for } t > m \ge 8 \, .$$

Analogous to the proof of Theorem 1.2, we estimate the expectation of the logarithm of the Grassmann condition. Defining $\tilde{e}(C) := \max\{e(C), 1\}$, so that in particular $\ln \tilde{e}(C) \ge 0$, we get

$$\begin{split} \mathbb{E}\left[\ln\mathscr{C}_{\mathsf{G}}(A)\right] &= \int_{0}^{\infty} \operatorname{Prob}[\ln\mathscr{C}_{\mathsf{G}}(A) > s] \, ds \\ &< \ln(m) + \ln(\tilde{e}(C)) + r + \int_{\ln(m) + \ln(\tilde{e}(C)) + r}^{\infty} 20 \cdot e(C) \cdot \sqrt{m} \cdot \exp(-s) \, ds \\ &= \ln(m) + \ln(\tilde{e}(C)) + r + \frac{20 \, e(C)}{\sqrt{m} \cdot \tilde{e}(C) \cdot \exp(r)} \\ &< \ln(m) + \ln(\tilde{e}(C)) + 3 \,, \quad \text{if } m \ge 8 \,, \end{split}$$

where the last inequality follows from choosing $r := \ln \left(\frac{20}{\sqrt{8}}\right)$. This completes the proof of Theorem 1.9.

6 Geometry of Grassmann manifolds

It remains to prove Proposition 4.2, which describes Σ_m as a smooth hypersurface in $\operatorname{Gr}_{n,m}$, as well as Theorem 4.5 on the Jacobian of the parameterization Ψ of the tube around Σ_m .

We provide these proofs in Section 7. As they require a good understanding of the metric properties of orthogonal groups and Grassmann manifolds, we collect here the necessary notions needed for these proofs. For a general background on Riemannian geometry we refer to [16], [6], or [11, Ch. 1]; as necessary we will give more specific references.

6.1 Orthogonal groups

The orthogonal group O(n) is the compact Lie group consisting of the $U \in \mathbb{R}^{n \times n}$ such that $U^T U = I_n$. Its Lie algebra is given by

$$T_{I_n}O(n) = \operatorname{Skew}_n := \{ U \in \mathbb{R}^{n \times n} \mid U^T = -U \}.$$

The tangent space of an element $Q \in O(n)$ is thus given by $T_QO(n) = Q \cdot \text{Skew}_n$.

As for the Riemannian metric on O(n), it is convenient to scale the (Euclidean) metric induced from $\mathbb{R}^{n \times n}$ by a factor of $\frac{1}{2}$. The Riemannian metric $\langle ., . \rangle_Q$ on $T_QO(n) = Q \cdot \text{Skew}_n$ is thus given by

$$\langle QU_1, QU_2 \rangle_Q = \frac{1}{2} \operatorname{tr}(U_1^T U_2).$$
 (6.1)

for $U_1, U_2 \in \text{Skew}_n$. Observe that we have a canonical basis for Skew_n given by $\{E_{ij} - E_{ji} \mid 1 \leq j < i \leq n\}$, where E_{ij} denotes the (i, j)th elementary matrix, i.e., the matrix whose entries are zero everywhere except for the (i, j)th entry, which is 1. This basis is orthogonal and by the choice of the scaling factor it is also orthonormal.

For the orthogonal group O(n), the exponential map $\exp_Q: T_QO(n) \to O(n)$ at $Q \in O(n)$ is given by the usual matrix exponential, i.e., for $U \in \operatorname{Skew}_n$ we have $\exp_Q(QU) = Q \cdot e^U = Q \cdot \sum_{k=0}^{\infty} \frac{U^k}{k!}$. For example, for

$$N := \begin{pmatrix} 0 & 0 & 1 \\ \hline 0 & 0 & 0 \\ \hline -1 & 0 & 0 \end{pmatrix}$$
(6.2)

the exponential map at Q in direction QN is given by the rotation

$$\exp_{Q}(\rho \cdot QN) = Q \cdot Q_{\rho} , \quad Q_{\rho} := \begin{pmatrix} \cos \rho & 0 & \sin \rho \\ \hline 0 & I_{n-2} & 0 \\ \hline -\sin \rho & 0 & \cos \rho \end{pmatrix}.$$
(6.3)

Note that $\frac{d}{d\rho}Q_{\rho} = Q_{\rho} \cdot N.$

6.2 Grassmann manifolds

We defined the *Grassmann manifold* $\operatorname{Gr}_{n,m}$, $1 \leq m \leq n$ as the set of all *m*-dimensional subspaces of \mathbb{R}^n . For our explicit explicit calculations, it is essential to view the Grassmann manifold as a quotient of the orthogonal group. Namely, we can describe $\operatorname{Gr}_{n,m}$ as the quotient $O(n)/H := \{QH \mid Q \in O(n)\}$ of O(n) by the subgroup

$$H := \left\{ \begin{pmatrix} Q' & 0\\ 0 & Q'' \end{pmatrix} \middle| Q' \in O(m), \ Q'' \in O(n-m) \right\} \simeq O(m) \times O(n-m)$$

in the following way:

In other words, the identification of $\operatorname{Gr}_{n,m}$ with the quotient O(n)/H amounts to identifying an *m*-dimensional linear subspace W of \mathbb{R}^n with the set of all orthogonal matrices, whose first *m* columns span *W*. Note that this identification endows $\operatorname{Gr}_{n,m}$ with the quotient topology on O(n)/H.

In the following paragraphs, we will give a concrete description of the tangent space $T_W \operatorname{Gr}_{n,m}$ for $W \in \operatorname{Gr}_{n,m}$, and we will describe the Riemannian metric and the exponential map on $\operatorname{Gr}_{n,m}$. Note that the natural action of O(n) on \mathbb{R}^n induces a corresponding action on $\operatorname{Gr}_{n,m}$. It can be shown that, up to scaling, there exists a unique Riemannian metric on $\operatorname{Gr}_{n,m}$, which is O(n)-invariant. This is the Riemannian metric, that we will next describe explicitly.

Let $W \in \operatorname{Gr}_{n,m}$ and let $Q \in \Pi^{-1}(W)$, i.e., the first *m* columns of *Q* span *W*. The coset QH is a submanifold of O(n), and its tangent space at *Q* is given by

$$T_Q Q H = Q \cdot T_{I_n} H = Q \cdot \left\{ \begin{pmatrix} U' & 0 \\ 0 & U'' \end{pmatrix} \middle| U' \in \operatorname{Skew}_m, \ U'' \in \operatorname{Skew}_{n-m} \right\}$$

Note that the orthogonal complement $(T_Q Q H)^{\perp}$ of $T_Q Q H$ in $T_Q O(n)$ is given by

$$(T_Q Q H)^{\perp} = Q \cdot \overline{\operatorname{Skew}_n} , \text{ where } \overline{\operatorname{Skew}_n} := \left\{ \begin{pmatrix} 0 & -X^T \\ X & 0 \end{pmatrix} \middle| X \in \mathbb{R}^{(n-m) \times m} \right\}.$$
 (6.5)

It can be shown (cf. [27, Lemma II.4.1]) that there exists an open ball B around the origin in $T_QO(n)$ such that the restriction of $\Pi \circ \exp_Q$ to $B \cap (T_QQH)^{\perp}$ is a diffeomorphism onto an open neighborhood of $W = \Pi(Q)$ in $\operatorname{Gr}_{n,m}$. The derivative of $\Pi \circ \exp_Q$ therefore yields a linear isomorphism

$$(T_Q Q H)^{\perp} \xrightarrow{\sim} T_W \operatorname{Gr}_{n,m}, \qquad Q U \mapsto \xi := D(\Pi \circ \exp_Q)(Q U),$$

where $U \in \overline{\text{Skew}_n}$.

The pair (Q, U) with $U \in \overline{\text{Skew}_n}$ thus defines the tangent vector $\xi := D(\Pi \circ \exp_Q(QU))$ in $T_W \operatorname{Gr}_{n,m}$. However, we may also represent the subspace W by a group element Qh, for any $h \in H$. A small computation shows that the pair $(Qh, h^{-1}Uh)$ represents the same tangent vector ξ . More generally, if we define an equivalence relation \sim on $O(n) \times H$ via

$$(Q,U) \sim (Q',U') \iff \exists h \in H \colon (Q',U') = (Qh,h^{-1}Uh),$$

then it follows that the tangent vector $\xi \in T_W \operatorname{Gr}_{n,m}$ can be identified with the equivalence class $[Q, U] := \{(Qh, h^{-1}Uh) \mid h \in H\} \in (O(n) \times H) / \sim$. We have thus obtained the following model for $T_W \operatorname{Gr}_{n,m}$:

$$T_W \operatorname{Gr}_{n,m} \simeq \left\{ [Q, U] \mid Q \in \Pi^{-1}(W), \ U \in \overline{\operatorname{Skew}_n} \right\}.$$
(6.6)

Note that in this model, the derivative $D_Q \Pi$ of Π at Q is given by

$$D_Q \Pi(QU) = [Q, \pi(U)], \tag{6.7}$$

where $\pi: \text{Skew} \to \overline{\text{Skew}_n}$ denotes the orthogonal projection.

We can now define the Riemannian metric on $\operatorname{Gr}_{n,m}$ by setting

$$\langle [Q, U_1], [Q, U_2] \rangle := \langle U_1, U_2 \rangle_{I_n} \stackrel{(6.1)}{=} \frac{1}{2} \cdot \operatorname{tr}(U_1^T \cdot U_2),$$
 (6.8)

for $U_1, U_2 \in \overline{\text{Skew}_n}$ (this is clearly a well-defined O(n)-invariant Riemannian metric). This way, $\Pi: O(n) \to \operatorname{Gr}_{n,m}$ becomes a *Riemannian submersion*, i.e., for every $Q \in O(n)$ the restriction of $D \exp_Q$ to the orthogonal complement of its kernel is an isometry. Using the above description of $D\Pi$ and elementary properties of geodesics (cf. for example [16, Sec. 3.2]), one can show that the exponential map on $\operatorname{Gr}_{n,m}$ is given by

$$\exp_W(\xi) = \Pi(\exp_Q(QU)) = \Pi(Q \cdot e^U), \quad \xi = [Q, U] \in T_W \operatorname{Gr}_{n,m}.$$
(6.9)

6.3 Frame bundle and Grassmann bundle

In the remainder of this section, we discuss some properties of frame bundles and Grassmann bundles.

Let V be a k-dimensional Euclidean vector space. A frame of V is an orthonormal basis of V. We denote by

$$F(V) = \{(q_1, \ldots, q_k) \in V^k \mid \forall i, j : \langle q_i, q_j \rangle = \delta_{ij}\}$$

the set of frames of V. We can identify $F(\mathbb{R}^k)$ with the orthogonal group O(k) by identifying the frame $(q_1, \ldots, q_k) \in F(\mathbb{R}^k)$ with the orthogonal matrix having the columns q_1, \ldots, q_k . This way, F(V) gets the structure of a smooth Riemannian manifold.

Recall the ℓ th Grassmann manifold $\operatorname{Gr}(V, \ell)$ consisting of the ℓ -dimensional linear subspace of V $(1 \leq \ell \leq k)$. It inherits from $\operatorname{Gr}(\mathbb{R}^k, \ell)$ the structure of a smooth Riemannian manifold, since $\operatorname{Gr}(\mathbb{R}^k, \ell) = \operatorname{Gr}_{k,\ell}$. Moreover, the smooth surjective map $F(V) \to \operatorname{Gr}(V, \ell), (q_1, \ldots, q_k) \mapsto$ $\operatorname{lin}\{q_1, \ldots, q_\ell\}$ provides a close connection between these two manifolds.

Let M be a k-dimensional smooth Riemannian manifold and $1 \le \ell \le k$. The orthonormal frame bundle and the ℓ th Grassmann bundle over M, respectively, are defined as

$$F(M) = \bigcup_{p \in M} \{p\} \times F(T_pM), \qquad \operatorname{Gr}(M, \ell) = \bigcup_{p \in M} \{p\} \times \operatorname{Gr}(T_pM, \ell).$$

Using charts of M to connect the manifolds $F(T_pM)$, one can show that F(M) has the structure of a smooth manifold. Moreover, $F(M) \to M$ is a fiber bundle (cf. for example [31, §I.5]). The same holds true for the Grassmann bundle $\operatorname{Gr}(M, \ell) \to M$. Furthermore, the maps of the fibers $F(T_pM) \to \operatorname{Gr}(T_pM, \ell)$ may be combined to a smooth surjective bundle map

$$\Pi_b \colon F(M) \to \operatorname{Gr}(M, \ell), \qquad \Pi_b(p, \bar{Q}) = (p, \lim\{q_1, \dots, q_\ell\}), \tag{6.10}$$

where $\bar{Q} = (q_1, \ldots, q_k)$.

For $(p, \overline{Q}) \in F(M)$ one has a natural decomposition of the tangent space of F(M) at (p, \overline{Q}) into a vertical space and a horizontal space,

$$T_{(p,\bar{Q})}F(M) = T^{v}_{(p,\bar{Q})}F(M) \oplus T^{h}_{(p,\bar{Q})}F(M).$$
(6.11)

The vertical space is defined by

$$T^{v}_{(p,\bar{Q})}F(M) := T_{(p,\bar{Q})}(\{p\} \times F(T_{p}M)).$$
(6.12)

For defining the horizontal space we consider the following construction. Let $\zeta \in T_p M$ and let $c \colon \mathbb{R} \to M$ be such that c(0) = p and $\dot{c}(0) = \zeta$. Furthermore, let \bar{Q}_t denote the *parallel* transport (cf. for example [6, Thm. VII.3.12]) of the frame \bar{Q} along c at time t. Then the map $c_F \colon \mathbb{R} \to F(M), t \mapsto (c(t), \bar{Q}_t)$, defines a smooth curve in F(M) and thus a tangent vector $\dot{c}_F(0) \in T_{(p,\bar{Q})}F(M)$. It can be shown (cf. for example [31, §II.3]) that this tangent vector does not depend on the specific choice of the curve c. Moreover, one can show that the induced map $T_pM \to T_{(p,\bar{Q})}F(M)$ sending each tangent vector ζ to the above defined tangent vector of F(M) at (p,\bar{Q}) , is an injective linear map. The image of this injective linear map is defined as the horizontal space. One can then show the decomposition (6.11) of the tangent space of F(M) at (p,\bar{Q}) into the direct sum of the vertical and the horizontal space.

Analogous statements about the decomposition of the tangent spaces also hold for the Grassmann bundle $\operatorname{Gr}(M, \ell)$. Moreover, the derivative of the bundle map $\Pi_b \colon F(M) \to \operatorname{Gr}(M, \ell)$ certainly maps the vertical spaces of F(M) to the vertical spaces of $\operatorname{Gr}(V, \ell)$. As for the horizontal spaces, note that the parallel transport of a linear subspace may be achieved by parallel transporting a basis for this subspace. This implies that also the horizontal spaces of F(M) are mapped to the horizontal spaces of $\operatorname{Gr}(V, \ell)$ via the derivative of the bundle map Π_b .

7 Computation of Normal Jacobians

For the sake of clarity, we first study a more general situation. Here is a brief outline: Let $M \subseteq S^{n-1}$ be a compact hypersurface with a distinguished unit normal vector field $\nu: M \to S^{n-1}$. We embed F(M) into O(n) via the map $\hat{\Phi}: F(M) \to F(\mathbb{R}^n) = O(n)$ that sends a frame (q_1, \ldots, q_{n-2}) of T_pM to the frame $(p, q_1, \ldots, q_{n-2}, \nu(p))$ of \mathbb{R}^n . In Section 7.1 we prove that $\hat{\Phi}$ is an injective immersion of F(M) into O(n). Hence the image $\hat{\Sigma}(M)$ of F(M) under $\hat{\Phi}$ is a smooth submanifold of O(n).

We are interested in the set $\Sigma(M)$, which is defined as the image of the map

$$\Phi_m \colon \operatorname{Gr}(M, m-1) \to \operatorname{Gr}_{n,m}, \quad (p, Y) \mapsto \mathbb{R}p + Y.$$

The point is that $\Sigma(M) = \Sigma_m(C)$ in the special case, where $M = \partial K$ is the boundary of a smooth $K \in \mathcal{K}^{sm}(S^{n-1})$ and $C = \operatorname{cone}(K)$. The idea is that $\Sigma(M)$ can also be obtained as the image of $\hat{\Sigma}(M)$ under the canonical projection $\Pi: O(n) \to \operatorname{Gr}_{n,m}$ defined in (6.4), see the commutative diagram (7.1).

In Section 7.2 we prove, via the detour over $\hat{\Phi}$, that $\Sigma(M)$ is a smooth hypersurface of $\operatorname{Gr}_{n,m}$ in the case where $M = \partial K$ with $K \in \mathcal{K}^{\operatorname{sm}}(S^{n-1})$. This provides the proof of Proposition 4.2. We then go on working in this framework to complete the proof of Theorem 4.5.

7.1 Analyzing the situation lifted to the frame bundle

We fix a compact hypersurface $M \subseteq S^{n-1}$ with a unit normal vector field $\nu: M \to S^{n-1}$.

In the following, we identify the tangent space T_pM for $p \in M$ with the linear subspace $T_pM = p^{\perp} \cap \nu(p)^{\perp}$ of \mathbb{R}^n , which has codimension 2. If $(p, \bar{Q}) \in F(M)$, then $\bar{Q} = (q_1, \ldots, q_{n-2})$ is an orthonormal basis of T_pM , and in the following we shall interpret \bar{Q} as the matrix in $\mathbb{R}^{n \times (n-2)}$ with the columns $q_i \in \mathbb{R}^n$. Note that $(p, \bar{Q}, \nu(p)) = (p, q_1, \ldots, q_{n-2}, \nu(p)) \in O(n)$. This defines the map

$$\hat{\Phi} \colon F(M) \to O(n), \quad (p, \bar{Q}) \mapsto Q = (p, \bar{Q}, \nu(p)).$$

We define the lifted Sigma set $\hat{\Sigma}(M)$ as the image of the map $\hat{\Phi}$:

$$\hat{\Sigma} := \hat{\Sigma}(M) := \hat{\Phi}(F(M)) = \{ Q \in O(n) \mid \exists p \in M : Q \cdot e_1 = p, \ Q \cdot e_n = \nu(p) \},\$$

where $e_i \in \mathbb{R}^n$ denote the canonical basis vectors. Analogous to the definition of $\hat{\Phi}$, we define for $1 \leq m \leq n-1$ the map

$$\Phi_m \colon \operatorname{Gr}(M, m-1) \to \operatorname{Gr}_{n,m}, \quad (p, Y) \mapsto \mathbb{R}p + Y,$$

where $Y \in Gr(T_pM, m-1)$ is interpreted as an (m-1)-dimensional subspace of \mathbb{R}^n . Furthermore, we define

$$\Sigma_m := \Sigma_m(M) := \Phi_m(\operatorname{Gr}(M, m-1)) = \{ W \in \operatorname{Gr}_{n,m} \mid \exists p \in M : p \in W, W \subseteq \nu(p)^{\perp} \}.$$

Note that we have $\Pi(\hat{\Sigma}(M)) = \Sigma_m$, where $\Pi: O(n) \to \operatorname{Gr}_{n,m}$ denotes the canonical projection (cf. (6.4)), but we have a strict inclusion $\hat{\Sigma}(M) \subsetneq \Pi^{-1}(\Sigma_m(M))$.

The following commutative diagram provides an overview over the relations, which are central for the understanding of Σ_m :

$$F := F(M) \xrightarrow{\hat{\Phi}} \hat{\Sigma} \longrightarrow O(n)$$

$$\downarrow \Pi_{b} \qquad \qquad \downarrow \Pi_{\Sigma} \qquad \qquad \downarrow \Pi \qquad . \tag{7.1}$$

$$G := \operatorname{Gr}(M, m-1) \xrightarrow{\Phi_{m}} \Sigma_{m} \longrightarrow \operatorname{Gr}_{n,m}$$

Here Π_b is defined as in (6.10), and Π_{Σ} is defined as the restriction of Π (cf. (6.4)) to $\hat{\Sigma}$. Note that if $(p, \bar{Q}) \in F(M)$ with $\bar{Q} = (q_1, \ldots, q_{n-2})$, then $\hat{\Phi}(p, \bar{Q}) = Q = (p, q_1, \ldots, q_{n-2}, \nu(p)) \in \hat{\Sigma}$ and $\Pi_b(p, \bar{Q}) = (p, Y)$, where Y is the span of q_1, \ldots, q_{m-1} .

The tangent spaces of the fiber bundles F(M) and Gr(M, m-1) have natural decompositions into vertical and horizontal components (cf. Section 6.3):

$$T_{(p,\bar{Q})}F = T^{v}_{(p,\bar{Q})}F \oplus T^{h}_{(p,\bar{Q})}F, \qquad T_{(p,Y)}G = T^{v}_{(p,Y)}G \oplus T^{h}_{(p,Y)}G.$$
(7.2)

We denote the images of the vertical and the horizontal space of the frame bundle at (p, Q)under the derivative $D\hat{\Phi}$ by

$$T_Q^v \hat{\Sigma} := D \hat{\Phi} \left(T_{(p,\bar{Q})}^v F \right), \qquad T_Q^h \hat{\Sigma} := D \hat{\Phi} \left(T_{(p,\bar{Q})}^h F \right).$$
(7.3)

We will give next concrete descriptions of these spaces.

Before we state the next result about the derivative of $\hat{\Phi}$, we define the following linear maps for $Q = (p, \bar{Q}, \nu(p)) \in \hat{\Sigma}$

$$\hat{E}^{v}: \text{Skew}_{n-2} \to \text{Skew}_{n}, \qquad \hat{E}^{h}: \mathbb{R}^{n-2} \to \text{Skew}_{n}, \qquad (7.4)$$

$$\hat{E}^{v}(\bar{U}) := \begin{pmatrix} 0 & 0 & 0 \\ \hline 0 & \bar{U} & 0 \\ \hline 0 & 0 & 0 \end{pmatrix}, \quad \hat{E}^{h}(a) := \begin{pmatrix} 0 & -a^{T} & 0 \\ \hline a & 0 & -b \\ \hline 0 & b^{T} & 0 \end{pmatrix}, \text{ where } b := \bar{Q}^{T} \cdot \mathcal{W}_{p}(\bar{Q}a).$$

Here $\mathcal{W}_p: T_pM \to T_pM$ is the Weingarten map of M at p, cf. (2.3), and we recall that the image of $\bar{Q} \in \mathbb{R}^{n \times (n-2)}$ equals T_pM , since $(p, \bar{Q}, \nu(p)) \in \hat{\Sigma}$. Note that \hat{E}^v is an isometric embedding independent of the manifold M and the element $Q \in \hat{\Sigma}$, while \hat{E}^h is a linear injection, which depends both on M and on Q. For the sake of simplicity, we do not reflect this dependence in the notation. Note further that the images of \hat{E}^v and \hat{E}^h are orthogonal subspaces of Skew_n.

Lemma 7.1. Let $(p, \overline{Q}) \in F(M)$ and $Q := \hat{\Phi}(p, \overline{Q}) = (p, \overline{Q}, \nu(p)) \in \hat{\Sigma}$. Then we have

$$T_Q^v \hat{\Sigma} = Q \cdot \operatorname{im}(\hat{E}^v), \qquad T_Q^h \hat{\Sigma} = Q \cdot \operatorname{im}(\hat{E}^h).$$
(7.5)

Proof. Since $p = Qe_1$ and $\nu(p) = Qe_n$, the image of the fiber $\{p\} \times F(T_pM)$ under the map $\hat{\Phi}$ is given by

$$\hat{\Phi}(\{p\} \times F(T_p M)) = \left\{ Q \cdot \left(\begin{array}{c|c} 1 & 0 & 0 \\ \hline 0 & \tilde{Q} & 0 \\ \hline 0 & 0 & 1 \end{array} \right) \middle| \tilde{Q} \in O(n-2) \right\}.$$

This implies that the image of the vertical space $T^v_{(p,\bar{Q})}F(M)$ under the derivative $D\hat{\Phi}$ is given by $T^v_Q\hat{\Sigma} = Q \cdot \operatorname{im}(\hat{E}^v)$, cf. (6.12).

As for the horizontal space, let $\xi \in T^h_{(p,\bar{Q})}F(M)$ be represented by the curve $c_F \colon \mathbb{R} \to F(M)$, i.e., $c_F(0) = (p,\bar{Q})$ and $\dot{c}_F(0) = \xi$, which is given in the following way: $c_F(t) = (c(t), \bar{Q}_t)$, where \bar{Q}_t is the parallel transport of \bar{Q} along the curve c (cf. Section 6.3). Let us denote by $\zeta := \dot{c}(0) \in T_p M$ the tangent vector at p defined by c. The image of the curve c_F under $\hat{\Phi}$ is thus given by $\hat{\Phi}(c_F(t)) = (c(t), \bar{Q}_t, \nu(c(t))) =: Q(t)$, and the image of ξ is given by $D\hat{\Phi}(\xi) = \dot{Q}(0)$. It is sufficient to show that $\dot{Q}(0)$ is given by

$$\dot{Q}(0) = Q \cdot \left(\begin{array}{c|c} 0 & -a^T & 0 \\ \hline a & 0 & -b \\ \hline 0 & b^T & 0 \end{array} \right), \text{ where } a = \bar{Q}^T \zeta, \quad b = \bar{Q}^T \mathcal{W}_p(\zeta).$$
(7.6)

To prove (7.6), note first that as $Q(t) \in O(n)$ and Q(0) = Q, we have $\dot{Q}(0) = Q \cdot U$ with $U \in \text{Skew}_n$. Recall that the columns of \bar{Q} form an orthonormal basis of $T_p M = p^{\perp} \cap \nu(p)^{\perp}$, hence $Q^T T_p M = e_1^{\perp} \cap e_n^{\perp}$. Therefore, $\dot{c}(0) = \zeta = \bar{Q}a$ for some $a \in \mathbb{R}^{n-2}$, which implies $a = \bar{Q}^T \zeta$. The first column of U is thus given by $Ue_1 = Q^T \dot{Q}(0)e_1 = Q^T \zeta = \begin{pmatrix} 0 \\ a \\ 0 \end{pmatrix}$. By skew-symmetry of U, this also gives us the first row of U. The zero matrix in the middle

follows from the fact that the frame \bar{Q} is parallel transported along c (cf. [6, §VII.3]). Finally, the last column of $\dot{Q}(0)$ is given by $D_p\nu(\zeta)$. This implies that the last column of U is given by

$$Q^T D_p \nu(\zeta) \stackrel{(2.3)}{=} - Q^T \mathcal{W}_p(\zeta).$$

As $\mathcal{W}_p(\zeta) \in T_p M = p^{\perp} \cap \nu(p)^{\perp}$, the last column of U has the form $\begin{pmatrix} 0 \\ -b \\ 0 \end{pmatrix}$. Therefore $\mathcal{W}_p(\zeta) = Q\begin{pmatrix} 0 \\ b \\ 0 \end{pmatrix} = \bar{Q}b$, which implies $b = \bar{Q}^T \mathcal{W}_p(\zeta)$. The last row follows again by skew-symmetry of U.

Corollary 7.2. The map $\hat{\Phi}$ is an injective immersion of F(M) into O(n). In particular, $\hat{\Sigma}$ is a smooth submanifold of O(n) of codimension n-1, and the tangent space $T_Q\hat{\Sigma}$ at $Q \in O(n)$ has the orthogonal decomposition $T_Q\hat{\Sigma} = T_O^v\hat{\Sigma} \oplus T_O^h\hat{\Sigma}$.

Proof. The fact that $\hat{\Phi}$ is a smooth injective map is obvious. Furthermore, by Lemma 7.1, it follows that the derivative $D\hat{\Phi}$ at (p, \bar{Q}) has full rank. The map $\hat{\Phi}$ is thus an injective immersion, and as the domain F(M) is compact, it is also an embedding. As for the dimension, we compute

$$\dim \hat{\Sigma} = \dim F(M) = \dim M + \dim O(n-2) = n - 2 + \frac{(n-2)(n-3)}{2} = \frac{(n-2)(n-1)}{2}$$
$$= \dim O(n) - (n-1).$$

The decomposition of the tangent space into the direct sum $T_Q \hat{\Sigma} = T_Q^v \hat{\Sigma} \oplus T_Q^h \hat{\Sigma}$ follows from the decomposition of the tangent space of the fiber bundle (7.2). The fact that $T_Q^v \hat{\Sigma}$ and $T_Q^h \hat{\Sigma}$ are orthogonal follows from the description given in Lemma 7.1.

Now that we have a clear description of the lifted Sigma set $\hat{\Sigma}$, we will transfer this description to Σ_m via the projection map $\Pi_{\Sigma} : \hat{\Sigma} \to \Sigma_m$ defined in (7.1). Analogously to the lifted case, we denote the images under the derivative $D\Phi_m$ of the vertical and the horizontal space, cf. (7.2), of the Grassmann bundle at (p, Y) by

$$T_W^{v}\Sigma_m := D\Phi_m\left(T_{(p,Y)}^{v}G\right), \qquad T_W^h\Sigma_m := D\Phi_m\left(T_{(p,Y)}^hG\right).$$
(7.7)

Recall that the subspace $\overline{\text{Skew}_n}$ defined in (6.5) serves as a model for the tangent spaces of $\text{Gr}_{n,m}$. We consider the linear map

$$\alpha \colon \mathbb{R}^{n-2} \to \overline{\operatorname{Skew}_n}, \quad x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{pmatrix} 0 & \frac{-x_2^T & 0}{0 & -x_1} \\ \hline \frac{x_2 & 0}{0 & x_1^T} & 0 \end{pmatrix},$$
(7.8)

where $x_1 \in \mathbb{R}^{m-1}$ and $x_2 \in \mathbb{R}^{n-m-1}$, and we denote its image by

$$S_n := \operatorname{im}(\alpha) \subseteq \operatorname{Skew}_n.$$

Note that dim $S_n = n - 2$. We now define the following linear maps for $Q = (p, \overline{Q}, \nu(p)) \in \hat{\Sigma}$:

$$E^{v} \colon \mathbb{R}^{(n-m-1)\times(m-1)} \to \overline{\operatorname{Skew}_{n}}, \qquad E^{h} \colon \mathbb{R}^{n-2} \to S_{n}, \qquad (7.9)$$

$$E^{v}(X) := \begin{pmatrix} 0 & 0 & 0 \\ \hline -X^{T} & 0 \\ \hline 0 & X & 0 \\ \hline 0 & 0 & 0 \end{pmatrix}, \qquad E^{h}(a) := \begin{pmatrix} 0 & -a_{2}^{*} & 0 \\ \hline 0 & 0 & -b_{1} \\ \hline a_{2} & 0 & \\ \hline 0 & b_{1}^{T} & 0 \\ \hline 0 & b_{1}^{T} & 0 \end{pmatrix},$$

where again $b := \bar{Q}^T \cdot \mathcal{W}_p(\bar{Q}a)$, and $a = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$, $b = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$ with $a_1, b_1 \in \mathbb{R}^{m-1}$, $a_2, b_2 \in \mathbb{R}^{n-m-1}$. The map E^v is an isometry if the scalar product on $\overline{\text{Skew}_n}$ induced from $\mathbb{R}^{n \times n}$ is scaled by $\frac{1}{2}$. Note that E^v is independent of M and Q. On the other hand, as in the lifted case, the map E^h depends on both M and Q. Unlike in the lifted case, the map E^h need not be injective. We will see below in Proposition 7.3 that it is injective iff the restriction $\mathcal{W}_{p,Y}$ of the Weingarten map \mathcal{W}_p to the subspace $Y = \lim\{q_1, \ldots, q_{m-1}\} \subseteq T_p M$, where $Q = (p, q_1, \ldots, q_{n-2}, \nu(p))$, has full rank. If this is the case, then im $E^h = S_n$.

Note that we have an orthogonal decomposition of $\overline{\text{Skew}_n}$ into

$$\overline{\operatorname{Skew}_n} = \operatorname{im} E^v \oplus S_n \oplus \mathbb{R}N, \qquad (7.10)$$

where $N \in \overline{\operatorname{Skew}_n}$ was defined in (6.2). If we define $\iota \colon \mathbb{R}^{(n-m-1)\times(m-1)} \to \operatorname{Skew}_{n-2}$, via $X \mapsto \begin{pmatrix} 0 & -X^T \\ X & 0 \end{pmatrix}$, and if we denote by $\pi \colon \operatorname{Skew}_n \to \overline{\operatorname{Skew}_n}$ the orthogonal projection, then we have the crucial relation

$$E^{v}(X) = \hat{E}^{v}(\iota(X)), \qquad E^{h}(a) = \pi(\hat{E}^{h}(a)).$$
 (7.11)

Proposition 7.3. 1. Let $(p, Y) \in \operatorname{Gr}(M, m-1)$ and $W := \Phi_m(p, Y)$, and let $Q \in \Sigma$ be such that $\Pi_{\Sigma}(Q) = W$. Then we have, using the model of tangent spaces of $\operatorname{Gr}_{n,m}$ described in (6.6):

$$T_W^{v} \Sigma_m = \{ [Q, U] \mid U \in im(E^{v}) \}, \qquad T_W^{h} \Sigma_m = \{ [Q, U] \mid U \in im(E^{h}) \}.$$
(7.12)

2. The rank of the map E^h is given by

$$\operatorname{rk}(E^{h}) = n - m - 1 + \operatorname{rk} \mathcal{W}_{p,Y},$$

where $\mathcal{W}_{p,Y}: Y \to Y$ is the restriction of the Weingarten map \mathcal{W}_p to the subspace Y of T_pM . Moreover, if $\mathcal{W}_{p,Y}$ has full rank and if we consider S_n to be endowed with the scalar product $\langle U_1, U_2 \rangle := \frac{1}{2} \cdot \operatorname{tr}(U_1^T \cdot U_2)$, then

$$|\det(E^h)| = |\det_Y(\mathcal{W}_p)|, \tag{7.13}$$

where $det_Y(\mathcal{W}_p)$ denotes the determinant of $\mathcal{W}_{p,Y}$ (cf. Definition 4.3).

3. The rank of the derivative $D_{(p,Y)}\Phi_m$ is given by

$$\operatorname{rk} D_{(p,Y)}\Phi_m = m(n-m) - m + \operatorname{rk} \mathcal{W}_{p,Y},$$

Proof. (1) Since the derivative of the bundle projection $\Pi_b \colon F(M) \to \operatorname{Gr}(M, \ell)$ defined in (6.10) maps the vertical spaces of the frame bundle to the vertical spaces of the Grassmann bundle (cf. Section 6.3), we have

$$T_W^v \Sigma_m \stackrel{(7.7)}{=} D\Phi_m \left(T_{(p,Y)}^v G \right) \stackrel{(7.1)}{=} D\Pi_{\Sigma} (T_Q^v \hat{\Sigma}) \stackrel{(7.5)}{=} D\Pi_{\Sigma} (Q \cdot \operatorname{im}(\hat{E}^v)).$$

Using $D_Q \Pi_{\Sigma}(QU) = [Q, \overline{U}]$ (cf. (6.7)), we may continue as

$$T_W^v \Sigma_m = \{ [Q, U] \mid U \in \pi(\operatorname{im}(\hat{E}^v)) \} = \{ [Q, U] \mid U \in \operatorname{im}(E^v) \}.$$

Similar arguments show the description (7.12) of the horizontal space.

(2) By the above choice of scalar product in S_n , the map α defined in (7.8) is an isometry on its image. Hence, instead of considering E^h we may focus on the map

$$\alpha^{-1} \circ E^h \colon \mathbb{R}^{n-2} \to \mathbb{R}^{n-2}, \quad a = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \mapsto \begin{pmatrix} b_1 \\ a_2 \end{pmatrix},$$

where as usual $b = \bar{Q}^T \cdot \mathcal{W}_p(\bar{Q}a)$, and $a = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$, $b = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$ with $a_1, b_1 \in \mathbb{R}^{m-1}$, $a_2, b_2 \in \mathbb{R}^{n-m-1}$. Let $\Lambda \in \mathbb{R}^{(n-2)\times(n-2)}$ be the representation matrix of \mathcal{W}_p with respect to the orthonormal basis q_1, \ldots, q_{n-2} of $T_p M$, i.e., $\Lambda a = \bar{Q}^T \cdot \mathcal{W}_p(\bar{Q}a) = b$. Furthermore, let Λ be decomposed as $\Lambda = \begin{pmatrix} \Lambda_1 & \Lambda_2 \\ \Lambda_3 & \Lambda_4 \end{pmatrix}$, where $\Lambda_1 \in \mathbb{R}^{(m-1)\times(m-1)}$ and the other blocks accordingly.

Then the representation matrix of $\alpha^{-1} \circ E^h$ is given by $\begin{pmatrix} \Lambda_1 & \Lambda_2 \\ 0 & I_{n-m-1} \end{pmatrix}$. As Λ_1 is the representation matrix of $\mathcal{W}_{p,Y}$ with respect to the orthonormal basis q_1, \ldots, q_{m-1} of Y, we obtain

$$\operatorname{rk}(E^h) = \operatorname{rk}(\alpha^{-1} \circ E^h) = n - m - 1 + \operatorname{rk}(\Lambda_1) = n - m - 1 + \operatorname{rk}(\mathcal{W}_{p,Y}).$$

Furthermore, if $\mathcal{W}_{p,Y}$ has full rank $\operatorname{rk} \mathcal{W}_{p,Y} = m - 1$, then

$$|\det(E^h)| = |\det(\alpha^{-1} \circ E^h)| = |\det(\Lambda_1)| = |\det_Y(\mathcal{W}_p)|.$$

(3) From (1) and (2) we obtain

$$\dim T_W^v \Sigma_m = \operatorname{rk}(E^v) = (m-1)(n-m-1),$$
$$\dim T_W^h \Sigma_m = \operatorname{rk}(E^h) = n-m-1 + \operatorname{rk} \mathcal{W}_{p,Y}.$$

This implies that the rank of the derivative of Φ_m is given by

$$\operatorname{rk} D_{(p,Y)}\Phi_m = \dim T_W^v \Sigma_m + \dim T_W^h \Sigma_m = m(n-m-1) + \operatorname{rk} \mathcal{W}_{p,Y}.$$

7.2 Specializing to the boundary of a convex set

We assume now that $M = \partial K$ for some $K \in \mathcal{K}^{\mathrm{sm}}(S^{n-1})$.

The subsequent corollary implies Proposition 4.2, as well as the claim about the normal Jacobian of Π_M in Theorem 4.5.

Corollary 7.4. Let $M = \partial K$ with $K \in \mathcal{K}^{\mathrm{sm}}(S^{n-1})$.

- 1. Then Φ_m is an injective immersion of $\operatorname{Gr}(M, m-1)$ into $\operatorname{Gr}_{n,m}$, and Σ_m is a smooth hypersurface of $\operatorname{Gr}_{n,m}$. Furthermore, for $W \in \Sigma_m$, the tangent space of Σ_m at W has the orthogonal decomposition $T_W \Sigma_m = T_W^v \Sigma_m \oplus T_W^h \Sigma_m$.
- 2. Recall $N \in \overline{\text{Skew}_n}$ defined in (6.2). If $W = \prod_{\Sigma}(Q) \in \Sigma_m$ for $Q \in \hat{\Sigma}$, then $\nu_{\Sigma}(W) = [Q, N] \in T_W \operatorname{Gr}_{n,m}$ is a unit normal vector of Σ_m at W that points into $\mathcal{P}_m(C)$. Moreover, $-\nu_{\Sigma}(W)$ points into $\mathcal{D}_m(C)$.
- 3. Consider $\Pi_M \colon \Sigma_m \to M, W \mapsto p$, where $W \cap K = \{p\}$, cf. (4.7). Then the normal Jacobian of Π_M at $W \in \Sigma_m$ is given by $\operatorname{ndet}(D_W \Pi_M) = \operatorname{det}_Y(\mathcal{W}_p)^{-1}$, where $Y := W \cap p^{\perp} \in \operatorname{Gr}(T_pM, m-1)$.

Proof. (1) The injectivity of Φ_m follows from Proposition 4.1. Furthermore, the Weingarten map \mathcal{W}_p of M is positive definite for every $p \in M$. Therefore, the restriction $\mathcal{W}_{p,Y}$ of \mathcal{W}_p to any subspace $Y \in \operatorname{Gr}(T_pM, m-1)$ is positive definite and in particular has full rank. It follows from Proposition 7.3 that Φ_m is an injective immersion. By compactness of the domain $\operatorname{Gr}(M, m-1)$, it follows that Φ_m is an embedding. The image Σ_m is thus a smooth submanifold of dimension dim $\Sigma_m = \dim \operatorname{Gr}(M, m-1) = m(n-m)-1$. The claimed orthogonal decomposition of $T_W \Sigma_m$ is a consequence of (7.12) and (7.10).

(2) It is clear from the orthogonal decompositions $T_W \Sigma_m = T_W^v \Sigma_m \oplus T_W^h \Sigma_m$ and (7.10) that $\nu_{\Sigma}(W)$ lies in the orthogonal complement of $T_W \Sigma_m$ in $T_W \operatorname{Gr}_{n,m}$. Consider the geodesic

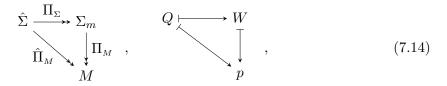
$$W_{\rho} := \exp_{W}(\rho \cdot \nu_{\Sigma}(W)) \stackrel{(6.9)}{=} \Pi(\exp_{Q}(QN)) \stackrel{(6.3)}{=} \Pi(Q \cdot Q_{\rho})$$

through W in direction $\nu_{\Sigma}(W)$.

The first column of $Q \cdot Q_{\rho}$ is given by $p_{\rho} := p \cos \rho - \nu(p) \sin \rho$. In particular, $p_{\rho} \in W_{\rho}$. By assumption, the normal vector $\nu(p)$ points inwards K. Therefore, for all $\rho < 0$ with $|\rho|$ small enough, we have $p_{\rho} \in K$, which implies $W_{\rho} \in \mathcal{D}_m(C)$. Hence $-\nu_{\Sigma}(W)$ points into $\mathcal{D}_m(C)$.

On the other hand, the orthogonal complement of $\nu(p)$ is a supporting hyperplane of $\operatorname{cone}(K)$. From this it follows that $W_{\rho} \cap K = \{0\}$ for all sufficiently small $\rho > 0$. Therefore, $W_{\rho} \in \operatorname{Gr}_{n,m} \setminus \mathcal{D}_m(C) \subseteq \mathcal{P}_m(C)$. Hence $\nu_{\Sigma}(W)$ points into $\mathcal{P}_m(C)$.

(3) We may lift the function $\Pi_M \colon \Sigma_m \to M$ to the function $\hat{\Pi}_M \colon \hat{\Sigma} \to M, Q \mapsto p$, where $Q = (p, q_1, \ldots, q_{n-2}, \nu(p))$. So we have the following commutative diagram



where $W = \lim\{p, q_1, \ldots, q_{m-1}\}$. We next show that the orthogonal complement of ker $D_W \Pi_M$ in $T_W \Sigma_m$ is given by the horizontal space $T_W^h \Sigma_m$.

As the map Π_M is just the projection onto the first column, the kernel of $D_Q \Pi_M$ is given by

$$\ker D_Q \widehat{\Pi}_M = \{ U \in T_Q \widehat{\Sigma} \mid QUe_1 = 0 \}.$$

It follows that $T_Q^v \hat{\Sigma} \subseteq \ker D_Q \hat{\Pi}_M$ and $T_Q^h \hat{\Sigma} \cap \ker D_Q \hat{\Pi}_M = 0$. Using the commutative diagram (7.14), we obtain $T_W^v \Sigma_m \subseteq \ker D_W \Pi_M$ and $T_W^h \Sigma_m \cap \ker D_W \Pi_M = 0$. The fact that $T_W \Sigma_m = T_W^v \Sigma_m \oplus T_W^h \Sigma_m$ is an orthogonal decomposition implies that $T_W^v \Sigma_m = \ker D_W \Pi_M$ and hence $T_W^h \Sigma_m = (\ker D_W \Pi_M)^{\perp}$.

In order to compute $D_W \Pi_M$ on the horizontal space $T_W^h \Sigma_m$, we consider for fixed $Q = (p, q_1, \ldots, q_{n-2}, \nu(p)) \in \hat{\Sigma}$ the following diagram

where $\beta(U) = [Q, U]$ for $U \in S_n$, and $\gamma(a) = \sum_{i=1}^{n-2} a_i \cdot q_i$ for $a = (a_1, \ldots, a_{n-2})^T \in \mathbb{R}^{n-2}$. Let us check that this diagram is commutative: using

$$D_Q \Pi_{\Sigma}(Q \cdot \hat{E}^h(a)) \stackrel{(6.7)}{=} [Q, \pi(\hat{E}^h(a))] \stackrel{(7.11)}{=} [Q, E^h(a)],$$

we get

$$D_W \Pi_M([Q, E^h(a)]) = D_W \Pi_M(D_Q \Pi_\Sigma(Q \cdot \hat{E}^h(a))) \stackrel{(7.14)}{=} D_Q \hat{\Pi}_M(Q \cdot \hat{E}^h(a)) = \gamma(a).$$

Since β and γ are isometric we obtain

$$\operatorname{ndet}(D_W \Pi_M) = |\det(E^h)|^{-1} \stackrel{(7.13)}{=} |\det_Y(\mathcal{W}_p)|^{-1} = \det_Y(\mathcal{W}_p)^{-1}$$

where the last equality follows from the positive definiteness of \mathcal{W}_p .

Proof of Theorem 4.5. It remains to show the claim about the Jacobian of Ψ .

Let us make yet another definition in the lifted setting. For $Q \in \hat{\Sigma}$ we define the direction $\hat{\nu}(Q) \in T_Q O(n)$ and the map $\hat{\Psi} : \hat{\Sigma} \times \mathbb{R} \to O(n)$ via

$$\hat{\nu}(Q) := Q \cdot N, \qquad \hat{\Psi}(Q, t) = \exp_Q(\arctan t \cdot \hat{\nu}(Q)),$$

where $N \in \text{Skew}_n$ is, as usual, defined in (6.2). Abbreviating $\rho := \arctan t$, we obtain from (6.3) that the map $\hat{\Psi}$ is given by $\hat{\Psi}(Q,t) = Q \cdot Q_{\rho}$, where Q_{ρ} was defined in (6.3). Furthermore, denoting $\hat{\Pi} := \Pi_{\Sigma} \times \text{id}_{\mathbb{R}}$, we get the following commutative diagram

We will compute the derivative $D\Psi$ via the lifting $D\hat{\Psi}$ in the following way. Let $W \in \Sigma_m$ and let $Q = (p, \bar{Q}, \nu(p)) \in \hat{\Sigma}$ be a lifting of W, i.e., $W = \Pi_{\Sigma}(Q)$. For $(\xi, \dot{t}) \in T_{(W,t)}(\Sigma_m \times \mathbb{R})$, let $\hat{\xi} \in T_Q \hat{\Sigma}$ be a lifting of ξ , i.e., $\xi = D\Pi_{\Sigma}(\hat{\xi})$. Using the relations displayed in the commutative diagram (7.15), we get

$$D\Psi(\xi,\dot{t}) = D\Psi(D\tilde{\Pi}(\hat{\xi},\dot{t})) \stackrel{(7.15)}{=} D\Pi(D\hat{\Psi}(\hat{\xi},\dot{t})).$$
(7.16)

From the explicit form $\hat{\Psi}(Q,t) = Q \cdot Q_{\rho}$, taking into account $\rho = \arctan t$, $\frac{d\rho}{dt} = (1+t^2)^{-1}$, and $\frac{d}{d\rho}Q_{\rho} = Q_{\rho}N$ (cf. (6.3)), we get

$$D_{(Q,t)}\hat{\Psi}(0,1) = (1+t^2)^{-1} \cdot Q \cdot Q_{\rho} \cdot N.$$

Using (7.16), we thus have

$$D_{(W,t)}\Psi(0,1) = D\Pi((1+t^2)^{-1} \cdot Q \cdot Q_{\rho} \cdot N)$$

$$\stackrel{(6.7)}{=} (1+t^2)^{-1} \cdot [Q \cdot Q_{\rho}, N].$$
(7.17)

It remains to compute the derivative of Ψ in the first component.

Taking into account the orthogonal decomposition $T_W \Sigma_m = T_W^v \Sigma_m \oplus T_W^h \Sigma_m$, cf. Corollary 7.4, we first consider the vertical space $T_W^v \Sigma_m$. By (7.12) every element $\xi \in T_W^v \Sigma_m$ is of the form $\xi = [Q, E^v(X)]$ for some $X \in \mathbb{R}^{(n-m-1)\times(m-1)}$. Furthermore, a lifting $\hat{\xi}$ of ξ is given by $\hat{\xi} = Q \cdot E^v(X)$, as $D\Pi_{\Sigma}([Q, E^v(X)]) = Q \cdot E^v(X)$, cf. (6.7). As for fixed ρ , the map $Q \mapsto Q \cdot Q_\rho$ is linear, we obtain from $\hat{\Psi}(Q, t) = Q \cdot Q_\rho$

$$D_{(Q,t)}\hat{\Psi}(\hat{\xi},0) = Q \cdot E^{v}(X) \cdot Q_{\rho} \stackrel{(*)}{=} Q \cdot Q_{\rho} \cdot E^{v}(X),$$

where the equality (*) follows from the fact that Q_{ρ} only acts on the first and the last columns or rows. This implies via (7.16) and (6.7)

$$D_{(W,t)}\Psi(\xi,0) = [Q \cdot Q_{\rho}, \ \pi(E^{v}(X))] = [Q \cdot Q_{\rho}, \ E^{v}(X)],$$
(7.18)

where, as usual, π : Skew_n $\rightarrow \overline{\text{Skew}_n}$ denotes the orthogonal projection.

As for the horizontal space, any element $\zeta \in T_W^v \Sigma_m$ is of the form $\zeta = [Q, E^h(a)]$ for some $a \in \mathbb{R}^{n-2}$, cf. (7.12). A lifting $\hat{\zeta}$ of ζ is given by $\zeta = Q \cdot \hat{E}^h(a)$, as

$$D\Pi_{\Sigma}(\hat{\zeta}) \stackrel{(6.7)}{=} [Q, \pi(\hat{E}^{h}(a))] \stackrel{(7.11)}{=} [Q, E^{h}(a)] = \zeta.$$

We thus get from $\hat{\Psi}(Q,t) = Q \cdot Q_{\rho}$

$$D_{(Q,t)}\hat{\Psi}(\hat{\zeta},0) = Q \cdot \hat{E}^h(a) \cdot Q_\rho = Q \cdot Q_\rho \cdot Q_\rho^T \cdot \hat{E}^h(a) \cdot Q_\rho.$$

This implies via (7.16) and (6.7)

$$D_{(W,t)}\Psi(\zeta,0) = \left[Q \cdot Q_{\rho}, \ \pi \left(Q_{\rho}^T \cdot \hat{E}^h(a) \cdot Q_{\rho}\right)\right].$$
(7.19)

To finish the computation, note that we have for $a, b \in \mathbb{R}^{n-2}$

$$Q_{\rho}^{T} \cdot \left(\begin{array}{c|c} 0 & -a^{T} & 0 \\ \hline a & 0 & -b \\ \hline 0 & b^{T} & 0 \end{array} \right) \cdot Q_{\rho} = \left(\begin{array}{c|c} 0 & -ca^{T} - sb^{T} & 0 \\ \hline ca + sb & 0 & sa - cb \\ \hline 0 & -sa^{T} + cb^{T} & 0 \end{array} \right),$$
(7.20)

where we use the abbreviations $s := \sin(\rho)$ and $c := \cos(\rho)$. Using the decompositions $a = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$, $b = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix}$ with $a_1, b_1 \in \mathbb{R}^{m-1}$, $a_2, b_2 \in \mathbb{R}^{n-m-1}$, we obtain

$$\pi \left(Q_{\rho}^{T} \left(\begin{array}{c|c} 0 & -a^{T} & 0 \\ \hline a & 0 & -b \\ \hline 0 & b^{T} & 0 \end{array} \right) Q_{\rho} \right)$$

$$\stackrel{(7.20)}{=} \left(\begin{array}{c|c} 0 & \frac{|-ca_{2}^{T} - sb_{2}^{T}| & 0 \\ \hline ca_{2} + sb_{2} & 0 \\ \hline ca_{2} + sb_{2} & 0 \\ \hline 0 & |-sa_{1}^{T} + cb_{1}^{T} \\ \hline 0 \end{array} \right). \quad (7.21)$$

Combining (7.21) with the formula in (7.19), we get an explicit formula for the derivative of Ψ on the horizontal space.

To summarize the results from (7.17), (7.18), and (7.19), let us define $W_{\rho} := \Pi(Q \cdot Q_{\rho})$, and set

$$T^1_{W_{\rho}} := D\Psi(0 \times \mathbb{R}), \qquad T^2_{W_{\rho}} := D\Psi(T^v_W \Sigma_m \times 0), \qquad T^3_{W_{\rho}} := D\Psi(T^h_W \Sigma_m \times 0).$$

Recall the orthogonal decomposition $\overline{\text{Skew}_n} = \mathbb{R}N \oplus \text{im } E^v \oplus \text{im } E^h$, cf. (7.10). This implies the orthogonal decomposition

$$T_{W_{\rho}}\operatorname{Gr}_{n,m} = T^{1}_{W_{\rho}} \oplus T^{2}_{W_{\rho}} \oplus T^{3}_{W_{\rho}}.$$

Furthermore, the corresponding restrictions of $D\Psi$ yield a dilation by the factor $(1 + t^2)^{-1}$ between $0 \times \mathbb{R}$ and $T^1_{W_{\rho}}$ (cf. (7.17)), an isometry between $T^v_W \Sigma_m \times 0$ and $T^2_{W_{\rho}}$ (cf. (7.18)), and a nontrivial linear map $\overline{D\Psi}$ between $T^h_W \Sigma_m \times 0$ and $T^3_{W_{\rho}}$ (cf. (7.19), (7.21)). This implies

$$\operatorname{ndet}(D_{(W,t)}\Psi) = (1+t^2)^{-1} \cdot |\det \overline{D\Psi}|.$$
(7.22)

,

We determine now $|\det \overline{D\Psi}|$.

We consider the following commutative diagram defining the linear map $\mu \colon \mathbb{R}^{n-2} \to \mathbb{R}^{n-2}$:

$$T^{h}_{W}\Sigma_{m} \times 0 \xrightarrow{\overline{D\Psi}} T^{3}_{W\rho}$$

$$\uparrow \beta \circ E^{h} \qquad \uparrow \beta \circ \alpha$$

$$\mathbb{R}^{n-2} \xrightarrow{\mu} \mathbb{R}^{(m-1)+(n-m-1)}$$

where β : Skew_n $\to T_W^h \Sigma_m$, $U \mapsto [Q, U]$, and $\alpha \colon \mathbb{R}^{n-2} \to \text{Skew}_n$ as defined in (7.8). As α, β are isometries, we obtain

$$|\det \overline{D\Psi}| = |\det(\beta \circ E^{h})^{-1}| \cdot |\det \mu| = |\det E^{h}|^{-1} \cdot |\det \mu| \stackrel{(7.13)}{=} \det_{Y}(\mathcal{W}_{p})^{-1} \cdot |\det \mu|.$$
(7.23)

As for the linear map μ , we obtain from (7.21) that μ has the transformation matrix $\begin{pmatrix} c\Lambda_1 - sI_{m-1} & c\Lambda_2 \\ s\Lambda_3 & cI_{n-m-1} + s\Lambda_4 \end{pmatrix}$, as $\begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \begin{pmatrix} \Lambda_1 & \Lambda_2 \\ \Lambda_3 & \Lambda_4 \end{pmatrix} \cdot \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$ and $\begin{pmatrix} c\Lambda_1 - sI_{m-1} & c\Lambda_2 \\ s\Lambda_3 & cI_{n-m-1} + s\Lambda_4 \end{pmatrix} \cdot \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} -sa_1 + cb_1 \\ ca_2 + sb_2 \end{pmatrix}$.

Using that $\frac{s}{c} = \tan \rho = t$ and $c = \cos \rho = 1/\sqrt{1+t^2}$, we obtain

$$\det \mu = \det \begin{pmatrix} c\Lambda_1 - sI_{m-1} & c\Lambda_2 \\ s\Lambda_3 & cI_{n-m-1} + s\Lambda_4 \end{pmatrix}$$
$$= c^{n-2} \cdot \det \begin{pmatrix} \Lambda_1 + tI_{m-1} & \Lambda_2 \\ -t\Lambda_3 & I_{n-m-1} - t\Lambda_4 \end{pmatrix}$$
$$= (1+t^2)^{-(n-2)/2} \cdot \operatorname{ch}_Y(\mathcal{W}_p, -t),$$

where the last equality is a consequence of (4.3). From (7.22) and (7.23) we thus get

$$\operatorname{ndet}(D_{(W,t)}\Psi) = (1+t^2)^{-1} \cdot \frac{|\det \mu|}{\det_Y \mathcal{W}_p} = (1+t^2)^{-n/2} \cdot \frac{|\operatorname{ch}_Y(\mathcal{W}_p, -t)|}{\det_Y \mathcal{W}_p}$$

which finishes the proof of Theorem 4.5.

A Averaging the twisted characteristic polynomial

Recall the setting of Section 4.2. Let $A \in \mathbb{R}^{k \times k}$ and $\varphi \colon \mathbb{R}^k \to \mathbb{R}^k, x \mapsto Ax$. Using the notation $\operatorname{ch}_{\ell}(A, t) = \operatorname{ch}_{Y_0}(\varphi, t)$, where $Y_0 = \mathbb{R}^{\ell} \times 0$, we have

$$\mathbb{E}_{Y}[\operatorname{ch}_{Y}(\varphi,t)] = \mathbb{E}_{Q}\left[\operatorname{ch}_{\ell}(Q^{T} A Q,t)\right].$$
(A.1)

(The reason is that $QY_0 \in \operatorname{Gr}_{k,\ell}$ is uniform random when $Q \in O(k)$ uniformly chosen at random.) This equality allows to prove Theorem 4.4 with basic matrix calculus. The main idea is to use the multilinearity of the determinant and the invariance of the coefficients $\sigma_i(A)$ under similarity transformations, to show that the coefficients of $\mathbb{E}[\operatorname{ch}_{\ell}(Q^T A Q, t)]$ are linear combinations of the $\sigma_i(A)$. We then compute the coefficients of these linear combinations by choosing for A scalar multiples of the identity matrix.

In the following, we use the notation $[k] := \{1, \ldots, k\}$, and we denote by $\binom{[k]}{i}$ the set of all *i*-element subsets of [k]. For $A \in \mathbb{R}^{k \times k}$ and $J \in \binom{[k]}{i}$, we denote by $\operatorname{pm}_J(A) := \det(A_J)$ the *J*th *principal minor* of *A*, where A_J denotes the submatrix of *A* obtained by selecting the rows and columns of *A* whose indices lie in *J*. It is well-known (cf. for example [28, Thm. 1.2.12]) that $\sigma_i(A)$ is the sum of all principal minors of *A* of size *i*, i.e.,

$$\sigma_i(A) = \sum_{J \in \binom{[k]}{i}} \operatorname{pm}_J(A) .$$
(A.2)

For $0 \leq \ell \leq k$, the ℓ th leading principal minor $\operatorname{lpm}_{\ell}(A) := \operatorname{pm}_{[\ell]}(A)$ is defined as the principal minor for $J = [\ell]$. Note that $\operatorname{lpm}_{\ell}(A) = \operatorname{det}_{\mathbb{R}^{\ell} \times 0}(\varphi)$.

Lemma A.1. Let $A \in \mathbb{R}^{k \times k}$, and $Q \in O(k)$ be chosen uniformly at random. Then, for all $J \in {\binom{[k]}{\ell}}$, we have

$$\mathbb{E}_{Q}\left[\mathrm{pm}_{J}(Q^{T}AQ)\right] = \mathbb{E}_{Q}\left[\mathrm{lpm}_{\ell}(Q^{T}AQ)\right] = \frac{1}{\binom{k}{\ell}}\sigma_{\ell}(A) .$$

↑

Proof. For the first equality let $J = \{j_1, \ldots, j_\ell\}, j_1 < \ldots < j_\ell$, and let π be any permutation of [k] such that $\pi(i) = j_i$ for all $i = 1, \ldots, \ell$. If M_{π} denotes the permutation matrix corresponding to π , i.e., $M_{\pi}e_i = e_{\pi(i)}$, then $A_J = (M_{\pi}^T A M_{\pi})_{[\ell]}$, and therefore $\text{pm}_J(A) = \text{lpm}_\ell(M_{\pi}^T A M_{\pi})$. This implies

$$\mathbb{E}_{Q}\left[\mathrm{pm}_{J}(Q^{T}AQ)\right] = \mathbb{E}_{Q}\left[\mathrm{lpm}_{\ell}(M_{\pi}^{T}Q^{T}AQM_{\pi})\right] = \mathbb{E}_{Q}\left[\mathrm{lpm}_{\ell}(Q^{T}AQ)\right] ,$$

where we have used the fact that right multiplication by the fixed element M_{π} leaves the uniform distribution on O(k) invariant. This implies

$$\mathbb{E}_{Q}\left[\operatorname{lpm}_{\ell}(Q^{T}AQ)\right] = \frac{1}{\binom{k}{\ell}} \sum_{J \in \binom{[k]}{\ell}} \mathbb{E}_{Q}\left[\operatorname{pm}_{J}(Q^{T}AQ)\right] = \frac{1}{\binom{k}{\ell}} \cdot \mathbb{E}_{Q}\left[\sum_{J \in \binom{[k]}{\ell}} \operatorname{pm}_{J}(Q^{T}AQ)\right] \\
\stackrel{(A.2)}{=} \frac{1}{\binom{k}{\ell}} \cdot \mathbb{E}_{Q}\left[\sigma_{\ell}(Q^{T}AQ)\right] = \frac{1}{\binom{k}{\ell}}\sigma_{\ell}(A) . \qquad \Box$$

Proof of Theorem 4.4. The statement (4.4) follows from (A.1) and Lemma A.1.

For proving (4.5), we start with a general observation. By multilinearity, we write the determinant of a matrix with columns $v_1, \ldots, v_{i-1}, v_i + \alpha \cdot e_i, v_{i+1}, \ldots, v_n$ in the form

$$\det(v_1, \dots, v_{i-1}, v_i + \alpha \cdot e_i, v_{i+1}, \dots, v_n) = \det(v_1, \dots, v_n) + \alpha \cdot \det(v_1, \dots, v_{i-1}, e_i, v_{i+1}, \dots, v_n).$$

Using this repeatedly, we obtain

$$\det(A + \operatorname{diag}(\alpha_1, \dots, \alpha_n)) = \sum_{J \subseteq [k]} \operatorname{pm}_J(A) \cdot \prod_{i \in [k] \setminus J} \alpha_i .$$
(A.3)

By (4.3) we can express the twisted characteristic polynomial as

$$ch_{\ell}(A,t) = t^{k-\ell} \cdot det(A + diag(-t,\ldots,-t,1/t,\ldots,1/t)) .$$

Applying (A.3), we expand this to obtain

$$\operatorname{ch}_{\ell}(A,t) = \sum_{J \subseteq [k]} (-1)^{c_1(J)} \cdot \operatorname{pm}_J(A) \cdot t^{c_2(J)} ,$$
 (A.4)

where $c_1, c_2: 2^{[k]} \to \mathbb{N}$ are some integer valued functions on the power set of [k]. Averaging the twisted characteristic polynomial with the help of Lemma A.1 yields

$$\begin{split} \mathbb{E}_{Q} \left[\mathrm{ch}_{\ell}(Q^{T}AQ, t) \right] &= \sum_{J \subseteq [k]} (-1)^{c_{1}(J)} \cdot \mathbb{E}_{Q} \left[\mathrm{pm}_{J}(Q^{T}AQ) \right] \cdot t^{c_{2}(J)} \\ &= \sum_{J \subseteq [k]} \frac{(-1)^{c_{1}(J)}}{\binom{k}{|J|}} \cdot \sigma_{|J|}(A) t^{c_{2}(J)} = \sum_{i,j=0}^{k} \tilde{d}_{ij} \cdot \sigma_{k-j}(A) \cdot t^{k-i} \;, \end{split}$$

for some rational constants \tilde{d}_{ij} . It remains to prove that the \tilde{d}_{ij} coincide with the d_{ij} defined in Theorem 4.4.

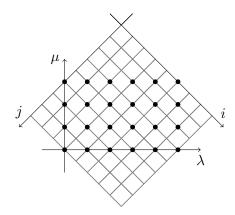


Figure 1: Illustration of the change of summation in (A.5) $(k = 8, \ell = 5)$.

To compute the \tilde{d}_{ij} , we choose $A = sI_k$. Then, $ch_\ell(sI_k, t) = (s-t)^\ell \cdot (1+st)^{k-\ell}$. Since $\sigma_{k-j}(sI_k) = {k \choose j} s^{k-j}$, and $Q^T sI_k Q = sI_k$, we get

$$(s-t)^{\ell} \cdot (1+st)^{k-\ell} = ch_{\ell}(sI_k, t) = \mathop{\mathbb{E}}_{Q} \left[ch_{\ell}(Q^T sI_k Q, t) \right] = \sum_{i,j=0}^{k} \tilde{d}_{ij} \binom{k}{j} s^{k-j} t^{k-i}$$

Let us expand the first term:

$$(s-t)^{\ell} \cdot (1+st)^{k-\ell} = \left(\sum_{\lambda=0}^{\ell} \binom{\ell}{\lambda} (-1)^{\ell-\lambda} s^{\lambda} t^{\ell-\lambda}\right) \cdot \left(\sum_{\mu=0}^{k-\ell} \binom{k-\ell}{\mu} s^{\mu} t^{\mu}\right)$$
$$= \sum_{\lambda=0}^{\ell} \sum_{\mu=0}^{k-\ell} (-1)^{\ell-\lambda} \binom{\ell}{\lambda} \binom{k-\ell}{\mu} s^{\lambda+\mu} t^{\ell-\lambda+\mu}$$
$$\stackrel{i=k-\ell+\lambda-\mu}{j=k-\lambda-\mu} \sum_{\substack{i,j=0\\ j=k-\lambda-\mu\\ j=k-\lambda-\mu\\ j=k-\lambda-\mu\\ (\mathrm{mod}\ 2)}}^{k} (-1)^{\frac{i-j}{2}-\frac{\ell}{2}} \binom{\ell}{\frac{i-j}{2}+\frac{\ell}{2}} \binom{k-\ell}{k-\frac{i+j+\ell}{2}} s^{k-j} t^{k-i},$$

where again we interpret $\binom{n}{m} = 0$ if m < 0 or m > n, i.e., the above summation over i, j in fact only runs over the rectangle determined by the inequalities $0 \le \frac{i-j}{2} + \frac{\ell}{2} \le \ell$ and $0 \le k - \frac{i+j+\ell}{2} \le k - \ell$. (See Figure 1 for an illustration of the change of summation.) Note that the reverse substitution is given by $\lambda = \frac{i-j+\ell}{2}$ and $\mu = k - \frac{i+j+\ell}{2}$.

Comparing the coefficients of the above two expressions for $(s - t)^{\ell} \cdot (1 + st)^{k-\ell}$ reveals that indeed $\tilde{d}_{ij} = d_{ij}$ as defined in Theorem 4.4. This completes the proof of (4.5)

For the last claim (4.6) in Theorem 4.4, we define the *positive characteristic polynomial*

$$\operatorname{ch}_{\ell}^{+}(A,t) = \operatorname{det} \begin{pmatrix} A_{1} + tI_{\ell} & A_{2} \\ tA_{3} & tA_{4} + I_{k-\ell} \end{pmatrix}$$

by replacing -t by t in (4.3). By the same reasoning as for (A.4), we get

$$\operatorname{ch}_{\ell}^{+}(A,t) = \sum_{J \subseteq [k]} \operatorname{pm}_{J}(A) \cdot t^{c_{2}(J)} , \qquad (A.6)$$

with the same function $c_2: 2^{[k]} \to \mathbb{N}$ as in (A.4). Moreover, by arguing as in the proof of (4.5) before, we show that

$$\mathbb{E}_{Q}\left[\operatorname{ch}_{\ell}^{+}(Q^{T}AQ, t)\right] = \sum_{i,j=0}^{k} |d_{ij}| \cdot \sigma_{k-j}(A) \cdot t^{k-i} .$$
(A.7)

Now assume that A is positive semidefinite. Then each of its principal minor is nonnegative, i.e., $pm_J(A) \ge 0$ for all $J \subseteq [k]$. Therefore, if $t \ge 0$, we get from (A.4) and (A.6)

$$\left| \operatorname{ch}_{\ell}(A,t) \right| = \left| \sum_{J \subseteq [k]} (-1)^{c_1(J)} \cdot \operatorname{pm}_J(A) \cdot t^{c_2(J)} \right| \le \sum_{J \subseteq [k]} \operatorname{pm}_J(A) \cdot t^{c_2(J)} = \operatorname{ch}_{\ell}^+(A,t) .$$

Taking into account (A.7) completes the proof of Theorem 4.4.

B Proof of some technical estimations

Recall that the symbol $\overline{\blacksquare}$ is used to mark simple estimates, which are easily checked with a computer algebra system.

Proof of Lemma 5.3. (1) We make a case distinction by the parity of ℓ . Using $\Gamma(x+1) = x \cdot \Gamma(x)$, we get for odd ℓ

$$\frac{\Gamma(\frac{m+\ell+1}{2})}{\Gamma(\frac{m}{2})} = \prod_{a=0}^{\frac{\ell-1}{2}} \left(\frac{m}{2}+a\right) \le \frac{m}{2} \cdot \left(\frac{m+\ell-1}{2}\right)^{\frac{\ell-1}{2}} \le \sqrt{\frac{m}{2}} \cdot \left(\frac{m+\ell}{2}\right)^{\frac{\ell}{2}} \ .$$

Using additionally $\Gamma(x+\frac{1}{2}) < \sqrt{x} \cdot \Gamma(x)$, we get for even ℓ

$$\frac{\Gamma(\frac{m+\ell+1}{2})}{\Gamma(\frac{m}{2})} = \prod_{a=0}^{\frac{\ell}{2}-1} \left(\frac{m+1}{2}+a\right) \cdot \frac{\Gamma(\frac{m+1}{2})}{\Gamma(\frac{m}{2})} < \left(\frac{m+\ell}{2}\right)^{\frac{\ell}{2}} \cdot \sqrt{\frac{m}{2}} \ .$$

(2) As for the second estimate, we distinguish the cases $i \ge 2k$ and $i \le 2k$. From $0 \le k \le m-1$ and $0 \le i-k \le n-m-1$ we get

$$\begin{array}{rrrr} 1 & \leq & m-k+i-k & \leq & n-1 \; , \\ 1 & \leq & n-(m-k+i-k) \; \leq \; n-1 \; . \end{array}$$

For $i \geq 2k$ we thus get

$$\left(\frac{m+i-2k}{n-m-i+2k}\right)^{\frac{i-2k}{2}} \le (n-1)^{\frac{i-2k}{2}} < n^{\frac{i}{2}},$$

and for $i \leq 2k$

$$\left(\frac{m+i-2k}{n-m-i+2k}\right)^{\frac{i-2k}{2}} = \left(\frac{n-m+2k-i}{m-2k+i}\right)^{\frac{2k-i}{2}} \le (n-1)^{\frac{2k-i}{2}} < n^{\frac{i}{2}} \ .$$

(3) The *I*-functions have been estimated in [10, Lemma 2.2] in the following way. Let $\varepsilon := \sin(\alpha) = \frac{1}{t}$. For i < n-2

$$I_{n,n-2-i}(\alpha) = \int_0^\alpha \cos(\rho)^{n-2-i} \cdot \sin(\rho)^i \, d\rho \le \frac{\varepsilon^{i+1}}{i+1} \, ,$$

and for i = n - 2, assuming $n \ge 3$,

$$I_{n,0}(\alpha) = \int_0^\alpha \sin(\rho)^{n-2} d\rho \le \frac{\mathcal{O}_{n-1} \cdot \varepsilon^{n-1}}{2\mathcal{O}_{n-2}} = \frac{\sqrt{\pi}}{2} \cdot \frac{\Gamma(\frac{n-1}{2})}{\Gamma(\frac{n}{2})} \cdot \varepsilon^{n-1} < \sqrt{\frac{\pi}{2(n-2)}} \cdot \varepsilon^{n-1} .$$

With these estimates we get

For $\varepsilon < n^{-\frac{3}{2}}$ we thus get

$$\sum_{i=0}^{n-2} \binom{n-2}{i} \cdot n^{\frac{i}{2}} \cdot I_{n,n-2-i}(\alpha) < \varepsilon \cdot \left(\underbrace{\left(1+\frac{1}{n}\right)^{n-2}}_{<\exp(1)} + 1.4 \cdot n^{\frac{3}{2}-n} \right) \stackrel{\scriptstyle{\scriptstyle{\scriptstyle{\scriptstyle{\blacksquare}}}}}{<} 3 \cdot \varepsilon \ .$$

Similarly we derive

$$\sum_{i=0}^{n-2} \binom{n-2}{i} \cdot I_{n,n-2-i}(\alpha) < \varepsilon \cdot \left((1+\varepsilon)^{n-2} + \frac{1.4}{\sqrt{n}} \cdot \varepsilon^{n-2} \right) .$$

For $\varepsilon < \frac{1}{m}$ we thus get

$$\sum_{i=0}^{n-2} \binom{n-2}{i} \cdot I_{n,n-2-i}(\alpha) < \varepsilon \cdot \left(\left(1+\frac{1}{m}\right)^{n-2} + \frac{1.4}{\sqrt{n} \cdot m^{n-2}} \right) \stackrel{\text{liff}}{<} \varepsilon \cdot \exp\left(\frac{n}{m}\right) . \qquad \Box$$

References

- [1] D. Amelunxen. Geometric analysis of the condition of the convex feasibility problem. PhD Thesis, Univ. Paderborn, 2011.
- [2] D. Amelunxen and P. Bürgisser. Intrinsic volumes of symmetric cones. arXiv 1205.1863.

- [3] D. Amelunxen and P. Bürgisser. A Coordinate-Free Condition Number for Convex Programming. SIAM J. Optim., 22(3):1029–1041, 2012.
- [4] A. Belloni and R. M. Freund. A geometric analysis of Renegar's condition number, and its interplay with conic curvature. *Math. Program.*, 119(1, Ser. A):95–107, 2009.
- [5] T. Bonnesen and W. Fenchel. Theorie der konvexen Körper. Springer-Verlag, Berlin, 1974. Berichtigter Reprint.
- [6] W. M. Boothby. An introduction to differentiable manifolds and Riemannian geometry, volume 120 of Pure and Applied Mathematics. Academic Press Inc., Orlando, FL, second edition, 1986.
- [7] S. Boyd and L. Vandenberghe. *Convex optimization*. Cambridge University Press, Cambridge, 2004.
- [8] P. Bürgisser. Smoothed analysis of condition numbers. In Foundations of computational mathematics, Hong Kong 2008, volume 363 of London Math. Soc. Lecture Note Ser., pages 1–41. Cambridge Univ. Press, Cambridge, 2009.
- [9] P. Bürgisser and F. Cucker. Condition: The geometry of numerical algorithms. Number 349 in Grundlehren der Mathematischen Wissenschaften. Springer Verlag, 2013. To appear.
- [10] P. Bürgisser, F. Cucker, and M. Lotz. The probability that a slightly perturbed numerical analysis problem is difficult. *Math. Comp.*, 77(263):1559–1583, 2008.
- [11] I. Chavel. Riemannian geometry, volume 98 of Cambridge Studies in Advanced Mathematics. Cambridge University Press, Cambridge, second edition, 2006. A modern introduction.
- [12] Z. Chen and J. J. Dongarra. Condition numbers of Gaussian random matrices. SIAM J. Matrix Anal. Appl., 27(3):603–620 (electronic), 2005.
- [13] D. Cheung and F. Cucker. A new condition number for linear programming. Math. Program., 91(1, Ser. A):163–174, 2001.
- [14] F. Cucker and J. Peña. A primal-dual algorithm for solving polyhedral conic systems with a finite-precision machine. SIAM J. Optim., 12(2):522–554 (electronic), 2001/02.
- [15] J.W. Demmel. The probability that a numerical analysis problem is difficult. Math. Comp., 50:449–480, 1988.
- [16] M. P. do Carmo. *Riemannian geometry*. Mathematics: Theory & Applications. Birkhäuser Boston Inc., Boston, MA, 1992. Translated from the second Portuguese edition by Francis Flaherty.
- [17] M. Epelman and R. M. Freund. A new condition measure, preconditioners, and relations between different measures of conditioning for conic linear systems. SIAM J. Optim., 12(3):627–655 (electronic), 2002.
- [18] H. Federer. Geometric measure theory. Die Grundlehren der mathematischen Wissenschaften, Band 153. Springer-Verlag New York Inc., New York, 1969.
- [19] S. Filipowski. On the complexity of solving feasible linear programs specified with approximate data. SIAM J. Optim., 9(4):1010–1040, 1999. Dedicated to John E. Dennis, Jr., on his 60th birthday.
- [20] R. M. Freund and F. Ordóñez. On an extension of condition number theory to nonconic convex optimization. Math. Oper. Res., 30(1):173–194, 2005.
- [21] R. M. Freund and J. R. Vera. Condition-based complexity of convex optimization in conic linear form via the ellipsoid algorithm. SIAM J. Optim., 10(1):155–176 (electronic), 1999.
- [22] R. M. Freund and J. R. Vera. Some characterizations and properties of the "distance to illposedness" and the condition measure of a conic linear system. *Math. Program.*, 86(2, Ser. A):225– 260, 1999.

- [23] F. Gao, D. Hug, and R. Schneider. Intrinsic volumes and polar sets in spherical space. Math. Notae, 41:159–176 (2003), 2001/02. Homage to Luis Santaló. Vol. 1 (Spanish).
- [24] S. Glasauer. Integralgeometrie konvexer Körper im sphärischen Raum. Thesis, Univ. Freiburg i. Br., 1995.
- [25] S. Glasauer. Integral geometry of spherically convex bodies. Diss. Summ. Math., 1(1-2):219–226, 1996.
- [26] G. H. Golub and C. F. Van Loan. *Matrix computations*. Johns Hopkins Studies in the Mathematical Sciences. Johns Hopkins University Press, Baltimore, MD, fourth edition, 2013.
- [27] S. Helgason. Differential geometry, Lie groups, and symmetric spaces, volume 80 of Pure and Applied Mathematics. Academic Press Inc. [Harcourt Brace Jovanovich Publishers], New York, 1978.
- [28] R. A. Horn and C. R. Johnson. *Matrix analysis*. Cambridge University Press, Cambridge, 1990. Corrected reprint of the 1985 original.
- [29] R. Howard. The kinematic formula in Riemannian homogeneous spaces. Mem. Amer. Math. Soc., 106(509):vi+69, 1993.
- [30] D. A. Klain and G.-C. Rota. Introduction to geometric probability. Lezioni Lincee. [Lincei Lectures]. Cambridge University Press, Cambridge, 1997.
- [31] S. Kobayashi and K. Nomizu. Foundations of differential geometry. Vol I. Interscience Publishers, a division of John Wiley & Sons, New York-Lond on, 1963.
- [32] F. Morgan. Geometric measure theory. Academic Press Inc., San Diego, CA, second edition, 1995. A beginner's guide.
- [33] M. Moszyńska. Selected topics in convex geometry. Birkhäuser Boston Inc., Boston, MA, 2006. Translated and revised from the 2001 Polish original.
- [34] J. Peña. Understanding the geometry of infeasible perturbations of a conic linear system. SIAM J. Optim., 10(2):534–550 (electronic), 2000.
- [35] J. Peña. A characterization of the distance to infeasibility under block-structured perturbations. Linear Algebra Appl., 370:193–216, 2003.
- [36] J. Peña and J. Renegar. Computing approximate solutions for convex conic systems of constraints. Math. Program., 87(3, Ser. A):351–383, 2000.
- [37] J. Renegar. Some perturbation theory for linear programming. Math. Programming, 65(1, Ser. A):73-91, 1994.
- [38] J. Renegar. Incorporating condition measures into the complexity theory of linear programming. SIAM J. Optim., 5(3):506–524, 1995.
- [39] J. Renegar. Linear programming, complexity theory and elementary functional analysis. Math. Programming, 70(3, Ser. A):279–351, 1995.
- [40] R. Schneider. Convex bodies: the Brunn-Minkowski theory, volume 44 of Encyclopedia of Mathematics and its Applications. Cambridge University Press, Cambridge, 1993.
- [41] R. Schneider and W. Weil. Stochastic and integral geometry. Probability and its Applications (New York). Springer-Verlag, Berlin, 2008.
- [42] S. Smale. Complexity theory and numerical analysis. In Acta numerica, 1997, volume 6 of Acta Numer., pages 523–551. Cambridge Univ. Press, Cambridge, 1997.
- [43] M. Spivak. Calculus on manifolds. A modern approach to classical theorems of advanced calculus.
 W. A. Benjamin, Inc., New York-Amsterdam, 1965.

- [44] M. Spivak. A comprehensive introduction to differential geometry. Vol. I. Publish or Perish Inc., third edition, 1999.
- [45] R. P. Stanley. Log-concave and unimodal sequences in algebra, combinatorics, and geometry. In Graph theory and its applications: East and West (Jinan, 1986), volume 576 of Ann. New York Acad. Sci., pages 500–535. New York Acad. Sci., New York, 1989.
- [46] J. A. Thorpe. Elementary topics in differential geometry. Undergraduate Texts in Mathematics. Springer-Verlag, New York, 1994.
- [47] J. C. Vera, J. C. Rivera, J. Peña, and Yao Hui. A primal-dual symmetric relaxation for homogeneous conic systems. J. Complexity, 23(2):245–261, 2007.
- [48] J. R. Vera. Ill-posedness and the complexity of deciding existence of solutions to linear programs. SIAM J. Optim., 6(3):549–569, 1996.
- [49] J. R. Vera. On the complexity of linear programming under finite precision arithmetic. Math. Programming, 80(1, Ser. A):91–123, 1998.
- [50] H. Weyl. On the Volume of Tubes. Amer. J. Math., 61(2):461–472, 1939.