# PSEUDO-HERMITIAN STRUCTURES ON A REAL HYPERSURFACE

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#### Introduction

The invariance properties of a real hypersurface M (of real dimension 2n+1) in complex (n+1) space  $\mathbb{C}^{n+1}$  with respect to the infinite pseudo-group of biholomorphic transformations are the object of study in pseudo-conformal geometry. The systematic study of such properties for hypersurfaces with nondegenerate Levi form was first made by Cartan [2] in 1932. More recently, the study of invariants for such M was taken up by S. S. Chern and J. Moser [6]. A main aspect of the theory is the existence of a complete system of local differential invariants.

In this paper we take a somewhat different point of view. Such a manifold M has an integrable, nondegenerate, Cauchy-Riemann structure. In particular, there is a subbundle H(M) of the tangent bundle T(M) each fiber of which has the structure of a complex n-dimensional vector space. We single out a real nonvanishing one-form  $\theta$  annihilating H(M) and consider invariants of the pair  $(M, \theta)$ .  $(M, \theta)$  will be called a pseudo-hermitian manifold.

In § 1 we apply the Cartan method of equivalence [3] to find a compete system of invariants. This results in a connection and curvature forms on the coframe bundle of M. These are not, in general, pseudo-conformal invariants; they depend on the choice of  $\theta$ . In § 3 we consider the relation between these two systems of invariants. (3.8) gives a formula for the fourth order curvature tensor of Chern and Moser. A similar formula was given by Bochner [1] as a formal analogue of the conformal curvature tensor for a Kähler manifold. Here a geometric interpretation of the formula is given. In § 4 we apply the theory to some examples. It is shown that an ellipsoid is not, in general, equivalent to a sphere.

Also, the author wishes to remark that the theory developed here provides a complete system of invariants for nondegenerate real hypersurfaces under volume-preserving biholomorphic transformations, when the ambient complex space is equipped with a volume form.

We will follow the notation adopted in [6]. Small Greek indices run from 1 to n, and the summation convention is used. The Levi form  $g_{\alpha\beta}$  and its inverse  $g^{\beta\alpha}$  are used to lower and raise indices, e.g.,

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$$heta_lpha = g_{lphaareta} heta^{areta}$$
 ,  $A^lpha_{eta} = g^{lpha \gamma}A_{\gammaeta}$  .

Thus the vertical as well as the horizontal position of an index carries information. Also, complex conjugation will be reflected in the indices, e.g.,

$$heta^{ar{eta}}=ar{ heta}^{eta}$$
 ,  $U_{ar{eta}}^{lpha}=ar{U}_{eta}{}^{lpha}$  ,  $ar{A}_{lphaar{eta}_{7}}=A_{lphaar{eta}_{7}}$  .

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### 1. The equivalence problem

Let  $(M, \theta)$  denote a (2n + 1)-dimensional pseudo-hermitian manifold.  $\theta$  is a fixed real one-form, and locally we can choose n complex one-forms  $\theta^{\alpha}$ , so that  $(\theta, \theta^{\alpha}, \theta^{\alpha})$  form a basis of complex covectors. They are determined up to

$$(1.1) \theta = \theta', \quad \theta^{\alpha} = \theta'^{\beta} U_{\beta}^{\alpha} + \theta v^{\alpha}, \quad \theta^{\alpha} = \theta'^{\beta} U_{\beta}^{\alpha} + \theta v^{\alpha}.$$

We require our structure to be integrable in the sense that

$$(1.2) d\theta \equiv d\theta^{\alpha} \equiv 0 , \text{mod } \theta, \theta^{r} .$$

Because  $\theta = \bar{\theta}$ , we must have

$$(1.3) d\theta = ig_{\alpha\bar{b}}\theta^{\alpha} \wedge \theta^{\bar{b}} + \theta \wedge (\eta_{\alpha}\theta^{\alpha} + \eta_{\bar{a}}\theta^{\bar{a}}),$$

where  $\eta_{\alpha} = \overline{\eta}_{\alpha}$ , and  $g_{\alpha\bar{\beta}}$  is hermitian:

$$g_{\alpha\bar{\beta}} = \bar{g}_{\beta\bar{\alpha}} = g_{\bar{\beta}\alpha} .$$

Under the change (1.1) we have

$$g_{\alpha\bar{\beta}} = U^{-1}{}_{\alpha}{}^{\rho}g'{}_{\rho\bar{\sigma}}U^{-1}{}_{\bar{\beta}}{}^{\bar{\sigma}}.$$

We will also assume that  $(M, \theta)$  is nondegenerate in the sense that the matrix (1.4) is nonsingular at each point. It will have a signature, say p negative and q positive eigenvalues, p+q=n, which we will speak of as the signature of  $(M, \theta)$ . If  $g_{\alpha\beta}$  is negative definite,  $(M, \theta)$  will be said to be strongly pseudoconvex. In the computations to follow  $g_{\alpha\beta}$  and its inverse  $g^{\beta\alpha}$  will be used to lower and raise indices.

In other words, we have a nondegenerate, integrable G-structure on M, G being the group of matrices

(1.6) 
$$\begin{pmatrix} 1 & v^{\alpha} & v^{\alpha} \\ 0 & U_{\beta}{}^{\alpha} & 0 \\ 0 & 0 & U_{\beta}{}^{\alpha} \end{pmatrix}, \quad v^{\alpha} \in \mathbb{C} , \quad (U_{\beta}{}^{\alpha}) \in GL(n, \mathbb{C}) .$$

To study the equivalence problem we begin by reducing the group (1.6). Substituting (1.1) with  $U_{\beta}^{\alpha} = \delta_{\beta}^{\alpha}$  into (1.3), we get

$$d\theta = ig_{\alpha\bar{\beta}}\theta^{\prime\alpha} \wedge \theta^{\prime\bar{\beta}} + \theta \wedge (\eta^{\prime}_{\alpha}\theta^{\prime\alpha} + \eta^{\prime}_{\bar{\alpha}}\theta^{\prime\bar{\alpha}}),$$

where

$$\eta'_{\alpha} = \eta_{\alpha} - ig_{\alpha\bar{\imath}}v^{\bar{\imath}}$$
.

Since  $g_{\alpha\bar{\tau}}$  is nondegenerate we can choose  $v^{\tau}$  so that  $\eta'_{\alpha} = 0$ , and if  $\eta_{\alpha} = \eta'_{\alpha} = 0$ , then  $v^{\alpha} = 0$ .

Hence by requiring

$$d\theta = ig_{\alpha\bar{\beta}}\theta^{\alpha} \wedge \theta^{\bar{\beta}},$$

we can reduce our group (1.6) to GL(n, C), that is, to changes

(1.8) 
$$\theta^{\alpha} = \theta'^{\beta} U_{\beta}^{\alpha} , \qquad \theta^{\overline{\alpha}} = \theta'^{\overline{\beta}} U_{\overline{\beta}}^{\overline{\alpha}} .$$

By also requiring

$$g_{\alpha\bar{\beta}} = \text{const.} = \pm \delta_{\alpha\bar{\beta}} ,$$

we can reduce our group further to U(p, q), the unitary group with signature (p, q). The conditions (1.7) and (1.9) are invariant under maps preserving our structure.

For a geometric interpretation of (1.7) let us consider the dual frame

$$(1.10) X = \overline{X}, \quad X_{\alpha}, \quad X_{\beta} = \overline{X}_{\alpha}$$

to  $(\theta, \theta^{\alpha}, \theta^{\bar{\alpha}})$ . The transformation (1.1) gives

$$(1.11) X' = X + v^{\alpha} X_{\alpha} + v^{\alpha} X_{\bar{\alpha}}, X_{\alpha} = U_{\alpha}^{\beta} X_{\bar{\beta}}, X_{\bar{\alpha}} = U_{\bar{\alpha}}^{\bar{\beta}} X_{\bar{\beta}}.$$

The condition (1.7) then singles out a unique transversal X to H(M).

Our admissible coframes are now those  $(\theta, \theta^{\alpha}, \theta^{\alpha})$  for which (1.7) holds. We allow  $g_{\alpha\beta}$  to be variable. Let P be the bundle of such coframes with structure group GL(n, C). On P we have globally defined functions  $g_{\alpha\beta}$  given locally by (1.5) and globally defined complex one-forms  $\theta^{\alpha}$ ,  $\theta^{\alpha}$  defined by (1.8), where now the  $U_{\beta}^{\alpha}$  are independent fibre coordinates on P. We also have the real one-form  $\theta$  pulled up to P and can view (1.7) as an equation on P. Since the real dimension of P is  $2n^2 + 2n + 1$ , we must find  $2n^2$  more independent, intrinsically defined one-forms on P.

We first differentiate (1.8) and see that locally

$$(1.12) d\theta^{\alpha} = \theta^{\beta} \wedge (-U^{-1}_{\beta}{}^{\gamma}dU_{\gamma}{}^{\alpha}) + d\theta'{}^{\beta}U_{\beta}{}^{\alpha}.$$

Because of the integrability condition (1.2) for  $\theta$ ,  $\theta'^{\alpha}$ , we have

$$(1.13) d\theta'^{\beta} U_{\beta}{}^{\alpha} = \theta^{\beta} \wedge \xi_{\beta}{}^{\alpha} + \theta \wedge \xi^{\alpha}$$

for some one-forms  $\xi_{\beta}^{\alpha}$ ,  $\xi^{\alpha}$  satisfying

(1.14) 
$$\xi_{\theta}^{\alpha} \equiv \xi^{\alpha} \equiv 0 , \quad \mod \theta, \theta^{r}, \theta^{\bar{r}} .$$

It follows from (1.12), (1.13), (1.14), and Cartan's lemma that the most general such expression of type (1.12) is

$$(1.15) d\theta^{\alpha} = \theta^{\beta} \wedge \omega_{\beta}^{\alpha} + \theta \wedge \tau^{\alpha},$$

where  $\omega_{\beta}^{\alpha}$  and  $\tau^{\alpha}$  are one-forms satisfying

(1.16) 
$$\omega_{\beta}^{\alpha} \equiv -U^{-1}_{\beta}{}^{r}dU_{r}^{\alpha}, \quad \text{mod } \theta, \theta^{r}, \theta^{\bar{r}},$$

(1.17) 
$$\tau^{\alpha} \equiv 0 , \quad \operatorname{mod} \theta, \theta^{r}, \theta^{\tilde{r}} .$$

From the form of (1.15) we see that we may require

$$\tau^{\alpha} \equiv 0 , \quad \mod \theta^{\bar{r}} .$$

Now the  $\omega_{\beta}^{\alpha}$  are determined up to a transformation of the form

$$(1.19) \omega_{\beta}{}^{\alpha} = \tilde{\omega}_{\beta}{}^{\alpha} + C_{\beta}{}^{\alpha}{}_{,}\omega^{r}, C_{\beta}{}^{\alpha}{}_{,r} = C_{r}{}^{\alpha}{}_{\beta},$$

and the  $\tau^{\alpha}$  are completely determined. The condition (1.18) allows us to put

(1.20) 
$$\tau_{\alpha} = A_{\alpha \gamma} \theta^{\gamma} .$$

Now we differentiate (1.7), using (1.15), to get

$$(1.21) \ \ 0 = i(dg_{\alpha\bar{\beta}} - \omega_{\alpha}{}^{\gamma}g_{\gamma\bar{\beta}} - g_{\alpha\bar{\gamma}}\omega_{\bar{\beta}}{}^{\bar{\gamma}}) \wedge \theta^{\alpha} \wedge \theta^{\bar{\beta}} + i\theta \wedge (\tau_{\bar{\alpha}} \wedge \theta^{\bar{\alpha}} + \theta^{\alpha} \wedge \tau_{\alpha}) \ .$$

With (1.20) substituted into (1.21), we see that

$$(1.22) dg_{\alpha\bar{\delta}} - \omega_{\alpha\bar{\delta}} - \omega_{\bar{\delta}\alpha} = A_{\alpha\bar{\delta}r}\theta^r + B_{\alpha\bar{\delta}\bar{r}}\theta^{\bar{r}},$$

where

$$A_{\alpha\bar{\beta}r} = A_{r\bar{\beta}\alpha}$$
,  $B_{\alpha\bar{\beta}\bar{r}} = B_{\alpha\bar{r}\bar{\beta}}$ ,

and that

(1.23) 
$$\tau_{\alpha} \wedge \theta^{\alpha} = 0 , \quad \text{or } A_{\alpha x} = A_{x\alpha} .$$

The hermitian condition (1.4) implies

$$B_{\alpha\bar{\beta}\bar{\tau}}=A_{\bar{\beta}\alpha\bar{\tau}}$$
.

It therefore follows that the change

$$(1.23a) \omega_{\beta\alpha} \to \omega_{\beta\alpha} + A_{\beta\alpha\gamma}\theta^{\gamma}$$

is of the form (1.19) and reduces (1.22) to

$$dg_{\alpha\bar{\beta}} - \omega_{\alpha}{}^{\bar{\gamma}}g_{\gamma\bar{\beta}} - g_{\alpha\bar{\gamma}}\omega_{\bar{\beta}}{}^{\bar{\gamma}} = 0.$$

The condition (1.24) for both  $\omega_{\beta}^{\alpha}$  and  $\tilde{\omega}_{\beta}^{\alpha}$  implies that  $C_{\beta}^{\alpha}{}_{\gamma} = 0$  in (1.19), so that the  $\omega_{\beta}^{\alpha}$  are uniquely determined. We have derived the following theorem.

**Theorem (1.1).** Let  $(M, \theta)$  be a nondegenerate, integrable pseudohermitian manifold. Then in the bundle P over M described above there is an intrinsic basis of one-forms

$$\{\theta, \theta^{\alpha}, \theta^{\bar{\alpha}}, \omega_{\beta}{}^{\alpha}, \omega_{\bar{\beta}}{}^{\bar{\alpha}}\}$$
,

one-forms  $\tau^{\alpha}$ , and functions  $g_{\alpha\beta}$  satisfying (1.7), (1.15), (1.18), and (1.24). We also have the relations (1.20) and (1.23).

Now that the one-forms  $\omega_{\beta}^{\alpha}$  are determined, we want to compute their exterior derivatives. If we differentiate (1.15) and make use of (1.7) and (1.15) itself, we get

$$(1.25) \ \ 0 = \theta^{\beta} \wedge \{d\omega_{\beta}{}^{\alpha} - \omega_{\beta}{}^{\gamma} \wedge \omega_{\gamma}{}^{\alpha} - i\theta_{\beta} \wedge \tau^{\alpha}\} + \theta \wedge \{d\tau^{\alpha} - \tau^{\beta} \wedge \omega_{\beta}{}^{\alpha}\}.$$

Next, we differentiate (1.24) to get

$$(1.26) 0 = (d\omega_{\alpha}{}^{r} - \omega_{\alpha}{}^{\mu} \wedge \omega_{\alpha}{}^{r})g_{r\bar{b}} + g_{\alpha\bar{t}}(d\omega_{\bar{b}}{}^{\bar{t}} - \omega_{\bar{b}}{}^{\bar{\mu}} \wedge \omega_{\bar{a}}{}^{\bar{t}}).$$

Therefore, if we put

$$\Omega_{\beta}^{\alpha} = d\omega_{\beta}^{\alpha} - \omega_{\beta}^{\tau} \wedge \omega_{r}^{\alpha} - i\theta_{\beta} \wedge \tau^{\alpha} + i\tau_{\beta} \wedge \theta^{\alpha},$$

$$\Omega^{\alpha} = d\tau^{\alpha} - \tau^{\beta} \wedge \omega_{\beta}^{\alpha},$$

then we get from (1.25), noting (1.23),

$$(1.29) 0 = \theta^{\beta} \wedge \Omega_{\beta}{}^{\alpha} + \theta \wedge \Omega^{\alpha}.$$

From (1.26) it follows that

$$(1.30) 0 = \Omega_{\beta}{}^{r}g_{r\alpha} + g_{\beta\bar{r}}\Omega_{\alpha}{}^{\bar{r}} \equiv \Omega_{\beta\alpha} + \Omega_{\alpha\beta}.$$

For future use we can, via (1.24), write (1.28) as

$$\Omega_{\alpha} = d\tau_{\alpha} - \omega_{\alpha}{}^{\beta} \wedge \tau_{\beta} .$$

(1.29) implies that

$$\Omega_{\beta\alpha} = \chi_{\beta\alpha\rho} \wedge \theta^{\rho} + \lambda_{\beta\alpha} \wedge \theta$$

for certain one-forms  $\chi_{\beta\alpha\rho}$  and  $\lambda_{\beta\alpha}$ , which we may assume contain no terms in  $\theta$ . From (1.30) and (1.32) we have

$$0 = \chi_{\beta\bar{\alpha}\rho} \wedge \theta^{\rho} + \chi_{\bar{\alpha}\beta\bar{\sigma}} \wedge \theta^{\bar{\sigma}} + (\lambda_{\beta\bar{\alpha}} + \lambda_{\bar{\alpha}\beta}) \wedge \theta ,$$

which implies

$$\chi_{etaar{lpha}
ho}=B_{etaar{lpha}
ho_{T}} heta^{r}-R_{etaar{lpha}
hoar{\sigma}} heta^{ar{\sigma}}$$
 ,

where

$$B_{etaar{lpha}
ho\gamma}=B_{etaar{lpha}\gamma
ho}$$
 ,

$$R_{\beta\bar{\alpha}\rho\bar{\sigma}} = \bar{R}_{\alpha\bar{\beta}\bar{\sigma}\rho} = R_{\alpha\bar{\beta}\bar{\sigma}\rho} ,$$

and furthermore

$$\lambda_{\beta\alpha} + \lambda_{\alpha\beta} = 0.$$

Thus we have

$$\Omega_{\beta\bar{a}} = R_{\beta\bar{a}\sigma\bar{b}}\theta^{\rho} \wedge \theta^{\bar{\sigma}} + \lambda_{\beta\bar{a}} \wedge \theta ,$$

which, substituted into (1.29), gives

(1.36) 
$$R_{\beta\bar{\alpha}\rho\bar{\sigma}} = R_{\rho\bar{\alpha}\beta\bar{\sigma}} \; ,$$
 
$$0 = \theta \wedge (\theta^{\beta} \wedge \lambda_{\beta}^{\alpha} + \Omega^{\alpha}) \; .$$

This last condition implies that

$$\Omega^{\alpha} = -\theta^{\beta} \wedge \lambda_{\beta}^{\alpha} + \mu^{\alpha} \wedge \theta ,$$

in which  $\mu^{\alpha}$  is some one-form, which we assume to have no  $\theta$ -term. Now we differentiate (1.23) using (1.31) and (1.15). It follows that

$$(1.38) 0 = \Omega^{\alpha} \wedge \theta_{\alpha} + \theta \wedge \tau^{\alpha} \wedge \tau_{\alpha}.$$

Putting (1.37) into (1.38) gives

$$(1.39) 0 = \lambda_{\beta\alpha} \wedge \theta^{\beta} \wedge \theta^{\alpha} + \theta \wedge (\tau^{\alpha} \wedge \tau_{\alpha} - \mu_{\alpha} \wedge \theta^{\alpha}).$$

Since  $\lambda_{\rho\alpha}$  was chosen to have no  $\theta$ -term, (1.39) implies that

$$\lambda_{\scriptscriptstyleetaar{lpha}}=\,W_{\scriptscriptstyleetaar{lpha} au} heta^{\scriptscriptstylear{\gamma}}+\,N_{\scriptscriptstyleetaar{lpha}ar{ar{\gamma}}} heta^{\scriptscriptstylear{\gamma}}$$
 ,

where

$$(1.40) W_{\beta \bar{\alpha}_{T}} = W_{r\bar{\alpha}\bar{\beta}} ,$$

and, because of (1.34),

$$N_{{\scriptscriptstyle eta}{\scriptscriptstyle ar{r}}} = -W_{{\scriptscriptstyle ar{lpha}}{\scriptscriptstyle ar{r}}}$$
 ,

We can now put

$$(1.41) \Omega_{\beta}{}^{\alpha} = R_{\beta}{}^{\alpha}{}_{\sigma\bar{\sigma}}\theta^{\rho} \wedge \theta^{\bar{\sigma}} + W_{\beta}{}^{\alpha}{}_{\sigma}\theta^{\rho} \wedge \theta - W_{\beta\bar{\sigma}}^{\alpha}\theta^{\bar{\sigma}} \wedge \theta ,$$

and the exterior derivatives  $d\omega_{\beta}^{\alpha}$  are determined.

(1.39) and the expression (1.20) for  $\tau_{\alpha}$  also imply

$$0 = \theta \wedge \theta^{\beta} \wedge (A_{\beta r} \tau^r + \mu_{\beta}),$$

so that

$$\mu_{\scriptscriptstyle eta} = -A_{\scriptscriptstyle eta r} au^{\scriptscriptstyle 
m r} + B_{\scriptscriptstyle eta r} heta^{\scriptscriptstyle 
m r} \; ,$$

where

$$(1.42) B_{\beta r} = B_{r\beta} .$$

Finally, (1.37) becomes

$$\Omega^{\alpha} = W^{\alpha}_{\phantom{\alpha}\bar{\rho}}\theta^{\rho} \wedge \theta^{\bar{\sigma}} - A^{\alpha}_{\phantom{\alpha}\bar{\tau}}\tau^{\bar{\tau}} \wedge \theta + B^{\alpha}_{\phantom{\alpha}\bar{\sigma}}\theta^{\bar{\sigma}} \wedge \theta ,$$

and we have also determined the derivatives  $d\tau^{\alpha}$ .

We sum these results up in the following:

**Theorem (1.1a).** The exterior derivatives of the forms  $\omega_{\beta}^{\alpha}$  and  $\tau^{\alpha}$  of Theorem (1.1) are given by (1.27) and (1.28), respectively, where  $\Omega_{\beta}^{\alpha}$  and  $\Omega^{\alpha}$  are given by (1.41) and (1.43), respectively. The coefficients satisfy (1.33), (1.36), (1.40), and (1.42).

The existence of the invariant forms  $\omega_{\beta}^{\alpha}$  on the bundle P with structure group reduced to U(p, q) gives the following.

**Theorem (1.2).** The group  $PsH(M, \theta)$  of all pseudo-hermitian transformations of the pseudo-hermitian space  $(M, \theta)$  of dimension 2n + 1 is a Lie transformation group of dimension not exceeding  $(n + 1)^2$ , with isotropy subgroups of dimension not exceeding  $n^2$ . If M is strongly pseudo-covex, then the isotropy groups are compact, and  $PsH(M, \theta)$  is compact for compact M.

#### 2. Geometric interpretation

We shall interpret the  $\omega_{\beta}^{\alpha}$  of Theorem (1.1) as connection forms of a connection on the complex vector bundle H(M). If we choose local forms  $\theta'^{\alpha}$  on M, then according to (1.8) and (1.16) we can put

$$(2.1) U_{\beta}{}^{\gamma}\omega_{r}{}^{\alpha} + dU_{\beta}{}^{\alpha} = \omega'_{\beta}{}^{r}U_{r}{}^{\alpha},$$

where

$$\omega'_{\beta}^{r} \equiv 0$$
,  $\mod \theta, \theta'^{\alpha}, \theta'^{\bar{\alpha}}$ .

In the usual manner [3] we see that the coefficients of the  $\omega'_{\beta}^{r}$  are independent of  $U_{\alpha}^{\sigma}$  by differentiating (2.1). Using (2.1) to eliminate  $dU_{\beta}^{\alpha}$  we get

$$(2.2) U_{\alpha}^{\gamma}(d\omega_{r}^{\beta} - \omega_{r}^{\rho} \wedge \omega_{\rho}^{\beta}) = (d\omega_{\alpha}^{\prime \gamma} - \omega_{\alpha}^{\prime \rho} \wedge \omega_{\rho}^{\prime \gamma})U_{r}^{\beta}.$$

By (1.27) and (1.41) we see that the left hand side of (2.2) is a two-form in  $\theta$ ,  $\theta^{\alpha}$ ,  $\theta^{\alpha}$ , therefore so is  $d\omega'_{\alpha}{}^{r}$ , and so  $\omega'_{\beta}{}^{\alpha}$  is a one-form on M.

Now we consider  $\theta^{\alpha}$ , as well as  $\theta'^{\alpha}$ , as local one-forms on M and (1.8) as a change of coframe. Let  $(X, X_{\alpha}, X_{\bar{\alpha}})$  be the dual frame to  $(\theta, \theta^{\alpha}, \theta^{\bar{\alpha}})$ , and let  $V = U^{-1}$ ; then

$$(2.3) X_{\alpha} = V_{\alpha}{}^{\beta}X'_{\beta} .$$

Define an operator D locally by

(2.4) 
$$DX_{\alpha} = \omega_{\alpha}^{\beta} X_{\beta}$$
,  $D: \Gamma(H(M)) \to \Gamma(T^*(M) \otimes H(M))$ .

Under the change (2.3) we get from (2.1)

$$(2.5) \omega_{\beta}{}^{r}V_{r}{}^{\alpha} = dV_{\beta}{}^{\alpha} + V_{\beta}{}^{r}\omega_{r}{}^{\alpha} ;$$

hence, (2.4) defines a connection on H(M).

We can define an hermitian metric (, -) in the fibres of H(M) by

$$(2.6) (X_{\alpha}, \overline{X}_{\delta}) = g_{\alpha\delta}.$$

The condition (1.24) yields that D is a metric connection.  $\tau^{\alpha}$  in (1.15) can be viewed as a kind of torsion. The condition (1.18) on  $\tau^{\alpha}$  is analogous to the requirement in hermitian geometry that the torsion form be of a given type (i.e., of type (2, 0)) [5].

With these interpretations we can restate Theorem (1.1) as

**Theorem (2.1).** Let  $(M, \theta)$  be a nondegenerate, integrable pseudo-hermitian manifold. Then there are a unique hermitian metric (2.6) determined by the Levi form and a unique metric connection D on H(M) with torsion form satisfying

$$\tau^{\alpha} \equiv 0, \mod \theta^{\bar{r}}.$$

Under the change (1.8) (or (2.3)) we have

$$\theta'_{\beta} = U_{\beta}{}^{\alpha}\theta_{\alpha} ,$$

(2.8) 
$$\tau'^{\beta}U_{\beta}{}^{\alpha}=\tau^{\alpha}, \qquad \tau'_{\beta}=U_{\beta}{}^{\alpha}\tau_{\alpha}.$$

By (2.2) the curvature matrix of  $\omega_{\beta}^{\alpha}$ ,

$$(2.9) \Pi_{\beta}{}^{\alpha} = d\omega_{\beta}{}^{\alpha} - \omega_{\beta}{}^{\tau} \wedge \omega_{\tau}{}^{\alpha} = \Omega_{\beta}{}^{\alpha} + i\theta_{\beta} \wedge \tau^{\alpha} - i\tau_{\beta} \wedge \theta^{\alpha},$$

transforms by

$$(2.10) U_{\alpha}^{\phantom{\alpha}\gamma} \Pi_{\gamma}^{\phantom{\gamma}\beta} = \Pi'_{\phantom{\alpha}\gamma}^{\phantom{\alpha}\gamma} U_{\gamma}^{\phantom{\gamma}\beta} .$$

We also have

$$(2.11) U_{\alpha}^{\ \gamma} \Omega_{r}^{\ \beta} = \Omega'_{\alpha}^{\ \gamma} U_{r}^{\ \beta} \ .$$

The two curvature matrices are equal when the torsion  $\tau^{\alpha}$  vanishes.

The vanishing of the torsion has a more geometric interpretation. Let  $L_X$  be Lie derivation by the transversal X to H(M). By the standard formula

$$L_X = \iota_X^{\circ} d + d^{\circ} \iota_X ,$$

(1.7) and (1.15) imply

(2.12) 
$$L_X \theta = 0$$
,  $L_X \theta^{\alpha} = -\phi_{\beta}^{\alpha}(X)\theta^{\beta} - \tau^{\alpha}(X)\theta + \tau^{\alpha}$ .

So if  $\tau^{\alpha} = 0$ , then X is an infinitesimal pseudo-conformal transformation.

Conversely, given a transverse infinitesimal pseudo-conformal transformation X, complete it to a basis by choosing  $X_{\alpha}$ . On the dual coframe we have

(2.13) 
$$L_X \theta = u \theta , \qquad L_X \theta^{\alpha} = \theta^{\beta} U_{\beta}^{\alpha} + \theta v^{\alpha} .$$

From (1.3) it follows that

$$L_X\theta = \eta_\alpha\theta^\alpha + \eta_\sigma\theta^\alpha$$
;

hence  $\eta_{\alpha} = u = 0$ , and we have an admissible coframe with respect to  $\theta$ . From (2.12) we see that  $\tau^{\alpha} = 0$ .

Hence we have shown

**Proposition (2.2).** The torsion  $\tau^{\alpha}$  vanishes if and only if the transversal X determined by  $\theta$  is an infinitesimal pseudo-conformal transformation.

Proposition 2.2 gives the condition required by Tanaka in [9].

Using the curvature tensor  $R_{\beta\alpha\rho\bar{\sigma}}$  in (1.41), we can define a kind of curvature for holomorphic plane sections in H(M) as follows: if

$$(2.14) Z = \xi^{\alpha} X_{\alpha} ,$$

then

$$(2.15) K(Z) = -\frac{1}{2} (R_{\beta \bar{\alpha} \rho \bar{\gamma}} \xi^{\beta} \xi^{\bar{\alpha}} \xi^{\rho} \xi^{\bar{\nu}}) / (g_{\alpha \bar{\beta}} \xi^{\alpha} \xi^{\bar{\beta}})^{2}.$$

The coefficient  $-\frac{1}{2}$  makes the unit hypersphere in  $\mathbb{C}^{n+1}$  have constant curvature +1 (see § 4). We also define the Ricci tensor

$$(2.16) R_{a\bar{a}} = R_{\alpha a\bar{a}}^{\alpha}$$

and the scalar curvature

$$(2.17) R = g^{\rho \bar{\sigma}} R_{\rho \bar{\sigma}}.$$

Finally, we can define a Riemannian metric on T(M) by

(2.18) 
$$ds^{2} = \theta \otimes \theta - \operatorname{Re} \left( g_{\alpha\beta} \theta^{\alpha} \otimes \theta^{\beta} \right) \\ = \theta \otimes \theta - \frac{1}{2} \left( g_{\alpha\beta} \theta^{\alpha} \otimes \theta^{\beta} + g_{\alpha\beta} \theta^{\alpha} \otimes \theta^{\beta} \right).$$

This metric is invariant under a pseudo-hermitian transformation.

### 3. Relation to pseudo-conformal invariants

The object of this section is to derive pseudo-conformal invariants from the curvature tensors introducted in part one. To do this we start with a local coframe field

(3.1) 
$$\omega = \theta$$
,  $\omega^{\alpha} = \theta^{\alpha}$ ,  $\omega^{\bar{\alpha}} = \theta^{\bar{\alpha}}$ 

adapted to the particular choice of  $\theta$ . We then try to find local forms  $\phi_{\beta}^{\alpha}$ ,  $\phi^{\alpha}$ , and  $\psi$  which will satisfy the structure equations [6, (A.1)–(A.6), p. 269] and [6, (4.21), p. 253]. Note that with our normalization

$$\phi = 0.$$

Because of (3.2), (1.15), (1.23), and (1.24) the choice

$$\phi_{\scriptscriptstyleeta}^{\;\;lpha}=\omega_{\scriptscriptstyleeta}^{\;\;lpha}\;,\;\;\phi^{\scriptscriptstylelpha}= au^{\scriptscriptstylelpha}\;,\;\;\psi=0$$

satisfies [6, (A.1), (A.2), (A.3), and (4.21)]. The transformation [6, (4.35)] indicates that we should try

$$\phi_{\beta}{}^{\alpha} = \omega_{\beta}{}^{\alpha} + D_{\beta}{}^{\alpha}\theta , \quad \phi^{\alpha} = \tau^{\alpha} + D_{\gamma}{}^{\alpha}\theta^{\gamma} , \quad \psi = 0 ,$$

where

$$(3.4) D_{\beta\alpha} + D_{\alpha\beta} = 0.$$

By the procedure of [6, § 4] the  $D_{\beta x}$  are determined by requiring that the contraction of equation [6, (A.4)] be trivial, mod  $\theta$ . Substituting (3.3) into this contracted equation gives

(3.5) 
$$\Phi_{\alpha}^{\ \alpha} \equiv \Omega_{\alpha}^{\ \alpha} + i(Dg_{\rho\bar{\sigma}} + (n+2)D_{\rho\bar{\sigma}})\theta^{\rho} \wedge \theta^{\bar{\sigma}} \\
\equiv (R_{\rho\bar{\sigma}} + i(Dg_{\rho\bar{\sigma}} + (n+2)D_{\rho\bar{\sigma}}))\theta^{\rho} \wedge \theta^{\bar{\sigma}}, \quad \text{mod } \theta,$$

where

$$D=D_{\alpha}{}^{\alpha}$$
,

and we have made use of (1.23), (1.27), and (1.41).

To make (3.5) vanish, mod  $\theta$ , we choose

(3.6) 
$$D_{\rho\bar{\sigma}} = \frac{i}{n+2} R_{\rho\bar{\sigma}} - \frac{i}{2(n+1)(n+2)} Rg_{\rho\bar{\sigma}}.$$

Then the  $\phi_{\beta}^{\alpha}$  in (3.3) is the intrinsic (pseudo-conformal) connection form. The substitution of (3.3) and (3.6) into [6, (A.4)] gives

(3.7) 
$$\Phi_{\beta}^{\alpha} \equiv \Omega_{\beta}^{\alpha} + i(D_{\beta}^{\alpha}g_{\rho\bar{\sigma}} + D_{\rho}^{\alpha}g_{\beta\bar{\sigma}} + \delta_{\beta}^{\alpha}D_{\rho\bar{\sigma}} + \delta_{\rho}^{\alpha}D_{\beta\bar{\sigma}})\theta^{\rho} \wedge \theta^{\bar{\sigma}} \\
\equiv S_{\beta\rho}^{\alpha}{}_{\bar{\sigma}}^{\alpha}\theta^{\rho} \wedge \theta^{\bar{\sigma}}, \quad \text{mod } \theta.$$

It now follows that Chern's pseudo-conformal curvature tensor is given by

$$(3.8) S_{\beta\rho}{}^{\alpha}{}_{\bar{\sigma}} = R_{\beta}{}^{\alpha}{}_{\rho\bar{\sigma}} - \frac{1}{n+2} (R_{\beta}{}^{\alpha}g_{\rho\bar{\sigma}} + R_{\rho}{}^{\alpha}g_{\beta\bar{\sigma}} + \delta_{\beta}{}^{\alpha}R_{\rho\bar{\sigma}} + \delta_{\rho}{}^{\alpha}R_{\beta\bar{\sigma}}) + \frac{R}{(n+1)(n+2)} (\delta_{\beta}{}^{\alpha}g_{\rho\bar{\sigma}} + \delta_{\rho}{}^{\alpha}g_{\beta\bar{\sigma}}) .$$

Formula (3.8) is similar to H. Weyl's formula for the conformal curvature tensor of a Riemannian manifold (see [7]). The trace of S with respect to  $\beta$  and  $\alpha$  is zero, so S vanishes identically when n = 1. When n > 1, S vanishes if and only if M is locally equivalent to the real hypersphere in  $C^{n+1}$  (see [6] and [10]). Formula (3.8) will be used to compute S for specific hypersurfaces in the next section.

We could continue the procedure of [6] to determine further relations, however, when n > 1, the Bianchi identities [6] can be used to show that all higher order invariants are obtained from S by covariant differentation with respect to the pseudo-conformal connection [10]. It can then be shown, with the aid of (3.2), (3.3), (3.6), and (3.8), that these invariants can be expressed in terms of the curvatures of  $(M, \theta)$  and their covariant derivatives with respect to the connection  $\omega_{\beta}^{\alpha}$ . Such expressions will be valid only with respect to coframes satisfying (3.2).

As a system of local functions on M, S transforms tensorially (explicit details are in [10]). Under the structure group (4.1) of [6] we have the changes

$$(3.9) \qquad \tilde{\theta} = u\theta \;, \quad ug_{\alpha\bar{\beta}} = \tilde{g}_{\rho\bar{\sigma}}U_{\alpha}{}^{\rho}U_{\bar{\beta}}{}^{\bar{\sigma}} \;, \quad S_{\beta\rho\bar{\alpha}\bar{\sigma}} = \tilde{S}_{\mu\nu\bar{\tau}\bar{\epsilon}}U_{\beta}{}^{\mu}U_{\rho}{}^{\nu}U_{\bar{\alpha}}{}^{\bar{\tau}}U_{\bar{\epsilon}}{}^{\bar{\epsilon}} \;.$$

If we define the norm of S with respect to  $\theta$  by

(3.10) 
$$||S||_{\theta}^{2} = g^{\alpha\bar{\beta}} g^{\rho\bar{\sigma}} g_{\gamma\bar{\mu}} g^{\nu\bar{\epsilon}} S_{\alpha\bar{\rho}\bar{\epsilon}} S_{\bar{\beta}\bar{\sigma}\bar{\mu}},$$

then (3.9) gives

$$||S||_{\theta} = |u| ||S||_{\tilde{\theta}}.$$

If M is strongly pseudo-convex, for example, we can restrict to changes (3.9) with u > 0. If, in addition, S does not vanish (3.11) shows that we can choose a unique  $\theta^*$  with respect to which S has norm one. This  $\theta^*$  and all the invariants of  $(M, \theta^*)$  are intrinsic to the C-R structure of M. In particular, the corresponding transversal X (1.10) and its integral curves are intrinsic to M. The latter are called principal curves [2].

Let N be a Kähler manifold with Kähler form  $\chi$ . Each point of N has a neighborhood U, with holomorphic coordinate vector Z, on which there is a positive function h satisfying

$$\chi = i\bar{\partial}\partial \log h .$$

On  $U \times C$  define

$$r = h(Z, \overline{Z})w\overline{w} - 1$$
,  $Z \in U$ ,  $w \in C$ ,

and let M be the real hypersurface on which r vanishes. Then  $\chi$  is also the Levi form of  $(M, \theta = i\partial r)$ . It is easily seen that the torsion  $\tau^{\alpha}$  vanishes, and that  $R_{\beta\alpha\rho\overline{\tau}}$  is also the curvature tensor of the Kähler metric associated to  $\chi$ .  $S_{\beta\rho}{}^{\alpha}{}_{\overline{\tau}}$  is then the same tensor defined by Bochner [1].

## 4. The curvature for real hypersurfaces in $C^{n+1}$ , spaces of constant curvature, & ellipsoids

In this section we will give a procedure for computing the torsion and curvature tensors for a real hypersurface  $(M, \theta)$  in  $C^{n+1}$  defined as the zero set of a given real valued function r.

We have coordinates

$$Z = (z^1, \dots, z^n), \qquad w = z^{n+1},$$

and, for the applications we have in mind, will assume that the Z and w variables are separated in r, i.e.,

$$(4.1) r(Z, w, \overline{Z}, \overline{w}) = p(Z, \overline{Z}) + q(w, \overline{w}),$$

p and q being real valued. We choose the one-form

(4.2) 
$$\theta = i\partial r = i(p_{\alpha}dz^{\alpha} + q_{w}dw).$$

Throughout we shall use the abbreviations

$$p_{\alpha} = \partial p/\partial z^{\alpha}$$
,  $q_{w} = \partial q/\partial w$ , etc.

Then we have

$$(4.3) \quad d\theta = i\bar{\partial}\partial r = ig_{\alpha\bar{\beta}}dz^{\alpha} \wedge dz^{\bar{\beta}} + \eta_{\alpha}dz^{\alpha} \wedge \theta + \eta_{\bar{\alpha}}dz^{\alpha} \wedge \theta = ig_{\alpha\bar{\beta}}\theta^{\alpha} \wedge \theta^{\bar{\beta}},$$

where

$$(4.4) g_{\alpha\bar{\beta}} = -p_{\alpha\bar{\beta}} - Qp_{\alpha}p_{\bar{\beta}}, Q = (q_{w\bar{w}})/(q_{w}q_{\bar{w}}),$$

$$\eta_{\alpha} = -Qp_{\alpha} , \qquad \eta^{\alpha} = g^{\alpha \bar{r}} \eta_{\bar{r}} ,$$

$$\theta^{\alpha} = dz^{\alpha} + i\eta^{\alpha}\theta.$$

The coframe  $(\theta, \theta^{\alpha}, \theta^{\bar{\alpha}})$  is admissible for  $(M, \theta)$ . Our computation will be valid where  $q_{\bar{w}} \neq 0$ . The dual frame, characterized by

$$(4.7) df = Xf\theta + X_{\alpha}f\theta^{\alpha} + X_{\alpha}f\theta^{\alpha}$$

for any function f on M, is given by

(4.8) 
$$X = -i\eta^{\alpha}(\partial/\partial z^{\alpha}) + i\eta^{\alpha}(\partial/\partial z^{\alpha}) - i(1 - p_{\mu}\eta^{\mu})(q_{w})^{-1}(\partial/\partial w) + i(1 - p_{\mu}\eta^{\mu})(q_{w})^{-1}(\partial/\partial \overline{w}),$$

(4.9) 
$$X_{\alpha} = (\partial/\partial z^{\alpha}) - p_{\alpha}(q_{w})^{-1}(\partial/\partial w) , \qquad X_{\bar{\alpha}} = \overline{X_{\alpha}} .$$

We first compute the connection and torsion forms  $\omega_{\beta\alpha}$ ,  $\tau_{\alpha}$ . Differentiating (4.6) gives

$$d\theta^{\alpha} = \theta^{\beta} \wedge (-\eta^{\alpha}\theta_{\beta} + iX_{\beta}\eta^{\alpha}\theta) + \theta \wedge (-iX_{\bar{\gamma}}\eta^{\alpha}\theta^{\bar{\gamma}}) = \theta^{\beta} \wedge \omega'_{\beta}{}^{\alpha} + \theta \wedge \tau^{\alpha}.$$

Next, we compute

$$dg_{\beta\bar{\alpha}} - \omega'_{\beta\bar{\alpha}} - \omega'_{\bar{\alpha}\bar{\beta}} = (X_r g_{\beta\bar{\alpha}} + \eta_{\beta} g_{r\bar{\alpha}})\theta^r + (X_{\bar{r}} g_{\beta\bar{\alpha}} + \eta_{\bar{\alpha}} g_{\beta\bar{r}})\theta^{\bar{r}},$$

where the  $\theta$ -term vanishes by (1.22). Therefore the change (1.23a) yields

$$\omega_{\beta\bar{\alpha}} = B_{\beta\bar{\alpha}r}\theta^r + C_{\beta\bar{\alpha}\bar{r}}\theta^{\bar{r}} + E_{\beta\bar{r}}\theta,$$

where

$$(4.11) B_{\beta\bar{\alpha}\gamma} = X_r g_{\beta\bar{\alpha}} + \eta_{\beta} g_{\bar{\alpha}\gamma} , C_{\beta\bar{\alpha}\bar{\gamma}} = -\eta_{\bar{\alpha}} g_{\beta\bar{\gamma}} , E_{\beta\bar{\alpha}} = i g_{\bar{\alpha}\gamma} X_{\bar{\beta}} \gamma^{\bar{\gamma}} .$$

Also, the torsion form is

$$\tau_{\alpha} = A_{\alpha \gamma} \theta^{\gamma} ,$$

where

$$(4.13) A_{\alpha r} = i g_{\alpha \bar{\mu}} X_r \eta^{\bar{\mu}} = i X_r \eta_{\alpha} - i \eta^{\bar{\mu}} X_r g_{\alpha \bar{\mu}}.$$

To find the curvature tensor  $R_{\beta\bar{\alpha}\rho\bar{\sigma}}$ , we substitute (4.10) and (4.12) into

$$\Omega_{\scriptscriptstyle eta ar{a}} = d\omega_{\scriptscriptstyle eta ar{a}} - \omega_{\scriptscriptstyle ar{a} r} \wedge \omega_{\scriptscriptstyle ar{a}}^{\; r} - i\theta_{\scriptscriptstyle eta} \wedge au_{\scriptscriptstyle ar{a}} + i au_{\scriptscriptstyle ar{a}} \wedge \theta_{\scriptscriptstyle ar{a}} \; ,$$

and compute mod  $\theta$ . We need to consider only the  $\theta^{\rho} \wedge \theta^{\bar{\theta}}$ -term. The coefficient of this term is

$$(4.14) R_{\beta\bar{\alpha}\rho\bar{\sigma}} = -X_{\bar{\sigma}}B_{\beta\bar{\alpha}\rho} + X_{\rho}C_{\beta\bar{\alpha}\bar{\sigma}} + B_{\beta}{}^{r}{}_{\rho}B_{\alpha\bar{r}\bar{\sigma}} + B_{\beta\bar{\alpha}\bar{r}}C_{\rho}{}^{r}{}_{\bar{\sigma}} \\ - C_{\beta\bar{\alpha}\bar{r}}C_{\bar{\sigma}}{}^{\bar{\tau}}{}_{\rho} - C_{\beta}{}^{r}{}_{\bar{\sigma}}C_{\alpha\bar{r}\rho} + iE_{\beta\bar{\alpha}}g_{\rho\bar{\sigma}}.$$

If we substitute (4.11) into (4.14) we get

$$(4.15) R_{\beta\bar{\alpha}\rho\bar{\sigma}} = -X_{\bar{\sigma}}X_{\rho}g_{\beta\bar{\alpha}} + g^{\gamma\bar{\mu}}X_{\rho}g_{\beta\bar{\mu}} \cdot X_{\bar{\sigma}}g_{\alpha\gamma} + g_{\rho\bar{\sigma}}\eta^{\bar{\gamma}}X_{\beta}g_{\alpha\gamma} - g_{\rho\bar{\sigma}}\eta^{\bar{\gamma}}X_{\gamma}g_{\beta\bar{\alpha}} - g_{\bar{\alpha}\rho}X_{\bar{\sigma}}\eta_{\beta} - g_{\beta\bar{\sigma}}X_{\rho}\eta_{\bar{\alpha}} - g_{\rho\bar{\sigma}}X_{\beta}\eta_{\bar{\alpha}} - \eta_{\beta}\eta_{\bar{\alpha}}g_{\rho\bar{\sigma}} - \eta_{\gamma}\eta^{\bar{\gamma}}g_{\beta\bar{\sigma}}g_{\rho\bar{\alpha}}.$$

**Examples.** A. Spaces of constant curvature. We will consider here three examples in  $C^{n+1}$  which are locally equivalent in the pseudo-conformal sense but differ according to the choice (4.2) of  $\theta$ .

(4.16.1) 
$$Q_0: \quad r_0 = h_{\alpha\beta} z^{\alpha} z^{\beta} + \frac{i}{2} (w - \overline{w}) = 0.$$

$$(4.16.2) Q_{+}(c): r_{+} = h_{\alpha\bar{\beta}}z^{\alpha}z^{\bar{\beta}} + w\overline{w} = c.$$

(4.16.3) 
$$Q_{-}(c): r_{-} = h_{\alpha\bar{\beta}} z^{\alpha} z^{\bar{\beta}} - w\bar{w} = -c.$$

The constant c is positive, and  $h_{\alpha\beta}$  is a constant nonsingular hermitian matrix with signature p positive and q negative eigenvalues, p+q=n.

The transformation

$$(4.17) w = c/w', z^{\alpha} = \sqrt{c} z'^{\alpha}/w'$$

maps  $Q_{-}(c)$  onto  $Q_{+}(c)$  minus  $\{w=0\}$ . A transformation mapping  $Q_{0}$  onto  $Q_{+}(c)$  minus a point is given in [6]. However, these transformations do not preserve the one-forms  $\theta=i\partial r$ .

(1)  $Q_0$ . Let  $G_0$  be the group of  $(n+1) \times (n+1)$  matrices

(4.18) 
$$\begin{pmatrix} 1 & b^{\beta} & b \\ 0 & B_{\alpha}{}^{\beta} & b_{\alpha} \\ 0 & 0 & 1 \end{pmatrix},$$

where

(4.19) 
$$B_{\alpha}{}^{r}h_{r\rho}B_{\beta}{}^{\rho}=h_{\alpha\beta}$$
,  $b_{\alpha}=2iB_{\alpha}{}^{\rho}h_{\rho\bar{r}}b^{\bar{r}}$ ,  $0=\frac{i}{2}(b-\bar{b})+h_{\alpha\beta}b^{\alpha}b^{\beta}$ .

 $G_0$  acts on  $C^{n+1}$  by

$$\tilde{z}^{\alpha} = b^{\alpha} + z^{\beta} B_{\beta}^{\alpha} , \qquad \tilde{w} = b + z^{\beta} b_{\beta} + w ,$$

preserves the function  $r_0$  defining  $Q_0$ , and hence preserves  $\theta = i\partial r$ .

The isotropy group of (0,0) in  $Q_0$  is the unitary group U(p,q) of the hermitian form  $h_{\alpha\bar{\beta}}$ . It follows that  $Q_0$  is homogeneous,

$$(4.21) Q_0 = G_0/U(p,q).$$

If we choose as our coframe

$$\theta, \theta^{\alpha} = dz^{\alpha}, \, \theta^{\bar{\alpha}} = dz^{\bar{\alpha}}$$

then

$$d\theta = -ih_{\alpha\bar{\beta}}\theta^{\alpha} \wedge \theta^{\bar{\beta}}$$
,

and  $\omega_{\beta}^{\alpha} = \tau^{\alpha} = 0$  since  $d\theta^{\alpha} = 0$ . The curvature and torsion of  $(Q_0, \theta)$  vanish identically.

(2)  $Q_+(c)$ . The function  $r_+$  in (4.16.2) is an hermitian form of signature (p+1,q). The unitary group U(p+1,q) acts transitively on  $Q_+(c)$  and preserves  $\theta = i\partial r_+$ . The isotropy group at  $(Z=0, w=\sqrt{c})$  is U(p,q); hence

$$Q_{+}(c) = U(p+1,q)/U(p,q).$$

(3)  $Q_{-}(c)$ . The function  $r_{-}$  in (4.16.3) is an hermitian form of signature (p, q + 1),  $\theta = i\partial r$  is invariant under U(p, q + 1), and

$$(4.23) O_{-}(c) = U(p, q+1)/U(p, q).$$

Because  $Q_{+}(c)$  and  $Q_{-}(c)$  are homogeneous, it suffices to compute their curvature and torsion at a point where Z=0. From (4.13), (4.5), and (4.9) we see that  $A_{\alpha \gamma}$  vanishes when Z=0. Also, substituting (4.4) and (4.5) into (4.15), we see that, when Z=0,

$$R_{etalpha
hoar{\sigma}} = -rac{arepsilon}{c}(g_{etaar{lpha}}g_{
hoar{\sigma}} + g_{
hoar{lpha}}g_{etaar{\sigma}}) \ ,$$

where  $\varepsilon = +1$  for  $Q_+(c)$  and  $\varepsilon = -1$  for  $Q_-(c)$ . From the definition of sectional curvature (2.15), we have  $K \equiv 1/c$  for  $Q_+(c)$  and  $K \equiv -1/c$  for  $Q_-(c)$ .

 $Q_0$ ,  $Q_+(c)$ , and  $Q_-(c)$  each have a transformation group of dimension  $(n+1)^2$ . It is easily seen from (3.8) that the tensor  $S_{\beta\rho\alpha\bar{\nu}}$  vanishes identically in each case.

B. Ellipsoids. For a less trivial example we consider the general ellipsoid E in  $C^{n+1}$  defined by

(4.24) 
$$r = A_1(X^1)^2 + B_1(y^1)^2 + \cdots + A_n(x^n)^2 + B_n(y^n)^2 + A(u)^2 + B(v)^2 - 1 = 0,$$

where  $x^{\alpha} + iy^{\alpha} = z^{\alpha}$ , u + iv = w, and A,  $A_{\alpha}$ , B,  $B_{\alpha}$  are all positive constants. We rewrite this as

$$(4.25) r = \sum_{\alpha=1}^{n} (a_{\alpha}(z^{\alpha})^{2} + a_{\alpha}(z^{\alpha})^{2} + b_{\alpha}z^{\alpha}z^{\alpha}) + a(w^{2} + \overline{w}^{2}) + bw\overline{w} - 1 = 0 ,$$

where

(4.26) 
$$a = \frac{1}{4}(A - B), \quad a_{\alpha} = \frac{1}{4}(A_{\alpha} - B_{\alpha}), \\ b = \frac{1}{2}(A + B) > 0, \quad b_{\alpha} = \frac{1}{2}(A_{\alpha} + B_{\alpha}) > 0.$$

More generally, we take

$$(4.27) r = p(Z, \overline{Z}) + q(w, \overline{w}),$$

where

$$(4.27a) p = a_{\alpha\beta} z^{\alpha} z^{\beta} + a_{\alpha\bar{\beta}} z^{\alpha} z^{\bar{\beta}} + b_{\alpha\bar{\beta}} z^{\alpha} z^{\bar{\beta}},$$

$$(4.27b) q = aw^2 + \bar{a}\bar{w}^2 + bw\bar{w} - 1,$$

all the coefficients are constant,  $a_{\alpha\beta}$  is symmetric,  $b_{\alpha\beta}$  is positive definite hermitian, and b is positive.

We will compute the curvature tensor  $S_{\beta\rho\bar{\alpha}\bar{\sigma}}$  for E along the curve  $E\cap (Z=0)$  by computing  $R_{\beta\bar{\alpha}\rho\bar{\sigma}}$  and using (3.8). We let  $|_{0}$  denote evaluation at Z=0. We have

(4.28) 
$$p_{\alpha|_{0}} = 0 , \qquad q_{w|_{0}} \neq 0 , p_{\alpha\bar{\beta}} = b_{\alpha\bar{\beta}} , \qquad p_{\alpha r} = 2a_{\alpha r} .$$

This, together with the expressions (4.4) and (4.5), gives

(4.29) 
$$X_{\rho}g_{\beta\bar{\alpha}} = \frac{Q_{w}}{q_{w}}p_{\rho}p_{\beta}p_{\alpha} - Qp_{\beta}b_{\rho\bar{\alpha}} - 2Qa_{\beta\rho}p_{\bar{\alpha}} ,$$

$$-X_{\bar{\sigma}}|_{0}(X_{\rho}g_{\beta\bar{\alpha}}) = Q(b_{\beta\bar{\sigma}}b_{\rho\bar{\alpha}} + 4a_{\beta\rho}a_{\alpha\bar{\sigma}}) ,$$

$$X_{\rho}|_{0}(g_{\beta\bar{\alpha}}) = 0 , \qquad X_{\bar{\sigma}}|_{0}(\eta_{\beta}) = -Qb_{\beta\bar{\alpha}} .$$

Substituting (4.29) into (4.15) gives

$$(4.30) R_{\beta\bar{\alpha}\rho\bar{\sigma}}|_{0} = -Q(b_{\beta\bar{\alpha}}b_{\rho\bar{\sigma}} + b_{\rho\bar{\alpha}}b_{\beta\bar{\sigma}} - 4a_{\beta\rho}a_{\bar{\alpha}\bar{\sigma}}),$$

where  $Q = Q|_{0} \neq 0$ . Let  $b^{\delta \alpha}$  be the inverse matrix of  $b_{\delta \alpha}$ . Then

$$(4.31) R_{a\bar{a}}|_{0} = Q((n+1)b_{a\bar{a}} - 4b^{\mu\bar{\nu}}a_{\mu a}a_{\nu\bar{a}}),$$

$$(4.32) R|_{0} = -Q(n(n+1) - 4b^{\mu\bar{\nu}}b^{\epsilon\bar{\tau}}a_{\mu\epsilon}a_{\bar{\nu}\bar{\tau}}).$$

Now, if we put (4.30), (4.31), and (4.32) into (3.8) with the index  $\alpha$  lowered, we get, after simplification,

$$(4.33) S_{\beta\rho\bar{\alpha}\bar{\sigma}}|_{0} = 4Qb^{\mu\bar{\nu}}b^{\epsilon\bar{\tau}}a_{\mu\epsilon}a_{\nu\bar{\tau}}(b_{\beta\bar{\alpha}}b_{\rho\bar{\sigma}} + b_{\rho\bar{\alpha}}b_{\beta\bar{\sigma}})$$

$$+ 4Qa_{\beta\rho}a_{\alpha\bar{\sigma}} - \frac{4Q}{n+2}(b^{\mu\bar{\nu}}a_{\mu\beta}a_{\nu\bar{\alpha}}b_{\rho\bar{\sigma}} + b^{\mu\bar{\beta}}a_{\mu\rho}a_{\nu\bar{\alpha}}b_{\beta\bar{\sigma}} + b^{\mu\bar{\nu}}a_{\mu\rho}a_{\nu\bar{\sigma}}b_{\beta\bar{\sigma}} + b^{\mu\bar{\nu}}a_{\mu\beta}a_{\nu\bar{\sigma}}b_{\sigma\bar{\sigma}}).$$

Now let us assume we have the form (4.25)-(4.26). Then

$$(4.34) S_{\alpha\alpha\bar{\alpha}\bar{\alpha}}|_{0} = \frac{8Q}{(n+1)(n+2)} \left(\sum_{r=1}^{n} a_{r}^{2}/b_{r}^{2}\right) b_{\alpha}^{2} + 4Q \frac{n-2}{n+2} a_{\alpha}^{2}.$$

It follows that if n=1,  $S_{11\bar{1}\bar{1}}|_0=0$ , as expected. However, if  $n\geq 2$ , then  $S_{\alpha\alpha\bar{\alpha}\bar{\alpha}}|_0$  vanishes for some  $\alpha$  if and only if  $a_1=\cdots=a_n=0$ . Since we can relable our variables, say  $z^1\leftrightarrow w$ , we see that E has nonflat points if  $a\neq 0$ , or if  $a_0\neq 0$  for some  $\alpha$ . Hence

**Theorem (4.1).** Let  $n \ge 2$ . The ellipsoid E given by (4.24) is equivalent to the real hypersphere if and only if

$$A_1 = B_1, \cdots, A_n = B_n, A = B$$
.

In [8] Fefferman has shown that a biholomorphic map between two bounded strongly pseudo-convex domains with smooth boundaries extends smoothly to the boundaries. Theorem (4.1) then gives a necessary and sufficient condition for an ellipsoidal domain to be equivalent to the unit ball.

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