# QUADRATIC AND QUASI-QUADRATIC FUNCTIONALS

PETER ŠEMRL

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ABSTRACT. In this note we show how Jordan \*-derivations arise as a "measure" of the representability of quasi-quadratic functionals by sesquilinear ones. Our main result can be considered as an extension of the Jordan-von Neumann characterization of pre-Hilbert space.

# 1. INTRODUCTION

Let M be a module over a \*-ring R. A mapping  $S: M \times M \to R$  is called a sesquilinear functional if it is linear in the first argument and antilinear in the second argument:

(1) 
$$S(ax + by, z) = aS(x, z) + bS(y, z), \quad x, y, z \in M, a, b \in R,$$

(2) 
$$S(x, ay + bz) = S(x, y)a^* + S(x, z)b^*$$
,  $x, y, z \in M, a, b \in R$ 

In the special case when R is a commutative ring with the trivial involution  $a^* = a$ , the relation (2) can be rewritten as S(x, ay + bz) = aS(x, y) + bS(x, z). In this case the mapping S is called bilinear.

A quadratic functional Q on M is defined as the composition of some sesquilinear functional from  $M \times M$  to R with the diagonal injection of Minto  $M \times M$ ; that is, Q(x) = S(x, x), where S is sesquilinear. There is something inappropriate about defining a quadratic functional which is a function of one variable in terms of a sesquilinear functional which involves two variables. This raises the question of what requirements can be imposed on a mapping from M to R to define the set of all quadratic functionals. The best-known identities satisfied by quadratic functionals are the parallelogram law

(3) 
$$Q(x+y) + Q(x-y) = 2Q(x) + 2Q(y), \quad x, y \in M,$$

and the homogeneity equation

(4) 
$$Q(ax) = aQ(x)a^*, \qquad x \in M, \ a \in R.$$

A mapping  $Q: M \to R$  satisfying these two identities is called a quasi-quadratic functional. In the special case that R is a commutative ring with the trivial involution the relation (4) can be rewritten as  $Q(ax) = a^2 Q(x)$ .

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It seems natural to ask when quasi-quadratic functionals are in fact quadratic functionals. In other words, given a quasi-quadratic functional Q, does there exist a sesquilinear functional S such that Q(x) = S(x, x)? In 1963, Halperin in his lectures on Hilbert spaces posed this problem for the special case that Mis a vector space over  $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$ . Here,  $\mathbb{R}$  and  $\mathbb{C}$  denote the field of real numbers and the field of complex numbers respectively, while  $\mathbb H$  denotes the skew-field of quaternions. In 1964, Kurepa [4] obtained the general form of quasi-quadratic functionals defined on a vector space over  $\mathbb{R}$ . In particular, he showed that there exist quasi-quadratic functionals which cannot be represented by bilinear functionals. In 1966, Gleason [2] generalized this result to vector spaces V, dim  $V \ge 2$ , over an arbitrary field F, not of characteristic 2, and with the trivial involution. He proved that all quasi-quadratic functionals on V are quadratic if and only if all additive derivations on F are zero. The same result holds for quasi-quadratic functionals defined on a module over a commutative ring R with the trivial involution in which 2 is a unit. This result follows from [1, Theorem 3]. It should be mentioned that in this commutative case with the trivial involution the result of Jordan and von Neumann [3] implies that for each quasi-quadratic functional Q the mapping S defined by

(5) 
$$4S(x, y) = Q(x + y) - Q(x - y)$$

is symmetric and biadditive and Q(x) = S(x, x) (see [2]). Thus, the abovementioned results imply that S is homogeneous in both variables if and only if all additive derivations on R are zero.

In 1965, Kurepa [5] gave a positive answer to Halperin's problem for quasiquadratic functionals defined on a vector space V over  $\mathbb{F} \in {\mathbb{C}, \mathbb{H}}$ . In 1984, Vukman [9] posed the problem of representability of quasi-quadratic functionals by sesquilinear ones on modules over complex \*-algebras. This problem was treated in [6-11]. The complete solution was given in [7]. It was proved that if Q is a quasi-quadratic functional on a module over a complex \*-algebra with an identity element, then the mapping S defined by

(6) 
$$S(x, y) = \frac{1}{4}(Q(x+y) - Q(x-y)) + \frac{i}{4}(Q(x+iy) - Q(x-iy))$$

is the unique sesquilinear functional satisfying Q(x) = S(x, x). This result is an extension of the Jordan-von Neumann theorem [3] which characterises pre-Hilbert space among all normed spaces.

A mapping J defined on a \*-ring R is called a Jordan \*-derivation if it is additive and satisfies

(7) 
$$J(a^2) = aJ(a) + J(a)a^*$$
.

We shall denote by  $\mathscr{J}$  the set of all Jordan \*-derivations on R. Over a commutative ring with the trivial involution in which 2 is not a zero divisor, the set of all Jordan \*-derivations is equal to the set of all additive derivations [1]. A mapping  $J_a: R \to R$ ,  $a \in R$ , defined by  $J_a(b) = ba - ab^*$  will be called an inner Jordan \*-derivation. In [8] it was proved that the representability of quasi-quadratic functionals by sesquilinear functionals on modules over a real Banach \*-algebra A with an identity element depends on the existence of Jordan \*-derivations on A which are not inner. The proof of this result given in [8] uses the fact that Banach algebras have enough invertible elements. It is the purpose of this note to extend this result to quasi-quadratic functionals defined on modules over arbitrary \*-rings. In this general setting it is impossible to find a relation (similar to (5) in the commutative case) telling us how to recover from a quadratic functional Q a sesquilinear functional S satisfying Q(x) = S(x, x).

### 2. Statement of the results

**Main Theorem.** Let R be a \*-ring with identity 1 such that 2 is a unit in R. Assume that for every Jordan \*-derivation  $J: R \to R$  there exists a unique  $a \in R$  such that  $J(b) = J_a(b) = ba - ab^*$ ,  $b \in R$ . Then every quasi-quadratic functional Q defined on an arbitrary unitary R-module M is a quadratic functional.

Note that the uniqueness of a in the above theorem is equivalent to the statement that  $ba - ab^* = 0$  for all  $b \in R$  implies a = 0. For the proof of the Main Theorem we shall need the following simple lemma.

**Lemma 1.** Let R be a \*-ring with identity 1 such that  $ba - ab^* = 0$  for all  $b \in R$  implies a = 0. If  $e_i$ , i = 1, 2, 3, 4, are elements from R such that

$$ae_1a^* + ae_2b^* + be_3a^* + be_4b^* = 0$$

for all  $a, b \in R$  then  $e_i = 0, i = 1, 2, 3, 4$ .

The next theorem shows that the existence of noninner Jordan \*-derivations yields the existence of quasi-quadratic functionals that cannot be represented by sesquilinear ones.

**Theorem 2.** Let R be a \*-ring with identity 1 such that 2 is not a zero divisor. If  $J: R \to R$  is a Jordan \*-derivation then the mapping  $Q: R \times R \to R$  given by  $Q((a, b)) = J(ba) - bJ(a) - J(a)b^*$  is a quasi-quadratic functional. If J is not inner then Q is not a quadratic functional.

A ring R is said to be a prime ring if  $aRb = \{0\}$  implies a = 0 or b = 0. We shall prove that the mapping  $F: R \to \mathcal{J}$ ,  $F(a) = J_a$ , is one-to-one if R is a noncommutative prime ring. Thus, we shall prove the following result.

**Corollary 3.** Let R be a noncommutative prime \*-ring with identity 1 such that 2 is a unit in R. Then all Jordan \*-derivations on R are inner if and only if every quasi-quadratic functional Q defined on an arbitrary unitary R-module M is a quadratic functional.

Next, we shall show that all the assumptions of the Main Theorem are satisfied if R is a complex \*-algebra with an identity element. This together with the Main Theorem implies the following extension of the Jordan-von Neumann characterization of pre-Hilbert spaces (see [7]).

**Corollary 4.** Let R be a complex \*-algebra with identity 1 and let M be a unitary R-module. Assume that  $Q: M \to R$  is a quasi-quadratic functional. Under these conditions the mapping  $S: M \times M \to R$  defined by the relation (6) is the unique sesquilinear functional satisfying Q(x) = S(x, x).

We shall conclude by giving an example of a Jordan \*-derivation which is not inner.

**Example 5.** There exists a Jordan \*-derivation on a finite-dimensional noncommutative real \*-algebra with an identity element which is not inner.

### 3. Proofs

Proof of Main Theorem. Let Q be a quasi-quadratic functional defined on a unitary *R*-module *M*. We shall divide our proof into two steps. First, we shall prove that if the restriction of Q to each submodule of *M* generated by two elements is a quadratic functional, then Q is a quadratic functional on *M*. Our second step will be to prove that under the assumptions of the Main Theorem every quasi-quadratic functional defined on an arbitrary unitary *R*-module *M* generated by two elements is a quadratic functional.

Step 1. Assume that the restriction of Q to each submodule of M generated by two elements is a quadratic functional. Let us choose arbitrary elements  $x, y \in M$ . We denote by  $M_{x,y} = \{ax + by : a, b \in R\}$  the submodule of Mgenerated by x and y. According to our assumption there exists a sesquilinear functional  $S_{x,y}: M_{x,y} \times M_{x,y} \to R$  such that

(8)  

$$Q(ax + by) = S_{x,y}(ax + by, ax + by)$$

$$= aS_{x,y}(x, x)a^{*} + aS_{x,y}(x, y)b^{*}$$

$$+ bS_{x,y}(y, x)a^{*} + bS_{x,y}(y, y)b^{*}, \quad a, b \in \mathbb{R}.$$

Let us define a functional  $S: M \times M \to R$  by  $S(x, y) = S_{x,y}(x, y)$  for all  $x, y \in M$ .

In order to see that the mapping S is well defined we assume that there exists another sesquilinear functional  $T_{x,y}: M_{x,y} \times M_{x,y} \to R$  satisfying

$$Q(ax + by) = T_{x,y}(ax + by, ax + by)$$
  
=  $aT_{x,y}(x, x)a^* + aT_{x,y}(x, y)b^*$   
+  $bT_{x,y}(y, x)a^* + bT_{x,y}(y, y)b^*$ ,  $a, b \in \mathbb{R}$ .

Comparing this with (8) and using Lemma 1 we get that  $S_{x,y}(x, y) = T_{x,y}(x, y)$ . Thus, S is well defined. Moreover, we have proved that

(9) 
$$S_{y,x}(x, y) = S_{x,y}(x, y)$$

holds for all  $x, y \in M$ . Let x, y, and z be elements from M. Then we have  $S_{x,y}(x, x) = Q(1x + 0y) = Q(1x + 0z) = S_{x,z}(x, x)$ . In particular, we obtain  $S_{x,x}(x, x) = S_{x,y}(x, x)$ . This last relation implies together with (9) that (8) can be rewritten as

(10) 
$$Q(ax + by) = aS(x, x)a^* + aS(x, y)b^* + bS(y, x)a^* + bS(y, y)b^*, \quad a, b \in \mathbb{R},$$

where x, y are arbitrary elements from M. It follows that Q(x) = S(x, x) is valid for all  $x \in M$ . In order to complete the first step of our proof we must show that S is a sesquilinear functional.

For arbitrary  $x, y \in M$  and  $a, b, c, d \in R$  we have

$$caS(x, x)a^{*}c^{*} + caS(x, y)b^{*}d^{*} + dbS(y, x)a^{*}c^{*} + dbS(y, y)b^{*}d^{*}$$
  
=  $Q(cax + dby) = cS(ax, ax)c^{*} + cS(ax, by)d^{*}$   
+  $dS(by, ax)c^{*} + dS(by, by)d^{*}$ .

Applying Lemma 1 we get  $S(ax, by) = aS(x, y)b^*$ . It remains to prove that S is biadditive. Define

$$b_1 = Q(a_1x_1 + a_2x_2 + a_3x_3), \qquad b_2 = Q(a_1x_1 + a_2x_2 - a_3x_3),$$

and

$$b_3 = Q(a_1x_1 - a_2x_2 - a_3x_3).$$

The parallelogram law (3) gives us

$$b_1 + b_2 = 2Q(a_1x_1 + a_2x_2) + 2Q(a_3x_3),$$
  

$$-b_2 - b_3 = -2Q(a_1x_1 - a_3x_3) - 2Q(a_2x_2),$$
  

$$b_1 + b_3 = 2Q(a_1x_1) + 2Q(a_2x_2 + a_3x_3).$$

Solving this system of equations and using (10) we obtain

$$b_1 = \sum_{i, j=1}^3 a_i S(x_i, x_j) a_j^*$$

In particular, for arbitrary  $x, y, z \in M$  and  $a, b \in R$  we have the relation

$$Q(ax + ay + bz) = a(S(x, x) + S(y, x) + S(x, y) + S(y, y))a^* + a(S(x, z) + S(y, z))b^* + b(S(z, x) + S(z, y))a^* + bS(z, z)b^*.$$

On the other hand, using (10) we get that

$$Q(a(x + y) + bz) = aS(x + y, x + y)a^* + aS(x + y, z)b^* + bS(z, x + y)a^* + bS(z, z)b^*.$$

Comparing the two expressions for Q(ax + ay + bz) we obtain, using Lemma 1, the biadditivity of S. Thus, under the assumptions of the Main Theorem, a quasi-quadratic functional Q on M is a quadratic functional if and only if its restriction to each submodule generated by two elements is a quadratic functional.

Step 2. Let  $M = \{ax + by : a, b \in R\}$  be a unitary *R*-module generated by x and y. We have to prove that for a given quasi-quadratic functional  $Q: M \to R$  there exists a sesquilinear functional S from  $M \times M$  to R such that Q(z) = S(z, z) for all  $z \in M$ .

Let us define a functional  $D: R \times R \to R$  by

(11) 
$$D(a, b) = Q(ax + by) - aQ(x)a^* - bQ(y)b^* - 2^{-1}(afb^* + bfa^*),$$

where f = Q(x + y) - Q(x) - Q(y). We shall first prove that D is biadditive. Clearly, it is enough to prove that the functional E given by  $E(a, b) = Q(ax + by) - aQ(x)a^* - bQ(y)b^*$  is biadditive. Applying the parallelogram law (3) we get

(12)  
$$2E(a, b) + 2E(c, b) = 2Q(ax + by) + 2Q(cx + by) - 2Q(ax) - 2Q(cx) - 4Q(by) = Q((a + c)x + 2by) + Q((a - c)x) - 2Q(ax) - 2Q(cx) - Q(2by) = Q((a + c)x + 2by) - Q((a + c)x) - Q(2by) = E(a + c, 2b).$$

Substituting c = 0 and using the obvious relation E(0, b) = 0 we obtain

(13) 
$$2E(a, b) = E(a, 2b).$$

It follows from (12) and (13) that the mapping E is additive in the first argument. The same must be true for the functional D. In the same way we prove that D is additive in the second argument.

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It is not difficult to verify that (4) and (11) imply

 $D(a, a) = 0, \qquad a \in \mathbb{R},$ 

and

$$D(ca, cb) = cD(a, b)c^*, \qquad a, b, c \in \mathbb{R}$$

Using these two relations and biadditivity of D we shall prove that the mapping  $J: R \to R$  given by J(a) = D(a, 1) is a Jordan \*-derivation satisfying

(14) 
$$D(a, b) = J(ab) - aJ(b) - J(b)a^*, \quad a, b \in \mathbb{R}.$$

Clearly, J is additive. For arbitrary  $a, b, c, d \in R$  we have

$$aD(b, c)a^{*} + D(db, ac) + D(ab, dc) + dD(b, c)d^{*}$$
  
=  $D((a+d)b, (a+d)c) = (a+d)D(b, c)(a+d)^{*}$   
=  $aD(b, c)a^{*} + dD(b, c)a^{*} + aD(b, c)d^{*} + dD(b, c)d^{*}$ ,

which yields

$$D(db, ac) + D(ab, dc) = dD(b, c)a^* + aD(b, c)d^*$$

Putting c = d = 1 we get  $D(b, a) + J(ab) = J(b)a^* + aJ(b)$ . As D(a, a) = 0 implies D(a, b) = -D(b, a), we have proved that (14) is valid. Replacing a in this relation by ba we see that

$$bJ(a)b^* = J(bab) - baJ(b) - J(b)a^*b^*$$

holds for all  $a, b \in R$ . Putting a = 1 and using J(1) = 0 we finally get  $J(b^2) = bJ(b) + J(b)b^*$  for all  $b \in R$ .

According to our assumptions, J is an inner Jordan \*-derivation. Thus, we can find an element  $g \in R$  such that  $J(a) = ag - ga^*$  is valid for all  $a \in R$ . It follows from (14) that

$$D(a, b) = agb^* - bga^*, \qquad a, b \in \mathbb{R}.$$

Applying (11) one can easily see that

$$Q(ax + by) = ae_{11}a^* + ae_{12}b^* + be_{21}a^* + be_{22}b^*, \qquad a, b \in \mathbb{R},$$

where  $e_{11} = Q(x)$ ,  $e_{12} = g + 2^{-1}f$ ,  $e_{21} = 2^{-1}f - g$ , and  $e_{22} = Q(y)$ . We define  $S: M \times M \to R$  by

$$S(ax + by, cx + dy) = ae_{11}c^* + ae_{12}d^* + be_{21}c^* + be_{22}d^*, \qquad a, b, c, d \in \mathbb{R}.$$

In order to see that S is well defined we choose  $a_1, a_2 \in R$  such that  $a_1x + a_2y = 0$ . For arbitrary elements  $b_1, b_2 \in R$  we have

$$\sum_{i,j=1}^{2} b_i e_{ij} b_j^* = Q(b_1 x + b_2 y) = Q((a_1 + b_1) x + (a_2 + b_2) y)$$
  
= 
$$\sum_{i,j=1}^{2} (a_i + b_i) e_{ij} (a_j^* + b_j^*)$$
  
= 
$$\sum_{i,j=1}^{2} a_i e_{ij} a_j^* + \sum_{i,j=1}^{2} a_i e_{ij} b_j^* + \sum_{i,j=1}^{2} b_i e_{ij} a_j^* + \sum_{i,j=1}^{2} b_i e_{ij} b_j^*.$$

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It follows from  $0 = Q(a_1x + a_2y) = \sum_{i,j=1}^{2} a_i e_{ij} a_j^*$  that

(15) 
$$\sum_{i,j=1}^{2} a_{i}e_{ij}b_{j}^{*} + \sum_{i,j=1}^{2} b_{i}e_{ij}a_{j}^{*} = 0.$$

Putting  $b_1 = 1$  and  $b_2 = 0$  we get p + q = 0, where

$$p = a_1 e_{11} + a_2 e_{21}, \qquad q = e_{11} a_1^* + e_{12} a_2^*.$$

On the other hand, if we set in (15)  $b_1 = c$  and  $b_2 = 0$ , we obtain  $pc^* + cq = 0$ . Together with cq + cp = 0 this implies  $cp - pc^* = 0$  for all  $c \in A$ . It follows that p = q = 0, or

$$S(a_1x + a_2y, x) = 0 = S(x, a_1x + a_2y).$$

In a similar way we get

$$S(a_1x + a_2y, y) = 0 = S(y, a_1x + a_2y).$$

Thus, S is well defined. Clearly, it is a sesquilinear functional satisfying Q(z) = S(z, z) for all  $z \in M$ . This completes the proof.

*Proof of Lemma* 1. Putting a = 1 and b = 0 we get  $e_1 = 0$ . Similarly, we obtain  $e_4 = 0$ . Substituting a = b = 1 we see that  $e_2 = -e_3$ . Substituting once again b = 1 we get that  $ae_2 - e_2a^* = 0$  is valid for all  $a \in R$ . Thus,  $e_2 = e_3 = 0$ . This completes the proof.

**Proof of Theorem 2.** It is easy to verify that Q satisfies the parallelogram law (3). In order to see that also the homogeneity law (4) is fulfilled we must show that every Jordan \*-derivation  $J: R \to R$  satisfies

(16) 
$$J(cbca) = cbJ(ca) + J(ca)b^*c^* + cJ(ba)c^* - cbJ(a)c^* - cJ(a)b^*c^*$$

for all  $a, b, c \in R$ . For this purpose first replace a by a + b in (7) to get

(17) 
$$J(ab) + J(ba) = bJ(a) + aJ(b) + J(a)b^* + J(b)a^*$$

for all  $a, b \in R$ . Consider now d = J(a(ab + ba) + (ab + ba)a). Using (17) we see that

$$\begin{aligned} d &= aJ(ab + ba) + (ab + ba)J(a) + J(ab + ba)a^* + J(a)(b^*a^* + a^*b^*) \\ &= 2abJ(a) + a^2J(b) + aJ(a)b^* + 2aJ(b)a^* + baJ(a) \\ &+ bJ(a)a^* + 2J(a)b^*a^* + J(b)a^{*2} + J(a)a^*b^* \,. \end{aligned}$$

On the other hand,

$$\begin{aligned} d &= 2J(aba) + J(a^2b) + J(ba^2) \\ &= 2J(aba) + bJ(a^2) + a^2J(b) + J(a^2)b^* + J(b)a^{*2} \\ &= 2J(aba) + baJ(a) + bJ(a)a^* + a^2J(b) + aJ(a)b^* + J(a)a^*b^* + J(b)a^{*2}. \end{aligned}$$

Comparing the two expressions for d we arrive at

(18) 
$$J(aba) = J(a)b^*a^* + aJ(b)a^* + abJ(a), \qquad a, b \in \mathbb{R}.$$

Replacing a in (18) by a + c we obtain

(19) 
$$J(abc + cba) = J(a)b^*c^* + aJ(b)c^* + abJ(c) + J(c)b^*a^* + cJ(b)a^* + cbJ(a), \quad a, b, c \in \mathbb{R}.$$

Applying (18) and (19) we get

$$J(cbca) = J(cb(ca) + (ca)bc) - J(c(ab)c) = cbJ(ca) + J(ca)b^*c^* + c(J(b)a^* + aJ(b) - J(ab))c^*.$$

Applying (17) we get (16). Thus, we have proved that Q is a quasi-quadratic functional.

Assume now that J is not inner. If there is a sesquilinear functional S which generates Q, then S is of the form  $S((a, b), (c, d)) = aed^* + bfc^*$  for some  $e, f \in R$ . The relation Q((a, b)) = S((a, b), (a, b)) with b = 1 gives us  $J(a) = -ae - fa^*$ . Since J(1) = 0, we have e = -f, so that J is an inner Jordan \*-derivation. This contradiction completes the proof.

*Proof of Corollary* 3. Let us first assume that all Jordan \*-derivations on R are inner. We claim that  $J_a = 0$ ,  $a \in R$ , implies a = 0. Indeed, for such an a we have

$$ba = ab^*$$

for all  $b \in R$ . Replacing b by bc and applying (20) two times we get

$$(21) (bc-cb)a = 0.$$

Substituting c = dc in (21) we obtain (bdc-dcb)a = 0, which can be rewritten as

$$(bd - db)ca + d(bc - cb)a = 0$$

where b, c, d are arbitrary elements from R. The second term is zero by (21). As R is noncommutative and prime, we have necessarily a = 0. Using the Main Theorem one can complete the proof of the "if part". Theorem 2 shows that the converse is also true.

*Proof of Corollary* 4. Substituting a = ia and b = i in (17) we prove that every Jordan \*-derivation on R is inner. From  $J_a(i) = 2ia$  it follows that  $a \neq 0$  implies that  $J_a$  is nonzero. Using the Main Theorem one can complete the proof.

Verification of Example 5. Let R be a real \*-algebra consisting of elements  $\lambda + u\mu$ , where  $\lambda$  and  $\mu$  are complex numbers. We define the operations by  $t(\lambda + u\mu) = t\lambda + u(t\mu)$  for real t,  $(\lambda_1 + u\mu_1) + (\lambda_2 + u\mu_2) = (\lambda_1 + \lambda_2) + u(\mu_1 + \mu_2)$ ,  $(\lambda_1 + u\mu_1)(\lambda_2 + u\mu_2) = \lambda_1\lambda_2 + u(\mu_1\lambda_2 + \overline{\lambda_1}\mu_2)$  and the involution by  $(\lambda + u\mu)^* = \overline{\lambda} - u\mu$ .

There exists a nontrivial and therefore discontinuous additive derivation on  $\mathbb{R}$ , that is, an additive function  $f: \mathbb{R} \to \mathbb{R}$  satisfying f(ts) = tf(s) + sf(t) for all pairs  $t, s \in \mathbb{R}$  (see [12]). Putting D(s + it) = f(s) - if(t) we get a function  $D: \mathbb{C} \to \mathbb{C}$  which is additive and satisfies  $D(\lambda^2) = 2\overline{\lambda}D(\lambda)$ . It is not difficult to verify that the mapping  $J: \mathbb{R} \to \mathbb{R}$  given by  $J(\lambda + u\mu) = uD(\lambda)$  is a Jordan \*-derivation. However, it is discontinuous and therefore noninner.

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Department of Mathematics, University of Ljubljana, Jadranska 19, 61000 Ljubljana, Slovenia

E-mail address: peter.semrl@uni-lj.si