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# REAL HYPERSURFACES IN COMPLEX TWO-PLANE GRASSMANNIANS WITH CERTAIN COMMUTING CONDITION

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Abstract. In this paper, first we introduce a new notion of commuting condition that  $\varphi\varphi_1A = A\varphi_1\varphi$  between the shape operator A and the structure tensors  $\varphi$  and  $\varphi_1$  for real hypersurfaces in  $G_2(\mathbb{C}^{m+2})$ . Suprisingly, real hypersurfaces of type (A), that is, a tube over a totally geodesic  $G_2(\mathbb{C}^{m+1})$  in complex two plane Grassmannians  $G_2(\mathbb{C}^{m+2})$  satisfy this commuting condition. Next we consider a complete classification of Hopf hypersurfaces in  $G_2(\mathbb{C}^{m+2})$  satisfying the commuting condition. Finally we get a characterization of Type (A) in terms of such commuting condition  $\varphi\varphi_1A = A\varphi_1\varphi$ .

 $\it Keywords$ : real hypersurface, complex two-plane Grassmannians, Hopf hypersurface, commuting shape operator

MSC 2010: 53C50, 53C55

## Introduction

We denote by  $G_2(\mathbb{C}^{m+2})$  the set of all complex two-dimensional linear subspaces in  $\mathbb{C}^{m+2}$ . This Riemannian symmetric space  $G_2(\mathbb{C}^{m+2})$  has a remarkable geometric structure. It is the unique compact irreducible Riemannian manifold with both a Kähler structure J and a quaternionic Kähler structure  $\mathfrak{J}$  not containing J. Namely,  $G_2(\mathbb{C}^{m+2})$  is a unique compact, irreducible, Kähler, quaternionic Kähler manifold which is not a hyper-Kähler manifold. Accordingly, in  $G_2(\mathbb{C}^{m+2})$  we have the two natural geometric conditions for real hypersurfaces M that the 1-dimensional distribution  $[\xi] = \operatorname{Span}\{\xi\}$  and the 3-dimensional distribution  $\mathfrak{D}^{\perp} = \operatorname{Span}\{\xi_1, \xi_2, \xi_3\}$  are invariant under the shape operator A of M (see [2], [3] and [4]).

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The almost contact structure vector field  $\xi$  defined by  $\xi = -JN$  is said to be a Reeb vector field, where N denotes a local unit normal vector field of M in  $G_2(\mathbb{C}^{m+2})$ . The almost contact 3-structure vector fields  $\{\xi_1, \xi_2, \xi_3\}$  for the 3-dimensional distribution  $\mathfrak{D}^{\perp}$  of M in  $G_2(\mathbb{C}^{m+2})$  are defined by  $\xi_{\nu} = -J_{\nu}N$  ( $\nu = 1, 2, 3$ ), where  $J_{\nu}$  denotes a canonical local basis of a quaternionic Kähler structure  $\mathfrak{J}$  and  $T_xM = \mathfrak{D} \oplus \mathfrak{D}^{\perp}$ ,  $x \in M$ .

By using the two invariant conditions mentioned above and the result in Alekseevskii [1], Berndt and Suh [3] proved the following:

**Theorem A.** Let M be a connected orientable real hypersurface in  $G_2(\mathbb{C}^{m+2})$ ,  $m \geq 3$ . Then both  $[\xi]$  and  $\mathfrak{D}^{\perp}$  are invariant under the shape operator of M if and only if

- (A) M is an open part of a tube around a totally geodesic  $G_2(\mathbb{C}^{m+1})$  in  $G_2(\mathbb{C}^{m+2})$ , or
- (B) m is even, say m = 2n, and M is an open part of a tube around a totally geodesic  $\mathbb{H}P^n$  in  $G_2(\mathbb{C}^{m+2})$ .

The Reeb vector field  $\xi$  is said to be Hopf if it is invariant under the shape operator A. The 1-dimensional foliation of M by the integral manifolds of the Reeb vector field  $\xi$  is said to be a Hopf foliation of M. We say that M is a Hopf hypersurface in  $G_2(\mathbb{C}^{m+2})$  if and only if the Hopf foliation of M is totally geodesic. By the formulas in Section 2 it can be easily checked that M is Hopf if and only if the Reeb vector field  $\xi$  is Hopf.

On the other hand, we say that the Reeb flow on M in  $G_2(\mathbb{C}^{m+2})$  is isometric, when the Reeb vector field  $\xi$  on M is Killing. In [4], Berndt and Suh gave some equivalent conditions for isometric Reeb flow. Among them, we want to introduce a commuting condition between the shape operator A and the structure tensor  $\varphi$ , that is,  $A\varphi = \varphi A$ . By such a commuting condition, a characterization of real hypersurfaces of Type (A) in Theorem A was given in terms of the Reeb flow on M as follows:

**Theorem B.** Let M be a connected orientable real hypersurface in  $G_2(\mathbb{C}^{m+2})$ ,  $m \ge 3$ . Then the Reeb flow on M is isometric if and only if M is an open part of a tube around a totally geodesic  $G_2(\mathbb{C}^{m+1})$  in  $G_2(\mathbb{C}^{m+2})$ .

In [7], Suh considered a condition that the almost contact 3-structure tensors  $\{\varphi_1, \varphi_2, \varphi_3\}$  commute with the shape operator A of real hypersurface M in  $G_2(\mathbb{C}^{m+2})$ , and he proved that there does not exist any real hypersurface M in  $G_2(\mathbb{C}^{m+2})$  with  $A\varphi_{\nu}X = \varphi_{\nu}AX$ ,  $\nu = 1, 2, 3$ , for any tangent vector field X on M. In addition, he gave a characterization of real hypersurface of Type (B) under assumption that M is a Hopf hypersurface in  $G_2(\mathbb{C}^{m+2})$  with  $A\varphi_{\nu}X = \varphi_{\nu}AX$ ,

 $\nu = 1, 2, 3$ , for any tangent vector field X on  $T_0$ . Here, the distribution  $T_0$  is defined by  $T_0 = \{X \in T_p M \mid \xi \perp X\}$  (see [7]).

Summing up these statements, naturally we ask what can we say about the commuting condition between the shape operator A and the two structure tensors  $\varphi$  and  $\varphi_1$ . According to such a problem, in this paper we consider a new condition that the shape operator A commutes with two kinds of structure tensors  $\varphi$  and  $\varphi_1$  for a real hypersurface M in  $G_2(\mathbb{C}^{m+2})$  as follows:

$$\varphi \varphi_1 A X = A \varphi_1 \varphi X$$

for any tangent vector field X on M.

Suprisingly, by Proposition A in Section 3, we know that real hypersurfaces of Type (A) in  $G_2(\mathbb{C}^{m+2})$  in Theorem A satisfy the formula (\*). From such a point of view, we give another characterization of real hypersurface of Type (A) in  $G_2(\mathbb{C}^{m+2})$  as follows:

**Main Theorem.** Let M be a connected orientable Hopf hypersurface in  $G_2(\mathbb{C}^{m+2})$ ,  $m \geq 3$ . Then the shape operator satisfies the commuting condition (\*) if and only if M is an open part of a tube around a totally geodesic  $G_2(\mathbb{C}^{m+1})$  in  $G_2(\mathbb{C}^{m+2})$ .

# 1. Riemannian geometry of $G_2(\mathbb{C}^{m+2})$

In this section we summarize basic material about  $G_2(\mathbb{C}^{m+2})$ , for details we refer to [2], [3] and [4]. By  $G_2(\mathbb{C}^{m+2})$  we denote the set of all complex two-dimensional linear subspaces in  $\mathbb{C}^{m+2}$ . The special unitary group G = SU(m+2) acts transitively on  $G_2(\mathbb{C}^{m+2})$  with stabilizer isomorphic to  $K = S(U(2) \times U(m)) \subset G$ . Then  $G_2(\mathbb{C}^{m+2})$  can be identified with the homogeneous space G/K, which we equip with the unique analytic structure for which the natural action of G on  $G_2(\mathbb{C}^{m+2})$  becomes analytic. Denote by  $\mathfrak{g}$  and  $\mathfrak{k}$  the Lie algebra of G and G, respectively, and by G then G then G is an G and G then G then G then G is an G and G is negative definite on G and G is negative definite on G. We put G is negative definite on G is negative restricted to G and G is negative definite inner product on G is negative restricted to G this inner product can be extended to a G-invariant Riemannian metric G on G and G is negative definite inner product on G invariant Riemannian metric G on G and G is negative definite inner product on G invariant Riemannian metric G on G and G is negative definite inner product on G invariant Riemannian metric G on G is negative definite inner product on G invariant Riemannian metric G on G is eight.

When m=1,  $G_2(\mathbb{C}^3)$  is isometric to the two-dimensional complex projective space  $\mathbb{C}P^2$  with constant holomorphic sectional curvature eight.

When m=2, we note that the isomorphism  $\mathrm{Spin}(6) \simeq SU(4)$  yields an isometry between  $G_2(\mathbb{C}^4)$  and the real Grassmann manifold  $G_2^+(\mathbb{R}^6)$  of oriented two-dimensional linear subspaces in  $\mathbb{R}^6$ . In this paper, we will assume  $m \geq 3$ .

The Lie algebra  $\mathfrak{k}$  has the direct sum decomposition  $\mathfrak{k} = \mathfrak{s}u(m) \oplus \mathfrak{s}u(2) \oplus \mathfrak{R}$ , where  $\mathfrak{R}$  denotes the center of  $\mathfrak{k}$ . Viewing  $\mathfrak{k}$  as the holonomy algebra of  $G_2(\mathbb{C}^{m+2})$ , the center  $\mathfrak{R}$  induces a Kähler structure J and the  $\mathfrak{s}u(2)$ -part a quaternionic Kähler structure  $\mathfrak{J}$  on  $G_2(\mathbb{C}^{m+2})$ . If  $J_{\nu}$  is any almost Hermitian structure in  $\mathfrak{J}$ , then  $JJ_{\nu} = J_{\nu}J$ , and  $JJ_{\nu}$  is a symmetric endomorphism with  $(JJ_{\nu})^2 = I$  and  $\operatorname{tr}(JJ_{\nu}) = 0$  for  $\nu = 1, 2, 3$ .

A canonical local basis  $\{J_1, J_2, J_3\}$  of  $\mathfrak J$  consists of three local almost Hermitian structures  $J_{\nu}$  in  $\mathfrak J$  such that  $J_{\nu}J_{\nu+1}=J_{\nu+2}=-J_{\nu+1}J_{\nu}$ , where the index  $\nu$  is taken modulo three. Since  $\mathfrak J$  is parallel with respect to the Riemannian connection  $\widetilde{\nabla}$  of  $(G_2(\mathbb C^{m+2}),g)$ , there exist for any canonical local basis  $\{J_1,J_2,J_3\}$  of  $\mathfrak J$  three local one-forms  $q_1,q_2,q_3$  such that

(1.1) 
$$\widetilde{\nabla}_X J_{\nu} = q_{\nu+2}(X) J_{\nu+1} - q_{\nu+1}(X) J_{\nu+2}$$

for all vector fields X on  $G_2(\mathbb{C}^{m+2})$ .

The Riemannian curvature tensor  $\widetilde{R}$  of  $G_2(\mathbb{C}^{m+2})$  is locally given by

(1.2) 
$$\widetilde{R}(X,Y)Z = g(Y,Z)X - g(X,Z)Y + g(JY,Z)JX \\ - g(JX,Z)JY - 2g(JX,Y)JZ \\ + \sum_{\nu=1}^{3} \left\{ g(J_{\nu}Y,Z)J_{\nu}X - g(J_{\nu}X,Z)J_{\nu}Y - 2g(J_{\nu}X,Y)J_{\nu}Z \right\} \\ + \sum_{\nu=1}^{3} \left\{ g(J_{\nu}JY,Z)J_{\nu}JX - g(J_{\nu}JX,Z)J_{\nu}JY \right\},$$

where  $\{J_1, J_2, J_3\}$  denotes a canonical local basis of  $\mathfrak{J}$ .

#### 2. Some fundamental formulas

In this section we derive some basic formulas and the Codazzi equation for a real hypersurface in  $G_2(\mathbb{C}^{m+2})$  (see [5], [6] and [7]).

Let M be a real hypersurface of  $G_2(\mathbb{C}^{m+2})$ , that is, a hypersurface of  $G_2(\mathbb{C}^{m+2})$  with real codimension one. The induced Riemannian metric on M will also be denoted by g, and  $\nabla$  denotes the Riemannian connection of (M,g). Let N be a local unit normal vector field of M and A the shape operator of M with respect to N.

Now let us put

(2.1) 
$$JX = \varphi X + \eta(X)N, \quad J_{\nu}X = \varphi_{\nu}X + \eta_{\nu}(X)N$$

for any tangent vector field X of a real hypersurface M in  $G_2(\mathbb{C}^{m+2})$ , where N denotes a unit normal vector field of M in  $G_2(\mathbb{C}^{m+2})$ . From the Kähler structure J of  $G_2(\mathbb{C}^{m+2})$  there exists an almost contact metric structure  $(\varphi, \xi, \eta, g)$  induced on M in such a way that

(2.2) 
$$\varphi^2 X = -X + \eta(X)\xi, \quad \eta(\xi) = 1, \quad \varphi \xi = 0, \quad \eta(X) = g(X, \xi)$$

for any vector field X on M. Furthermore, let  $\{J_1, J_2, J_3\}$  be a canonical local basis of  $\mathfrak{J}$ . Then the quaternionic Kähler structure  $J_{\nu}$  of  $G_2(\mathbb{C}^{m+2})$ , together with the condition  $J_{\nu}J_{\nu+1}=J_{\nu+2}=-J_{\nu+1}J_{\nu}$  in Section 1, induces an almost contact metric 3-structure  $(\varphi_{\nu}, \xi_{\nu}, \eta_{\nu}, g)$  on M as follows:

(2.3) 
$$\begin{cases} \varphi_{\nu}^{2}X = -X + \eta_{\nu}(X)\xi_{\nu}, & \eta_{\nu}(\xi_{\nu}) = 1, \quad \varphi_{\nu}\xi_{\nu} = 0, \\ \varphi_{\nu+1}\xi_{\nu} = -\xi_{\nu+2}, & \varphi_{\nu}\xi_{\nu+1} = \xi_{\nu+2}, \\ \varphi_{\nu}\varphi_{\nu+1}X = \varphi_{\nu+2}X + \eta_{\nu+1}(X)\xi_{\nu}, \\ \varphi_{\nu+1}\varphi_{\nu}X = -\varphi_{\nu+2}X + \eta_{\nu}(X)\xi_{\nu+1} \end{cases}$$

for any vector field X tangent to M. Moreover, from the commuting property of  $J_{\nu}J = JJ_{\nu}$ ,  $\nu = 1, 2, 3$  in Section 1 and (2.1), the relation between these two contact metric structures  $(\varphi, \xi, \eta, g)$  and  $(\varphi_{\nu}, \xi_{\nu}, \eta_{\nu}, g)$ ,  $\nu = 1, 2, 3$ , can be given by

(2.4) 
$$\varphi \varphi_{\nu} X = \varphi_{\nu} \varphi X + \eta_{\nu}(X) \xi - \eta(X) \xi_{\nu},$$
$$\eta_{\nu}(\varphi X) = \eta(\varphi_{\nu} X), \quad \varphi \xi_{\nu} = \varphi_{\nu} \xi.$$

On the other hand, from the Kähler structure J, that is,  $\widetilde{\nabla}J=0$  and the quaternionic Kähler structure  $J_{\nu}$  (see (1.1)), together with Gauss and Weingarten formulas it follows that

(2.5) 
$$(\nabla_X \varphi) Y = \eta(Y) A X - g(AX, Y) \xi, \quad \nabla_X \xi = \varphi A X,$$

(2.6) 
$$\nabla_X \xi_{\nu} = q_{\nu+2}(X)\xi_{\nu+1} - q_{\nu+1}(X)\xi_{\nu+2} + \varphi_{\nu}AX,$$

$$(2.7) (\nabla_X \varphi_{\nu})Y = -q_{\nu+1}(X)\varphi_{\nu+2}Y + q_{\nu+2}(X)\varphi_{\nu+1}Y + \eta_{\nu}(Y)AX - g(AX,Y)\xi_{\nu}$$

Summing up these formulas, we find the following

(2.8) 
$$\nabla_X(\varphi_{\nu}\xi) = \nabla_X(\varphi\xi_{\nu})$$

$$= (\nabla_X\varphi)\xi_{\nu} + \varphi(\nabla_X\xi_{\nu})$$

$$= q_{\nu+2}(X)\varphi_{\nu+1}\xi - q_{\nu+1}(X)\varphi_{\nu+2}\xi + \varphi_{\nu}\varphi AX$$

$$- g(AX, \xi)\xi_{\nu} + \eta(\xi_{\nu})AX.$$

Using the above expression (1.2) for the curvature tensor  $\widetilde{R}$  of  $G_2(\mathbb{C}^{m+2})$ , the equation of Codazzi becomes

$$(2.9) \qquad (\nabla_X A)Y - (\nabla_Y A)X = \eta(X)\varphi Y - \eta(Y)\varphi X - 2g(\varphi X, Y)\xi$$

$$+ \sum_{\nu=1}^{3} \{\eta_{\nu}(X)\varphi_{\nu}Y - \eta_{\nu}(Y)\varphi_{\nu}X - 2g(\varphi_{\nu}X, Y)\xi_{\nu}\}$$

$$+ \sum_{\nu=1}^{3} \{\eta_{\nu}(\varphi X)\varphi_{\nu}\varphi Y - \eta_{\nu}(\varphi Y)\varphi_{\nu}\varphi X\}$$

$$+ \sum_{\nu=1}^{3} \{\eta(X)\eta_{\nu}(\varphi Y) - \eta(Y)\eta_{\nu}(\varphi X)\}\xi_{\nu}.$$

#### 3. Key Lemmas

Now let us assume that M is a Hopf hypersurface in  $G_2(\mathbb{C}^{m+2})$  with commuting shape operator, that is, the shape operator A of M commutes with the structures tensors  $\varphi$  and  $\varphi_1$  as follows:

$$\varphi \varphi_1 A X = A \varphi_1 \varphi X$$

for any tangent vector field X on M.

First of all, we establish one of the key lemmas as follows:

**Lemma 3.1.** Let M be a Hopf hypersurface in complex two-plane Grassmannians  $G_2(\mathbb{C}^{m+2})$ ,  $m \geqslant 3$ . If M has commuting shape operator, then the Reeb vector field  $\xi$  belongs to either the distribution  $\mathfrak{D}$  or the distribution  $\mathfrak{D}^{\perp}$ .

Proof. In order to prove our lemma, let us put  $\xi = \eta(X_0)X_0 + \eta(\xi_1)\xi_1$  for some unit  $X_0 \in \mathfrak{D}$  and  $\xi_1 \in \mathfrak{D}^{\perp}$  and  $\eta(X_0)\eta(\xi_1) \neq 0$ .

From the assumption (\*) for  $X = \xi$  and (2.2), we have

(3.1) 
$$\varphi_1 A \xi = \eta(\varphi_1 A \xi) \xi.$$

On the other hand, from the assumption that M is Hopf, we see that

$$(3.2) A\xi = \alpha \xi = \alpha \eta(X_0) X_0 + \alpha \eta(\xi_1) \xi_1.$$

Combining with (3.1) and (3.2), we have

$$\alpha \eta(X_0)\varphi_1 X_0 = 0,$$

because  $\varphi_1 \xi_1 = 0$  and the structure tensor  $\varphi_1$  is skew-symmetric.

But we see that  $\varphi_1 X_0$  is non-vanishing at all points of M. In fact, we obtain

$$\|\varphi_1 X_0\|^2 = g(\varphi_1 X_0, \varphi_1 X_0) = -g(\varphi_1^2 X_0, X_0) = g(X_0, X_0) = 1,$$

where we have used the equation (2.3) and the fact that  $X_0$  is unit.

Then it follows that

$$\alpha \eta(X_0) = 0.$$

Thus we can consider the following two cases:

Case 1.  $\alpha = 0$ , that is,  $A\xi = 0$ . This case is trivial by Lemma 3.1 due to Pérez and Suh [6].

Case 2.  $\alpha \neq 0$ . From (3.3), we have  $\eta(X_0) = 0$ . This gives a contradiction.

So we complete the proof of our Lemma.

Now, we consider another commuting condition for the shape operator A on M when the Reeb vector  $\xi$  belongs to the distribution  $\mathfrak{D}^{\perp}$ . We prove the following lemma which will be useful in the proof of Lemma 4.2 in Section 4.

**Lemma 3.2.** Let M be a connected orientable Hopf hypersurface in  $G_2(\mathbb{C}^{m+2})$ ,  $m \ge 3$  with  $\xi \in \mathfrak{D}^{\perp}$ . If M satisfies the following condition

$$(**) \qquad \varphi \varphi_1 A X = A \varphi \varphi_1 X, \quad X \in \mathfrak{D}^{\perp},$$

then the distribution  $\mathfrak{D}^{\perp}$  is invariant under the shape operator A of M, that is,  $g(A\mathfrak{D}^{\perp},\mathfrak{D})=0$ .

Proof. From now on, since  $\xi \in \mathfrak{D}^{\perp}$ , let us put  $\xi = \xi_1$ . Taking the covariant derivative along any direction  $Y \in TM$ , we have

(3.4) 
$$\varphi AY = \nabla_Y \xi = \nabla_Y \xi_1 = q_3(Y)\xi_2 - q_2(Y)\xi_3 + \varphi_1 AY.$$

From this, taking the inner product with  $\xi_2$  and  $\xi_3$ , we have

(3.5) 
$$q_3(Y) = 2g(AY, \xi_3), \quad q_2(Y) = 2g(AY, \xi_2),$$

respectively.

Moreover, applying the structure tensor  $\varphi$  in (3.4), this equation can be written as

(3.6) 
$$AY = \alpha \eta(Y)\xi + 2g(AY, \xi_2)\xi_2 + 2g(AY, \xi_3)\xi_3 - \varphi \varphi_1 AY, \quad Y \in TM,$$

where we have used that M is Hopf and the formulas (2.2), (2.3) and (3.5).

Putting  $Y = \xi_2$  in (3.6), we get

$$A\xi_{2} = \alpha \eta(\xi_{2})\xi + 2g(A\xi_{2}, \xi_{2})\xi_{2} + 2g(A\xi_{2}, \xi_{3})\xi_{3} - \varphi \varphi_{1}A\xi_{2}$$

$$= 2g(A\xi_{2}, \xi_{2})\xi_{2} + 2g(A\xi_{2}, \xi_{3})\xi_{3} - \varphi \varphi_{1}A\xi_{2}$$

$$= 2g(A\xi_{2}, \xi_{2})\xi_{2} + 2g(A\xi_{2}, \xi_{3})\xi_{3} - A\xi_{2}.$$

Here from the condition (\*\*) we see that  $\varphi \varphi_1 A \xi_2 = A \varphi \varphi_1 \xi_2 = A \xi_2$ , because  $\xi_2 \in \mathfrak{D}^{\perp}$ . Therefore the third equality in the above equation holds. Consequently, it implies

(3.7) 
$$A\xi_2 = g(A\xi_2, \xi_2)\xi_2 + g(A\xi_2, \xi_3)\xi_3.$$

Similarly, if we consider  $Y = \xi_3$  in (3.6), we get

(3.8) 
$$A\xi_3 = g(A\xi_3, \xi_2)\xi_2 + g(A\xi_3, \xi_3)\xi_3,$$

because  $\varphi \varphi_1 A \xi_3 = A \varphi \varphi_1 \xi_3 = A \xi_3$ .

From the two equations (3.7), (3.8) and the assumption  $A\xi_1 = A\xi = \alpha\xi = \alpha\xi_1$ , we have  $A\xi_{\nu} \in \mathfrak{D}^{\perp}$  for any  $\nu = 1, 2, 3$ . So we conclude that the distribution  $\mathfrak{D}^{\perp}$  is invariant under the shape operator A of M, that is,  $A\mathfrak{D}^{\perp} \subset \mathfrak{D}^{\perp}$ . This gives a complete proof of our lemma.

Before giving the proof of our Main Theorem from the Introduction, let us check whether the shape operator A of real hypersurfaces of Type (A) or of Type (B) in Theorem A satisfies the condition (\*) or not.

First let us check for the case that M is locally congruent to a real hypersurface of Type (A), an open part of a tube around a totally geodesic  $G_2(\mathbb{C}^{m+1})$  in  $G_2(\mathbb{C}^{m+2})$ . We recall a proposition due to Berndt and Suh [3] as follows:

**Proposition A.** Let M be a connected real hypersurface of  $G_2(\mathbb{C}^{m+2})$ . Suppose that  $A\mathfrak{D} \subset \mathfrak{D}$ ,  $A\xi = \alpha \xi$ , and  $\xi$  is tangent to  $\mathfrak{D}^{\perp}$ . Let  $J_1 \in \mathfrak{J}$  be the almost Hermitian structure such that  $JN = J_1N$ . Then M has three (if  $r = \pi/2\sqrt{8}$ ) or four (otherwise) distinct constant principal curvatures

$$\alpha = \sqrt{8}\cot(\sqrt{8}r), \quad \beta = \sqrt{2}\cot(\sqrt{2}r), \quad \lambda = -\sqrt{2}\tan(\sqrt{2}r), \quad \mu = 0$$

with some  $r \in (0, \pi/\sqrt{8})$ . The corresponding multiplicities are

$$m(\alpha) = 1$$
,  $m(\beta) = 2$ ,  $m(\lambda) = 2m - 2 = m(\mu)$ ,

and the corresponding eigenspaces are

$$T_{\alpha} = \mathbb{R}\xi = \mathbb{R}JN = \mathbb{R}\xi_{1} = \operatorname{Span}\{\xi\} = \operatorname{Span}\{\xi_{1}\},$$

$$T_{\beta} = \mathbb{C}^{\perp}\xi = \mathbb{C}^{\perp}N = \mathbb{R}\xi_{2} \oplus \mathbb{R}\xi_{3} = \operatorname{Span}\{\xi_{2}, \xi_{3}\},$$

$$T_{\lambda} = \{X \mid X \perp \mathbb{H}\xi, \ JX = J_{1}X\},$$

$$T_{\mu} = \{X \mid X \perp \mathbb{H}\xi, \ JX = -J_{1}X\}$$

where  $\mathbb{R}\xi$ ,  $\mathbb{C}\xi$  and  $\mathbb{H}\xi$  respectively denotes real, complex and quaternionic span of the structure vector field  $\xi$  and  $\mathbb{C}^{\perp}\xi$  denotes the orthogonal complement of  $\mathbb{C}\xi$  in  $\mathbb{H}\xi$ .

Now let us check case by case whether the two sides in (\*) are equal to each other: Case A-1.  $X \in T_{\alpha}$  (i.e.  $X = \xi = \xi_1$ ). It can easily be checked that the two sides are equal to each other.

Case A-2.  $X \in T_{\beta}$ , (i.e.  $X = \xi_2$  or  $X = \xi_3$ ). Then we put  $A\xi_2 = \beta \xi_2$ ,  $A\xi_3 = \beta \xi_3$ , where  $\beta = \sqrt{2} \cot(\sqrt{2}r)$ . Then by putting  $X = \xi_2$  in (\*) we have

Left-Hand Side = 
$$\varphi \varphi_1 A \xi_2 = \beta \varphi \varphi_1 \xi_2 = \beta \varphi \xi_3 = \beta \varphi_3 \xi_1 = \beta \xi_2$$
,

and

Right-Hand Side = 
$$A\varphi_1\varphi\xi_2 = A\varphi_1\varphi_2\xi = A\varphi_1\varphi_2\xi_1 = -A\varphi_1\xi_3 = A\xi_2 = \beta\xi_2$$
.

From this we see that both sides are equal to  $\beta \xi_2$ . Similarly, by putting  $X = \xi_3$  in (\*) we know that they are equal to  $\beta \xi_3$ .

Case A-3.  $X \in T_{\lambda} = \{X \mid X \perp \mathbb{H}\xi, \ \varphi X = \varphi_1 X\}$ . For any  $X \in T_{\lambda}, \ \lambda = -\sqrt{2}\tan(\sqrt{2}r)$  we get

$$\varphi \varphi_1 X = \varphi^2 X = -X, \quad \varphi_1 \varphi X = {\varphi_1}^2 X = -X.$$

From this we know that the formula (\*) is equal to  $-\lambda X$ .

Case A-4.  $X \in T_{\mu} = \{X \mid X \perp \mathbb{H}\xi, \ \varphi X = -\varphi_1 X\}$ . We have  $\varphi \varphi_1 X = -\varphi^2 X = X$ ,  $\varphi_1 \varphi X = -\varphi_1^2 X = X$  for any  $X \in T_{\mu}$ . So we know that they are equal to  $\mu X = 0$ , because  $\mu = 0$ .

Hence we conclude with a remark as follows:

**Remark 3.3.** The shape operator A of real hypersurfaces of Type (A) in  $G_2(\mathbb{C}^{m+2})$  satisfies the condition (\*).

Second, let us check whether the shape operator A of real hypersurfaces of Type (B) satisfies the condition (\*). As is well known to us, a real hypersurface of Type (B) has five distinct constant principal curvatures as follows [3]:

**Proposition B.** Let M be a connected real hypersurface of  $G_2(\mathbb{C}^{m+2})$ . Suppose that  $A\mathfrak{D} \subset \mathfrak{D}$ ,  $A\xi = \alpha \xi$ , and  $\xi$  is tangent to  $\mathfrak{D}$ . Then the quaternionic dimension m of  $G_2(\mathbb{C}^{m+2})$  is even, say m = 2n, and M has five distinct constant principal curvatures

$$\alpha = -2\tan(2r), \quad \beta = 2\cot(2r), \quad \gamma = 0, \quad \lambda = \cot(r), \quad \mu = -\tan(r)$$

with some  $r \in (0, \pi/4)$ . The corresponding multiplicities are

$$m(\alpha) = 1$$
,  $m(\beta) = 3 = m(\gamma)$ ,  $m(\lambda) = 4n - 4 = m(\mu)$ 

and the corresponding eigenspaces are

$$T_{\alpha} = \mathbb{R}\xi = \operatorname{Span}\{\xi\},$$

$$T_{\beta} = \mathfrak{J}J\xi = \operatorname{Span}\{\xi_{\nu} \mid \nu = 1, 2, 3\},$$

$$T_{\gamma} = \mathfrak{J}\xi = \operatorname{Span}\{\varphi_{\nu}\xi \mid \nu = 1, 2, 3\},$$

$$T_{\lambda}, \quad T_{\mu},$$

where

$$T_{\lambda} \oplus T_{\mu} = (\mathbb{HC}\xi)^{\perp}, \quad \mathfrak{J}T_{\lambda} = T_{\lambda}, \quad \mathfrak{J}T_{\mu} = T_{\mu}, \quad JT_{\lambda} = T_{\mu}.$$

Here we suppose that a real hypersurface of Type (B) has the commuting shape operator A, that is, the shape operator A of M satisfies the commuting condition  $\varphi \varphi_1 AX = A \varphi_1 \varphi X$  for any tangent vector field X on M. Then we see that

$$\varphi \varphi_1 A \xi = A \varphi_1 \varphi \xi \Leftrightarrow \varphi \varphi_1 A \xi - A \varphi_1 \varphi \xi = 0$$

$$\Leftrightarrow \varphi \varphi_1 A \xi = 0$$

$$\Leftrightarrow \alpha \varphi \varphi_1 \xi = 0 \quad \text{(because } \xi \in T_\alpha \text{)}$$

$$\Leftrightarrow \alpha \varphi^2 \xi_1 = 0 \quad \text{(by eq: (2.4))}$$

$$\Leftrightarrow -\alpha \xi_1 = 0 \quad \text{(by eq: (2.2))}$$

$$\Leftrightarrow \alpha = 0. \quad \text{(because } \xi_1 \text{: unit)}$$

But this case can not occur for any  $r \in (0, \pi/4)$ . In fact,  $\alpha = -2\tan(2r)$  is non-vanishing in  $(0, \pi/4)$ . So we also state the following remark:

**Remark 3.4.** The shape operators A of real hypersurfaces of Type (B) in  $G_2(\mathbb{C}^{m+2})$  do not satisfy the commuting condition (\*).

# 4. The proof of the Main Theorem

In this section, we assume that M is a Hopf hypersurface in  $G_2(\mathbb{C}^{m+2})$  with commuting shape operator, that is, the shape operator satisfies the condition (\*). Then by Lemma 3.1 we consider the following two cases:

Case I: the Reeb vector field  $\xi$  belongs to the distribution  $\mathfrak{D}$ ,

Case II: the Reeb vector field  $\xi$  belongs to the distribution  $\mathfrak{D}^{\perp}$ .

First, let us consider Case I, that is,  $\xi \in \mathfrak{D}$ .

To consider this case, we recall a one theorem by Lee and Suh [5] as follows:

**Theorem C.** Let M be a connected orientable Hopf hypersurface in  $G_2(\mathbb{C}^{m+2})$ ,  $m \geq 3$ . Then the Reeb vector field  $\xi$  belongs to the distribution  $\mathfrak{D}$  if and only if M is locally congruent to an open part of a tube around a totally geodesic  $\mathbb{H}P^n$  in  $G_2(\mathbb{C}^{m+2})$ , where m=2n.

Then from Theorem C, we see that M is locally congruent to a real hypersurface of Type (B) under our assumption. But in Section 3 we have checked that the shape operator A of real hypersurface of Type (B) does not satisfy the condition (\*) (see Remark 3.4). From these facts, first we assert the following:

**Theorem 4.1.** There does not exist any Hopf hypersurface in  $G_2(\mathbb{C}^{m+2})$ ,  $m \ge 3$ , with the commuting shape operator  $\varphi \varphi_1 A = A \varphi_1 \varphi$  if the Reeb vector field  $\xi$  belongs to the distribution  $\mathfrak{D}$ .

Next we consider the case  $\xi \in \mathfrak{D}^{\perp}$ . Accordingly, we may put  $\xi = \xi_1$ . Then we have the following:

**Lemma 4.2.** Let M be a hypersurface in complex two-plane Grassmannians  $G_2(\mathbb{C}^{m+2})$ ,  $m \geq 3$  with  $\xi \in \mathfrak{D}^{\perp}$ . If M has commuting shape operator, that is, the shape operator A on M satisfies the condition (\*), then the distribution  $\mathfrak{D}^{\perp}$  is invariant under the shape operator A on M.

Proof. Since  $\xi \in \mathfrak{D}^{\perp}$ , let us assume  $\xi = \xi_1$ . Substituting  $X = \xi$  in our assumption (\*), we have

$$\varphi \varphi_1 A \xi = 0.$$

Applying  $\varphi$  in the above equation, it becomes

$$\varphi_1 A \xi = \eta(\varphi_1 A \xi) \xi.$$

Taking an inner product with  $\xi_1$ , we obtain  $\eta(\varphi_1 A \xi) \eta(\xi_1) = 0$ . Since  $\xi = \xi_1$ , it means that  $\eta(\varphi_1 A \xi) = 0$ . So, we have

$$\varphi_1 A \xi = 0.$$

From this, we have  $A\xi = \alpha\xi$  where  $\alpha = g(A\xi, \xi_1) = g(A\xi, \xi)$ , because  $\xi = \xi_1$ . Moreover, from (2.4), we see that

(4.1) 
$$\varphi_1 \varphi X = \varphi \varphi_1 X - \eta_1(X) \xi + \eta(X) \xi_1$$
$$= \varphi \varphi_1 X$$

for any tangent vector field X on M.

Thus we can write the condition (\*) as

$$(4.2) \varphi \varphi_1 A X = A \varphi_1 \varphi X = A \varphi \varphi_1 X$$

for any tangent vector field X on M.

Now putting  $X = \xi_{\nu}$ ,  $\nu = 2,3$  in (4.2), this equation can be written as

$$(4.3) \varphi \varphi_1 A \xi_{\nu} = A \varphi \varphi_1 \xi_{\nu}, \quad \nu = 2, 3.$$

From Lemma 3.2, we have  $A\xi_{\nu} \in \mathfrak{D}^{\perp}$ ,  $\nu = 2, 3$  under our assumption. This completes the proof of our Lemma.

Therefore from Theorem A in the Introduction, we conclude the following:

**Lemma 4.3.** Let M be a connected hypersurface in complex two-plane Grassmannians  $G_2(\mathbb{C}^{m+2})$ ,  $m \geq 3$  satisfying the commuting condition (\*). If the Reeb vector field  $\xi$  belongs to the distribution  $\mathfrak{D}^{\perp}$ , then M is locally congruent to an open part of a tube around a totally geodesic  $G_2(\mathbb{C}^{m+1})$  in  $G_2(\mathbb{C}^{m+2})$ .

As mentioned in Remark 3.3 in Section 3, the shape operator A for real hypersurfaces of Type (A) satisfies the commuting condition (\*) for any tangent vector field on M. From this fact and Lemma 4.3, we arrive at the following:

**Theorem 4.4.** Let M be a connected hypersurface in complex two-plane Grassmannians  $G_2(\mathbb{C}^{m+2})$ ,  $m \ge 3$  satisfying the commuting condition (\*). Then the Reeb vector field  $\xi$  belongs to the distribution  $\mathfrak{D}^{\perp}$  if and only if M is locally congruent to an open part of a tube around a totally geodesic  $G_2(\mathbb{C}^{m+1})$  in  $G_2(\mathbb{C}^{m+2})$ .

Summing up Lemma 3.1, and Theorems 4.1 and 4.4, we give a complete proof of our Main Theorem from the Introduction.  $\Box$ 

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