

**REGULAR EIGENVALUE PROBLEM WITH EIGENPARAMETER
CONTAINED IN THE EQUATION AND THE BOUNDARY CONDITIONS**

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ABSTRACT. The purpose of this paper is to establish the expansion theorem for a regular right-definite eigenvalue problem for the Laplace operator in R^n , ($n \geq 2$) with an eigenvalue parameter λ contained in the equation and the Robin boundary conditions on two "parts" of a smooth boundary of a simply connected bounded domain.

KEY WORDS AND PHRASES. An expansion theorem, a regular right-definite eigenvalue problem, an eigenparameter in Robin boundary conditions, a simply connected bounded domain with a smooth boundary.

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1. INTRODUCTION.

Regular right-definite eigenvalue problems for ordinary differential equations with eigenvalue parameter in the boundary conditions have been studied by Fulton [1], Hinton [2], Ibrahim [3], Schneider [4], Walter [5], Zayed and Ibrahim [6], Zayed [7] and many others, while in the present paper we shall study regular right-definite eigenvalue problems for partial differential equations with eigenvalue parameter in Robin boundary conditions.

The object of this paper is to prove the expansion theorem for the following problem:

Let $\Omega \subseteq R^n$, ($n \geq 2$) be a simply connected bounded domain with a smooth boundary $\partial\Omega$. Consider the partial differential equation

$$\tau u := \frac{1}{r}(-\Delta_n u) = \lambda u \quad \text{in } \Omega, \quad (1.1)$$

together with the Robin boundary conditions

$$u_\nu + h_1(x)u = \lambda u \quad \text{on } \Gamma, \quad (1.2)$$

and

$$u_{\nu} + h_2(\underline{x})u = \lambda u \quad \text{on } \partial\Omega \setminus \Gamma \quad (1.3)$$

where we assume throughout that

(i) $\Delta_n = \sum_{i=1}^n \frac{\partial^2}{\partial x_i^2}$ is the Laplace operator in R^n , ($n \geq 2$).

(ii) $u_{\nu} = \sum_{i=1}^n u_{x_i}(\underline{x})v_i(\underline{x})$ denotes differentiation of $u(\underline{x})$ along the outward unit normal $\nu(\underline{x}) = (\nu_1(\underline{x}), \dots, \nu_n(\underline{x}))$ to the boundary $\partial\Omega$, where $\underline{x} = (x_1, \dots, x_n)$ is a generic point in the Euclidean space R^n .

(iii) The weight function $r(\underline{x})$ is a real-valued positive function with $r \in C^{\alpha}(\bar{\Omega})$, $\bar{\Omega} = \Omega \cup \partial\Omega$ where $C^{\alpha}(\bar{\Omega})$ is the space of all Hölder continuous functions with exponent α , $0 < \alpha < 1$ which are defined on $\bar{\Omega}$, while $C^{k+\alpha}(\bar{\Omega})$ denotes the space of all functions in $C^k(\bar{\Omega})$ whose derivatives are Hölder continuous with exponent α .

(iv) $h_1(\underline{x})$, ($\underline{x} \in \Gamma$) and $h_2(\underline{x})$, ($\underline{x} \in \partial\Omega \setminus \Gamma$) are non-negative real functions, where Γ is a part of the boundary $\partial\Omega$ while $\partial\Omega \setminus \Gamma$ is the remaining part of $\partial\Omega$.

(v) λ is a complex number.

If $\lambda = 0$, $h_1(\underline{x}) = -\mu$, $h_2(\underline{x}) = 0$, then problem (1.1)-(1.3) reduces to

$$\Delta_n u = 0 \quad \text{in } \Omega, \quad (1.4)$$

$$u_{\nu} = \mu u \quad \text{on } \Gamma, \quad (1.5)$$

$$u_{\nu} = 0 \quad \text{on } \partial\Omega \setminus \Gamma, \quad (1.6)$$

wherein μ is an eigenvalue parameter. The eigenvalue problem (1.4)-(1.6) is called a "Steklov problem", which has been studied by Canavati and Minzoni [8], Odhnoff [9] and many others. Odhnoff's approach is to give problem (1.4)-(1.6) an operator-theoretic formulation by associating with it a semi-bounded self-adjoint extension operator A and to obtain a direct expansion theorem by using the spectral resolution of A . Moreover, Odhnoff proved that there exists a complete set of generalized eigenfunctions of every self-adjoint extension operator A . Canavati and Minzoni have associated with problem (1.4)-(1.6) a self-adjoint operator L which has compact resolvent and they have shown that the spectrum of L consists of a sequence $\{\lambda_j\}$ of non-negative eigenvalues such that $\lambda_j \rightarrow 0$ as $j \rightarrow \infty$. Furthermore, they have derived an eigenfunction expansion by using a suitable Green's function.

Recently, Ibrahim [3] has discussed the eigenvalue equation (1.1) together with the Robin boundary condition

$$u_{\nu} + h(\underline{x})u = \lambda u \quad \text{on } \partial\Omega, \quad (1.7)$$

where $h(\underline{x})$ is a non-negative real function on the whole boundary $\partial\Omega$. Ibrahim's approach is to give the regular right-definite eigenvalue problem (1.1) and (1.7) an operator-theoretic formulation by associating with it a self-adjoint operator A with compact resolvent in a suitable Hilbert space H and he has shown that the spectrum of A consists of an unbounded sequence of eigenvalues $\{\lambda_j\}$ such that $\lambda_j \rightarrow \infty$ as $j \rightarrow \infty$ and also that the corresponding eigenfunctions of A form a complete fundamental system in H .

In this paper, our approach is to find a suitable Hilbert space H and an essentially self-adjoint operator A with compact resolvent defined in H in such a way that problem (1.1)-(1.3) can be considered as an eigenvalue problem of this operator.

2. HILBERT SPACE FORMULATION.

Let $L^2_r(\Omega)$, $L^2(\Gamma)$ and $L^2(\partial\Omega \setminus \Gamma)$ be three complex Hilbert spaces of Lebesgue measurable functions $f(x)$ in Ω , on Γ and on $\partial\Omega \setminus \Gamma$ respectively, satisfying

(i) $\int_{\Omega} r(x) |f(x)|^2 dx < \infty$,

(ii) $\int_{\Gamma} |f(x)|^2 ds_1 < \infty$,

and

(iii) $\int_{\partial\Omega \setminus \Gamma} |f(x)|^2 ds_2 < \infty$.

DEFINITION 2.1. We define a Hilbert space H of three-component vectors by

$$H = L^2_r(\Omega) \oplus L^2(\Gamma) \oplus L^2(\partial\Omega \setminus \Gamma); \tag{2.1}$$

with inner product

$$\langle f, g \rangle = \int_{\Omega} r(x) \overline{f_1(x)} g_1(x) dx + \int_{\Gamma} \overline{f_2(x)} g_2(x) ds_1 + \int_{\partial\Omega \setminus \Gamma} \overline{f_3(x)} g_3(x) ds_2, \tag{2.2}$$

and norm

$$\|f\|^2 = \int_{\Omega} r(x) |f_1(x)|^2 dx + \int_{\Gamma} |f_2(x)|^2 ds_1 + \int_{\partial\Omega \setminus \Gamma} |f_3(x)|^2 ds_2, \tag{2.3}$$

for each $f = (f_1, f_2, f_3)$ and $g = (g_1, g_2, g_3)$ in H , where $dx = dx_1 \dots dx_n$ is the volume element corresponding to Ω while ds_1 and ds_2 are the surface elements corresponding to Γ and $\partial\Omega \setminus \Gamma$ respectively.

DEFINITION 2.2. Let H_1 be a set of all those elements f satisfying

$$f \in C^1(\overline{\Omega}) \cap C^2(\Omega) \quad \text{and} \quad \Delta_n f \in L^2_r(\Omega).$$

We define a linear operator $A: D(A) \rightarrow H$ by

$$Af = (\tau f_1, f_{1\nu} + h_1(x) f_1, f_{1\nu} + h_2(x) f_1) \tag{2.4}$$

for each $f = (f_1, f_2, f_3)$ in $D(A)$, in which the domain $D(A)$ of A is defined as follows:

$$D(A) = \{ (f|_{\Omega}, f|_{\Gamma}, f|_{\partial\Omega \setminus \Gamma}) \in H : f \in H_1 \}$$

where $f|_{\Omega}$, $f|_{\Gamma}$ and $f|_{\partial\Omega \setminus \Gamma}$ are restrictions of f on Ω , on Γ and on $\partial\Omega \setminus \Gamma$ respectively.

REMARK 2.1. The parameter λ is an eigenvalue and f_1 is a corresponding eigenfunction of problem (1.1)-(1.3) if and only if

$$f = (f_1, f_2, f_3) \in D(A) \quad \text{and} \quad Af = \lambda f. \tag{2.5}$$

Therefore, the eigenvalues and the eigenfunctions of problem (1.1)-(1.3) are equivalent to the eigenvalues and the eigenfunctions of operator A in H .

REMARK 2.2. $D(A)$ is a dense subset of H with respect to the inner product (2.2).

LEMMA 2.1. The linear operator A in H is symmetric.

PROOF. Let $f = (f_1, f_2, f_3)$ and $g = (g_1, g_2, g_3)$ be any two elements in $D(A)$, then

$$\begin{aligned} \langle Af, g \rangle = & - \int_{\Omega} \{ \Delta_n f_1(x) \} \overline{g_1(x)} dx + \int_{\Gamma} \{ f_{1\nu}(x) + h_1(x) f_1(x) \} \overline{g_2(x)} ds_1 + \\ & + \int_{\partial\Omega \setminus \Gamma} \{ f_{1\nu}(x) + h_2(x) f_1(x) \} \overline{g_3(x)} ds_2. \end{aligned} \tag{2.6}$$

Making use of first Green's formula [10, p. 50] in (2.6), we obtain

$$\begin{aligned} \langle Af, g \rangle &= \int_{\Omega} (\text{grad } f_1, \text{grad } g_1) dx + \int_{\Gamma} f_1(x) h_1(x) \overline{g_1(x)} dS_1 + \\ &+ \int_{\partial\Omega \setminus \Gamma} f_1(x) h_2(x) \overline{g_1(x)} dS_2. \end{aligned} \quad (2.7)$$

where

$$(\text{grad } f_1, \text{grad } g_1) = \sum_{i=1}^n f_{1x_i}(x) \overline{g_{1x_i}(x)} \quad \text{for } x \in \Omega.$$

Applying a similar argument, it follows that

$$\begin{aligned} \langle f, Ag \rangle &= \int_{\Omega} (\text{grad } f_1, \text{grad } g_1) dx + \int_{\Gamma} f_1(x) h_1(x) \overline{g_1(x)} dS_1 + \\ &+ \int_{\partial\Omega \setminus \Gamma} f_1(x) h_2(x) \overline{g_1(x)} dS_2. \end{aligned} \quad (2.8)$$

From (2.7) and (2.8) we find that

$$\langle Af, g \rangle = \langle f, Ag \rangle. \quad (2.9)$$

Therefore A is a symmetric linear operator in H.

LEMMA 2.2. Let $f = (f_1, f_2, f_3) \in C^1(\overline{\Omega})$ be a complex-valued function. Then

$$\begin{aligned} \int_{\Omega} |f_1(x)|^2 dx &\leq 16\mu^2 \int_{\Omega} |\text{grad } f_1(x)|^2 dx + 2\mu \int_{\Gamma} |f_2(x)|^2 dS_1 + \\ &+ 2\mu \int_{\partial\Omega \setminus \Gamma} |f_3(x)|^2 dS_2 \end{aligned} \quad (2.10)$$

where

$$\mu = \sup\{|x_1| : x = (x_1, \dots, x_n) \in \Omega\}.$$

PROOF. Since $|f_1(x)|$ is a real-valued function and $|f_1(x)| \in C^1(\overline{\Omega})$, then by using Theorem 2 in [10, p. 67], we have

$$\begin{aligned} \int_{\Omega} |f_1(x)|^2 dx &\leq 4\mu^2 \int_{\Omega} \sum_{i=1}^n \{|f_1(x)|_{x_i}\}^2 dx + 2\mu \int_{\Gamma} |f_2(x)|^2 dS_1 + \\ &+ 2\mu \int_{\partial\Omega \setminus \Gamma} |f_3(x)|^2 dS_2. \end{aligned} \quad (2.11)$$

Substituting the inequality

$$\{|f_1(x)|_{x_i}\}^2 \leq 4\{|f_{1x_i}(x)|\}^2, \quad x \in \Omega,$$

into (2.11) we arrive at (2.10).

REMARK 2.3. Since A in H is symmetric, then it has only real eigenvalues.

3. THE BOUNDEDNESS.

We shall show that the linear operator A in H is bounded from below, unbounded from above and strictly positive.

LEMMA 3.1. The linear operator A in H is bounded from below.

PROOF. Let $f = (f_1, f_2, f_3)$ be any element in D(A). We have

$$\begin{aligned} \langle Af, f \rangle &= - \int_{\Omega} \{\Delta_n f_1(x)\} \overline{f_1(x)} dx + \int_{\Gamma} \{f_{1\nu}(x) + h_1(x) f_1(x)\} \overline{f_2(x)} dS_1 + \\ &+ \int_{\partial\Omega \setminus \Gamma} \{f_{1\nu}(x) + h_2(x) f_1(x)\} \overline{f_3(x)} dS_2. \end{aligned} \quad (3.1)$$

By using the first Green's formula, (3.1) becomes

$$\langle Af, f \rangle = \int_{\Omega} |\text{grad } f_1(x)|^2 dx + \int_{\Gamma} h_1(x) |f_2(x)|^2 dS_1 + \int_{\partial\Omega \setminus \Gamma} h_2(x) |f_3(x)|^2 dS_2 \quad (3.2)$$

With $\beta = \max\{16\mu^2, 2\mu, 2\mu\}$, Lemma 2.2. gives the inequality

$$\frac{1}{\beta} \int_{\Omega} |f_1(\underline{x})|^2 dx - \int_{\Gamma} |f_2(\underline{x})|^2 dS_1 - \int_{\partial\Omega \setminus \Gamma} |f_3(\underline{x})|^2 dS_2 \leq \int_{\Omega} |\text{grad } f_1(\underline{x})|^2 dx. \quad (3.3)$$

Substituting (3.3) into (3.2), we have

$$\begin{aligned} \langle Af, f \rangle &\geq \frac{1}{\beta} \int_{\Omega} \frac{1}{r(\underline{x})} r(\underline{x}) |f_1(\underline{x})|^2 dx + \int_{\Gamma} \{h_1(\underline{x})-1\} |f_2(\underline{x})|^2 dS_1 + \\ &+ \int_{\partial\Omega \setminus \Gamma} \{h_2(\underline{x})-1\} |f_3(\underline{x})|^2 dS_2 \geq C_0 \|f\|^2, \end{aligned} \quad (3.4)$$

where

$$C_0 = \min\left\{\frac{1}{\beta} \inf_{\underline{x} \in \Omega} \frac{1}{r(\underline{x})}, \inf_{\underline{x} \in \Gamma} [h_1(\underline{x})-1], \inf_{\underline{x} \in \partial\Omega \setminus \Gamma} [h_2(\underline{x})-1]\right\}. \quad (3.5)$$

This proves that the linear operator A in H is bounded from below.

REMARK 3.1.

(i) Since $r(\underline{x}) > 0$ for $\underline{x} \in \Omega$, and if $h_1(\underline{x}) > 1$ for $\underline{x} \in \Gamma$ and if $h_2(\underline{x}) > 1$ for $\underline{x} \in \partial\Omega \setminus \Gamma$ then $C_0 > 0$ and consequently the linear operator A in H is strictly

positive. We assume these conditions on $h_1(\underline{x})$ and $h_2(\underline{x})$ for the remainder of the paper.

(ii) Since A in H is strictly positive, then $\lambda = 0$ is not an eigenvalue of A in H.

LEMMA 3.2. The linear operator A in H is unbounded from above.

PROOF. Let $\chi(\underline{x})$ be a test function with the compact support on $\bar{\Omega}$ and define a sequence of this test function in D(A) by

$$\chi_N(\underline{x}) = \chi(N\underline{x}), \quad \underline{x} \in \bar{\Omega}, \quad N = 1, 2, \dots$$

By using the same argument of Lemma 3.1, we find that

$$\langle A\chi_N, \chi_N \rangle \geq C_1 N^4 \|\chi_N\|^2 \quad (3.6)$$

where C_1 is a positive constant.

Taking the limit as $N \rightarrow \infty$ in (3.6), we obtain

$$\lim_{N \rightarrow \infty} \langle A\chi_N, \chi_N \rangle = \infty. \quad (3.7)$$

In other words, A is unbounded from above.

REMARK 3.2.

(i) Since A in H is bounded from below, then the set of all eigenvalues of A is also bounded from below by the constant C_0 defined by (3.5).

(ii) Since A in H is unbounded from above, then the set of all eigenvalues is too.

DEFINITION 3.1. The linear operator A in H is said to be essentially self-adjoint if

(i) A in H is symmetric

(ii) $(A + iE)D(A)$ and $(A - iE)D(A)$ are dense in H, where E is the identity operator and $i = \sqrt{-1}$ (see [10, p. 172]).

REMARK 3.3. Since A in H is symmetric, then $\pm i$ cannot be an eigenvalue of A.

LEMMA 3.3. The linear operator A in H is essentially self-adjoint.

PROOF. We must prove that $(A \pm iE)D(A)$ is dense in H . Suppose the contrary; first of all, suppose that $(A + iE)D(A)$ is not dense in H . Then there exists a non-zero element $0 \neq f = (f_1, f_2, f_3) \in H$ such that

$$\langle f, (A + iE)g \rangle = 0, \quad \forall g = (g_1, g_2, g_3) \in D(A).$$

By using the same argument of Lemma 2.1, we find that

$$\langle (A - iE)f, g \rangle = 0, \quad \forall g \in C^1(\bar{\Omega}) \cap C^2(\Omega),$$

which means that $(A - iE)f = 0$ and consequently $Af = if$.

Since $f \in H$, it follows that $Af \in H$. Thus $f \in D(A)$ and since $f \neq 0$, then $+i$ must be an eigenvalue of A . This contradicts the fact that A in H is symmetric.

Similarly, we can show that $(A - iE)D(A)$ is dense in H .

4. THE RESOLVENT OPERATOR.

Since $\lambda = 0$ is not an eigenvalue of the linear operator A in H , then the inverse operator A^{-1} of A exists in H . To study the operator A^{-1} it is convenient to give an explicit formula for it in terms of the Robin's function $R(\underline{x}, \underline{y})$ for the Laplacian Δ_n on Ω .

Here it is difficult to characterize $D(A^{-1}) = R(A)$, the range of A , exactly.

In any case, it is not true that

$$D(A^{-1}) = \{(f|_{\Omega}, f|_{\Gamma}, f|_{\partial\Omega \setminus \Gamma}) \in H : f \in C^0(\bar{\Omega})\};$$

because for such an f we cannot in general find $u = (u_1, u_2, u_3) \in D(A)$ with $Au = f$. Hence we define A^{-1} in H by

$$D(A^{-1}) = \{(f|_{\Omega}, f|_{\Gamma}, f|_{\partial\Omega \setminus \Gamma}) \in H : f \in C^\alpha(\bar{\Omega})\}, \tag{4.1}$$

and

$$A^{-1} : D(A^{-1}) \rightarrow H,$$

$$A^{-1}f = \left(\int_{\Omega} R(\underline{x}, \underline{y}) f_1(\underline{y}) r(\underline{y}) d\underline{y}, \int_{\Gamma} R(\underline{x}, \underline{y}) f_2(\underline{y}) dS_1, \int_{\partial\Omega \setminus \Gamma} R(\underline{x}, \underline{y}) f_3(\underline{y}) dS_2 \right), \tag{4.2}$$

for each $f = (f_1, f_2, f_3) \in D(A^{-1})$.

REMARK 4.1.

- (i) $D(A^{-1})$ is dense in H .
- (ii) A^{-1} is a linear operator in H .

REMARK 4.2.

The Robin's function $R(\underline{x}, \underline{y})$ for fixed $\underline{x} \in \bar{\Omega}$ is a fundamental solution of Δ_n with respect to Ω (see [10], [11]), i.e.,

$$R(\underline{x}, \underline{y}) = S(\underline{x}, \underline{y}) + K(\underline{x}, \underline{y}) \tag{4.3}$$

where $S(\underline{x}, \underline{y})$ is a singularity function defined as follows:

$$S(\underline{x}, \underline{y}) = \begin{cases} \frac{1}{(n-2)\omega_n} |\underline{x} - \underline{y}|^{2-n} & \text{for } n > 2, \\ -\frac{1}{2\pi} \log |\underline{x} - \underline{y}| & \text{for } n = 2, \end{cases} \tag{4.4}$$

which is the solution of the equation $\Delta_n u = 0$ for $\underline{x} \neq \underline{y}$, where ω_n denotes the surface of the unit ball in R^n , while $K(\underline{x}, \underline{y})$ is a regular function satisfying the following:

$$K(\underline{x}, \underline{y}) \in C^1(\bar{\Omega}) \cap C^2(\Omega),$$

$$\Delta_{\underline{n}} K(\underline{x}, \underline{y}) = 0 \quad \text{in } \Omega,$$

$$K_{\underline{v}}(\underline{x}, \underline{y}) + h_1(\underline{y})K(\underline{x}, \underline{y}) = -(S_{\underline{v}}(\underline{x}, \underline{y}) + h_1(\underline{y})S(\underline{x}, \underline{y})) \quad \text{on } \Gamma,$$

and

$$K_{\underline{v}}(\underline{x}, \underline{y}) + h_2(\underline{y})K(\underline{x}, \underline{y}) = -(S_{\underline{v}}(\underline{x}, \underline{y}) + h_2(\underline{y})S(\underline{x}, \underline{y})) \quad \text{on } \partial\Omega \setminus \Gamma.$$

DEFINITION 4.1. We define the linear operators B_1, B_2, B_3 as follows:

(i) $D(B_1) = \{u \in L^2_{\underline{r}}(\Omega) : u \in C^0(\bar{\Omega})\},$

$$B_1 u = \int_{\Omega} R(\underline{x}, \underline{y}) u(\underline{y}) r(\underline{y}) d\underline{y},$$

for each $u \in D(B_1).$

(ii) $D(B_2) = \{u \in L^2(\Gamma) : u \in C^0(\bar{\Omega})\},$

$$B_2 u = \int_{\Gamma} R(\underline{x}, \underline{y}) u(\underline{y}) dS_1,$$

for each $u \in D(B_2).$

(iii) $D(B_3) = \{u \in L^2(\partial\Omega \setminus \Gamma) : u \in C^0(\bar{\Omega})\},$

$$B_3 u = \int_{\partial\Omega \setminus \Gamma} R(\underline{x}, \underline{y}) u(\underline{y}) dS_2,$$

for each $u \in D(B_3).$

REMARK 4.3.

(i) With reference to [10, p. 128] we conclude that the linear operators B_1, B_2, B_3 are compact in $L^2_{\underline{r}}(\Omega), L^2(\Gamma), L^2(\partial\Omega \setminus \Gamma)$ respectively. Consequently, formula (4.2) shows that A^{-1} is also compact.

(ii) From Lemmas 2.1, 3.1, 3.2 and theorem 3 in [10, p. 60], we deduce that the set of all eigenvalues of A , counted according to multiplicity, forms an increasing sequence

$$0 < C_0 \leq \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_j \leq \dots, \quad \lambda_j \rightarrow \infty \quad \text{as } j \rightarrow \infty.$$

(iii) Since A in H is symmetric, then A^{-1} in H is also symmetric.

(iv) Since $D(A^{-1}) \neq H$, then only the closure of A^{-1} is self-adjoint.

(v) On using theorem 3 in [10, p. 30] we deduce that the density of $D(A)$ in H gives us the completeness of the orthonormal system of the eigenfunctions $\phi_1, \phi_2, \phi_3, \dots$ of the operator A .

5. AN EXPANSION THEOREM.

We now arrive at the problem of expanding an arbitrary function $f \in H$ in terms of the eigenfunctions $\{\phi_j\}_{j=1}^{\infty}$ of the operator A .

The results of our investigations are summarized in the following theorem:

THEOREM 5.1. The spectrum of A consists of an unbounded sequence of real eigenvalues of finite multiplicity without accumulation point in $(-\infty, \infty)$.

Denoting them by

$$0 < \lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \dots$$

and the corresponding eigenfunctions by $\phi_1, \phi_2, \phi_3, \dots$, we have $\{\phi_j\}_{j=1}^{\infty}$ forms a complete fundamental system in H and for every $f \in H$ we have the expansion formula

$$f = \sum_{j=1}^{\infty} \langle f, \phi_j \rangle \phi_j \tag{5.1}$$

in the sense of strong convergence in H .

The above theorem has some interesting corollaries for particular choices of the function $f \in H$.

COROLLARY 5.1. If $f = (f_1, f_2, 0) \in H$, $f_1 \in L^2_r(\Omega)$ and $f_2 \in L^2(\Gamma)$ then we have

$$f_1(x) = \sum_{j=1}^{\infty} \left\{ \int_{\Omega} r(x) f_1(x) \phi_{j1}(x) dx + \int_{\Gamma} f_2(x) \phi_{j2}(x) dS_1 \right\} \phi_{j1}(x),$$

$$f_2(x) = \sum_{j=1}^{\infty} \left\{ \int_{\Omega} r(x) f_1(x) \phi_{j1}(x) dx + \int_{\Gamma} f_2(x) \phi_{j2}(x) dS_1 \right\} \phi_{j2}(x),$$

and

$$0 = \sum_{j=1}^{\infty} \left\{ \int_{\Omega} r(x) f_1(x) \phi_{j1}(x) dx + \int_{\Gamma} f_2(x) \phi_{j2}(x) dS_1 \right\} \phi_{j3}(x).$$

COROLLARY 5.2. If $f = (f_1, 0, f_3) \in H$, $f_1 \in L^2_r(\Omega)$ and $f_3 \in L^2(\partial\Omega \setminus \Gamma)$ then we have

$$f_1(x) = \sum_{j=1}^{\infty} \left\{ \int_{\Omega} r(x) f_1(x) \phi_{j1}(x) dx + \int_{\partial\Omega \setminus \Gamma} f_3(x) \phi_{j3}(x) dS_2 \right\} \phi_{j1}(x),$$

$$0 = \sum_{j=1}^{\infty} \left\{ \int_{\Omega} r(x) f_1(x) \phi_{j1}(x) dx + \int_{\partial\Omega \setminus \Gamma} f_3(x) \phi_{j3}(x) dS_2 \right\} \phi_{j2}(x),$$

and

$$f_3(x) = \sum_{j=1}^{\infty} \left\{ \int_{\Omega} r(x) f_1(x) \phi_{j1}(x) dx + \int_{\partial\Omega \setminus \Gamma} f_3(x) \phi_{j3}(x) dS_2 \right\} \phi_{j3}(x).$$

COROLLARY 5.3. If $f = (0, f_2, f_3) \in H$, $f_2 \in L^2(\Gamma)$ and $f_3 \in L^2(\partial\Omega \setminus \Gamma)$ then we have

$$0 = \sum_{j=1}^{\infty} \left\{ \int_{\Gamma} f_2(x) \phi_{j2}(x) dS_1 + \int_{\partial\Omega \setminus \Gamma} f_3(x) \phi_{j3}(x) dS_2 \right\} \phi_{j1}(x),$$

$$f_2(x) = \sum_{j=1}^{\infty} \left\{ \int_{\Gamma} f_2(x) \phi_{j2}(x) dS_1 + \int_{\partial\Omega \setminus \Gamma} f_3(x) \phi_{j3}(x) dS_2 \right\} \phi_{j2}(x),$$

and

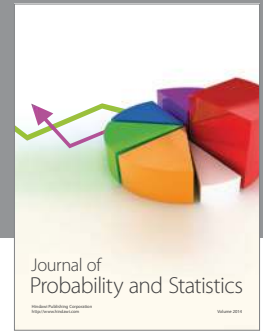
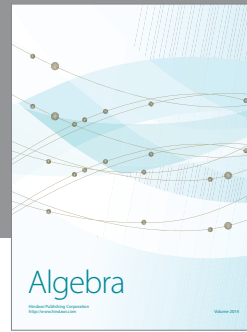
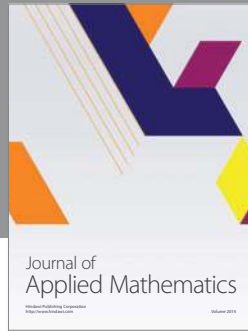
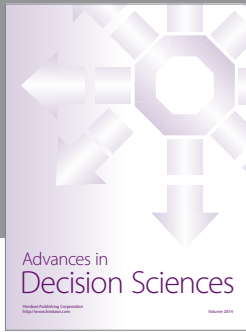
$$f_3(x) = \sum_{j=1}^{\infty} \left\{ \int_{\Gamma} f_2(x) \phi_{j2}(x) dS_1 + \int_{\partial\Omega \setminus \Gamma} f_3(x) \phi_{j3}(x) dS_2 \right\} \phi_{j3}(x).$$

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