

REGULARITY CRITERION ON WEAK SOLUTIONS TO THE NAVIER-STOKES EQUATIONS

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ABSTRACT. Consider a weak solution u of the Navier-Stokes equations in the class $L^2((0, T); \dot{X}_1(\mathbb{R}^d)^d)$. We establish a new approach to treat the regularity problem for the Navier-Stokes equation in term of the multiplier space $\dot{X}_1(\mathbb{R}^d)$.

1. Introduction

Consider the Navier-Stokes equations in $(0, T) \times \mathbb{R}^d$ with $0 < T < \infty$ and $d \geq 3$:

$$(1.1) \quad \begin{aligned} \partial_t u + (u \cdot \nabla) u - \Delta u + \nabla p &= 0, & (x, t) \in \mathbb{R}^d \times (0, \infty), \\ \nabla \cdot u &= 0, & (x, t) \in \mathbb{R}^d \times (0, \infty), \\ u(x, 0) &= a(x), & x \in \mathbb{R}^d, \end{aligned}$$

where $u = u(x, t)$ is the velocity field, $p = p(x, t)$ is the scalar pressure and $a(x)$ with $\operatorname{div} a = 0$ in the sense of distribution is the initial velocity field. For simplicity, we assume that the external force has a scalar potential and is included into the pressure gradient.

In their famous paper, Leray [12] and Hopf [6] constructed a weak solution u of (1.1) for arbitrary $a \in L^2_\sigma$. The solution is called the Leray-Hopf weak solution. In the general case the problem on uniqueness and regularity of Leray-Hopf's weak solutions are still open question. Masuda [14] extended Serrin's class for uniqueness of weak solutions and made it clear that the class $L^\infty((0, T); L^d(\mathbb{R}^d))$ plays an important role for uniqueness of weak solutions. Kozono-Sohr [8] showed that the uniqueness holds in $L^\infty((0, T); L^d)$.

Foias [4] and Serrin [16] introduced the class $L^\alpha((0, \infty); L^q)$ and showed that under the additional assumption

$$u \in L^\alpha((0, \infty); L^q) \quad \text{for} \quad \frac{2}{\alpha} + \frac{d}{q} = 1 \quad \text{with} \quad q > d,$$

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u is the only weak solution.

The purpose of this paper is to improve the criterion on regularity of weak solutions to in the class $L^2((0, T); \dot{X}_1(\mathbb{R}^d)^d)$. We know that for every $a \in L^2_\sigma(\mathbb{R}^d)$, there is at least one weak solution u of (1.1) satisfying the energy inequality :

$$\|u(t)\|_{L^2}^2 + 2 \int_0^t \|\nabla u(\tau)\|_{L^2}^2 d\tau \leq \|a\|_{L^2}^2.$$

This is the solution obtained by Leray [12] in the class $L^\infty((0, T); L^2_\sigma) \cap L^2((0, T); \dot{H}^1_\sigma)$ and satisfying (1.1) in the sense of distributions. The natural regularity obtained from the above energy inequality is that

$$u \in L^\alpha((0, T); L^q(\mathbb{R}^d)) \quad \text{for} \quad \frac{2}{\alpha} + \frac{d}{q} = 2 \quad \text{with} \quad 2 \leq q \leq \frac{2d}{d-2}.$$

If Leray's weak solution u satisfies the following

$$u \in L^\alpha((0, T); L^q(\mathbb{R}^d)) \quad \text{for} \quad \frac{2}{\alpha} + \frac{d}{q} = 1 \quad \text{with} \quad q > d,$$

then u is regular on $(0, T)$. For more facts concerning regularity of weak solutions, we refer to a celebrated paper of Kozono-Sohr [8].

1.1. *BMO* and Hardy space $\mathcal{H}^1(\mathbb{R}^d)$

We recall that a locally summable function g on \mathbb{R}^d is said to have bounded mean oscillation if

$$\|g\|_{BMO} = \sup_{x,R} \frac{1}{|B(x,R)|} \int_{B(x,R)} |g(y) - g_{B(x,R)}| dy < \infty,$$

where

$$g_{B(x,R)} = \frac{1}{|B(x,R)|} \int_{B(x,R)} g(y) dy.$$

The class of functions of bounded mean oscillation is denoted by *BMO* and often is referred as John-Nirenberg space.

Note that

$$\|g\|_{BMO} = 0 \quad \text{if and only if} \quad g = \text{const.}$$

It is thus natural to consider the quotient space BMO/\mathbb{R} with the norm induced by $\|\cdot\|_{BMO}$. Then BMO/\mathbb{R} is a Banach space, which will also be denoted *BMO* for simplicity. We easily see that $L^\infty \subset BMO$ with continuous injection. For $f(x) = \log|x|$, we have $f \in BMO$ but $f \notin L^\infty$, so *BMO* is strictly larger than L^∞ .

Next, we recall the definition and some of the main properties of Hardy spaces $\mathcal{H}^p(\mathbb{R}^d)$ introduced by E. Stein and G. Weiss [18] (for more facts on these spaces see C. Fefferman and E. Stein [5]).

Definition 1 ([5]). Let $0 < p < \infty$, and let $\varphi \in \mathcal{S}(\mathbb{R}^d)$ satisfy $\int_{\mathbb{R}^d} \varphi dx = 1$. A tempered distribution f belongs to the Hardy space $\mathcal{H}^p(\mathbb{R}^d)$ if

$$(1.2) \quad f^*(x) = \sup_{t>0} |(\varphi_t * f)(x)| \in L^p(\mathbb{R}^d),$$

where $\varphi_t(x) = t^{-d}\varphi(t^{-1}x)$.

It is known that if $f \in \mathcal{H}^p(\mathbb{R}^d)$, then (1.2) holds for all $\varphi \in \mathcal{S}(\mathbb{R}^d)$ satisfying $\int_{\mathbb{R}^d} \varphi dx = 1$. The (quasi)-norm of $\mathcal{H}^p(\mathbb{R}^d)$ is defined, up to equivalence, by

$$\|f\|_{\mathcal{H}^p(\mathbb{R}^d)} = \|f^*(x)\|_{L^p(\mathbb{R}^d)} = \left(\int_{\mathbb{R}^d} |f^*(x)|^p dx \right)^{\frac{1}{p}}.$$

We know by ([5], [17]) that if $1 \leq p < \infty$, then \mathcal{H}^p is a Banach space :

$$\begin{aligned} \mathcal{H}^p(\mathbb{R}^d) &= L^p(\mathbb{R}^d) \quad \text{for } 1 < p < \infty, \\ \mathcal{H}^1(\mathbb{R}^d) &\subset L^1(\mathbb{R}^d) \quad \text{with continuous injection,} \end{aligned}$$

and that $\mathcal{H}^p(\mathbb{R}^d)$, $0 < p < 1$, are quasi-Banach spaces in the quasi-norm $\|\cdot\|_{\mathcal{H}^p(\mathbb{R}^d)}$.

The crucial fact for our purpose is the boundedness of the Riesz transforms R_j on all of the spaces \mathcal{H}^p . Furthermore, an L^1 -function f on \mathbb{R}^d belongs to $\mathcal{H}^1(\mathbb{R}^d)$ if and only if its Riesz transforms $R_j f$ all belong to $L^1(\mathbb{R}^d)$ and

$$\|f\|_{\mathcal{H}^1(\mathbb{R}^d)} \cong \|f\|_{L^1(\mathbb{R}^d)} + \sum_{j=1}^d \|R_j f\|_{L^1(\mathbb{R}^d)} \quad (\text{equivalent norms}).$$

Notice that all function $f \in \mathcal{H}^1(\mathbb{R}^d)$ satisfy

$$(1.3) \quad \int_{\mathbb{R}^d} f(x) dx = 0.$$

Indeed, the assumption $f \in \mathcal{H}^1(\mathbb{R}^d)$ implies that the Fourier transforms

$$\widehat{f}(\xi) = \int f(x)e^{-ix\xi} dx \quad \text{and} \quad \widehat{R_j f}(\xi) = \frac{i\xi_j}{|\xi|} \widehat{f}(\xi), \quad (j = 1, \dots, d),$$

are all continuous on \mathbb{R}^d , so $\widehat{f}(0) = 0$, and (1.3) is proved.

A fundamental theorem in the theory of Hardy spaces $\mathcal{H}^1(\mathbb{R}^d)$ developed by C. Fefferman and E. Stein [5] asserts

Theorem 1 (Fefferman). *The dual space of $\mathcal{H}^1(\mathbb{R}^d)$ is BMO. More precisely, L is a continuous linear functional on $\mathcal{H}^1(\mathbb{R}^d)$ if and only if it can be represented*

as

$$L(f) = \int_{\mathbb{R}^d} fg$$

for some function g in BMO, moreover for any $g \in BMO$ and any $f \in \mathcal{H}^1(\mathbb{R}^d)$ we have

$$(1.4) \quad \left| \int_{\mathbb{R}^d} fg dx \right| \leq c(d) \|f\|_{\mathcal{H}^1} \|g\|_{BMO}.$$

Let $\gamma > 1$. We define the maximal function of f depending on γ ,

$$M_\gamma f(x) = \sup_{t>0} \left(\frac{1}{|B_t(x)|} \int_{B_t(x)} |f(y)|^\gamma dy \right)^{\frac{1}{\gamma}}.$$

We begin by establishing the following result which is a variant of the Hardy-Littlewood maximal theorem. We need

Lemma 1. *If $\gamma < p \leq \infty$, then*

$$M_\gamma : L^p(\mathbb{R}^d) \rightarrow L^p(\mathbb{R}^d) \quad \text{is bounded.}$$

See [17] for the proof.

In [2], Coifman, Lions, Meyer, and Semmes, it was shown that the Hardy spaces can be used to analyze the regularity of the various nonlinear quantities by the compensated compactness theory due to L. Murat [13] and F. Tartar [15]. Since then, these spaces play an important role in studying the regularity of solutions to partial differential equations. In particular, it was shown that for exponents p, q with $1 < p < \infty$, $\frac{1}{p} + \frac{1}{q} = 1$, and vector fields $u \in L^p(\mathbb{R}^d)^d$, $v \in L^q(\mathbb{R}^d)^d$ with $\text{div } u = 0$, $\text{curl } v = 0$ in the sense of distributions, the scalar product $u \cdot v$ belongs to the Hardy space $\mathcal{H}^1(\mathbb{R}^d)$. Moreover, there exists a positive constant C such that

$$\|u \cdot v\|_{\mathcal{H}^1(\mathbb{R}^d)} \leq C \|u\|_{L^p} \|v\|_{L^q}.$$

The main purpose of this subsection is to prove two facts about div-curl lemma without assuming any a priori assumptions on exact cancelation, namely the divergence and curl need not be zero, and which lead to $\text{div}(uv)$ being in the Hardy space $\mathcal{H}^1(\mathbb{R}^d)$.

The proof will be divided into two parts. In part 1, we consider the case u and v are supported on the ball $|x| \leq R_0$ where $R_0 > 1$ is a positive constant to be determined later, while in part 2, the general case follows by partition of unity. In order to simplify the presentation, we take $p = q = 2$.

The Sobolev space $H_p^1(\mathbb{R}^d)$, $1 \leq p < \infty$, consists of functions $f \in L^p(\mathbb{R}^d)$ such that $|\nabla f| \in L^p(\mathbb{R}^d)$. It is a Banach space with respect to the norm

$$\|f\|_{H_p^1} = \|f\|_{L^p} + \|\nabla f\|_{L^p}.$$

Specifically, we will prove

Theorem 2. *Let $u \in H_p^1(\mathbb{R}^d)^d$ and $v \in H_q^1(\mathbb{R}^d)$, $p > 1$, $\frac{1}{p} + \frac{1}{q} = 1$. Then there exists a positive constant $C(d)$ such that*

$$(1.5) \quad \|\operatorname{div}(uv)\|_{\mathcal{H}^1(\mathbb{R}^d)} \leq C (\|u\|_{L^p} \|\nabla v\|_{L^q} + \|\operatorname{div} u\|_{L^p} \|v\|_{L^q}).$$

Remark 1. Such inequalities and their generalizations are useful in hydrodynamics. Reader is referred, in particular to [2], [3].

Theorem 2 is a generalized version of the “div-curl” lemma ([2], Theorem II.1). Observe that when $\operatorname{div} u = 0$, Theorem 2 reduces to the classical div-curl lemma [2].

The following result due to [2], shows the importance of the Hardy space theory in estimating the non-linear term $u \cdot \nabla v$ attached to the Navier-Stokes equations and this produces a useful tool for PDE.

Lemma 2. *Let $1 < p < \infty$, $1 < q < d$ and $\frac{1}{r} = \frac{1}{p} + \frac{1}{q} < \frac{1}{d} + 1$. If $u \in L^p(\mathbb{R}^d)^d$ with $\nabla \cdot u = 0$ and $\nabla v \in L^q(\mathbb{R}^d)$. Then*

$$u \cdot \nabla v \in \mathcal{H}^r(\mathbb{R}^d),$$

and

$$\|u \cdot \nabla v\|_{\mathcal{H}^r(\mathbb{R}^d)} \leq C \|u\|_{L^p} \|\nabla v\|_{L^q}.$$

Proof. The result is due to [2]; but we give it here a detailed proof for the reader’s convenience. Observe that

$$f = u \cdot \nabla v = \nabla \cdot (u \otimes (v - c))$$

for an arbitrary constant vector c . So we get

$$(\varphi_t * f)(x) = t^{-d-1} \int_{B_t(x)} (\nabla \varphi)(t^{-1}(x - y)) u(y) (v(y) - m_B(v)) dy,$$

where

$$m_B(v) = \frac{1}{|B_t(x)|} \int_{B_t(x)} v(y) dy.$$

Taking

$$1 < \gamma < \infty, \quad 1 < \beta < d, \quad \text{with} \quad \frac{1}{\gamma} + \frac{1}{\beta} = 1 + \frac{1}{d},$$

and writing

$$\frac{1}{\beta^*} = \frac{1}{\beta} - \frac{1}{d},$$

we see by Poincaré-Sobolev inequality that

$$\begin{aligned} |(\varphi_t * f)(x)| &\leq \frac{C}{t^{d+1}} \left(\int_{B_t(x)} |u(y)|^\gamma dy \right)^{\frac{1}{\gamma}} \left(\int_{B_t(x)} |v(y) - m_B(v)|^{\beta^*} dy \right)^{\frac{1}{\beta^*}} \\ &\leq \frac{C}{t^{d+1}} \left(\int_{B_t(x)} |u(y)|^\gamma dy \right)^{\frac{1}{\gamma}} \left(\int_{B_t(x)} |\nabla v(y)|^\beta dy \right)^{\frac{1}{\beta}} \\ &= C \left(\frac{1}{|B_t(x)|} \int_{B_t(x)} |u(y)|^\gamma dy \right)^{\frac{1}{\gamma}} \left(\frac{1}{|B_t(x)|} \int_{B_t(x)} |\nabla v(y)|^\beta dy \right)^{\frac{1}{\beta}} \\ &\leq C (M_\gamma u)(x) \cdot (M_\beta(\nabla v))(x). \end{aligned}$$

We thus obtain

$$\sup_{t>0} |(\varphi_t * f)(x)| \leq C (M_\gamma u)(x) \cdot (M_\beta(\nabla v))(x).$$

Since we can take γ and β so that

$$1 < \gamma < p, \quad 1 < \beta < q < d,$$

it follows from Lemma 1 that

$$\|M_\gamma u\|_{L^p} \leq C \|u\|_{L^p}, \quad \|M_\beta(\nabla v)\|_{L^q} \leq C \|\nabla v\|_{L^q}.$$

Lemma 2 now follows from Hölder's inequality :

$$\|f \cdot g\|_{L^r} \leq \|f\|_{L^p} \|g\|_{L^q} \quad \left(0 < p < \infty, 0 < q < \infty, \frac{1}{r} = \frac{1}{p} + \frac{1}{q} \right).$$

This finishes the proof of the lemma. □

We are now in a position to proof Theorem 2.

Proof. To prove this, we distinguish three cases.

Case A. Let us assume first that

$$\nabla \cdot u = 0.$$

In this case we get

$$\operatorname{div}(vu) = (\nabla v) \cdot u + v \operatorname{div} u = u \cdot \nabla v.$$

Then we have $u \in L^p(\mathbb{R}^d)^d$, $\nabla v \in L^q(\mathbb{R}^d)$ with $\operatorname{div} u = 0$, $\operatorname{curl}(\nabla v) = 0$ in the sense of distributions. It follows from Lemma 2 that

$$u \cdot \nabla v \in \mathcal{H}^1(\mathbb{R}^d)$$

and there exists an absolute constant C such that

$$\|\operatorname{div}(vu)\|_{\mathcal{H}^1(\mathbb{R}^d)} \leq C \|u\|_{L^p} \|\nabla v\|_{L^q}.$$

Case B. We may of course suppose under additional assumptions that u and v are supported on the ball $|x| \leq R_0$. In order to simplify the presentation, we take $p = q = 2$. We shall write Ω for the ball in \mathbb{R}^d of radius R_0 centered at the origin. By $H_0^1(\Omega)$ we denote the closed subspace of $H^1(\Omega)$ which is the closure of $C_0^\infty(\Omega)$ in the H^1 norm. Let

$$g = \operatorname{div} u \in L^2(\mathbb{R}^d).$$

By the classical result (see e.g. [20]) we know that

$$g = \partial_1 g_1 + \cdots + \partial_d g_d,$$

where g_1, \dots, g_d belong to $H_0^1(\Omega)$. Setting

$$G = (g_1, \dots, g_d) \quad \text{and} \quad r = u - G.$$

Then it follows that

$$\operatorname{div} r = 0 \quad \text{and} \quad r \in L^2(\Omega).$$

Using Lemma 2 we infer

$$\operatorname{div}(rv) \in \mathcal{H}^1(\mathbb{R}^d).$$

Further we set

$$f = \operatorname{div}(Gv).$$

For this purpose we use Lemma 3 below, it follows that $f \in \mathcal{H}^1(\mathbb{R}^d)$.

Case C. The general case. We call φ a smooth bump function with compact support such that

$$1 = \sum_{k \in \mathbb{Z}^d} \varphi^2(x - k).$$

We have thus, if f and g are two functions,

$$\begin{aligned} f(x)g(x) &= \sum_{k \in \mathbb{Z}^d} f(x)\varphi^2(x - k)g(x) \\ &= \sum_{k \in \mathbb{Z}^d} f_k(x)g_k(x), \end{aligned}$$

where

$$f_k(x) = \varphi(x - k)f(x) \quad \text{and} \quad g_k(x) = \varphi(x - k)g(x).$$

Now set

$$u_k(x) = \varphi(x - k)u(x) \quad \text{and} \quad v_k(x) = \varphi(x - k)v(x)$$

for $k \in \mathbb{Z}^d$. We then have

$$\operatorname{div}(uv) = \sum_{k \in \mathbb{Z}^d} (u_k v_k) = \sum_{k \in \mathbb{Z}^d} w_k, \quad w_k = \operatorname{div}(u_k v_k).$$

We are going to check that

$$\sum_{k \in \mathbb{Z}^d} \|w_k\|_{\mathcal{H}^1(\mathbb{R}^d)} < \infty.$$

To do this, we apply the local version (**Case A**) and it follows

$$\begin{aligned} \|w_k\|_{\mathcal{H}^1(\mathbb{R}^d)} &\leq C (\|u_k\|_{L^2} + \|\operatorname{div} u_k\|_{L^2}) (\|v_k\|_{L^2} + \|\operatorname{div} v_k\|_{L^2}) \\ &= \epsilon_k \in l^1(\mathbb{Z}^d). \end{aligned}$$

Up to now we have proved

$$(1.6) \quad \|\operatorname{div}(uv)\|_{\mathcal{H}^1(\mathbb{R}^d)} \leq C (\|u\|_{L^2} + \|\operatorname{div} u\|_{L^2}) (\|v\|_{L^2} + \|\operatorname{div} v\|_{L^2}).$$

This automatically yields the estimate

$$(1.7) \quad \|\operatorname{div}(uv)\|_{\mathcal{H}^1(\mathbb{R}^d)} \leq C (\|u\|_{L^2} \|\nabla v\|_{L^2} + \|v\|_{L^2} \|\operatorname{div} u\|_{L^2}).$$

To see this, we may replace u in the inequality above by

$$u = \delta^{(\frac{1}{2} - \frac{d}{2})} u\left(\frac{x}{\delta}\right), \quad \text{whenever } 0 < \delta < \infty.$$

and similarly v by

$$v_\delta = \delta^{(\frac{1}{2} - \frac{d}{2})} v\left(\frac{x}{\delta}\right), \quad \text{whenever } 0 < \delta < \infty.$$

Thus the left-hand side of (1.6) fortunately does not change, while at right-hand we get rid the undesirable terms by letting δ either to 0, or to $+\infty$. This completes the proof. \square

Now we turn to the proof of Lemma 3. One can show that every function $f \in L^p(\mathbb{R}^d)$, $p \in (1, +\infty]$, with compact support and $\int f dx = 0$ belongs to $\mathcal{H}^1(\mathbb{R}^d)$. In particular,

Lemma 3. *If $d^* = \frac{d}{d-1}$, $f \in L^{d^*}$, $\operatorname{supp} f \subset \bar{\Omega}$ and*

$$\int f dx = 0,$$

then $f \in \mathcal{H}^1(\mathbb{R}^d)$.

Proof. We have

$$f = \operatorname{div}(G)v + G \cdot \nabla v$$

and we have to prove that the two terms belong to L^{d^*} . We consider the first term on the right. Since $\nabla v \in L^2$, we have

$$\operatorname{div}(G) \in L^2 \quad \text{and} \quad v \in L^q, \quad \text{where} \quad \frac{1}{2} - \frac{1}{q} = \frac{1}{d}.$$

Thus,

$$v \operatorname{div}(G) \in L^{d^*}.$$

A similar argument works in the second term and this completes the proof of the lemma. \square

1.2. Multipliers and Morrey-Campanato spaces

In this section, we give a description of the multiplier space \dot{X}_r introduced recently by P. G. Lemarié-Rieusset in his work [10] (see also [11]). The space \dot{X}_r of pointwise multipliers which map L^2 into \dot{H}^{-r} is defined in the following way

Definition 2. For $0 \leq r < \frac{d}{2}$, we define the homogeneous space \dot{X}_r by

$$\dot{X}_r = \left\{ f \in L^2_{loc} : \forall g \in \dot{H}^{-r} \quad fg \in L^2 \right\},$$

where we denote by $\dot{H}^{-r}(\mathbb{R}^d)$ the completion of the space $\mathcal{D}(\mathbb{R}^d)$ with respect to the norm $\|u\|_{\dot{H}^{-r}} = \left\| (-\Delta)^{\frac{r}{2}} u \right\|_{L^2}$.

The norm of \dot{X}_r is given by the operator norm of pointwise multiplication

$$\|f\|_{\dot{X}_r} = \sup_{\|g\|_{\dot{H}^{-r}} \leq 1} \|fg\|_{L^2}.$$

Similarly, we define the nonhomogeneous space X_r for $0 \leq r < \frac{d}{2}$ equipped with the norm

$$\|f\|_{X_r} = \sup_{\|g\|_{H^r} \leq 1} \|fg\|_{L^2}.$$

We have the homogeneity properties : $\forall x_0 \in \mathbb{R}^d$

$$\begin{aligned} \|f(x + x_0)\|_{X_r} &= \|f\|_{X_r} \\ \|f(x + x_0)\|_{\dot{X}_r} &= \|f\|_{\dot{X}_r} \\ \|f(\lambda x)\|_{X_r} &\leq \frac{1}{\lambda^r} \|f\|_{X_r}, \quad 0 < \lambda \leq 1 \\ \|f(\lambda x)\|_{\dot{X}_r} &\leq \frac{1}{\lambda^r} \|f\|_{\dot{X}_r}, \quad \lambda > 0. \end{aligned}$$

The following imbedding

$$\begin{aligned} L^{\frac{d}{t}} &\subset X_r, \quad 0 \leq r < \frac{d}{2}, \quad 0 \leq t \leq r. \\ L^{\frac{d}{t}} &\subset \dot{X}_r, \quad 0 \leq r < \frac{d}{2} \end{aligned}$$

holds.

Example 1. If $u(x) \in \mathcal{D}(\mathbb{R}^d)$, $\varphi(x) = \left(\sum_{k=1}^d |x_k|^{\gamma_k} \right)^{-1}$, $\gamma_k > 0$, $d > 2$, and

$\sum_{k=1}^d \gamma_k^{-1} = \frac{d}{2}$, then

$$\int_{\mathbb{R}^d} \varphi(x) |u(x)|^2 dx \leq C \int_{\mathbb{R}^d} |\nabla u(x)|^2 dx$$

and $\varphi \in X_1(\mathbb{R}^d)$.

Indeed, the inequality

$$\begin{aligned} & \int_{\lambda < |x| < 2\lambda} \varphi(x) |u(x)|^2 dx \\ & \leq \left[\int_{\lambda < |x| < 2\lambda} |u(x)|^{\frac{2d}{d-2}} dx \right]^{\frac{d-2}{2}} \cdot \left[\int_{\lambda < |x| < 2\lambda} \varphi(x)^{\frac{d}{2}} dx \right]^{\frac{2}{d}} \end{aligned}$$

and the Sobolev theorem imply that for $\lambda > 0$

$$\begin{aligned} & \int_{\lambda < |x| < 2\lambda} \varphi(x) |u(x)|^2 dx \\ & \leq C \left[\int_{\lambda < |x| < 2\lambda} |\nabla u(x)|^2 dx + \int_{\lambda < |x| < 2\lambda} \frac{|u(x)|^2}{|x|^2} dx \right] \cdot \left[\int_{\lambda < |x| < 2\lambda} \varphi(x)^{\frac{d}{2}} dx \right]^{\frac{2}{d}}, \end{aligned}$$

where C does not depend on λ . Let us estimate the integral

$$S(\lambda) = \int_{\lambda < |x| < 2\lambda} \varphi(x)^{\frac{d}{2}} dx.$$

The domain $\lambda < |x| < 2\lambda$ can be represented as a finite sum of domain $\Omega_{j\lambda}$ such that $|x_j| > \frac{\lambda}{2}$ if $x \in \Omega_{j\lambda}$ for $j = 1, \dots, d$. Let for instance $|x_1| > \frac{\lambda}{2}$. Then

$$\int_{\Omega_{j\lambda}} \varphi(x)^{\frac{d}{2}} dx \leq \frac{3\lambda}{2} \int_{\lambda < |x| < 2\lambda} \frac{dx_1 \cdots dx_d}{\left(\left(\frac{\lambda}{2}\right)^{\gamma_1} + |x_2|^{\gamma_2} + \cdots + |x_d|^{\gamma_d} \right)^{\frac{d}{2}}}.$$

The substitution $x_j = t_j \left(\frac{\lambda}{2}\right)^{\frac{\gamma_1}{\gamma_j}}$ gives the relations

$$\begin{aligned} S(\lambda) & \leq C \int_{\mathbb{R}^{d-1}} \frac{dt_1 \cdots dt_d}{(1 + |t_2|^{\gamma_2} + \cdots + |t_d|^{\gamma_d})^{\frac{d}{2}}} \\ & \leq C, \end{aligned}$$

since the integral is converging. To see this, set $t_s = \tau_s^{\frac{1}{\gamma_s}}$. Then

$$\int_{\mathbb{R}^{d-1}} \frac{dt_1 \cdots dt_d}{(1 + |t_2|^{\gamma_2} + \cdots + |t_d|^{\gamma_d})^{\frac{d}{2}}}$$

$$\begin{aligned} &\leq C \int_{\mathbb{R}^{d-1}} \frac{|\tau|^{\frac{1}{\gamma_2} + \dots + \frac{1}{\gamma_d} - (d-1)}}{(1 + |\tau|)^{\frac{d}{2}}} d\tau_1 \cdots d\tau_d \\ &\leq C \int_0^\infty \frac{d|\tau|}{(1 + |\tau|)^{\frac{1}{\gamma} + 1}} < \infty. \end{aligned}$$

Therefore,

$$\int_{\lambda < |x| < 2\lambda} \varphi(x) |u(x)|^2 dx \leq C_5 \left[\int_{\lambda < |x| < 2\lambda} |\nabla u(x)|^2 dx + \int_{\lambda < |x| < 2\lambda} \frac{|u(x)|^2}{|x|^2} dx \right].$$

Setting $\lambda = 2^m$, $m \in \mathbb{Z}$ and assuming these inequalities over all m , we obtain that

$$\int_{\mathbb{R}^d} \varphi(x) |u(x)|^2 dx \leq C \left(\int_{\mathbb{R}^d} |\nabla u(x)|^2 dx + \int_{\mathbb{R}^d} \frac{|u(x)|^2}{|x|^2} dx \right).$$

By Hardy's inequality in \mathbb{R}^d , $d \geq 3$

$$\int_{\mathbb{R}^d} \frac{|u(x)|^2}{|x|^2} dx \leq \frac{4}{(d-2)^2} \int_{\mathbb{R}^d} |\nabla u(x)|^2 dx, \quad u(x) \in \mathcal{D}(\mathbb{R}^d),$$

and hence

$$\int_{\mathbb{R}^d} \varphi(x) |u(x)|^2 dx \leq C \int_{\mathbb{R}^d} |\nabla u(x)|^2 dx.$$

Now we recall the definition of Morrey-Campanato spaces ([7], [19]):

Definition 3. For $1 < p \leq q \leq +\infty$, the Morrey-Campanato space $\mathcal{M}_{p,q}$ is defined by :

$$(1.8) \quad \mathcal{M}_{p,q} = \left\{ f \in L^p_{loc}(\mathbb{R}^d) : \|f\|_{\mathcal{M}_{p,q}} = \sup_{x \in \mathbb{R}^d} \sup_{0 < R \leq 1} R^{d/q - d/p} \|f(y) 1_{B(x,R)}(y)\|_{L^p(dy)} < \infty \right\}.$$

Let us define the homogeneous Morrey-Campanato spaces $\dot{\mathcal{M}}_{p,q}$ for $1 < p \leq q \leq +\infty$ by

$$(1.9) \quad \|f\|_{\dot{\mathcal{M}}_{p,q}} = \sup_{x \in \mathbb{R}^d} \sup_{R > 0} R^{d/q - d/p} \left(\int_{B(x,R)} |f(y)|^p dy \right)^{1/p}.$$

It is easy to check the following properties :

$$\begin{aligned} \|f(\lambda x)\|_{\mathcal{M}_{p,q}} &= \frac{1}{\lambda^{\frac{d}{q}}} \|f\|_{\mathcal{M}_{p,q}}, \quad 0 < \lambda \leq 1, \\ \|f(\lambda x)\|_{\dot{\mathcal{M}}_{p,q}} &= \frac{1}{\lambda^{\frac{d}{q}}} \|f\|_{\dot{\mathcal{M}}_{p,q}}, \quad \lambda > 0. \end{aligned}$$

We shall assume the following classical results [7].

- a) For $1 \leq p \leq p'$, $p \leq q \leq +\infty$ and for all function f so that $f \in \dot{\mathcal{M}}_{p,q} \cap L^\infty$:

$$\|f\|_{\dot{\mathcal{M}}_{p',q} \frac{p'}{p}} \leq \|f\|_{L^\infty}^{1-\frac{p}{p'}} \|f\|_{\dot{\mathcal{M}}_{p,q}}^{\frac{p}{p'}}.$$

- b) For p, q, p', q' so that $\frac{1}{p} + \frac{1}{p'} \leq 1$, $\frac{1}{q} + \frac{1}{q'} \leq 1$, $f \in \dot{\mathcal{M}}_{p,q}$, $g \in \dot{\mathcal{M}}_{p',q'}$. Then

$$fg \in \dot{\mathcal{M}}_{p'',q''} \text{ with } \frac{1}{p} + \frac{1}{p'} = \frac{1}{p''}, \frac{1}{q} + \frac{1}{q'} = \frac{1}{q''}.$$

- c) For $1 \leq p \leq d$, we have

$$\forall \lambda > 0, \|\lambda f(\lambda x)\|_{\dot{\mathcal{M}}_{p,d}} = \|f\|_{\dot{\mathcal{M}}_{p,d}}.$$

- d) If $p' < p$,

$$\begin{aligned} \dot{\mathcal{M}}_{p,q} &\subset \mathcal{M}_{p,q}, \\ \dot{\mathcal{M}}_{p,q} &\subset \mathcal{M}_{p',q}. \end{aligned}$$

- e) If $q_2 < q_1$, we have

$$\begin{aligned} \mathcal{M}_{p,q_1} &\subset \mathcal{M}_{p,q_2}, \\ L^q &= \dot{\mathcal{M}}_{q,q} \subset \dot{\mathcal{M}}_{p,q}, \quad p \leq q. \end{aligned}$$

We have the following comparison between multipliers and Morrey-Campanato spaces :

Proposition 1. For $0 \leq r < \frac{d}{2}$, we have

$$\begin{aligned} X_r &\subseteq \mathcal{M}_{2, \frac{d}{r}}, \\ \dot{X}_r &\subseteq \dot{\mathcal{M}}_{2, \frac{d}{r}}. \end{aligned}$$

Proof. Let $f \in X_r$, $0 < R \leq 1$, $x_0 \in \mathbb{R}^d$ and $\phi \in \mathcal{D}$, $\phi \equiv 1$ on $B(\frac{x_0}{R}, 1)$. We have

$$\begin{aligned} R^{r-\frac{d}{2}} \left(\int_{|x-x_0| \leq R} |f(x)|^2 dx \right)^{1/2} &= R^r \left(\int_{|y-\frac{x_0}{R}| \leq 1} |f(Ry)|^2 dy \right)^{1/2} \\ &\leq R^r \left(\int_{y \in \mathbb{R}^d} |f(Ry)\phi(y)|^2 dy \right)^{1/2} \\ &\leq R^r \|f(Ry)\|_{X_r} \|\phi\|_{H^r} \\ &\leq \|f(y)\|_{X_r} \|\phi\|_{H^r} \\ &\leq C \|f(y)\|_{X_r}. \end{aligned}$$

We observe that the same proof is also valid for homogeneous spaces. □

Additionally, for $2 < p \leq \frac{d}{r}$ and $0 \leq r < \frac{d}{2}$, we have the following inclusion relations :

$$L^{\frac{d}{r}}(\mathbb{R}^d) \subset L^{\frac{d}{r}, \infty}(\mathbb{R}^d) \subset \dot{\mathcal{M}}_{p, \frac{d}{r}}(\mathbb{R}^d) \subset \dot{X}_r(\mathbb{R}^d) \subset \dot{\mathcal{M}}_{2, \frac{d}{r}}(\mathbb{R}^d),$$

where $L^{p, \infty}$ denotes the usual Lorentz (weak L^p) space. For the definition and basic properties of Lorentz spaces $L^{p, q}$ we refer to [18].

2. Regularity theorem

In this section we give the regularity criterion by velocity to the Leray type weak solution of the Navier-Stokes equation (1.1). Before turning our attention to regularity issues, we start with some prerequisites for our main result. We use the notations

$$D_j = \frac{\partial}{\partial x_j}, \quad j = 1, \dots, d$$

means the j^{th} partial derivative and

$$\nabla = (D_1, \dots, D_d)$$

the gradient.

$$\nabla^2 = (D_j D_k)_{j, k=1}^d$$

means the matrix of the second order derivatives. Let

$$\begin{aligned} u &: \mathbb{R}^d \rightarrow \mathbb{R}^d \\ x &\mapsto u(x) = (u_1(x), \dots, u_d(x)) \end{aligned}$$

be a vector field. Then we set

$$\begin{aligned} \operatorname{div} u &= \nabla \cdot u = D_1 u_1 + \dots + D_d u_d, \\ \Delta u &= \operatorname{div} \nabla u = (D_1^2 + \dots + D_d^2) u, \\ \nabla u &= (D_1, \dots, D_d) u = (D_j u_k)_{j, k=1}^d, \\ \nabla^2 u &= (D_j D_k)_{j, k=1}^d u = (D_j D_k u_l)_{j, k, l=1}^d, \end{aligned}$$

and

$$\begin{aligned} u \cdot \nabla u &= (u \cdot \nabla) u = (u_1 D_1 + \dots + u_d D_d) u \\ &= (u_1 D_1 u_k + \dots + u_d D_d u_k)_{k=1}^d \end{aligned}$$

whenever this is meaningful. Further we set

$$\begin{aligned} \operatorname{div} (u u) &= D_1 (u_1 u) + \dots + D_d (u_d u) \\ &= (D_1 (u_1 u_k) + \dots + D_d (u_d u_k))_{k=1}^d, \end{aligned}$$

where the matrix $u u = u \otimes u = (u_j u_k)_{j, k=1}^d$ means the usual tensor product. We prefer the simple notation $u u$.

If $\operatorname{div} u = 0$, we call u is divergence free or solenoidal. In this case we get

$$\begin{aligned} u \cdot \nabla u &= D_1(u_1 u) + \dots + D_d(u_d u) - (u_1 D_1 + \dots + u_d D_d) u \\ &= D_1(u_1 u) + \dots + D_d(u_d u) \\ &= \operatorname{div}(u u). \end{aligned}$$

Let

$$C_{0,\sigma}^\infty(\mathbb{R}^d) = \left\{ \varphi \in (C_0^\infty(\mathbb{R}^d))^d : \operatorname{div} \varphi = 0 \right\} \subseteq (C_0^\infty(\mathbb{R}^d))^d.$$

The subspace

$$L_\sigma^2(\mathbb{R}^d) = \overline{C_{0,\sigma}^\infty(\mathbb{R}^d)}^{\|\cdot\|_{L^2}} = \left\{ u \in L^2(\mathbb{R}^d)^d : \operatorname{div} u = 0 \right\}$$

obtained as the closure of $C_{0,\sigma}^\infty$ with respect to L^2 -norm $\|\cdot\|_{L^2}$. H_σ^r denotes the closure of $C_{0,\sigma}^\infty$ with respect to the norm

$$\|u\|_{H^r} = \|u\|_{L^2} + \left\| (1 - \Delta)^{\frac{r}{2}} u \right\|_{L^2} \quad \text{for } r \geq 0.$$

Our definition of Leray-Hopf weak solutions (see e.g., [9], [8]) now reads :

Definition 4 (weak solutions). Let $a \in L_\sigma^2$ and $T > 0$. A measurable function u is called a weak solution of (1.1) on $(0, T)$ if u satisfies the following properties

- (1) $u \in L^\infty((0, T); L_\sigma^2) \cap L^2\left((0, T); \dot{H}_\sigma^1\right)$ for all $T > 0$;
- (2) $u(t)$ is continuous in time in the weak topology of L_σ^2 with

$$\langle u(t), \phi \rangle \rightarrow \langle a, \phi \rangle \quad \text{as } t \rightarrow 0^+$$

for all $\phi \in L_\sigma^2$;

- (3) for any $0 \leq s \leq t \leq T$, u satisfies the identity

$$(2.1) \quad \int_s^t \{ -\langle u, \partial_\tau \phi \rangle + \langle u \cdot \nabla u, \phi \rangle + \langle \nabla u, \nabla \phi \rangle \} d\tau = -\langle u(t), \phi(t) \rangle + \langle u(s), \phi(s) \rangle$$

for all $\phi \in H^1((s, t); H_\sigma^1)$. Here $\langle \cdot, \cdot \rangle$ denotes the scalar product and $\|\cdot\|_{L^2}$ denotes the norm in $L^2(\mathbb{R}^d)^d$.

Remark 2. For u and ϕ as above, the integral

$$\int_0^T \langle u \cdot \nabla u, \phi \rangle d\tau$$

is well defined since we have by the Sobolev inequality

$$\|u\|_{L^{\frac{2d}{d-2}}} \leq C \|\nabla u\|_{L^2}$$

that

$$\begin{aligned} \left| \int_0^T \langle u, \nabla u, \phi \rangle d\tau \right| &\leq \int_0^T \|u\|_{L^{\frac{2d}{d-2}}} \|\nabla u\|_{L^2} \|\phi\|_{L^d} d\tau \\ &\leq C \sup_{0 < t < T} \|\phi\|_{L^d} \int_0^T \|\nabla u\|_{L^2}^2 d\tau. \end{aligned}$$

Existence of weak solutions has been established by Leray in [12] for initial velocity in $L^2_\sigma(\mathbb{R}^d)$. The result is the following

Theorem 3 (Leray - Hopf). *Let $T > 0$. Let $a \in L^2_\sigma(\mathbb{R}^d)$ and*

$$u \in L^\infty((0, T); L^2_\sigma) \cap L^2\left((0, T); \dot{H}^1_\sigma\right)$$

be a weak solution of the Navier-Stokes equation (1.1) satisfying the strong type energy inequality:

$$(2.2) \quad \|u(t)\|_{L^2}^2 + 2 \int_0^t \|\nabla u(s)\|_{L^2}^2 ds \leq \|a\|_{L^2}^2 \quad \text{for a.a. } 0 \leq t < T.$$

We assume that the solution satisfies

$$\|u(t) - a\|_{L^2} \rightarrow 0 \quad \text{as } t \rightarrow +0.$$

Let us introduced the class $L^s((0, T); L^\gamma)$ with the norm $\|\cdot\|_{L^s((0, T); L^\gamma)}$

$$\|u\|_{L^s((0, T); L^\gamma)} = \left(\int_0^T \|u(t)\|_{L^\gamma}^s dt \right)^{\frac{1}{s}}.$$

The classical result on uniqueness and regularity of weak solutions in the class $L^s((0, T); L^\gamma)$ was given by Foias, Serrin and Masuda [4], [16], [14].

Theorem 4 (Foias-Serrin-Masuda). *Let $a \in L^2_\sigma(\mathbb{R}^d)$.*

(i) *Let u and v are two weak solutions of (1.1) on $(0, T)$. Suppose that u satisfies*

$$(2.3) \quad u \in L^s((0, T); L^\gamma) \quad \text{for } \frac{2}{s} + \frac{d}{\gamma} = 1 \quad \text{with } d < \gamma < \infty.$$

Assume that v fulfills the energy inequality (2.2) for $0 \leq t < T$. Then we have $u = v$ on $[0, T)$.

(ii) *Every weak solution u of (1.1) in the class (2.3) satisfies*

$$(2.4) \quad \frac{\partial u}{\partial t}, \frac{\partial^{\alpha_1 + \dots + \alpha_d} u}{\partial x_1^{\alpha_1} \dots \partial x_d^{\alpha_d}} \in C((0, T) \times \mathbb{R}^d)$$

for all multi-indices $\alpha = (\alpha_1, \dots, \alpha_d)$ with $|\alpha| = \alpha_1 + \dots + \alpha_d \leq 2$.

Kozono and Taniuchi [9] proved

Theorem 5 (Kozono-Taniuchi). *Let $a \in L^2_\sigma(\mathbb{R}^d)$.*

- (i) (uniqueness) *Let u, v be two weak solutions of (1.1) on $(0, T)$. Suppose that*

$$u \in L^2((0, T); BMO)$$

and that v satisfies the energy inequality (2.2). Then we have $u = v$ on $[0, T]$.

- (ii) (regularity) *Suppose that u is a weak solution satisfying either of the following conditions*

$$u \in L^2((0, T); BMO) \quad \text{or} \quad \text{rot } u \in L^1((0, T); BMO).$$

Then u is a solution of (1.1) in the class

$$(2.5) \quad u \in C([\epsilon, T]; H^s_\sigma) \cap C^1([\epsilon, T]; H^s) \cap C([\epsilon, T]; H^{s+2}), \quad s > \frac{d}{2} - 1$$

for all $0 < \epsilon < T$. Actually u is regular in $\mathbb{R}^d \times (0, T)$.

Our aim result is to show a new regularity criterion for each of the problems to (1.1).

Theorem 6. *Let u be a smooth solution to (1.1) in some interval $[0, T)$ with initial data $a \in L^2_\sigma(\mathbb{R}^d)^d$. Suppose that the solution u satisfies*

$$\int_0^T \|\nabla u(\tau)\|_{\dot{X}_1(\mathbb{R}^d)}^2 d\tau < \infty.$$

Then the solution

$$u \in C\left((0, T); \dot{H}^1_\sigma(\mathbb{R}^d)^d\right) \cap L^2\left((0, T); \dot{H}^1_\sigma(\mathbb{R}^d)^d \cap H^2(\mathbb{R}^d)^d\right).$$

Moreover,

$$\begin{aligned} & \sup_{0 \leq t < T} \|\nabla u(t)\|_{L^2}^2 + \int_0^T \|\nabla^2 u(\tau)\|_{L^2}^2 d\tau \\ & \leq C \|\nabla u(0)\|_{L^2}^2 \left[1 + \exp\left(c \int_0^T \|\nabla u(\tau)\|_{\dot{X}_1(\mathbb{R}^d)}^2 d\tau\right) \right]. \end{aligned}$$

The same result holds when the assumption $\nabla u \in L^2((0, T); \dot{X}_1(\mathbb{R}^d)^d)$ is replaced by $u \in L^2((0, T); BMO(\mathbb{R}^d)^d)$.

Remark 3. Theorem 6 covers the borderline case $s = 2$ and $\gamma = d$. Our class $L^2((0, T); \dot{X}_1(\mathbb{R}^d)^d)$ is larger than $L^2((0, T); L^d(\mathbb{R}^d)^d)$.

To clarify the main part of the result, we recall the known regularity criterion in the following.

Lemma 4 (Beirão da Veiga [1]). *If we assume the following condition on the gradient of velocity for the Leray-Hopf weak solution u :*

$$(2.6) \quad \int_0^T \|\nabla u(\tau)\|_{L^\gamma}^s d\tau < \infty, \quad \frac{2}{s} + \frac{d}{\gamma} = 2, \quad \frac{d}{2} < \gamma \leq \infty,$$

then the weak solution is smooth on $(0, T]$.

Corollary 1. *If we assume the following condition on the gradient of velocity for the Leray-Hopf weak solution u :*

$$\int_0^T \|\nabla u(\tau)\|_{X_1}^2 d\tau < \infty,$$

then the weak solution is smooth on $(0, T]$.

The marginales case $q = \infty$ was considered by Kozono and Taniuchi in *BMO* frame work.

Lemma 5 (Kozono-Taniuchi [9]). *Instead of the condition (2.6), if we assume the following condition on the vorticity of the weak solution u :*

$$\int_0^T \|\text{rot } u(\tau)\|_{BMO} d\tau < \infty,$$

then the weak solution is smooth on $(0, T]$.

The following lemmas play a fundamental role in estimating the nonlinear term.

Lemma 6. *Let $f \in H^1(\mathbb{R}^d)$, $g(x) = (g_i(x))_{i=1}^d$ with $\nabla \cdot g = 0$ and $g \in L^2(\mathbb{R}^d)^d$. Furthers we assume that $\nabla h \in \dot{X}_1(\mathbb{R}^d)$. Then there exists a constant $C(d) > 0$ independent of f, g and h such that*

$$(2.7) \quad \left| \int_{\mathbb{R}^d} fg \cdot \nabla h dx \right| \leq C \|\nabla f\|_{L^2(\mathbb{R}^d)} \|g\|_{L^2(\mathbb{R}^d)^d} \|\nabla h\|_{\dot{X}_1(\mathbb{R}^d)}$$

and

$$(2.8) \quad \left| \int_{\mathbb{R}^d} \nabla f \cdot gh dx \right| \leq C \|\nabla f\|_{L^2(\mathbb{R}^d)} \|g\|_{L^2(\mathbb{R}^d)^d} \|\nabla h\|_{\dot{X}_1(\mathbb{R}^d)}.$$

Proof. The proof is easy, due to definition of $\dot{X}_1(\mathbb{R}^d)$. Suppose that $\nabla h \in \dot{X}_1(\mathbb{R}^d)$ and using Cauchy-Schwarz inequality, we get

$$\begin{aligned} \left| \int_{\mathbb{R}^d} fg \cdot \nabla h dx \right| &\leq \left(\int_{\mathbb{R}^d} |f|^2 |\nabla h|^2 dx \right)^{\frac{1}{2}} \|g\|_{L^2(\mathbb{R}^d)^d} \\ &\leq C \|\nabla h\|_{\dot{X}_1(\mathbb{R}^d)} \left(\int_{\mathbb{R}^d} |\nabla f|^2 dx \right)^{\frac{1}{2}} \|g\|_{L^2(\mathbb{R}^d)^d}, \end{aligned}$$

where the constant C is independent of f, g and h . Thus the Lemma is proved in the case of (2.7). The proof is similar in the case of (2.8). \square

The same result holds when we replace the assumption $\nabla h \in \dot{X}_1(\mathbb{R}^d)$ by the assumption $h \in H^1(\mathbb{R}^d) \cap BMO(\mathbb{R}^d)$. Indeed, we know that

$$h(x) = \log|x| \in BMO$$

and

$$|\nabla h|^2 \leq \frac{1}{|x|^2},$$

then by Hardy' s inequality in \mathbb{R}^d ($d \geq 3$), we have

$$\int_{\mathbb{R}^d} \frac{|f(x)|^2}{|x|^2} dx \leq C(d) \int_{\mathbb{R}^d} |\nabla f|^2 dx, \quad \forall f \in H^1(\mathbb{R}^d).$$

This remark suggest that the lemma will also be holds when we replace the $\dot{X}_1(\mathbb{R}^d)$ -norm of ∇h by BMO -norm of h . In fact, the following is a combination of the compensated compactness results of Coifman, Lions, Meyer and Semmes [2] and the duality of the space BMO , we have :

Lemma 7. *Let $f \in H^1(\mathbb{R}^d)$, $g = (g_i(x))_{i=1}^d$ with $\nabla \cdot g = 0$ and $g \in L^2(\mathbb{R}^d)^d$ and a function $h \in H^1(\mathbb{R}^d) \cap BMO(\mathbb{R}^d)$. Then there exists a constant $C(d) > 0$ independent of f, g and h such that*

$$(2.9) \quad |\langle g \cdot \nabla f, h \rangle| \leq C \|\nabla f\|_{L^2(\mathbb{R}^d)} \|g\|_{L^2(\mathbb{R}^d)^d} \|h\|_{BMO(\mathbb{R}^d)}.$$

Proof. It is an immediate consequence of Lemma 2 and the duality inequality (1.4)

$$\begin{aligned} |\langle g \cdot \nabla f, h \rangle| &\leq C \|g \cdot \nabla f\|_{\mathcal{H}^1(\mathbb{R}^d)} \|h\|_{BMO(\mathbb{R}^d)} \\ &\leq C \|\nabla f\|_{L^2(\mathbb{R}^d)} \|g\|_{L^2(\mathbb{R}^d)^d} \|h\|_{BMO(\mathbb{R}^d)}. \end{aligned}$$

\square

Next we recall the following well-known result :

Lemma 8 (Poincaré inequality). *Suppose Q is a unit cube in \mathbb{R}^d of side length ρ and f is C^2 on Q with $\nabla f \in L^2(Q)$. There exists c not depending on f such that*

$$(2.10) \quad \int_Q |f - m_Q f|^2 dy \leq c \rho^2 \int_Q |\nabla f(y)|^2 dy,$$

where $m_Q f = \frac{1}{|Q|} \int_Q f(y) dy$ is the integral mean of f on Q .

Combining this result with Proposition 1 gives :

Proposition 2. *If $f \in H^1(\mathbb{R}^d)$ and $\nabla f \in \dot{X}_1(\mathbb{R}^d)$, then*

$$f \in BMO(\mathbb{R}^d).$$

Proof. Since $\dot{X}_1(\mathbb{R}^d) \subset \dot{\mathcal{M}}_{2,d}(\mathbb{R}^d)$, it follows that

$$\nabla f \in \dot{\mathcal{M}}_{2,d}(\mathbb{R}^d).$$

By the classical Poincaré inequality (2.10), we have

$$\begin{aligned} \int_{B(x,R)} |f(y) - m_{B(x,R)} f(y)|^2 dy &\leq C R^2 \int_{B(x,R)} |\nabla f(y)|^2 dy \\ &\leq C R^d \|\nabla f\|_{\dot{\mathcal{M}}_{2,d}}^2 \end{aligned}$$

for every ball $B(x, R)$ of any radius R and there holds

$$\begin{aligned} \|f\|_{BMO}^2 &= \sup_{x \in \mathbb{R}^d} \sup_{R>0} \frac{1}{|B(x, R)|} \int_{B(x,R)} |f(y) - m_{B(x,R)} f(y)|^2 dy \\ &\leq C \|\nabla f\|_{\dot{\mathcal{M}}_{2,d}}^2 \\ &\leq C \|\nabla f\|_{\dot{X}_1(\mathbb{R}^d)}^2. \end{aligned}$$

□

Now we turn into the proof of our Theorem 2.

Proof. Let u be a smooth solution to (1.1) on $[0, T)$. By operating the Laplacian to the equation and then taking a L^2 inner product of the equation with $(-\Delta u)$, we have

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|\nabla u\|_{L^2}^2 + \|\nabla^2 u\|_{L^2}^2 d\tau &= \langle u \cdot \nabla u, \Delta u \rangle - \langle \nabla p, \Delta u \rangle \\ &= \sum_{j,l=1}^d \int_{\mathbb{R}^d} u_j D_j u_l \Delta u_l dx + \langle p, \operatorname{div} \Delta u \rangle \\ &= \sum_{j,l=1}^d \int_{\mathbb{R}^d} u_j D_j u_l \Delta u_l dx, \end{aligned}$$

where we have used

$$\operatorname{div} u = 0 = \operatorname{div} \Delta u.$$

Now, we use integration by parts to have

$$\begin{aligned} & \sum_{j,l=1}^d \int_{\mathbb{R}^d} u_j D_j u_l \Delta u_l dx \\ &= - \sum_{j,k,l=1}^d \int_{\mathbb{R}^d} D_k u_j D_j u_l D_k u_l dx - \sum_{j,k,l=1}^d \int_{\mathbb{R}^d} u_j D_j D_k u_l D_k u_l dx, \end{aligned}$$

or

$$\begin{aligned} \sum_{j,k,l=1}^d \int_{\mathbb{R}^d} u_j D_j (D_k u_l D_k u_l) dx &= \frac{1}{2} \sum_{j=1}^d \int_{\mathbb{R}^d} u_j D_j |\nabla u|^2 dx \\ &= -\frac{1}{2} \int_{\mathbb{R}^d} \operatorname{div} u |\nabla u|^2 dx = 0. \end{aligned}$$

Then

$$\begin{aligned} \sum_{j,l=1}^d \int_{\mathbb{R}^d} u_j D_j u_l \Delta u_l dx &= \sum_{j,k,l=1}^d \int_{\mathbb{R}^d} (D_k u_j) (D_j D_k u_l) u_l dx \\ &= \langle u, \nabla u, \nabla^2 u \rangle. \end{aligned}$$

From Lemma 6 with

$$g = \nabla u, \quad \nabla f = \nabla^2 u \quad \text{and} \quad h = u$$

yields directly

$$|\langle u, \nabla u, \nabla^2 u, \rangle| \leq C \|\nabla u\|_{L^2(\mathbb{R}^d)} \|\nabla^2 u\|_{L^2(\mathbb{R}^d)^d} \|\nabla u\|_{X_1(\mathbb{R}^d)}.$$

By the Young inequality, we have

$$\begin{aligned} & \left| \int_0^t \langle \nabla u, \Delta u, u \rangle d\tau \right| \\ (2.11) \quad & \leq \frac{1}{2} \int_0^t \|\nabla^2 u\|_{L^2(\mathbb{R}^d)}^2 d\tau + \frac{C}{2} \int_0^t \|\nabla u\|_{L^2(\mathbb{R}^d)^d}^2 \|\nabla u\|_{X_1(\mathbb{R}^d)}^2 d\tau. \end{aligned}$$

Hence

$$(2.12) \quad \frac{1}{2} \frac{d}{dt} \|\nabla u(t)\|_{L^2}^2 + \|\nabla^2 u\|_{L^2}^2 d\tau \leq C \int_0^t \|\nabla u\|_{L^2(\cdot)^d}^2 \|\nabla u\|_{X_1(\mathbb{R}^d)}^2 d\tau$$

for all $t > 0$. Since $\nabla u \in L^2\left((0, T); \dot{X}_1(\mathbb{R}^d)^d\right)$, it follows from the Gronwall inequality that

$$\sup_{0 \leq t < T} \|\nabla u(t)\|_{L^2}^2 \leq \|\nabla a\|_{L^2}^2 \left(1 + \exp \left\{ C \int_0^t \|\nabla u\|_{\dot{X}_1(\mathbb{R}^d)}^2 d\tau \right\} \right)$$

from which we get the desired result. \square

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