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Retargetting Motion to New Characters

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Retargetting Motion to New Characters

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Motion Retargetting

Apply the motion of one character to another

- Re-use motions created for another character
- Target character mimics motions
 - -retain the quality of the original motion
- Retain, not necessarily improve, the motion
 - -garbage in, garbage out
 - -aesthetic appropriateness not considered

Motion Retargetting

DDBBBBBB

More Specifically

Focus on characters with same structure

- Corresponding degrees of freedom
 example: articulated figures with same joints
- Use as first step in more general problem
- Parameter values can be transferred
 - -results are may not be the same
 - must adapt motion values (curves)

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Previous Work

- Compute a new motion (parameterized controllers, resynthesis, ...)
- Adjust each frame or key (using inverse kinematics or manual adjustment)
- Apply signal processing to motion
- Use Spacetime Constraints
 - -they're not just for physical synthesis

Why didn't you?

- Synthesize a new motion? We like our original motion!
- Solve the constraints on each frame using IK? Can't preserve temporal characteristics of motion
- Use Signal Processing?
 Doesn't allow for re-satisfying constraints
- Use global optimization (spacetime constraints)?

What is Important?

Change what isn't important to retain what is

- · Hard to define what is important
 - motion specific
 - -high-level qualities
- Stick to what's easy to define
 - -geometric constraints
 - basic signal characteristics



Basic Idea 1: Constraints



Basic geometric constraints are the most critical characteristics of a motion

- These constraints must be maintained when applying the motion to a different character
- Retargetting must adapt a motion to re-establish any violated constraints

Basic Idea 2: Frequency content

High frequencies are significant characteristics of motions

- Altering high frequencies changes motions
- Adaptations should avoid disturbing high frequencies
- Adaptations (not the underlying motion) should be frequency bounded



The Constraint Problem

- · Constraints for specific, geometric attributes
 - -specify position of hand, foot on floor
 - -joint limits, feet above floor
- Constraints placed at specific times
 - -create durations as a series of individual times
- Functions of character's parameters
 - include character's kinematics

The Constraints (notation)

 $\begin{array}{ll} \mbox{Motion} & m(t) \in \Re \Rightarrow \Re^n \\ \mbox{Constraint Function} & f(q) \in \Re^n \Rightarrow \Re \\ \mbox{Constraint} & f(q) = c \\ & f(q) \geq c \\ \mbox{Initial Motion} & m_0(t) \\ \mbox{Each constraint has the form:} \end{array}$

 $f(\mathbf{m}(t_0)) = c \text{ or } f(\mathbf{m}(t_0)) \ge c$

Finding Adaptations



Frequency bounded constraint solving

- Can't consider frames independently
 - Individual changes may add high frequencies
 - -Need to look ahead and behind
- Must consider entire motion simultaneously



Implementing the Frequency Limit

- · Find a motion that:
 - -satisfies the constraints
 - -avoids adding high frequencies
 - minimizes the difference to original
- Impose frequency limits by selecting the form of the answer
- Solve a single, large, numerical problem to compute the adapted motion



What Frequency Limit?

Must pick proper frequency bounds

- Too high?
 - -adds jerkiness to motion
- Too low?
 - overfitting makes "big" changes to motion
- Just right?

Choosing the Frequency Limit

- A Heuristic Method
- Decompose original motion into frequency bands
- Choose highest frequency band with lots of energy
- Or, use trial and error

Constraint Solving: Method 1



Sequential Quadratic Programming (SQP)

- Too few constraints? Many possible solutions
 - -define an objective function to pick "best"
 - -pick simple objective to make easy to solve
- Constrained minimization
- Solve a sequence of linear sub-problems
 linearize non-linear constraints at each step

Constraint Solving: Method 2

Non-linear least squares

- Too many constraints? No exact solution
 minimize residual error
 - -add constraints to make over-determined
- Unconstrained minimization
- Solve a sequence of linear sub-problems – linearize non-linear constraints at each step

Character size not constant

Target size needs to be known in each frame – it doesn't have to be the same



World not constant

Adaptation can change any parameters – not just those for the changed character

- We can choose which parameters are affected by the adaptation
- Solve for everything at once



Different Structure

When the parameters aren't the same, the problem is harder

- Couple corresponding "body" parts
- Characters must be similarly sized
- Retargetting makes characters the same size
- Minimize distance between old and new points
- Must deal with different numbers of parameters



Skipping Can Example

1. human motion

- 2. retarget to canproportioned human
- 3. tie corresponding points
- 4. solve for new motion



Why does it fail?

- Implementation limitations
- Need richer constraints
 - -balance, strength, collision, ballet form, ...
- Fundamental over-simplifications
 - -similarity computed on poses
 - -additive adaptations (no scaling or time-shift)
 - -limit of adaptation (sometimes, need new motions)



Summary

We can retarget motions created for one character to another

- Re-establish geometric constraints
- Avoid adding high frequencies
- Compute adaptation with spacetime constraints

Because I thought you'd ask....

Answers to frequently asked questions

- I don't know.
- Nothing is specific to mocap. That's just what I had.
- Yes, I'd love your examples to try.
- The examples take a few seconds on a mac.
- The heads were lost in a bad mocap accident.
- The method is not specific to articulated figures.
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