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Reynolds-dependence of turbulent skin-friction drag reduction induced by spanwise forcing

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This paper examines how increasing the value of the Reynolds number Re affects the ability of spanwise-forcing techniques to yield turbulent skin-friction drag reduction. The control strategy is the streamwise-travelling waves of spanwise wall velocity (Quadrio *et al. J. Fluid Mech.*, vol. 627, 2009, pp. 161–178). The study builds upon an extensive drag-reduction database created with Direct Numerical Simulation of a turbulent channel flow for two, 5-fold separated values of Re , namely $Re_\tau = 200$ and $Re_\tau = 1000$. The sheer size of the database, which for the first time systematically addresses the amplitude of the forcing, allows a comprehensive view of the drag-reducing characteristics of the travelling waves, and enables a detailed description of the changes occurring when Re increases. The effect of using a viscous scaling based on the friction velocity of either the non-controlled flow or the drag-reduced flow is described. In analogy with other wall-based drag reduction techniques, like for example riblets, the performance of the travelling waves is well described by a vertical shift of the logarithmic portion of the mean streamwise velocity profile. Except when Re is very low, this shift remains constant with Re , at odds with the percentage reduction of the friction coefficient, which is known to present a mild, logarithmic decline. Our new data agree with the available literature, which is however mostly based on low- Re information and hence predicts a quick drop of maximum drag reduction with Re . The present study supports a more optimistic scenario, where for an airplane at flight Reynolds numbers a drag reduction of nearly 30% would still be possible thanks to the travelling waves.

1. Introduction

Reducing the turbulent drag in general, and the turbulent skin-friction drag in particular, is a potentially rewarding technological goal which, however, presents several challenges that span from the understanding of a complex physics to the design of a reliable and affordable control system.

In the last few decades, fundamental research efforts in skin-friction drag reduction met with considerable success, and several viable strategies to reduce drag have been introduced, although often only proofs-of-concept based on numerical simulations or laboratory experiments are available. For obvious reasons, such studies are typically limited to low-Reynolds number flows, and the question naturally arises how to extrapolate the observed performance (in terms of e.g. maximum drag reduction, or energy cost of the

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control technique) to the higher values of the Reynolds number Re typical of most industrial applications.

Some of the earliest techniques, however, have already been demonstrated in the envisaged application: the most notable example is perhaps riblets (Walsh 1980; Bechert & Bartenwerfer 1989; García-Mayoral & Jiménez 2011), i.e. small streamwise-aligned grooves patterned on an otherwise smooth surface, which have been tested on a full-scale airplane in flight conditions (Walsh *et al.* 1989). Although in flight tests an indirect measure of the riblets effectiveness based on changes in fuel consumption is often preferred, in simple and well-controlled laboratory flows like a channel flow the friction drag reduction achieved by riblets is typically characterized in terms of the drag reduction rate \mathcal{R} , defined as the relative change of skin-friction coefficient C_f between the controlled and the reference flow:

$$\mathcal{R} = 1 - \frac{C_f}{C_{f,0}}. \quad (1.1)$$

In this definition, the subscript "0" indicates a quantity measured in the reference flow, and the skin-friction coefficient is defined as

$$C_f = 2 \frac{\tau_w}{\rho U_b^2}, \quad (1.2)$$

where τ_w is the wall-shear stress, ρ is the fluid density and U_b the bulk velocity. The maximum drag reduction for riblets is known (Luchini 1996; Spalart & McLean 2011) to vary with Re , owing to the (mild) Re -dependency of C_f itself. A Re -independent quantification of the riblets ability to reduce drag is obtained by considering riblets as a particular roughness distribution that yields a decrease of the skin friction instead of the typical increase. Hence, drag changes due to riblets can be characterized by a quantity often employed to describe the effects of wall roughness: the vertical shift induced in the logarithmic portion of the mean velocity profile when plotted in the law-of-the-wall form. This shift, positive (upward) in case of drag reduction and physically interpreted as a consequence of the thickening of the viscous sublayer (Choi 1989), implicitly contains the Re -dependency of C_f through the friction velocity used for the adimensionalization. Thus, if Re is large enough for the logarithmic law to be valid in a Re -independent form, the amount of this shift is constant with Re , and is the preferred way to characterize the ability of riblets to reduce drag, as clearly advocated by Spalart & McLean (2011).

Turning now our attention to active, wall-based techniques for skin-friction drag reduction, a lively debate is taking place in the scientific community regarding the high- Re behaviour of the last generation of techniques, in particular the open-loop ones that promise large benefits with the advantage of reasonable implementation complexity. Such techniques operate by enforcing suitable temporal and spatial distributions of velocity perturbations at the wall, and have been shown to be able to relaminarize an otherwise turbulent flow, with an energy cost that can be significantly smaller than the energy savings. Assessing their potential for achieving sizeable benefits at high Re is obviously important to motivate further research in this field.

The specific case of spanwise-forcing techniques for drag reduction includes the well-known spanwise-oscillating wall (Jung *et al.* 1992) and its generalizations made by the spanwise-travelling waves (Du *et al.* 2002) and streamwise-travelling waves (Quadrio *et al.* 2009); although most of the available information concerns internal flows, numerical experiments (Skote 2011; Lardeau & Leschziner 2013; Skote 2013; Mishra & Skote 2015) have shown that the forcing is effective in external flows too. The streamwise-travelling waves, in particular, yield larger maximum drag reduction and, more importantly, improved energetic efficiency, which is essential if drag reduction is motivated by the need

to save energy. Thanks to the wealth of data available for this class of forcing, it is known that the impressive low- Re performance, i.e. 58% drag reduction and 28% net energy saving at $Re_\tau = 200$ in a turbulent channel flow (Quadrio *et al.* 2009), and flow relaminarization at $Re_\tau = 200$ in a turbulent pipe flow (Xie 2014), does indeed degrade with Re .

The drag reduction rate \mathcal{R} is often considered to decrease with the Reynolds number following a power law, i.e. $\mathcal{R} \sim Re_\tau^{-\gamma}$ with the exponent γ determined empirically. Early Re -dependency studies were typically based upon a large parameter study carried out at low Re and fixed forcing amplitude, where the best combination of parameters for drag reduction was first identified; this sole or a few sets of parameters were then tested at higher Re , and the performance drop measured under the assumption that the control parameters identifying the optimal point scale in viscous wall units. However, as discussed by Quadrio (2011), the assumption of viscous scaling not only needs to be verified, but also implies a choice in selecting the velocity scale: in drag reduction studies, besides the friction velocity $u_{\tau,0}$ of the non-controlled flow, an additional friction velocity is available to build viscous units, namely the actual friction velocity u_τ of the drag-reduced flow. In this paper, we will indicate with the customary + superscript the “reference” wall units, whereas a * superscript will indicate the “actual” wall units. Limiting to the literature where more than one value of Re was considered, quantities have been scaled through either reference + units (Quadrio *et al.* 2009; Toubert & Leschziner 2012; Gatti & Quadrio 2013; Hurst *et al.* 2014) or actual actual * units (Moarref & Jovanović 2012). The choice of nondimensionalization is particularly delicate and may cause spurious Re effects, since \mathcal{R} is function of all control parameters including Re .

A recent study that thoroughly describes the literature relevant to the higher- Re behaviour of spanwise-forcing techniques is that by Hurst *et al.* (2014). Choi *et al.* (2002) considered the oscillating wall for $Re_\tau = 100, 200$ and 400 and, although not addressing the Reynolds dependency directly, provided results implying $\gamma = 0.2 - 0.4$. Ricco & Quadrio (2008) considered the oscillating wall at $Re_\tau = 200$ and $Re_\tau = 400$ and measured $\gamma = 0.21$ for the point with largest drag reduction, although the rate of decrease appeared to depend on the parameters of the oscillating wall. Quadrio *et al.* (2009) for the streamwise-travelling waves measured $\gamma = 0.24$. Toubert & Leschziner (2012) went up to $Re_\tau = 1000$ for the oscillating wall and suggested $\gamma = 0.20$. This is a rather strong decrease rate: with $\gamma = 0.24$, the 58% drag reduction of the travelling waves at $Re_\tau = 200$ would become a mere 7% at $Re_\tau = 10^6$. Note that these figures do not account yet for the energy cost of the active control.

However, there are indications that the picture might be more complicated and possibly not as negative. First of all, the few experimental data available (Choi & Graham 1998; Ricco & Wu 2004) observe small, if any, Re effect. Moreover, numerical studies based on alternative approaches suggest a different scenario. Duque-Daza *et al.* (2012) solved the linearized Navier–Stokes equations to study how the growth of the near-wall streaks is affected by the travelling waves; they found no significant Re -effect when comparing the growth between $Re_\tau = 200$ and $Re_\tau = 2600$. They also observed that, at least at $Re_\tau = 200$ where DNS data for the drag change are available, streak amplification correlates well with drag reduction. Thus, the implicit message is that drag reduction might be mildly affected by increasing Re , similarly to streak growth. Moarref & Jovanović (2012) developed a model-based approach for studying spanwise-wall oscillations. They used eddy-viscosity-enhanced linearization of the turbulent flow with control in conjunction with turbulence modelling to determine skin-friction drag without resorting to heavy simulations. Unfortunately, their method relies upon the availability of statistical results from a DNS of the uncontrolled flow at the same Re , and does not lend itself to being used

at very high Reynolds numbers. However, up to $Re_\tau = 1000$ they found $\gamma = 0.15$ for the oscillating wall. Belan & Quadrio (2013) studied turbulent drag reduction in conjunction with the RANS equations, and carried out an asymptotic analysis to extrapolate the performance of streamwise-travelling waves at high Re . Their finding is that at $Re_\tau = 20,600$ drag reduction decreases only by 15% from the value at $Re_\tau = 200$, which is equivalent to $\gamma = 0.04$.

The recent study by Gatti & Quadrio (2013) began to shed some light upon these contrasting indications. Their numerical study, based on DNS applied to rather small computational domains, went up to $Re_\tau = 1000$ with a few points at $Re_\tau = 2000$, and confirmed that maximum drag reduction at the considered forcing amplitude indeed decreases quickly with $\gamma \approx 0.2$. However, Gatti & Quadrio (2013) were able to carry out a larger parameter study at $Re_\tau = 1000$ too, and evaluated γ at several points in the space of control parameters, finding that γ is a strong function of the parameters which define the forcing, and that the performance drop is more pronounced where drag reduction at low Re is maximum. The results obtained by Gatti & Quadrio (2013) were confirmed by Hurst *et al.* (2014) with a less detailed parameter study but with the added reliability of using DNS with full-size computational domains. Data at $Re_\tau = 200, 400, 800$ and 1600 confirmed that γ depends on the flow control parameters, typically ranging between 0.1 and 0.5.

Overall, this calls for a deeper understanding and generalization of these findings, as the outlook for practical applications would be strongly affected. Hence, the goal of the present paper is to further address the high- Re behavior of spanwise forcing techniques. Two DNS databases are built to characterize the streamwise-traveling waves in terms of drag reduction and net energy savings at two, well separated values of the Reynolds number: $Re_\tau = 200$ and $Re_\tau = 1000$. The parameter study is extremely large and is made by 4020 DNS calculations on small domain sizes, plus 20 additional cases with a larger domain size. For the first time the amplitude of the travelling waves is systematically studied together with their wavelength and speed: this will for the first time allow for a clear interpretation of the results in terms of the actual forcing intensity. Details of the numerical procedures and the computational parameters are given in §2, with particular attention to the spatial discretization issue: the employed computational domain, like in Gatti & Quadrio (2013), is smaller than the usual to reduce the computational cost, and monitoring the uncertainty of the results is essential. The results are then presented and discussed in §3, while in §4 the drag reduction data are examined in terms of γ , to show that this quantity is not particularly well suited to describe the Re -effect. The vertical shift in the logarithmic portion of the mean mean velocity profile is then shown to be a more robust alternative. An analytical relation is eventually developed to predict drag reduction at arbitrarily high values of Re based on low- Re information.

2. Method

Direct Numerical Simulations (DNS) of the turbulent flow in a doubly periodic channel are used to study the effect of the Reynolds number Re on the reduction of turbulent drag achieved by streamwise-travelling waves of spanwise wall velocity (Quadrio *et al.* 2009), imposed on both walls as the boundary condition:

$$W_w(x, t) = A \sin(\kappa x - \omega t). \quad (2.1)$$

In the above expression for the wall forcing, W_w is the spanwise velocity enforced at the wall, A is the amplitude of the forcing, κ is the streamwise wavenumber and ω is the angular frequency. x and t are the streamwise coordinate and time respectively. The

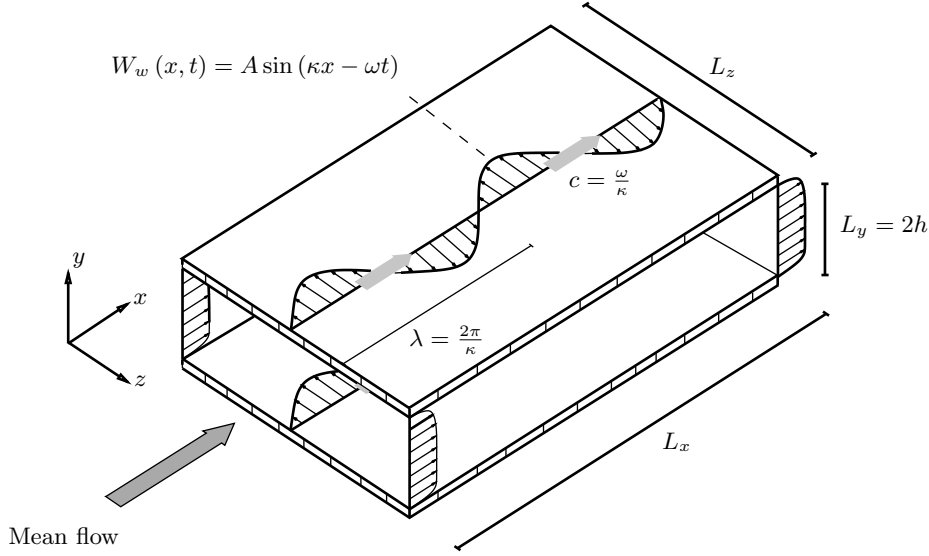


FIGURE 1. Schematic of a turbulent channel flow modified by streamwise-travelling waves of spanwise wall velocity, with amplitude A , streamwise wavenumber κ and angular frequency ω . λ is the streamwise wavelength and c is the phase speed of the waves. L_x , $L_y = 2h$ and L_z are the dimensions of the computational domain in the streamwise, wall-normal and spanwise directions, respectively.

forcing, sketched in figure 1, consists in a wall distribution of streamwise-modulated waves of the spanwise (z) velocity component with wavelength $\lambda = 2\pi/\kappa$ and period $T = 2\pi/\omega$, which travel at speed $c = \omega/\kappa$ forward ($c > 0$) or backward ($c < 0$) with respect to the direction x of the mean flow. The three independent parameters (for example A , κ , ω) of the control law (2.1) combined with the Reynolds number Re define a 4-dimensional parameter space, whose complete investigation represents a computational challenge.

The simulations have been run with the solver for the incompressible Navier–Stokes equations developed by Luchini & Quadrio (2006), and adapted in this work to run on a Blue Gene/Q system at the CINECA computing centre, where most of the calculations were carried out. Simulations enforcing either a constant flow rate (CFR) or a constant pressure gradient (CPG) (see Hasegawa *et al.* 2014; Quadrio *et al.* 2015, for details) are considered. The aim is to obtain and compare two comprehensive sets of cases at $Re_\tau = 200$ and $Re_\tau = 1000$, where $Re_\tau = u_\tau h/\nu$ is the Reynolds number based on the channel half-height h , the friction velocity u_τ of the uncontrolled flow and the kinematic viscosity ν of the fluid. This is enforced directly in the CPG cases where the value of Re_τ is specified as an input parameter, while in the CFR cases the imposed flow rate (hence the input value of $Re_b = U_b h/\nu$) leads to values of Re_τ which only approximately correspond to the target. In the following, for ease of discussion we will conventionally refer to the two casesets as the low- Re (or $Re_\tau = 200$) caseset and the high- Re (or $Re_\tau = 1000$) caseset.

In both casesets, the initial condition is that of an uncontrolled turbulent flow, and care is taken to begin the statistical analysis after properly discarding the initial transient (of duration up to 1,000 viscous time units) where the control leads the flow towards a reduced level of friction drag. The spatial resolution in wall units is always better than $\Delta x^+ = 12.3$ and $\Delta z^+ = 6.1$ (or $\Delta x^+ = 8.2$ and $\Delta z^+ = 4.1$ if the additional modes used to completely remove the aliasing error are considered). Δy^+ smoothly varies from $\Delta y^+ \approx 1$ near the wall to $\Delta y^+ \approx 7$ at the centerline. In the CFR cases, the spatial

Type	N_{cases}	Re_b	Re_τ	L_x/h	L_z/h	L_x^+	L_z^+	$N_x \times N_y \times N_z$
CFR	1530	6627	203.0	1.59π	0.80π	1015	507	$96 \times 100 \times 96$
CFR	480	6627	203.4	2.05π	1.02π	1308	654	$128 \times 100 \times 128$
CFR	1530	39333	905.6	0.32π	0.16π	906	453	$96 \times 500 \times 96$
CFR	480	39333	948.3	0.43π	0.22π	1290	645	$128 \times 500 \times 128$
CFR	5	6360	199.9	4π	2π	2512	1256	$256 \times 128 \times 256$
CPG	5	6358	200.0	4π	2π	2513	1257	$256 \times 128 \times 256$
CFR	5	39980	1000.0	4π	2π	12566	6283	$1024 \times 500 \times 1024$
CPG	5	39900	998.6	4π	2π	12549	6274	$1024 \times 500 \times 1024$

TABLE 1. Details of the small-box (upper half) and large-box (lower half) simulations. Every caseset is detailed in terms of simulation type (CFR or CPG), number of cases N_{cases} , values of bulk Reynolds number Re_b and friction Reynolds number Re_τ , length and width of the computational domain in inner and outer units, number of Fourier modes in the homogeneous directions (additional modes are used for dealiasing, according to the 3/2 rule) and collocation points in the wall-normal direction.

resolution in every direction strongly improves with drag reduction and the related drop in Re_τ . Time integration is carried out with a partially implicit approach, with a Crank-Nicolson scheme for the viscous terms and a third-order Runge-Kutta scheme for the convective terms. The CFL number is set at unity, well below the stability limit of the temporal integration scheme; the consequent average size of the timestep is always below $\Delta t^+ = 0.17$ for the low- Re cases, and below $\Delta t^+ = 0.1$ for the high- Re cases. The duration of the simulation obviously affects the quality of the estimate of the mean value of drag: the total integration time is thus adjusted in order to reach an acceptably small uncertainty over the whole dataset. The integration time is at least 24,000 viscous time units, and in certain cases it increases up to 80,000 viscous units. For each value of Re , the computational study considers two distinct sets of simulations, described below, details of which are reported in table 1.

2.1. The small-box large database

The first set (upper half of table 1) is a parameter study designed to produce a massive database of drag reduction data (4020 cases overall); the parameter space includes the forcing wavenumber κ , the forcing angular frequency ω and, for the first time, the forcing amplitude A too. For each Re , six values of $A^+ = \{2, 4.5, 5.5, 7, 12, 20\}$, a wide frequency range $-0.5 \leq \omega^+ \leq 1$, and 13 different values of κ^+ are considered, between the limiting case $\kappa^+ = 0$ when the control law (2.1) reduces to the classic spanwise-oscillating wall and the maximum considered wavenumber $\kappa^+ = 0.05$. Previous knowledge of the drag reduction pattern is exploited to focus on the interesting regions of the parameter space through a non-uniform distribution of the simulation points. Values of A^+ are chosen to describe reasonably well the region for maximum energetic efficiency near $A^+ = 5$, to include the point $A^+ = 12$ that corresponds to most available information (Quadrio *et al.* 2009; Toubert & Leschziner 2012; Hurst *et al.* 2014), and to include an additional point at larger A^+ to better characterize the absolute maximum of drag reduction. Availability of data at different A^+ is essential for appreciating the difference, discussed below, between “reference u_τ ” or + scaling and “actual u_τ ” or * scaling.

For this set of calculations, carried out under the CFR condition, a relatively small computational domain (whose dimensions are kept constant in wall units when Re is increased) is employed: the consequent savings in computing time are key to make this

huge parameter study possible. For each value of Re , two subsets of simulations are reported in table 1, which differ for the slightly different value of the length L_x of the computational domain. Since the wave length of the wall forcing is constrained to integer submultiples of the box length, this mitigates the quantization effect and allows a better investigation of the lower forcing wavenumbers. In changing box size, the aspect ratio of the computational domain is always kept constant at $L_x = 2L_z$, and the number of Fourier modes in the wall-parallel directions is adjusted as to keep the spatial resolution in wall units unchanged.

2.2. The large-box small database

The second set of simulations (lower half of table 1) employs a larger domain size, whose dimensions are kept constant in outer units when Re is increased. Owing to the larger computational cost, only a few representative cases are computed. For both Re we consider the reference uncontrolled case, and four other cases at the amplitude $A^+ = 7$. One case is for the oscillating wall at nearly optimal period $T^+ = 75$, one case with oscillating wall at the larger period $T^+ = 250$, one case with travelling waves with large drag reduction ($\omega^+ = 0.0239$ and $\kappa^+ = 0.01$) and one case for travelling waves with drag increase ($\omega^+ = 0.12$ and $\kappa^+ = 0.01$). Each case is run under both CFR and CPG (and for the latter the forcing parameters listed above are to be intended in actual wall units), for a total of 20 simulations featuring the larger computational domain.

2.3. Domain size and uncertainty

For the simulations described in §2.1, the computational domain is rather small, with a streamwise length of the order of 1000 wall units (one half of that for the domain width). Such domains, which imply a reduced computational cost per timestep, have been already used in the past for similar studies. Although several times larger than the minimal domain shown by Jiménez & Moin (1991) to be capable of sustaining the near-wall turbulent cycle, the present computational domain is not large enough to guarantee truly truncation-independent flow statistics. The large outer structures that become more and more important as Re increases do not entirely fit into such a small domain, the mean velocity in the outer region progressively deviates from the correct profile, and even the prediction of wall friction is affected by an error. Trace of this can be observed in table 1, where at high Re a 35% increase in box length brings about a 5% change in Re_τ .

However, Gatti & Quadrio (2013) demonstrated that reliable information concerning drag reduction can still be extracted from such simulations. In fact, most of the inaccuracy in predicting friction cancels out when the two friction coefficients (with and without control) are subtracted to compute drag reduction. It must be noted that the much shorter computing time per timestep comes at the cost of a larger number of timesteps required to obtain meaningful temporal averages of spatially-averaged quantities, which present larger temporal fluctuations as a consequence of the lesser contribution of the spatial average (Jiménez & Moin 1991). Lozano-Durán & Jiménez (2014) have shown that the standard deviation of the spatially-averaged skin friction is roughly inversely proportional to the square root of the area of the computational box. Hence, it is imperative to monitor the statistical uncertainty of the main quantities, and to increase the averaging time (i.e. the duration of the simulations) until the uncertainty reduces to an acceptable level.

In the present paper, the main quantity of interest is the drag reduction rate \mathcal{R} , as defined in Eq. (1.1). Its uncertainty $\delta\mathcal{R}$ is written by propagating the standard uncertainty of the skin-friction coefficients for the uncontrolled and controlled flows, and by

assuming they are independent variables:

$$\delta\mathcal{R} = \frac{C_f}{C_{f,0}} \sqrt{\left(\frac{\delta C_f}{C_f}\right)^2 + \left(\frac{\delta C_{f,0}}{C_{f,0}}\right)^2} \quad (2.2)$$

and then extended to a 95% confidence interval. The standard uncertainties $\delta C_{f,0}$ and δC_f are evaluated with the procedure described by Oliver *et al.* (2014), by calculating an integral timescale via an autoregressive method. This is slightly different from the strategy employed by Gatti & Quadrio (2013), who estimated the timescale differently, and it is interesting to note that the two methods end up with essentially the same result. For instance, when applied to the time history of skin-friction in an unmanipulated channel flow at $Re_\tau = 200$, with domain size $L_x = 4\pi h, L_z = 2\pi h$ and an integration time of $4480 h/U_b$, the present method yields a relative standard uncertainty of 0.70% while the method by Gatti & Quadrio (2013) the slightly lower value of 0.66%. Similar values of 0.61% and 0.64% are obtained respectively with the well-known method of non-overlapping batch means (Schmeiser 1982), which is related to the procedure followed by Hoyas & Jiménez (2008), and the similar method proposed by Mockett *et al.* (2010), which relies on the known statistical properties of white noise.

The uncertainty on the value of other quantities, such as the mean velocity profile or the control performance estimators presented below, is computed analogously. Hereinafter the uncertainty is always reported in the text when applicable and represented with error bars or shading in all the relevant figures.

3. Results

3.1. Validation for the oscillating wall

We show first the results for the temporal oscillation of the wall (i.e. $\kappa = 0$), that can be used as a further validation of the present dataset, thanks to the availability of several literature data at various Re . Figure 2 shows in the left panel the drag reduction rate against the period of wall oscillation T^+ for oscillations with an amplitude of $A^+ = 12$ in reference inner scaling. At $Re_\tau = 200$ the present results agree very well with those from Gatti & Quadrio (2013), who employed a comparable domain size, as well as with the full-size simulations of Touber & Leschziner (2012) and Hurst *et al.* (2014). At the low- Re optimal period of wall oscillation $T^+ \approx 100 - 125$ and $A^+ = 12$, for instance, Touber & Leschziner (2012) observed $\mathcal{R} = 0.385$, Hurst *et al.* (2014) $\mathcal{R} = 0.364$ and Gatti & Quadrio (2013) $\mathcal{R} = 0.384$. All agree well with the present value of 0.374 ± 0.018 . The only exception is the data point at $T^+ \approx 200$ by Hurst *et al.* (2014), which lies well below the other datasets. The comparison against the reference dataset by Quadrio & Ricco (2004) confirms the slight (less than 0.02) overestimation of \mathcal{R} in a narrow region close to the optimal period $T^+ \approx 100$, already known (cfr. the discussion of figures 5 and 6 in Gatti & Quadrio 2013) and attributed to domain size effects; this is limited to the region of largest drag reduction ($\mathcal{R} > 0.3$) and becomes milder for streamwise-travelling waves ($\kappa > 0$). The agreement between the present dataset and the available literature data is excellent also at $Re_\tau = 1000$. The datapoints by Hurst *et al.* (2014) lie slightly above the present results for small oscillation periods, but it must be recalled that they are computed at the lower $Re_\tau = 800$. As already known (Gatti & Quadrio 2013; Hurst *et al.* 2014), the optimal oscillation period decreases with Re and becomes $T^+ \approx 75$ at $Re_\tau = 1000$. At this value of T^+ a drag reduction of 0.277 ± 0.016 is measured, which is very close to $\mathcal{R} = 0.275$ measured by Hurst *et al.* (2014) and $\mathcal{R} = 0.29$ reported by Touber & Leschziner (2012) at $T^+ = 100$.

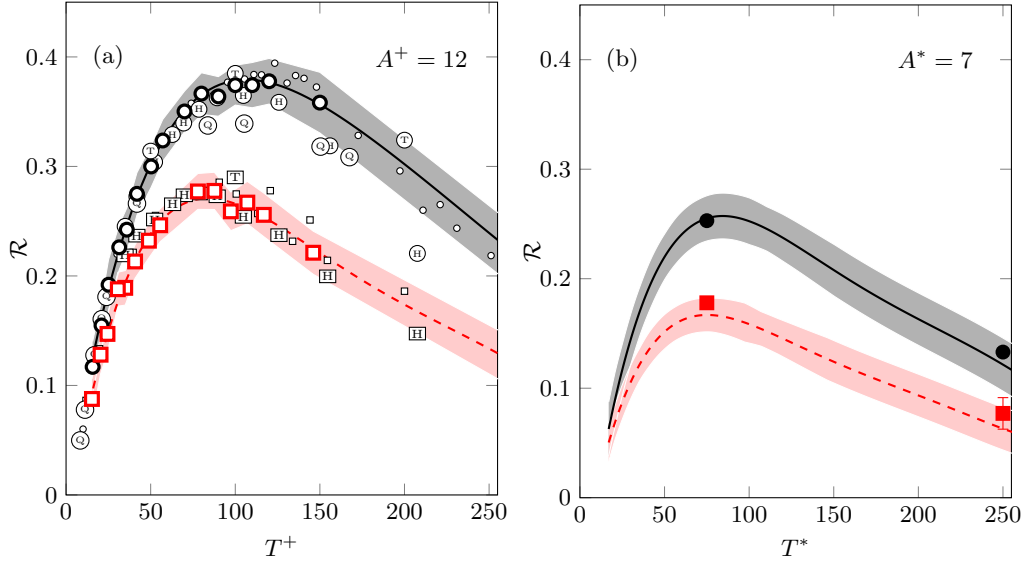


FIGURE 2. Drag reduction rate \mathcal{R} versus period of wall oscillation T^+ at $A^+ = 12$ in reference scaling (a) and versus T^* at $A^* = 7$ in actual scaling (b). Black (darker) color identifies low- Re data, and red (lighter) color corresponds to high- Re data. Present data are identified by lines, with shaded area representing the corresponding interval at 95% confidence level. In panel (a), open symbols are from Gatti & Quadrio (2013), while letters within symbols identify literature data: Q, Quadrio & Ricco (2004); T, Touber & Leschziner (2012); H, Hurst *et al.* (2014) with the higher Reynolds data at $Re_\tau = 800$. In panel (b), symbols are present data for large-box simulations.

Figure 2(b) shows \mathcal{R} versus T^* at constant $A^* = 7$, i.e. with actual viscous scaling, which would require data from simulations driven at CPG. The present small-box simulations are indeed computed at CFR, but the availability of data at several values of A^+ makes a $*$ scaling possible through interpolation. As far as we know, no such data exist for $Re_\tau = 1000$ or nearby; the only data we can compare with are the large-domain CPG simulations described in table 1, and this motivates the choice of the amplitude $A^* = 7$. At $Re_\tau = 200$ the optimal period is $T^* \approx 75$, where a drag reduction of 0.255 ± 0.020 is achieved. This value is very close to 0.253 ± 0.002 of the full-size data point at the same T^* . Good agreement between the present full-size DNS and reduced domain database is evident also at $Re_\tau = 1000$, where at $T^* = 75$ the former achieved 0.167 ± 0.015 and the latter 0.175 ± 0.005 . The shift of the optimal T^* with Re is much milder than that of T^+ , suggesting that actual inner scaling might be more appropriate.

3.2. The whole dataset at a glance

Travelling-wave results are now presented as in Quadrio *et al.* (2009) and Hurst *et al.* (2014), by plotting drag reduction maps in the space of the control parameters (κ^+, ω^+) at $A^+ = 12$. The data just discussed in figure 2 are those lying on the $\kappa = 0$ horizontal axis. Note that to produce such maps, the raw results are first interpolated on a finer Cartesian grid, without any smoothing or outliers removal, on which the contour lines are drawn. Using $*$ scaling also implies interpolation along the third axis (forcing amplitude). Figure 3 compares the drag reduction rate \mathcal{R} at $Re_\tau = 200$ and $Re_\tau = 1000$. The map at $Re_\tau = 200$ reproduces the well known shape described by Quadrio *et al.* (2009), with a maximum \mathcal{R} at fixed $A^+ = 12$ of $\mathcal{R}_{m,A^+} = 0.500 \pm 0.015$ located at $(\omega^+, \kappa^+) = (0.0195, 0.0063)$, which agrees with $\mathcal{R}_{m,A^+} = 0.48$ at $(0.018, 0.005)$ measured by Quadrio

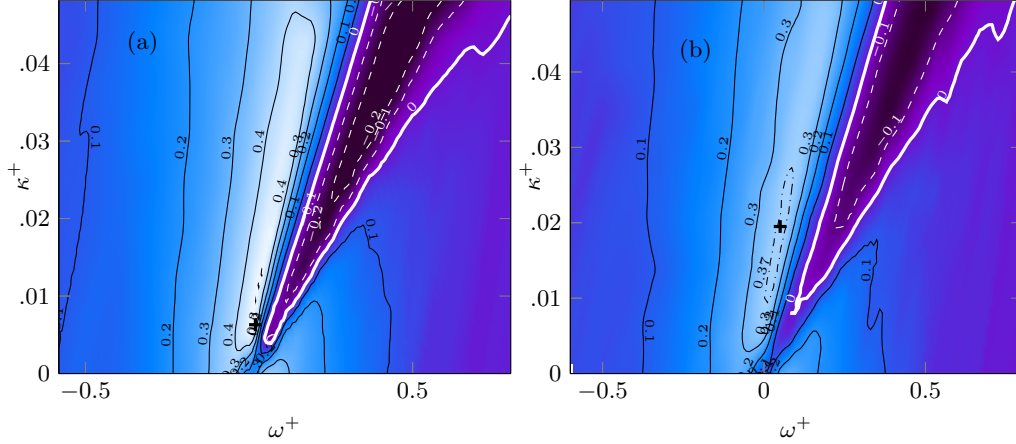


FIGURE 3. Map of drag reduction \mathcal{R}_{A^+} at constant forcing amplitude for streamwise traveling waves at $A^+ = 12$, for $Re_\tau = 200$ (a) and $Re_\tau = 1000$ (b). Contours are spaced by 0.1, negative contours are dashed. The thick white line corresponds to zero drag change while the dash-dotted line is the locus of points where $\mathcal{R} = \mathcal{R}_{m,A^+} - \delta\mathcal{R}$, and the cross indicates the position of \mathcal{R}_{m,A^+} .

et al. (2009) and $\mathcal{R}_{m,A^+} = 0.5$ at $(0.025, 0.008)$ obtained by Hurst *et al.* (2014). The side-by-side comparison with data at $Re_\tau = 1000$ clearly shows that, consistent with all previous information, the forcing becomes less effective as Re grows, since both the largest drag reduction and drag increase weaken. \mathcal{R}_{m,A^+} decreases to 0.388 ± 0.014 and its location in the plane moves along the drag reduction ridge towards higher frequencies and wavenumbers to $(\omega^+, \kappa^+) = (0.05, 0.0195)$. It must be observed, however, that the precise location of \mathcal{R}_{m,A^+} in the (ω^+, κ^+) plane is not a robust information, since the region of maximum drag reduction presents a rather flat peak. This is particularly true at $Re_\tau = 1000$, where the contour level drawn for $\mathcal{R} = 0.388 - 0.014$, i.e. \mathcal{R}_{m,A^+} minus its uncertainty, is an elongated region which almost encloses the low- Re maximum. However, the decrease of \mathcal{R}_{m,A^+} at larger Re as well as its shift towards higher frequencies and wavenumbers is clear, and it agrees with previous evidence by Gatti & Quadrio (2013) and by Hurst *et al.* (2014), with the latter being based on fewer data at $Re_\tau = 800$ but computed on a larger computational domain.

The present database contains much more information than that shown in figure 3, because several values of forcing amplitude are considered. Figure 4 shows the entire dataset at a glance in the three-dimensional parameter space $(\omega^+, \kappa^+, A^+)$, in comparative form between the two Reynolds numbers. The three-dimensional field of \mathcal{R} is visualised via isosurfaces of $\mathcal{R} = const$, and the clouds of tiny dots in the figure indicates the 4020 points where a DNS has been performed. Such an extensive database makes the description of \mathcal{R} with actual inner scaling possible. In the past, only few channel flow studies (for example Ricco *et al.* 2012) were performed at CPG, thus ensuring that drag reduction does not lead to changes in Re_τ . When CFR is employed, a significant drop in the friction velocity and Re_τ due to drag reduction implies that the inner scaling changes, and in particular that A^+ becomes significantly larger than A^* . Hence, in this case $+$ scaling is just a disguised outer scaling (Quadrio 2011). The present data have been computed on $A^+ = const$ planes, but they can be easily interpolated to produce figure 5, where a map of \mathcal{R} in the (ω^*, κ^*) plane at $A^* = 12$ is shown. At $Re_\tau = 200$, the maximum drag reduction at constant A^* is $\mathcal{R}_{m,A^*} = 0.453 \pm 0.015$ at $(\omega^*, \kappa^*) = (0.0167, 0.067)$, to be compared with $\mathcal{R}_{m,A^+} = 0.500 \pm 0.015$ at $(\omega^+, \kappa^+) = (0.0195, 0.0063)$. This agrees with data at same A^* and Re by Quadrio & Ricco (2011), who drove the channel at CPG and

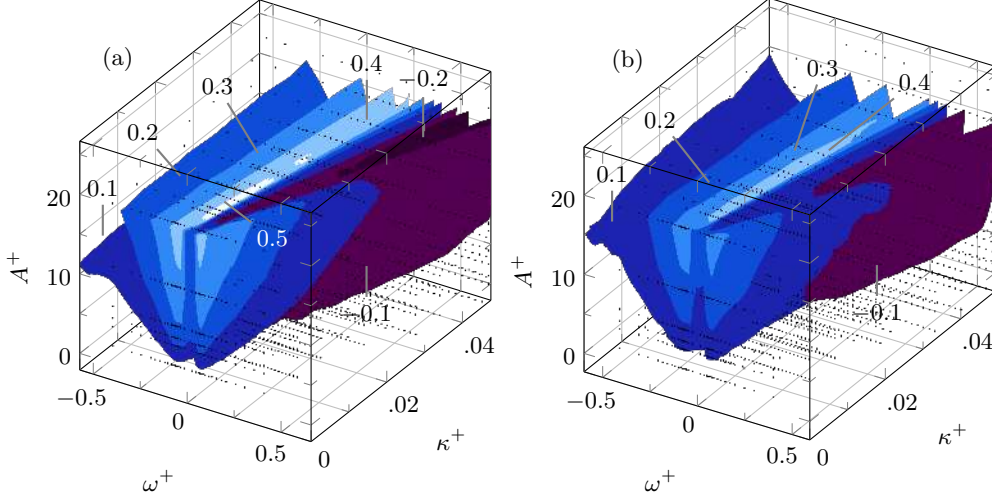


FIGURE 4. Isosurfaces of drag reduction \mathcal{R} in the three-dimensional parameter space $(\omega^+, \kappa^+, A^+)$ for $Re_\tau = 200$ (a) and $Re_\tau = 1000$ (b). Isosurface from dark to light range from $\mathcal{R} = -0.2$ to 0.5 in steps of 0.1 . The cloud of dots represents the 2010 data points where, at each Re , a DNS has been carried out.

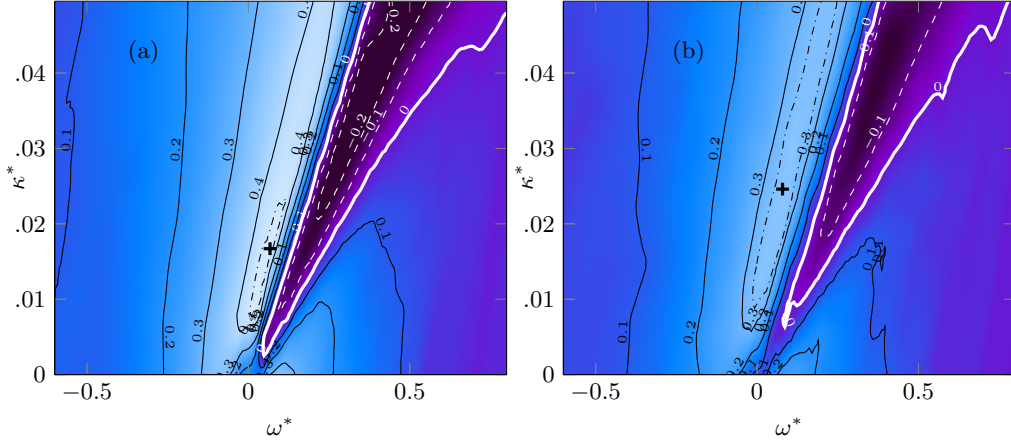


FIGURE 5. Map of drag reduction \mathcal{R}_{A^*} at constant forcing amplitude for streamwise traveling waves at $A^* = 12$, for $Re_\tau = 200$ (a) and $Re_\tau = 1000$ (b). Lines and symbols as in figure 3.

found $\mathcal{R}_{m,A^*} = 0.45$ at $(\omega^*, \kappa^*) = (0.012, 0.045)$. At the higher $Re_\tau = 1000$, $\mathcal{R}_{m,A^*} = 0.343 \pm 0.019$ at $(\omega^*, \kappa^*) = (0.0246, 0.0789)$ is observed instead of $\mathcal{R}_{m,A^+} = 0.388 \pm 0.014$ at $(\omega^+, \kappa^+) = (0.05, 0.0195)$.

Looking at \mathcal{R} with different scalings leads to important remarks. First, the difference between \mathcal{R}_{m,A^+} and \mathcal{R}_{m,A^*} is small at $A^+ = 12$. This is explained by the known weak dependence of \mathcal{R} on A at large amplitudes where saturation occurs (Quadrio *et al.* 2009). Indeed, at lower forcing intensities we observe a stronger drop, which at the lower Re is from $\mathcal{R}_{m,A^+} = 0.035 \pm 0.016$ for $A^+ = 4.5$ to $\mathcal{R}_{m,A^*} = 0.29 \pm 0.015$ for $A^* = 4.5$. Second, the effect of Re on the value of \mathcal{R}_{m,A^*} is qualitatively similar to the one on \mathcal{R}_{m,A^+} , and the shift of the location of the maximum in the (ω, κ) plane is confirmed. Since the maximum of drag reduction is rather flat, this last observation is better highlighted in figure 6 by observing, at several values of A^* , how the shape and size of the region

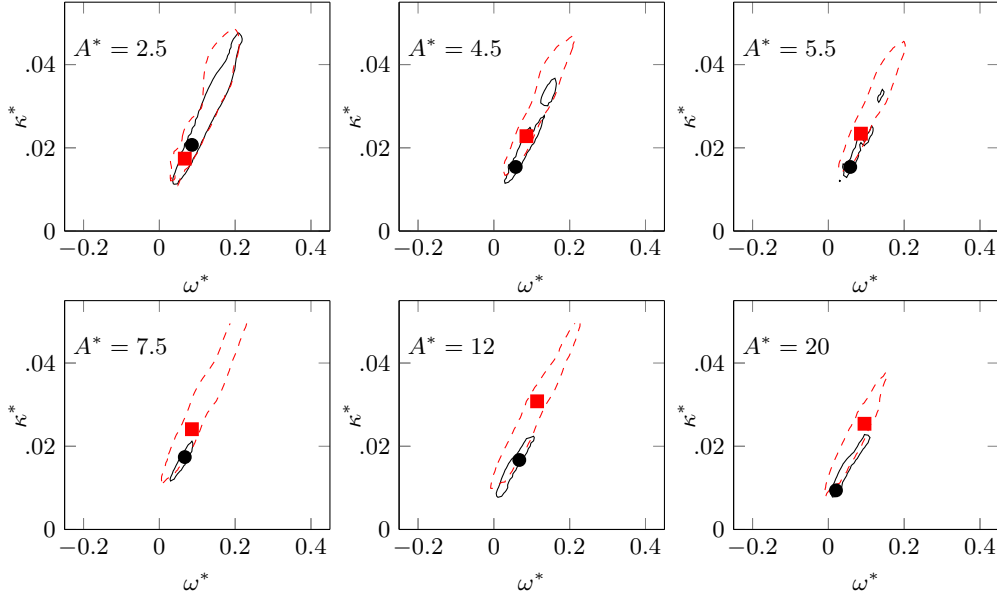


FIGURE 6. Region of large drag reduction, defined as the region where \mathcal{R} is at least $\mathcal{R}_{m,A^*} - 0.015$, for various values of A^* . Solid black lines: $Re_\tau = 200$; dashed red lines: $Re_\tau = 1000$. The location of \mathcal{R}_{m,A^*} is marked by a black circle at $Re_\tau = 200$ and a red square at $Re_\tau = 1000$.

where \mathcal{R} is nearly maximum change while Re increases. This region is identified by the contour line drawn for $\mathcal{R} = \mathcal{R}_{m,A^*} - 0.015$, with 0.015 being a representative value of $\delta\mathcal{R}$. For every value of A^* , this region at $Re_\tau = 1000$ is found to be larger than the one at $Re_\tau = 200$, which is enclosed by the former but for a small part at low wavenumbers and frequencies.

A global view of the drag reduction performance of the traveling waves as determined by the present dataset can be obtained from figure 7, that shows for both values of Re how the maximum drag reduction $\mathcal{R}_{m,A}$ increases with the forcing amplitude. It is confirmed that, regardless of the scaling adopted, the general shape of the curve is always that of a saturated growth of \mathcal{R} with A . The curves with $*$ scaling are consistently lower than the curves with $+$ scaling, and data at $Re_\tau = 1000$ are lower than data at $Re_\tau = 200$. The figure also includes a few datapoints from Quadrio *et al.* (2009) at $Re_\tau = 200$. Their point at $A^+ = 12$ falls slightly below the present data, something that Gatti & Quadrio (2013) already documented as an effect of the limited computational domain. However, the larger values of \mathcal{R}_{m,A^+} observed for $A^+ < 12$ in the present study also descend from a better scan of the parameter space. In fact, Quadrio *et al.* (2009) simply assumed a simple (reference) viscous scaling for the location of \mathcal{R}_{m,A^+} , whereas here a full parameter study avoids this assumption and determines that $\mathcal{R}_{m,A^+} = 0.38 \pm 0.017$ can still be achieved at $A^+ = 5.5$ and $Re_\tau = 200$, which becomes $\mathcal{R}_{m,A^+} = 0.26 \pm 0.020$ at $Re_\tau = 1000$. The comparison at $A^+ = 12$ with the data from Hurst *et al.* (2014) shows excellent agreement, considered that the slightly higher \mathcal{R} of the high- Re datapoint is due to its lower value of $Re_\tau = 800$.

3.3. Performance indicators

Active techniques for skin-friction drag reduction should not be characterised by \mathcal{R} alone: the net power saving rate \mathcal{S} , which also accounts for the energy cost of the control, is an important additional figure of merit for a complete assessment. \mathcal{S} can be defined as

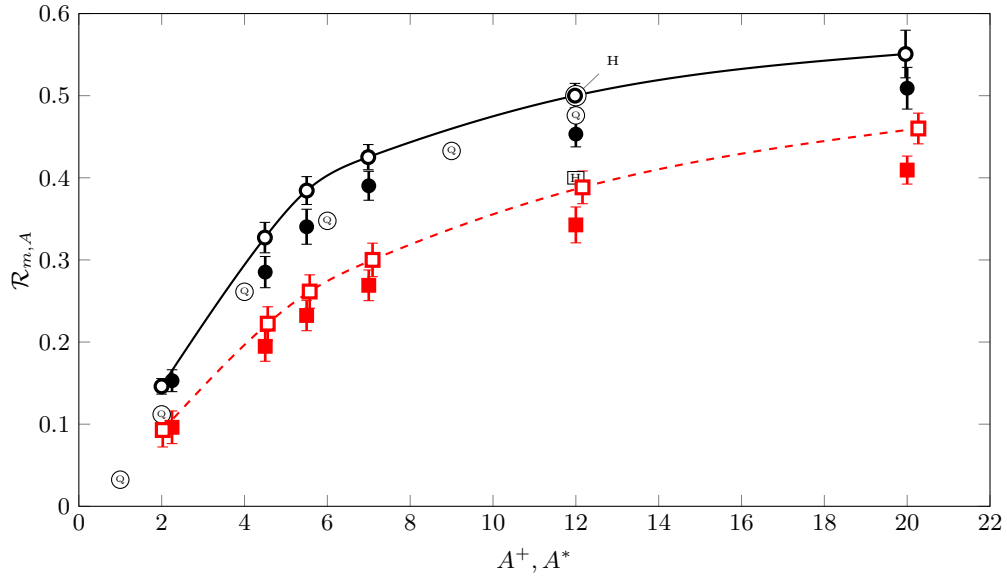


FIGURE 7. Maximum drag reduction $\mathcal{R}_{m,A}$ as function of the forcing amplitude. Black continuous line and symbols are for low- Re data, and red dashed line and symbols are for high- Re data. At each Re , open symbols refer to reference scaling (\mathcal{R}_{m,A^+} against A^+), and closed symbols to actual scaling (\mathcal{R}_{m,A^*} against A^*). As in figure 2, open symbols with letters are literature data. Note that Quadrio *et al.* (2009) assumed reference inner scaling for the optimal (ω^+, κ^+) pair determined at $A^+ = 12$.

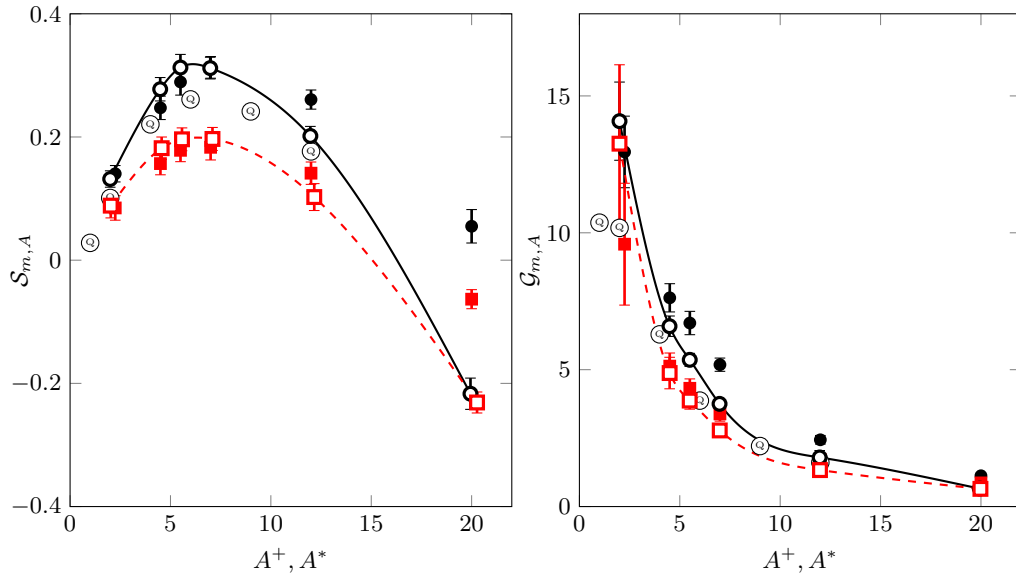


FIGURE 8. Maximum net power saving $\mathcal{S}_{m,A}$ (a) and maximum control gain $\mathcal{G}_{m,A}$ (b) as function of the forcing amplitude. Lines and symbols as in figure 7.

follows:

$$\mathcal{S} = \mathcal{R} - \frac{P_{in}}{P_0}, \quad (3.1)$$

where P_0 is the power (per unit area) required to drive the uncontrolled channel flow, and P_{in} is the control input power, computed here following Baron & Quadrio (1996) by neglecting the mechanical losses of a real actuator. Figure 8(a) presents the maximum net power saving $\mathcal{S}_{m,A}$ at fixed amplitude. At both Re the largest $\mathcal{S}_{m,A}$ is observed at $A^+ \approx 6$, where the travelling waves yield $\mathcal{S}_{m,A^+} = 0.31 \pm 0.021$ at $Re_\tau = 200$ and $\mathcal{S}_{m,A^+} = 0.19 \pm 0.018$ at $Re_\tau = 1000$. In comparison with existing data from Quadrio *et al.* (2009), there is a noticeable improvement due to the more detailed scan of the parameter space at low forcing amplitude. As observed by Ricco & Quadrio (2008) and Gatti & Quadrio (2013), the power expenditure per unit pumping power P_{in}/P_0 decreases with Re at a rate proportional to $Re_\tau^{-0.136}$ and faster than \mathcal{R} in many parts of the control parameter space. This means that \mathcal{S} decreases as \mathcal{R} , or at a slower rate. \mathcal{S}_{m,A^*} is slightly lower than \mathcal{S}_{m,A^+} at both Re up to $A^* \approx 7$. In this range of forcing amplitudes the main contributor to \mathcal{S} is \mathcal{R} , being the input power much smaller, and lower \mathcal{R} is achieved if forcing is performed at constant A^* compared to constant A^+ . Starting from $A^* \approx 7$, the opposite occurs and \mathcal{S}_{m,A^*} becomes larger than \mathcal{S}_{m,A^+} , because at high forcing amplitude \mathcal{S} is dominated by $-P_{in}/P_0$, which is smaller (in absolute value) when forcing is considered at constant A^* than at A^+ .

The control gain \mathcal{G} is defined as the power benefit per unit control power:

$$\mathcal{G} = \frac{\mathcal{R}P_0}{P_{in}}, \quad (3.2)$$

and is plotted in figure 8 (b). \mathcal{G}_{m,A^+} increases rapidly for decreasing forcing amplitude, since P_{in} is proportional to the square root of A (Quadrio & Ricco 2011), while \mathcal{R} varies less than linearly with A . At the amplitude value yielding the largest \mathcal{S}_{m,A^+} we measure $\mathcal{G} = 5.3 \pm 0.24$ at $Re_\tau = 200$ and $\mathcal{G} = 3.9 \pm 0.31$ at $Re_\tau = 1000$, with a mild decrease with Re . In fact, the beneficial Re effect on P_{in}/P_0 is even more effective on \mathcal{G} than on \mathcal{S} .

4. The effect of Re on drag reduction

We now focus our attention on understanding how the drag reduction performance of the streamwise-traveling waves is affected by an increase of the Reynolds number.

4.1. Characterizing \mathcal{R} via a power law

The effect of Re on \mathcal{R} has been traditionally quantified, as discussed in §1, by assuming (Choi *et al.* 2002; Moarref & Jovanović 2012; Toubert & Leschziner 2012; Duque-Daza *et al.* 2012; Belan & Quadrio 2013) that \mathcal{R} decreases with Re according to a simple power law, i.e.

$$\mathcal{R} \propto Re_\tau^{-\gamma}. \quad (4.1)$$

The power-law assumption was originally adopted by Choi *et al.* (2002) to fit early DNS-computed drag reduction results obtained for the spanwise-oscillating wall, and it is not endowed with a specific physical significance. Recently, Gatti & Quadrio (2013) and Hurst *et al.* (2014) observed that γ is not a simple constant, but depends on the control parameters ω , κ and A . The function $\gamma = \gamma(\omega^*, \kappa^*, A^*)$ can easily be constructed from the present dataset. For a given $(\omega^*, \kappa^*, A^*)$ combination, one knows the drag reduction values \mathcal{R}_{200} and \mathcal{R}_{1000} measured at $Re_\tau = 200$ and $Re_\tau = 1000$, and γ can be computed

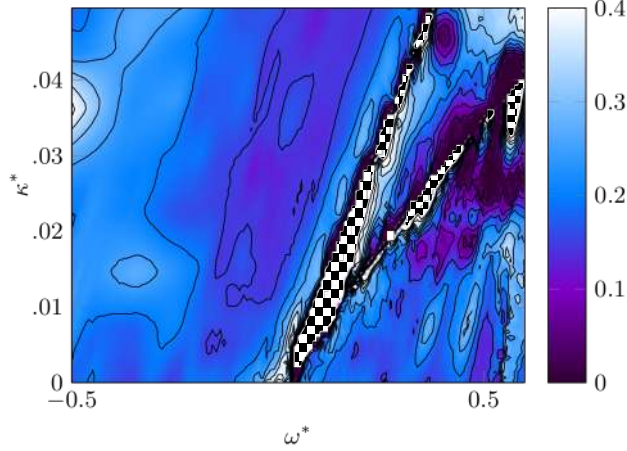


FIGURE 9. Power-law exponent γ as a function of κ^* and ω^* at $A^* = 12$, measured according to the formula (4.2). Contour lines from 0 to 0.45 in 10 steps. In the regions marked by the checkerboard pattern the exponent γ is undefined.

as:

$$\gamma = \frac{\ln(\mathcal{R}_{200}/\mathcal{R}_{1000})}{\ln(200/1000)}. \quad (4.2)$$

This quantity is shown in figure 9 for $A^* = 12$. The details might certainly change depending, for example, on the specific value of A^* , on the choice between working at constant A^+ or constant A^* , or on the choice between using in (4.2) the nominal values of Re_τ or the actual ones reported in table 1. However, the emerging picture is consistently as rich as chaotic. The known result that γ strongly varies across the parameter space is easily confirmed, and this implies that some regions more than others are sensitive to the increase in Re . For example, in most of the ridge of large drag reduction γ assumes intermediate values between 0.1 and 0.15, while the largest values are seen in the low-wavenumber region of the drag increase valley.

The complexity of figure 9 graphically illustrates how γ is not well suited to comprehensively describe the effect of Re on the drag reduction. Indeed, γ is an ill-conditioned quantity, which is sensitive to small uncertainties in \mathcal{R} , and according to definition (4.2) it grows to infinity whenever either \mathcal{R}_{200} or \mathcal{R}_{1000} is zero, while it becomes undefined when drag reduction at one Re turns into drag increase at the other Re (see the checkerboard-marked areas in figure ??). However, the most significant conceptual drawback of using γ is that, owing to the lack of physical rationale in the assumption of a power-law behaviour, extrapolation of existing data at higher Re (for example those which are typical of aeronautical applications) is entirely arbitrary. In fact, γ might well be a function of Re too, as some results by Hurst *et al.* (2014) seem to indicate. Hence, in our view γ should be merely regarded as a (not well-conditioned) indicator with the same limited predictive capability of other, more trivial quantities, like the relative decrease of drag reduction. In the following, we will overcome the problem by introducing a more physically sound indicator.

4.2. Characterizing \mathcal{R} via the vertical shift ΔB of the mean velocity profile

When dealing with distributed wall roughness (also including those particular roughness distributions, like streamwise aligned riblets, that reduce friction drag instead of increasing it), it is well known that the consequent friction changes are reflected in the

logarithmic region of the velocity profile. According to the classical theory (Pope 2000), the streamwise mean velocity profile $\langle u \rangle(y)$ over a smooth wall (for which the distinction between the reference inner scaling $+$ and the actual inner scaling $*$ is irrelevant) presents a thin near-wall region, called the viscous sublayer, where $\langle u \rangle^+ = y^+$, which is connected through the buffer region to the logarithmic layer, where the profile follows a logarithmic law:

$$\langle u \rangle^+ = \frac{1}{k} \ln y^+ + B. \quad (4.3)$$

In the above expression, k is the von Kármán constant and B is the so-called additive constant or near-wall intercept. Both constants are known to assume values that weakly depend on Re when Re is low. For instance, Kim *et al.* (1987) reported $k = 0.4$ and $B = 5.5$ at $Re_\tau = 180$, whereas $k = 0.386$ and $B = 4.40$ at $Re_\tau = 4079$ or $k = 0.384$ and $B = 4.27$ at $Re_\tau = 5200$ have been reported respectively by Bernardini *et al.* (2014) and Lee & Moser (2015). As stressed by Jiménez (2004), the additive constant B is determined by the no-slip boundary condition at the wall but, since the logarithmic law is only valid for $y^+ \gg 1$, its value depends on the details of the buffer and viscous layers. In the region further from the wall, the velocity-defect law, which describes the difference between the local mean velocity and the centerline mean velocity U_c , takes the following form (Pope 2000):

$$U_c^+ - \langle u \rangle^+ = -\frac{1}{k} \ln \left(\frac{y}{h} \right) + B_1 \quad (4.4)$$

where B_1 is a flow-dependent constant representing the difference between the actual centerline velocity U_c and the velocity value obtained by extrapolating the velocity-defect law up to the centerline. In channel flows, B_1 is close to zero (Pope 2000).

If the logarithmic law (4.3) and the defect law (4.4) are added together, and U_c is substituted with the more convenient U_b thanks to the relation $U_c^+ = U_b^+ + 1/k$ (Pope 2000), the use of the definition (1.2) for the friction coefficient C_f leads to the following friction law, i.e. an implicit relationship between C_f and the Reynolds number Re_τ :

$$\sqrt{\frac{2}{C_f}} = \frac{1}{k} \ln Re_\tau + B + B_1 - \frac{1}{k}. \quad (4.5)$$

When surface roughness is present, a classical statistical description of its effects (see e.g. Clauser 1956; Jiménez 2004) is via the so-called roughness function, which quantifies the roughness-induced drag change via the downward shift of the velocity profile in the logarithmic layer, i.e. via the (negative) change ΔB of the additive constant B . The same approach is used for the drag-reducing riblets (Luchini *et al.* 1991; García-Mayoral & Jiménez 2011), which produce a positive ΔB . Luchini (1996) has shown that ΔB is equivalent to the amount of drag reduction, and is proportional to the so-called protrusion height, defined as the distance between two virtual wall-parallel planes where no-slip boundary conditions for the profiles of the spanwise and streamwise velocity components hold.

One is naturally led to think that what applies to changes in wall geometry (roughness) might as well apply to the present, wall-based control strategy. Hence, our initial step consists in verifying whether the travelling waves consistently produce a vertical shift ΔB of the mean velocity profile. This is a known result (see for instance Baron & Quadrio 1996; Choi *et al.* 1998; Ricco & Wu 2004; Yudhistira & Skote 2011; Ricco *et al.* 2012; Touber & Leschziner 2012; Skote 2014; Hurst *et al.* 2014) that is systematically checked in figure 10 (a)-(d). The mean velocity profiles are obtained at both Re from the large-box simulations described in §2.2 (discretization details have been reported in the lower

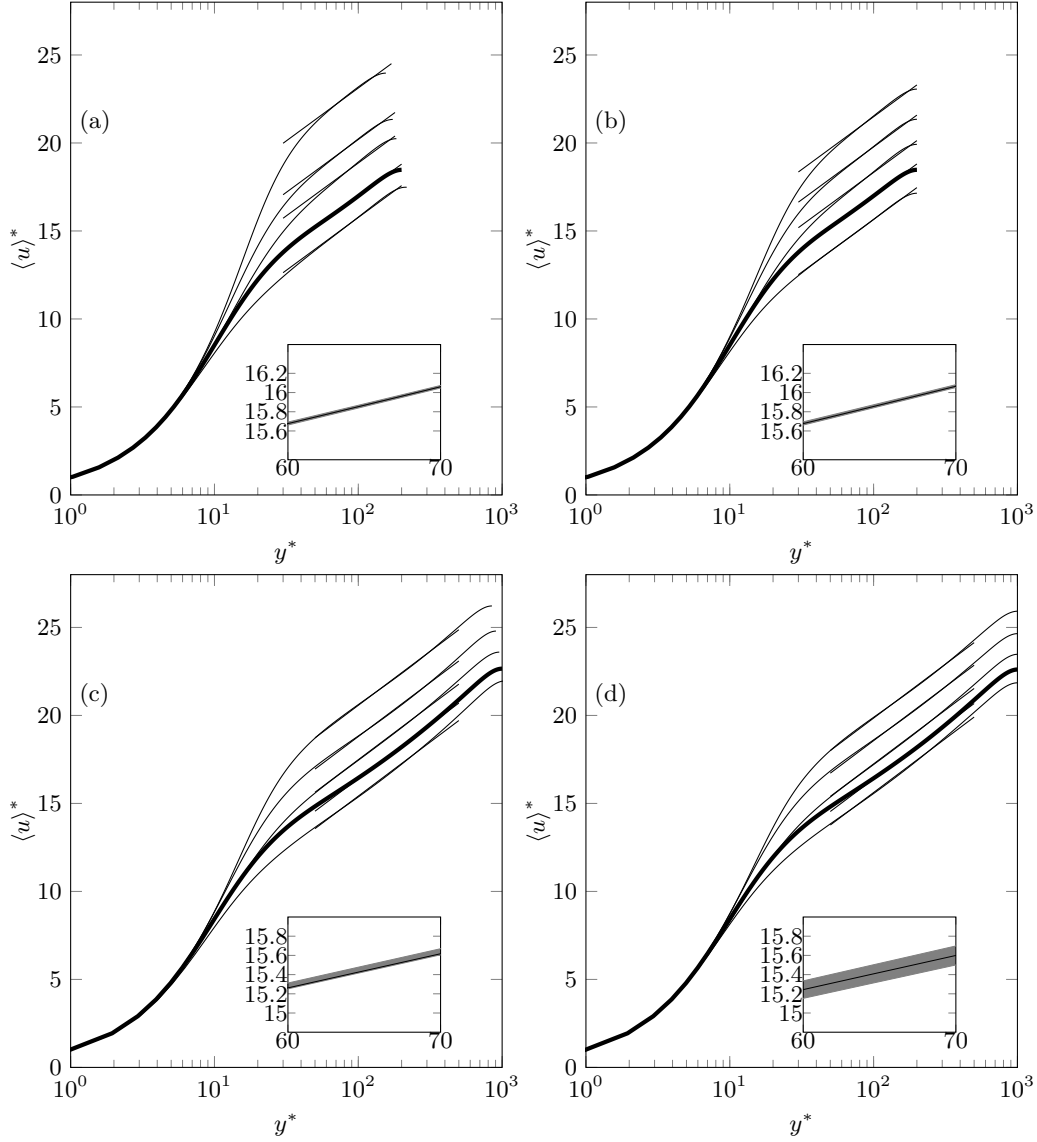


FIGURE 10. Mean velocity profiles obtained from the large-domain simulations reported in the lower half of table 1. Top: $Re_\tau = 200$; bottom: $Re_\tau = 1000$. Left: CFR cases; right: CPG cases. The thick line is the reference case and the thin lines correspond to control yielding both drag reduction and drag increase (see text). The insets enlarge a portion of the logarithmic layer to show the (very small) statistical uncertainty at 95% confidence, denoted by the shaded area.

half of table 1). Since we do not want to limit the discussion to the case of maximum drag reduction, at each Re five different cases are computed: the no-control case and four additional ones, all with forcing amplitude of $A^+ = 7$. These are two oscillating wall cases at $T^+ = 75$ and $T^+ = 250$, and two travelling waves cases, one with drag reduction at $\omega^+ = 0.0238$ and $\kappa^+ = 0.01$, and one with drag increase at $\omega^+ = 0.12$ and $\kappa^+ = 0.01$. Every case is computed twice, at the nominal value of Re_b with CFR and at the nominal value of Re_τ with CPG. For the CPG cases, the viscous quantities mentioned above to define the control conditions must be intended in actual viscous units.

Figure 10 (a)-(d) confirms that the spanwise forcing consistently produces a rigid upward (when drag is reduced) or downward (when drag is increased) shift of the mean velocity profile in the logarithmic region, while the parameter B_1 and the von Kármán constant do not change appreciably. In other words, the effect of the spanwise forcing can be quantified via the change ΔB of the additive constant, regardless of the control type, the value of Re , and the simulation strategy. Similar observations were recently put forward by Skote (2014), who observed changes of ΔB with drag reduction obtained by spanwise oscillations in a turbulent boundary layer, as well as changes in the von Kármán constant. The changes in k , however, are a direct consequence of the spatial transient present in the boundary layer setting, while in the present parallel flow ΔB fully describes the effect of the spanwise forcing.

Once the control is seen to modify the mean velocity profile through ΔB , we can follow what has been already done for riblets e.g. by Luchini *et al.* (1991) and by García-Mayoral & Jiménez (2011), and exploit the friction law (4.5) to obtain a dimensionless relation between the Reynolds number Re_τ , the drag reduction rate \mathcal{R} and the control-induced change ΔB of the additive constant. Equation (4.5) can be written twice, once for the uncontrolled flow (characterized by $Re_{\tau,0}$ and $C_{f,0}$) and once for the controlled flow (with Re_τ and C_f). By subtracting the latter formula from the former, one obtains:

$$\sqrt{\frac{2}{C_f}} - \sqrt{\frac{2}{C_{f,0}}} = \frac{1}{k} \ln \frac{Re_\tau}{Re_{\tau,0}} + \Delta B, \quad (4.6)$$

under the assumption that k and B_1 are unaffected by the control. These assumptions are discussed and verified in the Appendix.

Now, if the uncontrolled and controlled flows are compared under the CFR constraint, equation (4.6) can be solved for ΔB and further manipulated by substituting $C_f = C_{f,0}(1 - \mathcal{R})$ and $Re_\tau = Re_{\tau,0}\sqrt{1 - \mathcal{R}}$, to yield:

$$\Delta B^+ = \sqrt{\frac{2}{C_{f,0}}} \left[(1 - \mathcal{R})^{-1/2} - 1 \right] - \frac{1}{2k} \ln(1 - \mathcal{R}). \quad (4.7)$$

If on the other hand the pressure gradient is kept constant across the comparison (CPG), then by definition $Re_\tau = Re_{\tau,0}$, and the above equation further simplifies to:

$$\Delta B^* = \sqrt{\frac{2}{C_{f,0}}} \left[(1 - \mathcal{R})^{-1/2} - 1 \right]. \quad (4.8)$$

It is worth noting that equations (4.7) and (4.8) differ from the relationships proposed by Luchini *et al.* (1991) and by García-Mayoral & Jiménez (2011) for the turbulent flow over a surface with riblets. In fact, those are linearized under the assumption of small \mathcal{R} , which is definitely a reasonable assumption for riblets but does not apply to the present forcing, which is capable to yield quite large \mathcal{R} and consequently is better described by the fully non-linear expression.

The main point is that, since $C_{f,0}$ is a function of Re_b only, equations (4.7) and (4.8) link ΔB and \mathcal{R} , provided Re_b is large enough for the friction law (4.5) to hold. This can easily be tested with our DNS data, as shown in figure 11, where data from the large-box simulations already considered in figure 10 are used. At $Re_\tau = 1000$ the agreement is excellent, for both the CPG and CFR cases. The agreement is less good at $Re_\tau = 200$, and it is interesting to note that the largest deviation occurs for the CFR case with largest \mathcal{R} at $Re_\tau = 200$, i.e. for the case possessing the lowest actual Re_τ (namely $Re_\tau = 173$). It comes at no surprise that, at such low Re_τ , the assumptions underlying the friction law

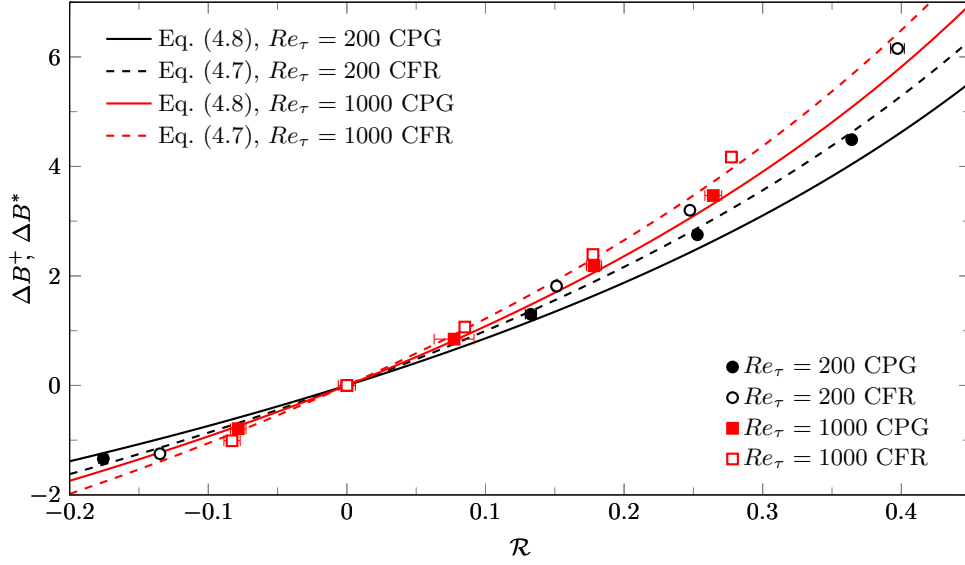


FIGURE 11. Relationship between the upward shift ΔB and the drag reduction rate \mathcal{R} . Symbols are present large-box DNS data, and lines are predictions from (4.7) and (4.8) for the CFR and CPG cases.

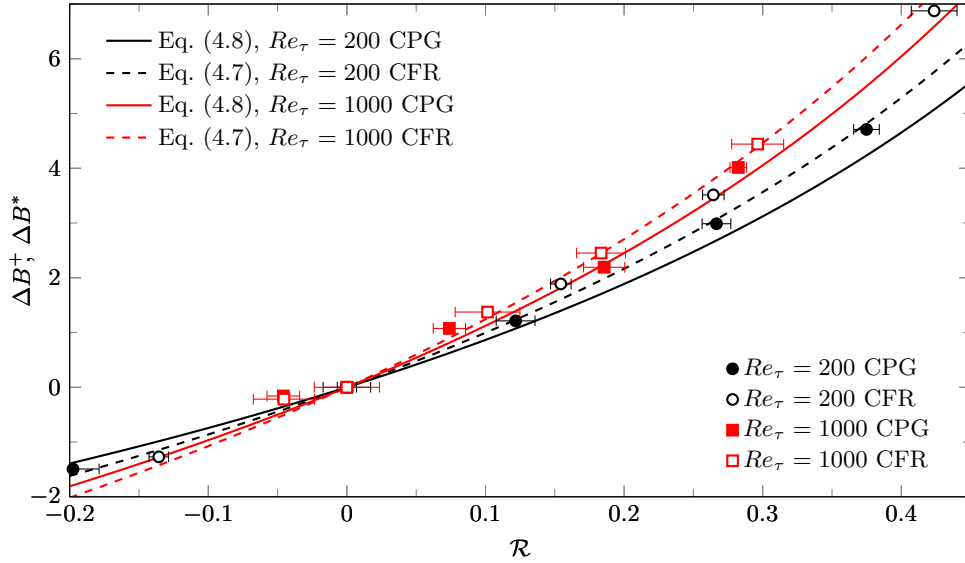


FIGURE 12. Relationship between the upward shift ΔB and the drag reduction rate \mathcal{R} . Symbols are present small-box DNS data, and lines are predictions from (4.7) and (4.8) for the CFR and CPG cases.

(4.5), which implies that the flow rate is well approximated by the wall-normal integral of the logarithmic velocity profile, do not apply in full.

Quite surprisingly, a very similar picture is observed in figure 12 for the small-box simulations, where the mean velocity profile in the outer region is expected to be affected by the size of the computational domain. Despite the larger statistical uncertainty of \mathcal{R} and the indeed quite small extent of healthy logarithmic region, the data at $Re_\tau = 1000$ agree fairly well with equations (4.7) and (4.8), while those at $Re_\tau = 200$ do not,

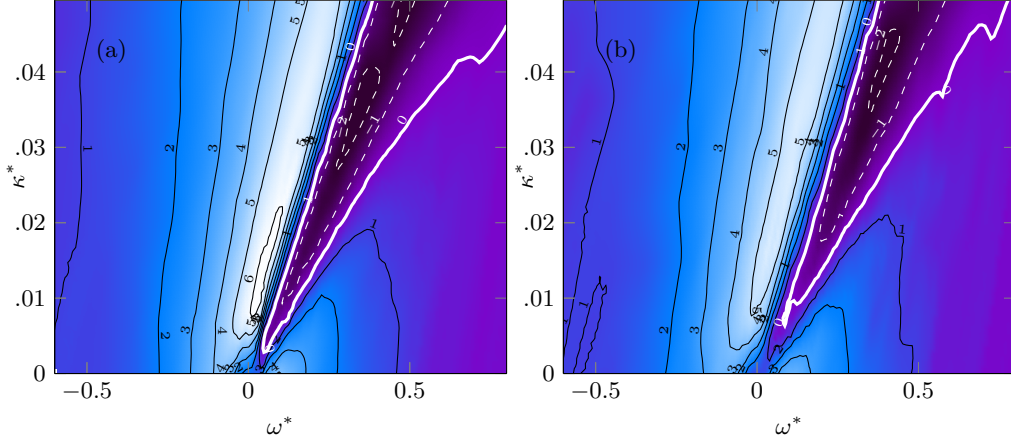


FIGURE 13. Map of ΔB^* for streamwise traveling waves at $A^* = 12$, for $Re_\tau = 200$ (a) and $Re_\tau = 1000$ (b). Contours are spaced by 1, negative contours are dashed. The thick white line corresponds to $\Delta B^* = 0$.

because Re is too low, in the very same way as the corresponding data from the large-box simulations.

The evidence that equations (4.7) and (4.8) describe well the relationship among $C_{f,0}$ (hence Re_τ), \mathcal{R} and ΔB at sufficiently high Re implies that these equations also describe the effect of Re on \mathcal{R} , provided information is known on the Re -dependency of ΔB . This information can be educed from the small-box database introduced in §2.1. Figure 13 shows the map of ΔB^* at $Re_\tau = 200$ and $Re_\tau = 1000$, in actual viscous scaling at $A^* = 12$. Instead of measuring ΔB from the velocity profiles, ΔB is computed here *ex-post* from the independently validated values of \mathcal{R} through equation (4.7). In this way, the computed value of ΔB matches the measured value at $Re_\tau = 1000$, while it is consistently slightly smaller at $Re_\tau = 200$ (see figures 11 and 12). This estimate of ΔB at low Re is still meaningful, as it can be interpreted to represent the ΔB value epurated from the low- Re effects that are due to deviations from the predictions of the friction law.

When compared to the two maps in figure 5, where \mathcal{R} is observed to decrease significantly across the whole plane, the two maps of ΔB^* appear much more similar, if exception is made for a localized change near the origin of the (ω^*, κ^*) plane. Figure 14 emphasizes the changes of ΔB^* with Re , by plotting the difference between the two previous maps, i.e. the pointwise difference between ΔB^* at $Re_\tau = 200$ and ΔB^* at $Re_\tau = 1000$. The figure strengthens the previous claim that ΔB is roughly constant with Re , once low- Re effects are discarded. In fact, except for a thin stripe located on the right of the drag reduction ridge, the variation of ΔB^* with Re is essentially zero. In this region, which includes the whole area of large drag reduction except its right boundary, the function $\Delta B^*(\omega^*, \kappa^*)$ is solely determined by the control parameters, and equation (4.6) can be used to describe the decrease of \mathcal{R} with Re . The thin stripe, on the other hand, is a low- Re effect that represents a non-trivial feature specific to the present control technique.

Although this is not enough for the ultimate demonstration that ΔB^* does not depend on Re , the scenario depicted above is more than reasonable, and is reinforced by the parallel made with riblets. Moreover, additional data exist to support it. For example, Hurst *et al.* (2014) plot in their figure 16 mean streamwise velocity profiles for channel flow modified by stationary waves at $\omega^+ = 0$ and $\kappa^+ = 0.008$ with $A^+ = 12$ and $Re_\tau =$

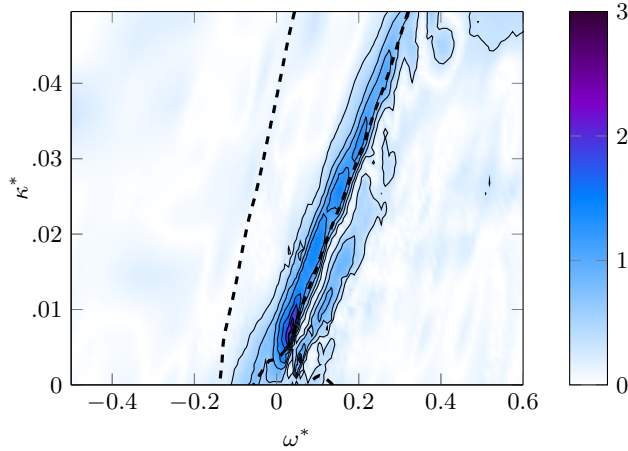


FIGURE 14. Map of the difference between ΔB^* at $Re_\tau = 200$ and ΔB^* at $Re_\tau = 1000$ for $A^* = 12$. Contour lines from 0 to 3 in 10 steps. The thick dashed line marks the region of large drag reduction, i.e. $\mathcal{R} > 0.3$, at $Re_\tau = 200$.

$\{200, 400, 800, 1600\}$. By comparison with the reference profiles, they report $\Delta B^+ = \{7.6, 6.2, 5.5, 5.0\}$ respectively. The changes clearly are progressively decreasing as Re is increased. Moreover, it should be noted that the point at $\omega^+ = 0$ and $\kappa^+ = 0.008$ lies in the small area where the residual Re -effect is maximum (see our figure 14) and some change ΔB is expected. Lastly, Hurst *et al.* (2014) adopted a reference viscous scaling, which by itself induces a change in ΔB : as Re increases, \mathcal{R} shrinks, $u_\tau/u_{\tau,0}$ increases and the actual forcing amplitude A^* decreases. Hence, data from Hurst *et al.* (2014) are compatible with the present work in suggesting that for a large enough Re the function $\Delta B(\omega^*, \kappa^*)$ characterizes the forcing, and becomes constant with Re above a threshold value. We estimate this minimum Re to be $Re_\tau \approx 2000$.

5. Concluding discussion

In this study a large drag reduction DNS database has been produced for a turbulent plane channel flow subject to a spanwise forcing. 4020 simulations have been used to describe how increasing the value of the Reynolds number from $Re_\tau = 200$ to $Re_\tau = 1000$ affects drag reduction, and to propose a rationale behind the observed performance deterioration. To the authors' knowledge, this is the first study on spanwise forcing that includes a wide range of forcing amplitudes, as well as Constant Pressure Gradient (CPG) data at different values of Re . The large size of the numerical study has been possible thanks to the use of relatively small computational domains, which at the same time also constitutes its main limitation. This strategy has been already proved by Gatti & Quadrio (2013) to successfully provide useful and accurate information about changes in friction drag. Moreover, the numerical results and the main conclusions have been corroborated by 20 additional cases where a large computational domain is employed. The main findings of this study can be summarized as follows.

(a) The existing information regarding spanwise forcing has been significantly extended. Thanks to the depth of the numerical study, the maximum *net* saving rate of streamwise-travelling waves at $Re_\tau = 200$ is 0.31 ± 0.021 , condition at which they produce a drag reduction of 0.382 ± 0.002 and a gain of 5.3 ± 0.24 ; these figures become 0.19 ± 0.002 , 0.255 ± 0.02 and 3.9 ± 0.31 at $Re_\tau = 1000$. We have shown how the scaling

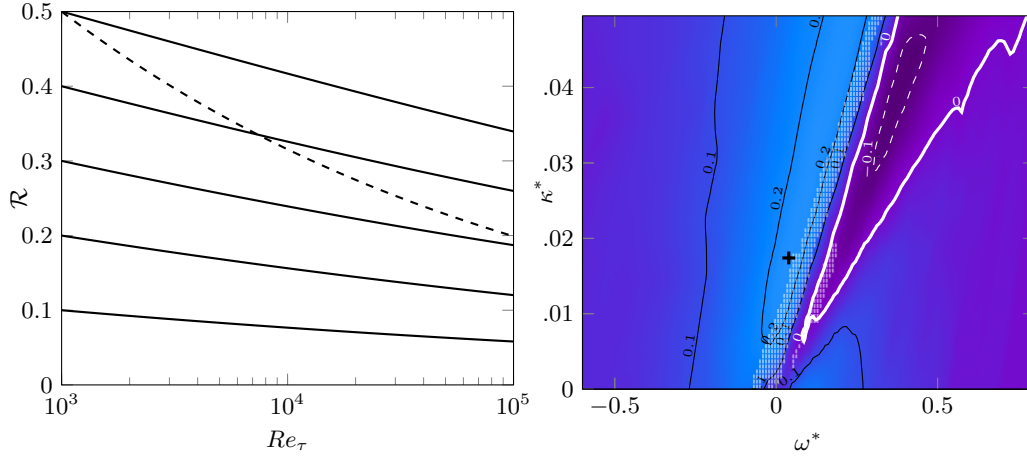


FIGURE 15. Extrapolation of drag reduction data from $Re_\tau = 1000$ to $Re_\tau = 100,000$. (a) Continuous lines are prediction by equation (4.6), while the dashed line shows a decrease of $\mathcal{R} \propto Re_\tau^{-0.2}$. (b) Extrapolated drag reduction map at $Re_\tau = 10^5$ for $A^* = 12$, lines and symbols as in figure 3. The white shaded area is excluded from the contour plot as there ΔB is found to vary between $Re_\tau = 200$ and $Re_\tau = 1000$.

choices (viscous units based on the reference friction velocity, i.e. “+” scaling, or viscous units based on the actual friction velocity of the drag-reduced flow, i.e. “*” scaling) impact the results, and the ensuing differences have been discussed. Though less practical to implement, actual * scaling has been shown to be more advantageous to describe a wall-based phenomenon like skin-friction drag reduction.

(b) The deterioration of performance with Re has been confirmed, in agreement with the majority of existing data. The often assumed but arbitrary power-law decrease of drag reduction with Re , i.e. $\mathcal{R} \sim Re_\tau^{-\gamma}$, yields values of the exponent γ which vary strongly across the space of control parameters. The lack of rationale of a power-law dependency is such that a γ -based extrapolation at higher Re of existing data should be regarded as potentially unreliable.

(c) The classic argument linking the skin-friction drag changes of a rough wall to the vertical shift ΔB of the logarithmic portion of the mean velocity profile has been shown to apply to the case of spanwise forcing. A non-linear expression has been derived that can be specialized to the CFR or CPG cases. As for drag-reducing riblets, characterizing drag reduction through ΔB is more informative than the simple statement of “percentage drag reduction”. Indeed, ΔB already contains the necessary Re dependency through the friction law and, if the control parameters in actual units are constant, it does not significantly change once Re is above the threshold where the mean velocity profile features a well-defined logarithmic region, and the validity of the friction law (4.5) is ensured.

(d) Under the assumption that ΔB^* measured in the present work at $Re_\tau = 1000$ is already Re -independent, equation (4.6) can be used to extrapolate drag reduction at higher Re_τ , as done in figure 15(a), showing that a drag reduction of $\mathcal{R} = 0.5$ at $Re_\tau = 1000$ translates into $\mathcal{R} = 0.34$ at $Re_\tau = 10^5$. The decrease is still significant but not as dramatic as the low- Re evidence suggests: this can be easily appreciated by looking at the dashed line, that describes $\mathcal{R} \sim Re_\tau^{-\gamma}$ with $\gamma = 0.20$. The whole drag reduction map at $A^* = 12$ is extrapolated from $Re_\tau = 1000$ to $Re_\tau = 10^5$ in figure 15(b). The maximum drag reduction in the plane reduces from 0.34 to 0.23, which is still a sizeable amount considered the two-decades increase of Re .

(e) While we are not in the position to make a claim of generality, we believe that the line of reasoning developed in this paper for spanwise forcing might apply to other wall-based active control techniques, as long as they do not disrupt the shape of the mean velocity profile. The relation among ΔB , $C_{f,0}$ and \mathcal{R} and the observation that ΔB becomes Re -independent provide an unbiased framework to describe the effect of the Reynolds number on turbulent drag reduction obtained via wall-based control. For riblets, ΔB depends on the riblet geometry alone. For spanwise forcing, a given set of control parameters determines the properties of the generalized Stokes layer (Quadrio & Ricco 2011), whose features, such as its thickness (Quadrio & Ricco 2011) or spanwise shear stress at a certain wall distance (Yakeno *et al.* 2014), determine the shift ΔB or, equivalently, the Re -dependent drag reduction rate \mathcal{R} according to equations (4.7) or (4.8). Hence, the comparison between wall-based control at different Reynolds numbers should be in terms of ΔB , not of \mathcal{R} .

(f) Although the present results are sound from a quantitative standpoint, we believe that an accurate DNS study of the drag-reduction properties of the travelling waves at higher Re is still needed. Such study would be forcedly less vast than the present one, but could be designed taking advantage of the available information. The view presented in this paper, with its Achille's heel of being based on small-box simulations, will surely benefit from an independent confirmation. Moreover, $Re_\tau = 1000$ is still not large enough to reach a complete Re -independency for the values of ΔB , which, as mentioned above, is expected to start at $Re_\tau \approx 2000$. It must be stressed, however, that this additional study is all what is needed to know drag reduction capabilities of the travelling waves at any Re .

Although so far we have deliberately avoided to mention turbulent structures, by strictly limiting our discussion to the simplest first-order statistics, we would like to close this paper with a remark of a more general nature.

On a fundamental level, the dependence of C_f upon Re may be seen to reflect the variable extension of the different portions of a turbulent wall flow, in particular the inner and the outer layers, and the way they interact with each other. The importance of the inner layer has been probably overemphasized in the last decades: indeed, at the low values of Re typical of most studies addressing near-wall turbulence and its control, the inner layer occupies a significant portion of the whole flow. At higher Re , however, the wall-normal extension of the inner layer becomes progressively smaller with respect to the outer layer, and at application-level Re most of the boundary layer is just outer layer. It is also known, thanks for example to the FIK identity (Fukagata *et al.* 2002), that the portion of Reynolds shear stresses located in the outer layer carries an increasing contribution to the skin-friction coefficient as Re increases. These Reynolds stresses are due to the very large turbulent structures (Ganapathisubramani *et al.* 2003; Guala *et al.* 2006) that populate the outer layer and modulate the smaller structures residing near the wall (Brown & Thomas 1977; Ganapathisubramani *et al.* 2012; Lozano-Durán & Jiménez 2014). This modulation has been confirmed also in the case of drag-reducing flows (see for example Toubert & Leschziner 2012). Those among the present results which are computed in small computational domains obviously do not account for the large structures, that at $Re_\tau = 1000$ already carry a non-negligible contribution to Reynolds stresses and hence to turbulent drag (Ganapathisubramani *et al.* 2003). This explains the significant deviations of the values of C_f from the correct value observed for the uncontrolled flow. Nonetheless, the nearly correct prediction of changes in C_f , i.e. drag reduction, via small-box simulations indicates that the large outer structures do not significantly interfere with the working mechanism of wall-based strategies for drag

reduction. The control action takes place at the wall and targets turbulence in the very vicinity of the wall, and the largest eddies which attach to the wall (Lozano-Durán & Jiménez 2014) perceive a modified inner layer with a lower mean shear. In other words, the fact that the near-wall region contributes progressively less to drag is already accounted for in the friction law. The present results thus blend nicely with the result, presented by Iwamoto *et al.* (2005), that artificially removing the turbulent fluctuations in a thin wall layer of constant thickness when measured in inner units produces a reduction of friction which is unexpectedly robust with respect to the increase in Re . There is thus no need to control the outer structures directly to achieve drag reduction at high Re , although of course being able to do so would yield additional benefits.

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Appendix

In §4.2 equations (4.7) and (4.8) reciprocally linking drag reduction, the friction coefficient and Re have been deduced under the assumption that the von Kármán constant k is independent upon Re , and the intercept B_1 is negligible for channel flows. The validity of these assumptions can be verified by measuring k , B and B_1 for the whole set of 20 large-box simulations by fitting the log-law (4.4) to the mean velocity profiles shown in figure 10. The results are summarized in Table 2.

The extrema of the least-squares fitted region in wall-normal direction are chosen in such a way that the width of the fitted region is as large as possible, while keeping a correlation coefficient $r^2 \geq 0.9995$ (where $r^2 = 1$ means perfect fit). The same procedure was employed by Lee & Moser (2015) with $r^2 = 0.9999$ at $Re_\tau = 5186$. The present, slightly lower threshold for r^2 descends from the lower Re , which implies a shorter logarithmic region. The lower bound of the fit is set at least ten wall units past the relative minimum of the diagnostic function $y^+ d \langle u \rangle^+ / dy^+$. Note that choosing the range for this curve fit is somewhat arbitrary (Lee & Moser 2015).

The near-wall intercept B is a function of k and is very sensitive to small variation thereof. Thus, small uncertainties on k due to the arbitrariness of the log-region range strongly affect B and make its measure not readily comparable among different simulations. Therefore, the numerical value of k in the controlled cases is kept equal to the

Full-size simulations at Constant Flow Rate (CFR)								
Re_τ	Re_b	κ^+	ω^+	k	B^*	B_1^*	\mathcal{R}	$\delta\mathcal{R}$
199.9	6361	-	-	0.390	5.151	-0.29	-	0.003
173.3	6361	0	0.0838	0.390	8.351	-0.32	0.248	0.003
184.1	6361	0	0.0251	0.386	6.965	-0.30	0.151	0.003
155.1	6361	0.01	0.0238	0.390	11.305	-0.32	0.397	0.004
213.0	6361	0.01	0.12	0.386	3.904	-0.29	-0.135	0.006
998.7	39990	-	-	0.386	4.494	0.26	-	0.003
905.7	39990	0	0.0838	0.386	6.885	0.26	0.178	0.002
955.2	39990	0	0.0251	0.378	5.560	0.25	0.085	0.003
848.9	39990	0.01	0.0238	0.386	8.665	0.10	0.277	0.005
1039.2	39990	0.01	0.12	0.385	3.484	0.46	-0.083	0.003
Full-size simulations at Constant Pressure Gradient (CPG)								
Re_τ	Re_b	κ^*	ω^*	k	B^*	B_1^*	\mathcal{R}	$\delta\mathcal{R}$
200	6358	-	-	0.390	5.187	-0.30	-	0.003
200	7356	0	0.0838	0.387	7.940	-0.31	0.253	0.002
200	6827	0	0.0251	0.381	6.487	-0.31	0.133	0.004
200	5864	0.01	0.0238	0.390	9.675	-0.30	0.364	0.002
200	5864	0.01	0.12	0.388	3.849	-0.32	-0.176	0.003
1000	39992	-	-	0.387	4.525	0.25	-	0.006
1000	44119	0	0.0838	0.386	7.711	0.10	0.178	0.005
1000	41635	0	0.0251	0.380	5.371	0.27	0.077	0.001
1000	46627	0.01	0.0238	0.388	7.993	0.09	0.264	0.006
1000	38512	0.01	0.12	0.390	3.735	0.28	-0.078	0.006

TABLE 2. Values of the von Kármán constant k , the intercepts B^* and B_1^* , the drag reduction rate \mathcal{R} and its uncertainty $\delta\mathcal{R}$, for the 20 large-box cases detailed in table 1.

uncontrolled value while the validity of the aforementioned assumption is verified indirectly by monitoring that the change in k is smaller than 0.01. In fact, the value of k is known to weakly influence the way the logarithmic and defect-laws (4.3) and (4.4) approximate the mean velocity profile (Del Álamo *et al.* 2004).