# RIEMANNIAN RICCI CURVATURE LOWER BOUNDS IN METRIC MEASURE SPACES WITH $\sigma$-FINITE MEASURE 

LUIGI AMBROSIO, NICOLA GIGLI, ANDREA MONDINO, AND TAPIO RAJALA


#### Abstract

In a prior work of the first two authors with Savaré, a new Riemannian notion of a lower bound for Ricci curvature in the class of metric measure spaces $(X, \mathbf{d}, \mathbf{m})$ was introduced, and the corresponding class of spaces was denoted by $R C D(K, \infty)$. This notion relates the $C D(K, N)$ theory of Sturm and Lott-Villani, in the case $N=\infty$, to the Bakry-Emery approach. In this prior work the $R C D(K, \infty)$ property is defined in three equivalent ways and several properties of $R C D(K, \infty)$ spaces, including the regularization properties of the heat flow, the connections with the theory of Dirichlet forms and the stability under tensor products, are provided. In the above-mentioned work only finite reference measures $\mathbf{m}$ have been considered. The goal of this paper is twofold: on one side we extend these results to general $\sigma$-finite spaces, and on the other we remove a technical assumption that appeared in the earlier work concerning a strengthening of the $C D(K, \infty)$ condition. This more general class of spaces includes Euclidean spaces endowed with Lebesgue measure, complete noncompact Riemannian manifolds with bounded geometry and the pointed metric measure limits of manifolds with lower Ricci curvature bounds.


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## 1. Introduction

In a recent paper 4 written jointly with Savaré, the first and second author introduced a notion of Riemannian Ricci lower bound for metric measure spaces $(X, \mathrm{~d}, \mathfrak{m})$, relying on the calculus tools they had developed in [3. This definition, in the spirit of the $C D(K, N)$ theory proposed by Lott-Villani [25] and Sturm [32, 33, relies on optimal transportation tools and suitable convexity properties of the relative entropy functional $\mathrm{Ent}_{\mathfrak{m}}$. In the framework of [4, these conditions are

[^0]enforced by adding the assumption that the so-called Cheeger energy (playing here the role of the classical Dirichlet energy) is quadratic.

More precisely, the class of $R C D(K, \infty)$ spaces of [4] can be defined in three equivalent ways thanks to this equivalence result (see $\$ 2.3$ for the precise formulation of gradient flows involved here, in the metric sense and in the $E V I_{K}$ sense):

Theorem 1.1 (4). Let $(X, \mathrm{~d}, \mathfrak{m})$ be a metric measure space with $(X, \mathrm{~d})$ complete and separable, $\mathfrak{m}(X) \in(0, \infty)$ and supp $\mathfrak{m}=X$. Then the following are equivalent:
(i) $(X, \mathrm{~d}, \mathfrak{m})$ is a strict $C D(K, \infty)$ space and the $W_{2}$-gradient flow $\mathscr{H}_{t}$ of Ent ${ }_{\mathfrak{m}}$ on $\mathscr{P}_{2}(X)$ is additive.
(ii) $(X, \mathrm{~d}, \mathfrak{m})$ is a strict $C D(K, \infty)$ space and Ch is a quadratic form on $L^{2}(X, \mathfrak{m})$.
(iii) $(X, \mathrm{~d}, \mathfrak{m})$ is a length space and any $\mu \in \mathscr{P}_{2}(X)$ is the starting point of an $E V I_{K}$ gradient flow of $\mathrm{Ent}_{\mathfrak{m}}$.

This equivalence is crucial for the study of the spaces $R C D(K, \infty)$ : for instance the fine properties of the heat flow and the Bakry-Emery condition obtained in [4] need (ii), while the stability of $R C D(K, \infty)$ spaces under Sturm's convergence 33] of metric measure spaces (a variant of measured Gromov-Hausdorff convergence) depends in a crucial way on (iii) and on the stability properties of $E V I_{K}$ flows of (2).

The aim of this paper is to extend of the theory of $R C D(K, \infty)$ spaces to a class of $\sigma$-finite metric measure spaces. This extension includes fundamental examples such as the Lebesgue measure in $\mathbb{R}^{n}$, noncompact Riemannian manifolds with bounded geometry and the pointed metric measure limits of manifolds with lower Ricci curvature bounds studied by Cheeger and Colding [11-13]. In our class of spaces we obtain the perfect analogue of Theorem 1.1 (see Theorem6.1). Actually, even in the finite case we improve Theorem 1.1, replacing strict $C D(K, \infty)$ with $C D(K, \infty)$ in (i) and (ii); this is possible mainly thanks to the fine results of Section 4 .

Let us now briefly and informally explain the terminology implicit in Theorem 1.1 and the technical difficulties arising when one considers $\sigma$-finite reference measures $\mathfrak{m}$. Cheeger's energy Ch can be defined in $L^{2}(X, \mathfrak{m})$ by a relaxation procedure

$$
\operatorname{Ch}(f):=\frac{1}{2} \inf \left\{\liminf _{h \rightarrow \infty} \int_{X}\left|D f_{h}\right|^{2} \mathrm{dm}: f_{h} \text { Lipschitz, } f_{h} \rightarrow f \text { in } L^{2}(X, \mathfrak{m})\right\}
$$

where $|D f|$ is the slope; see (2.6). Instead of this direct construction, we shall exclusively work in this paper with another equivalent one (equivalence follows by Theorem 6.2 of (3), based on the notion of a weak upper gradient $|D f|_{w}$; see Definition [3.2. The weak upper gradient provides integral representation for Ch , namely

$$
\operatorname{Ch}(f)=\frac{1}{2} \int_{X}|D f|_{w}^{2} \mathrm{dm} \quad \text { whenever } \operatorname{Ch}(f)<\infty
$$

Since Ch is convex and lower semicontinuous on $L^{2}(X, \mathfrak{m})$, its gradient flow $\mathrm{h}_{t} f$ is well defined starting from any initial condition. One of the main results of [3] is the coincidence of $\mathrm{h}_{t}$ with the quadratic optimal transport distance semigroup $\mathscr{H}_{t}$ (the $W_{2}$ gradient flow of $\mathrm{Ent}_{\mathfrak{m}}$ ) under the $C D(K, \infty)$ assumption. More precisely, if $f \in L^{2}(X, \mathfrak{m})$ and $\int f(x) \mathrm{d}^{2}\left(x, x_{0}\right) \mathrm{d} \mathfrak{m}(x)$ is finite, then $\mathscr{H}_{t}(f \mathfrak{m})=\left(\mathrm{h}_{t} f\right) \mathfrak{m}$; see Theorem 6.2. This explains the connection between (i) and (ii), where finiteness of $\mathfrak{m}$ does not play any role. Passing to the $E V I_{K}$ condition, deeply studied by the first two authors and Savaré in [2] and by Daneri and Savaré in [15], it amounts
(see Definition 2.5) to a family of differential inequalities indexed by $\sigma \in \mathscr{P}_{2}(X)$ :

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \frac{1}{2} W_{2}^{2}\left(\mu_{t}, \sigma\right) \leq \operatorname{Ent}_{\mathfrak{m}}(\sigma)-\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right)-\frac{K}{2} W_{2}^{2}\left(\mu_{t}, \sigma\right) \quad \text { for a.e. } t \in(0, \infty) \tag{1.1}
\end{equation*}
$$

Set $\mu_{t}=\left(\mathrm{h}_{t} f\right) \mathfrak{m}$ and let $\varphi_{t}$ be Kantorovich potentials from $\mu_{t}$ to $\sigma$. The analysis in (4] shows that

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \frac{1}{2} W_{2}^{2}\left(\mu_{t}, \sigma\right) \leq \lim _{\varepsilon \downarrow 0} \frac{\mathrm{Ch}\left(f_{t}-\varepsilon \varphi_{t}\right)-\mathrm{Ch}\left(f_{t}\right)}{\varepsilon} \tag{1.2}
\end{equation*}
$$

on the one hand, and that the $C D(K, \infty)$ condition gives

$$
\begin{equation*}
\lim _{\varepsilon \downarrow 0} \frac{\operatorname{Ch}\left(\varphi_{t}-\varepsilon f_{t}\right)-\operatorname{Ch}\left(\varphi_{t}\right)}{\varepsilon} \leq \operatorname{Ent}_{\mathfrak{m}}(\sigma)-\operatorname{Ent}\left(\mu_{t}\right)-\frac{K}{2} W_{2}^{2}\left(\mu_{t}, \sigma\right) \tag{1.3}
\end{equation*}
$$

on the other hand. If Ch is quadratic, then we can formally write that both the right hand side in (1.2) and the left hand side in (1.3) coincide with $-\int_{X} D f_{t} \cdot D \varphi_{t} \mathrm{dm}$, thus providing the connection from (ii) to (iii). However, in the derivation of (1.3) a key role is played by the Sobolev regularity of $\log f_{t}$, that can be easily achieved if $f_{t} \geq c>0$. But, this assumption is not compatible with the $\sigma$-finite case, since $f_{t}$ is a probability density, and even local space-time lower bounds on $f_{t}$ can hardly be obtained in our framework, where no finite dimensionality assumption on ( $X, \mathrm{~d}, \mathfrak{m}$ ) is made. It turns out that this derivation is still possible, but only working in a time-dependent weighted Sobolev space. Formally we write

$$
\int_{X} D f_{t} \cdot D \varphi_{t} \mathrm{~d} \mathfrak{m}=\int_{X} D \log f_{t} \cdot D \varphi_{t} \mathrm{~d}\left(f_{t} \mathfrak{m}\right)
$$

and, thanks to the energy dissipation estimate

$$
\operatorname{Ent}_{\mathfrak{m}}\left(f_{T} \mathfrak{m}\right)+\int_{0}^{T} \int_{X} \frac{\left|D f_{t}\right|_{w}^{2}}{f_{t}} \mathrm{~d} \mathfrak{m} \mathrm{~d} t \leq \operatorname{Ent}_{\mathfrak{m}}(f \mathfrak{m})
$$

we know that $\log f_{t}$ belongs for a.e. $t$ to the Sobolev space with weight $f_{t}$. Then we prove that for a.e. $t>0$ the first inequality (1.2) holds, when written in terms of weighted Sobolev spaces, for any choice of the Kantorovich potential $\varphi_{t}$, while the second inequality (1.3) holds for at least one. This suffices for the derivation of (1.1).

Besides the application to $\sigma$-finite $R C D(K, \infty)$ spaces, several results of this paper have an independent interest and do not rely on curvature assumptions; see, for instance, Lemma 2.3 which provides compactness properties of Kantorovich potentials and Theorem [3.6 which analyzes the weighted Cheeger energies. Also, it is worthwhile to mention that the existence of geodesics with $L^{\infty}$ bounds in Section 4 applies to $\sigma$-finite $C D(K, \infty)$ spaces, i.e. no quadratic assumption on Ch is needed for the results of the section. Also, since finiteness of $\mathfrak{m}$ was used in [4] essentially only for the equivalence of Theorem 1.1, we describe in the last section the properties of $R C D(K, \infty)$ spaces proved in [4, whose proof extends with no additional effort to the $\sigma$-finite case: among them we just mention the Bakry-Emery condition

$$
\left|D\left(\mathrm{~h}_{t} f\right)\right|_{w}^{2} \leq \mathrm{e}^{-2 K t}|D f|_{w}^{2} \quad \mathfrak{m} \text {-a.e. in } X .
$$

Further analysis of the Bakry-Emery condition appears in [6]. The extension of the stability of the $R C D(K, \infty)$ condition under Sturm's metric measure convergence to the $\sigma$-finite case is far from being trivial. We refer to 19 for the positive answer to this question.

The paper is organized as follows. In Section 2 we gather a few facts on relative entropy and optimal transportation, mostly stated without proofs (standard references are [1], [2], [34); the only original contribution is a compactness result for Kantorovich potentials via De Giorgi's $\Gamma$-convergence stated in Lemma 2.3

In Section 3 we recall the main results of the theory of weak gradients as developed by the first two authors with Savaré in [3, emphasizing also the connections with the points of view developed by Cheeger in [10, Koskela-MacManus in 23] and Shanmugalingam in 30. The main result of the section is Theorem 3.6 which states that, for probability densities $\rho=g \mathfrak{m}$ with $g \in L^{\infty}(X, \mathfrak{m})$ and $\mathrm{Ch}(\sqrt{g})<\infty$, roughly speaking weak gradients w.r.t. to $\mathfrak{m}$ and weak gradients with respect to $\rho$ are the same, even though no (local) lower bound on $g$ is assumed. Furthermore, Cheeger's energy $\mathrm{Ch}_{\rho}$ induced by $\rho$ is quadratic if Ch is quadratic. Section 4 is crucial for the development of (short time) $L^{\infty}$ estimates for displacement interpolation in $C D(K, \infty)$ spaces (see Theorem 4.2 for a precise statement) which are new in the situation when $(X, \mathrm{~d})$ is unbounded and $\mathfrak{m}$ is not finite. These estimates, which hold when the density of the first measure decays at least as $c_{1} \mathrm{e}^{-c_{2} \mathrm{~d}^{2}\left(x, x_{0}\right)}$ for some $c_{1}, c_{2}>0$ and the second measure has bounded density and support, are obtained by carefully combining entropy minimization (an approach proposed by Sturm and then developed by Rajala in [27,28]) and splitting optimal geodesic plans. Section 5 is devoted to the proof of some auxiliary convergence results dealing with entropy, difference quotients of probability densities and Kantorovich potentials, and bilinear form $\mathrm{Ch}_{\rho}$ associated to a measure $\rho \in \mathscr{P}_{2}(X)$ as in Section 3. Section 6 contains the proof of Theorem 6.1, which provides the equivalence result analogous to Theorem 1.1 in the present $\sigma$-finite setting.

## 2. Preliminaries

In this section we introduce our notation, including the relative entropy functional $\mathrm{Ent}_{\mathrm{n}}$ in (2.1), the slope $|D f|$ of a function $f$ in (2.6), the one-sided slopes $\left|D^{ \pm} f\right|$ in (2.7), the class $A C^{p}(J ; X)$ of absolutely continuous curves with metric derivative in $L^{p}(J)$, the class of geodesics (2.8) and the notions of geodesic and length space. We then review optimal transport, prove the existence of special Lipschitz Kantorovich potentials (Proposition [2.2) and prove a compactness theorem of Kantorovich potentials (Lemma 2.3).

We assume throughout the paper that $(X, \mathrm{~d}, \mathfrak{m})$ is a metric measure space with ( $X, \mathrm{~d}$ ) complete and separable and $\mathfrak{m}$ a nonnegative Borel measure finite on bounded sets and satisfying supp $\mathfrak{m}=X$.

We denote by $\mathscr{P}(X)$ the space of Borel probability measures on $(X, \mathrm{~d})$ and set $\mathscr{P}_{2}(X):=\left\{\mu \in \mathscr{P}(X): \int_{X} \mathrm{~d}^{2}\left(x_{0}, x\right) \mathrm{d} \mu(x)<\infty\right.$ for some (and hence all) $\left.x_{0} \in X\right\}$. Given a nonnegative Borel measure $\mathfrak{n}$, the relative entropy functional Ent $_{\mathfrak{n}}: \mathscr{P}_{2}(X)$ $\rightarrow[-\infty, \infty]$ with respect to $\mathfrak{n}$ is defined as in Sturm's paper [32] by

$$
\operatorname{Ent}_{\mathfrak{n}}(\mu):= \begin{cases}\lim _{\epsilon \downarrow 0} \int_{\{\rho>\epsilon\}} \rho \log \rho \mathrm{dn} & \text { if } \mu=\rho \mathfrak{n}  \tag{2.1}\\ \infty & \text { otherwise }\end{cases}
$$

It coincides with $\int_{\{\rho>0\}} \rho \log \rho \mathrm{d} \mathfrak{n} \in[-\infty, \infty)$ if the positive part of $\rho \log \rho$ is $\mathfrak{n}$ integrable, and it is equal to $\infty$ otherwise.

In the sequel we use the notation

$$
\begin{equation*}
D\left(\operatorname{Ent}_{\mathfrak{n}}\right):=\left\{\mu \in \mathscr{P}_{2}(X): \operatorname{Ent}_{\mathfrak{n}}(\mu) \in[-\infty, \infty)\right\} \tag{2.2}
\end{equation*}
$$

By Jensen's inequality, $\mathrm{Ent}_{\mathfrak{n}}$ is nonnegative when $\mathfrak{n} \in \mathscr{P}(X)$. More generally, we recall (see [3, Lemma 7.2] for the simple proof) that when $\mathfrak{n}$ satisfies the growth condition

$$
\begin{equation*}
\int_{X} \mathrm{e}^{-\mathrm{cd}^{2}\left(x_{0}, x\right)} \mathrm{dn}(x)<\infty, \tag{2.3}
\end{equation*}
$$

for some $x_{0} \in X$ and $\mathrm{c} \in(0, \infty)$, then Ent $_{\mathrm{n}}$ can bounded from below as follows. Letting $z=\int_{X} \mathrm{e}^{-c d^{2}\left(x, x_{0}\right)} \mathrm{dn}$ and

$$
\begin{equation*}
\tilde{\mathfrak{n}}=\frac{1}{z} \mathrm{e}^{-c \mathrm{~d}^{2}\left(x, x_{0}\right)} \mathfrak{n} \in \mathscr{P}(X), \quad V(x)=\mathrm{d}\left(x, x_{0}\right), \tag{2.4}
\end{equation*}
$$

and using the simple formula for the change of the reference measure

$$
\begin{equation*}
\operatorname{Ent}_{\mathfrak{n}}(\mu)=\operatorname{Ent}_{\tilde{\mathfrak{n}}}(\mu)-c \int_{X} V^{2} \mathrm{~d} \mu-\log z, \quad \forall \mu \in \mathscr{P}_{2}(X) \tag{2.5}
\end{equation*}
$$

we see that Ent $_{n}$ can be bounded from below in terms of the second moment of $\mu$. It is important to recall that if $(X, \mathrm{~d}, \mathfrak{m})$ is a $C D(K, \infty)$ space (see Definition 4.1), then the reference measure $\mathfrak{m}$ always satisfies the growth condition (2.3), as shown by Sturm in [32, Theorem 4.24].
2.1. Metric structure. We shall denote by $\operatorname{Lip}(X)$ the space of Lipschitz functions $f: X \rightarrow \mathbb{R}$ and by $\operatorname{Lip}_{b}(X)$ the subspace of bounded Lipschitz functions.

Given $f: X \rightarrow \mathbb{R}$ we define its slope $|D f|$ at $x$ by

$$
\begin{equation*}
|D f|(x):=\limsup _{y \rightarrow x} \frac{|f(y)-f(x)|}{\mathrm{d}(y, x)} \tag{2.6}
\end{equation*}
$$

We shall also use, in connection with Kantorovich potentials, the one-sided counterparts of the slope, namely the ascending slope and descending slopes:

$$
\begin{equation*}
\left|D^{+} f\right|(x):=\limsup _{y \rightarrow x} \frac{[f(y)-f(x)]^{+}}{\mathrm{d}(y, x)}, \quad\left|D^{-} f\right|(x):=\limsup _{y \rightarrow x} \frac{[f(y)-f(x)]^{-}}{\mathrm{d}(y, x)} . \tag{2.7}
\end{equation*}
$$

Given an open interval $J \subset \mathbb{R}$, an exponent $p \in[1, \infty]$ and $\gamma: J \rightarrow X$, we say that $\gamma$ belongs to $A C^{p}(J ; X)$ if there exists $g \in L^{p}(J)$ satisfying

$$
\mathrm{d}\left(\gamma_{s}, \gamma_{t}\right) \leq \int_{s}^{t} g(r) \mathrm{d} r \quad \forall s, t \in J, s<t
$$

The case $p=1$ corresponds to absolutely continuous curves, denoted $A C(J ; X)$. It turns out that if $\gamma$ belongs to $A C^{p}(J ; X)$, there is a minimal function $g$ with this property, called the metric derivative, and given for a.e. $t \in J$ by

$$
\left|\dot{\gamma}_{t}\right|:=\lim _{s \rightarrow t} \frac{\mathrm{~d}\left(\gamma_{s}, \gamma_{t}\right)}{|s-t|}
$$

See [2, Theorem 1.1.2] for the simple proof. We say that an absolutely continuous curve $\gamma_{t}$ has constant speed if $\left|\dot{\gamma}_{t}\right|$ is (equivalent to) a constant.

We call ( $X, \mathrm{~d}$ ) a geodesic space if for any $x_{0}, x_{1} \in X$ there exists $\gamma:[0,1] \rightarrow X$ satisfying $\gamma_{0}=x_{0}, \gamma_{1}=x_{1}$ and

$$
\begin{equation*}
\mathrm{d}\left(\gamma_{s}, \gamma_{t}\right)=|t-s| \mathrm{d}\left(\gamma_{0}, \gamma_{1}\right) \quad \forall s, t \in[0,1] . \tag{2.8}
\end{equation*}
$$

We will denote by $\operatorname{Geo}(X)$ the space of all constant speed geodesics $\gamma:[0,1] \rightarrow X$, namely $\gamma \in \operatorname{Geo}(X)$ if (2.8) holds. Recall also that the weaker notion of length space: for all $x_{0}, x_{1} \in X$ and $\varepsilon>0$ there exists $\gamma \in A C([0,1] ; X)$ such that $\int_{0}^{1}\left|\dot{\gamma}_{t}\right| \mathrm{d} t<\mathrm{d}\left(x_{0}, x_{1}\right)+\varepsilon$.

From the measure-theoretic point of view, when considering measures on $A C^{p}(J ; X)($ resp. Geo $(X))$, we shall consider them as measures on the Polish space $C(J ; X)$ endowed with the sup norm, concentrated on the Borel set $A C^{p}(J ; X)$ (resp. closed set $\mathrm{Geo}(X))$. We shall also use the notation $\mathrm{e}_{t}: C(J ; X) \rightarrow X, t \in J$, for the evaluation map at time $t$, namely $\mathrm{e}_{t}(\gamma):=\gamma_{t}$.
2.2. Optimal transport. Given $\mu, \nu \in \mathscr{P}_{2}(X)$, we define the quadratic optimal transport distance $W_{2}$ between them as

$$
\begin{equation*}
W_{2}^{2}(\mu, \nu):=\inf \int_{X \times X} \mathrm{~d}^{2}(x, y) \mathrm{d} \boldsymbol{\gamma}(x, y), \tag{2.9}
\end{equation*}
$$

where the infimum is taken among all Kantorovich transport plans, namely probability measures $\gamma$ on $X \times X$ such that

$$
\pi_{\sharp}^{1} \boldsymbol{\gamma}=\mu, \quad \pi_{\sharp}^{2} \boldsymbol{\gamma}=\nu .
$$

Here, for $\mu \in \mathscr{P}(X)$, a topological space $Y$ and a $\mu$-measurable map $T: X \rightarrow Y$, the push-forward measure $T_{\sharp} \mu \in \mathscr{P}(Y)$ is defined by $T_{\sharp} \mu(B):=\mu\left(T^{-1}(B)\right)$ for every Borel set $B \subset Y$.

Since $(X, \mathrm{~d})$ is complete and separable, the space $\left(\mathscr{P}_{2}(X), W_{2}\right)$ is complete and separable. Since the cost $\mathrm{d}^{2}$ is lower semicontinuous, the infimum in the definition (2.9) of $W_{2}^{2}$ is attained. All plans $\gamma$ achieving the minimum will be called optimal.

For all $\mu, \nu \in \mathscr{P}_{2}(X)$ Kantorovich's duality formula holds:

$$
\begin{equation*}
\frac{1}{2} W_{2}^{2}(\mu, \nu)=\sup \left\{\int_{X} \varphi \mathrm{~d} \mu+\int_{X} \psi \mathrm{~d} \nu: \varphi(x)+\psi(y) \leq \frac{1}{2} \mathrm{~d}^{2}(x, y)\right\} \tag{2.10}
\end{equation*}
$$

where the supremum is taken among all functions $\varphi \in L^{1}(X, \mu)$ and $\psi \in L^{1}(X, \nu)$.
Recall that the $c$-transform $\varphi^{c}$ of $\varphi: X \rightarrow \mathbb{R} \cup\{-\infty\}$ is defined by

$$
\varphi^{c}(y):=\inf \left\{\frac{\mathrm{d}^{2}(x, y)}{2}-\varphi(x): x \in X\right\}
$$

and that $\psi$ is said to be $c$-concave if $\psi=\varphi^{c}$ for some $\varphi$.
Definition 2.1 (Kantorovich potential). We say that a map $\varphi: X \rightarrow \mathbb{R} \cup\{-\infty\}$ is a Kantorovich potential relative to $(\mu, \nu)$ if:
(i) there exists a Borel map $\psi: X \rightarrow \mathbb{R} \cup\{-\infty\}$ such that $\psi \in L^{1}(X, \nu)$ and $\varphi=\psi^{c}$;
(ii) $\varphi \in L^{1}(X, \mu)$ and the pair $(\varphi, \psi)$ maximizes (2.10).

Notice that the inequality $\varphi(x)+\psi(y) \leq \frac{1}{2} \mathrm{~d}^{2}(x, y)$, when integrated against an optimal plan $\gamma$, forces the integrability of the positive part of $\varphi$. For this reason, in (ii) we may equivalently require integrability of the negative part of $\varphi$ only. In the next proposition we illustrate some key properties of Kantorovich potentials $\varphi$ and show how, in the special case when $\operatorname{supp} \nu$ is bounded, a special choice of $\psi$ provides better properties of $\varphi=\psi^{c}$.

Proposition 2.2 (Existence of Kantorovich potentials). If $\mu, \nu \in \mathscr{P}_{2}(X)$, then $a$ Kantorovich potential $\varphi=\psi^{c}$ relative to $(\mu, \nu)$ exists and satisfies

$$
\begin{equation*}
\varphi(x)+\psi(y)=\frac{1}{2} \mathrm{~d}^{2}(x, y) \quad \text { for } \boldsymbol{\gamma} \text {-a.e. in }(x, y) \in X \times X \tag{2.11}
\end{equation*}
$$

for any optimal Kantorovich plan $\gamma$ and

$$
\begin{equation*}
\left|D^{+} \varphi\right|(x) \leq \mathrm{d}(x, y) \quad \text { for } \gamma \text {-a.e. }(x, y) \tag{2.12}
\end{equation*}
$$

In addition, if $\operatorname{supp} \nu \subset \bar{B}_{R}\left(y_{0}\right)$ for some $R \geq 1$, then a locally Lipschitz Kantorovich potential $\varphi=\psi^{c}$ exists with $\psi \equiv-\infty$ on $X \backslash \operatorname{supp} \nu, \psi \leq R^{2} / 2$ on $\operatorname{supp} \nu$ and

$$
\begin{equation*}
|D \varphi|(x) \leq R+\mathrm{d}\left(x, y_{0}\right), \quad|\varphi(x)| \leq 2 R^{2}\left(1+\mathrm{d}^{2}\left(x, y_{0}\right)\right) \tag{2.13}
\end{equation*}
$$

Proof. Since any complete and separable metric space can be isometrically embedded in a complete, separable and geodesic metric space, we can assume with no loss of generality that the space ( $X, \mathrm{~d}$ ) is geodesic. The existence part is well known, so let us discuss briefly (2.12), the choice of gauge and the regularity properties of $\varphi$ when $\nu$ has bounded support. From (2.11) and the inequality $\varphi+\varphi^{c} \leq \mathrm{d}^{2} / 2$ we get

$$
\varphi(z)-\varphi(x) \leq \frac{1}{2}\left(\mathrm{~d}^{2}(z, y)-\mathrm{d}^{2}(x, y)\right) \quad \text { for all } z
$$

for $\gamma$-a.e. $(x, y)$, so that $\left|D^{+} \varphi\right|(x) \leq \mathrm{d}(x, y)$ for $\gamma$-a.e. $(x, y)$.
Now, let us set

$$
\tilde{\psi}(x):= \begin{cases}\psi(x) & \text { if } x \in \operatorname{supp} \nu \\ -\infty & \text { otherwise }\end{cases}
$$

and $\tilde{\varphi}:=(\tilde{\psi})^{c}$. Since $\tilde{\varphi} \geq \varphi$, it is obvious that its negative part is $\mu$-integrable and that $(\tilde{\varphi}, \tilde{\psi})$ is a maximizing pair, so that $\tilde{\varphi}$ is a Kantorovich potential. From

$$
\tilde{\varphi}(x)=\inf _{y \in \operatorname{supp} \nu} \frac{1}{2} \mathrm{~d}^{2}(x, y)-\tilde{\psi}(y)
$$

and the inclusion $\operatorname{supp} \nu \subset B_{R}\left(y_{0}\right)$ it is immediate to obtain the linear growth of $|D \tilde{\varphi}|$, in the form stated in (2.13). Finally, possibly adding and subtracting the same constant to the potentials in the maximizing pair, we can assume that $\tilde{\varphi}\left(y_{0}\right)=0$. Then, the inequality $\tilde{\psi} \leq \frac{1}{2} \mathrm{~d}^{2}\left(y_{0}, \cdot\right)$ gives $\tilde{\psi} \leq R^{2} / 2$ on supp $\nu$. The linear growth of $|D \tilde{\varphi}|$ gives the quadratic growth of $|\varphi|$, since $(X, \mathrm{~d})$ is geodesic.

In the proof of the next lemma we use De Giorgi's $\Gamma$-convergence. Strictly speaking, we use $\Gamma^{-}$-convergence, the one designed for convergence of minimum problems. We recall the definition and the basic facts, referring to Dal Maso's book 14 for a full account of this theory. If $(Y, d)$ is a metric space and $f_{h}$ : $Y \rightarrow[-\infty,+\infty], f: Y \rightarrow[-\infty,+\infty]$ are lower semicontinuous, we say that $\left(f_{h}\right)$ $\Gamma$-converges to $f$ and write $f=\Gamma-\lim _{h} f_{h}$ if:
(a) for any sequence $\left(y_{h}\right) \subset Y$ convergent to $y \in Y$, one has $\liminf _{h} f_{h}\left(y_{h}\right) \geq$ $f(y)$;
(b) for all $y \in Y$ there exists $\left(y_{h}\right) \subset Y$ convergent to $y$ and satisfying $\lim \sup _{h} f_{h}\left(y_{h}\right) \leq f(y)$.
It is immediate to check that $\Gamma$-convergence is invariant by additive constant perturbations. In addition, (a) yields that $f \mapsto \inf _{A} f$ is lower semicontinuous w.r.t. $\Gamma$-convergence for any open set $A \subset Y$, while (b) yields that $f \mapsto \min _{K} f$ is upper
semicontinuous w.r.t. $\Gamma$-convergence for any compact set $K \subset Y$. If $Y$ is compact we can choose $A=K=Y$ to obtain

$$
\begin{equation*}
\Gamma-\lim _{h \rightarrow \infty} f_{h}=f \quad \Longrightarrow \quad \lim _{h \rightarrow \infty} \min _{Y} f_{h}=\min _{Y} f \tag{2.14}
\end{equation*}
$$

We need one more property of $\Gamma$-convergence: if $Y$ is separable, then any sequence of lower semicontinuous maps $f_{h}: Y \rightarrow[-\infty,+\infty]$ admits a $\Gamma$-convergent subsequence $f_{h(k)}$. To see this, let $\mathscr{U}$ be a countable basis of open sets of $Y$ and extract with a diagonal argument a subsequence $h(k)$ such that $\inf _{U} f_{k(k)}$ has a limit in $[-\infty,+\infty]$ for all $U \in \mathscr{U}$. Then, the function

$$
f(y):=\sup _{U \ni y, U \in \mathscr{U}} \lim _{k \rightarrow \infty} \inf _{U} f_{h(k)}, \quad y \in Y,
$$

provides the $\Gamma$-limit of $f_{h(k)}$.
Lemma 2.3 (Compactness of Kantorovich potentials). Consider probability densities $\sigma, \eta=f \mathfrak{m}, \eta_{n}=f_{n} \mathfrak{m} \in \mathscr{P}_{2}(X)$ satisfying the following conditions:
(a) $\sigma$ has compact support;
(b) $f_{n} \rightarrow f \mathfrak{m}$-a.e. in $X$ and $\sup _{n} f_{n}(x)\left(1+\mathrm{d}^{2}\left(x, x_{0}\right)\right) \in L^{1}(X, \mathfrak{m})$ for some $x_{0} \in X$.
Suppose there exist $C>0$ and Kantorovich potentials $\varphi_{n}=\psi_{n}^{c}$ relative to ( $\eta_{n}, \sigma$ ) in the sense of Definition [2.1, satisfying

$$
\begin{equation*}
\left|\varphi_{n}(x)\right| \leq C\left(1+\mathrm{d}^{2}\left(x, x_{0}\right)\right) \quad \forall x \in X \tag{2.15}
\end{equation*}
$$

and

$$
\begin{equation*}
\psi_{n} \equiv-\infty \quad \text { on } X \backslash \operatorname{supp} \sigma \quad \text { and } \quad \psi_{n}(x) \leq C \forall x \in X \tag{2.16}
\end{equation*}
$$

Then there exist a subsequence $n(k)$ and a Kantorovich potential $\varphi=\psi^{c}$ of the transportation problem relative to $(\eta, \sigma)$ such that $\varphi_{n(k)} \rightarrow \varphi$ pointwise. In addition (2.15) is fulfilled by $\varphi$ and $\psi \leq C$.

Proof. Since $X$ is separable, by the compactness properties of $\Gamma$-convergence we can assume with no loss of generality that $-\psi_{n} \Gamma$-converges as $n \rightarrow \infty$, and we shall denote by $-\psi$ its $\Gamma$-limit. Observe that, since by the definition of $\Gamma$-convergence for every $x \in X$ there exists a sequence $x_{n} \rightarrow x$ such that $-\psi_{n}\left(x_{n}\right) \rightarrow-\psi(x), \psi$ still satisfies (2.16).

By the invariance of $\Gamma$-convergence under continuous additive perturbations we get

$$
\begin{equation*}
\left(\frac{1}{2} \mathrm{~d}^{2}(x, \cdot)-\psi\right)=\Gamma-\lim _{n \rightarrow \infty}\left(\frac{1}{2} \mathrm{~d}^{2}(x, \cdot)-\psi_{n}\right) \quad \forall x \in X . \tag{2.17}
\end{equation*}
$$

Because of (2.16) and of the compactness of $\operatorname{supp} \sigma$, we can use (2.14) to get

$$
\begin{equation*}
\varphi_{n}(x)=\min _{X}\left(\frac{1}{2} \mathrm{~d}^{2}(x, \cdot)-\psi_{n}\right) \rightarrow \min _{X}\left(\frac{1}{2} \mathrm{~d}^{2}(x, \cdot)-\psi\right)=\varphi(x), \tag{2.18}
\end{equation*}
$$

where the last equality has to be understood as the definition of $\varphi(x)$. Obviously (2.15) is fulfilled by $\varphi$, so that $\varphi \in L^{1}(X, f \mathfrak{m})$. In connection with $\psi$, obviously its positive part is $\sigma$-integrable.

Now we claim that $\varphi=\psi^{c}$ is a Kantorovich potential for the limit transportation problem $(f \mathfrak{m}, \sigma)$. We have to prove that

$$
\begin{equation*}
\int_{X} \varphi \mathrm{~d}(f \mathfrak{m})+\int_{X} \psi \mathrm{~d} \sigma \geq \frac{1}{2} W_{2}^{2}(f \mathfrak{m}, \sigma) \tag{2.19}
\end{equation*}
$$

since this inequality also provides at the same time integrability of the negative part of $\psi$. Since by assumption $\varphi_{n}=\psi_{n}^{c}$ is a Kantorovich potential for $\left(f_{n} \mathfrak{m}, \sigma\right)$, we already know that

$$
\begin{equation*}
\int_{X} \varphi_{n} \mathrm{~d}\left(f_{n} \mathfrak{m}\right)+\int_{X} \psi_{n} \mathrm{~d} \sigma=\frac{1}{2} W_{2}^{2}\left(f_{n} \mathfrak{m}, \sigma\right) \tag{2.20}
\end{equation*}
$$

Using (b) it is immediate to check the weak convergence of $f_{n} \mathfrak{m}$ to $f \mathfrak{m}$, so that (see for instance Proposition 2.5 in (1)

$$
\begin{equation*}
W_{2}^{2}(f \mathfrak{m}, \sigma) \leq \liminf _{n} W_{2}^{2}\left(f_{n} \mathfrak{m}, \sigma\right) \tag{2.21}
\end{equation*}
$$

Moreover, using (b) and (2.15), the dominated convergence theorem gives

$$
\begin{equation*}
\int_{X} \varphi_{n} \mathrm{~d}\left(f_{n} \mathfrak{m}\right) \rightarrow \int_{X} \varphi \mathrm{~d}(f \mathfrak{m}) \tag{2.22}
\end{equation*}
$$

Finally, by the very definition of $\Gamma$-limit we have

$$
-\psi(x)=\inf \left\{\liminf _{n \rightarrow \infty}-\psi_{n}\left(x_{n}\right) \mid x_{n} \rightarrow x\right\} \leq \liminf _{n \rightarrow \infty}-\psi_{n}(x)
$$

Moreover, by assumption (2.16), $-\psi_{n} \geq-C$. Hence Fatou's lemma gives

$$
\begin{equation*}
\limsup _{n \rightarrow \infty} \int_{X} \psi_{n} \mathrm{~d} \sigma \leq \int_{X} \psi \mathrm{~d} \sigma \tag{2.23}
\end{equation*}
$$

Putting together (2.20), (2.21), (2.22) and (2.23) we get (2.19) as desired.
Let us close this section by discussing the geodesic structure of $\left(\mathscr{P}_{2}(X), W_{2}\right)$; see [1. Theorem 2.10] or [24]. If $\mu_{0}, \mu_{1} \in \mathscr{P}_{2}(X)$ are connected by a constant speed geodesic $\mu_{t}$ in $\left(\mathscr{P}_{2}(X), W_{2}\right)$, then there exists $\boldsymbol{\pi} \in \mathscr{P}(\operatorname{Geo}(X))$ with $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi}=\mu_{t}$ for all $t \in[0,1]$ and
$W_{2}^{2}\left(\mu_{s}, \mu_{t}\right)=\int_{\operatorname{Geo}(X)} \mathrm{d}^{2}\left(\gamma_{s}, \gamma_{t}\right) \mathrm{d} \boldsymbol{\pi}(\gamma)=(s-t)^{2} \int_{\operatorname{Geo}(X)} \ell^{2}(\gamma) \mathrm{d} \boldsymbol{\pi}(\gamma) \quad \forall s, t \in[0,1]$, where $\ell(\gamma)=\mathbf{d}\left(\gamma_{0}, \gamma_{1}\right)$ is the length of the geodesic $\gamma$. The collection of all the measures $\boldsymbol{\pi}$ with the above properties is denoted by $\operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$. The measure $\boldsymbol{\pi}$ is not uniquely determined by $\mu_{t}$, unless ( $X, \mathrm{~d}$ ) is nonbranching. The relation between optimal geodesic plans and optimal Kantorovich plans is given by the fact that $\gamma:=\left(\mathrm{e}_{0}, \mathrm{e}_{1}\right)_{\sharp} \boldsymbol{\pi}$ is optimal whenever $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$.
2.3. Gradient flows. In this section we review the notions of gradient flows in the metric sense, in the $E V I_{K}$ sense and in the classical sense provided, in Hilbert spaces, by the theory of monotone operators.

Let $\left(Y, \mathrm{~d}_{Y}\right)$ be a complete and separable metric space and $K \in \mathbb{R}$. We say that $E: Y \rightarrow \mathbb{R} \cup\{+\infty\}$ is $K$-geodesically convex if for any $y_{0}, y_{1} \in D(E)$ there exists $\gamma \in \operatorname{Geo}(Y)$ satisfying $\gamma_{0}=y_{0}, \gamma_{1}=y_{1}$ and

$$
E\left(\gamma_{t}\right) \leq(1-t) E\left(y_{0}\right)+t E\left(y_{1}\right)-\frac{K}{2} t(1-t) \mathrm{d}_{Y}^{2}\left(y_{0}, y_{1}\right) \quad \text { for every } t \in[0,1]
$$

Definition 2.4 (Metric formulation of gradient flow). Let $E: Y \rightarrow \mathbb{R} \cup\{+\infty\}$ be a $K$-geodesically convex and l.s.c. functional. We say that a locally absolutely continuous curve $[0, \infty) \ni t \mapsto y_{t} \in D(E)$ is a gradient flow of $E$ starting from $y_{0} \in D(E)$ if

$$
\begin{equation*}
E\left(y_{0}\right)=E\left(y_{t}\right)+\int_{0}^{t} \frac{1}{2}\left|\dot{y}_{r}\right|^{2}+\frac{1}{2}\left|D^{-} E\right|^{2}\left(y_{r}\right) \mathrm{d} r \quad \forall t \geq 0 \tag{2.24}
\end{equation*}
$$

Next we recall a stronger formulation of gradient flows, introduced and extensively studied in [2, 15.

Definition 2.5 (Gradient flows in the $E V I_{K}$ sense). Let $E: Y \rightarrow \mathbb{R} \cup\{+\infty\}$ be a lower semicontinuous functional, $K \in \mathbb{R}$ and $(0, \infty) \ni t \mapsto y_{t} \in D(E)$ be a locally absolutely continuous curve. We say that $\left(y_{t}\right)$ is a $K$-gradient flow for $E$ in the Evolution Variational Inequalities sense (or, simply, it is an $E V I_{K}$ gradient flow) if for any $z \in Y$ we have

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \frac{\mathrm{~d}_{Y}^{2}\left(y_{t}, z\right)}{2}+\frac{K}{2} \mathrm{~d}_{Y}^{2}\left(y_{t}, z\right)+E\left(y_{t}\right) \leq E(z) \quad \text { for a.e. } t \in(0, \infty) \tag{2.25}
\end{equation*}
$$

If $\lim _{t \downarrow 0} y_{t}=y_{0} \in \overline{D(E)}$, we say that the gradient flow starts from $y_{0}$.
Notice that the derivative in (2.25) exists for a.e. $t>0$, since $t \mapsto \mathrm{~d}_{Y}\left(y_{t}, z\right)$ is locally absolutely continuous in $(0, \infty)$.

We recall some basic and useful properties of gradient flows in the $E V I_{K}$ sense (see Proposition 2.22 in [4); we also refer to [2, Chap. 4] for more results. In particular, we emphasize that the maps $\mathrm{S}_{t}: y_{0} \mapsto y_{t}$, that at every $y_{0}$ associate the value at time $t \geq 0$ of the unique $K$-gradient flow starting from $y_{0}$, give rise to a continuous semigroup of $K$-contractions according to (2.26) in a closed (possibly empty) subset of $Y$.

Proposition 2.6 (Properties of gradient flows in the $E V I_{K}$ sense). Let $Y, E, K$, $y_{t}$ be as in Definition [2.5 and suppose that $\left(y_{t}\right)$ is an $E V I_{K}$ gradient flow of $E$ starting from $y_{0}$. Then:
(i) If $y_{0} \in D(E)$, then $y_{t}$ is also a metric gradient flow, i.e. (2.24) holds.
(ii) If $\left(\tilde{y}_{t}\right)$ is another $E V I_{K}$ gradient flow for $E$ starting from $\tilde{y}_{0}$, then

$$
\begin{equation*}
\mathrm{d}_{Y}\left(y_{t}, \tilde{y}_{t}\right) \leq e^{-K t} \mathrm{~d}_{Y}\left(y_{0}, \tilde{y}_{0}\right) . \tag{2.26}
\end{equation*}
$$

In particular, $E V I_{K}$ gradient flows uniquely depend on the initial condition.
(iii) The existence of $E V I_{K}$ gradient flows starting from any point in $D \subset Y$ implies the existence starting from any point in $\bar{D}$.

If $\left(Y, \mathrm{~d}_{Y}\right)$ is a Hilbert space with distance induced by the scalar product, the gradient flow of a lower semicontinuous functional $E: Y \rightarrow \mathbb{R} \cup\{+\infty\}$ can also be defined as a locally absolutely continuous map $y_{t}:(0, \infty) \rightarrow H$ satisfying

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} y_{t} \in-\partial^{-} E\left(y_{t}\right) \text { for a.e. } t>0, \quad \lim _{t \downarrow 0} y_{t}=y \text { in } H, \tag{2.27}
\end{equation*}
$$

where the Frechet subdifferential $\partial^{-} E(y)$ is defined by

$$
\begin{equation*}
\partial^{-} E(y):=\left\{\xi \in H: \liminf _{y^{\prime} \rightarrow y} \frac{E\left(y^{\prime}\right)-E(y)-\left\langle\xi, y^{\prime}-y\right\rangle}{\mathrm{d}_{Y}\left(y^{\prime}, y\right)} \geq 0\right\} . \tag{2.28}
\end{equation*}
$$

Under a $K$-convexity assumption the subdifferential can be equivalently defined as

$$
\begin{equation*}
\partial^{-} E(y):=\left\{\xi \in H: E\left(y^{\prime}\right) \geq E(y)+\left\langle\xi, y^{\prime}-y\right\rangle+\frac{K}{2} \mathrm{~d}_{Y}^{2}\left(y^{\prime}, y\right) \text { for all } y^{\prime} \in H\right\} . \tag{2.29}
\end{equation*}
$$

Differentiating the squared distance in (2.25) yields that the $E V I_{K}$ formulation and (2.27) are equivalent in the Hilbert setting, for $K$-convex functionals.

## 3. Weak gradients and weighted Cheeger energies

In this section we recall the main results of the theory of weak gradients as developed by the first two authors with Savaré in [3], emphasizing the connections with the points of view developed by Cheeger in [10, Koskela-MacManus in 23] and Shanmugalingam in [30. We prove in Theorem [3.6 the equivalence of weak gradients defined with reference measures $\mathfrak{n}$ and $\mathfrak{m}$, under suitable assumptions on the density of $\mathfrak{n}$ w.r.t. $\mathfrak{m}$. We introduce in (3.6) the weighted Cheeger energy $\mathrm{Ch}_{\mathfrak{n}}$ and show in Theorem 3.9 that, under the assumptions of Theorem 3.6 $\mathrm{Ch}_{\mathfrak{n}}$ is quadratic whenever Ch is quadratic.

In the next two definitions we consider test plans and "Sobolev" functions with respect to a reference nonnegative Borel measure $\mathfrak{n}$ in $X$, finite on bounded sets. In the sequel we shall denote by $\mathcal{M}$ this class of measures, including both probability measures and our reference measure $\mathfrak{m}$.

Definition 3.1 (Test plan). We say that $\boldsymbol{\pi} \in \mathscr{P}(C([0,1] ; X))$ is a 2-test plan relative to $\mathfrak{n} \in \mathcal{M}$ if:
(i) $\boldsymbol{\pi}$ is concentrated on $A C^{2}([0,1] ; X)$ and the 2 -action of $\boldsymbol{\pi}$ is finite:

$$
\mathcal{A}_{2}(\boldsymbol{\pi}):=\iint_{0}^{1}\left|\dot{\gamma}_{t}\right|^{2} \mathrm{~d} t \mathrm{~d} \boldsymbol{\pi}(\gamma)<\infty
$$

(ii) There exists $C \geq 0$ such that $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi} \leq C \mathfrak{n}$ for all $t \in[0,1]$.

The following definition was inspired by Heinonen-Koskela's concept [21] of an upper gradient, that we now illustrate. A Borel function $G: X \rightarrow[0, \infty]$ is an upper gradient of a Borel function $f: X \rightarrow \mathbb{R}$ if

$$
\left|f\left(\gamma_{b}\right)-f\left(\gamma_{a}\right)\right| \leq \int_{a}^{b} G\left(\gamma_{s}\right)\left|\dot{\gamma}_{s}\right| \mathrm{d} s
$$

for any absolutely continuous curve $\gamma:[a, b] \rightarrow X$. Since the inequality is invariant under reparameterization, one can also reduce to curves defined in $[0,1]$.

Let $\mathscr{C}(X)$ be the set of continuous parametric curves $C \subset X$ with finite length, where curves equivalent under reparameterization are identified. Recall that any such curve $C$ can be written as $\gamma([0, \ell])$, where $\ell$ is the length of $C$ and $\gamma:[0, \ell] \rightarrow X$ is Lipschitz with $|\dot{\gamma}|=1$ a.e. in $[0, \ell]$. We shall denote by $i: A C^{2}([0,1] ; X) \rightarrow \mathscr{C}(X)$ the natural surjection.

Recall also that the 2 -modulus of $\Gamma \subset \mathscr{C}(X)$ is defined by

$$
\begin{equation*}
\operatorname{Mod}_{2, \mathfrak{n}}(\Gamma):=\inf \left\{\int_{X} g^{2} \mathrm{dn}: g: X \rightarrow[0, \infty] \text { Borel, } \int_{\gamma} g \geq 1 \text { for all } \gamma \in \Gamma\right\} \tag{3.1}
\end{equation*}
$$

Shanmugalingam proved in 30 that functions with an upper gradient in $L^{2}(X, \mathfrak{n})$ are absolutely continuous along a $\operatorname{Mod}_{2, \mathfrak{n}}$-a.e. curve in $\mathscr{C}(X)$. We also recall the following simple consequence of (3.1): for any $\operatorname{Mod}_{2, \mathfrak{n}}$-negligible set $\Gamma$ there exist Borel functions $r_{h}: X \rightarrow[0, \infty]$ satisfying $\int_{X} r_{h}^{2} \mathrm{~d} \mathfrak{n} \rightarrow 0$ and $\int_{\gamma} r_{h}=\infty$ for all $\gamma \in \Gamma$. Also, the inequality

$$
\operatorname{Mod}_{2, \mathfrak{n}}\left(\left\{\gamma: \int_{\gamma} g \geq t\right\}\right) \leq \frac{1}{t}\left(\int_{X} g^{2} \mathrm{dn}\right)^{1 / 2}, \quad t>0
$$

immediately yields that functions in $L^{2}(X, \mathfrak{m})$ have a finite integral on $\gamma$ for $\operatorname{Mod}_{2, \mathfrak{n}^{-}}$ a.e. $\gamma$.

Definition 3.2 (The space $\mathcal{S}_{\mathfrak{n}}^{2}$ and weak upper gradients). Let $f: X \rightarrow \mathbb{R}, G$ : $X \rightarrow[0, \infty]$ be Borel functions. We say that $G$ is a 2 -weak upper gradient relative to $\mathfrak{n}$ of $f$ if

$$
\left|f\left(\gamma_{1}\right)-f\left(\gamma_{0}\right)\right| \leq \int_{0}^{1} G\left(\gamma_{s}\right)\left|\dot{\gamma}_{s}\right| \mathrm{d} s<\infty \quad \text { for } \boldsymbol{\pi} \text {-a.e. } \gamma
$$

for all 2 -test plans $\boldsymbol{\pi}$ relative to $\mathfrak{n}$.
We write $f \in \mathcal{S}_{\mathfrak{n}}^{2}$ if $f$ has a 2 -weak upper gradient in $L^{2}(X, \mathfrak{n})$. The 2 -weak upper gradient relative to $\mathfrak{n}$ with minimal $L^{2}(X, \mathfrak{n})$ norm (the so-called minimal 2-weak upper gradient) will be denoted by $|D f|_{w, \mathfrak{n}}$.

Remark 3.3 (Sobolev regularity along curves). A consequence of $\mathcal{S}_{\mathfrak{n}}^{2}$ regularity is (see Proposition 5.7 in [3) the Sobolev property along curves, namely for any 2 -test plan $\boldsymbol{\pi}$ relative to $\mathfrak{n}$ the function $t \mapsto f\left(\gamma_{t}\right)$ belongs to the Sobolev space $W^{1,1}(0,1)$ and

$$
\left|\frac{\mathrm{d}}{\mathrm{~d} t} f\left(\gamma_{t}\right)\right| \leq|D f|_{w}\left(\gamma_{t}\right)\left|\dot{\gamma}_{t}\right| \quad \text { a.e. in }(0,1)
$$

for $\boldsymbol{\pi}$-a.e. $\gamma$. Conversely, assume that $g$ is Borel nonnegative, that for any 2 -test plan $\boldsymbol{\pi}$ the map $t \mapsto f\left(\gamma_{t}\right)$ is $W^{1,1}(0,1)$ and that

$$
\left|\frac{\mathrm{d}}{\mathrm{~d} t} f\left(\gamma_{t}\right)\right| \leq g\left(\gamma_{t}\right)\left|\dot{\gamma}_{t}\right| \quad \text { a.e. in }(0,1)
$$

for $\boldsymbol{\pi}$-a.e. $\gamma$. Then, the fundamental theorem of calculus in $W^{1,1}(0,1)$ gives that $g$ is a 2 -weak upper gradient of $f$.

Because of the absolute continuity condition $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi} \ll \mathfrak{n}$ imposed on test plans, it is immediate to check that the property of being in $\mathcal{S}_{\mathfrak{n}}^{2}$, as well as $|D f|_{w, \mathfrak{n}}$, are invariant under modifications of $f$ in $\mathfrak{n}$-negligible sets. Furthermore, these concepts are easily seen to be local with respect to $\mathfrak{n}$ in the following sense: if $f \in \mathcal{S}_{\mathfrak{n}}^{2}$, then $f \in \mathcal{S}_{\mathfrak{n}^{\prime}}^{2}$ for all measures $\mathfrak{n}^{\prime}=\mathfrak{n}\left\llcorner B\right.$ with $B \subset X$ Borel, and $|D f|_{w, \mathfrak{n}^{\prime}} \leq|D f|_{w, \mathfrak{n}}$ $\mathfrak{n}^{\prime}$-a.e. on $B$ : this is due to the fact that test plans relative to $\mathfrak{n}^{\prime}$ are test plans relative to $\mathfrak{n}$. Conversely,

$$
\begin{equation*}
f \in \mathcal{S}_{\mathfrak{n}_{R}}^{2} \text { with } \mathfrak{n}_{R}:=\mathfrak{n}\left\llcorner\bar{B}_{R}\left(x_{0}\right), \sup _{R} \int_{X}|D f|_{w, \mathfrak{n}_{R}}^{2} \mathrm{~d} \mathfrak{n}_{R}<\infty \quad \Longrightarrow \quad f \in \mathcal{S}_{\mathfrak{n}}^{2}\right. \tag{3.2}
\end{equation*}
$$

This is due to the fact that any curve is bounded, hence any test plan $\boldsymbol{\pi}$ relative to $\mathfrak{n}$ can be monotonically approximated by test plans concentrated on curves contained in a bounded set.

Another property we shall need is the locality with respect to $f$; see [6] for the simple proof.
Proposition 3.4 (Locality). Let $f_{1}, f_{2}: X \rightarrow \mathbb{R}$ Borel and let $G_{1}, G_{2} \in L^{2}(X, \mathfrak{n})$ be 2 -weak upper gradients of $f_{1}, f_{2}$ relative to $\mathfrak{n}$ respectively. Then

$$
\tilde{G}_{1}:= \begin{cases}G_{1} & \text { on }\left\{f_{1} \neq f_{2}\right\}, \\ \min \left\{G_{1}, G_{2}\right\} & \text { on }\left\{f_{1}=f_{2}\right\}\end{cases}
$$

is a 2 -weak upper gradient of $f_{1}$. In particular, by minimality we get

$$
\begin{equation*}
\left|D f_{1}\right|_{w, \mathfrak{n}}=\left|D f_{2}\right|_{w, \mathfrak{n}} \quad \mathfrak{n} \text {-a.e. on }\left\{f_{1}=f_{2}\right\} . \tag{3.3}
\end{equation*}
$$

Weak gradients share with classical gradients many features, in particular the chain rule [3 Proposition 5.14]

$$
\begin{equation*}
|D \phi(f)|_{w, \mathfrak{n}}=\phi^{\prime}(f)|D f|_{w, \mathfrak{n}} \quad \mathfrak{n} \text {-a.e. in } X \tag{3.4}
\end{equation*}
$$

for all $\phi: \mathbb{R} \rightarrow \mathbb{R}$ Lipschitz and nondecreasing on an interval containing the image of $f$. By convention, as in the classical chain rule, $\phi^{\prime}(f)$ is arbitrarily defined at all points $x$ such that $\phi$ is not differentiable at $x$, taking into account the fact that $|D f|_{w, \mathfrak{n}}=0 \mathfrak{n}$-a.e. on this set of points.

In the sequel we shall adopt the conventions

$$
\begin{equation*}
|D f|_{w}:=|D f|_{w, \mathfrak{m}}, \quad \quad \mathcal{S}^{2}:=\mathcal{S}_{\mathfrak{m}}^{2} \tag{3.5}
\end{equation*}
$$

In Theorem 3.5 below we analyze in detail the behaviour of $|D f|_{w, \mathfrak{n}}$ and $\mathcal{S}_{\mathfrak{n}}^{2}$ under modifications of the reference measure $\mathfrak{n}$.

Theorem 3.5. The following properties hold:
(a) If $\mathfrak{n} \in \mathcal{M}$ and $\Gamma \subset \mathscr{C}(X)$ is $\operatorname{Mod}_{2, \mathfrak{n}}$-negligible, then any Borel set $\tilde{\Gamma} \subset$ $A C^{2}([0,1] ; X)$ such that $i(\tilde{\Gamma}) \subset \Gamma$ is $\pi$-negligible for any 2 -test plan $\boldsymbol{\pi}$ relative to $\mathfrak{n}$. In addition, for any Borel and $\mathfrak{n}$-negligible set $N \subset X$ the following holds:

$$
\operatorname{Mod}_{2, n}\left(\left\{\gamma \in \mathscr{C}(X): \int_{\gamma^{-1}(N)}|\dot{\gamma}| \mathrm{d} t>0\right\}\right)=0
$$

(b) If either $\mathfrak{n} \in \mathscr{P}(X)$ and $f \in \mathcal{S}_{\mathfrak{n}}^{2}$, or $\mathfrak{n} \in \mathcal{M}$ and $f \in \mathcal{S}_{\mathfrak{n}}^{2} \cap L^{1}(X, \mathfrak{n})$, there exist $\phi_{n} \in \operatorname{Lip}_{b}(X) \cap L^{2}(X, \mathfrak{n})$ satisfying $\phi_{n} \rightarrow f \mathfrak{n}$-a.e. in $X$ and $\left|D \phi_{n}\right| \rightarrow$ $|D f|_{w, \mathfrak{n}}$ in $L^{2}(X, \mathfrak{n})$.
(c) If either $\mathfrak{n} \in \mathscr{P}(X)$ and $f \in \mathcal{S}_{\mathfrak{n}}^{2}$, or $\mathfrak{n} \in \mathcal{M}$ and $f \in \mathcal{S}_{\mathfrak{n}}^{2} \cap L^{1}(X, \mathfrak{n})$, then there exists a Borel function $\tilde{f}$ coinciding with $f$ out of an $\mathfrak{n}$-negligible set and having an upper gradient in $L^{2}(X, \mathfrak{n})$; in addition, there exist upper gradients $G_{n}$ of $\tilde{f}$ converging to $|D f|_{w, \mathfrak{n}}$ in $L^{2}(X, \mathfrak{n})$.
Proof. (a) The first statement is a simple consequence of Hölder inequality; see [3, Remark 5.3]. The second one follows just by taking the function $g$ identically equal to $\infty$ on $N$ and null out of $N$ in (3.1).
(b) Using the chain rule (3.4) we reduce the proof to the case of nonnegative functions $f$. If $f$ belong to $L^{2}(X, \mathfrak{n})$ the existence of $\phi_{n}$ is one of the main results of [3]; see Theorem 6.2 therein. In the general case we approximate $f$ by the truncated functions $f_{N}=\min \{f, N\}$ and use the chain rule again to show $\left|D f_{N}\right|_{w, \mathfrak{n}} \rightarrow|D f|_{w, \mathfrak{n}}$ in $L^{2}(X, \mathfrak{n})$. Then, a diagonal argument provides the result.
(c) This is part of the theory developed by Koskela-MacManus in [23] and Shanmugalingam in [30: if $f_{n} \rightarrow f \mathfrak{n}$-a.e. and $G_{n}$ are upper gradients of $f_{n}$ weakly convergent to $G$ in $L^{2}(X, \mathfrak{n})$, then we can find a Borel function $\tilde{f}$ equal to $f \mathfrak{n}$-a.e. and a Borel function $\tilde{G}$ equal to $G \mathfrak{n}$-a.e. such that $\tilde{G}$ satisfies the upper gradient property relative to $\tilde{f}$ along $\operatorname{Mod}_{2, \mathfrak{n}}$-a.e. curve. In our case when $f \in \mathcal{S}_{\mathfrak{n}}^{2}$ we may apply statement (b) with $G=|D f|_{w, \mathfrak{n}}$ and choose $f_{n}=\phi_{n}$ to find $\tilde{f}$ and $\tilde{G}$. Then, denoting by $\Gamma$ the set of curves where the upper gradient property fails and considering

$$
G_{h}:=\tilde{G}+r_{h},
$$

where $r_{h} \in L^{2}(X, \mathfrak{n})$ satisfy $\int_{X} r_{h}^{2} \mathrm{~d} \mathfrak{n} \rightarrow 0$ and $\int_{\gamma} r_{\epsilon}=\infty$ for all $\gamma \in \Gamma$, we obtain upper gradients $G_{h}$ of $\tilde{f}$ approximating $|D f|_{w, \mathfrak{n}}$ in $L^{2}(X, \mathfrak{n})$.

Theorem 3.6 (Change of reference measure). Assume that $\rho=g \mathfrak{m} \in \mathscr{P}_{2}(X)$ with $g \in L^{\infty}(X, \mathfrak{m})$ and $|D \sqrt{g}|_{w} \in L^{2}(X, \mathfrak{m})$. Then:
(a) $f \in \mathcal{S}^{2}$ and $|D f|_{w} \in L^{2}(X, \rho)$ imply $f \in \mathcal{S}_{\rho}^{2}$ and $|D f|_{w, \rho}=|D f|_{w} \rho$-a.e. in $X$;
(b) $\log g \in \mathcal{S}_{\rho}^{2}$ and $|D \log g|_{w, \rho}=|D g|_{w} / g \rho$-a.e. in $X$.

Proof. (a) Thanks to the locality properties with respect to $\mathfrak{m}$ stated after Definition 3.2 (see in particular (3.2)) we can reduce ourselves to the case when $\mathfrak{m}(X)=1$. Since the statement is invariant under modification of $f$ and $g$ in $\mathfrak{m}$-negligible sets, by Theorem 3.5(b) we can assume that $\sqrt{g}$ and $f$ are absolutely continuous along $\operatorname{Mod}_{2, \mathfrak{m}}$-a.e. curve in $\mathscr{C}(X)$; even more, we can assume that $f$ has an upper gradient $H$ with $\int H^{2} \mathrm{dm}<\infty$.

Let us first prove the inequality $|D f|_{w, \rho} \leq|D f|_{w} \rho$-a.e. in $X$. By a truncation argument we can assume with no loss of generality that $f$ is bounded; under this assumption we can find bounded Lipschitz functions $\phi_{n}$ with $\left|D \phi_{n}\right| \rightarrow|D f|_{w}$ in $L^{2}(X, \mathfrak{m})$. Since $g$ is bounded it follows that $\left|D \phi_{n}\right| \rightarrow|D f|_{w}$ in $L^{2}(X, \rho)$; we can now use the stability properties of weak upper gradients [3, Theorem 5.12] to obtain that $|D f|_{w, \rho} \leq|D f|_{w} \rho$-a.e. in $X$.

In order to prove the converse inequality $|D f|_{w, \rho} \geq|D f|_{w} \rho$-a.e. in $X$, we consider a function $\tilde{f}$ coinciding with $f \rho$-a.e. in $X$ and an upper gradient $L$ of $\tilde{f}$ with $\int L^{2} \mathrm{~d} \rho<\infty$. The converse inequality follows by letting $L \rightarrow|D f|_{w, \rho}$ in $L^{2}(X, \rho)$ if we are able to show that

$$
L_{1}(x):= \begin{cases}H(x) & \text { if } g(x)=0 \\ \min \{H(x), L(x)\} & \text { if } g(x)>0\end{cases}
$$

is a 2 -weak upper gradient of $f$ relative to $\mathfrak{m}$. More precisely, we will prove that the upper gradient inequality with $L_{1}$ in the right hand side holds along $\operatorname{Mod}_{2, \mathfrak{m}}$-a.e. curve. We notice first that

$$
\left|\tilde{f}\left(\gamma_{\ell(\gamma)}\right)-\tilde{f}\left(\gamma_{0}\right)\right| \leq \int_{\gamma} L
$$

along $\operatorname{Mod}_{2, \mathfrak{m}}$-a.e. curve $\gamma$ satisfying $\inf _{\gamma} g>0$ (here we are using the invariance under reparameterization, selecting the arclength one, with $\ell(\gamma)$ equal to the length of $\gamma$ ). Indeed, by definition of 2 -modulus, the set

$$
\left\{\gamma \in \mathscr{C}(X): \inf _{\gamma} g>0, \int_{\gamma} L=\infty\right\}
$$

is not only $\operatorname{Mod}_{2, \rho}$-negligible, but also $\operatorname{Mod}_{2, \mathfrak{m}}$-negligible. If we write the upper gradient inequality in averaged form,

$$
\frac{1}{\epsilon \ell(\gamma)} \int_{0}^{\epsilon \ell(\gamma)}\left|\tilde{f}\left(\gamma_{\ell(\gamma)-r}\right)-\tilde{f}\left(\gamma_{r}\right)\right| \mathrm{d} r \leq \int_{\gamma} L \quad \text { with } \quad \epsilon<\frac{1}{2}
$$

and use Theorem 3.5(a) with the $\mathfrak{m}$-negligible set $N=\{f \neq \tilde{f}\} \cap\{g>0\}$, we may replace $\tilde{f}$ with $f$ in the previous inequality. Now we use the absolute continuity of $f$ along $\operatorname{Mod}_{2, \mathfrak{m}}$-a.e. curve and pass to the limit along a sequence $\epsilon_{k} \downarrow 0$ to get

$$
\left|f\left(\gamma_{b}\right)-f\left(\gamma_{a}\right)\right| \leq \int_{\gamma} L
$$

along $\operatorname{Mod}_{2, \mathfrak{m}}$-a.e. curve $\gamma:[a, b] \rightarrow X$ with $\inf _{\gamma} g>0$.

The set of curves $\gamma \in \mathscr{C}(X)$ containing a subcurve $\gamma^{\prime}:[a, b] \rightarrow X$ with $\inf _{\gamma^{\prime}} g>0$ and $\left|f\left(\gamma_{b}^{\prime}\right)-f\left(\gamma_{a}^{\prime}\right)\right|>\int_{\gamma^{\prime}} L$ is $\operatorname{Mod}_{2, \mathfrak{m}}$-negligible as well. If $\gamma$ does not belong to this set and $f \circ \gamma$ is absolutely continuous, it is immediate to check (recall that $g$ is continuous along $\operatorname{Mod}_{2, \mathfrak{m}}$-a.e. curve) that its derivative is bounded a.e. by $L_{1} \circ \gamma|\dot{\gamma}|$, whence the upper gradient inequality along $\gamma$ follows.
(b) We consider the functions $f_{\varepsilon}=\log (g+\varepsilon)$. Since $|D g|_{w}^{2} / g^{2} \in L^{1}(X, \rho)$ it is immediate to check that all functions $f_{\varepsilon}$ satisfy the assumption in (a), hence $f_{\varepsilon} \in \mathcal{S}_{\rho}^{2}$ and $\left|D f_{\varepsilon}\right|_{w, \rho}=\left|D f_{\varepsilon}\right|_{w}=|D g|_{w} /(g+\varepsilon) \rho$-a.e. in $X$. We can now pass to the limit as $\varepsilon \downarrow 0$ and again use the stability of weak upper gradients to get $|D f|_{w, \rho} \leq|D g|_{w} / g \rho$-a.e. in $X$. The converse inequality follows by the chain rule (3.4) with $\phi(s):=\log \left(\mathrm{e}^{s}+1\right)$ :

$$
\frac{|D g|_{w}}{g+1}=\left|D f_{1}\right|_{w, \rho}=\phi^{\prime}(f)|D f|_{w, \rho}=\frac{g}{g+1}|D f|_{w, \rho}
$$

Remark 3.7. Notice that for the validity of (a) it suffices, as the proof shows, the existence of a nonnegative function $\tilde{g}$ continuous along a $\operatorname{Mod}_{2, \mathfrak{m}}$-a.e. curve and satisfying $\mathfrak{m}(\{g \neq \tilde{g}\})=0$.

We shall define $\mathrm{Ch}: L^{1}(X, \mathfrak{m}) \rightarrow[0, \infty], \mathrm{Ch}_{\mathfrak{n}}: L^{1}(X, \mathfrak{n}) \rightarrow[0, \infty]$ by

$$
\begin{equation*}
\operatorname{Ch}(f):=\frac{1}{2} \int_{X}|D f|_{w}^{2} \mathrm{~d} \mathfrak{m}, \quad f \in \mathcal{S}^{2}, \quad \operatorname{Ch}_{\mathfrak{n}}(f):=\frac{1}{2} \int_{X}|D f|_{w, \mathfrak{n}}^{2} \mathrm{~d} \mathfrak{n}, \quad f \in \mathcal{S}_{\mathfrak{n}}^{2} \tag{3.6}
\end{equation*}
$$

with the conventions $\mathrm{Ch}(f)=\infty$ on $L^{1}(X, \mathfrak{m}) \backslash \delta^{2}, \mathrm{Ch}_{\mathfrak{n}}(f)=\infty$ on $L^{1}(X, \mathfrak{n}) \backslash \mathcal{S}_{\mathfrak{n}}^{2}$. We will choose $\mathfrak{n}$, as explained in the introduction, to be probability measures.

We shall also denote, whenever $\mathrm{Ch}\left(\mathrm{resp} . \mathrm{Ch}_{\mathfrak{n}}\right.$ ) is a quadratic form, by
$\mathcal{E}(f, g):=\frac{1}{2}(\mathrm{Ch}(f+g)-\mathrm{Ch}(f-g)) \quad\left(\right.$ resp. $\left.\mathcal{E}_{\mathfrak{n}}(f, g):=\frac{1}{2}\left(\mathrm{Ch}_{\mathfrak{n}}(f+g)-\mathrm{Ch}_{\mathfrak{n}}(f-g)\right)\right)$
the associated symmetric bilinear form, defined on $\mathcal{S}^{2} \cap L^{1}(X, \mathfrak{m})$ (resp. $\mathcal{S}_{\mathfrak{n}}^{2} \cap$ $\left.L^{1}(X, \mathfrak{n})\right)$.

Still under the assumption that Ch is quadratic, as in [4, Definition 4.13] (see also Gigli's work [17] for a more general, non-quadratic framework), we can define

$$
\begin{equation*}
G(f, g):=\lim _{\varepsilon \ngtr 0} \frac{|D(f+\varepsilon g)|_{w}^{2}-|D f|_{w}^{2}}{2 \varepsilon}, \quad f, g \in \mathcal{S}^{2} \tag{3.8}
\end{equation*}
$$

where the limit takes place in $L^{1}(X, \mathfrak{m})$. Notice that $G(f, f)=|D f|_{w}^{2} \mathfrak{m}$-a.e. and that $G(\cdot, \cdot)$ provides integral representation to $\mathcal{E}$, namely

$$
\mathcal{E}(f, g)=\int_{X} G(f, g) \mathrm{d} \mathfrak{m}
$$

The inequality $|D(f+\varepsilon g)|_{w}^{2} \leq\left(|D f|_{w}+\varepsilon|D g|_{w}\right)^{2}=|D f|_{w}^{2}+2 \varepsilon|D f|_{w}|D g|_{w}+$ $\varepsilon^{2}|D g|_{w}^{2}$ provides the bound

$$
\begin{equation*}
|G(f, g)| \leq|D f|_{w}|D g|_{w} \quad \text { m-a.e. in } X . \tag{3.9}
\end{equation*}
$$

Also, locality of weak gradients gives

$$
\begin{equation*}
G(f, g)=G\left(f, g^{\prime}\right) \quad \text { m-a.e. on }\left\{g=g^{\prime}\right\} . \tag{3.10}
\end{equation*}
$$

We will need a chain rule with respect to the second argument (see [4, Lemma 4.7] for the simple proof):

$$
\begin{equation*}
\int_{X} G(f, \phi(g)) \mathrm{d} \mathfrak{m}=\int_{X} \phi^{\prime}(g) G(f, g) d \mathfrak{m} \tag{3.11}
\end{equation*}
$$

for all $\phi: \mathbb{R} \rightarrow \mathbb{R}$ nondecreasing and Lipschitz on an interval containing the image of $g$, with the same convention on the value of $\phi^{\prime}(g)$ mentioned in (3.4). Finally, we will need the following lemma, whose proof is more delicate: it relies on the chain rule for $G(\cdot, \cdot)$ also with respect to the first factor and on the Leibniz rule with respect to the second factor (see [4] for finite measures and [17, Proposition 4.20] for the general case).

Lemma 3.8. If Ch is quadratic, then $G(\cdot, \cdot)$ is a symmetric bilinear form. In particular $\int|D f|_{w}^{2} g \mathrm{dm}=\int G(f, f) g \mathrm{dm}$ is a quadratic form for any nonnegative $g \in L^{\infty}(X, \mathfrak{m})$.

Theorem 3.9 (Weighted Cheeger energy). Assume that $\rho=g \mathfrak{m} \in \mathscr{P}_{2}(X)$ with $g \in L^{\infty}(X, \mathfrak{m})$ and $\operatorname{Ch}(\sqrt{g})<\infty$. If Ch is a quadratic form, then $\mathrm{Ch}_{\rho}$ is a quadratic form and

$$
\begin{equation*}
\mathcal{E}_{\rho}(\log g, \varphi)=\mathcal{E}(g, \varphi) \quad \text { for all } \varphi: X \rightarrow \mathbb{R} \text { Lipschitz with bounded support. } \tag{3.12}
\end{equation*}
$$

Proof. By Theorem 3.6(a) and Lemma 3.8, $\mathrm{Ch}_{\rho}$ is a quadratic form on bounded Lipschitz functions with bounded support. By approximation $\mathrm{Ch}_{\rho}$ is a quadratic form on bounded Lipschitz functions and eventually, taking Theorem 3.5(b) into account, on $L^{2}(X, \rho)$.

Let $f_{\varepsilon}=\log (g+\varepsilon) \in \mathcal{S}^{2}$. Then, again using the independence of weak gradients upon the reference measure given by Theorem [3.6(a) and (3.11), we get

$$
\begin{aligned}
\mathcal{E}_{\rho}\left(\varphi, f_{\varepsilon}\right) & =\lim _{\delta \downarrow 0} \frac{\operatorname{Ch}_{\rho}\left(\varphi+\delta f_{\varepsilon}\right)-\mathrm{Ch}_{\rho}(\varphi)}{\delta}=\lim _{\delta \downarrow 0} \int_{X} \frac{\left|D\left(\varphi+\delta f_{\varepsilon}\right)\right|_{w}^{2}-|D \varphi|_{w}^{2}}{2 \delta} \mathrm{~d} \rho \\
& =\int_{X} G\left(\varphi, f_{\varepsilon}\right) \mathrm{d} \rho=\int_{X} G(\varphi, g) \frac{g}{g+\varepsilon} \mathrm{dm} .
\end{aligned}
$$

Passing to the limit as $\varepsilon \downarrow 0$ provides the result, since convergence of the right hand sides is obvious, while convergence of the left hand sides can be obtained by working in the vector space $H:=L^{2}\left(X, \rho^{\prime}\right) \cap \mathcal{S}_{\rho}^{2}$ endowed with the scalar product

$$
\left\langle h, h^{\prime}\right\rangle:=\int_{X} h h^{\prime} \mathrm{d} \rho^{\prime}+\mathcal{E}_{\rho}\left(h, h^{\prime}\right) \quad \text { with } \quad \rho^{\prime}:=\frac{1}{1+\log ^{2} g} \rho .
$$

This is indeed a Hilbert space because $\mathrm{Ch}_{\rho}$ is easily seen to be lower semicontinuous (since a truncation argument allows the reduction to sequences uniformly bounded in $\left.L^{\infty}(X, \rho)\right)$ also w.r.t. $L^{2}\left(X, \rho^{\prime}\right)$ convergence; moreover, clearly $f_{\varepsilon} \rightarrow f$ in $L^{2}(X, \tilde{\rho})$, and since their norms are uniformly bounded we have weak convergence in $H$. Finally $g \mapsto \mathcal{E}_{\rho}(\varphi, g)$ is continuous in $H$.

## 4. Existence of good geodesics

This section is devoted to the proof of the existence of geodesics in $\left(\mathscr{P}_{2}(X), W_{2}\right)$ which are (at least for some initial time interval) better than the ones given directly by the usual $C D(K, \infty)$ inequality given by Lott and Villani [25] and Sturm [32.

Definition 4.1. We say that $(X, \mathrm{~d}, \mathfrak{m})$ is a $C D(K, \infty)$ space if for all $\mu_{0}, \mu_{1} \in$ $D\left(\operatorname{Ent}_{\mathfrak{m}}\right)($ recall (2.2) $)$ there exists a geodesic $\left(\mu_{t}\right) \in \operatorname{Geo}\left(\mathscr{P}_{2}(X)\right)$ which satisfies the convexity inequality

$$
\begin{equation*}
\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right) \leq(1-t) \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{0}\right)+t \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{1}\right)-\frac{K}{2} t(1-t) W_{2}^{2}\left(\mu_{0}, \mu_{1}\right) \quad \forall t \in[0,1] \tag{4.1}
\end{equation*}
$$

The idea of constructing good geodesics in $C D(K, N)$ spaces was recently used by Rajala in [28] to study $C D(K, N)$ spaces with branching geodesics. There the initial motivation was to obtain geodesics good enough so that the approach of [29] for proving local Poincaré inequalities could be adapted to these spaces. Constructing geodesics by selecting midpoints is a standard approach; see for example Gromov's proof that the GH limit of length spaces is a length space [20, Proposition 3.8].

Here we modify some of Rajala's results in [28] and [27] to the setting of this paper, repeating with some detail the arguments because on some occasions the adaptation is not trivial. The version of these results which we will need in the later sections is the following.

Theorem 4.2. Let $(X, \mathrm{~d}, \mathfrak{m})$ be a $C D(K, \infty)$ space and let $\mu_{0}=\rho_{0} \mathfrak{m}, \mu_{1}=\rho_{1} \mathfrak{m} \in$ $D\left(\mathrm{Ent}_{\mathfrak{m}}\right)$. Assume in addition that $\mu_{1}$ has bounded support and density and that the density $\rho_{0}$ satisfies the growth-bound

$$
\begin{equation*}
\rho_{0}(x) \leq c_{1} \mathrm{e}^{-c_{2} \mathrm{~d}^{2}\left(x, x_{0}\right)} \quad \forall x \in X \tag{4.2}
\end{equation*}
$$

for some $c_{1}, c_{2}>0$ and $x_{0} \in X$.
Then there exist $t_{0} \in(0,1)$ and a geodesic $\left(\mu_{t}\right) \in \operatorname{Geo}\left(\mathscr{P}_{2}(X)\right)$ between $\mu_{0}, \mu_{1}$ satisfying the convexity inequality (4.1) for all $t \in[0,1]$ and the density bound

$$
\begin{equation*}
\sup _{t \in\left[0, t_{0}\right]}\left\|\rho_{t}\right\|_{L^{\infty}(X, \mathfrak{m})}<\infty \tag{4.3}
\end{equation*}
$$

In 4.1 we discuss the convexity of the entropy along intermediate measures formed by using an inductive process and prove existence of entropy minimizers. In 44.2 we review some results of Rajala in [27] in $C D^{*}(K, N)$ spaces. In $\$ 4.3$ we prove that the minimizers satisfy density bounds by adapting Rajala's result in [28. Finally, in 84.4 we prove Theorem 4.2 using these ingredients.
4.1. Intermediate measures and the existence of minimizers. The measures with minimal entropy will be selected from the set of all intermediate measures. Recall that for any two measures $\mu_{0}, \mu_{1} \in \mathscr{P}_{2}(X)$ the set of all intermediate points (with a parameter $t \in(0,1)$ ) will be denoted by

$$
\begin{aligned}
\mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)=\left\{\nu \in \mathscr{P}_{2}(X): W_{2}\left(\mu_{0}, \nu\right)=\right. & t W_{2}\left(\mu_{0}, \mu_{1}\right) \\
& \left.\quad \text { and } W_{2}\left(\mu_{1}, \nu\right)=(1-t) W_{2}\left(\mu_{0}, \mu_{1}\right)\right\} .
\end{aligned}
$$

It is not difficult to show that the set of $t$-intermediate points is a convex and closed subset of $\mathscr{P}_{2}(X)$,

Even though the selection process is countable, it will define the whole geodesic by completion. To get the convexity inequality (4.1) for all times we will then need the lower semicontinuity of the entropy w.r.t. $W_{2}$-convergence (a direct consequence of (2.5) and of the weak lower semicontinuity of $E^{n} t_{\mathfrak{n}}$ in $\mathscr{P}(X)$ when $\left.\mathfrak{n} \in \mathscr{P}(X)\right)$ and tightness estimates. Let us now indicate how the first property of the good geodesics follows easily if we define the geodesic by taking any intermediate point where (4.1) is satisfied.

Proposition 4.3. Let $\mu_{0}, \mu_{1} \in \mathscr{P}_{2}(X)$. Suppose that we have selected inductively at step $(n+1)$ measures $\mu_{t} \in \mathcal{J}_{\frac{t-s}{r-s}}\left(\mu_{s}, \mu_{r}\right)$ satisfying

$$
\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right) \leq \frac{(r-t)}{(r-s)} \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{s}\right)+\frac{(t-s)}{(r-s)} \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{r}\right)-\frac{K}{2} \frac{(t-s)}{(r-s)} \frac{(r-t)}{(r-s)} W_{2}^{2}\left(\mu_{s}, \mu_{r}\right)
$$

where $s<t<r$ and the times $s$ and $r$ are two consecutive timepoints in the set of times where the measures have already been selected at step $n$.

Then (4.1) holds for all $\mu_{t}$ chosen at the $(n+1)$-th step. In particular, if the closure of the selected times is the whole interval $[0,1]$, defining $\mu_{t}$ by completion, we have a geodesic between $\mu_{0}$ and $\mu_{1}$ along which (4.1) holds.

Proof. Suppose that we have selected a measure $\mu_{t} \in \mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$ satisfying

$$
\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right) \leq(1-t) \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{0}\right)+t \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{1}\right)-\frac{K}{2} t(1-t) W_{2}^{2}\left(\mu_{0}, \mu_{1}\right)
$$

and after it a measure $\mu_{t s} \in \mathcal{J}_{s}\left(\mu_{0}, \mu_{t}\right)$ satisfying

$$
\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t s}\right) \leq(1-s) \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{0}\right)+s \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right)-\frac{K}{2} s(1-s) W_{2}^{2}\left(\mu_{0}, \mu_{t}\right)
$$

Then for the measure $\mu_{t s}$ we also have $\mu_{t s} \in \mathcal{J}_{t s}\left(\mu_{0}, \mu_{1}\right)$ and

$$
\begin{aligned}
& \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t s}\right) \leq(1-s) \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{0}\right)+s \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right)-\frac{K}{2} s(1-s) W_{2}^{2}\left(\mu_{0}, \mu_{t}\right) \\
& \leq(1-s) \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{0}\right)+s\left((1-t) \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{0}\right)+t \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{1}\right)-\frac{K}{2} t(1-t) W_{2}^{2}\left(\mu_{0}, \mu_{1}\right)\right) \\
& \quad-\frac{K}{2} s(1-s) W_{2}^{2}\left(\mu_{0}, \mu_{t}\right) \\
&=((1-s)+s(1-t)) \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{0}\right)+t s \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{1}\right) \\
&-\frac{K}{2}\left(t s(1-t)+t^{2} s(1-s)\right) W_{2}^{2}\left(\mu_{0}, \mu_{1}\right) \\
&=(1-t s) \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{0}\right)+t s \operatorname{Ent}_{\mathfrak{m}}\left(\mu_{1}\right)-\frac{K}{2} t s(1-t s) W_{2}^{2}\left(\mu_{0}, \mu_{1}\right) .
\end{aligned}
$$

Therefore the claim holds for all the points $t_{i}$. By the lower semicontinuity of the entropy it then also holds for the closure.

Now that we know from Proposition 4.3 that the first property of the geodesic in Theorem 4.2 is easily satisfied, we turn to the more difficult part of obtaining the density bound (4.3). To do this we will not only select intermediate measures that satisfy (4.1), but measures where the entropy is minimal. The obvious first step is then to prove that there indeed exist such minimizers. In general the set $\mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$, though closed, is not compact in $\left(\mathscr{P}_{2}(X), W_{2}\right)$. However, when we consider a subset of $\mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$ with the entropy bounded from above, we have compactness. In particular, we therefore have the existence of minimizers.

Lemma 4.4. Let $\mu_{0}, \mu_{1} \in \mathscr{P}_{2}(X)$. Then for all $t \in[0,1]$ there exists a minimizer of the entropy in $\mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$.

Proof. Without loss of generality we can assume the existence of $\nu \in \mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$ with $\operatorname{Ent}_{\mathfrak{m}}(\nu)<\infty$. We know that the entropy is lower semicontinuous and that $\mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$ is closed. The claim then follows if we are able to show that the set

$$
\mathcal{K}=\left\{\mu \in \mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right): \operatorname{Ent}_{\mathfrak{m}}(\mu) \leq \operatorname{Ent}_{\mathfrak{m}}(\nu)\right\} \subset \mathscr{P}_{2}(X)
$$

is relatively compact in $\left(\mathscr{P}_{2}(X), W_{2}\right)$. It suffices to prove that the set $\mathcal{K}$ is uniformly 2-integrable and tight; see [2, Proposition 7.15]. Let us first prove the uniform 2integrability of the set $\mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$. This follows from the fact that for any $\mu \in$ $\mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$ we have

$$
\int_{X \backslash \bar{B}\left(x_{0}, k\right)} \mathrm{d}^{2}\left(x_{0}, x\right) \mathrm{d} \mu \leq \int_{X \backslash \bar{B}\left(x_{0}, k / 2\right)} 4 \mathrm{~d}^{2}\left(x_{0}, x\right) \mathrm{d}\left(\mu_{0}+\mu_{1}\right) \rightarrow 0, \quad \text { as } k \rightarrow \infty
$$

since $\mu_{0}, \mu_{1} \in \mathscr{P}_{2}(X)$.
Let us next prove that $\mathcal{K}$ is tight. If $\tilde{\mathfrak{m}} \in \mathscr{P}(X)$ is defined as in (2.4), (2.5) shows that $\sup _{\mu \in \mathcal{K}} \operatorname{Ent}_{\tilde{\mathfrak{m}}}(\mu)$ is finite. Then, tightness of $\mathcal{K}$ is a simple consequence of the equi-integrability of the densities w.r.t. $\tilde{\mathfrak{m}}$.

As a technical tool we will need the excess mass functional $\mathcal{F}_{C}: \mathscr{P}_{2}(X) \rightarrow[0,1]$ which is defined for all thresholds $C \geq 0$ as

$$
\begin{equation*}
\mathcal{F}_{C}(\mu)=\left\|(\rho-C)^{+}\right\|_{L^{1}(X, \mathfrak{m})}+\mu^{s}(X) \tag{4.4}
\end{equation*}
$$

where $\mu=\rho \mathfrak{m}+\mu^{s}$ with $\mu^{s} \perp \mathfrak{m}$. This functional, lower semicontinuous under weak convergence, was used in [28] to obtain the first good geodesics in $C D(K, N)$ spaces. The motivation for using the excess mass functional is that its variations under perturbation of the minimizer are easier to estimate, since one only cares about the amount of mass exceeding the threshold.
4.2. Localization in transport distance. As we will later see, the task of finding the first good intermediate measure between $\mu_{0}$ and $\mu_{1}$ is slightly more difficult than finding the rest of the geodesic. This is due to the fact that after some $\mu_{t}$ with $t \in(0,1)$ has been fixed we can consider the transport distances to be essentially constant. This useful observation was made by Rajala in [27. It follows from two simple statements. First when one fixes an intermediate measure, the length of the curves along which the transport is done gets fixed. This is the content of the next proposition which was proved in [27, Proposition 1].
Proposition 4.5. Let $\mu_{0}, \mu_{1} \in \mathscr{P}_{2}(X)$ and $t_{0} \in(0,1)$. Suppose that there exist constants $0 \leq C_{1} \leq C_{2}<\infty$ and a measure $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$ with

$$
\begin{equation*}
C_{1} \leq l(\gamma) \leq C_{2} \quad \text { for } \boldsymbol{\pi} \text {-a.e. } \gamma \in \operatorname{Geo}(X) \tag{4.5}
\end{equation*}
$$

Then the bounds in (4.5) hold $\tilde{\boldsymbol{\pi}}$-a.e. for any $\tilde{\boldsymbol{\pi}} \in \operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$ with $\left(\mathrm{e}_{t_{0}}\right) \sharp \tilde{\boldsymbol{\pi}}=$ $\left(\mathrm{e}_{\boldsymbol{t}_{0}}\right)_{\sharp} \boldsymbol{\pi}$.

In order to use the previous proposition we will need another observation which is a simple consequence of cyclical monotonicity (cf. Chapter 5 in Villani's survey [34] for a review of cyclical monotonicity). Namely, when we work on a part of the transport with some bounds on the lengths of the curves, this part will not get mixed with other parts of the measure at any intermediate time. For the proof of this fact see [27, Lemma 2.5].
Lemma 4.6. Take $0 \leq C_{1} \leq C_{2} \leq C_{3} \leq C_{4} \leq \infty$ and define
$A_{1}=\left\{\gamma \in \operatorname{Geo}(X): C_{1} \leq l(\gamma) \leq C_{2}\right\} \quad$ and $\quad A_{2}=\left\{\gamma \in \operatorname{Geo}(X): C_{3}<l(\gamma) \leq C_{4}\right\}$.
Then for any $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$ and any $t \in(0,1)$ there exists a Borel set $E \subset$ $\operatorname{Geo}(X)$ with $\boldsymbol{\pi}(E)=0$ such that

$$
\left\{(\gamma, \hat{\gamma}) \in\left(A_{1} \backslash E\right) \times\left(A_{2} \backslash E\right): \gamma_{t}=\hat{\gamma}_{t}\right\}=\emptyset
$$

4.3. Density bounds for the minimizers. The information from the minimizers of the entropy and of the excess mass functional are obtained with a contradiction argument. First we assume that there exists a minimizer which does not have the desired density bound. After this we isolate the part of the minimizer where the density bound is exceeded and redefine this part of the measure to be something slightly better. If this new measure is again an intermediate point and we have strictly decreased the energy we are minimizing (the entropy or the excess mass), we obtain a contradiction, so the minimizer must satisfy the density bound. To prove that we indeed get an intermediate point we use the next lemma, whose proof relies on the joint convexity of $(\mu, \nu) \mapsto W_{2}^{2}(\mu, \nu)$, which was again proved by Rajala in [28, Lemma 3.5].
Lemma 4.7. Let $\mu_{0}, \mu_{1} \in \mathscr{P}_{2}(X)$. Then for any $\lambda \in(0,1)$, any $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$, any Borel function $f: \operatorname{Geo}(X) \rightarrow[0,1]$ with $c=(f \boldsymbol{\pi})(\operatorname{Geo}(X)) \in(0,1)$ and any

$$
\nu \in \mathcal{J}_{\lambda}\left(\frac{1}{c}\left(\mathrm{e}_{0}\right)_{\sharp}(f \boldsymbol{\pi}), \frac{1}{c}\left(\mathrm{e}_{1}\right)_{\sharp}(f \boldsymbol{\pi})\right)
$$

we have

$$
\left(\mathrm{e}_{\lambda}\right)_{\sharp}((1-f) \boldsymbol{\pi})+c \nu \in \mathcal{J}_{\lambda}\left(\mu_{0}, \mu_{1}\right) .
$$

The first step which uses the minimization of the excess mass functional $\mathcal{F}_{C}$ in (4.4) is the same one that was taken in [28, Proposition 3.11]. We repeat some key points of the proof for the convenience of the reader. In [28] the functionals $\mathcal{F}_{C}$ were minimized only in the bounded case. A reduction to this case can also be made here, and so the following proposition which was proved in a slightly different form in [28, Proposition 3.9 and Proposition 3.11] will suffice.

Proposition 4.8. Assume that ( $X, \mathrm{~d}$ ) is a bounded metric space with a finite measure $\mathfrak{m}$. Let $\nu_{0}, \nu_{1} \in \mathscr{P}_{2}(X)$ and $t \in[0,1]$. Suppose that there exists a constant $C>0$ so that for any $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\nu_{0}, \nu_{1}\right)$ and $A \subset X$ Borel with $\boldsymbol{\pi}\left(\mathrm{e}_{t}^{-1}(A)\right)>0$ we have that for the measures

$$
\begin{equation*}
\hat{\nu}_{0}=\frac{1}{\boldsymbol{\pi}\left(\mathrm{e}_{t}^{-1}(A)\right)}\left(\mathrm{e}_{0}\right)_{\sharp}\left(\boldsymbol{\pi}\left\llcorner\mathrm{e}_{t}^{-1}(A)\right), \quad \hat{\nu}_{1}=\frac{1}{\boldsymbol{\pi}\left(\mathrm{e}_{t}^{-1}(A)\right)}\left(\mathrm{e}_{1}\right)_{\sharp}\left(\boldsymbol{\pi}\left\llcorner\mathrm{e}_{t}^{-1}(A)\right)\right.\right. \tag{4.6}
\end{equation*}
$$

there exists a measure $\hat{\nu} \in \mathcal{J}_{t}\left(\hat{\nu}_{0}, \hat{\nu}_{1}\right)$ with

$$
\begin{equation*}
\operatorname{Ent}_{\mathfrak{m}}(\hat{\nu}) \leq \log \frac{C}{\pi\left(\mathrm{e}_{t}^{-1}(A)\right)} \tag{4.7}
\end{equation*}
$$

Then there exists a minimizer $\mu_{t}$ of $\mathcal{F}_{C}$ in $\mathcal{J}_{t}\left(\nu_{0}, \nu_{1}\right)$ and the minimum value is zero, so that $\mu_{t} \ll \mathfrak{m}$ and its density is less than $C \mathfrak{m}$-a.e. in $X$.

Proof. Take a threshold $C^{\prime}>C$. It suffices to prove that the minimum of $\mathcal{F}_{C^{\prime}}$ in $\mathcal{J}_{t}\left(\nu_{0}, \nu_{1}\right)$ is zero and then let $C^{\prime} \downarrow C$. Without loss of generality we may assume that all minimizers, whose existence is ensured by tightness of $\mathcal{J}_{t}\left(\nu_{0}, \nu_{1}\right)$ in $\mathscr{P}(X)$ and lower semicontinuity, are absolutely continuous with respect to $\mathfrak{m}$. Indeed, suppose that there is a measure $\omega \in \mathcal{J}_{t}\left(\nu_{0}, \nu_{1}\right)$ with a singular part. Let $A$ be an $\mathfrak{m}$-negligible Borel set where the singular part of $\omega$ is concentrated. By the assumption of the proposition together with Lemma 4.7 we can then redefine the part of $\omega$ which is supported on $A$ to be a measure having finite entropy. In particular it will be absolutely continuous with respect to $\mathfrak{m}$. Since we are redefining only the singular part of $\omega$, the value of the functional $\mathcal{F}_{C^{\prime}}$ does not increase after the redefinition.

Assume, contrary to the claim, that the infimum of $\mathcal{F}_{C^{\prime}}$ in $\mathcal{J}_{t}\left(\nu_{0}, \nu_{1}\right)$ is positive. Denote by $\mathcal{M}_{\text {min }} \subset \mathcal{J}_{t}\left(\nu_{0}, \nu_{1}\right)$ the set of minimizers of $\mathcal{F}_{C^{\prime}}$ in $\mathcal{J}_{t}\left(\nu_{0}, \nu_{1}\right)$. Applying the proof of [28, Proposition 3.9] we see that the set $\mathcal{M}_{\text {min }}$ is always nonempty. Take $\nu \in \mathcal{M}_{\text {min }}$ for which

$$
\begin{equation*}
\mathfrak{m}\left(\left\{x \in X: \rho_{\nu}(x)>C^{\prime}\right\}\right) \geq\left(\frac{C}{C^{\prime}}\right)^{\frac{1}{4}} \sup _{\omega \in \mathcal{M}_{\min }} \mathfrak{m}\left(\left\{x \in X: \rho_{\omega}(x)>C^{\prime}\right\}\right), \tag{4.8}
\end{equation*}
$$

where $\nu=\rho_{\nu} \mathfrak{m}$ and $\omega=\rho_{\omega} \mathfrak{m}$. Let $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\nu_{0}, \nu_{1}\right)$ be such that $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi}=\nu$.
There exists $\delta>0$ so that

$$
\mathfrak{m}(A)>\left(\frac{C}{C^{\prime}}\right)^{\frac{1}{2}} \mathfrak{m}\left(A^{\prime}\right)
$$

with

$$
\begin{equation*}
A^{\prime}=\left\{x \in X: \rho_{\nu}(x)>C^{\prime}\right\} \quad \text { and } \quad A=\left\{x \in A^{\prime}: \rho_{\nu}(x)>C^{\prime}+\delta\right\} . \tag{4.9}
\end{equation*}
$$

From the assumption of the proposition we know the existence of a measure $\hat{\nu}=\hat{\rho} \mathfrak{m} \in \mathcal{J}_{t}\left(\hat{\nu}_{0}, \hat{\nu}_{1}\right)$ with $\operatorname{Ent}_{\mathfrak{m}}(\hat{\nu}) \leq \log (C / \nu(A))$, where $\hat{\nu}_{0}$ and $\hat{\nu}_{1}$ are given by (4.6). By Jensen's inequality we then have

$$
\begin{equation*}
\mathfrak{m}(\{\hat{\rho}>0\}) \geq \frac{\nu(A)}{C} \geq \frac{C^{\prime}}{C} \mathfrak{m}(A) \geq\left(\frac{C^{\prime}}{C}\right)^{\frac{1}{2}} \mathfrak{m}\left(A^{\prime}\right) \tag{4.10}
\end{equation*}
$$

We can now consider a new measure $\tilde{\nu}=\tilde{\rho} \mathfrak{m}$ defined as the combination

$$
\begin{equation*}
\tilde{\nu}=\nu\left\llcorner(X \backslash A)+\frac{C^{\prime}}{C^{\prime}+\delta} \nu\left\llcorner A+\frac{\delta}{C^{\prime}+\delta} \nu(A) \hat{\nu} .\right.\right. \tag{4.11}
\end{equation*}
$$

By Lemma 4.7 and the convexity of $\mathcal{J}_{t}$ we have $\tilde{\nu} \in \mathcal{J}_{t}\left(\nu_{0}, \nu_{1}\right)$. Due to the definition of (4.9) we only redistribute some of the mass above the density $C^{\prime}$ when we replace the measure $\nu$ by the measure $\tilde{\nu}$, so that $\tilde{\nu} \in \mathcal{M}_{\text {min }}$. Let us calculate how much the excess mass functional changes in this replacement:

$$
\mathcal{F}_{C^{\prime}}(\nu)-\mathcal{F}_{C^{\prime}}(\tilde{\nu})=\int_{\left\{\rho_{\nu}<C^{\prime}\right\}} \min \left\{C^{\prime}-\rho_{\nu}, \frac{\delta}{C^{\prime}+\delta} \nu(A) \hat{\rho}\right\} \mathrm{d} \mathfrak{m} .
$$

Because of the minimality of $\mathcal{F}_{C^{\prime}}$ at $\nu$ this integral must be zero. Therefore $\{\hat{\rho}>$ $0\} \cap\left\{\rho_{\nu}<C^{\prime}\right\}$ is $\mathfrak{m}$-negligible. On the other hand, for any $y \in\{\hat{\rho}>0\} \cap\left\{\rho_{\nu} \geq C^{\prime}\right\}$ we have $\tilde{\rho}(y)>C^{\prime}$ (if $y \in X \backslash A$ this is trivial, if $y \in A$ the second term in (4.11) gives a contribution larger than $C^{\prime}$ ). This, together with our choice (4.8) of $\nu$, leads to a contradiction:

$$
\mathfrak{m}\left(\left\{\tilde{\rho}>C^{\prime}\right\}\right) \geq \mathfrak{m}(\{\hat{\rho}>0\}) \geq\left(\frac{C^{\prime}}{C}\right)^{\frac{1}{2}} \mathfrak{m}\left(A^{\prime}\right) \geq\left(\frac{C^{\prime}}{C}\right)^{\frac{1}{4}} \sup _{\omega \in \mathcal{M}_{\min }} \mathfrak{m}\left(\left\{\rho_{\omega}>C^{\prime}\right\}\right)
$$

Next we make another minimization. This time for the entropy itself. A similar argument was used in [27] to obtain good geodesics in metric spaces satisfying the reduced curvature dimension condition $C D^{*}(K, N)$.

Proposition 4.9. Let $\mu_{0}, \mu_{1} \in \mathscr{P}_{2}(X)$ and $t \in[0,1]$. Suppose that there exists a constant $C>0$ so that for any $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$ and $A \subset X$ Borel with $\boldsymbol{\pi}\left(\mathrm{e}_{t}^{-1}(A)\right)>0$ we have that for the restricted measures $\hat{\nu}_{0}, \hat{\nu}_{1}$ in (4.6) there exists a measure $\hat{\nu} \in \mathcal{J}_{t}\left(\hat{\mu}_{0}, \hat{\mu}_{1}\right)$ satisfying (4.7). Then for any minimizer $\mu_{\min }$ of the entropy in $\mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$ we have $\mu_{\text {min }} \leq C \mathfrak{m}$.

Proof. Without loss of generality, we can assume $t \in(0,1)$. Let $\nu=\rho \mathfrak{m}$ be one of the minimizers of the entropy in $\mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$, which by Lemma 4.4 we know to exist. By (4.7) with $A=X$ we know that $\operatorname{Ent}_{\mathfrak{m}}(\nu)<\infty$. We need only show that $\mathcal{F}_{C}(\nu)=0$.

Let $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$ be such that $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi}=\nu$. Suppose now by contradiction that $\mathcal{F}_{C}(\nu)>0$, let $\eta>0$ be such that $\mathfrak{m}(\{\rho>C+2 \eta\})>0$ and define

$$
C_{1}=\frac{1}{\eta}[\mathfrak{m}(\{\rho>C+\eta\})-\mathfrak{m}(\{\rho>C+2 \eta\})] \geq 0
$$

Since $\tau \mapsto g(\tau):=\mathfrak{m}(\{\rho \geq C+\tau\})$ is nonincreasing, there exists $\delta \in(\eta, 2 \eta)$ such that $-g^{\prime}(\delta) \leq C_{1}$. In particular, choosing $\delta$ in this way and fixing $x_{0} \in X$, for $\phi \in(0, \eta / 3)$ sufficiently small and $R=R(\phi)$ sufficiently large, one has $\mathfrak{m}\left(L^{\prime}\right)<$ $\mathfrak{m}(L)+\left(1+C_{1}\right) \phi$, where
$L=\left\{x \in B\left(x_{0}, R\right): \rho(x)>C+\delta\right\} \quad$ and $\quad L^{\prime}=\{x \in X: \rho(x) \geq C+\delta-3 \phi\}$.
Let $\Gamma \subset \mathrm{Geo}(X)$ be a cyclically monotone set on which $\boldsymbol{\pi}$ is supported. Fix $\bar{\gamma} \in \Gamma \cap \mathrm{e}_{t}^{-1}(L)$ and consider any $\gamma \in \Gamma \cap \mathrm{e}_{t}^{-1}(L)$. Using cyclical monotonicity we get (similarly as in [34, Theorem 8.22])

$$
\begin{aligned}
\mathrm{d}^{2}\left(\gamma_{0}, \gamma_{1}\right) \leq & \mathrm{d}^{2}\left(\bar{\gamma}_{0}, \bar{\gamma}_{1}\right)+\mathrm{d}^{2}\left(\gamma_{0}, \gamma_{1}\right) \leq \mathrm{d}^{2}\left(\bar{\gamma}_{0}, \gamma_{1}\right)+\mathrm{d}^{2}\left(\gamma_{0}, \bar{\gamma}_{1}\right) \\
\leq & \left(\mathrm{d}\left(\gamma_{t}, \gamma_{1}\right)+\operatorname{diam}(L)+l(\bar{\gamma})\right)^{2}+\left(\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)+\operatorname{diam}(L)+l(\bar{\gamma})\right)^{2} \\
= & \left((1-t)^{2}+t^{2}\right) \mathrm{d}^{2}\left(\gamma_{0}, \gamma_{1}\right)+2(\operatorname{diam}(L)+l(\bar{\gamma})) \mathrm{d}\left(\gamma_{0}, \gamma_{1}\right) \\
& +2(\operatorname{diam}(L)+l(\bar{\gamma}))^{2} .
\end{aligned}
$$

Since $(1-t)^{2}+t^{2}=1-2(1-t) t<1$, the length of the geodesic $\gamma$ has a bound from above given in terms of only $\operatorname{diam}(L)$ and $l(\bar{\gamma})$. Hence the measure $\boldsymbol{\pi}\left\llcorner\mathrm{e}_{t}^{-1}(L)\right.$ is supported in a uniformly bounded set of curves.

We can use Proposition 4.8 with $\nu_{i}=(\nu(L))^{-1}\left(\mathrm{e}_{i}\right)_{\sharp} \pi\left\llcorner\mathrm{e}_{t}^{-1}(L)\right.$ to find a measure

$$
\tilde{\nu}=\tilde{\rho} \mathfrak{m} \in \mathcal{J}_{t}\left(\frac{\left(\mathrm{e}_{0}\right)_{\sharp} \boldsymbol{\pi}\left\llcorner\mathrm{e}_{t}^{-1}(L)\right.}{\nu(L)}, \frac{\left(\mathrm{e}_{1}\right)_{\sharp} \boldsymbol{\pi}\left\llcorner\mathrm{e}_{t}^{-1}(L)\right.}{\nu(L)}\right)
$$

with $\tilde{\rho} \leq C / \nu(L) \mathfrak{m}$-a.e. in $X$.
Now consider a new measure $\hat{\nu}=\hat{\rho} \mathfrak{m}$ defined as the combination

$$
\hat{\nu}=\nu\left\llcorner(X \backslash L)+\frac{C+\delta-\phi}{C+\delta} \nu\left\llcorner L+\frac{\phi}{C+\delta} \nu(L) \tilde{\nu} .\right.\right.
$$

By Lemma 4.7 we have $\hat{\nu} \in \mathcal{J}_{t}\left(\mu_{0}, \mu_{1}\right)$.
For $x \in L$ we have the estimates

$$
\begin{align*}
\hat{\rho}(x) & \leq \frac{C+\delta-\phi}{C+\delta} \rho(x)+\frac{\phi}{C+\delta} \nu(L) \tilde{\rho}(x) \leq \frac{(C+\delta-\phi) \rho(x)+C \phi}{C+\delta}  \tag{4.12}\\
& =\rho(x)+\frac{(C-\rho(x)) \phi}{C+\delta}<\rho(x)-\frac{\delta \phi}{C+\delta}
\end{align*}
$$

and

$$
\begin{equation*}
\hat{\rho}(x) \geq \frac{C+\delta-\phi}{C+\delta} \rho(x)>C+\delta-\phi \tag{4.13}
\end{equation*}
$$

For $x \in L^{\prime} \backslash L$ we have

$$
\begin{equation*}
\hat{\rho}(x) \leq \rho(x)+\frac{\phi}{C+\delta} \nu(L) \tilde{\rho}(x) \leq \rho(x)+\frac{C \phi}{C+\delta}<C+\delta+\phi, \tag{4.14}
\end{equation*}
$$

and for $x \in X \backslash L^{\prime}$ we get

$$
\begin{equation*}
\hat{\rho}(x) \leq \rho(x)+\frac{\phi}{C+\delta} \nu(L) \tilde{\rho}(x) \leq C+\delta-3 \phi+\frac{C \phi}{C+\delta}<C+\delta-2 \phi \tag{4.15}
\end{equation*}
$$

Write $C_{2}=\frac{\delta}{C+\delta} \mathfrak{m}(L)$. Let us estimate the change in the entropy when we replace $\nu$ by $\hat{\nu}$ : using the convexity inequality $x \log x-y \log y \leq(x-y)(\log x+1)$ we can estimate from above $\operatorname{Ent}_{\mathfrak{m}}(\hat{\nu})-\operatorname{Ent}_{\mathfrak{m}}(\nu)$ by

$$
\int_{X}(\hat{\rho}-\rho)(\log \hat{\rho}+1) \mathrm{d} \mathfrak{m}=\int_{X}(\hat{\rho}-\rho) \log \hat{\rho} \mathrm{d} \mathfrak{m}
$$

Now, we set $w:=\hat{\rho}-\rho$, split $X$ as $L \cup\left(X \backslash L^{\prime}\right) \cup\left(L^{\prime} \backslash L\right)$ and use the fact that $w \leq 0$ on $L$ and $w \geq 0$ on $X \backslash L$, the inequalities (4.12), (4.13), (4.14), (4.15) and eventually the concavity of log to get

$$
\begin{aligned}
& \int_{L} w \log (C+\delta-\phi) \mathrm{d} \mathfrak{m}+\int_{X \backslash L^{\prime}} w \log (C+\delta-2 \phi) \mathrm{d} \mathfrak{m} \\
& +\int_{L^{\prime} \backslash L} w \log (C+\delta+\phi) \mathrm{d} \mathfrak{m} \\
= & (\log (C+\delta-\phi)-\log (C+\delta-2 \phi)) \int_{L} w \mathrm{~d} \mathfrak{m} \\
& +(\log (C+\delta+\phi)-\log (C+\delta-2 \phi)) \int_{L^{\prime} \backslash L} w \mathrm{~d} \mathfrak{m} \\
\leq & -(\log (C+\delta-\phi)-\log (C+\delta-2 \phi)) \frac{\delta \phi}{C+\delta} \mathfrak{m}(L) \\
& +(\log (C+\delta+\phi)-\log (C+\delta-2 \phi)) \frac{C \phi}{C+\delta} \mathfrak{m}\left(L^{\prime} \backslash L\right) \\
< & -(\log (C+\delta-\phi)-\log (C+\delta-2 \phi)) C_{2} \phi \\
& +(\log (C+\delta+\phi)-\log (C+\delta-2 \phi))\left(1+C_{1}\right) \phi^{2} \\
\leq & -C_{2} \phi \frac{\phi}{C+\delta-2 \phi}+\left(1+C_{1}\right) \phi^{2} \frac{3 \phi}{C+\delta-2 \phi}<0
\end{aligned}
$$

for small enough $\phi \in(0, \eta / 3)$. This contradicts the minimality of the entropy at $\nu$.

### 4.4. Construction of the geodesic.

Proof of Theorem 4.2. In this proof, to avoid a cumbersome notation, we switch to the $\exp$ notation and set $C_{1}:=\left\|\rho_{1}\right\|_{L^{\infty}(X, \mathfrak{m})}$. Let $D>0$ be such that $\operatorname{supp}\left(\mu_{1}\right) \subset$ $B\left(x_{0}, D\right)$. We will prove the claim with

$$
t_{0}:=\min \left\{\frac{c_{2}}{2 K^{-}}, \frac{1}{2}\right\}
$$

The geodesic is constructed as follows. First we fix the measure $\mu_{t_{0}}=\rho_{t_{0}} \mathfrak{m} \in$ $\mathcal{J}_{t_{0}}\left(\mu_{0}, \mu_{1}\right)$ to be a minimizer of the entropy in $\mathcal{J}_{t_{0}}\left(\mu_{0}, \mu_{1}\right)$. After this we define the rest of the geodesic for times $t \in\left(0, t_{0}\right)$ inductively. Suppose that for some $n \in \mathbb{N}$ we have defined $\mu_{k 2^{-n} t_{0}}$ for all $k=0,1, \ldots, 2^{n}$. Then for all odd $k \in$ $\mathbb{N}$ with $0<k<2^{n+1}$ we define $\mu_{k^{-n-1} t_{0}}$ to be a minimizer of the entropy in $\mathcal{J}_{\frac{1}{2}}\left(\mu_{(k-1) 2^{-n-1} t_{0}}, \mu_{(k+1) 2^{-n-1} t_{0}}\right)$. We construct the geodesic on the interval $\left(t_{0}, 1\right]$ in a similar way by iteratively selecting the midpoints with minimal entropy. The
rest of the geodesic is given by completion. Let $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$ be such that $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi}=\mu_{t}$ for all $t \in[0,1]$.

Since we are selecting minimizers of the entropy among all the possible intermediate measures in a $C D(K, \infty)$-space, the selected measures satisfy the convexity inequality (4.1) between the given endpoint measures. Therefore, by Proposition4.3 the inequality (4.1) holds for all $t \in[0,1]$.

Let us then concentrate on the entropy estimates assumed in Proposition 4.8 and Proposition4.9, Let $\boldsymbol{\pi} \in \operatorname{OptGeo}\left(\mu_{0}, \mu_{1}\right)$ and $A \subset X$ Borel with $M:=\boldsymbol{\pi}\left(\mathrm{e}_{t_{0}}^{-1}(A)\right)>$ 0 , write

$$
\hat{\mu}_{0}=\hat{\rho}_{0} \mathfrak{m}=\frac{1}{M}\left(\mathrm{e}_{0}\right)_{\sharp}\left(\boldsymbol{\pi}\left\llcorner\mathrm{e}_{t_{0}}^{-1}(A)\right) \quad \text { and } \quad \hat{\mu}_{1}=\hat{\rho}_{1} \mathfrak{m}=\frac{1}{M}\left(\mathrm{e}_{1}\right)_{\sharp}\left(\pi\left\llcorner\mathrm{e}_{t_{0}}^{-1}(A)\right),\right.\right.
$$

and take a measure $\nu \in \mathcal{J}_{t_{0}}\left(\hat{\mu}_{0}, \hat{\mu}_{1}\right)$ which satisfies the convexity inequality (4.1) between these measures. Now, using (4.2), we have the estimate (with $V(x)=$ $\left.\mathrm{d}\left(x, x_{0}\right)\right)$

$$
\begin{aligned}
\operatorname{Ent}_{\mathfrak{m}}(\nu) \leq & \left(1-t_{0}\right) \operatorname{Ent}_{\mathfrak{m}}\left(\hat{\mu}_{0}\right)+t_{0} \operatorname{Ent}_{\mathfrak{m}}\left(\hat{\mu}_{1}\right)+\frac{K^{-}}{2} t_{0}\left(1-t_{0}\right) W_{2}^{2}\left(\hat{\mu}_{0}, \hat{\mu}_{1}\right) \\
\leq & t_{0} \log \left(\frac{C_{1}}{M}\right)+\left(1-t_{0}\right) \\
& \times \int_{X} \hat{\rho}_{0}(x)\left(\log \hat{\rho}_{0}(x)+\frac{K^{-}}{2} t_{0}(D+V(x))^{2}\right) \mathrm{d} \mathfrak{m}(x) \\
\leq & t_{0} \log \left(\frac{C_{1}}{M}\right)+\left(1-t_{0}\right) \\
& \times \int_{X} \hat{\rho}_{0}(x)\left(\log \left(\frac{c_{1}}{M}\right)-c_{2} V^{2}(x)+K^{-} t_{0}\left(D^{2}+V^{2}(x)\right)\right) \operatorname{dm}(x) \\
\leq & \log \left(\frac{\max \left\{C_{1}, c_{1}\right\}}{M}\right)+K^{-} D^{2}=\log \left(\frac{\max \left\{C_{1}, c_{1}\right\} \exp \left[K^{-} D^{2}\right]}{M}\right)
\end{aligned}
$$

since $K^{-} t_{0} \leq c_{2}$ by the choice of $t_{0}$. By Proposition 4.9 we then have the estimate

$$
\left\|\rho_{t_{0}}\right\|_{L^{\infty}(X, \mathfrak{m})} \leq \max \left\{C_{1}, c_{1}\right\} \exp \left[K^{-} D^{2}\right] \leq \max \left\{C_{1}, c_{1}\right\} \exp \left[\left(2 K^{-}+c_{2}\right) D^{2}\right]=: C .
$$

Next we prove that for all $t \in\left[0, t_{0}\right]$ we have $\mu_{t}=\rho_{t} \mathfrak{m}$ with the estimate

$$
\begin{equation*}
\rho_{t}\left(\gamma_{t}\right) \leq C \exp \left[-\frac{1}{2}\left(1-\frac{t}{t_{0}}\right)\left(c_{2}-K^{-} t t_{0}\right) \ell^{2}(\gamma)\right] \quad \text { for } \boldsymbol{\pi} \text {-a.e. } \gamma \in \operatorname{Geo}(X) \tag{4.16}
\end{equation*}
$$

First of all the estimate (4.16) is true for $t=t_{0}$. For $t=0$ we have that, thanks to (4.2), $\rho_{0}\left(\gamma_{0}\right)$ can be estimated from above by

$$
\begin{aligned}
c_{1} \exp \left[-c_{2} \mathrm{~d}^{2}\left(\gamma_{0}, x_{0}\right)\right] & \leq c_{1} \exp \left[-c_{2}\left([\ell(\gamma)-D]^{+}\right)^{2}\right] \leq c_{1} \exp \left[-\frac{c_{2}}{2} \ell^{2}(\gamma)+c_{2} D^{2}\right] \\
& \leq C \exp \left(-\frac{c_{2}}{2} \ell^{2}(\gamma)\right)
\end{aligned}
$$

and so (4.16) holds also at $t=0$.
Suppose that for some $n \in \mathbb{N}$ the estimate (4.16) holds for all $t=k 2^{-n} t_{0}$ with $k=0,1, \ldots, 2^{n}$. Take an odd integer $k$ with $0<k<2^{n+1}$. Our aim is to prove (4.16) for $t=k 2^{-n-1} t_{0}$.

Let $l \in(0, \infty)$ and $\epsilon>0$ be such that we have $\tilde{M}=\boldsymbol{\pi}(\{\gamma: l \leq l(\gamma) \leq l+\epsilon\})>0$. Then by Proposition 4.5 we know that any measure
$\tilde{\boldsymbol{\pi}} \in \operatorname{OptGeo}\left(\frac{1}{\tilde{M}}\left(\mathrm{e}_{0}\right)_{\sharp} \boldsymbol{\pi}\left\llcorner\{\gamma: l \leq \ell(\gamma) \leq l+\epsilon\}, \frac{1}{\tilde{M}}\left(\mathrm{e}_{1}\right)_{\sharp} \boldsymbol{\pi}\llcorner\{\gamma: l \leq \ell(\gamma) \leq l+\epsilon\})\right.\right.$ is concentrated on geodesics with lengths in the interval $[l, l+\epsilon]$. On the other hand, by Lemma 4.6 we know that

$$
\left(\mathrm{e}_{k 2^{-n-1} t_{0}}\right)_{\sharp} \tilde{\boldsymbol{\pi}} \perp\left(\mathrm{e}_{k 2^{-n-1} t_{0}}\right)_{\sharp} \boldsymbol{\pi}\left\llcorner\left\{\gamma: \ell(\gamma) \notin[l, l+\epsilon] \text { and } \gamma_{k 2^{-n-1} t_{0}} \in A\right\} .\right.
$$

Therefore, in proving (4.16) we may separately deal with the parts of the measure where all the geodesics have lengths in an interval $[l, l+\epsilon]$. Now take a Borel set $A \subset X$ such that for the measure $\hat{\boldsymbol{\pi}}=\boldsymbol{\pi}\left\llcorner\left\{\gamma: l \leq \ell(\gamma) \leq l+\epsilon\right.\right.$ and $\left.\gamma_{k 2^{-n-1} t_{0}} \in A\right\}$ we have $\hat{M}=\hat{\boldsymbol{\pi}}(\operatorname{Geo}(X))>0$.

Suppose that the measure

$$
\tilde{\nu} \in \mathcal{J}_{\frac{1}{2}}\left(\frac{1}{\hat{M}}\left(\mathrm{e}_{(k-1) 2^{-n-1} t_{0}}\right)_{\sharp} \hat{\boldsymbol{\pi}}, \frac{1}{\hat{M}}\left(\mathrm{e}_{(k+1) 2^{-n-1} t_{0}}\right)_{\sharp} \hat{\boldsymbol{\pi}}\right)
$$

satisfies the convexity inequality (4.1). Then

$$
\begin{aligned}
\operatorname{Ent}_{\mathfrak{m}}(\tilde{\nu}) \leq & \frac{1}{2} \operatorname{Ent}_{\mathfrak{m}}\left(\hat{M}^{-1}\left(\mathrm{e}_{(k-1) 2^{-n-1} t_{0}}\right)_{\sharp} \hat{\boldsymbol{\pi}}\right)+\frac{1}{2} \operatorname{Ent}_{\mathfrak{m}}\left(\hat{M}^{-1}\left(\mathrm{e}_{(k+1) 2^{-n-1} t_{0}}\right)_{\sharp} \hat{\boldsymbol{\pi}}\right) \\
& +\frac{K^{-}}{8} W_{2}^{2}\left(\hat{M}^{-1}\left(\mathrm{e}_{(k-1) 2^{-n-1} t_{0}}\right)_{\sharp} \hat{\boldsymbol{\pi}}, \hat{M}^{-1}\left(\mathrm{e}_{(k+1) 2^{-n-1} t_{0}}\right)_{\sharp} \hat{\boldsymbol{\pi}}\right) \\
\leq & \frac{1}{2} \log \frac{C}{\hat{M}}-\frac{1}{4}\left(\left(1-(k-1) 2^{-n-1}\right)\left(c_{2}-K^{-}(k-1) 2^{-n-1} t_{0}^{2}\right) l^{2}\right) \\
& +\frac{1}{2} \log \frac{C}{\hat{M}}-\frac{1}{4}\left(\left(1-(k+1) 2^{-n-1}\right)\left(c_{2}-K^{-}(k+1) 2^{-n-1} t_{0}^{2}\right) l^{2}\right) \\
& +\frac{K^{-}}{8}\left(2^{-n} t_{0}(l+\epsilon)\right)^{2} \\
= & \log \frac{C}{\hat{M}}-\frac{1}{2}\left(\left(1-k 2^{-n-1}\right)\left(c_{2}-K^{-} k 2^{-n-1} t_{0}^{2}\right) l^{2}\right)+\frac{K^{-}}{8} 2^{-2 n} t_{0}^{2}(2 l+\epsilon) \epsilon .
\end{aligned}
$$

Proposition 4.9 then gives

$$
\rho_{t}\left(\gamma_{t}\right) \leq C \exp \left[-\frac{1}{2}\left(1-\frac{t}{t_{0}}\right)\left(c_{2}-K^{-} t t_{0}\right) l^{2}+\frac{K^{-}}{8} 2^{-2 n} t_{0}^{2}(2 l+\epsilon) \epsilon\right]
$$

for $\boldsymbol{\pi}$-a.e. $\gamma \in \operatorname{Geo}(X)$ with $\ell(\gamma) \in[l, l+\epsilon]$. By letting $\epsilon \downarrow 0$ we then obtain (4.16) for $t=k 2^{-n-1} t_{0}$.

Notice that the estimate (4.16) gives $\rho_{t}\left(\gamma_{t}\right) \leq C \exp \left[-\frac{1}{2}\left(1-\frac{t}{t_{0}}\right)\left(c_{2}-K^{-} t t_{0}\right) \ell^{2}(\gamma)\right]$ $\leq C$ for all $t \in\left[0, t_{0}\right]$ for $\pi$-a.e $\gamma \in \operatorname{Geo}(X)$, which is equivalent to (4.3).

## 5. Convergence results

This section is devoted to the proof of some auxiliary convergence results. The first one deals with entropy convergence. Recall the notation $V(x)=\mathrm{d}\left(x, x_{0}\right)$.
Lemma 5.1. Let $f_{n} \mathfrak{m}$, $f \mathfrak{m}$ be positive finite measures in $X$. If $f_{n} \uparrow f \mathfrak{m}$-a.e. and $\int f V^{2} \mathrm{~d} \mathfrak{m}<\infty$, then

$$
\begin{equation*}
\int_{X} f_{n} \log f_{n} \mathrm{~d} \mathfrak{m} \rightarrow \int_{X} f \log f \mathrm{~d} \mathfrak{m} \tag{5.1}
\end{equation*}
$$

The same conclusion holds if $f_{n} \downarrow f \mathfrak{m}$-a.e. and $\int f_{1} V^{2} \mathrm{dm}<\infty$.

Proof. Assume first that $\mathfrak{m}$ is a finite measure. Let us first consider the case $f_{n} \uparrow f$. Observe that the function $t \mapsto t \log t$ is decreasing on $\left[0, \mathrm{e}^{-1}\right]$ and increasing on $\left[\mathrm{e}^{-1}, \infty\right)$; we write it as the difference $\phi_{1}-\phi_{2}$, with

$$
\phi_{1}(t):=\left\{\begin{array}{ll}
-\frac{1}{\mathrm{e}} & \text { if } t \in\left[0, \frac{1}{\mathrm{e}}\right], \\
t \log t & \text { if } t \geq \frac{1}{\mathrm{e}},
\end{array} \quad \phi_{2}(t):= \begin{cases}-\frac{1}{\mathrm{e}}-t \log t & \text { if } t \in\left[0, \frac{1}{\mathrm{e}}\right] \\
0 & \text { if } t \geq \frac{1}{\mathrm{e}} .\end{cases}\right.
$$

Notice that $\phi_{i}$ are nondecreasing and bounded from below. Therefore we can apply the monotone convergence theorem for $\int \phi_{i}\left(f_{n}\right) \mathrm{dm}$ to conclude. In the case $f_{n} \downarrow f$ the argument is the same.

In the general $\sigma$-finite case we use (2.5) to reduce ourselves to the previous case, noticing that our assumptions on $f_{n}$ imply $\int f_{n} V^{2} \mathrm{~d} \mathfrak{m} \rightarrow \int f V^{2} \mathrm{~d} \mathfrak{m}<\infty$.

Recall that, according to Definition 3.2 and (3.5), the space $\mathcal{S}^{2}$ consists of $\mathfrak{m}$ measurable functions having a weak upper gradient in $L^{2}(X, \mathfrak{m})$.
Lemma 5.2. Let $x_{0} \in X, \mu=f \mathfrak{m}, \sigma=g \mathfrak{m} \in \mathscr{P}_{2}(X)$ with $f(x) \leq c_{1} \mathrm{e}^{-c_{2} \mathrm{~d}^{2}\left(x, x_{0}\right)}$ for some $c_{1}, c_{2}>0, \inf _{B_{R}\left(x_{0}\right)} f>0$ for all $R>0$ and $g \in L^{\infty}(X, \mathfrak{m})$ with bounded support. Let $\boldsymbol{\pi} \in \operatorname{OptGeo}(\mu, \sigma)$ be a good geodesic given by Theorem 4.2. Then:
(1) For $h \in \mathcal{S}^{2}$ satisfying $|D h|_{w} \in L^{2}(X, \mu)$ and

$$
\begin{equation*}
|D h|_{w}^{2}(x) \leq C\left(1+\mathrm{d}^{2}\left(x, x_{0}\right)\right) \quad \text { for any } x \in B_{R_{*}}^{c}\left(x_{0}\right) \tag{5.2}
\end{equation*}
$$

for some $C, R_{*}>0$, the following holds (understanding the integrals on $\operatorname{Geo}(X))$ :

$$
\begin{equation*}
\limsup _{t \downarrow 0} \int\left|\frac{h\left(\gamma_{t}\right)-h\left(\gamma_{0}\right)}{\mathrm{d}\left(\gamma_{t}, \gamma_{0}\right)}\right|^{2} \mathrm{~d} \boldsymbol{\pi}(\gamma) \leq \int|D h|_{w}^{2}\left(\gamma_{0}\right) \mathrm{d} \boldsymbol{\pi}(\gamma) . \tag{5.3}
\end{equation*}
$$

(2) For all Kantorovich potentials $\varphi$ relative to $(\mu, \sigma)$ with $|D \varphi|$ having linear growth one has

$$
\begin{equation*}
\lim _{t \downarrow 0} \frac{\varphi\left(\gamma_{0}\right)-\varphi\left(\gamma_{t}\right)}{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)}=\lim _{t \downarrow 0} \frac{\mathrm{~d}\left(\gamma_{0}, \gamma_{t}\right)}{t}=|D \varphi|_{w}\left(\gamma_{0}\right) \quad \text { in } L^{2}(C([0,1] ; X), \boldsymbol{\pi}) \tag{5.4}
\end{equation*}
$$

Proof. (1) Call $f_{t}$ the density of $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi}$, i.e. $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi}=f_{t} \mathfrak{m}$; we know that for $t>0$ sufficiently small, say $t \in\left(0, t_{0}\right), f_{t}$ exists and there exists a constant $C_{*}$ such that $f_{t} \leq C_{*} \mathfrak{m}$-a.e. in $X$ for all $t \in\left(0, t_{0}\right)$. By the definition of a weak upper gradient, for any $t \in\left(0, t_{0}\right)$ and $\boldsymbol{\pi}$-a.e. $\gamma$ one has

$$
\left|\frac{h\left(\gamma_{t}\right)-h\left(\gamma_{0}\right)}{\mathrm{d}\left(\gamma_{t}, \gamma_{0}\right)}\right|^{2} \leq \frac{\left(\int_{0}^{t}|D h|_{w}\left(\gamma_{s}\right)\left|\dot{\gamma}_{s}\right| \mathrm{d} s\right)^{2}}{\mathrm{~d}^{2}\left(\gamma_{t}, \gamma_{0}\right)} \leq \frac{1}{t} \int_{0}^{t}|D h|_{w}^{2}\left(\gamma_{s}\right) \mathrm{d} s
$$

therefore applying Fubini's theorem twice and using the identity $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi}=f_{t} \mathfrak{m}$ we get

$$
\begin{align*}
\int\left|\frac{h\left(\gamma_{t}\right)-h\left(\gamma_{0}\right)}{\mathrm{d}\left(\gamma_{t}, \gamma_{0}\right)}\right|^{2} \mathrm{~d} \boldsymbol{\pi}(\gamma) & \leq \int\left(\frac{1}{t} \int_{0}^{t}|D h|_{w}^{2}\left(\gamma_{s}\right) \mathrm{d} s\right) \mathrm{d} \boldsymbol{\pi}(\gamma)  \tag{5.5}\\
& =\int_{X}\left(\frac{1}{t} \int_{0}^{t} f_{s} \mathrm{~d} s\right)|D h|_{w}^{2} \mathrm{~d} \boldsymbol{m}
\end{align*}
$$

The conclusion of the lemma follows once the following claim is proved:

$$
\begin{equation*}
\lim _{t \downarrow 0} \int_{X}\left(\frac{1}{t} \int_{0}^{t} f_{s} \mathrm{~d} s\right)|D h|_{w}^{2} \mathrm{~d} \mathfrak{m}=\int_{X}|D h|_{w}^{2} f \mathrm{~d} \mathfrak{m} \tag{5.6}
\end{equation*}
$$

In order to prove the claim we use both the uniform $L^{\infty}$ estimates on $f_{t}$ and the 2-uniform integrability of $V^{2}$ w.r.t. $f_{t} \mathfrak{m}$. Notice first that the local boundedness of $f^{-1}$ implies $|D h|_{w}^{2} \in L^{1}\left(B_{R}\left(x_{0}\right), \mathfrak{m}\right)$ for all $R>0$; moreover

$$
\begin{equation*}
\bar{f}_{t}:=\left(\frac{1}{t} \int_{0}^{t} f_{s} \mathrm{~d} s\right) \rightarrow f \quad \text { in duality with } L^{1}\left(B_{R}\left(x_{0}\right), \mathfrak{m}\right) . \tag{5.7}
\end{equation*}
$$

Indeed the weak convergence $f_{t} \mathfrak{m} \rightarrow f \mathfrak{m}$ implies the weak convergence of $\bar{f}_{t}$ to $f$ in the duality with $C_{b}\left(B_{R}\left(x_{0}\right)\right)$; then (5.7) follows by the uniform $L^{\infty}$ bound on $\bar{f}_{t}$. Second, observe that (5.2) gives

$$
\begin{align*}
\left.\left|\int_{X} \bar{f}_{t}\right| D h\right|_{w} ^{2} \mathrm{~d} \mathfrak{m}-\int_{B_{R}\left(x_{0}\right)} \bar{f}_{t}|D h|_{w}^{2} \mathrm{~d} \mathfrak{m} \mid \leq & \frac{C}{t} \int_{0}^{t} \int_{B_{R}^{c}\left(x_{0}\right)}\left(1+\mathrm{d}^{2}\left(x, x_{0}\right)\right) f_{s} \mathrm{~d} \mathfrak{m} \mathrm{~d} s  \tag{5.8}\\
& \rightarrow 0 \quad \text { as } R \rightarrow \infty \text { uniformly in } t \in\left(0, t_{0}\right)
\end{align*}
$$

the second line comes from the observation that the geodesic $\left(f_{s} \mathfrak{m}\right)_{s \in[0,1]}$ is a compact subset in $\left(\mathscr{P}_{2}(X), W_{2}\right)$, hence tight and 2-uniformly integrable (see [2, Proposition 7.1.5]). The claim (5.6) then follows by combining (5.8) and (5.7).
(2) Observe we are under the assumptions of the Metric Brenier Theorem 10.3 in [3]. Therefore there exists a Borel function $L$ satisfying $L\left(\gamma_{0}\right):=\mathrm{d}\left(\gamma_{0}, \gamma_{1}\right)$ for $\pi$-a.e. $\gamma \in \operatorname{Geo}(X)$ and, in addition,

$$
\begin{equation*}
|D \varphi|_{w}(x)=\left|D^{+} \varphi\right|(x)=L(x) \quad \text { for } \mathfrak{m} \text {-a.e. } x \in X \tag{5.9}
\end{equation*}
$$

It trivially follows that for $\boldsymbol{\pi}$-a.e. $\gamma \in \operatorname{Geo}(X)$

$$
|D \varphi|_{w}\left(\gamma_{0}\right)=\mathrm{d}\left(\gamma_{0}, \gamma_{1}\right)=\frac{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)}{t} \quad \text { for every } t \in(0,1)
$$

The missing part is the $L^{2}$ convergence of difference quotients, proved and stated in [3] under a different set of assumptions; we adapt the argument to our case, where $|D \varphi|$ has linear growth. Since by optimality we have for $\pi$-a.e. $\gamma$ that

$$
\varphi\left(\gamma_{0}\right)+\varphi^{c}\left(\gamma_{1}\right)=\frac{\mathrm{d}^{2}\left(\gamma_{0}, \gamma_{1}\right)}{2}, \quad \varphi\left(\gamma_{t}\right)+\varphi^{c}\left(\gamma_{1}\right) \leq \frac{\mathrm{d}^{2}\left(\gamma_{t}, \gamma_{1}\right)}{2}
$$

we get with a subtraction that

$$
\varphi\left(\gamma_{0}\right)-\varphi\left(\gamma_{t}\right) \geq \frac{1-(1-t)^{2}}{2} d^{2}\left(\gamma_{0}, \gamma_{1}\right)=\frac{2 t-t^{2}}{2} d^{2}\left(\gamma_{0}, \gamma_{1}\right) \quad \text { for } \boldsymbol{\pi} \text {-a.e. } \gamma \text {. }
$$

Therefore, dividing both sides by $\mathrm{d}\left(\gamma_{t}, \gamma_{0}\right)=t \mathrm{~d}\left(\gamma_{1}, \gamma_{0}\right)$, for $\boldsymbol{\pi}$-a.e. $\gamma$ one has

$$
\begin{equation*}
\liminf _{t \downarrow 0} \frac{\varphi\left(\gamma_{0}\right)-\varphi\left(\gamma_{t}\right)}{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)} \geq \mathrm{d}\left(\gamma_{0}, \gamma_{1}\right)=|D \varphi|_{w}\left(\gamma_{0}\right) \tag{5.10}
\end{equation*}
$$

On the other hand, by the definition of ascending slope,

$$
\begin{equation*}
\limsup _{t \downarrow 0} \frac{\varphi\left(\gamma_{0}\right)-\varphi\left(\gamma_{t}\right)}{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)} \leq\left|D^{+} \varphi\right|\left(\gamma_{0}\right) \tag{5.11}
\end{equation*}
$$

So, combining (5.9) and (5.10) with (5.11) we get

$$
\begin{equation*}
\lim _{t \downarrow 0} \frac{\varphi\left(\gamma_{0}\right)-\varphi\left(\gamma_{t}\right)}{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)}=|D \varphi|_{w}\left(\gamma_{0}\right) \quad \text { for } \pi \text {-a.e. } \gamma \text {. } \tag{5.12}
\end{equation*}
$$

Now we claim that

$$
\begin{equation*}
\frac{\varphi\left(\gamma_{0}\right)-\varphi\left(\gamma_{t}\right)}{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)} \rightharpoonup|D \varphi|_{w} \circ \mathrm{e}_{0} \quad \text { weakly in } L^{2}(\operatorname{Geo}(X), \boldsymbol{\pi}) \tag{5.13}
\end{equation*}
$$

Since by assumption $|D \varphi|$ has linear growth, by part (1) of the present lemma we have

$$
\begin{equation*}
\underset{t \downarrow 0}{\limsup } \int\left|\frac{\varphi\left(\gamma_{0}\right)-\varphi\left(\gamma_{t}\right)}{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)}\right|^{2} \mathrm{~d} \boldsymbol{\pi} \leq \int|D \varphi|_{w}^{2}\left(\gamma_{0}\right) \mathrm{d} \boldsymbol{\pi} \tag{5.14}
\end{equation*}
$$

If $\psi$ is a weak limit point of the difference quotients as $t \downarrow 0$, by Mazur's lemma a sequence of convex combinations of these difference quotients strongly converges in $L^{2}(\operatorname{Geo}(X), \boldsymbol{\pi})$ to $\psi$. Since a further subsequence converges $\boldsymbol{\pi}$-a.e., from (5.12) we obtain that $\psi=\left|D^{+} \varphi\right|$. By weak compactness, the claim follows.

We conclude by observing that the lower semicontinuity of the norm under weak convergence together with (5.14) ensure convergence of the $L^{2}(\mathrm{Geo}(X), \boldsymbol{\pi})$ norms. Since in Hilbert spaces weak convergence and convergence of the norms give strong convergence, the lemma is proved.

Our third result deals with weak convergence in the weighted Cheeger space; it will be applied to sequences of Kantorovich potentials. In this and in the next lemma we assume that Ch is quadratic, so that by Theorem $3.9 \mathrm{Ch}_{\eta}$ is quadratic whenever $\eta=g \mathfrak{m} \in \mathscr{P}_{2}(X)$ with $g \in L^{\infty}(X, \mathfrak{m})$ and with $\mathrm{Ch}(\sqrt{g})<\infty$. Recall that $\mathcal{E}_{\eta}$ denotes, according to (3.7), the bilinear form associated to $\mathrm{Ch}_{\eta}$.

Lemma 5.3. Let $(X, \mathrm{~d}, \mathfrak{m})$ have a quadratic Cheeger energy. Let $\eta=g \mathfrak{m} \in \mathscr{P}_{2}(X)$ with $g \in L^{\infty}(X, \mathfrak{m})$ and $\operatorname{Ch}(\sqrt{g})<\infty$. Consider a sequence $\left(f_{n}\right) \subset \mathcal{S}^{2}$ with

$$
\begin{equation*}
\sup _{n \in \mathbb{N}} \int_{X}\left|D f_{n}\right|_{w}^{2} \mathrm{~d} \eta<\infty, \quad \sup _{n \in \mathbb{N}}\left|f_{n}\right|(x) \leq C\left(1+\mathrm{d}^{2}\left(x, x_{0}\right)\right) \tag{5.15}
\end{equation*}
$$

and assume that $f_{n} \rightarrow f \mathfrak{m}$-a.e. in $X$. Then

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \varepsilon_{\eta}\left(f_{n}, \log g\right)=\mathcal{E}_{\eta}(f, \log g) \tag{5.16}
\end{equation*}
$$

Proof. We argue as in Theorem 3.9, Let us consider the weighted measure

$$
\tilde{\eta}:=\frac{1}{1+V^{2}} \eta
$$

and the corresponding weighted Sobolev space $H:=L^{2}(X, \tilde{\eta}) \cap \mathcal{S}_{\eta}^{2}$, endowed with the scalar product

$$
\langle f, g\rangle_{H}:=\int_{X} f g \mathrm{~d} \tilde{\eta}+\mathcal{E}_{\eta}(f, g)
$$

Observe that, since $L^{2}(X, \tilde{\eta})$ is a Hilbert space, in order to check the completeness of the norm $\|\cdot\|_{H}$ induced by this scalar product it is enough to check the lower semicontinuity of $\|\cdot\|_{H}$ with respect to strong convergence in $L^{2}(X, \tilde{\eta})$; but this is clear since $\mathrm{Ch}_{\eta}$ is lower semicontinuous with respect to $L^{2}(X, \eta)$ convergence and, on sequences uniformly bounded in $L^{\infty}(X, \eta)$, the finiteness of $\eta$ turns $L^{2}(X, \tilde{\eta})$ convergence into $L^{2}(X, \eta)$ convergence. By a truncation argument one obtains that $\mathrm{Ch}_{\eta}$ is $L^{2}(X, \tilde{\eta})$-lower semicontinuous. We conclude that $\left(H,\langle\cdot, \cdot\rangle_{H}\right)$ is a Hilbert space (it is even separable, see [4. Proposition 4.10], but we shall not need this fact in the sequel).

Now since $\eta \in \mathscr{P}(X)$, from the second assumption (5.15) and dominated convergence we have that $f_{n} \rightarrow f$ strongly in $L^{2}(X, \tilde{\eta})$. On the other hand, the first assumption in (5.15) implies that $\left\|f_{n}\right\|_{H}$ is bounded. By reflexivity it follows that
$f_{n} \rightarrow f$ weakly in $H$. The conclusion follows by noticing that, since $\operatorname{Ch}(\sqrt{g})<\infty$, the map

$$
h \mapsto \varepsilon_{\eta}(h, \log g)
$$

is linear and continuous from $H$ to $\mathbb{R}$.
In this last result we estimate how much $\mathcal{E}_{\rho}(\log g, \varphi)$ changes under modifications of the density $g$ of $\rho$.

Lemma 5.4. Let $\eta=g \mathfrak{m}, \eta^{\prime}=g^{\prime} \mathfrak{m} \in \mathscr{P}_{2}(X)$ with $g, g^{\prime} \in L^{\infty}(X, \mathfrak{m})$ and $\operatorname{Ch}(\sqrt{g})$, $\mathrm{Ch}\left(\sqrt{g^{\prime}}\right)$ finite. Let $\varphi: X \rightarrow \mathbb{R}$ be a locally Lipschitz function whose gradient has linear growth. Then, setting $E:=\left\{g \neq g^{\prime}\right\}$, one has

$$
\begin{align*}
\left|\mathcal{E}_{\eta}(\log g, \varphi)-\mathcal{E}_{\eta^{\prime}}\left(\log g^{\prime}, \varphi\right)\right| \leq & \left(\int_{E}|D \sqrt{g}|_{w}^{2} \mathrm{dm}\right)^{1 / 2}\left(\int_{E}|D \varphi|_{w}^{2} \mathrm{~d} \eta\right)^{1 / 2}  \tag{5.17}\\
& +\left(\int_{E}\left|D \sqrt{g^{\prime}}\right|_{w}^{2} \mathrm{dm}\right)^{1 / 2}\left(\int_{E}|D \varphi|_{w}^{2} \mathrm{~d} \eta^{\prime}\right)^{1 / 2}
\end{align*}
$$

Proof. By Lemma 5.3 we can assume, by a simple approximation argument, that $\varphi$ has bounded support. Under this assumption the quantity to be estimated reduces, thanks to (3.12) and (3.10), to

$$
\begin{aligned}
\left|\int_{X} G(\varphi, g)-G\left(\varphi, g^{\prime}\right) \mathrm{d} \mathfrak{m}\right| & =\left|\int_{E} G(\varphi, g)-G\left(\varphi, g^{\prime}\right) \mathrm{d} \mathfrak{m}\right| \\
& \leq \int_{E}\left(|D g|_{w}|D \varphi|_{w}+\left|D g^{\prime}\right|_{w}|D \varphi|_{w}\right) \mathrm{d} \mathfrak{m}
\end{aligned}
$$

and, after dividing and multiplying by $\sqrt{g}$ and $\sqrt{g^{\prime}}$, we can use Hölder's inequality to provide the result.

## 6. Equivalence of the different formulations of $R C D(K, \infty)$

In this section we prove the following result, extending Theorem 1.1 to $\sigma$-finite metric measure spaces.
Theorem 6.1. Let $(X, \mathrm{~d}, \mathfrak{m})$ be a metric measure space with $(X, \mathrm{~d})$ complete, separable, $\mathfrak{m}$ finite on bounded sets and with supp $\mathfrak{m}=X$. Then the following properties are equivalent:
(i) $(X, \mathrm{~d}, \mathfrak{m})$ is a $C D(K, \infty)$ space and the semigroup $\mathscr{H}_{t}$ on $\mathscr{P}_{2}(X)$ is additive.
(ii) $(X, \mathrm{~d}, \mathfrak{m})$ is a $C D(K, \infty)$ space and Ch is a quadratic form on $L^{2}(X, \mathfrak{m})$.
(iii) $(X, \mathrm{~d}, \mathfrak{m})$ is a length space, (2.3) holds and any $\mu \in \mathscr{P}_{2}(X)$ is the starting point of an $E V I_{K}$ gradient flow of $E n t_{\mathfrak{m}}$.
Any metric measure space ( $X, \mathrm{~d}, \mathfrak{m}$ ) satisfying these assumptions and one of the equivalent properties (i), (ii), (iii) will be called a ( $\sigma$-finite) $R C D(K, \infty)$ space.

Here $\mathscr{H}_{t}$ is the $W_{2}$-gradient flow of $\mathrm{Ent}_{\mathfrak{m}}$, according to Definition 2.4 (which is known to exist and to be unique for any given initial datum in $D\left(\right.$ Ent $\left._{\mathfrak{m}}\right)$; see 16] and [3), while $\mathrm{h}_{t}$ stands for the gradient flow of Ch in $L^{2}(X, \mathfrak{m})$ (or, equivalently, the $E V I_{0}$ gradient flow).

Note that the implications (i) to (ii) and (iii) to (i) were already proved by the first two authors with Savaré in [4, because the same proof works in the $\sigma$-finite setting. The key implication from (ii) (or (i)) to (iii) is given by the derivative of
quadratic optimal transport distance along the heat flow and of the entropy along a geodesic, estimated in the next two subsections. Consequently we shall always assume in this section that Ch is quadratic.

We denote by $\Delta$ the infinitesimal generator of the linear semigroup $h_{t}$, so that

$$
\frac{\mathrm{d}}{\mathrm{~d} t} \mathrm{~h}_{t} f=\Delta \mathrm{h}_{t} \quad \text { for a.e. } t>0 .
$$

Also, since Ch is quadratic, $\Delta$ is related to the bilinear form $\mathcal{E}$ in (3.7) by

$$
\begin{equation*}
\int_{X} g \Delta f \mathrm{~d} \mathfrak{m}=\mathcal{E}(f, g) \quad \forall g \in \mathcal{S}^{2} \cap L^{2}(X, \mathfrak{m}), f \in D(\Delta) . \tag{6.1}
\end{equation*}
$$

One of the main results of the work of the first two authors with Savaré 3 has been the following identification theorem in $C D(K, \infty)$; see (8.5), Theorem 8.5 and Theorem 9.3(iii) therein.

Theorem 6.2 (The heat flow as gradient flow). Let ( $X, \mathrm{~d}, \mathfrak{m}$ ) be a $C D(K, \infty)$ space and let $f \in L^{2}(X, \mathfrak{m})$ be such that $\mu=f \mathfrak{m} \in \mathscr{P}_{2}(X)$. Then $\mathscr{H}_{t} \mu=\mathrm{h}_{t} f \mathfrak{m}$ for all $t \geq 0, t \mapsto \operatorname{Ent}_{\mathfrak{m}}\left(\mathscr{H}_{t} \mu\right)$ is locally absolutely continuous in $[0, \infty)$, and

$$
\begin{equation*}
-\frac{\mathrm{d}}{\mathrm{~d} t} \operatorname{Ent}_{\mathfrak{m}}\left(\mathscr{H}_{t} \mu\right)=\left|\dot{\mathscr{H}}_{t} \mu\right|^{2}=\int_{\left\{\mathrm{h}_{t} f>0\right\}} \frac{\left|D \mathrm{~h}_{t} f\right|_{w}^{2}}{\mathrm{~h}_{t} f} \mathrm{~d} \mathfrak{m} \quad \text { for a.e. } t>0 . \tag{6.2}
\end{equation*}
$$

In other words, one can unambiguously define the heat flow on a $C D(K, \infty)$ space either as the gradient flow of Ch in $L^{2}(X, \mathfrak{m})$ or as the $W_{2}$-gradient flow of Ent $_{\mathrm{m}}$.
6.1. Derivative of $W_{2}^{2}(\cdot, \sigma)$ along the heat flow. Notice that this result, whose proof is achieved by a duality argument, requires no curvature assumption. We need only to assume that Ch is quadratic and that $\mathfrak{m}$ satisfies the growth condition (2.3).

Theorem 6.3. Let $\mu=f \mathfrak{m} \in D\left(\right.$ Ent $\left._{\mathfrak{m}}\right)$ and define $\mu_{t}:=\left(\mathrm{h}_{t} f\right) \mathfrak{m}=f_{t} \mathfrak{m}$. Let $\sigma \in \mathscr{P}_{2}(X)$ with bounded support. Then, for a.e. $t>0$ the following property holds: for any Kantorovich potential $\varphi_{t}$ relative to $\left(\mu_{t}, \sigma\right)$ whose slope has linear growth, one has

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \frac{1}{2} W_{2}^{2}\left(\mu_{t}, \sigma\right)=-\varepsilon_{\mu_{t}}\left(\varphi_{t}, \log f_{t}\right) . \tag{6.3}
\end{equation*}
$$

Proof. By the energy dissipation estimate (6.2), we have $\int_{0}^{\infty} \mathrm{Ch}\left(\sqrt{f_{t}}\right) \mathrm{d} t<\infty$. Furthermore, the maximum principle proved in Theorem 4.20 of [3] shows that $f_{t} \leq\|f\|_{\infty} \mathfrak{m}$-a.e. in $X$ for all $t \geq 0$. Also, by Proposition 2.2 the potential $\varphi_{t}$ belongs to $L^{1}(X, \nu)$ for all $\nu \in \mathscr{P}_{2}(X)$ and its slope has linear growth. Furthermore, the $L^{1}$ estimate is uniform in $t$ and in bounded subsets of $\mathscr{P}_{2}(X)$ and the estimate on the slope depends on $\sigma$ only.

Thanks to (6.2), the map $t \mapsto f_{t} \mathfrak{m}$ is a locally absolutely continuous curve in $\mathscr{P}_{2}(X)$; hence the derivative on the left hand side of (6.3) exists for a.e. $t>0$. Also, the derivative of $t \mapsto f_{t}$ exists in $L^{2}(X, \mathfrak{m})$ and coincides with $\Delta f_{t}$ for a.e. $t>0$. Fix $t_{0}>0$ where both properties hold, which is also a Lebesgue point for $\mathrm{Ch}\left(\sqrt{f_{t}}\right)$.

We now claim that

$$
\begin{equation*}
\lim _{h \downarrow 0} \int_{X} \psi \frac{f_{t_{0}}-f_{t_{0}-h}}{h} \mathrm{~d} \mathfrak{m}=-\varepsilon_{\mu_{t_{0}}}\left(\psi, \log f_{t_{0}}\right) \tag{6.4}
\end{equation*}
$$

for all locally Lipschitz functions $\psi$ whose gradient has linear growth. The proof of (6.4) is easy if we assume, in addition, that $\psi$ has bounded support. Indeed, $h^{-1}\left(f_{t_{0}+h}-f_{t_{0}}\right) \rightarrow \Delta f_{t_{0}}$ as $h \rightarrow 0$ in $L^{2}(X, \mathfrak{m})$, so that (3.12) and (6.1) give

$$
\lim _{h \rightarrow 0} \int_{X} \psi \frac{f_{t_{0}+h}-f_{t_{0}}}{h} \mathrm{~d} \mathfrak{m}=\int_{X} \psi \Delta f_{t_{0}} \mathrm{~d} \mathfrak{m}=-\mathcal{E}\left(\psi, f_{t_{0}}\right)=-\mathcal{E}_{\mu_{t_{0}}}\left(\psi, \log f_{t_{0}}\right) .
$$

For the general case, let $\chi_{N}: X \rightarrow[0,1]$ satisfy $\operatorname{Lip}\left(\chi_{N}\right) \leq 1, \chi_{N} \equiv 1$ on $B_{N}\left(x_{0}\right)$ and $\chi_{N} \equiv 0$ on $X \backslash B_{2 N}\left(x_{0}\right)$ and define $\psi^{N}:=\psi \chi_{N}$. Applying Lemma 6.4 below with $\varphi_{N}:=\psi-\psi^{N}$ we get

$$
\sup _{|h|<t_{0} / 2}\left|\int \varphi_{N} \frac{\rho_{t_{0}+h}-\rho_{t_{0}}}{h} \mathrm{dm}\right|^{2} \leq \sup _{|h|<t_{0} / 2} \frac{8}{h} \int_{t_{0}-|h|}^{t_{0}+|h|} \operatorname{Ch}\left(\sqrt{f_{s}}\right) \int_{X}\left|D \varphi_{N}\right|_{w}^{2} \mathrm{~d} \mu_{s} \mathrm{~d} s
$$

Hence (by our choice of $t_{0}$ and the 2 -uniform integrability of $\mu_{s}$ )

$$
\limsup _{N \rightarrow \infty} \sup _{|h|<t_{0} / 2}\left|\int_{X} \varphi_{N} \frac{f_{t_{0}+h}-f_{t_{0}}}{h} d \mathfrak{m}\right|=0
$$

which, taking into account that $\varepsilon_{\mu_{t_{0}}}\left(\psi^{N}, \log f_{t_{0}}\right) \rightarrow \mathcal{E}_{\mu_{t_{0}}}\left(\psi, \log f_{t_{0}}\right)$ thanks to Lemma 5.3 implies (6.4).

Now, notice that since $\varphi_{t_{0}}$ is a Kantorovich potential for $\left(\mu_{t_{0}}, \sigma\right)$ one has

$$
\begin{aligned}
\frac{1}{2} W_{2}^{2}\left(\mu_{t_{0}}, \sigma\right) & =\int_{X} \varphi_{t_{0}} \mathrm{~d} \mu_{t_{0}}+\int \varphi_{t_{0}}^{c} \mathrm{~d} \sigma \\
\frac{1}{2} W_{2}^{2}\left(\mu_{t_{0}-h}, \sigma\right) & \geq \int_{X} \varphi_{t_{0}} \mathrm{~d} \mu_{t_{0}-h}+\int \varphi_{t_{0}}^{c} \mathrm{~d} \sigma \quad \text { for all } h \text { such that } t_{0}-h>0
\end{aligned}
$$

Taking the difference between the first identity and the second inequality and using the claim with $\psi=\varphi_{t_{0}}$ we get

$$
\frac{1}{2} W_{2}^{2}\left(\mu_{t_{0}+h}, \sigma\right)-\frac{1}{2} W_{2}^{2}\left(\mu_{t_{0}}, \sigma\right) \geq-h \varepsilon_{\mu_{t_{0}}}\left(\log f_{t_{0}}, \varphi_{t_{0}}\right)+o(h)
$$

Since $t \mapsto W_{2}^{2}\left(\mu_{t}, \sigma\right)$ is differentiable at $t=t_{0}$ we conclude.
Lemma 6.4. Let $\mu_{s}=f_{s} \mathfrak{m}$ be as in the previous theorem and let $\varphi: X \rightarrow \mathbb{R}$ be locally Lipschitz, with $|D \varphi|$ having linear growth. Then, for $[s, t] \subset(0, \infty)$ one has

$$
\begin{equation*}
\left|\int \varphi \frac{f_{t}-f_{s}}{t-s} \mathrm{dm}\right|^{2} \leq \frac{8}{t-s} \int_{s}^{t} \operatorname{Ch}\left(\sqrt{f_{r}}\right)\left(\int|D \varphi|_{w}^{2} \mathrm{~d} \mu_{r}\right) \mathrm{d} r \tag{6.5}
\end{equation*}
$$

Proof. Assume first that $\varphi \in L^{2}(X, \mathfrak{m})$. Then integrating by parts we get

$$
\left|\int \varphi \Delta f_{r} \mathrm{~d} \mathfrak{m}\right|^{2} \leq\left(\int|D \varphi|_{w}\left|D f_{r}\right|_{w} \mathrm{~d} \mathfrak{m}\right)^{2} \leq \int|D \varphi|_{w}^{2} \mathrm{~d} \mu_{r} \int \frac{\left|D f_{r}\right|_{w}^{2}}{f_{r}} \mathrm{~d} \mathfrak{m}
$$

for all $r>0$, and the thesis follows by integration in $(s, t)$. For the general case, we approximate $\varphi$ by $\varphi \chi_{N}$, with $\chi_{N}$ chosen as in the proof of the previous theorem.
6.2. Derivative of the entropy along Ent ${ }_{\mathfrak{m}}$-convex $L^{\infty}$-bounded geodesics. The goal of this subsection is to prove the following theorem, where both the curvature condition and the fact that Ch is quadratic play a role.

Theorem 6.5 (Entropy inequality). Assume that ( $X, \mathrm{~d}, \mathfrak{m}$ ) is a $C D(K, \infty)$ space. Let $\eta=f \mathfrak{m}, \sigma=g \mathfrak{m} \in \mathscr{P}_{2}(X)$ with $g$ uniformly bounded and having compact support, and $f$ uniformly bounded with $\mathrm{Ch}(\sqrt{f})<\infty$. Then there exists a Kantorovich potential $\varphi$ from $\eta$ to $\sigma$ such that $|D \varphi|$ has linear growth and

$$
\begin{equation*}
\operatorname{Ent}_{\mathfrak{m}}(\sigma)-\operatorname{Ent}_{\mathfrak{m}}(\eta)-\frac{K}{2} W_{2}^{2}(\eta, \sigma) \geq-\varepsilon_{\eta}(\varphi, \log f) \tag{6.6}
\end{equation*}
$$

The proof of Theorem 6.5 carried by approximation, is presented at the end of the subsection; the first crucial step is the following proposition, whose proof relies on Proposition 2.2 and Lemma 5.2,

Proposition 6.6. Under the assumptions of Theorem 6.5, for $\delta>0$ call

$$
\begin{equation*}
f_{\delta, n}=c_{\delta, n}\left[\left(\chi_{n}^{2}\right) \eta \vee \delta \mathrm{e}^{-2 c V^{2}}\right], \tag{6.7}
\end{equation*}
$$

where $c$ is strictly larger than the constant c in (2.3), $c_{\delta, n}$ is the normalizing constant such that $f_{\delta, n} \mathfrak{m}$ is a probability density, and $\chi_{n}$ is a 1-Lipschitz cut-off function equal to 1 on $B_{n}\left(x_{0}\right)$ and null outside $B_{2 n}\left(x_{0}\right)$.

Then there exists a Kantorovich potential $\varphi_{\delta, n}$ from $\eta_{\delta, n}:=f_{\delta, n} \mathfrak{m}$ to $\sigma$ satisfying the growth conditions

$$
\begin{equation*}
\left|\varphi_{\delta, n}(x)\right| \leq C(\sigma)\left(1+\mathrm{d}^{2}\left(x, x_{0}\right)\right), \quad\left|D \varphi_{\delta, n}\right|(x) \leq C(\sigma)\left(1+\mathrm{d}\left(x, x_{0}\right)\right) \tag{6.8}
\end{equation*}
$$

such that

$$
\begin{equation*}
\operatorname{Ent}_{\mathfrak{m}}(\sigma)-\operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta, n}\right)-\frac{K}{2} W_{2}^{2}\left(\eta_{\delta, n}, \sigma\right) \geq-\varepsilon_{\eta_{\delta, n}}\left(\varphi_{\delta, n}, \log f_{\delta, n}\right) \tag{6.9}
\end{equation*}
$$

Proof. First of all we are under the assumptions of Theorem 4.2, so let $\pi \in$ $\operatorname{OptGeo}\left(\eta_{\delta, n}, \sigma\right)$ and let $\left(\mathrm{e}_{t}\right)_{\sharp} \boldsymbol{\pi}=\mu_{t}=f_{t} \mathfrak{m}, t \in[0,1]$, be the associated good geodesic from $\eta_{\delta, n}$ to $\sigma$ with a uniform $L^{\infty}$ bound on the density for $t \in\left(0, t_{0}\right)$ and the $K$-convexity of the entropy. Also let $\varphi$ be the Kantorovich potential, given by Proposition 2.2, with quadratic growth and whose slope has linear growth.

Let us now check that $f_{\delta, n}$ satisfies the assumptions of Lemma 5.2. Indeed, $\left|D \log f_{\delta, n}\right| \leq C\left(1+\mathrm{d}\left(x, x_{0}\right)\right)$ whenever $\mathrm{d}\left(x, x_{0}\right)>2 n$, because in this set $f_{\delta_{n}}$ coincides with $c_{\delta, n} \delta \mathrm{e}^{-2 c V^{2}}$; in addition, the locality of weak gradients and the partition $X=\left\{\chi_{n}^{2} \eta>\delta \mathrm{e}^{-2 c V^{2}}\right\} \cup\left\{\chi_{n}^{2} \eta \leq \delta \mathrm{e}^{-2 c V^{2}}\right\}$ ensure that $\left|D \log f_{\delta, n}\right|_{w} \in L^{2}\left(X, \eta_{\delta, n}\right)$ because the finiteness of $\operatorname{Ch}(\sqrt{f})$ ensures that $|D \log f|_{w} \in L^{2}(X, \eta)$.

Observe that the convexity of $z \mapsto z \log z$ gives

$$
\begin{align*}
\frac{\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right)-\operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta, n}\right)}{t} & \geq \int_{X} \log f_{\delta, n} \frac{f_{t}-f_{\delta, n}}{t} \mathrm{~d} \mathfrak{m}  \tag{6.10}\\
& =\int \frac{\log \left(f_{\delta, n} \circ \mathrm{e}_{t}\right)-\log \left(f_{\delta, n} \circ \mathrm{e}_{0}\right)}{t} \mathrm{~d} \boldsymbol{\pi}
\end{align*}
$$

Define the functions $F_{t}, G_{t}: A C^{2}([0,1] ; X) \rightarrow \mathbb{R}$ as

$$
\begin{equation*}
F_{t}(\gamma):=\frac{\log \left(f_{\delta, n} \circ \mathrm{e}_{0}\right)-\log \left(f_{\delta, n} \circ \mathrm{e}_{t}\right)}{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)}, \quad G_{t}(\gamma):=\frac{\varphi \circ \mathrm{e}_{0}-\varphi \circ \mathrm{e}_{t}}{\mathrm{~d}\left(\gamma_{0}, \gamma_{t}\right)} \tag{6.11}
\end{equation*}
$$

Multiplying and dividing the right hand side of (6.10) by $\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)$ we obtain

$$
\begin{equation*}
\liminf _{t \downarrow 0} \frac{\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right)-\operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta, n} \mathfrak{m}\right)}{t} \geq-\limsup _{t \downarrow 0} \int F_{t}(\gamma) \frac{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)}{t} \mathrm{~d} \boldsymbol{\pi}(\gamma) \tag{6.12}
\end{equation*}
$$

Now we claim that

$$
\begin{equation*}
-\limsup _{t \downarrow 0} \int F_{t}(\gamma) \frac{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)}{t} \mathrm{~d} \boldsymbol{\pi}(\gamma)=-\underset{t \downarrow 0}{\limsup } \int F_{t} G_{t} \mathrm{~d} \boldsymbol{\pi} \tag{6.13}
\end{equation*}
$$

The proof of (6.13) follows at once by

$$
\begin{equation*}
\lim _{t \downarrow 0} \int\left|G_{t}(\gamma)-\frac{\mathrm{d}\left(\gamma_{0}, \gamma_{t}\right)}{t}\right|^{2} \mathrm{~d} \boldsymbol{\pi}=0 \quad \text { and } \quad \sup _{t \leq t_{0}} \int\left|F_{t}\right|^{2} \mathrm{~d} \boldsymbol{\pi}<\infty . \tag{6.14}
\end{equation*}
$$

The first fact in (6.14) is ensured by (2) of Lemma 5.2, as well as the identity

$$
\begin{equation*}
\int|D \varphi|_{w}^{2} \circ \mathrm{e}_{0} \mathrm{~d} \boldsymbol{\pi}=\lim _{t \downarrow 0} \int\left|G_{t}\right|^{2} \mathrm{~d} \boldsymbol{\pi} \tag{6.15}
\end{equation*}
$$

The second fact in (6.14) is ensured by (1) of the same lemma applied to $h=\log f_{\delta, n}$. Combining (6.12) and (6.13) we get

$$
\begin{equation*}
\liminf _{t \downarrow 0} \frac{\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right)-\operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta, n} \mathfrak{m}\right)}{t} \geq-\limsup _{t \downarrow 0} \int F_{t} G_{t} \mathrm{~d} \boldsymbol{\pi} . \tag{6.16}
\end{equation*}
$$

Now, applying Lemma 5.2 to $h=\varphi+\epsilon \log f_{\delta, n}$ gives that

$$
\begin{equation*}
\int\left|D\left(\varphi+\epsilon \log f_{\delta, n}\right)\right|_{w}^{2} \circ \mathrm{e}_{0} \mathrm{~d} \boldsymbol{\pi} \geq \underset{t \downarrow 0}{\limsup } \int\left|G_{t}(\gamma)+\epsilon F_{t}(\gamma)\right|^{2} \mathrm{~d} \boldsymbol{\pi}(\gamma) \tag{6.17}
\end{equation*}
$$

Subtracting to (6.17) the equality (6.15) and dividing by $\epsilon$ gives

$$
\begin{align*}
\limsup _{t \downarrow 0} \int G_{t} F_{t} \mathrm{~d} \boldsymbol{\pi} & \leq \liminf _{\epsilon \downarrow 0} \int_{X} \frac{\left|D\left(\varphi+\epsilon \log f_{\delta, n}\right)\right|_{w}^{2}-|D \varphi|_{w}^{2}}{2 \epsilon} f_{\delta, n} \mathrm{dm}  \tag{6.18}\\
& =\varepsilon_{\eta_{\delta, n}}\left(\log f_{\delta, n}, \varphi\right),
\end{align*}
$$

where we again used the uniform bound on the $L^{2}$ norm of $F_{t}$. Combining (6.16) and (6.18) we obtain

$$
\begin{equation*}
\liminf _{t \downarrow 0} \frac{\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right)-\operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta, n}\right)}{t} \geq-\varepsilon_{\eta_{\delta, n}}\left(\log f_{\delta, n}, \varphi\right) . \tag{6.19}
\end{equation*}
$$

The conclusion follows by (6.19) recalling that, by construction, the entropy is $K$-convex along the geodesic $\left(\mu_{t}\right)_{t \in[0,1]}$; see (4.1).

Proof of Theorem 6.5, In this proof we denote for brevity $a \vee b=\max \{a, b\}$. For every $\delta \in(0,1)$ define the density

$$
\begin{equation*}
\tilde{f}_{\delta}:=f \vee\left(\delta \mathrm{e}^{-2 c V^{2}}\right) \quad \text { and } f_{\delta}:=c_{\delta} \tilde{f}_{\delta} \text { with } c_{\delta} \uparrow 1 \text { as } \delta \downarrow 0 \tag{6.20}
\end{equation*}
$$

(here $c>0$ is the constant in (2.3)), so that $\tilde{f}_{\delta} \geq f$ and $c_{\delta}$ are the normalizing constants. We need a further regularization of $f_{\delta}$; to this aim, let $\chi_{n}$ be standard cut-off functions, namely $0 \leq \chi_{n} \leq 1, \operatorname{Lip}\left(\chi_{n}\right) \leq 1, \chi_{n} \equiv 1$ on $B_{n}\left(x_{0}\right)$ and $\chi_{n} \equiv 0$ on $B_{2 n}^{c}\left(x_{0}\right)$. Then, for every $n>1, \delta>0$ we define the densities
(6.21) $\tilde{f}_{\delta, n}:=\left(\chi_{n}^{2} f\right) \vee\left(\delta \mathrm{e}^{-2 c V^{2}}\right) \quad$ and $f_{\delta, n}:=c_{\delta, n} \tilde{f}_{\delta, n}$ with $c_{\delta, n} \downarrow c_{\delta}$ as $n \rightarrow \infty$,
so that $\tilde{f}_{\delta, n} \leq \tilde{f}_{\delta}$ and $c_{\delta, n}$ are the normalizing constants. Of course $f_{\delta, n}$ is uniformly bounded and $\eta_{\delta, n}:=f_{\delta, n} \mathfrak{m} \in \mathscr{P}_{2}(X)$; moreover $\mathrm{Ch}\left(\sqrt{f_{\delta, n}}\right)$ is finite. Indeed by the chain rule and the locality of the weak gradients we have that

$$
\begin{aligned}
\left|D \sqrt{f_{\delta, n}}\right|_{w} & =\sqrt{c_{\delta, n}}\left|D\left(\chi_{n} \sqrt{f}\right)\right|_{w} \\
& \leq \sqrt{c_{\delta, n}}\left(\chi_{n}|D \sqrt{f}|_{w}+\sqrt{f}\left|D \chi_{n}\right|_{w}\right) \quad \text { if } \chi_{n}^{2} f \geq \delta \mathrm{e}^{-2 c V^{2}}, \\
\left|D \sqrt{f_{\delta, n}}\right|_{w} & =\sqrt{\delta c_{\delta, n}}\left|D \mathrm{e}^{-2 c V^{2}}\right|_{w} \\
& \leq 4 c \sqrt{\delta c_{\delta, n}} \mathrm{~d}\left(\cdot, x_{0}\right) e^{-2 c V^{2}} \quad \text { otherwise. }
\end{aligned}
$$

Since by assumption $\mathrm{Ch}(\sqrt{f})<\infty$, it follows not only that $\left|D \sqrt{f_{\delta, n}}\right|_{w}^{2}$ are uniformly bounded in $L^{1}(X, \mathfrak{m})$, but also that they are equi-integrable:

$$
\begin{equation*}
\sup _{\delta \in(0,1), n \in \mathbb{N}} \operatorname{Ch}\left(\sqrt{f_{\delta, n}}\right)<\infty \quad \text { and } \quad E_{j} \downarrow \emptyset \Rightarrow \sup _{\delta \in(0,1), n \in \mathbb{N}} \int_{E_{j}}\left|D \sqrt{f_{\delta, n}}\right|_{w}^{2} \mathrm{~d} \mathfrak{m} \rightarrow 0 \tag{6.22}
\end{equation*}
$$

Observe that $\left(\eta_{\delta, n}, \sigma\right)$ has the structure described in Proposition 6.6, so there exists a Kantorovich potential $\varphi_{\delta, n}$ from $\eta_{\delta, n}$ to $\sigma$ satisfying the growth conditions (6.8) and such that the entropy inequality holds:

$$
\begin{equation*}
\operatorname{Ent}_{\mathfrak{m}}(\sigma)-\operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta, n}\right)-\frac{K}{2} W_{2}^{2}\left(\eta_{\delta, n}, \sigma\right) \geq-\varepsilon_{\eta_{\delta, n}}\left(\varphi_{\delta, n}, \log f_{\delta, n}\right) \tag{6.23}
\end{equation*}
$$

Passage to the limit as $n \rightarrow \infty$. Consider the transportation problem from $\eta_{\delta}:=f_{\delta} \mathfrak{m}$ to $\sigma$. We claim the existence of a Kantorovich potential $\varphi_{\delta}$ such that

$$
\begin{equation*}
\operatorname{Ent}_{\mathfrak{m}}(\sigma)-\operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta}\right)-\frac{K}{2} W_{2}^{2}\left(\eta_{\delta}, \sigma\right) \geq-\mathcal{E}_{\eta_{\delta}}\left(\varphi_{\delta}, \log f_{\delta}\right) \tag{6.24}
\end{equation*}
$$

We would like to pass to the limit as $n \rightarrow \infty$ in (6.23). Let us start by considering the left hand side: applying Lemma 5.1 to $\tilde{\eta}_{\delta, n} \uparrow \tilde{\eta}_{\delta} \mathfrak{m}$-a.e, and recalling that $c_{\delta, n} \downarrow c_{\delta}$ as $n \rightarrow \infty$, we get

$$
\begin{equation*}
\operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta, n}\right) \rightarrow \operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta}\right) \quad \text { as } n \rightarrow \infty . \tag{6.25}
\end{equation*}
$$

It is easy to check that $\eta_{\delta, n}$ weakly converge to $\eta_{\delta}$ and have uniformly integrable 2-moments, so by [2, Proposition 7.1.5] we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty} W_{2}^{2}\left(\eta_{\delta, n}, \sigma\right)=W_{2}^{2}\left(\eta_{\delta}, \sigma\right) \tag{6.26}
\end{equation*}
$$

Now let us show the convergence of the right hand side of (6.23). To simplify the problem we prove first that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left|\mathcal{E}_{\eta_{\delta, n}}\left(\varphi_{\delta, n}, \log f_{\delta, n}\right)-\frac{c_{\delta, n}}{c_{\delta}} \mathcal{E}_{\eta_{\delta}}\left(\varphi_{\delta, n}, \log f_{\delta}\right)\right|=0 \tag{6.27}
\end{equation*}
$$

Notice that, saying $A_{\delta}:=\left\{x \in X: f(x) \geq \delta \mathrm{e}^{-2 c V^{2}(x)}\right\}$, we have $f_{\delta, n}=\frac{c_{\delta, n}}{c_{\delta}} f_{\delta}$ on the complement $\left(A_{\delta} \cap B_{n}\left(x_{0}\right)\right) \cup A_{\delta}^{c}$ of $A_{\delta} \backslash B_{n}\left(x_{0}\right)$. Since $A_{\delta} \backslash B_{n}\left(x_{0}\right) \downarrow \emptyset$ we can use (5.17) of Lemma (5.4) to obtain (6.27), taking (6.22) into account.

From (6.27), and taking into account that $c_{\delta, n} \rightarrow c_{\delta}$ as $n \rightarrow \infty$, in order to prove the convergence of the right hand side of (6.23), it is enough to show the existence of a Kantorovich potential $\varphi_{\delta}$ for $\left(\eta_{\delta}, \sigma\right)$ such that

$$
\begin{equation*}
\mathcal{E}_{\eta_{\delta}}\left(\varphi_{\delta, n}, \log f_{\delta}\right) \rightarrow \mathcal{E}_{\eta_{\delta}}\left(\varphi_{\delta}, \log f_{\delta}\right) \quad \text { as } n \rightarrow \infty \tag{6.28}
\end{equation*}
$$

Now we use in a crucial way Lemma 2.3, which ensures the existence of a Kantorovich potential $\varphi_{\delta}$ for $\left(\eta_{\delta}, \sigma\right)$ and of a subsequence $n(k)$ such that $\varphi_{\delta, n(k)} \rightarrow \varphi_{\delta}$
pointwise in $X$. Recalling that $\left|\varphi_{\delta, n}\right| \leq C\left(1+V^{2}\right)$ and that $\int\left|D \varphi_{\delta, n}\right|_{w}^{2} \mathrm{~d} \eta_{\delta}$ is uniformly bounded, we are in a position to apply Lemma 5.3 and to conclude that (6.28) holds. Therefore we proved the convergence of all terms in (6.23), so that (6.24) holds.

Passage to the limit as $\delta \downarrow 0$. The inequality (6.24) passes to the limit as $\delta \downarrow 0$ : more precisely, we claim the existence of a Kantorovich potential $\varphi$ from $f \mathfrak{m}$ to $\sigma$ such that

$$
\begin{equation*}
\operatorname{Ent}_{\mathfrak{m}}(\sigma)-\operatorname{Ent}_{\mathfrak{m}}(\eta)-\frac{K}{2} W_{2}^{2}(\eta, \sigma) \geq-\varepsilon_{\eta}(\varphi, \log f) \tag{6.29}
\end{equation*}
$$

As in the passage to the limit as $n \rightarrow \infty$, Lemma 5.1 easily implies that $\operatorname{Ent}_{\mathfrak{m}}\left(\eta_{\delta}\right) \rightarrow$ $\operatorname{Ent}_{\mathfrak{m}}(\eta)$; moreover it is easy to check that $\eta_{\delta}$ weakly converge to $\eta$ and have uniformly integrable 2-moments, so [2, Proposition 7.1.5] gives $W_{2}\left(\eta_{\delta}, \sigma\right) \rightarrow W_{2}(\eta, \sigma)$. In order to show the convergence of the right hand side of (6.29) we first prove that

$$
\begin{equation*}
\lim _{\delta \downarrow 0}\left|\varepsilon_{\eta_{\delta}}\left(\varphi_{\delta}, \log f_{\delta}\right)-c_{\delta} \varepsilon_{\eta}\left(\varphi_{\delta}, \log f\right)\right|=0 . \tag{6.30}
\end{equation*}
$$

First of all notice that, after calling $A_{\delta}:=\left\{x \in X: f(x) \geq \delta \mathrm{e}^{-2 c V^{2}(x)}\right\}$, we have $f_{\delta}=c_{\delta} f$ on $A_{\delta}$. Since $X \backslash A_{\delta} \downarrow\{f=0\}$ as $\delta \downarrow 0$ and $|D f|_{w}=0 \mathfrak{m}$-a.e. on $\{f=0\}$, we can use (5.17) of Lemma 5.4 to show (6.30), taking (6.22) into account.

Now that (6.30) is proved, taking into account that $c_{\delta} \rightarrow 1$ as $\delta \downarrow 0$, it is enough to prove the existence of a Kantorovich potential $\varphi$ from $\eta$ to $\sigma$ such that

$$
\begin{equation*}
\lim _{i \rightarrow \infty} \varepsilon_{\eta}\left(\varphi_{\delta_{i}}, \log f\right)=\varepsilon_{\eta}(\varphi, \log f) \tag{6.31}
\end{equation*}
$$

for some sequence $\delta_{i} \downarrow 0$. Recall that $\varphi_{\delta}$ were constructed using Lemma 2.3 so they still satisfy the growth condition (6.8); again applying Lemma [2.3 we get the existence of a Kantorovich potential $\varphi$ from $\eta$ to $\sigma$ and $\delta_{i} \downarrow 0$ such that $\varphi_{\delta_{i}} \rightarrow \varphi$ pointwise in $X$ as $i \rightarrow \infty$. Moreover, by (2.12) and $f \leq c_{\delta}^{-1} f_{\delta} \leq 2 f_{\delta}$ for $\delta$ small enough, we have

$$
\int_{X}\left|D \varphi_{\delta_{i}}\right|_{w}^{2} f \mathrm{~d} \mathfrak{m} \leq 2 \int_{X}\left|D \varphi_{\delta_{i}}\right|_{w}^{2} f_{\delta_{i}} \mathrm{~d} \mathfrak{m} \leq 2 W_{2}^{2}\left(\eta_{\delta_{i}}, \sigma\right)
$$

for $i$ large enough. Hence we can apply Lemma 5.3 and conclude that (6.31) holds. Therefore (6.29) is proved and the proof of Theorem 6.5 is then complete.
6.3. Proof of Theorem 6.1, The implications from (i) to (ii) and from (iii) to (i) can be proven exactly as in Theorem 5.1 of 4] (as these proofs need no finiteness assumption on $\mathfrak{m}$ ), so let us focus on the implication from (ii) to (iii). Note that Sturm has proven in 32 (see Remark 4.6 (iii) therein) that supp $\mathfrak{m}$ is a length space for all $C D(K, \infty)$ spaces ( $X, \mathrm{~d}, \mathfrak{m}$ ) (his proof, based on an approximate midpoint construction, does not use the local compactness).

It remains to show that the $E V I_{K}$-condition holds assuming the $C D(K, \infty)$ condition and the fact that Ch is quadratic. By the contractivity properties of $E V I_{K}$-gradient flows stated in Proposition 2.6 it is sufficient to show that $\mu_{t}:=$ $\left(\mathrm{h}_{t} f\right) \mathfrak{m}$ is an $E V I_{K}$ gradient flow for Ent $_{\mathfrak{m}}$ for any initial measure $f \mathfrak{m} \in \mathscr{P}_{2}(X)$ whose density $f$ is bounded and satisfies $\mathrm{Ch}(\sqrt{f})<\infty$. By the maximum principle proven in [3] (see Theorem 4.20 therein) one has $\mathrm{h}_{t} f \leq\|f\|_{L^{\infty}(X, \mathfrak{m})} \mathfrak{m}$-a.e. in $X$ for all $t \geq 0$; furthermore $\left\{\mu_{t}: t \in[0, T]\right\}$ is a bounded subset of $\mathscr{P}_{2}(X)$ for all $T>0$
and (6.2) gives

$$
\begin{equation*}
\int_{0}^{\infty} \mathrm{Ch}\left(\sqrt{\mathrm{~h}_{t} f}\right) \mathrm{d} t<\infty \tag{6.32}
\end{equation*}
$$

By a simple density argument on the class of "test" measures $\sigma$ in (1.1) (see for instance [4, Proposition 2.20]), we can restrict ourselves to measures $\sigma$ of the form $g \mathfrak{m}$ with $g \in L^{\infty}(X, \mathfrak{m})$ and supp $\sigma$ compact.

By (6.3) of Theorem 6.3) we get that for a.e. $t>0$, for any choice of a Kantorovich potential $\varphi_{t}$ from $\mu_{t}$ to $\sigma$ whose slope has linear growth, one has

$$
\begin{equation*}
\frac{\mathrm{d}}{\mathrm{~d} t} \frac{1}{2} W_{2}^{2}\left(\mu_{t}, \sigma\right)=-\varepsilon_{\mu_{t}}\left(\varphi_{t}, \log \mathrm{~h}_{t} f\right) \tag{6.33}
\end{equation*}
$$

Therefore, to conclude that (1.1) holds, it suffices to show for a.e. $t>0$ the existence of a Kantorovich potential $\varphi_{t}$ from $\mu_{t}$ to $\sigma$ whose slope has linear growth and satisfies

$$
\begin{equation*}
-\varepsilon_{\mu_{t}}\left(\varphi_{t}, \log \mathrm{~h}_{t} f\right) \leq \operatorname{Ent}_{\mathfrak{m}}(\sigma)-\operatorname{Ent}_{\mathfrak{m}}\left(\mu_{t}\right)-\frac{K}{2} W_{2}^{2}\left(\mu_{t}, \sigma\right) \tag{6.34}
\end{equation*}
$$

This is precisely the statement of Theorem 6.5 (with $\eta=\mu_{t}$ ), and this concludes the proof.

## 7. Properties of $R C D(K, \infty)$ spaces

In this section we state without proof some properties of $R C D(K, \infty)$ spaces whose proofs are given by the first two authors and Savaré in [4. Their proofs do not rely on the finiteness assumption of $\mathfrak{m}$. Refer to [4] for details of the proofs and a more complete discussion.
7.1. The heat semigroup and its regularizing properties. In this section we describe in more detail the properties of the $L^{2}$-semigroup $\mathrm{h}_{t}$ in an $R C D(K, \infty)$ space and the additional information that one can obtain from the identification with $W_{2}$-semigroup $\mathscr{H}_{t}$. By the definition of $R C D(K, \infty)$ spaces, we know that for any $x \in X$ there exists a unique $E V I_{K}$ gradient flow $\mathscr{H}_{t}\left(\delta_{x}\right)$ of $E n t_{\mathfrak{m}}$ starting from $\delta_{x}$ and related to $\mathrm{h}_{t}$ by

$$
\begin{equation*}
\left(\mathrm{h}_{t} f\right) \mathfrak{m}=\int f(x) \mathscr{H}_{t}\left(\delta_{x}\right) \mathrm{d} \mathfrak{m}(x) \quad \forall f \in L^{2}(X, \mathfrak{m}) \tag{7.1}
\end{equation*}
$$

Since $\operatorname{Ent}_{\mathfrak{m}}\left(\mathscr{H}_{t}\left(\delta_{x}\right)\right)<\infty$ for any $t>0$, one has $\mathscr{H}_{t}\left(\delta_{x}\right) \ll \mathfrak{m}$, so that $\mathscr{H}_{t}\left(\delta_{x}\right)$ has a density, that we shall denote by $\rho_{t}[x]$. The functions $\rho_{t}[x](y)$ are the socalled transition probabilities of the semigroup. By standard measurable selection arguments we can choose versions of these densities in such a way that the map $(x, y) \mapsto \rho_{t}[x](y)$ is $\mathfrak{m} \times \mathfrak{m}$-measurable for all $t>0$.

In the next theorem we prove additional properties of the flows. The information on both benefits from the identification theorem: for instance the symmetry property of transition probabilities is not at all obvious when looking at $\mathscr{H}_{t}$ only from the optimal transport point of view, and heavily relies on (7.1). On the other hand, the regularizing properties of $\mathrm{h}_{t}$ are deduced by duality by those of $\mathscr{H}_{t}$, using in particular the contractivity estimate

$$
\begin{equation*}
W_{2}\left(\mathscr{H}_{t}(\mu), \mathscr{H}_{t}(\nu)\right) \leq e^{-K t} W_{2}(\mu, \nu), \quad t \geq 0, \mu, \nu \in \mathscr{P}_{2}(X, \mathfrak{m}) \tag{7.2}
\end{equation*}
$$

and the regularization estimates for the Entropy and its slope

$$
\begin{equation*}
\mathrm{I}_{K}(t) \operatorname{Ent}_{\mathfrak{m}}\left(\mathscr{H}_{t}(\mu)\right)+\frac{\left(\mathrm{I}_{K}(t)\right)^{2}}{2}\left|D^{-} \operatorname{Ent}_{\mathfrak{m}}\right|^{2}\left(\mathscr{H}_{t}(\mu)\right) \leq \frac{1}{2} W_{2}^{2}(\mu, \mathfrak{m}) \tag{7.3}
\end{equation*}
$$

which are typical of $E V I_{K}$-solutions, with $\mathrm{I}_{K}(t):=\int_{0}^{t} \mathrm{e}^{K r} \mathrm{~d} r$. Notice also that (7.2) yields $W_{1}\left(\mathscr{H}_{t}\left(\delta_{x}\right), \mathscr{H}_{t}\left(\delta_{y}\right)\right) \leq \mathrm{e}^{-K t} \mathrm{~d}(x, y)$ for all $x, y \in X$ and $t \geq 0$. This implies that $R C D(K, \infty)$ spaces have Ricci curvature bounded from below by $K$ according to the $W_{1}$-contractivity property taken as a definition in Ollivier [26] and Joulin 22].

Theorem 7.1 (Regularizing properties of the heat flow; Theorem 6.1 in [4). Let $(X, \mathrm{~d}, \mathfrak{m})$ be a $R C D(K, \infty)$ space. Then:
(i) The transition probability densities are symmetric,

$$
\begin{equation*}
\rho_{t}[x](y)=\rho_{t}[y](x) \quad \mathfrak{m} \times \mathfrak{m} \text {-a.e. in } X \times X, \text { for all } t>0, \tag{7.4}
\end{equation*}
$$

and satisfy for all $x \in X$ the Chapman-Kolmogorov formula
$\rho_{t+s}[x](y)=\int \rho_{t}[x](z) \rho_{s}[z](y) \mathrm{d} \mathfrak{m}(z) \quad$ for $\mathfrak{m}$-a.e. $y \in X$, for all $t, s \geq 0$.
(ii) The formula

$$
\begin{equation*}
\tilde{\mathrm{h}}_{t} f(x):=\int f(y) \mathrm{d} \mathscr{H}_{t}\left(\delta_{x}\right)(y), \quad x \in X \tag{7.6}
\end{equation*}
$$

provides a version of $\mathrm{h}_{t} f$ for every $f \in L^{2}(X, \mathfrak{m})$, an extension of $\mathrm{h}_{t}$ to a continuous contraction semigroup in $L^{1}(X, \mathfrak{m})$ which is pointwise everywhere defined if $f \in L^{\infty}(X, \mathfrak{m})$.
(iii) The semigroup $\tilde{\mathrm{h}}_{t}$ maps contractively $L^{\infty}(X, \mathfrak{m})$ in $C_{b}(X)$ and, in addition, $\tilde{\mathrm{h}}_{t} f(x)$ belongs to $C_{b}((0, \infty) \times X)$.
(iv) If $f: X \rightarrow \mathbb{R}$ is Lipschitz, then $\tilde{\mathrm{h}}_{t} f$ is Lipschitz on $X$ as well and $\operatorname{Lip}\left(\tilde{\mathrm{h}}_{t} f\right) \leq$ $e^{-K t} \operatorname{Lip}(f)$.

Theorem 7.2 (Bakry-Émery in $R C D(K, \infty)$ spaces; Theorem 6.2 in [4]). For any $f \in L^{2}(X, \mathfrak{m}) \cap S^{2}$ and $t>0$ we have

$$
\begin{equation*}
\left|D\left(\mathrm{~h}_{t} f\right)\right|_{w}^{2} \leq \mathrm{e}^{-2 K t} \mathrm{~h}_{t}\left(|D f|_{w}^{2}\right) \quad \mathfrak{m} \text {-a.e. in } X . \tag{7.7}
\end{equation*}
$$

In addition, if $|D f|_{w} \in L^{\infty}(X, \mathfrak{m})$ and $t>0$, then $\mathrm{e}^{-K t}\left(\tilde{\mathrm{~h}}_{t}|D f|_{w}^{2}\right)^{1 / 2}$ is an upper gradient of $\tilde{\mathrm{h}}_{t} f$ on $X$, so that

$$
\begin{equation*}
\left|D^{-} \tilde{\mathrm{h}}_{t} f\right| \leq \mathrm{e}^{-K t}\left(\tilde{\mathrm{~h}}_{t}|D f|_{w}^{2}\right)^{1 / 2} \quad \text { pointwise in } X \tag{7.8}
\end{equation*}
$$

and $f$ has a Lipschitz version $\tilde{f}: X \rightarrow \mathbb{R}$, with $\operatorname{Lip}(\tilde{f}) \leq\left\||D f|_{w}\right\|_{\infty}$.
The regularization properties (7.3) of $E V I_{K}$-flows provide an $L \log L$ regularization of the semigroup $\mathscr{H}_{t}$ starting from arbitrary measures in $\mathscr{P}_{2}(X)$. When $X$ is an $R C D(K, \infty)$-space with $K>0$, then combining the slope inequality for $K$-geodesically convex functionals [2, Lemma 2.4.13]

$$
\operatorname{Ent}_{\mathfrak{m}}(\mu) \leq \frac{1}{2 K}\left|D^{-} \operatorname{Ent}_{\mathfrak{m}}\right|^{2}(\mu)
$$

with the identity $\left|D^{-} \operatorname{Ent}_{\mathfrak{m}}\right|^{2}(f \mathfrak{m})=\int|D f|_{w}^{2} / f \mathrm{dm}$ between slope and Fisher information, we get the Logarithmic-Sobolev inequality

$$
\begin{equation*}
\int_{X} f \log f \mathrm{~d} \mathfrak{m} \leq \frac{1}{2 K} \int_{f>0} \frac{|D f|_{w}^{2}}{f} \mathrm{~d} \mathfrak{m} \quad \text { if } \sqrt{f} \in W^{1,2}(X, \mathrm{~d}, \mathfrak{m}), f \mathfrak{m} \in \mathscr{P}(X), \tag{7.9}
\end{equation*}
$$

which in particular yields the hypercontractivity of $h_{t}$; see e.g. 7. When $h_{t}$ is ultracontractive, i.e. there exists $p>1$ such that

$$
\begin{equation*}
\left\|\mathrm{h}_{t} f\right\|_{p} \leq C(t)\|f\|_{1} \quad \text { for every } f \in L^{2}(X, \mathfrak{m}), t>0 \tag{7.10}
\end{equation*}
$$

then one can also obtain global Lipschitz regularity for the transition probabilities [4, Proposition 6.4]; see also [18, Proposition 4.4]. The stronger regularizing property (7.10) is known to be true, for instance, if doubling and Poincaré hold in ( $X, \mathrm{~d}, \mathfrak{m}$ ); see [31, Corollary 4.2].

We conclude this section with an example of the application of the Bakry-Émery estimate (7.2), which can be proven following the $\Gamma$-calculus tools of Bakry [8]; see Theorem 6.5 in $[4$ for a detailed proof.

Theorem 7.3 (Lipschitz regularization). If $f \in L^{2}(X, \mathfrak{m})$, then $\mathrm{h}_{t} f \in \mathcal{S}^{2}$ for every $t>0$ and

$$
\begin{equation*}
2 \mathrm{I}_{2 K}(t)\left|D \mathrm{~h}_{t} f\right|_{w}^{2} \leq \mathrm{h}_{t} f^{2} \quad \mathfrak{m} \text {-a.e. in } X \tag{7.11}
\end{equation*}
$$

in particular, if $f \in L^{\infty}(X, \mathfrak{m})$, then $\tilde{\mathrm{h}}_{t} f \in \operatorname{Lip}(X)$ for every $t>0$ with

$$
\begin{equation*}
\sqrt{2 \mathrm{I}_{2 K}(t)} \operatorname{Lip}\left(\tilde{\mathrm{h}}_{t} f\right) \leq\|f\|_{\infty} \quad \text { for every } t>0 \tag{7.12}
\end{equation*}
$$

7.2. Connections with Dirichlet forms and Markov processes. Since Ch is quadratic, lower semicontinuous in $L^{2}(X, \mathfrak{m})$ and since $|D f|_{w}$ has strong locality properties, it turns out that the bilinear form $\mathcal{E}$ associated to Ch , whose domain is from now on restricted from $L^{1}(X, \mathfrak{m}) \cap \mathcal{S}^{2}$ to $L^{2}(X, \mathfrak{m}) \cap \delta^{2}$, is a local Dirichlet form. In the theory of Dirichlet forms a canonical object is the induced distance, namely

$$
\begin{equation*}
\mathrm{d}_{\mathcal{E}}(x, y):=\sup \{|\tilde{g}(x)-\tilde{g}(y)|: g \in D(\mathcal{E}),[g] \leq \mathfrak{m}\} \quad \forall(x, y) \in X \times X \tag{7.13}
\end{equation*}
$$

where the function $\tilde{g}$ is the continuous representative in the Lebesgue class of $g$; see Theorem [7.2. Another canonical object is the local energy measure, namely the measure [u] defined by

$$
[u](\varphi):=\mathcal{E}(u, u \varphi)-\frac{1}{2} \mathcal{E}\left(u^{2}, \varphi\right), \quad \varphi \in L^{2}(X, \mathfrak{m}) \cap \mathcal{S}^{2}
$$

A consequence of Lemma 3.8 is that $[u]=|D u|_{w}^{2} \mathfrak{m}$ for all $u \in L^{2}(X, \mathfrak{m}) \cap \mathcal{S}^{2}$. Also the distances can be identified:

Theorem 7.4 (Identification of $\mathrm{d}_{\varepsilon}$ and d ; Theorem 6.10 of [4]). The function $\mathrm{d}_{\varepsilon}$ in (7.13) coincides with d on $X \times X$.

Finally, using a tightness property of $\mathcal{\varepsilon}$, the theory of Dirichlet forms can be applied to obtain the representation of transition probabilities in terms of a continuous Markov process:

Theorem 7.5 (Brownian motion; Theorem 6.8 of [4). Let ( $X, \mathrm{~d}, \mathfrak{m}$ ) be an $R C D(K, \infty)$ space. There exists a unique (in law) Markov process $\left\{\mathbf{X}_{t}\right\}_{\{t \geq 0\}}$ in
$(X, \mathrm{~d})$ with continuous sample paths in $[0, \infty)$ and transition probabilities $\mathscr{H}_{t}\left(\delta_{x}\right)$, i.e.

$$
\begin{equation*}
\mathbf{P}\left(\mathbf{X}_{s+t} \in A \mid \mathbf{X}_{s}=x\right)=\mathscr{H}_{t}\left(\delta_{x}\right)(A) \quad \forall s, t \geq 0, A \text { Borel } \tag{7.14}
\end{equation*}
$$

for $\mathfrak{m}$-a.e. $x \in X$.
7.3. Tensorization. Recall that a metric space $(X, \mathrm{~d})$ is said to be nonbranching if the map $\left(\mathrm{e}_{0}, \mathrm{e}_{t}\right): \operatorname{Geo}(X) \rightarrow X^{2}$ is injective for all $t \in(0,1)$, i.e., geodesics do not split.

Theorem 7.6 (Tensorization; Theorem 6.13 of [4). Let $\left(X, \mathrm{~d}_{X}, \mathfrak{m}_{X}\right)$, $\left(Y, \mathrm{~d}_{Y}, \mathfrak{m}_{Y}\right)$ be metric measure spaces and define the product space $(Z, \mathrm{~d}, \mathfrak{m})$ as $Z:=X \times Y$, $\mathfrak{m}:=\mathfrak{m}_{X} \times \mathfrak{m}_{Y}$ and

$$
\mathrm{d}\left((x, y),\left(x^{\prime}, y^{\prime}\right)\right):=\sqrt{\mathrm{d}_{X}^{2}\left(x, x^{\prime}\right)+\mathrm{d}_{Y}^{2}\left(y, y^{\prime}\right)} .
$$

Assume that both $\left(X, \mathrm{~d}_{X}, \mathfrak{m}_{X}\right)$ and $\left(Y, \mathrm{~d}_{Y}, \mathfrak{m}_{Y}\right)$ are $R C D(K, \infty)$ and nonbranching. Then $(Z, \mathrm{~d}, \mathfrak{m})$ is $R C D(K, \infty)$ and nonbranching as well.

In [6] the first two authors in collaboration with Savaré proved that the tensorization property of $R C D(K, \infty)$ persists even when the nonbranching assumption on the base spaces is removed.

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Dipartimento di Matematica, Scuola Normale Superiore, Pisa, Italy
E-mail address: luigi.ambrosio@sns.it
Département de Mathématiques, University of Nice, Nice, France
E-mail address: ngigli@sissa.it
Dipartimento di Matematica, Scuola Normale Superiore, Pisa, Italy
E-mail address: andrea.mondino@math.ethz.ch
Department of Mathematics, University of Jyväskylä, FI-40014 Jyväskylä, Finland
E-mail address: tapio.m.rajala@jyu.fi


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