

Rough Membership Functions

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Abstract. A variety of numerical approaches for reasoning with uncertainty have been investigated in the literature. We propose *rough membership functions*, rm-functions, for short, as a basis for such reasoning. These functions have values in the interval [0,1] of the real numbers and they are computable on the basis of the observable information about the objects rather than on the objects themselves. We investigate properties of the rm-functions. In particular we show that our approach is intensional with respect to the class of all information systems [P91]. As a consequence we point out some differences between the rm-functions and the fuzzy membership functions [Z65], e.g. the rm-function values for $X \cup Y$ ($X \cap Y$) cannot be computed in general by applying the operation \max (\min) to the rm-function values for X and Y . We propose the algorithm for computing the rm-functions for the sets from a given field of sets.

Key words: reasoning with incomplete information, rough sets, fuzzy sets, evidence theory.

1. Introduction

One of the fundamental problem studied in artificial intelligence is related to the object classification that is the problem of associating a particular object to one of many predefined sets. We study that problem. Our approach is based on the observation that the classification of objects is performed on the basis of the accessible information about them. Objects with the same accessible information will be considered as indiscernible [P91]. Therefore we are faced with the problem of determining whether or not an object belongs to a given set when only some properties (i.e. attribute values) of the object are accessible.

We introduce the rough membership function (rm-functions, for short) which allow us to measure the degree with which any object with given attribute values belongs to a given set X . The information about objects is stored in data tables called information systems [P91]. Any rm-function μ_X^A is defined relatively to a given information system A and a given set X of objects.

The paper is structured as follows.

Section 2 contains a brief discussion of information systems [P91], information functions [Sk91] and rough sets [P91]. In Section 3 we define a partition of boundary regions [S91] and we present some basic properties of this partition, which we apply latter.

In Section 4 we define the *rm*-functions and we study their basic properties.

In Section 5 we present formulas for computing the *rm*-function values $\mu_{XUY}^A(x)$ and $\mu_{X\cap Y}^A(x)$ from the values $\mu_X^A(x)$ and $\mu_Y^A(x)$ (when it is possible, i.e. when classified objects are not in a particular boundary region) if information encoded in the information system A is accessible. In the construction of those formulas we apply a partition of boundary regions related to X and Y defined in Section 3. One can interpret that result as follows: the computation of *rm*-function values $\mu_{XUY}^A(x)$ and $\mu_{X\cap Y}^A(x)$ (if one exclude a particular boundary region !) is *extensional* under the condition that the information system is fixed.

We show also, in Section 5, that our approach is *intensional* with respect to the set of all information systems (with a universe including sets X and Y), namely it is not possible, in general, to compute the *rm*-function values $\mu_{XUY}^A(x)$ and $\mu_{X\cap Y}^A(x)$ from the values $\mu_X^A(x)$ and $\mu_Y^A(x)$ when information about A is not accessible (Theorem 3).

In Section 5 we specify the maximal classes of information systems such that the computation of *rm*-function values for union and intersection is *extensional* when related to those classes, and is defined by the operations *min* and *max* (as in the fuzzy set approach [Z65, DP80]), i.e. the values $\mu_{XUY}^A(x)$ and $\mu_{X\cap Y}^A(x)$ are obtained by applying the operation *min* and the operation *max* to the values $\mu_X^A(x)$ and $\mu_Y^A(x)$, respectively (if A belongs to those maximal classes).

In Section 6 we present an algorithm for computing the *rm*-function values $\mu_X^A(x)$ for $x \in X$, where X is any set generated by the set theoretical operations $\cup, \cap, -$ from a given family of finite sets.

2. Information systems and rough sets

Information systems (sometimes called data tables, attribute-value systems, condition-action tables etc.) are used for representing knowledge. The information system notion presented here is due to Pawlak and was investigated by several researchers (see the references in [P91]).

The rough sets have been introduced as a tool to deal with inexact, uncertain or vague knowledge in artificial intelligence applications, like for example knowledge based systems in medicine, natural language processing, pattern recognition, decision systems, approximate reasoning. Since 1982 the rough sets have been intensively studied and by now many practical applications based on the theory of rough sets have been implemented.

In this section we present some basic notions related to information systems and rough sets which will be necessary for understanding our results.

An information system is a pair $A = (U, A)$, where

U - a non-empty, finite set called the universe and

A - a nonempty, finite set of attributes i.e.

$$a: U \rightarrow V_a \text{ for } a \in A,$$

where V_a is called the value set of a .

With every subset of attributes $B \subseteq A$ we associate a binary relation $IND(B)$, called B -indiscernibility relation, and defined as follows:

$$IND(B) = \{(x, y) \in U^2 : \text{for every } a \in B, a(x) = a(y)\}.$$

By $[x]_{IND(B)}$ or $[x]_B$ we denote the equivalence class of the equivalence relation $IND(B)$ generated by x , i.e. the set $\{y \in U : x IND(B) y\}$.

We have that

$$IND(B) = \bigcap_{a \in B} IND(a).$$

If $x IND(B) y$ then we say that the objects x and y are indiscernible with respect to attributes from B . In other words, we cannot distinguish x from y in terms of attributes in B .

Some subsets of objects in an information system cannot be expressed exactly in terms of the available attributes, they can be only roughly defined.

If $A=(U,A)$ is an information system, $B \subseteq A$ and $X \subseteq U$ then the sets

$$\underline{B}X = \{x \in U: [x]_B \subseteq X\} \text{ and } \overline{B}X = \{x \in X: [x]_B \cap X \neq \emptyset\}$$

are called the B -lower and the B -upper approximation of X in A , respectively.

The set $BN_B(X) = \overline{B}X - \underline{B}X$ will be called the B -boundary of X .

Clearly, $\underline{B}X$ is the set of all elements of U , which can be with certainty classified as elements of X with respect to the values of attributes from B ; and $\overline{B}X$ is the set of those elements of U which can be possibly classified as elements of X with respect of the values of the attributes from B ; finally, $BN_B(X)$ is the set of elements which can be classified neither in X nor in $-X$ on the basis of the values of attributes from B .

A set X is said to be B -definable if $\overline{B}X = \underline{B}X$. It is easy to observe that $\underline{B}X$ is the greatest B -definable set contained in X , whereas $\overline{B}X$ is the smallest B -definable set containing X . One can observe that a set is B -definable iff it is the union of some equivalence classes of the indiscernibility relation $IND(B)$.

By $\mathcal{P}(X)$ we denote the power set of X .

Every information system $A=(U,A)$ determines an information function

$$Inf_A : U \rightarrow \mathcal{P}(A \times \bigcup_{a \in A} V_a)$$

defined as follows:

$$Inf_A(x) = \{(a, a(x)) : a \in A\}.$$

Hence $x IND_A y$ iff $Inf_A(x) = Inf_A(y)$.

We restrict our considerations in the paper to the information functions related to information systems but our results can be extended to the case of more general information functions [Sk91]. One can consider as information function an arbitrary function f defined on the set of objects U with values in some computable set C .

For example, one may take as the set U of objects the set Tot_A of total elements in the Scott information system A [Sc82] and as C a computable (an accessible) subset of the

set D of sentences in \mathbb{A} . The information function f related to C can be defined as follows $f(x) = x \cap C$ for $x \in \text{Tot}_{\mathbb{A}}$.

Every such general information function f defines the indiscernibility relation $\text{IND}(f) \subseteq U \times U$ as follows :

$$x \text{IND}(f) y \quad \text{iff} \quad f(x) = f(y).$$

3. An approximation of classifications

In this section we introduce and study the notion of approximation of classification. It was preliminary considered in [S91, SG91]. The main idea is based on observation that it is possible to classify boundary regions corresponding to sets from a given classification, i.e. a partition of object universe.

Let $\mathbb{A} = (U, \mathcal{A})$ be an information system and let \mathcal{X}, \mathcal{Z} be families of subsets of U such that $\mathcal{Z} \subseteq \mathcal{X}$ and $|\mathcal{Z}| > 1$, where $|\mathcal{Z}|$ denotes the cardinality of \mathcal{Z} . The set

$$\bigcap_{X \in \mathcal{Z}} B_{\mathbb{A}}(X) \cap \bigcap_{X \in \mathcal{X} - \mathcal{Z}} (U - B_{\mathbb{A}}(X))$$

is said to be the \mathcal{Z} -boundary region defined by \mathcal{X} and \mathbb{A} and is denoted by $Bd_{\mathbb{A}}(\mathcal{Z}, \mathcal{X})$.

By $\text{CLASS_APPR}_{\mathbb{A}}(\mathcal{X})$ we denote the set family

$$\{AX : X \in \mathcal{X}\} \cup \{Bd_{\mathbb{A}}(\mathcal{Z}, \mathcal{X}) : \mathcal{Z} \subseteq \mathcal{X} \text{ and } |\mathcal{Z}| > 1\}.$$

From the above definitions we get the following proposition [S91]:

Proposition 1. Let $\mathbb{A} = (U, \mathcal{A})$ be an information system and let \mathcal{X} be a family of pairwise disjoint subsets of U such that $\bigcup \mathcal{X} = U$. Let $\mathcal{Z} \subseteq \mathcal{X}$ and $|\mathcal{Z}| > 1$. Then

- (i) The set $Bd_{\mathbb{A}}(\mathcal{Z}, \mathcal{X})$ is definable in \mathbb{A} ;
- (ii) $\text{CLASS_APPR}_{\mathbb{A}}(\mathcal{X}) - \{\emptyset\}$ is a partition of U ;
- (iii) If $x \in Bd_{\mathbb{A}}(\mathcal{Z}, \mathcal{X})$ then $[x]_{\mathbb{A}} \subseteq \bigcup \mathcal{Z}$;
- (iv) If $x \in Bd_{\mathbb{A}}(\mathcal{Z}, \mathcal{X})$ then for every $X \in \mathcal{X}$ the following equivalence is true:

$$[x]_{\mathbb{A}} \cap X \neq \emptyset \text{ iff } X \in \mathcal{Z};$$

- (v) The following equality holds:

$$\underline{A}(\bigcup \mathcal{Y}) = \bigcup_{X \in \mathcal{Y}} AX \cup \bigcup_{\substack{|\mathcal{Z}| > 1 \\ \mathcal{Z} \subseteq \mathcal{Y}}} Bd_{\mathbb{A}}(\mathcal{Z}, \mathcal{X}), \text{ where } \mathcal{Y} \subseteq \mathcal{X}.$$

(\supseteq) Let $x \in A \cup Y$, i.e. $[x] \subseteq A \cup Y$. If $x \notin X$ for $X \in Y$ then let $Z_x = \{X \in Y : [x]_A \cap X \neq \emptyset\}$. Hence $|Z_x| > 1$ and $[x]_A \subseteq \bigcup Z_x$. Thus, we have $x \in Bd_A(Z_x, X)$.

□

4. Rough membership functions - definition and basic properties

One of the fundamental notions of set theory is the membership relation, usually denoted by \in . When one considers subsets of a given universe it is possible to apply the characteristic functions for expressing the fact whether or not a given element belongs to a given set. We discuss the case when only partial information about objects is accessible. In this section we show it is possible to extend characteristic function notion to that case.

Let $A = (U, A)$ be an information system and let $\emptyset \neq X \subseteq U$. The rough A -membership function of the set X (or *rm-function*, for short) denoted by μ_X^A , is defined as follows :

$$\mu_X^A(x) = \frac{|[x]_A \cap X|}{|[x]_A|} \text{ for } x \in U.$$

The above definition is illustrated on Fig.1.

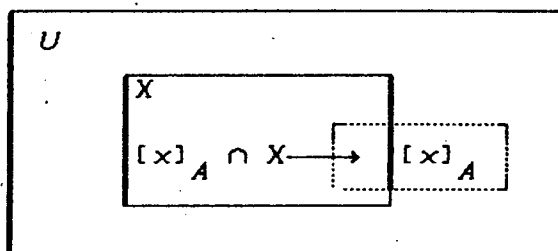


Figure 1

One can observe a similarity of the expression on the right hand side of the above definition with that expression used to define the conditional probability.

From the definition of μ_X^A we have the following proposition characterizing some basic properties of *rm-functions*.

Proposition 2. Let $A=(U, A)$ be an information system and let $X, Y \subseteq U$.

The μ -function μ_X^A has the following properties:

- (i) $\mu_X^A(x) = 1$ iff $x \in \underline{A}X$;
- (ii) $\mu_X^A(x) = 0$ iff $x \in U - \bar{A}X$;
- (iii) $0 < \mu_X^A(x) < 1$ iff $x \in BN_A(X)$;
- (iv) If $IND(A) = \{(x, x) : x \in U\}$ then μ_X^A is the characteristic function of X ;
- (v) If $x IND(A) y$ then $\mu_X^A(x) = \mu_X^A(y)$.
- (vi) $\mu_{U-X}^A(x) = 1 - \mu_X^A(x)$ for any $x \in X$;
- (vii) $\mu_{XUY}^A(x) \geq \max(\mu_X^A(x), \mu_Y^A(x))$ for any $x \in U$;
- (viii) $\mu_{X \cap Y}^A(x) \leq \min(\mu_X^A(x), \mu_Y^A(x))$ for any $x \in U$;
- (ix) If \mathcal{X} is a family of pairwise disjoint subsets of U then

$$\mu_{\bigcup_{X \in \mathcal{X}} X}^A(x) = \sum_{X \in \mathcal{X}} \mu_X^A(x) \quad \text{for any } x \in U.$$

Proof. (i) We have $x \in \underline{A}X$ iff $[x]_A \subseteq X$ iff $\mu_X^A(x) = 1$.

(ii) We have $x \in U - \bar{A}X$ iff $[x]_A \cap X = \emptyset$ iff $\mu_X^A(x) = 0$.

(iii) We have

$x \in BN_A(X)$ iff

$[x]_A \cap X \neq \emptyset$ and $[x]_A \cap (U - X) \neq \emptyset$ iff

$$(\mu_X^A(x) > 0 \text{ and } \mu_X^A(x) < 1).$$

(iv) If $IND(A) = \{(x, x) : x \in U\}$ then $|[x]_A| = 1$ for any $x \in X$.

Moreover $|[x]_A \cap X| = 1$ if $x \in X$ and $|[x]_A \cap X| = 0$ if $x \in U - X$.

(v) Since $[x]_A = [y]_A$ we have $\mu_X^A(x) = \mu_X^A(y)$.

$$(vi) \mu_{U-X}^A(x) = \frac{|[x]_A \cap (U-X)|}{|[x]_A|} = 1 - \frac{|[x]_A \cap X|}{|[x]_A|} = 1 - \mu_X^A(x).$$

$$(vii) \mu_{XUY}^A(x) = \frac{|[x]_A \cap (XUY)|}{|[x]_A|} \geq \frac{|[x]_A \cap X|}{|[x]_A|} = \mu_X^A(x). \quad \text{In}$$

the similar way one can obtain $\mu_{XUY}^A(x) \geq \mu_Y^A(x)$.

(viii) Proof runs as in the case (vi).

$$\begin{aligned}
 \text{(ix)} \quad \mu_{\bigcup X}^{\mathbb{A}}(x) &= \frac{|[x]_{\mathbb{A}} \cap \bigcup X|}{|[x]_{\mathbb{A}}|} = \frac{|\bigcup \{[x]_{\mathbb{A}} \cap X : X \in \mathcal{X}\}|}{|[x]_{\mathbb{A}}|} = \\
 &= \sum_{X \in \mathcal{X}} \mu_X^{\mathbb{A}}(x).
 \end{aligned}$$

The last equality follows from the assumption that \mathcal{X} is a family of pairwise disjoint sets. □

The set $\{Inf_{\mathbb{A}}(x) : x \in U\}$ is called the \mathbb{A} -information set and it is denoted by $INF(\mathbb{A})$. For every $X \subseteq U$ we define the rough \mathbb{A} -information function, denoted by $\hat{\mu}_X^{\mathbb{A}}$, as follows:

$$\hat{\mu}_X^{\mathbb{A}}(u) = \mu_X^{\mathbb{A}}(x), \text{ where } u \in INF(\mathbb{A}) \text{ and } Inf_{\mathbb{A}}(x) = u.$$

The correctness of the above definition follows from (v) in Proposition 1.

If $\mathbb{A} = (U, \mathcal{A})$ is an information system then we define rough \mathbb{A} -inclusion of subsets of U in the standard way, namely:

$$X \leq_{\mathbb{A}} Y \quad \text{iff} \quad \mu_X^{\mathbb{A}}(x) \leq \mu_Y^{\mathbb{A}}(x) \text{ for any } x \in U.$$

Proposition 3. If $X \leq_{\mathbb{A}} Y$ then $\underline{A}X \subseteq \underline{A}Y$ and $\bar{A}X \subseteq \bar{A}Y$.

Proof. Follows from Proposition 2 (see (i) and (ii)). □

The above definition of the rough \mathbb{A} -inclusion is not equivalent to the one of [P91]. Indeed in [P91] the reverse implication to that formulated in Proposition 2 is not valid.

One can show that they are equivalent for any information system \mathbb{A} only if $\underline{A}X \subseteq \underline{A}Y$. This is a consequence of our definition taking into account some additional information about objects from the boundary regions.

5. Rough membership functions for union and intersection

Now we present some results which are obtained as a consequence of our assumption that objects are observable by means of partial information about them represented by attribute values. In this section we prove that the inequalities in (vii) and (viii) of Proposition 1 cannot be in general substituted by the equalities.

We also prove that for some boundary regions it is not possible to compute the values of the rm-functions for union

XUY and intersection $X \cap Y$ knowing the values of μ -functions for X and Y only (if information about information systems is not accessible and do not hold some special relations between sets X and Y). These results show that the assumptions about properties of the fuzzy membership functions [DP80 p.11] related to the union and intersection should be modified if one would like to take into account that objects are classified on the basis of a partial information about them. We present also the necessary and sufficient conditions for the following equalities (which are the ones used in fuzzy set theory) to be true:

$$\mu_{X \cup Y}^A(x) = \max(\mu_X^A(x), \mu_Y^A(x)) \text{ and}$$

$$\mu_{X \cap Y}^A(x) = \min(\mu_X^A(x), \mu_Y^A(x)) \text{ for any } x \in U.$$

These conditions are expressed by means of the boundary regions of a partition of U defined by sets X and Y or by means of some relationships which should hold for the sets X and Y . In particular we show that the above equalities are true for arbitrary information system A iff $X \subseteq Y$ or $Y \subseteq X$.

First we prove the following two lemmas.

Lemma 1. Let $A=(U, A)$ be an information systems, $X, Y \subseteq U$ and $\mathcal{X} = \{X \cap Y, X \cap \bar{Y}, \bar{X} \cap Y, \bar{X} \cap \bar{Y}\}$. If $x \in U - Bd_A(\mathcal{X}, \mathcal{X})$ then

$$\mu_{X \cap Y}^A(x) =$$

if $x \in Bd_A(\{X \cap \bar{Y}, \bar{X} \cap Y\}, \mathcal{X}) \cup Bd_A(\{X \cap \bar{Y}, \bar{X} \cap Y, \bar{X} \cap \bar{Y}\}, \mathcal{X})$

then 0

else if $x \in Bd_A(\{X \cap Y, X \cap \bar{Y}, \bar{X} \cap Y\}, \mathcal{X})$ then $\mu_X^A(x) + \mu_Y^A(x) - 1$

else $\min(\mu_X^A(x), \mu_Y^A(x))$.

Proof. In the proof we apply the property (iii) from Proposition 1.

Let $x \in Bd_A(\{X \cap \bar{Y}, \bar{X} \cap Y\} \cup Bd_A(\{X \cap \bar{Y}, \bar{X} \cap Y, \bar{X} \cap \bar{Y}\}))$. Hence $[x]_A \subseteq (X \cap \bar{Y}) \cup (\bar{X} \cap Y) \cup (\bar{X} \cap \bar{Y})$, so $[x]_A \cap (X \cap Y) = \emptyset$ and $\mu_{X \cap Y}^A(x) = 0$.

If $x \in Bd_A(\{X \cap Y, X \cap \bar{Y}, \bar{X} \cap Y\}, \mathcal{X})$ then

$$[x]_A \subseteq (X \cap Y) \cup (X \cap \bar{Y}) \cup (\bar{X} \cap Y)$$

Hence $[x]_A = [x]_A \cap (X \cap Y) \cup [x]_A \cap (X \cap \bar{Y}) \cup [x]_A \cap (\bar{X} \cap Y)$, so $[x]_A = [x]_A \cap X \cup [x]_A \cap Y$. We obtain $|[x]_A| = |[x]_A \cap X| + |[x]_A \cap Y| - |[x]_A \cap (X \cap Y)|$. Hence $\mu_{X \cap Y}^A(x) = \mu_X^A(x) + \mu_Y^A(x) - 1$.

If $x \in \underline{A}(X \cap Y)$ then $[x]_A \subseteq X \cap Y$. Hence $\mu_{X \cap Y}^A(x) = 1$. We have also $[x]_A \subseteq X$ and $[x]_A \subseteq Y$ because $X \cap Y \subseteq X$ and $X \cap Y \subseteq Y$. Hence $\mu_X^A(x) = \mu_Y^A(x) = 1$.

If $x \in \underline{A}(X \cap \bar{Y})$ then $[x]_A \subseteq X \cap \bar{Y}$. Hence $[x]_A \cap (X \cap Y) = \emptyset$ and $[x]_A \cap Y \subseteq (X \cap \bar{Y}) \cap Y = \emptyset$, so

$$\mu_{X \cap Y}^A(x) = \min(\mu_X^A(x), \mu_Y^A(x)).$$

If $x \in \underline{A}(\bar{X} \cap Y)$ the proof is analogous to the latter case.

If $x \in \underline{A}(\bar{X} \cap \bar{Y})$ we obtain $\mu_{X \cap Y}^A(x) = \mu_X^A(x) = \mu_Y^A(x) = 0$.

If $x \in \text{Bd}_A((X \cap Y, X \cap \bar{Y}), \mathcal{X})$ we have $[x]_A = [x]_A \cap (X \cap Y) \cup [x]_A \cap (X \cap \bar{Y})$. Hence $[x]_A \cap (X \cap Y) = [x]_A \cap Y$ and $[x]_A \cap (X \cap \bar{Y}) \cap X \subseteq X$. Hence $\mu_{X \cap Y}^A(x) = \mu_Y^A(x) \leq \mu_X^A(x) = 1$.

If $x \in \text{Bd}_A((X \cap Y, \bar{X} \cap Y), \mathcal{X})$ the proof is analogous to the latter case.

If $x \in \text{Bd}_A((X \cap \bar{Y}, \bar{X} \cap \bar{Y}), \mathcal{X})$ one can calculate $\mu_{X \cap Y}^A(x) = \mu_Y^A(x) = 0 \leq \mu_X^A(x)$. Similarly, in the case when $x \in \text{Bd}_A((\bar{X} \cap Y, \bar{X} \cap \bar{Y}), \mathcal{X})$ one can calculate that $\mu_{X \cap Y}^A(x) = \mu_X^A(x) = 0 \leq \mu_Y^A(x)$.

If $x \in \text{Bd}_A((X \cap Y, \bar{X} \cap \bar{Y}), \mathcal{X})$ we have $\mu_{X \cap Y}^A(x) = \mu_X^A(x) = \mu_Y^A(x)$. □

Lemma 2. Let $\mathbb{A} = (U, \mathcal{A})$ be an information systems, $X, Y \subseteq U$ and $\mathcal{X} = (X \cap Y, X \cap \bar{Y}, \bar{X} \cap Y, \bar{X} \cap \bar{Y})$. If $x \in U - \text{Bd}_A(\mathcal{X}, \mathcal{X})$ then

$$\mu_{X \cup Y}^A(x) =$$

if $x \in \text{Bd}_A((X \cap \bar{Y}, \bar{X} \cap \bar{Y}), \mathcal{X}) \cup \text{Bd}_A((X \cap \bar{Y}, \bar{X} \cap Y, \bar{X} \cap \bar{Y}), \mathcal{X})$

then $\mu_X^A(x) + \mu_Y^A(x)$

else if $x \in \text{Bd}_A((X \cap Y, X \cap \bar{Y}, \bar{X} \cap Y), \mathcal{X})$ then 1

else $\max(\mu_X^A(x), \mu_Y^A(x))$.

Proof. In the proof we apply the property (iii) from Proposition 1.

If $x \in Bd_A(\langle X \cap Y, -X \cap Y \rangle)$ then

$$[x]_A = [x]_A \cap (X \cap Y) \cup [x]_A \cap (-X \cap Y).$$

Hence $[x]_A \cap X = [x]_A \cap X \cap -Y$, $[x]_A \cap Y = [x]_A \cap -X \cap Y$.

Since

$$[x]_A \cap (X \cup Y) = ([x]_A \cap X) \cup ([x]_A \cap Y) \text{ and} \\ ([x]_A \cap X) \cap ([x]_A \cap Y) = [x]_A \cap X \cap -Y \cap -X \cap Y = \emptyset$$

we get $\mu_{X \cup Y}^A(x) = \mu_X^A(x) + \mu_Y^A(x)$.

If $x \in Bd_A(\langle X \cap Y, -X \cap Y, -X \cap -Y \rangle, \mathcal{X})$ then

$$[x]_A = [x]_A \cap (X \cap Y) \cup [x]_A \cap (-X \cap Y) \cup [x]_A \cap (-X \cap -Y).$$

Since

$$[x]_A \cap (X \cup Y) = ([x]_A \cap X) \cup ([x]_A \cap Y) \text{ and} \\ ([x]_A \cap X) \cap ([x]_A \cap Y) = [x]_A \cap X \cap -Y \cap -X \cap Y = \emptyset$$

we get $\mu_{X \cup Y}^A(x) = \mu_X^A(x) + \mu_Y^A(x)$.

If $x \in Bd_A(\langle X \cap Y, X \cap -Y, -X \cap Y \rangle, \mathcal{X})$ then

$$[x]_A = [x]_A \cap (X \cap Y) \cup [x]_A \cap (X \cap -Y) \cup [x]_A \cap (-X \cap Y).$$

Hence $[x]_A \cap (X \cup Y) = [x]_A$, so $\mu_{X \cup Y}^A(x) = 1$.

If $x \in \underline{A}(-X \cap -Y)$ then $[x]_A = [x]_A \cap (-X \cap -Y)$. Hence $[x]_A \cap (X \cup Y) = [x]_A \cap X = [x]_A \cap Y = \emptyset$.

If $x \in \underline{A}(X \cap Y)$ then $[x]_A = [x]_A \cap X \cap Y$. Hence $[x]_A \cap (X \cup Y) = [x]_A = [x]_A \cap X = [x]_A \cap Y$.

If $x \in \underline{A}(-X \cap Y)$ then $[x]_A = [x]_A \cap (-X \cap Y)$. Hence $[x]_A \cap (X \cup Y) = [x]_A \cap Y \neq \emptyset$ and $[x]_A \cap X = \emptyset$. If $x \in \underline{A}(-X \cap Y)$ a proof is analogous as in the latter case.

If $x \in Bd_A(\langle X \cap Y, X \cap -Y \rangle, \mathcal{X})$ then

$$[x]_A = [x]_A \cap (X \cap Y) \cup [x]_A \cap (X \cap -Y).$$

Hence $[x]_A \cap (X \cup Y) = [x]_A \cap X \supseteq [x]_A \cap (X \cap Y) = [x]_A \cap Y$.

If $x \in Bd_A(\langle X \cap Y, -X \cap Y \rangle, \mathcal{X})$ then the proof is analogous as in the latter case.

If $x \in Bd_A(\langle X \cap Y, -X \cap -Y \rangle, \mathcal{X})$ then $\mu_{XUY}^A(x) = \mu_X^A(x) = \mu_Y^A(x)$.

If $x \in Bd_A(\langle X \cap -Y, -X \cap -Y \rangle, \mathcal{X})$ then $\mu_{XUY}^A(x) = \mu_X^A(x)$ and $\mu_Y^A(x) = 0$.

If $x \in Bd_A(\langle -X \cap Y, -X \cap -Y \rangle, \mathcal{X})$ then $\mu_{XUY}^A(x) = \mu_Y^A(x)$ and $\mu_X^A(x) = 0$.

If $x \in Bd_A(\langle X \cap -Y, X \cap Y, -X \cap -Y \rangle, \mathcal{X})$ then $\mu_{XUY}^A(x) = \mu_X^A(x) \geq \mu_Y^A(x)$.

If $x \in Bd_A(\langle -X \cap Y, X \cap Y, -X \cap -Y \rangle, \mathcal{X})$ then $\mu_{XUY}^A(x) = \mu_Y^A(x) \geq \mu_X^A(x)$. □

Theorem 1. Let \mathcal{A} be a (non-empty) class of information systems with the universe including sets X and Y . The following conditions are equivalent:

- (i) $\mu_{X \cap Y}^A(x) = \min(\mu_X^A(x), \mu_Y^A(x))$ for any $x \in U$ and $A = (U, A) \in \mathcal{A}$;
- (ii) $Bd_A(Y, \mathcal{X}) = \emptyset$ for any $Y \supseteq \langle X \cap -Y, -X \cap Y \rangle$ and $A = (U, A) \in \mathcal{A}$.

Proof.

(ii) \rightarrow (i)

Follows from Lemma 1.

(i) \rightarrow (ii)

Suppose that $Bd_A(Y, \mathcal{X}) \neq \emptyset$ for some $Y \supseteq \langle X \cap -Y, -X \cap Y \rangle$ and $A \in \mathcal{A}$.

If $x \in Bd_A(\langle X \cap -Y, -X \cap Y \rangle, \mathcal{X}) \neq \emptyset$ for some $A \in \mathcal{A}$ then

$$[x]_A \cap (X \cap -Y) \neq \emptyset \text{ and } [x]_A \cap (-X \cap Y) \neq \emptyset.$$

Hence $\mu_X^A(x) > 0$ and $\mu_Y^A(x) > 0$. We also have from Lemma 1

$\mu_{X \cap Y}^A(x) = 0$. Thus we have $\mu_{X \cap Y}^A(x) \neq \min(\mu_X^A(x), \mu_Y^A(x))$, i.e. a

contradiction with (i).

If $x \in Bd_A(\langle X \cap -Y, -X \cap Y, -X \cap -Y \rangle, \mathcal{X})$ for some $A \in \mathcal{A}$ and $x \in U$ then one can see that it contradicts (i) in the same manner as before.

If $x \in Bd_A(\langle X \cap -Y, -X \cap Y, X \cap Y \rangle, \mathcal{X}) \neq \emptyset$ for some $A \in \mathcal{A}$ then we have $[x]_A = [x]_A \cap (X \cap -Y) \cup [x]_A \cap (-X \cap Y) \cup [x]_A \cap (X \cap Y)$.

Hence

$$[x]_A \cap X = [x]_A \cap (X \cap -Y) \cup [x]_A \cap (X \cap Y) \text{ and}$$

$$[x]_A \cap Y = [x]_A \cap (-X \cap Y) \cup [x]_A \cap (X \cap Y).$$

Since $[x]_A \cap (X \cap Y) \neq \emptyset$ and $[x]_A \cap (-X \cap Y) \neq \emptyset$ we would have $\mu_X^A(x) > \mu_{X \cap Y}^A(x)$ and $\mu_Y^A(x) > \mu_{X \cap Y}^A(x)$ but this contradicts the assumption (i).

If $x \in Bd_A((X \cap Y, -X \cap Y, -X \cap Y, X \cap Y), \mathcal{X})$ for some $A \in \mathcal{A}$ then

$$[x]_A = [x]_A \cap (X \cap Y) \cup [x]_A \cap (-X \cap Y) \cup [x]_A \cap (X \cap Y) \cup [x]_A \cap (-X \cap Y).$$

Again we would have

$$[x]_A \cap X = [x]_A \cap (X \cap Y) \cup [x]_A \cap (X \cap Y) \text{ and}$$

$$[x]_A \cap Y = [x]_A \cap (-X \cap Y) \cup [x]_A \cap (X \cap Y).$$

Since $[x]_A \cap (X \cap Y) \neq \emptyset$ and $[x]_A \cap (-X \cap Y) \neq \emptyset$ we would have $\mu_X^A(x) > \mu_{X \cap Y}^A(x)$ and $\mu_Y^A(x) > \mu_{X \cap Y}^A(x)$ but this contradicts the assumption (i).

This completes the proof of (i) \rightarrow (ii). □

Theorem 2. Let \mathcal{A} be a (non-empty) class of information systems with the set of objects including sets X and Y . The following conditions are equivalent:

$$(i) \mu_{X \cup Y}^A(x) = \max(\mu_X^A(x), \mu_Y^A(x)) \text{ for any } x \in U \text{ and } A = (U, A) \in \mathcal{A};$$

$$(ii) Bd_A(Y, \mathcal{X}) = \emptyset \text{ for any } Y \supseteq (X \cap Y, -X \cap Y) \text{ and } A = (U, A) \in \mathcal{A}.$$

Proof.

(ii) \rightarrow (i)

Follows from Lemma 2.

(i) \rightarrow (ii)

Suppose that $Bd_A(Y, \mathcal{X}) \neq \emptyset$ for some $Y \supseteq (X \cap Y, -X \cap Y)$ and $A \in \mathcal{A}$.

If $x \in Bd_A((X \cap Y, -X \cap Y), \mathcal{X}) \neq \emptyset$ for some $A \in \mathcal{A}$ then

$$[x]_A \cap (X \cap Y) \neq \emptyset \text{ and } [x]_A \cap (-X \cap Y) \neq \emptyset.$$

Hence $\mu_X^A(x) > 0$ and $\mu_Y^A(x) > 0$. We have also from Lemma 2 that $\mu_{X \cup Y}^A(x) = \mu_X^A(x) + \mu_Y^A(x)$. This gives $\mu_{X \cup Y}^A(x) > \mu_X^A(x)$ and $\mu_{X \cup Y}^A(x) > \mu_Y^A(x)$, contrary to (i).

If $x \in Bd_A((X \cap Y, -X \cap Y, -X \cap Y, X \cap Y), \mathcal{X})$ for some $A \in \mathcal{A}$ and $x \in U$

then one can see that it contradicts (i) in the same manner as before.

If $x \in Bd_A((X \cap Y, -X \cap Y, X \cap Y), \mathcal{X}) \neq \emptyset$ for some $A \in \mathcal{A}$ then we have $[x]_A = [x]_A \cap (X \cap Y) \cup [x]_A \cap (-X \cap Y) \cup [x]_A \cap (X \cap Y)$ and $[x]_A \cap Z \neq \emptyset$ for $Z \in (X \cap Y, -X \cap Y, X \cap Y)$. Hence

$$|[x]_A| > |[x]_A \cap X| \quad \text{and} \quad |[x]_A| > |[x]_A \cap Y|.$$

Thus $\mu_X^A(x) < 1$ and $\mu_Y^A(x) < 1$. However $\mu_{XUY}^A(x) = 1$ from Lemma 2. This contradicts our assumption (i).

Now let us assume that

$$x \in Bd_A((X \cap Y, -X \cap Y, -X \cap Y, X \cap Y), \mathcal{X}) \text{ for some } A \in \mathcal{A}.$$

Then $[x]_A =$

$$[x]_A \cap (X \cap Y) \cup [x]_A \cap (-X \cap Y) \cup [x]_A \cap (X \cap Y) \cup [x]_A \cap (-X \cap Y)$$

and

$$[x]_A \cap Z \neq \emptyset \text{ for } Z \in (X \cap Y, -X \cap Y, -X \cap Y, X \cap Y).$$

$$\text{Hence } [x]_A \cap (XUY) = [x]_A \cap X \cup [x]_A \cap (-X \cap Y)$$

$$[x]_A \cap (XUY) = [x]_A \cap Y \cup [x]_A \cap (X \cap Y).$$

Consequently $\mu_{XUY}^A(x) > \mu_X^A(x)$ and $\mu_{XUY}^A(x) > \mu_Y^A(x)$. This contradicts our assumption (i), which completes the proof of (i) \rightarrow (ii). □

Now we would like to characterize the conditions related to the boundary regions occurring in Theorem 1 and Theorem 2.

Lemma 3. Let \mathcal{A} be a class of information systems with the set of objects including sets X and Y . The following conditions are equivalent for arbitrary $A = (U, A) \in \mathcal{A}$:

$$(i) \quad Bd_A(\mathcal{V}, \mathcal{X}) = \emptyset \text{ for any } \mathcal{V} \supseteq (X \cap Y, -X \cap Y);$$

(ii) $\alpha \vee \beta \vee \gamma \vee \delta$ where

$$\alpha: = (X \subseteq Y \text{ or } Y \subseteq X);$$

$$\beta: = (X - Y \neq \emptyset \text{ and } Y - X \neq \emptyset \text{ and } XUY = U \\ \text{and } X \cap Y = \emptyset \text{ and } Bd_A((X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset);$$

$$\gamma: = (X - Y \neq \emptyset \text{ and } Y - X \neq \emptyset \text{ and } XUY = U \text{ and } X \cap Y \neq \emptyset \text{ and} \\ Bd_A((X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset \text{ and} \\ Bd_A((X \cap Y, -X \cap Y, X \cap Y), \mathcal{X}) = \emptyset);$$

$$\delta := (X \neq Y \text{ and } Y \neq X \text{ and } XUY \neq U \text{ and } X \cap Y = \emptyset \text{ and } \\ Bd_A((X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset \text{ and } \\ Bd_A((X \cap Y, -X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset);$$

$$\varepsilon := (X \neq Y \text{ and } Y \neq X \text{ and } XUY \neq U \text{ and } X \cap Y \neq \emptyset \text{ and } \\ Bd_A((X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset \text{ and } \\ Bd_A((X \cap Y, -X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset \text{ and } \\ Bd_A((X \cap Y, -X \cap Y, X \cap Y), \mathcal{X}) = \emptyset \text{ and } \\ Bd_A((X \cap Y, -X \cap Y, X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset).$$

Proof. We have the following equivalencies:

$$Bd_A((X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset \text{ iff } X \subseteq Y \text{ or } Y \subseteq X \text{ or } (X \neq Y \text{ and } \\ Y \neq X \text{ and } Bd_A((X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset);$$

$$Bd_A((X \cap Y, -X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset \text{ iff } \\ X \subseteq Y \text{ or } Y \subseteq X \text{ or } XUY = U \text{ or } (X \neq Y \text{ and } Y \neq X \text{ and } XUY \neq U \text{ and } \\ Bd_A((X \cap Y, -X \cap Y, -X \cap Y), \mathcal{X}) = \emptyset);$$

$$Bd_A((X \cap Y, -X \cap Y, X \cap Y), \mathcal{X}) = \emptyset \text{ iff } \\ X \subseteq Y \text{ or } Y \subseteq X \text{ or } X \cap Y = \emptyset \text{ or } (X \neq Y \text{ and } Y \neq X \text{ and } X \cap Y \neq \emptyset \text{ and } \\ Bd_A((X \cap Y, -X \cap Y, X \cap Y), \mathcal{X}) = \emptyset);$$

$$Bd_A((X \cap Y, -X \cap Y, -X \cap Y, X \cap Y), \mathcal{X}) = \emptyset \text{ iff } \\ X \subseteq Y \text{ or } Y \subseteq X \text{ or } X \cap Y = \emptyset \text{ or } XUY = U \text{ or } \\ (X \neq Y \text{ and } Y \neq X \text{ and } X \cap Y \neq \emptyset \text{ and } XUY \neq U \text{ and } \\ Bd_A((X \cap Y, -X \cap Y, -X \cap Y, X \cap Y), \mathcal{X}) = \emptyset).$$

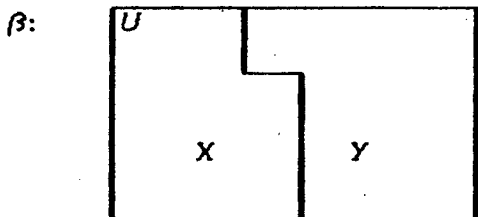
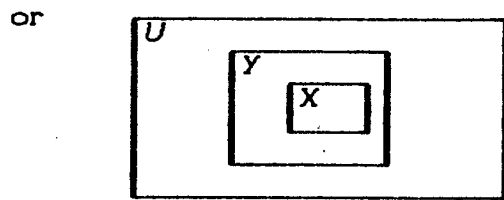
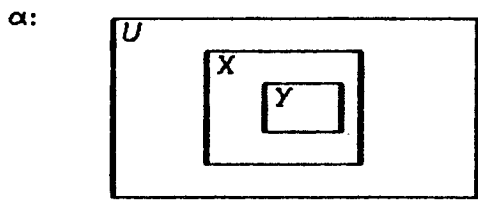
Hence, taking the conjunction of above equivalencies, we obtain:

$$Bd_A(Y, \mathcal{X}) = \emptyset \text{ for any } Y \supseteq (X \cap Y, -X \cap Y) \text{ iff one of the } \\ \text{conditions } \alpha, \beta, \gamma, \delta, \varepsilon \text{ from (ii) is satisfied.}$$

□

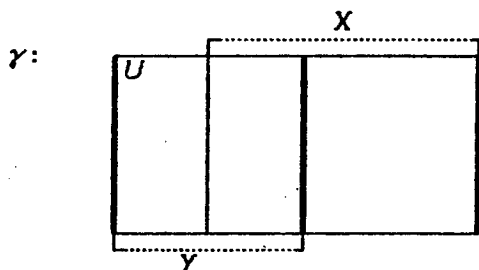
Let us remark that only when condition α holds, i.e. when $X \subseteq Y$ or $Y \subseteq X$, condition (ii) is independent from the properties of boundary regions in the information systems.

Below we illustrate the conditions formulated in (ii) of Lemma 3.



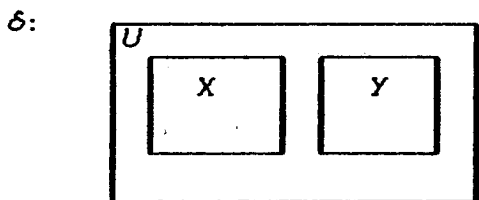
X and Y form a partition of U.
The condition for the boundary regions is the following:

$$Bd_A(\langle X \cap Y, -X \cap Y \rangle, \mathcal{X}) = \emptyset.$$



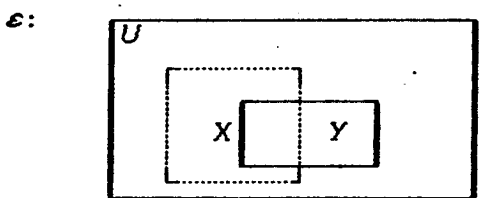
The conditions for the boundary regions are the following:

$$Bd_A(\langle X \cap Y, -X \cap Y \rangle, \mathcal{X}) = \emptyset \text{ and} \\ Bd_A(\langle X \cap Y, -X \cap Y, X \cap Y \rangle, \mathcal{X}) = \emptyset.$$



The conditions for the boundary regions are the following:

$$Bd_A(\langle X \cap Y, -X \cap Y \rangle, \mathcal{X}) = \emptyset \text{ and} \\ Bd_A(\langle X \cap Y, -X \cap Y, -X \cap Y \rangle, \mathcal{X}) = \emptyset.$$



The conditions for the boundary regions are the following:

$$Bd_A(\langle X \cap Y, -X \cap Y \rangle, \mathcal{X}) = \emptyset \text{ and} \\ Bd_A(\langle X \cap Y, -X \cap Y, X \cap Y \rangle, \mathcal{X}) = \emptyset \text{ and} \\ Bd_A(\langle X \cap Y, -X \cap Y, -X \cap Y \rangle, \mathcal{X}) = \emptyset \text{ and} \\ Bd_A(\langle X \cap Y, -X \cap Y, X \cap Y, -X \cap Y \rangle, \mathcal{X}) = \emptyset.$$

Now we prove that the assumptions from Lemma 1 and Lemma 2 related to the boundary region $Bd_A(X, X)$ cannot be removed because otherwise it will not be possible to compute the values of $\mu_{XUY}^A(x)$ and $\mu_{X\cap Y}^A(x)$ knowing the values $\mu_X^A(x)$ and $\mu_Y^A(x)$ only.

Theorem 3. There is no function $F : [0,1] \times [0,1] \rightarrow [0,1]$ such that for any finite sets X and Y and any information system $A=(U, A)$ such that $X, Y \subseteq U$ the following equality holds:

$$\mu_{XUY}^A(x) = F(\mu_X^A(x), \mu_Y^A(x)) \text{ for any } x \in U.$$

Proof. Let us take $X=\{1,2,3,5\}$ and $Y=\{1,2,3,4\}$. Let $U=\{1, \dots, 8\}$. It is easy to construct an attribute sets A and A' such that $[1]_A=U$ and $[1]_{A'}=\{1,4,5,6\}$.

Thus we have

$$\mu_X^A(1)=\mu_Y^A(1)=1/2 \text{ and } \mu_{XUY}^A(1) = 5/8, \text{ where } A=(U, A)$$

$$\text{and } \mu_X^B(1)=\mu_Y^B(1)=1/2 \text{ and } \mu_{XUY}^B(1) = 3/4, \text{ where } B=(U, A').$$

□

Similarly one can prove:

Theorem 4. There is no function $F : [0,1] \times [0,1] \rightarrow [0,1]$ such that for any finite sets X and Y and any information system $A=(U, A)$ such that $X, Y \subseteq U$ the following equality hold:

$$\mu_{X\cap Y}^A(x) = F(\mu_X^A(x), \mu_Y^A(x)) \text{ for any } x \in U.$$

□

6. An algorithm for computing the rough membership function values

In the previous section we proved that it is not possible, in general, to construct a function such that it can be used for computing values of the rm-function corresponding to the XUY or $X\cap Y$ from the values of the rm-functions corresponding to X and Y . Hence any particular functions e.g. min or max applied for computing the values of rm-functions will give incorrect values. This shows a major drawback of some approaches in fuzzy set theory.

We present an efficient algorithm for computing values of rm-functions based on the properties of the atomic components of the sets.

Let \mathcal{X} be a (non-empty) family of subsets of a given finite set U . By $\mathcal{B}(\mathcal{X})$ we denote the field set generated by \mathcal{X} , i.e. $\mathcal{B}(\mathcal{X})$ is the least family of sets satisfying the following two conditions:

- (i) $\mathcal{X} \subseteq \mathcal{B}(\mathcal{X})$;
- (ii) if $X, Y \in \mathcal{B}(\mathcal{X})$ then $X \cup Y, X \cap Y, -X \in \mathcal{B}(\mathcal{X})$.

If $X \subseteq U$ then we define $X^0 = X$ and $X^1 = U - X$. By $AT(\mathcal{A}, \mathcal{X})$ we denote the set of all non-empty atoms generated by $\mathcal{X} = \{X_1, \dots, X_k\}$, i.e. $AT(\mathcal{A}, \mathcal{X}) =$

$$\{X_1^{i_1} \cap \dots \cap X_k^{i_k} : i_1, \dots, i_k \in \{0, 1\} \text{ and } X_1^{i_1} \cap \dots \cap X_k^{i_k} \neq \emptyset\}.$$

We will apply the well known properties of atoms.

Proposition 3. Let \mathcal{X} be a (non-empty) family of subsets of a given set U . The following properties hold :

- (i) If $Y, Y' \in AT(\mathcal{A}, \mathcal{X})$ and $Y \neq Y'$ then $Y \cap Y' = \emptyset$.
- (ii) If $\emptyset \neq Y \in AT(\mathcal{A}, \mathcal{X})$ then there exists a uniquely determined set of (non-empty) atoms $\mathcal{Y} \subseteq AT(\mathcal{A}, \mathcal{X})$ such that $Y = \bigcup_{X \in \mathcal{Y}} X$.

□

Let $\mathcal{A} = (U, \mathcal{A})$ be an information system and let \mathcal{X} be a family of subsets of U . For every $u \in INF(\mathcal{A})$ we define the set $AT(\mathcal{A}, \mathcal{X}, u)$ of all atoms $Y \in AT(\mathcal{A}, \mathcal{X})$ such that

$$Y \cap u_{\mathcal{A}} \neq \emptyset, \text{ where } u_{\mathcal{A}} = \{x \in U : Inf_{\mathcal{A}}(x) = u\}.$$

Moreover, let $f(\mathcal{A}, \mathcal{X}, u)$ be a function from $AT(\mathcal{A}, \mathcal{X})$ into non-negative reals such that

$$f(\mathcal{A}, \mathcal{X}, u)(Y) = \frac{|u_{\mathcal{A}} \cap Y|}{|u_{\mathcal{A}}|} \text{ for any } Y \in AT(\mathcal{A}, \mathcal{X}).$$

From the definition we have the following equality:

$$f(\mathcal{A}, \mathcal{X}, Inf_{\mathcal{A}}(x))(Y) = \mu_Y^{\mathcal{A}}(x) \text{ for any } x \in X \text{ and } Y \in AT(\mathcal{A}, \mathcal{X}).$$

There is a simple method for computing all functions from the family $\{f(\mathcal{A}, \mathcal{X}, u)\}_{u \in INF(\mathcal{A})}$ for a given information system \mathcal{A} . We represent the family $\{f(\mathcal{A}, \mathcal{X}, u)\}_{u \in INF(\mathcal{A})}$ in a table $T(\mathcal{A}, \mathcal{X})$ in which rows correspond to different information $u \in INF(\mathcal{A})$ and the columns correspond to different atoms from $AT(\mathcal{A}, \mathcal{X})$. In the table $T(\mathcal{A}, \mathcal{X})$ the position corresponding to an information u and to an atom $Y \in AT(\mathcal{A}, \mathcal{X})$ is empty if $Y \notin AT(\mathcal{A}, \mathcal{X}, u)$ and contains the value $f(\mathcal{A}, \mathcal{X}, u)(Y)$ if $Y \in AT(\mathcal{A}, \mathcal{X}, u)$.

Example 1. Let us consider the following information system. Let $U = \{1, \dots, 20\}$, $A = \{a, b, c, d, e\}$, $\mathcal{X} = \{X_1, X_2\}$, $X_1 = \{5, \dots, 15\}$, $X_2 = \{10, \dots, 20\}$ and the attributes are defined as follows:

	a	b	c	d	e
1	1	1	0	0	0
2	0	0	1	0	1
3	1	0	1	0	1
4	1	1	1	1	1
5	0	0	1	0	1
6	1	1	1	1	1
7	1	0	1	0	1
8	1	1	0	0	0
9	0	1	0	1	0
10	0	0	1	1	1

	a	b	c	d	e
11	0	0	1	0	1
12	0	0	0	0	0
13	0	0	1	1	1
14	1	1	0	0	0
15	0	0	0	0	0
16	1	1	1	0	0
17	0	0	1	0	1
18	1	1	1	1	1
19	1	1	1	1	1
20	0	0	0	0	0

From the above definitions we get:

$$\begin{aligned} \text{ATCA}(\mathcal{X}) &= \langle Y_1, Y_2, Y_3, Y_4 \rangle, \text{ where } Y_1 = X_1 \cap X_2 = \langle 10, \dots, 15 \rangle, \\ Y_2 &= X_1 \cap \neg X_2 = \langle 5, \dots, 9 \rangle, \\ Y_3 &= \neg X_1 \cap X_2 = \langle 16, \dots, 20 \rangle, \\ Y_4 &= \neg X_1 \cap \neg X_2 = \langle 1, \dots, 4 \rangle; \end{aligned}$$

$$\text{INFCA} = \langle 11000, 00101, 10101, 11111, 01010, 00111, 00000, 11100 \rangle;$$

$$11000_A = \langle 1, 8, 14 \rangle; 00101_A = \langle 2, 5, 11, 17 \rangle; 10101_A = \langle 3, 7 \rangle;$$

$$11111_A = \langle 4, 6, 18, 19 \rangle; 01010_A = \langle 9 \rangle; 00111_A = \langle 10, 13 \rangle;$$

$$00000_A = \langle 12, 15, 20 \rangle; 11100_A = \langle 16 \rangle;$$

$$\text{ATCA}(\mathcal{X}, 11000) = \langle Y_1, Y_2, Y_4 \rangle; \text{ATCA}(\mathcal{X}, 00101) = \langle Y_1, Y_2, Y_3, Y_4 \rangle;$$

$$\text{ATCA}(\mathcal{X}, 10101) = \langle Y_2, Y_4 \rangle; \text{ATCA}(\mathcal{X}, 11111) = \langle Y_2, Y_3, Y_4 \rangle;$$

$$\text{ATCA}(\mathcal{X}, 01010) = \langle Y_2 \rangle; \text{ATCA}(\mathcal{X}, 00111) = \langle Y_1 \rangle;$$

$$\text{ATCA}(\mathcal{X}, 00000) = \langle Y_1, Y_3 \rangle; \text{ATCA}(\mathcal{X}, 11100) = \langle Y_3 \rangle.$$

Thus, we have the following table $T(A, \mathcal{X})$ specifying the functions $f(A, \mathcal{X}, u)$ for $u \in \text{INF}(A)$:

u	y_1	y_2	y_3	y_4
11000	$1/3$	$1/3$		$1/3$
00101	$1/4$	$1/4$	$1/4$	$1/4$
10101		$1/2$		$1/2$
11111		$1/4$	$1/2$	$1/4$
01010		1		
00111	1			
00000	$2/3$		$1/3$	
11100		1		

□

Let us denote by $[A, \mathcal{X}]$ the extension of the data table corresponding to A by the columns corresponding to the characteristic functions of sets from \mathcal{X} .

One can show that the table $T(A, \mathcal{X})$ can be constructed from $[A, \mathcal{X}]$ in the number of steps of order $O(n^2(m+k))$, where $n=|U|$, $m=|A|$, and $k=|\mathcal{X}|$.

Let us observe that by a slight modification of the construction of the table $T(A, \mathcal{X})$ one can obtain a table for computing the belief and plausibility functions of the information systems [S91, SG91]. This modification can be realized by adding to $T(A, \mathcal{X})$ one additional column in which on the position corresponding to u the cardinality of u_A is stored.

After such a modification one can easily compute the A -basic probability assignment $m_A(\theta)$ for any non-empty set θ of atoms. It is sufficient, in fact, i) to find all rows with non-empty entries corresponding exactly to elements of θ , ii) compute the sum s of all numbers appearing in the last column of these rows, and iii) put $m_A(\theta) = s/|U|$.

Now we are ready to present a simple method for computing the rm-function values.

We assume that the family $\{f(A, \mathcal{X}, w)\}_{w \in \text{INF}(A)}$ is represented by its data table $T(A, \mathcal{X})$ in the way described before. We also assume that the information system A is represented in the standard way by its data table. The data table of a given information system A is extended by one additional column containing for any $x \in U$ a pointer to the row labelled by $\text{Inf}_A(x)$ in the table $T(A, \mathcal{X})$. A set X of objects is represented by marking all columns in the table $T(A, \mathcal{X})$ corresponding to atoms included in X .

ROUGH MEMBERSHIP FUNCTION PROCEDURE :

INPUT: representations of \mathcal{X} , A , $\{f(A, \mathcal{X}, w)\}_{w \in \text{INF}(A)}$ and $X \in \mathcal{B}(\mathcal{X})$ in the form described above.

OUTPUT: μ_X^A .

1. For any $x \in U$ perform the following steps:

1.1 For a given x find in the table $T(A, \mathcal{X})$ the row corresponding to $u = \text{Inf}_A(x)$;

1.2 Compute $\mu_X^A(x) = \sum f(A, \mathcal{X}, w)(Y)$,

where the above sum is taken for all Y such that i) the entry in $T(A, \mathcal{X})$ corresponding to the column labelled by Y and the row labelled by u is nonempty and ii) Y corresponds to a marked column in $T(A, \mathcal{X})$.

The correctness of this method follows from Proposition 2 (part (ix)) and from the construction of the table $T(A, \mathcal{X})$. One can see that the sum in Step 1.2 is taken for all $Y \in \mathcal{Y} \cap \text{AT}(A, \mathcal{X}, w)$, where \mathcal{Y} is a set of atoms such that $X = \bigcup \mathcal{Y}$.

The number of steps to realize Step 2 is of order $O(n^2)$ (at most n additions for each w), where $n = |U|$.

Example 2. (continuation of Example 1).

Let $X = X_1 \cup X_2$. We have $X = X_1 \cap X_2 \cup X_1 \cap \neg X_2 \cup \neg X_1 \cap X_2 = Y_1 \cup Y_2 \cup Y_3$. Hence $\mathcal{Y} = \{Y_1, Y_2, Y_3\}$.

Let $x=7$. Then $\text{Inf}_A(7) = 10101$,

$\mathcal{Y} \cap \text{AT}(A, \mathcal{X}, 10101) = \{Y_2\}$

and $\mu_X^A(7) = f(A, \mathcal{X}, 10101)(Y_2) = 1/2$.

Let $x = 6$. Then $\text{Inf}_A(6) = 11111$,

$$V \cap \text{AT}(A, X, 11111) = \langle Y_2, Y_3 \rangle,$$

$$\begin{aligned} \text{and } \mu_X^A(6) &= f(A, X, 11111)(Y_2) + f(A, X, 11111)(Y_3) \\ &= 1/4 + 1/2 = 3/4. \end{aligned}$$

□

Conclusions

We introduced the rough membership functions (rm-functions) as a new tool for reasoning with uncertainty. The definition of those functions is based on the observation that objects are classified by means of partial information which is available. That definition allows us to overcome some problems which may be encountered if we used other approaches (like the ones mentioned in Section 5). We have investigated the properties of the rm-functions and in particular, we have shown that the rm-functions are computable in an algorithmic way, so that, their values can be derived without the help of an expert.

We would also like to point out one important topic for further research based on the presented here results. Our rm-functions are defined relatively to information systems. We will look for a calculus with rules based on properties of rm-functions and also on belief and plausibility functions for information systems. One important problem to be studied is the definition of strategies which can allow to reconstruct those rules when the information systems are modified by environment. In some sense we would like to embed a non-monotonic reasoning on our rm-functions approach as well as the belief and plausibility functions related to the information systems [Sh76, S91, SG91].

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