# Scientific Computing in the $\mathbf{C}^{\mathbf{H}}$ Programming Language 

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#### Abstract

We have developed a general-purpose block-structured interpretive programming language. The syntax and semantics of this language called $\mathrm{C}^{\mathrm{H}}$ are similar to $\mathrm{C} . \mathrm{C}^{\mathrm{H}}$ retains most features of C from the scientific computing point of view. In this paper, the extension of C to $\mathrm{C}^{\mathrm{H}}$ for numerical computation of real numbers will be described. Metanumbers of $-0.0,0.0, \operatorname{Inf},-\operatorname{lnf}$, and NaN are introduced in $\mathrm{C}^{\mathrm{H}}$. Through these metanumbers, the power of the IEEE 754 arithmetic standard is easily available to the programmer. These metanumbers are extended to commonly used mathematical functions in the spirit of the IEEE 754 standard and ANSI C. The definitions for manipulation of these metanumbers in I/O; arithmetic, relational, and logic operations; and built-in polymorphic mathematical functions are defined. The capabilities of bitwise, assignment, address and indirection, increment and decrement, as well as type conversion operations in ANSI $C$ are extended in $\mathrm{C}^{H}$. In this paper, mainly new linguistic features of $\mathrm{C}^{\mathrm{H}}$ in comparison to C will be described. Example programs programmed in $\mathrm{C}^{H}$ with metanumbers and polymorphic mathematical functions will demonstrate capabilities of $\mathrm{C}^{\mathrm{H}}$ in scientific computing. © 1994 John Wiley \& Sons, Inc.


## 1 INTRODUCTION

We have developed a general-purpose blockstructured interpretive programming language. Due to our research interests, this language called $\mathrm{C}^{\mathrm{H}}$ has been developed to be especially suitable for research and applications in scientific and system programming. $\mathrm{C}^{\mathrm{H}}$ is expressive with modern programming constructs and rich sets of data types and operators. At its current implementation, $\mathrm{C}^{\mathrm{H}}$ supports most features of the C programming language except data structures. Some

[^0]rough edges incompatible with the ANSI C [1] will be smoothed out in the future. By then, one may consider $\mathrm{C}^{\mathrm{H}}$ as a C language with High-level extensions. $\mathrm{C}^{\mathrm{H}}$ extends the capabilities of C in many aspects. $\mathrm{C}^{\mathrm{H}}$ not only supports C 's basic data types such as int and float, but also provides many additional data types such as complex and others. The handling of complex and dual numbers in $\mathrm{C}^{\mathrm{H}}$ are described by Cheng [2, 3]. The constants, variables, and operators of new data types in $\mathrm{C}^{\mathrm{H}}$ follow the same syntax rules of basic data types such as int and float. C, a modern language originally invented for the Unix system programming [ $4, \tilde{0}]$, is commonly regarded as a mid-level computer language. $\mathrm{C}^{\mathrm{H}}$ retains low-level features of C with respect to interface to hardware. However, $\mathrm{C}^{\mathrm{H}}$ is a high-level language, designed for both novice users and experienced programmers. If one
makes mistakes in a $\mathrm{C}^{\mathrm{H}}$ program, the system will prompt informative warning or error messages for the debugging of the program.
$\mathrm{C}^{\mathrm{H}}$ is a language designed for both scientific and system programming. Currently, Fortran [6, 7] and C are the two predominant computer languages for scientific computing. $\mathrm{C}^{\mathrm{H}}$ has been designed to make the porting of both Fortran and C code to $\mathrm{C}^{\mathrm{H}}$ as easy as possible. However, as the name of the language implies, whenever there is a syntax conflict between C and other languages, the interpretation will follow that of C. As a result, the syntax and semantics of $\mathrm{C}^{\mathrm{H}}$ are similar to those of C in many aspects. Therefore, unless indicated otherwise, all code fragments included in this paper will have the same implications as those in the ANSI C. The detailed explanations for each single line of code presented in this paper will not be given.

In this paper, the scientific computing aspect of the $\mathrm{C}^{\mathrm{H}}$ language will be addressed. $\mathrm{C}^{\mathrm{H}}$ retains most features of C from the scientific computing point of view. The ANSI/IEEE 754 standard for binary floating-point arithmetic $[8,9]$ is a significant milestone on the road to consistent floatingpoint arithmetic with respect to real numbers. This standard has significantly influenced the design of $\mathrm{C}^{\mathrm{H}}$. The IEEE 754 standard distinguishes +0.0 from -0.0 , which introduces an extra complexity for programming. The rationale for this extra complexity is not well understood and accepted by all computer scientists and C experts [10]. Many have challenged the necessity for the sign of zeros. Apparently, how to handle best "the sign of nothing" is still a topic to be further investigated. Another important feature of the IEEE 754 standard is the internal representation for mathematical infinity and invalid value. The mathematical infinity $\infty$ is represented by the symbol of Inf. A mathematically indeterminate or an undefined value such as division of zero by zero is represented by NaN , which stands for Not-aNumber. Many computer hardware have signed zeros, infinity, and NaN [11, 12]. Information about low-level and limited high-level instruction sets provided by hardware vendors may not be relevant to the application programmer and most features of a final system depend on the software implementation. Even for IEEE machines, if there is no provision for propagating the sign of zeros, infinity, and NaN in a consistent and useful manner through the software support, they will have to be programmed as if zeros are unsigned without infinity and NaN. For example, the proposed Ada
standard does not distinguish -0.0 from 0.0 and has no provision for consistent handling of infinity and NaN [13-18]. As another example, the standard mathematical C library implemented by Plauger [10] has provisions for signed infinities and NaN, but zeros are unsigned. Based on IEEE machines, some vendors provide software support for the IEEE 754 standard through libraries [1921]. However, these special values in libraries are not transparent to the programmer. Due to different design considerations, they have defined different values for many operations and functions discussed in this paper. For example, the SUN's mathematical library will deliver the following results: $\infty^{0}=1 ; N a N^{0}=1 ; 0^{0}=1 ;(-\infty)^{x}=\infty$; $(-\infty)^{-\infty}=0 ;(-\infty)^{0}=1 ;(-x)^{\infty}=\infty ;(-x)^{-\infty}=0 ;$ $(-\infty)^{-f}=0$, which differ from $\mathrm{C}^{\mathrm{H}}$. Although the application of symbols such as Inf and NaN can be found in some software packages, their handling of these special numbers are often time full of flaws. For example, one can find ComplexInfinity in the software package Mathematica [22], and Inf and NaN in MATLAB [23]. In Mathematica, there is no distinction between complex infinity and real infinities, nor between -0.0 and 0.0 ; therefore, many operations defined in this paper cannot be achieved in this package. In MATLAB, there is no complex infinity, and one will be surprised by some of its results. At one point, the sign of a zero is honored; but at other point, it may not. For example, according to the IEEE 754 standard, sqrt $(-0.0)$ should be -0.0 , but, $\mathbf{s q r t}(-0.0)=0.0$ in MATLAB (version 4.0, 1992). As another example, acosh(Inf) equals NaN whereas $\operatorname{acos}(\operatorname{Inf})$ is a complex NaN . Results of mathematical functions in many cases are not consistent with mathematical conventions. It is in these grey areas that the standard is not supported in many implementations of hardware and software systems.

To make the power of the IEEE 754 standard easily available to the programmer, the floatingpoint numbers of $-0.0,0.0, \operatorname{lnf},-\operatorname{lnf}$, and NaN , referred to as metanumbers, are introduced in $\mathrm{C}^{\mathrm{H}}$. These metanumbers are transparent to the programmer. Signed zeros +0.0 and -0.0 in $\mathrm{C}^{\mathrm{H}}$ behave like correctly signed infinitesimal quantities $0_{+}$and $0_{-}$; whereas symbols Inf and -Inf correspond to mathematical infinities $\infty$ and $-\infty$, respectively. The manipulation capabilities of Inf and NaN in $\mathrm{C}^{\mathrm{H}}$ go way beyond the scope use in mathematical software packages such as Mathematica and MATLAB. The integration of the metanumbers in the C programming language will be
described in this article. The IEEE 754 standard only addresses the arithmetic involving these metanumbers. In this article, these metanumbers are extended consistently to commonly used mathematical functions in the spirit of the IEEE 754 standard. The linguistic features of $\mathrm{C}^{\mathrm{H}}$, as it is currently implemented, in dealing with metanumbers will be presented in this article. The emphasis is placed on the handling of metanumbers in $\mathrm{I} / \mathrm{O}$; arithmetic, relational, and logic operations; and polymorphic mathematical functions. The concepts presented in this article have been extended to complex numbers in [2].

It should be mentioned that related to the work described in this article is the current effort pursued by Numerical C Extension Group (NCEG), the subcommittee X3J11.1 of the ANSI C X3J11 committee. The NCEG is working on floatingpoint C extension standard: to make features of the IEEE 754 standard available for use by programmers is one of its efforts. Reviewing its preliminary draft [24] for the proposed floating-point C extension standard reveals that some features presented in this article are in conformance with the proposed standard. However, there are many differences between $\mathrm{C}^{\mathrm{H}}$ and the proposal. For example, recognizing that operations like isnan ( x ) can be problematic in dealing with NaN , the proposal introduces eight additional relational operators of ! <>=, <>, $<>=,!<=,!<,!>=$, $!>,!<>$ on top of the existing operators $<,>$, $<=,>=,==,!=$. But, to preserve the clarity and succinctness of C , no additional relational operator has been introduced in $\mathrm{C}^{\mathrm{H}}$. The handling of NaN in $\mathrm{C}^{\mathrm{H}}$ will be described in detail in this paper. There is no -NaN in $\mathrm{C}^{\mathrm{H}}$ whereas the sign of NaN is honored in the proposal. The proposal suggests function overloading for elementary mathematical functions in C. However, unlike $\mathrm{C}^{++}$[25], there is no provision for function overloading in ANSI C. Consequently, mechanisms for function overloading are to be introduced, which will likely complicate the syntax of C. All mathematical functions are built polymorphically with optional auxiliary arguments into $\mathrm{C}^{\mathrm{H}}$ itself [2]. Therefore, unlike the proposal, there is no need in $\mathrm{C}^{\mathrm{H}}$ for distinction of functions $\log (\mathbf{x})$ and $\log 1 \mathrm{p}(\mathrm{x})$, which is expected to be more accurate than $\log ()$ for small magnitude of $x$ because these two functions can be easily reconciled inside $\mathrm{C}^{\mathrm{H}}$. The proposal introduces several new functions, most of which can be easily implemented as external functions in $\mathrm{C}^{\mathrm{H}}$. Due to different considerations, the design of $\mathrm{C}^{\mathrm{H}}$ is different from the pro-
posal in some other aspects. For example, $\mathrm{C}^{\mathrm{H}}$ is definitive; results of all operations and functions involving metanumbers are properly defined in $\mathrm{C}^{\mathrm{H}}$ whereas the proposal still leaves room for unspecified values. The proposed floating-point C extension is still at its preliminary stage. The final specification and actual language implementation of the proposed standard remain to be seen.

The rest of the paper is arranged as follows. Section 2 presents the number system in $\mathrm{C}^{\mathrm{H}}$. The different data types and their internal memory representations are described. Section 3 describes the external representations of numerical constants in $\mathrm{C}^{\mathrm{H}}$. Section 4 discusses the I/O extension of C to $\mathrm{C}^{\mathrm{H}}$ for numerical data and metanumbers. Section 5 defines arithmetic, relational, and logic operations involving metanumbers. In addition, the $\mathrm{C}^{\mathrm{H}}$ extensions of bitwise, assignment, address and indirection, increment and decrement operations, as well as explicit type conversions will be highlighted. Section 6 defines polymorphic mathematical functions with metanumbers as input arguments or as returned results. Example programs in Section 7 with metanumbers and polymorphic mathematical functions will demonstrate $\mathrm{C}^{\mathrm{H}}$ 's capabilities in scientific computing. Some conclusions will be made in section 8.

## 2 REAL NUMBERS IN CH

$\mathrm{C}^{\mathrm{H}}$ is a loosely typed language. The $\mathrm{C}^{\mathrm{H}}$ programming language has a rich set of data types. Lnlike languages such as Pascal [26], which prohibits automatic type conversion, one data type in $\mathrm{C}^{\mathrm{H}}$ can be automatically converted to another data type if it makes sense in context. As it is currently implemented, $\mathrm{C}^{\mathrm{H}}$ encapsulates Fortran's four numeric data types of integer, real, double precision, and complex. Programming with complex numbers in $\mathrm{C}^{\mathrm{H}}$ will be described [2]. In this paper, we discuss only the real numbers directly related to scientific computing. The formats of these data stored in a computer memory depend on the machine architecture in use. How these numbers are internally represented in a computer system for manipulation inside $\mathrm{C}^{\mathrm{H}}$ will be illustrated in this section. The discussion is based on the architecture of the RISC processor for SUN SPARCStations [20]. But, ideas are applicable to all IEEE machines. Data types of short, unsigned, long double, double complex, and long double complex are not available in $\mathrm{C}^{\mathrm{H}}$ at its current implementation, mainly because our applications of $\mathrm{C}^{\mathrm{H}}$
can bypass these data types. As users' base of $\mathrm{C}^{\mathrm{H}}$ increases, they will be supported in the future if necessary.

### 2.1 Integers

Integer is a basic data type for any computer language. An integer in $\mathrm{C}^{\mathrm{H}}$ can be represented in data types of char or int. Numerical manipulations of char and int data in $\mathrm{C}^{\mathrm{H}}$ follow the rules defined in ANSI C.

### 2.1.1 Char Data Representation

The char data are used to store characters such as letters and punctuations. An array of char can be used to store a string. A character is actually stored in integer according to a certain numerical code such as the ASCII code. Under this code, certain integers represent certain characters. The standard ASCII code ranges from 0 to 127 , which

### 2.1.2 Int Data Representation

An int data is a signed integer in $\mathrm{C}^{\mathrm{H}}$. An int number is a whole number that can be negative, positive, or zero. The int ranges from INT_MIN to INT_MAX. The parameters INT_MIN and INT_MAX, defined in the ANSI C standard header limits.h, are precalculated system constants in $\mathrm{C}^{\mathrm{H}}$. Unlike some of C 's implementations, in which an int data may occupy only 2 bytes, an int data uses 4 bytes ( 32 bits) for storage with 1 bit for sign in $\mathrm{C}^{\mathrm{H}}$. Negative numbers are stored in 4-byte two's complement minus 1 . The values of INT_MIN and INT_MAX then become $-2147483648\left(2^{31}\right)$ and 2147483647 , respectively. The int type of $\mathrm{C}^{\mathrm{H}}$ is the same as the int data type defined in the ANSI C. Operations such as addition, subtraction, multiplication, and division in $\mathrm{C}^{\mathrm{H}}$ are fully compatible with those defined in the ANSI C. For example, the following statements are valid in $\mathrm{C}^{\mathrm{H}}$.

```
char c[2][3], *cptr;
int i, *iptr; /* /# comment */
c[0][1] = 'a'; /# c[0][1] becomes 'a' */
i = c[0] [ 1]; /# /* i becomes 97, ASCII number for 'a' */
c[1,2] = i+1 /* c[1,2] becomes 'b', ASCII number for 'b' is 98 */
i += c[1 , 2]; /# i becomes 194 = 97 +97
iptr =&i; /* iptr points to address of i */
*iptr /= 2; /* i becomes 97 = 194/2 */
```

needs only 7 bits to represent. In $\mathrm{C}^{\mathrm{H}}$, the char variable is a signed integer ranging from CHAR_ MIN to CHAR_MAX. The parameters CHAR_ MIN and CHAR_MAX, defined in the ANSI C standard header limits. $h$, are system constants in $\mathrm{C}^{\mathrm{H}}$. Typically, a char constant or variable occupies 1 byte of unit memory. Bit 8 is a sign bit. The maximum positive integer for a signed 1 -byte representation is 127 or 01111111 in the binary form. A negative number is stored as the binary complement of its absolute value minus 1. For example, the decimal value of -2 is determined by the binary value of 11111110 in an 1 -byte two's complement value as

$$
\operatorname{com}(11111110)_{2}=(00000001+1)_{2}=(10)_{2}
$$

where the subscript of 2 indicates the base of the integer number. The minimum integer values for a signed char is $\mathbf{1 2 8}$ or 10000000 in binary form. The range of integers for a char is then from -128 to +127 .

Like C, comments of a $\mathrm{C}^{\mathrm{H}}$ program can be enclosed within a pair of delimiters $/ *$ and $* /$. These two comment delimiters cannot be nested. In addition, the symbol / \# in $\mathrm{C}^{\mathrm{H}}$ will comment out a subsequent text terminated at the end of a line. A /\# can be used to comment out $/ *$ or $* /$ and $/ * * /$ can be used to comment out / \#. These two companion methods provide a convenient mechanism to comment out a section of $\mathrm{C}^{\mathrm{H}}$ code that contains comments. When a comment does not start at the beginning of a line, the use of / \# is recommended for $\mathrm{C}^{\mathrm{H}}$ programs. It should be mentioned that, in ANSI C, a combined use of preprocessor directives \#if, \#elif, \#else, and \#endif can also comment out a section of C code. Note that arrays in $\mathrm{C}^{\mathrm{H}}$ can be declared and accessed by c[i] [j] or c[i,j]. The former is in ANSI C style whereas the latter has a Fortran flavor. All white space and tab characters will be ignored in the $\mathrm{C}^{\mathrm{H}}$ program, except when they are characters within a string. A program using invisible characters such as a tab character as delimit-
ers and control sequences is very difficult to debug. Such design examples are not difficult to find in computer systems.

### 2.2 Real Numbers

The integer data type serves well for some software development projects, especially for system programming. However, for scientific computing, the floating-point numbers are used extensively. The floating-point numbers correspond to real numbers that include the numbers between integers. These numbers are defined in $\mathrm{C}^{\mathrm{H}}$ as float or double, which are equivalent to real and double precision in Fortran, respectively. Floating-point numbers are analogous to the representations of numbers in scientific notion. Floating-point arithmetic is complicated as compared with the integer arithmetic. This paper mainly addresses issues related to the floating-point operations and built-in functions in $\mathrm{C}^{\mathrm{H}}$.

The most common implementation of floatingpoint arithmetic is based upon the IEEE 754 standard. In this standard, a float or double is represented in the form of

$$
\begin{equation*}
(-1)^{\text {sign }} 2^{\text {exponent-bias }} 1 . f \tag{1}
\end{equation*}
$$

where $1 . f$ is the significand and $f$ is the bit in the significand fraction. This normalized float or double number contains a "hidden" bit because it
has one more bit of precision than would otherwise be the case.

### 2.2.1 Float Data Representation

The float data type uses 32 bits for its storage. The result of a float data is formulated as

$$
\begin{equation*}
(-1)^{\text {sign }} 2^{\text {exponent }-127} 1 . f \tag{2}
\end{equation*}
$$

Bit 31 is a sign bit; it is 1 if the number is negative. Eight-bit exponent of bits 23 to 30 is biased by 127; values of all zeros and all ones are reserved for metanumbers. Bits 0 to 22 are the fraction component of a normalized significand. The leading integer value 1 of the normalized significand is hidden. The hexadecimal representations of some typical float numbers are given in Table 1. For example, according to Equation (2), float numbers 1.0 and -2.0 can be obtained by $(-1)^{0} 2^{127-127} 1.0=1.0$ and $(-1)^{1} 2^{128-127} 1.0=$ 2.0 , respectively. Remember that the fraction of the normalized significand is stored in a binary fraction. The float number 3.0 can be calculated by $(-1)^{0} 2^{128-127}(1.1)_{2}=2 *(1.1)_{2}=2 *(1.5)_{10}=$ $(3.0)_{10}$ where subscripts indicate the base of the floating-point number. Note that the IEEE 754 standard distinguishes +0.0 from -0.0 for float-ing-point numbers. For user's convenience, these two constants are predefined as system constants Zero and NZero in $\mathrm{C}^{\mathrm{H}}$. NZero stands for negativezero.

Table 1. Hexadecimal Representation of Selected Real Numbers

| Value | Float | Double |
| ---: | :---: | :---: |
| 0.0 | 00000000 | 0000000000000000 |
| -0.0 | 80000000 | 8000000000000000 |
| 1.0 | $3 F 800000$ | $3 F F 0000000000000$ |
| -1.0 | BF800000 | BFF0000000000000 |
| 2.0 | 40000000 | 4000000000000000 |
| -2.0 | C0000000 | C0000000000000000 |
| 3.0 | 40400000 | 4080000000000000 |
| -3.0 | C0400000 | C080000000000000 |
| Inf | 7F800000 | 7FF0000000000000 |
| -Inf | FF800000 | FFF0000000000000 |
| NaN | 7FFFFFFF | 7FFFFFFFFFFFFFFF |
| FLT_MAX | 7F7FFFFF |  |
| DBL_MAX |  | 7FEFFFFFFFFFFFFF |
| FLT_MIN | $007 F F F F F$ |  |
| DBL_MIN |  | $000 F F F F F F F F F F F F F$ |
| FLT_MINIMUM | 00000001 |  |
| DBL_MINIMUM |  | 0000000000000001 |

The parameter FLT_MAX, defined as the maximum representable finite floating-point number in the float data type in the ANSI C standard header float. h , is a precalculated system constant in $\mathrm{C}^{\mathrm{H}}$. As mentioned before, that 8 -bit exponent of bits 23 to 30 is biased by 127 ; values of all ones for 8 -bit exponent of bits 23 to 30 are reserved for metanumbers. If a number is larger than FLT_MAX, which is called an overflow, it will be represented by the symbol of Inf, which corresponds to the mathematical infinity $\infty$. This is the result of many operations such as division of a finite number by zero although an inexact exception may be raised in an IEEE machine. In the same manner, if a number is less than -FLT_MAX, it will be represented by -Inf, which is equivalent to the negative infinity $-\infty$.

The value of the parameter FLT_MIN is defined in the ANSI C standard library header float. h as a minimum normalized positive float-ing-point float number. If a number is less than FLT_MIN, it is called an underflow. The IEEE 754 standard provides a gradual underflow. When a number is too small for a normalized representation, leading zeros are placed in the significand to produce a denormalized representation. A denormalized number is a nonzero number that is not normalized and whose exponent is the minimum exponent for the storage type. The maximum representable positive denormalized float is defined as FLT_MINIMUM in $\mathrm{C}^{H}$ as shown in Table 1. There is only one unit in the last place for FLT_MINIMUM so that it is commonly referred to as ulp. Almost all floating-point implementations substitute the value zero for a value that is smaller than FLT_MINIMUM for IEEE machines, FLT_MIN for non-IEEE machines. However, in the arithmetic operations and mathematical functions defined in $\mathrm{C}^{\mathrm{H}}$, there is a qualitative difference between FLT_MINIMUM which is smaller than FLT_MIN and zero. In this paper, by the value of 0.0 means that it is a zero, not a small number. The $\mathrm{C}^{\mathrm{H}}$ expressions of $0 ., 0.00$, and .0 are the same as 0.0 . In the same token, the following $\mathrm{C}^{\mathrm{H}}$ floating-point constant expressions - 0.0 , $-0 .,-0.00$, and -.0 are equivalent. Mathematically, divisions of zero by zero of $0.0 / 0.0$ and infinity by infinity of $\infty / \infty$ are indeterminate. The results of these operations are represented by the symbol of NaN , which stands for Not-a-Number. It should be mentioned that the IEEE 754 standard distinguishes quiet NaN from signaling NaN . The signaling NaN should generate a signal or raise an exception. In $\mathrm{C}^{\mathrm{H}}$, all NaNs are treated as quiet NaNs. Furthermore, the IEEE 754 standard
does not interpret the sign of NaN. However, many floating-point arithmetic implementations such as in the SUN's ANSI C. Apple's Standard Apple Numeric Environment, and preliminary proposed floating-point C extensions distinguish NaN from -NaN . But, from the user's point of view, what is the difference between a negative Not-a-Number and a positive Not-a-Number? After all, Not-a-Number is not a number. Therefore, no - NaN will be produced as a result of arithmetic and functions in $\mathrm{C}^{\mathrm{H}}$ although it can be created by manipulating the bit pattern of the memory location of a float variable. The expression -NaN is interpreted as NaN in $\mathrm{C}^{\mathrm{H}}$. The metanumbers are treated just as regular floating-point numbers. The internal hexadecimal representations of the metanumbers for the float type are also given in Table 1.

### 2.2.2 Double Data Representation

For a large range of representable floating-point numbers, a double data can be used in $\mathrm{C}^{\mathrm{H}}$. The double data type uses 64 bits as its storage. The result of the double data is formulated as

$$
\begin{equation*}
(-1)^{\operatorname{sign}} 2 \text { exponent-1023 } 1 . f \tag{3}
\end{equation*}
$$

Bit 63 is a sign bit; it is 1 if the number is negative. Eleven-bit exponent of bits 52 to 62 is biased by 1023; values of all zeros and all ones are reserved for metanumbers. Bits 0 to 51 are fractional components of normalized significands. Like float, the integral value 1 of the normalized significand is hidden. The hexadecimal representation of some typical double numbers are also given in Table 1. Note that the width and bias value of the exponent of double is different from those of float. Therefore, a float cannot be converted into a double just by padding zeros in its fraction. On the other hand, when a double data is cast into a float, the result cannot be obtained just by ignoring the values in bits 0 to 31 . Note that there is no external distinction between float Inf and double Inf although their internal representations differ. This is also true for metanumbers -Inf and NaN. Similar to float, parameters DBL_MAX, DBL_MIN, and DBL_MINIMUM are precalculated constants in $\mathrm{C}^{\mathrm{H}}$. The internal memory representations of these special finite double floating-point numbers are also given in Table 1. Note that due to the finite precision of the floatingpoint number representation, the exact values of irrational numbers such as $\pi$ are not representable in a computer system whether they are represented in float or double.

## 3 CONSTANTS OF REAL NUMBERS

In this section, we will describe the external representations of data types discussed in the previous section. Besides declared variables and system defined parameters, all different data types in $\mathrm{C}^{\mathrm{H}}$ can have their corresponding constants at the programmer's disposal.

Char and int constants in $\mathrm{C}^{\mathrm{H}}$ are in full compliance with the ANSI C standard. A character constant, stored as an integer, can be written as one character within a pair of single quotes like ' x '. Character constants enclosed in a pair of single quotes cannot contain the ' character. In order to represent the ' character and certain other characters such as a newline character, the escape sequence may be used. For example, $c=$ ' $\backslash$ ' ' will assign the ' character to $c$ whereas $c=$ ' $\backslash n$ ' will give $c$ a newline character.

A decimal integer constant like 12345 is an int. An integer can also be specified in octal or hexadecimal instead of decimal. A leading 0 (zero) on an integer constant indicates an octal integer whereas a leading $0 x$ or $0 X$ means hexadecimal. Besides these integral values defined in ANSI C, $\mathrm{C}^{\mathrm{H}}$ introduces a binary constant with leading 0 b or $0 B$. For example, decimal 30 can be written as 036 in octal, 0X1e or $0 \times 1 \mathrm{E}$ in hexadecimal, and 0b11110 or OB11110 in binary. Note that expressions like 029 and 0 b211 are illegal, which can be detected by $\mathrm{C}^{\mathrm{H}}$.

The value of 0 in $\mathrm{C}^{\mathrm{H}}$ means that it is an integer zero. Unlike real numbers, there is no $0_{-}$in int. Therefore, the integer value of -0 equals 0 in $\mathrm{C}^{\mathrm{H}}$. The domain [-FLT_MAX, FLT_MAX] of real numbers is larger than the domain [-INT_MIN, INT_MAX] of integer numbers. When a real number smaller than INT_MIN, including -Inf, is converted to an integer, the result is INT_MIN. For a real number larger than $\mathrm{INT}_{-}$MAX, including Inf, the converted integral value is INT_MAX. When NaN is assigned to an integral variable, the system will print a warning message, and the resultant integral value becomes INT_MAX whose memory map is the same as that of NaN .

In $K \& R \mathrm{C}[27,28]$ all floats in expressions are converted into doubles before evaluation. As a result, any operations involving floating-point operands, even with two float operands, will produce
a double result. This is not applicable to many scientific computations in which speed and memory of a program are critical. The inconvenient floating-point operation modes for 32- and 64-bit operands of the original hardware platform, a PDP-11/45 FPP, for running $C$ programs was a major factor in the design of this implicit data conversion of $\mathrm{K} \& \mathrm{R} \mathrm{C}[10,29]$. Although this indiscriminate conversion is sometimes complemented with a positive tone for its generosity, it is harshly criticized by the numerically oriented scientific programmers as a language design fault [30]. Because of the indiscriminate conversion rules in the early design of $C$, every floating-point constant like 3.5 and 3 e 7 is taken as double. This default double mode for floating-point constants has been carried over to the ANSI C standard. However, the ANSI $C$ has provided a mechanism to specify a float constant. The suffixes $F$ or $f$ indicate a float constant.

In regards to the default data type of floatingtype constants, $\mathrm{C}^{\mathrm{H}}$ follows the lead of Fortran, but with an ANSI C modern syntax style. Floatingpoint numbers are represented in scientific notation. All floating-point constants such as 2.4, $2 e+3,-2 . E-3$, and $+2.1 e 3$ are float constants by default because, in most applications, a float-ing-point constant with a small number of digits after a decimal point is intended to be float. This default mode, however, can be switched by the function floatconst(onoff). After execution of command floatconst(FALSE), the aforementioned floating-point constants will be taken as double. However, the default mode can always be overruled by the suffixes $F$ or $f$ for float, $D$ or $d$ for double. For example, constants $3.4 e 3 F, 3 E-3 f$, and $3 e+3 F$ are floats whereas constants $3.4 e 3 D$, $3 E-3 d$, and $3 e+3 D$ are doubles regardless of the default mode for floating-point constants. However, the constant metanumbers Zero, NZero, $\pm \operatorname{Inf}$, and NaN are always taken as floats unless they are values of double variables. According to this design, the range of representable floating-point numbers can be expanded automatically. For example, the values of FLT_MAX and DBL_MAX for SUN SPARCStations are $3.4 e 38$ and $1.8 e 308$, respectively. The following $\mathrm{C}^{\mathrm{H}}$ program

```
printf("pow(10.0, 39) < Inf is %d /n", pow(10.0, 39) < Inf);
floatconst (FALSE) ;
printf("pow(10.0, 39) < Inf is %d /n", pow(10.0, 39) < Inf);
```

will print out

$$
\begin{aligned}
& \text { pow }(10.0,39)<\operatorname{Inf} \text { is } 0 \\
& \text { pow }(10.0,39)<\operatorname{Inf} \text { is } 1
\end{aligned}
$$

In the first statement of the program, the value of $10^{39}$ calculated by pow $(10.0,39)$ has overflowed as Inf because it is larger than FLT_MAX. By switching the default mode of floating-point constants to double through the function floatconst(FALSE), the value of $10^{39}$ calculated by $\operatorname{pow}(10.0,39)$ in double data is still within the representable range of -DBL_MAX $<$ pow $(10.0$, 39) < DBL_MAX. In the second case, the metanumber $\operatorname{Inf}$ is expanded as a double infinity larger than DBL_MAX. The float mode for float-ing-point constants can be switched back by the command floatconst(TRUE). With this mode switching function, both Fortran and C codes can be ported to $\mathrm{C}^{\mathrm{H}}$ conveniently. Details about relational operator < and polymorphic function pow() will be discussed in Sections 5 and 6, respectively. In the remaining presentation of this paper, we assume that the default mode for floating-point constants is float.

## 4 I/O FOR REAL NUMBERS

In ANSI C, the input of integers and floating-point numbers is obtained through the standard I/O functions $\boldsymbol{\operatorname { s c a n f }}()$, fscanf$(1)$, and etc.; the output is accomplished using the function printf(), fprintf(), and etc. These functions are also available in $\mathrm{C}^{\mathrm{H}}$ and will be in full compliance with the ANSI C standard. However, implementation of these functions in $\mathrm{C}^{\mathrm{H}}$ is different from C . In this section, the differences of these functions between $\mathrm{C}^{\mathrm{H}}$ and C , and enhancements of these functions in $\mathrm{C}^{\mathrm{H}}$ will be discussed.

The major difference of these functions between $\mathrm{C}^{\mathrm{H}}$ and C is that these functions are built-in internal functions in $\mathrm{C}^{\mathrm{H}}$ whereas they are external functions in C. Therefore, they can be reconciled inside $\mathrm{C}^{\mathrm{H}}$ so that they are more flexible and pow-
erful. The standard input/output/error devices stdin/stdout/stderr defined in the ANSI C header stdio. $h$ are provided as system constants in $\mathrm{C}^{\mathrm{H}}$. The inclusion of header stdio. h in a program is, therefore, unnecessary in $\mathrm{C}^{\mathrm{H}}$. Other than this difference, a C programmer will not notice any difference in these functions between $\mathrm{C}^{\mathrm{H}}$ and C . But, these I/O functions in $\mathrm{C}^{\mathrm{H}}$ are enhanced. Here, we only briefly discuss the enhancements related to real numbers for the function printf(). The underlying principle can be applied to other I/O functions as well. The format of function printf() in $\mathrm{C}^{\mathrm{H}}$ is as follows
int printf(char *format, arg1, arg2, ...)
The function printf() prints output to the standard output device under the control of the string pointed to by format and returns the number of characters printed. If the format string contains two types of objects: ordinary characters and conversion specifications beginning with a character of $\%$ and ending with a conversion character, the ANSI C rules for printf() will be used. Besides the control characters specified by the ANSI C standard, $\mathrm{C}^{\mathrm{H}}$ has one more conversion character ' b ' that is used to print real numbers in binary format. An integer number between the symbol \% and the character ' $b$ ' specifies how many bits starting with bit 0 will be printed. If without an integer number between the symbol $\%$ and the character ' $b$ ', the default format will print int data without leading zeros, float data in 32 bits, and double data in 64 bits. This binary format is very convenient to examine the bit patterns of metanumbers. If the format string in printf() contains only ordinary characters, the subsequent numerical constants or variables will be printed according to preset default formats. The default format for int, float, and double are $\% \mathrm{~d}, \% .3 \mathrm{f}$, and $\%$ lf, respectively. The metanumbers $\operatorname{Inf}$ and NaN are treated as regular numbers in I/O functions. The default data types for these numbers are float. The following $\mathrm{C}^{\mathrm{H}}$ program illustrates how b format and metanumbers are handled by the I/O functions printf() and $\operatorname{scanf}()$.

```
float finf, fNaN;
double dInf, dNaN ;
printf ("Please type 'Inf NaN Inf NaN' \(\backslash n "\) );
scanf (\&fInf, \&fNaN, \&dInf, \&dNaN);
printf ("The float Inf \(=\% \mathrm{f} \backslash \mathrm{n}\) ", finf);
printf("The float \(-\operatorname{Inf}=",-f \operatorname{lnf}, " \backslash n ")\);
printf("The float \(\quad \mathrm{NaN}=\% \mathrm{f} \backslash \mathrm{n} ", \mathrm{fNaN}\) );
```

```
printf("The float Inf = %b \n", fInf);
printf("The float -Inf =%b \n", fInf);
printf("The float NaN = %b \n", fNaN);
printf("The double Inf =%lf\n", dInf);
printf("The double -Inf = ", -dInf, "\n");
printf("The double NaN = %lf \n", dNaN);
printf("The double Inf = %b \n", dInf);
printf("The double -Inf = %b \n", -dInf);
printf("The double NaN = %b \n", dNaN);
printf("The int 2 = %b \n", 2);
printf("The int 2 = %32b \n", 2);
printf("The int -2 = %b \n", -2);
printf("The float 0.0 = %b \n", 0.0);
printf("The float -0.0 = %b \n", -0.0);
printf("The float 1.0 = %b \n", 1.0);
printf("The float -1.0 = %b \n", -1.0);
printf("The float 2.0 = %b \n", 2.0);
printf("The float -2.0 = %b \n", -2.0);
```

The first two lines of the program declare two float variables flnf and $\mathfrak{f N a N}$, and two double variables dInf and dNaN . The function scanf() will get $\operatorname{Inf}$ and NaN for the declared variables from the standard input device, which is the terminal keyboard in this example. These metanumbers will be printed in default formats $\% .3 \mathrm{f}$ for float and $\%$ lf
for double. These numbers are also printed using the binary format $\%$ b. For comparison, the memory storage for integers of $\pm 2$, and floats of $\pm 0.0$, $\pm 1.0, \pm 2.0$ are printed. The result of the interactive execution of the above program is shown as follows

```
Please type 'Inf NaN Inf NaN'
Inf Nan Inf Nan
The float Inf = Inf
The float - Inf = - Inf
The float NaN = NaN
The float Inf = 01111111100000000000000000000000
The float -Inf = 11111111100000000000000000000000
The float NaN = 0111111111111111111111111111111111
The double Inf = Inf
The double -Inf = -Inf
The double NaN = NaN
The double Inf =
    0111111111110000000000000000000000000000000000000000000000000000
The double -Inf =
    1111111111110000000000000000000000000000000000000000000000000000
The double NaN =
    0111111111111111111111111111111111111111111111111111111111111111111111
The int 2 = 10
The int 2 = 00000000000000000000000000000010
The int -2 = 111111111111111111111111111111110
The float 0.0 = 00000000000000000000000000000000
The float -0.0 = 10000000000000000000000000000000
The float 1.0 = 00111111100000000000000000000000
The float -1.0 = 10111111100000000000000000000000
The float 2.0 = 01000000000000000000000000000000
The float -2.0 = 11000000000000000000000000000000
```

where the second line in italic is the input and the rest are the output of the program. For metanumbers Inf, -Inf, and NaN, there is no difference between float and double types from the user's point of view. It can be easily verified that the bitmappings of all these numbers in memory match with data representations discussed in the previous sections.

## 5 REAL OPERATIONS

In this section, the arithmetic, relational, logic, bitwise, assignment, address and indirection, increment and decrement operations, as well as explicit type conversions of real numbers in $\mathrm{C}^{\mathrm{H}}$ will be discussed. The operation precedence for different operators in $\mathrm{C}^{\mathrm{H}}$ is in full compliance with the ANSI C standard, except the new operator ${ }^{\wedge}$ ^ introduced in Section 5.2. Following the ANSI C standard, the algorithms and resultant data types of operations for floating-point numbers will depend on the data types of operands in $\mathrm{C}^{\mathrm{H}}$. The conversion rules for char, int, float, and double in $\mathrm{C}^{\mathrm{H}}$ follow the type conversion rules defined in the ANSI C standard. A data type that occupies less memory can be converted to a data type that occupies more memory space without loss of any information. For example, a char integer can be cast into int or float without problem. However, a reverse conversion may result in loss of information. The order of real numbers in $\mathrm{C}^{\mathrm{H}}$ ranges from char, int, float, to double. The char data type is the lowest and double the highest. Like the ANSI C, the algorithms and resultant data types of the operations depend on the data types of operands in $\mathrm{C}^{\mathrm{H}}$. For binary operations, such as addition, subtraction, multiplication, and division, the resultant data type will take the higher order data type of two operands. For example, addition of two float numbers will result in a float number whereas addition of a float number and a double number will become a double number.

The operation rules for regular real numbers and metanumbers in $\mathrm{C}^{\mathrm{H}}$ are presented in Tables 2 to 12. In Tables 2 to $12, \mathrm{x}, \mathrm{x} 1$, and x 2 are regular
positive normalized floating-point numbers in float or double; metanumbers $0.0,-0.0$, Inf. -Inf, and NaN are constants or the values of float or double variables. By default, the constant metanumbers are float constants.

### 5.1 Arithmetic Operations

For the negation operation shown in Table 2, the data type of the result is the same as the data type of the operand, a real number will change its sign by negation operation. There is no -NaN in $\mathrm{C}^{\mathrm{H}}$. The leading plus sign ' + ', a unary plus operator, in an expression such as $+57864-x$ will be ignored. It should be pointed out that the negation of a positive integer zero is still a positive zero. Based on two's complement representation of negative integer numbers discussed before, we cannot represent $\operatorname{Inf}$ and NaN in the int data type.

According to the IEEE 754 standard, some operations depend on the rounding mode. For example, in case of rounding toward zero, overflow will deliver FLT_MAX rather than Inf with the appropriate sign. This rounding mode is necessary for Fortran implementation and for machines that lack infinity. If the rounding mode is round toward $-\infty$, both $-0.0+0.0$ and $0.0-0.0$ deliver -0.0 rather than 0.0 . For scientific programming, consistency and determinancy are essential. $\mathrm{C}^{\mathrm{H}}$ is currently implemented using the default rounding mode of round to nearest so that overflow will result in Inf, and both $-0.0+0.0$ and $0.0-0.0$ deliver 0.0 as shown in Tables 3 and 4. Note that the modulus operator $\%$ in $\mathrm{C}^{\mathrm{H}}$ is ANSI C compatible.

For addition, subtraction, multiplication, and division operations shown in Tables 3 to 6 , the resultant data type will be double if any one of two operands is double; otherwise, the result is a float. The mathematically indeterminate expressions such as $\infty-\infty, \infty * 0.0, \infty / \infty$, and $0.0 / 0.0$ will result in NaNs. The values of $\pm 0.0$ play important roles in the multiplication and division operations. For example, a finite positive value of x 2 divided by 0.0 results in a positive infinity $+\infty$ whereas division by -0.0 will create a negative infinity $-\infty$.

Table 2. Negation Results

|  | Negation - |  |  |  |  |  |  |  |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: | ---: | :--- |
|  | Operand | $-\operatorname{Inf}$ | $-x 1$ | -0.0 | 0.0 | $x 2$ | $\operatorname{Inf}$ | NaN |
| Result | $\operatorname{Inf}$ | x 1 | 0.0 | -0.0 | -x 2 | $-\operatorname{Inf}$ | NaN |  |

Table 3. Addition Results

| Addition + |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Right Operand |  |  |  |  |  |  |
| Left Operand | $-\operatorname{Inf}$ | -x1 | -0.0 | 0.0 | x 2 | Inf | Na |
| Inf | NaN | Inf | Inf | Inf | Inf | Inf | NaN |
| y2 | - Inf | $\mathrm{y} 2-\mathrm{x} 1$ | y2 | y2 | $\mathrm{y}^{2}+\mathrm{x} 2$ | Inf | NaN |
| 0.0 | - Inf | -x1 | 0.0 | 0.0 | x 2 | Inf | NaN |
| -0.0 | $-\operatorname{lnf}$ | -x1 | -0.0 | 0.0 | $\times 2$ | Inf | NaN |
| -y1 | $-\operatorname{lnf}$ | - $\mathrm{y} 1-\mathrm{x} 1$ | -y1 | -y1 | $-\mathrm{y} 1+\mathrm{x} 2$ | Inf | Na.N |
| - Inf | - Inf | $-\operatorname{lnf}$ | - Inf | $-\operatorname{lnf}$ | $-\operatorname{lnf}$ | Yaर | Na |
| NaN | NaN | NaN | Na N | NaN | NaN | NaN | Na.N |

Table 4. Subtraction Results

| Subtraction - |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Right Operand |  |  |  |  |  |  |
| Left Operand | $-\operatorname{lnf}$ | -x1 | -0.0 | 0.0 | x 2 | Inf | Na . |
| Inf | Inf | Inf | Inf | Inf | Inf | NaN | NaN |
| y2 | Inf | $\mathrm{y} 2+\mathrm{x} 1$ | y2 | y2 | $\mathrm{y} 2-\mathrm{x} 2$ | $-\operatorname{Inf}$ | NaN |
| 0.0 | Inf | x 1 | 0.0 | 0.0 | -x2 | $-\operatorname{lnf}$ | NaN |
| -0.0 | Inf | x 1 | 0.0 | -0.0 | -x2 | $-\operatorname{Inf}$ | NaN |
| -y1 | Inf | $-\mathrm{y} 1+\mathrm{x} 1$ | -y1 | -y1 | -y1-x2 | $-\operatorname{lnf}$ | Na, |
| - Inf | NaN | - Inf | $-\operatorname{Inf}$ | $-\operatorname{Inf}$ | - Inf | $-\operatorname{Inf}$ | NaN |
| NaN | NaN | NaN | Na V | NaV | NaN | NaN | NaN |

Table 5. Multiplication Results
Multiplication *

| Left Operand | Right Operand |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $-\operatorname{Inf}$ | -x1 | -0.0 | 0.0 | x 2 | Inf | NaN |
| Inf | $-\operatorname{Inf}$ | $-\operatorname{Inf}$ | NaN | NaN | $\ln f$ | Inf | NaN |
| y2 | $-\operatorname{lnf}$ | $-\mathrm{y} 2 * \mathrm{x} 1$ | -0.0 | 0.0 | $\mathrm{y} 2 * \mathrm{x} 2$ | Inf | NaN |
| 0.0 | NaN | -0.0 | -0.0 | 0.0 | 0.0 | NaN | NaN |
| -0.0 | NaN | 0.0 | 0.0 | -0.0 | -0.0 | NaN | NaN |
| - y 1 | Inf | $\mathrm{y} 1 * \mathrm{x} 1$ | 0.0 | $-0.0$ | $-\mathrm{y} 1 * x 2$ | $-\operatorname{Inf}$ | NaN |
| - Inf | Inf | Inf | NaN | NaN | - Inf | - Inf | NaN |
| NaN | NaN | NaN | NaN | NaN | NaN | NaN | NaN |

Table 6. Division Results

| Division - |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Right Operand |  |  |  |  |  |  |
| Left Operand | - Inf | -x1 | -0.0 | 0.0 | x2 | Inf | NaN |
| Inf | NaN | -Inf | NaN | NaN | Inf | NaN | NaN |
| y2 | -0.0 | $-\mathrm{y} 2 / \mathrm{x} 1$ | $-\operatorname{lnf}$ | Inf | y $2 / \mathrm{x} 2$ | 0.0 | NaN |
| 0.0 | $-0.0$ | -0.0 | NaN | NaN | 0.0 | 0.0 | NaN |
| -0.0 | 0.0 | 0.0 | NaN | NaN | -0.0 | -0.0 | NaN |
| - y 1 | 0.0 | $\mathrm{y} 1 / \mathrm{x} 1$ | Inf | - Inf | - $\mathrm{y} 1 / \mathrm{x} 2$ | -0.0 | NaN |
| - Inf | NaN | Inf | Inf | $-\operatorname{Inf}$ | $-\operatorname{Inf}$ | NaN | NaN |
| NaN | NaN | NaN | NaN | NaN | NaN | NaN | NaN |

Table 7. Less Than Comparison Results
Less Than Comparison <

|  | Right Operand |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Left Operand | - Inf | -x 1 | -0.0 | 0.0 | x 2 | Inf | NaN |  |
| $\operatorname{Inf}$ | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |
| $\mathbf{y} 2$ | 0 | 0 | 0 | 0 | $\mathrm{y} 2<\mathrm{x} 2$ | $\mathbf{1}$ | 0 |  |
| 0.0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 |  |
| -0.0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 |  |
| $-\mathbf{y 1}$ | 0 | $-\mathrm{y} 1<-\mathrm{x} 1$ | 1 | 1 | 1 | 1 | 0 |  |
| $-\operatorname{lnf}$ | 0 | 1 | 1 | $\mathbf{1}$ | 1 | $\mathbf{1}$ | 0 |  |
| NaN | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |

If any one of operands of binary arithmetic operations is NaN , the result is NaN .

### 5.2 Relational Operations

For relational operations given in Tables 7-12, the result is always an integer with a logic value of 1 or 0 corresponding to TRUE or FALSE, which are predefined system constants. According to the IEEE 754 standard, there is a distinction between +0.0 and -0.0 for floating-point numbers. In $\mathrm{C}^{\mathrm{H}}$, the value of 0.0 means that the value approaches zero from positive numbers along the real line and it is a zero; the value of -0.0 means that the value approaches zero from negative numbers along the real line and it is infinitely smaller than 0.0 in many cases. Signed zeros +0.0 and -0.0 in a $\mathrm{C}^{\mathrm{H}}$ program behave like correctly signed infinitesimal quantities $0_{+}$and $0_{-}$, respectively. Although there is a distinction between -0.0 and 0.0 for floatingpoint numbers in many operations, according to the IEEE 754 standard, the comparison shall ignore the sign of zeros so that -0.0 equals 0.0 in relational operations. For the convenience of the programmer, two polymorphic logic operations
isposzero(x) and isnegzero(x) are introduced in $\mathrm{C}^{\mathrm{H}}$, which can test if the argument x is 0.0 or -0.0 . The argument x can be char, int, float, or double. If $\mathbf{x}$ is 0.0 , isposzero ( $\mathbf{x}$ ) and isnegzero ( $\mathbf{x}$ ) return 1 and 0 , respectively. If $\mathbf{x}$ is -0.0 , isposzero ( x ) and isnegzero ( x ) return 0 and 1 , respectively. If $x$ is a complex or dual number, only its real part will be used in these operations. More elaborative, but less frequently used, functions such as signbit ( x ) and copy$\operatorname{sign}(x, y)$ can be easily implemented as external functions in $\mathrm{C}^{\mathrm{H}}$. The value of -0.0 could be regarded different from 0.0 for comparison operations in $\mathrm{C}^{\mathrm{H}}$. For the convenience of porting C code to $\mathrm{C}^{\mathrm{H}}$, zero is unsigned in comparison operations. The equality for metanumbers has different implications in $\mathrm{C}^{\mathrm{H}}$. Two identical metanumbers are considered to be equal to each other. As a result, comparing two Infs or two NaNs will get logic TRUE. This is just for the convenience of programming because, mathematically, the infinity of $\infty$ and not-a-number of NaN are undefined values that cannot be compared with each other. Metanumbers of $\operatorname{Inf},-\operatorname{Inf}$, and NaN in $\mathrm{C}^{\mathrm{H}}$ are treated as regular floating-point numbers consistently in

Table 8. Less Than or Equal Comparison Results

| Less or Equal Comparison $<=$ |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Right Operand |  |  |  |  |  |  |
| Left Operand | - Inf | -x1 | -0.0 | 0.0 | $\times 2$ | Inf | NaN |
| Inf | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| $\mathrm{y}^{2}$ | 0 | 0 | 0 | 0 | $y 2<=x 2$ | 1 | 0 |
| 0.0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| -0.0 | 0 | 0 | 1 | 1 | 1 | 1 | 0 |
| -y1 | 0 | $-\mathrm{y} 1<=-\mathrm{x} 1$ | 1 | 1 | 1 | 1 | 0 |
| - Inf | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| NaN | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

Table 9. Equal Comparison Results

| Equal Comparison $==$ |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Left Operand | Right Operand |  |  |  |  |  |  |
|  | - Inf | -x1 | -0.0 | 0.0 | x2 | Inf | NaN |
| Inf | 0 | 0 | 0 | 0 | 0 | 1 | 0 |
| y2 | 0 | 0 | 0 | 0 | $\mathrm{y}^{2}=\mathrm{x} 2$ | 0 | 0 |
| 0.0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 |
| -0.0 | 0 | 0 | 1 | 1 | 0 | 0 | 0 |
| -y1 | 0 | $-\mathrm{y} 1==-\mathrm{x} 1$ | 0 | 0 | 0 | 0 | 0 |
| - Inf | 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| NaN | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

Table 10. Greater Than or Equal Comparison Results

| Greater or Equal Comparison $>=$ |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Right Operand |  |  |  |  |  |  |
| Left Operand | $-\operatorname{Inf}$ | -x1 | -0.0 | 0.0 | x2 | Inf | NaN |
| Inf | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| y2 | 1 | 1 | 1 | 1 | $\mathrm{y} 2>=\mathrm{x} 2$ | 0 | 0 |
| 0.0 | 1 | 1 | 1 | 1 | 0 | 0 | 0 |
| -0.0 | 1 | 1 | 1 | 1 | 0 | 0 | 0 |
| -y1 | 1 | $-\mathrm{y} 1>=-\mathrm{x} 1$ | 0 | 0 | 0 | 0 | 0 |
| - Inf | 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| NaN | 0 | 0 | 0 | 0 | 0 | 0 | 1 |

Table 11. Greater Than Comparison Results

| Greater Than Comparison > |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Right Operand |  |  |  |  |  |  |
| Left Operand | - Inf | -x1 | -0.0 | 0.0 | $\times 2$ | Inf | NaN |
| Inf | 1 | 1 | 1 | 1 | 1 | 0 | 0 |
| y2 | 1 | 1 | 1 | 1 | $\mathrm{y} 2>\mathrm{x} 2$ | 0 | 0 |
| 0.0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 |
| -0.0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 |
| -y1 | 1 | $-\mathrm{y} 1>=-\mathrm{x} 1$ | 0 | 0 | 0 | 0 | 0 |
| $-\operatorname{Inf}$ | 0 | - 0 | 0 | 0 | 0 | 0 | 0 |
| NaN | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Table 12. Not Equal Comparison Results

| Not Equal Comparison != |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Right Operand |  |  |  |  |  |  |
| Left Operand | - Inf | -x1 | -0.0 | 0.0 | x 2 | Inf | NaN |
| Inf | 1 | 1 | 1 | 1 | 1 | 0 | 1 |
| y2 | 1 | 1 | 1 | 1 | $\mathrm{y} 2!=\mathrm{x} 2$ | 1 | 1 |
| 0.0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| -0.0 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| -y1 | 1 | - $\mathrm{y} 1!=-\mathrm{x} 1$ | 1 | 1 | 1 | 1 | 1 |
| - Inf | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| NaN | 1 | 1 | 1 | 1 | 1 | 1 | 0 |

arithmetic, relational, and logic operations. There is no need to use functions such as isnan ( x ), isinf ( $x$ ), etc. as is introduced in some software packages and mathematical libraries according to the recommendation of the IEEE 754 standard. Note that NaN is unordered and does not compare equal to itself in the IEEE 754 standard. However, for the convenience of the programmer, NaN is handled in the same manner as Inf in $\mathrm{C}^{\mathrm{H}} . \mathrm{NaN}$ is still unordered, but it equals itself, which is the only place in which $\mathrm{C}^{\mathrm{H}}$ is not in compliance with the IEEE 754 standard. The difference from the standard is likely to cause arguments and resistances. However, with this slight change, programming with metanumbers is much cleaner than would otherwise be the case.

### 5.3 Logic Operations

In $C^{H}$, there are four logic operators ! , \&\&, $|\mid$, and ^^ corresponding to logic operations not, and, inclusive or, and exclusive or, respectively. The operations of $!,| |, \& \&$ in $\mathrm{C}^{\mathrm{H}}$ comply with the ANSI C standard. The operator ${ }^{\wedge}{ }^{\wedge}$ is introduced in $\mathrm{C}^{\mathrm{H}}$ due to the consideration of programming convenience and orthogonality between logic operators and bitwise operators. Note that, like ANSI C, both the \&\& and $\left|\mid\right.$ operations in $\mathrm{C}^{\mathrm{H}}$ permit the right operand to be evaluated only if the left operand evaluates to TRUE and FALSE, respectively. This "short circuit" behavior for the " "operator does not exist because, for either TRUE or FALSE of the first operand, an exclusive-or operation can return TRUE, depending on the second operand. The precedence of operator ${ }^{\wedge}$ ^ is higher than operator ||, but lower than \&\&. This operation precedence is similar to that for bitwise operators \& , |, and ${ }^{\wedge}$, which will be discussed in the next section. Because there are only two values of either TRUE or FALSE for logic operations, the values of $\pm 0.0$ are treated as logic FALSE whereas the metanumbers -Inf, Inf, and NaN are considered as logic TRUE. For example, evaluations of ! $(-0.0)$ and $!\mathrm{NaN}$ will get the values of 1 and 0 , respectively.

### 5.4 Bitwise Operations

In $\mathrm{C}^{\mathrm{H}}$, there are six bitwise operators \& $\mid, \wedge, \ll$, $\gg$, and ", corresponding to bitwise and, inclusive or, exclusive or, left shift, right shift, and one's complement, respectively. These operators in $\mathrm{C}^{\mathrm{H}}$ are in full compliance with the ANSI C standard. They can only be applied to integral data that are char and int at its current implementation of $\mathrm{C}^{\mathrm{H}}$. The returned data
type depends on the data types of operands. The result of the unary operator ${ }^{\text {n }}$ keeps the data type of its operand. Results of binary operators \&, |, and " will have the higher data type of two operands. The binary operators $\ll$ and $\gg$ return the data type of the left operand.

However, some undefined behaviors in ANSI C are defined in $\mathrm{C}^{\mathrm{H}}$. For operators $\ll$ and $\gg$, the right operand can be any data type so long as it can be converted into int internally whereas the right operand must be a positive integral value in ANSI C. In $\mathrm{C}^{\mathrm{H}}$, if the right operand is a negative integral value that may be converted from a float-ing-point data, the shifting direction will be reversed. For example, the expression of $7 \ll-2.0$ is equivalent to $7 \gg 2.0$ in $\mathrm{C}^{\mathrm{H}}$. Therefore, only one of these two shift operators is needed in $\mathrm{C}^{\mathrm{H}}$. The use of operator $\ll$ is recommended for $\mathrm{C}^{\mathrm{H}}$ programming. A program with dual shift directions for one operator can be cleaner as compared with unidirectional shifts of two operators.

### 5.5 Assignment Operations

Besides the regular assignment statement, there are nine assignment operators of $+=,-=, *=$, $1=, \&=, \mid=,{ }^{\wedge}=, \ll=$, and $\gg=$. These assignment operators are ANSI C compatible. An lvalue is any object that occurs on the left-hand side of an assignment statement. The lvalue refers to a memory such as a variable or pointer, not a function or constant. The $\mathrm{C}^{\mathrm{H}}$ expression of lvalue $\mathrm{op}=$ rvalue is defined as lvalue = lvalue op rvalue where lvalue is any valid lvalue including complex numbers discussed by Cheng [2] and it is only evaluated once. For example, i $+=3$ is equivalent to $\mathrm{i}=\mathrm{i}+3$, and real (c) $*=2$ is the same as real (c) = real (c)*2. But, statement *ptr++ += 2 is different from statement *ptr++ $=* \mathrm{ptr}+++2$ because lvalue $* \mathrm{ptr}++$ contains an increment operation. The operation rules for operators of $+,-, *, /, \&, \mid,{ }^{\wedge}, \lll$, and $\ggg$ have been discussed in the previous sections.

### 5.6 Address and Indirection Operations

The unary operator \& gives the address of an object. The operator \& , which is ANSI C compatible, can only be applied to a valid lvalue.

When a unary indirection operator * is applied to a pointer, it accesses the object to which the pointer points. A pointer and an integer can be added or subtracted. The expression $\mathrm{ptr}+\mathrm{n}$ gives the address of the nth object beyond the one ptr currently points to. The memory locations of
pointers $\mathrm{ptr}+\mathrm{n}$ and ptr are $\mathrm{n} *$ sizeof (*ptr) bytes apart, that is, $n$ is scaled to $n * s i z e o f$ (*ptr) bytes according to declaration of pointer variable $p t r$. Pointer subtraction for pointers with the same data type is permitted. If ptr $1>\operatorname{ptr} 2$, ptr1 - ptr2i gives the number of objects between $p \operatorname{tr} 2$ and $\operatorname{ptr} 1$. Array of pointers can also be declared. When a pointer is declared, it is initialized to zero. The symbolic constant NULL, instead of zero, can be used in the program. If ptr is NULL, the operand $* p t r$ in an expression is evaluated as zero when *ptr is used as an lvalue, and a memory of sizeof(*ptr) will be allocated automatically for pointer ptr. In both cases, the system will print out warning messages. The automatical memory allocation for a pointer that does not point to a valid location can avoid a system crash.

Two pointers and constant NULL can be used in the relational operations $<,<=,==,>=,>$, and $!=$. In assignment and relational operations, pointers with different data types can work together without explicit type conversions. For example, following is a valid $\mathrm{C}^{\mathrm{H}}$ program.

```
int *iptr;
float *fptr;
iptr = (int *)malloc(90);
fptr = malloc(80);
    /# fptr = (float *)malloc(80)
if(iptr != NULL && iptr != fptr)
    free(iptr);
iptr = fptr;
```

Unlike ANSI C, not only all variables are initialized to zero when they are declared, but also the memory allocated by either function malloc() or calloc() is initialized to zero in $\mathrm{C}^{\mathrm{H}}$. The casting operation for three memory allocation functions malloc(), calloc(), and realloc() is unnecessary. If no memory is available, these functions will return NULL and the system will print out error messages. The function free(ptr) will deallocate the memory allocated by these three functions and set pointer ptr to NULL. In C, ptr is not set to NULL when the memory to which it points is deallocated. This dangling memory makes the debugging of the C program very difficult because the problem will not surface until this deallocated
memory is claimed again by other parts of the program. The other related functions such as memcpy() in $\mathrm{C}^{\mathrm{H}}$ for memory manipulations are ANSI C compatible.

As described before, there are several system defined parameters such as NaN, Inf, FLT_MAX, INT_MIN, FLT_EPSILON, etc. These parameters cannot be used as lvalues so that an accidental change of values of these parameters can be avoided. However, if really necessary, the values of these parameters can be modified by accessing their memory locations through pointers. For example, a numerical algorithm may depend on the parameters FLT_EPSILON and Inf. One can change the values of FLT_EPSILON to $10^{-4}$ and Inf to FLT_MAX by the following $\mathrm{C}^{\mathrm{H}}$ code

```
float *fptr;
fptr = & FLT_EPSILON; *fptr = 1e-4;
fptr = &Inf; *fptr = FLT_MAX;
```

which may, in effect, change the underlying numerical algorithm.

### 5.7 Increment and Decrement Operations

C is well known for the succinctness of its syntax. The increment operator ++ and decrement operator -- are unique to C . These two operators in $\mathrm{C}^{\mathrm{H}}$ are compatible with ANSI C. The increment operator ++ adds 1 to its operand whereas the decrement operator -- substracts 1 . If ++ or -- is used as a prefix operator, the expression increments or decrements operand before its value is used, respectively. If it is used as a postfix operator, the operation will be performed after its value has been used.

However, additional functions are added to these two operators in $\mathrm{C}^{\mathrm{H}}$. The repeated use of operator ++ means successive increment whereas repeated use of operator -- indicates successive decrement. These two operators can be combined in any combinations. A single + is treated as an addition or unary plus operator depending on the context. Likewise, a single - can be a subtraction or unary negation operator. For example, following is the valid $\mathrm{C}^{\mathrm{H}}$ code.

```
i = +(-9);
i++++;
j = ++i-m;
j = ++++++i;
```

```
/# unary plus and negation operators
```

/\# unary plus and negation operators

```
/# i = i+2
```

/\# i = i+2
/\# i = i+1; j = i; i = i-1;
/\# i = i+1; j = i; i = i-1;
/\# i = 3; j = i;

```
/# i = 3; j = i;
```

```
\(\mathbf{j}=+++++++\mathbf{i}-\quad / \# \mathrm{i}=\mathrm{i}+3 ; \mathrm{j}=\mathrm{i} ; \mathrm{i}=\mathrm{i}-\mathbf{1}\);
\(j=i---\); \(\quad / \# j=i ; i=i-2\);
\(\mathbf{i}=(* \mathrm{ptr}++++)++; \quad / \# \mathrm{ptr}=\mathrm{ptr}+2 ; \mathrm{i}=* \mathrm{ptr} ; * \mathrm{ptr}=* \mathrm{ptr}+1\);
```

By definition, ++ lvalue means lvalue $=$ lvalue +1 and expression lvalue +1 , and lvalue-- is equivalent to expression lvalue-1 and lvalue $=$ lvalue -1 . The ++ and -- operators can be applied to any valid lvalues, not just integral variables, so long as the lvalue can add or subtract an integer value of 1 according to internal data conversion rules. Following is the valid $\mathrm{C}^{\mathrm{H}}$ code.
*)iptr are valid $\mathrm{C}^{\mathrm{H}}$ expressions. There is an additional functional type casting operation in $\mathrm{C}^{\mathrm{H}}$ in the form of type (expr) for data types of single object or type (expr1, expr2, ...) for data types of aggregate such as complex and dual [2, $3]$. In this functional type casting operation, type shall not be a pointer data type. For example, int $(9.3)$, complex (float $(3), 2)$, dual $(2$, float $(3))$
int i, a[4], *aptr[5];
complex z, *zptr; /\# declare complex variable and complex pointer
$z=z++; \quad / \# z=z+1 ; z$ is a complex variable
zptr $=($ complex *) malloc (sizeof (complex) *90);
$\operatorname{aptr}[3]=\operatorname{malloc}(90) ; \quad / \# \operatorname{aptr}[3]=$ (int *) malloc (90);
/* imaginary (z) =complex (0.0, 4.0) ; zptr=zptr+1; *aptr[3]=1; i=i-1 */
imaginary (z) $=++++$ real ( $+++++*(z p \operatorname{tr}+++2 *(i n t)$ real ( $++* \operatorname{aptr}[3+\mathrm{i}--]$ )) );
real $(z)++; \quad / \#$ real $(z)=\operatorname{real}(z)+1$;
————imaginary (*zptr); /\# imaginary(*zptr) = imaginary(*zptr) - 2;
$\mathrm{a}[-\mathrm{i}]=\mathrm{a}[2]++; \quad / \# \mathrm{i}=\mathbf{i}-1 ; \mathrm{a}[\mathrm{i}]=\mathrm{a}[2] ; \mathrm{a}[2]=\mathrm{a}[2]+1$;

Details about complex numbers and functions real() and imaginary() in $\mathrm{C}^{\mathrm{H}}$ are described by Cheng [2]. Note that the memory allocated by function malloc() is initialized to zero.

### 5.8 Type Conversions

In $\mathrm{C}^{\mathrm{H}}$, the explicit type conversion is not necessary in many cases when $C$ needs it as is shown in the previous section for $\operatorname{aptr}[3]=\operatorname{malloc}(90)$. However, sometimes it is necessary to convert a value of one type explicitly to a value of another type. This can be achieved by the traditional $C$ cast operation (type) expr where expr is a $C^{H}$ expression and type is a data type of a single object such as char, int, float, double, or any pointer declaration identifiers such as char $*$, double *, complex *, etc. For example, (int)9.3, (float)ptr, (double) 9 , (float*)\&i, and (complex-
are valid $\mathrm{C}^{\mathrm{H}}$ expressions. Operation float() is the same as real() if they are used as operands. However, function real() can be used as an lvalue as described in Cheng [2] whereas float() cannot.

The sizeof() function can also use a type identifier. For example, ptr $=$ malloc (5+sizeof (int*) +sizeof ((int)2.3) + sizeof ((int) float (90)+7)) is a valid $\mathrm{C}^{\mathrm{H}}$ statement.

One important feature of C is its capability for hardware interface by accessing a specific memory location in a computer. This is achieved by pointing a pointer to a specific memory location or register. This hardware interface capability is retained in $\mathrm{C}^{\mathrm{H}}$. For example, the following statements will assign the integer value at the memory location $(68 \mathrm{FFE})_{16}$ to variable $i$ and set the byte at the memory address $(\mathrm{FF} 000)_{16}$ to $(01101001)_{2}$ :

```
char *cptr;
int i, *iptr, j;
iptr = (int *)0X68FFE; /# iptr points to the memory location at 0x68FFE
i = *iptr;
cptr = (char *)0XFF000; /# cptr points to the memory location at 0xFF000
*cptr = 0B01101001; /# 0B01101001 is assigned to 0XFF000
cptr = (float *)cptr + 1;/# cptr points to 0XFF004, not 0XFF001.
    /# note: (float *)cptr++ is (float *) (cptr++)
j = int(cptr); /# j becomes 0xFF004
```

Note that an integral value cannot be assigned to a pointer variable without an explicit type cast, and vice versa. The lower segment of the memory in a computer is usually reserved for the operating system and system programs. An application program will be terminated with exception handling if these protected segments of memory are messed up by pointers.

## 6 REAL FUNCTIONS

A computer language with no mathematical functions is not suitable for scientific computing and many other applications. The C language is a small language; it does not provide mathematical functions internally. The mathematical functions are provided in a standard library of mathematical functions. Writing good mathematical functions is not easy as pointed out by Plauger [10]. The mathematical functions implemented by Plauger [10] have provisions for handling -Inf, Inf, and NaN ; but they do not distinguish -0.0 from +0.0 , which is the case for most implementations of mathematical functions in C. Because C does not provide mathematical functions internally, like arithmetic operations in $\mathrm{K} \& \mathrm{R} \mathrm{C}$, the returned value from a standard mathematical function is a double floating-point number regardless of the data types of the input arguments. In some of C implementations, if the input arguments are not doubles the mathematical functions may return erroneous results without warning. Numerically oriented programmers have little tolerance with respect to the implicit conversion of the data type from float to double for arithmetic operations of a computer language as discussed in Section 3. However, they generally accept the strongly typed implementation of mathematical functions. Note that the ANSI C mathematical standard library does not provide any float functions. If a different return data type is desired for a mathematical function, a new function with a different name will be needed. For example, the operation $\sin (1)$ appears right in C. Indeed, most C programs will execute this operation calmly, but, maybe with an erroneous result because the input data type of integer is not what $\boldsymbol{\operatorname { s i n }}$ ) function expected. As another example, the function abs $($ in C returns an absolute int number whereas fabs () will result in a double number. To get a float absolute value, a new function has to be created. As a result, one has to remember many arcane names for different functions.

The external functions of $\mathrm{C}^{\mathrm{H}}$ can be created in
the same manner as in C. Unlike C, however, the commonly used mathematical functions are built internally into $\mathrm{C}^{\mathrm{H}}$. The mathematical functions in $\mathrm{C}^{\mathrm{H}}$ can handle different data types of the arguments gracefully. The output data type of a function depends on the data types of the input arguments, which is called polymorphism. Like arithmetic operators, the built-in commonly used mathematical functions in $\mathrm{C}^{\mathrm{H}}$ are polymorphic. For example, for the polymorphic function abs (), if the data type of the input argument is int, it will return an int as the absolute value. If the input argument of $\mathbf{a b s}()$ is a float or double, the output will return the same data type of float or double, respectively. For a complex number input, the result of abs() is a float with the value of the modulus of the input complex number. Similarly, if the argument data type is lower than or equal to float, $\boldsymbol{\operatorname { s i n }}()$ will return a float result correctly. Function $\boldsymbol{\operatorname { s i n }}()$ can also return double and complex results for double and complex input arguments, respectively. Because I/O functions are also built into $\mathrm{C}^{\mathrm{H}}$ itself, different data types are reconciled inside $\mathrm{C}^{\mathrm{H}}$. For example, printf ("\%f", x) in C can print x if x is a float. However, if x is changed to int in a program, the printing statement must also be changed accordingly as printf ("\%d", x). Therefore, the change of data type declaration of a variable will have to accompany the change of many other parts of the program. Unlike C , the commands printf(x) and printf( $\sin (x))$ in $C^{H}$ can handle different data types of $x ; x$ can be char, int, float, double, or complex.

For portability, all mathematical functions included in the ANSI C header math. h have been implemented polymorphically in $\mathrm{C}^{\mathrm{H}}$. The names of built-in mathematical functions of $\mathrm{C}^{H}$ presented in this paper are based upon the ANSI C header math. h. However, one can change, add, or remove these functions and operators in $\mathrm{C}^{\mathrm{H}}$ at his/her discretion. These mathematical functions are ANSI C compatible. If the arguments of these functions have the data types of the corresponding ANSI C mathematical functions, there is no difference between the ANSI C and $\mathrm{C}^{\mathrm{H}}$ functions from a user's point of view. Besides the aforementioned polymorphic nature, the mathematical function in $\mathrm{C}^{\mathrm{H}}$ is more powerful due to its abilities to handle metanumbers.

The ANSI C standard is descriptive, and many special cases are implementation dependent. Most mathematical operations related to the metanumbers have not been spelled out in the ANSI C standard. Therefore, loosely speaking, the built-in polymorphic mathematical functions of
$\mathrm{C}^{\mathrm{H}}$ are ANSI C compatible. Lnlike ANSI C, polymorphic mathematical function names in this section, by default, are keywords. In the same token, Inf and NaN are keywords in $\mathrm{C}^{\mathrm{H}}$. The metanumbers Inf and NaN are handled as system constants in a similar manner as constants such as 2.0 . Therefore, a declaration statement like

$$
\text { int Inf, } N a N, \sin ;
$$

is not valid in $\mathrm{C}^{\mathrm{H}}$ by default. However, keywords and symbols in $\mathrm{C}^{\mathrm{H}}$ can be added, changed, and removed by the built-in functions addkey (char *old_resword_or_symbol, *new_resword_or_symbol), chkey (char *old_resword_or_symbol, *new_resword_ or_symbol), and remkey (char *resword_ or_symbol), respectively. For example, the command addkey("fabs", "abs") will make function $f$ abs () the same as function abs () . The following $\mathrm{C}^{\mathrm{H}}$ program is valid.

```
chkey("sin", "SIN");
addkey("printf", "write");
addkey("double", "double_precision");
addkey("=", "equals");
addkey("+", "plus");
begin
    /# real code begins here {
    double_precision sin;
            /# double sin;
    sin equals SIN(30) plus 6;
            /# sin = SIN(30)+6;
    write
        ("The keyword changeability is");
    write("unique to CH. \n");
end /# end }
```

where chkey ("sin", "SIN") changes the keyword sin to SIN. Once a default keyword sin is changed, it then can be used as a regular variable. However, using function names in a standard library as variable names is considered a bad programming practice. Whether an object is a keyword can be tested by the built-in function iskey (char *name). The case sensitivity for a $\mathrm{C}^{\mathrm{H}}$ program can be switched off and on through a boolean switch function casesen(onoff). Therefore, porting code written in other languages and software packages to $\mathrm{C}^{\mathrm{H}}$ is not very difficult due to the keyword changeability. The detailed exploration of this unique $\mathrm{C}^{\mathrm{H}}$ feature is beyond the scope of this paper.

In this section, the built-in mathematical functions of $\mathrm{C}^{\mathrm{H}}$ will be discussed. The input and out-
put of the functions involving the metanumbers will be highlighted. The results of the mathematical functions involving metanumbers are given in Tables 13 to 16. In Tables 13 to 16, unless indicated otherwise, $x, x_{1}, x_{2}$ are real numbers with 0 $<x, x_{1}, x_{2}<\infty$; and $k$ is an integral value. The value of pi is the finite representation of the irrational number $\pi$ in floating-point numbers. The returned data of a function is float or double depending on the data type of the input arguments. In Table 13, if the order of the data type x is less than or equal to float, the returned data type is float. The returned data type is double if x is a double datum. If the argument $x$ of a function in Table 13 is NaN, the function will return NaN. In Tables 14 to 16, the returned data type will be the same as the higher order data type of two input arguments if any of two arguments is float or double. Otherwise, the float is the default returned data type.

Functions defined in this section will return float or double, except for functions abs() and pow(). If arguments of these two functions are integral values, the returned data types are ints. For example, pow $(2,16)$ will return the integral value of 65536. In $\mathrm{C}^{\mathrm{H}}$, if the exponent of the second argument of function pow() is an integral value, the computation will be more efficient than its real counterpart. For example, pow $(\mathbf{x}, 3)$ is more efficient than pow(x,3.0). Function pow() will optimize the performance for applications that involve a large amount of integer exponentiation. Function pow() behaves like the exponentiation operator $* *$ in Fortran. Note that ANSI C forces function pow() to deliver a double data, which not only inhibits the optimization for integer exponentiation, but also changes the data type of an integral expression into a floating-point expression due to the internal data type conversion. This is not applicable for many applications.

The absolute function $\mathbf{a b s}(\mathbf{x})$ will compute the absolute value of an integer or a floating-point number. The absolute value of a negative infinity $-\infty$ is a positive infinity $\infty$.

The sqrt(x) function computes the nonnegative square root of $x$. If $x$ is negative, the result is NaN, except that sqrt $(-0.0)=-0.0$ according to the IEEE 754 standard. The square root of infinity $\operatorname{sqrt}(\infty)$ is infinity.

The $\exp (x)$ function computes the exponential function of $\mathbf{x}$. The following results hold: $e^{-\infty}=$ $0.0 ; e^{\infty}=\infty ; e^{ \pm 0.0}=1.0$.

The $\log (\mathbf{x})$ function computes the natural logarithm of $x$. If $x$ is negative, the result is NaN . The

Table 13. Results of Real Functions for $\pm 0.0, \pm \infty$, and NaN

\begin{tabular}{|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Function} \& \multicolumn{7}{|c|}{x Value and Results} <br>
\hline \& - Inf \& -x1 \& -0.0 \& 0.0 \& x 2 \& Inf \& Na N <br>
\hline abs (x) \& Inf \& $x_{1}$ \& 0.0 \& 0.0 \& $x_{2}$ \& Inf \& NaN <br>
\hline $\operatorname{sqrt}(\mathbf{x})$ \& NaN \& NaN \& -0.0 \& 0.0 \& sqrt (x) \& Inf \& NaN <br>
\hline $\exp (\mathbf{x})$ \& 0.0 \& $e^{-x_{1}}$ \& 1.0 \& 1.0 \& $e^{x_{2}}$ \& Inf \& NaN <br>
\hline $\log (\mathbf{x})$ \& NaN \& NaN \& - Inf \& $-\operatorname{lnf}$ \& $\log \left(x_{2}\right)$ \& Inf \& Na <br>
\hline $\log 10(x)$ \& NaN \& NaN \& - Inf \& -Inf \& $\log _{10}\left(x_{2}\right)$ \& Inf \& NaN <br>
\hline $\sin (\mathrm{x})$ \& NaN \& $-\sin \left(x_{1}\right)$ \& -0.0 \& 0.0 \& $\sin \left(x_{2}\right)$ \& NaN \& NaN <br>
\hline $\cos (\mathbf{x})$ \& NaN \& $\cos \left(x_{1}\right)$ \& 1.0 \& 1.0 \& $\cos \left(x_{2}\right)$ \& NaN \& NaN <br>
\hline $\boldsymbol{\operatorname { t a n }}(\mathrm{x})$ \& NaN \& $-\tan \left(x_{1}\right)$ \& -0.0 \& 0.0 \& $\tan \left(x_{2}\right)$ \& NaN \& NaN <br>
\hline \multicolumn{8}{|c|}{Note: $\tan ( \pm \pi / 2+2 * k * \pi)= \pm \operatorname{lnf}$} <br>
\hline $\operatorname{acos}(\mathbf{x})$ \& Note:
Na,
Note: \& (x)
$=$ NaN, for $|x|$
$\operatorname{acos}\left(x_{1}\right)$

$=\operatorname{NaN}$, for $|x|$ \& $$
\mathrm{pi} / 2
$$ \& pi/2 \& $\operatorname{acos}\left(x_{2}\right)$ \& NaN \& NaN <br>

\hline $\operatorname{atan}(\mathbf{x})$ \& -pi/2 \& $-\operatorname{atan}\left(x_{1}\right)$ \& -0.0 \& 0.0 \& $\operatorname{atan}\left\langle\boldsymbol{x}_{2}\right\rangle$ \& pi/2 \& NaN <br>
\hline $\sinh (\mathbf{x})$ \& - Inf \& $-\sinh \left(x_{1}\right)$ \& -0.0 \& 0.0 \& $\sinh \left(x_{2}\right)$ \& Inf \& NaN <br>
\hline $\cosh (\mathbf{x})$ \& Inf \& $\cosh \left(x_{1}\right)$ \& 1.0 \& 1.0 \& $\cosh \left(x_{2}\right)$ \& Inf \& NaN <br>
\hline $\tanh (\mathbf{x})$ \& -1.0 \& $-\tanh \left(x_{1}\right)$ \& -0.0 \& 0.0 \& $\tanh \left(x_{2}\right)$ \& 1.0 \& NaN <br>
\hline $\operatorname{asinh}(\mathbf{x})$ \& - Inf \& $-\operatorname{asinh}\left(x_{1}\right)$ \& $-0.0$ \& 0.0 \& $\operatorname{asinh}\left(x_{2}\right)$ \& Inf \& NaN <br>
\hline $\operatorname{acosh}(\mathrm{x})$ \& NaN \& NaN \& NaN \& NaN \& $\operatorname{acosh}\left(x_{2}\right)$ \& Inf \& NaN <br>
\hline $\operatorname{atanh}(\mathbf{x})$ \& Note:
NaN
Note: \& $\begin{aligned}(\mathbf{x})= & \mathrm{NaN}, \text { for } x \\ & -\operatorname{atanh}\left(x_{1}\right) \\ (\mathbf{x})= & \mathrm{NaN}, \text { for }|x|\end{aligned}$ \& $0 ; \mathrm{acos}$
-0.0
$.0 ;$ ata \& $=0$.
0.0
$1.0)=$
0.0 \& $\operatorname{atanh}\left(x_{2}\right)$ \& NaN \& NaN <br>
\hline $\operatorname{ceil}(\mathbf{x})$ \& $-\operatorname{Inf}$ \& $\operatorname{ceil}\left(-x_{1}\right)$ \& -0.0 \& 0.0 \& $\operatorname{ceil}\left(x_{2}\right)$ \& Inf \& NaN <br>
\hline floor( $\mathbf{x}$ ) \& - Inf \& floor $\left(-x_{1}\right)$ \& -0.0 \& 0.0 \& floor $\left(x_{2}\right)$ \& Inf \& NaN <br>
\hline $\operatorname{ldexp}(\mathrm{x}, \mathrm{k})$ \& - Inf \& $\operatorname{ldexp}\left(-x_{1}, k\right)$ \& -0.0 \& 0.0 \& $\underline{\operatorname{ld}} \exp \left(x_{2}, k\right)$ \& Inf \& NaN <br>
\hline $\operatorname{modf}(\mathbf{x}, \& y)$ \& -0.0 \& $\operatorname{modf}\left(-x_{1}, 8 y y\right)$ \& -0.0 \& 0.0 \& $\operatorname{modf}\left(x_{2}, \& y y\right)$ \& 0.0 \& NaN <br>
\hline y ( \& - Inf \& $y$ \& -0.0 \& 0.0 \& $y$ \& Inf \& NaN <br>
\hline frexp (x, \&k) \& - Inf \& $\operatorname{frexp}\left(-x_{1}, \& k\right)$ \& -0.0 \& 0.0 \& $\boldsymbol{f r e x p}\left(x_{2}, \& k\right)$ \& Inf \& NaN <br>
\hline k \& 0 \& $k$ \& 0 \& 0 \& $k$ \& 0 \& 0 <br>
\hline
\end{tabular}

value of -0.0 is considered equal to 0.0 in this case. The following results hold: $\boldsymbol{\operatorname { l o g }}( \pm 0.0)=-\infty$; $\log (\infty)=\infty$. The $\log 10(\mathbf{x})$ function computes the base-ten logarithm of $\mathbf{x}$. If $\mathbf{x}$ is negative, the result is a NaN. Like the function $\log ()$, the value of
-0.0 is considered equal to 0.0 . The following results hold: $\log 10( \pm 0.0)=-\infty ; \log 10(\infty)=\infty$.

The trigonometric functions $\boldsymbol{\operatorname { s i n }}(\mathbf{x}), \cos (\mathbf{x})$, and $\boldsymbol{\operatorname { t a n }}(\mathrm{x})$ compute sine, cosine, and tangent of x measured in radians, respectively. The sine and

Table 14. Results of the Function $\operatorname{pow}(\mathbf{y}, \mathbf{x})$ for $\pm 0.0, \pm \infty$, and NaN

| $\underline{p o w(y, ~ x)}$ |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| y Value | $x$ Value |  |  |  |  |  |  |  |  |  |  |
|  | - Inf | -x1 | $-2 k-1$ | $-2 \mathrm{k}$ | -0.0 | 0.0 | 2 k | $2 k+1$ | $\times 2$ | Inf | NaN |
| Inf | 0.0 | 0.0 | 0.0 | 0.0 | NaN | NaN | Inf | Inf | Inf | Inf | NaN |
| $\mathrm{y} 2>1$ | 0.0 | $y_{2}^{-x_{1}}$ | $y_{2}^{-2 k-1}$ | $y_{2}{ }^{-2 k}$ | 1.0 | 1.0 | $y_{2}^{2 k}$ | $y_{2}^{2 k+1}$ | $y_{2}^{x_{2}}$ | Inf | NaN |
| 1.0 | NaN | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | 1.0 | NaN | NaN |
| $0<\mathrm{y} 2<1$ | Inf | $y_{2}^{-x_{1}}$ | $y_{2}^{-2 k-1}$ | $y_{2}^{-2 k}$ | 1.0 | 1.0 | $y_{2}^{2 k}$ | $y_{2}^{2 k+1}$ | $y_{2}^{x 2}$ | 0.0 | NaN |
| 0.0 | Inf | Inf | Inf | Inf | NaN | NaN | 0.0 | 0.0 | 0.0 | 0.0 | NaN |
| -0.0 | Inf | Inf | - $\ln \mathrm{f}$ | Inf | NaN | NaN | 0.0 | -0.0 | 0.0 | 0.0 | NaN |
| -y1 | NaN | NaN | $-y_{1}^{-2 k-1}$ | $y_{1}^{-2 k}$ | NaN | NaN | $y_{1}^{2 k}$ | $-y_{1}^{2 k+1}$ | NaN | NaN | NaN |
| - Inf | NaN | NaN | -0.0 | 0.0 | NaN | NaN | Inf | -Inf | NaN | NaN | NaN |
| NaN | NaN | NaN | NaN | NaN | NaN | NaN | NaN | NaN | NaN | NaN | NaN |

Table 15. Results of the Function $\operatorname{atan}(y, x)$ for $\pm 0.0, \pm \infty$, and NaN

| $\operatorname{atan} 2(y, x)$ |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| y Value | $x$ Value |  |  |  |  |  |  |
|  | -Inf | -x1 | -0.0 | 0.0 | x2 | Inf | NaN |
| Inf | $3 * \mathrm{pi} / 4$ | $\mathrm{pi} / 2$ | pi/2 | pi/2 | pi/2 | pi/4 | NaN |
| y2 | pi | $\operatorname{atan} 2\left(y_{2},-x_{1}\right)$ | pi/2 | pi/2 | $\operatorname{atan} 2\left(y_{2}, x_{2}\right)$ | 0.0 | NaN |
| 0.0 | pi | pi | pi | 0.0 | 0.0 | 0.0 | NaN |
| -0.0 | -pi | -pi | $-3 * \mathrm{pi} / 4$ | -pi/2 | -0.0 | -0.0 | NaN |
| -y1 | -pi | $\operatorname{atan} 2\left(-y_{1},-x_{1}\right)$ | -pi/2 | -pi/2 | $\operatorname{atan} 2\left(-y_{1}, x_{2}\right)$ | -0.0 | NaN |
| - Inf | $-3 * \mathrm{pi} / 4$ | -pi/2 | -pi/2 | -pi/2 | -pi/2 | -pi/4 | NaN |
| NaN | NaN | NaN | NaN | NaN | NaN | NaN | NaN |

tangent are odd functions so that $\sin ( \pm 0.0)=$ $\pm 0.0$ and $\tan ( \pm 0.0)= \pm 0.0$. The cosine is an even function so that $\cos ( \pm 0.0)=1.0$. When the value of the argument is positive or negative infinity, all these functions return NaNs. Theoretically, it is true that $\boldsymbol{\operatorname { t a n }}( \pm \pi / 2+2 * k * \pi)= \pm \infty$. But, in practice, because the irrational number $\pi$ cannot be represented exactly in float or double data, the $\boldsymbol{\operatorname { t a n }}(\mathbf{x})$ function will never return infinities of $\pm \infty$. The function $\tan ()$ is not continuous at $\pi / 2$, $\tan (\pi / 2-\varepsilon)=\infty$, and $\tan (\pi / 2+\varepsilon)=-\infty$, where $\varepsilon$ is a very small number. Due to the finite precision and round-off errors of floating-point numbers, one may get a wrong result near the value of $\pi / 2$.

The properties of odd functions of sine and tangent are reflected in their inverse functions $\operatorname{asin}(x)$ and $\operatorname{atan}(x)$. The $\boldsymbol{\operatorname { a s i n }}(\mathbf{x})$ function computes the principal value of the arc sine of $\mathbf{x}$. When the value of $x$ is in the range of $[-1.0,1.0]$, the $\operatorname{asin}(x)$ function returns the value in the range of $[-\pi / 2, \pi / 2]$ radians. When x is outside the range of $[-1.0,1.0]$, the arc sine is undefined and $\boldsymbol{\operatorname { a s i n }}(\mathbf{x})$ returns NaN . The range of the input value for the even function $\operatorname{acos}(x)$ of arc cosine is the same as that of $\operatorname{asin}(\mathbf{x})$. The $\operatorname{acos}(\mathbf{x})$ function computes the principal value of the arc cosine of
$x$. The range of the principal value of the are cosine is $[0.0, \pi]$ radians. The atan( $\mathbf{x})$ function computes the principal value of the arc tangent of $x$. The $\operatorname{atan}(x)$ function returns the value in the range of $[-\pi / 2, \pi / 2]$ radians. The following results hold: $\operatorname{atan}( \pm \infty)= \pm \pi / 2$.

Like trigonometric functions $\sin (x)$ and $\tan (x)$, the hyperbolic functions $\sinh (x)$ and $\tanh (x)$ are odd functions. The $\sinh (x)$ and $\tanh (x)$ functions compute the hyperbolic sine and tangent of $x$, respectively. The even function $\cosh (x)$ computes the hyperbolic cosine of $x$. The following results hold: $\sinh ( \pm 0.0)= \pm 0.0 ; \cosh ( \pm 0.0)=1.0$; $\tanh ( \pm 0.0)= \pm 0.0 ; \boldsymbol{\operatorname { s i n h }}( \pm \infty)= \pm \infty ; \boldsymbol{\operatorname { c o s h }}( \pm \infty)$ $=\infty ; \tanh ( \pm \infty)= \pm 1.0$.

The inverse hyperbolic functions are not defined by the ANSI C standard. In $\mathrm{C}^{\mathrm{H}}$, the inverse hyperbolic sine, cosine, and tangent are defined as $\operatorname{asinh}(x), \operatorname{acosh}(x)$, and $\operatorname{atanh}(x)$, respectively. For the $\operatorname{acosh}(x)$ function, if the argument is less than 1.0 , it is undefined and $\mathbf{a c o s h}(\mathbf{x})$ returns NaN. $\operatorname{acosh}(1.0)$ returns a positive zero. The valid domain for function $\operatorname{atanh}(x)$ is $[-1.0$, 1.0]. The following results hold: $\operatorname{asinh}( \pm 0.0)=$ $\pm 0.0 ; \operatorname{asinh}( \pm \infty)= \pm \infty ; \boldsymbol{\operatorname { a c o s h }}(\infty)=\infty$; $\operatorname{atanh}( \pm 0.0)= \pm 0.0 ; \boldsymbol{\operatorname { a t a n h }}( \pm 1.0)= \pm \infty$.

The ceil $(x)$ function computes the smallest

Table 16. Results of the Function $\operatorname{fmod}(y, x)$ for $\pm 0.0, \pm \infty$, and NaN

| $\mathrm{fmod}(\mathrm{y}, \mathrm{x})$ |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $x$ Value |  |  |  |  |  |  |
| y Value | - Inf | -x1 | -0.0 | 0.0 | x2 | Inf | NaN |
| Inf | NaN | NaN | NaN | Na , | NaN | NaN | Na N |
| y2 | $y_{2}$ | $f m o d\left(y_{2},-x_{1}\right)$ | NaN | NaN | $\operatorname{fmod}\left(y_{2}, x_{2}\right)$ | $y_{2}$ | NaN |
| 0.0 | 0.0 | 0.0 | NaN | Na , | 0.0 | 0.0 | NaN |
| -0.0 | -0.0 | -0.0 | NaN | NaN | -0.0 | -0.0 | NaN |
| -y1 | $y_{1}$ | $\mathrm{fmod}\left(-y_{1},-x_{1}\right)$ | NaN | NaN | $\operatorname{fmod}\left(-y_{1}, x_{2}\right)$ | $-y_{1}$ | NaN |
| - Inf | NaN | NaN | NaN | NaN | NaN | NaN | NaN |
| NaN | NaN | NaN | NaN | NaN | NaN | NaN | NaN |

integral value not less than the value of $x$. The counterpart of $\operatorname{ceil}(\mathbf{x})$ is the function floor( $\mathbf{x})$, which computes the largest integral value not greater than the value of x . The following results hold: $\operatorname{ceil}( \pm 0.0)= \pm 0.0 ;$ floor $( \pm 0.0)= \pm 0.0$; $\operatorname{ceil}( \pm \infty)= \pm \infty ;$ floor $( \pm \infty)= \pm \infty$.

The $\operatorname{ldexp}(\mathbf{x}, \mathbf{k})$ function multiplies the value of the floating-point number $x$ with the value of 2 raised to the power of $k$. The returned value of $x *$ $2^{k}$ keeps the sign of $\boldsymbol{x}$.

The functions modf( $\mathbf{x}, \mathrm{xptr}$ ) and $\operatorname{frexp}(\mathrm{x}, \mathrm{iptr})$ have two arguments. The first argument is the input data and the second argument is a pointer that will store the resulted integral part of the function call. The modf( $\mathbf{x}$, xptr) function breaks the argument x into integral and fractional parts, each of which has the same sign as the argument. The $\operatorname{modf}()$ function returns the fractional part and the integral part is stored to the memory pointed to by the second argument. The basic data types of two arguments must be the same. For example, if the first argument x is float, the second argument xptr must be a pointer to float. If the first argument is a metanumber, the integral part will equal the metanumber whereas the fractional part becomes zero with the sign of the first argument except for NaN . The $\operatorname{frexp}(\mathrm{x}, \mathrm{iptr})$ function breaks a floating-point number into a normalized fraction and an integral power of 2 in the form of $x * 2^{k}$. The $\boldsymbol{f r e x p}(\mathbf{x}$, iptr) function returns the normalized fraction and the integral part is stored to the memory pointed to by the second argument, which is a pointer to int. If the first argument is a metanumber, the fractional part will equal the metanumber whereas the integral part becomes zero.

The mathematical functions $\operatorname{pow}(\mathbf{y}, \mathbf{x}), \operatorname{atan} 2$ $(\mathbf{y}, \mathrm{x})$, and $\mathrm{fmod}(\mathrm{y}, \mathrm{x})$ have two input arguments. The results of these three functions are given in Tables 14 to 16. The $\operatorname{pow}(\mathbf{y}, \mathbf{x})$ function computes y raised to the power of x , which is $y^{x}$ or $e^{x \log (y)}$. If x is negative, $y^{x}$ becomes $1 / y^{|x|}$ with the defined division operation given in Table 6. If $y$ is less than zero and $x$ is not an integral value, the function is undefined. The value of -0.0 is considered equal to 0.0 in the evaluation of $\log (-0.0)$ when the value of $x$ is not an integral number. When $x$ is an odd integer number and $y$ is negative, the result is negative. If both $y$ and $x$ are zeros, $0^{0}$ is indeterminate. For a positive value of $y$, the result depends on the value of $y$ when $x$ is infinity. If $y$ is less than $1, y^{\infty}$ is $0.0 ; 1.0^{\infty}$ is indeterminate; if $y$ is greater than $1, y^{\infty}$ is infinity. If $y$ is infinity and x is zero, $( \pm \infty)^{ \pm 0.0}$ is indeterminate. It has been suggested that $x^{0.0}=1$ for any x , includ-
ing 0.0 , Inf, and $\mathrm{NaN}[24,31]$, which has been implemented in many computer systems [19]. It is true that if $f(x)$ and $g(x)$ are analytic at $a$, and $\lim _{x \rightarrow a} f(x)=0$ and $\lim _{x \rightarrow a} g(x)=0$, then $\lim _{x \rightarrow a}$ $f(x)^{g(x)}=0^{0}=1$. For example, $\lim _{x \rightarrow 0} x^{x}=1$ and $\lim _{x \rightarrow 0} x^{\sin (x)}=1$. It is not difficult to find examples that $0^{0} \neq 1$ such as in $\lim _{x \rightarrow a} x^{\log (x)}=e$ and $\lim _{x \rightarrow a}$ $\left(e^{-1 / x}\right)^{x}=1 / e$. To ensure the proper flow, a $\mathrm{C}^{\mathrm{H}}$ program shall not stop during the execution due to invalid operations. $\mathrm{C}^{\mathrm{H}}$ is designed to be deterministic; all operations and built-in functions either deliver correct numerical results, including Inf or NaN . It is a bad design for a computer language if at one point it can deliver a correct numerical result while at other point it returns a wrong numerical result. In general, whenever there is a problem in defining the value for a function or operation mathematically, the corresponding $\mathrm{C}^{\mathrm{H}}$ expression will return NaN. Because $\mathrm{C}^{\mathrm{H}}$ expressions such as $1 / \log (0.0)$ and $\exp (1 /-0.0)$ evaluate to 0.0 , therefore, pow $(0.0,0.0)$ is defined as NaN in $\mathrm{C}^{\mathrm{H}}$. For the same reason, pow(Inf, 0.0) and pow (NaN, 0.0) are also defined as NaN . Due to the similar considerations, our decision on $x^{0}$ has concurred with the proposed standard for Ada $[13,14]$. The definition given in Table 14 is much more inclusive than what is proposed for Ada. In general, all mathematically indeterminate expressions are defined as NaN in $\mathrm{C}^{\mathrm{H}}$. For an interesting historical debate about whether $0^{0}$ equal 1 or $0^{0}$ is undefined, see Knuth [32].

The $\operatorname{atan} 2(y, x)$ function computes the principal value of the arc tangent of $y / x$ using the signs of both arguments to determine the returned value in the range of $[-\pi, \pi]$ radians. Given the $(x, y)$ coordinates of a point in the X-Y plane, the $\operatorname{atan} 2(y, x)$ function computes the angle of the radius from the origin to the point. Any positive number that overflows is represented by Inf. The negative overflow is -Inf. The following results hold: $\operatorname{atan} 2( \pm \operatorname{Inf},-\operatorname{Inf})= \pm 3 \pi / 4 ;$ atan2 $( \pm \operatorname{Inf}$, Inf $)= \pm \pi / 4 ; \operatorname{atan} 2( \pm \operatorname{Inf}, \mathbf{x})= \pm \pi / 2 ; \operatorname{atan} 2( \pm y$, Inf) $= \pm 0.0$; and $\operatorname{atan} 2( \pm y,-\operatorname{lnf})= \pm \pi$. When both values of $y$ and $x$ are zeros, the function $\operatorname{atan} 2(\mathbf{y}, \mathrm{x})$ will return the results consistent with the manipulation of metanumbers discussed so far. The value of -0.0 is considered as a negative number less than zero. Therefore, the following results are defined for these special operations: $\boldsymbol{\operatorname { a t a n } 2}(0.0,-0.0)=\pi ; \boldsymbol{\operatorname { a t a n } 2}(0.0,0.0)=0.0 ;$ $\operatorname{atan} 2(-0.0,-0.0)=-3 \pi / 4 ;$ and $\operatorname{atan} 2(-0.0$, $0)=-\pi / 2$, which is consistent with the treatment of the metanumbers of $\pm \operatorname{Inf}$ in $\operatorname{atan} 2(-\operatorname{Inf},-\operatorname{Inf})$ $=-3 p i / 4$. In $\mathrm{C}^{\mathrm{H}}, \operatorname{atan} 2(0.0,0.0)$ is a specially defined value. These results are different from
those by the SUN's ANSI C compiler, which is in conformance with 4.3 Berkeley Software Delivery [19]. According to 4.3BSD, the results for these special cases are $\operatorname{atan} 2( \pm 0.0,-0.0)= \pm 0.0$ and $\operatorname{atan} 2( \pm 0.0,0.0)= \pm \pi$, which implies that the values of $\pm 0.0$ on the $x$-axis are different from those on the $y$-axis.

The $\mathbf{f m o d}(\mathbf{y}, \mathbf{x})$ function computes the floatingpoint remainder of $y / x$. The $\operatorname{fmod}(\mathbf{y}, \mathrm{x})$ function returns the value of $y-i * x$ for some integer $i$. The magnitude of the returned value with the same sign of $x$ is less than the magnitude of $x$. If $x$ is zero, the function is undefined and returns NaN. When $y$ is infinity, the result is also undefined. If $x$ is infinity and $y$ is a finite number, the result is the same as $y$.

## 7 PROGRAMMING EXAMPLES

### 7.1 Computation of Extreme Values of Floating-Point Numbers

Due to different machine architectures for representation of floating-point numbers, the extreme values such as the maximum representable float-

Inf and NaN . The use of metanumbers such as Inf and NaN instead of parameters is recommended for $\mathrm{C}^{\mathrm{H}}$ programming.

### 7.1.1 Minimum Floating-Point Numbers FLT_MIN and FLT_MINIMUM

The parameter FLT_MIN is defined in the ANSI C standard library header float. h as a minimum normalized positive floating-point float number. If a number is less than FLT_MIN, it is called an underflow. Because the IEEE 754 standard provides a gradual underflow, the minimum denormalized positive floating-point float number is defined as FLT_MINIMUM in $\mathrm{C}^{\mathrm{H}}$. Because of gradual underflow, the $\mathrm{C}^{\mathrm{H}}$ expression $\mathrm{x}-\mathrm{y}=0$ is TRUE iff $x=y$, which is not true for systems that lack gradual underflow. This parameter is very useful from a programming point of view. As an example, assume that values of FLT_MINIMUM and FLT_MIN are 1.401298e-45 and $1.175494 \mathrm{e}-38$, respectively. The following $\mathrm{C}^{\mathrm{H}}$ code will illustrate subtleties of these two parameters.

```
float f, *flt_minimum;
int minimum, i;
flt_minimum = &minimum;
i}=*flt_minimum > 0.0
i = FLT_MIN > *flt_minimum;
i = fabs(*flt_minimum) > 0.0;
f = (*flt_minimum)/(*flt_minimum);
f=f/1.e-46
```

minimum $=1$; /\# memory location becomes 00000001
ing-point value are different. For two machines with the same representation of floating-point values, the same operations such as adding two values on each machine may get different results, depending on the schemes for rounding a number that cannot be represented exactly. To aid serious numerically oriented programmers in writing their programs, the ANSI C standard added header float. h as a companion to the existing header limits. h to deal with the machine-dependent integer values only. In this section, we will show how parameters defined in the ANSI C standard library float . h can be computed in $\mathrm{C}^{\mathrm{H}}$ without knowing the intricate architecture of the computer. A program can less depend on these parameters if a language can support metanumbers

```
/# *flt_minimum becomes FLT_MINIMUM
/# i becomes 1
/# i becomes 1
/# i becomes 1
/# f becomes 1.0; note 0.0/0.0= NaN
/# f becomes Inf: note 1.e-46 < FLT_MINIMUM
```

Applications of these two numbers in handling of branch cuts of multiple-valued complex functions are described by Cheng [2].

### 7.1.2 Machine Epsilon FLT_EPSILON

The machine epsilon FLT_EPSILON is the difference between 1 and the least value greater than 1 that is representable in float. This parameter, defined in the ANSI C header float. $h$, is a system constant in $\mathrm{C}^{\mathrm{H}}$. This parameter is very useful for scientific computing. For example, due to the finite precision of the floating-point representation and alignment of addition operation, when a significantly small value and a large number are added together, the small number may not have contribution to the summation. Using

FLT_EPSILON, adding a small positive number $x$ to a large positive number $y$ can at least capture three decimal digits of significance of $y$ that can be tested by

$$
\text { if }(\mathrm{x}<\mathrm{y} * \text { FLT_EPSILON } * 1000)
$$

The following $\mathrm{C}^{\mathrm{H}}$ code can calculate and print out the machine epsilon on the screen

```
float epsilon;
epsilon = 1.0;
while(epsilon+1 > 1)
    epsilon /= 2;
epsilon *= 2;
printf("The machine epsilon");
printf("FLT_EPSILON is %e", epsilon);
```

For SUN SPARCStations, the output from the execution of the above code is as follows:

```
The machine epsilon FLT_EPSILON is
    1.192093e-07,
```

which matches the value of the parameter FLT_EPSILON defined in the ANSI C header float. h. Although the above computation of the parameter FLT_EPSILON is simple in $\mathrm{C}^{\mathrm{H}}$, which uses the default rounding mode of round toward nearest, it may be vulnerable to other rounding modes. A more robust method [10] to obtain this parameter is to manipulate the bit pattern of the
memory of a float variable is as shown in Section 7.1.1.

### 7.1.3 Maximum Floating-Point Number FLT_MAX

The parameter FLT_MAX defined in the ANSI C header float. h is the maximum representable finite floating-point number. Any value that is larger than FLT_MAX will be represented as Inf and any value less than -FLT_MAX is represented by -Inf. If the value of FLT_MAX is represented as fltmax $* 10^{e}$, then the following two equations will be satisfied

$$
\begin{gathered}
\left(\text { fltmax }+F L T_{-} E P S I L O N\right) * 10^{e}=\text { Inf } \\
\left(\text { fltmax }+F L T_{-} E P S I L O N / 2\right) * 10^{e}=F L T_{-} M A X
\end{gathered}
$$

where the machine epsilon FLT_EPSILON was defined in Section 7.1.2 and the exponential value $e$ is to be calculated. The following $\mathrm{C}^{\mathrm{H}}$ program will calculate FLT_MAX as well as FLT_MAX_10_EXP and FLT_MAX_EXP of the machine and print them on the screen. The value of FLT_MAX_10_EXP is the maximum integer such that 10 raised to its power is in the range of the representable finite floating-point numbers. The value of FLT_MAX_EXP is the maximum integer such that 2 raised to its power minus 1 is a representable finite floating-point number. For the illustrative purpose, only the while-loop control structure is used in this example.

```
float b, f, flt_max;
int e, i, flt_max_exp, flt_max_10_exp;
\(\mathrm{b}=10 ; \mathrm{e}=0 ; \mathrm{f}=\mathrm{b}\);
/* calculate exponential number e, 38 in the example */
while(f ! \(=\operatorname{Inf})\)
\{
    e++; f * \(=\mathrm{b}\);
\}
flt_max_10_exp \(=\) e;
/* calculate leading non-zero number, 3 in the example */
\(\mathrm{i}=0 ; \mathrm{f}=0.0\);
while (f \(!=\operatorname{Inf})\)
    \(\mathrm{f}=++\mathrm{i} * \operatorname{pow}(\mathrm{~b}, \mathrm{e})\);
/* calculate numbers after decimal point, 40282347... in the example */
flt_max \(=\mathrm{i}\);
while (e \(!=0\) )
\{
    flt_max \(=\)--flt_max \(* \mathrm{~b}\);
    e-; i = 0; f = 0. 0 ;
    while( f ! \(=\operatorname{Inf} \& \& \mathrm{i}<10\) )
```

```
    {
    f = ++flt_max * pow(b, e);
    i++;
    }
}
f = frexp(flt_max, &flt_max_exp); /# calculate FLT_MAX_EXP
printf("FLT_MAX = %.8e \n", flt_max);
printf("FLT_MAX (in binary format) = %b \n", flt_max);
printf("FLT_MAX_10_EXP = %d \n", flt_max_10_exp);
printf("FLT_MAX_EXP = %d \n", flt_max_exp);
```

The output of the above code on SUN SPARCStations is as follows:

```
FLT_MAX = 3.40282347e+38
FLT_MAX (in binary format)
    = 01111111011111111111111111111111
FLT_MAX_10_EXP = 38
FLT_MAX_EXP = 128
```

The above values for FLT_MAX, FLT_MAX_ 10_EXP, and FLT_MAX_EXP are the same as the parameters defined in the ANSI C header float. h. By just changing the declaration of the first statement from float to double, the corresponding extreme values DBL_MAX, DBL_MAX_ 10_EXP, and DBL_MAX_EXP for double can be obtained. In this case, the polymorphic arithmetic operators and mathematical functions pow() and frexp() will return double data. The default mode for floating-point constants is float, which can be switched to double by function floatconst (FALSE).

In the above calculation of the extreme float-ing-point values, the user does not need to know the intricate machine representation of floatingpoint numbers. If one knows the machine representation of a floating-point number, the calculation of the extreme values can be much simpler. For example, according to Table 1, the value of FLT_MAX is represented in a hexadecimal form as (7F7FFFFF) ${ }_{16}$. The following $\mathrm{C}^{\mathrm{H}}$ program can be used to calculate the maximum representable finite floating-point number FLT_MAX.

```
int i; float *flt_max;
flt_max = &i;
    /# flt_max points to the memory
    /# location of i
i = 0X7F7FFFFF;
    /# *flt_max becomes FLT_MAX
```

The maximum float number FLT_MAX can also be readily obtained by the I/O function scanf()
with the binary input format "\%32b". For interested readers, can you think of any other method for computing the maximum representable finite floating-point number FLT_MAX by a C or Fortran program without knowing the machine architecture? The major difficult is that, due to the internal alignment for calculation of the floating-point numbers, the significantly small number will be ignored when it is added to or subtracted from a large number. For example, the execution of the command $f=$ FLT_MAX $+3.0 e 30$ will give the variable $f$ the value of FLT_MAX although the value of $3.0 * 10^{30}$ is not a small number, but it is significantly smaller than FLT_MAX and ignored in the above addition operation. The following two $\mathrm{C}^{\mathrm{H}}$ expressions will further demonstrate the difference between FLT_MAX and Inf, $1 /$ Inf $*$ FLT_MAX $=0.0$, and $1 /$ FLT_ MAX $*$ FLT_MAX $=1.0$.

### 7.2 Programming With Metanumbers

The $\mathrm{C}^{\mathrm{H}}$ language distinguishes -0.0 from 0.0 for real numbers. The metanumbers $0.0,-0.0$, Inf, -Inf, and NaN are very useful for scientific computing. For example, the function $f(x)=e^{1 / x}$ is not continuous at the origin as is shown in Figure 1. This discontinuity can be handled gracefully in $\mathrm{C}^{\mathrm{H}}$. The evaluation of the $\mathrm{C}^{\mathrm{H}}$ expression $\exp (1 / 0.0)$ will return $\operatorname{Inf}$ and $\exp (1 /(-0.0))$ gives 0.0 , which corresponds to mathematical expressions $e^{1 / 0_{+}}$and $e^{1 / 0-}$ or $\lim _{x \rightarrow 0_{+}} e^{1 / x}$ and $\lim _{x \rightarrow 0} e^{1 / x}$, respectively. In addition, the evaluation of expressions $\exp (1.0 / \operatorname{lnf})$ and $\exp (1.0 /$ $(-\operatorname{lnf}))$ will get the value of 1.0 . As another example, the function finite (x) recommended by the IEEE 754 standard is equivalent to the $\mathrm{C}^{\mathrm{H}}$ expression $-\operatorname{Inf}<\mathrm{x} \& \& \mathrm{x}<\operatorname{Inf}$, where $x$ can be a float/double variable or expression. If $x$ is a float, $-\operatorname{Inf}<\mathrm{x} \& \& \mathrm{x}<\operatorname{Inf}$ is equivalent to -FLT_MAX $<=\mathrm{x} \& \& \mathrm{x}<=$ FLT_MAX; if $x$ is a double, - Inf $<\mathrm{x}$ $\& \& x<$ Inf is equivalent to - DBL_MAX $<=x \& \& x$


FIGURE 1 Function $f(x)=e^{1 / x}$.
$<=$ DBL_MAX. The mathematical statement "if $\infty<$ value $<=\infty$, then $y$ becomes $\infty^{\prime \prime}$ can be easily programmed in $\mathrm{C}^{\mathrm{H}}$ as follows

$$
\text { if }(-\operatorname{Inf}<\text { value } \& \& \text { value }<=\operatorname{Inf}) \mathrm{y}=\operatorname{Inf} ;
$$

However, a computer can only evaluate an expression step by step. Although the metanumbers are limits of the floating-point numbers, they cannot replace mathematical analysis. For example, the natural number e equal to 2.718281828 . is defined as the limit value of the expression

$$
\lim _{x \rightarrow \infty}\left(1+\frac{1}{x}\right)^{x}=e
$$

However, the value of the expression pow $1.0+$ $1.0 / \operatorname{Inf}, \operatorname{Inf})$ in $\mathrm{C}^{\mathrm{H}}$ is NaN . The evaluation of this expression is carried out as follows:

$$
\left(1.0+\frac{1.0}{\operatorname{Inf}}\right)^{\operatorname{lnf}}=(1.0+0.0)^{\operatorname{lnf}}=1.0^{\operatorname{Inf}}=\mathrm{NaN}
$$

If the value FLT_MAX instead of $\operatorname{Inf}$ is used in the above expression, the result is obtained by

$$
\begin{aligned}
\left(1.0+\frac{1.0}{F L T_{-} M A X}\right)^{F L T_{-} M A X} & =(1.0+0.0)^{F L T_{-} M A X} \\
& =1.0^{F L T_{-} M A X}=1.0
\end{aligned}
$$

According to rules for negation, subtraction, and equal comparison operations given in Tables 2,4 , and 9 , the $\mathrm{C}^{\mathrm{H}}$ expression $\mathrm{x}-\mathrm{y}=-(\mathrm{y}-\mathrm{x})$ will always return TRUE for any values of $x$ and $y$ with $x$ equal to $y$, including $\mathrm{NaN}, \pm 0.0$, and $\pm \operatorname{Inf}$. The outcome of this computation really matches our intuition regarding algebra. However, there is a subtle difference between two expressions $x-y$ and $-(x-y)$ in $\mathrm{C}^{\mathrm{H}}$. When $x=y$ and $\mathrm{NaN} \neq x \neq$ Inf, $x-y$ will produce 0.0 whereas $-(x-y)$ will return -0.0 . If the IEEE 754 standard for handling NaN in relational operations was strictly follow, the implication of the above operation would be much more complicated.

The application of NaN can be further demonstrated by numerically solving quadratic equation

$$
a x^{2}+b x+c=0
$$

The execution of the following $\mathrm{C}^{\mathrm{H}}$ program

```
float root[2];
float a,b,c;
a=1; b = 2; c = 2;
root[0] = (-b+sqrt (b*b-4*a*c))/(2*a);
root[1] = (-b-sqrt(b*b-4*a*c))/(2*a);
if (root[0] == NaN)
    printf("Solutions are complex");
    printf("numbers.\n");
```

will produce the following output

## Solutions are complex numbers.

because solutions to the equation of $x^{2}+2 x+$ $2=0$ are $-1 \pm i$. This equation will be solved in complex numbers in [2].

Because metanumber NaN is unordered, a program involving relational operations should be handled cautiously. For example, the expression $x>y$ is not equivalent to ! ( $x<=y$ ) if either $x$ or $y$ is a NaN . As another example, the following $\mathrm{C}^{\dot{H}}$ code fragment
if $(x>0.0)$ function1(); else function2();
is different from the code fragment

```
if(x<= 0.0) function2();
else function1();
```

The second if-statement should be written as if $(x<=0.0| | x==N a N)$ in order to have the same functionality for these two code fragments.

## 8 CONCLUSIONS

$\mathrm{C}^{\mathrm{H}}$ not only retains most features of C from the scientific computing point of view, but also extends C's numerical computational capabilities. Metanumbers of $-0.0,0.0, \operatorname{Inf},-\operatorname{Inf}$, and NaN introduced in $\mathrm{C}^{\mathrm{H}}$ are external, which makes the power of the IEEE 754 arithmetic standard easily available to the programmer. Furthermore, these metanumbers are extended to commonly used mathematical functions in the spirit of the IEEE 754 standard. The rules for manipulation of these metanumbers in I/O; arithmetic, relational, and logic operations; and commonly used mathematical functions in $\mathrm{C}^{\mathrm{H}}$ are defined in this article. The $\mathrm{C}^{\mathrm{H}}$ extensions related to bitwise, assignment, address and indirection, increment and decrement, as well as type conversion operations to ANSI C have been highlighted. The gradual underflow feature of the IEEE 754 standard has been explored through parameter FLT_MINIMUM. Because the ANSI C standard is descriptive, the rigorous definitions defined in this article will not violate the standard. Like arithmetic operators, the built-in mathematical functions in $\mathrm{C}^{\mathrm{H}}$ are polymorphic, which means that the returned data type of a function depends on the data types of the input arguments. This will simplify the scientific programming significantly.

All points delineated in this article have been implemented and tested in $\mathrm{C}^{\mathrm{H}}$. Example programs with metanumbers and polymorphic mathematical functions are given in this article. The function names can be added, removed, and changed; and the mathematical operators can be added and removed in $\mathrm{C}^{\mathrm{H}}$. Therefore, porting code from other languages to $\mathrm{C}^{\mathrm{H}}$ is relatively simple. Most C programs can be executed in the $\mathrm{C}^{\mathrm{H}}$ environment with minimum modification related to the interpretive nature of the current implementation of $\mathrm{C}^{\mathrm{H}}$. The extension of scientific programming with real numbers to scientific programming with complex numbers has been addressed by Cheng [2].

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