

Separation of variables and scalar products at any rank

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ABSTRACT: Separation of variables (SoV) is a special property of integrable models which ensures that the wavefunction has a very simple factorised form in a specially designed basis. Even though the factorisation of the wavefunction was recently established for higher rank models by two of the authors and G. Sizov, the measure for the scalar product was not known beyond the case of rank one symmetry. In this paper we show how this measure can be found, bypassing an explicit SoV construction. A key new observation is that the measure for spin chains in a highest-weight infinite dimensional representation of $\mathfrak{sl}(N)$ couples Q-functions at different nesting levels in a non-symmetric fashion. We also managed to express a large number of form factors as ratios of determinants in our new approach. We expect our method to be applicable in a much wider setup including the problem of computing correlators in integrable CFTs such as the fishnet theory, $\mathcal{N} = 4$ SYM and the ABJM model.

KEYWORDS: Bethe Ansatz, Lattice Integrable Models

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1 Introduction

Integrability provides powerful methods to study certain quantum systems at the nonperturbative level. The integrable models share many universal features and the underlying mathematical structures which to a great extent depend on the global symmetries of the model. While a bit counterintuitive, in fact the integrable structure becomes increasingly more complex for systems with a larger symmetry.

The observables that are most easily accessible to integrability are the eigenvalues of the Hamiltonian and other integrals of motion. However, it is usually much more difficult to extract information on the energy eigenvectors, as well as on more complicated observables such as form factors and correlators. A very powerful method that allows one to make advance in this direction was pioneered by Sklyanin in [1–4] and is known as the Separation of Variables (SoV). It is based on the fact that in integrable systems the wave functions $|\Psi\rangle$ for eigenstates of the integrals of motion (also known as Bethe states) are expected to factorize completely in a suitable system of coordinates. The most elementary example is the wavefunction for the hydrogen atom which factorizes in spherical coordinates.

In the case of a spin chain with L sites and rank-one $\mathfrak{sl}(2)$ symmetry one aims to find a basis for the Hilbert space parametrized by a set of L separated variables, $\langle \mathbf{x} |$, labelled by a set of L real numbers $\mathbf{x} = \{x_i\}_{i=1}^L$, such that the Bethe state becomes a product,

$$\Psi(\mathbf{x}) \equiv \langle \mathbf{x} | \Psi \rangle = \prod_{i=1}^L Q(x_i). \tag{1.1}$$

In most realizations of SoV, the one-particle factors coincide precisely with the Q-function, which is a fundamental object in quantum integrability directly related to the solution of the spectral problem. The Q-function is fixed by the Baxter TQ relation, a finite difference equation of order equal to the rank of the symmetry group, which in the SoV framework can be interpreted as equivalent to the Schrödinger equation. The explicit form of the change of coordinates to the SoV basis is quite complicated, however, in many important cases one could reformulate the problem directly in the SoV coordinates. It was observed that for a number of important observables the result written in the SoV basis is surprisingly simple [5–13]. Crucially, one can define the scalar product bypassing the original physical basis directly in SoV. The scalar product involves the so-called Sklyanin’s measure $M(\mathbf{x})$ such that $\langle \Psi_A | \Psi_B \rangle = \int d^L \mathbf{x} \Psi_A(\mathbf{x}) M(\mathbf{x}) \Psi_B(\mathbf{x})$. In particular for the Bethe states it becomes

$$\langle \Psi_A | \Psi_B \rangle = \int d^L \mathbf{x} \left(\underbrace{\prod_{i=1}^L Q^{(A)}(x_i)}_{\text{state } A} \right) \underbrace{M(\mathbf{x})}_{\text{measure}} \left(\underbrace{\prod_{i=1}^L Q^{(B)}(x_i)}_{\text{state } B} \right). \tag{1.2}$$

As emphasised by the colours in the formula, the two states are represented by the respective factorized wavefunctions. The scalar product is implemented by integration over the values of the separated variables with the measure $M(\mathbf{x})$, which is independent of the states.

Of course, different eigenstates of Hermitian integrals of motion are orthogonal, therefore the integral in (1.2) should vanish for any two different Bethe states $\langle \Psi_A |$ and $|\Psi_B \rangle$. One can, in fact, reverse the logic and derive the measure (up to a constant factor) from the orthogonality of the Bethe states. In this paper we use this fact as an inspiration for the generalisation to higher rank symmetries.

Originally, for $\mathfrak{sl}(2)$ spin chains the basis $|\mathbf{x} \rangle$ was constructed explicitly and the measure derived rigorously in [14, 15]. It was shown to take the form of a determinant of a $L \times L$ matrix^{1,2}

$$M(\mathbf{x}) = \text{sym}_{\{\theta_i\}} \left| \left(\frac{x_i^{j-1}}{1 + e^{2\pi(x_i - \theta_i)}} \right) \right|_{1 \leq i, j \leq L}, \tag{1.3}$$

¹This formula is valid for the most general case of inhomogeneous spin chain with twisted boundary conditions. The reduction to the untwisted case can be obtained by carefully taking the corresponding limit.

²For compact spin chains we have sums instead of integrals and the corresponding measure was derived in e.g. [6] (see also [10, 16, 17]).

where θ_i are L distinct inhomogeneities, and “sym” denotes symmetrization of the determinant w.r.t. the inhomogeneities. This operation makes the expression (1.3) completely symmetric w.r.t. the variables x_i , and does not affect the integral defining the scalar product.

For models with higher rank symmetries, SoV methods have so far not been understood to the same extent as we described above. In fact, problems with obtaining the measure were anticipated recently in [18]. At the same time, extra motivation to explore this direction comes from string theory and integrability observed in $\mathcal{N} = 4$ super Yang-Mills, which has a much more complicated $\mathfrak{psu}(2, 2|4)$ symmetry [19].

It was essentially conjectured in the original papers of Sklyanin [20, 21] how to construct the SoV basis $|x_i\rangle$ in the first higher rank case, i.e. for $\mathfrak{sl}(3)$. These results were extended to $\mathfrak{sl}(N)$ by Smirnov [22] following the classical case [23, 24] (see also [25, 26]). However, for a long time there was no precise indication of how Bethe states can be written in the separated coordinates and what are the corresponding factors.

One of the obvious difficulties in generalizing (1.2) to higher rank is that for $\mathfrak{gl}(N)$ -invariant systems there are 2^N independent Q-functions (see [27–32] and [33–35] for a recent pedagogical introduction), and it not clear a priori which of them should enter the factorised expression for the Bethe states generalising (1.1). A convenient way to label the Q-functions is by using completely antisymmetric multi-indices³

$$Q_{i_1 \dots i_k} \ , \ i_n \in \{1, \dots, N\} \ . \tag{1.4}$$

The answer to the question about which Q-functions should appear in the factorization of the Bethe states was obtained in [17] for the case of compact spin chain in the fundamental representation of $\mathfrak{sl}(N)$. Firstly, it was demonstrated that the Bethe states can be constructed as

$$|\Psi\rangle = \prod_k \hat{B}^{\text{good}}(u_k) |0\rangle \ , \tag{1.5}$$

where $\hat{B}^{\text{good}}(u)$ is a degree $L \times (N - 1)$ polynomial in u operator,⁴ such that it commutes with itself for different values of u . Importantly, u_k 's are the roots of the Q_1 polynomial Q-function.⁵ Following the same procedure as in [3, 37] for $\mathfrak{sl}(2)$ case one can label the left eigenstates of the operator $\hat{B}^{\text{good}}(u)$ by a set of $L \times (N - 1)$ real numbers $\mathbf{x} \equiv \{x_{i,a}\}$ with $i = 1, \dots, L$ and $a = 1, \dots, N - 1$, such that

$$\langle \mathbf{x} | \hat{B}^{\text{good}}(u) = \prod_{i=1}^L \prod_{a=1}^{N-1} (x_{i,a} - u) \langle \mathbf{x} | \ , \tag{1.6}$$

³At the same time there are only $N - 1$ Q-functions whose roots appear in the nested Bethe ansatz equations. These are for example $Q_1, Q_{12}, \dots, Q_{12\dots N-1}$. However, the nesting procedure contains ambiguity and can generate a number of equivalent sets of equations. Considering all such possibilities we will recover all 2^N Q-functions. For more details see e.g. [34].

⁴When building this operator it is important to introduce an extra similarity transformation of the monodromy matrix. Such a transformation was also studied for the $\mathfrak{sl}(2)$ case in [36] for a slightly different model.

⁵In fact depending on the choice of the reference state $|0\rangle$ one can use roots of any Q_i , the Q-function with one index.

from which, together with (1.5), it immediately follows that the Bethe state $|\Psi\rangle$ does indeed factorize into the product of $Q_1(x_{i,a})$ in this basis,

$$\langle \mathbf{x} | \Psi \rangle = \prod_{i=1}^L \prod_{a=1}^{N-1} Q_1(x_{i,a}), \tag{1.7}$$

thus generalizing (1.1). These results were later proven and shown to hold beyond the fundamental representation, first for $\mathfrak{sl}(3)$ in [38] and then for $\mathfrak{sl}(N)$ in [39] where the spectrum of separated variables \mathbf{x} in more general cases was also obtained.⁶ The eigenstates construction (1.5) was extended to the supersymmetric case in [47].

However, the factorisation property (1.7) does not guarantee the existence of a simple formula for the scalar product. The main difficulty is that \hat{B}^{good} is not self-conjugate, thus its left and right eigenvectors are not simply Hermitian conjugate to each other. This implies that the bra $\langle \Psi |$ and ket $|\Psi\rangle$ Bethe states cannot be simultaneously factorised in the same way (1.7). Alternatively, one can ensure the factorization property by using the Hermitian conjugate of (1.1); however the completeness relation for $|\mathbf{x}\rangle$ and $(|\mathbf{x}\rangle)^\dagger$ is not diagonal since there is no reason to expect that $|\mathbf{x}\rangle$ and $(|\tilde{\mathbf{x}}\rangle)^\dagger$ are orthogonal for $\mathbf{x} \neq \tilde{\mathbf{x}}$, meaning that the measure would depend on the two sets of variables $M(\mathbf{x}, \tilde{\mathbf{x}})$ giving a much more complicated expression for the norm.

In this paper, we find a different argument, independent on the explicit construction of separated variables, leading us to a concise proposal for a formula generalising (1.2) at any rank. Our derivation is based only on the Baxter TQ relations. The main difference with the approach based on \hat{B}^{good} , described above, is that our result indicates that the factorization of the bra and ket states takes place in a more intriguing way — whereas one state still factorizes into the product of Q_1 's as in (1.7), the other state necessarily decomposes into a different set of factors. More precisely we find

$$\langle \Psi_A | \Psi_B \rangle = \int \left(\prod_{a=1}^{N-1} \prod_{i=1}^L dx_{i,a} \right) \underbrace{\left(\prod_{a=1}^{N-1} \prod_{i=1}^L Q_1^{(A)}(x_{i,a}) \right)}_{\text{state A}} \hat{M}(\mathbf{x}) \underbrace{\left(\prod_{a=1}^{N-1} \prod_{i=1}^L Q_{\bar{a}}^{(B)}(x_{i,a}) \right)}_{\text{state B}}, \tag{1.8}$$

where $Q_{\bar{a}}$ are the Q-functions containing the Bethe roots at the deepest level of nesting. Explicitly,

$$Q_{\bar{a}} \equiv \frac{\epsilon^{b_1, \dots, b_{N-1}, N+1-a}}{(N-1)!} Q_{b_1, \dots, b_{N-1}}, \tag{1.9}$$

and the analogue of Sklyanin's measure is a state-independent operator acting on the wave function for one of the states. Like the Sklyanin's measure is a determinant of $L \times L$ matrix (1.3), $\hat{M}(\mathbf{x})$ is a determinant of a $L \times (N-1)$ -dimensional matrix. For instance, for $\mathfrak{sl}(3)$ we only have two functions $Q_{\bar{1}} = Q_{12}$ and $Q_{\bar{2}} = Q_{13}$ and the measure factor takes

⁶The form of the SoV basis $|x_i\rangle$ for the noncompact $\mathfrak{sl}(3)$ case was elucidated recently in [40], while for compact spin chains an alternative construction was proposed in [41–43]. Some related results for the noncompact case such as the construction of Q-operators were presented in [44–46].

the form

$$\hat{M}(\mathbf{x}) \equiv \text{sym}_{\{\theta_i\}} \det \left| \begin{array}{c} \left(\frac{x_{i,1}^{j-1} \mathcal{D}_{x_{i,1}}}{1 + e^{2\pi(x_{i,1} - \theta_i)}} \right) \\ \left(\frac{x_{i,2}^{j-1} \mathcal{D}_{x_{i,2}}}{1 + e^{2\pi(x_{i,2} - \theta_i)}} \right) \end{array} \right|_{1 \leq i, j \leq L}, \quad (1.10)$$

where \mathcal{D}_x is the shift operator in variable x :

$$\mathcal{D}_x \circ f(x) \equiv f(x + i/2). \quad (1.11)$$

For illustration we write this result explicitly in the simplest case of $L = 1$ $\mathfrak{sl}(3)$ spin chain in appendix A. Schematically, we can represent (1.10) as the determinant of a tensor product

$$\hat{M}(\mathbf{x}) = \text{sym}_{\{\theta_i\}} \det \left| \underbrace{\left(\frac{\hat{x}^{j-1}}{1 + e^{2\pi(\hat{x} - \theta_i)}} \right)}_{1 \leq i, j \leq L} \otimes \begin{pmatrix} \mathcal{D}_x & \mathcal{D}_x^{-1} \\ \mathcal{D}_x & \mathcal{D}_x^{-1} \end{pmatrix} \right|, \quad (1.12)$$

where the first factor is the matrix appearing in the standard $\mathfrak{sl}(2)$ Sklyanin's measure. In this form the generalization to any rank is simply

$$\hat{M}(\mathbf{x}) = \text{sym}_{\{\theta_i\}} \det \left| \underbrace{\left(\frac{\hat{x}^{j-1}}{1 + e^{2\pi(\hat{x} - \theta_i)}} \right)}_{1 \leq i, j \leq L} \otimes \underbrace{\begin{pmatrix} \mathcal{D}_x^{N-2} & \mathcal{D}_x^{N-4} & \dots & \mathcal{D}_x^{2-N} \\ \vdots & \vdots & \ddots & \vdots \\ \mathcal{D}_x^{N-2} & \mathcal{D}_x^{N-4} & \dots & \mathcal{D}_x^{2-N} \end{pmatrix}}_{(N-1) \times (N-1)} \right|. \quad (1.13)$$

It would still be interesting to derive this formula starting from (1.5). It should involve the construction of a new operator, which we can tentatively denote $\hat{C}^{\text{good}}(u)$, which would also create the states but when acting from the right on the vacuum and evaluated at the roots of the $Q_{\bar{a}}$'s. This would lead to a rigorous derivation of the scalar product we found in this paper.

For concreteness, in this paper we exemplify the method in the case of non-compact spin chains in a specific representation⁷ with highest weight $(-1, 0, \dots, 0)$. We expect that the argument can be generalized to other representations, as well as to the compact case, and to be applicable also in the case of the fishnet model [48] and $\mathcal{N}=4$ super Yang-Mills. In fact methods similar to the ones used in this paper already played a role in the computation of certain three point functions in these theories [50, 51], and we expect this extension to higher rank will help to develop a SoV approach to the computation of correlation functions.

Let us mention that the rough structure of the general type (1.13) was anticipated in [52] (for a different model) based on hints from the classical SoV construction. In particular, the presence of the shift operators is nicely suggested by the classical picture (see also [53]).

The paper is organised as follows. In section 2 we discuss in more detail our strategy and outline the derivation of our results. In section 3 we discuss the simplest example of

⁷In our notation the fundamental representation has highest weight $(1, 0, \dots, 0)$.

the $\mathfrak{sl}(2)$ spin chain, for which in particular we reproduce the known Sklyanin’s measure, which was obtained before in [14, 15] via a highly involved computation. Then in section 4 we derive the scalar product for the first higher rank case $\mathfrak{sl}(3)$ and discuss in detail various complications which we will see are neatly resolved by using algebraic properties of transfer matrices. Finally in section 5 we generalize our results to any $\mathfrak{sl}(N)$. We summarize and conclude in section 6.

2 General strategy and notation

In this section we briefly outline the strategy, which we use in the rest of the paper to derive our main result — the expression for the measure factor in the scalar product in separated variables given in (1.8). We skip most of the technical details here.

Q-functions and Bethe roots. The most familiar approach to the spin chains is in terms of the Bethe ansatz, which is a set of algebraic equations on the Bethe roots $u_{k,\alpha}$, where $\alpha = 1, \dots, N - 1$ represents the nesting level [56, 57]. The lowest level roots $u_{k,1}$ are the *momentum-carrying Bethe roots*: they play a special role as the energy and momentum of a Bethe states can be expressed solely in terms of those. Instead of using explicitly the Bethe roots it is much more convenient to pack them into the Q-functions also known as twisted Baxter polynomials. In particular $Q_1 = e^{u\phi_1} \prod_k (u - u_{k,1})$, where $e^{i\phi_1}$ is an eigenvalue of the twist matrix for the quasi-periodic chain. One can show that the twisted polynomial Q_1 uniquely identifies the Bethe state (by twisted polynomial we mean polynomial times exponent). Another important set of objects, which will play the central role, are the Q-functions with $N - 1$ indices, which we denote by $Q_{\bar{a}}$ as in (1.9). Those contain the roots on the last level of nesting $u_{k,N-1}$, however, there is a number of ways the Bethe ansatz equations can be written, which results in $N - 1$ different sets of roots at the level $\alpha = N - 1$, which are labelled by the index $a = 1, \dots, N - 1$ of $Q_{\bar{a}}$. The Bethe roots $u_{k,N-1}$ *do not* characterise the state uniquely, as there are plenty of states with no roots at the last nesting level. However, the set of all $Q_{\bar{a}}$, $a = 1, \dots, N - 1$ does determine the state uniquely as is clear from the identity

$$Q_1 = \det \left(Q_{\bar{a}}^{[N-2b]} \right)_{1 \leq a, b \leq N-1} , \tag{2.1}$$

where we introduced the notation

$$f^{[n]} \equiv f(u + in/2), \quad f^{\pm} \equiv f(u \pm i/2) \tag{2.2}$$

for the shifts in the argument. The relation (2.1) follows from the QQ-relations, see e.g. the review [34].

Baxter TQ relations. In order to find the Q-functions $Q_1(u)$, one should solve an N -th order finite-difference Baxter equation, which schematically has the form

$$\hat{O} \circ Q_1 = 0 , \tag{2.3}$$

where the difference operator \hat{O} is given by

$$\hat{O} \circ f \equiv \tau_0^{[N]} f^{[N]} - \tau_1^{[N-2]} f^{[N-2]} + \dots + (-1)^{N-1} \tau_{N-1}^{[-N+2]} f^{[-N+2]} + (-1)^N \tau_N^{[-N]} f^{[-N]} \quad (2.4)$$

and the coefficients $\tau_k(u)$ for a spin chain of length L are L^{th} order polynomials, which are⁸ the eigenvalues of the spin chain transfer matrices in the finite-dimensional antisymmetric $\mathfrak{sl}(N)$ irreps (see e.g. [25]). The first and the last coefficients are related by $\tau_0(u + i/2) = \tau_N(u - i/2)$ and fixed to be the same for all states, which allows to introduce the polynomial Q_θ such that $\tau_0 = Q_\theta^-$, $\tau_N = Q_\theta^+$. The other polynomials τ_a , whose expansion in u yields the integrals of motion for the state under consideration,

$$\tau_a(u) = u^L \chi_a(G) + \sum_{j=1}^L u^{j-1} I_{a,j-1}, \quad a = 1, \dots, N-1, \quad (2.5)$$

have to be determined from the self-consistency of the equations (2.3) with certain polynomiality conditions for the Q-functions. The leading u^L coefficient in $\tau_a(u)$ is the character of the a -th antisymmetric $\mathfrak{su}(N)$ representation $\chi_a(G)$ of the diagonal $SU(N)$ twist matrix $G = \text{diag}(e^{i\phi_1}, \dots, e^{i\phi_N})$.⁹ In the generic situation we will find only one twisted polynomial solution $Q_1(u)$ to the difference equation (2.3), which would determine us the momentum-carrying Bethe roots. The polynomial Q_θ determines the system and its roots have the meaning of inhomogeneities. In the simplest case of the homogeneous spin chain $Q_\theta = u^L$. However, the expressions we obtain are more natural in the most general case when

$$Q_\theta = \prod_{i=1}^L (u - \theta_i), \quad (2.6)$$

with all θ_i taken different.

It happens that the “dual” set of Q-functions $Q_{\bar{a}}$ satisfies a very similar finite difference equation

$$\hat{\hat{O}} \circ Q_{\bar{a}} = 0, \quad a = 1, 2, \dots, N-1, \quad (2.7)$$

with

$$\hat{\hat{O}} \circ g \equiv \tau_0 g^{[-N]} - \tau_1 g^{[-N+2]} + \dots + (-1)^{N-1} \tau_{N-1} g^{[N-2]} + (-1)^N \tau_N g^{[N]}. \quad (2.8)$$

Again, one can check that the equation (2.8), where the polynomial coefficients are already fixed to be the same as in (2.3), in general has N independent solutions, but only $N-1$ of them can be chosen to be twisted polynomials, which are precisely our $Q_{\bar{a}}$, $a = 1, \dots, N-1$.

The strategy. By looking at (2.3) and (2.8) we may notice that the operators \hat{O} and $\hat{\hat{O}}$ are in a sense conjugate to each other. Indeed, they contain the same coefficients, but with different shifts in the argument. To make this idea more precise we have to define an inner product for functions of one variable (which should not be confused with the scalar

⁸Up to shifts of the argument and trivial overall factors.

⁹More precisely we have $\det(1 + \lambda G) = \sum_{a=0}^N \chi_a(G) \lambda^a$.

product of two spin chain states). The key observation is that in fact one can define not just one but L such inner products

$$\langle gf \rangle_j \equiv \int_{-\infty}^{+\infty} du g(u) \mu_j(u) f(u), \quad j = 1, \dots, L. \quad (2.9)$$

Below we specify more precisely the explicit form of the factors $\mu_j(u)$ defining the norm, at this stage we notice that $\mu_j(u)$ should be i -periodic functions. In this case, assuming we can move the integration contour up and down in the complex plane by a multiple of i , we can transfer the shifts from f onto g while also modifying the shifts in the polynomial coefficients τ_n . In this way we precisely obtain that the two finite difference operators \hat{O} and $\hat{\tilde{O}}$ are indeed conjugate to each other with respect to these inner products,

$$\langle f \hat{O} g \rangle_j = \langle g \hat{\tilde{O}} f \rangle_j, \quad 1 \leq j \leq L. \quad (2.10)$$

In practice the exact form of the factors μ_j is constrained by the possibility to move the contours up and down and by the convergence of the integral when f and g are twisted polynomials. In addition, the proof of (2.10) involves certain identities, which f and g should satisfy, which luckily do hold in the situations where we use this argument below. In the next sections we provide more details on this and show how our approach works in explicit examples.

Having the conjugation property (2.10), we can use standard arguments to prove “orthogonality” conditions that are satisfied by the Q-functions Q^A and Q^B corresponding to different Bethe states $|\Psi_A\rangle$ and $|\Psi_B\rangle$. In fact, using (2.10) we immediately derive $L \times (N-1)$ independent equations

$$\langle Q_1^A (\hat{O}^A - \hat{O}^B) \circ Q_a^B \rangle_j = 0, \quad 1 \leq a \leq N-1, \quad 1 \leq j \leq L, \quad (2.11)$$

where \hat{O}^A and \hat{O}^B are the Baxter operators (2.8) defined in terms of the transfer matrix eigenvalues $\tau_a^A(u)$ and $\tau_a^B(u)$ for the two states. Notice that (2.11) can also be viewed as a linear system of equations on the coefficients of the polynomials $\tau_a^A(u) - \tau_a^B(u)$. At least one of these coefficients is nonzero whenever we consider two different Bethe states. We have $N-1$ non-trivial polynomials τ_a of degree L , which makes in total around $\sim (N-1) \times L$ non-trivial coefficients.¹⁰ At the same time we have exactly $(N-1) \times L$ equations (2.11). In order for this homogeneous system to have a non-zero solution we must have the determinant of the system to be zero for $A \neq B$:

$$\det_{(a,i),(b,j)} \left(\langle Q_1^A u^i Q_a^{B[N-2b]} \rangle_j \right) \propto \delta_{AB}, \quad (2.12)$$

where we use the above notation to denote the determinants of the $L \times (N-1)$ matrix

¹⁰In order to make the precise counting one needs to consider the generic *twisted* boundary conditions.

defined by blocks. Explicitly,

$$\left| \begin{array}{cccc}
 \left(\langle Q_1^A Q_1^B [N-2] u^{j-1} \rangle_i \right) & \left(\langle Q_1^A Q_1^B [N-4] u^{j-1} \rangle_i \right) & \dots & \left(\langle Q_1^A Q_1^B [-N+2] u^{j-1} \rangle_i \right) \\
 \left(\langle Q_1^A Q_2^B [N-2] u^{j-1} \rangle_i \right) & \left(\langle Q_1^A Q_2^B [N-4] u^{j-1} \rangle_i \right) & \dots & \left(\langle Q_1^A Q_2^B [-N+2] u^{j-1} \rangle_i \right) \\
 \vdots & \vdots & \ddots & \vdots \\
 \left(\langle Q_1^A Q_{N-1}^B [N-2] u^{j-1} \rangle_i \right) & \left(\langle Q_1^A Q_{N-1}^B [N-4] u^{j-1} \rangle_i \right) & \dots & \left(\langle Q_1^A Q_{N-1}^B [-N+2] u^{j-1} \rangle_i \right)
 \end{array} \right|_{1 \leq i, j \leq L} \propto \delta_{AB}, \quad (2.13)$$

which leads to the Sklyanin-like scalar product defined as the r.h.s. of (1.8). Therefore, we have proved rigorously that this expression satisfies a crucial property for the scalar product $\langle \Psi_A | \Psi_B \rangle$: it vanishes for any two different Bethe states. This derivation also reproduces the $\mathfrak{sl}(2)$ result as its particular case $N = 2$.

To offer more justification to why the proposed expression (1.8) is the scalar product in the SoV basis, we will also consider the computation of a physically well defined quantity that is easily obtainable in our formalism. Namely, we compute the matrix element of the derivative of one of the conserved quantities I_n with respect to some parameter p (it could be the twist angle or the inhomogeneity). Whereas \hat{I}_n itself acts diagonally on the Bethe states, its derivative $\partial \hat{I}_n / \partial p$ is not diagonalized by the Bethe states. By computing the expectation value of this operator on a Bethe state we found that the result is a ratio of two determinants. The one in the denominator again precisely coincides with the scalar product (1.8) for $A = B$.

Note that the condition of orthogonality, which our result does obey, is extremely constraining. The spectrum of the spin chain contains infinitely many states and even more distinct pairs of states, which imposes infinitely many conditions on the state-independent operator $\hat{M}(x)$. Given its amazingly simple form (1.10) and the fact that it reduces to the known norm in the $N = 2$ case, there is little doubt in the validity of our result. Nevertheless, it would be interesting to develop a rigorous derivation, which would involve explicit construction of the operator \hat{C}^{good} and its spectrum as described in the introduction.

3 Sklyanin measure for $\mathfrak{sl}(2)$ revisited

In this section we pedagogically describe how our method works for the simplest example, namely the $\mathfrak{sl}(2)$ noncompact rational spin chain. We will consider the case when at each site of the spin chain we have an infinite-dimensional $s = -1/2$ representation of $\mathfrak{sl}(2)$. The Bethe ansatz equations in the most general case of inhomogeneous spin chain with twisted boundary conditions are

$$\prod_{n=1}^L \frac{u_j - \theta_n - i/2}{u_j - \theta_n + i/2} = -e^{2i\phi} \prod_{k=1}^M \frac{u_j - u_k + i}{u_j - u_k - i}, \quad j = 1, \dots, M, \quad (3.1)$$

where the θ_n 's are the fixed inhomogeneities at each site, which we assume to be real,¹¹ and ϕ is the fixed twist parameter. We assume ϕ is nonzero and real and then as we see

¹¹this does not reduce the generality of our results as one can always analytically continue the result in θ_i 's, treating carefully the integration contours.

from (3.1) we can always restrict to $\phi \in (0, \pi)$. The spectrum of integrals of motion is determined in terms of the Bethe roots u_j , which one can find from (3.1).

In order to define the eigenvalues of the integrals of motion we introduce the *twisted* Baxter polynomial¹²

$$Q_1(u) = e^{u\phi} \prod_i (u - u_i), \tag{3.2}$$

then the eigenvalues of the transfer matrix can be deduced from the Baxter TQ relation

$$\hat{O} \circ Q_1 \equiv Q_\theta^+ Q_1^{++} - \tau_1 Q_1 + Q_\theta^- Q_1^{--} = 0, \tag{3.3}$$

with Q_θ defined as before in (2.6). The transfer matrix eigenvalue $\tau(u)$ is a polynomial in u of the form

$$\tau(u) = 2 \cos \phi u^L + \sum_{n=0}^{L-1} I_n u^n. \tag{3.4}$$

Notice that its first coefficient is fixed by (3.2) together with the Baxter equation. The remaining coefficients I_n correspond to eigenvalues of the nontrivial integrals of motion, which in general are different for different states.

The Baxter equation (3.3) is equivalent to the initial set of Bethe ansatz equations (3.1) after imposing polynomiality of $\tau_1(u)$ and also requiring $Q_1(u)$ to be of the form $e^{u\phi} \times$ [polynomial]. Under these conditions the Baxter equation (3.3) has a discrete set of solutions which are in one-to-one correspondence with the states of the spin chain.

3.1 Orthogonality relations

In this section we describe yet another way of finding the Bethe roots or equivalently $Q_1(u)$. One notices that the Q-function has many similarities with orthogonal polynomials. For instance, for the case of spin chain of length $L = 1$ one can show that the polynomials $q(u) = e^{-\phi u} Q_1(u)$ are orthogonal polynomials for the measure $\frac{e^{2u\phi}}{1+e^{2\pi(u-\theta_1)}}$. More precisely

$$\langle Q_1^A Q_1^B \rangle \equiv \int_{-\infty}^{\infty} \mu(u) Q_1^A(u) Q_1^B(u) du \propto \delta_{AB}, \quad \mu(u) \equiv \frac{1}{1 + e^{2\pi(u-\theta_1)}}. \tag{3.5}$$

First, we see that the integral above is convergent due to the choice $0 < \phi < \pi$.¹³ Second, the orthogonality relation actually defines the polynomials $q(u)$ uniquely for a given degree of the polynomial. Thus (3.5) is an alternative way of writing the Bethe ansatz equations for $Q_1(u)$.

For general $L > 1$ there is more than one solution of the Bethe equations for a given number of roots, so the strict analogy with the orthogonal polynomials does not go further in the naive way. To understand how that works, let us first derive (3.5) for $L = 1$ from the Baxter equation, which defines for us a finite difference operator \hat{O} (2.4) (which itself depends on the Bethe state through $\tau(u)$) such that $\hat{O} \circ Q_1 = 0$. As we discussed in

¹²We use the subscript Q_1 to emphasize the fact that the Q-system contains in this case two Q-functions. Indeed the Baxter equation has a second independent solution, Q_2 , which contrary to Q_1 is not a twisted polynomial but instead has poles.

¹³The untwisting limit $\phi = 0$ can be derived in a similar way.

section 2 there is a second operator \hat{O} which in general annihilates the dual Q-functions $Q_{\bar{a}}$, but in the case of $\mathfrak{sl}(2)$ there is only one $Q_{\bar{1}}$ and it coincides with Q_1 . In other words we need to show that \hat{O} is self-conjugate under the scalar product (3.5), i.e. for any¹⁴ twisted polynomials F_1, F_2

$$\langle F_1 \hat{O} \circ F_2 \rangle = \langle F_2 \hat{O} \circ F_1 \rangle . \tag{3.6}$$

We start from

$$\langle F_1 \hat{O} \circ F_2 \rangle = \int du \mu(u) F_1 (Q_{\theta}^+ F_2^{++} + Q_{\theta}^- F_2^{--} - \tau F_2) . \tag{3.7}$$

Shifting the integration contour by $-i$ in the first term (i.e. replacing there $u \rightarrow u - i$) and by i in the second term, we find that this expression becomes precisely $\langle F_2 \hat{O} \circ F_1 \rangle$ as we wanted. However, we should justify the possibility to shift the integration contour. When doing the shift $u \rightarrow u - i$ for the first term in r.h.s. of (3.7), we should be careful as we are moving the contour through the point $u = \theta_1 - i/2$ where the measure μ has a simple pole. However, we have chosen this pole to be precisely at the location where the factor Q_{θ}^+ , originating from the Baxter equation, has a zero. Thus we can indeed move the contour. The same argument applies to the second term in (3.7), in which the pole at $u = \theta_1 + i/2$ is compensated by Q_{θ}^- . As a result, (3.6) is indeed valid. Now, the proof of the orthogonality (3.5) is almost immediate:

$$\begin{aligned} 0 &= 0 - 0 = \langle Q_1^A \hat{O}^B \circ Q_1^B \rangle - \langle Q_1^B \hat{O}^A \circ Q_1^A \rangle = \langle Q_1^A (\hat{O}^B - \hat{O}^A) \circ Q_1^B \rangle \\ &= \langle Q_1^A (\tau^A - \tau^B) Q_1^B \rangle = (I_0^A - I_0^B) \langle Q_1^A Q_1^B \rangle , \end{aligned} \tag{3.8}$$

where we added the superscripts A and B to indicate that \hat{O} is different for the two different states. Finally, we note that for two different states the values of integrals of motion I_0 have to be distinct, leading to the conclusion that (3.5) is indeed true.

Orthogonality for general L . Now we can see the difficulty one would have for $L > 1$. The self-conjugation property of \hat{O} would be still valid and all steps in (3.8) would go through, except for the last one. What we get instead is

$$\langle Q_1^A (\tau^A - \tau^B) Q_1^B \rangle = \sum_{i=0}^{L-1} (I_i^A - I_i^B) \langle Q_1^A u^i Q_1^B \rangle = 0 , \tag{3.9}$$

which no longer implies (3.5). However, for $L > 1$ we also gain a freedom in how to define $\mu(u)$. Namely, we can use any of the following measures:

$$\mu_j(u) = \frac{1}{1 + e^{2\pi(u-\theta_j)}} , \quad j = 1, \dots, L , \tag{3.10}$$

and we will denote the corresponding integrals as

$$\langle f \rangle_j \equiv \int_{-\infty}^{\infty} \mu_j(u) f(u) du . \tag{3.11}$$

¹⁴Their twists should be such that the integral is convergent.

This means that we have a set of L equations like (3.9),

$$\sum_{i=1}^L (I_{i-1}^A - I_{i-1}^B) \langle Q_1^A u^{i-1} Q_1^B \rangle_j = 0 \quad , \quad j = 1, \dots, L \quad , \quad (3.12)$$

where $\langle \cdot \rangle_j$ is defined by (3.11). This homogeneous system of equations is only compatible if the determinant of the linear system is zero, so we get

$$\det \left| \langle Q_1^A u^{i-1} Q_1^B \rangle_j \right|_{1 \leq i, j \leq L} \propto \delta_{AB} \quad . \quad (3.13)$$

Note that each entry in the matrix (3.13) is defined as a single integral. However, we can rewrite it in the form that leads precisely to Sklyanin's scalar product for $\mathfrak{sl}(2)$,

$$\int \prod_{i=1}^L dx_i Q_1^A(x_i) M(\mathbf{x}) Q_1^B(x_i) \propto \delta_{AB} \quad , \quad (3.14)$$

where we also use that we can symmetrize over the integration coordinates x_i , ensuring that the measure factor M is symmetric in its L arguments:

$$M(\mathbf{x}) = \frac{\prod_{j < k} (e^{2\pi x_j} - e^{2\pi x_k})(x_j - x_k)}{\prod_{j, k} (1 + e^{2\pi(x_j - \theta_k)})} \quad , \quad (3.15)$$

which is precisely the measure derived in [14, 15]. So, in conclusion, we have re-derived the orthogonality of the Bethe states $|\Psi\rangle$ written in the SoV basis via (3.12). We can now change the direction of the logic and declare that the orthogonality relation (3.14) is a way alternative to (3.1) for defining this system from which one can determine $Q_1(u)$ and thus find the spectrum. We see that the knowledge of the measure is a powerful and non-trivial seed containing the knowledge of the spectrum. In addition one can utilize it to compute some non-trivial matrix elements as we show in the next section.

3.2 Simple form factors

Some form-factors, such as 1-point functions in 2D Sinh-Gordon theory, can be expressed in a nice way in terms of the Sklyanin's type of measure [58]. Generalization of this approach could lead to a non-perturbative expression of some 3-point functions in much more complicated theories such as 4D $\mathcal{N} = 4$ SYM. Here we consider a prototype of such observable — a diagonal matrix element of the variation of an integral of motion \hat{I}_n w.r.t. a parameter p . In $\mathcal{N} = 4$ SYM for instance one could consider the variation of the dilatation operator with respect to the coupling constant. The corresponding expectation values are associated to diagonal OPE coefficients involving the Lagrangian \mathcal{L} .¹⁵ In some limits of this theory studied together with A. Sever we indeed found a formula reminiscent of SoV for this observable [50, 51]. Here we generalise the method introduced there.

¹⁵More generally, in any CFT one can obtain in this way diagonal OPE coefficients $\mathcal{C}_{\mathcal{O}\mathcal{O}\mathcal{M}}$, involving a generic operator \mathcal{O} and a marginal operator \mathcal{M} [49].

For simplicity in the present setting we consider variations with respect to the twist, $p = \phi$. To study the matrix element one can use the standard logic of the perturbation theory,¹⁶

$$0 = \partial_p \langle \Psi | (\hat{I}_n - I_n) | \Psi \rangle = \langle \Psi | (\partial_p \hat{I}_n - \partial_p I_n) | \Psi \rangle \quad (3.16)$$

meaning that the expectation value of the non-diagonal operator $\partial_p \hat{I}_n$ is given by the derivative of the eigenvalue I_n w.r.t. the parameter,

$$\frac{\langle \Psi | \frac{\partial \hat{I}_n}{\partial p} | \Psi \rangle}{\langle \Psi | \Psi \rangle} = \frac{\partial I_n}{\partial p} . \quad (3.17)$$

The r.h.s. is already much easier to compute — one could find a solution of the Bethe ansatz equations at two close values of the parameter p and then find the difference of the T-function coefficient. However, if we think about the l.h.s. of (3.17) as a matrix element we should be able to write it in the SoV basis, which should look similar to the expression for the norm (3.14) with possible extra insertions, meaning that we should be able to express the result in terms of Q_1 computed at one given value of p .

To achieve this we can use some tricks from the previous section. Namely, consider

$$0 = \langle Q_1 | (\hat{O} + \delta \hat{O}) \circ (Q_1 + \delta Q_1) \rangle_i = \langle Q_1 | \hat{O} \circ \delta Q_1 \rangle_i + \langle Q_1 | \delta \hat{O} \circ Q_1 \rangle_i , \quad (3.18)$$

where δ stands for the variation w.r.t. the parameter p . Note that the first term vanishes since we can act with \hat{O} to the left, as a result we get

$$\langle Q_1 | (\partial_p \hat{O}) \circ Q_1 \rangle_i = 0 . \quad (3.19)$$

For definiteness let us take $p = \phi$. In this case $\partial_p \hat{O} = \partial_p \tau(u) = \sum_{n=0}^L u^n \partial_p I_n$. The main difference with the previous section is that the leading term in $\tau(u)$ does not cancel, since $I_L = 2 \cos \phi$. This means that the system of equations (3.19) is a non-homogeneous system of the form

$$\sum_{n=0}^{L-1} \langle Q_1^2 u^n \rangle_i \partial_\phi I_n = 2 \sin \phi \langle Q_1^2 u^L \rangle_i , \quad i = 1, \dots, L , \quad (3.20)$$

We see that the matrix in this linear system is exactly the same as in (3.12) with $A = B$. This means that by solving the linear equation (3.20) by Cramer's rule, we obtain an expression of the form factor in terms of a ratio of determinants, where in the denominator we have the same determinant (3.13) defining the “square norm” of the state, and in the numerator the determinant of the same matrix, but with one column replaced:

$$\partial_\phi I_k = \frac{1}{2 \sin \phi} \frac{\det_{i,j=1,\dots,L} m_{ij}^{(k)}}{\det_{i,j=1,\dots,L} m_{ij}} , \quad k = 0, \dots, L-1 , \quad (3.21)$$

where

$$m_{ij} \equiv \langle Q_1^2 u^{j-1} \rangle_i ; \quad m_{ij}^{(k)} = m_{ij} , \quad \text{for } j \neq k+1 \quad \text{and} \quad m_{i,k+1}^{(k)} = \langle Q_1^2 u^L \rangle_i . \quad (3.22)$$

¹⁶For real inhomogeneities and twists the coefficients \hat{I}_n in the transfer matrix should be linear combinations of mutually commuting self-conjugate operators.

Evaluating these determinants explicitly we get the SoV-type formula

$$\frac{\langle \Psi | \frac{\partial \hat{I}_l}{\partial \phi} | \Psi \rangle}{\langle \Psi | \Psi \rangle} = \frac{(-1)^l}{2 \sin \phi} \frac{\int d^L \mathbf{x} \Psi(\mathbf{x}) M(\mathbf{x}) P_{L-l+1}(\mathbf{x}) \Psi(\mathbf{x})}{\int d^L \mathbf{x} \Psi(\mathbf{x}) M(\mathbf{x}) \Psi(\mathbf{x})}, \quad (3.23)$$

where the wave function in separated variables is given by the factorized product of the Q-function (1.1), and P_n is a homogeneous polynomial of degree n , obtained as a symmetrized product of n distinct variables from x_1, \dots, x_L , with unit normalization for each monomial.¹⁷

Note that in our case the insertion resulting from $\partial_\phi \hat{I}_n$ is just a function of \mathbf{x} , however, it is clear that already for $\partial_{\theta_j} \hat{I}_n$ we would get also some shift operators acting on one of the $\Psi(\mathbf{x})$ in the numerator of (3.23). This is in fact a generic feature of the SoV type of integrals as we will see in the next section.

4 SoV scalar product in $\mathfrak{sl}(3)$ spin chains

In this section we exemplify our approach for the $\mathfrak{sl}(3)$ case. Our starting point is a set of nested Bethe ansatz equations [56, 57],

$$\prod_{n=1}^L \frac{u_j - \theta_n - i/2}{u_j - \theta_n + i/2} = e^{i(\phi_1 - \phi_2)} \prod_{k \neq j}^{N_u} \frac{u_j - u_k + i}{u_j - u_k - i} \prod_{l=1}^{N_v} \frac{u_j - v_l - i/2}{u_j - v_l + i/2}, \quad (4.1)$$

$$1 = e^{i(\phi_2 - \phi_3)} \prod_{k \neq j}^{N_v} \frac{v_j - v_k + i}{v_j - v_k - i} \prod_{l=1}^{N_u} \frac{v_j - u_l - i/2}{v_j - u_l + i/2}, \quad (4.2)$$

where u_j are the momentum-carrying roots and v_j are the auxiliary Bethe roots. We consider the quasi-periodic boundary conditions parametrized by three twist angles ϕ_i , with $\sum_{i=1}^3 \phi_i = 0$.

As we already mentioned in the introduction the nested Bethe ansatz is ambiguous and in the current case has an alternative “dual” form (see e.g. [32, 59, 60])

$$\prod_{n=1}^L \frac{u_j - \theta_n - i/2}{u_j - \theta_n + i/2} = e^{i(\phi_1 - \phi_3)} \prod_{k \neq j}^{N_u} \frac{u_j - u_k + i}{u_j - u_k - i} \prod_{l=1}^{N_w} \frac{u_j - w_l - i/2}{u_j - w_l + i/2}, \quad (4.3)$$

$$1 = e^{i(\phi_3 - \phi_2)} \prod_{k \neq j}^{N_w} \frac{w_j - w_k + i}{w_j - w_k - i} \prod_{l=1}^{N_u} \frac{w_j - u_l - i/2}{w_j - u_l + i/2}, \quad (4.4)$$

where $N_w = N_u - N_v$.

As in the previous section we introduce the Baxter (twisted) polynomials

$$Q_1 = e^{\phi_1 u} \prod_{j=1}^{N_u} (u - u_j), \quad Q_{12} = e^{(\phi_1 + \phi_2)u} \prod_{j=1}^{N_v} (u - v_j), \quad Q_{13} = e^{(\phi_1 + \phi_3)u} \prod_{j=1}^{N_w} (u - w_j). \quad (4.5)$$

The “dual” roots w_k are not independent and can be derived from given u_j and v_k via the QQ-relation

$$Q_1 \propto Q_{12}^+ Q_{13}^- - Q_{12}^- Q_{13}^+, \quad (4.6)$$

which is valid up to a trivial proportionality factor.

¹⁷E.g., for $L = 3$, $P_1(\mathbf{x}) = x_1 + x_2 + x_3$, $P_2(\mathbf{x}) = x_1 x_2 + x_1 x_3 + x_2 x_3$, $P_3(\mathbf{x}) = x_1 x_2 x_3$.

Like in the previous section, we need to show that the Q-functions satisfy a finite difference equation with some polynomial coefficients as we outlined in (2.4) and (2.8). Let us define two polynomials τ_1 and τ_2 [29, 61]

$$\begin{aligned} \tau_1 &= Q_\theta^+ \frac{Q_1^{++}}{Q_1} + Q_\theta^- \frac{Q_1^{--}}{Q_1} \frac{Q_{12}^+}{Q_{12}^-} + Q_\theta^- \frac{Q_{12}^{[-3]}}{Q_{12}^-} , \\ \tau_2 &= Q_\theta^+ \frac{Q_{12}^{[+3]}}{Q_{12}^+} + Q_\theta^+ \frac{Q_1^{++}}{Q_1} \frac{Q_{12}^-}{Q_{12}^+} + Q_\theta^- \frac{Q_1^{--}}{Q_1} . \end{aligned} \tag{4.7}$$

One can check that these combinations of the Q-functions are indeed polynomials by observing that all poles must cancel due to the Bethe equations (4.1) and (4.2). Also, it is easy to check from (4.6) that in (4.7) one can replace Q_{12} by Q_{13} without changing the l.h.s. Finally, one can see that τ_2 and τ_1 are complex conjugate to each other.

Having τ_1 and τ_2 defined, we can easily verify that

$$\hat{O} \circ Q_1 \equiv Q_\theta^{++} Q_1^{[+3]} - \tau_1^+ Q_1^+ + \tau_2^- Q_1^- - Q_\theta^{--} Q_1^{[-3]} = 0 , \tag{4.8}$$

$$\hat{O} \circ Q_{\bar{a}} \equiv Q_\theta^- Q_{\bar{a}}^{[-3]} - \tau_1 Q_{\bar{a}}^- + \tau_2 Q_{\bar{a}}^+ - Q_\theta^+ Q_{\bar{a}}^{[+3]} = 0 , \tag{4.9}$$

where the second equation is satisfied by both $Q_{\bar{1}} \equiv Q_{12}$ and $Q_{\bar{2}} \equiv Q_{13}$. To check (4.8) and (4.9) one should simply plug the definition (4.7) into the above equations and check that all terms cancel.

As was outlined in the section 2, we need to demonstrate that these two finite difference operators (4.8) and (4.9) are conjugate w.r.t. some inner product. Since (4.8) and (4.9) do have the correct form as in (2.4) and (2.8), this property is almost guaranteed if we are allowed to move the integration contour. In the next section we verify that all extra contributions arising from the shifts of the contours do cancel.

4.1 Poles cancellation

Like in the previous section we define the bracket

$$\langle f \rangle_j \equiv \int_{-\infty}^{\infty} \mu_j(u) f(u) du , \quad \mu_j(u) = \frac{1}{1 + e^{2\pi(u-\theta_j)}} . \tag{4.10}$$

What we are going to show is that

$$\langle Q_1 \hat{O} \circ f \rangle_j = 0 , \tag{4.11}$$

where f is a twisted polynomial with the same asymptotic as any of $Q_{\bar{a}}$, in other words we do not require the roots of f to satisfy the Bethe ansatz equations, otherwise the statement (4.11) would be trivial. First let us comment on the convergence of this integral. Assuming $f = e^{\alpha u} \times [\text{polynomial}]$, the integrand in (4.11) goes like $e^{(\phi_1 + \alpha - 2\pi)u} \times [\text{polynomial}]$ at $u \rightarrow +\infty$ and $e^{(\phi_1 + \alpha)u} \times [\text{polynomial}]$ at $u \rightarrow -\infty$. From this we deduce the condition of convergence $0 < \phi_1 + \alpha < 2\pi$. Since this inequality should hold for $\alpha = \phi_1 + \phi_2$ or $\alpha = \phi_1 + \phi_3$, which are the twists in $Q_{\bar{1}}$ and $Q_{\bar{2}}$, we get

$$0 < \phi_1 - \phi_2 < 2\pi , \quad 0 < \phi_1 - \phi_3 < 2\pi . \tag{4.12}$$

Note, that the condition (4.12) does not restrict the generality of our consideration as one can always choose ϕ_a 's so that (4.12) is satisfied. The only physically distinguished combinations of the ϕ_a 's are the phases $e^{i(\phi_1-\phi_2)}$ and $e^{i(\phi_2-\phi_3)}$, appearing in the Bethe ansatz equations (4.1) (where we still assume that $\phi_1 + \phi_2 + \phi_3 = 0$).

To prove (4.11), we show that we can transfer \hat{O} to become \hat{O} acting on Q_1 , which gives zero,

$$\begin{aligned} \langle Q_1 \hat{O} \circ f \rangle_j &= \int_{-\infty}^{+\infty} \mu_j(u) Q_1(u) \left[Q_\theta^- f^{[-3]} - \tau_1 f^- + \tau_2 f^+ - Q_\theta^+ f^{[+3]} \right] du \quad (4.13) \\ &= \int_{-\infty+i0}^{+\infty+i0} \mu_j \left(u + \frac{i}{2} \right) \left[\underbrace{Q_\theta^{++} Q_1^{[+3]} - \tau_1^+ Q_1^+ + \tau_2^- Q_1^- - Q_\theta^{--} Q_1^{[-3]}}_{\hat{O} \circ Q_1 = 0} \right] f(u) du \\ &\quad + \text{residues from poles ,} \end{aligned}$$

where we shifted the integration contour in each term so that at the end f appears with no shift. This results in shifts in Q_1 and we see that we get precisely the Baxter equation for Q_1 in the square brackets and also a shift of the argument in the i -periodic measure factor $\mu_j(u + \frac{i}{2})$. As a result, the only potentially nonzero contribution comes from residues at poles of the measure μ_j that we cross when shifting the contour. The measure $\mu_j(u)$ has poles at $u = \theta_j + \frac{i}{2} + in$, $n \in \mathbb{Z}$ with the same residue $-\frac{1}{2\pi}$. We are going to compute these residues.

Residues from the first term. For the first term $\mu_j(u) Q_1(u) Q_\theta(u - \frac{i}{2}) f(u - \frac{3i}{2})$ we will need to shift the contour up by $\frac{3i}{2} + 0i$, so that the final integration in the second line of (4.13) is slightly above the real axis. While shifting the contour we have two potential locations of residues which can contribute to the result — these are at $u = \theta_j + \frac{i}{2}$ and at $u = \theta_j + \frac{3i}{2}$. However, the first one does not contribute since $Q_\theta(\theta_j) = 0$. So we are left with the contribution

$$r_1 = -i Q_1 \left(\theta_j + \frac{3i}{2} \right) Q_\theta \left(\theta_j + \frac{i}{2} \right) f(\theta_j). \quad (4.14)$$

Residues from the second term. For the second term $-\mu_j(u) Q_1(u) \tau_1(u) f(u - \frac{i}{2})$ we only have one contribution at $u = \theta_j + \frac{i}{2}$, which gives

$$r_2 = +i Q_1 \left(\theta_j + \frac{i}{2} \right) \tau_1 \left(\theta_j + \frac{i}{2} \right) f(\theta_j). \quad (4.15)$$

Similarly, one can see there are no extra contributions from the remaining two terms and we get the following result

$$\langle Q_1 \hat{O} \circ f \rangle_j = r_1 + r_2 = i f(\theta_j) \left[Q_1 \left(\theta_j + \frac{i}{2} \right) \tau_1 \left(\theta_j + \frac{i}{2} \right) - Q_1 \left(\theta_j + \frac{3i}{2} \right) Q_\theta \left(\theta_j + \frac{i}{2} \right) \right]. \quad (4.16)$$

Finally, by looking at the definition (4.7) of the transfer matrix eigenvalue we see that the expression in the square brackets is precisely zero. This leads to the result (4.11).

We view this cancellation of residues as a significant indication of the validity of our approach. We see that even though those extra poles can spoil the generalisation from $\mathfrak{sl}(2)$ to $\mathfrak{sl}(3)$, luckily there exist these extra relations between Q-functions and transfer matrix eigenvalues, enabling the formalism to work.

4.2 Orthogonality relations

As we have already explained in section 2, the relation of the type (4.11) is the starting point for the derivation of the scalar product. Here we demonstrate that the general argument for the scalar product and the orthogonality relation goes through in the $\mathfrak{sl}(3)$ case.

First, consider the relation

$$\left\langle Q_1^A (\hat{O}^A - \hat{O}^B) \circ Q_a^B \right\rangle_i = 0, \quad a = 1, 2, \quad i = 1, \dots, L, \quad (4.17)$$

where we again use the superscript A and B to indicate that those Q-functions and Baxter operators correspond to two different Bethe states $|\Psi^A\rangle$ and $|\Psi^B\rangle$. To prove the relation above we use that $\hat{O}^B Q_a^B = 0$ and the property (4.11) with $f = Q_a^B$.

Next, we use again that the first and the last terms in \hat{O} do not depend on the state by definition (4.9) and we get

$$(\hat{O}^A - \hat{O}^B) \circ Q_a^B = \sum_{j=1}^L [-(I_{1,j-1}^A - I_{1,j-1}^B) u^{j-1} \mathcal{D}^{-1} \circ Q_a^B + (I_{2,j-1}^A - I_{2,j-1}^B) u^{j-1} \mathcal{D} \circ Q_a^B], \quad (4.18)$$

with the shift operator defined as in (1.11). Plugging (4.18) into the relation (4.17) we get a linear system of equations:

$$\sum_{(b,j)=(1,1)}^{(2,L)} \left\langle Q_1^A u^{j-1} \mathcal{D}^{-3+2b} \circ Q_a^B \right\rangle_i \times (-1)^b (I_{b,j-1}^A - I_{b,j-1}^B) = 0, \quad (4.19)$$

where we introduce the multi-index (b, j) , which takes $2L$ different values. This equation tell that $(-1)^b (I_{b,j-1}^A - I_{b,j-1}^B)$ should be a null vector of the $2L \times 2L$ matrix. In other words the determinant of this matrix should be zero for $|\Psi^A\rangle \neq |\Psi^B\rangle$, as for two different states at least some conserved charges should be different, so we get

$$\det_{(a,i),(b,j)} \left\langle Q_1^A u^{j-1} \mathcal{D}^{-3+2b} \circ Q_a^B \right\rangle_i = 0. \quad (4.20)$$

This is our orthogonality relation (2.13). We emphasise again that the existence of a simple orthogonality relation is highly nontrivial as there are infinitely many states in this model. Such an orthogonality relation should have an explanation at the level of the operators acting on the spin chain states such as $\hat{B}^{\text{good}}(u)$ and $\hat{C}^{\text{good}}(u)$, discussed in the introduction.

5 Extension to any $\mathfrak{sl}(N)$

In this section we extend the observations made in the previous section to the case of $\mathfrak{sl}(N)$ and prove the general formula for the scalar product (2.13).

There are two main relations to prove. First, we have to show that the Baxter equations for Q_1 and $Q_{\bar{a}}$ are indeed of the form (2.4), (2.8). Second, we need to demonstrate the cancellation of poles in the identity (4.11) for the case of any $\mathfrak{sl}(N)$. After that we can use (4.11) to derive the orthogonality relation between two different states in the SoV basis and read off the SoV measure from that as was done in the previous section.

5.1 Baxter operators for $\mathfrak{sl}(N)$ spin chain

Here we use the general formalism which allows one to build the eigenvalues of the transfer matrices in finite-dimensional totally antisymmetric representations τ_k .¹⁸ corresponding to Young diagrams with k boxes developed in [29] (for a review see [61]). In this method they are obtained from the generating functional

$$\mathcal{W} = \sum_{k=0}^N (-1)^k \tau_k \mathcal{D}^{2k}, \tag{5.1}$$

which can be written in analogy with the generating function for characters of antisymmetric $\mathfrak{sl}(N)$ representations as

$$\mathcal{W} = Q_{\theta}^{-} (1 - R_1 \mathcal{D}^2) (1 - R_2 \mathcal{D}^2) \dots (1 - R_N \mathcal{D}^2), \tag{5.2}$$

where each of the factors contains the shift operator \mathcal{D} and a rational function R_i , which is a combination of the twisted Baxter polynomials,

$$R_1 = \frac{Q_{\theta}^{+}}{Q_{\theta}^{-}} \frac{Q_1^{++}}{Q_1^{-}}, \quad R_i = \frac{Q_{J_{i-1}}^{[-i]}}{Q_{J_{i-1}}^{[2-i]}} \frac{Q_{J_i}^{[3-i]}}{Q_{J_i}^{[1-i]}}, \quad i = 2, \dots, N, \tag{5.3}$$

where we define the multi-index $J_i \equiv 12 \dots i$, such that for example $Q_{\bar{1}} = Q_{J_{N-1}}$. We also define

$$Q_{J_0} \equiv \frac{1}{Q_{\theta}}, \quad Q_{J_N} \equiv 1. \tag{5.4}$$

We assume that the twisted Baxter polynomials have the following form

$$Q_{i_1 \dots i_l} = e^{u \sum_{p=1}^l \phi_{i_p}} \times [\text{polynomial}], \tag{5.5}$$

with $\sum_{a=1}^N \phi_a = 0$.

We also have to show that τ_k 's are actually polynomials. This is not totally trivial as R_i are rational functions with various poles. We need to show that these poles cancel as a consequence of the Bethe ansatz equations. Let's look at the poles related to the Bethe roots at nesting level k , i.e. coming from zeros of Q_{J_k} . There are two R 's which contain Q_{J_k} in the denominator: R_k and R_{k+1} . Let us focus on the two terms containing these R 's,

$$\dots (1 - R_k \mathcal{D}^2) (1 - R_{k+1} \mathcal{D}^2) \dots = \dots (1 - (R_k + R_{k+1}) \mathcal{D}^2 + R_k R_{k+1} \mathcal{D}^4) \dots \tag{5.6}$$

$$= \dots \left(1 - \left[\frac{Q_{J_{k-1}}^{[-k]} Q_{J_k}^{[3-k]}}{Q_{J_{k-1}}^{[2-k]} Q_{J_k}^{[1-k]}} + \frac{Q_{J_k}^{[-k-1]} Q_{J_{k+1}}^{[2-k]}}{Q_{J_k}^{[1-k]} Q_{J_{k+1}}^{[-k]}} \right] \mathcal{D}^2 + \frac{Q_{J_{k-1}}^{[-k]} Q_{J_{k+1}}^{[4-k]}}{Q_{J_{k-1}}^{[2-k]} Q_{J_{k+1}}^{[2-k]}} \mathcal{D}^4 \right) \dots \tag{5.7}$$

¹⁸The actual eigenvalues T_k of the transfer matrices are related to τ_k in the following way: $T_k = \prod_{l=2}^k Q_{\theta}^{[2l-3]} \tau_k$ and $T_1 = \tau_1$, $T_0 = 1$.

We see that the poles due to zeros of Q_{J_k} in the square bracket cancel if we impose at the roots of $Q_{J_k}(u) = 0$ the following condition

$$\frac{Q_{J_{k-1}}^- Q_{J_k}^{++} Q_{J_{k+1}}^-}{Q_{J_{k-1}}^+ Q_{J_k}^{--} Q_{J_{k+1}}^+} = -1, \tag{5.8}$$

which is exactly the Bethe ansatz equation at the nesting level k . This argument applies for all $k = 1, \dots, N - 1$. In addition we should check that the poles at $u = \theta_j + \frac{i}{2}$ in R_1 cancel, however, this pole is nicely cancelled by the Q_θ^- prefactor in \mathcal{W} . Thus indeed all τ_k 's are polynomials due to the Bethe equations, just like in the $\mathfrak{sl}(3)$ case.

Now let us show that

$$\hat{O} = \mathcal{W} \mathcal{D}^{-N}, \tag{5.9}$$

indeed we see that it annihilates $Q_{\bar{1}}$,

$$\begin{aligned} \mathcal{W} \mathcal{D}^{-N} Q_{\bar{1}} &= \mathcal{W} \mathcal{D}^{-N} Q_{J_{N-1}} = \dots (1 - R_N \mathcal{D}^2) Q_{J_{N-1}}^{[-N]} \\ &= \dots \left(Q_{J_{N-1}}^{[-N]} - \frac{Q_{J_{N-1}}^{[-N]}}{Q_{J_{N-1}}^{[2-N]}} Q_{J_{N-1}}^{[2-N]} \right) = 0. \end{aligned} \tag{5.10}$$

Furthermore, it is obvious that $\tau_0 = Q_\theta^-$ and

$$\tau_N = Q_\theta^- R_1 R_2^{++} \dots R_N^{[2N]} = Q_\theta^+. \tag{5.11}$$

So indeed the Baxter equation for $Q_{\bar{1}}$ is of the general form given in (2.8). We should also show that \hat{O} annihilates *any* $Q_{\bar{a}}$, $a = 1, \dots, N - 1$. The remaining $Q_{\bar{a}}$'s are defined through the bosonic duality transformation [59–61]. Like in the $\mathfrak{sl}(3)$ case, one can show that the polynomials τ_k 's are invariant under this transformation [61]. For example, the duality transformation which defines $Q_{\bar{2}} = Q_{1,2,\dots,N-2,N}$ is

$$Q_{J_{N-2}} \propto Q_{\bar{1}}^+ Q_{\bar{2}}^- - Q_{\bar{1}}^- Q_{\bar{2}}^+, \tag{5.12}$$

which leads to the following identity

$$(1 - R_{N-1} \mathcal{D}^2)(1 - R_N \mathcal{D}^2) = (1 - \tilde{R}_{N-1} \mathcal{D}^2)(1 - \tilde{R}_N \mathcal{D}^2), \tag{5.13}$$

where \tilde{R}_i are the same as R_i with $Q_{J_{N-1}} = Q_{\bar{1}}$ replaced by $Q_{\bar{2}}$. After that one can repeat the same argument as in (5.10) to show that $\mathcal{W} \mathcal{D}^{-N} Q_{\bar{2}} = 0$. To obtain all $Q_{\bar{a}}$ one should apply the bosonic duality to other factors in \mathcal{W} as well, as explained in detail in [61].

In a similar way we can construct the Baxter equation for $Q_{\bar{1}}$. For that consider

$$\mathcal{W}^\dagger \equiv (1 - R_N^{--} \mathcal{D}^{-2})(1 - R_{N-1}^{--} \mathcal{D}^{-2}) \dots (1 - R_1^{--} \mathcal{D}^{-2}) Q_\theta^-, \tag{5.14}$$

which is related to \mathcal{W} by a formal conjugation, which flips the order of the operators and replaces \mathcal{D} by its inverse i.e. these two generating functionals are related according to the

rules $\mathcal{D}^\dagger \equiv \mathcal{D}^{-1}$ and $f(u)^\dagger \equiv f(u)$ and $(AB)^\dagger \equiv B^\dagger A^\dagger$.¹⁹ Applying this operation to the representation of \mathcal{W} (5.1) we get

$$\mathcal{W}^\dagger = \sum_{k=0}^N (-1)^k \tau_k^{[-2k]} \mathcal{D}^{-2k}. \quad (5.15)$$

We now can see that $\hat{O} = \mathcal{W}^\dagger$. Indeed

$$\mathcal{W}^\dagger Q_1 = \dots (1 - R_1^- \mathcal{D}^{-2}) Q_\theta^- Q_1 = \dots \left(Q_\theta^- Q_1 - \frac{Q_\theta^-}{Q_\theta^{[-3]}} \frac{Q_1}{Q_1^-} Q_\theta^{[-3]} Q_1^- \right) = 0. \quad (5.16)$$

Also we see that \hat{O} defined in this way indeed agrees with (2.4) in section 2 due to (5.15).

5.2 Poles cancellation

We have to demonstrate that the relation (4.11) still holds for general $\mathfrak{sl}(N)$. First, we need to ensure the convergence of the integral (4.11). This time we assume that $f(u)$ can be of the form $e^{-u\phi_c} \times [\text{polynomial}]$ for $c = 2, \dots, N$. In analogy with the analysis of the convergence for the $\mathfrak{sl}(3)$ case we have to require $0 < \phi_1 - \phi_c < 2\pi$ for $c = 2, \dots, N$, which should be always possible to achieve without reducing the generality.²⁰

Plugging the explicit form of \hat{O} from (5.9) into (4.11) we get

$$\langle Q_1 \hat{O} \circ f \rangle_j = \int_{-\infty}^{\infty} \mu_j(u) Q_1 Q_\theta^- (1 - R_1 \mathcal{D}^2) \underbrace{(1 - R_2 \mathcal{D}^2) \dots (1 - R_N \mathcal{D}^2)}_{\equiv F(u)} \mathcal{D}^{-N} f \, du. \quad (5.17)$$

Writing R_1 in an explicit way, and using the notation $F(u)$ for the product of all factors starting from the second acting on $f(u)$, we find

$$\langle Q_1 \hat{O} \circ f \rangle_j = \int_{-\infty}^{\infty} \mu_j(u) \left[Q_1(u) Q_\theta \left(u - \frac{i}{2} \right) F(u) - Q_1(u+i) Q_\theta \left(u + \frac{i}{2} \right) F(u+i) \right] du, \quad (5.18)$$

Next we see that we can shift the integration contour for the second term down by i to cancel precisely the first term. Shifting the contour we have to be careful at $u = \theta_j - \frac{i}{2}$ where $\mu_j(u)$ has a simple pole. However, the factor $Q_\theta(u + \frac{i}{2})$ vanishes exactly at $u = \theta_j - \frac{i}{2}$ ensuring that there are no extra contributions. There are no other poles to worry about because $Q_1(u)F(u)$ is pole-free due to the Bethe ansatz equations, which can be seen via the same argument as for \mathcal{W} itself before. This ends the proof of (4.11) for general $\mathfrak{sl}(N)$.

5.3 Orthogonality relations

Now having (4.11) proven in the general case, we can simply repeat the same steps as in section 4. Namely, instead of (4.17) for two different Bethe states $|\Psi^A\rangle$ and $|\Psi^B\rangle$ we have

$$\langle Q_1^A (\hat{O}^A - \hat{O}^B) \circ Q_a^B \rangle_i = 0, \quad a = 1, \dots, N-1, \quad i = 1, \dots, L. \quad (5.19)$$

¹⁹This transformation is consistent with the main algebraic identity for the shifts operators $\mathcal{D}f = f^+ \mathcal{D}$, which transforms under \dagger to $f \mathcal{D}^{-1} = \mathcal{D}^{-1} f^+$ which is equivalent to the initial one.

²⁰With an exception for the boundary cases e.g. $\phi_c = 0$, which can be obtained by taking the corresponding limits.

Next we use again that the first and the last terms in \hat{O} do not depend on the state by definition (4.9) and we get

$$\left(\hat{O}^A - \hat{O}^B\right) \circ Q_{\bar{a}}^B = \sum_{j=1}^L \sum_{b=1}^{N-1} (-1)^b (I_{b,j-1}^A - I_{b,j-1}^B) u^{j-1} \mathcal{D}^{[2b-N]} \circ Q_{\bar{a}}^B . \quad (5.20)$$

So it is clear that the generalization of (4.20) reads

$$\langle \Psi_A | \Psi_B \rangle \equiv \det_{(a,i),(b,j)} m_{(a,i),(b,j)} = 0 \quad , \quad m_{(a,i),(b,j)} \equiv \left\langle Q_1^A u^{j-1} \mathcal{D}^{2b-N} \circ Q_{\bar{a}}^B \right\rangle_i . \quad (5.21)$$

for the case when the two states are different. We claim that this should give the orthogonality relation of two Bethe states written in SoV representation. Above we again use $(N-1) \times L$ dimensional multi-indexes (a, i) and (b, j) to indicate the determinant of the rectangular matrix of the dimension $(N-1) \times L$. Another form of this orthogonality relation is given in the introduction in (1.8), (1.10).

5.4 Form factors

In this section we generalise the considerations of section 3.2, where we introduced a particular type of form factors of the operators which can be obtained as a derivative of the integrals of motion w.r.t. some parameter p , which can be a twist angle ϕ_a , $a = 1, \dots, N-1$ or one of inhomogeneities θ_i , $i = 1, \dots, L$. In section 3.2, we considered $p = \phi_a$. In general for both $p = \phi_a$ and $p = \theta_i$ we create quite a broad class of operators acting on the spin chain states, in total one can estimate that $p = \theta_i$ creates $\sim (N-1) \times L^2$ operators $\partial_{\theta_i} \hat{I}_{a,j-1}$ and for $p = \phi_a$ we get $\sim (N-1)^2 \times L$ operators $\partial_{\phi_a} \hat{I}_{a,j-1}$. It is not immediately clear if all of them are independent and if they form a complete enough algebra of operators, so that the general spin chain operator can be obtained as a multiple action of those. We postpone these interesting questions to future studies.

In analogy with (3.19) we have

$$\langle Q_1 \partial_p \hat{O} \circ Q_{\bar{a}} \rangle_i = 0 \quad , \quad a = 1, \dots, N-1 \quad , \quad i = 1, \dots, L . \quad (5.22)$$

Note that the right way to generalize (3.19) is to use $\partial_p \hat{O}$, rather than $\partial_p \hat{O}$, for exactly the same reason as in the previous section since (4.11) discriminates between the two. We have

$$\partial_p \hat{O} = \sum_{(b,j)} \partial_p I_{b,j-1} u^{j-1} \mathcal{D}^{2b-N} + \underbrace{[\partial_p Q_{\theta}^- \mathcal{D}^{-N} + (-1)^N \partial_p Q_{\theta}^+ \mathcal{D}^N]}_{\equiv -\hat{Y}_p} + \sum_b \partial_p I_{b,L} u^L \mathcal{D}^{2b-N} , \quad (5.23)$$

where we denoted by \hat{Y}_p the inhomogeneous part of the linear system for $\partial_p I_{n,j-1}$. Plugging into (5.19) we get

$$\sum_{(b,j)} m_{(a,i),(b,j)} \partial_p I_{b,j-1} = y_{(a,i)} \quad , \quad y_{(a,i)} \equiv \langle Q_1 \hat{Y}_p \circ Q_{\bar{a}} \rangle_i , \quad (5.24)$$

where $m_{(a,i),(b,j)}$ is the same matrix as defined in the previous section in (5.21) with two states taken to be the same.

Solving this system with Cramer’s method we obtain the following structure

$$\partial_p I_{c,k-1} = \frac{\det_{(a,i),(b,j)} \tilde{m}_{(a,i),(b,j)}}{\det_{(a,i),(b,j)} m_{(a,i),(b,j)}}, \tag{5.25}$$

where $\tilde{m}_{(a,i),(b,j)}$ is the matrix $m_{(a,i),(b,j)}$ with the column (c, k) replaced with $y_{(a,i)}$ defined in (5.24). Notice that the denominator has the meaning of the norm square $\|\Psi\|^2$ when comparing with (5.21). Furthermore, both numerator and denominator can be written in the SoV-like form

$$\partial_p I_{c,k-1} = \frac{\int d\mathbf{x} \Psi^\dagger(\mathbf{x}) \widehat{M}(\mathbf{x}) \circ \Psi(\mathbf{x})}{\int d\mathbf{x} \Psi^\dagger(\mathbf{x}) \widehat{M}(\mathbf{x}) \circ \Psi(\mathbf{x})}, \tag{5.26}$$

where we denote $\Psi(\mathbf{x}) = \prod_{(a,i)} Q_{\bar{a}}(x_{a,i})$ and $\Psi^\dagger(\mathbf{x}) = \prod_{(a,i)} Q_1(x_{a,i})$.

6 Conclusions

In this paper we have proposed the way to compute scalar products and form factors in SoV basis. Our method bypasses successfully the explicit construction of the separated variables and is valid for higher rank $\mathfrak{sl}(N)$ spin chains. Nevertheless, we hope that our result gives very strong hints of how to proceed with the first principle SoV construction too. We believe our construction should open the way to various new applications of the SoV methods beyond rank one systems. Let us discuss several of the promising future directions.

One of the important hints our result gives is that there should exist a “dual” SoV basis, potentially associated with some kind of $\widehat{C}^{\text{good}}$ operator, in analogy with the $\mathfrak{su}(2)$ case. In this dual basis the wave function should factorise into the product of dual Q-functions, or Baxter polynomials at the last nesting level $Q_{\bar{a}}$. This observation of our paper could also resolve the problems outlined at the classical level in [18]. Another question is to build an explicit map from the natural spin chain variables to the separated variables like it was done for $\mathfrak{sl}(2)$ in [37]. Having some explicit matrix elements, like those computed in this paper, could help to find an explicit integral transformation between these two bases.

We derived an expression for the SoV type of scalar product of two Bethe states. It would be interesting to see if this expression remains the same when one of the states is taken off-shell (even though this may not be always well defined). A more well-posed problem is to relate our result with the Gaudin norm. We expect that they coincide up to a simple prefactor, and we expect the proof to go the same way as in appendix of [17] for the case of $\mathfrak{su}(2)$. In regards to our results for the form-factors, it would be interesting to see if they could be generalised to the case with two different Bethe states.

As a natural extension, it would be interesting to generalize our results to other types of spin chains based on B_n, C_n, D_n Lie algebras, and especially to the supersymmetric case (particularly relevant for AdS/CFT applications), and also to various deformations, including trigonometric or even elliptic models, Gaudin models and boundary problems. It would be interesting to explore the implications of this construction for various classical/quantum and spectral dualities between integrable models [62–65].

While we have considered spin chains in a simple infinite-dimensional highest-weight representation, we expect the results should generalize to other representations since we only use the Baxter equations which are quite universal. We have already explored several examples [51] where the same approach works for more involved principal series representations appearing in integrable fishnet CFTs, where it is important to also add a spacetime twist serving as a regulator [66]. One of the methods one could try to use here is the *fusion* [55], which should allow one to directly generalise any construction from the fundamental to any representation obtained as a tensor product of fundamentals.

Our results should also play a role in developing the SoV solution of the integrable fishnet CFT [48] and of the *fishchain* model that serves as its dual [54] and is reminiscent of Toda chains. The advantage of the fishchain model is that we can also analyse the SoV construction in the simplified settings of the classical regime.

In this paper we also considered a particular type of form factors of the operators which can be obtained as a variation of the integrals of motions w.r.t. some parameters. These form factors are analogous to the 3-point correlators of the type $\langle \mathcal{O}\mathcal{O}\mathcal{L} \rangle$ in the fishnet theory or $\mathcal{N} = 4$ super Yang-Mills, where \mathcal{L} is a marginal operator such as the Lagrangian insertion²¹ and \mathcal{O} is a non-trivial single trace operator. SoV-type expressions for such structure constants, and even more general ones, have already been found in different parameter limits of $\mathcal{N} = 4$ SYM in a growing number of cases [50, 51, 68–70],²² giving strong indications of the viability of a SoV strategy for correlators. Generalization of our construction should give a closed totally non-perturbative expression for such 3-point correlator in terms of Q-functions, which are known from the Quantum Spectral Curve method developed in [72, 73], see [34, 35] for reviews. The simpler fishnet model should serve as an ideal playground to work out the details of the construction before uplifting it to the parent $\mathcal{N} = 4$ SYM theory. For the full $\mathcal{N} = 4$ SYM our results already suggest what structures to anticipate, for example we can expect to have the \mathbf{Q}_i and \mathbf{Q}^i Q-functions coupled in the scalar product.

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²¹Recently also considered in [67].

²²See also the recent results of [71] for a 3-point function expressed in terms of TBA solutions, suggesting additional fruitful connections.

A Explicit result for the $\mathfrak{sl}(3)$ scalar product at length 1

For the simplest higher rank example, namely the $\mathfrak{sl}(3)$ inhomogenous spin chain with 1 site and twisted boundary conditions, our scalar product (1.8) can be written in a compact determinant form

$$\langle \Psi_A | \Psi_B \rangle \propto \begin{vmatrix} \langle Q_1^A Q_{12}^{B+} \rangle & \langle Q_1^A Q_{12}^{B-} \rangle \\ \langle Q_1^A Q_{13}^{B+} \rangle & \langle Q_1^A Q_{13}^{B-} \rangle \end{vmatrix}, \quad (\text{A.1})$$

where

$$\langle f \rangle = \int_{-\infty}^{+\infty} dx \frac{1}{1 + e^{2\pi(x-\theta_1)}} f(x). \quad (\text{A.2})$$

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