

SINFA: Multivariate uncertainty analysis for confusion matrices

MARILYN D. WANG

University of Maryland Baltimore County
Baltimore, Maryland 21228

Stimulus-response confusion matrices are often used to summarize the results of perceptual experiments in which subjects must identify which stimulus, from a closed set of stimuli, has been presented on a given trial. The subject's performance is often assessed by calculating the amount of stimulus information transmitted. In the terminology of uncertainty analysis (Garner, 1962), transmitted information is a special case of contingent uncertainty $U(S:R)$, where the contingency is between stimuli and responses.

When the stimuli are multidimensional, it is possible to assess the amount of information transmitted for a single dimension or feature. This is accomplished by combining the cells of the confusion matrix to form a feature confusion matrix and calculating contingent uncertainty for this reduced matrix. If stimulus features are orthogonal and if the subject's responses to the different features are independent, then $U(S:R)$ is simply the sum of the contingent uncertainties for the features. If the stimulus features are redundant or if the responses to the features are not independent, then the sum of the feature contingent uncertainties will be greater than $U(S:R)$ because the redundancy has not been taken into account.

For multidimensional stimulus sets containing features F_1, F_2, \dots, F_k , $U(S:R)$ may be represented as a multiple contingent uncertainty $U(F_1, F_2, \dots, F_k: f_1, f_2, \dots, f_k)$, where uppercase letters designate stimulus features and lowercase letters designate response features. Garner (1962) has shown that the multiple contingent uncertainty can be partitioned into additive components and that there are a great many ways to perform the partitioning. One method of partitioning involves calculation of k^2 terms, k of which are of the form: $U(F_1: f_1)$, $U_{F_1, f_1}(F_2: f_2)$, $U_{F_1, F_2, f_1, f_2}(F_3: f_3)$, \dots , $U_{F_1, F_2, \dots, F_{k-1}, f_1, f_2, \dots, f_{k-1}}(F_k: f_k)$. The first term is the contingent uncertainty for F_1 . The second term is a partial contingent uncertainty for F_2 in which the effects of F_1 have been partialled out. The third term is a partial contingent uncertainty for F_3 in which the effects of both F_1 and F_2 have been partialled. The sum of k such terms will always be less than or equal to $U(S:R)$ and, there-

fore, the sum gives a measure of the amount of transmitted information accounted for by a given set of features. The sum is almost always less than $U(S:R)$ because the complete partitioning also involves $k(k-1)$ additional terms which represent partial "cross-contingencies" between a stimulus feature and a different response feature. These quantities are analogous to dimensional interactions.

SINFA (sequential information analysis) is a FORTRAN IV program which partitions $U(S:R)$ into a set of contingent uncertainties, each of which is associated with a single feature. Cross-contingencies are not computed. The order in which feature contingent uncertainties are calculated may be specified by the user (fixed mode) or may be determined by the program (free mode). In free mode, contingent uncertainty for a feature in a given iteration is divided by the maximum possible value for that feature to obtain a relative performance measure. In a given iteration, the feature with the highest relative level of performance is selected. In free mode an additional criterion is imposed on feature selection. A feature will not be selected unless the partial contingent necessary for the feature, divided by $U(S:R)$, is at least C , where C may be specified by the user. A more detailed description and illustration of the analysis may be found in Wang and Bilger (1973), and application of the method to confusion matrices for individual subjects is reported in Bilger and Wang (1976).

Input. Required input to the program consists of the number of stimuli, the number of features, a set of feature names and feature definitions, the order in which features are to be selected if the program is to be run in fixed mode, and the stimulus-response confusion matrix. Optional input consists of a 75-character title, a user-specified value of C (default value is .01), and a request for optional output described below.

Output. The SINFA summary table provides the following information for each iteration: the name of the feature selected, the partial contingent uncertainty for that feature, and the partial contingent uncertainty divided by $U(S:R)$. The latter value must be at least equal to C , and it gives the proportion of the total transmitted information accounted for by the feature when previously selected features are held constant. The sum across iterations for each of these measures is also given. Optional output consists of a table for each iteration which gives the following information for each feature: the partial contingent uncertainty, the maximum value of the partial contingent uncertainty, and the ratio of these two quantities (i.e., the relative performance measure).

Program limitations. SINFA will accept a confusion matrix for 30 stimuli and will accept up to 20 features with a maximum of 8 categories each. These values may

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easily be modified by changing the appropriate dimension statements. The program was written for a UNIVAC 1108 computer and requires 12,000 locations.

Availability. Detailed instructions for running the program and a source listing are available without cost from the author at the Department of Psychology, University of Maryland Baltimore County, Baltimore, Maryland 21228.

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