

SINGULARITIES OF EDDY CURRENT PROBLEMS

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Abstract. We consider the time-harmonic eddy current problem in its electric formulation where the conductor is a polyhedral domain. By proving the convergence in energy, we justify in what sense this problem is the limit of a family of Maxwell transmission problems: Rather than a low frequency limit, this limit has to be understood in the sense of Bossavit [11]. We describe the singularities of the solutions. They are related to edge and corner singularities of certain problems for the scalar Laplace operator, namely the interior Neumann problem, the exterior Dirichlet problem, and possibly, an interface problem. These singularities are the limit of the singularities of the related family of Maxwell problems.

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1. MAXWELL EQUATIONS AND THE EDDY CURRENT LIMIT

Let us consider the model case of an homogeneous conducting body Ω_C which we assume to be a three-dimensional bounded polyhedral domain with a Lipschitz boundary B . The conductivity $\sigma = \sigma_C$ is constant and positive inside Ω_C , while σ vanishes outside Ω_C , *i.e.*, $\sigma \equiv 0$ in the “air” (or “empty”) region $\Omega_E = \mathbb{R}^3 \setminus \overline{\Omega}_C$. For the sake of simplicity we further assume that the boundary B of Ω_C is connected^(*). The electric permittivity ε is equal to a positive constant ε_C inside Ω_C and has another value ε_E in the exterior medium. Similarly, the magnetic permeability μ is equal to $\mu_C > 0$ in Ω_C and to $\mu_E > 0$ in Ω_E . The treatment of piecewise constant $\sigma_C, \varepsilon_C, \mu_C$ and μ_E can be made in a similar manner.

1.1. Maxwell and eddy current problems

Let $\omega > 0$ be a fixed frequency. The time harmonic Maxwell equations are

$$\operatorname{curl} \mathbf{E} = -i\omega\mu\mathbf{H} \quad \text{in } \mathbb{R}^3, \quad (1)$$

$$\operatorname{curl} \mathbf{H} = (i\omega\varepsilon + \sigma)\mathbf{E} + \mathbf{j}_0 \quad \text{in } \mathbb{R}^3, \quad (2)$$

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^(*)The issue of a multiple connected B is independent of the question of singularities. We will just mention the modifications necessary when B is multiply connected, see Remark 2.1 at the end of Section 2.

\mathbf{E} (resp. \mathbf{H}) is the electric (resp. magnetic) field and \mathbf{j}_0 is the source current density which is supposed to be a $L^2(\mathbb{R}^3)$ field with support in Ω_C and to be divergence free, *i.e.* $\operatorname{div} \mathbf{j}_0 = 0$ in \mathbb{R}^3 . Let us recall

Lemma 1.1. *Let $\mathbf{u} \in L^2(\mathbb{R}^3)^3$ be such that $\mathbf{u}|_{\Omega_E} \equiv 0$ and $\operatorname{div} \mathbf{u} = 0$ in \mathbb{R}^3 . Then the normal trace $\mathbf{u}|_{\Omega_C} \cdot \mathbf{n}$ on B is zero (here \mathbf{n} denotes the unit outward normal vector on B , pointing from Ω_C to Ω_E).*

Thus the assumption on $\operatorname{div} \mathbf{j}_0$ is equivalent to

$$\operatorname{div} \mathbf{j}_0 = 0 \text{ in } \Omega_C \quad \text{and} \quad \mathbf{j}_0 \cdot \mathbf{n} = 0 \text{ on } B.$$

Note that, taking the divergence of equation (2), we obtain the following equation on the divergence of \mathbf{E} :

$$\operatorname{div}(i\omega\varepsilon + \sigma)\mathbf{E} = 0 \quad \text{in } \mathbb{R}^3. \tag{3}$$

Equations (1)–(2) have to be completed by conditions at infinity (Silver-Müller radiation conditions)

$$\lim_{|x| \rightarrow \infty} (\mathbf{H} \times x - |x| \mathbf{E}) = 0. \tag{4}$$

The time-harmonic eddy current problem [3, 10, 11, 22] reads

$$\operatorname{curl} \mathbf{E} = -i\omega\mu\mathbf{H} \quad \text{in } \mathbb{R}^3, \tag{5}$$

$$\operatorname{curl} \mathbf{H} = \sigma\mathbf{E} + \mathbf{j}_0 \quad \text{in } \mathbb{R}^3. \tag{6}$$

Let us denote $\mathbf{E}|_{\Omega_C}$ and $\mathbf{E}|_{\Omega_E}$ by \mathbf{E}_C and \mathbf{E}_E , respectively. Now, taking the divergence of equation (6) we only obtain, thanks to Lemma 1.1, $\operatorname{div} \mathbf{E}_C = 0$ in Ω_C and $\mathbf{E}_C \cdot \mathbf{n} = 0$ on B . These conditions *have to be completed by the gauge conditions*:

$$\operatorname{div} \mathbf{E}_E = 0 \text{ in } \Omega_E \quad \text{and} \quad \int_B \mathbf{E}_E \cdot \mathbf{n} \, dS = 0. \tag{7}$$

The condition at infinity takes the form

$$\mathbf{E}(x) = O(|x|^{-1}), \quad \mathbf{H}(x) = O(|x|^{-1}) \quad \text{as } |x| \rightarrow \infty. \tag{8}$$

Remark 1.1. Equations (5)–(6) are clearly obtained from (1)–(2) by setting ε to zero. The gauge conditions (7) can also be obtained from (3): Since $i\omega\varepsilon + \sigma$ is equal to the two non-zero constants $i\omega\varepsilon_C + \sigma$ in Ω_C and $i\omega\varepsilon_E$ in Ω_E , (3) implies that $\operatorname{div} \mathbf{E}_C = 0$ in Ω_C , $\operatorname{div} \mathbf{E}_E = 0$ in Ω_E and (by a result similar to Lem. 1.1)

$$(i\omega\varepsilon_C + \sigma_C)\mathbf{E}_C \cdot \mathbf{n} = i\omega\varepsilon_E\mathbf{E}_E \cdot \mathbf{n} \quad \text{on } B. \tag{9}$$

The condition $\operatorname{div} \mathbf{E}_C = 0$ implies by integration by parts that $\int_B \mathbf{E}_C \cdot \mathbf{n} = 0$. Then, by (9), we obtain that

$$\int_B \mathbf{E}_E \cdot \mathbf{n} \, dS = 0. \tag{10}$$

Setting $\varepsilon_C = \varepsilon_E = 0$, we obtain (7) and the two conditions issued from the equation $\operatorname{div}(\sigma\mathbf{E}) = 0$, that is

$$\operatorname{div} \mathbf{E} = 0 \text{ in } \Omega_C \cup \Omega_E \quad \text{and} \quad \mathbf{E}_C \cdot \mathbf{n} = 0 \text{ on } B. \tag{11}$$

Thus we see that the gauge conditions (7) are natural. But we obtain them by *first* deducing conditions on the divergence of the Maxwell solution \mathbf{E} and *then* passing to the limit. The converse order does not provide (7).

Remark 1.2. The conditions at infinity (4) imply the uniqueness of solutions for equations (1)–(2) (Rellich lemma). Moreover, with the (exterior) wave number $k := \omega\sqrt{\varepsilon_E\mu_E}$, we have the following asymptotics at infinity (here $\hat{x} := x/|x|$):

$$\mathbf{E}(x) = \frac{e^{ik|x|}}{|x|} \left(\mathbf{E}^\infty(\hat{x}) + O(|x|^{-1}) \right) \quad \text{as } |x| \rightarrow \infty.$$

The function \mathbf{E}^∞ is the *electric far field pattern*, see [12].

Concerning equations (5)–(7), the conditions at infinity (8) also imply the uniqueness, and the following asymptotics at infinity holds [3, Prop. 3.1]

$$\mathbf{E}(x) = O(|x|^{-2}), \quad \mathbf{H}(x) = O(|x|^{-2}) \quad \text{as } |x| \rightarrow \infty.$$

This means that the far field pattern goes to zero in the eddy current limit.

1.2. Eddy current limit

We want to give a sense to the notion of *eddy current limit*: This means that the quantities $\omega\varepsilon_C/\sigma_C$ and $\omega\varepsilon_E/\sigma_C$ are small. For a conducting material, the permittivity ε_C is of the same order of magnitude than ε_E (also denoted ε_0), but ε_C/σ_C is very small. For moderate frequencies ω the quantities $\omega\varepsilon_C/\sigma_C$ and $\omega\varepsilon_E/\sigma_C$ are still small. Let us fix two numbers $\hat{\varepsilon}_C$ and $\hat{\varepsilon}_E$ which are of the same order than σ_C and such that there exists $\delta > 0$ (thus δ is small)

$$\varepsilon_C = \delta\hat{\varepsilon}_C \quad \text{and} \quad \varepsilon_E = \delta\hat{\varepsilon}_E. \quad (12)$$

Thus

$$i\omega\varepsilon + \sigma = \begin{cases} i\omega\delta\hat{\varepsilon}_C + \sigma_C & \text{in } \Omega_C \\ i\omega\delta\hat{\varepsilon}_E & \text{in } \Omega_E. \end{cases} \quad (13)$$

We fix σ_C , ω , $\hat{\varepsilon}_C$ and $\hat{\varepsilon}_E$. The eddy current limit is the limit as $\delta \rightarrow 0$. This notion of limit coincides with that presented in [11, Ch. 4].

Thus, we may say that this limit is a “low frequency limit” only in the special sense that it is not a high frequency limit. *This limit is not a limit as $\omega \rightarrow 0$.* This fact is important, since there is a notion of high frequency asymptotics inside the eddy current model, which gives rise to boundary layers inside the conductor (skin effect).

1.3. Outline of the paper

In this paper, our main goal is the description of the singularities near the edges and corners of B of the eddy current problem (5)–(8). Moreover, considering a one parameter family of Maxwell problems along the lines of (12)–(13), we want to follow the singularities as $\delta \rightarrow 0$. The “standard” regularity and singularity results for the Maxwell interface problem from [9, 15, 17] can be adapted for $\delta > 0$, but not for the limit $\delta = 0$.

We show here that the regularity and the singularities of the solution of the eddy current problem are related to the regularity and the singularities of the interior Neumann Laplace operator, the exterior Dirichlet Laplace operator and the interface Laplace operator (for the parameter μ). To our knowledge this coupling phenomenon seems to be new. As in [15, 17] our technique relies on a regularized formulation of the problem and on the use of Mellin transformation.

Such results are useful for the numerical analysis of the eddy current problem as considered in [1, 22], where certain refinement rules or weighted regularization are susceptible to give a better order of convergence [6, 16, 19, 29].

Moreover, we show how the singularities of the eddy current problem are the limit as $\delta \rightarrow 0$ of the singularities of the Maxwell problem.

It turns out that from the point of view of singularities, the eddy current limit $\delta \rightarrow 0$ behaves like a regular perturbation problem. This means that one can choose the singular functions in such a way that they depend analytically on δ for δ in a neighborhood of 0, see Section 7. It does not mean, however, that the regularity of the solution as measured by Sobolev regularity in Ω_C (or in Ω_E) is a continuous function of δ : Indeed, if

the conductor is convex, the electric field \mathbf{E}_C in the eddy current model will be a bounded function *inside* the conductor, whereas the *exterior* electric field \mathbf{E}_E will be unbounded, in general. In the full Maxwell interface problem, *i.e.* for any $\delta > 0$, both parts \mathbf{E}_C and \mathbf{E}_E of the field will be unbounded, in general. In terms of Sobolev indices, the regularity of \mathbf{E}_C may jump from H^s with $\frac{1}{2} < s < 1$ to more than H^1 regularity as $\delta \rightarrow 0$.

Here is the outline of our paper: Since we are mainly interested in the singularities near B , and since their structure is of local nature, we will define our one-parameter family of problems in a bounded domain Ω and work in that framework in the remainder of the paper. In Section 2 we first replace the problems in \mathbb{R}^3 with problems in Ω , we propose equivalent regularized variational formulations and we prove the convergence of solutions in the energy space in the eddy current limit, *i.e.* as $\delta \rightarrow 0$.

Section 3 is devoted to a splitting of the variational space into a regular vector field which is piecewise H^1 and a singular part which is the gradient of a singular solution of a Laplace interface problem; this kind of decomposition is in the spirit of [5, 7–9].

After a short description of the corner and edge singularities for the Laplace interface problem in Section 4, we start the analysis of their dependence on the parameter δ and prove that their *exponents* (degrees) depend continuously on δ up to the limit $\delta = 0$.

We describe in Section 5 the corner and edge singularities for our eddy current problem (case when $\delta = 0$, the case $\delta > 0$ being already investigated in [17]). Section 6 is devoted to the regularity of the solution of the eddy current problem in terms of standard Sobolev spaces, we further give two different decompositions into a regular part and a singular one.

Finally Section 7 analyzes the *continuous dependence* of the singular functions on the parameter δ using Mellin symbols and the Cauchy residue formula.

For D a subdomain of \mathbb{R}^3 we denote by $H^s(D)$ the standard Sobolev space of order s , with norm denoted by $\|\cdot\|_{s,D}$.

2. VARIATIONAL FORMULATIONS

Let us take the polyhedron Ω_C with connected boundary B as in the previous section and let Ω be a smooth domain with trivial topology (for example a ball) which contains $\overline{\Omega}_C$. Now the exterior domain Ω_E is defined as $\Omega_E = \Omega \setminus \overline{\Omega}_C$.

For a function u defined in Ω we set u_C (resp. u_E) its restriction to Ω_C (resp. Ω_E). For a function u defined near B and such that the traces of u_C and of u_E on B have a meaning, we set $[u] = u_C - u_E$ its jump through B .

The partial differential operator ∂_n defined on B is the unit normal derivative pointing from Ω_C to Ω_E .

2.1. Strong form of equations

Instead of conditions at infinity (4) or (8), we will simply impose the perfect conductor boundary conditions on the exterior boundary $\partial\Omega$.

According to (13), we set $\hat{\varepsilon} = \hat{\varepsilon}_C$ in Ω_C and $\hat{\varepsilon} = \hat{\varepsilon}_E$ in Ω_E . Our Maxwell problem with parameter δ is

$$\begin{cases} \operatorname{curl} \mathbf{E}^\delta = -i\omega\mu\mathbf{H}^\delta & \text{in } \Omega, \\ \operatorname{curl} \mathbf{H}^\delta = (i\omega\delta\hat{\varepsilon} + \sigma)\mathbf{E}^\delta + \mathbf{j}_0 & \text{in } \Omega, \\ \mathbf{E}^\delta \times \mathbf{n} = 0 \quad \text{and} \quad \mathbf{H}^\delta \cdot \mathbf{n} = 0 & \text{on } \partial\Omega, \end{cases} \quad (14)$$

whereas the eddy current problem is

$$\begin{cases} \operatorname{curl} \mathbf{E}^0 = -i\omega\mu\mathbf{H}^0 & \text{in } \Omega, \\ \operatorname{curl} \mathbf{H}^0 = \sigma\mathbf{E}^0 + \mathbf{j}_0 & \text{in } \Omega, \\ \operatorname{div} \mathbf{E}^0 = 0 & \text{in } \Omega_E, \\ \int_B \mathbf{E}_E^0 \cdot \mathbf{n} \, dS = 0 \\ \mathbf{E}^0 \times \mathbf{n} = 0 \quad \text{and} \quad \mathbf{H}^0 \cdot \mathbf{n} = 0 & \text{on } \partial\Omega. \end{cases} \quad (15)$$

The resolution of the last problem is usually made by eliminating either the electric field (**H**-formulation or magnetic approach [2, 10, 11]) or the magnetic field (**E**-formulation or electric approach [1, 3, 10, 11, 22]). Here we focus on the electric approach, for both (14) and (15). We find the following systems of equations for any δ . This includes for $\delta \geq 0$ both the Maxwell and the eddy current problems.

$$\left\{ \begin{array}{ll} (i) & \mathbf{curl} \mu_C^{-1} \mathbf{curl} \mathbf{E}_C^\delta + i\omega\sigma_C \mathbf{E}_C^\delta - \delta\omega^2 \hat{\varepsilon}_C \mathbf{E}_C^\delta = -i\omega \mathbf{j}_0 \quad \text{in } \Omega_C, \\ (ii) & \operatorname{div} \mathbf{E}_C^\delta = 0 \quad \text{in } \Omega_C, \\ (iii) & \mathbf{curl} \mu_E^{-1} \mathbf{curl} \mathbf{E}_E^\delta - \delta\omega^2 \hat{\varepsilon}_E \mathbf{E}_E^\delta = 0 \quad \text{in } \Omega_E, \\ (iv) & \operatorname{div} \mathbf{E}_E^\delta = 0 \quad \text{in } \Omega_E, \\ (v) & \int_B \mathbf{E}_E^\delta \cdot \mathbf{n} \, dS = 0 \\ (vi) & [\mathbf{E}^\delta \times \mathbf{n}] = 0 \quad \text{on } B, \\ (vii) & i\delta\omega[\hat{\varepsilon} \mathbf{E}^\delta \cdot \mathbf{n}] + \sigma_C \mathbf{E}_C^\delta \cdot \mathbf{n} = 0 \quad \text{on } B, \\ (viii) & \mathbf{E}^\delta \times \mathbf{n} = 0 \quad \text{on } \partial\Omega. \end{array} \right. \quad (16)$$

The magnetic field is then given by $\mathbf{H}^\delta = \frac{i}{\omega\mu} \mathbf{curl} \mathbf{E}^\delta$ in Ω .

2.2. Variational space and forms

We now propose a variational space suitable for a regularized formulation, and *independent of δ* , *i.e.* suitable both for the Maxwell and eddy current problems. Let $\mathbf{H}_0(\mathbf{curl}, \Omega)$ be the standard space

$$\mathbf{H}_0(\mathbf{curl}, \Omega) = \{ \mathbf{u} \in L^2(\Omega)^3 : \mathbf{curl} \mathbf{u} \in L^2(\Omega)^3, \quad \mathbf{u} \times \mathbf{n} = 0 \text{ on } \partial\Omega \}.$$

Our variational space is $\mathbf{Y}(\Omega)$ defined as

$$\mathbf{Y}(\Omega) = \left\{ \mathbf{u} \in \mathbf{H}_0(\mathbf{curl}, \Omega) : \operatorname{div} \mathbf{u}_C \in L^2(\Omega_C), \operatorname{div} \mathbf{u}_E \in L^2(\Omega_E), \int_B \mathbf{u}_E \cdot \mathbf{n} = 0 \right\}$$

equipped with the norm

$$\|\mathbf{u}\|_{\mathbf{Y}(\Omega)}^2 = \|\mathbf{u}\|_{0,\Omega}^2 + \|\mathbf{curl} \mathbf{u}\|_{0,\Omega}^2 + \|\operatorname{div} \mathbf{u}_C\|_{0,\Omega_C}^2 + \|\operatorname{div} \mathbf{u}_E\|_{0,\Omega_E}^2.$$

The gradient fields belonging to $\mathbf{Y}(\Omega)$ are associated with potentials φ in the space

$$\left\{ \varphi \in L^2(\Omega) : \varphi_C \in H^1(\Omega_C), \varphi_E \in H^1(\Omega_E), \right. \\ \left. [\varphi] = c_1 \text{ on } B, \varphi = 0 \text{ on } \partial\Omega, \quad c_1 \in \mathbb{C}, \right. \\ \left. \Delta\varphi_C \in L^2(\Omega_C), \Delta\varphi_E \in L^2(\Omega_E), \int_B \partial_n \varphi_E \, dS = 0 \right\}. \quad (17)$$

For such potentials, the associated field in $\mathbf{Y}(\Omega)$ is the “broken” gradient field $\tilde{\nabla}\varphi \in L^2(\Omega)^3$ defined as

$$(\tilde{\nabla}\varphi)|_{\Omega_C} = \nabla\varphi_C \quad \text{and} \quad (\tilde{\nabla}\varphi)|_{\Omega_E} = \nabla\varphi_E.$$

The following result on potentials in the exterior part Ω_E will be used several times. Note that B and $\partial\Omega$ are the two components of the boundary $\partial\Omega_E$ of Ω_E .

Lemma 2.1. *For any $f \in L^2(\Omega_E)$, $v \in H^{1/2}(B)$ and $b \in \mathbb{C}$, there exists a unique solution $\varphi \in H^1(\Omega_E)$ of the following boundary value problem*

$$\begin{cases} \Delta\varphi = f \text{ in } \Omega_E, \\ \varphi = 0 \text{ on } \partial\Omega, \\ \int_B \partial_n \varphi \, dS = b. \end{cases} \quad \varphi = v + c \text{ on } B \text{ for some } c \in \mathbb{C}, \quad (18)$$

There is an estimate

$$\|\varphi\|_{1,\Omega_E} \leq C(\|f\|_{0,\Omega_E} + \|v\|_{H^{1/2}(B)/\mathbb{C}} + |b|). \quad (19)$$

Proof. Let φ_0 be the solution of the Dirichlet problem $\Delta\varphi_0 = f$ in Ω_E , $\varphi_0 = 0$ on $\partial\Omega$ and $\varphi_0 = v$ on B . Let q be the solution of the problem $\Delta q = 0$ in Ω_E , $q = 0$ on $\partial\Omega$, $q = \text{constant}$ on B and $\int_B \partial_n q = 1$ (compare with [4, Prop. 3.18]).

With $\ell = \int_B \partial_n \varphi_0$, the function $\varphi := \varphi_0 + (b - \ell)q$ is the solution of (18).

For the estimate (19), one notes that

$$\|\varphi_0\|_{1,\Omega_E} + |\ell| \leq C_1(\|f\|_{0,\Omega_E} + \|v\|_{1/2,B})$$

and hence

$$\begin{aligned} \|\varphi\|_{1,\Omega_E} &\leq \|\varphi_0\|_{1,\Omega_E} + (|\ell| + |b|)\|q\|_{1,\Omega_E} \\ &\leq C_2(\|f\|_{0,\Omega_E} + \|v\|_{1/2,B} + |b|) \end{aligned}$$

with $C_2 = \max\{C_1, C_1\|q\|_{1,\Omega_E}, \|q\|_{1,\Omega_E}\}$.

We can replace $\|v\|_{H^{1/2}(B)}$ by $\|v\|_{H^{1/2}(B)/\mathbb{C}}$ here because φ depends only on v modulo the constants. \square

Let us further define the following bilinear form on $\mathbf{Y}(\Omega)$: For $\mathbf{u}, \mathbf{v} \in \mathbf{Y}(\Omega)$:

$$a^\delta(\mathbf{u}, \mathbf{v}) = \int_\Omega (\mu^{-1} \mathbf{curl} \, \mathbf{u} \cdot \mathbf{curl} \, \bar{\mathbf{v}} - \delta\omega^2 \hat{\varepsilon} \mathbf{u} \cdot \bar{\mathbf{v}}) \, dx + i\omega \int_{\Omega_C} \sigma_C \mathbf{u} \cdot \bar{\mathbf{v}} \, dx$$

and its regularized version

$$a_R^\delta(\mathbf{u}, \mathbf{v}) = a^\delta(\mathbf{u}, \mathbf{v}) + \int_{\Omega_C} \operatorname{div} \mathbf{u}_C \operatorname{div} \bar{\mathbf{v}}_C \, dx + \int_{\Omega_E} \operatorname{div} \mathbf{u}_E \operatorname{div} \bar{\mathbf{v}}_E \, dx.$$

Lemma 2.2. *Let the positive constants μ_C , μ_E , $\hat{\varepsilon}_C$, $\hat{\varepsilon}_E$, σ_C and ω be fixed. Then there exists $\delta_0 > 0$ such that for all $\delta \in [0, \delta_0]$, a_R^δ is strongly coercive on $\mathbf{Y}(\Omega)$: $\exists \alpha \in \mathbb{C}$, $\exists c_0 > 0$, $\forall \delta \in [0, \delta_0]$, $\forall \mathbf{u} \in \mathbf{Y}(\Omega)$*

$$\operatorname{Re}(\alpha a_R^\delta(\mathbf{u}, \mathbf{u})) \geq c_0 \|\mathbf{u}\|_{\mathbf{Y}(\Omega)}^2. \quad (20)$$

Proof. Since $|a_R^\delta(\mathbf{u}, \mathbf{u}) - a_R^0(\mathbf{u}, \mathbf{u})| \leq C\delta \|\mathbf{u}\|_{0,\Omega}^2 \leq C\delta \|\mathbf{u}\|_{\mathbf{Y}(\Omega)}^2$, it is clearly enough to prove the coerciveness property for $\delta = 0$: We check that if the coerciveness estimate (16) holds for $\delta = 0$ with the constant c_0 , then it holds for any $\delta \in [0, \delta_0]$ with $\delta_0 = c_0/2C$ and with $c_0/2$ instead of c_0 .

Let us take $\alpha = e^{-i\pi/4}$. Then

$$\operatorname{Re}(\alpha a_R^0(\mathbf{u}, \mathbf{u})) \gtrsim \|\mathbf{curl} \, \mathbf{u}\|_{0,\Omega}^2 + \|\mathbf{u}\|_{0,\Omega_C}^2 + \|\operatorname{div} \mathbf{u}\|_{0,\Omega_C}^2 + \|\operatorname{div} \mathbf{u}\|_{0,\Omega_E}^2.$$

It remains to prove that the right hand side above is an upper bound for $\|\mathbf{u}\|_{0,\Omega_E}^2$.

Let $\mathbf{w} \in H^1(\Omega)^3$ be such that $\mathbf{curl} \mathbf{w} = \mathbf{curl} \mathbf{u}$ in Ω and $\mathbf{w} \times \mathbf{n} = 0$ on $\partial\Omega$. This exists according to [4, Lem. 3.5] and can be chosen such that $\text{div} \mathbf{w} = 0$ in Ω , with the estimate

$$\|\mathbf{w}\|_{1,\Omega} \lesssim \|\mathbf{curl} \mathbf{u}\|_{0,\Omega}.$$

Since Ω is simply connected, there is $\varphi \in H_0^1(\Omega)$ such that

$$\mathbf{u} = \mathbf{w} + \nabla\varphi \quad \text{in } \Omega.$$

On Ω_E , φ satisfies

$$\begin{cases} \Delta\varphi = \text{div} \mathbf{u} & \text{in } \Omega_E, \\ \varphi = 0 & \text{on } \partial\Omega, \\ \int_B \partial_n \varphi \, dS = \int_B \mathbf{w} \cdot \mathbf{n} \, dS. \end{cases}$$

According to Lemma 2.1, we have an estimate

$$\|\varphi\|_{1,\Omega_E} \leq C \left(\|\text{div} \mathbf{u}\|_{0,\Omega_E} + \|\varphi|_B\|_{H^{1/2}(B)/\mathbb{C}} + \left| \int_B \mathbf{w} \cdot \mathbf{n} \, dS \right| \right).$$

Because of

$$\|\mathbf{u}\|_{0,\Omega_E} \leq \|\mathbf{w}\|_{0,\Omega_E} + \|\nabla\varphi\|_{0,\Omega_E} \lesssim \|\mathbf{curl} \mathbf{u}\|_{0,\Omega_E} + \|\varphi\|_{1,\Omega_E},$$

it remains to bound $\|\varphi|_B\|_{H^{1/2}(B)/\mathbb{C}}$ and $|\int_B \mathbf{w} \cdot \mathbf{n} \, dS|$.

The latter clearly satisfies $|\int_B \mathbf{w} \cdot \mathbf{n} \, dS| \lesssim \|\mathbf{w}\|_{1,\Omega} \lesssim \|\mathbf{curl} \mathbf{u}\|_{0,\Omega}$.

Finally (see [20] for the trace estimates)

$$\begin{aligned} \|\varphi|_B\|_{H^{1/2}(B)/\mathbb{C}} &\leq \|\mathbf{n} \times \nabla\varphi\|_{-1/2,B} \leq \|\mathbf{n} \times \mathbf{u}\|_{-1/2,B} + \|\mathbf{n} \times \mathbf{w}\|_{-1/2,B} \\ &\lesssim \|\mathbf{u}\|_{\mathbf{H}(\mathbf{curl}, \Omega_C)} + \|\mathbf{w}\|_{1,\Omega} \\ &\lesssim \|\mathbf{u}\|_{0,\Omega_C} + \|\mathbf{curl} \mathbf{u}\|_{0,\Omega_C} + \|\mathbf{curl} \mathbf{u}\|_{0,\Omega}. \end{aligned} \quad \square$$

2.3. Variational problems

For all $\delta \in [0, \delta_0]$, we consider the variational problem:

$$\text{Find } \mathbf{E} \in \mathbf{Y}(\Omega) \text{ s. t. } a_R^\delta(\mathbf{E}, \mathbf{v}) = -i\omega(\mathbf{j}_0, \mathbf{v})_{\Omega_C}, \quad \forall \mathbf{v} \in \mathbf{Y}(\Omega), \tag{21}$$

where $(\cdot, \cdot)_D$ is the $L^2(D)^3$ hermitian inner product.

Theorem 2.3. *Let \mathbf{j}_0 satisfy*

$$\mathbf{j}_0 \in L^2(\Omega), \quad \mathbf{j}_0 = 0 \text{ in } \Omega_E, \quad \text{div} \mathbf{j}_0 = 0 \text{ in } \Omega_C, \quad \mathbf{j}_0 \cdot \mathbf{n} = 0 \text{ on } B. \tag{22}$$

Let the positive constants $\mu_C, \mu_E, \hat{\varepsilon}_C, \hat{\varepsilon}_E, \sigma_C$ and ω be fixed. With δ_0 given in Lemma 2.2, for all $\delta \in [0, \delta_0]$:

- (i) *there exists a unique solution \mathbf{E}^δ to problem (21);*
- (ii) *the solution \mathbf{E}^δ satisfies all equations in (16);*
- (iii) *the norms of the \mathbf{E}^δ in $\mathbf{Y}(\Omega)$ are uniformly bounded:*

$$\exists C > 0, \quad \forall \delta \in [0, \delta_0], \quad \|\mathbf{E}^\delta\|_{\mathbf{Y}(\Omega)} \leq C;$$

- (iv) *as $\delta \rightarrow 0$, $\mathbf{E}^\delta \rightarrow \mathbf{E}^0$ and we have the convergence estimate*

$$\exists C > 0, \quad \forall \delta \in [0, \delta_0], \quad \|\mathbf{E}^\delta - \mathbf{E}^0\|_{\mathbf{Y}(\Omega)} \leq C\delta.$$

Proof. (i) is a mere consequence of Lemma 2.2.

(ii) We first take as test functions $\mathbf{v} = \nabla\varphi$, with $\varphi_C \in H_0^1(\Omega_C, \Delta)$ ^(†) extended by zero outside Ω_C . This yields

$$\int_{\Omega_C} ((i\omega\sigma - \delta\omega^2\hat{\varepsilon})\mathbf{E} \cdot \nabla\varphi + \operatorname{div} \mathbf{E} \operatorname{div} \nabla\varphi) dx = -i\omega \int_{\Omega_C} \mathbf{j}_0 \cdot \nabla\varphi dx.$$

By Green's formula and the properties of \mathbf{j}_0 , we obtain

$$\int_{\Omega_C} \operatorname{div} \mathbf{E}((-i\omega\sigma + \delta\omega^2\hat{\varepsilon})\varphi + \Delta\varphi) dx = 0, \quad \forall \varphi \in H_0^1(\Omega_C, \Delta).$$

This yields (16) (ii) since $(-i\omega\sigma + \delta\omega^2\hat{\varepsilon})\varphi + \Delta\varphi$ runs through the whole $L^2(\Omega_C)$ for $\varphi \in H_0^1(\Omega_C, \Delta)$.

A similar argument in Ω_E yields (16) (iv) since, as a consequence of Lemma 2.1, for δ small enough, the operator $\varphi \mapsto \delta\omega^2\hat{\varepsilon}\varphi + \Delta\varphi$ is surjective from

$$\left\{ \varphi \in H^1(\Omega_E) : \varphi|_B = c, \varphi|_{\partial\Omega} = 0, \int_B \partial_n \varphi dS = 0, \Delta\varphi \in L^2(\Omega_E) \right\}$$

onto $L^2(\Omega_E)$.

Next for any $\chi \in H^{1/2}(B)$, we take $\mathbf{v} = \nabla\varphi$ with φ in the space (17) such that φ_E is solution of the Dirichlet problem $\Delta\varphi_E = 0$ in Ω_E and $\varphi_E = \chi + c$ on B (we use once more Lem. 2.1). Using this test function in (21), we get

$$\int_{\Omega_C} (i\delta\omega\hat{\varepsilon} \mathbf{E} + \sigma \mathbf{E}) \cdot \nabla\varphi dx + \int_{\Omega_E} i\delta\omega\hat{\varepsilon} \mathbf{E} \cdot \nabla\varphi dx = - \int_{\Omega_C} \mathbf{j}_0 \cdot \nabla\varphi dx.$$

Hence

$$\int_B (i\delta\omega[\hat{\varepsilon}\mathbf{E}] + \sigma \mathbf{E}) \cdot \mathbf{n} \chi dS - c \int_B i\delta\omega\hat{\varepsilon}_E \mathbf{E}_E \cdot \mathbf{n} dS = 0.$$

Since $\int_B \mathbf{E}_E \cdot \mathbf{n} = 0$, we conclude that we have (16) (vii).

The other equations of (16) are then obtained in a standard way.

(iii) is a consequence of the uniform coerciveness proved in Lemma 2.2.

(iv) We have for all $\mathbf{v} \in \mathbf{Y}(\Omega)$:

$$a_R^0(\mathbf{E}^\delta - \mathbf{E}^0, \mathbf{v}) = a_R^0(\mathbf{E}^\delta, \mathbf{v}) - a^\delta(\mathbf{E}^\delta, \mathbf{v}) = \delta \int_{\Omega} \omega^2 \hat{\varepsilon} \mathbf{E}^\delta \cdot \bar{\mathbf{v}} dx.$$

Taking $\mathbf{v} = \mathbf{E}^\delta - \mathbf{E}^0$ and using the uniform coerciveness estimate, we obtain

$$\|\mathbf{E}^\delta - \mathbf{E}^0\|_{\mathbf{Y}(\Omega)}^2 \leq C\delta \|\mathbf{E}^\delta\|_{L^2(\Omega)} \|\mathbf{E}^\delta - \mathbf{E}^0\|_{L^2(\Omega)}.$$

With the help of the continuous imbeddings $\mathbf{Y}(\Omega) \subset L^2(\Omega)^3 \subset \mathbf{Y}'(\Omega)$ we conclude, thanks to (iii). \square

Remark 2.1. All results above extend to the case when B is not simply connected. Let B_i for $i = 1, \dots, I$ be the connected components of B . Let us prove that

$$(\mathbf{E}, \mathbf{H}) \text{ solution of (1)-(2)} \implies \int_{B_i} \mathbf{E}_E \cdot \mathbf{n} dS = 0, \quad i = 1, \dots, I. \quad (23)$$

^(†)Here $H_0^1(\Omega_C, \Delta)$ is the subspace of the $\varphi \in H_0^1(\Omega_C)$ such that $\Delta\varphi_C \in L^2(\Omega_C)$.

The equation $\operatorname{div} \mathbf{E}_C = 0$ is not sufficient now to deduce (23). By [4, Lem. 3.5] we know that there exists a vector potential $\mathbf{J}_0 \in H^1(\mathbf{curl}, \Omega_C)$ for \mathbf{j}_0 : $\mathbf{j}_0 = \mathbf{curl} \mathbf{J}_0$ in Ω_C . Therefore equation (2) yields that

$$\mathbf{E} = \mathbf{curl} \psi \quad \text{with} \quad \psi = (i\omega\varepsilon_C + \sigma_C)^{-1}(\mathbf{H} - \mathbf{J}_0).$$

The proof goes as in [4, Lem. 3.5]: Let $\mu_i \in C_0^\infty(\mathbb{R}^3)$ such that $\mu_i \equiv 1$ in a neighborhood of B_i and $\mu_i \equiv 0$ in a neighborhood of the other connected components of B . Then

$$\int_{B_i} \mathbf{E}_C \cdot \mathbf{n} \, dS = \int_{\Omega_C} \operatorname{div}\{\mathbf{curl}(\mu_i \psi)\} \, dx = 0.$$

Then we deduce that $\int_{B_i} \mathbf{E}_E \cdot \mathbf{n} \, dS = 0$ as before. The gauge conditions for the eddy current problem are now $\operatorname{div} \mathbf{E}_E = 0$ in Ω_E and

$$\int_{B_i} \mathbf{E}_E \cdot \mathbf{n} \, dS = 0, \quad i = 1, \dots, I. \quad (24)$$

In the definition of the space $\mathbf{Y}(\Omega)$ the gauge conditions (24) are now present.

The modification of Lemma 2.1 is obvious: The boundary conditions on B_i are $\varphi = v + c_i$ and $\int_{B_i} \partial_n \varphi \, dS = b_i$ with b_i given constants. The estimate (19) contains the term $\sum_i |b_i|$ instead of $|b|$. The proof relies on the full [4, Prop. 3.18]. Lemma 2.2 and Theorem 2.3 are still valid under these assumptions. The extension of the proofs is straightforward.

3. SINGULARITIES OF THE VARIATIONAL SPACES

In this section, we investigate the splitting of the variational solutions of (21) into the sum of a regular field $\mathbf{w} \in H^1(\Omega)^3$ and of a singular gradient $\nabla \Phi$, where Φ is not, in general, in $H^2(\Omega)$.

3.1. General situation

The space $\mathbf{Y}(\Omega)$ contains some of the essential boundary conditions appearing in (16), namely, (16) (vi) and (viii). But the essential condition (16) (vii) depends on δ . On the other hand we do not impose the gauge condition $\int_B \mathbf{E}_E \cdot \mathbf{n} \, dS = 0$ for this analysis. Let us then set

$$\mathbf{X}(\Omega) = \{\mathbf{u} \in \mathbf{H}_0(\mathbf{curl}, \Omega) : \operatorname{div} \mathbf{u}_C \in L^2(\Omega_C), \operatorname{div} \mathbf{u}_E \in L^2(\Omega_E)\}$$

and for $\delta \geq 0$:

$$\mathbf{X}^\delta(\Omega) = \{\mathbf{u} \in \mathbf{X}(\Omega) : i\delta\omega[\hat{\varepsilon} \mathbf{u} \cdot \mathbf{n}] + \sigma_C \mathbf{u}_C \cdot \mathbf{n} = 0 \text{ on } B\}.$$

In fact, the solution of (21) belongs to $\mathbf{X}^\delta(\Omega)$. Note that the variational formulation could equivalently be set in $\mathbf{X}^\delta \cap \mathbf{Y}(\Omega)$, but, in order to prove the convergence result as $\delta \rightarrow 0$ we preferred to use a space independent of δ .

Let us recall more classical notations [15]: For a domain D

$$\mathbf{X}_N(D) = \{\mathbf{u} \in \mathbf{H}_0(\mathbf{curl}, D) : \operatorname{div} \mathbf{u} \in L^2(D)\},$$

and

$$\mathbf{X}_T(D) = \{\mathbf{u} \in \mathbf{H}(\mathbf{curl}, D) : \operatorname{div} \mathbf{u} \in L^2(D), \mathbf{u} \cdot \mathbf{n} = 0 \text{ on } \partial D\}.$$

By a straightforward adaptation of the result [17, Th. 3.5] to the situation of complex coefficients, we obtain the splitting result for the spaces $\mathbf{X}^\delta(\Omega)$ when $\delta > 0$. In order to state it, we need the introduction of the interface Laplacian $\Delta_{\underline{\delta}}$ over $H_0^1(\Omega)$:

$$(\Delta_{\underline{\delta}} \varphi, \psi)_\Omega = \int_{\Omega_C} (\sigma_C + i\delta\omega\hat{\varepsilon}_C) \nabla \varphi_C \cdot \nabla \bar{\psi}_C + \int_{\Omega_E} (i\delta\omega\hat{\varepsilon}_E) \nabla \varphi_E \cdot \nabla \bar{\psi}_E, \quad (25)$$

for any $\varphi, \psi \in H_0^1(\Omega)$. Then for $\delta > 0$, under a technical condition ^(†), any field $\mathbf{v} \in \mathbf{X}^\delta(\Omega)$ admits a decomposition

$$\mathbf{v} = \mathbf{w} + \nabla\Phi, \quad (26)$$

where $\mathbf{w} \in \mathbf{X}^\delta(\Omega)$ is such that $\mathbf{w}_C \in H^1(\Omega_C)^3$, $\mathbf{w}_E \in H^1(\Omega_E)^3$ and $\Phi \in H_0^1(\Omega)$ satisfies $\Delta_{\underline{\delta}}\Phi \in L^2(\Omega)$.

3.2. The eddy current case

The goal of this subsection is to describe the decomposition of vector fields from the eddy current variational space $\mathbf{X}^0(\Omega)$ into regular fields and singular ones in the spirit of [5, 7–9, 15, 17] (and even using some results from these papers).

Theorem 3.1. *Any field $\mathbf{v} \in \mathbf{X}^0(\Omega)$ admits a decomposition*

$$\mathbf{v} = \mathbf{w} + \nabla\Phi, \quad (27)$$

with $\mathbf{w} \in \mathbf{X}^0(\Omega)$ such that $\mathbf{w}_C \in H^1(\Omega_C)^3$, $\mathbf{w}_E \in H^1(\Omega_E)^3$ and the potential $\Phi \in H^1(\Omega)$ satisfies

$$\Delta\Phi_C \in L^2(\Omega_C), \quad (28)$$

$$\partial_n\Phi_C = 0 \quad \text{on } B, \quad (29)$$

$$\Delta\Phi_E \in L^2(\Omega_E), \quad (30)$$

$$\Phi_E = 0 \quad \text{on } \partial\Omega. \quad (31)$$

Proof. We remark that the restriction \mathbf{v}_C of \mathbf{v} to Ω_C belongs to $\mathbf{X}_T(\Omega_C)$. Therefore by Theorem 1.1 of [15] (see also [7, 8] or Th. 3.5 of [17]), \mathbf{v}_C admits a decomposition

$$\mathbf{v}_C = \mathbf{w}_C + \nabla\Phi_C \quad \text{in } \Omega_C, \quad (32)$$

where $\mathbf{w}_C \in H^1(\Omega_C)^3 \cap \mathbf{X}_T(\Omega_C)$ and $\Phi_C \in H^1(\Omega_C)$ satisfies (28)–(29).

Now consider $\chi \in H^1(\Omega_E)$ the unique weak solution of

$$\begin{aligned} \Delta\chi &= 0 && \text{in } \Omega_E, \\ \chi &= \Phi_C && \text{on } B. \end{aligned}$$

Denote by $\tilde{\Phi}_C$ the function defined by

$$\tilde{\Phi}_C = \begin{cases} \Phi_C & \text{in } \Omega_C, \\ \chi & \text{in } \Omega_E. \end{cases}$$

By construction $\tilde{\Phi}_C$ belongs to $H^1(\Omega)$. Denote furthermore by $\tilde{\mathbf{w}}_C$ an extension of \mathbf{w}_C to Ω which belongs to $H^1(\Omega)^3$ and is zero on $\partial\Omega$. Let us now set

$$\tilde{\mathbf{v}}_C = \tilde{\mathbf{w}}_C + \nabla\tilde{\Phi}_C. \quad (33)$$

Then by construction this is equal to \mathbf{v}_C in Ω_C and it satisfies

$$[\tilde{\mathbf{v}}_C \times \mathbf{n}] = 0 \quad \text{on } B.$$

These properties imply that \mathbf{u}_E defined in Ω_E by

$$\mathbf{u}_E = \mathbf{v}_E - \tilde{\mathbf{v}}_C|_{\Omega_E} \quad (34)$$

^(†)The interface Laplacian $\Delta_{\underline{\delta}}$ has no edge exponent equal to 1 and no corner exponent equal to $\frac{1}{2}$. This condition is probably not necessary.

satisfies

$$\begin{aligned} \mathbf{u}_E \times \mathbf{n} &= 0 \quad \text{on } B, \\ \mathbf{curl} \mathbf{u}_E &= \mathbf{curl} \mathbf{v}_E - \mathbf{curl} \tilde{\mathbf{w}}_C|_{\Omega_E} \in L^2(\Omega_E)^3, \\ \operatorname{div} \mathbf{u}_E &= \operatorname{div} \mathbf{v}_E - \operatorname{div} \tilde{\mathbf{w}}_C|_{\Omega_E} - \operatorname{div}(\nabla\chi) \in L^2(\Omega_E). \end{aligned}$$

This means that \mathbf{u}_E belongs to $\mathbf{X}_N(\Omega_E)$. Again by Theorem 1.1 of [15] (see also [7, 8] or Th. 3.5 of [17]) \mathbf{u}_E admits a decomposition

$$\mathbf{u}_E = \mathbf{w}_{RE} + \nabla\varphi_E \quad \text{in } \Omega_E, \quad (35)$$

where $\mathbf{w}_{RE} \in H^1(\Omega_E)^3 \cap \mathbf{X}_N(\Omega_E)$ and φ_E belongs to $H^1(\Omega_E)$ and satisfies (30) and the Dirichlet boundary condition

$$\varphi_E = 0 \quad \text{on } B \cup \partial\Omega.$$

This decomposition (35) into the splitting (34) gives with the help of (33)

$$\mathbf{v}_E = \mathbf{w}_{RE} + \nabla\varphi_E + \tilde{\mathbf{w}}_C|_{\Omega_E} + \nabla\chi \quad \text{in } \Omega_E,$$

or equivalently

$$\mathbf{v}_E = \mathbf{w}_E + \nabla\Phi_E \quad \text{in } \Omega_E, \quad (36)$$

once we set $\mathbf{w}_E = \mathbf{w}_{RE} + \tilde{\mathbf{w}}_C|_{\Omega_E}$ and $\Phi_E = \varphi_E + \chi$. The conclusion follows from (32), (36) and the above properties of \mathbf{w}_{RE} , $\tilde{\mathbf{w}}_C$, φ_E and χ . \square

The relation between the general decomposition (26) and Theorem 3.1 in the limit when $\delta \rightarrow 0$ is not straightforward and will be clarified later.

4. LAPLACE SINGULARITIES FOR THE POTENTIALS

The singularities of the Maxwell and eddy current problems are produced by the corners \mathbf{a} and the edges \mathbf{e} of Ω_C . – Note that the corners and edges are all part of the interface B . Concerning the Maxwell interface problems (corresponding to $\delta > 0$), these singularities are known [17] to derive from those of scalar problems for potentials, namely $\Delta_{\underline{\delta}}$ and Δ_{μ} , where $\Delta_{\underline{\delta}}$ is defined in (25) and the latter operator is defined as:

$$(\Delta_{\mu}\varphi, \psi)_{\Omega} = \int_{\Omega_C} \mu_C \nabla\varphi_C \cdot \nabla\bar{\psi}_C + \int_{\Omega_E} \mu_E \nabla\varphi_E \cdot \nabla\bar{\psi}_E,$$

for any $\varphi, \psi \in H^1(\Omega)$.

We will now recall the singularities of these two interface Laplacians $\Delta_{\underline{\delta}}$ (electric) and Δ_{μ} (magnetic). For the sake of brevity we restrict ourselves to a minimal description and refer to [15, 17, 24, 26–28] for more details. Moreover, we describe the singularities of the coupled Neumann-Dirichlet problem (28)–(31) of the eddy current problem. We show that their exponents (*i.e.* degrees of homogeneity) are the limit of the interface singularity exponents of $\Delta_{\underline{\delta}}$ as $\delta \rightarrow 0$. We give complements on the behavior of all singularities (scalar and Maxwell) in the eddy current limit as $\delta \rightarrow 0$ in Section 7.

4.1. General definitions for Laplace singularities in cones and sectors

As we know from [23], the singularities (singular parts of solutions) of elliptic problems at a corner 0 are obtained as non-zero quasi-homogeneous solutions of the same problem with zero right hand side in the infinite cone (or sector) which coincides with the finite domain at this corner 0.

Let Γ be an infinite cone in \mathbb{R}^d for $d = 3$ or 2 (Γ is then a sector), centered in 0 . Let (ρ, ϑ) be the polar coordinates centered at 0 . Let G be the intersection of Γ with the unit sphere. The singularities in Γ are quasi-homogeneous functions: Let us set for $\lambda \in \mathbb{C}$:

$$S^\lambda(\Gamma) = \left\{ \Psi(x) = \rho^\lambda \sum_{q=0}^Q (\log \rho)^q \psi_q(\vartheta) : \psi_q \in H^1(G) \right\}.$$

The singularities of an elliptic problem are the non-zero solutions in some $S^\lambda(\Gamma)$ of the same problem with zero right hand side. The corresponding λ are the *exponents of singularities*.

The *set of exponents* can be found by searching solutions in the subspace of *homogeneous functions*, $\overline{S}^\lambda(\Gamma) := \{\Psi(x) = \rho^\lambda \psi(\vartheta) : \psi \in H^1(G)\}$.

4.1.1. Dirichlet problem.

We denote the set of exponents of the Dirichlet problem for Δ on Γ by $\Lambda^{\text{Dir}}(\Gamma)$, *i.e.* the λ for which there exists a non-zero $\Psi \in \overline{S}^\lambda(\Gamma)$, solution of the problem

$$\Delta \Psi = 0 \text{ in } \Gamma \quad \text{and} \quad \Psi = 0 \text{ on } \partial\Gamma. \quad (37)$$

For λ in this set, let $Z_{\text{Dir}}^\lambda(\Gamma)$ be the corresponding space of singularities.

Let L be the positive Laplace-Beltrami operator on the unit sphere ($L = -\partial_\vartheta^2$ if $d = 2$). For $\Psi(x) = \rho^\lambda \psi(\vartheta)$, we have $-\Delta \Psi = \rho^{\lambda-2}(L\psi - \nu\psi)$ where

$$\nu = \lambda^2 \text{ if } d = 2 \quad \text{and} \quad \nu = \lambda(\lambda + 1) \text{ if } d = 3. \quad (38)$$

Thus it is standard to prove that $\Lambda^{\text{Dir}}(\Gamma)$ is the set λ such that ν in (38) is an eigenvalue of the Dirichlet problem for L on G . Moreover $Z_{\text{Dir}}^\lambda(\Gamma)$ is the space of $\rho^\lambda \psi(\vartheta)$ with ψ an eigenvector associated with the eigenvalue ν in (38).

4.1.2. Neumann problem.

The set $\Lambda^{\text{Neu}}(\Gamma)$ of Neumann exponents is similarly defined as the λ for which there exists a non-zero $\Psi \in \overline{S}^\lambda(\Gamma)$, solution of

$$\Delta \Psi = 0 \text{ in } \Gamma \quad \text{and} \quad \partial_n \Psi = 0 \text{ on } \partial\Gamma. \quad (39)$$

The space $Z_{\text{Neu}}^\lambda(\Gamma)$ is defined analogously and the Neumann eigenpairs of L on G yield the singularities as above.

4.1.3. Interface problems.

The interface problems that we consider in most of this paper are of simple type. They correspond to the separation of the whole space $\Gamma = \mathbb{R}^2$ or \mathbb{R}^3 into two conical regions Γ_C and Γ_E , *i.e.* $\Gamma = \overline{\Gamma}_C \cup \overline{\Gamma}_E$ and $\Gamma_C \cap \Gamma_E = \emptyset$. We note that

$$S^\lambda(\Gamma) = \{ \Psi : \Psi_C \in S^\lambda(\Gamma_C), \quad \Psi_E \in S^\lambda(\Gamma_E), \quad \Psi_C = \Psi_E \text{ on } I := \partial\Gamma_C = \partial\Gamma_E \}.$$

Let α be a piecewise constant function, equal to $\alpha_C \in \mathbb{C}$ in Γ_C and to $\alpha_E \in \mathbb{C}$ in Γ_E . The set of exponents of the interface problem associated with the operator

$$(\Phi, \Psi) \longmapsto \int_{\Gamma_C} \alpha_C \nabla \Phi_C \cdot \nabla \overline{\Psi}_C + \int_{\Gamma_E} \alpha_E \nabla \Phi_E \cdot \nabla \overline{\Psi}_E, \quad (40)$$

is the set $\Lambda_\alpha(\Gamma)$ of the λ for which there exists a non-zero $\Psi \in \overline{S}^\lambda(\Gamma)$, solution of (see, *e.g.*, [19,24,25,29])

$$\begin{cases} (i) & \Delta \Psi_C = 0 & \text{in } \Gamma_C, \\ (ii) & \Delta \Psi_E = 0 & \text{in } \Gamma_E, \\ (iii) & \alpha_C \partial_{n_C} \Psi_C + \alpha_E \partial_{n_E} \Psi_E = 0 & \text{on } I. \end{cases} \quad (41)$$

For λ in this set, let $Z^\lambda(\Gamma; \alpha)$ be the corresponding space of singularities. Then the $\lambda \in \Lambda_\alpha(\Gamma)$ are such that ν in (38) are the eigenvalues of the problem

$$\psi \in H^1(\mathbb{S}^{d-1}), \quad \forall \varphi \in H^1(\mathbb{S}^{d-1}), \quad \int_{\mathbb{S}^{d-1}} \alpha \nabla \psi \cdot \nabla \varphi = \nu \int_{\mathbb{S}^{d-1}} \alpha \psi \varphi. \quad (42)$$

When $\alpha > 0$, the space $Z^\lambda(\Gamma; \alpha)$ contains only homogeneous functions of the form $\rho^\lambda \psi(\vartheta)$ with ψ solution of (42).

4.2. The eddy current limit for potentials

For $\delta > 0$, the singularities of the electric transmission Laplacian Δ_δ are the non-zero $\Psi \in \overline{S}^\lambda(\Gamma)$ solution of the problem (41) with $\alpha = \alpha^\delta$ where

$$\alpha_C^\delta = \sigma_C + i\delta\omega\hat{\varepsilon}_C \quad \text{and} \quad \alpha_E^\delta = i\delta\omega\hat{\varepsilon}_E. \quad (43)$$

Going back to problem (28)–(31) for the eddy current potentials, we see that its singularities are the solutions $\Psi \in \overline{S}^\lambda(\Gamma)$ of the problem (41) with $\alpha = \alpha^0$, where $\alpha_C^0 = \sigma_C$ and $\alpha_E^0 = 0$. Inserting $\Psi(x) = \rho^\lambda \psi(\vartheta)$ in (41) with $\alpha = \alpha^0$ we obtain the eigenvalue problem:

$$\begin{cases} (i) & L\psi_C = \nu\psi_C & \text{in } G_C, \\ (ii) & L\psi_E = \nu\psi_E & \text{in } G_E, \\ (iii) & \partial_{n_C}\psi_C = 0 & \text{on } J := \partial G_C = \partial G_E. \end{cases} \quad (44)$$

We are going to exhibit a common variational formulation for problems (42) and (44), and deduce that the spectrum of (42) for $\alpha = \alpha^\delta$ tends to the spectrum of (44) as $\delta \rightarrow 0$.

Let us divide equation (42) for $\alpha = \alpha^\delta$ by $\sigma_C + i\delta\omega\hat{\varepsilon}_C$ and let us set

$$\eta = \frac{i\delta\omega\hat{\varepsilon}_E}{\sigma_C + i\delta\omega\hat{\varepsilon}_C}. \quad (45)$$

Then the eigenvalue problem (42) with $\alpha = \alpha^\delta$ becomes

Find $\psi \in H^1(\mathbb{S}^{d-1})$, $\psi \neq 0$, $\forall \varphi \in H^1(\mathbb{S}^{d-1})$:

$$\int_{G_C} \nabla \psi_C \cdot \nabla \varphi_C + \eta \int_{G_E} \nabla \psi_E \cdot \nabla \varphi_E = \nu \left\{ \int_{G_C} \psi_C \varphi_C + \eta \int_{G_E} \psi_E \varphi_E \right\}. \quad (46)$$

Let us denote by P_E the harmonic extension from G_C into G_E : For ψ_C in $H^1(G_C)$, $P_E\psi_C$ is the solution of $L\varphi = 0$ in G_E and $\varphi = \psi_C$ on $\partial G_E = \partial G_C$. Consequently there holds

$$\forall \varphi_0 \in H_0^1(G_E), \quad \int_{G_E} \nabla(P_E\psi_C) \cdot \nabla \varphi_0 = 0. \quad (47)$$

For any $\psi \in H^1(\mathbb{S}^{d-1})$, we have

$$\psi_E = P_E\psi_C + \psi_0, \quad \text{where } \psi_0 \in H_0^1(G_E).$$

We write similarly $\varphi_E = P_E\varphi_C + \varphi_0$, with $\varphi_0 \in H_0^1(G_E)$. Inserting this in (46) and using (47), we obtain $\forall \varphi_C \in H^1(G_C)$ and $\forall \varphi_0 \in H_0^1(G_E)$:

$$\int_{G_C} \nabla \psi_C \cdot \nabla \varphi_C + \eta \int_{G_E} (\nabla P_E \psi_C \cdot \nabla P_E \varphi_C + \nabla \psi_0 \cdot \nabla \varphi_0) = \nu \left\{ \int_{G_C} \psi_C \varphi_C + \eta \int_{G_E} (P_E \psi_C P_E \varphi_C + P_E \psi_C \varphi_0 + \psi_0 P_E \varphi_C + \psi_0 \varphi_0) \right\},$$

i.e.

$$\forall \varphi_C \in H^1(G_C), \int_{G_C} \nabla \psi_C \cdot \nabla \varphi_C + \eta \int_{G_E} \nabla P_E \psi_C \cdot \nabla P_E \varphi_C = \nu \left\{ \int_{G_C} \psi_C \varphi_C + \eta \int_{G_E} (P_E \psi_C P_E \varphi_C + \psi_0 P_E \varphi_C) \right\} \tag{48}$$

and

$$\forall \varphi_0 \in H_0^1(G_E), \int_{G_E} \nabla \psi_0 \cdot \nabla \varphi_0 = \nu \int_{G_E} (P_E \psi_C \varphi_0 + \psi_0 \varphi_0). \tag{49}$$

For $\eta = 0$, equation (48) becomes

$$\forall \varphi_C \in H^1(G_C), \int_{G_C} \nabla \psi_C \cdot \nabla \varphi_C = \nu \int_{G_C} \psi_C \varphi_C. \tag{50}$$

The solutions of the system (49)–(50) are the solutions of system (44). Thus we have written the eigenproblems (42) for $\alpha = \alpha^\delta$ and (44) using the unified variational formulation (48)–(49), which has the form *Find* $(\psi_C, \psi_0) \in H^1(G_C) \times H_0^1(G_E)$, $\forall (\varphi_C, \varphi_0) \in H^1(G_C) \times H_0^1(G_E)$:

$$a_\eta(\psi_C, \psi_0; \varphi_C, \varphi_0) = \nu b_\eta(\psi_C, \psi_0; \varphi_C, \varphi_0)$$

where a_η and b_η depend continuously on $\eta \in [0, \eta_0]$.

As a consequence of the analysis above, we have proved the following:

Proposition 4.1.

- (i) For $\eta = 0$, the set of eigenvalues ν of the system (49)–(50) is the union of the set of Neumann eigenvalues in G_C and the set of Dirichlet eigenvalues in G_E .
- (ii) When $\eta \rightarrow 0$, the eigenvalues of the system (48)–(49) tend to the eigenvalues of the system (49)–(50).

4.3. Corner singularities

Now, we go back to the specific description of the singularities of the interface Laplacians Δ_δ (and problem (28)–(31) for $\delta = 0$) and Δ_μ at the corners of Ω_C . Note that the external Dirichlet or Neumann boundary conditions hold on the external smooth boundary $\partial\Omega$ and do not influence the interface singularities.

Fix a corner $\mathbf{a} \in B$. There exist infinite polyhedral cones $\Gamma_{C,\mathbf{a}}$ and $\Gamma_{E,\mathbf{a}}$ with vertex \mathbf{a} and such that for $\rho_0 > 0$ small enough

$$\Omega_C \cap \mathcal{B}(\mathbf{a}, \rho_0) = \Gamma_{C,\mathbf{a}} \cap \mathcal{B}(\mathbf{a}, \rho_0) \quad \text{and} \quad \Omega_E \cap \mathcal{B}(\mathbf{a}, \rho_0) = \Gamma_{E,\mathbf{a}} \cap \mathcal{B}(\mathbf{a}, \rho_0).$$

Note that $\overline{\Gamma_{C,\mathbf{a}}} \cup \overline{\Gamma_{E,\mathbf{a}}}$ is the full space $\Gamma = \mathbb{R}^3$. We refer to this conical partition of \mathbb{R}^3 associated with \mathbf{a} by the notation $\Gamma_{\mathbf{a}}$.

Then we denote by $\Lambda_\delta(\Gamma_{\mathbf{a}})$ the set of the exponents determined by problem (41) with $\alpha = \alpha^\delta$, see (43), for $\delta \geq 0$, and with $\Gamma_C = \Gamma_{C,\mathbf{a}}$ and $\Gamma_E = \Gamma_{E,\mathbf{a}}$. We denote similarly the spaces of singularities by $Z^\lambda(\Gamma_{\mathbf{a}}, \underline{\delta})$. As a consequence of Proposition 4.1, we obtain

Lemma 4.2. *For $\delta = 0$, the set of singular exponents satisfies*

$$\Lambda_{\underline{0}}(\Gamma_{\mathbf{a}}) = \Lambda^{\text{Neu}}(\Gamma_{C, \mathbf{a}}) \cup \Lambda^{\text{Dir}}(\Gamma_{E, \mathbf{a}}).$$

When $\delta \rightarrow 0$, the set $\Lambda_{\underline{\delta}}(\Gamma_{\mathbf{a}})$ tends to $\Lambda_{\underline{0}}(\Gamma_{\mathbf{a}})$.

The exponents and singular spaces associated with Δ_{μ} are denoted by $\Lambda_{\mu}(\Gamma_{\mathbf{a}})$ and $Z^{\lambda}(\Gamma_{\mathbf{a}}, \mu)$, according to Section 4.2 (iii).

4.4. Edge singularities

Let $\mathbf{e} \subset B$ be an edge of $\partial\Omega_C$. There exist two plane sectors $\Gamma_{C, \mathbf{e}}$ and $\Gamma_{E, \mathbf{e}}$ such that for any point $x \in \mathbf{e}$ there exists a neighborhood \mathcal{B} of x and a Cartesian system of coordinates such that

$$\Omega_C \cap \mathcal{B} = (\Gamma_{C, \mathbf{e}} \times \mathbb{R}) \cap \mathcal{B} \quad \text{and} \quad \Omega_E \cap \mathcal{B} = (\Gamma_{E, \mathbf{e}} \times \mathbb{R}) \cap \mathcal{B}.$$

Let $\omega_{C, \mathbf{e}}$ and $\omega_{E, \mathbf{e}}$ be the opening of $\Gamma_{C, \mathbf{e}}$ and $\Gamma_{E, \mathbf{e}}$ respectively. Of course we have $\omega_{C, \mathbf{e}} + \omega_{E, \mathbf{e}} = 2\pi$. We refer to this partition of \mathbb{R}^2 into two sectors associated with \mathbf{e} by the notation $\Gamma_{\mathbf{e}}$.

Like for corners, we denote by $\Lambda_{\underline{\delta}}(\Gamma_{\mathbf{e}})$ the set of the exponents determined by problem (41) with $\alpha = \alpha^{\delta}$, see (43), for $\delta \geq 0$, and with $\Gamma_C = \Gamma_{C, \mathbf{e}}$ and $\Gamma_E = \Gamma_{E, \mathbf{e}}$. We denote similarly the spaces of singularities by $Z^{\lambda}(\Gamma_{\mathbf{e}}, \underline{\delta})$. As a consequence of Proposition 4.1, we obtain

Lemma 4.3. *For $\delta = 0$, the set of singular exponents satisfies*

$$\Lambda_{\underline{0}}(\Gamma_{\mathbf{e}}) = \left\{ \frac{k\pi}{\omega_{C, \mathbf{e}}} : k \in \mathbb{Z} \right\} \cup \left\{ \frac{k\pi}{\omega_{E, \mathbf{e}}} : k \in \mathbb{Z} \setminus \{0\} \right\}.$$

For $\delta > 0$, $\Lambda_{\underline{\delta}}(\Gamma_{\mathbf{e}})$ is the set of $\lambda = \sqrt{\nu}$ with ν solution in \mathbb{C} of the equation

$$(1 + \eta) \sin \nu\pi = \pm(1 - \eta) \sin \nu(\pi - \omega_{C, \mathbf{e}}), \quad \text{with } \eta \text{ given in (45).}$$

When $\delta \rightarrow 0$, the set $\Lambda_{\underline{\delta}}(\Gamma_{\mathbf{e}})$ tends to $\Lambda_{\underline{0}}(\Gamma_{\mathbf{e}})$.

The exponents and singular spaces associated with Δ_{μ} are denoted by $\Lambda_{\mu}(\Gamma_{\mathbf{e}})$ and $Z^{\lambda}(\Gamma_{\mathbf{e}}, \mu)$, according to Section 4.2 (iii).

5. CORNER AND EDGE SINGULARITIES OF THE EDDY CURRENT PROBLEM

The singularities of the solution \mathbf{E}^{δ} of problem (16) for $\delta > 0$ are those of a Maxwell transmission problem, very similar to that investigated in [17]. Here, we concentrate on the solution of the eddy current problem $\mathbf{E} = \mathbf{E}^0$, which is also the solution of the regularized variational formulation (21) for $\delta = 0$, i.e.

$$\text{Find } \mathbf{E} \in \mathbf{Y}(\Omega) \quad \text{s. t.} \quad a_R^0(\mathbf{E}, \mathbf{v}) = -i\omega(\mathbf{j}_0, \mathbf{v})_{\Omega_C}, \quad \forall \mathbf{v} \in \mathbf{Y}(\Omega). \quad (51)$$

In this section we describe the corner and edge singularities of problem (51). These singularities are obtained as in [15, 17] with the necessary adaptations.

5.1. Corner singularities

Fix a corner \mathbf{a} of Ω_C and denote by $(\rho_{\mathbf{a}}, \vartheta_{\mathbf{a}})$ the spherical coordinates centered at \mathbf{a} . Denote furthermore by $\Gamma_{C, \mathbf{a}}$ (resp. $\Gamma_{E, \mathbf{a}}$) the infinite polyhedral cone which coincides with Ω_C (resp. Ω_E) near \mathbf{a} . Like in Section 4.3,

we denote by $\Gamma_{\mathbf{a}}$ the space \mathbb{R}^3 when we refer to its partition into Γ_C, \mathbf{a} and Γ_E, \mathbf{a} . For shortness we now drop the index \mathbf{a} . As usual we are looking for solutions of the homogeneous eddy current problem in the space

$$\mathbf{S}^\lambda(\Gamma) = \left\{ \mathbf{u} \in \mathbf{X}_{loc}(\Gamma) \mid \operatorname{div} \mathbf{u}_C \in H^1_{loc}(\Gamma_C), \operatorname{div} \mathbf{u}_E \in H^1_{loc}(\Gamma_E), \right. \\ \left. \mathbf{u}(x) = \rho^\lambda \sum_{q=0}^Q (\log \rho)^q \mathbf{U}_q(\vartheta) \right\},$$

the index *loc* meaning that the properties hold in all bounded domains far from \mathbf{a} . This means that we look for a non-polynomial solution $\mathbf{u} \in \mathbf{S}^\lambda(\Gamma)$ of (the last two boundary conditions may be justified by taking arbitrary right-hand sides $f \in L^2(\Omega)$ in (51), using arguments as in Th. 1.1 of [17])

$$\left\{ \begin{array}{ll} \operatorname{curl}(\mu_C^{-1} \operatorname{curl} \mathbf{u}) - \nabla \operatorname{div} \mathbf{u} = 0 & \text{in } \Gamma_C, \\ \operatorname{curl}(\mu_E^{-1} \operatorname{curl} \mathbf{u}) - \nabla \operatorname{div} \mathbf{u} = 0 & \text{in } \Gamma_E, \\ \mathbf{u}_C \cdot \mathbf{n} = 0 & \text{on } I := \partial\Gamma_C = \partial\Gamma_E, \\ [\mathbf{u} \times \mathbf{n}] = 0 & \text{on } I, \\ [\mu^{-1} \operatorname{curl} \mathbf{u} \times \mathbf{n}] = 0, [\operatorname{curl} \mathbf{u} \cdot \mathbf{n}] = 0 & \text{on } I, \\ \partial_n(\operatorname{div} \mathbf{u}_C) = 0 & \text{on } I, \\ \operatorname{div} \mathbf{u}_E = 0 & \text{on } I. \end{array} \right. \tag{52}$$

If a nontrivial solution exists then we say that λ is an eddy current corner exponent.

For the sake of simplicity we assume that Γ_C and Γ_E are simply connected, the general case can be treated as in [15] and simply yields additional ‘‘topological’’ singular exponents.

As in [15, 17], this problem is split up into three subproblems by introducing the auxiliary unknowns

$$\boldsymbol{\psi} = \mu^{-1} \operatorname{curl} \mathbf{u}$$

and

$$q = \begin{cases} \operatorname{div} \mathbf{v}_C & \text{in } \Gamma_C, \\ \operatorname{div} \mathbf{v}_E & \text{in } \Gamma_E. \end{cases}$$

With these notations, problem (52) is equivalent to looking for $q, \boldsymbol{\psi}, \mathbf{u}$, successive solutions of

$$\left\{ \begin{array}{ll} \Delta q = 0 & \text{in } \Gamma_C, \\ \Delta q = 0 & \text{in } \Gamma_E, \\ \partial_n q_C = 0 & \text{on } I, \\ q_E = 0 & \text{on } I, \end{array} \right. \tag{53}$$

$$\left\{ \begin{array}{ll} \operatorname{curl} \boldsymbol{\psi} = \nabla q, \operatorname{div}(\mu_C \boldsymbol{\psi}) = 0 & \text{in } \Gamma_C, \\ \operatorname{curl} \boldsymbol{\psi} = \nabla q, \operatorname{div}(\mu_E \boldsymbol{\psi}) = 0 & \text{in } \Gamma_E, \\ [\boldsymbol{\psi} \times \mathbf{n}] = 0, [\mu \boldsymbol{\psi} \cdot \mathbf{n}] = 0 & \text{on } I, \end{array} \right. \tag{54}$$

$$\left\{ \begin{array}{ll} \operatorname{curl} \mathbf{u} = \mu_C \boldsymbol{\psi}, \operatorname{div} \mathbf{u} = q & \text{in } \Gamma_C, \\ \operatorname{curl} \mathbf{u} = \mu_E \boldsymbol{\psi}, \operatorname{div} \mathbf{u} = q & \text{in } \Gamma_E, \\ \mathbf{u}_C \cdot \mathbf{n} = 0 & \text{on } I, \\ [\mathbf{u} \times \mathbf{n}] = 0 & \text{on } I. \end{array} \right. \tag{55}$$

This means that we have three types of singularities:

Type 1: $q = 0, \boldsymbol{\psi} = 0$ and \mathbf{u} is a general solution of (55);

Type 2: $q = 0, \boldsymbol{\psi}$ is a general solution of (54) and \mathbf{u} a particular solution of (55);

Type 3: q is a general solution of (53), $\boldsymbol{\psi}$ a particular solution of (54) and \mathbf{u} a particular solution of (55).

These three types of singularities may be described with the help of the corner singularities of the Neumann problem in Γ_C , of the Dirichlet problem in Γ_E and of the transmission operator Δ_μ .

Since for our problem (51), $\text{div } \mathbf{E}_C$ and $\text{div } \mathbf{E}_E$ are regular, we do not describe the singularities of type 3 since they cannot occur for any solution of (51).

Let us start with the singularity of type 1:

Lemma 5.1. *Assume that $\lambda \neq -1$. Then $\mathbf{u} \in \mathbf{S}^\lambda(\Gamma)$ is a singularity of type 1 if and only if (i) or (ii) below holds.*

(i) $\lambda + 1$ belongs to $\Lambda^{\text{Neu}}(\Gamma_C)$, $\mathbf{u} = \nabla\Phi$, with $\Phi_C \in Z_{\text{Neu}}^{\lambda+1}(\Gamma_C)$ and $\Phi_E \in S^{\lambda+1}(\Gamma_E)$ solution of

$$\begin{cases} \Delta\Phi_E = 0 & \text{in } \Gamma_E, \\ \Phi_E = \Phi_C & \text{on } I. \end{cases} \tag{56}$$

(ii) $\lambda + 1$ belongs to $\Lambda^{\text{Dir}}(\Gamma_E)$, $\mathbf{u} = \nabla\Phi$, with $\Phi_C = 0$ and $\Phi_E \in Z_{\text{Dir}}^{\lambda+1}(\Gamma_E)$.

Proof. As

$$\begin{aligned} \mathbf{curl } \mathbf{u}_C &= 0 & \text{in } \Gamma_C, \\ \mathbf{curl } \mathbf{u}_E &= 0 & \text{in } \Gamma_E, \end{aligned}$$

there exists $\Phi_C \in S^{\lambda+1}(\Gamma_C)$ and $\Phi_E \in S^{\lambda+1}(\Gamma_E)$ such that

$$\begin{aligned} \mathbf{u}_C &= \nabla\Phi_C & \text{in } \Gamma_C, \\ \mathbf{u}_E &= \nabla\Phi_E & \text{in } \Gamma_E. \end{aligned}$$

From (55) we deduce that

$$\begin{cases} \Delta\Phi_C = 0 & \text{in } \Gamma_C, \\ \Delta\Phi_E = 0 & \text{in } \Gamma_E, \\ \partial_n\Phi_C = 0 & \text{on } I, \\ \Phi_C = \Phi_E & \text{on } I. \end{cases}$$

Then either Φ_C is not zero and we are in the case (i) or $\Phi_C = 0$ and we are in the case (ii). □

Lemma 5.2. *Assume that $\lambda > 0$. Then $\mathbf{u} \in \mathbf{S}^\lambda(\Gamma)$ is a singularity of type 2 if and only if λ belongs to $\Lambda_\mu(\Gamma)$, $\psi = \nabla\Psi$, with $\Psi \in Z^\lambda(\Gamma, \mu)$ and \mathbf{u} given by*

$$\mathbf{u} = \frac{1}{\lambda + 1} (\mu(\nabla\Psi \times \mathbf{x}) + \nabla r), \tag{57}$$

where $r_C \in S^{\lambda+1}(\Gamma_C)$, $r_E \in S^{\lambda+1}(\Gamma_E)$ are solutions of

$$\begin{cases} \Delta r_C = 0 & \text{in } \Gamma_C, \\ \Delta r_E = 0 & \text{in } \Gamma_E, \\ \partial_n r_C = -\mu_C(\nabla\Psi_C \times \mathbf{x}) \cdot \mathbf{n} & \text{on } I, \\ r_C = r_E & \text{on } I. \end{cases} \tag{58}$$

Proof. As

$$\begin{aligned} \mathbf{curl } \psi_C &= 0 & \text{in } \Gamma_C, \\ \mathbf{curl } \psi_E &= 0 & \text{in } \Gamma_E, \end{aligned}$$

there exists $\Psi_C \in S^\lambda(\Gamma_C)$ and $\Psi_E \in S^\lambda(\Gamma_E)$ such that

$$\begin{aligned}\psi_C &= \nabla \Psi_C \quad \text{in } \Gamma_C, \\ \psi_E &= \nabla \Psi_E \quad \text{in } \Gamma_E.\end{aligned}$$

From (54) we deduce that

$$\begin{cases} \operatorname{div}(\mu_C \nabla \Psi_C) = 0 & \text{in } \Gamma_C, \\ \operatorname{div}(\mu_E \nabla \Psi_E) = 0 & \text{in } \Gamma_E, \\ [\Psi] = 0, \quad [\mu \partial_n \Psi] = 0 & \text{on } I. \end{cases}$$

This means that $\Psi \in Z^\lambda(\Gamma, \mu)$.

Now we readily check that \mathbf{u} in the form (57) is solution of (55) if and only if r is solution of (58), whose solution exists by Theorem 4.14 of [26]. \square

Lemma 5.3. (i) $\lambda = -1$ is not a corner singularity of type 1.
(ii) $\lambda = 0$ is not a corner singularity of type 2.

Proof.

(i) If \mathbf{u} is a singularity of type 1 for $\lambda = -1$, then \mathbf{u}_C is a singularity of type 1 for $\lambda = -1$ for the Maxwell system in Γ_C with the boundary condition $\mathbf{u}_C \cdot \mathbf{n} = 0$ on I . Therefore by Lemma 7.8 of [15] $\mathbf{u}_C = 0$. With this information, \mathbf{u}_E is now a singularity of type 1 for $\lambda = -1$ for the Maxwell system in Γ_E with the boundary condition $\mathbf{u}_E \times \mathbf{n} = 0$ on I . Again by Lemma 7.8 of [15] we get $\mathbf{u}_E = 0$.

(ii) If \mathbf{u} is a singularity of type 2 for $\lambda = 0$, then $\psi = \mu^{-1} \operatorname{curl} \mathbf{u}_C$ is a singularity of type 1 for $\lambda = -1$ for the Maxwell interface system in \mathbb{R}^3 with the parameter μ . Therefore by Lemma 5.4 of [17] we get $\psi = 0$. \square

Since the singularities of our problem (51) have to be locally in $\mathbf{X}(\Gamma)$ with a piecewise smooth divergence, among the singular exponents described above, we select the subset $\Lambda_{\mathbf{a}}$ of $\lambda > -\frac{3}{2}$ such that there exists $\mathbf{u} \in \mathbf{S}^\lambda(\Gamma)$ solution of (52) such that

$$\chi \mathbf{u} \in \mathbf{X}(\Gamma),$$

where χ is a cut-off function equal to 1 near \mathbf{a} . This last condition implies the following constraints for our two types of singularities (see [17]):

Type 1: $\lambda + 1 \in \Lambda^{\operatorname{Neu}}(\Gamma_C)$ or $\lambda + 1 \in \Lambda^{\operatorname{Dir}}(\Gamma_E)$ and since $\Lambda^{\operatorname{Dir}}(\Gamma_E) \cap [-1, 0]$ and $\Lambda^{\operatorname{Neu}}(\Gamma_C) \cap [-1, 0]$ are empty, by Lemma 5.3 we get $\lambda > -1$;

Type 2: $\lambda \in \Lambda_\mu(\Gamma)$ and by the condition $\operatorname{curl}(\chi \mathbf{u}) \in [L^2(\mathbb{R}^3)]^3$, we get $\lambda > -\frac{1}{2}$. By Lemma 5.3 and the fact that $\Lambda_\mu(\Gamma) \cap [-1, 0]$ is empty, we get $\lambda > 0$.

In conclusion we have

$$\begin{aligned}\Lambda_{\mathbf{a}} &= \{\lambda > -1 : \lambda + 1 \in \Lambda^{\operatorname{Neu}}(\Gamma_C)\} \cup \{\lambda > -1 : \lambda + 1 \in \Lambda^{\operatorname{Dir}}(\Gamma_E)\} \\ &\quad \cup \{\lambda > 0 : \lambda \in \Lambda_\mu(\Gamma)\}.\end{aligned}$$

5.2. Edge singularities

Fix an edge \mathbf{e} of Ω_C and denote by $\Gamma_C \times \mathbb{R}$ (resp. $\Gamma_E \times \mathbb{R}$) the infinite polyhedral cone which coincides with Ω_C (resp. Ω_E) near \mathbf{e} (Γ_C and Γ_E are then two-dimensional sectors). Denote by (r, θ, z) the cylindrical coordinates along \mathbf{e} . As before we are looking for solutions of the homogeneous eddy current problem (52) in $\Gamma_C \times \mathbb{R}$ and $\Gamma_E \times \mathbb{R}$. Now Γ refers to \mathbb{R}^2 with its partition into the two sectors Γ_C and Γ_E , cf Section 4.4. Writing $\mathbf{u} = (\mathbf{v}, w)$, where \mathbf{v} are the first two components of \mathbf{u} in the Cartesian coordinates (x_1, x_2, x_3) (according to the above notation, the x_3 -axis contains the edge \mathbf{e}), the system (52) is split up into the following two independent

problems in \mathbb{R}^2 :

$$\begin{cases} \mathbf{curl}(\mu_C^{-1} \mathbf{curl} \mathbf{v}) - \nabla \operatorname{div} \mathbf{v} = 0 & \text{in } \Gamma_C, \\ \mathbf{curl}(\mu_E^{-1} \mathbf{curl} \mathbf{v}) - \nabla \operatorname{div} \mathbf{v} = 0 & \text{in } \Gamma_E, \\ \mathbf{v}_C \cdot \mathbf{n} = 0 & \text{on } I := \partial\Gamma_C = \partial\Gamma_E, \\ [\mathbf{v} \times \mathbf{n}] = 0 & \text{on } I, \\ [\mu^{-1} \mathbf{curl} \mathbf{v} \times \mathbf{n}] = 0 & \text{on } I, \\ \partial_n(\operatorname{div} \mathbf{v}_C) = 0 & \text{on } I, \\ \operatorname{div} \mathbf{v}_E = 0 & \text{on } I. \end{cases} \tag{59}$$

$$\begin{cases} \operatorname{div}(\mu_C^{-1} \nabla w_C) = 0 & \text{in } \Gamma_C, \\ \operatorname{div}(\mu_E^{-1} \nabla w_E) = 0 & \text{in } \Gamma_E, \\ [w] = 0, \quad [\mu^{-1} \partial_n w] = 0 & \text{on } I. \end{cases} \tag{60}$$

Problem (60) is a standard transmission problem whose set of singularities $\Lambda_{\mu^{-1}}(\Gamma) = \Lambda_\mu(\Gamma)$ (see Lem. 6.2 of [17]) were described in Section 4. Problem (59) is a two-dimensional eddy current problem whose singularities may be described as in 3D, by introducing the auxiliary unknowns $\psi = \mu^{-1} \mathbf{curl} \mathbf{v}$ and

$$q = \begin{cases} \operatorname{div} \mathbf{v} & \text{in } \Gamma_C, \\ \operatorname{div} \mathbf{v} & \text{in } \Gamma_E. \end{cases}$$

As before, singularities of type 1, 2 and 3 then appear. We can show that singularities of type 2 do not exist (compare with [15, 17]), singularities of type 3 are not studied for the same reason as before, while singularities of type 1 are analyzed exactly as in Lemma 5.1.

In conclusion we can state the following result.

Lemma 5.4. *The set Λ_e of edge exponents associated with \mathbf{e} is given by*

$$\begin{aligned} \Lambda_e = \{ \lambda > -1 : \lambda + 1 \in \Lambda^{\text{Neu}}(\Gamma_C) \} &\cup \{ \lambda > -1 : \lambda + 1 \in \Lambda^{\text{Dir}}(\Gamma_E) \} \\ &\cup \{ \lambda > 0 : \lambda \in \Lambda_\mu(\Gamma) \}. \end{aligned}$$

If $\lambda \notin \mathbb{N} \setminus \{0\}$, then the associated singular function $\mathbf{u} = (\mathbf{v}, w)$ is as follows:

- If $\lambda + 1 \in \Lambda^{\text{Neu}}(\Gamma_C)$, then $w = 0$,

$$\mathbf{v}_C = \nabla (r^{\lambda+1} \varphi_C),$$

with $\varphi_C(\theta) = \cos((\lambda + 1)\theta)$ (the half-lines $\theta = 0$ and $\theta = \omega_C$ are assumed to be the interfaces between Γ_C and Γ_E , the interior opening of Γ_C (resp. Γ_E) is then ω_C (resp. $\omega_E = 2\pi - \omega_C$)), and if $\frac{\omega_E}{\omega_C}$ is not a rational number, then

$$\mathbf{v}_E = \nabla (r^{\lambda+1} \varphi_E),$$

with $\varphi_E(\theta) = c_1 \cos((\lambda + 1)\theta) + c_2 \sin((\lambda + 1)\theta)$, for some (explicit) constants c_1 and c_2 . If $\frac{\omega_E}{\omega_C}$ is a rational number, then a logarithmic term possibly appears in the expression of \mathbf{v}_E ;

- if $\lambda + 1 \in \Lambda^{\text{Dir}}(\Gamma_E)$, then $w = 0$, $\mathbf{v}_C = 0$ and

$$\mathbf{v}_E = \nabla (r^{\lambda+1} \varphi_E),$$

with $\varphi_E(\theta) = \sin((\lambda + 1)(\theta - \omega_C))$;

- if $\lambda \in \Lambda_\mu(\Gamma)$, then $\mathbf{v} = 0$ and $w = r^\lambda \varphi$, with φ an eigenvector of problem (42) for $\alpha = \mu$, associated with the eigenvalue $\nu = \lambda^2$.

6. REGULARITY AND SINGULARITY RESULTS FOR THE EDDY CURRENT PROBLEM

We describe the regularity as well as singular decompositions of any solution \mathbf{E} of the regularized problem (51) with a source current density \mathbf{j}_0 such that

$$\operatorname{div} \mathbf{j}_0 = 0, \quad \operatorname{supp} \mathbf{j}_0 \subset \Omega_C, \quad \mathbf{j}_0 \in [H^{s-1}(\Omega_C)]^3 \text{ for } s \geq 1. \tag{61}$$

These results are based on the knowledge of corner and edge singularities described in the previous section and rely on the application of Mellin techniques as in [15, 17].

6.1. Regularity

For any corner \mathbf{a} in the interface B introduce

$$\begin{aligned} \lambda_{C, \mathbf{a}}^{\text{Neu}} &= \min\{\lambda > 0 : \lambda \in \Lambda^{\text{Neu}}(\Gamma_{C, \mathbf{a}})\}, \\ \lambda_{E, \mathbf{a}}^{\text{Dir}} &= \min\{\lambda > 0 : \lambda \in \Lambda^{\text{Dir}}(\Gamma_{E, \mathbf{a}})\}, \\ \lambda_{\mu, \mathbf{a}} &= \min\{\lambda > 0 : \lambda \in \Lambda_{\mu}(\Gamma_{\mathbf{a}})\}, \end{aligned}$$

where $\Lambda_{\mu}(\Gamma_{\mathbf{a}})$ is defined in Section 4.3 for the subdivision of \mathbb{R}^3 into $\Gamma_{C, \mathbf{a}}$ and $\Gamma_{E, \mathbf{a}}$. Similarly for any edge $\mathbf{e} \subset B$ define

$$\lambda_{\mu, \mathbf{e}} = \min\{\lambda > 0 : \lambda \in \Lambda_{\mu}(\Gamma_{\mathbf{e}})\}.$$

Now we can set

$$\begin{aligned} \tau_{\mathbf{e}}^{(1)} &:= \min\left(\frac{\pi}{\omega_{C, \mathbf{e}}}, \frac{\pi}{\omega_{E, \mathbf{e}}}\right), \\ \tau_{\mathbf{a}}^{(1)} &:= \min(\lambda_{C, \mathbf{a}}^{\text{Neu}}, \lambda_{E, \mathbf{a}}^{\text{Dir}}), \\ \tau^{(1)} &:= \min\left(\min_{\mathbf{e}} \tau_{\mathbf{e}}^{(1)}, \frac{1}{2} + \min_{\mathbf{a}} \tau_{\mathbf{a}}^{(1)}\right), \\ \tau_C^{(1)} &:= \min\left(\min_{\mathbf{e}} \frac{\pi}{\omega_{C, \mathbf{e}}}, \frac{1}{2} + \min_{\mathbf{a}} \lambda_{C, \mathbf{a}}^{\text{Neu}}\right), \\ \tau^{(2)} &:= \min\left(\min_{\mathbf{e}} \lambda_{\mu, \mathbf{e}}, \frac{1}{2} + \min_{\mathbf{a}} \lambda_{\mu, \mathbf{a}}\right), \end{aligned}$$

when $\omega_{C, \mathbf{e}}$ is the opening of Ω_C along \mathbf{e} and $\omega_{E, \mathbf{e}} = 2\pi - \omega_{C, \mathbf{e}}$ is the opening of Ω_E along \mathbf{e} .

Then we have

Theorem 6.1. *Let $\mathbf{E} \in \mathbf{Y}(\Omega)$ be a solution of problem (51) with \mathbf{j}_0 satisfying (61) for $s \geq 1$. Then we have*

$$\begin{aligned} \mathbf{E}_C &\in H^{\tau_C}(\Omega_C), \quad \forall \tau_C < \min(\tau_C^{(1)}, \tau^{(2)} + 1, s + 1), \\ \mathbf{E}_E &\in H^{\tau_E}(\Omega_E), \quad \forall \tau_E < \min(\tau^{(1)}, \tau^{(2)} + 1, s + 1). \end{aligned}$$

6.2. Singularities

We start with a general result and then restrict ourselves to a particular case where there remain only singularities of type 1.

The general result is proved exactly as in [15, 17] and can be stated as follows:

Theorem 6.2. *Assume that $s \geq 1$ such that for all corners \mathbf{a} , $s - \frac{1}{2}$ does not belong to $\Lambda_{\mathbf{a}}$ and for all edges \mathbf{e} , s does not belong to $\Lambda_{\mathbf{e}}$. Assume furthermore that the edge exponents in $[-1, s]$ are contained in an interval of*

length < 1 . Let $\mathbf{E} \in \mathbf{Y}(\Omega)$ be a solution of problem (51) with \mathbf{j}_0 satisfying (61) for this regularity exponent s . Then \mathbf{E} admits the decomposition

$$\mathbf{E} = \mathbf{E}^{(R)} + \mathbf{E}^{(S)}, \quad (62)$$

where the regular part satisfies

$$\mathbf{E}_C^{(R)} \in H^{s+1}(\Omega_C) \quad \text{and} \quad \mathbf{E}_E^{(R)} \in H^{s+1}(\Omega_E).$$

On the other hand the singular part $\mathbf{E}^{(S)}$ has the standard structure

$$\mathbf{E}^{(S)} = \sum_{\mathbf{a}} \sum_{\lambda \in \Lambda_{\mathbf{a}} \cap [-\frac{3}{2}, s-\frac{1}{2}]} \sum_p \gamma_{\mathbf{a}}^{\lambda,p} \chi_{\mathbf{a}}(\rho_{\mathbf{a}}) \mathbf{u}_{\mathbf{a}}^{\lambda,p}(\rho_{\mathbf{a}}, \vartheta_{\mathbf{a}}) \quad (63)$$

$$+ \sum_{\mathbf{e}} \sum_{\lambda \in \Lambda_{\mathbf{e}} \cap [-1, s]} \sum_p \mathcal{K}[\gamma_{\mathbf{e}}^{\lambda,p}] \chi_{\mathbf{e}}(\rho_{\mathbf{e}}) \mathbf{u}_{\mathbf{e}}^{\lambda,p}(\rho_{\mathbf{e}}, \theta_{\mathbf{e}}), \quad (64)$$

where $\mathbf{u}_{\mathbf{a}}^{\lambda,p}$ (resp. $\mathbf{u}_{\mathbf{e}}^{\lambda,p}$) are the corner (resp. edge) singularities of type 1 or 2 described in the previous section, $\chi_{\mathbf{a}}$ (resp. $\chi_{\mathbf{e}}$) is a smooth cut-off function equal to 1 near $\rho = 0$, $\rho_{\mathbf{e}} = r_{\mathbf{e}} d_{\mathbf{e}}^{-1}$ when $d_{\mathbf{e}}$ is a smooth function which is equivalent to the distance of the endpoints of \mathbf{e} , \mathcal{K} is a convolution operator (cf. [15, 17, 18]) and $\gamma_{\mathbf{a}}^{\lambda,p}$ (resp. $\gamma_{\mathbf{e}}^{\lambda,p}$) are real constant (resp. functions defined in the edge \mathbf{e} and belonging to some weighted Sobolev spaces).

Exactly as in [15, 17], if one wants to eliminate the singularities of type 2, we introduce a parameter $\tau \leq s$ satisfying

$$\tau < \min\{\tau^{(1)}, \tau^{(2)}\}. \quad (65)$$

Using Lemmas 4.11 and 4.13 of [15], we obtain

Theorem 6.3. *Let $\mathbf{E} \in \mathbf{Y}(\Omega)$ be a solution of problem (51) with \mathbf{j}_0 as in the introduction and the regularity $\mathbf{j}_0 \in [H^{s-1}(\Omega_C)]^3$ with $s \geq 1$. Let $\tau \leq s$ satisfy (65) and such that the edge exponents in $[-1, \tau]$ are contained in an interval of length < 1 . Then \mathbf{E} admits the decomposition*

$$\mathbf{E} = \mathbf{E}^{(R)} + \nabla \Phi,$$

where the regular part satisfies

$$\mathbf{E}_C^{(R)} \in H^{\tau+1}(\Omega_C) \quad \text{and} \quad \mathbf{E}_E^{(R)} \in H^{\tau+1}(\Omega_E),$$

while $\Phi \in H^1(\Omega)$ satisfies

$$\Delta \Phi_C \in H^{\tau}(\Omega_C)$$

$$\partial_n \Phi_C = 0 \quad \text{on } B,$$

and

$$\Delta \Phi_E \in H^{\tau}(\Omega_E),$$

$$\Phi_E = \Phi_C \quad \text{on } B.$$

If $\tau = 0$ the above theorem reduces to Theorem 3.1. For τ not necessarily equal to zero, as in that theorem, Φ_C has the singularities of the interior Neumann problem, while Φ_E has induced exterior singularities as well as exterior Dirichlet ones.

7. CONTINUITY OF THE SINGULAR FUNCTIONS IN THE EDDY CURRENT LIMIT

If we put together:

- (1) the result of Section 4.2 which yields the continuity of the singular exponents with respect to δ for the associated scalar problem;
- (2) the common structure of Maxwell and eddy current singularities of type 1 (as gradients of scalar singularities);
- (3) the similar structure of Maxwell and eddy current singularities of type 2 (compare our Lem. 5.2 with [17, Lem. 5.2]);

we may wonder whether it is possible to define a basis of singular fields $\mathbf{u}_a^{\lambda,p}[\delta]$ and $\mathbf{u}_e^{\lambda,p}[\delta]$ for the eddy current problem (51), $\delta = 0$, and the Maxwell problem (21), $\delta > 0$, which should be regular with respect to $\delta \in [0, \delta_0]$ and so that a decomposition like that of Theorem 6.2 holds with coefficients depending smoothly on δ .

In this paper, we will not address this question in its full complexity, but show that it is possible to choose bases of singular functions in a regular way with respect to δ , up to the limit $\delta = 0$. This means that we have mainly to investigate the behavior of all singularities (*i.e.* in $S^\lambda(\Gamma)$) of the scalar problems (40) when $\alpha = \alpha^\delta$ given by (43), as $\delta \rightarrow 0$. Similar questions are addressed in [13, 14, 27]. Since the direct application of these references is not straightforward, we are going to state the main steps of a relevant construction.

In the general case, we cannot exclude any of the phenomena such as “crossing” and “branching” that appear for singularity problems depending on a parameter. Since, in our situation, the coefficients are non-real, we may expect singularity exponents that have algebraic branch points for certain values of δ , even for $\delta = 0$, *i.e.* in the eddy current limit. We also can have changes of multiplicities, even for $\delta = 0$, for example in the case where a singular exponent for the Neumann problem in Γ_C coincides with a singular exponent for the Dirichlet problem in Γ_E .

In both these situations, any individual singular function of the transmission problem Δ_δ of the form $\rho^{\lambda_\delta} \psi_\delta(\vartheta)$ will converge to a singular function $\rho^{\lambda_0} \psi_0(\vartheta)$ of the limit problem, but the coefficients of a such singular function may be non-regular with respect to δ or even blow up for $\delta \rightarrow 0$. Clustering several singular functions together and choosing a basis depending analytically on δ as explained below in Section 7.2 will avoid such pathologies.

7.1. Mellin symbols

It is known from [23] that the corner singularities solution of (41) are produced by the poles of the associated *Mellin symbol*: Let us recall that the Mellin symbol of an operator A homogeneous of degree m with constant coefficients is $\lambda \mapsto \mathfrak{A}(\lambda)$ where

$$A(\partial_x) = \rho^{-m} \mathfrak{A}(\vartheta; \rho \partial_\rho, \partial_\vartheta) \quad \text{and} \quad \mathfrak{A}(\lambda) := \mathfrak{A}(\vartheta; \lambda, \partial_\vartheta).$$

Let us consider the situation of threedimensional cones ($d = 3$). The symbol associated with the operator (40) – see also (41), is

$$\psi \mapsto \begin{cases} L\psi_C - \lambda(\lambda + 1)\psi_C & \text{in } G_C, \\ L\psi_E - \lambda(\lambda + 1)\psi_E & \text{in } G_E, \\ \alpha_C \partial_{n_C} \psi_C + \alpha_E \partial_{n_E} \psi_E & \text{on } J := \partial G_C = \partial G_E. \end{cases} \tag{66}$$

Let us denote by $\mathfrak{M}_\alpha(\lambda)$ the operator (66) acting between function spaces:

$$\mathfrak{M}_\alpha(\lambda) : \mathbf{Z}(G_C, G_E) \longrightarrow L^2(G_C) \times L^2(G_E) \times H^{-1/2}(J),$$

where the source space $\mathbf{Z}(G_C, G_E)$ is defined as

$$\mathbf{Z}(G_C, G_E) = \{ \varphi \in H^1(S^2) : \Delta \varphi_C \in L^2(G_C), \Delta \varphi_E \in L^2(G_E) \}.$$

When $\alpha = \alpha^\delta$ is given by (43), we denote $\mathfrak{M}_\alpha(\lambda)$ by $\mathfrak{M}_\delta(\lambda)$.

We are going to prove that for all $\delta \in [0, \delta_0]$ there exists λ such that $\mathfrak{M}_{\underline{\delta}}(\lambda)$ is invertible. Let (f_C, f_E, g) belong to $L^2(G_C) \times L^2(G_E) \times H^{-1/2}(J)$ and let us fix λ such that $-\lambda(\lambda + 1) > 0$.

- If $\delta = 0$, we first solve the Neumann problem

$$\begin{aligned} (L - \lambda(\lambda + 1))\psi_C &= f_C & \text{in } G_C, \\ \alpha_C \partial_{n_C} \psi_C &= g & \text{on } J \end{aligned}$$

and then the Dirichlet problem

$$\begin{aligned} (L - \lambda(\lambda + 1))\psi_E &= f_E & \text{in } G_E, \\ \psi_E &= \psi_C|_J & \text{on } J. \end{aligned}$$

- If $\delta > 0$, we use a variational formulation as in (42): $\forall \varphi \in H^1(\mathbb{S}^{d-1})$,

$$\int_{\mathbb{S}^{d-1}} \alpha \nabla \psi \cdot \nabla \varphi - \lambda(\lambda + 1) \int_{\mathbb{S}^{d-1}} \alpha \psi \varphi = \int_{G_C} f_C \varphi_C + \int_{G_E} f_E \varphi_E + \int_J g \psi.$$

Since the right hand side is clearly in $H^{-1}(\mathbb{S}^{d-1})$, the coerciveness yields a unique solution.

The analytic Fredholm theorem yields that for all $\delta \in [0, \delta_0]$, $\lambda \mapsto \mathfrak{M}_{\underline{\delta}}(\lambda)^{-1}$ is meromorphic. As the dependency of the symbol on δ is analytic, such is also the case for its inverse.

7.2. Stable bases for singularities

Let $\delta \in [0, \delta_0]$ be fixed. We recall that we have denoted by $\Lambda_{\underline{\delta}}(\Gamma)$ the set of the singular exponents of the operator $\Delta_{\underline{\delta}}$ (transmission or coupling).

The singular exponents in $\Lambda_{\underline{\delta}}(\Gamma)$ coincide with the poles λ_0 of $\mathfrak{M}_{\underline{\delta}}(\lambda)^{-1}$. Moreover the corresponding space of singularities $Z^{\lambda_0}(\Gamma; \underline{\delta})$ (the space of solutions in $S^{\lambda_0}(\Gamma)$ of (41) for $\alpha = \alpha^{\delta}$) is also given by a Cauchy residue formula:

$$Z^{\lambda_0}(\Gamma; \underline{\delta}) = \left\{ \Psi : \exists F \in \mathcal{O}(D(\lambda_0)), \quad \Psi = \frac{1}{2i\pi} \int_{\partial D(\lambda_0)} \rho^\lambda \mathfrak{M}_{\underline{\delta}}(\lambda)^{-1} F(\lambda) \, d\lambda \right\}$$

where

- $D(\lambda_0)$ is a disc in the complex plane centered in λ_0 and not containing any other pole of $\mathfrak{M}_{\underline{\delta}}(\lambda)^{-1}$;
- The notation $F \in \mathcal{O}(D(\lambda_0))$ means that $\lambda \mapsto F(\lambda)$ is holomorphic in a neighborhood of $\overline{D(\lambda_0)}$ with values in the target space $L^2(G_C) \times L^2(G_E) \times H^{-1/2}(J)$.

Note that if D contains several elements of $\Lambda_{\underline{\delta}}(\Gamma)$, but $\partial D \cap \Lambda_{\underline{\delta}}(\Gamma)$ is empty, then

$$\left\{ \Psi : \exists F \in \mathcal{O}(D), \quad \Psi = \frac{1}{2i\pi} \int_{\partial D} \rho^\lambda \mathfrak{M}_{\underline{\delta}}(\lambda)^{-1} F(\lambda) \, d\lambda \right\} = \bigoplus_{\lambda \in \Lambda_{\underline{\delta}}(\Gamma) \cap D} Z^\lambda(\Gamma; \underline{\delta}).$$

The smooth dependency on δ of $\mathfrak{M}_{\underline{\delta}}(\lambda)^{-1}$ implies the principle of smooth dependency of the singular spaces $Z^\lambda(\Gamma; \underline{\delta})$ on δ in the following sense: Since we are interested in the eddy current limit let us consider a pole λ_0 of $\mathfrak{M}_{\underline{\delta}}(\lambda)^{-1}$ and a disc $D = D(\lambda_0)$ such that λ_0 is the only pole of $\mathfrak{M}_{\underline{\delta}}(\lambda)^{-1}$ in \overline{D} . There exists $\delta(\lambda_0)$ such that for all $\delta \in [0, \delta(\lambda_0)]$ the symbols $\mathfrak{M}_{\underline{\delta}}(\lambda)^{-1}$ are invertible on ∂D . Then the spaces

$$\left\{ \Psi : \exists F \in \mathcal{O}(D), \quad \Psi = \frac{1}{2i\pi} \int_{\partial D} \rho^\lambda \mathfrak{M}_{\underline{\delta}}(\lambda)^{-1} F(\lambda) \, d\lambda \right\}, \quad (67)$$

depend smoothly on δ up to the limit $\delta = 0$. In other words

$$\bigoplus_{\lambda \in \Lambda_{\underline{\delta}}(\Gamma) \cap D} Z^\lambda(\Gamma; \underline{\delta}) \xrightarrow{\delta \rightarrow 0} Z^{\lambda_0}(\Gamma; \underline{0}).$$

Indeed, this statement shows the necessity of keeping together some *clusters* of poles.

We obtain easily a basis depending smoothly on δ : Choose F^1, \dots, F^m in $\mathcal{O}(D)$ such that

$$\Psi_0^n(\rho, \vartheta) := \frac{1}{2i\pi} \int_{\partial D} \rho^\lambda \mathfrak{M}_{\underline{0}}(\lambda)^{-1} F^n(\lambda) \, d\lambda, \quad n = 1, \dots, m$$

is a basis of $Z^{\lambda_0}(\Gamma; \underline{0})$. Then, for δ small enough the functions

$$\Psi_\delta^n(\rho, \vartheta) := \frac{1}{2i\pi} \int_{\partial D} \rho^\lambda \mathfrak{M}_{\underline{\delta}}(\lambda)^{-1} F^n(\lambda) \, d\lambda, \quad n = 1, \dots, m$$

are a basis of $\bigoplus_{\lambda \in \Lambda_{\underline{\delta}}(\Gamma) \cap D} Z^\lambda(\Gamma; \underline{\delta})$. The mappings $\delta \mapsto \Psi_\delta^n$ are analytic with respect to $\delta \in [0, \delta_0]$.

7.3. Simple singularities

If the dimension of $Z^{\lambda_0}(\Gamma; \underline{0})$ is 1, or more generally if $\delta = 0$ is not a point of crossing or branching for the singularities, then the behavior of individual singular functions is very simple indeed. Let us consider the two typical situations where this happens:

- (1) if $\lambda_0 \in \Lambda^{\text{Dir}}(\Gamma_E)$ is a simple eigenvalue and such that $\lambda_0 \notin \Lambda^{\text{Neu}}(\Gamma_C)$, then we can find a unique $\lambda_\delta \in \Lambda_{\underline{\delta}}(\Gamma)$ such that $\delta \mapsto \lambda_\delta$ is analytic for δ in a neighborhood of 0. If we fix a $\rho^{\lambda_0} \psi_0$ in the singular space $Z_{\text{Dir}}^{\lambda_0}(\Gamma_E)$, then we find a generator $\rho^{\lambda_\delta} \psi_\delta$ of $Z^\lambda(\Gamma; \underline{\delta})$ such that $\delta \mapsto \psi_\delta$ is analytic for δ small enough. Then $\psi_{\delta,C} \rightarrow 0$ on G_C in $H^1(G_C)$ and $\psi_{\delta,E} \rightarrow \psi_{0,E}$ on G_E in $H^1(G_E)$;
- (2) if $\lambda_0 \in \Lambda^{\text{Neu}}(\Gamma_C) \setminus \Lambda^{\text{Dir}}(\Gamma_E)$, we have a singular function $\rho^{\lambda_\delta} \psi_\delta$ with $\delta \mapsto \lambda_\delta$ and $\delta \mapsto \psi_\delta$ analytic. Here $\rho^{\lambda_0} \psi_{0,C}$ is a singular function of the Neumann problem in Γ_C and $\psi_{0,E}$ is the harmonic extension of $\psi_{0,C}$ to \mathbb{S}^2 .

Situation 1, resp. 2, occurs for the first corner singularity of the eddy current problem where Ω_C has a corner like a cube, resp. like the exterior of a cube.

Situation 1 or 2 always occurs for the *first edge singularity* where the exponent is

$$\lambda = \min \left\{ \frac{\pi}{\omega_C}, \frac{\pi}{\omega_E} \right\} - 1,$$

because π/ω_C and $\pi/\omega_E = \pi/(2\pi - \omega_C)$ never coincide. Although unpredictable in general, the simplicity of limiting exponents of singularity is generic.

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